EVQ6531-V-00A

5V to 60V, Three-Phase Brushless DC Motor Pre-Driver Evaluation Board

DESCRIPTION

The EVQ6531-V-00A is an evaluation board for the MPQ6531, a three-phase BLDC motor pre-driver.

It operates from a supply voltage of up to 60V. It is configured to drive 3 half bridges consisting of 6 N-channel Power MOSFETs. The rotor position information is provided by the Hall sensors assembled in the motor and the driving control signals are generated by the external controller, such as MCU, FPGA, etc.

ELECTRICAL SPECIFICATIONS

| Parameter	Symbol	Value	Units
Input Voltage	VIN	5 - 60	V
OC_REF	OC_REF	0.1 – 2.4	V
Hall Voltage	VH	3.3 or 5	V

FEATURES

- Wide 5V to 60V Input Voltage Range
- Programmable OCP Threshold
- Support 100% Duty Cycle Operation
- OCP, OTP
- Fault Indication Output

APPLICATIONS

- 3-Phase Brushless DC Motors and Permanent Magnet Synchronous Motors
- Power Drills
- Impact Drivers
- E-Bike

EVQ6531-V-00A EVALUATION BOARD
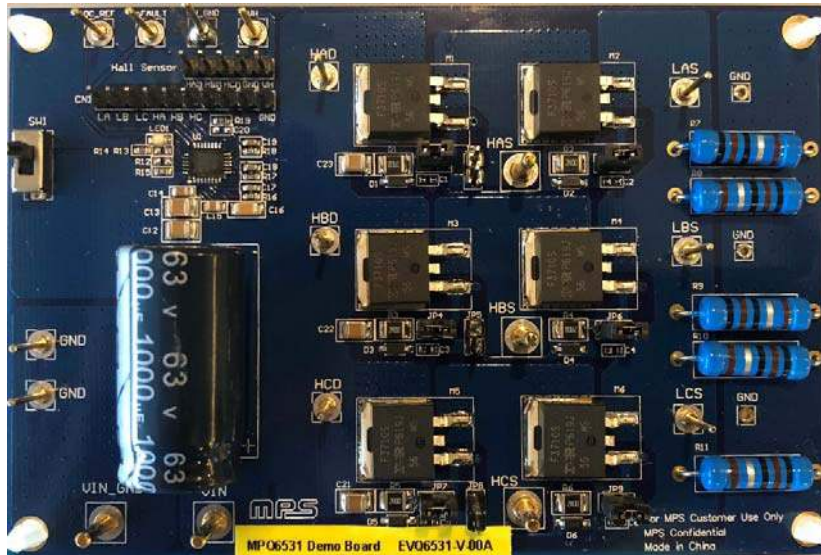
(L x W x H) 4.68" x 3.12" x 0.4"
(11.7cm x 7.8cm x 1cm)

Board Number	MPS IC Number
EVQ6531-V-00A	MPQ6531GV-AEC1

EVALUATION BOARD SCHEMATIC
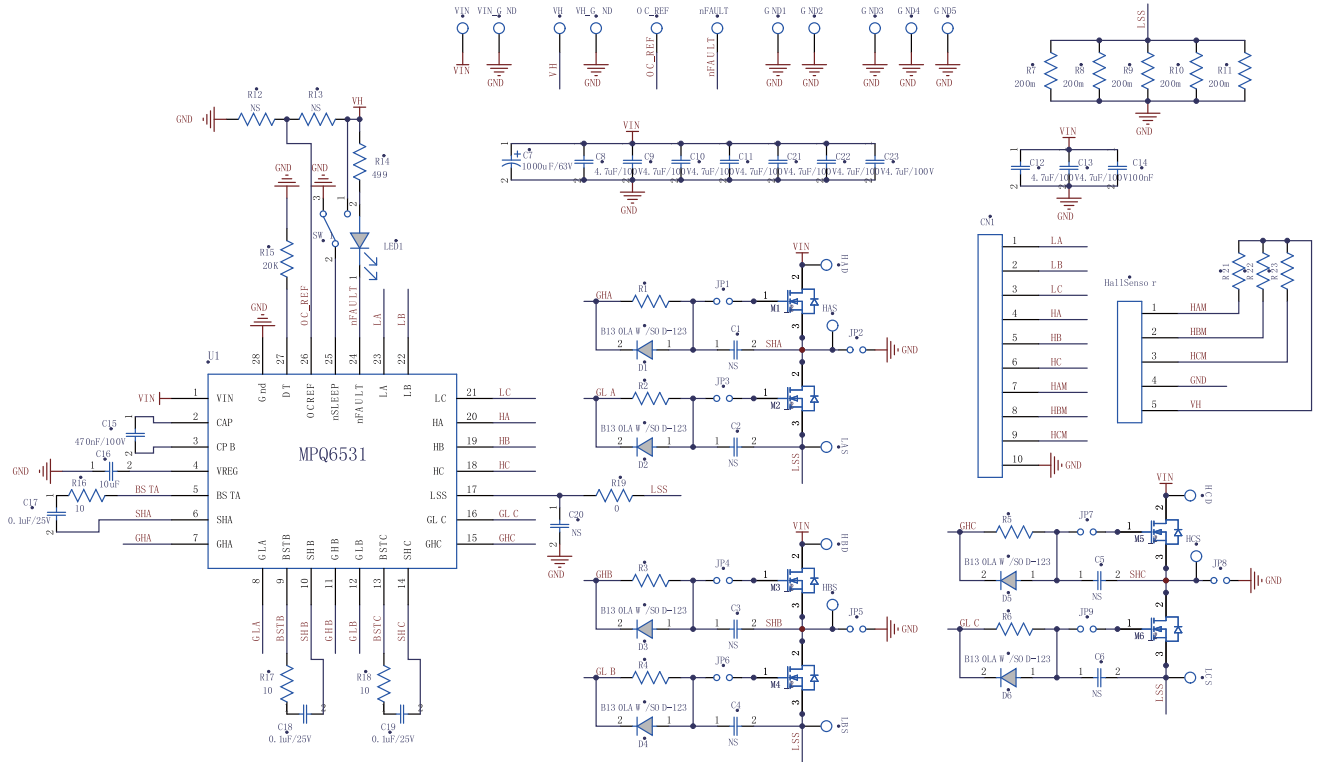
EVQ6531-V-00A BILL OF MATERIALS

Qty	RefDes	Value	Description	Package	Manufacturer	Manufacturer P/N
12	C1,C2,C3,C4,C5,C6, C20,R12,R13,R21,R 22,R23	NS				
1	C7	1000µF	Electrolytic Cap. 63V	DIP	Jianghai	CD263-63V1000
9	C8,C9,C10,C11,C12 ,C13,C21,C22,C23	4.7µF	Ceramic Cap. 100V, X7S	1210	TDK	C3225X7S2A475K
1	C14	100nF	Ceramic Cap. 100V, X7R	0805	TDK	CGA4J2X7R2A104K
1	C15	470nF	Ceramic Cap. 100V, X7R	0805	Murata	GRM21BR72A474K A73L
1	C16	10µF	Ceramic Cap. 25V, X5R	1206	Murata	GRM31CR61E106K A12L
3	C17,C18,C19	0.1µF	Ceramic Cap. 25V, X7R	0603	Murata	GRM188R71E104K A01D
6	R1,R2,R3,R4,R5,R6	2Ω	Film Resistor. 1%	1210	Yageo	RC1210FR-072RL
5	R7,R8,R9,R10,R11	100mΩ	Resistor. 2W	DIP	闽达	
1	R14	499Ω	Film Resistor. 1%	0603	Yageo	RC0603FR-07499RL
1	R15	20k	Film Resistor ,1%	0603	Yageo	RC0603FR-0720KL
3	R16,R17,R18,	10Ω	Film Resistor ,1%	0603	Yageo	RC0603FR-0710RL
1	R19	0Ω	Film Resistor ,1%	0603	Yageo	RC0603FR-070RL
6	D1,D2,D3,D4,D5,D6		Schottky Diode. 30V, 1A	SOD-123	Diodes	B130LAW-7-F
6	M1,M2,M3,M4,M5,M 6		N-channel MOSFET, 100V,57A, Qg=130nC, 23mΩ@Vgs=10V , Id=28A	TO-263	IR	IRF3710S
1	LED1		LED. 红光	0805	Bright LED	BL-HUF35A-TRB
1	SW1		Button			SK-12D01EG4
9	JP1,JP2,JP3,JP4,JP 5,JP6,JP7,JP8,JP9		2PIN. 2.54MM			
6	JP1,JP3,JP4,JP6,JP 7,JP9		2.54MM Short Jumper			
1	CN1		10PIN. 2.54MM			
1	Hall Sensor		5PIN. 2.54MM			
5	VIN,VIN_GND,HAS, HBS,HCS		2.0 公针			
9	OC_REF,nFAULT, VH,VH_GND,LAS,L BS,LCS,GND,GND		1.0 公针			
1	U1		3-Phase BLDC Motor Pre-Driver	QFN28 (4x5mm)	MPS	MPQ6531GV-AEC1

PRINTED CIRCUIT BOARD LAYOUT

Figure 1: Top

Figure 2: Top Silk

Figure 3: Inner1

Figure 4: Inner2

Figure 5: Bottom

Figure 6: Bottom Silk

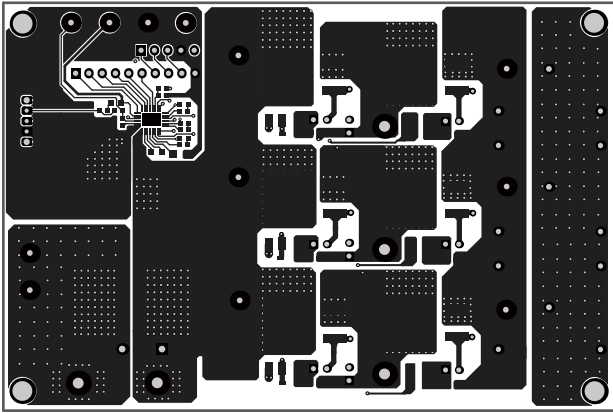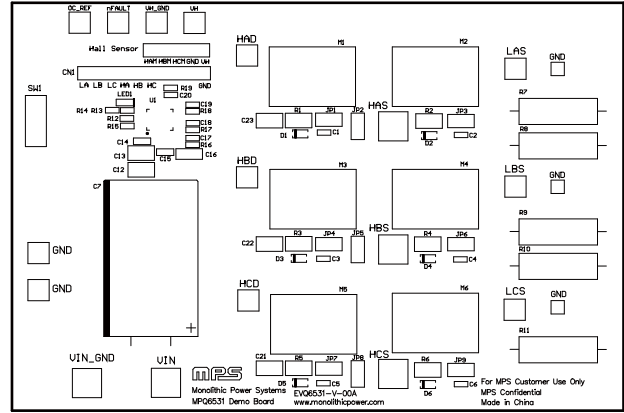## QUICK START GUIDE

1. Attach the input voltage (5V ≤ V_{IN} ≤ 60V) and input ground to the VIN and GND connectors respectively.

2. Attach a 3.3V or 5V constant voltage to the VH connector and switch the SW1 to the position 1(Top side) to enable the chip.

3. Attach the OCP reference voltage (0.1V ≤ V_{OC_REF} ≤ 2.4V) to the OC_REF connector to set OCP threshold.

4. Attach the hall signals coming from the motor to the Hall Sensor connector.

5. Attach the driving control signals generated by the external controller to the CN1 connector.