

mikroProg™ for Stellaris®

mikroProg™ is a fast USB programmer with hardware Debugger support. Smart engineering allows mikroProg™ to support all Stellaris® ARM® Cortex™-M3 and Cortex™-M4 microcontrollers in a single programmer.



TO OUR VALUED CUSTOMERS

I want to express my thanks to you for being interested in our products and for having confidence in MikroElektronika.

The primary aim of our company is to design and produce high quality electronic products and to constantly improve the performance thereof in order to better suit your needs.

A handwritten signature in white ink, appearing to read 'N. Matic', is positioned above the name and title of the General Manager.

Nebojsa Matic
General Manager

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Introduction to mikroProg™



mikroProg™ for Stellaris® is a fast programmer and hardware debugger. Smart engineering allows mikroProg™ to support all Stellaris® ARM® Cortex™-M3 and Cortex™-M4 devices in a single programmer! Outstanding performance, easy operation, elegant design and low price are its top features. It is supported in mikroElektronika ARM® compilers, as well as in other ARM® compilers.

Key features

- **Hardware Debugging**
- No need for firmware update
- New microcontrollers supported via latest version of **mikroProg Suite™** for **ARM®** software

What you see

- 01 Flat cable
- 02 USB MINIB connector
- 03 DATA transfer indication LED
- 04 ACTIVE indication LED
- 05 LINK indication LED
- 06 POWER indication LED



1. Driver installation



On-board mikroProg™ requires drivers in order to work. Drivers are located on the Product DVD that you received with the package:

`DVD://download/eng/software/development-tools/arm/stellaris/mikroprog/
mikroprog_stellaris_drivers_v100.zip`

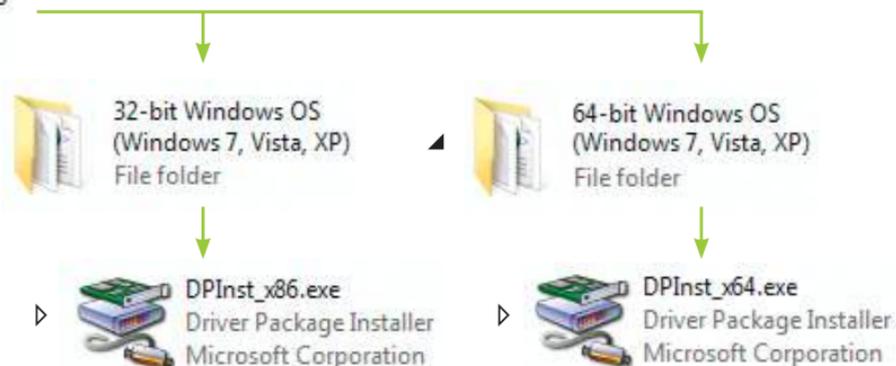
When you locate the drivers, please extract files from the ZIP archive. Folder with extracted files contains folders with drivers for different operating systems. Depending on which operating system you use, choose adequate folder and open it.



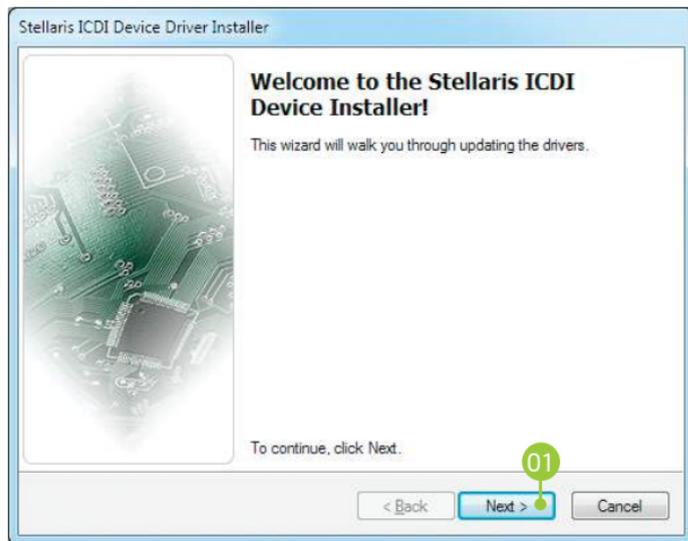
mikroprog_stellaris_drivers_v100.zip
WinRAR ZIP archive
2.38 MB

In the opened folder you should be able to locate the driver setup file. Double click the setup file to begin installation of the programmer drivers.

NOTE: Make sure to disconnect mikroProg™ before installing drivers.



step 1 - Start installation



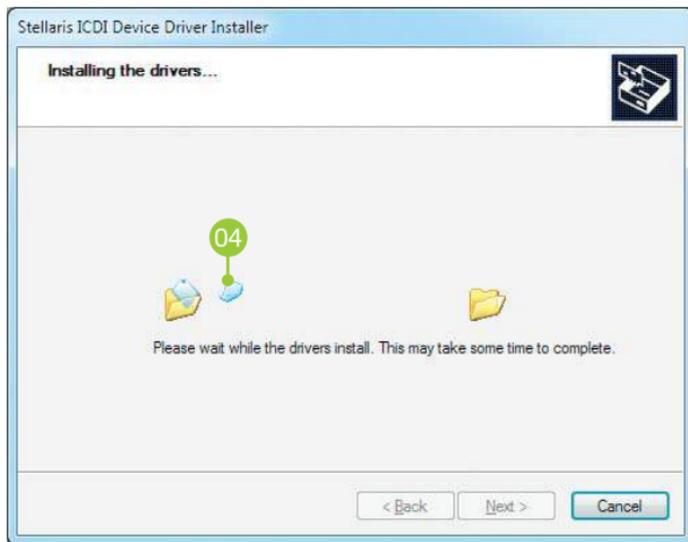
- 01 In welcome screen click the **Next >** button

step 2 - Accept EULA



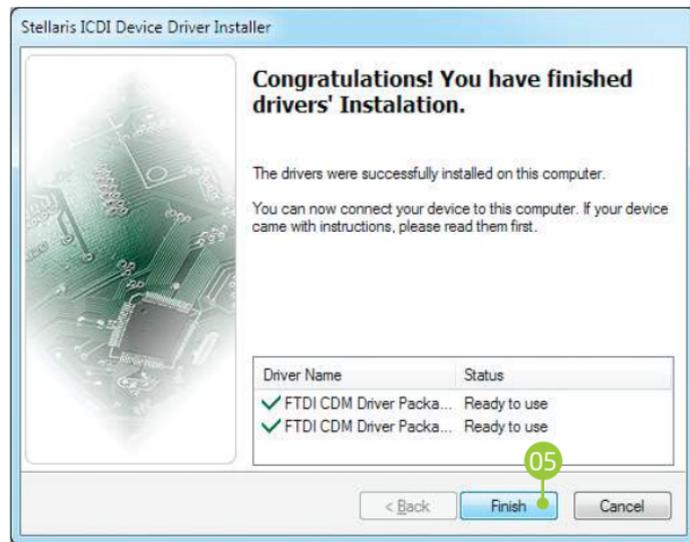
- 02 In order to proceed select **I accept the this EULA** (End User License Agreement)
- 03 Click the **Next >** button

step 3 - Installing the drivers



04 Drivers are installed automatically

step 4 - Finish installation



05 Click the **Finish** button to end installation process

2. Connecting to a PC



After driver installation is complete, you can now connect the programmer with your PC using USB cable provided with the package. Green **POWER LED** should turn ON, indicating the presence of power supply. Amber-colored **LINK LED** will turn ON when link between mikroProg™ and PC is established. Link can be established only when correct drivers are installed on your PC.

3. mikroProg Suite™ for ARM® software



mikroProg™ for Stellaris® programmer requires special programming software called mikroProg Suite™ for ARM®. This software is used for programming ALL of Stellaris® ARM® Cortex-M3™ and Cortex-M4™ microcontroller families. It features intuitive interface and SingleClick™ programming technology. Software installation comes on a Product DVD:



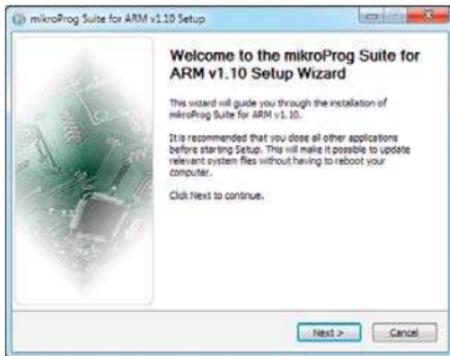
DVD://download/eng/software/development-tools/arm/stellaris/mikroprog/mikroprog_suite_for_arm_v110.zip

After downloading, extract the package and double click the executable setup file, to start installation.



Figure 3-1:
mikroProg Suite™ for ARM®
window

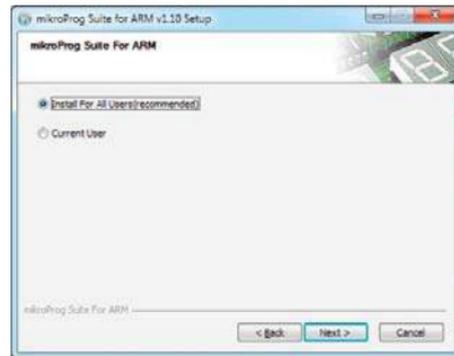
Software installation wizard



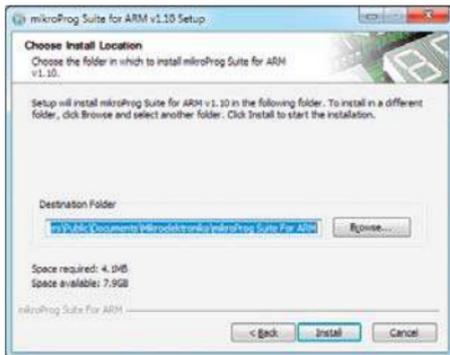
01 Start Installation



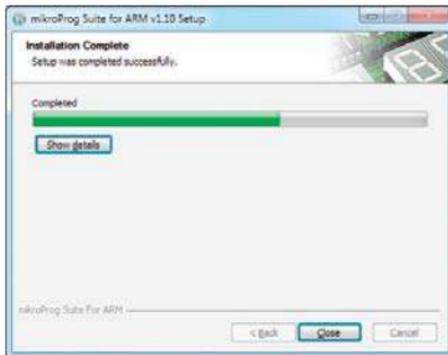
02 Accept EULA and continue



03 Install for all users



04 Choose destination folder



05 Installation in progress



06 Finish installation

4. Connecting with a target device

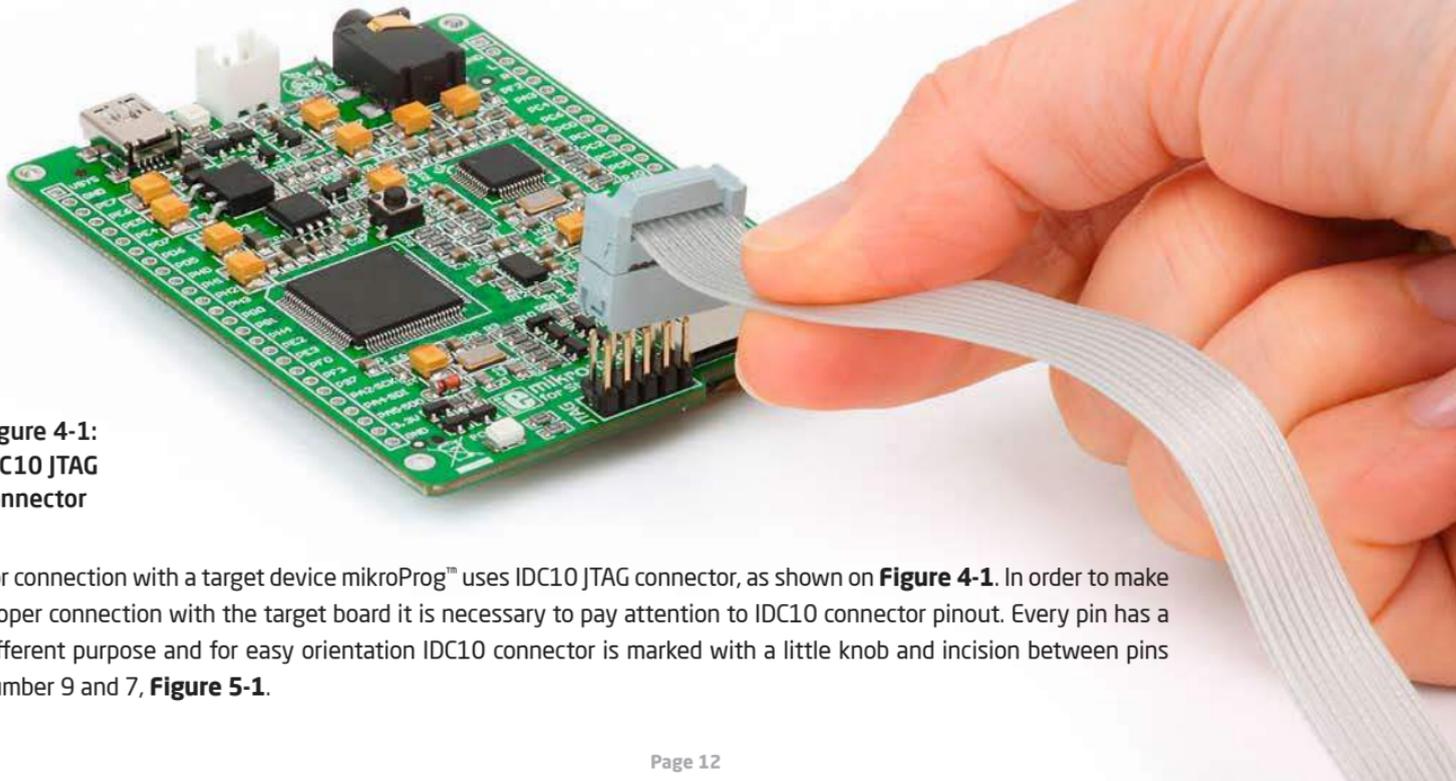


Figure 4-1:
IDC10 JTAG
connector

For connection with a target device mikroProg™ uses IDC10 JTAG connector, as shown on **Figure 4-1**. In order to make proper connection with the target board it is necessary to pay attention to IDC10 connector pinout. Every pin has a different purpose and for easy orientation IDC10 connector is marked with a little knob and incision between pins number 9 and 7, **Figure 5-1**.

5. Connector Pinout

01 **VCC-3.3V** - MCU power supply

03 **GND** - Ground

05 **GND** - Ground

07 **N/C** - Not Connected

09 **GND** - Ground

02 **TMS** - Mode Select

04 **TCK** - Clock

06 **TDO** - Data output

08 **TDI** - Data input

10 **SRSTn** - System Reset

JTAG programming/
debugging lines

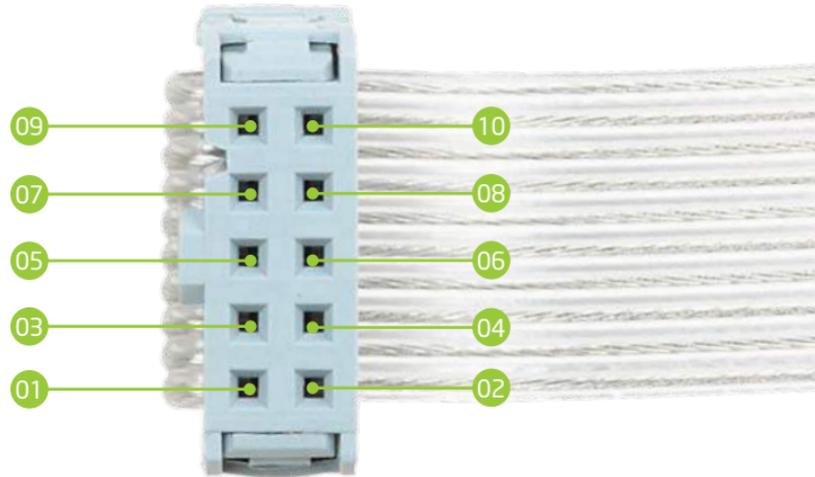
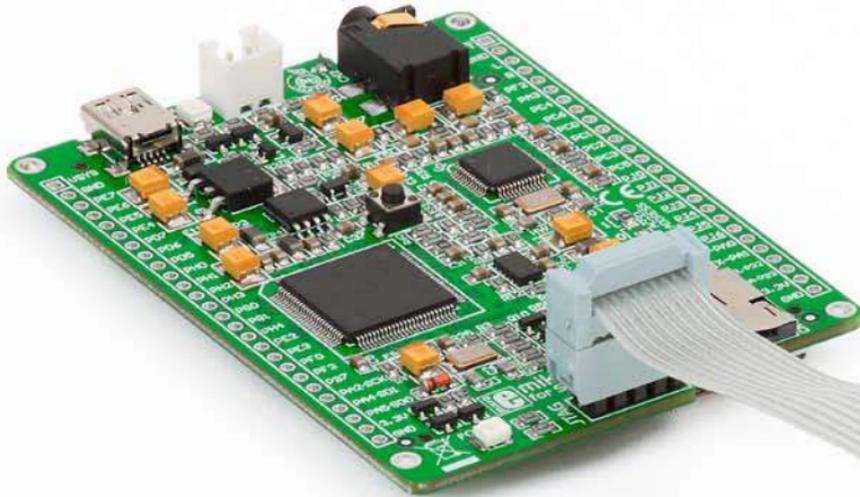


Figure 5-1: Female connector pinout

6. Connection schematic examples



Following examples demonstrate connections with some of the most popular supported microcontrollers. Each one is carefully selected as a representative of the entire family. All MCUs use TMS, TCK, TDO, TDI and SRSTn lines for programming. These lines are located on same microcontroller pins within a family.

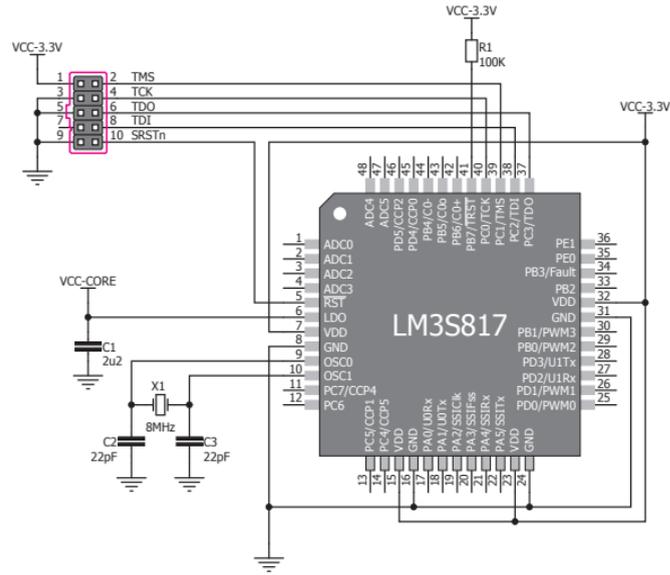


Figure 6-1: Connection schematics for 48-pin LM3S817 MCU via 2x5 male header

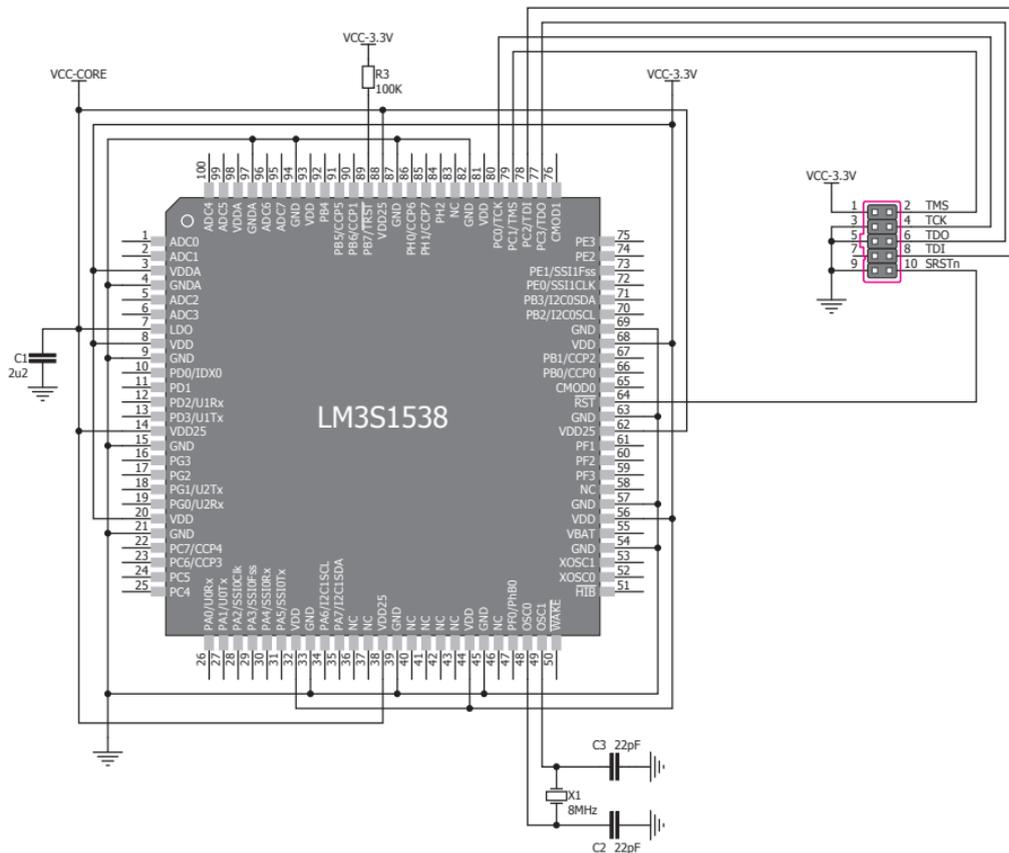


Figure 6-2: Connection schematics for 100-pin LM3S1538 MCU via 2x5 male header

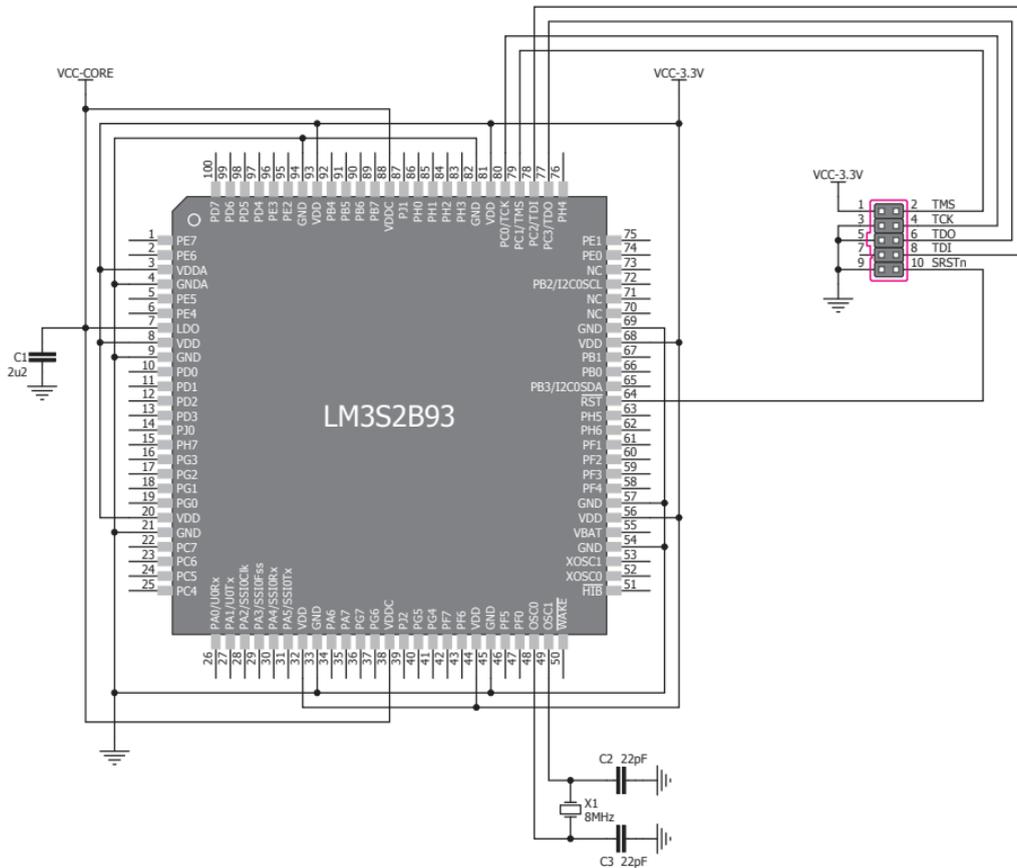


Figure 6-3: Connection schematics for 100-pin LM3S2B93 MCU via 2x5 male header

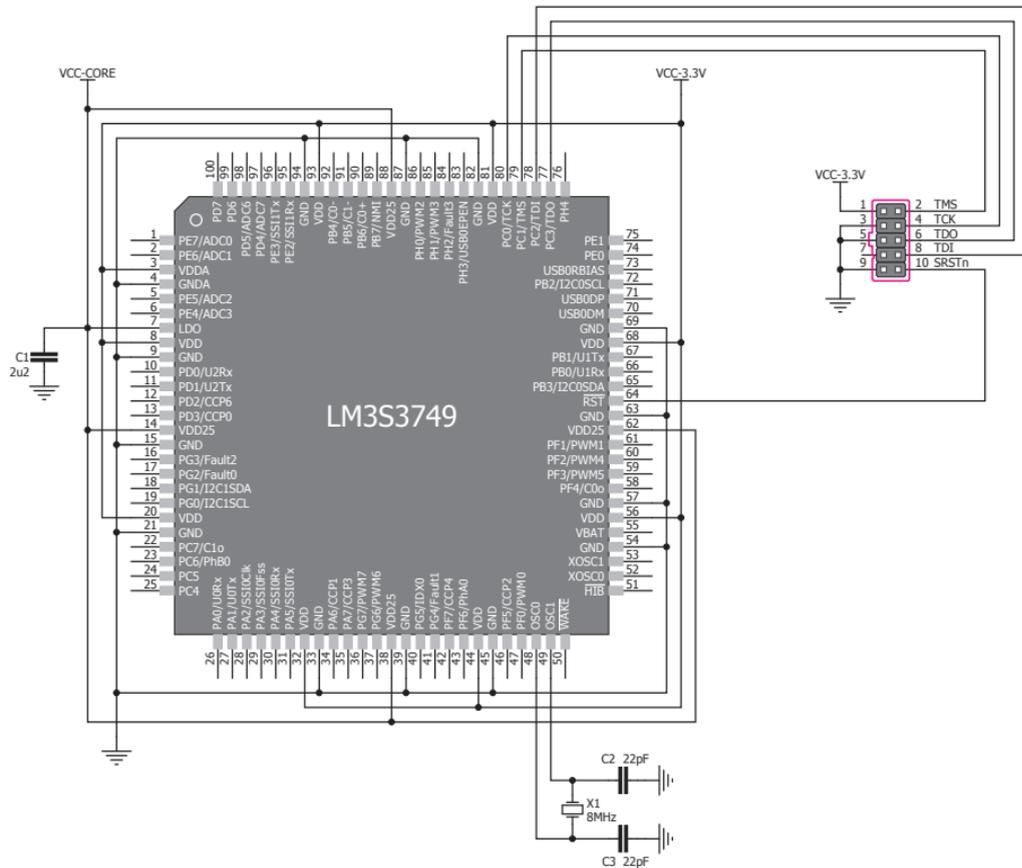


Figure 6-4: Connection schematics for 100-pin LM3S3749 MCU via 2x5 male header

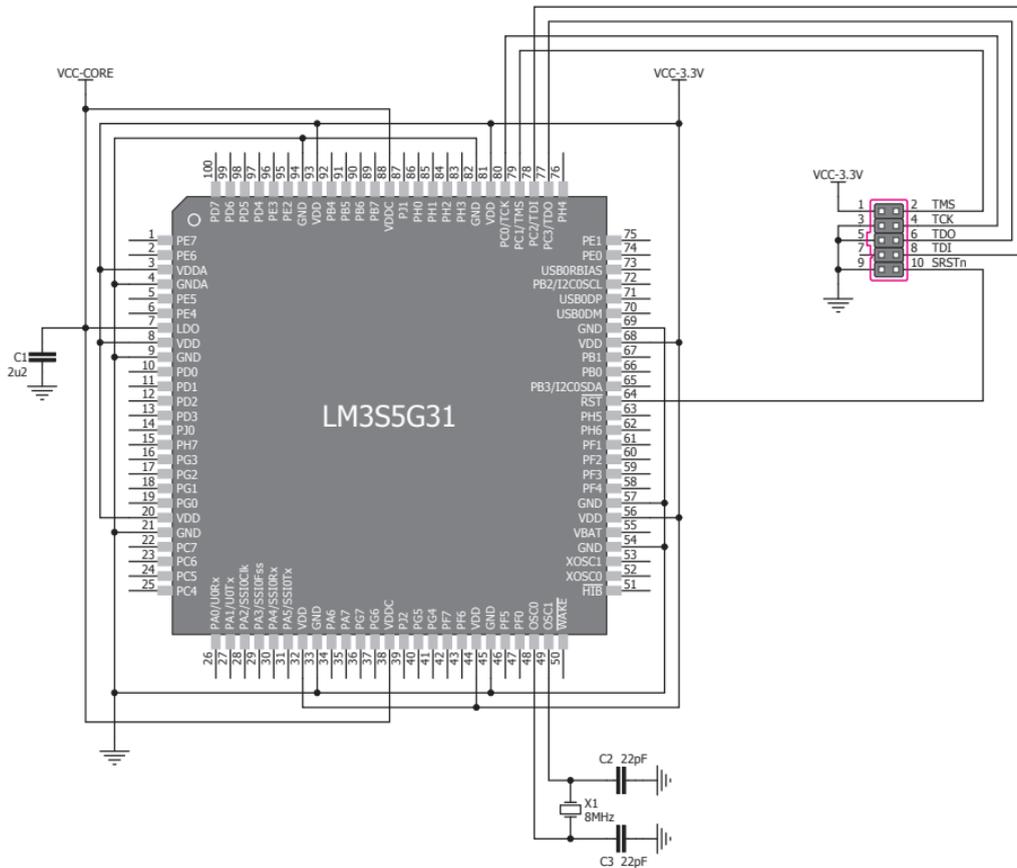


Figure 6-5: Connection schematics for 100-pin LM355G31 MCU via 2x5 male header

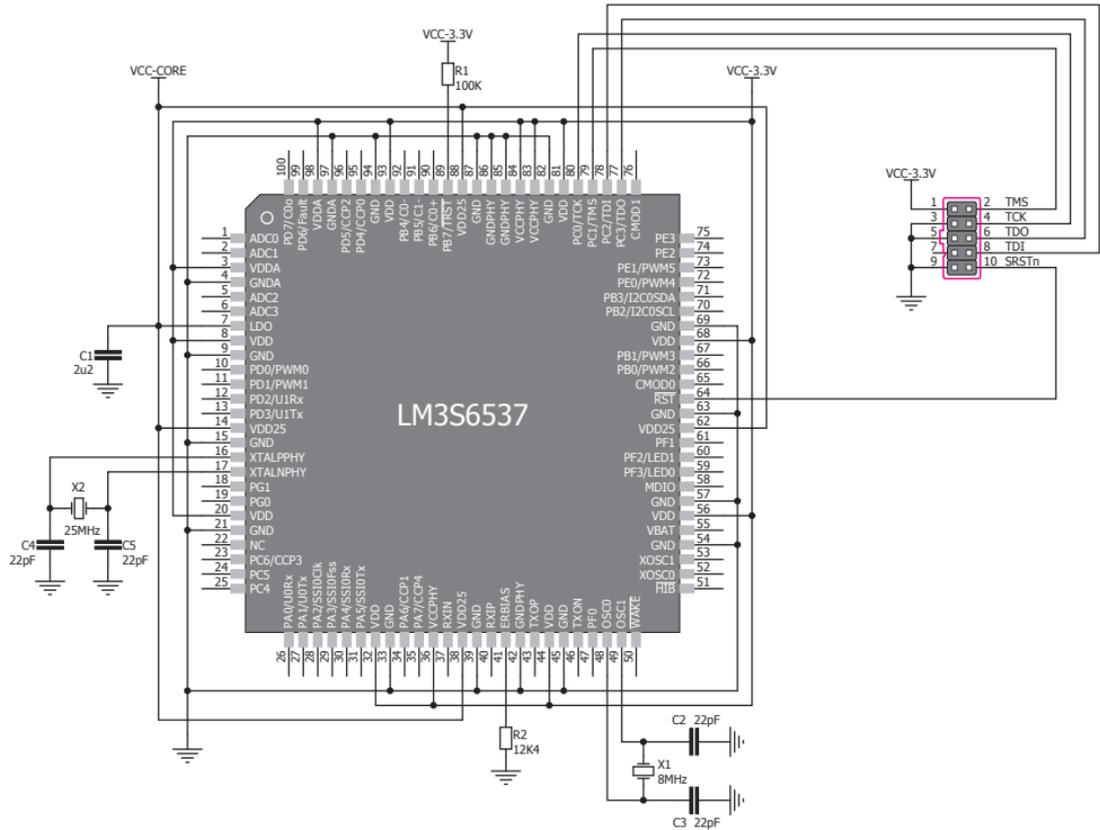


Figure 6-6: Connection schematics for 100-pin LM3S6537 MCU via 2x5 male header

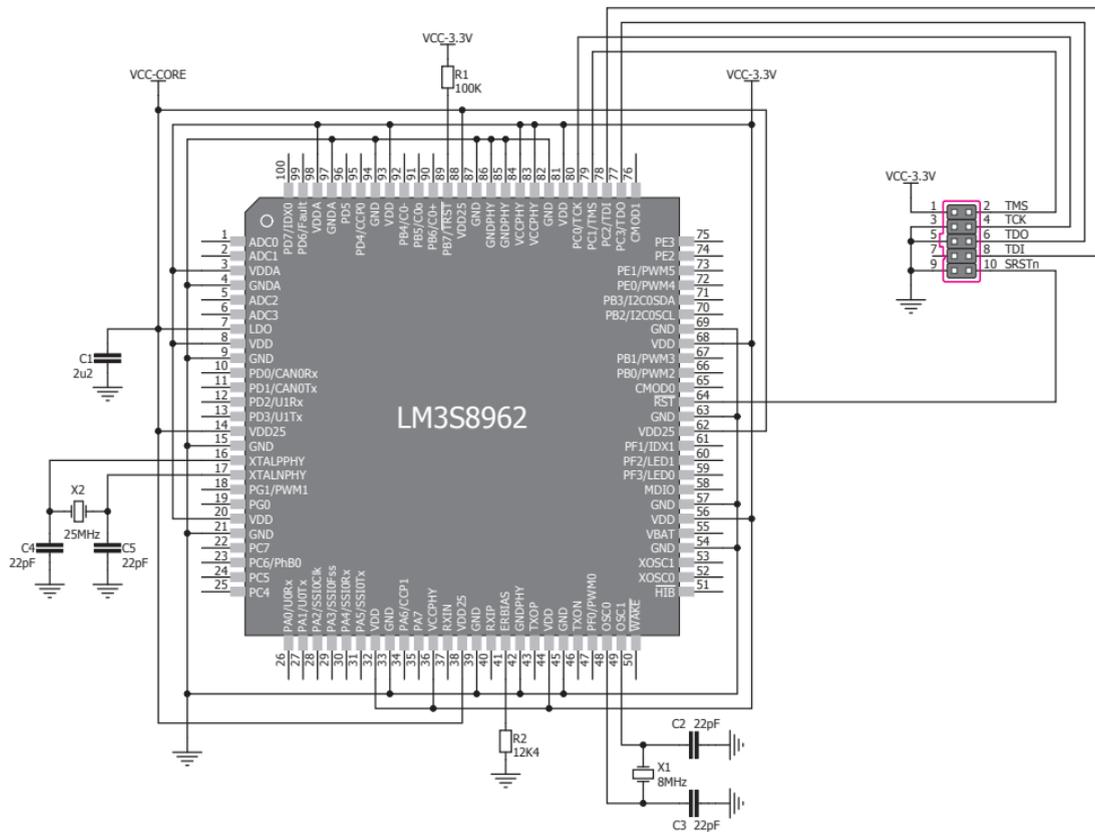


Figure 6-7: Connection schematics for 100-pin LM3S8962 MCU via 2x5 male header

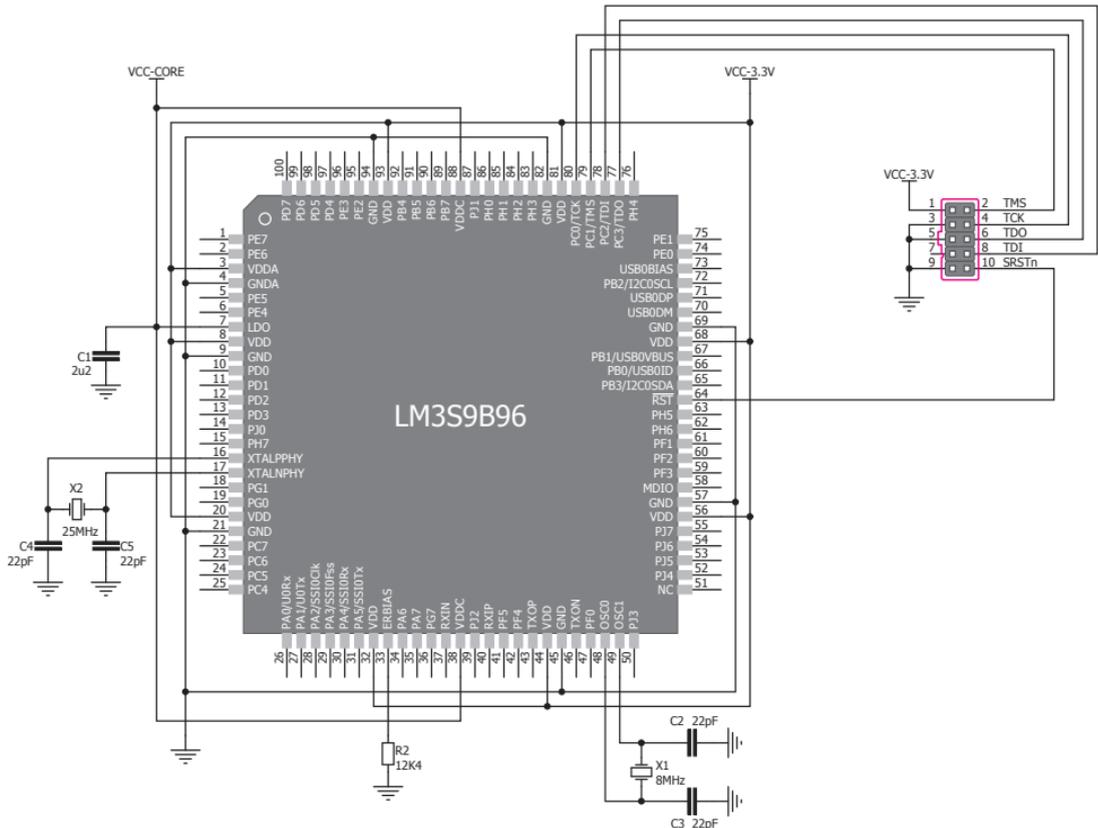


Figure 6-8: Connection schematics for 100-pin LM3S9B96 MCU via 2x5 male header

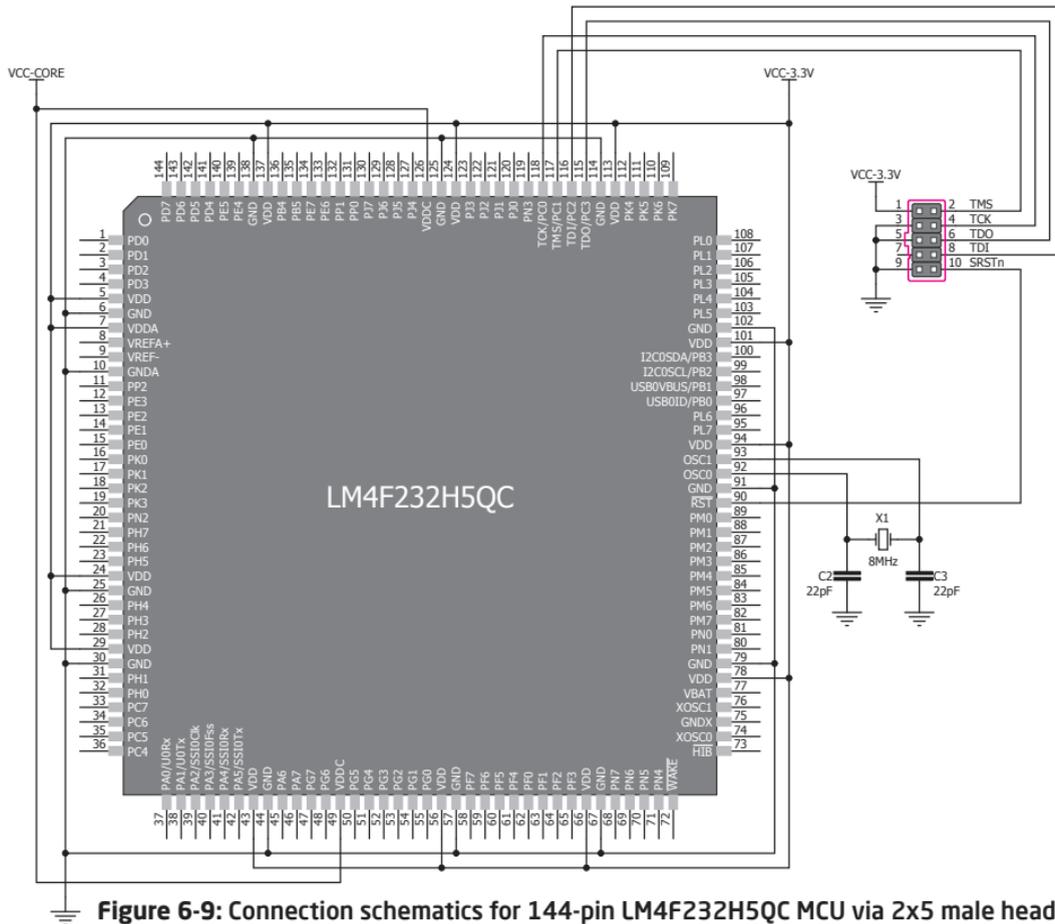
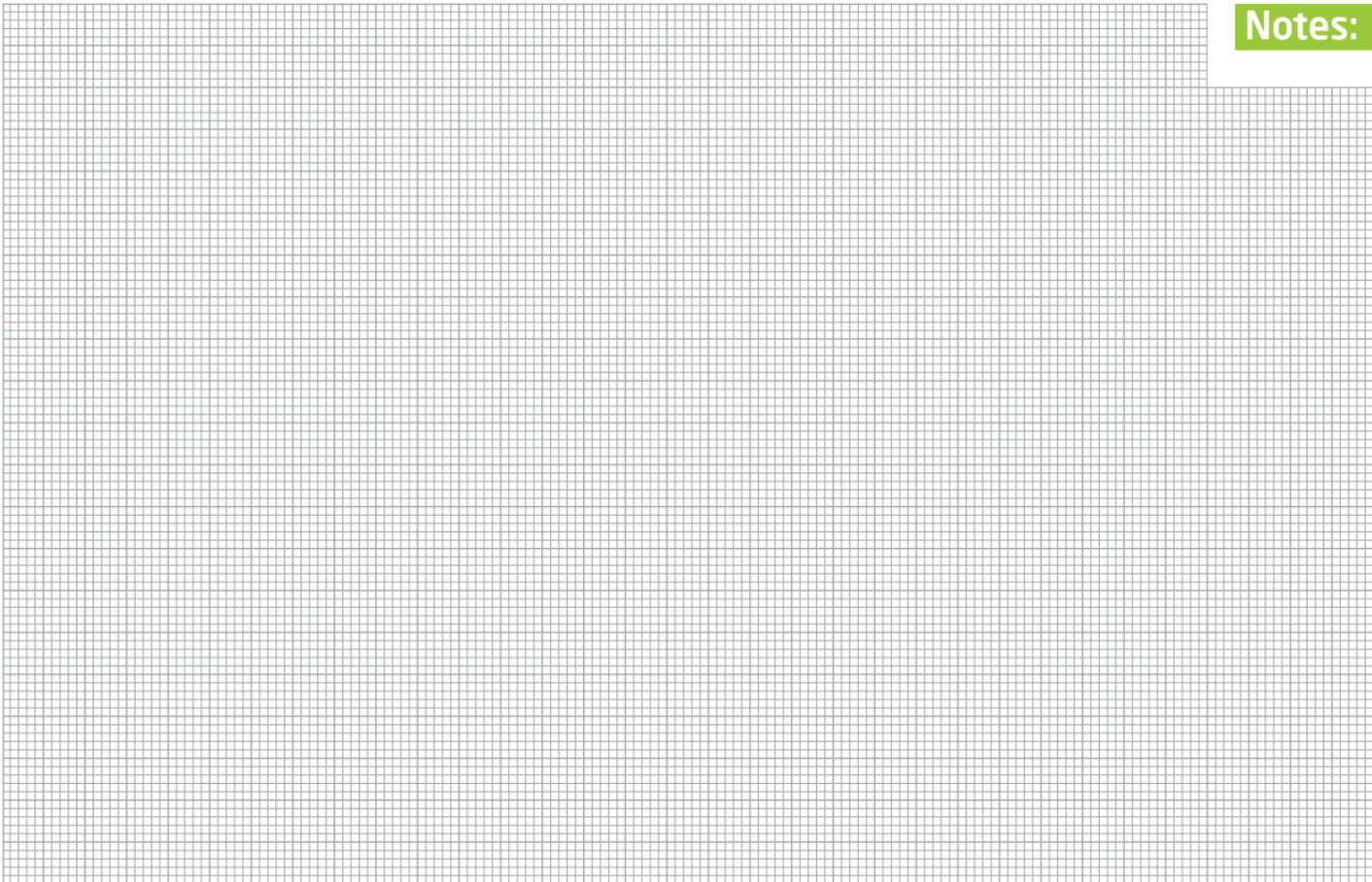


Figure 6-9: Connection schematics for 144-pin LM4F232H5QC MCU via 2x5 male header

Notes:

Notes:



Notes:

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