INTEGRATED CIRCUITS

DATA SHEET

74ALVCH16623

16-bit transceiver with dual enable; 3-state

Product specification Supersedes data of 1998 Aug 31 File under Integrated Circuits, IC24 1999 Sep 20





16-bit transceiver with dual enable; 3-state

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FEATURES

- Complies with JEDEC standard no. 8-1A
- CMOS low power consumption
- · Direct interface with TTL levels
- MULTIBYTE™ flow-through standard pin-out architecture
- All data inputs have bus hold circuitry
- Output drive capability 50 Ω transmission lines at 85 °C
- Current drive ±24 mA at 3.0 V.

DESCRIPTION

The 74ALVCH16623 is a high-performance, low-power, low-voltage, Si-gate CMOS device, superior to most advanced CMOS compatible TTL families.

The 74ALVCH16623 is a 16-bit transceiver featuring non-inverting 3-state bus compatible outputs in both send and receive directions.

This 16-bit bus transceiver is designed for asynchronous two-way communication between data buses. The control function implementation allows maximum flexibility in timing. This device allows data transmission from the A bus to the B bus or from the B bus to the A bus, depending upon the logic levels at the enable inputs (nOEAB, nOEBA). The enable inputs can be used to disable the device so that the buses are effectively isolated. The dual enable function configuration gives this transceiver the capability to store data by simultaneous enabling of nOEAB and nOEBA. Each output reinforces its input in this transceiver configuration. Thus, when all control inputs are enabled and all other data sources to the four sets of the bus lines are at high-impedance OFF-state, all sets of bus lines will remain at their last states. The 8-bit codes appearing on the two double sets of buses will be complementary. This device can be used as two 8-bit transceivers or one 16-bit transceiver.

To ensure the high-impedance state during power-on or power-down, \overline{OE}_{BA} should be tied to V_{CC} through a pull-up resistor and OE_{AB} should be tied to GND through a pull-down resistor; the minimum value of the resistor is determined by the current-sinking/current-sourcing capability of the driver.

Active bus hold circuitry is provided to hold unused or floating data inputs at a valid logic level.

QUICK REFERENCE DATA

Ground = 0; $T_{amb} = 25 \, ^{\circ}\text{C}$; $t_r = t_f = 2.5 \, \text{ns}$.

SYMBOL	PARAMETER	CONDITIONS	TYPICAL	UNIT
t _{PHL} /t _{PLH}	propagation delay nA _n , nB _n to nB _n , nA _n	$C_L = 30 \text{ pF}; V_{CC} = 2.5 \text{ V}$	2.0	ns
		$C_L = 50 \text{ pF}; V_{CC} = 3.3 \text{ V}$	1.9	ns
C _{I/O}	input/output capacitance		10.0	pF
C _I	input capacitance		3.0	pF
C _{PD}	power dissipation capacitance per buffer	notes 1 and 2		
		outputs enabled	35	pF
		outputs disabled	5	pF

Notes

1. C_{PD} is used to determine the dynamic power dissipation (P_D in μW).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where:

 f_i = input frequency in MHz;

 C_1 = output load capacitance in pF;

f_o = output frequency in MHz;

V_{CC} = supply voltage in Volts;

 $\Sigma (C_L \times V_{CC}^2 \times f_0) = \text{sum of outputs.}$

2. The condition is $V_I = GND$ to V_{CC} .

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ORDERING INFORMATION

TYPE NUMBER	PACKAGE								
I I FE NOWBER	TEMPERATURE RANGE	PINS	PACKAGE	MATERIAL	CODE				
74ALVCH16623DGG	–40 to +85 °C	48	TSSOP	plastic	SOT362-1				

FUNCTION TABLE

See note 1.

INP	UTS	INPUTS/OUTPUTS			
nOE _{AB}	n OE _{BA}	nA _n	nB _n		
L	L	A = B	inputs		
Н	Н	inputs	B = A		
L	Н	Z	Z		
Н	L	A = B	B = A		

Note

1. H = HIGH voltage level;

L = LOW voltage level;

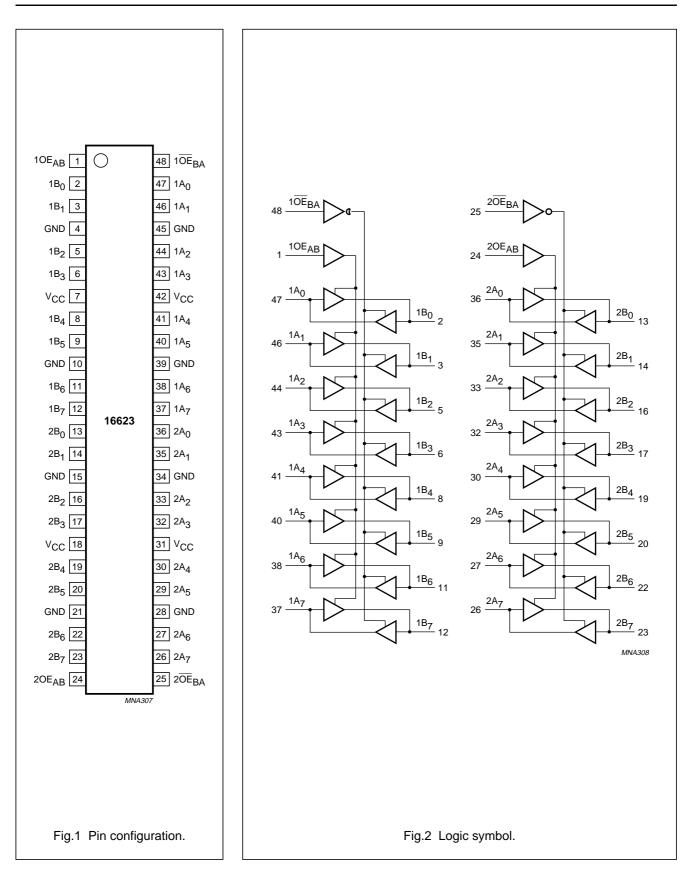
Z = high-impedance OFF-state.

PINNING

PIN	SYMBOL	DESCRIPTION		
1, 24	10E _{AB} , 20E _{AB}	output enable input (active HIGH)		
2, 3, 5, 6, 8, 9, 11, 12	1B ₀ to 1B ₇	data inputs/outputs		
4, 10, 15, 21, 28, 34, 39, 45	GND	ground (0 V)		
7, 18, 31, 42	V _{CC}	DC supply voltage		
13, 14, 16, 17, 19, 20, 22, 23	2B ₀ to 2B ₇	data inputs/outputs		
25, 48	2 OE _{BA} , 1 OE _{BA}	output enable input (active LOW)		
26, 27, 29, 30, 32, 33, 35, 36	2A ₇ to 2A ₀	data inputs/outputs		
37, 38, 40, 41, 43, 44, 46, 47	1A ₇ to 1A ₀	data inputs/outputs		

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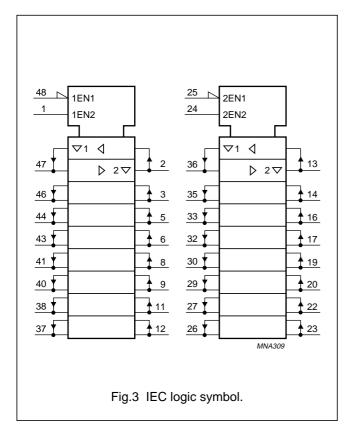


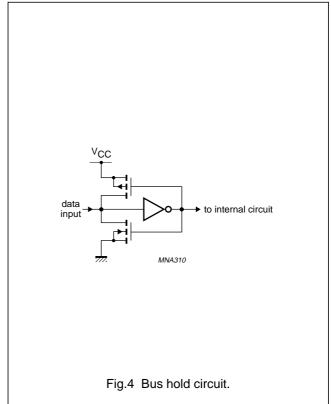
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RECOMMENDED OPERATING CONDITIONS

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V _{CC}	DC supply voltage					
	for max. speed performance	C _L = 30 pF	2.3	2.5	2.7	V
	for max. speed performance	C _L = 50 pF	3.0	3.3	3.6	V
	for low-voltage applications		1.2	2.4	3.6	V
VI	DC input voltage		0	_	V _{CC}	V
Vo	DC output voltage		0	_	V _{CC}	V
T _{amb}	operating ambient temperature	in free air	-40	_	+85	°C
t _r , f _t	input rise and fall times	V _{CC} = 2.3 to 3.0 V	0	_	20	ns/V
		V _{CC} = 3.0 to 3.6 V	0	_	10	ns/V

LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 134); voltages are referenced to GND (ground = 0 V).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V _{CC}	DC supply voltage		-0.5	+4.6	V
I _{IK}	DC input diode current	V _I < 0	_	-50	mA
VI	DC input voltage	note 1	-0.5	+4.6	V
I _{OK}	DC output diode current	$V_O > V_{CC}$ or $V_O < 0$	_	±50	mA
Vo	DC output voltage	note 1	-0.5	V _{CC} + 0.5	V
Io	DC output source or sink current	$V_O = 0$ to V_{CC}	_	±50	mA
I_{CC} , I_{GND}	DC V _{CC} or GND current		_	±100	mA
T _{stg}	storage temperature		-65	+150	°C
P _{tot}	power dissipation	for temperature range: –40 to +125 °C; note 2	_	600	mW

Notes

- 1. The input and output voltage ratings may be exceeded if the input and output current ratings are observed.
- 2. Above 55 $^{\circ}\text{C}$ the value of Ptot derates linearly with 8 mW/K.

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DC CHARACTERISTICS

Over recommended operating conditions. Voltage are referenced to GND (ground = 0 V).

CVMDOL	DADAMETED	TE	ST CONDITIO	NS	T _{amb} =	-40 TO +85	°С	LINUT
SYMBOL	PARAMETER	V _I (V)	OTHER	V _{CC} (V)	MIN.	TYP.(1)	MAX.	UNIT
V _{IH}	HIGH-level input voltage			2.3 to 2.7	1.7	1.2	_	٧
				2.7 to 3.6	2.0	1.5	-	
V _{IL}	LOW-level input voltage			2.3 to 2.7	_	1.2	0.7	٧
				2.7 to 3.6	_	1.5	0.8	
V _{OH}	HIGH-level output voltage	V _{IH} or V _{IL}	$I_{O} = -100 \mu A$	2.3 to 3.6	V _{CC} - 0.2	V _{CC}	_	٧
			$I_O = -6 \text{ mA}$	2.3	V _{CC} - 0.3	V _{CC} - 0.08	_	
			$I_0 = -12 \text{ mA}$	2.3	V _{CC} - 0.6	V _{CC} - 0.26	_	
			$I_{O} = -12 \text{ mA}$	2.7	V _{CC} - 0.5	V _{CC} – 0.14	_	
			$I_{O} = -12 \text{ mA}$	3.0	V _{CC} - 0.6	V _{CC} - 0.09	_	
			$I_{O} = -24 \text{ mA}$	3.0	V _{CC} – 1.0	V _{CC} – 0.28	_	
V _{OL}	LOW-level output voltage	V _{IH} or V _{IL}	I _O = 100 μA	2.3 to 3.6	_	GND	0.20	٧
			$I_O = 6 \text{ mA}$	2.3	_	0.07	0.40	
			I _O = 12 mA	2.3	_	0.15	0.70	
			I _O = 12 mA	2.7	_	0.14	0.40	
			I _O = 24 mA	3.0	_	0.27	0.55	
I _I	input leakage current	V _{CC} or GND		2.3 to 3.6	_	0.1	5	μΑ
I _{OZ}	3-state output OFF-state current	VI _H or V _{IL}	V _O = V _{CC} or GND	2.3 to 3.6	_	0.1	10	μΑ
I _{CC}	quiescent supply voltage	V _{CC} or GND	I _O = 0	2.3 to 3.6	_	0.2	40	μΑ
Δl _{CC}	additional quiescent supply current given per data I/O pin with bus hold	V _{CC} – 0.6	I _O = 0	2.3 to 3.6	-	150	750	μΑ
I _{BHL}	bus hold LOW sustaining	0.7 ⁽²⁾		2.3 ⁽²⁾	45	_	_	μΑ
	current	0.8(2)		3.0(2)	75	150	_	
I _{BHH}	bus hold HIGH sustaining	1.7 ⁽²⁾		2.3 ⁽²⁾	-45		_	μΑ
	current	2.0(2)		3.0(2)	-75	-175	_	
I _{BHLO}	bus hold LOW overdrive current			3.6 ⁽²⁾	500	_	_	μΑ
Івнно	bus hold LOW overdrive current			3.6 ⁽²⁾	-500	_	_	μА

Notes

- 1. All typical values are measured at T_{amb} = 25 °C.
- 2. Valid for data inputs of bus hold parts.

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AC CHARACTERISTICS FOR V_{CC} = 2.3 TO 2.7 V

Ground = 0 V; $t_r = t_f \le 2.0 \text{ ns}$; $C_L = 30 \text{ pF}$.

SYMBOL	SYMBOL PARAMETER		IONS	T _{amb} =	UNIT		
STIVIBUL	PARAMETER	WAVEFORMS	V _{CC} (V)	MIN.	TYP. ⁽¹⁾	MAX.	UNII
t _{PHL} /t _{PLH}	propagation delay nA _n , nB _n to nB _n , nA _n	see Figs 5 and 8	2.3 to 2.7	1.0	2.4	3.5	ns
t _{PZH} /t _{PZL}	3-state output enable time nOE _{AB} to nB _n	see Figs 7 and 8	2.3 to 2.7	1.0	3.0	5.0	ns
t _{PHZ} /t _{PLZ}	3-state output disable time $n\overline{OE}_{BA}$ to nA_n	see Figs 6 and 8	2.3 to 2.7	1.0	3.0	5.1	ns
t _{PZH} /t _{PZL}	3-state output enable time nOE _{AB} to nB _n	see Figs 7 and 8	2.3 to 2.7	1.0	2.8	4.5	ns
t _{PHZ} /t _{PLZ}	3-state output disable time nOE _{BA} to nA _n	see Figs 6 and 8	2.3 to 2.7	1.0	2.4	4.0	ns

Note

1. All typical values are measured at T_{amb} = 25 °C and V_{CC} = 2.5 V.

AC CHARACTERISTICS FOR V_{CC} = 2.7 V AND V_{CC} = 3.0 TO 3.6 V

Ground = 0 V; $t_r = t_f \le 2.5 \text{ ns}$; $C_L = 50 \text{ pF}$.

SYMBOL	PARAMETER	TEST CONDI	TIONS	T _{amb}	= -40 TO ·	+85 °C	UNIT
STWIBOL	PARAMETER	WAVEFORMS	V _{CC} (V)	MIN.	TYP. ⁽¹⁾ MAX.		UNII
t _{PHL} /t _{PLH}	propagation delay	see Figs 5 and 8	2.7	_	2.5	3.4	ns
	nA_n , nB_n to nB_n , nA_n		3.0 to 3.6	1.0	2.6(2)	3.1	
t _{PZH} /t _{PZL}	3-state output enable time	see Figs 7 and 8	2.7	_	2.8	4.5	ns
	nOE _{AB} to nB _n		3.0 to 3.6	1.0	2.6 ⁽²⁾	4.0	
t _{PHZ} /t _{PLZ}	3-state output disable time	see Figs 6 and 8	2.7	_	3.3	5.0	ns
	nOE _{BA} to nA _n		3.0 to 3.6	1.0	2.8(2)	4.2	
t _{PZH} /t _{PZL}	3-state output enable time	see Figs 7 and 8	2.7	_	3.8	5.4	ns
	nOE _{AB} to nB _n		3.0 to 3.6	1.0	3.3(2)	4.6	
t _{PHZ} /t _{PLZ}	3-state output disable time	see Figs 6 and 8	2.7	_	3.2	4.5	ns
	nOE _{BA} to nA _n		3.0 to 3.6	1.0	3.0(2)	4.3	

Notes

- 1. All typical values are measured at T_{amb} = 25 °C.
- 2. Typical values at $V_{CC} = 3.3 \text{ V}$.

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AC WAVEFORMS

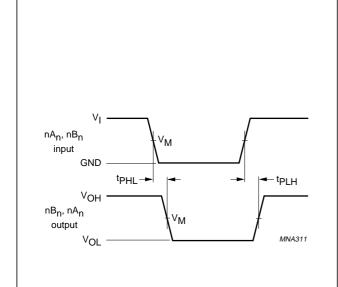


Fig.5 The input nA_n , nB_n to output nB_n , nA_n propagation delay times.

Notes: $V_{CC} = 2.3$ to 2.7 V

 $V_{M} = 0.5V_{CC};$

 $V_X = V_{OL} + 150 \text{ mV};$

 $V_Y = V_{OH} - 150 \text{ mV};$

 $V_I = V_{CC};$

 V_{OL} and V_{OH} are typical output voltage drop that occur with the output load.

Notes: $V_{CC} = 3.0$ to 3.6 V and $V_{CC} = 2.7$ V

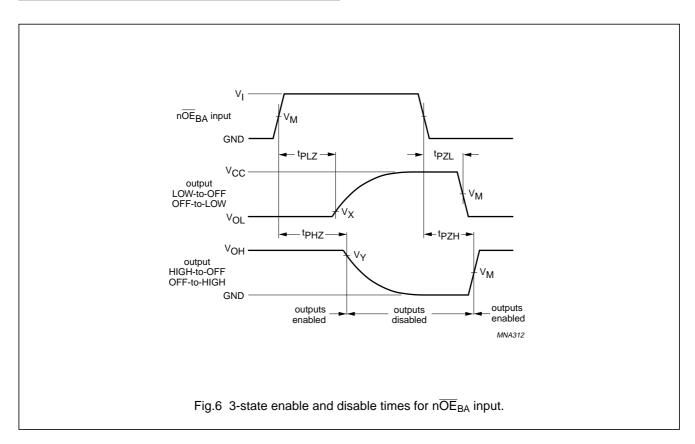
 $V_{M} = 1.5 V;$

 $V_X = V_{OL} + 300 \text{ mV};$

 $V_Y = V_{OH} - 300 \text{ mV};$

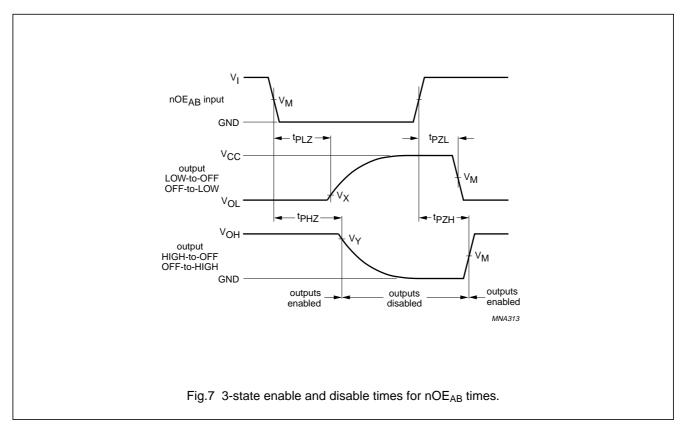
 $V_1 = 2.7 V;$

 $\ensuremath{V_{OL}}$ and $\ensuremath{V_{OH}}$ are typical output voltage drop that occur with the output load.



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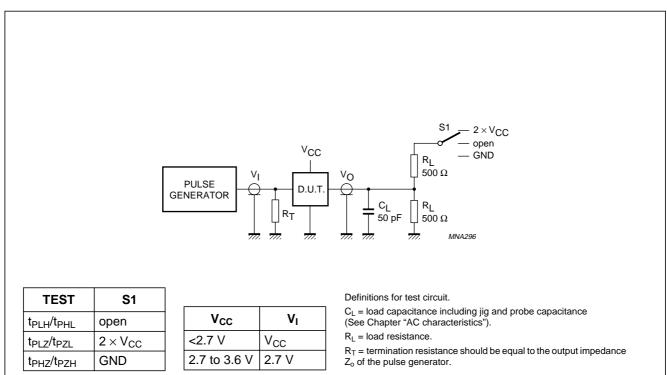


Fig.8 Load circuitry for switching times.

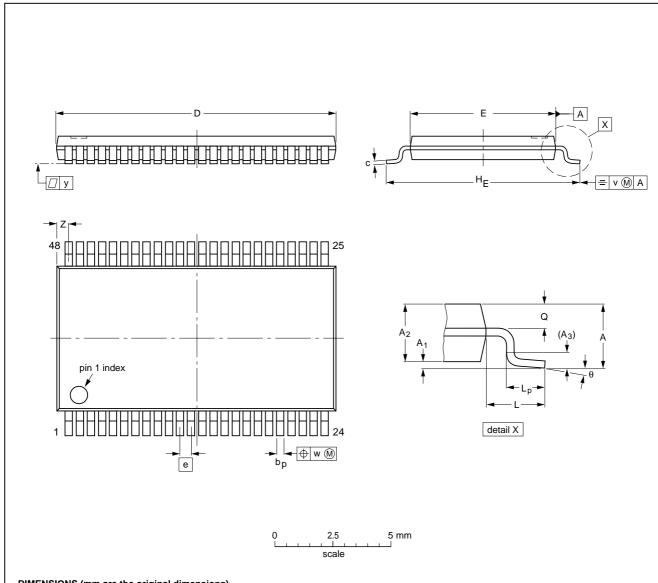
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PACKAGE OUTLINE

TSSOP48: plastic thin shrink small outline package; 48 leads; body width 6.1 mm

SOT362-1



DIMENSIONS (mm are the original dimensions).

UNIT	A max.	A ₁	A ₂	A ₃	bp	С	D ⁽¹⁾	E ⁽²⁾	е	HE	L	Lp	Q	v	w	у	z	θ
mm	1.2	0.15 0.05	1.05 0.85	0.25	0.28 0.17	0.2 0.1	12.6 12.4	6.2 6.0	0.5	8.3 7.9	1	0.8 0.4	0.50 0.35	0.25	0.08	0.1	0.8 0.4	8° 0°

Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	ENCES		EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	EIAJ		PROJECTION	ISSUE DATE	
SOT362-1		MO-153ED				-93-02-03 95-02-10	

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SOLDERING

Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our "Data Handbook IC26; Integrated Circuit Packages" (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering is not always suitable for surface mount ICs, or for printed-circuit boards with high population densities. In these situations reflow soldering is often used.

Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several methods exist for reflowing; for example, infrared/convection heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 to 250 °C. The top-surface temperature of the packages should preferable be kept below 230 °C.

Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
 - larger than or equal to 1.27 mm, the footprint longitudinal axis is preferred to be parallel to the transport direction of the printed-circuit board;
 - smaller than 1.27 mm, the footprint longitudinal axis must be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

 For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time is 4 seconds at 250 $^{\circ}$ C. A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320 $^{\circ}$ C.

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Suitability of surface mount IC packages for wave and reflow soldering methods

PACKAGE	SOLDERING METHOD				
PACKAGE	WAVE	REFLOW ⁽¹⁾			
BGA, SQFP	not suitable	suitable			
HLQFP, HSQFP, HSOP, HTSSOP, SMS	not suitable ⁽²⁾	suitable			
PLCC ⁽³⁾ , SO, SOJ	suitable	suitable			
LQFP, QFP, TQFP	not recommended ⁽³⁾⁽⁴⁾	suitable			
SSOP, TSSOP, VSO	not recommended ⁽⁵⁾	suitable			

Notes

- 1. All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the "Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods".
- 2. These packages are not suitable for wave soldering as a solder joint between the printed-circuit board and heatsink (at bottom version) can not be achieved, and as solder may stick to the heatsink (on top version).
- 3. If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- 4. Wave soldering is only suitable for LQFP, TQFP and QFP packages with a pitch (e) equal to or larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- 5. Wave soldering is only suitable for SSOP and TSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.

DEFINITIONS

Data sheet status	
Objective specification	This data sheet contains target or goal specifications for product development.
Preliminary specification	This data sheet contains preliminary data; supplementary data may be published later.
Product specification	This data sheet contains final product specifications.
Limiting values	
Limiting values given are in	accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or

Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

Application information

Where application information is given, it is advisory and does not form part of the specification.

LIFE SUPPORT APPLICATIONS

These products are not designed for use in life support appliances, devices, or systems where malfunction of these products can reasonably be expected to result in personal injury. Philips customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Philips for any damages resulting from such improper use or sale.

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NOTES

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NOTES

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