

bq2512x Evaluation Module

The bq2512x evaluation module (EVM) is a high-performance, easy-to-use development kit for the design of a compact, flexible, high-efficiency, lower power management solution for single-cell, Li-ion and Li-polymer batteries used in wearables and low-power portable applications.

This user's guide details both the bq25120EVM and bq25121EVM features, test summary, and test results. Also included are the EVM schematic, bill of materials, and PCB board layouts.

PCB Configurations

Device	PCB		
bq25120	PWR731		
bq25121	PWR812		

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1 Introduction

1.1 bq2512x IC Features

The bq2512x is a highly-integrated battery charge management IC that integrates the most common functions for wearable devices: linear charger, regulated output, load switch, manual reset with timer, and battery voltage monitor. The low quiescent current during operation and shutdown enables maximum battery life. The device supports charge currents from 5 mA to 300 mA. The input current limit, charge current, PWM output voltage, LDO output voltage, and other parameters are programmable through the I²C interface. The battery is charged using a standard Li-lon charge profile with three phases: precharge, constant current, and constant voltage.

1.2 bq2512x EVM Features

The bq2512x EVM is a complete battery power management module for evaluating compact, highlyintegrated, flexible, high efficiency, linear charging solution for single cell, Li-Ion and Li-Polymer batterypowered systems used in wearables and low-power portable applications. Key EVM features include:

- Configurable 300-mA buck regulator (1.8-V default)
- 700-nA typical I_{Q} with PWM enabled
- 0.5% accurate battery voltage regulation (configurable from 3.6 V to 4.65 V in 10-mV steps)
- Configurable termination current down to 500 μA
- 2.5 mm × 2.5 mm WCSP package and 6 external components for minimum solution
- · Power path management for powering the system and charging the battery
- Power path management enables < 150 nA ship mode battery quiescent current for longest shelf life
- · Push-button wake-up and reset with adjustable timers
- Battery charger operates from 3.4 V 5.5 V V $_{\rm IN}$ (5.5-V OVP / 20-V tolerant)
- I²C control of key parameters



1.3 Schematic

Figure 1 illustrates the EVM schematic.

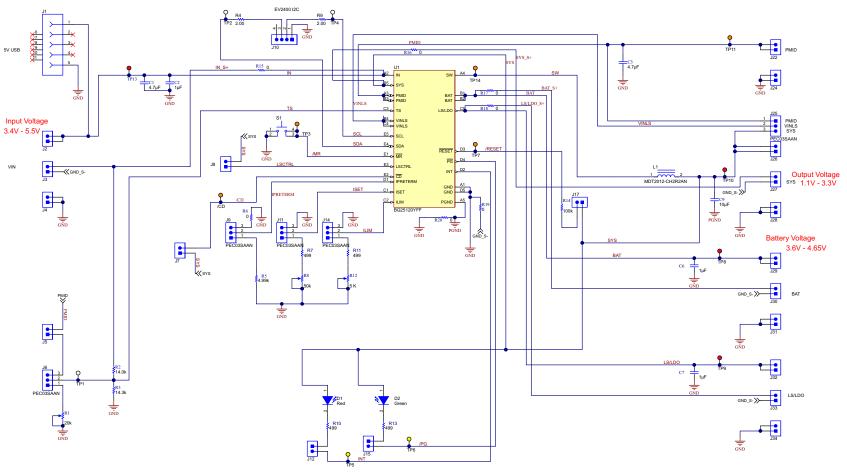


Figure 1. bq2512xEVM Schematic (bq25120 Represented)

Introduction

1.4 I/O Description

Table 1 lists the descriptions of the IO connectors on the PCB.

Header or Terminal Block	Description		
J1 - USB power input	Micro USB connector for USB input power		
J2 - IN (Force line)	Headers for extra connections to IN-Force		
J3 - IN/GND (Sense line)	Headers for IN-Sense and GND		
J4 - GND	Headers for extra connections to GND		
J5 - TS to PMID	Headers for TS pin to be pulled up to PMID		
J6 - TS	Headers for TS pin to be connected either to PMID or external resistor		
J7 - CD	Headers for /CD pin to be pulled up to SYS pin		
J8 - LS/CTRL	Headers for LS/CTRL pin to be pulled up to SYS pin		
J9 - IPRETERM	Headers for IPRETERM pin to be connected to an external resistor or shorted to GND		
J10 - EV2400	The 4-wire connector for EV2400 communication interface		
J11 - ISET	Headers for ISET pin to be connected to an external resistor or shorted to GND		
J12 - INT	Headers for INT pin to be pulled up to SYS pin through a LED light		
J14 - ILIM	Headers for ILIM pin to be connected to an external resistor or shorted to GND		
J15 - /PG	Headers for /PG pin to be pulled up to SYS pin through a LED light		
J17 - /RESET	Headers for /RESET pin to be pulled up to SYS pin through a 100-k Ω resistor		
J22 - PMID	Headers for extra connections to PMID		
J24 - GND	Headers for extra connections to GND		
J25 - PMID/VINLS/SYS	Headers for PMID/VINLS/SYS connections		
J26 - SYS	Headers for extra connections to SYS-Force		
J27 - SYS/GND (Sense line)	Headers for SYS-Sense and GND		
J28 - GND	Headers for extra connections to GND		
J29 - BAT	Headers for extra connections to BAT-Force		
J30 - BAT/GND (Sense line)	Headers for BAT-Sense and GND		
J31 - GND	Headers for extra connections to GND		
J32 - LS/LDO	Headers for extra connections to LS/LDO-Force		
J33 - LS/LDO (Sense line)	Headers for LS/LDO-Sense and GND		
J34 - GND	Headers for extra connections to GND		



1.5 Test Points

Table 2 provides descriptions of the test points.

Test Points	Description
TP1	TS pin
TP2	SDA pin
TP3	/MR pin
TP4	SCL pin
TP5	INT pin
TP6	/PG pin
TP7	/RESET pin
TP8	BAT pin
TP9	LS/LDO pin
TP10	SYS pin
TP11	PMID pin
TP13	IN pin
TP14	SW pin
TP /CD	/CD pin

Table 2. Test Points Description

1.6 Default Settings

The bq2512xEVM module has provided the capability of changing key parameters using I²C and the EV2400 communication interface. However, I²C communication is not required for this device to operate. The module is programmed to the default settings as is described in Table 3, Table 4 shows the initial jumper positions on the PCB.

Parameter	Options	bq2512x	
BAT_UVLO	2.2 V to 3.4 V (200-mV step)	3.0 V	
VSYS	1.1 V to 3.3 V (100-mV step)	1.8 V	
LS/LDO	LS, 0.8 V to 3.3 V (100-mV step)	LS	
VBREG	3.6 V to 4.65 V (10-mV step)	4.2 V	
ICHG	5 mA to 300 mA	10 mA	
IPRETERM	500 μA to 50 mA	2 mA	
Input ILIM	50 mA to 400 mA (50-mA step)	100 mA	
VIN_DPM_ON	On or Off	On	
VIN_DPM Threshold	4.2 V to 4.9 V	4.6 V	
Auto Charge	On or Off	On	
Safety Timer	30 min, 3 hr, 9 hr, Disabled	3 hr	

Table 4. Initial Jumper Position

J6	J9	J11	J12	J14	J15	J25
TS = TS_Pot	ITERM = GND	ISET= GND	Installed	ILIM = GND	Installed	VINLS = PMID

1.7 Recommended Operating Conditions

The recommended operating conditions are shown in Table 5.

		MIN	NOM	MAX	Unit
V _{IN}	IN voltage range	3.4	5	20	V
	IN operating voltage range, recommended	3.4	5	5.5	
V _{BAT}	VBAT operating voltage range			5.5(1)	V
V _{VINLS}	VINLS voltage range for Load Switch	0.8		5.5(2)	V
V _{VINLS}	VINLS voltage range for LDO	2.2		5.5	V
I _{IN}	Input Current, IN input			400	mA
I _{sw}	Output Current from SW, DC			300	mA
I _{PMID}	Output Current from PMID, DC			300	mA
I _{LS/LDO}	Output Current from LS/LDO			100	mA
I _{bat} , I _{sys}	Charging and discharging using internal battery FET			300	mA
TJ	Operating junction temperature range	-40		125	°C

⁽¹⁾ Any voltage greater than shown should be a transient event.

⁽²⁾ These inputs will support 6.6 V for less than 10% of the lifetime at V_(BAT) or V_{IN}, with a reduced current and/or performance.

2 Test Summary

This section describes the test configuration of the bq2512xEVM evaluation module for bench evaluation.

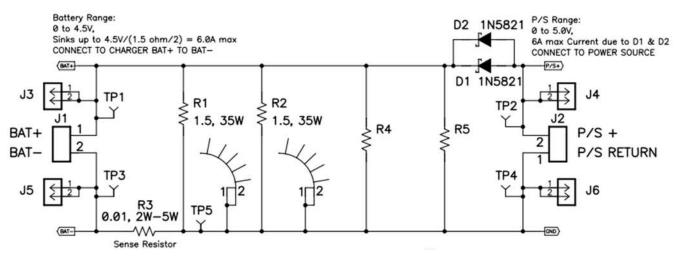
2.1 Recommended Test Equipment

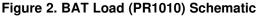
2.1.1 Power Supplies

- 1. Power Supply #1 (PS#1): a power supply capable of supplying 5 V at 1 A is required.
- 2. Power Supply #2 (PS#2): a power supply capable of supplying 5 V at 1 A is required.

2.1.2 Load

Testing with an actual battery is the best way to verify operation in the system. If a battery is unavailable, then a source meter like a Keithley 2420, capable of both sourcing and sinking current, or a circuit similar to the one shown in Figure 2 can simulate a battery when connected to PS#2.







2.1.3 Meters

Three voltage meters and two current meters. The current meters must be able to measure at least 0.5-A current.

2.1.4 Tool/Software GUI (Optional)

The following optional items can be used for testing:

- 1. EV2400 Communication Interface Board
- 2. bqStudio Software GUI

2.2 Recommended Test Equipment Setup

The following guidelines provide the recommended test equipment setup:

- 1. Set power supply #1 (PS#1) for 5 V ±100 mV DC, 1-A current limit and then turn off supply. Set power supply #2 (PS#2) for 3.5 V and then turn off supply.
- Connect the positive output of PS#1 through a current meter (CM#2) to IN (J2) and negative output to GND (J34).
- 3. Connect a voltage meter (VM#1) across J2 and J34.
- Connect the PR1010 BAT+ terminal of PR1010 in series with a current meter (CM#1) to BAT (J29). Connect PR1010 BAT – to GND (J34). Connect the P/S+ and P/S return side of PR1010 to PS#2, set the voltage to 3.5 V ±50 mV, then disable PS#2.
- 5. Connect a voltage meter (VM#2) across BAT (J29) and GND (J34).
- 6. Connect a DMM (VM#3) across SYS (SYS_S+ of J27) and GND (GND_S- of J27).
- 7. Configure jumpers as shown in Table 4.

After the preceding steps are accomplished, the test setup for PWR731 is as shown in Figure 3. The setup is similar for PWR812 with the bq25121.

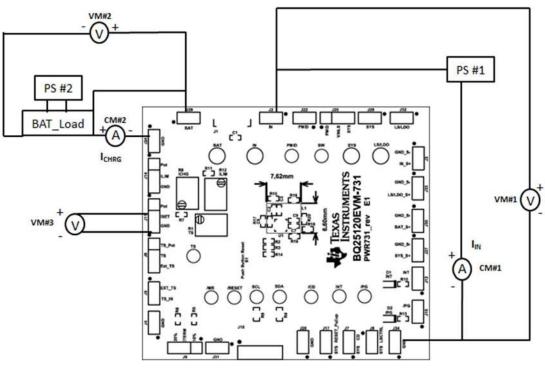


Figure 3. Test Setup (PWR731 for bq2512xEVM-731 Shown)

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Test Summary



Test Summary

2.3 Software GUI (When f C Communication is Used)

When using I²C communication, implement the following steps with the software GUI:

- 1. Install the <u>bqStudio</u> software GUI.
- 2. Connect the EV2400 interface board to the EVM (as shown in Figure 4) http://www.ti.com/tool/EV2400.
- 3. Open Software GUI and go to "Field View" page (as shown in Figure 5).
- 4. Change the parameters in the pull-down menu or check/uncheck the selection box.

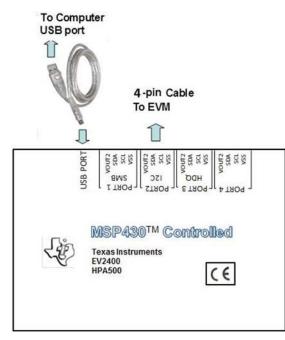


Figure 4. EV2400 Interface Box Connection

View Window Help				
vanced Comm			E	a Battery Mana.
oq25120 Default View 🗢 bq25120 Field View 🛛				0
ad Registers Save Registers Read Write Auto Read:	OFF - Update	Mode Immediate 🗸 I2C Address D4(6A) 👻 Default View	Device ACK OK	
Multi-bit I2C Pulldown Menu Termination Charge Current 10 mA ▼ Charge Current 10 mA ▼ Termination Charge Current SYS attery Regulation Voltage 4.20 V ▼ SYS	Current 2 mA	Status Charger Status Charging in Progres Reset Fault Normal	A 7 6 5 4 3 2 1 0 D W 00 0 1 0 0 0 0 0 1 41 W 01 0 0 0 0 0 0 0 0 0 0 0 0 W	R
MRWAKE2 1500 ms < MR -	WAKE1 50 ms < MR < • MRREC Hi-Z Mode •	Safety Timer Normal VINDPM Status Inactive CD Status CD low, IC enabled	02 1 0 0 0 1 0 0 88 W	R
Input Current Limit 100 mA Input VIN_DPM voltage 4.60 V Safety Timer Time	BUVLO 3.2 V • he Limit 3 hour fast ch •	SYS_EN_STAT SW enabled VIN_OV Fault Status VIN_UV Fault Status Normal	04 0 0 0 0 1 1 1 0 0E W 05 0 1 1 1 1 0 0 0 78 W 06 1 0 1 0 1 0 1 0 1 0 AA W	R
Ingle-bit I2C Selection EN, SHIPMODE Mask VM Undervoltage Fault Mask BAT_OCP Fault Mask BAT_OCP Fault Mask BAT_OCP Fault Mask BAT_UCQ Fault Mask BAT_UCP Fault Isable INF Function Mask KBET Condition Mask KBET Condition Mask RESET Condition Isable Charge Enable ISC Enable ISC Reade Charge Current Termination Reset Register VEMONT, READ	uit	BAT_UVLO Fault Status Normal BAT_OCP Fault Status Normal TS Fault Open No TS OFF fault Wake! Status Not meets the WAKE Wake2 Status Not meets the WAKE VBMON_TH N/A	07 0 1 1 1 1 0 0 7C Weilling 08 0 1 1 0 0 0 86 Weilling 09 0 0 0 1 1 1 0 0 0 86 Weilling 0A 0 0 0 0 0 0 0 0 0 0 0 0 0 0 Weilling Weilling	R R
Disable VINDPM Enable 2x Timer Wath Dog Timer eriod 20 Sec •				

Figure 5. bq2512x Software GUI



3 Test Procedure

3.1 Set the Potentiometers

- 1. Set VM#3 DMM to measure resistance
- 2. Install J11 to POT
- 3. Install J14 to POT
- 4. Turn the potentiometer R8 until the measure on VM#3 \rightarrow R[J11 (ISET), J11(GND)] = 2 k Ω .
- 5. Move the positive side of VM#3 DMM to J14 (ILIM).
- 6. Turn the potentiometer R12 until the measure on VM#3 \rightarrow R[J14(ILIM), J14(GND)] = 499 Ω .
- 7. Move the positive side of VM#3 DMM to J6 (TS).
- 8. Turn the potentiometer R1 until the measure on VM#3 \rightarrow R[J6 (TS), J14(GND)] = 5.5 k Ω 6.5 k Ω .
- 9. Move the positive side of VM#3 DMM to J27 (SYS_S+).
- 10. Set VM#3 DMM to measure voltage.

3.2 Charge Disabled

- 1. Install the jumper on J7 connect CD to SYS
- 2. Enable PS#1 and PS#2
- 3. Observe D2 is on, D1 is off
- 4. Measure on VM#3 \rightarrow V[J27(SYS_S+) J14(GND)] = 1.8V ±50 mV
- 5. Measure on CM#2 \rightarrow ICHRG \leq 0–1 mA
- 6. Measure on CM#1 \rightarrow IIN < 2 mA
- 7. Disable PS#1 and PS#2

3.3 Charge Current Regulation

- 1. Remove the jumper on J7 disconnect CD to SYS
- 2. Enable PS#1 and PS#2
- 3. Observe D2 is on, D1 is on
- 4. Adjust PS#2 so that the voltage measured by VM#2, across BAT and GND, measures 3.5 V
- 5. Adjust the PS#1 so that VM#1 still reads 5.0 V \pm 100 mV
- 6. Measure on VM#3 \rightarrow V[J27(SYS_S+) J14(GND)] = 1.8 V ±50 mV
- 7. Measure on CM#2 \rightarrow ICHRG = 90–110 mA
- 8. Measure on CM#1 \rightarrow IIN = 93–113 mA
- 9. Disable PS#1 and PS#2

3.4 Ship Mode (Optional if *PC* Control not Used)

- 1. Enable PS#1 and PS#2
- 2. Open the software GUI
- 3. Go to Field View of the GUI and then read all the registers. All the default register values should be shown in the register map (as shown in Figure 3).
- 4. Measure on CM#2 \rightarrow ICHRG = 9–11 mA
- 5. Install the jumper on J7 connect CD to SYS
- 6. Disable PS#1
- 7. Measure on CM#2 \rightarrow ICHRG = 5–7 μA
- 8. Check the box in front of "EN_SHIPMODE" in the software GUI



Multi-bit I2C Pulldown Me	nu		
Charge Current	10 mA	•	
Battery Regulation Voltage	4.20 V	•	
LS/LDO Voltage	Load Swite	ch 👻	
MRWAKE2	1500 ms <	MR 👻	
MRRESET	8s +/- 500ms 🔻		
Input Current Limit	100 mA	•	
Input VIN_DPM voltage	4.60 V	•	s
Single-bit I2C Selection		🔲 Ma	sk
Mask VIN Undervoltage I	Fault	📃 Ma	sk
Mask BAT_OCP Fault		V Ena	ab
Enable INT Function		📃 Ma	sk
Mask RESET Condition	Ma	sk	
Disable Charger		Ena	ab
Enable Charge Current T	ermination	V Ena	ab
Enable LS/LDO		MR	R

Figure 6. Select EN_SHIPMODE

- 9. Measure on CM#2 \rightarrow ICHRG < 100 nA
- 10. Disable PS#2

4 Helpful Hints

The following steps provide useful information when using the EVM:

- 1. The leads and cables to the various power supplies have resistance. The current meters also have series resistance. Therefore, voltmeters must be used to measure the voltage as close to the IC pins as possible instead of relying on each supply's digital measurement.
- 2. When using a source meter as your battery simulator, it is highly recommended to configure the source meter for 4-wire sensing, eliminating the need for a separate voltmeter to measure the voltage at the OUT pin.
- To observe the taper current as the battery voltage approaches the set regulation voltage, allow the battery to charge, or if using BAT_Load (PR1010), slowly increase the PS#2 voltage powering BAT_Load (PR1010). Use VM#2 across OUT and GND to measure the battery voltage seen by the IC.
- To find out more details about battery I_Q and how to measure it on power supplies, please refer to the application note: *IQ: What it is, what it isn't, and how to use it* (SLYT412)



5 Bill of Materials and Board Layout

This section provides the bq2512x EVM bill of materials (BOM) and the printed-circuit board (PCB) layout illustrations.

5.1 Bill of Materials

Table 6 lists the EVM BOM.

Item #	Designator	Qty	Value	Part Number	Manufacturer	Description	Package Reference
1	!PCB	1		PWR812	Any	Printed Circuit Board	
2	C1, C3	2	4.7uF	GRM188R61E475KE11D	Murata	CAP, CERM, 4.7 μF, 25 V, +/- 10%, X5R, 0603	0603
3	C2	1	1uF	C1005X5R1E105K050BC	TDK	CAP, CERM, 1 µF, 25 V, +/- 10%, X5R, 0402	0402
4	C6, C7	2	1uF	GRM155R61A105KE15D	Murata	CAP, CERM, 1 µF, 10 V, +/- 10%, X5R, 0402	0402
5	C9	1	10uF	CL05A106MP5NUNC	Samsung Electro- Mechanics	CAP, CERM, 10 µF, 10 V, +/- 20%, X5R, 0402	0402
6	D1	1	Red	LTST-C190CKT	Lite-On	LED, Red, SMD	Red LED, 1.6x0.8x0.8mm
7	D2	1	Green	LTST-C190GKT	Lite-On	LED, Green, SMD	1.6x0.8x0.8mm
8	H12, H13, H14, H15	4		SJ61A1	3M	Bumpon, Cylindrical, 0.312 X 0.200, Black	Black Bumpon
9	J1	1		105017-0001	Molex	Receptacle, Micro-USB-B, Right Angle, SMD	Micro USB receptacle
10	J2, J3, J4, J5, J7, J8, J12, J15, J17, J22, J24, J26, J27, J28, J29, J30, J31, J32, J33, J34	20		PEC02SAAN	Sullins Connector Solutions	Header, 100mil, 2x1, Tin plated, TH	Header, 2 PIN, 100mil, Tin
11	J6, J9, J11, J14, J25	5		PEC03SAAN	Sullins Connector Solutions	Header, 100mil, 3x1, Tin, TH	Header, 3 PIN, 100mil, Tin
12	J10	1		22-05-3041	Molex	Header (friction lock), 100mil, 4x1, R/A, TH	4x1 R/A Header
13	L1	1	2.2uH	LQM21PN2R2MGH	Murata	Inductor, Multilayer, Ferrite, 2.2 µH, 0.7 A, 0.125 ohm, SMD	2.0x1.0x1.2mm
14	LBL1	1		THT-14-423-10	Brady	Thermal Transfer Printable Labels, 0.650" W x 0.200" H - 10,000 per roll	PCB Label 0.650"H x 0.200"W
15	R1	1	20k	3266W-1-203LF	Bourns	Trimmer, 20k ohm, 0.25W, TH	4.5x8x6.7mm
16	R2	1	14.0k	CRCW040214K0FKED	Vishay-Dale	RES, 14.0k ohm, 1%, 0.063W, 0402	0402
17	R3	1	14.3k	CRCW040214K3FKED	Vishay-Dale	RES, 14.3k ohm, 1%, 0.063W, 0402	0402
18	R4, R9	2	2.00	CRCW06032R00FKEA	Vishay-Dale	RES, 2.00 ohm, 1%, 0.1W, 0603	0603
19	R5	1	4.99k	CRCW04024K99FKED	Vishay-Dale	RES, 4.99 k, 1%, 0.063 W, 0402	0402
20	R6, R15, R16, R17, R18, R19, R20	7	0	CRCW04020000Z0ED	Vishay-Dale	RES, 0, 5%, 0.063 W, 0402	0402

Table 6. bq2512xEVM Bill of Materials



Bill of Materials and Board Layout

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Table 6. bq2512xEVM Bill of Materials (continued)

Item #	Designator	Qty	Value	Part Number	Manufacturer	Description	Package Reference
21	R7, R10, R11, R13	4	499	CRCW0402499RFKED	Vishay-Dale	RES, 499 ohm, 1%, 0.063W, 0402	0402
22	R8	1	50k	3266W-1-503LF	Bourns	Trimmer, 50k ohm, 0.25W, TH	4.5x8x6.7mm
23	R12	1	5 K	3266W-1-502LF	Bourns	Trimmer, 5k ohm, 0.25W, TH	4.5x8x6.7mm
24	R14	1	100k	CRCW0402100KFKED	Vishay-Dale	RES, 100k ohm, 1%, 0.063W, 0402	0402
25	S1	1		KST221JLFS	C&K Components	Switch, Tactile, SPST-NO, SMT	Switch, 6.2X5X6.2 mm
26	SH-JP1, SH- JP2, SH-JP3, SH-JP4, SH- JP5, SH-JP6, SH-JP7	7	1x2	969102-0000-DA	3M	Shunt, 100mil, Gold plated, Black	Shunt
27	TP1, TP2, TP4	3	White	5002	Keystone	Test Point, Miniature, White, TH	White Miniature Testpoint
28	TP3, TP7, TP11, TP14, TP15	5	Orange	5003	Keystone	Test Point, Miniature, Orange, TH	Orange Miniature Testpoint
29	TP5, TP6	2	Yellow	5004	Keystone	Test Point, Miniature, Yellow, TH	Yellow Miniature Testpoint
30	TP8, TP9, TP10, TP13	4	Red	5005	Keystone	Test Point, Compact, Red, TH	Red Compact Testpoint
31	U1	1		BQ25121YFPR	Texas Instruments	700-nA Low IQ Highly Integrated Battery Charge Management Solution for Wearables and IoT, YFP0025BABD	YFP0025BABD
32	FID1, FID2, FID3, FID4, FID5, FID6	0		N/A	N/A	Fiducial mark. There is nothing to buy or mount.	Fiducial

5.2 Board Layouts

5.2.1 PWR731 Layouts

Figure 7 through Figure 16 illustrate the PWR731 EVM PCB board layouts.

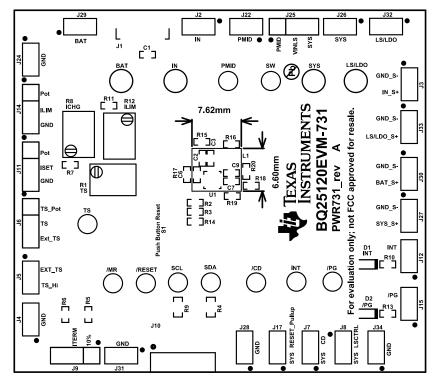


Figure 7. Top Overlay

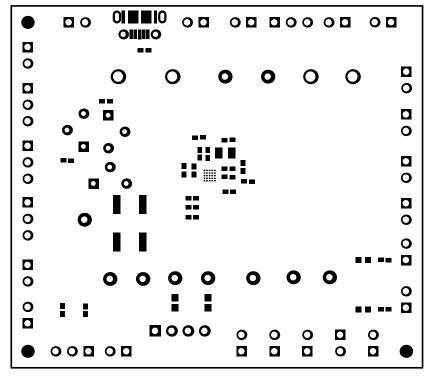


Figure 8. Top Solder Mask



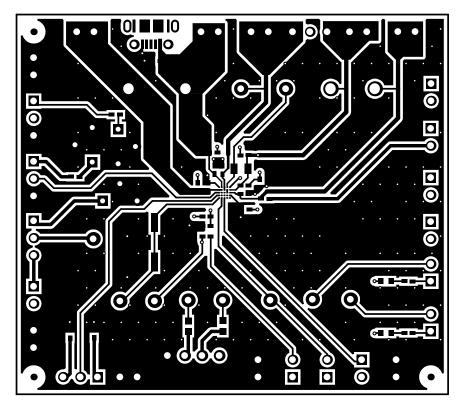


Figure 9. Top Layer

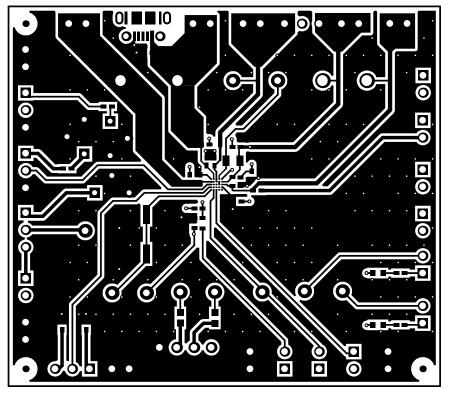


Figure 10. Signal Layer 1



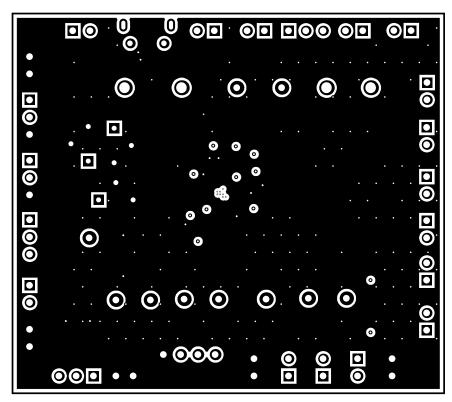


Figure 11. Signal Layer 2

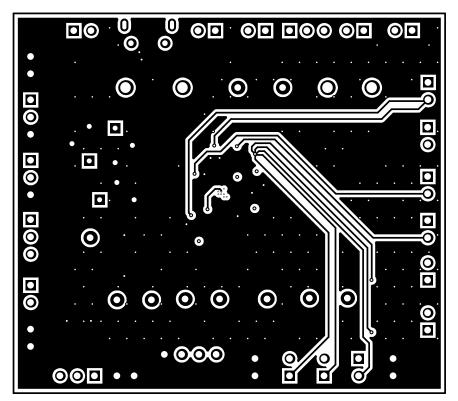


Figure 12. Bottom Layer



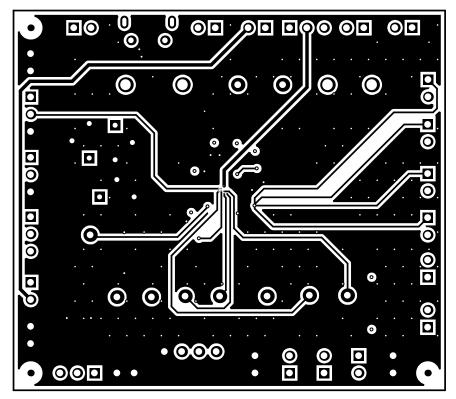


Figure 13. Bottom Solder Mask

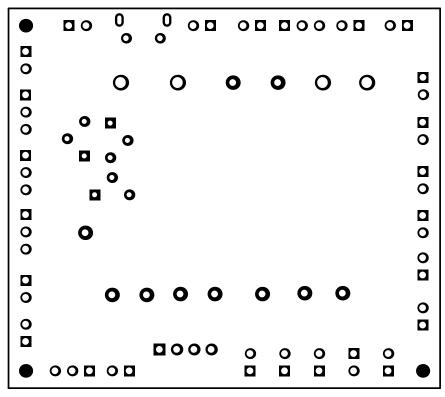
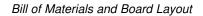


Figure 14. Bottom Overlay





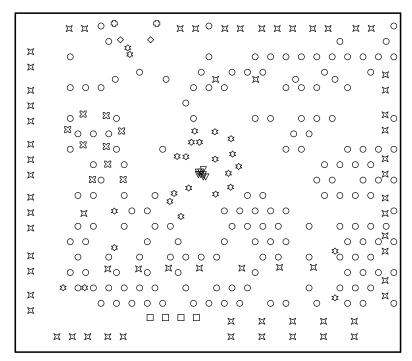


Figure 15. Drill Drawing

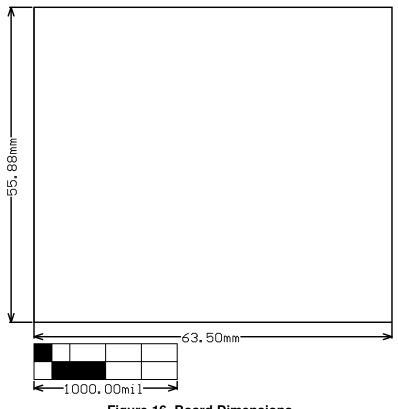
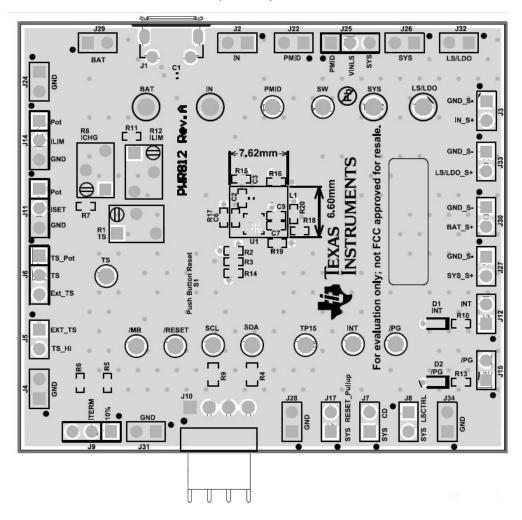


Figure 16. Board Dimensions

Revision History

5.2.2 PWR812 Layout

Figure 17 illustrates the PWR812 PCB composite layout.





Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	changes from Original (August 2015) to A Revision	Page
•	Changed user's guide globally to accommodate both the bq25120 and bq25121 EVMs.	1
•	Replaced existing BOM with PWR812A BOM.	11

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CAUTION

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Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

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FCC Interference Statement for Class B EVM devices

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- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- · Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210

Concerning EVMs Including Radio Transmitters:

This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

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Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur

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