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74AVCH16T245

16-bit dual supply translating transceiver with configurable voltage translation; 3-state

Rev. 5 — 1 March 2012

Product data sheet

1. General description

The 74AVCH16T245 is a 16-bit transceiver with bidirectional level voltage translation and 3-state outputs. The device can be used as two 8-bit transceivers or as a 16-bit transceiver. It has dual supplies ($V_{CC(A)}$ and $V_{CC(B)}$) for voltage translation and four 8-bit input-output ports (nAn, nBn) each with its own output enable ($n\overline{OE}$) and send/receive (nDIR) input for direction control. $V_{CC(A)}$ and $V_{CC(B)}$ can be independently supplied at any voltage between 0.8 V and 3.6 V making the device suitable for low voltage translation between any of the following voltages: 0.8 V, 1.2 V, 1.5 V, 1.8 V, 2.5 V and 3.3 V. A HIGH on nDIR selects transmission from nAn to nBn while a LOW on nDIR selects transmission from nBn to nAn. A HIGH on $n\overline{OE}$ causes the outputs to assume a high-impedance OFF-state

The device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing any damaging backflow current through the device when it is powered down. In suspend mode when either $V_{\text{CC}(A)}$ or $V_{\text{CC}(B)}$ are at GND level, both A and B outputs are in the high-impedance OFF-state. The bus-hold circuitry on the powered-up side always stays active.

The 74AVCH16T245 has active bus hold circuitry which is provided to hold unused or floating data inputs at a valid logic level. This feature eliminates the need for external pull-up or pull-down resistors.

2. Features and benefits

- Wide supply voltage range:
 - ◆ V_{CC(A)}: 0.8 V to 3.6 V
 - ◆ V_{CC(B)}: 0.8 V to 3.6 V
- Complies with JEDEC standards:
 - ◆ JESD8-12 (0.8 V to 1.3 V)
 - ◆ JESD8-11 (0.9 V to 1.65 V)
 - ◆ JESD8-7 (1.2 V to 1.95 V)
 - ◆ JESD8-5 (1.8 V to 2.7 V)
 - ◆ JESD8-B (2.7 V to 3.6 V)
- ESD protection:
 - HBM JESD22-A114F Class 3B exceeds 8000 V
 - MM JESD22-A115-A exceeds 200 V
 - CDM JESD22-C101D exceeds 1000 V
- Maximum data rates:
 - ◆ 380 Mbit/s (≥ 1.8 V to 3.3 V translation)



- ◆ 200 Mbit/s (≥ 1.1 V to 3.3 V translation)
- ◆ 200 Mbit/s (≥ 1.1 V to 2.5 V translation)
- ◆ 200 Mbit/s (≥ 1.1 V to 1.8 V translation)
- ◆ 150 Mbit/s (≥ 1.1 V to 1.5 V translation)
- ◆ 100 Mbit/s (≥ 1.1 V to 1.2 V translation)
- Suspend mode
- Bus hold on data inputs
- Latch-up performance exceeds 100 mA per JESD 78 Class II
- Inputs accept voltages up to 3.6 V
- I_{OFF} circuitry provides partial Power-down mode operation
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

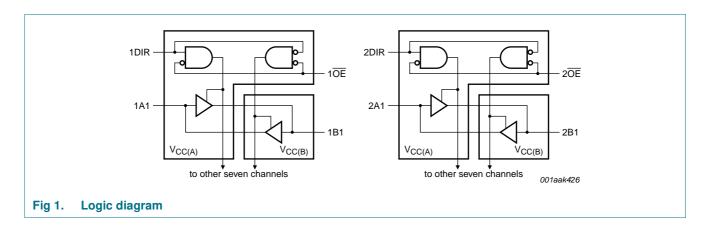
3. Ordering information

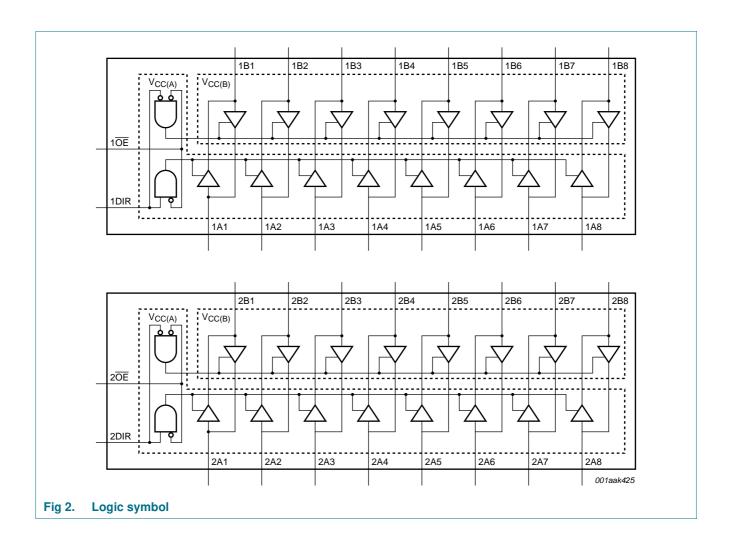
Table 1. Ordering information

| Type number | Package | | | |
|-----------------|-------------------|------------|---|-----------|
| | Temperature range | Name | Description | Version |
| 74AVCH16T245DGG | –40 °C to +125 °C | TSSOP48 | plastic thin shrink small outline package; 48 leads; body width 6.1 mm | SOT362-1 |
| 74AVCH16T245DGV | –40 °C to +125 °C | TSSOP48[1] | plastic thin shrink small outline package; 48 leads; body width 4.4 mm; lead pitch 0.4 mm | SOT480-1 |
| 74AVCH16T245EV | –40 °C to +125 °C | VFBGA56 | plastic very thin fine-pitch ball grid array package; 56 balls; body $4.5 \times 7 \times 0.65$ mm | SOT702-1 |
| 74AVCH16T245BX | –40 °C to +125 °C | HXQFN60 | plastic compatible thermal enhanced extremely thin quad flat package; no leads; 60 terminals; body $4\times6\times0.5$ mm | SOT1134-2 |

^[1] Also known as TVSOP48.

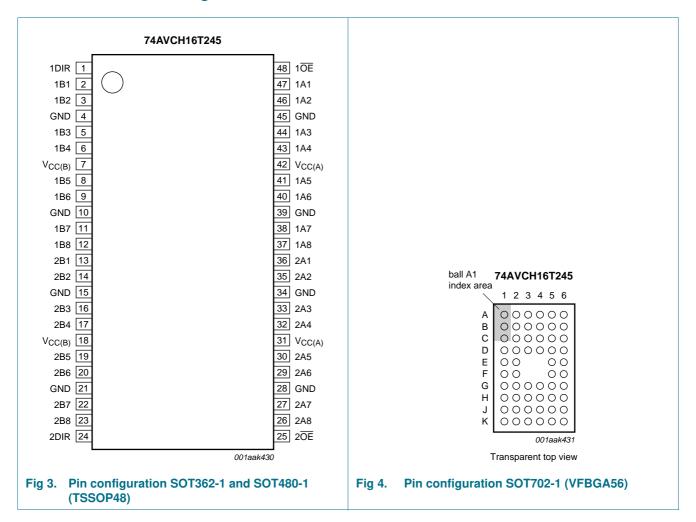
4. Functional diagram





5. Pinning information

5.1 Pinning



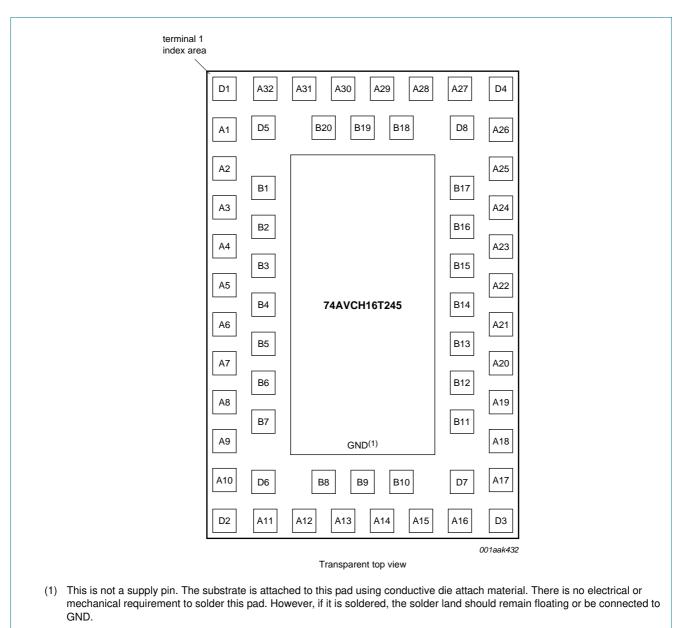


Fig 5. Pin configuration SOT1134-2 (HXQFN60)

5.2 Pin description

Table 2. Pin description

| Symbol | Pin | | | Description |
|-------------|-----------------------------------|-----------------------------------|--|--|
| | SOT362-1 and SOT480-1 | SOT702-1 | SOT1134-2 | _ |
| 1DIR, 2DIR | 1, 24 | A1, K1 | A30, A13 | direction control |
| 1B1 to 1B8 | 2, 3, 5, 6, 8, 9, 11, 12 | B2, B1, C2, C1, D2, D1, E2, E1 | B20, A31, D5, D1, A2, B2, B3, A5 | data input or output |
| 2B1 to 2B8 | 13, 14, 16, 17, 19, 20, 22, 23 | F1, F2, G1, G2, H1, H2, J1, J2 | A6, B5, B6, A9, D2, D6, A12, B8 | data input or output |
| GND[1] | 4, 10, 15, 21, 28, 34, 39, 45 | B3, D3, G3, J3, J4, G4, D4, B4 | A32, A3, A8, A11, A16, A19, A24, A27 | ground (0 V) |
| $V_{CC(B)}$ | 7, 18 | C3, H3 | A1, A10 | supply voltage B (nBn inputs are referenced to $V_{\text{CC(B)}}$) |
| 1OE, 2OE | 48, 25 | A6, K6 | A29, A14 | output enable input (active LOW) |
| 1A1 to 1A8 | 47, 46, 44, 43, 41, 40, 38, 37 | B5, B6, C5, C6, D5, D6, E5, E6 | B18, A28, D8, D4, A25, B16, B15, A22 | data input or output |
| 2A1 to 2A8 | 36, 35, 33, 32, 30, 29, 27, 26 | F6, F5, G6, G5, H6, H5, J6, J5 | A21, B13, B12, A18, D3, D7, A15, B10 | data input or output |
| $V_{CC(A)}$ | 31, 42 | C4, H4 | A17, A26 | supply voltage A (nAn, n $\overline{\text{OE}}$ and nDIR inputs are referenced to $V_{\text{CC(A)}}$) |
| n.c. | - | A2, A3, A4, A5, K2, K3, K4, K5 | A4, A7, A20, A23, B1, B4, B7, B9, B11, B14, B17, B19 | not connected |

^[1] All GND pins must be connected to ground (0 V).

6. Functional description

Table 3. Function table[1]

| Supply voltage | Input | | Input/output[3] | | |
|---|--------|---------|-----------------|-----------|--|
| V _{CC(A)} , V _{CC(B)} | nOE[2] | nDIR[2] | nAn[2] | nBn[2] | |
| 0.8 V to 3.6 V | L | L | nAn = nBn | input | |
| 0.8 V to 3.6 V | L | Н | input | nBn = nAn | |
| 0.8 V to 3.6 V | Н | X | Z | Z | |
| GND[3] | Χ | X | Z | Z | |

^[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

^[2] The nAn, nDIR and n $\overline{\text{OE}}$ input circuit is referenced to $V_{\text{CC(A)}}$; The nBn input circuit is referenced to $V_{\text{CC(B)}}$.

^[3] If at least one of $V_{CC(A)}$ or $V_{CC(B)}$ is at GND level, the device goes into suspend mode.

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

| | | , | • | | • |
|------------------|-------------------------|---|-----------------|-----------------|------|
| Symbol | Parameter | Conditions | Min | Max | Unit |
| $V_{CC(A)}$ | supply voltage A | | -0.5 | +4.6 | V |
| $V_{CC(B)}$ | supply voltage B | | -0.5 | +4.6 | V |
| I _{IK} | input clamping current | $V_I < 0 V$ | –50 | - | mA |
| VI | input voltage | | <u>[1]</u> –0.5 | +4.6 | V |
| l _{OK} | output clamping current | V _O < 0 V | –50 | - | mA |
| V _O | output voltage | Active mode | [1][2][3] -0.5 | $V_{CCO} + 0.5$ | V |
| | | Suspend or 3-state mode | <u>[1]</u> –0.5 | +4.6 | V |
| I _O | output current | $V_O = 0 V \text{ to } V_{CC}$ | [2] - | ±50 | mA |
| I _{CC} | supply current | $I_{CC(A)}$ or $I_{CC(B)}$ | - | 100 | mA |
| I _{GND} | ground current | | -100 | - | mA |
| T _{stg} | storage temperature | | -65 | +150 | °C |
| P _{tot} | total power dissipation | $T_{amb} = -40 ^{\circ}\text{C} \text{ to } +125 ^{\circ}\text{C};$ | | | |
| | | TSSOP48 package | <u>[4]</u> _ | 500 | mW |
| | | VFBGA56 package | <u>[5]</u> _ | 1000 | mW |
| | | HXQFN60 package | <u>[5]</u> _ | 1000 | mW |
| | | | | | |

^[1] The minimum input voltage ratings and output voltage ratings may be exceeded if the input and output current ratings are observed.

8. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|---------------------|-------------------------------------|---|-------|-----------|------|
| $V_{CC(A)}$ | supply voltage A | | 0.8 | 3.6 | V |
| V _{CC(B)} | supply voltage B | | 0.8 | 3.6 | V |
| VI | input voltage | | 0 | 3.6 | V |
| V_{O} | output voltage | Active mode | [1] 0 | V_{CCO} | V |
| | | Suspend or 3-state mode | 0 | 3.6 | V |
| T _{amb} | ambient temperature | | -40 | +125 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | $V_{CCI} = 0.8 \text{ V to } 3.6 \text{ V}$ | [2] _ | 5 | ns/V |

^[1] V_{CCO} is the supply voltage associated with the output port.

^[2] V_{CCO} is the supply voltage associated with the output port.

^[3] $V_{CCO} + 0.5 \text{ V}$ should not exceed 4.6 V.

^[4] Above 60 °C the value of Ptot derates linearly with 5.5 mW/K.

^[5] Above 70 °C the value of Ptot derates linearly with 1.8 mW/K.

^[2] V_{CCI} is the supply voltage associated with the input port.

9. Static characteristics

Table 6. Typical static characteristics at $T_{amb} = 25 \text{ °C} \frac{[1][2]}{}$

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| | | , , | | | | |
|-------------------|---------------------------------|--|--------------|--------|-------|------|
| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
| V_{OH} | HIGH-level output voltage | $V_I = V_{IH}$ or V_{IL} | | | | |
| | | $I_{O} = -1.5 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 0.8 \text{ V}$ | - | 0.69 | - | V |
| V_{OL} | LOW-level output voltage | $V_I = V_{IH}$ or V_{IL} | | | | |
| | | $I_O = 1.5 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 0.8 \text{ V}$ | - | 0.07 | - | ٧ |
| lı | input leakage current | nDIR, n \overline{OE} input; V _I = 0 V or 3.6 V; V _{CC(A)} = V _{CC(B)} = 0.8 V to 3.6 V | - | ±0.025 | ±0.25 | μА |
| I _{BHL} | bus hold LOW current | A or B port; $V_I = 0.42 \text{ V}$; $V_{CC(A)} = V_{CC(B)} = 1.2 \text{ V}$ | [3] _ | 26 | - | μΑ |
| I _{BHH} | bus hold HIGH current | A or B port; $V_I = 0.78 \text{ V}$; $V_{CC(A)} = V_{CC(B)} = 1.2 \text{ V}$ | [4] _ | -24 | - | μΑ |
| I _{BHLO} | bus hold LOW overdrive current | A or B port; $V_{CC(A)} = V_{CC(B)} = 1.2 \text{ V}$ | <u>[5]</u> _ | 27 | - | μА |
| I _{внно} | bus hold HIGH overdrive current | A or B port; $V_{CC(A)} = V_{CC(B)} = 1.2 \text{ V}$ | <u>[6]</u> _ | -26 | - | μА |
| l _{OZ} | OFF-state output current | A or B port; $V_O = 0 \text{ V or } V_{CCO}$; $V_{CC(A)} = V_{CC(B)} = 3.6 \text{ V}$ | [7] - | ±0.5 | ±2.5 | μА |
| | | suspend mode A port; $V_O = 0 \text{ V or } V_{CCO}$; $V_{CC(A)} = 3.6 \text{ V}$; $V_{CC(B)} = 0 \text{ V}$ | [7] - | ±0.5 | ±2.5 | μА |
| | | suspend mode B port; $V_O = 0 \text{ V or } V_{CCO}$; $V_{CC(A)} = 0 \text{ V}$; $V_{CC(B)} = 3.6 \text{ V}$ | <u>[7]</u> _ | ±0.5 | ±2.5 | μА |
| l _{OFF} | power-off leakage current | A port; V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0.8$ V to 3.6 V | - | ±0.1 | ±1 | μА |
| | | B port; V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0.8$ V to 3.6 V | - | ±0.1 | ±1 | μА |
| Cı | input capacitance | nDIR, n \overline{OE} input; V _I = 0 V or 3.3 V; V _{CC(A)} = V _{CC(B)} = 3.3 V | - | 2.0 | - | pF |
| C _{I/O} | input/output capacitance | A and B port; $V_O = 3.3 \text{ V or } 0 \text{ V}$; $V_{CC(A)} = V_{CC(B)} = 3.3 \text{ V}$ | - | 4.5 | - | pF |

^[1] V_{CCO} is the supply voltage associated with the output port.

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^[2] V_{CCI} is the supply voltage associated with the data input port.

^[3] The bus hold circuit can sink at least the minimum low sustaining current at V_{IL} max. I_{BHL} should be measured after lowering V_I to GND and then raising it to V_{IL} max.

^[4] The bus hold circuit can source at least the minimum high sustaining current at V_{IH} min. I_{BHH} should be measured after raising V_I to V_{CC} and then lowering it to V_{IH} min.

^[5] An external driver must source at least I_{BHLO} to switch this node from LOW to HIGH.

^[6] An external driver must sink at least I_{BHHO} to switch this node from HIGH to LOW.

^[7] For I/O ports, the parameter I_{OZ} includes the input leakage current.

Table 7. Static characteristics [1][2]

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | –40 °C t | o +85 °C | -40 °C to | +125 °C | Un |
|---------|-----------------------------------|--|------------------------|------------------------|------------------------|------------------------|----|
| | | | Min | Max | Min | Max | |
| , IH | HIGH-level | data input | | 1 | ı | | |
| | input voltage | V _{CCI} = 0.8 V | 0.70V _{CCI} | - | $0.70V_{CCI}$ | - | ٧ |
| | | V _{CCI} = 1.1 V to 1.95 V | 0.65V _{CCI} | - | 0.65V _{CCI} | - | ٧ |
| | | V _{CCI} = 2.3 V to 2.7 V | 1.6 | - | 1.6 | - | ٧ |
| | | V _{CCI} = 3.0 V to 3.6 V | 2 | - | 2 | - | ٧ |
| | | nDIR, nOE input | | | | | |
| | | V _{CC(A)} = 0.8 V | 0.70V _{CC(A)} | - | 0.70V _{CC(A)} | - | ٧ |
| | | $V_{CC(A)} = 1.1 \text{ V to } 1.95 \text{ V}$ | 0.65V _{CC(A)} | - | 0.65V _{CC(A)} | - | ٧ |
| | | $V_{CC(A)} = 2.3 \text{ V to } 2.7 \text{ V}$ | 1.6 | - | 1.6 | - | ٧ |
| | | $V_{CC(A)} = 3.0 \text{ V to } 3.6 \text{ V}$ | 2 | - | 2 | - | ٧ |
| IL | LOW-level | data input | | | | | |
| | input voltage | V _{CCI} = 0.8 V | - | 0.30V _{CCI} | - | 0.30V _{CCI} | ٧ |
| | | V _{CCI} = 1.1 V to 1.95 V | - | 0.35V _{CCI} | - | 0.35V _{CCI} | ٧ |
| | V _{CCI} = 2.3 V to 2.7 V | - | 0.7 | - | 0.7 | ٧ | |
| | | V _{CCI} = 3.0 V to 3.6 V | - | 0.8 | - | 0.8 | ٧ |
| | | nDIR, nOE input | | | | | |
| | | V _{CC(A)} = 0.8 V | - | 0.30V _{CC(A)} | - | 0.30V _{CC(A)} | ٧ |
| | | V _{CC(A)} = 1.1 V to 1.95 V | - | 0.35V _{CC(A)} | - | 0.35V _{CC(A)} | ٧ |
| | | $V_{CC(A)} = 2.3 \text{ V to } 2.7 \text{ V}$ | - | 0.7 | - | 0.7 | ٧ |
| | | $V_{CC(A)} = 3.0 \text{ V to } 3.6 \text{ V}$ | - | 0.8 | - | 8.0 | ٧ |
| ОН | HIGH-level | $V_I = V_{IH}$ or V_{IL} | | | | | |
| | output voltage | $I_{O} = -100 \ \mu A;$ $V_{CC(A)} = V_{CC(B)} = 0.8 \ V$ to 3.6 V | V _{CCO} - 0.1 | - | V _{CCO} - 0.1 | - | ٧ |
| | | $I_{O} = -3 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V}$ | 0.85 | - | 0.85 | - | ٧ |
| | | $I_{O} = -6 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.4 \text{ V}$ | 1.05 | - | 1.05 | - | ٧ |
| | | $I_{O} = -8 \text{ mA};$ $V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$ | 1.2 | - | 1.2 | - | ٧ |
| | | $I_{O} = -9 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$ | 1.75 | - | 1.75 | - | ٧ |
| | | $I_{O} = -12 \text{ mA};$ $V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$ | 2.3 | - | 2.3 | - | V |
| OL | LOW-level | $V_I = V_{IH} \text{ or } V_{IL}$ | | | | | |
| | output voltage | $I_O = 100~\mu A;$ $V_{CC(A)} = V_{CC(B)} = 0.8~V$ to 3.6 V | - | 0.1 | - | 0.1 | ٧ |
| | | $I_{O} = 3 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V}$ | - | 0.25 | - | 0.25 | ٧ |
| | | $I_{O} = 6 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.4 \text{ V}$ | - | 0.35 | - | 0.35 | ٧ |
| | | $I_{O} = 8 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$ | - | 0.45 | - | 0.45 | ٧ |
| | | $I_{O} = 9 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$ | - | 0.55 | - | 0.55 | ٧ |
| | | $I_{O} = 12 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$ | - | 0.7 | - | 0.7 | ٧ |
| | input leakage current | nDIR, n \overline{OE} input; V _I = 0 V or 3.6 V; V _{CC(A)} = V _{CC(B)} = 0.8 V to 3.6 V | - | ±1 | - | ±5 | μA |

74AVCH16T245

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 Table 7.
 Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | | -40 °C t | o +85 °C | –40 °C to | +125 °C | Unit |
|-------------------|----------------------|---|-----|------------|----------|------------|---------|------|
| | | | | Min | Max | Min | Max | |
| I _{BHL} | bus hold | A or B port | [3] | | | | | |
| | LOW current | $V_I = 0.49 \text{ V}; V_{CC(A)} = V_{CC(B)} = 1.4 \text{ V}$ | | 15 | - | 15 | - | μА |
| | | $V_I = 0.58 \text{ V};$ $V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$ | | 25 | - | 25 | - | μΑ |
| | | $V_{I} = 0.70 \text{ V}; V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$ | | 45 | - | 45 | - | μА |
| | | $V_{I} = 0.80 \text{ V}; V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$ | | 100 | - | 90 | - | μА |
| I _{BHH} | bus hold | A or B port | [4] | | | | | |
| | HIGH current | $V_I = 0.91 \text{ V}; V_{CC(A)} = V_{CC(B)} = 1.4 \text{ V}$ | | -15 | - | -15 | - | μА |
| | | $V_I = 1.07 \text{ V};$ $V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$ | | –25 | - | –25 | - | μΑ |
| | | $V_I = 1.60 \text{ V}; V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$ | | -45 | - | -45 | - | μА |
| | | $V_{I} = 2.00 \text{ V}; V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$ | | -100 | - | -100 | - | μА |
| I _{BHLO} | bus hold | A or B port | [5] | | | | | |
| | LOW overdrive | $V_{CC(A)} = V_{CC(B)} = 1.6 \text{ V}$ | | 125 | - | 125 | - | μΑ |
| | current | $V_{CC(A)} = V_{CC(B)} = 1.95 \text{ V}$ | | 200 | - | 200 | - | μΑ |
| | | $V_{CC(A)} = V_{CC(B)} = 2.7 \text{ V}$ | | 300 | - | 300 | - | μА |
| | | $V_{CC(A)} = V_{CC(B)} = 3.6 \text{ V}$ | | 500 | - | 500 | - | μА |
| I_{BHHO} | bus hold | A or B port | [6] | | | | | |
| | HIGH overdrive | $V_{CC(A)} = V_{CC(B)} = 1.6 \text{ V}$ | | -125 | - | -125 | - | μΑ |
| | current | $V_{CC(A)} = V_{CC(B)} = 1.95 \text{ V}$ | | -200 | - | -200 | - | μΑ |
| | | $V_{CC(A)} = V_{CC(B)} = 2.7 \text{ V}$ | | -300 | - | -300 | - | μΑ |
| | | $V_{CC(A)} = V_{CC(B)} = 3.6 \text{ V}$ | | -500 | - | -500 | - | μА |
| I_{OZ} | OFF-state output | A or B port; $V_O = 0 \ V$ or V_{CCO} ; $V_{CC(A)} = V_{CC(B)} = 3.6 \ V$ | [7] | - | ±5 | - | ±30 | μΑ |
| | current | suspend mode A port; $V_O = 0 \ V \ or \ V_{CC(A)}; \ V_{CC(A)} = 3.6 \ V; \ V_{CC(B)} = 0 \ V$ | [7] | - | ±5 | - | ±30 | μΑ |
| | | suspend mode B port; $V_O = 0 \ V \ or \ V_{CC(A)}; \ V_{CC(A)} = 0 \ V;$ $V_{CC(B)} = 3.6 \ V$ | [7] | - | ±5 | - | ±30 | μА |
| I _{OFF} | power-off leakage | A port; V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0.8$ V to 3.6 V | | - | ±5 | - | ±30 | μΑ |
| | current | B port; V_1 or V_0 = 0 V to 3.6 V; $V_{CC(B)}$ = 0 V; $V_{CC(A)}$ = 0.8 V to 3.6 V | | - | ±5 | - | ±30 | μΑ |

Table 7. Static characteristics ... continued [1][2]

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | -40 °C t | o +85 °C | –40 °C to | +125 °C | Unit | |
|-----------------|-----------|--|---|----------|-----------|---------|------|----|
| | | | Min | Max | Min | Max | | |
| I _{CC} | supply | A port; $V_I = 0 V \text{ or } V_{CCI}$; $I_O = 0 A$ | | | | | ' | |
| | current | $V_{CC(A)} = 0.8 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 0.8 \text{ V to } 3.6 \text{ V}$ | - | 30 | - | 125 | μА | |
| | | $V_{CC(A)} = 1.1 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$ | - | 25 | - | 100 | μА | |
| | | $V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$ | - | 25 | - | 100 | μΑ | |
| | | $V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 3.6 \text{ V}$ | -5 | - | -20 | - | μΑ | |
| | | B port; $V_I = 0 \text{ V or } V_{CCI}$; $I_O = 0 \text{ A}$ | | | | | | |
| | | | $V_{CC(A)} = 0.8 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 0.8 \text{ V to } 3.6 \text{ V}$ | - | 30 | - | 125 | μА |
| | | $V_{CC(A)} = 1.1 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$ | - | 25 | - | 100 | μА | |
| | | $V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$ | -5 | - | -20 | - | μΑ | |
| | | $V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 3.6 \text{ V}$ | - | 25 | - | 100 | μΑ | |
| | | A plus B port $(I_{CC(A)} + I_{CC(B)})$; $I_O = 0$ A; $V_I = 0$ V or V_{CCI} ; $V_{CC(A)} = 0.8$ V to 3.6 V; $V_{CC(B)} = 0.8$ V to 3.6 V | - | 55 | - | 185 | μΑ | |
| | | A plus B port ($I_{CC(A)} + I_{CC(B)}$); $I_O = 0$ A; $V_I = 0$ V or V_{CCI} ; $V_{CC(A)} = 1.1$ V to 3.6 V; $V_{CC(B)} = 1.1$ V to 3.6 V | - | 45 | - | 150 | μА | |

- [1] V_{CCO} is the supply voltage associated with the output port.
- [2] V_{CCI} is the supply voltage associated with the data input port.
- [3] The bus hold circuit can sink at least the minimum low sustaining current at V_{IL} max. I_{BHL} should be measured after lowering V_I to GND and then raising it to V_{IL} max.
- [4] The bus hold circuit can source at least the minimum high sustaining current at V_{IH} min. I_{BHH} should be measured after raising V_I to V_{CC} and then lowering it to V_{IH} min.
- [5] An external driver must source at least I_{BHLO} to switch this node from LOW to HIGH.
- [6] An external driver must sink at least I_{BHHO} to switch this node from HIGH to LOW.
- [7] For I/O ports, the parameter I_{OZ} includes the input leakage current.

Table 8. Typical total supply current $(I_{CC(A)} + I_{CC(B)})$

| V _{CC(A)} | V _{CC(B)} | | | | | | Unit | |
|--------------------|--------------------|-------|-------|-------|-------|-------|-------|----|
| | 0 V | 0.8 V | 1.2 V | 1.5 V | 1.8 V | 2.5 V | 3.3 V | |
| 0 V | 0 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | μΑ |
| 0.8 V | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.3 | 1.6 | μΑ |
| 1.2 V | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 8.0 | μΑ |
| 1.5 V | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.4 | μΑ |
| 1.8 V | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.2 | μΑ |
| 2.5 V | 0.1 | 0.3 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | μΑ |
| 3.3 V | 0.1 | 1.6 | 0.8 | 0.4 | 0.2 | 0.1 | 0.1 | μΑ |

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10. Dynamic characteristics

Table 9. Typical power dissipation capacitance at $V_{CC(A)} = V_{CC(B)}$ and $T_{amb} = 25$ °C [1][2] Voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | | | V _{CC(A)} = | V _{CC(B)} | | | Unit |
|----------|-------------------------------|---|-------|-------|----------------------|--------------------|-------|-------|------|
| | | | 0.8 V | 1.2 V | 1.5 V | 1.8 V | 2.5 V | 3.3 V | |
| C_{PD} | power dissipation capacitance | A port: (direction nAn to nBn); output enabled | 0.2 | 0.2 | 0.2 | 0.2 | 0.3 | 0.4 | pF |
| | | A port: (direction nAn to nBn); output disabled | 0.2 | 0.2 | 0.2 | 0.2 | 0.3 | 0.4 | pF |
| | | A port: (direction nBn to nAn); output enabled | 9 | 9.7 | 9.8 | 10.3 | 11.7 | 13.7 | pF |
| | | A port: (direction nBn to nAn); output disabled | 0.6 | 0.6 | 0.6 | 0.7 | 0.7 | 0.7 | pF |
| | | B port: (direction nAn to nBn); output enabled | 9 | 9.7 | 9.8 | 10.3 | 11.7 | 13.7 | pF |
| | | B port: (direction nAn to nBn); output disabled | 0.6 | 0.6 | 0.6 | 0.7 | 0.7 | 0.7 | pF |
| | | B port: (direction nBn to nAn); output enabled | 0.2 | 0.2 | 0.2 | 0.2 | 0.3 | 0.4 | pF |
| | | B port: (direction nBn to nAn); output disabled | 0.2 | 0.2 | 0.2 | 0.2 | 0.3 | 0.4 | pF |

^[1] C_{PD} is used to determine the dynamic power dissipation (P_D in μW).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where:

f_i = input frequency in MHz;

f_o = output frequency in MHz;

C_L = load capacitance in pF;

V_{CC} = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}{}^2 \times f_o) = sum \ of \ the \ outputs.$

[2] f_i = 10 MHz; V_I = GND to V_{CC} ; t_r = t_f = 1 ns; C_L = 0 pF; R_L = ∞ Ω .

Table 10. Typical dynamic characteristics at $V_{CC(A)} = 0.8 \text{ V}$ and $T_{amb} = 25 \,^{\circ}\text{C}$ [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

| Symbol | Parameter | Conditions | V _{CC(B)} | | | | | | Unit |
|------------------|-------------------|------------|--------------------|-------|-------|-------|-------|-------|------|
| | | | 0.8 V | 1.2 V | 1.5 V | 1.8 V | 2.5 V | 3.3 V | |
| t_{pd} | propagation delay | nAn to nBn | 14.4 | 7.0 | 6.2 | 6.0 | 5.9 | 6.0 | ns |
| | nBn to nAn | 14.4 | 12.4 | 12.1 | 11.9 | 11.8 | 11.8 | ns | |
| t _{dis} | disable time | nOE to nAn | 16.2 | 16.2 | 16.2 | 16.2 | 16.2 | 16.2 | ns |
| | | nOE to nBn | 17.6 | 10.0 | 9.0 | 9.1 | 8.7 | 9.3 | ns |
| t _{en} | enable time | nOE to nAn | 21.9 | 21.9 | 21.9 | 21.9 | 21.9 | 21.9 | ns |
| | | nOE to nBn | 22.2 | 11.1 | 9.8 | 9.4 | 9.4 | 9.6 | ns |

^[1] t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} .

Table 11. Typical dynamic characteristics at $V_{CC(B)} = 0.8 \text{ V}$ and $T_{amb} = 25 \,^{\circ}\text{C}$ [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

| Symbol | Parameter | Conditions | $V_{CC(A)}$ | | | | | | | | |
|-----------------------------------|--------------|------------|-------------|-------|-------|-------|-------|-------|----|--|--|
| | | | 0.8 V | 1.2 V | 1.5 V | 1.8 V | 2.5 V | 3.3 V | | | |
| t _{pd} propagation delay | | nAn to nBn | 14.4 | 12.4 | 12.1 | 11.9 | 11.8 | 11.8 | ns | | |
| | | nBn to nAn | 14.4 | 7.0 | 6.2 | 6.0 | 5.9 | 6.0 | ns | | |
| t _{dis} | disable time | nOE to nAn | 16.2 | 5.9 | 4.4 | 4.2 | 3.1 | 3.5 | ns | | |
| | | nOE to nBn | 17.6 | 14.2 | 13.7 | 13.6 | 13.3 | 13.1 | ns | | |
| t _{en} | enable time | nOE to nAn | 21.9 | 6.4 | 4.4 | 3.5 | 2.6 | 2.3 | ns | | |
| | | nOE to nBn | 22.2 | 17.7 | 17.2 | 17.0 | 16.8 | 16.7 | ns | | |

^[1] t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} .

Table 12. Dynamic characteristics for temperature range -40 °C to +85 °C [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 8</u>; for wave forms see <u>Figure 6</u> and <u>Figure 7</u>.

| | | | | * | | | · · · · · · · · · · · · · · · · · · · | | | | | | _ |
|----------------------|----------------|------------|-------|---------|-------|---------|---------------------------------------|--------|-------|---------|-------|---------|------|
| Symbol | Parameter | Conditions | | | | | | C(B) | | | | | Unit |
| | | | 1.2 V | ± 0.1 V | 1.5 V | ± 0.1 V | 1.8 V ± | 0.15 V | 2.5 V | ± 0.2 V | 3.3 V | ± 0.3 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| V _{CC(A)} = | 1.1 V to 1.3 V | | | | | | | | | | | | |
| t _{pd} | propagation | nAn to nBn | 0.5 | 9.2 | 0.5 | 6.9 | 0.5 | 6.0 | 0.5 | 5.1 | 0.5 | 4.9 | ns |
| | delay | nBn to nAn | 0.5 | 9.2 | 0.5 | 8.7 | 0.5 | 8.5 | 0.5 | 8.2 | 0.5 | 8.0 | ns |
| t _{dis} | disable time | nOE to nAn | 1.5 | 11.6 | 1.5 | 11.6 | 1.5 | 11.6 | 1.5 | 11.6 | 1.5 | 11.6 | ns |
| | | nOE to nBn | 1.5 | 12.5 | 1.5 | 9.7 | 1.5 | 9.5 | 1.0 | 8.1 | 1.0 | 8.9 | ns |
| t _{en} | enable time | nOE to nAn | 1.0 | 14.5 | 1.0 | 14.5 | 1.0 | 14.5 | 1.0 | 14.5 | 1.0 | 14.5 | ns |
| | | nOE to nBn | 1.1 | 14.9 | 1.1 | 11.0 | 1.1 | 9.6 | 1.0 | 8.1 | 1.0 | 7.7 | ns |
| V _{CC(A)} = | 1.4 V to 1.6 V | | | | | | | | | | | | |
| t _{pd} | propagation | nAn to nBn | 0.5 | 8.7 | 0.5 | 6.2 | 0.5 | 5.2 | 0.5 | 4.1 | 0.5 | 3.7 | ns |
| | delay | nBn to nAn | 0.5 | 6.9 | 0.5 | 6.2 | 0.5 | 5.9 | 0.5 | 5.6 | 0.5 | 5.5 | ns |
| t _{dis} | disable time | nOE to nAn | 1.5 | 9.1 | 1.5 | 9.1 | 1.5 | 9.1 | 1.5 | 9.1 | 1.5 | 9.1 | ns |
| | | nOE to nBn | 1.5 | 11.4 | 1.5 | 8.7 | 1.5 | 7.5 | 1.0 | 6.5 | 1.0 | 6.3 | ns |
| t _{en} | enable time | nOE to nAn | 1.0 | 10.1 | 1.0 | 10.1 | 1.0 | 10.1 | 1.0 | 10.1 | 1.0 | 10.1 | ns |
| | | nOE to nBn | 1.0 | 13.5 | 1.0 | 10.1 | 0.5 | 8.1 | 0.5 | 5.9 | 0.5 | 5.2 | ns |
| V _{CC(A)} = | 1.65 V to 1.95 | V | | | | | | | | | | | |
| t _{pd} | propagation | nAn to nBn | 0.5 | 8.5 | 0.5 | 5.9 | 0.5 | 4.8 | 0.5 | 3.7 | 0.5 | 3.3 | ns |
| | delay | nBn to nAn | 0.5 | 6.0 | 0.5 | 5.2 | 0.5 | 4.8 | 0.5 | 4.5 | 0.5 | 4.4 | ns |
| t _{dis} | disable time | nOE to nAn | 1.5 | 7.7 | 1.5 | 7.7 | 1.5 | 7.7 | 1.5 | 7.7 | 1.5 | 7.7 | ns |
| | | nOE to nBn | 1.5 | 11.1 | 1.5 | 8.4 | 1.5 | 7.1 | 1.0 | 5.9 | 1.0 | 5.7 | ns |
| t _{en} | enable time | nOE to nAn | 1.0 | 7.8 | 1.0 | 7.8 | 1.0 | 7.8 | 1.0 | 7.8 | 1.0 | 7.8 | ns |
| | | nOE to nBn | 1.0 | 13.0 | 1.0 | 9.2 | 0.5 | 7.4 | 0.5 | 5.3 | 0.5 | 4.5 | ns |
| V _{CC(A)} = | 2.3 V to 2.7 V | | | | | | | | | | | | |
| t _{pd} | propagation | nAn to nBn | 0.5 | 8.2 | 0.5 | 5.6 | 0.5 | 4.6 | 0.5 | 3.3 | 0.5 | 2.8 | ns |
| | delay | nBn to nAn | 0.5 | 5.1 | 0.5 | 4.1 | 0.5 | 3.7 | 0.5 | 3.4 | 0.5 | 3.2 | ns |
| t _{dis} | disable time | nOE to nAn | 1.0 | 6.1 | 1.0 | 6.1 | 1.0 | 6.1 | 1.0 | 6.1 | 1.0 | 6.1 | ns |
| | | nOE to nBn | 1.0 | 10.6 | 1.0 | 7.9 | 1.0 | 6.6 | 1.0 | 6.1 | 1.0 | 5.2 | ns |
| t _{en} | enable time | nOE to nAn | 0.5 | 5.3 | 0.5 | 5.3 | 0.5 | 5.3 | 0.5 | 5.3 | 0.5 | 5.3 | ns |
| | | nOE to nBn | 0.5 | 12.5 | 0.5 | 9.4 | 0.5 | 7.3 | 0.5 | 5.1 | 0.5 | 4.5 | ns |
| V _{CC(A)} = | 3.0 V to 3.6 V | | | | | | | | | | | | |
| t _{pd} | propagation | nAn to nBn | 0.5 | 8.0 | 0.5 | 5.5 | 0.5 | 4.4 | 0.5 | 3.2 | 0.5 | 2.7 | ns |
| * | delay | nBn to nAn | 0.5 | 4.9 | 0.5 | 3.7 | 0.5 | 3.3 | 0.5 | 2.9 | 0.5 | 2.7 | ns |
| t _{dis} | disable time | nOE to nAn | 0.5 | 5.0 | 0.5 | 5.0 | 0.5 | 5.0 | 0.5 | 5.0 | 0.5 | 5.0 | ns |
| | | nOE to nBn | 1.0 | 10.3 | 1.0 | 7.7 | 1.0 | 6.5 | 1.0 | 5.2 | 0.5 | 5.0 | ns |
| t _{en} | enable time | nOE to nAn | 0.5 | 4.3 | 0.5 | 4.3 | 0.5 | 4.2 | 0.5 | 4.1 | 0.5 | 4.0 | ns |
| 311 | | nOE to nBn | 0.5 | 12.4 | 0.5 | 9.3 | 0.5 | 7.2 | 0.5 | 4.9 | 0.5 | 4.0 | ns |

^[1] t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} .

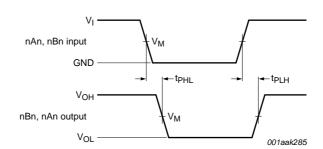
Table 13. Dynamic characteristics for temperature range –40 °C to +125 °C [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

| Symbol | Parameter | Conditions | | | | | Vc | C(B) | | | | | Unit |
|----------------------|----------------|------------|-------|---------|-------|---------|---------|----------|-------|---------|-------|---------|------|
| | | | 1.2 V | ± 0.1 V | 1.5 V | ± 0.1 V | 1.8 V ± | ± 0.15 V | 2.5 V | ± 0.2 V | 3.3 V | ± 0.3 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| V _{CC(A)} = | 1.1 V to 1.3 V | · | | 1 | | | | 1 | | | | | |
| t _{pd} | propagation | nAn to nBn | 0.5 | 10.2 | 0.5 | 7.6 | 0.5 | 6.6 | 0.5 | 5.7 | 0.5 | 5.4 | ns |
| | delay | nBn to nAn | 0.5 | 10.2 | 0.5 | 9.6 | 0.5 | 9.4 | 0.5 | 9.1 | 0.5 | 8.8 | ns |
| t _{dis} | disable time | nOE to nAn | 1.5 | 12.8 | 1.5 | 12.8 | 1.5 | 12.8 | 1.5 | 12.8 | 1.5 | 12.8 | ns |
| | | nOE to nBn | 1.5 | 13.8 | 1.5 | 10.7 | 1.5 | 10.5 | 1.0 | 9.0 | 1.5 | 9.8 | ns |
| t _{en} | enable time | nOE to nAn | 1.0 | 16.0 | 1.0 | 16.0 | 1.0 | 16.0 | 1.0 | 16.0 | 1.0 | 16.0 | ns |
| | | nOE to nBn | 1.1 | 16.4 | 1.1 | 12.1 | 1.1 | 10.6 | 1.0 | 9.0 | 1.0 | 8.5 | ns |
| V _{CC(A)} = | 1.4 V to 1.6 V | | | | | | | | | | | | |
| t _{pd} | propagation | nAn to nBn | 0.5 | 9.6 | 0.5 | 6.9 | 0.5 | 5.8 | 0.5 | 4.6 | 0.5 | 4.1 | ns |
| | delay | nBn to nAn | 0.5 | 7.6 | 0.5 | 6.9 | 0.5 | 6.5 | 0.5 | 6.2 | 0.5 | 6.1 | ns |
| t _{dis} | disable time | nOE to nAn | 1.5 | 10.1 | 1.5 | 10.1 | 1.5 | 10.1 | 1.5 | 10.1 | 1.5 | 10.1 | ns |
| | | nOE to nBn | 1.5 | 12.6 | 1.5 | 9.6 | 1.5 | 8.3 | 1.0 | 7.2 | 1.0 | 7.0 | ns |
| t _{en} | enable time | nOE to nAn | 1.0 | 11.2 | 1.0 | 11.2 | 1.0 | 11.2 | 1.0 | 11.2 | 1.0 | 11.2 | ns |
| | | nOE to nBn | 1.0 | 14.9 | 1.0 | 11.2 | 0.5 | 9.0 | 0.5 | 6.5 | 0.5 | 5.8 | ns |
| V _{CC(A)} = | 1.65 V to 1.95 | V | | | | | | | | | | | |
| t _{pd} | propagation | nAn to nBn | 0.5 | 9.4 | 0.5 | 6.5 | 0.5 | 5.3 | 0.5 | 4.1 | 0.5 | 3.7 | ns |
| | delay | nBn to nAn | 0.5 | 6.6 | 0.5 | 5.8 | 0.5 | 5.3 | 0.5 | 5.0 | 0.5 | 4.9 | ns |
| t _{dis} | disable time | nOE to nAn | 1.5 | 8.5 | 1.5 | 8.5 | 1.5 | 8.5 | 1.5 | 8.5 | 1.5 | 8.5 | ns |
| | | nOE to nBn | 1.5 | 12.3 | 1.5 | 9.3 | 1.5 | 7.9 | 1.0 | 6.5 | 1.0 | 6.3 | ns |
| t _{en} | enable time | nOE to nAn | 1.0 | 8.6 | 1.0 | 8.6 | 1.0 | 8.6 | 1.0 | 8.6 | 1.0 | 8.6 | ns |
| | | nOE to nBn | 1.0 | 14.3 | 1.0 | 10.2 | 0.5 | 8.2 | 0.5 | 5.9 | 0.5 | 5.0 | ns |
| V _{CC(A)} = | 2.3 V to 2.7 V | | | | | | | | | | | | |
| t _{pd} | propagation | nAn to nBn | 0.5 | 9.1 | 0.5 | 6.2 | 0.5 | 5.1 | 0.5 | 3.7 | 0.5 | 3.1 | ns |
| | delay | nBn to nAn | 0.5 | 5.7 | 0.5 | 4.6 | 0.5 | 4.1 | 0.5 | 3.8 | 0.5 | 3.6 | ns |
| t _{dis} | disable time | nOE to nAn | 1.0 | 6.8 | 1.0 | 6.8 | 1.0 | 6.8 | 1.0 | 6.8 | 1.0 | 6.8 | ns |
| | | nOE to nBn | 1.0 | 11.7 | 1.0 | 8.7 | 1.0 | 7.3 | 1.0 | 6.8 | 1.0 | 5.8 | ns |
| t _{en} | enable time | nOE to nAn | 0.5 | 5.9 | 0.5 | 5.9 | 0.5 | 5.9 | 0.5 | 5.9 | 0.5 | 5.9 | ns |
| | | nOE to nBn | 0.5 | 13.8 | 0.5 | 10.4 | 0.5 | 8.1 | 0.5 | 5.7 | 0.5 | 5.0 | ns |
| V _{CC(A)} = | 3.0 V to 3.6 V | | | | | | | | | | | | |
| t_{pd} | propagation | nAn to nBn | 0.5 | 8.8 | 0.5 | 6.1 | 0.5 | 4.9 | 0.5 | 3.6 | 0.5 | 3.0 | ns |
| | delay | nBn to nAn | 0.5 | 5.4 | 0.5 | 4.1 | 0.5 | 3.7 | 0.5 | 3.2 | 0.5 | 3.0 | ns |
| t_{dis} | disable time | nOE to nAn | 0.5 | 5.5 | 0.5 | 5.5 | 0.5 | 5.5 | 0.5 | 5.5 | 0.5 | 5.5 | ns |
| | | nOE to nBn | 1.0 | 11.4 | 1.0 | 8.5 | 1.0 | 7.2 | 1.0 | 5.8 | 0.5 | 5.5 | ns |
| t _{en} | enable time | nOE to nAn | 0.5 | 4.8 | 0.5 | 4.8 | 0.5 | 4.7 | 0.5 | 4.6 | 0.5 | 4.4 | ns |
| | | nOE to nBn | 0.5 | 13.7 | 0.5 | 10.3 | 0.5 | 8.0 | 0.5 | 5.4 | 0.5 | 4.4 | ns |

^[1] t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} .

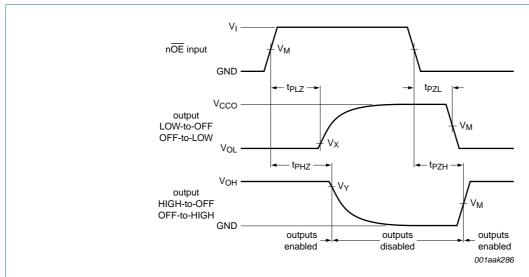
11. Waveforms



Measurement points are given in Table 14.

 $\ensuremath{V_{\text{OL}}}$ and $\ensuremath{V_{\text{OH}}}$ are typical output voltage levels that occur with the output load.

Fig 6. The data input (nAn, nBn) to output (nBn, nAn) propagation delay times



Measurement points are given in Table 14.

V_{OL} and V_{OH} are typical output voltage levels that occur with the output load.

Fig 7. Enable and disable times

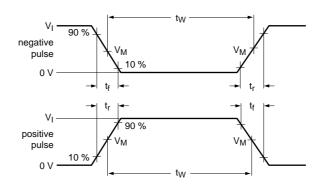
Table 14. Measurement points

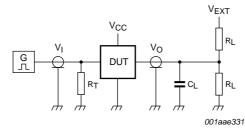
| Supply voltage | Input ^[1] | Output ^[2] | | |
|---|----------------------|-----------------------|--------------------------|--------------------------|
| V _{CC(A)} , V _{CC(B)} | V _M | V _M | V _X | V _Y |
| 0.8 V to 1.6 V | 0.5V _{CCI} | 0.5V _{CCO} | $V_{OL} + 0.1 V$ | $V_{OH}-0.1\ V$ |
| 1.65 V to 2.7 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.15 V | V _{OH} – 0.15 V |
| 3.0 V to 3.6 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.3 V | V _{OH} – 0.3 V |

^[1] V_{CCI} is the supply voltage associated with the data input port.

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^[2] V_{CCO} is the supply voltage associated with the output port.





Test data is given in Table 15.

R_L = Load resistance.

C_L = Load capacitance including jig and probe capacitance.

 R_T = Termination resistance.

 V_{EXT} = External voltage for measuring switching times.

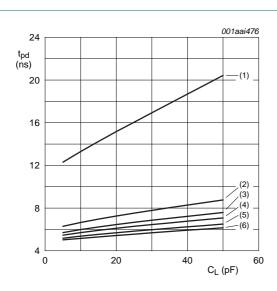
Fig 8. Test circuit for measuring switching times

Table 15. Test data

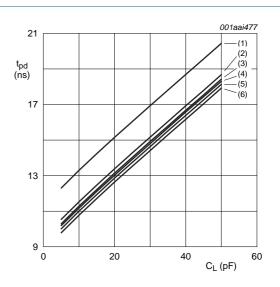
| Supply voltage | Input | | Load | Load | | V _{EXT} | | | |
|---|--------------------|-----------------|-------|----------------|-------------------------------------|-------------------------------------|---|--|--|
| V _{CC(A)} , V _{CC(B)} | V _I [1] | Δt/ΔV[2] | CL | R _L | t _{PLH} , t _{PHL} | t _{PZH} , t _{PHZ} | t _{PZL} , t _{PLZ} [3] | | |
| 0.8 V to 1.6 V | V_{CCI} | \leq 1.0 ns/V | 15 pF | 2 kΩ | open | GND | 2V _{CCO} | | |
| 1.65 V to 2.7 V | V _{CCI} | \leq 1.0 ns/V | 15 pF | 2 kΩ | open | GND | 2V _{CCO} | | |
| 3.0 V to 3.6 V | V _{CCI} | \leq 1.0 ns/V | 15 pF | 2 kΩ | open | GND | 2V _{CCO} | | |

- [1] V_{CCI} is the supply voltage associated with the data input port.
- [2] dV/dt ≥ 1.0 V/ns
- [3] V_{CCO} is the supply voltage associated with the output port.

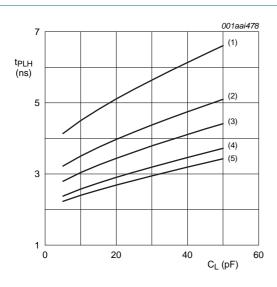
12. Typical propagation delay characteristics

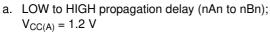


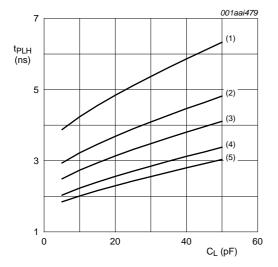
- a. Propagation delay (nAn to nBn); $V_{CC(A)} = 0.8 \text{ V}$
- (1) $V_{CC(B)} = 0.8 \text{ V}.$
- (2) $V_{CC(B)} = 1.2 \text{ V}.$
- (3) $V_{CC(B)} = 1.5 \text{ V}.$
- (4) $V_{CC(B)} = 1.8 \text{ V}.$
- (5) $V_{CC(B)} = 2.5 \text{ V}.$
- (6) $V_{CC(B)} = 3.3 \text{ V}.$



- b. Propagation delay (nAn to nBn); $V_{CC(B)} = 0.8 \text{ V}$
- (1) $V_{CC(A)} = 0.8 \text{ V}.$
- (2) $V_{CC(A)} = 1.2 \text{ V}.$
- (3) $V_{CC(A)} = 1.5 \text{ V}.$
- (4) $V_{CC(A)} = 1.8 \text{ V}.$ (5) $V_{CC(A)} = 2.5 \text{ V}.$
- (6) $V_{CC(A)} = 3.3 \text{ V}.$
- Fig 9. Typical propagation delay versus load capacitance; $T_{amb} = 25$ °C



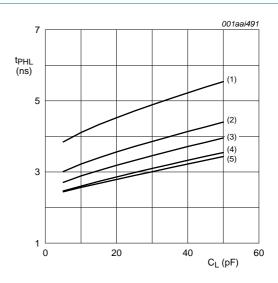




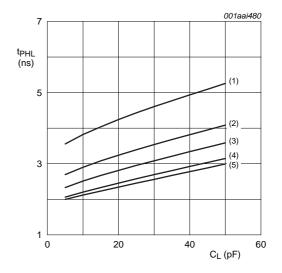
c. LOW to HIGH propagation delay (nAn to nBn); $V_{CC(A)} = 1.5 \text{ V}$



- (2) $V_{CC(B)} = 1.5 \text{ V}.$
- (3) $V_{CC(B)} = 1.8 \text{ V}.$
- (4) $V_{CC(B)} = 2.5 \text{ V}.$
- (5) $V_{CC(B)} = 3.3 \text{ V}.$

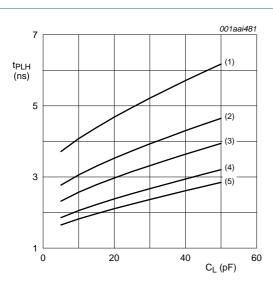


b. HIGH to LOW propagation delay (nAn to nBn); $V_{CC(A)} = 1.2 \text{ V}$

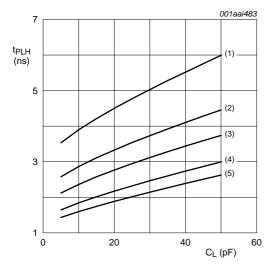


d. HIGH to LOW propagation delay (nAn to nBn); $V_{CC(A)} = 1.5 \text{ V}$

Fig 10. Typical propagation delay versus load capacitance; T_{amb} = 25 °C

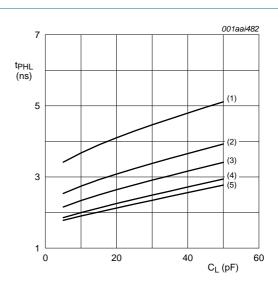


a. LOW to HIGH propagation delay (nAn to nBn); $V_{\text{CC}(A)} = 1.8 \text{ V}$

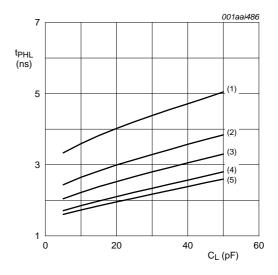


c. LOW to HIGH propagation delay (nAn to nBn); $V_{\text{CC(A)}} = 2.5 \text{ V}$

- (1) $V_{CC(B)} = 1.2 \text{ V}.$
- (2) $V_{CC(B)} = 1.5 \text{ V}.$
- (3) $V_{CC(B)} = 1.8 \text{ V}.$
- (4) $V_{CC(B)} = 2.5 \text{ V}.$
- (5) $V_{CC(B)} = 3.3 \text{ V}.$

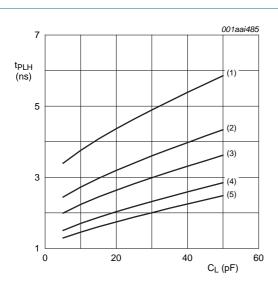


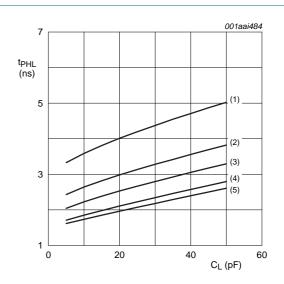
b. HIGH to LOW propagation delay (nAn to nBn); $V_{CC(A)} = 1.8 \text{ V}$



d. HIGH to LOW propagation delay (nAn to nBn); $V_{CC(A)} = 2.5 \text{ V}$

Fig 11. Typical propagation delay versus load capacitance; T_{amb} = 25 °C





- a. LOW to HIGH propagation delay (nAn to nBn); $V_{\text{CC(A)}} = 3.3 \text{ V}$
- b. HIGH to LOW propagation delay (nAn to nBn); $V_{CC(A)} = 3.3 \text{ V}$

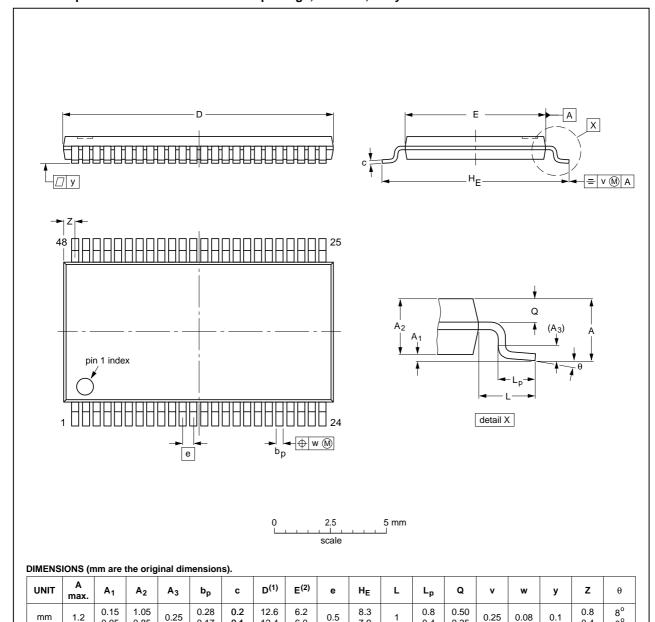
- (1) $V_{CC(B)} = 1.2 \text{ V}.$
- (2) $V_{CC(B)} = 1.5 \text{ V}.$
- (3) $V_{CC(B)} = 1.8 \text{ V}.$
- (4) $V_{CC(B)} = 2.5 \text{ V}.$
- (5) $V_{CC(B)} = 3.3 \text{ V}.$

Fig 12. Typical propagation delay versus load capacitance; T_{amb} = 25 °C

13. Package outline

TSSOP48: plastic thin shrink small outline package; 48 leads; body width 6.1 mm

SOT362-1



1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.

0.17

12.4

2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

| OUTLINE | | REFER | ENCES | EUROPEAN | ISSUE DATE |
|----------|-----|--------|-------|------------|---------------------------------|
| VERSION | IEC | JEDEC | JEITA | PROJECTION | ISSUE DATE |
| SOT362-1 | | MO-153 | | | 99-12-27 03-02-19 |

7.9

Fig 13. Package outline SOT362-1 (TSSOP48)

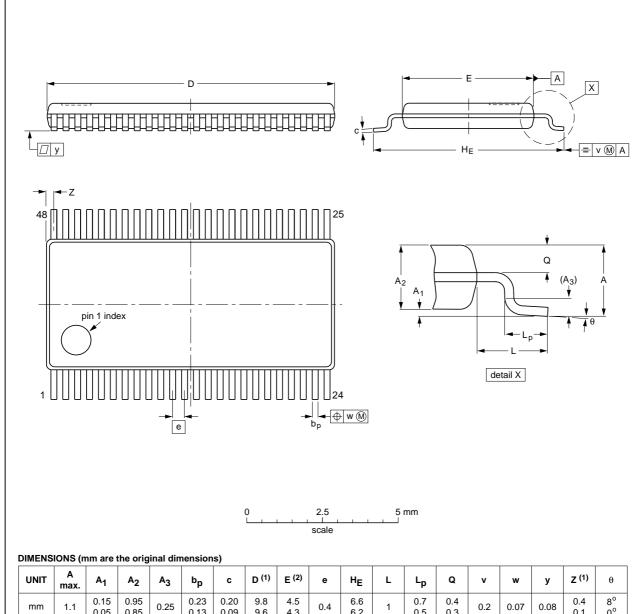
0.05

0.85

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TSSOP48: plastic thin shrink small outline package; 48 leads; body width 4.4 mm; lead pitch 0.4 mm

SOT480-1



| UNIT | A max. | A ₁ | A ₂ | A ₃ | bp | С | D (1) | E (2) | е | HE | L | Lp | Q | v | w | у | Z (1) | θ |
|------|-----------|----------------|----------------|----------------|--------------|--------------|------------|------------|-----|------------|---|------------|------------|-----|------|------|------------|----------|
| mm | 1.1 | 0.15 0.05 | 0.95 0.85 | 0.25 | 0.23 0.13 | 0.20 0.09 | 9.8 9.6 | 4.5 4.3 | 0.4 | 6.6 6.2 | 1 | 0.7 0.5 | 0.4 0.3 | 0.2 | 0.07 | 0.08 | 0.4 0.1 | 8° 0° |

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

| | OUTLINE | | REFER | EUROPEAN | ISSUE DATE | | | |
|---|----------|-----|--------|----------|------------|------------|---------------------------------|---|
| | VERSION | IEC | JEDEC | JEITA | | PROJECTION | ISSUE DATE | |
| | SOT480-1 | | MO-153 | | | | 99-12-27 03-02-18 | |
| _ | | | | | | | | • |

Fig 14. Package outline SOT480-1 (TSSOP48)

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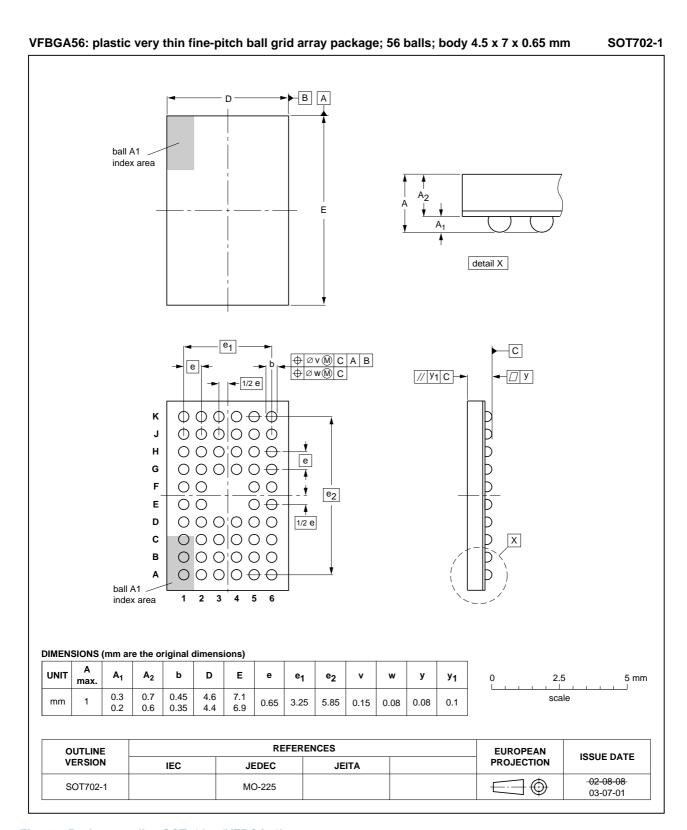


Fig 15. Package outline SOT702-1 (VFBGA56)

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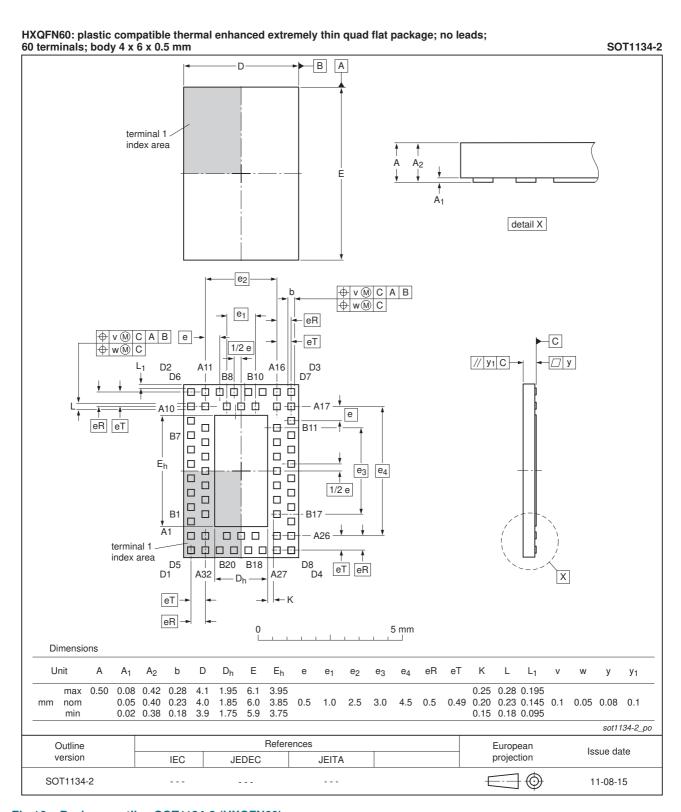


Fig 16. Package outline SOT1134-2 (HXQFN60)

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14. Abbreviations

Table 16. Abbreviations

| Acronym | Description |
|---------|-------------------------|
| CDM | Charged Device Model |
| DUT | Device Under Test |
| ESD | ElectroStatic Discharge |
| НВМ | Human Body Model |
| MM | Machine Model |

15. Revision history

Table 17. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|------------------|----------------------------------|------------------------|------------------------|------------------|
| | | | 290000 | • |
| 74AVCH16T245 v.5 | 20120301 | Product data sheet | - | 74AVCH16T245 v.4 |
| Modifications: | For type nur | mber 74AVCH16T245BX th | ne SOT code has change | ed to SOT1134-2. |
| 74AVCH16T245 v.4 | 20111207 | Product data sheet | - | 74AVCH16T245 v.3 |
| Modifications: | Legal pages | updated. | | |
| 74AVCH16T245 v.3 | 20110616 | Product data sheet | - | 74AVCH16T245 v.2 |
| 74AVCH16T245 v.2 | 20100329 | Product data sheet | - | 74AVCH16T245 v.1 |
| 74AVCH16T245 v.1 | 20091014 | Product data sheet | - | - |
| | | | | |

16. Legal information

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| Document status[1][2] | Product status[3] | Definition |
|--------------------------------|-------------------|---|
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| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

- [1] Please consult the most recently issued document before initiating or completing a design
- [2] The term 'short data sheet' is explained in section "Definitions"
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