

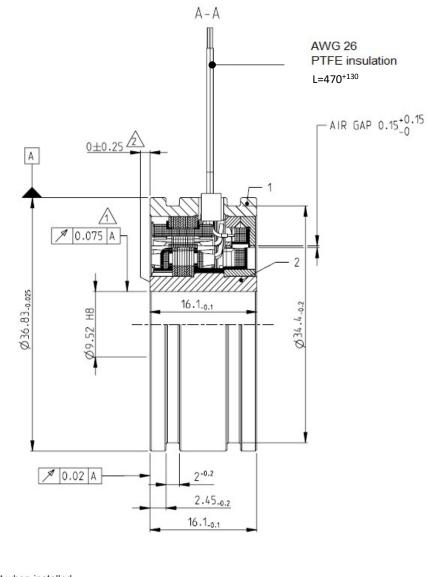
Part Number	1-1414631-0			
Description	V23401- S1001-B101			
Size	15			
Shaft inner diameter [mm]	9.52H8	}		
Speed (pair of poles) [p]	1			
Number of poles	2		Customer PN	
Application Specification	114 – 160394			
Test protocol	Results saved to manufacturing site archives. Available by request.			
Input voltage (V _{rms}) [V]	7.0		Input resistance R1–R2 [Ω]	82
Frequency (typical) [kHz]	10.0		R1–R2 tolerance [%]	± 10
Input current max [mA]	40		Output resistance S1–S3 or S2–S4 [Ω]	68
Transformation ratio (r_T)	0.50	Based on specified	S1–S3 or S2–S4 tolerance [%]	± 10
Transf. ratio tolerance [%]	± 4	Input voltage and		
Phase shift (ψ) min [⁰]	-2	Frequency	Z _{RO} [Ω] (±15%) = 133+j154	
Phase shift (ψ) max [º]	8		Z _{RS} [Ω] (±15%) = 117+j134	
Angular Error ^[1] max [']	± 10 (20)		Z _{SO} [Ω] (±15%) = 121+j189	
Residual voltage max [mV]	25		Z _{SS} [Ω] (±15%) = 205+j341	
^[1] Angular error spread $\Delta arphi$ = $arphi$ _{ei} - $arphi$	_{mech} .p	Electrica	data measured at room temperature (22°C).	
High Voltage test	Voltage:	500V _{AC} (A)	Measured between:	
	250V _{AC} (B)		A: Winding R1–R2 and housing	
	Time: 1s		Winding S1–S3 and housing	
			Winding S2–S4 and housing	
Isolation test	Voltage: 500V _{DC} (A,B)		B: Windings S1–S3 and S2–S4	
	Criterium R _{isol.} > 50MΩ			
"Zero" setting	Electrical "0" is when Coils $V_{\rm S2-S4}$ = 0 and $V_{\rm S1-S3}$ are in phase with $V_{\rm R1-R2}$			
Transfer function	Looking at transformation part and turning rotor clockwise			
	$V_{S1-S3} = +r_T * V_{R1-R2} * \cos(p*\alpha)$			
	$V_{S2-S4} = +r_T * V_{R1-R2} * sin(p*\alpha)$			
Rotor Inertia	approx. 20g.cm ²			
Max. Rotational Speed	20 000 rpm			
Shock resistance (11ms sine)	1000 m/s ²			
Vibration	200 m/s ²			
Operating temperature	-55°C+150°C			
Permissible radial runout	0.075 mm			
Permissible axial offset	± 0.25 mm			

DATA SHEET - HOLLOW SHAFT RESOLVER

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 \triangle Total runout when installed

Axial offset

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