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# **FAN104W High-Frequency Primary-Side-Regulation PWM Controller**

### **Features**

- Achieves <30 mW; Energy Star's 5-Star Level
- Proprietary 500 V High-Voltage JFET Startup Reduces Startup Resistor Loss
- Low Operation Current in Burst Mode: 600 µA
- Constant-Voltage (CV) and Constant-Current (CC) Control without Secondary-Feedback Circuitry
- Green Mode: PWM Frequency Linearly-Decreasing
- PWM Frequency at 85 kHz with Frequency Hopping to Solve EMI Problem
- Boundary-Conduction-Mode (BCM) Operation at Lower AC Input Voltage
- Cable Compensation in CV Mode
- Cycle-by-Cycle Current Limiting
- Gate Output Maximum Voltage Clamped at 14 V
- V<sub>DD</sub> Under-Voltage Lockout (UVLO) Available
- Built-in Protections:
	- **Output Short-Circuit Protection**
	- Output Over-Voltage-Protection (VSOVP) with Latch Mode
	- $V_{DD}$  Over-Voltage-Protection ( $V_{DD}$  OVP)
	- CS Pin Single-Fault Protection
	- VS Pin single-Fault Protection
	- Over-Temperature-Protection (OTP) with Latch Mode
- SOIC Package

### **Description**

This highly integrated PWM controller, FAN104W, provides several features to enhance the performance of low-power flyback converters. The proprietary topology of FAN104W enables simplified circuit design for battery charger applications. The result is a lowercost, smaller, and lighter charger compared to a conventional design or a linear transformer.

To minimize standby power consumption, a proprietary green-mode function provides off-time modulation to linearly decrease PWM frequency under light-load conditions. Green Mode assists the power supply in meeting power conservation requirements.

By using FAN104W, a charger can be implemented with few external components and minimized cost. An output CV/CC characteristic envelope is shown in Figure 1.

### **Applications**

- Battery chargers for smart phones, Pad, PDA, digital cameras.
- Best choice to replace linear transformer and RCC SMPS



**Figure 1. Typical Output V-I Characteristic** 

## **Ordering Information Part Number Operating Temperature Range 19 Cycle 2018 Package Packing Method 19 Cycle 2019 Packing Method 19 Cycle 2019 Packing Method** FAN104WMX  $\begin{vmatrix} 3 & -40^{\circ}C & 8 \end{vmatrix}$  8-Lead, Small Outline Integrated Circuit (SOIC), JEDEC MS-012, .150-Inch Narrow Body Tape & Reel





## **Pin Definitions**



## **Absolute Maximum Ratings**

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.



#### **Notes:**

1. Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device.

2. All voltage values, except differential voltages, are given with respect to GND pin.

3. ESD ratings including HV pin: HBM=1 kV, CDM=1.25 kV.

## **Recommended Operating Conditions**

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to Absolute Maximum Ratings.



 $V_{DD}$ =15V, T<sub>A</sub>=25°C, unless otherwise specified.



*Continued on the following page…* 

## **Electrical Characteristics** (Continued)

 $V_{DD}$ =15V, T<sub>A</sub>=25°C, unless otherwise specified.



*Continued on the following page…* 

## **Electrical Characteristics** (Continued)

 $V_{DD}$ =15 V, T<sub>A</sub>=25°C, unless otherwise specified.



**Notes:** 

4. Not tested; guaranteed by design.

5. f<sub>OSC-CC-MIN</sub> occurs when the power unit enters BCM operation.

6. OTP and VSOVP protection are Latch Mode.







### **Functional Description**

#### **Basic CV/CC Control Principle**

Figure 22 shows the basic circuit diagram of a Primary-Side Regulated (PSR) flyback converter with typical waveforms shown in Figure 23. Generally, Discontinuous Conduction Mode (DCM) or Boundary Conduction Mode (BCM) operation is preferred for PSR since it allows better output regulation. The operation principles of DCM/BCM flyback converter are as follows:

During the MOSFET on time  $(t_{ON})$ , input voltage  $(V_{DL})$  is applied across the primary-side inductor  $(L_m)$ . Then  $MOSFET$  current ( $I_{DS}$ ) increases linearly from zero to the peak value  $(I_{pk})$ . During this time, the energy is drawn from the input and stored in the inductor.

When the MOSFET is turned off, the energy stored in the inductor forces the secondary diode  $(D<sub>sec</sub>)$  to turn on. While the diode is conducting, the output voltage  $(V_0)$ , together with diode forward voltage drop  $(V_F)$ , are applied across the secondary-side inductor  $(L_m \times N_s^2)$  $N_p^2$ ) and the diode current (I<sub>D</sub>) decreases linearly from the peak value  $(I_{\nu k} \times N_{\nu}/N_s)$  to zero. At the end of inductor current discharge time  $(t_{DIS})$ , all the energy stored in the inductor has been delivered to the output.

When the diode current reaches zero, the transformer auxiliary winding voltage  $(V_{Aux})$  begins to oscillate by the resonance between the primary-side inductor  $(L_m)$  and the effective capacitor loaded across MOSFET. For BCM operation, this period does not exist.

During the inductor current discharge time, the sum of output voltage and diode forward-voltage drop is reflected to the auxiliary winding side as  $(V_0+V_F) \times$ *NAux/Ns*. Since the diode forward-voltage drop decreases as current decreases, the auxiliary winding voltage reflects the output voltage best at the end of diode conduction time, where the diode current diminishes to zero. By sampling the winding voltage at the end of the diode conduction time, the output voltage information can be obtained. The internal error amplifier for output voltage regulation (EAV) compares the sampled voltage with internal precise reference to generate error voltage (COMV), which determines the duty cycle of the MOSFET in CV Mode.

Meanwhile, the output current is obtained by averaging the triangular output diode current area over a switching cycle as:

$$
I_{O} = _{AVG} = \frac{1}{2} \cdot I_{PK} \cdot \frac{N_{P}}{N_{S}} \cdot \frac{T_{DIS}}{T_{S}}
$$
(1)

The internal FAN104W circuits identify the peak value of the drain current with a peak detection circuit and calculate the output current using the inductor discharge time  $(t_{DIS})$  and switching period  $(t_S)$ . This output information (EAI) is compared with internal precise reference to generate error voltage (COMI), which determines the duty cycle of the MOSFET in CC Mode. With Fairchild's TRUECURRENT® technique, constant current output can be precisely controlled.

With a given current sensing resistor, the output current can be programmed as:

$$
I_o = \frac{1.25}{K} \cdot \frac{N_p}{N_s} \cdot \frac{1}{R_{cs}}
$$
 (2)

where K is the design parameter of IC, which is 10.5.

Of the two error voltages, COMV and COMI, the smaller one determines the duty cycle. During Constant Voltage regulation, COMV determines the duty cycle while COMI is saturated to HIGH. During Constant Current regulation, COMI determines the duty cycle while COMV is saturated to HIGH.



**Figure 22. Simplified PSR Flyback Converter Circuit**





#### **BCM Operation Function**

FAN104W allows BCM operation for better conversion efficiency and low standby power design margin. BCM delays the next cycle turn-on of MOSFET until the discharge time  $(t_{DIS})$  on the VS pin is obtained, as shown in Figure 24. To utilize BCM, FAN104W prohibits the turn-on of next switching cycle for 10% of its switching period after discharge time  $(t_{DIS})$  is obtained. In Figure 24, the first switching cycle has a discharge time  $(t_{DIS})$ before 90% of its original switching period and therefore the turn-on instant of the next cycle is determined its original switching period without being affected by the discharge time  $(t_{DIS})$  point. The second switching cycle does not have discharge time  $(t_{DIS})$  points by the end of its original switching period. Thus, the turn-on of the third switching cycle occurs after discharge time  $(t_{DIS})$ points is obtained, with a delay of 10% of its original switching period. The minimum switching frequency that BCM allows is 10 kHz ( $f_{\text{OSC-BCM}}$ ). If the discharge time point is not given until the end of maximum switching period of 100 μs (10 kHz), the converter can go into CCM operation losing output regulation.





**Figure 24. BCM Operation Function Waveform** 

#### **Green-Mode Operation in CV Mode**

The FAN104W uses a voltage regulation error amplifier output (COMV) as an indicator of the output load and modulates the PWM frequency. The switching frequency decreases as load decreases. In heavy load conditions, the switching frequency is fixed at 85 kHz. Once COMV decreases below 2.9 V, PWM frequency linearly decreases from 85 kHz. When FAN104W enters "deep" Green Mode, the PWM frequency is reduced to a minimum frequency ( $f_{\text{OSC-N-MIN}}$ ) of 1.2 kHz, saving power to meet international power conservation requirements.



**Figure 26. Frequency Reduction Curve in CV Mode** 

#### **Frequency Reduction in CC Mode**

The discharge time  $(t_{DIS})$  of diode current increases as the output voltage decreases in CC Mode.FAN104W decreases switching frequency as output voltage drops, as shown in Figure 27. FAN104W indirectly monitors the output voltage by the sample-and-hold voltage (EAV) of V<sub>s</sub>, which is taken at 70% of diode current discharge time of the previous switching cycle. Figure 28 shows how the frequency reduces as the sample-and-hold voltage (EAV) of  $V<sub>O</sub>$  decreases.



**Figure 27. Frequency Reduction with EAV** 



**Figure 28. Frequency Reduction Curve in CC Mode** 

#### **Frequency Hopping**

EMI reduction is accomplished by frequency hopping, which spreads the energy over a wider frequency range than the bandwidth of the EMI test equipment, allowing conformation to EMI limitations. The FAN104W internal frequency-hopping circuit changes the switching frequency progressively between 82 kHz and 88 kHz with a period  $t_{\text{FHR}}$  of 3 ms.



#### **Slope Compensation**

The sensed voltage across the current-sense resistor is used for Current-Mode control and pulse-by-pulse current limiting. A synchronized ramp signal with positive slope is added to the current sense information at each switching cycle, improving noise immunity of Current-Mode control.

#### **Cable Voltage Drop Compensation**

When it comes to cellular phone charger applications, the battery is located at the end of cable, which typically causes several percentage of voltage drop on the actual battery voltage. FAN104W has a built-in cable voltage drop compensation, which provides a constant output voltage at the end of the cable over the entire load range in CV Mode. As load increases, the voltage drop across the cable is compensated by increasing the reference voltage of voltage regulation error amplifier.

### **Operating Current**

The operating current in FAN104W is as small as 3.5 mA. The small operating current results in higher efficiency and reduces the  $V_{DD}$  hold-up capacitance requirement. Once FAN104W enters deep Green Mode, the operating current is reduced to 600 µA, assisting the power supply meet power conservation requirements.

#### **High-Voltage Startup**

Figure 30 shows the HV-startup circuit for FAN104W applications. The HV pin is connected to the line input or bulk capacitor through a resistor, R<sub>Start</sub> (100 kΩ is recommended). During startup, the internal startup circuit is enabled. Meanwhile, line input supplies the current  $I_{HV}$ , to charge the hold-up capacitor,  $C_{VDD}$ through  $R_{start}$ . When the  $V_{DD}$  voltage reaches  $V_{DD-ON}$ , the internal startup circuit is disabled, blocking  $I_{HV}$  from flowing into the HV pin. Once the IC turns on,  $C_{VDD}$  is the only energy source to supply the IC consumption current before the PWM starts to switch. Thus,  $C_{VDD}$ must be large enough to prevent  $V_{DD}$  from dropping to V<sub>DD-OFF</sub> before the power can be delivered from the auxiliary winding. The  $V_{DD}$  capacitance tolerance is an important factor to consider for  $C_{DD}$  selection. Connecting a 22  $\mu$ F capacitor between the V<sub>DD</sub> and GND pins is recommended to ensure the system stability across a wide operating temperature range.



#### **Protections**

The FAN104W self-protection functions include  $V_{DD}$ Over-Voltage-Protection (V<sub>DD</sub> OVP), Over-Temperature-Protection (OTP), VS Over-Voltage Protection (VSOVP), CS pin short-circuit protection, brownout protection, and VS pin low-side resistor open/short protection, and high-side resistor-open protection. The V<sub>DD</sub> OVP, brownout protection, VS pin low-side resistor short protection, VS pin high-side open protection, and CS pin short-circuit protection are implemented as Auto-Restart Mode. The VSOVP, VS pin low-side resistor open protection and internal OTP are implemented as Latch Mode.

When an Auto-Restart Mode protection is triggered, switching is terminated and the MOSFET remains off, causing  $V_{DD}$  to drop. When  $V_{DD}$  reaches the  $V_{DD}$  turn-off voltage of 5 V; the protection is reset, the internal startup circuit is enabled, and the supply current drawn from the HV pin charges the hold-up capacitor. When  $V_{DD}$  reaches the turn-on voltage of 16 V, normal operation resumes. In this manner, Auto-Restart alternately enables and disables the switching of the MOSFET until the abnormal condition is eliminated, as shown in Figure 31.

When a Latch Mode protection is triggered, PWM switching is terminated and the MOSFET remains off. causing  $V_{DD}$  to drop. When  $V_{DD}$  drops to the  $V_{DD}$  turn-off voltage of 5 V, the internal startup circuit is enabled without resetting the protection and the supply current drawn from HV pin charges the hold-up capacitor. Since the protection is not reset, the IC does not resume PWM switching even when  $V_{DD}$  reaches the turn-on voltage of 16 V, disabling HV startup circuit. Then,  $V_{DD}$  drops again down to 5 V. In this manner, a Latch Mode protection alternately charges and discharges  $V_{DD}$  until there is no more energy in DC link capacitor. The protection is reset when  $V_{DD}$  drops to 2.5 V, which is allowed only after power supply is unplugged from the AC line, as shown in Figure 32.





#### **Leading-Edge Blanking (LEB)**

Each time the power MOSFET is switched on, a turn-on spike occurs at the sense resistor. To avoid premature termination of the switching pulse, a 150 ns leadingedge blanking time is built in. Conventional RC filtering can therefore be omitted. During this blanking period, the current-limit comparator is disabled and it cannot switch off the gate driver.

#### **Noise Immunity**

Noise from the current sense or the control signal can cause significant pulse width jitter, particularly in Continuous-Conduction Mode. While slope compensation helps alleviate these problems, further precautions should still be taken. Good placement and layout practices should be followed. Avoiding long PCB traces and component leads, locating compensation and filter components near the FAN104W, and increasing the power MOS gate resistance is advised.



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Rev. 163

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