

# **TMR1305**

TMR Z-Axis Omnipolar Switch

### **General Description**

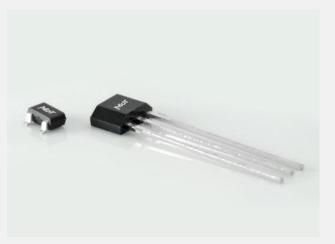
TMR1305 is a digital omnipolar magnetic switch that integrates TMR and CMOS technology in order to provide a magnetically triggered digital switch with high sensitivity, high speed, and ultra-low power consumption. It is designed for use in applications that are both power-critical and performance-demanding. It contains a push-pull half-bridge TMR magnetic sensor and CMOS signal processing circuitry within the same package, including an on-chip TMR voltage generator for precise magnetic sensing, a TMR voltage amplifier and comparator plus a Schmitt trigger to provide switching hysteresis for noise rejection, and CMOS push-pull output. An internal band gap regulator is used to provide a temperature compensated supply voltage for internal circuits, permitting a wide range of supply voltages. The TMR1305 draws only 2µA resulting in ultra-low power operation. It has fast response, accurate switching points, excellent thermal stability, and immunity to stray field interference. It is available in the SOT23-3 package (P/N TMR1305S) or the TO-92S package (P/N TMR1305T).

#### **Features and Benefits**

- Tunneling Magnetoresistance (TMR) Technology
- Ultra Low Power Consumption at 2uA
- High Frequency Response > 1kHz
- Operation with North or South Pole
- Low Switching Points for High Sensitivity
- Compatible with a Wide Range of Supply Voltages
- Excellent Thermal Stability
- High Tolerance to External Magnetic Field Interference

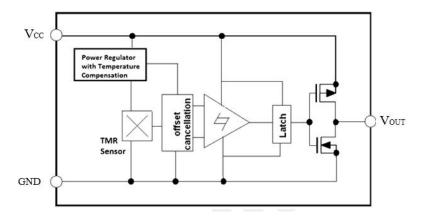
### **Applications**

- Utility Meters including Water, Gas, and Heat Meters
- Proximity Switches
- Position and Speed Sensing
- Motor and Fan Control

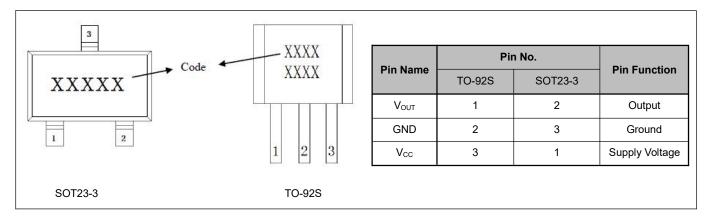


TMR1305S (Left), TMR1305T (Right)

#### **Block Diagram**



# **Pin Configuration**



# **Absolute Maximum Ratings**

Parameter	Symbol	Limit	Unit
Supply Voltage	Vcc	7	V
Reverse Supply Voltage	V <sub>RCC</sub>	0.3	V
Output Current	loutsink	9	mA
Magnetic Flux Density	В	2800	G
ESD level(HBM)	Vesd	2	kV
Operating Ambient Temperature	T <sub>A</sub>	-40 ~125	°C
Storage Temperature	T <sub>stg</sub>	-50 ~ 150	°C

# Electrical Characteristics (V<sub>CC</sub>=3.0V, T<sub>A</sub>=25°C)

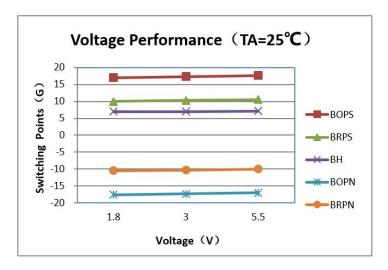
Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
Supply Voltage	V <sub>CC</sub>	Operating	1.8	3.0	5.5	V
Output High Voltage	V <sub>OH</sub>		Vcc-0.3	-	Vcc	V
Output Low Voltage	VoL		0	-	0.2	٧
Supply Current	Icc	Output Open	-	2.0	2.5	μA
Response Frequency	F		-	1000	-	Hz

Note: a 100nF capacitor is connected between  $V_{\text{CC}}$  and GND during all tests in the above table.

# Magnetic Characteristics ( $V_{CC} = 3.0V$ , $T_A = 25$ °C)

Parameters	Symbol	Min	Тур.	Max	Units
On a water Delint	Bops	8	-	34	G
Operate Point	B <sub>OPN</sub>	-34	-	-8	G
Release Point	B <sub>RPS</sub>	5	-	30	G
	B <sub>RPN</sub>	-30	-	-5	G
Hysteresis	Вн	3	-	15	G

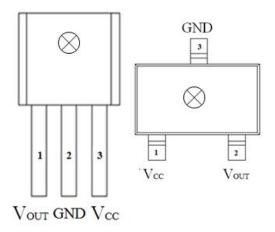
### **Voltage Characteristics**



### **Output Behavior vs. Magnetic Pole**

Parameter	Test Conditions	Output	
South Pole	B > B <sub>OPS</sub>	Low (On)	
South Fole	0< B < B <sub>RPS</sub>	High (Off)	
North Pole	B < B <sub>OPN</sub>	Low (On)	
Note Pole	0 > B > B <sub>RPN</sub>	High (Off)	

Note: when power is turned on under zero magnetic field, the output is "High".



OUTPUT OFF

BOPN

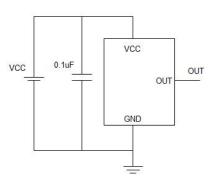
Sensing Direction of Magnetic Field

Magnetic Flux

### **Application Information**

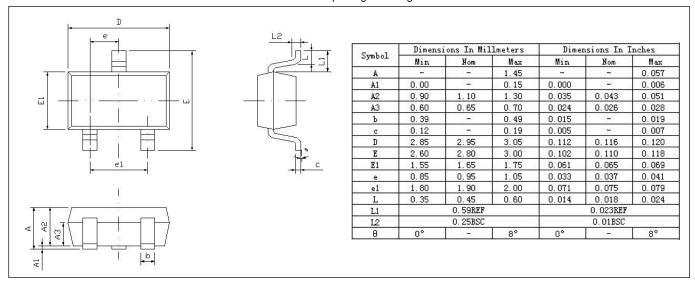
The output of the TMR1305 switches low (turns on) when a magnetic field to the sensing axis exceeds the operate point threshold,  $B_{OP}$ . When the magnetic field is reduced below the release point,  $B_{RP}$ , the device output switches high (turns off). The difference between the  $B_{OP}$  and  $B_{RP}$  is the hysteresis  $B_H$  of the device.

It is strongly recommended that an external bypass capacitor be connected in close proximity to the device between the supply and ground pins to reduce noise. The recommended value for the external bypass capacitor is  $0.1\mu F$ .

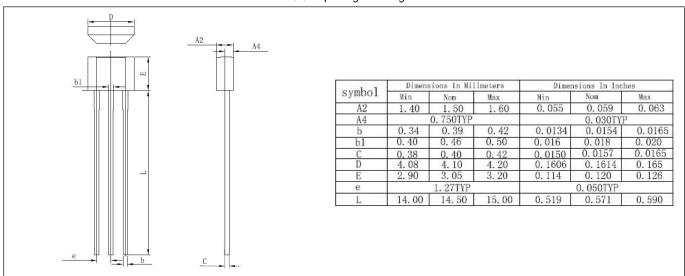


### **Package Information**

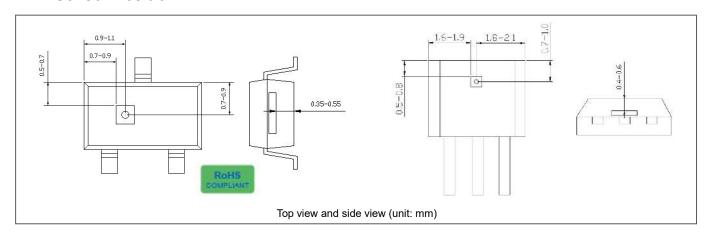
### SOT23-3 package drawing



TO-92S package drawing



#### **TMR Sensor Position**







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