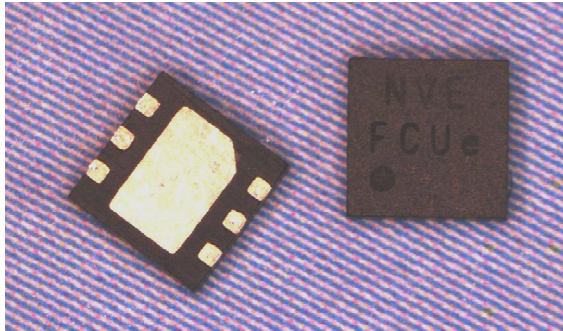
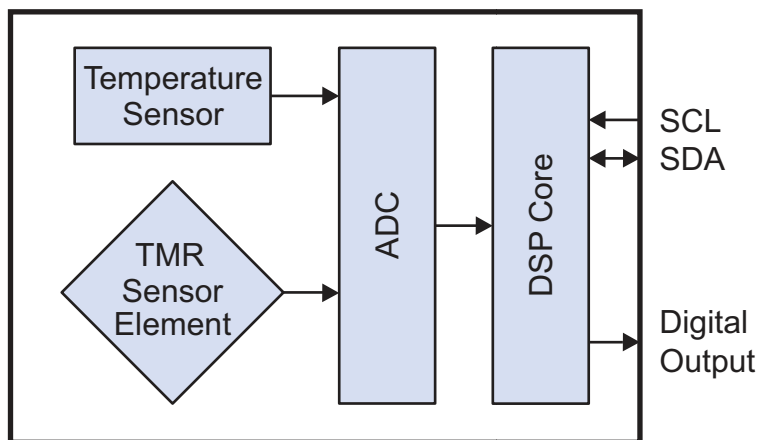


## SM324-10E Ultraprecise TMR Smart Magnetometer



### Block Diagram



### Features

- Can detect magnets more than 50 mm away
- In-plane sensitivity—more usable than Hall sensors
- Internal temperature compensation
- I<sup>2</sup>C field measurement plus on/off digital output
- Ultraminiature 2.5 x 2.5 x 0.8 mm TDFN6 package

### Key Specifications

- 0 to ±20 Oe (0 to ±2m T) magnetic field operating range
- Ultra-accurate— ±0.3% of full scale at 25 °C
- 1.5 mA typical supply current
- 300 samples/second
- -40 °C to +125 °C operating range

### Applications

- Proximity sensors
- Noncontact current sensing
- Automotive applications
- Robotics
- Internet of Things (IoT) end nodes

### Description

The SM324 Smart Magnetometer provides ultraprecise magnetic field measurements.

The sensor combines an ultraprecise Tunneling Magnetoresistance (TMR) sensor element with sophisticated digital signal processing. The digital signal processing improves accuracy and allows application-specific calibration. Calibration coefficients are stored in an internal nonvolatile memory.

Unlike awkward, old-fashioned Hall-effect sensors, TMR is sensitive in-plane for optimal current sensing and easy mechanical interfaces. TMR also provides more sensitivity, higher precision, and lower noise than Hall.

An I<sup>2</sup>C interface provides data as well as a programming interface. A digital output provides precise, programmable magnetic thresholds.

Designed for harsh industrial or automotive environments, the SM324 has robust ESD protection and full -40 °C to +125 °C operating temperature range.

## Absolute Maximum Ratings

---

Parameter	Min.	Max.	Units
Supply voltage	-0.4	3.63	Volts
Input/ Output voltages (SCL, SDA, Digital Out)	-0.5	V <sub>DD</sub> +0.5	Volts
Storage temperature	-50	130	°C
ESD (Human Body Model)	4000		Volts
Applied magnetic field		Unlimited	Oe

**Operating Specifications**

Parameter	Symbol	Min.	Typ.	Max.	Units	Test Condition
Operating temperature	$T_{MIN}; T_{MAX}$	-40		125	°C	
Supply voltage	$V_{DD}$	1.68		3.6	V	
Supply current ( $V_{DD} = 3.3$ V)	$I_{DD}$		1.5 20 50	2.5 250 750	mA nA nA	Active; $T_{MIN}$ to $T_{MAX}$ Idle Mode; $\leq 85^{\circ}\text{C}$ Idle Mode; $\leq 125^{\circ}\text{C}$
<b>Power-Up and Power-Down</b>						
Power-on reset low voltage	$V_{BOR}$	0		0.2	V	
Power down time (duration below $V_{BOR}$ )	$t_{BOR}$	3			$\mu\text{s}$	
Power-on reset rising slope	$SR_{VDD}$	10			V/ms	
Start-up time	$t_{ST1}$			1	ms	$V_{DD}$ ramp time to active communication
	$t_{ST2}$			2.5	ms	$V_{DD}$ ramp time to active operation
Wake-up time	$t_{WU1}$			0.5	ms	Idle to active communication
	$t_{WU2}$			2	ms	Idle to active operation
<b>Internal Temperature Sensor</b>						
Temperature resolution	$T_{RES}$		0.003		°K/LSB	$T_{MIN}$ to $T_{MAX}$
<b>Magnetic Measurements</b>						
Operating magnetic field strength	H			20	Oe	
Conversion rate	$f_{CON}$	270	300		S/s	
Accuracy				$\pm 0.3$ $\pm 1$	%FS	25°C $T_{MIN}$ to $T_{MAX}$
	Hysteresis			0.1	%FS	$T_{MIN}$ to $T_{MAX}$
Output resolution				24	bits	
<b>Digital Output</b>						
Update rate	$f_{UPDATE}$		300		S/s	During repeated 0xAA commands
Sink current	$I_{SOURCE}$		10		mA	$V_{DD} = 3.3\text{V}$ $V_{OL} < 0.5\text{V}; V_{OH} > 2.8\text{V}$
Source current	$I_{SINK}$		10		mA	
Low-level analog output voltage	$V_{OL}$	0		50	mV	$I_L = -50 \mu\text{A}$
High-level analog output voltage	$V_{OH}$	$V_{DD} - 0.05$		$V_{DD}$	V	$I_L = 50 \mu\text{A}$
<b>Nonvolatile Memory</b>						
Write time			5	16	msec	
Endurance		1000	10000		cycles	
<b>Thermal Characteristics</b>						
Junction-to-ambient thermal resistance	$\theta_{JA}$		320		°C/W	
Package power dissipation			500		mW	
<b>I<sup>2</sup>C Interface</b>						
Data transfer rate	DR			400 k 3.4 M	Baud	Standard mode
						I <sup>2</sup> C fast mode
Bus voltage	$V_{BUS}$	3		$V_{DD} + 0.5$	V	
Low level input threshold voltage	$V_{IL}$	0.8			V	
High level input threshold voltage	$V_{IH}$			2.2	V	
Low level output current	$I_{OL}$	3		mA		$V_{OL} = 0.4\text{V}$
Capacitive load	$C_B$			400	pF	
I/O capacitance	$C_{I/O}$			10	pF	

**SM324 Overview**

The SM324 is a non-contact magnetometer designed for proximity or current sensing.

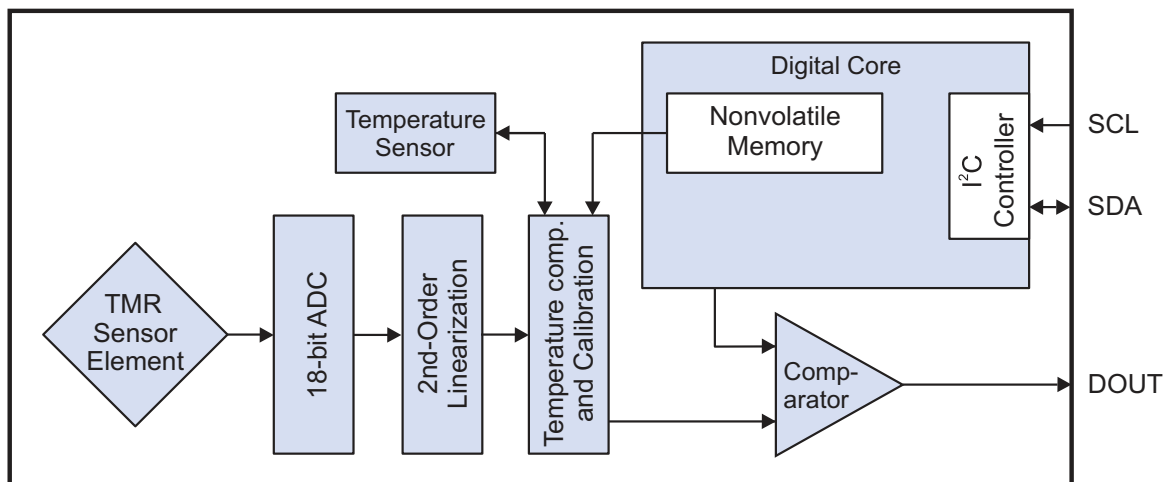
The heart of the SM324 is a unique tunneling magnetoresistance (TMR) sensor, which yields negligible hysteresis of less than 0.1%, or 0.04 Oe / 4 μT from -40°C to 125°C.

Factory calibration for gain and offset, plus temperature correction and digital linearization provide extraordinary accuracy of ±0.3% of full scale. Combined with a high-sensitivity TMR element, absolute accuracy is 0.12 Oe / 12 μT at 25°C, or 0.4 Oe / 40 μT from -40°C to 125°C.

With a tiny 2.5 by 2.5 mm TDFN package and typical 1.5 mA active supply current and 50 nA idle current, the SM324 is also the smallest, lowest-power magnetometer in its class.

**SM324 Operation**

A block diagram is shown below:



**Figure 1. Detailed block diagram.**

A robust 18-bit ADC, second-order linearization, and temperature compensation provide ultra-precise magnetic field measurements.

The digital core provides three bytes (24 bits) of mathematical precision.

Two outputs are available: an industry-standard I<sup>2</sup>C output for interfacing directly to microcontrollers and FPGAs, and a simple digital output for threshold detection of proximity, fault, overcurrent, and saturating magnetic fields.

Several other parameters can be programmed into the SM324 through the I<sup>2</sup>C interface.

### User Defined Memory

Twenty-six 16-bit blocks of nonvolatile memory are available for part identification or general purpose use. This number can be overwritten if needed. Note that the nonvolatile memory is subject to endurance limitations and should only be used for occasionally updated data.

### Sensor Offset

The sensor core of the SM324 is factory calibrated for highest accuracy, and a programmable three-byte parameter, OFFS, is available for user adjustments to environments with non-zero magnetic fields. OFFS has a sign/magnitude form where the most-significant bit is the sign (1 = negative), and the range is  $\pm 50\%$  of the  $\pm 20$  Oe ( $\pm 2$  mT) full-scale range.

### Internal Temperature Sensor

The SM324 utilizes an internal temperature sensor for compensation. The thermometer is factory calibrated and a user-programmable three-byte variable, TEMP, is available for additional temperature offset calibration. Similar to the OFFS parameter, TEMP has a sign/magnitude form where the most-significant bit is the sign (1 = negative), and the range is  $\pm 50\%$  of the  $165^\circ\text{C}$  full-scale temperature range.

## Digital Output for Threshold Detection

The SM324 has a programmable digital output that can be configured for threshold detection. The output is push-pull CMOS, and can source or sink up to 10 mA.

### Digital Output Parameters

The output is programmable using two 24-bit threshold parameters (THRSH1 and THRSH2). THRSH1 and THRSH2 are unsigned integers, each representing 0 to 100% of full scale, where 50% is zero field, 0 is the negative end of the range ( $-20$  Oe /  $-2$  mT), and  $0\text{xFFFFFF}$  is the positive high end of the range ( $+20$  Oe /  $+2$  mT).

### Digital Threshold Updating

DOUT updates automatically with each sample in the Cyclic Mode, although the refresh rate is limited to eight samples per second in that mode. In normal mode, DOUT updates with each I<sup>2</sup>C data request, so the sensor must be connected to a I<sup>2</sup>C Master continuously requesting data for the output to be usable.

### Digital Threshold Modes

The digital output can be programmed as a high-field, low field, or window comparator. The output can also be reversed with a two-bit parameter, so either a high-field or low-field output can be generated. The figures below show the outputs for the three comparator modes as set by the CONFIG parameter.

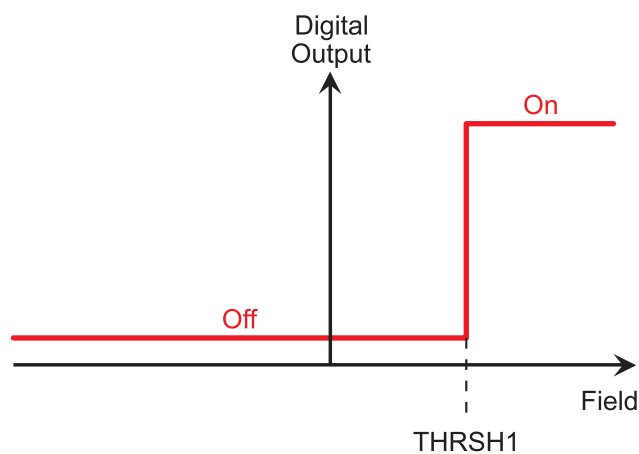


Fig. 2a. Normal mode (CONFIG = 01 bin).

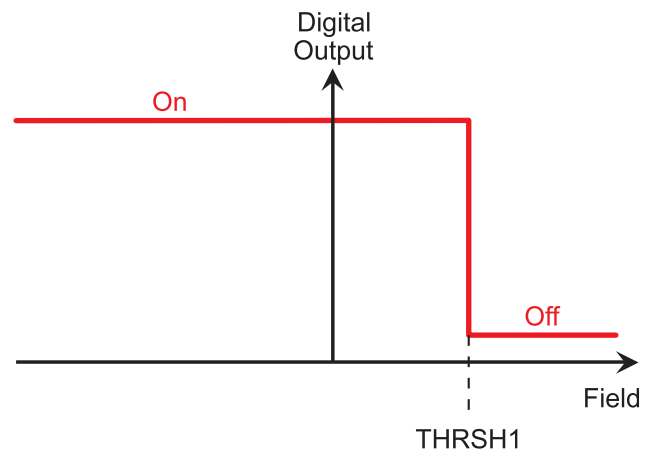
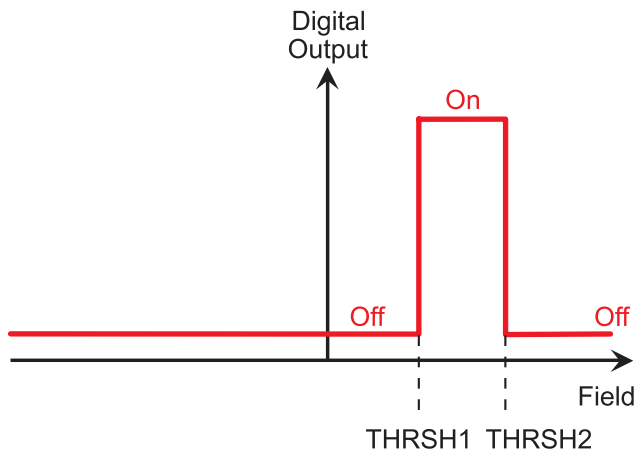
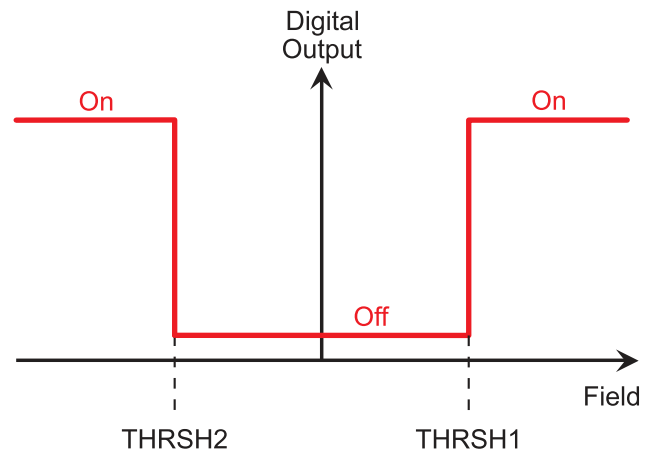


Fig. 2b. Inverted mode (CONFIG = 10 bin).



**Fig. 2c. Window mode (CONFIG=11 bin; THRS2>THRS1).**



**Fig. 2d. Inverted window mode (CONFIG=11; THRS1>THRS2).**

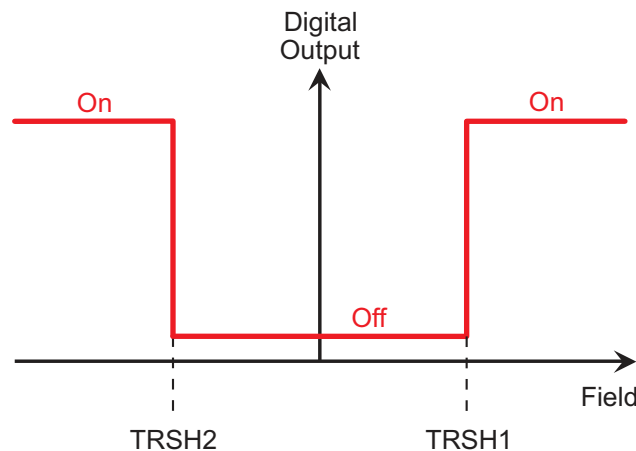
These graphs are with respect to magnetic field, with zero field at the y-axis intercept in the center of the x-axis. The I<sup>2</sup>C output is unsigned, with zero field corresponding to 50%.

The Digital Threshold Modes are summarized in the following table:

CONFIG (bin)	DOUT
01	0: Measurement < THRS1 1: Measurement > THRS1
10	0: Measurement > THRS1 1: Measurement < THRS1
11	Output determined by threshold settings. If THRS1 > THRS2 1: Measurement > THRS1 OR Measurement < THRS2 0: THRS1 > Measurement > THRS2 If THRS2 > THRS1 1: THRS1 < Measurement < THRS2 0: Measurement > THRS2 OR Measurement < THRS1

**Table 1. Digital Output (DOUT) Threshold Configuration**

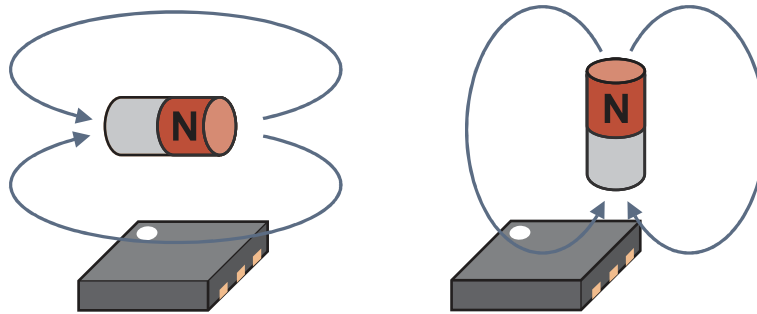
The Window mode (CONFIG = 11) can be used to provide a response independent of polarity. For example, the default settings of CONFIG = 11, THRS1 = 75% (0xC0000), and THRS2 = 25% (0x40000) cause DOUT to be high if the field magnitude is more than 10 Oe / 1 mT (i.e., greater than +10 Oe or less than -10 Oe) as shown in the following diagram:



**Fig. 2e. Default DOUT configuration (CONFIG=11; THRS1=75%; THRS2=25%; for omnipolar DOUT).**

**Directions of Sensitivity**

The diagrams below show two permanent magnet orientations that will activate the sensor in the direction of sensitivity:

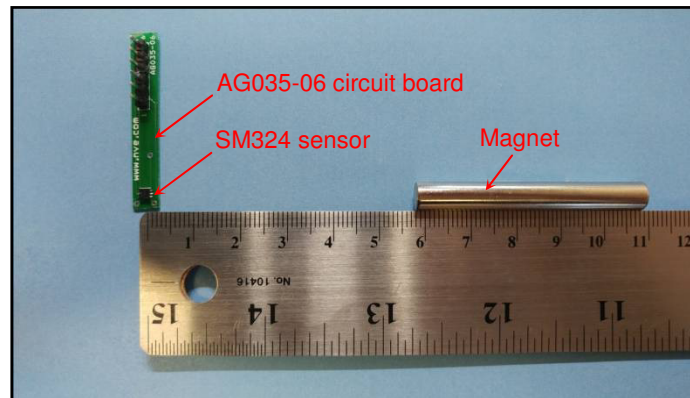


**Figure 3. Magnetic orientation.**

Unlike Hall effect or other sensors, TMR sensors are sensitive to fields in the plane of the package, which is more convenient. The axis of sensitivity is in the pin 2 to pin 5 sensor axis, which is ideal for position sensing, or for current sensing since a current-sensing trace can be run under the sensor without crossing the pins.

**Position Sensing**

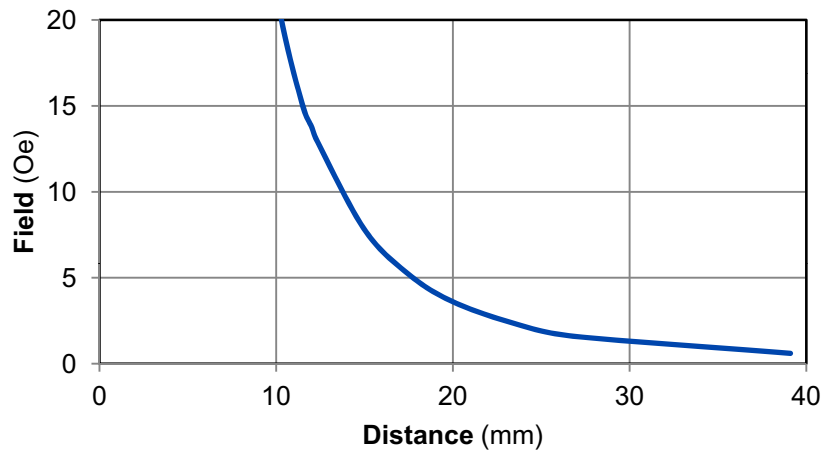
A typical proximity sensor using an SM324-10E sensor and magnet is shown below. With a 4 Oe (0.4 mT) operate point, the sensor actuates with a rare-earth magnet at more than 50 mm (two inches) from the sensor:



**Figure 4. The SM324-10E sensor can be activated by a magnet more than 50 mm away.**

Thresholds even lower than 4 Oe can be programmed for the SM324-10E, although care must be taken to account for the earth's magnetic field, which is approximately 0.5 Oe or 50  $\mu$ T.

Typical magnetic operate distances are illustrated below for an inexpensive ceramic disk magnet:



**Figure 5. Field vs. distance from the center of the sensor**  
(NVE part number 12216; ferrite magnet; d=6 mm; t=4 mm; C1/Y10T;  $M_s=B_r=2175$  G).

Larger and stronger magnets allow farther operate and release distances. For more calculations, use our axial disc magnetic field versus distance Web application at:

[www.nve.com/spec/calculators.php#tabs-Axial-Disc-Magnet-Field](http://www.nve.com/spec/calculators.php#tabs-Axial-Disc-Magnet-Field).



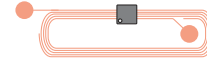
**Current Sensing**

In a typical current sensor configuration, a magnetic field provided by an off-chip current strap produces a magnetic field in the plane of the sensor. The digital output can be used for current threshold detection or overcurrent protection.

Typical current sensing configurations are shown below:

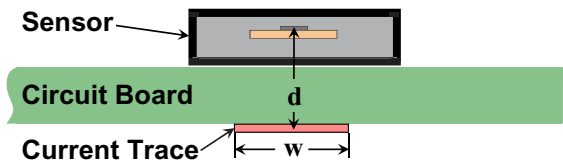


**Figure 6a. 0.05" (1.3 mm) trace  
(0 – 5 A typ.).**



**Figure 6b. Five turns of  
0.0055" (0.14 mm) trace  
(0 – 1 A typ.).**

For the geometry shown below and narrow traces, the magnetic field generate can be approximated by Ampere’s law:



**Figure 7. The geometry of current-sensing over a circuit board trace.**

$$H = \frac{2I}{d} \quad [“H” \text{ in oersteds, “I” in amps, and “d” in millimeters}]$$

For traces on the top side of the board, “d” is simply the distance of the sensor element from the bottom of the package, which is 0.5 millimeters.

Traces on the top side of the board are typically used for currents of five amps or less. Large traces on the bottom side of the PCB can be used for currents of more than five amps.

More precise calculations can be made by breaking the trace into a finite element array of thin traces, and calculating the field from each array element. We have a free, Web-based application with a finite-element model to estimate magnetic fields and sensor outputs in this application:

[www.nve.com/spec/calculators.php#tabs-Current-Sensing](http://www.nve.com/spec/calculators.php#tabs-Current-Sensing)

## Power-Up and Initialization

Parts power in the “normal” (single-reading) mode. In this mode, the sensor output and DOUT are updated when data is requested via I<sup>2</sup>C, so the sensor should be connected to a I<sup>2</sup>C Master continuously requesting data. If the “cyclic” mode (DOUT automatically updated) is desired, it should be invoked with the appropriate I<sup>2</sup>C commands.

Parameters such as I<sup>2</sup>C address, temperature and field offsets, digital output thresholds and configuration are stored in nonvolatile memory and retain their state through power cycle unless they are deliberately changed. As specified in “Operating Specifications—Power-Up and Power-Down,” a reasonably fast supply rise time is necessary to guarantee a power-on reset.

## DOUT Update Modes

Two operational modes are available with the SM324. The “normal” mode allows the user to update DOUT and retrieve a single sensor reading via I<sup>2</sup>C. The part returns to a low-power idle state when communication is complete.

The Cyclic Mode automatically updates the sensor read buffer and DOUT at a programmed interval. Field and temperature can be read via I<sup>2</sup>C during cyclic mode, and such reads update the measurements and DOUT. Note that the minimum Cyclic Mode Interval is 125 ms, so without I<sup>2</sup>C data reads, DOUT is only updated a maximum of eight times per second in Cyclic Mode. Although data can be read, parameters cannot read or written in Cyclic Mode.

The DOUT mode can be set via I<sup>2</sup>C (see Table 2 below), and the cyclic interval is programmed using the CINT parameter (see Table 3):

Command	Command Value (hex)	Notes
Read User Memory	0x20-0x38	16-bit user defined data
Write User Memory	0x60-0x78	16-bit user defined data
Checksum	0x90	Perform memory update to CHECKSUM.
Single Measurement	0xAA	24-bit field plus 24-bit temperature measurement
Cyclic Measurement	0xAB	Cyclic 24-bit field and temperature measurements
2x Oversample Measure	0xAC	Complete 2x full continuous measurements and compute average values
4x Oversample Measure	0xAD	Complete 4x full continuous measurements and compute average values
8x Oversample Measure	0xAE	Complete 8x full continuous measurements and compute average values
16x Oversample Measure	0xAF	Complete 16x full continuous measurements and compute average values
Cyclic Measure Stop	0xBF	Stops cyclic measurements

Table 2. SM324 command options.

Parameter Value (binary)	Cyclic Mode Update Interval
000	Not assigned
001	125 msec
010	250 msec
011	500 msec
100	1000 msec
101	2000 msec
110	4000 msec
111	Not assigned

Table 3. CINT (Cyclic Interval) parameter values.

**Sensor Measurements and Offsets**

**Field and Temperature Measurements**

The sensor provides field and temperature measurements with each reading.

The measurements are 24-bit unsigned integers. 0x000000 represents the minimum value, which is -20 Oe / -2 mT for field and -40°C for temperature. 0xFFFFFFFF represents full scale, which is +20 Oe / +2 mT for field and +125°C for temperature.

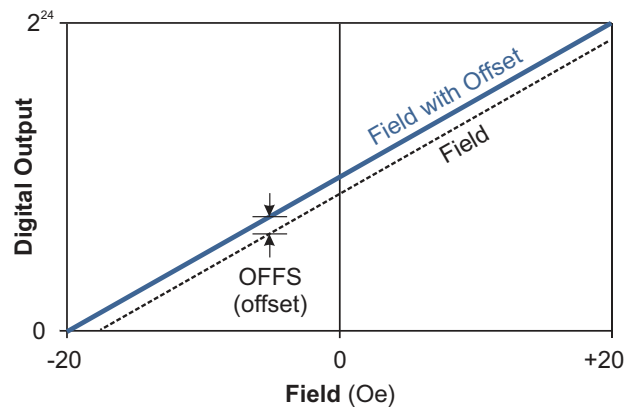
**Saturation and Overflow**

All measurements responses start with a status byte followed by the data. Bit 0 of the status byte indicates the sensor is saturated because field is too high for an accurate measurement. In this case, Bit 0 of the status byte will be set and the field measurement will remain at or near 0xFFFFFFFF.

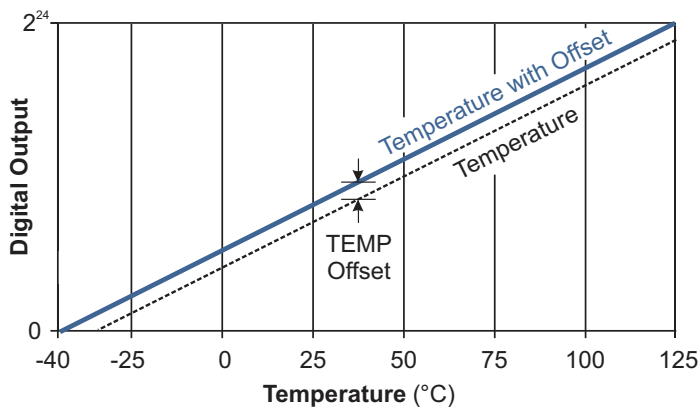
**Offsets**

Temperature and field offsets are factory calibrated, but can be reprogrammed if necessary. Offsets are in 24-bit sign/magnitude format, where the most significant bit (bit 23) is the sign (0 = positive; 1 = negative), and bits 22:0 are the magnitude. The offset range is ±50% of full-scale, where field full-scale is ±20 Oe / ±2 mT; and temperature full-scale is 165°C.

Measurements and offsets are illustrated below:



**Fig. 8a. Sensor output versus field.**



**Fig. 8b. Sensor output versus temperature.**

## I<sup>2</sup>C Interface

The I<sup>2</sup>C interface is an industry standard full-duplex 400 kHz connection with the sensor as the slave to an external master such as a microcontroller.

Consistent with industry practice, SDA and SCL are open-drain, and pull up resistors to V<sub>DD</sub> are normally needed. The SDA / SCL pins should not be left floating for proper power-up/operation.

A schematic of a typical microcontroller interface is show in the Applications section.

### I<sup>2</sup>C Address

The SM324 has a seven-bit address, which can be defined in the nonvolatile memory with the I<sup>2</sup>C<sub>ADD</sub> parameter. Allowable I<sup>2</sup>C addresses are 8 to 127. Addresses 4 to 7 are reserved for I<sup>2</sup>C High-Speed Mode. The factory default I<sup>2</sup>C Slave Address is 16 (0x10 hex). A power cycle is required for a device to respond to an I<sup>2</sup>C<sub>ADD</sub> change.

### Data Format

Each command follows the sequence shown below. All I<sup>2</sup>C read responses start with a status byte followed by the data. The data depends on the previous commands. Only the number of bytes that are needed for the command must be sent. An exception is the I<sup>2</sup>C High-Speed Mode where three bytes must always be sent. After the execution of a command, the expected data can be read or if no data is returned by the command, the next command can be sent. You can read the same data more than once if the read request is repeated.

### Command or I<sup>2</sup>C Memory Write Sequence

S	Addr	W	A	Command	A	P
---	------	---	---	---------	---	---

S	Addr	W	A	Command	A	Data [15:8]	A	Data [7:0]	A	P
---	------	---	---	---------	---	-------------	---	------------	---	---

S	Addr	W	A	Memory Address	A	Data [15:8]	A	Data [7:0]	A	P
---	------	---	---	----------------	---	-------------	---	------------	---	---

### Read Sequence Following AA<sub>HEX</sub> Command

S	Addr	R	A	Status	A	Field [23:16]	A	Field [15:8]	A	Field [7:0]	A	Temp [23:16]	A	Temp [15:8]	A	Temp [7:0]	N	P
---	------	---	---	--------	---	---------------	---	--------------	---	-------------	---	--------------	---	-------------	---	------------	---	---

### Read Sequence Following 2-byte Memory Write Command

S	Addr	R	A	Status	A	Data [15:8]	A	Data [7:0]	N	P
---	------	---	---	--------	---	-------------	---	------------	---	---

### Key:

S/P: Start/Stop

A/N: Acknowledge / Not Acknowledge

R/W: Read (1) / Write (0)

### Status Byte

A read status can be executed at any time with the following command sequence:

S	Addr	R	A	Status	N	P
---	------	---	---	--------	---	---

The status byte contains the following bits:

Bit	7	6	5	4, 3	2	1	0
Meaning	0	Voltage OK?	Busy?	00	Memory Error?	0	Saturation?

*Voltage check* (bit 6): “1” if the sensor is properly powered; “0” if the supply voltage is out of range and data may be unreliable.

*Busy indication* (bit 5): “1” if the device is busy, which indicates that the data for the last command is not available yet. No new commands are processed if the device is busy. Note that the device is always busy if the cyclic measurement operation has been started.

*Memory integrity/error flag* (bit 2): Indicates the checksum test failed. The bit is calculated only on power-up, so a newly-written CHECKSUM will only be used for verification after the next power-on reset. Also, the CHECKSUM is only recalculated on request (a 0x90 command), so the flag will indicate an error if the memory is changed without requesting a CHECKSUM recalculation.

*Saturation* (bit 0): “1” if the last sensor measurement indicates the sensor is saturated.

## Memory Register

The SM324 uses an internal nonvolatile memory to enable user programmable parameters such as I<sup>2</sup>C address, temperature and field offsets, digital output thresholds and configuration parameter, and cyclic mode interval. Each register is 16 bits and is written using the scheme described in the I<sup>2</sup>C interface section.

The memory address and number of bits for each parameter are also provided. Memory address bit 6 is a write bit, so writing to nonvolatile memory uses an address 0x40 higher than the address for reading.

Table 4 summarizes programmable parameters:

Parameter	Symbol	Read Address (hex)	Write Address (hex)	Bits	Default		Notes
					Hex	Value	
<b>Device Identifiers</b>							
User Memory		00-01; 20-38	40-41; 60-78	[15:0]	--	--	
I <sup>2</sup> C Address	I <sup>2</sup> C <sub>ADD</sub>	0x02	0x42	[6:0]	0x10	16 dec	Changes requires a power cycle.
<b>Offsets</b>							
Temperature Offset (lower 16 bits)	TEMP	0x18	0x58	[15:0]	Factory Calibrated		Sign/Magnitude format; most significant bit is sign (1=negative); bits 22:0 are magnitude ( $\pm 50\%$ of full scale); full scale field = $\pm 20$ Oe; full scale temp. = 165°C.
Temperature Offset (sign bit + upper 7 bits)		0x19	0x59	[15:8]			
Field Offset (lower 16 bits)	OFFS	0x17	0x57	[15:0]			
Field Offset (sign bit + upper 7 bits)		0x19	0x59	[7:0]			
<b>Mode Parameters</b>							
Cyclic Interval	CINT	0x02	0x42	[14:12]	000 <sub>BIN</sub>	0	Time between automatic measurements (= $2^{CINT-4}$ sec.; see Table 3).
<b>Digital Output Configuration</b>							
Threshold 1 (LSB)	THRSH1	0x13	0x53	[15:0]	0x0000	10 Oe /	Unsigned (0–100% of full scale)
Threshold 1 (MSB)		0x15	0x55	[7:0]	0xC0	1 mT	
Threshold 2 (LSB)	THRSH2	0x14	0x54	[15:0]	0x0000	-10 Oe /	
Threshold 2 (MSB)		0x15	0x55	[15:8]	0x40	-1 mT	
Threshold Configuration	CONFIG	0x02	0x42	[8:7]	11 <sub>BIN</sub>	3	(See Table 1)

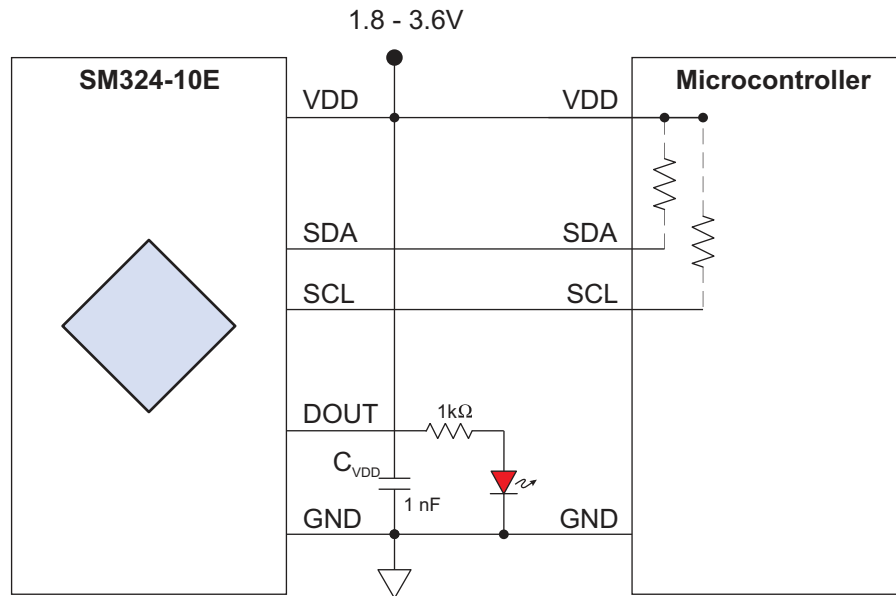
**Table 4. SM324 programmable parameters.**

**Supply Decoupling**

$V_{DD}$  should be bypassed with a 1 nF (0.001  $\mu$ F) capacitor placed as close as possible to the supply and ground pins. A larger capacitor is not required and could interfere with power-up timing.

**Typical Circuit**

A typical microcontroller interface is shown below:



**Figure 9. Typical microcontroller interface.**

The SM324 is configured as a Slave and the microcontroller should be configured as the Master. The SM324 I<sup>2</sup>C interface is compatible with 1.8 to five-volt nominal microcontrollers.

The SM324 SDA and SCL lines are open-drain, so the microcontroller's internal pull-up resistor should be activated in software. If external pull-ups are used with different power supplies, they should be connected to the lower supply voltage, which is usually the sensor (Slave) supply.

$V_{DD}$  should be bypassed with a 1 nF (0.001  $\mu$ F) capacitor placed as close as possible to the  $V_{DD}$  and GND pins.

A LED can be used to indicate the digital output. The digital output can source or sink 10 mA. The appropriate series resistor depends on the supply voltage and LED type, and of course the LED cannot be operated at the low end of the sensor supply voltage range, such as 1.8 volts.

## Illustrative Microcontroller Code

The following pseudocode illustrates a typical I<sup>2</sup>C read of the sensor output, as well as memory read and memory write. Actual implementation is, of course, hardware dependent.

```
//===== Read 24-bit magnetic field and temperature ===== //
Command Request

I2C_Start()           // Send start
I2C_Write( 0x20 )     // Write I2C target address (16) with read/write bit set to write (0)
I2C_ReadACK()        // Read ACK(acknowledge) from target
I2C_Write( 0xAA )    // Write command(0xAA = read magnetic field and temperature)
I2C_ReadACK()        // Read ACK from target
I2C_Stop()           // Send stop

// Read data

I2C_Start()           // Send start
I2C_Write( 0x21 )     // Write I2C target address (16) with read/write bit set to read (1)
I2C_ReadACK()        // Read ACK from target
I2C_Read( &status_byte ) // Read status byte
I2C_SendACK()        // Send ACK
I2C_Read(&field_bits_23_16) // Read magnetic field bits 23:16
I2C_SendACK()        // Send ACK
I2C_Read(&field_bits_15_8) // Read magnetic field bits 15:8
I2C_SendACK()        // Send ACK
I2C_Read(&field_bits_7_0) // Read magnetic field bits 7:0
I2C_SendACK()        // Send ACK
I2C_Read(&temp_bits_23_16) // Read temperature bits 23:16
I2C_SendACK()        // Send ACK
I2C_Read(&temp_bits_15_8) // Read temperature bits 15:8
I2C_SendACK()        // Send ACK
I2C_Read(&temp_bits_7_0) // Read temperature bits 7:0
I2C_SendNACK()       // Send NACK (not acknowledged)
I2C_Stop()           // Send stop
```

### Status byte interpretation:

Bit 7: Not used - always 0  
 Bit 6: Powered - always 1  
 Bit 5: Busy - 0=measurement complete, 1=measurement in progress Bit 4: Not used - always 0 Bit 3:  
 Not used - always 0 Bit 2: Memory error - 0=checksum matches memory contents, 1=checksum does not  
 match Bit 1: Not used - always 0 Bit 0: Saturation - 0=OK, 1=Sensor saturation (i.e. field is too  
 strong)

### Common status bytes:

0x40 = Measurement successful.  
 0x44 = Measurement successful but checksum doesn't match memory contents (send 0x90 to reset  
 checksum) 0x60 = Measurement not yet complete. Repeat read command.  
 0x41 = Measurement complete but not valid because sensor is saturated.



```
//===== Read from memory register 0 ===== // Command request

I2C_Start()           // Send start
I2C_Write( 0x20 )     // Write target I2C address (16) with read/write bit set to write (0)
I2C_ReadACK()        // Read ACK(acknowledge) from target
I2C_Write( 0x00 )     // Write command (0x00 = read memory address 0)
I2C_ReadACK()        // Read ACK from target
I2C_Stop()           // Send stop

// Read data

I2C_Start()           // Send start
I2C_Write( 0x21 )     // Write target I2C address (16) with read/write bit set to read (1)
I2C_ReadACK()        // Read ACK from target
I2C_Read( &status_byte ) // Read status byte
I2C_SendACK()        // Send ACK
I2C_Read( &data_bits_15_8 ) // Read contents of memory (bits 15:8)
I2C_SendACK()        // Send ACK
I2C_Read( &data_bits_7:0 ) // Read contents of memory (bits 7:0)
I2C_SendNACK()       // Send NACK (not acknowledged)
I2C_Stop()           // Send stop

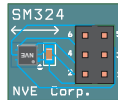
//===== Write value 0x1234 to memory register 0 ===== // Command
request

I2C_Start()           // Send start
I2C_Write( 0x20 )     // Write target I2C address (16) with read/write bit set to write (0)
I2C_ReadACK()        // Read ACK(acknowledge) from target
I2C_Write( 0x40 )     // Write command (0x40 = write to memory address 0)
I2C_ReadACK()        // Read ACK from target
I2C_Write( 0x12 )     // Write bits 15:8 of 0x1234
I2C_ReadACK()        // Read ACK from target
I2C_Write( 0x34 )     // Write bits 7:0 of 0x1234
I2C_ReadACK()        // Read ACK from target
I2C_Stop()           // Send stop
```

**Evaluation Support**

**Breakout Board**

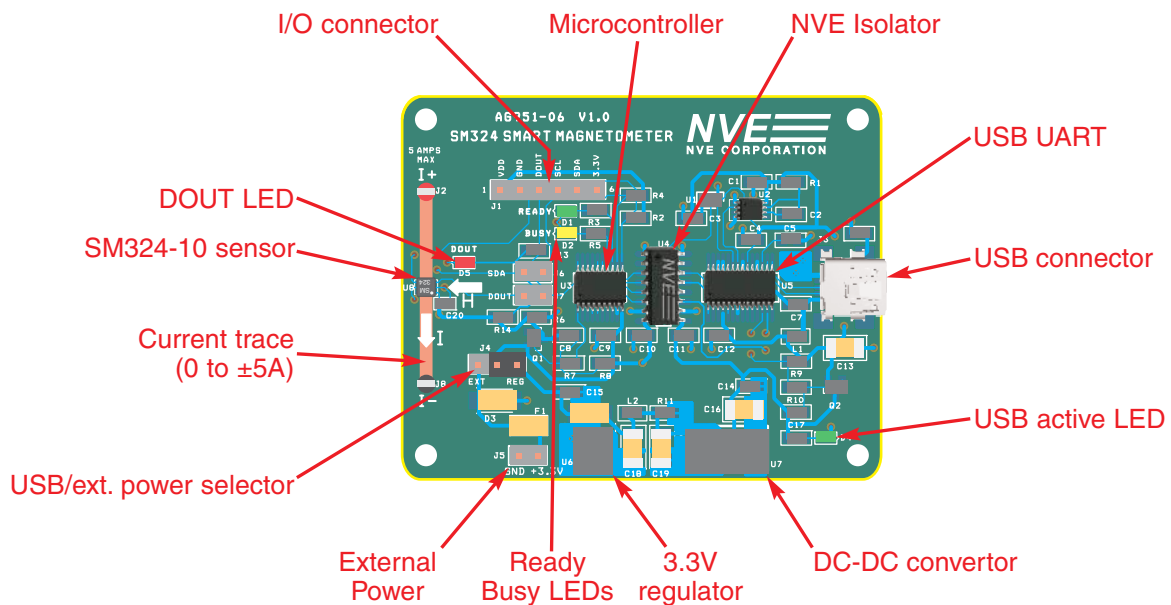
The AG960-07E breakout board provides easy connections to an SM324-10E sensor with a six pin connector. It also has a recommended 1 nF bypass capacitor:



**Figure 10. AG960-07E breakout board (actual size)  
0.5" x 0.6" (12 mm x 15 mm)**

**Evaluation Kit**

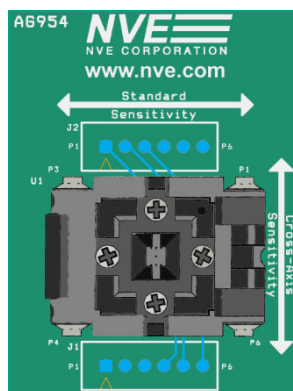
This board includes an SM324-10E Smart Magnetometer, a microcontroller that interfaces to the SM324 via I<sup>2</sup>C, and interfaces to a PC via USB. The sensor can be activated with a magnet or an on-board current trace. A Windows-based user interface provides two-way communication with the sensor to display the sensor outputs and allowing field calibration.



**Figure 11. AG951-07E: SM324-10E Smart Magnetometer Evaluation Kit board (actual size).**

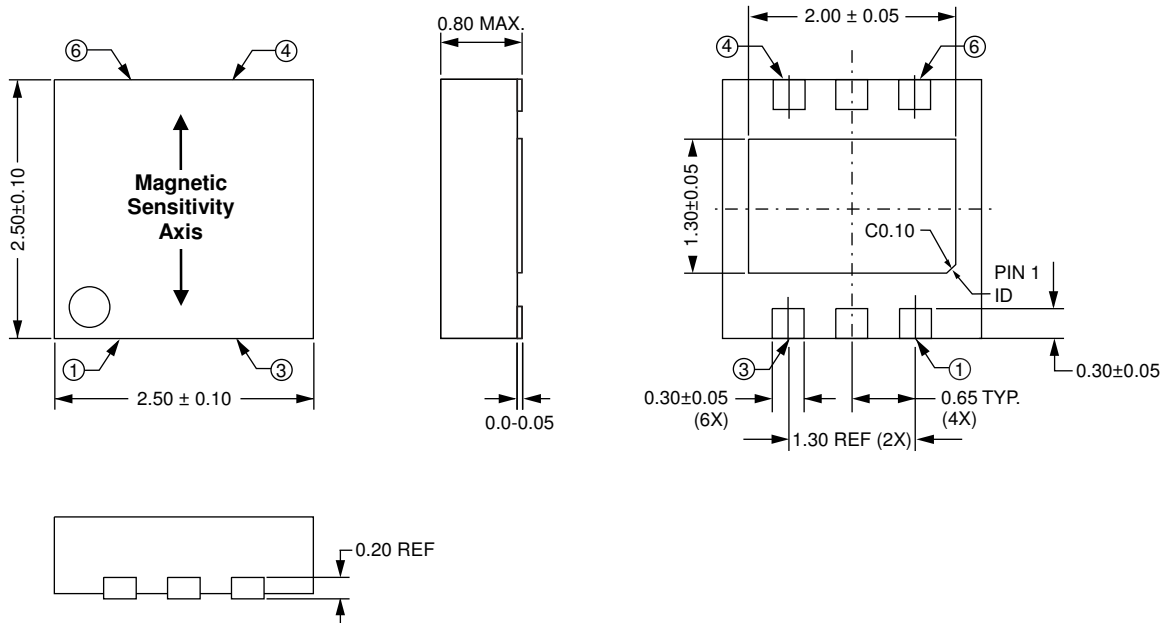
**Socket Board**

The AG954-07E provides a TDFN6 socket for easy interface to smart sensors such as the SM324-10E without soldering:



**Figure 12. AG954-07E: TDFN socket board  
1.5" x 2" (38 mm x 50 mm)(actual size)**

**2.5 x 2.5 mm TDFN6 Package (approx. 15x actual size)**



Pin	Symbol	Description
1	VDD	Power Supply (bypass with a 1 nF capacitor)
2	GND	Ground / $V_{SS}$
3	DOUT	Digital Output (push-pull CMOS output)
4	SCL	I <sup>2</sup> C Clock (input)
5	SDA	I <sup>2</sup> C Data (bidirectional/open drain)
6	NC	Not internally connected



**Notes:**

- Dimensions in millimeters.
- Soldering profile per JEDEC J-STD-020C, MSL 1.

**Ordering Information**

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## SM324 - 10E TR13

**Product Family**

SM = Smart Magnetometer

**Precision**

3 = 3-Byte resolution; TMR Sensor Element

**Magnetic Orientation**

2 = Cross-axis (sensitive to a field vector in the pin 2 to pin 5 direction)

**Field Range**

4 = 20 Oe / 2 mT Magnetic Field Range

**Part Package**

10E = RoHS-Compliant 2.5 x 2.5 mm TDFN6 Package

**Bulk Packaging**

TR13 = 13" Tape and Reel Bulk Packaging

## Revision History

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### SB-00-077 Rev. D

August 2019

#### Change

- Added SI units (mT or  $\mu$ T) where appropriate throughout.
- Added diagram showing magnetic orientations (Figure 3; p. 7).
- Added Evaluation Support section with Breakout Board, Evaluation Kit, and Socket Board (p. 17).

### SB-00-077 Rev. C

April 2019

#### Change

- Added “Illustrative Microcontroller Code” section (pp. 15 - 16).

### SB-00-077 Rev. B

February 2019

#### Change

- Added “Power-Up and Initialization” section and clarified Cyclic Mode (p. 9).
- Added charts showing field and temperature outputs (p. 10).
- More detailed descriptions of bit/byte concatenation (p. 11).
- Clearer Table 4 memory map; merged Table 5 into Table 4 (p. 13).
- Clarified direction of sensitivity (p. 15).
- Corrected minor specification inconsistencies.

### SB-00-077 Rev. A

September 2018

#### Change

- Dropped “Preliminary” designation.
- Misc. style changes.
- Dropped fax number.

### SB-00-077-PRELIM2

August 2018

#### Change

- Dropped “Product Preview” designation.
- Added 25°C accuracy specification.
- Added hysteresis specification.
- Misc. minor changes.

### SB-00-077-PRELIM

July 2018

#### Change

- Initial preliminary release.

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