

## 74AC191 Up/Down Counter with Preset and Ripple Clock

### General Description

The AC191 is a reversible modulo 16 binary counter. It features synchronous counting and asynchronous presetting. The preset feature allows the AC191 to be used in programmable dividers. The Count Enable input, the Terminal Count output and the Ripple Clock output make possible a variety of methods of implementing multistage counters. In the counting modes, state changes are initiated by the rising edge of the clock.

### Features

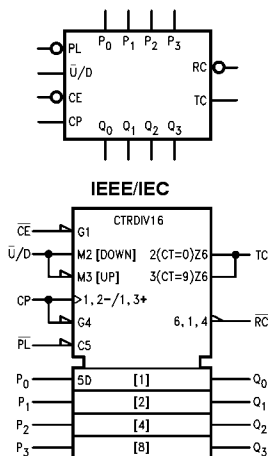
- $I_{CC}$  reduced by 50%
- High speed—133 MHz typical count frequency
- Synchronous counting
- Asynchronous parallel load
- Cascadable
- Outputs source/sink 24 mA

### Ordering Code:

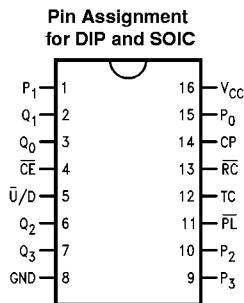
Order Number	Package Number	Package Description
74AC191SC	M16A	16-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150" Narrow Body
74AC191SJ	M16D	16-Lead Small Outline Package (SOP), EIAJ TYPE II, 5.3mm Wide
74AC191MTC	MTC16	16-Lead Thin Shrink Small Outline Package (TSSOP), JEDEC MO-153, 4.4mm Wide
74AC191PC	N16E	16-Lead Plastic Dual-In-Line Package (PDIP), JEDEC MS-001, 0.300" Wide

Device also available in Tape and Reel. Specify by appending suffix letter "X" to the ordering code.

### Logic Symbols



### Connection Diagram



### Pin Descriptions

Pin Names	Description
$\overline{CE}$	Count Enable Input
CP	Clock Pulse Input
$P_0$ – $P_3$	Parallel Data Inputs
$\overline{PL}$	Asynchronous Parallel Load Input
$\overline{U/D}$	Up/Down Count Control Input
$Q_0$ – $Q_3$	Flip-Flop Outputs
$\overline{RC}$	Ripple Clock Output
TC	Terminal Count Output

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## Functional Description

The AC191 is a synchronous up/down counter. The AC191 is organized as a 4-bit binary counter. It contains four edge-triggered flip-flops with internal gating and steering logic to provide individual preset, count-up and count-down operations.

Each circuit has an asynchronous parallel load capability permitting the counter to be preset to any desired number. When the Parallel Load ( $\overline{PL}$ ) input is LOW, information present on the Parallel Load inputs ( $P_0$ – $P_3$ ) is loaded into the counter and appears on the Q outputs. This operation overrides the counting functions, as indicated in the Mode Select Table.

A HIGH signal on the  $\overline{CE}$  input inhibits counting. When  $\overline{CE}$  is LOW, internal state changes are initiated synchronously by the LOW-to-HIGH transition of the clock input. The direction of counting is determined by the  $\overline{U/D}$  input signal, as indicated in the Mode Select Table.  $\overline{CE}$  and  $\overline{U/D}$  can be changed with the clock in either state, provided only that the recommended setup and hold times are observed.

Two types of outputs are provided as overflow/underflow indicators. The terminal count (TC) output is normally LOW. It goes HIGH when the circuits reach zero in the count down mode or 15 in the count up mode. The TC output will then remain HIGH until a state change occurs, whether by counting or presetting or until  $\overline{U/D}$  is changed. The TC output should not be used as a clock signal because it is subject to decoding spikes.



The TC signal is also used internally to enable the Ripple Clock ( $\overline{RC}$ ) output. The  $\overline{RC}$  output is normally HIGH. When  $\overline{CE}$  is LOW and TC is HIGH,  $\overline{RC}$  output will go LOW when the clock next goes LOW and will stay LOW until the clock

goes HIGH again. This feature simplifies the design of multistage counters, as indicated in Figure 1 and Figure 2. In Figure 1, each  $\overline{RC}$  output is used as the clock input for the next higher stage. This configuration is particularly advantageous when the clock source has a limited drive capability, since it drives only the first stage. To prevent counting in all stages it is only necessary to inhibit the first stage, since a HIGH signal on  $\overline{CE}$  inhibits the  $\overline{RC}$  output pulse, as indicated in the  $\overline{RC}$  Truth Table. A disadvantage of this configuration, in some applications, is the timing skew between state changes in the first and last stages. This represents the cumulative delay of the clock as it ripples through the preceding stages.



A method of causing state changes to occur simultaneously in all stages is shown in Figure 2. All clock inputs are driven in parallel and the  $\overline{RC}$  outputs propagate the carry/borrow signals in ripple fashion. In this configuration the LOW state duration of the clock must be long enough to allow the negative-going edge of the carry/borrow signal to ripple through to the last stage before the clock goes HIGH. There is no such restriction on the HIGH state duration of the clock, since the  $\overline{RC}$  output of any device goes HIGH shortly after its CP input goes HIGH.



The configuration shown in Figure 3 avoids ripple delays and their associated restrictions. The  $\overline{CE}$  input for a given stage is formed by combining the TC signals from all the preceding stages. Note that in order to inhibit counting an enable signal must be included in each carry gate. The simple inhibit scheme of Figure 1 and Figure 2 doesn't apply, because the TC output of a given stage is not affected by its own  $\overline{CE}$ .

## Mode Select Table

Inputs				Mode
$\overline{PL}$	$\overline{CE}$	$\overline{U/D}$	CP	
H	L	L		Count Up
H	L	H		Count Down
L	X	X	X	Preset (Asyn.)
H	H	X	X	No Change (Hold)

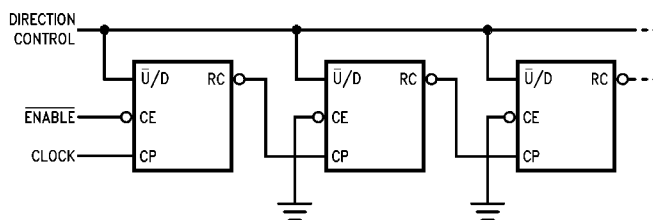
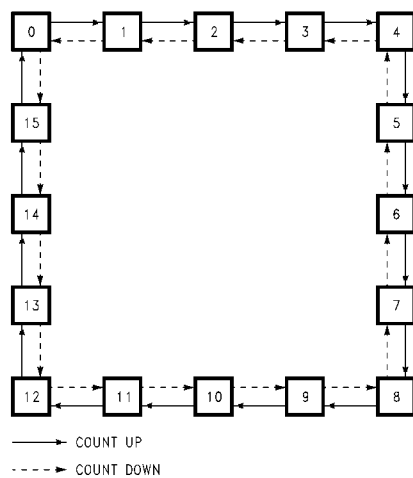
## $\overline{RC}$ Truth Table

Inputs				Outputs
PL	CE	TC (Note 1)	CP	$\overline{RC}$
H	L	H		
H	H	X	X	H
H	X	L	X	H
L	X	X	X	H

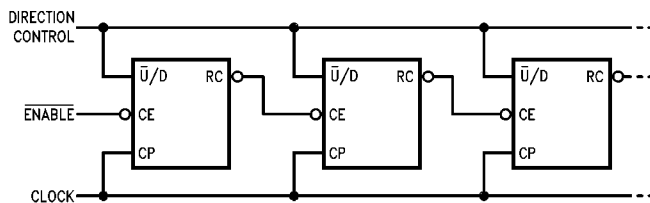
H = HIGH Voltage Level  
 L = LOW Voltage Level  
 X = Immaterial  
 = LOW-to-HIGH Transition  
 = Clock Pulse

**Note 1:** TC is generated internally

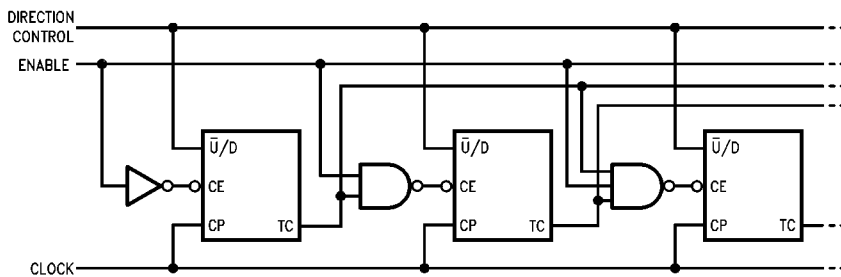
**State Diagram**



**FIGURE 1. N-Stage Counter Using Ripple Clock**

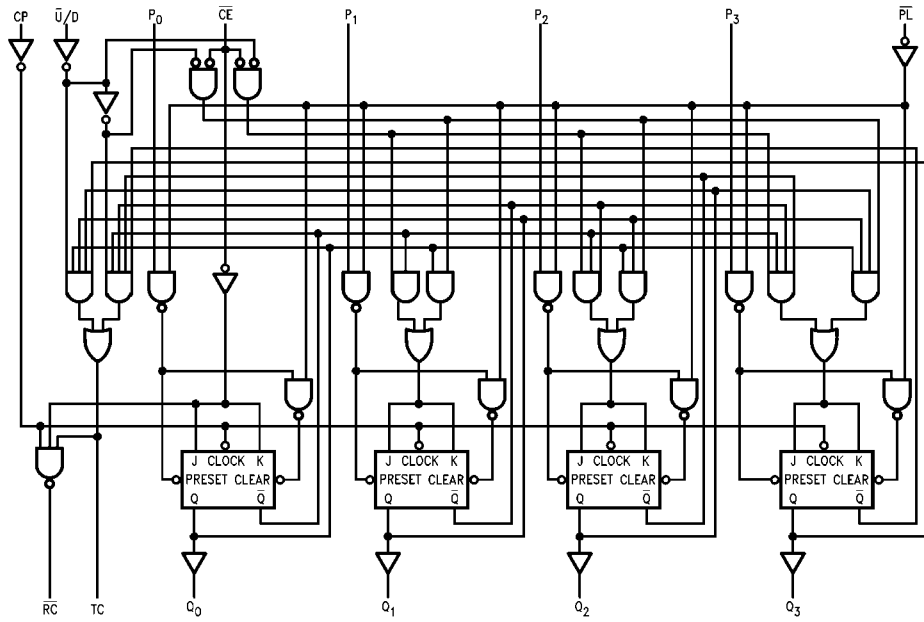


**FIGURE 2. Synchronous N-Stage Counter Using Ripple Carry/Borrow**



**FIGURE 3. Synchronous N-Stage Counter with Parallel Gated Carry/Borrow**

### Logic Diagram



Please note that this diagram is provided only for the understanding of logic operations and should not be used to estimate propagation delays.

Absolute Maximum Ratings (Note 2)		Junction Temperature ( $T_J$ )
Supply Voltage ( $V_{CC}$ )	-0.5V to +7.0V	PDIP 140°C
DC Input Diode Current ( $I_{IK}$ )		
$V_I = -0.5V$	-20 mA	
$V_I = V_{CC} + 0.5V$	+20 mA	
DC Input Voltage ( $V_I$ )	-0.5V to $V_{CC} + 0.5V$	
DC Output Diode Current ( $I_{OK}$ )		
$V_O = -0.5V$	-20 mA	
$V_O = V_{CC} + 0.5V$	+20 mA	
DC Output Voltage ( $V_O$ )	-0.5V to $V_{CC} + 0.5V$	
DC Output Source		
or Sink Current ( $I_O$ )	$\pm 50$ mA	
DC $V_{CC}$ or Ground Current		
per Output Pin ( $I_{CC}$ or $I_{GND}$ )	$\pm 50$ mA	
Storage Temperature ( $T_{STG}$ )	-65°C to +150°C	

Recommended Operating Conditions	
Supply Voltage ( $V_{CC}$ )	2.0V to 6.0V
Input Voltage ( $V_I$ )	0V to $V_{CC}$
Output Voltage ( $V_O$ )	0V to $V_{CC}$
Operating Temperature ( $T_A$ )	-40°C to +85°C
Minimum Input Edge Rate ( $\Delta V/\Delta t$ )	
$V_{IN}$ from 30% to 70% of $V_{CC}$	
$V_{CC}$ @ 3.3V, 4.5V, 5.5V	125 mV/ns

**Note 2:** Absolute maximum ratings are those values beyond which damage to the device may occur. The databook specifications should be met, without exception, to ensure that the system design is reliable over its power supply, temperature, output/input loading variables. Fairchild does not recommend operation of FACT™ circuits outside databook specifications.

## DC Electrical Characteristics

Symbol	Parameter	$V_{CC}$ (V)	$T_A = +25^\circ\text{C}$		$T_A = -40^\circ\text{C to } +85^\circ\text{C}$	Units	Conditions
			Typ	Guaranteed Limits			
$V_{IH}$	Minimum HIGH Level Input Voltage	3.0	1.5	2.1	2.1	V	$V_{OUT} = 0.1V$ or $V_{CC} - 0.1V$
		4.5	2.25	3.15	3.15		
		5.5	2.75	3.85	3.85		
$V_{IL}$	Maximum LOW Level Input Voltage	3.0	1.5	0.9	0.9	V	$V_{OUT} = 0.1V$ or $V_{CC} - 0.1V$
		4.5	2.25	1.35	1.35		
		5.5	2.75	1.65	1.65		
$V_{OH}$	Minimum HIGH Level Output Voltage	3.0	2.99	2.9	2.9	V	$I_{OUT} = -50 \mu A$
		4.5	4.49	4.4	4.4		
		5.5	5.49	5.4	5.4		
		3.0		2.56	2.46	V	$V_{IN} = V_{IL}$ or $V_{IH}$ $I_{OH} = 12$ mA $I_{OH} = -24$ mA $I_{OH} = -24$ mA (Note 3)
		4.5		3.86	3.76		
5.5		4.86	4.76				
$V_{OL}$	Maximum LOW Level Output Voltage	3.0	0.002	0.1	0.1	V	$I_{OUT} = 50 \mu A$
		4.5	0.001	0.1	0.1		
		5.5	0.001	0.1	0.1		
		3.0		0.36	0.44	V	$V_{IN} = V_{IL}$ or $V_{IH}$ $I_{OL} = 12$ mA $I_{OL} = 24$ mA $I_{OL} = 24$ mA (Note 3)
		4.5		0.36	0.44		
5.5		0.36	0.44				
$I_{IN}$ (Note 5)	Maximum Input Leakage Current	5.5		$\pm 0.1$	$\pm 1.0$	$\mu A$	$V_I = V_{CC}, GND$
$I_{OLD}$	Minimum Dynamic	5.5			75	mA	$V_{OLD} = 1.65V$ Max
$I_{OHD}$	Output Current (Note 4)	5.5			-75	mA	$V_{OHD} = 3.85V$ Min
$I_{CC}$ (Note 5)	Maximum Quiescent Supply Current	5.5		4.0	40.0	$\mu A$	$V_{IN} = V_{CC}$ or GND

**Note 3:** All outputs loaded; thresholds on input associated with output under test.

**Note 4:** Maximum test duration 2.0 ms, one output loaded at a time.

**Note 5:**  $I_{IN}$  and  $I_{CC}$  @ 3.0V are guaranteed to be less than or equal to the respective limit @ 5.5V  $V_{CC}$ .

AC Electrical Characteristics								
Symbol	Parameter	V <sub>CC</sub> (V) (Note 6)	C <sub>L</sub> = 50 pF T <sub>A</sub> = +25°C			T <sub>A</sub> = -40°C to +85°C C <sub>L</sub> = 50 pF		Units
			Min	Typ	Max	Min	Max	
f <sub>max</sub>	Maximum Count	3.3	70	105		65		MHz
	Frequency	5.0	90	133		85		
t <sub>PLH</sub>	Propagation Delay	3.3	2.0	8.5	15.0	1.5	16.0	ns
	CP to Q <sub>n</sub>	5.0	1.5	6.0	11.0	1.5	12.0	
t <sub>PHL</sub>	Propagation Delay	3.3	2.5	8.5	14.5	2.0	16.0	ns
	CP to Q <sub>n</sub>	5.0	1.5	6.0	10.5	1.5	11.5	
t <sub>PLH</sub>	Propagation Delay	3.3	3.5	10.5	18.0	2.5	20.0	ns
	CP to TC	5.0	2.5	7.5	12.0	1.5	14.0	
t <sub>PHL</sub>	Propagation Delay	3.3	4.0	10.5	17.5	3.0	19.0	ns
	CP to TC	5.0	2.5	7.5	12.5	2.0	13.5	
t <sub>PLH</sub>	Propagation Delay	3.3	2.5	7.5	12.0	2.0	13.5	ns
	CP to $\overline{RC}$	5.0	2.0	5.5	9.5	1.0	10.5	
t <sub>PHL</sub>	Propagation Delay	3.3	2.5	7.0	11.5	2.0	12.5	ns
	CP to $\overline{RC}$	5.0	1.5	5.0	8.5	1.0	9.5	
t <sub>PLH</sub>	Propagation Delay	3.3	2.5	7.0	12.0	1.5	13.5	ns
	$\overline{CE}$ to $\overline{RC}$	5.0	1.5	5.0	8.5	1.0	9.5	
t <sub>PHL</sub>	Propagation Delay	3.3	2.0	6.5	11.0	1.5	12.5	ns
	$\overline{CE}$ to $\overline{RC}$	5.0	1.5	5.0	8.0	1.0	9.0	
t <sub>PLH</sub>	Propagation Delay	3.3	2.5	6.5	12.5	2.0	14.5	ns
	$\overline{U}/D$ to $\overline{RC}$	5.0	1.5	5.0	9.0	1.0	10.0	
t <sub>PHL</sub>	Propagation Delay	3.3	2.5	7.0	12.0	2.0	13.5	ns
	$\overline{U}/D$ to $\overline{RC}$	5.0	1.5	5.0	8.5	1.0	10.0	
t <sub>PLH</sub>	Propagation Delay	3.3	2.0	7.0	11.5	1.5	13.5	ns
	$\overline{U}/D$ to TC	5.0	1.5	5.0	8.5	1.0	9.5	
t <sub>PHL</sub>	Propagation Delay	3.3	2.0	6.5	11.0	1.5	12.5	ns
	$\overline{U}/D$ to TC	5.0	1.5	5.0	8.5	1.0	9.5	
t <sub>PLH</sub>	Propagation Delay	3.3	2.5	8.0	13.5	2.0	15.5	ns
	P <sub>n</sub> to Q <sub>n</sub>	5.0	2.0	5.5	9.5	1.0	10.5	
t <sub>PHL</sub>	Propagation Delay	3.3	2.5	7.5	13.0	1.5	14.5	ns
	P <sub>n</sub> to Q <sub>n</sub>	5.0	1.5	5.5	9.5	1.0	10.5	
t <sub>PLH</sub>	Propagation Delay	3.3	3.5	9.5	14.5	2.5	17.5	ns
	$\overline{P}$ to Q <sub>n</sub>	5.0	2.0	5.5	9.5	1.0	10.5	
t <sub>PHL</sub>	Propagation Delay	3.3	3.0	8.0	13.5	2.0	15.5	ns
	$\overline{P}$ to Q <sub>n</sub>	5.0	2.0	6.0	10.0	1.5	11.0	

**Note 6:** Voltage Range 3.3 is 3.3V ±0.3V  
Voltage Range 5.0 is 5.0V ±0.5V

## AC Operating Requirements

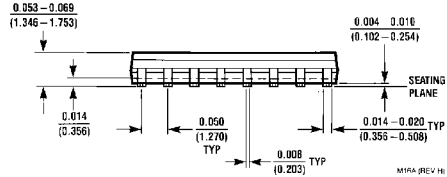
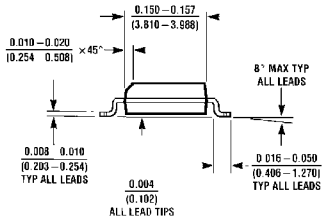
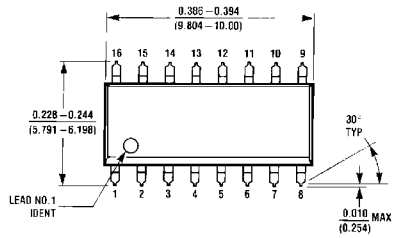
Symbol	Parameter	V <sub>CC</sub> (V) (Note 7)	T <sub>A</sub> = +25°C C <sub>L</sub> = 50 pF		T <sub>A</sub> = -40°C to +85°C C <sub>L</sub> = 50 pF		Units
			Typ	Guaranteed Minimum			
t <sub>S</sub>	Setup Time, HIGH or LOW P <sub>n</sub> to $\overline{PL}$	3.3	1.0	3.0	3.0	ns	
		5.0	0.5	2.0	2.5		
t <sub>H</sub>	Hold Time, HIGH or LOW P <sub>n</sub> to $\overline{PL}$	3.3	-1.5	0.5	1.0	ns	
		5.0	-0.5	1.0	1.0		
t <sub>S</sub>	Setup Time, LOW $\overline{CE}$ to CP	3.3	3.0	6.0	7.0	ns	
		5.0	1.5	4.0	4.5		
t <sub>H</sub>	Hold Time, LOW $\overline{CE}$ to CP	3.3	-4.0	-0.5	-0.5	ns	
		5.0	-2.5	0	0		
t <sub>S</sub>	Setup Time, HIGH or LOW $\overline{UD}$ to CP	3.3	4.0	8.0	9.0	ns	
		5.0	2.5	5.5	6.5		
t <sub>H</sub>	Hold Time, HIGH or LOW $\overline{UD}$ to CP	3.3	-5.0	0	0	ns	
		5.0	-3.0	0.5	0.5		
t <sub>W</sub>	$\overline{PL}$ Pulse Width, LOW	3.3	2.0	3.5	4.0	ns	
		5.0	1.0	1.0	1.0		
t <sub>W</sub>	CP Pulse Width, LOW	3.3	2.0	3.5	4.0	ns	
		5.0	2.0	3.0	4.0		
t <sub>rec</sub>	Recovery Time $\overline{PL}$ to CP	3.3	-0.5	0	0	ns	
		5.0	-1.0	0	0		

Note 7: Voltage Range 3.3 is 3.3V ±0.3V  
Voltage Range 5.0 is 5.0V ±0.5V

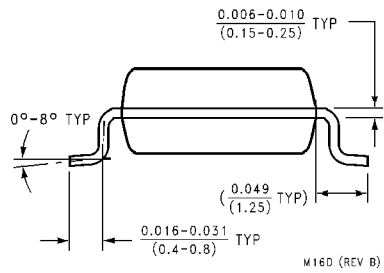
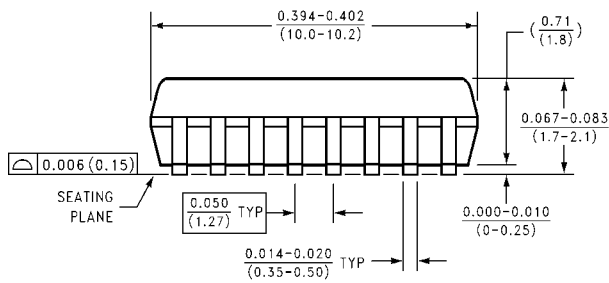
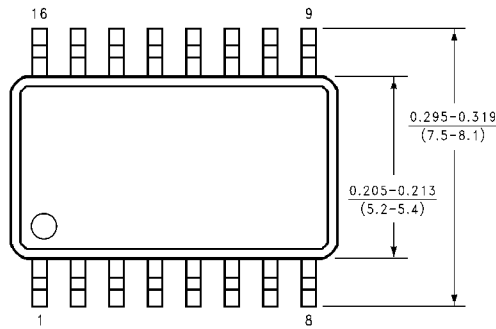
## Capacitance

Symbol	Parameter	Typ	Units	Conditions
C <sub>IN</sub>	Input Capacitance	4.5	pF	V <sub>CC</sub> = OPEN
C <sub>PD</sub>	Power Dissipation Capacitance	75.0	pF	V <sub>CC</sub> = 5.0V

**Physical Dimensions** inches (millimeters) unless otherwise noted



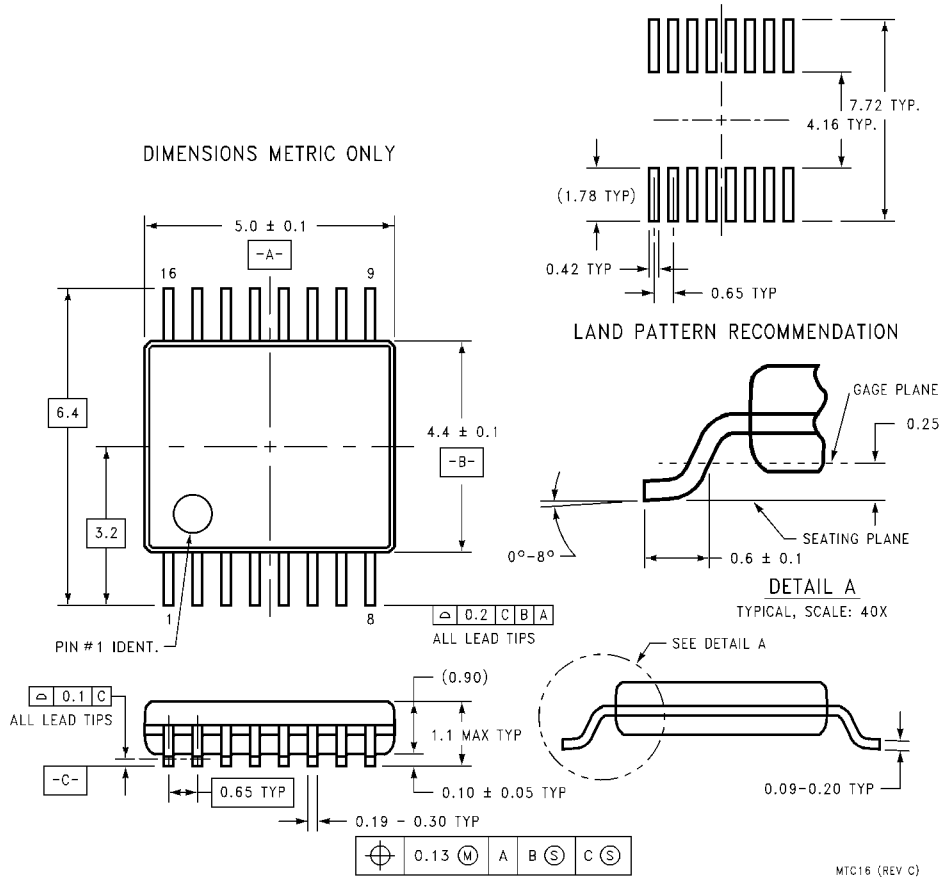
**16-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150" Narrow Body  
Package Number M16A**



**16-Lead Small Outline Package (SOP), EIAJ TYPE II, 5.3mm Wide  
Package Number M16D**

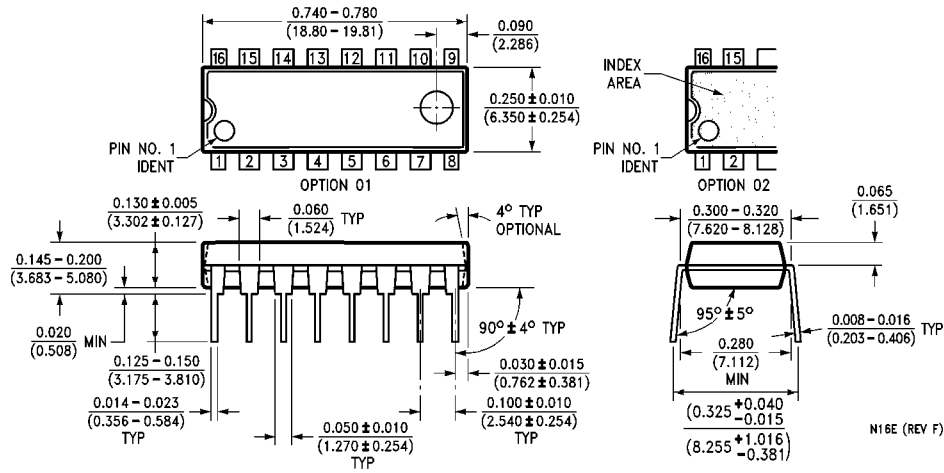


**Physical Dimensions** inches (millimeters) unless otherwise noted (Continued)



**16-Lead Thin Shrink Small Outline Package (TSSOP), JEDEC MO-153, 4.4mm Wide  
 Package Number MTC16**

**Physical Dimensions** inches (millimeters) unless otherwise noted (Continued)



**16-Lead Plastic Dual-In-Line Package (PDIP), JEDEC MS-001, 0.300" Wide Package Number N16E**

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2. A critical component in any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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