

2.0A Inductor Built-in Step-Down DC/DC Converters

☆GreenOperationCompatible

GENERAL DESCRIPTION

MYRGM080200X41RA and MYRGM080200C41RA is a synchronous step-down mini DC/DC converter which integrates an inductor and a control IC in one tiny package (3.1mm × 4.7mm, h=1.3mm).

An internal coil simplifies the circuit and enables minimization of noise and

Other operational trouble due to the circuit wiring.

A wide operating voltage range of 2.7V to 6.0V enables support for applications

That require an externally set output voltage can be selected.

The MYRGM-X/C series use synchronous rectification at an operating frequency of 2.4MHz.

PWM control (MYRGM080200X41RA) or automatic PWM/PFM switching control (MYRGM080200C41RA) can be selected.

The MYRGM080200X41RA has a fixed frequency, enabling the suppression of output ripple.

The MYRGM080200C41RA achieves high efficiency while holding down output ripple

across the full range of loads, from light to heavy, enabling the extension of battery operation time.

The series have a high speed soft-start as fast as 1ms in typical for quick turn-on. With the built-in UVLO (Under Voltage Lock Out) function, the internal P-channel driver transistor is forced OFF when input voltage becomes 2.4V or lower. It's suitable for large-current application due to limit current is configured 4.0A in typical. The integrated C_L discharge function which enables the electric charge at the output capacitor C_L to be discharged via the internal discharge switch located between the LX and GND pins. Due to C_L discharge function, malfunction on LX is prevented when Stand-by mode.

APPLICATIONS

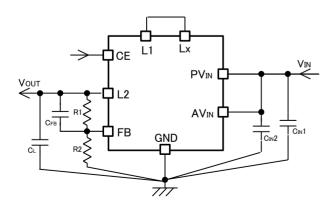
- Note PCs
- Printers
- Tablet PCs
- PND(Portable Navigation Device)

FEATURES

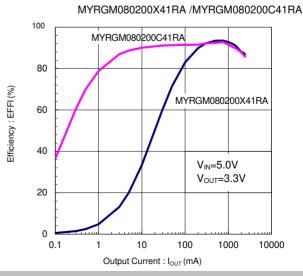
Package Size	: 3.1mm × 4.7mm, h=1.3mm				
Input Voltage	: 2.7V~6.0V				
Output Voltage	: 0.9V~V _{IN} (FB Voltage=0.8V±2%)				
High Efficiency	: 94% (VIN=5.0V, VOUT=3.3V)				
Output Current	: 2.0A				
Switching Frequency	: 2.4MHz (±15%)				
Maximum Duty Cycle	: 100%				
Control Methods	: PWM MYRGM080200X41RA)				
	PWM/PFM (MYRGM080200C41RA)				
Functions	: Current Limit Circuit (automatic return)				
	Soft-Start Circuit Built-In				
	C∟Discharge, UVLO				
Output Capacitor	: Low ESR Ceramic Capacitor				
Operating Ambient Ter	Operating Ambient Temperature : -40°C~+85°C				
Environmentally Friend	lly : EU RoHS Compliant, Pb Free				

Halogen Free

TYPICAL APPLICATION CIRCUIT



TYPICAL PERFORMANCE CHARACTERISTICS



Export Control Code : X0863, Document No : D90DH00053

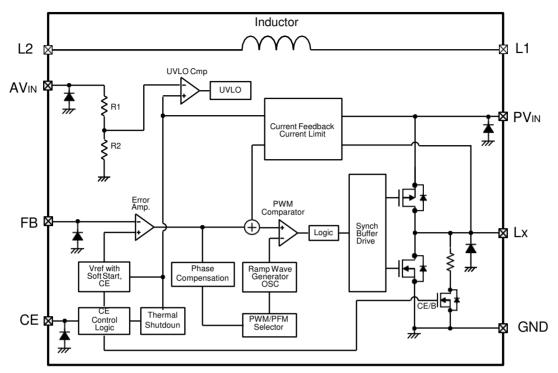




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BLOCK DIAGRAM

MYRGM080200X41RA / MYRGM080200C41RA



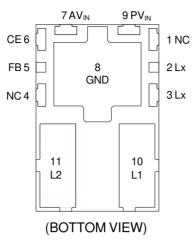
* MYRGM080200X41RA offers a fixed PWM control, a Control Logic of PWM/PFM Selector is fixed at "PWM" internally. MYRGM080200C41RA control scheme is a fixed PWM/PFM automatic switching, a Control Logic of PWM/PFM Selector is fixed at "PWM/PFM automatic switching" internally.

Diodes inside the circuit are an ESD protection diode and a parasitic diode.



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■ PIN CONFIGURATION



* Please connect the AV_Npin (No.7) and the PV_Npin (No.9) when operating. * Please connect the L_xpins (No.2 and No.3).

PIN ASSIGNMENT

PIN NUMBER	PIN NAME	FUNCTIONS
1	NC	No Connection
2	Lx	Switching Output
3	Lx	Switching Output
4	NC	No Connection
5	FB	Output Voltage Monitor
6	CE	Chip Enable
7	AV _{IN}	Analog Input
8	GND	Ground
9	PVIN	Power Input
10	L1	Inductor Electrodes
11	L2	Inductor Electrodes

■ CE PIN FUNCTION

PIN NAME	SIGNAL	STATUS
CE	Low	Stand-by
UE	High	Active

* Please do not leave the CE pin open.

ABSOLUTE MAXIMUM RATINGS

			Ta=25°C
PARAMETER	SYMBOL	RATINGS	UNIT
PVIN Pin Voltage	VPVIN	-0.3 ~ +7.0 ^(*1)	v
AVIN Pin Voltage	VAVIN	-0.3 ~ +7.0 ()/	v
CE Pin Voltage	VCE	-0.3 ~ +7.0	V
FB Pin Voltage	V _{FB}	-0.3 ~ +7.0	V
Lx Pin Voltage	VLx	-0.3 ~ +7.0 or V_{PVIN} +0.3 $^{(*2)}$	V
Lx Pin Current	I _{Lx}	±6.0 ^(*3)	Α
Power Dissipation	Pd	1000(40mm x 40mm Standard board) (*4)	mW
Operating Ambient Temperature	Topr	-40 ~ +85	°C
Storage Temperature	T _{stg}	-55 ~ +125	°C

All voltages are described based on the ground voltage of GND.

 $^{(^*1)}$ Please connect $\mathsf{PV}_{\mathsf{IN}}\,\mathsf{pin}$ (No.9) and $\mathsf{AV}_{\mathsf{IN}}\,\mathsf{pin}$ (No.7) for use.

 $^{(^{\ast}2)}$ The maximum value should be either +7.0 or $V_{\text{PVIN}}\text{+}0.3$ in the lowest.

 $^{(^{\ast}3)}$ It is measured when the two Lx pins (No.2 and 3) are tied up to each other.

 $\ensuremath{^{(\ensuremath{^{\circ}}\ensuremath{^{\circ}}\ensuremath{^{\circ}}}$ The power dissipation figure shown is PCB mounted and is for reference only.

Please see the power dissipation page for the mounting condition.



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ELECTRICAL CHARACTERISTICS

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNIT	CIRCUIT
FB Voltage	V _{FB}	V_{IN} =5.0V, V_{CE} =5.0V Voltage to start oscillation while V_{FB} =0.72V \rightarrow 0.88V	0.784	0.800	0.816	v	3
Operating Voltage Range	V _{IN}	When connected to external components	2.7	-	6.0	V	1
Maximum Output Current	I _{OUTMAX}	$V_{IN}=V_{CE}=5.0V$ (*1,*2) When connected to external components	2.0	-	-	А	1
UVLO Voltage	V _{UVLO}	$V_{CE}{=}5.0V,~V_{FB}{=}0.72V$ Voltage which Lx pin holding "L" level $^{(\mbox{``3)}}$	2.00	-	2.68	V	3
Quiescent Current	lq	$V_{IN} = V_{CE} = 5.0V, V_{FB} = 0.88V$	-	53	92	μA	2
Stand-by Current	I _{STB}	V_{IN} =5.0V, V_{CE} =0V, V_{FB} =0.88V	-	0.01	1.00	μA	2
Switching Frequency	f _{osc}	V _{IN} =V _{CE} =5.0V, I _{OUT} =300mA When connected to external components	2040	2400	2760	kHz	1
PFM Switch Current (*4)	I _{PFM}	$V_{IN}=V_{CE}=6.0V$, $I_{OUT}=1mA$ When connected to external components	-	680	-	mA	1
PFM Duty Limit ^(*4)	DTY_{LIMIT_PFM}	$V_{IN}=V_{CE}=2.7V$, $I_{OUT}=1mA$ When connected to external components	-	180	250	%	1
Maximum Duty Cycle	D _{MAX}	$V_{IN} = V_{CE} = 5.0V, V_{FB} = 0.72V$	100	-	-	%	3
Minimum Duty Cycle	D _{MIN}	$V_{IN}=V_{CE}=5.0V, V_{FB}=0.88V$	-	-	0	%	3
LXSW"H"ON Resistance	R _{LXH}	$V_{IN}=V_{CE}=4.0V, V_{FB}=0.72V^{(*5)}$	-	0.11	0.21	Ω	4
LXSW"L"ON Resistance	R _{LXL}		-	0.12	0.30 (*6)	Ω	_
LXSW"H" Leakage Current	I _{LeakH}	V _{IN} =5.0V, V _{CE} =0V, V _{FB} =0.88V, V _{Lx} =0V	-	0.01	1.00 (*7)	μA	(5)
Current Limit	I _{LIM}	V _{IN} =V _{CE} =5.0V, V _{FB} =0.72V ^(*8)	-	4.0	-	A	4
Output Voltage Temperature Characteristics	ΔV _{OUT} / (Δtopr・V _{OUT})	I _{OUT} =100mA -40°C≦Topr≦85°C When connected to external components	-	±100	-	ppm/°C	1
CE "H" Voltage	V_{CEH}	V_{IN} =5.0V, V_{FB} =0.72V Applied voltage to V_{CE} Voltage changes Lx to "H" level	1.2	-	V _{IN}	V	3
CE "L" Voltage	V _{CEL}	$V_{\text{IN}}\!\!=\!\!5.0\text{V},V_{\text{FB}}\!\!=\!\!0.72\text{V}$ Applied voltage to V_{CE} Voltage changes Lx to "L" level	GND	-	0.4	V	3
CE "H" Current	I _{CEH}	$V_{\text{IN}}{=}5.0V, \ V_{\text{CE}}{=}5.0V, \ V_{\text{FB}}{=}0V$	-0.1	-	0.1	μA	5
CE "L" Current		V_{IN} =5.0V, V_{CE} =0V, V_{FB} =0V	-0.1	-	0.1	μA	5
FB "H" Current	I _{FBH}	V _{IN} =5.0V, V _{CE} =0V, V _{FB} =5.0V	-0.1	-	0.1	μA	5
FB "L" Current	I _{FBL}	V _{IN} =5.0V, V _{CE} =0V, V _{FB} =0V	-0.1	-	0.1	μA	5
Soft-Start Time	t _{ss}	$\label{eq:Vineta} V_{\text{IN}}{=}5.0\text{V}, \ V_{\text{CE}}{=}0\text{V} \rightarrow 5.0\text{V}, \ I_{\text{OUT}}{=}1\text{mA}$ When connected to external components	0.3	1.0	2.0	ms	1
Thermal Shutdown Temperature	T_{TSD}		-	150	-	°C	-
Hysteresis Width	T _{HYS}		-	20	-	°C	_
C _L Discharge Resistance	R _{DCHG}	V _{IN} =5.0V, V _{CE} =0V, V _{FB} =0.72V, V _{Lx} =1.0V	80	130	160	Ω	6
Inductance	L	Test Freq.=1.0MHz	-	1.5	-	μH	-
Inductor Rated Current	I _{DC}	ΔT=+40°C	-	2.3	-	Α	_

 $\mbox{External Components: } C_{IN1} = 20 \mu F(\mbox{ceramic}), \ C_{IN2} = 1 \mu F(\mbox{ceramic}), \ C_L = 20 \mu F(\mbox{ceramic}), \ R1 = 15 k \Omega, \ R2 = 30 k \Omega, \ C_{FB} = 1000 p F(\mbox{ceramic}), \ R1 = 15 k \Omega, \ R2 = 30 k \Omega, \ C_{FB} = 1000 p F(\mbox{ceramic}), \ R1 = 1000 p F(\mbox{ceramic}$

Condition: Unless otherwise stated,"H"= V_{IN} ~ V_{IN} - 1.2V, "L"= + 0.1V ~ -0.1V

⁽¹⁾ Mount conditions affect heat dissipation. Maximum output current is not guaranteed when T_{TSD} starts to operate earlier.

⁽²⁾ When the difference between the input and the output is small, some cycles may be skipped completely before current maximizes.

If current is further pulled from this state, output voltage will decrease because of P-ch driver ON resistance.

(3) These values include UVLO detect voltage, UVLO release voltage and hysteresis operating voltage range.

UVLO release voltage is defined as the V_{IN} voltage which makes Lx pin "H".

 $^{(4)}$ MYRGM080200X41RA exclude I_{PFM} and DTY_{LIMIT_PFM} because those are only for the PFM control's functions.

 $^{(*5)}$ On resistance = (V_{IN} - Lx pin measurement voltage) / 0.1A

(*6) Design value

(*7) When temperature is high, a current of approximately 20µA (maximum) may leak.

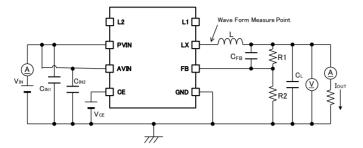
(*8) Current limit denotes the level of detection at peak of coil current.



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TEST CIRCUITS

< Circuit No.(1) >

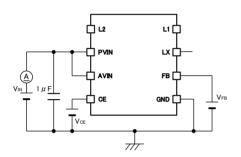


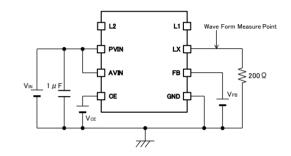
 $\label{eq:expectation} \begin{array}{l} & & & \\ & &$

< Circuit No.②>

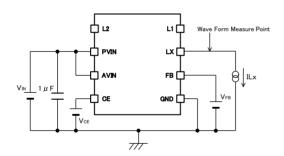
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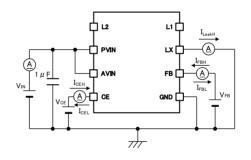
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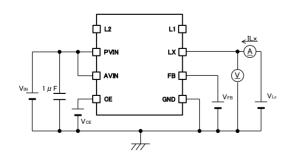


< Circuit No.④>





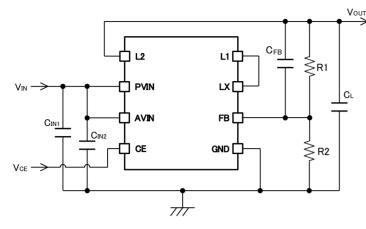
< Circuit No.(6) >





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TYPICAL APPLICATION CIRCUIT



NOTE:

The integrated Inductor can be used only for this DC/DC converter. Please do not use this inductor for other reasons.

[External Components]		
	VALUE	
CIN1 CL	10V/10µF	
	10V/22µF	
Cin2	16V/1µF	

NOTE:

The minimum value of the C_{IN1} should be 10μ F, and it is optimum to set a capacitance value depends on the input impedance. The value of the C_L should be within the range from 20μ F to 47μ F.

<Output Voltage Setting>

Output voltage can be set by adding external split resistors. Output voltage is determined by the following equation, based on the values of RFB1 and RFB2. The sum of RFB1 and RFB2 should normally be $100k\Omega$ or less. Output voltage range is $0.9V\sim5.5V$ by a 0.8V (±2.0%) reference voltage. When input voltage (V_{IN}) \leq setting output voltage, output voltage (V_{OUT}) can not output the power more than input voltage (V_{IN}).

 $V_{OUT} = 0.8 x (R1 + R2) / R2$

The value of C_{FB}, speed-up capacitor for phase compensation, should be $f_{ZFB} = 1 / (2 \times \pi \times CFB \times RFB1)$ which is equal to 20kHz. Adjustments are required from 1kHz to 10kHz depending on the application, value of inductance (L), and value of load capacitance (C_L).

[Example of calculation]

When R_{FB1} =47k Ω , R_{FB2} =15k Ω , V_{OUT} =0.8×(47k Ω +15k Ω) / 15k Ω =3.3V

When C_{FB}=330pF, *fzfb*= $1/(2 \times \pi \times 330 \text{pF} \times 47 \text{ k}\Omega) = 10.26 \text{kHz}$

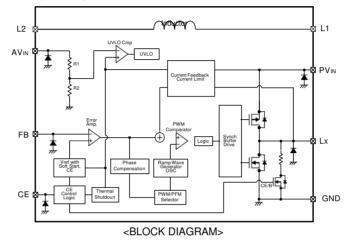
Vout	R _{FB1}	R _{FB2}	Сгв	Vout	R _{FB1}	R _{FB2}	Сгв
(V)	(kΩ)	(kΩ)	(pF)	(V)	(kΩ)	(kΩ)	(pF)
1.0	7.5	30	2000	2.5	51	24	300
1.2	15	30	1000	3.0	33	12	470
1.5	26	30	560	3.3	47	15	330
1.8	30	24	510	5.0	43	8.2	390



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OPERATIONAL DESCRIPTION

The MYRGM-X/C series consists of a reference voltage source, ramp wave circuit, error amplifier, PWM comparator, phase compensation circuit, output voltage adjustment resistors, P-channel MOS driver transistor, N-channel MOS switching transistor for the synchronous switch, current limiter circuit, UVLO circuit and others. (See the BLOCK DIAGRAM below) The series ICs compare, using the error amplifier, the voltage of the internal voltage reference source with the feedback voltage from the FB pin. Phase compensation is performed on the resulting error amplifier output, to input a signal to the PWM comparator to determine the turn-on time during PWM operation. The PWM comparator compares, in terms of voltage level, the signal from the error amplifier with the ramp wave from the ramp wave circuit, and delivers the resulting output to the buffer driver circuit to cause the Lx pin to output a switching duty cycle. This process is continuously performed to ensure stable output voltage. The current feedback circuit monitors the P-channel MOS driver transistor current for each switching operation, and modulates the error amplifier output signal to provide multiple feedback signals. This enables a stable feedback loop even when a low ESR capacitor such as a ceramic capacitor is used ensuring stable output voltage.



<Reference Voltage Source>

The reference voltage source provides the reference voltage to ensure stable output voltage of the DC/DC converter.

<Ramp Wave Circuit>

The ramp wave circuit determines switching frequency. The frequency is fixed internally and can be selected from 1.2MHz or 2.4MHz. Clock pulses generated in this circuit are used to produce ramp waveforms needed for PWM operation, and to synchronize all the internal circuits.

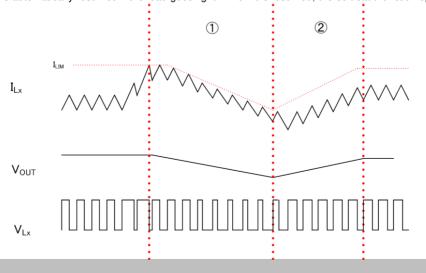
<Error Amplifier>

The error amplifier is designed to monitor output voltage. The amplifier compares the reference voltage with the feedback voltage divided by the external split resistors, R1 and R2. When a voltage lower than the reference voltage is fed back, the output voltage of the error amplifier increases. The gain and frequency characteristics of the error amplifier output are fixed internally to deliver an optimized signal to the mixer.

<Current Limit>

The MYRGM-X/C series includes a fold-back circuit, which aids the operation of the current limiter and circuit protection. The MYRGM-X/C series monitors the current flowing through the P-channel MOS driver transistor

When current flowing through P-channel MOS driver transistor reaches current limit I_{LIM}, the current limiter circuit operates to limit the inductor current I_{LX}. If this state continues, the fold-back circuit operates and limit the output current in order to protect the IC from damage.
The output voltage is automatically resumed if the load goes light. When it is resumed, the soft-start function operates.





2.0A Inductor Built-in Step-Down DC/DC Converters

OPERATIONAL DESCRIPTION (Continued)

<Thermal Shutdown>

For protection against heat damage, the thermal shutdown function monitors chip temperature. When the chip's temperature reaches 150°C (TYP.), the thermal shutdown circuit starts operating and the P-channel driver transistor will be turned off. At the same time, the output voltage decreases. When the temperature drops to 130°C (TYP.) after shutting off the current flow, the IC performs the soft start function to initiate output startup operation.

<Function of CE pin >

The MYRGM-X/C series will enter into stand-by mode by inputting a low level signal to the CE pin. During a stand-by mode, the current consumption of the IC becomes $0 \mu A$ (TYP.). The IC starts its operation by inputting a high level signal to the CE pin. The input of the CE pin is a CMOS input and the sink current is $0 \mu A$ (TYP.).

<UVLO>

When the VIN pin voltage becomes 2.4V (TYP.) or lower, the P-channel MOS driver transistor output driver transistor is forced OFF to prevent false pulse output caused by unstable operation of the internal circuitry. When the V_{IN} pin voltage becomes 2.68V (MAX.) or higher, switching operation takes place. By releasing the UVLO function, the IC performs the soft start function to initiate output startup operation. The soft start function operates even when the VIN pin voltage falls momentarily below the UVLO operating voltage. The UVLO circuit does not cause a complete shutdown of the IC, but causes pulse output to be suspended; therefore, the internal circuitry remains in operation.

<Soft Start>

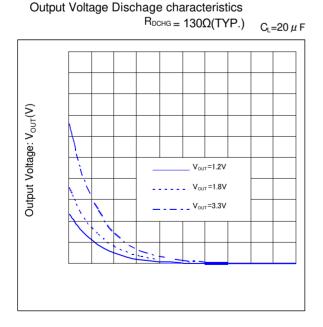
The MYRGM-X/C series provide 1.0ms (TYP). Soft start time is defined as the time interval to reach 90% of the output voltage from the time when the V_{CE} is turned on.

<CL High Speed Discharge>

The MYRGM-X/C series can quickly discharge the electric charge at the output capacitor (C_L) when a low signal to the CE pin which enables a whole IC circuit put into OFF state, is inputted via the N-channel MOS switch transistor located between the L_x pin and the V_{GND} pin. When the IC is disabled, electric charge at the output capacitor (C_L) is quickly discharged so that it may avoid application malfunction. Discharge time of the output capacitor (C_L) is set by the C_L auto-discharge resistance (R) and the output capacitor (C_L). By setting time constant of a C_L auto-discharge resistance value [R] and an output capacitor value (C_L) as τ (τ =C x R), discharge time of the output voltage after discharge via the N-channel transistor is calculated by the following formulas.

 $V = V_{OUT(E)} \times e^{-t/\tau}$ or $t = \tau h(V_{OUT(E)}/V)$

 $\begin{array}{l} V: Output \mbox{ voltage after discharge } \\ V_{OUT(E)}: Output \mbox{ voltage } \\ t: Discharge time \\ \tau C_L \times R_{DCHG} \\ C_L: Capacitance \mbox{ of Output capacitor } \\ R_{DCHG}: C_L \mbox{ auto-discharge resistance } \end{array}$





2.0A Inductor Built-in Step-Down DC/DC Converters

OPERATIONAL DESCRIPTION (Continued)

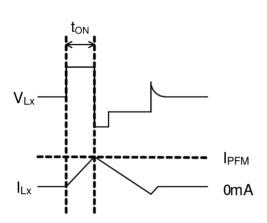
<PFM Switch Current> (*1)

In PFM control operation, until coil current reaches to a specified level (IPFM), the IC keeps the P-channel MOS driver transistor on. In this case, time that the P-channel MOS driver transistor is kept on (t_{ON}) can be given by the following formula. Please refer to I_{PFM} $t_{ON} = L \times I_{PFM} / (V_{IN} - V_{OUT})$

<PFM Duty Limit> (*1)

In PFM control operation, the PFM duty limit (DTY_{LIMIT_PFM}) is set to 200% (TYP.). Therefore, under the condition that the duty increases (e.g. the condition that the step-down ratio is small), it's possible for P-channel MOS driver transistor to be turned off even when coil current doesn't reach to IPFM. Please refer to I_{PFM}

(*1) MYRGM080200X41RA is excluded.



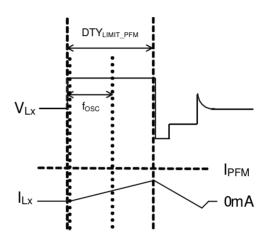


Fig. I_{PFM}(1)





2.0A Inductor Built-in Step-Down DC/DC Converters

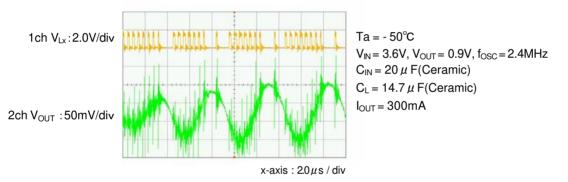
- 1. Please use this IC within the stated maximum ratings. For temporary, transitional voltage drop or voltage rising phenomenon, the IC is liable to malfunction should the ratings be exceeded.
- 2. Where wiring impedance is high, operations may become unstable due to noise and/or phase lag depending on output current.
- Please wire the input capacitor (C_{IN}) and the output capacitor (C_L) as close to the IC as possible.
- 3. When the difference between V_{IN} and V_{OUT} is large in PWM control, very narrow pulses will be outputted, and there is the possibility that some cycles may be skipped completely.
- 4. When the difference between V_{IN} and V_{OUT} is small, and the load current is heavy, very wide pulses will be outputted and there is the possibility that some cycles may be skipped completely.
- 5. With the IC, the peak current of the coil is controlled by the current limit circuit. Since the peak current increases when dropout voltage or load current is high, current limit starts operation, and this can lead to instability. When peak current becomes high, please adjust the coil inductance value and fully check the circuit operation. In addition, please calculate the peak current according to the following formula:

 $lpk = (V_{IN}-V_{OUT}) \times OnDuty / (2 \times L \times f_{OSC}) + I_{OUT}$

L : Coil Inductance Value

fosc: Switching Frequency

- 6. Use of the IC at voltages below the recommended voltage range may lead to instability.
- 7. This IC should be used within the stated absolute maximum ratings in order to prevent damage to the device.
- 8. When the IC is used in high temperature, output voltage may increase up to input voltage level at no load because of the leak current of the P-channel driver transistor.
- 9. The MYRGM-X/C series use fold-back circuit limiter. However, fold-back may become "droop" affected by the wiring conditions. Care must be taken especially for C_{IN} distance and position.
- 10. If C_L capacitance reduction happens such as in the case of low temperature, the IC may enter unstable operation. Care must be taken for C_L capacitor selection and its capacitance value.



11. MURATA places an importance on improving our products and its reliability.

However, by any possibility, we would request user fail-safe design and post-aging treatment on system or equipment.



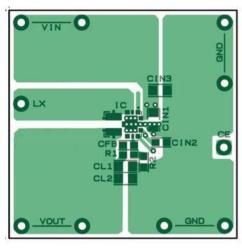
■ NOTE ON USE (Continued) 2.0A Inductor Built-in Step-Down DC/DC Converters

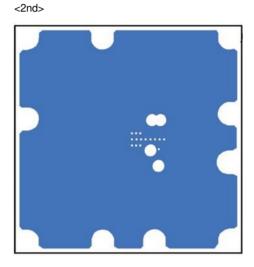
12) Instructions of pattern layouts

- (1) In order to stabilize V_{IN} voltage level, we recommend that that a by-pass capacitor (C_{IN}) be connected as close as possible to PV_{IN} pin, AV_{IN} pin and GND pins.
- (2) Make sure to avoid noise from the PV_{IN} pin to the AV_{IN} pin.
- (3) Please mount each external component as close to the IC as possible.
- (4) Wire external components as close to the IC as possible and use thick, short connecting traces to reduce the circuit impedance.
- (5) Make sure that the PCB GND traces are as thick as possible, as variations in ground potential caused by high ground currents at the time of switching may result in instability of the IC.
- (6) This series' internal driver transistors bring on heat because of the output current and ON resistance of P-channel and N-channel MOS driver transistors.

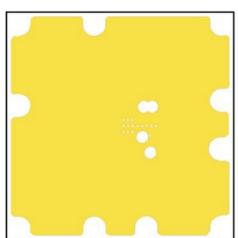
<Reference Pattern Layout>

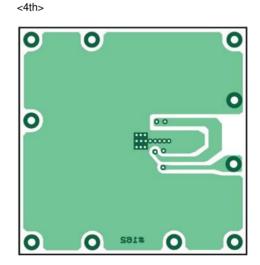
<1st>





<3rd>

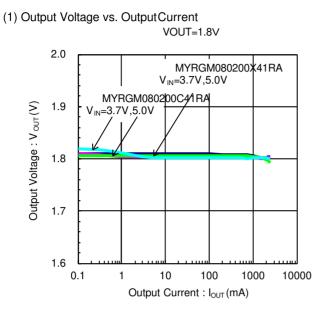




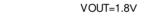


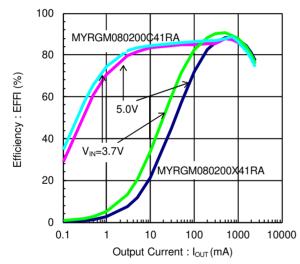
2.0A Inductor Built-in Step-Down DC/DC Converters

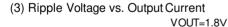
TYPICAL PERFORMANCE CHARACTERISTICS

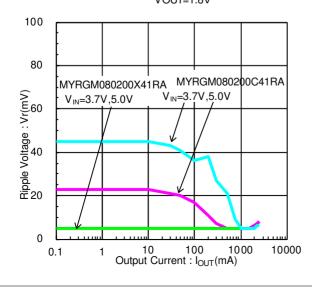


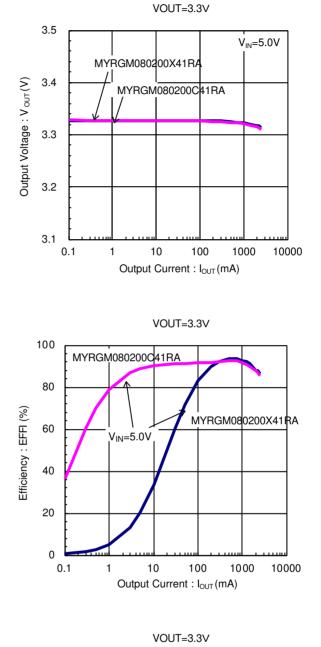
(2) Efficiency vs. Output Current

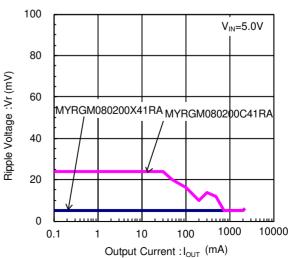










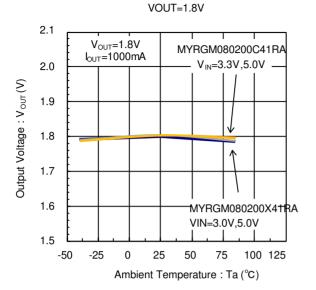


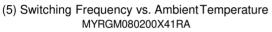


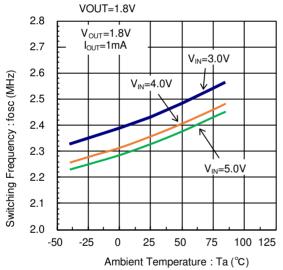
2.0A Inductor Built-in Step-Down DC/DC Converters

TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(4) Output Voltage vs. AmbientTemperature

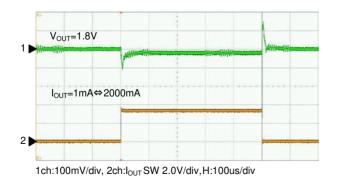


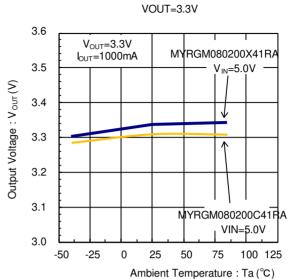


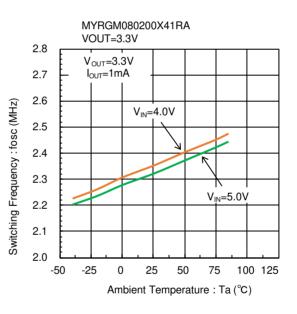


(6) Load Transient Response

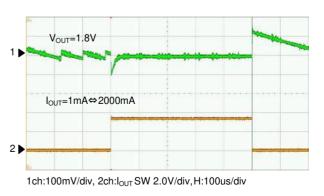
MYRGM080200X41RA Vout=1.8V







MYRGM080200C41RA Vout=1.8V



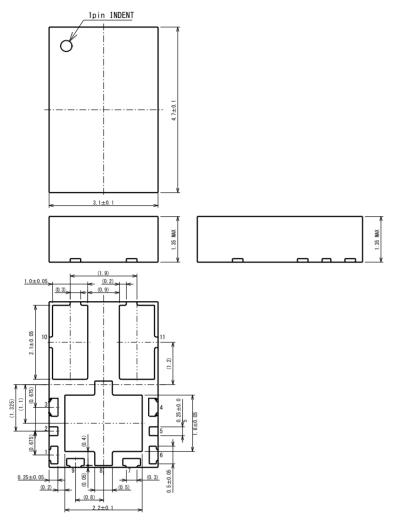


INNOVATOR IN EL

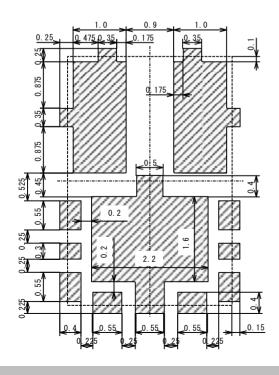
2.0A Inductor Built-in Step-Down DC/DC Converters

PACKAGING INFORMATION

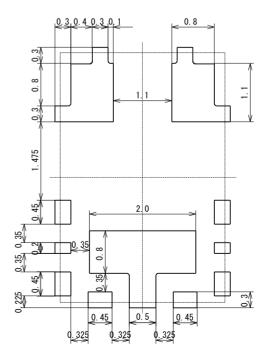
• package (3.1mm×4.7mm, h=1.3mm)



• Reference Pattern Layout (unit: mm)



• Reference Metal Mask Design (unit: mm)





2.0A Inductor Built-in Step-Down DC/DC Converters

Power Dissipation (40mm x 40mm Standard board)

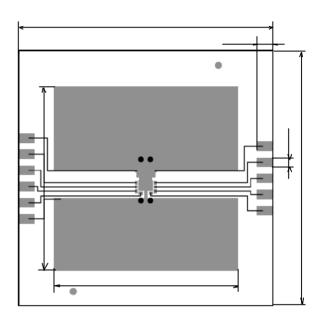
Power dissipation data is shown in this page.

The value of power dissipation varies with the mount board conditions.

Please use this data as the reference data taken in the following condition.

1. Measurement Condition

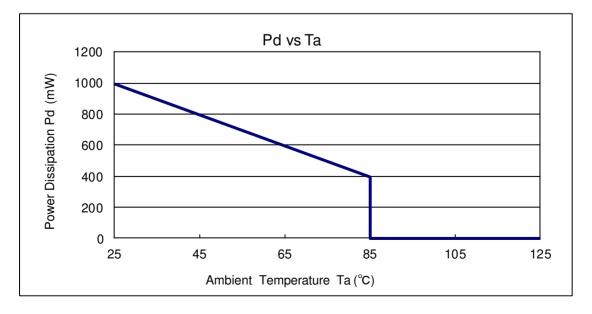
Condition :	Mount on a board
Ambient :	Natural convection
Soldering :	Lead (Pb) free
Board :	Dimensions 40 x 40 mm
	(1600 mm2 in one side)
	Copper (Cu) traces occupy 50% of the
	board area In top and back faces
	Package heat-sink is tied to the copper traces
Material :	Glass Epoxy (FR-4)
Thickness :	1.6mm
Through-hole :	4 x 0.8 Diameter



Evaluation Board (Unit : mm)

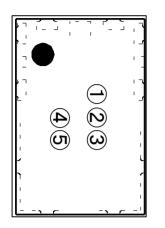
2. Power Dissipation vs. Ambient Temperature

<u>Board Mount (Tj max = 12</u>	25°C)	
Ambient Temperature(°C)	Power Dissipation Pd(mW)	Thermal Resistance (°C/W)
25	1000	100.00
85	400	100.00





MARKING RULE



"PicoBK™" MYRGM-X / MYRGM-C series

2.0A Inductor Built-in Step-Down DC/DC Converters

1 represents product series

MARK	PRODUCT SERIES		
С	MYRGM080200X41RA		
D	MYRGM080200C41RA		

2 represents integer of the reference voltage

•	v	
MARK	REFERENCE VOLTAGE (V)	PRODUCT SERIES
А	0.8 (fix)	MYRGM080200*41RA

③ represents switching Frequency

MARK	SWITCHING FREQUENCY (MHz)	PRODUCT SERIES
2	2.4	MYRGM080200*41RA

(4)(5) represents production lot number

01 to 09, 0A to 0Z, 11 to 9Z, A1 to A9, AA to AZ, B1 to ZZ repeated

(G, I, J, O, Q, W excluded)

*No character inversion used.



"PicoBK[™]" MYRGM-X / MYRGM-C series 2.0A Inductor Built-in Step-Down DC/DC Converters

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