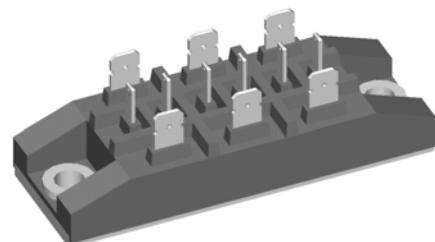
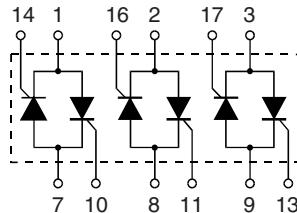


Three Phase AC Controller Modules

I_{RMS} = 3x 60 A
V_{RRM} = 1200-1600 V

Preliminary data

V _{RSM} V _{DSM}	V _{RRM} V _{DRM}	Type
V	V	
1200	1200	VWO 60-12io7
1400	1400	VWO 60-14io7
1600	1600	VWO 60-16io7



Symbol	Conditions	Maximum Ratings	
I _{RMS}	T _K = 85°C, 50 - 400 Hz (per phase)	60	A
I _{TRMS}	T _{VJ} = T _{VJM}	43	A
I _{TAVM}	T _K = 85°C; (180° sine)	27	A
I _{TSM}	T _{VJ} = 45°C; V _R = 0	550 600	A A
	t = 10 ms (50 Hz), sine t = 8.3 ms (60 Hz), sine		
	T _{VJ} = T _{VJM} V _R = 0	500 550	A A
	t = 10 ms (50 Hz), sine t = 8.3 ms (60 Hz), sine		
I ² t	T _{VJ} = 45°C V _R = 0	1520 1520	A ² s A ² s
	t = 10 ms (50 Hz), sine t = 8.3 ms (60 Hz), sine		
	T _{VJ} = T _{VJM} V _R = 0	1250 1250	A ² s A ² s
(di/dt) _{cr}	T _{VJ} = T _{VJM} f = 50 Hz, t _p = 200 µs V _D = 2/3 V _{DRM} I _G = 0.45 A di _G /dt = 0.45 A/µs	repetitive, I _T = 25 A non repetitive, I _T = I _{TAVM}	150 A/µs
(dv/dt) _{cr}	T _{VJ} = T _{VJM} ; R _{GR} = ∞; method 1 (linear voltage rise)	V _{DR} = 2/3 V _{DRM}	1000 V/µs
P _{GM}	T _{VJ} = T _{VJM} I _T = I _{TAVM}	t _p = 30 µs t _p = 300 µs	10 W 5 W
P _{GAVM}			0.5 W
V _{RGM}			10 V
T _{VJ}		-40...+125	°C
T _{VJM}		125	°C
T _{stg}		-40...+125	°C
V _{ISOL}	50/60 Hz, RMS I _{ISOL} ≤ 1 mA	t = 1 min t = 1 s	2500 V~ 3000 V~
M _d	Mounting torque (M5) (10-32 UNF)	5 ± 15 % 44 ± 15 %	Nm lb.in.
Weight	typ.	110	g

Data according to IEC 60747 refer to a single thyristor/diode unless otherwise stated.

Features

- Thyristor controller for AC (circuit W3C acc. to IEC) for mains frequency
- Package with metal base plate
- Isolation voltage 3000 V~
- Planar passivated chips
- UL applied
- 1/4" fast-on power terminals

Applications

- Switching and control of three phase AC circuits
- Softstart AC motor controller
- Solid state switches
- Light and temperature control

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling capability
- High power density
- Light weight and compact

G

Symbol	Conditions	Characteristic Values		
I_D, I_R	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤	5	mA
V_T	$I_T = 45 \text{ A}; T_{VJ} = 25^\circ\text{C}$	≤	1.45	V
V_{TO}	For power-loss calculations only	0.85	V	
r_T		11	$\text{m}\Omega$	
V_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	≤	1.5	V
	$T_{VJ} = -40^\circ\text{C}$	≤	1.6	V
I_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	≤	100	mA
	$T_{VJ} = -40^\circ\text{C}$	≤	200	mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤	0.2	V
I_{GD}		≤	5	mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$	≤	450	mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	≤	200	mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$	≤	2	μs
t_q	$T_{VJ} = T_{VJM}; I_T = 20 \text{ A}, t_p = 200 \mu\text{s}; di/dt = -10 \text{ A}/\mu\text{s}$ $V_R = 100 \text{ V}; dv/dt = 15 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$	typ.	150	μs
R_{thJC}	per thyristor; sine 180°el	0.9	K/W	
	per module	0.15	K/W	
R_{thJK}	per thyristor; sine 180°el	1.1	K/W	
	per module	0.183	K/W	
d_s	Creeping distance on surface	16.1	mm	
d_A	Creepage distance in air	6.0	mm	
a	Max. allowable acceleration	50	m/s^2	

Dimensions in mm (1 mm = 0.0394")

