

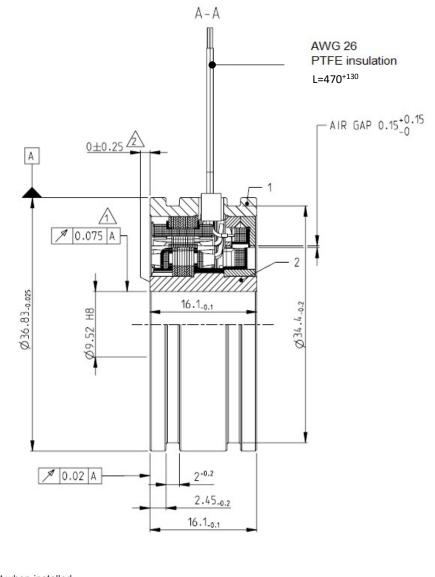
Part Number	1-1414631-0			
Description	V23401- S1001-B101			
Size	15			
Shaft inner diameter [mm]	9.52H8	}		
Speed (pair of poles) [p]	1			
Number of poles	2		Customer PN	
Application Specification	114 – 160394			
Test protocol	Results saved to manufacturing site archives. Available by request.			
Input voltage (V <sub>rms</sub> ) [V]	7.0		Input resistance R1–R2 [Ω]	82
Frequency (typical) [kHz]	10.0		R1–R2 tolerance [%]	± 10
Input current max [mA]	40		Output resistance S1–S3 or S2–S4 [Ω]	68
Transformation ratio $(r_T)$	0.50	Based on specified	S1–S3 or S2–S4 tolerance [%]	± 10
Transf. ratio tolerance [%]	± 4	Input voltage and		
Phase shift (ψ) min [⁰]	-2	Frequency	Z <sub>RO</sub> [Ω] (±15%) = 133+j154	
Phase shift (ψ) max [º]	8		Z <sub>RS</sub> [Ω] (±15%) = 117+j134	
Angular Error <sup>[1]</sup> max [']	± 10 (20)		Z <sub>SO</sub> [Ω] (±15%) = 121+j189	
Residual voltage max [mV]	25		Z <sub>SS</sub> [Ω] (±15%) = 205+j341	
<sup>[1]</sup> Angular error spread $\Delta arphi$ = $arphi$ <sub>ei</sub> - $arphi$	<sub>mech</sub> .p	Electrica	data measured at room temperature (22°C).	
High Voltage test	Voltage:	500V <sub>AC</sub> (A)	Measured between:	
	250V <sub>AC</sub> (B)		A: Winding R1–R2 and housing	
	Time: 1s		Winding S1–S3 and housing	
			Winding S2–S4 and housing	
Isolation test	Voltage: 500V <sub>DC</sub> (A,B)		B: Windings S1–S3 and S2–S4	
	Criterium R <sub>isol.</sub> > 50MΩ			
"Zero" setting	Electrical "0" is when Coils $V_{\rm S2-S4}$ = 0 and $V_{\rm S1-S3}$ are in phase with $V_{\rm R1-R2}$			
Transfer function	Looking at transformation part and turning rotor clockwise			
	$V_{S1-S3} = +r_T * V_{R1-R2} * \cos(p*\alpha)$			
	$V_{S2-S4} = +r_T * V_{R1-R2} * sin(p*\alpha)$			
Rotor Inertia	approx. 20g.cm <sup>2</sup>			
Max. Rotational Speed	20 000 rpm			
Shock resistance (11ms sine)	1000 m/s <sup>2</sup>			
Vibration	200 m/s <sup>2</sup>			
Operating temperature	-55°C+150°C			
Permissible radial runout	0.075 mm			
Permissible axial offset	± 0.25 mm			

## DATA SHEET - HOLLOW SHAFT RESOLVER

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 $\triangle$  Total runout when installed

Axial offset

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