General Description

The 9ZX21901 is Intel DB1900Z Differential Buffer suitable for PCI-Express Gen3 or QPI applications. The part is backwards compatible to PCIe Gen1 and Gen2. A fixed external feedback maintains low drift for critical QPI applications. In bypass mode, the 9ZX21901 can provide outputs up to 400MHz.

Recommended Application

• 19-output PCIe Gen3/QPI buffer with fixed feedback for Romley platforms

Output Features

• 19 – 0.7V current mode differential HCSL output pairs

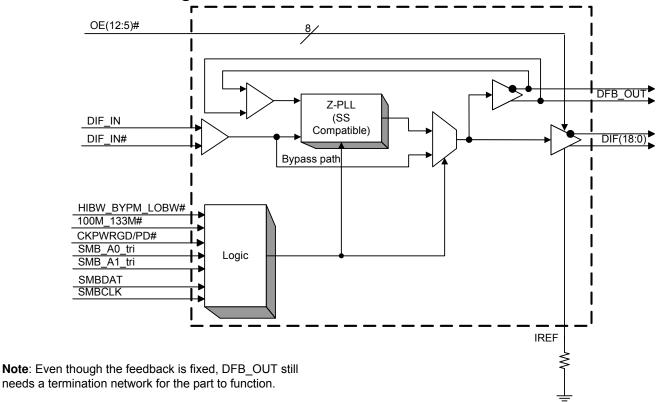
Key Specifications

- Cycle-to-cycle jitter: < 50ps
- Output-to-output skew: <65ps
- Input-to-output delay: Fixed at 0 ps
- Input-to-output delay variation: <50ps
- Phase jitter: PCIe Gen3 < 1ps rms
- Phase jitter: QPI 9.6GB/s < 0.2ps rms

Features/Benefits

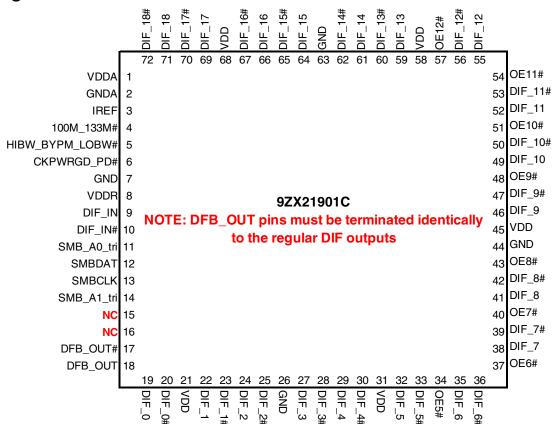
- Fixed feedback path/ 0ps input-to-output delay
- 9 Selectable SMBus addresses; Multiple devices can share same SMBus segment
- 8 dedicated OE# pins; hardware control of outputs
- · PLL or bypass mode; PLL can dejitter incoming clock
- Selectable PLL BW; minimizes jitter peaking in downstream PLL's
- Spread spectrum compatible; tracks spreading input clock for EMI reduction
- SMBus Interface; unused outputs can be disabled
- 100MHz & 133.33MHz PLL mode; legacy QPI support
- · Undriven differential outputs in Power Down mode for maximum power savings

Functional Block Diagram





Pin Configuration



72-pin VFQFPN

Functionality at Power Up (PLL Mode)

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100M_133M#	DIF_IN (MHz)	DIF_x (MHz)						
1	100.00	DIF_IN						
0	133.33	DIF_IN						

PLL Operating Mode Readback Table

HiBW_BypM_LoBW#	Byte0, bit 7	Byte 0, bit 6					
Low (Low BW)	0	0					
Mid (Bypass)	0	1					
High (High BW)	1	1					

PLL Operating Mode

HiBW_BypM_LoBW#	MODE
Low	PLL Lo BW
Mid	Bypass
High	PLL Hi BW

NOTE: PLL is OFF in Bypass Mode

Tri-level Input Thresholds

Level	Voltage
Low	<0.8V
Mid	1.2 <vin<1.8v< td=""></vin<1.8v<>
High	Vin > 2.2V

Power Connections

Pin Number		
VDD	GND	Description
1	2	Analog PLL
8	7	Analog Input
21, 31, 45, 58, 68	26, 44, 63	DIF clocks

9ZX21901 SMBus Addressing

CEXETOO! CHIEGO Radioconing						
Pi	n	SMBus Address				
SMB_A1_tri	(Rd/Wrt bit = 0)					
0	0	D8				
0	М	DA				
0	1	DE				
М	0	C2				
M	М	C4				
М	1	C6				
1	0	CA				
1	М	CC				
1	1	CE				



Pin Descriptions

PIN#	PIN NAME	PIN TYPE	DESCRIPTION
1	VDDA	PWR	3.3V power for the PLL core.
2	GNDA	GND	Ground pin for the PLL core.
3	IREF	OUT	This pin establishes the reference for the differential current-mode output pairs. It requires a fixed precision resistor to ground. 4750hm is the standard value for 1000hm differential impedance. Other impedances require different values. See data sheet.
4	100M_133M#	IN	Input to select operating frequency 1 = 100MHz, 0 = 133.33MHz
5	HIBW_BYPM_LOBW#	IN	Trilevel input to select High BW, Bypass or Low BW mode. See PLL Operating Mode Table for Details.
6	CKPWRGD_PD#	IN	3.3V Input notifies device to sample latched inputs and start up on first high assertion, or exit Power Down Mode on subsequent assertions. Low enters Power Down Mode.
7	GND	GND	Ground pin.
8	VDDR	PWR	3.3V power for differential input clock (receiver). This VDD should be treated as an analog power rail and filtered appropriately.
9	DIF_IN	IN	0.7 V Differential True input
10	DIF_IN#	IN	0.7 V Differential Complementary Input
11	SMB_A0_tri	IN	SMBus address bit. This is a tri-level input that works in conjunction with the SMB_A1 to decode 1 of 9 SMBus Addresses.
12	SMBDAT	I/O	Data pin of SMBUS circuitry, 5V tolerant
13	SMBCLK	IN	Clock pin of SMBUS circuitry, 5V tolerant
14	SMB_A1_tri	IN	SMBus address bit. This is a tri-level input that works in conjunction with the SMB_A0 to decode 1 of 9 SMBus Addresses.
15	NC	N/A	No Connection.
16	NC	N/A	No Connection.
17	DFB_OUT#	OUT	Complementary half of differential feedback output, provides feedback signal to the PLL for synchronization with input clock to eliminate phase error.
18	DFB_OUT	OUT	True half of differential feedback output, provides feedback signal to the PLL for synchronization with the input clock to eliminate phase error.
19	DIF_0	OUT	0.7V differential true clock output
20	 DIF_0#	OUT	0.7V differential Complementary clock output
21	VDD	PWR	Power supply, nominal 3.3V
22	DIF_1	OUT	0.7V differential true clock output
23	DIF_1#	OUT	0.7V differential Complementary clock output
24	DIF_2	OUT	0.7V differential true clock output
25	DIF_2#	OUT	0.7V differential Complementary clock output
26	GND	GND	Ground pin.
27	DIF_3	OUT	0.7V differential true clock output
28	DIF_3#	OUT	0.7V differential Complementary clock output
29	DIF_4	OUT	0.7V differential true clock output
30	DIF_4#	OUT	0.7V differential Complementary clock output
31	VDD	PWR	Power supply, nominal 3.3V
32	DIF_5	OUT	0.7V differential true clock output
33	DIF_5#	OUT	0.7V differential Complementary clock output
34	OE5#	IN	Active low input for enabling DIF pair 5. 1 =disable outputs, 0 = enable outputs
35	DIF_6	OUT	0.7V differential true clock output
36	DIF_6#	OUT	0.7V differential Complementary clock output



Pin Descriptions (cont.)

PIN#	PIN NAME	PIN TYPE	DESCRIPTION
37	OE6#	IN	Active low input for enabling DIF pair 6.
37	UE0#	IIN	1 =disable outputs, 0 = enable outputs
38	DIF_7	OUT	0.7V differential true clock output
39	DIF_7#	OUT	0.7V differential Complementary clock output
40	OE7#	IN	Active low input for enabling DIF pair 7.
40			1 =disable outputs, 0 = enable outputs
41	DIF_8	OUT	0.7V differential true clock output
42	DIF_8#	OUT	0.7V differential Complementary clock output
43	OE8#	IN	Active low input for enabling DIF pair 8.
			1 =disable outputs, 0 = enable outputs
44	GND	GND	Ground pin.
45	VDD	PWR	Power supply, nominal 3.3V
46	DIF_9	OUT	0.7V differential true clock output
47	DIF_9#	OUT	0.7V differential Complementary clock output
48	OE9#	IN	Active low input for enabling DIF pair 9.
			1 =disable outputs, 0 = enable outputs
49	DIF_10	OUT	0.7V differential true clock output
50	DIF_10#	OUT	0.7V differential Complementary clock output
51	OE10#	IN	Active low input for enabling DIF pair 10.
			1 =disable outputs, 0 = enable outputs
52	DIF_11	OUT	0.7V differential true clock output
53	DIF_11#	OUT	0.7V differential Complementary clock output
54	OE11#	IN	Active low input for enabling DIF pair 11.
		OUT.	1 =disable outputs, 0 = enable outputs
55	DIF_12	OUT	0.7V differential true clock output
56	DIF_12#	OUT	0.7V differential Complementary clock output
57	OE12#	IN	Active low input for enabling DIF pair 12.
	VDD	DWD	1 =disable outputs, 0 = enable outputs
58	VDD	PWR	Power supply, nominal 3.3V
59	DIF_13	OUT	0.7V differential true clock output
60 61	DIF_13# DIF_14	OUT	0.7V differential Complementary clock output
62		OUT	0.7V differential true clock output
63	DIF_14# GND	GND	0.7V differential Complementary clock output Ground pin.
64	DIF_15	OUT	0.7V differential true clock output
65	DIF_15 DIF_15#	OUT	0.7V differential true clock output 0.7V differential Complementary clock output
66	DIF_15#	OUT	0.7V differential Complementary clock output
67	DIF_16#	OUT	0.7V differential tide clock output 0.7V differential Complementary clock output
68	VDD	PWR	Power supply, nominal 3.3V
69	DIF_17	OUT	0.7V differential true clock output
70	DIF_17#	OUT	0.7V differential Gook output
71	DIF_18	OUT	0.7V differential complementary clock output
72	DIF_18#	OUT	0.7V differential Complementary clock output



Electrical Characteristics – Absolute Maximum Ratings

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
3.3V Core Supply Voltage	VDDA				4.6	V	1,2
3.3V Logic Supply Voltage	VDD				4.6	٧	1,2
Input Low Voltage	V_{IL}		GND-0.5			٧	1
Input High Voltage	V_{IH}	Except for SMBus interface			V _{DD} +0.5V	V	1
Input High Voltage	V_{IHSMB}	SMBus clock and data pins			5.5V	٧	1
Storage Temperature	Ts		-65		150	°C	1
Junction Temperature	Tj				125	°C	1
Case Temperature	Tc				110	°C	1
Input ESD protection	ESD prot	Human Body Model	2000			V	1

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics – DIF_IN Clock Input Parameters

T_{AMB}=T_{COM} unless otherwise indicated, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

		11 7 0 1					
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input Crossover Voltage - DIF_IN	V _{CROSS}	Cross Over Voltage	150		900	mV	1
Input Swing - DIF_IN	V_{SWING}	Differential value	300			mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.4		8	V/ns	1,2
Input Leakage Current	I _{IN}	$V_{IN} = V_{DD}$, $V_{IN} = GND$	-5		5	uA	
Input Duty Cycle	d _{tin}	Measurement from differential wavefrom	45		55	%	1
Input Jitter - Cycle to Cycle	J_{DIFIn}	Differential Measurement	0		125	ps	1

¹ Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics – Current Consumption

 $TA = T_{COM}$; Supply Voltage VDD/VDDA = 3.3 V +/-5%, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Operating Supply Current	I _{DD3.3OP}	All outputs active @100MHz, C _L = Full load;		407	500	mA	1
Powerdown Current	I _{DD3.3PDZ}	All differential pairs tri-stated		12	36	mA	1

¹Guaranteed by design and characterization, not 100% tested in production.

² Operation under these conditions is neither implied nor guaranteed.

²Slew rate measured through +/-75mV window centered around differential zero



Electrical Characteristics – Input/Supply/Common Parameters

TA = T_{COM}; Supply Voltage VDD/VDDA = 3.3 V +/-5%, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Ambient Operating Temperature	T _{COM}	Commmercial range	0		70	°C	1
Input High Voltage	V _{IH}	Single-ended inputs, except SMBus, low threshold and tri-level inputs	2		V _{DD} + 0.3	٧	1
Input Low Voltage	V_{IL}	Single-ended inputs, except SMBus, low threshold and tri-level inputs	GND - 0.3		0.8	>	1
	I _{IN}	Single-ended inputs, $V_{IN} = GND$, $V_{IN} = VDD$	-5		5	uA	1
Input Current	I _{INP}	$\label{eq:single-ended} Single-ended inputs \\ V_{IN} = 0 \ V; \ Inputs \ with internal \ pull-up \ resistors \\ V_{IN} = \ VDD; \ Inputs \ with \ internal \ pull-down \ resistors \\$	-200		200	uA	1
	F_{ibyp}	V _{DD} = 3.3 V, Bypass mode	33		400	MHz	2
Input Frequency	F _{ipII}	$V_{DD} = 3.3 \text{ V}, 100\text{MHz PLL mode}$	90	100.00	105	MHz	2
	F_{ipII}	$V_{DD} = 3.3 \text{ V}, 133.33 \text{MHz PLL mode}$	120	133.33	140	MHz	2
Pin Inductance	L_{pin}				7	nΗ	1
	C_{IN}	Logic Inputs, except DIF_IN	1.5		5	pF	1
Capacitance	C _{INDIF_IN}	DIF_IN differential clock inputs	1.5		2.7	pF	1,4
	C_{OUT}	Output pin capacitance			6	pF	1
Clk Stabilization	T _{STAB}	From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock			1.8	ms	1,2
Input SS Modulation Frequency	f _{MODIN}	Allowable Frequency (Triangular Modulation)	30		33	kHz	1
OE# Latency	t _{LATOE#}	DIF start after OE# assertion DIF stop after OE# deassertion	4		12	clocks	1,3
Tdrive_PD#	t _{DRVPD}	DIF output enable after PD# de-assertion			300	us	1,3
Tfall	t _F	Fall time of control inputs			5	ns	1,2
Trise	t _R	Rise time of control inputs			5	ns	1,2
SMBus Input Low Voltage	V_{ILSMB}				0.8	V	1
SMBus Input High Voltage	V_{IHSMB}		2.1		V_{DDSMB}	V	1
SMBus Output Low Voltage	V_{OLSMB}	@ I _{PULLUP}			0.4	V	1
SMBus Sink Current	I _{PULLUP}	@ V _{OL}	4			mA	1
Nominal Bus Voltage	$V_{\rm DDSMB}$	3V to 5V +/- 10%	2.7		5.5	V	1
SCLK/SDATA Rise Time	t _{RSMB}	(Max VIL - 0.15) to (Min VIH + 0.15)			1000	ns	1
SCLK/SDATA Fall Time	t _{FSMB}	(Min VIH + 0.15) to (Max VIL - 0.15)			300	ns	1
SMBus Operating Frequency	f _{MAXSMB}	Maximum SMBus operating frequency			100	kHz	1,5

¹Guaranteed by design and characterization, not 100% tested in production.

²Control input must be monotonic from 20% to 80% of input swing.

³Time from deassertion until outputs are >200 mV

⁴ DIF_IN input

⁵The differential input clock must be running for the SMBus to be active



Electrical Characteristics – DIF 0.7V Current Mode Differential Outputs

TA = T_{COM}: Supply Voltage VDD/VDDA = 3.3 V +/-5%, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate	dV/dt	Scope averaging on	1	2.5	4	V/ns	1, 2, 3
Slew rate matching	∆dV/dt	Slew rate matching, Scope averaging on			20	%	1, 2, 4
Rise/Fall Time Matching	ΔTrf	Rise/fall matching, Scope averaging off			125	ps	1, 7, 8
Voltage High	VHigh	Statistical measurement on single-ended signal using oscilloscope math function. (Scope	660	750	850	mV	1
Voltage Low	VLow	averaging on)	-150		150		1
Max Voltage	Vmax	Measurement on single ended signal using			1150	mV	1
Min Voltage	Vmin	absolute value. (Scope averaging off)	-300			IIIV	1
Vswing	Vswing	Scope averaging off	300			mV	1, 2
Crossing Voltage (abs)	Vcross_abs	Scope averaging off	250		550	mV	1, 5
Crossing Voltage (var)	Δ-Vcross	Scope averaging off			140	mV	1, 6

 $^{^{1}}$ Guaranteed by design and characterization, not 100% tested in production. IREF = VDD/(3xR_R). For R_R = 475Ω (1%), I_{REF} = 2.32mA. I_{OH} = 6 x I_{REF} and V_{OH} = 0.7V @ Z_O=50Ω (100Ω differential impedance).

² Measured from differential waveform

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

⁴ Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

⁵ Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

⁶ The total variation of all Vcross measurements in any particular system. Note that this is a subset of V_cross_min/max (V_cross absolute) allowed. The intent is to limit Vcross induced modulation by setting V_cross_delta to be smaller than V_cross absolute.

⁷ Measured from single-ended waveform

⁸ Measured with scope averaging off, using statistics function. Variation is difference between min and max.



Electrical Characteristics – Skew and Differential Jitter Parameters

TA = T_{COM}: Supply Voltage VDD/VDDA = 3.3 V +/-5%, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
CLK_IN, DIF[x:0]	t _{SPO_PLL}	Input-to-Output Skew in PLL mode nominal value @ 25°C, 3.3V	-100	0	100	ps	1,2,4,5,8
CLK_IN, DIF[x:0]	t _{PD_BYP}	Input-to-Output Skew in Bypass mode nominal value @ 25°C, 3.3V	2.5	3.5	4.5	ns	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DSPO_PLL}	Input-to-Output Skew Varation in PLL mode across voltage and temperature	-50	0	50	ps	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DSPO_BYP}	Input-to-Output Skew Varation in Bypass mode across voltage and temperature	-250		250	ps	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DTE}	Random Differential Tracking error beween two 9ZX devices in Hi BW Mode		3	5	ps (rms)	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DSSTE}	Random Differential Spread Spectrum Tracking error beween two 9ZX devices in Hi BW Mode		15	75	ps	1,2,3,5,8
DIF{x:0]	t _{SKEW_ALL}	Output-to-Output Skew across all outputs (Common to Bypass and PLL mode)		37	65	ps	1,2,3,8
PLL Jitter Peaking	j _{peak-hibw}	LOBW#_BYPASS_HIBW = 1	0	1.3	2.5	dB	7,8
PLL Jitter Peaking	j _{peak-lobw}	LOBW#_BYPASS_HIBW = 0	0	0.8	2	dB	7,8
PLL Bandwidth	pll _{HIBW}	LOBW#_BYPASS_HIBW = 1	2	3	4	MHz	8,9
PLL Bandwidth	pll_LOBW	LOBW#_BYPASS_HIBW = 0	0.7	1.1	1.4	MHz	8,9
Duty Cycle	t _{DC}	Measured differentially, PLL Mode	45	50	55	%	1
Duty Cycle Distortion	t _{DCD}	Measured differentially, Bypass Mode @100MHz	-2	0	2	%	1,10
Jitter, Cycle to cycle	t	PLL mode		41	50	ps	1,11
Notes for preceding table.	t _{jcyc-cyc}	Additive Jitter in Bypass Mode		20	50	ps	1,11

Notes for preceding table:

¹ Measured into fixed 2 pF load cap. Input to output skew is measured at the first output edge following the corresponding input.

² Measured from differential cross-point to differential cross-point. This parameter can be tuned with external feedback path, if present.

³ All Bypass Mode Input-to-Output specs refer to the timing between an input edge and the specific output edge created by it.

⁴ This parameter is deterministic for a given device

⁵ Measured with scope averaging on to find mean value. DIF_IN slew rate must be matched to DIF output slew rate.

⁶.t is the period of the input clock

⁷ Measured as maximum pass band gain. At frequencies within the loop BW, highest point of magnification is called PLL jitter peaking.

^{8.} Guaranteed by design and characterization, not 100% tested in production.

⁹ Measured at 3 db down or half power point.

¹⁰ Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.

¹¹ Measured from differential waveform



Electrical Characteristics – Phase Jitter Parameters

TA = T_{COM}; Supply Voltage VDD/VDDA = 3.3 V +/-5%, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	Notes
	t _{jphPCleG1}	PCIe Gen 1		39	86	ps (p-p)	1,2,3
		PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		1.1	3	ps (rms)	1,2
	t _{jphPCleG2}	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		2.6	3.1	ps (rms)	1,2
Jitter, Phase	t _{jphPCleG3}	PCIe Gen 3 (PLL BW of 2-4MHz, CDR = 10MHz)		0.6	1	ps (rms)	1,2,4
		QPI & SMI (100MHz or 133MHz, 4.8Gb/s, 6.4Gb/s 12UI)		0.36	0.5	ps (rms)	1,5
	t _{jphQPI_SMI}	QPI & SMI (100MHz, 8.0Gb/s, 12UI)		0.23	0.3	ps (rms)	1,5
		QPI & SMI (100MHz, 9.6Gb/s, 12UI)		0.18	0.2	ps (rms)	1,5
	t _{jphPCleG1}	PCIe Gen 1		4	10	ps (p-p)	1,2,3
		PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.25	0.3	ps (rms)	1,2,6
	t _{jphPCleG2}	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		0.57	0.7	ps (rms)	1,2,6
Additive Phase Jitter, Bypass mode	t _{jphPCleG3}	PCIe Gen 3 (PLL BW of 2-4MHz, CDR = 10MHz)		0.20	0.3	ps (rms)	1,2,4,6
Dypaco mode	t _{jphQPI_} SMI	QPI & SMI (100MHz or 133MHz, 4.8Gb/s, 6.4Gb/s 12UI)		0.22	0.3	ps (rms)	1,5,6
		QPI & SMI (100MHz, 8.0Gb/s, 12UI)		0.08	0.1	ps (rms)	1,5,6
		QPI & SMI (100MHz, 9.6Gb/s, 12UI)		0.08	0.1	ps (rms)	1,5,6

¹ Applies to all outputs.

Power Management Table

Inputs		Control Bits/Pins			5		
CKPWRGD_PD#	DIF_IN/ DIF_IN#	SMBus EN bit	OE# Pin	DIF(5:12)/ Other DIF/ DFB_OUT/ DIF(5:12)# DIF# DFB_OUT#		PLL State	
0	Х	Х	Х	Hi-Z ¹	Hi-Z ¹	Hi-Z ¹	OFF
		0	Х	Hi-Z ¹	Hi-Z ¹	Running	ON
1	Running	1	0	Running	Running	Running	ON
		1	1	Hi-Z ¹	Running	Running	ON

NOTE: 1. Due to external pull down resistors, HI-Z results in Low/Low on the True/Complement outputs

² See http://www.pcisig.com for complete specs

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

⁴ Subject to final radification by PCI SIG.

⁵ Calculated from Intel-supplied Clock Jitter Tool v 1.6.3

⁶ For RMS figures, additive jitter is calculated by solving the following equation: (Additive jitter)² = (total jitter)² - (input jitter)²



Clock Periods – Differential Outputs with Spread Spectrum Disabled

			Measurement Window							
SSC OFF	Center Freq. MHz	1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock		
		-c2c jitter AbsPer Min	-SSC Short-Term Average Min	- ppm Long-Term Average Min	0 ppm Period Nominal	+ ppm Long-Term Average Max	+SSC Short-Term Average Max	+c2c jitter AbsPer Max	Units	Notes
DIF	100.00	9.94900		9.99900	10.00000	10.00100		10.05100	ns	1,2,3
DIF	133.33	7.44925		7.49925	7.50000	7.50075		7.55075	ns	1,2,4

Clock Periods - Differential Outputs with Spread Spectrum Enabled

	Measurement Window									
SSC ON	Center Freq. MHz	1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock		
		-c2c jitter AbsPer Min	-SSC Short-Term Average Min	- ppm Long-Term Average Min	0 ppm Period Nominal	+ ppm Long-Term Average Max	+SSC Short-Term Average Max	+c2c jitter AbsPer Max	Units	Notes
DIF	99.75	9.94906	9.99906	10.02406	10.02506	10.02607	10.05107	10.10107	ns	1,2,3
DIF	133.00	7.44930	7.49930	7.51805	7.51880	7.51955	7.53830	7.58830	ns	1,2,4

Notes:

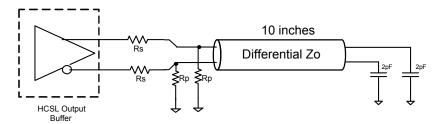
Thermal Characteristics

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Units
Thermal Resistance Junction to Ambient	θЈА	Still air		26.2		°C/W
	θЈА	1 m/s air flow		23.1		°C/W
	θЈА	3 m/s air flow		19.6		°C/W
Thermal Resistance Junction to Case	θЈС			10.4		°C/W
Thermal Resistance Junction to Board	θЈВ			0.3		°C/W

Differential Output Termination Table

DIF Zo (Ω)	Iref (Ω)	Rs (Ω)	Rp (Ω)
100	475	33	50
85	412	27	42.2 or 43.2

9ZX21901 Differential Test Loads



¹Guaranteed by design and characterization, not 100% tested in production.

² All Long Term Accuracy specifications are guaranteed with the assumption that the input clock complies with CK420BQ/CK410B+ accuracy requirements (+/-100ppm). The 96Z61027 itself does not contribute to ppm error.

³ Driven by SRC output of main clock, 100 MHz PLL Mode or Bypass mode

⁴ Driven by CPU output of main clock, 133 MHz PLL Mode or Bypass mode



General SMBus Serial Interface Information (see also 9ZX21901 SMBus Addressing on page 2)

How to Write

- Controller (host) sends a start bit
- Controller (host) sends the write address XX_(H)
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) sends the byte count = X
- IDT clock will acknowledge
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will acknowledge each byte one at a time
- · Controller (host) sends a Stop bit

	Index BI	ock W	/rite Operation
Control	ler (Host)		IDT (Slave/Receiver)
Т	starT bit		
Slave	Address		
WR	WRite		
			ACK
Beginnin	g Byte = N		
			ACK
Data Byte	Count = X		
			ACK
Beginnir	ng Byte N		
			ACK
0		$ \times $	
0		X Byte	0
0		Ф	0
			0
Byte N	I + X - 1		
			ACK
Р	stoP bit		

Note: XX_(H) is defined by SMBus Address select pins.

How to Read

- Controller (host) will send a start bit
- Controller (host) sends the write address XX(H)
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) will send a separate start bit
- Controller (host) sends the read address YY(H)
- IDT clock will acknowledge
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends Byte 0 through Byte X (if X_(H) was written to Byte 8)
- · Controller (host) will need to acknowledge each byte
- · Controller (host) will send a not acknowledge bit
- · Controller (host) will send a stop bit

	Index Block F	Read O	peration
Coi	ntroller (Host)		IDT (Slave/Receiver)
Т	starT bit		
S	ave Address		
WR	WRite		
			ACK
Beg	nning Byte = N		
			ACK
RT	Repeat starT		
SI	ave Address		
RD	ReaD		
			ACK
			Data Byte Count=X
	ACK		
			Beginning Byte N
	ACK		
		ē	0
	0	X Byte	0
	0	×	0
0			
	_		Byte N + X - 1
N	Not acknowledge		
Р	stoP bit		



SMBusTable: PLL Mode, and Frequency Select Register

Byte	0 Pin#	Name	Control Function	Type	0	1	Default
Bit 7	5	PLL Mode 1	PLL Operating Mode Rd back 1	R	See PLL Operating Mode		Latch
Bit 6	5	PLL Mode 0	PLL Operating Mode Rd back 0	R Readback Table		ck Table	Latch
Bit 5	72/71	DIF_18_En	Output Control overrides OE# pin	RW	Hi-Z	Enable	1
Bit 4	70/69	DIF_17_En	Output Control overrides OE# pin	RW	Hi-Z	Enable	1
Bit 3	67/66	DIF_16_En	Output Control overrides OE# pin	RW	Hi-Z	Enable	1
Bit 2			Reserved				0
Bit 1		Reserved					
Bit 0	4	100M 133M#	Frequency Select Readback	R	133MHz	100MHz	Latch

SMBusTable: Output Control Register

Byte	1 Pin#	Name	Control Function	Type	0	1	Default
Bit 7	39/38	DIF_7_En	Output Control overrides OE# pin	RW			1
Bit 6	35/36	DIF_6_En	Output Control overrides OE# pin	RW			1
Bit 5	32/33	DIF_5_En	Output Control overrides OE# pin	RW		Enable	1
Bit 4	29/30	DIF_4_En	Output Control overrides OE# pin	RW	Hi-Z		1
Bit 3	27/28	DIF_3_En	Output Control overrides OE# pin	RW	□ -∠	Enable	1
Bit 2	24/25	DIF_2_En	Output Control overrides OE# pin	RW			1
Bit 1	22/23	DIF_1_En	Output Control overrides OE# pin	RW			1
Bit 0	19/20	DIF_0_En	Output Control overrides OE# pin	RW			1

SMBusTable: Output Control Register

Byte	2 Pin #	Name	Control Function	Type	0	1	Default
Bit 7	65/64	DIF_15_En	Output Control overrides OE# pin	RW			1
Bit 6	6 62/61 DIF 14 En		Output Control overrides OE# pin	RW			1
Bit 5	60/59	DIF_13_En	Output Control overrides OE# pin	RW			1
Bit 4	56/55 DIF_12_En		Output Control overrides OE# pin	RW	Hi-Z	Enable	1
Bit 3	53/52	DIF_11_En	Output Control overrides OE# pin	RW] '"-2	Lilable	1
Bit 2	50/49	DIF_10_En	Output Control overrides OE# pin	RW			1
Bit 1	47/46 DIF_9_En		Output Control overrides OE# pin	RW			1
Bit 0	42/41	DIF_8_En	Output Control overrides OE# pin	RW	Ī		1

SMBusTable: Output Enable Pin Status Readback Register

Byte	93 Pin #			Type	0	1	Default
Bit 7	57	OE_RB12	Real Time readback of OE#12	R			Real time
Bit 6	54	OE_RB11	Real Time readback of OE#11	R			Real time
Bit 5	51	OE_RB10	Real Time readback of OE#10	R			Real time
Bit 4	48	OE_RB9	Real Time readback of OE#9	R	OE# pin Low	OE# Pin High	Real time
Bit 3	43	OE_RB8	Real Time readback of OE#8	R	OE# pill Low		Real time
Bit 2	40	OE_RB7	Real Time readback of OE#7	R			Real time
Bit 1	37	OE_RB6	Real Time readback of OE#6	R			Real time
Bit 0	34	OE_RB5	Real Time readback of OE#5	R			Real time

SMBusTable: Reserved Register

Byte	e 4	Pin #	Name	Control Function	Type	0	1	Default		
Bit 7			Reserved							
Bit 6				Reserved						
Bit 5			Reserved							
Bit 4			Reserved							
Bit 3				Reserved				0		
Bit 2			Reserved							
Bit 1			Reserved							
Bit 0			Reserved							



SMBusTable: Vendor & Revision ID Register

Byte 5 Pin #		Name	Control Function	Type	0	1	Default
Bit 7	-	RID3		R			X
Bit 6	-	RID2	REVISION ID	R	B rev	= 0001	Х
Bit 5	-	RID1	NEVISION ID	R	C Rev	= 0010	Х
Bit 4	-	RID0		R			X
Bit 3	-	VID3		R	-	-	0
Bit 2	-	VID2	VENDOR ID	R	-	-	0
Bit 1	-	VID1	VENDOR ID	R	-	-	0
Bit 0	-	VID0		R	-	-	1

SMBusTable: DEVICE ID

Byte 6 Pin # Name		Name	Control Function	Туре	0	1	Default
Bit 7	-	De	Device ID 7 (MSB)				1
Bit 6	-		Device ID 6	R			1
Bit 5	-		Device ID 5]		0
Bit 4	-	Device ID 4		R	Device ID is 219 decimal or		1
Bit 3	-		Device ID 3		DB	hex.	1
Bit 2	-		Device ID 2				0
Bit 1	-	Device ID 1		R			1
Bit 0	-		Device ID 0	R			1

SMBusTable: Byte Count Register

Byte	te 7 Pin # Name		Control Function	Type	0	1	Default	
Bit 7			Reserved	Reserved				
Bit 6			Reserved					
Bit 5		Reserved						
Bit 4	-	BC4		RW			0	
Bit 3	-	BC3	Writing to this register configures how	RW	Default value	is 8 hex, so 9	1	
Bit 2	-	BC2	many bytes will be read back.	RW	bytes (0 to 8) w	ill be read back	0	
Bit 1	-	BC1	many bytes will be read back.	RW	by de	efault.	0	
Bit 0	-	BC0		RW			0	

SMBusTable: Reserved Register

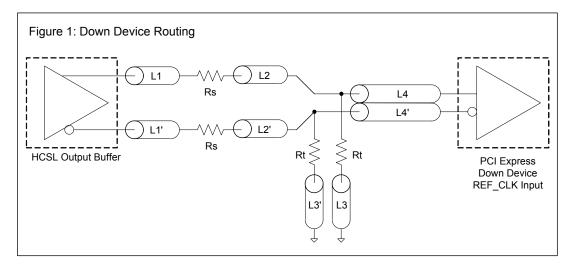
Byte 8	Byte 8 Pin # Name		Control Function	Type	0	1	Default		
Bit 7		Reserved							
Bit 6			Reserved				0		
Bit 5			Reserved						
Bit 4		Reserved							
Bit 3			Reserved				0		
Bit 2		Reserved							
Bit 1		Reserved							
Bit 0		Reserved							

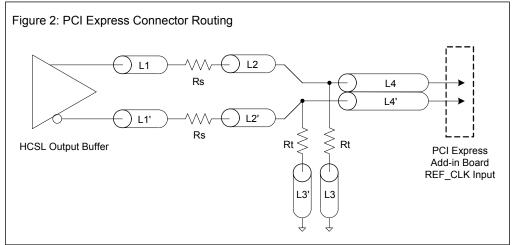


DIF Reference Clock						
Common Recommendations for Differential Routing	Dimension or Value	Unit	Figure			
L1 length, route as non-coupled 50ohm trace	0.5 max	inch	1			
L2 length, route as non-coupled 50ohm trace	0.2 max	inch	1			
L3 length, route as non-coupled 50ohm trace	0.2 max	inch	1			
Rs	33	ohm	1			
Rt	49.9	ohm	1			

Down Device Differential Routing		
L4 length, route as coupled microstrip 100ohm differential trace 2 min to 16	nax inch 1	
L4 length, route as coupled stripline 100ohm differential trace 1.8 min to 1	.4 max inch 1	

Differential Routing to PCI Express Connector			
L4 length, route as coupled microstrip 100ohm differential trace	0.25 to 14 max	inch	2
L4 length, route as coupled stripline 100ohm differential trace	0.225 min to 12.6 max	inch	2

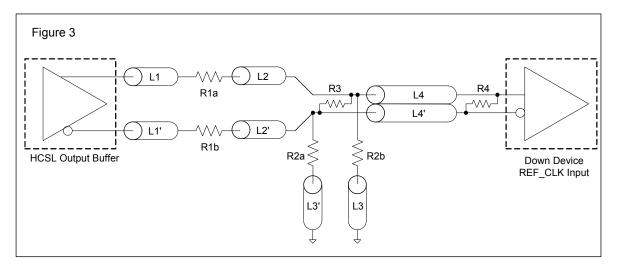




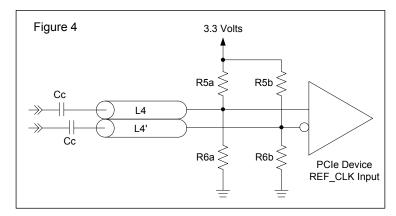


	Alternative Termination for LVDS and other Common Differential Signals (figure 3)						
Vdiff	Vp-p	Vcm	R1	R2	R3	R4	Note
0.45v	0.22v	1.08	33	150	100	100	
0.58	0.28	0.6	33	78.7	137	100	
0.80	0.40	0.6	33	78.7	none	100	ICS874003i-02 input compatible
0.60	0.3	1.2	33	174	140	100	Standard LVDS

R1a = R1b = R1R2a = R2b = R2

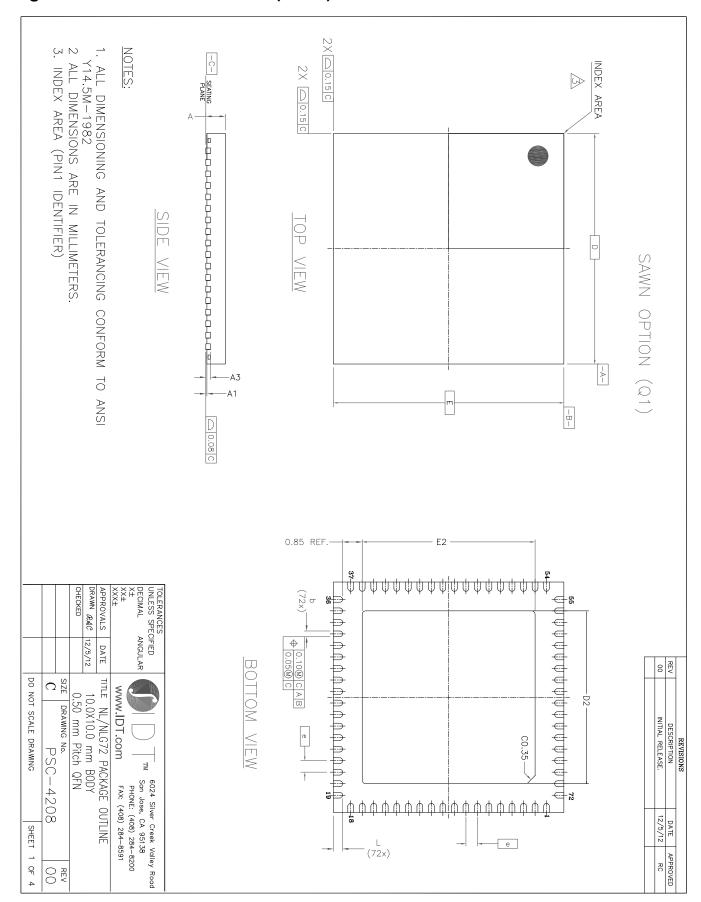


Cable Connected AC Coupled Application (figure 4)						
Component	Value	Note				
R5a, R5b	8.2K 5%					
R6a, R6b	1K 5%					
Сс	0.1 μF					
Vcm	0.350 volts					



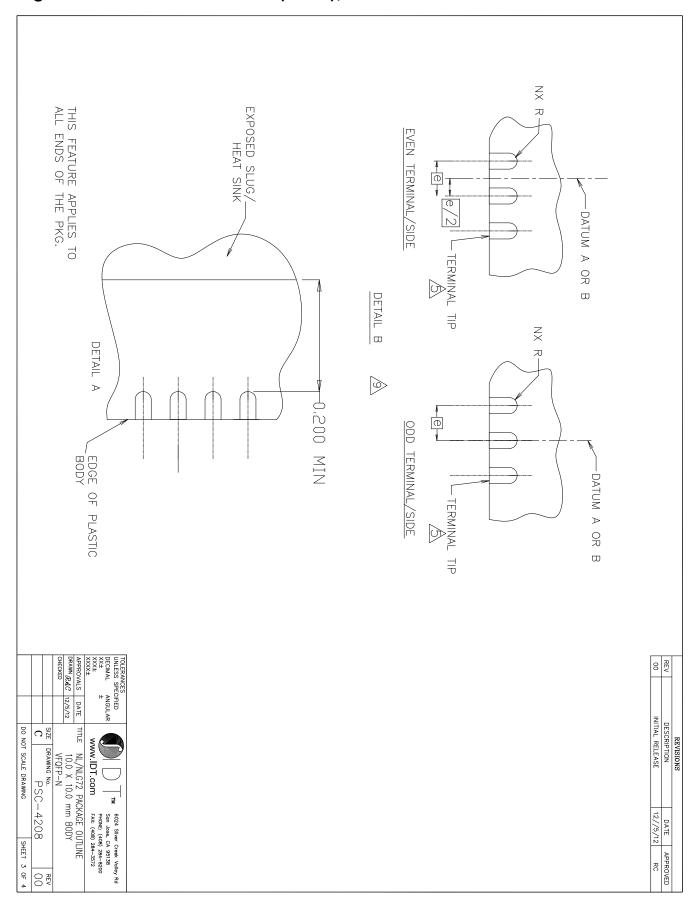


Package Outline and Dimensions (NL72)





Package Outline and Dimensions (NL72), cont.





Package Outline and Dimensions (NL72) cont. – use EPAD Option P3 and Lead Option Z2

SHALL CONFORM TO JEDEC PUB. 95 SEC. 4.3 SPP-002. DETAILS OF TERMINIDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 IDENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE. DIMENSION 6 APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25mm AND 0.30mm FROM TERMINAL TIP. ND AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY. T. DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.	SYMBOL 0.40mm 0.50mm Gag 0.10 0.15 bbb 0.07 0.10 CCC 0.10 0.10 ddd 0.05 0.05 NOTES: 1. DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994. 2. ALL DIMENSIONS ARE IN MILLIMETERS. ANGLES ARE IN DEGREES. 3. N IS THE TOTAL NUMBER OF TERMINALS IN Y-DIRECTION. & Ne IS THE NUMBER OF TERMINALS IN Y-DIRECTION.	SAW VERSION: DIMENSION OTEN OT
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MIDT.com TM Son Jose, CA 95139 PHONE: (409) 284-8200 NUL/NIG72 PACKAGE OUTLINE 10.0 X 10.0 mm BODY VFOIFD-IN. PSC-4208 SCALE DRAWING SHEET 4 OF 4		DATE APPROVED 12/5/12 RC



Marking Diagram



Notes:

- 1. "LOT" is the lot sequence number.
- 2. "COO" denotes country of origin.
- 3. "YYWW" is the last two digits of the year and week that the part was assembled.
- 4. "LF" denotes RoHS compliant package.

Ordering Information

Part / Order Number	rt / Order Number Shipping Package		Temperature	
9ZX21901CKLF	Trays	72-pin VFQFPN	0 to +70°C	
9ZX21901CKLFT	Tape and Reel	72-pin VFQFPN	0 to +70°C	

Revision History

Rev.	Issue Date	Who	Description	Page #
K 4	4/15/2013	IHIJVVI	1. Corrected typo in OE# Latency parameter; changed 1 min. to 3 max. cycles to 4	5
			min. to 12 max. clocks.	
L	1/30/2015	DC	Updated package dimensions and outline drawing with NL72 SAWN version.	Various
	4/23/2015 R	DDW	Added marking diagram and associated notes.	Various
				Re-created datasheet in latesrt IDT template.
N	11/19/2015	1/19/2015 RDW	Update Input Clock spec with new standardized table matching PCIe SIG input	5
			specs.	3



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