

FEATURES

Radio frequency (RF) 2×2 transceiver with integrated 12-bit DACs and ADCs Wide bandwidth: 325 MHz to 3.8 GHz Supports time division duplex (TDD) and frequency division duplex (FDD) operation Tunable channel bandwidth (BW): up to 20 MHz **Receivers: 6 differential or 12 single-ended inputs** Superior receiver sensitivity with a noise figure: 3 dB Receive (Rx) gain control Real-time monitor and control signals for manual gain Independent automatic gain control (AGC) **Dual transmitters: 4 differential outputs Highly linear broadband transmitter** Transmit (Tx) error vector magnitude (EVM): -34 dB Tx noise: ≤-157 dBm/Hz noise floor Tx monitor: 66 dB dynamic range with 1 dB accuracy Integrated fractional N synthesizers 2.4 Hz local oscillator (LO) step size **CMOS/LVDS digital interface**

APPLICATIONS

3G enterprise femtocell base stations 4G femtocell base stations Wireless video transmission

GENERAL DESCRIPTION

The AD9363 is a high performance, highly integrated RF agile transceiver designed for use in 3G and 4G femtocell applications. Its programmability and wideband capability make it ideal for a broad range of transceiver applications. The device combines an RF front end with a flexible mixed-signal baseband section and integrated frequency synthesizers, simplifying design-in by providing a configurable digital interface to a processor. The AD9363 operates in the 325 MHz to 3.8 GHz range, covering most licensed and unlicensed bands. Channel bandwidths from less than 200 kHz to 20 MHz are supported.

The two independent direct conversion receivers have state-ofthe-art noise figure and linearity. Each Rx subsystem includes independent automatic gain control (AGC), dc offset correction, quadrature correction, and digital filtering, thereby eliminating the need for these functions in the digital baseband. The AD9363 also has flexible manual gain modes that can be externally controlled. Two high dynamic range ADCs per channel digitize the received I and Q signals and pass them through configurable decimation filters and 128-tap finite impulse response (FIR) filters to produce a 12-bit output signal at the appropriate

Rev. D

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RF Agile Transceiver

AD9363

FUNCTIONAL BLOCK DIAGRAM



sample rate.

The transmitters use a direct conversion architecture that achieves high modulation accuracy with ultralow noise. This transmitter design produces a best-in-class Tx EVM of –34 dB, allowing significant system margin for the external power amplifier (PA) selection. The on-board Tx power monitor can be used as a power detector, enabling highly accurate Tx power measurements.

The fully integrated phase-locked loops (PLLs) provide low power fractional N frequency synthesis for all receive and transmit channels. Channel isolation, demanded by FDD systems, is integrated into the design. All voltage controlled oscillators (VCOs) and loop filter components are integrated.

The core of the AD9363 can be powered directly from a 1.3 V regulator. The IC is controlled via a standard 4-wire serial port and four real-time I/O control pins. Comprehensive power-down modes are included to minimize power consumption during normal use. The AD9363 is packaged in a 10 mm \times 10 mm, 144-ball chip scale package ball grid array (CSP_BGA).

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TABLE OF CONTENTS

Features
Applications1
Functional Block Diagram1
General Description
Revision History
Specifications
Current Consumption—VDD_INTERFACE
Current Consumption—VDDD1P3_DIG and VDDAx (Combination of All 1.3 V Supplies)
Absolute Maximum Ratings15
Reflow Profile15
Thermal Resistance
ESD Caution15
Pin Configuration and Function Descriptions16
Typical Performance Characteristics
800 MHz Frequency Band20

2.4 GHz Frequency Band	24
Гheory of Operation	
General	
Receiver	
Transmitter	
Clock Input Options	
Synthesizers	
Digital Data Interface	29
Enable State Machine	29
SPI Interface	30
Control Pins	30
GPO Pins (GPO_3 to GPO_0)	30
Auxiliary Converters	
Packaging and Ordering Information	32
Outline Dimensions	
Ordering Guide	32

REVISION HISTORY

11/2016—Revision D: Initial Version

SPECIFICATIONS

Electrical characteristics at VDD_GPO = 3.3 V, VDD_INTERFACE = 1.8 V, and all other VDDx pins (VDDA1P3_TX_LO, VDDA1P3_ TX_VCO_LDO, VDDA1P3_RX_LO, VDDA1P3_RX_VCO_LDO, VDDA1P3_RX_RF, VDDA1P3_RX_TX, VDDA1P3_TX_LO_BUFFER, VDDA1P3_TX_SYNTH, VDDA1P3_RX_SYNTH, VDDD1P3_DIG, and VDDA1P3_BB) = 1.3 V, T_A = 25°C, unless otherwise noted.

Table 1.								
Parameter ¹	Symbol	Min	Тур	Max	Unit	Test Conditions/Comments		
RECEIVERS, GENERAL								
Center Frequency		325		3800	MHz			
Rx Bandwidth				20	MHz			
Gain								
Minimum			0		dB			
Maximum			74.5		dB	At 800 MHz		
			73.0		dB	At 2300 MHz (RX1A_x, RX2A_x)		
			72.0		dB	At 2300 MHz (RX1B_x, RX1C_x, RX2B_x, RX2C_x)		
Gain Step			1		dB			
Received Signal Strength Indicator	RSSI							
Range			100		dB			
Accuracy			±2		dB			
RECEIVERS, 800 MHz								
Noise Figure	NF		2.5		dB	Maximum Rx gain		
Third-Order Input Intermodulation Intercept Point	IIP3		-18		dBm	Maximum Rx gain		
Second-Order Input Intermodulation Intercept Point	IIP2		40		dBm	Maximum Rx gain		
Local Oscillator (LO) Leakage			-122		dBm	At Rx front-end input		
Quadrature								
Gain Error			0.2		%			
Phase Error			0.2		Degrees			
Modulation Accuracy (EVM)			-34		dB	19.2 MHz reference clock		
Input Return Loss	S11		-10		dB			
RX1x_x to RX2x_x Isolation								
RX1A_x to RX2A_x, RX1C_x to RX2C_x			70		dB			
RX1B_x to RX2B_x			55		dB			
RX2_x to RX1_x Isolation								
RX2A_x to RX1A_x, RX2C_x to RX1C_x			70		dB			
RX2B_x to RX1B_x			55		dB			
RECEIVERS, 2.4 GHz								
Noise Figure	NF		3		dB	Maximum Rx gain		
Third-Order Input Intermodulation Intercept Point	IIP3		-14		dBm	Maximum Rx gain		
Second-Order Input Intermodulation Intercept Point	IIP2		45		dBm	Maximum Rx gain		
Local Oscillator (LO) Leakage			-110		dBm	At Rx front-end input		
Quadrature								
Gain Error			0.2		%			
Phase Error			0.2		Degrees			
Modulation Accuracy (EVM)			-34		dB	40 MHz reference clock		
Input Return Loss	S11		-10		dB			
RX1x_x to RX2x_x Isolation								
RX1A_x to RX2A_x, RX1C_x to RX2C_x			65		dB			
RX1B_x to RX2B_x			50		dB			

Parameter ¹	Symbol	Min	Тур	Мах	Unit	Test Conditions/Comments
RX2x_x to RX1x_x Isolation						
RX2A_x to RX1A_x, RX2C_x to RX1C_x			65		dB	
RX2B_x to RX1B_x			50		dB	
RECEIVERS, 3.5 GHz						
Noise Figure	NF		3.3		dB	Maximum Rx gain
Third-Order Input Intermodulation	IIP3		-15		dBm	Maximum Rx gain
Intercept Point						
Second-Order Input Intermodulation Intercept Point	IIP2		44		dBm	Maximum Rx gain
Local Oscillator (LO) Leakage			-100		dBm	At Rx front-end input
Quadrature						
Gain Error			0.2		%	
Phase Error			0.2		Degrees	
Modulation Accuracy (EVM)			-34		dB	40 MHz reference clock
Input Return Loss	S11		-10		dB	
RX1x_x to RX2x_x Isolation						
RX1A_x to RX2A_x, RX1C_x to RX2C_x			60		dB	
RX1B_x to RX2B_x			48		dB	
RX2x_x to RX1x_x Isolation						
RX2A_x to RX1A_x, RX2C_x to RX1C_x			60		dB	
RX2B_x to RX1B_x			48		dB	
TRANSMITTERS, GENERAL						
Center Frequency		325		3800	MHz	
Tx Bandwidth				20	MHz	
Power Control Range			90		dB	
Power Control Resolution			0.25		dB	
TRANSMITTERS, 800 MHz						
Output Return Loss	S22		-10		dB	
Maximum Output Power			8		dBm	1 MHz tone into 50 Ω load
Modulation Accuracy (EVM)			-34		dB	19.2 MHz reference clock
Third-Order Output Intermodulation	OIP3		23		dBm	
Intercept Point			50		10	
Carrier Leakage			-50		dBc	0 dB attenuation
			-32		dRC	40 dB attenuation
NOISE FIOOR			-157		abm/Hz	90 MHZ Offset
			50		٥Ŀ	
			50			
			50		ub	
Output Return Loss	522		_10		dB	
Maximum Output Power	522		-10 75		dBm	1 MHz tone into 50 O load
Maximum Output Fower			-34		dB	40 MHz reference clock
Third-Order Output Intermodulation	OIP3		-3 - 19		dBm	
Intercept Point	011 5		12		abiii	
Carrier Leakage			-50		dBc	0 dB attenuation
-			-32		dBc	40 dB attenuation
Noise Floor			-156		dBm/Hz	90 MHz offset
Isolation						
TX1x_x to TX2x_x			50		dB	
TX2x_x to TX1x_x			50		dB	
TRANSMITTERS, 3.5 GHz						
Output Return Loss	S22		-10		dB	
Maximum Output Power			7.0		dBm	1 MHz tone into 50 Ω load
Modulation Accuracy (EVM)			-34		dB	40 MHz reference clock

Parameter ¹	Symbol	Min	Тур	Мах	Unit	Test Conditions/Comments
Third-Order Output Intermodulation Intercept Point	OIP3		18		dBm	
Carrier Leakage			-50		dBc	0 dB attenuation
			-31		dBc	40 dB attenuation
Noise Floor			-154		dBm/Hz	90 MHz offset
Isolation						
TX1 to TX2			50		dB	
TX2 to TX1			50		dB	

¹ When referencing a single function of a multifunction pin in the parameters, only the portion of the pin name that is relevant to the specification is listed. For full pin names of multifunction pins, refer to the Pin Configuration and Function Descriptions section.

Table 2.						
Parameter ¹	Symbol	Min	Тур	Max	Unit	Test Conditions/Comments
TX MONITOR INPUTS (TX_MON1, TX_MON2)						
Maximum Input Level			4		dBm	
Dynamic Range			66		dB	
Accuracy			1		dB	
LO SYNTHESIZER						
LO Frequency Step			2.4		Hz	2.4 GHz, 40 MHz reference clock
Integrated Phase Noise			0.3		°rms	100 Hz to 100 MHz
REFERENCE CLOCK (REF_CLK)						REF_CLK is the input to the XTALN pin
Input Frequency Range		10		80	MHz	External oscillator
Input Signal Level			1.3		V p-р	AC-coupled external oscillator
AUXILIARY ADC						
Resolution			12		Bits	
Input Voltage						
Minimum			0.05		v	
Maximum			VDDA1P3_BB -		v	
			0.05			
AUXILIARY DAC						
Resolution			10		Bits	
Output Voltage						
Minimum			0.5		V	
Maximum			VDD_GPO - 0.3		V	
Output Current			10		mA	
DIGITAL SPECIFICATIONS (CMOS)						
Logic Inputs						
Input Voltage High		VDD_INTERFACE × 0.8		VDD_INTERFACE	V	
Input Voltage Low		0		VDD_INTERFACE × 0.2	V	
Input Current High		-10		+10	μA	
Input Current Low		-10		+10	μA	
Logic Outputs						
Output Voltage High		VDD_INTERFACE × 0.8		VDD_INTERFACE	v	
Output Voltage Low		0		VDD_INTERFACE × 0.2	v	
DIGITAL SPECIFICATIONS (LVDS)					1	
Logic Inputs						
Input Voltage Range		825		1575	mV	Each differential input in the
						pair
Input Differential Voltage Threshold		-100		+100	mV	
		F	Rev. D Page 5 of 32			

Paramotor ¹	Symbol	Min	Тир	Max	Unit	Test Conditions/Comments
Receiver Differential Input	Symbol		100	Max	0	rest conditions/comments
Impedance			100		12	
Output Voltage High				1375	mV	
Output Voltage Low		1025			mV	
Output Differential		150			mV	Programmable in 75 mV steps
Voltage						
Output Offset Voltage			1200		mV	
GENERAL-PURPOSE OUTPUTS						
Output Voltage High		$VDD_GPO \times 0.8$		VDD_GPO	V	
Output Voltage Low		0		VDD_GPO \times 0.2	V	
Output Current			10		mA	
SPITIMING						VDD_INTERFACE = 1.8 V
SPI_CLK						
Period	t _{cp}	20			ns	
Pulse Width	t _{MP}	9			ns	
SPI_EN Setup to First	t _{sc}	1			ns	
	50					
Last SPI_CLK Falling Edge to	t _{HC}	0			ns	
SPI_ENB Hold						
SPI_DI		2				
Data Input Setup to SPI_CLK	t _s	2			ns	
Data Input Hold to SPI_CLK	t _H	1			ns	
SPI_CLK Rising Edge to Output Data Delay						
4-Wire Mode	t _{co}	3		8	ns	
3-Wire Mode	t _{co}	3		8	ns	
Bus Turnaround Time, Read (Master)	t _{HZM}	t _H		t _{co (MAX)}	ns	After baseband processors (BBP) drives the last address bit
Bus Turnaround Time, Read (Slave)	t _{HZS}	0		t _{co (MAX)}	ns	After AD9363 drives the last data bit
DIGITAL DATA TIMING (CMOS), VDD INTERFACE = 1.8 V						
DATA_CLK_x Clock Period	t _{cP}	16.276			ns	61.44 MHz
DATA_CLK_x and FB_CLK_x	t _{MP}	45% of t _{CP}		55% of t _{CP}	ns	
Pulse Width		C.		c.		
Tx Data						TX_FRAME_x, P0_Dx, and P1_Dx
Setup to FB_CLK_x	t _{stx}	1			ns	
Hold to FB_CLK_x	t _{HTX}	0			ns	
DATA_CLK_x to Data Bus Output Delay	t _{DDRX}	0		1.5	ns	
DATA_CLK_x to RX_FRAME_x Delay	t _{DDDV}	0		1.0	ns	
Pulse Width						
ENABLE	t _{enpw}	t _{cp}			ns	
TXNRX	t _{TXNRXPW}	t _{CP}			ns	FDD independent enable state
	+				20	machine (ENSM) mode
I AINKA SELUP TO EINABLE	LTXNRXSU				ns	TDD mode
	+	2.4			nc	ווטער
	L _{RPRE}	2 X L _{CP}			ns	
Aller nx Conocitivo Lood	L _{RPST}	∠ × ι _{CP}	2		nE	
Capacitive Lodu			3		pr pF	
cupacitive input	1	1	J		I PI	

AD9363

Parameter ¹	Symbol	Min	Тур	Max	Unit	Test Conditions/Comments
DIGITAL DATA TIMING (CMOS),						
$VDD_INTERFACE = 2.3 V$	+	16 276			nc	61 44 MH7
DATA_CLK_x and EB_CLK_x	t	45% of t		55% of t	ns	01.44 10112
Pulse Width	ч _{МР}			5570 OF 1 _{CP}	115	
Tx Data						TX_FRAME_x, P0_Dx, and P1_Dx
Setup to FB_CLK_x	t _{stx}	1			ns	
Hold to FB_CLK_x	t _{HTX}	0			ns	
DATA_CLK_x to Data Bus Output Delay	t _{DDRX}	0.25		1.25	ns	
DATA_CLK_x to RX_FRAME_x Delay	t _{DDDV}	0.25		1.25	ns	
Pulse Width						
ENABLE	t _{ENPW}	t _{CP}			ns	
TXNRX	t _{TXNRXPW}	t _{CP}			ns	FDD independent ENSM mode
TXNRX Setup to ENABLE	t _{TXNRXSU}	0			ns	TDD ENSM mode
Bus Turnaround Time						TDD mode
Before Rx	t _{RPRE}	$2 \times t_{CP}$			ns	
After Rx	t _{RPST}	$2 \times t_{CP}$			ns	
Capacitive Load			3		pF	
Capacitive Input			3		pF	
DIGITAL DATA TIMING (LVDS)						
DATA_CLK_x Clock Period	t _{CP}	4.069			ns	245.76 MHz
DATA_CLK_x and FB_CLK_x Pulse Width	t _{MP}	45% of t_{CP}		55% of t_{CP}	ns	
Tx Data						TX_FRAME_x and TX_Dx
Setup to FB_CLK_x	t _{stx}	1			ns	
Hold to FB_CLK_x	t _{HTX}	0			ns	
DATA_CLK_x to Data Bus Output Delay	t _{DDRX}	0		1.5	ns	
DATA_CLK_x to RX_FRAME_x Delay	t _{DDDV}	0		1.0	ns	
Pulse Width						
ENABLE	t _{ENPW}	t _{cp}			ns	
TXNRX	t _{TXNRXPW}	t _{CP}			ns	FDD independent ENSM mode
TXNRX Setup to ENABLE	t _{TXNRXSU}	0			ns	TDD ENSM mode
Bus Turnaround Time						
Before Rx	t _{RPRE}	$2 \times t_{CP}$			ns	
After Rx	t _{RPST}	$2 \times t_{CP}$			ns	
Capacitive Load			3		рF	
Capacitive Input			3		рF	
SUPPLY CHARACTERISTICS						
1.3 V Main Supply		1.267	1.3	1.33	V	
VDD_INTERFACE Supply						
CMOS		1.2		2.5	V	
LVDS		1.8		2.5	v	
VDD_GPO Supply		1.3	3.3	3.465	V	When unused, must be set to 1.3 V
Current Consumption						
VDDx, Sleep Mode			180		μA	Sum of all input currents
VDD_GPO			50		μΑ	No load

¹ When referencing a single function of a multifunction pin in the parameters, only the portion of the pin name that is relevant to the specification is listed. For full pin names of multifunction pins, refer to the Pin Configuration and Function Descriptions section.

CURRENT CONSUMPTION—VDD_INTERFACE

Table 3. VDD_INTERFACE = 1.2 V

Parameter	Min Typ	Max	Unit	Test Conditions/Comments
SLEEP MODE	45		μΑ	Power applied, device disabled
ONE Rx CHANNEL, ONE Tx CHANNEL, DOUBLE DATA RATE (DDR)				
LTE10				
Single Port	2.9		mA	30.72 MHz data clock, CMOS
Dual Port	2.7		mA	15.36 MHz data clock, CMOS
LTE20				
Dual Port	5.2		mA	30.72 MHz data clock, CMOS
TWO Rx CHANNELS, TWO Tx CHANNELS, DDR				
LTE3				
Dual Port	1.3		mA	7.68 MHz data clock, CMOS
LTE10				
Single Port	4.6		mA	61.44 MHz data clock, CMOS
Dual Port	5.0		mA	30.72 MHz data clock, CMOS
LTE20				
Dual Port	8.2		mA	61.44 MHz data clock, CMOS
GSM				
Dual Port	0.2		mA	1.08 MHz data clock, CMOS
WiMAX 8.75 MHz				
Dual Port	3.3		mA	20 MHz data clock, CMOS
WiMAX 10 MHz				
Single Port				
TDD Rx	0.5		mA	22.4 MHz data clock, CMOS
TDD Tx	3.6		mA	22.4 MHz data clock, CMOS
FDD	3.8		mA	44.8 MHz data clock, CMOS
WiMAX 20 MHz				
Dual Port				
FDD	6.7		mA	44.8 MHz data clock, CMOS

Table 4. VDD_INTERFACE = 1.8 V

Parameter	Min	Тур	Max	Unit	Test Conditions/Comments
SLEEP MODE		84		μΑ	Power applied, device disabled
ONE Rx CHANNEL, ONE Tx CHANNEL, DDR					
LTE10					
Single Port		4.5		mA	30.72 MHz data clock, CMOS
Dual Port		4.1		mA	15.36 MHz data clock, CMOS
LTE20					
Dual Port		8.0		mA	30.72 MHz data clock, CMOS
TWO Rx CHANNELS, TWO Tx CHANNELS, DDR					
LTE3					
Dual Port		2.0		mA	7.68 MHz data clock, CMOS
LTE10					
Single Port		8.0		mA	61.44 MHz data clock, CMOS
Dual Port		7.5		mA	30.72 MHz data clock, CMOS
LTE20					
Dual Port		14.0		mA	61.44 MHz data clock, CMOS
GSM					
Dual Port		0.3		mA	1.08 MHz data clock, CMOS
WiMAX 8.75 MHz					
Dual Port		5.0		mA	20 MHz data clock, CMOS
WiMAX 10 MHz					
Single Port					
TDD Rx		0.7		mA	22.4 MHz data clock, CMOS
TDD Tx		5.6		mA	22.4 MHz data clock, CMOS
FDD		6.0		mA	44.8 MHz data clock, CMOS
WiMAX 20 MHz					
Dual Port					
FDD		10.7		mA	44.8 MHz data clock, CMOS

Table 5. VDD_INTERFACE = 2.5 V

Parameter	Min	Тур	Max	Unit	Test Conditions/Comments
SLEEP MODE		150		μΑ	Power applied, device disabled
ONE Rx CHANNEL, ONE Tx CHANNEL, DDR					
LTE10					
Single Port		6.5		mA	30.72 MHz data clock, CMOS
Dual Port		6.0		mA	15.36 MHz data clock, CMOS
LTE20					
Dual Port		11.5		mA	30.72 MHz data clock, CMOS
TWO Rx CHANNELS, TWO Tx CHANNELS, DDR					
LTE3					
Dual Port		3.0		mA	7.68 MHz data clock, CMOS
LTE10					
Single Port		11.5		mA	61.44 MHz data clock, CMOS
Dual Port		10.0		mA	30.72 MHz data clock, CMOS
LTE20					
Dual Port		20.0		mA	61.44 MHz data clock, CMOS
GSM					
Dual Port		0.5		mA	1.08 MHz data clock, CMOS
WiMAX 8.75 MHz					
Dual Port		7.3		mA	20 MHz data clock, CMOS
WiMAX 10 MHz					
Single Port					
TDD Rx		1.3		mA	22.4 MHz data clock, CMOS
TDD Tx		8.0		mA	22.4 MHz data clock, CMOS
FDD		8.7		mA	44.8 MHz data clock, CMOS
WiMAX 20 MHz					
Dual Port					
FDD		15.3		mA	44.8 MHz data clock, CMOS

CURRENT CONSUMPTION—VDDx (COMBINATION OF ALL 1.3 V SUPPLIES)

Table 6. TDD Mode, 800 MHz

Parameter	Min Typ	Max	Unit	Test Conditions/Comments
ONE Rx CHANNEL				Continuous Rx
5 MHz BW	180		mA	
10 MHz BW	210		mA	
20 MHz BW	260		mA	
TWO Rx CHANNELS				Continuous Rx
5 MHz BW	265		mA	
10 MHz BW	315		mA	
20 MHz BW	405		mA	
ONE TX CHANNEL				Continuous Tx
5 MHz BW				
7 dBm	340		mA	
–27 dBm	190		mA	
10 MHz BW				
7 dBm	360		mA	
–27 dBm	220		mA	
20 MHz BW				
7 dBm	400		mA	
–27 dBm	250		mA	
TWO Tx CHANNELS				Continuous Tx
5 MHz BW				
7 dBm	550		mA	
–27 dBm	260		mA	
10 MHz BW				
7 dBm	600		mA	
–27 dBm	310		mA	
20 MHz BW				
7 dBm	660		mA	
–27 dBm	370		mA	

Table 7. TDD Mode, 2.4 GHz

Parameter	Min Typ	Max	Unit	Test Conditions/Comments
ONE Rx CHANNEL				Continuous Rx
5 MHz BW	175		mA	
10 MHz BW	200		mA	
20 MHz BW	240		mA	
TWO Rx CHANNELS				Continuous Rx
5 MHz BW	260		mA	
10 MHz BW	305		mA	
20 MHz BW	390		mA	
ONE Tx CHANNEL				Continuous Tx
5 MHz BW				
7 dBm	350		mA	
–27 dBm	160		mA	
10 MHz BW				
7 dBm	380		mA	
–27 dBm	220		mA	
20 MHz BW				
7 dBm	410		mA	
–27 dBm	260		mA	
TWO Tx CHANNELS				Continuous Tx
5 MHz BW				
7 dBm	580		mA	
–27 dBm	280		mA	
10 MHz BW				
7 dBm	635		mA	
–27 dBm	330		mA	
20 MHz BW				
7 dBm	690		mA	
–27 dBm	390		mA	

Table 8. FDD Mode, 800 MHz

Parameter	Min Typ	Max	Unit	Test Conditions/Comments
ONE Rx CHANNEL, ONE Tx CHANNEL				Continuous Rx and Tx
5 MHz BW				
7 dBm	490		mA	
–27 dBm	345		mA	
10 MHz BW				
7 dBm	540		mA	
–27 dBm	395		mA	
20 MHz BW				
7 dBm	615		mA	
–27 dBm	470		mA	
TWO Rx CHANNELS, ONE Tx CHANNEL				Continuous Rx and Tx
5 MHz BW				
7 dBm	555		mA	
–27 dBm	410		mA	
10 MHz BW				
7 dBm	625		mA	
–27 dBm	480		mA	
20 MHz BW				
7 dBm	740		mA	
–27 dBm	600		mA	
ONE Rx CHANNEL, TWO Tx CHANNELS				Continuous Rx and Tx
5 MHz BW				
7 dBm	685		mA	
–27 dBm	395		mA	
10 MHz BW				
7 dBm	755		mA	
–27 dBm	465		mA	
20 MHz BW				
7 dBm	850		mA	
–27 dBm	570		mA	
TWO Rx CHANNELS, TWO Tx CHANNELS				
5 MHz BW				
7 dBm	790		mA	
–27 dBm	495		mA	
10 MHz BW				
7 dBm	885		mA	
–27 dBm	590		mA	
20 MHz BW				
7 dBm	1020		mA	
–27 dBm	730		mA	

Table 9. FDD Mode, 2.4 GHz

Parameter	Min Typ	Max	Unit	Test Conditions/Comments
ONE Rx CHANNEL, ONE Tx CHANNEL				Continuous Rx and Tx
5 MHz BW				
7 dBm	500		mA	
–27 dBm	350		mA	
10 MHz BW				
7 dBm	540	1	mA	
–27 dBm	390		mA	
20 MHz BW				
7 dBm	620	1	mA	
–27 dBm	475	1	mA	
TWO Rx CHANNELS, ONE Tx CHANNEL				Continuous Rx and Tx
5 MHz BW				
7 dBm	590	1	mA	
–27 dBm	435		mA	
10 MHz BW				
7 dBm	660	1	mA	
–27 dBm	510		mA	
20 MHz BW				
7 dBm	770	1	mA	
–27 dBm	620		mA	
ONE Rx CHANNEL, TWO Tx CHANNELS				Continuous Rx and Tx
5 MHz BW				
7 dBm	730		mA	
–27 dBm	425	1	mA	
10 MHz BW				
7 dBm	800		mA	
–27 dBm	500		mA	
20 MHz BW				
7 dBm	900	1	mA	
–27 dBm	600	1	mA	
TWO Rx CHANNELS, TWO Tx CHANNELS				Continuous Rx and Tx
5 MHz BW				
7 dBm	820	1	mA	
–27 dBm	515	1	mA	
10 MHz BW				
7 dBm	900	1	mA	
–27 dBm	595	1	mA	
20 MHz BW				
7 dBm	1050	1	mA	
–27 dBm	740	1	mA	

ABSOLUTE MAXIMUM RATINGS

Table 10.

Parameter	Rating
VDDx to VSSx	–0.3 V to +1.4 V
VDD_INTERFACE to VSSx	–0.3 V to +3.0 V
VDD_GPO to VSSx	–0.3 V to +3.9 V
Logic Inputs and Outputs to VSSx	–0.3 V to VDD_INTERFACE + 0.3 V
Input Current to Any Pin Except Supplies	±10 mA
RF Inputs (Peak Power)	2.5 dBm
Tx Monitor Input Power (Peak Power)	9 dBm
Package Power Dissipation	$(T_{JMAX} - T_A)/\theta_{JA}$
Maximum Junction Temperature (T _{JMAX})	110°C
Temperature Range	
Operating	-40°C to +85°C
Storage	–65°C to +150°C
Reflow	260°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

REFLOW PROFILE

The AD9363 reflow profile is in accordance with the JEDEC JESD20 criteria for Pb-free devices. The maximum reflow temperature is 260°C.

THERMAL RESISTANCE

Thermal performance is directly linked to printed circuit board (PCB) design and operating environment.

Careful attention to PCB thermal design is required.

 θ_{JA} is the natural convection junction to ambient thermal resistance measured in a one cubic foot sealed enclosure.

 θ_{IC} is the junction to case thermal resistance.

Table 11. Thermal Resistance

Package Type	Airflow Velocity (m/sec)	θ_{JA}^{2}	θ」。3	Unit
BC-144-7 ¹	0	32.3	9.6	°C/W
	1.0	29.6	N/A ⁴	°C/W
	2.5	27.8	N/A ⁴	°C/W

¹ Per JEDEC JESD51-7, plus JEDEC JESD51-5 2S2P test board.

² Per JEDEC JESD51-2 (still air) or JEDEC JESD51-6 (moving air).

³ Per MIL-STD-883, Method 1012.1.

⁴ N/A means not applicable.

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

10558-002

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

	1	2	3	4	5	6	7	8	9	10	11	12
A	RX2A_N	RX2A_P	DNC	VSSA	TX_MON2	VSSA	TX2A_N	TX2A_P	TX2B_N	TX2B_P	VDDA1P1_ TX_VCO	VSSA
в	VSSA	VSSA	AUXDAC1	GPO_3	GPO_2	GPO_1	GPO_0	VDD_GPO	VDDA1P3_ TX_LO	VDDA1P3_ TX_VCO_ EDO	TX_VCO_ LDO_OUT	VSSA
с	RX2C_P	VSSA	AUXDAC2	TEST/ ENABLE	CTRL_IN0	CTRL_IN1	VSSA	VSSA	VSSA	VSSA	VSSA	VSSA
D	RX2C_N	VDDA1P3_ RX_RF	VDDA1P3_ RX_TX	CTRL_OUT0	CTRL_IN3	CTRL_IN2	P0_D9/ TX_D4_P	P0_D7/ TX_D3_P	P0_D5/ TX_D2_P	P0_D3/ TX_D1_P	P0_D1/ TX_D0_P	VSSD
Е	RX2B_P	VDDA1P3_ RX_LO	VDDA1P3_ TX_LO BUFFER	CTRL_OUT1	CTRL_OUT2	CTRL_OUT3	P0_D11/ TX_D5_P	P0_D8/ TX_D4_N	P0_D6/ TX_D3_N	P0_D4/ TX_D2_N	P0_D2/ TX_D1_N	P0_D0/ TX_D0_N
F	RX2B_N	VDDA1P3_ RX_VCO_ LDO	VSSA	CTRL_OUT6	CTRL_OUT5	CTRL_OUT4	VSSD	P0_D10/ TX_D5_N	VSSD	FB_CLK_P	VSSD	VDDD1P3_ DIG
G	VSSA	RX_VCO_ LDO_OUT	VDDA1P1_ RX_VCO	CTRL_OUT7	EN_AGC	ENABLE	RX_ FRAME_N	RX_ FRAME_P	TX_ FRAME_P	FB_CLK_N	DATA_ CLK_P	VSSD
н	RX1B_P	VSSA	VSSA	TXNRX	VSSA	VSSA	VSSD	P1_D11/ RX_D5_P	TX_ FRAME_N	VSSD	DATA_ CLK_N	VDD_ INTERFACE
J	RX1B_N	VSSA	VDDA1P3_ RX_SYNTH	SPI_DI	SPI_CLK	CLK_OUT	P1_D10/ RX_D5_N	P1_D9/ RX_D4_P	P1_D7/ RX_D3_P	P1_D5/ RX_D2_P	P1_D3/ RX_D1_P	P1_D1/ RX_D0_P
к	RX1C_P	VSSA	VDDA1P3_ TX_SYNTH	VDDA1P3_ BB	RESET	SPI_EN	P1_D8/ RX_D4_N	P1_D6/ RX_D3_N	P1_D4/ RX_D2_N	P1_D2/ RX_D1_N	P1_D0/ RX_D0_N	VSSD
L	RX1C_N	VSSA	VSSA	RBIAS	AUXADC	SPI_DO	VSSA	VSSA	VSSA	VSSA	VSSA	VSSA
м	RX1A_P	RX1A_N	DNC	VSSA	TX_MON1	VSSA	TX1A_P	TX1A_N	TX1B_P	TX1B_N	DNC	XTALN

Figure 2. Pin Configuration, Top View

Table 12. Pin Function Descriptions

Pin No.	Type ¹	Mnemonic	Description
A1, A2	I	RX2A_N, RX2A_P	Receive Channel 2 Differential A Inputs. Alternatively, each pin can be used as a single-ended input. Unused pins must be tied to ground.
A3, M3, M11	NC	DNC	Do Not Connect. Do not connect to these pins.
A4, A6, A12, B1, B2, B12, C2, C7 to C12, F3, G1, H2, H3, H5, H6, J2, K2, L2, L3, L7 to L12, M4, M6	GND	VSSA	Analog Ground. Tie these pins directly to the VSSD digital ground on the PCB (one ground plane).
A5	I	TX_MON2	Transmit Channel 2 Power Monitor Input. If this pin is unused, tie it to ground.
A7, A8	0	TX2A_N, TX2A_P	Transmit Channel 2 Differential A Outputs. Unused pins must be tied to 1.3 V.
A9, A10	0	TX2B_N, TX2B_P	Transmit Channel 2 Differential B Outputs. Unused pins must be tied to 1.3 V.
A11	Р	VDDA1P1_TX_VCO	Transmit VCO Supply Input. Connect to B11.
B3	0	AUXDAC1	Auxiliary DAC 1 Output. If using the auxiliary DAC, connect a 0.1 μF capacitor from this pin to ground.
B4 to B7	0	GPO_3 to GPO_0	3.3 V Capable General-Purpose Outputs.
B8	I	VDD_GPO	2.5 V to 3.3 V Supply for the AUXDAC and General-Purpose Output Pins. If the VDD_GPO supply is not used, this supply must be set to 1.3 V.
B9	I	VDDA1P3_TX_LO	Transmit Local Oscillator (LO) 1.3 V Supply Input.
B10	I	VDDA1P3_TX_VCO_LDO	Transmit VCO LDO 1.3 V Supply Input. Connect to B9.
B11	0	TX_VCO_LDO_OUT	Transmit VCO LDO Output. Connect to A11 and to a 1 μF bypass capacitor in series with a 1 Ω resistor to ground.
C1, D1	I	RX2C_P, RX2C_N	Receive Channel 2 Differential C Inputs. Alternatively, use each pin as a single-ended input. Unused pins must be tied to ground.
C3	0	AUXDAC2	Auxiliary DAC 2 Output. If using the auxiliary DAC, connect a 0.1 μ F capacitor from this pin to ground.
C4	T	TEST/ENABLE	Test Input. Ground this pin for normal operation.
C5, C6, D5, D6	I	CTRL_IN0 to CTRL_IN3	Control Inputs. Use these pins for manual Rx gain and Tx attenuation control.

Rev. D | Page 16 of 32

Pin No.	Type ¹	Mnemonic	Description
D2	I	VDDA1P3_RX_RF	Receiver 1.3 V Supply Input. Connect to D3.
D3	1	VDDA1P3_RX_TX	Receiver and Transmitter 1.3 V Supply Input.
D4, E4 to E6, F4 to F6, G4	0	CTRL_OUT0, CTRL_OUT1 to CTRL_OUT3, CTRL_OUT6 to CTRL_OUT4, CTRL_OUT7	Control Outputs. These pins are multipurpose outputs that have programmable functionality.
D7	I/O	P0_D9/TX_D4_P	Digital Data Port 0, Data Bit 9/Transmit Differential Input Bus, Data Bit 4. This is a dual function pin. As P0_D9, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D4_P, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
D8	I/O	P0_D7/TX_D3_P	Digital Data Port 0, Data Bit 7/Transmit Differential Input Bus, Data Bit 3. This is a dual function pin. As P0_D7, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D3_P, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
D9	I/O	P0_D5/TX_D2_P	Digital Data Port 0, Data Bit 5/Transmit Differential Input Bus, Data Bit 2. This is a dual function pin. As P0_D5, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D2_P, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
D10	I/O	P0_D3/TX_D1_P	Digital Data Port 0, Data Bit 3/Transmit Differential Input Bus, Data Bit 1. This is a dual function pin. As P0_D3, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D1_P, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
D11	I/O	P0_D1/TX_D0_P	Digital Data Port 0, Data Bit 1/Transmit Differential Input Bus, Data Bit 0. This is a dual function pin. As P0_D1, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D0_P, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
D12, F7, F9, F11, G12, H7, H10, K12	GND	VSSD	Digital Ground. Tie these pins directly to the VSSA analog ground on the PCB (one ground plane).
E1, F1	I	RX2B_P, RX2B_N	Receive Channel 2 Differential B Inputs. Alternatively, each pin can be used as a single-ended input. Unused pins must be tied to ground.
E2	I	VDDA1P3_RX_LO	Receive LO 1.3 V Supply Input.
E3	I	VDDA1P3_TX_LO_BUFFER	Transmitter LO Buffer 1.3 V Supply Input.
E7	I/O	P0_D11/TX_D5_P	Digital Data Port 0, Data Bit 11/Transmit Differential Input Bus, Data Bit 5. This is a dual function pin. As P0_D11, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D5_P, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
E8	I/O	P0_D8/TX_D4_N	Digital Data Port 0, Data Bit 8/Transmit Differential Input Bus, Data Bit 4. This is a dual function pin. As P0_D8, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D4_N, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
E9	I/O	P0_D6/TX_D3_N	Digital Data Port 0, Data Bit 6/Transmit Differential Input Bus, Data Bit 3. This is a dual function pin. As P0_D6, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D3_N, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
E10	I/O	P0_D4/TX_D2_N	Digital Data Port 0, Data Bit 4/Transmit Differential Input Bus, Data Bit 2. This is a dual function pin. As P0_D4, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D2_N, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
E11	I/O	P0_D2/TX_D1_N	Digital Data Port 0, Data Bit 2/Transmit Differential Input Bus, Data Bit 1. This is a dual function pin. As P0_D2, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D1_N, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
E12	I/O	P0_D0/TX_D0_N	Digital Data Port 0, Data Bit 0/Transmit Differential Input Bus, Data Bit 0. This is a dual function pin. As P0_D0, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D0_N, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
F2	I	VDDA1P3_RX_VCO_LDO	Receive VCO LDO 1.3 V Supply Input. Connect to E2.

Pin No.	Type ¹	Mnemonic	Description
F8	I/O	P0_D10/TX_D5_N	Digital Data Port 0, Data Bit 10/Transmit Differential Input Bus, Data Bit 5. This is a dual function pin. As P0_D10, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, as TX_D5_N, it functions as part of the LVDS 6-bit Tx differential input bus with internal LVDS termination.
F10, G10	T	FB_CLK_P, FB_CLK_N	Feedback Clock Inputs. These pins receive the FB_CLK signal that clocks in Tx data. In CMOS mode, use FB_CLK_P as the input and tie FB_CLK_N to ground.
F12	I	VDDD1P3_DIG	1.3 V Digital Supply Input.
G2	0	RX_VCO_LDO_OUT	Receive VCO LDO Output. Connect to G3 and to a 1 μF bypass capacitor in series with a 1 Ω resistor to ground.
G3	1	VDDA1P1_RX_VCO	Receive VCO Supply Input. Connect to G2.
G5	I	EN_AGC	Manual Control Input for Automatic Gain Control (AGC).
G6	T	ENABLE	Control Input. This pin moves the device through various operational states.
G7, G8	0	RX_FRAME_N, RX_FRAME_P	Receive Digital Data Framing Outputs. These pins transmit the RX_FRAME signal that indicates whether the Rx output data is valid. In CMOS mode, use RX_FRAME_P as the output and leave RX_FRAME_N unconnected.
G9, H9	I	TX_FRAME_P, TX_FRAME_N	Transmit Digital Data Framing Inputs. These pins receive the TX_FRAME signal that indicates when Tx data is valid. In CMOS mode, use TX_FRAME_P as the input and tie TX_FRAME_N to ground.
G11, H11	0	DATA_CLK_P, DATA_CLK_N	Receive Data Clock Outputs. These pins transmit the DATA_CLK signal that the BBP uses to clock the Rx data. In CMOS mode, use DATA_CLK_P as the output and leave DATA_CLK_N unconnected.
H1, J1	I	RX1B_P, RX1B_N	Receive Channel 1 Differential B Inputs. Alternatively, use each pin as a single-ended input. Unused pins must be tied to ground.
H4	I	TXNRX	Enable State Machine Control Signal. This pin controls the data port bus direction. A logic low selects the Rx direction; a logic high selects the Tx direction.
H8	I/O	P1_D11/RX_D5_P	Digital Data Port P1, Data Bit 11/Receive Differential Output Bus, Data Bit 5. This is a dual function pin. As P1_D11, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D5_P, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
H12	1	VDD_INTERFACE	1.2 V to 2.5 V Supply for Digital I/O Pins (1.8 V to 2.5 V in LVDS Mode).
J3	1	VDDA1P3_RX_SYNTH	Receiver Synthesizer 1.3 V Supply Input.
J4	I	SPI_DI	SPI Serial Data Input.
J5	I	SPI_CLK	SPI Clock Input.
JG	0	CLK_OUT	Output Clock. This pin can be configured to output either a buffered version of the external input clock (the digital controlled crystal oscillator (DCXO)) or a divided-down version of the internal ADC sample clock (ADC_CLK).
J7	I/O	P1_D10/RX_D5_N	Digital Data Port 1, Data Bit 10/Receive Differential Output Bus, Data Bit 5. This is a dual function pin. As P1_D10, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D5_N, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
8L	I/O	P1_D9/RX_D4_P	Digital Data Port 1, Data Bit 9/Receive Differential Output Bus, Data Bit 4. This is a dual function pin. As P1_D9, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D4_P, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
9	I/O	P1_D7/RX_D3_P	Digital Data Port 1, Data Bit 7/Receive Differential Output Bus, Data Bit 3. This is a dual function pin. As P1_D7, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D3_P, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
J10	I/O	P1_D5/RX_D2_P	Digital Data Port 1, Data Bit 5/Receive Differential Output Bus, Data Bit 2. This is a dual function pin. As P1_D5, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D2_P, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
J11	I/O	P1_D3/RX_D1_P	Digital Data Port 1, Data Bit 3/Receive Differential Output Bus, Data Bit 1. This is a dual function pin. As P1_D3, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D1_P, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.

Pin No.	Type ¹	Mnemonic	Description
J12	I/O	P1_D1/RX_D0_P	Digital Data Port 1, Data Bit 1/Receive Differential Output Bus, Data Bit 0. This is a dual function pin. As P1_D1, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D0_P, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
K1, L1	I	RX1C_P, RX1C_N	Receive Channel 1 Differential C Inputs. Alternatively, use each pin as a single-ended input. Tie unused pins to ground.
K3	I	VDDA1P3_TX_SYNTH	Transmitter Synthesizer 1.3 V Supply Input. Connect this pin to a 1.3 V regulator through a separate trace to a common supply point.
K4	I	VDDA1P3_BB	Baseband 1.3 V Supply Input. Connect this pin to a 1.3 V regulator through a separate trace to a common supply point.
K5	1	RESET	Asynchronous Reset Input. A logic low resets the device.
K6	1	SPI_EN	SPI Enable. Set this pin to logic low to enable the SPI bus.
К7	I/O	P1_D8/RX_D4_N	Digital Data Port 1, Data Bit 8/Receive Differential Output Bus, Data Bit 4. This is a dual function pin. As P1_D8, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D4_N, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
К8	I/O	P1_D6/RX_D3_N	Digital Data Port 1, Data Bit 6/Receive Differential Output Bus, Data Bit 3. This is a dual function pin. As P1_D6, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D3_N, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
К9	I/O	P1_D4/RX_D2_N	Digital Data Port 1, Data Bit 4/Receive Differential Output Bus, Data Bit 2. This is a dual function pin. As P1_D4, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D2_N, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
K10	I/O	P1_D2/RX_D1_N	Digital Data Port 1, Data Bit 2/Receive Differential Output Bus, Data Bit 1. This is a dual function pin. As P1_D2, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D1_N, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
K11	I/O	P1_D0/RX_D0_N	Digital Data Port 1, Data Bit 0/Receive Differential Output Bus, Data Bit 0. This is a dual function pin. As P1_D0, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, as RX_D0_N, it functions as part of the LVDS 6-bit Rx differential output bus with internal LVDS termination.
L4	I	RBIAS	Bias Input Reference. Connect this pin through a 14.3 k Ω (1% tolerance) resistor to ground.
L5	1	AUXADC	Auxiliary ADC Input. If this pin is unused, tie it to ground.
L6	0	SPI_DO	SPI Serial Data Output in 4-Wire Mode, High-Z in 3-Wire Mode.
M1, M2	I	RX1A_P, RX1A_N	Receive Channel 1 Differential A Inputs. Alternatively, use each pin as a single-ended input. Tie unused pins to ground.
M5	1	TX_MON1	Transmit Channel 1 Power Monitor Input. If this pin is unused, tie it to ground.
M7, M8	0	TX1A_P, TX1A_N	Transmit Channel 1 Differential A Outputs. Tie unused pins to 1.3 V.
M9, M10	0	TX1B_P, TX1B_N	Transmit Channel 1 Differential B Outputs. Tie unused pins to 1.3 V.
M12	I	XTALN	Reference Frequency Connection. Connect the external clock source to XTALN.

 $^{\rm 1}$ I is input, NC is not connected, GND is ground, O is output, P is power, and I/O is input/output.

TYPICAL PERFORMANCE CHARACTERISTICS

ATTEN is the attenuation setting. $f_{LO_{TX}}$ and $f_{LO_{TX}}$ are the receive and transmit local oscillator frequencies, respectively.

800 MHZ FREQUENCY BAND



Figure 4. RSSI Error vs. Rx Input Power, LTE 10 MHz Modulation (Referenced to -50 dBm Input Power at 800 MHz)



Figure 5. Rx EVM vs. Interferer Power Level, LTE 10 MHz Signal of Interest with $P_{IN} = -82 \text{ dBm}$, 5 MHz Orthogonal Frequency Division Multiplexing (OFDM) Blocker at 7.5 MHz Offset







Figure 7. Rx Noise Figure vs. Interferer Power Level, Enhanced Data Rates for GSM Evolution (EDGE) Signal of Interest with $P_{IN} = -90$ dBm, Continuous Wave (CW) Blocker at 3 MHz Offset, Gain Index = 64



Figure 8. Rx Gain vs. Rx LO Frequency, Gain Index = 76 (Maximum Setting)



Figure 9. Third-Order Input Intercept Point (IIP3) vs. Rx Gain Index, f1 = 1.45 MHz, f2 = 2.89 MHz, GSM Mode



Figure 10. Second-Order Input Intercept Point (IIP2) vs. Rx Gain Index, f1 = 2.00 MHz, f2 = 2.01 MHz, GSM Mode



Figure 11. Rx LO Leakage vs. Rx LO Frequency



Figure 12. Rx Emission at LNA Input vs. Frequency, DC to 12 GHz, f_{LO_RX} = 800 MHz, LTE 10 MHz, f_{LO_TX} = 860 MHz



Figure 13. Tx Output Power vs. Tx LO Frequency, Attenuation Setting = 0 dB, Single-Tone Output



Figure 14. Tx Power Control Step Linearity Error vs. Attenuation Setting







Figure 16. Integrated Tx LO Phase Noise vs. Frequency, 19.2 MHz REF_CLK



Figure 17. Tx Carrier Rejection vs. Frequency



Figure 18. Tx Second-Order Harmonic Distortion (HD2) vs. Frequency







Figure 20. Tx Third-Order Output Intercept Point (OIP3) vs. Tx Attenuation Setting



Figure 21. Tx Signal-to-Noise Ratio (SNR) vs. Tx Attenuation Setting, LTE 10 MHz Signal of Interest with Noise Measured at 90 MHz Offset



2.4 GHZ FREQUENCY BAND





Figure 24. RSSI Error vs. Input Power (Referenced to -50 dBm Input Power at 2.4 GHz)



Figure 25. Rx EVM vs. Interferer Power Level, LTE 20 MHz Signal of Interest with $P_{\rm IN}$ = -75 dBm, LTE 20 MHz Blocker at 20 MHz Offset



Figure 26. Rx EVM vs. Interferer Power Level, LTE 20 MHz Signal of Interest with $P_{\rm IN}$ = -75 dBm, LTE 20 MHz Blocker at 40 MHz Offset



Figure 27. Rx Gain vs. Rx LO Frequency, Gain Index = 76 (Maximum Setting)



Figure 28. Third-Order Input Intercept Point (IIP3) vs. Rx Gain Index, f1 = 30 MHz, f2 = 61 MHz



Figure 29. Second-Order Input Intercept Point (IIP2) vs. Rx Gain Index, f1 = 60 MHz, f2 = 61 MHz



Figure 30. Rx Local Oscillator (LO) Leakage vs. Rx LO Frequency



Figure 31. Rx Emission at LNA Input vs. Frequency, DC to 12 GHz, $f_{LO_{RX}} = 2.4$ GHz, LTE 20 MHz, $f_{LO_{TX}} = 2.46$ GHz



Figure 32. Tx Output Power vs. Tx LO Frequency, Attenuation Setting = 0 dB, Single-Tone Output



Figure 33. Tx Power Control Step Linearity Error vs. Attenuation Setting



Figure 34. Tx Output Power vs. Frequency Offset from Carrier Frequency, $f_{LO_TX} = 2.3$ GHz, LTE 20 MHz Downlink (Digital Attenuation Variations Shown)



Figure 35. Integrated Tx LO Phase Noise vs. Frequency, 40 MHz REF_CLK







Figure 37. Tx Second-Order Harmonic Distortion (HD2) vs. Frequency



Figure 38. Tx Third-Order Harmonic Distortion (HD3) vs. Frequency



Figure 39. Tx Third-Order Output Intercept Point (OIP3) vs. Tx Attenuation Setting



Figure 40. Tx Signal-to-Noise Ratio (SNR) vs. Tx Attenuation Setting, LTE 20 MHz Signal of Interest with Noise Measured at 90 MHz Offset



THEORY OF OPERATION general

The AD9363 is a highly integrated radio frequency (RF) transceiver capable of being configured for a wide range of applications. The device integrates all RF, mixed-signal, and digital blocks necessary to provide all transceiver functions in a single device. Programmability allows this broadband transceiver to be adapted for use with multiple communication standards, including FDD and TDD systems. This programmability also allows the device to interface to various BBPs using a single 12-bit parallel data port, dual 12-bit parallel data ports, or a 12-bit low voltage differential signaling (LVDS) interface.

The AD9363 also provides self calibration and AGC systems to maintain a high performance level under varying temperatures and input signal conditions. In addition, the device includes several test modes that allow system designers to insert test tones and create internal loopback modes to debug their designs during prototyping and optimize their radio configuration for a specific application.

RECEIVER

The receiver section contains all blocks necessary to receive RF signals and convert them to digital data that is usable by a BBP. Two independently controlled channels can receive signals from different sources, allowing the device to be used in multiple input, multiple output (MIMO) systems while sharing a common frequency synthesizer.

Each channel has three inputs that can be multiplexed to the signal chain, making the AD9363 suitable for use in diversity systems with multiple antenna inputs. The receiver is a direct conversion system that contains a low noise amplifier (LNA) followed by matched in-phase (I) and quadrature (Q) amplifiers, mixers, and band shaping filters that downconvert received signals to baseband for digitization. External LNAs can also be interfaced to the device, allowing designers the flexibility to customize the receiver front end for their specific application.

Gain control is achieved by following a preprogrammed gain index map that distributes gain among the blocks for optimal performance at each level. This gain control can be achieved by enabling the internal AGC in either fast or slow mode or by using manual gain control, allowing the BBP to make the gain adjustments as needed. Additionally, each channel contains independent RSSI measurement capability, dc offset tracking, and all circuitry necessary for self calibration.

The receivers include 12-bit, sigma-delta (Σ - Δ) ADCs and adjustable sample rates that produce data streams from the received signals. The digitized signals can be conditioned further by a series of decimation filters and a fully programmable 128-tap FIR filter with additional decimation settings. The sample rate of each digital filter block can also be adjusted by changing the decimation factors to produce the desired output data rate.

TRANSMITTER

The transmitter section consists of two identical and independently controlled channels that provide all digital processing, mixed-signal, and RF blocks necessary to implement a direct conversion system while sharing a common frequency synthesizer. The digital data received from the BBP passes through a fully programmable 128-tap FIR filter with interpolation options. The FIR output is sent to a series of interpolation filters that provide additional filtering and data rate interpolation prior to reaching the DAC. Each 12-bit DAC has an adjustable sampling rate. Both the I and Q channels are fed to the RF block for upconversion.

After being converted to baseband analog signals, the I and Q signals are filtered to remove sampling artifacts and provide band shaping, and then they are passed to the upconversion mixers. At this point, the I and Q signals are recombined and modulated on the carrier frequency for transmission to the output stage. The output stage provides attenuation control that provides a range of output levels while keeping the output impedance at 50 Ω . A wide range of attenuation adjustment with fine granularity is included to help designers optimize SNR.

Self calibration circuitry is included in the transmit channel to provide internal adjustment capability. The transmitter also provides a Tx monitor block that receives the transmitter output and routes it back through an unused receiver channel to the BBP for signal monitoring. The Tx monitor blocks are available only in TDD mode operation while the receiver is idle.

CLOCK INPUT OPTIONS

The AD9363 uses a reference clock provided by an external oscillator or clock distribution device (such as the AD9548) connected to the XTALN pin. The frequency of this reference clock can vary from 10 MHz to 80 MHz. This reference clock supplies the synthesizer blocks that generate all data clocks, sample clocks, and local oscillators inside the device.

SYNTHESIZERS RF PLLs

The AD9363 contains two identical synthesizers to generate the required LO signals for the RF signal paths—one for the receiver and one for the transmitter. PLL synthesizers are fractional N designs that incorporate completely integrated VCOs and loop filters. In TDD mode, the synthesizers turn on and off as appropriate for the Rx and Tx frames. In FDD mode, the Tx PLL and the Rx PLL can be activated at the same time. These PLLs require no external components.

BB PLL

The AD9363 also contains a baseband PLL (BB PLL) synthesizer that generates all baseband related clock signals. These signals include the ADC and DAC sampling clocks, the DATA_CLK signal (see the Digital Data Interface section), and all data framing signals. The BB PLL is programmed from 700 MHz to 1400 MHz based on the data rate and sample rate requirements of the system.

DIGITAL DATA INTERFACE

The AD9363 data interface uses parallel data ports (P0 and P1) to transfer data between the device and the BBP. The data ports can be configured in either single-ended CMOS format or differential LVDS format. Both formats can be configured in multiple arrangements to match system requirements for data ordering and data port connections. These arrangements include single port data bus, dual port data bus, single data rate, double data rate, and various combinations of data ordering to transmit data from different channels across the bus at appropriate times.

Bus transfers are controlled using simple hardware handshake signaling. The two ports can be operated in either bidirectional (TDD) mode or in full duplex (FDD) mode, where half the bits are used for transmitting data and half are used for receiving data. The interface can also be configured to use only one of the data ports for applications that do not require high data rates and require fewer interface pins.

DATA_CLK Signal

The AD9363 outputs the DATA_CLK signal that the BBP uses to sample receiver data. The signal is synchronized with the receiver data such that data transitions occur out of phase with DATA_CLK. The DATA_CLK can be set to a rate that provides single data rate (SDR) timing, where data is sampled on each rising clock edge, or it can be set to provide double data rate (DDR) timing, where data is captured on both rising and falling clock edges. SDR or DDR timing applies to operation using either a single port or both ports.

FB_CLK Signal

For transmit data, the interface uses the FB_CLK signal as the timing reference. The FB_CLK signal allows source synchronous timing with rising edge capture for burst control signals and either rising edge capture (SDR mode) or both edge capture (DDR mode) for transmit signal bursts. The FB_CLK signal must have the same frequency and duty cycle as DATA_CLK.

RX_FRAME and TX_FRAME Signals

The device generates an RX_FRAME output signal whenever the receiver outputs valid data. This signal has two modes: level mode (the RX_FRAME signal stays high as long as the data is valid) and pulse mode (the RX_FRAME signal pulses with a 50% duty cycle). Similarly, the BBP must provide a TX_FRAME signal that indicates the beginning of a valid data transmission with a rising edge. Like the RX_FRAME signal, the TX_FRAME signal stays high throughout the burst or it pulses with a 50% duty cycle.

ENABLE STATE MACHINE

The AD9363 transceiver includes an ENSM that allows realtime control over the current state of the device. The device can be placed in several different states during normal operation, including

- Wait—power save, synthesizers disabled
- Sleep—wait with all clocks and the BB PLL disabled
- Tx—Tx signal chain enabled
- Rx—Rx signal chain enabled
- FDD—Tx and Rx signal chains enabled
- Alert—synthesizers enabled

The ENSM has two control modes: SPI control and pin control.

SPI Control Mode

In SPI control mode, the ENSM is controlled asynchronously by writing to SPI registers to advance the current state to the next state. SPI control is considered asynchronous to the DATA_CLK signal because the SPI clock can be derived from a different clock reference and can still function properly. The SPI control ENSM mode is recommended when real-time control of the synthesizers is not necessary. SPI control can be used for real-time control as long as the BBP can perform timed SPI writes accurately.

Pin Control Mode

In pin control mode, the enable functions of the ENABLE pin and the TXNRX pin allow real-time control of the current state. The ENSM allows TDD or FDD operation, depending on the configuration of the corresponding SPI register. The ENABLE and TXNRX pin control mode is recommended if the BBP has extra control outputs that can be controlled in real time, allowing a simple 2-wire interface to control the state of the device. To advance the current state of the ENSM to the next state, drive the enable function of the ENABLE pin by either a pulse (edge detected internally) or a level.

When a pulse is used, it must have a minimum pulse width of one cycle of the FB_CLK signal. In level mode, the ENABLE and TXNRX pins are also edge detected by the AD9363 and must meet the same minimum pulse width requirement of one cycle of the FB_CLK signal.

In FDD mode, the ENABLE and TXNRX pins can be remapped to serve as real-time Rx and Tx data transfer control signals. In this mode, the ENABLE pin assumes the receive on (RXON) function (controls when the Rx path is enabled and disabled), and the TXNRX pin assumes the transmit on (TXON) function (controls when the Tx path is enabled and disabled). The ENSM must be controlled by SPI writes in this mode while the ENABLE and TXNRX pins control all data flow. For more information about RXON and TXON, see the AD9363 reference manual, available from Integrated Wideband RF Transceiver Design Resources.

SPI INTERFACE

The AD9363 uses a serial peripheral interface (SPI) to communicate with the BBP. The SPI can be configured as a 4-wire interface with dedicated receive and transmit ports, or it can be configured as a 3-wire interface with a bidirectional data communication port. This bus allows the BBP to set all device control parameters using a simple address data serial bus protocol.

Write commands follow a 24-bit format. The first six bits set the bus direction and number of bytes to transfer. The next 10 bits set the address where data is to be written. The final eight bits are the data to be transferred to the specified register address (MSB to LSB). The AD9363 also supports an LSB first format that allows the commands to be written in LSB to MSB format. In this mode, the register addresses are incremented for multibyte writes.

Read commands follow a similar format with the exception that the first 16 bits are transferred on the SPI_DI pin, and the final eight bits are read from the AD9363, either on the SPI_DO pin in 4-wire mode or on the SPI_DI pin in 3-wire mode.

CONTROL PINS

Control Outputs (CTRL_OUT7 to CTRL_OUT0)

The AD9363 provides eight simultaneous real-time output signals for use as interrupts to the BBP. These outputs can be configured to output a number of internal settings and measurements that the BBP uses when monitoring trans-ceiver performance in different situations. The control output pointer register selects the information that is output to these pins, and the control output enable register determines which signals are activated for monitoring by the BBP. Signals used for manual gain mode, calibration flags, state machine states, and the ADC output are among the outputs that can be monitored on these pins.

Control Inputs (CTRL_IN3 to CTRL_IN0)

The AD9363 provides four edge detected control input pins. In manual gain mode, the BBP uses these pins to change the gain table index in real time.

GPO PINS (GPO_3 TO GPO_0)

The AD9363 provides four 3.3 V capable general-purpose logic output pins: GPO_3, GPO_2, GPO_1, and GPO_0. These pins control other peripheral devices such as regulators and switches via the AD9363 SPI bus, or they function as slaves for the internal AD9363 state machine.

AUXILIARY CONVERTERS

AUXADC

The AD9363 contains an auxiliary ADC that monitors system functions such as temperature or power output. The converter is 12 bits wide and has an input range of 0.05 V to VDDA1P3_BB – 0.05 V. When enabled, the ADC is free running. SPI reads provide the last value latched at the ADC output. A multiplexer in front of the ADC allows the user to select between the AUXADC input pin and a built-in temperature sensor.

AUXDAC1 and AUXDAC2

The AD9363 contains two identical auxiliary DACs that can provide power amplifier (PA) bias or other system functionality. The auxiliary DACs are 10 bits wide, have an output voltage range of 0.5 V to VDD_GPO – 0.3 V and a current drive of 10 mA, and can be directly controlled by the internal ENSM.

POWERING THE AD9363

The AD9363 must be powered by the following three supplies: the analog supply (VDDx = 1.3 V), the interface supply (VDD_ INTERFACE = 1.8 V), and the GPO supply (VDD_GPO = 3.3 V).

For applications requiring optimal noise performance, split and source the 1.3 V analog supply from low noise, low dropout (LDO) regulators. Figure 42 shows the recommended method.



Figure 42. Low Noise Power Solution for the AD9363

For applications where board space is at a premium, and optimal noise performance is not an absolute requirement, provide the 1.3 V analog rail directly from a switcher, and adopt a more integrated power management unit (PMU) approach. Figure 43 shows this approach.



Figure 43. Space Optimized Power Solution for the AD9363

APPLICATIONS INFORMATION

For additional information about how to program the AD9363 device, see the AD9363 reference manual, and for additional information about the AD9363 registers, see the AD9363 register map reference manual, both of which are available by registering at the Integrated Wideband RF Transceiver Design Resources web page and clicking **Download the AD9363 Design File Package**. The register map is provided as a convenient and informational resource about low level operation of the device; however, it is not recommended for creating user software. Analog Devices, Inc., provides complete drivers for the AD9363 for both bare metal/no operating system (no OS) and Linux operating systems. The AD9361, AD9363, and AD9364 share the same application program interface (API). For the AD9361 drivers, visit the following online locations:

- Linux wiki page
- No OS wiki page

For support for these drivers, visit the following online locations:

- Linux Engineer Zone[®] page
- No OS Engineer Zone page

PACKAGING AND ORDERING INFORMATION

OUTLINE DIMENSIONS



Figure 44. 144-Ball Chip Scale Package Ball Grid Array [CSP_BGA] (BC-144-7) Dimensions shown in millimeters

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option
AD9363ABCZ	-40°C to +85°C	144-Ball Chip Scale Package Ball Grid Array [CSP_BGA]	BC-144-7
AD9363ABCZ-REEL	-40°C to +85°C	144-Ball Chip Scale Package Ball Grid Array [CSP_BGA]	BC-144-7
ADRV9363-W/PCBZ		Evaluation Board, 325 MHz to 3800 MHz Matching Circuits	

 1 Z = RoHS Compliant Part.



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