

Description

The AM4961 is a full wave driver IC with PWM control function. It is used for single phase motor and is capable of speed control by changing output duty cycle.

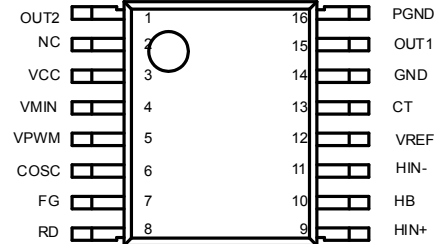
The AM4961 is available in SSOP-16 and HTSSOP-14 packages.

Features

- Built-In Hall Bias Circuit
- Built-In PWM Speed Control Circuit
- Built-In Minimal Speed Setup Circuit
- Rotation Speed Indication (FG)
- Rotation or Lock State Indication (RD)
- Built-In Thermal Shutdown Circuit
- Lock Protection
- Output Current Limit
- **Totally Lead-Free & Fully RoHS Compliant (Notes 1 & 2)**
- **Halogen and Antimony Free. "Green" Device (Note 3)**

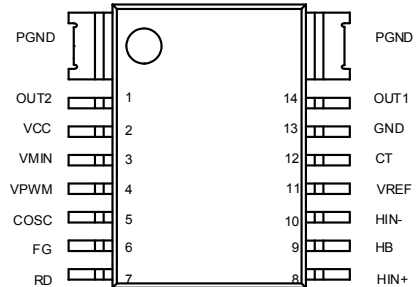
Pin Assignments

(Top View)



SSOP-16

(Top View)



HTSSOP-14

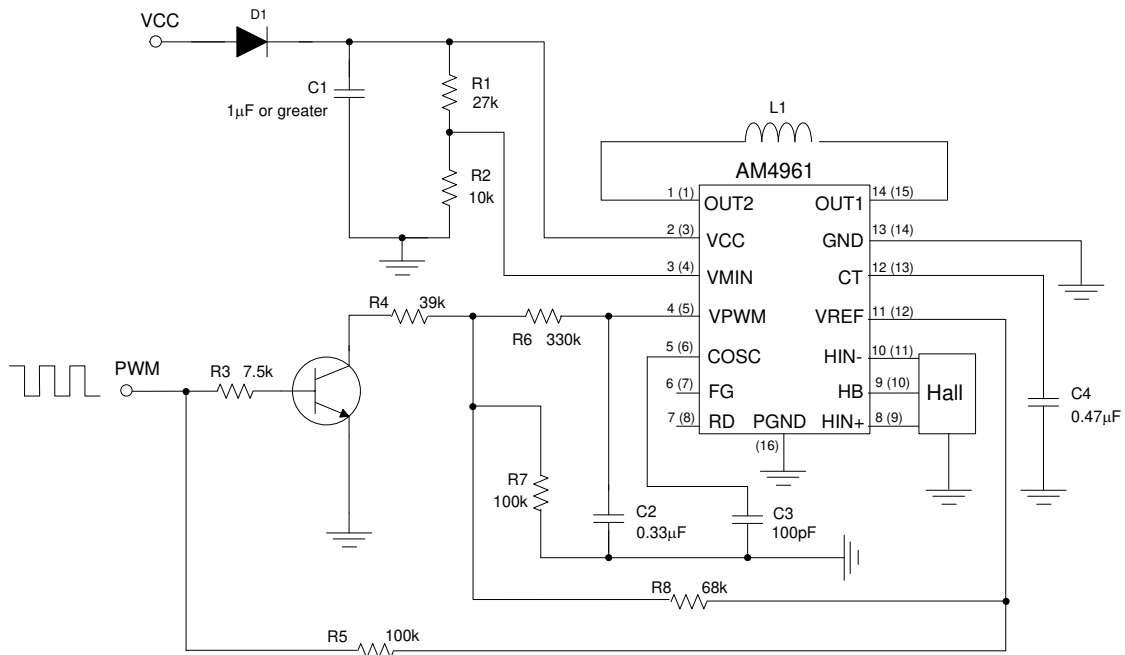
Applications

- CPU Cooler Fan in PC
- Brushless DC Motor Driver

Notes:

1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS), 2011/65/EU (RoHS 2) & 2015/863/EU (RoHS 3) compliant.
2. See <https://www.diodes.com/quality/lead-free/> for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.
3. Halogen- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine (<1500ppm total Br + Cl) and <1000ppm antimony compounds.

Typical Applications Circuit (Note 4)



Note 4:

*1. Ground Line Layout

PGND is connected to motor supply stage and GND is connected to control stage. All ground lines from control stage are connected to GND.

*2. Stability of Power Supply

C1 is employed to stabilize VCC. Its capacitance is no less than 1µF.

*3. Hall Input

To avoid noise, the shortest line is recommended to connect with Hall stage which has about 20mV hysteresis. Thus, the ideal Hall input is 50mV or over.

*4. COSC Capacitor

When CCP is 100pF, the COSC frequency will be 25kHz.

*5. FG Output

FG output terminal is open collector output which varies with phase change.

*6. RD Output

RD output terminal is open collector output. It is low at rotation mode and high when stopped.

*7. HB Pin

This pin is available to output a 1.25V Hall bias voltage.

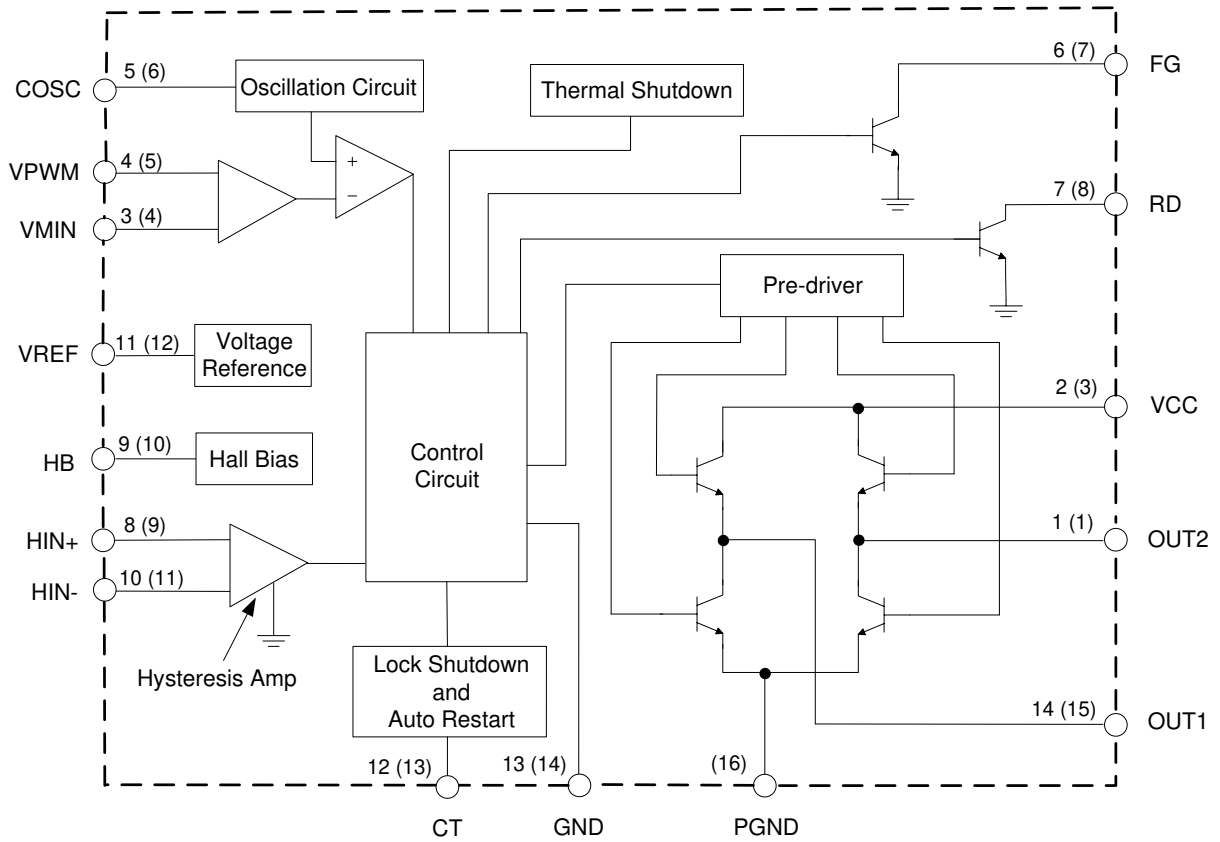
*8. VMIN Pin

If this pin is disused, connect it directly with VPWM, the minimum duty cycle will be 10%.

Pin Descriptions

Pin Number		Pin Name	Function
HTSSOP-14	SSOP-16		
1	1	OUT2	Driver output 2
–	2	NC	No connection
2	3	VCC	Power supply
3	4	VMIN	Minimum duty setting
4	5	VPWM	Adjustable Input
5	6	COSC	Oscillator capacitor
6	7	FG	Rotation speed indicator
7	8	RD	Rotation/lock state indicator
8	9	HIN+	Hall sensor input +
9	10	HB	Hall sensor bias regulator
10	11	HIN-	Hall sensor input
11	12	VREF	Reference voltage regulator
12	13	CT	Lock and rotation setting capacitor terminal
13	14	GND	Ground for control circuit
14	15	OUT1	Driver output 1
–	16	PGND	Power ground

Functional Block Diagram



A (B)
A for 14-pin B for 16-pin

Absolute Maximum Ratings (Note 5)

Symbol	Parameter	Value		Unit
V _{CC}	Supply Voltage	18		V
I _{OUT}	Output Current	1.0		A
V _{OUT}	Output Voltage	18		V
I _{HB}	HB Output Current	10		mA
V _{PWM}	VPWM Input Voltage	6		V
V _{RD}	RD Output Voltage	18		V
V _{FG}	FG Output Voltage	18		V
I _{RD}	RD Output Current	10		mA
I _{FG}	FG Output Current	10		mA
P _D	Power Dissipation (Note 6)	SSOP-16	0.8	W
		HTSSOP-14	1.1	W
T _{STG}	Storage Temperature Range	-55 to +150		°C
ESD	ESD (Human Body Model)	2000		V
ESD	ESD (Machine Model)	250		V

Notes: 5. Stresses greater than those listed under "Absolute Maximum Ratings" can cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "Recommended Operating Conditions" is not implied. Exposure to "Absolute Maximum Ratings" for extended periods can affect device reliability
6. T_A = +25°C, no external heatsink.

Recommended Operating Conditions

Symbol	Parameter	Min	Typ	Max	Unit
V _{CC}	Supply Voltage	3.5	12	16	V
V _{IN+}	Hall Input Voltage + (Note 7)	0.2	–	3	V
V _{IN-}	Hall Input Voltage - (Note 7)	0.2	–	3	V
T _A	Ambient Temperature	-30	–	+90	°C

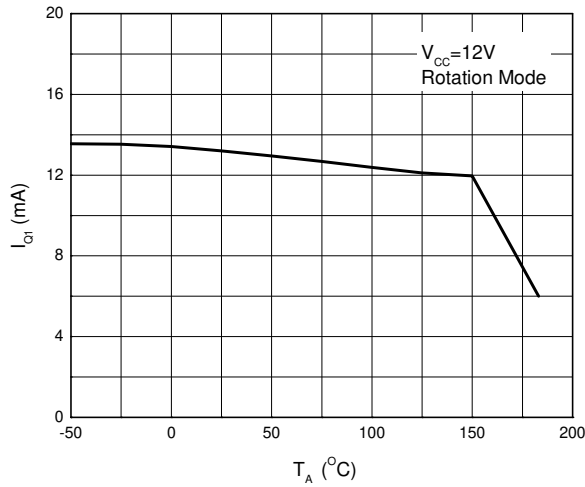
Note: 7. Hall input voltage range includes the amplitude of signal.

Electrical Characteristics ($V_{CC}=12V$, $T_A=+25^{\circ}C$, unless otherwise specified.)

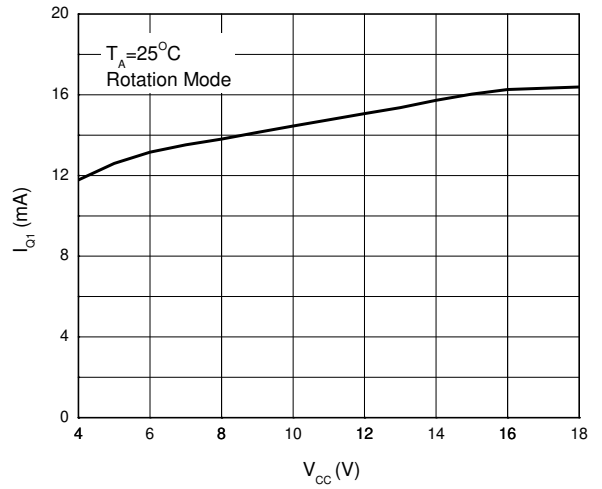
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{Q1}	Quiescent Current	Lock Off	10.2	15	18.76	mA
I_{Q2}		Lock On	5.38	8	10.55	
V_{REF}	VREF Voltage	$I_{REF}=5mA$	5.8	6	6.2	V
V_{SATH}	Output Saturation Voltage at High Side	$I_{SOURCE}=200mA$	–	1.0	1.17	V
V_{SATL}	Output Saturation Voltage at Low Side	$I_{SINK}=200mA$	–	0.2	0.3	V
f_{OSC}	COSC Frequency	$C_{OSC}=100pF$	18	25	32	kHz
V_{OSCH}	COSC High Level Voltage	–	3.45	3.6	3.75	V
V_{OSCL}	COSC Low Level Voltage	–	1.83	1.95	2.07	V
V_{HYS}	Hall Input Hysteresis	–	–	± 10	± 20	mV
V_{HB}	Hall Bias Voltage	$I_{HB}=5mA$	1.1	1.25	1.4	V
V_{CTH}	CT High Level Voltage	–	3.55	3.7	3.88	V
V_{CTL}	CT Low Level Voltage	–	1.55	1.7	1.85	V
I_{CHG}	CT Charge Current	–	1.5	2	2.85	μA
I_{DHG}	CT Discharge Current	–	0.14	0.2	0.285	μA
R_{CD}	CT Charge and Discharge Ratio	I_{CHG}/I_{DHG}	8.5	10	14.5	–
V_{FGL}	FG Output Low Level Voltage	$I_{FG}=5mA$	–	0.2	0.3	V
I_{LFG}	FG Leakage Current	$V_{FG}=12V$	–	–	30	μA
$V_{RD L}$	RD Output Low Level Voltage	$I_{RD}=5mA$	–	0.2	0.3	V
I_{LRD}	RD Leakage Current	$V_{RD}=12V$	–	–	30	μA

Performance Characteristics

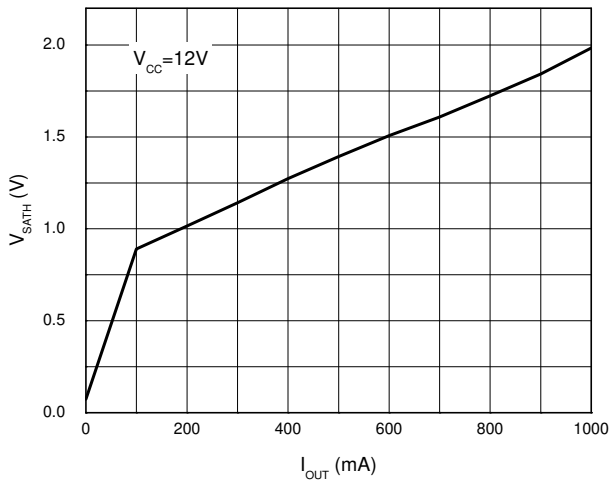
Quiescent Current vs. Ambient Temperature



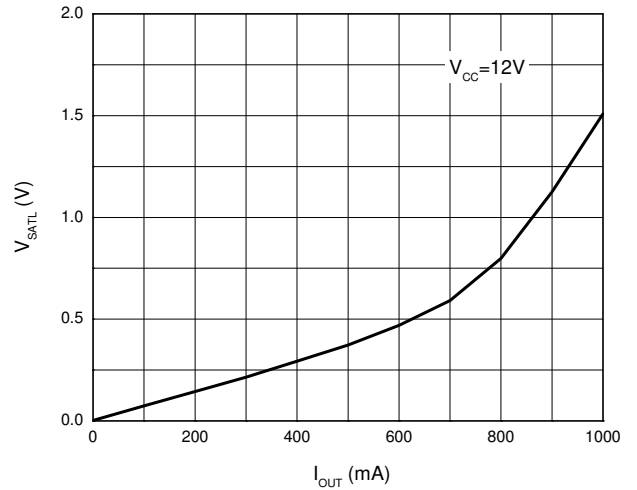
Quiescent Current vs. Supply Temperature



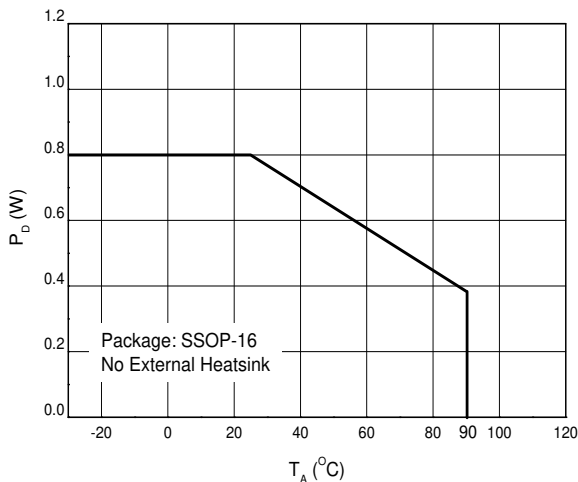
Output Saturation Voltage (High) vs. Output Current



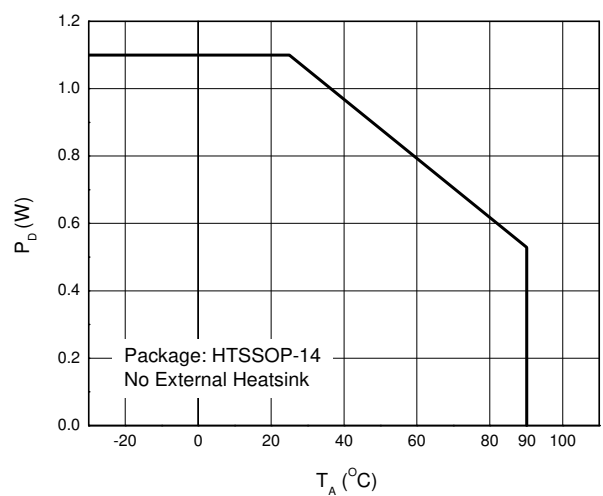
Output Saturation Voltage (Low) vs. Output Current



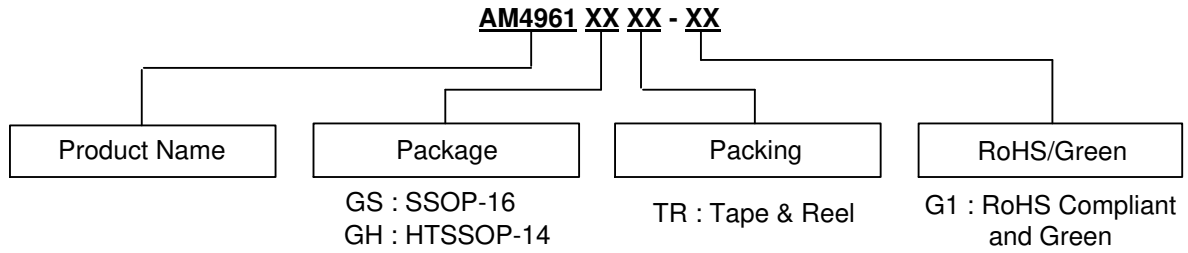
Power Dissipation vs. Ambient Temperature



Power Dissipation vs. Ambient Temperature

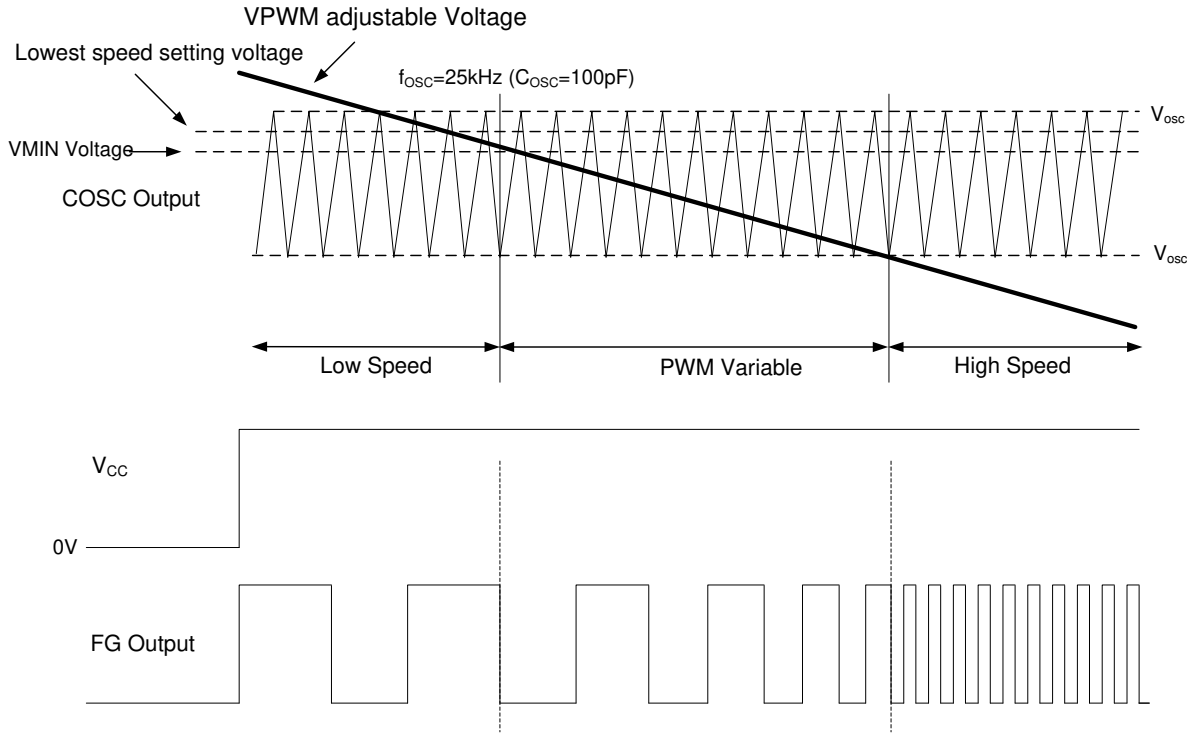


Ordering Information



Package	Temperature Range	Part Number	Marking ID	13" Tape and Reel
				Quantity
SSOP-16	-30 to +90°C	AM4961GSTR-G1	AM4961GS-G1	3000/Tape & Reel
HTSSOP-14	-30 to +90°C	AM4961GHTR-G1	AM4961GH-G1	3000/Tape & Reel

Operating Diagram (Note 8)



Note 8:

1. Low Speed Setting Mode

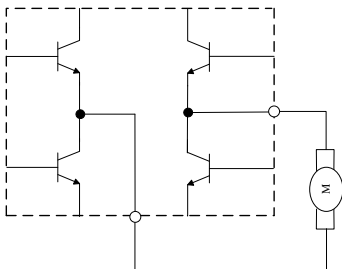
When VPWM voltage is higher than VMIN pin voltage, motor speed is settable by VMIN pin voltage. The minimum drive duty cycle is settable by comparing COSC oscillating voltage and VMIN pin voltage.

VPWM voltage is decided by variation of PWM duty.

2. Variable Speed Setting Mode

When VPWM voltage is lower than VMIN pin voltage, PWM control system works by comparing VPWM voltage and COSC voltage. If VPWM voltage is higher, the ON duty cycle of the upper side transistors will be minimized and motor speed becomes lower. Vice versa.

3. Full Speed Rotation Mode

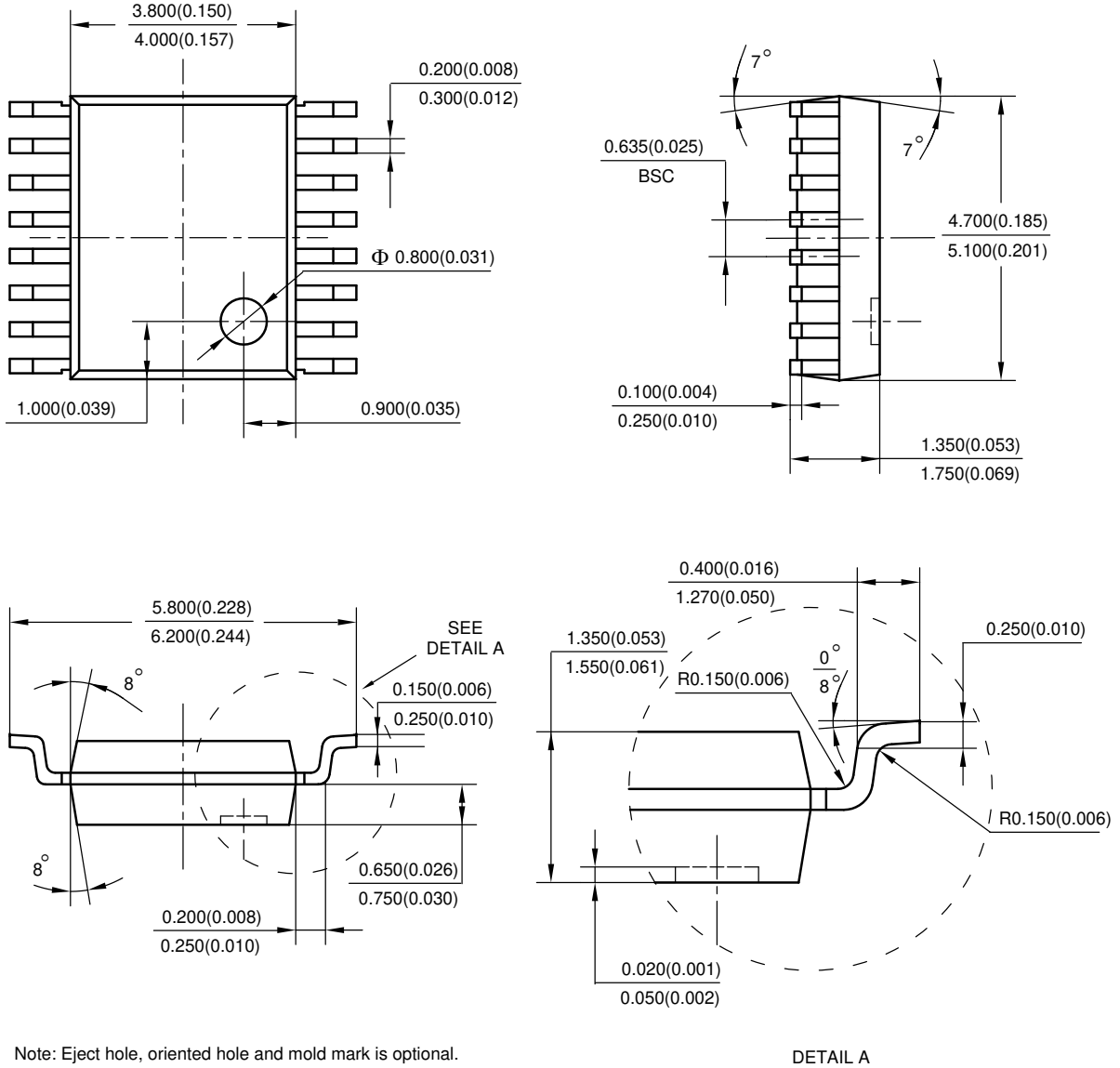


At a certain PWN duty, when VPWM voltage is lower than the low side of COSC output voltage, the motor will run at full speed.

Package Outline Dimensions (All dimensions in mm(inch).)

Please see <http://www.diodes.com/package-outlines.html> for the latest version.

(1) Package Type: SSOP-16



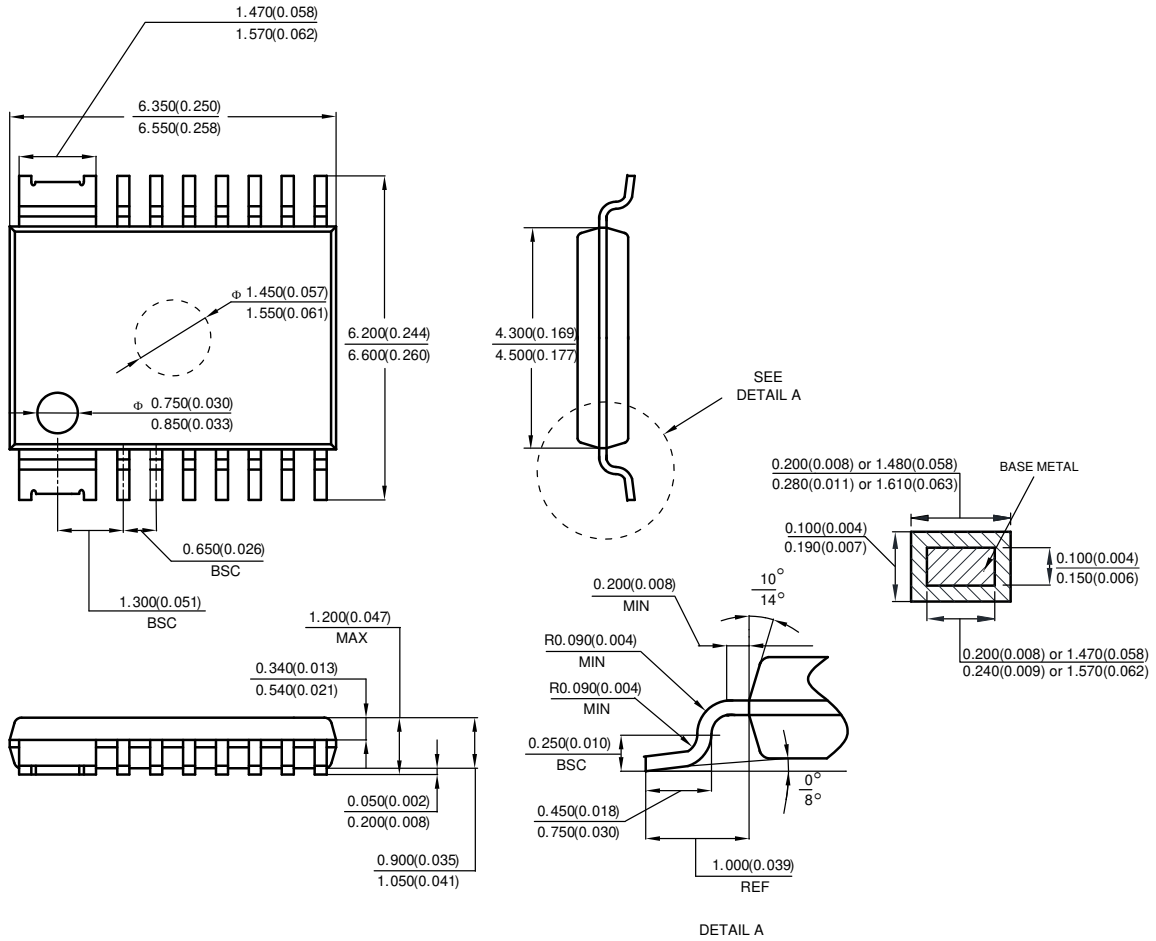
Note: Eject hole, oriented hole and mold mark is optional.

DETAIL A

Package Outline Dimensions (continued. All dimensions in mm(inch).)

Please see <http://www.diodes.com/package-outlines.html> for the latest version.

(2) Package Type: HTSSOP-14

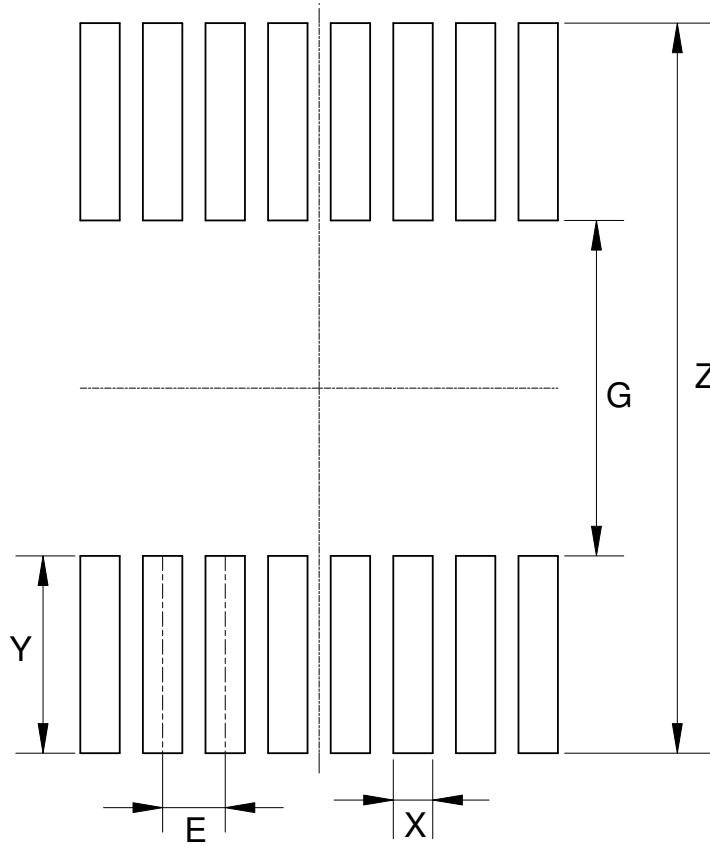


Note: Eject hole, oriented hole and mold mark is optional.

Suggested Pad Layout

Please see <http://www.diodes.com/package-outlines.html> for the latest version.

(1) Package Type: SSOP-16

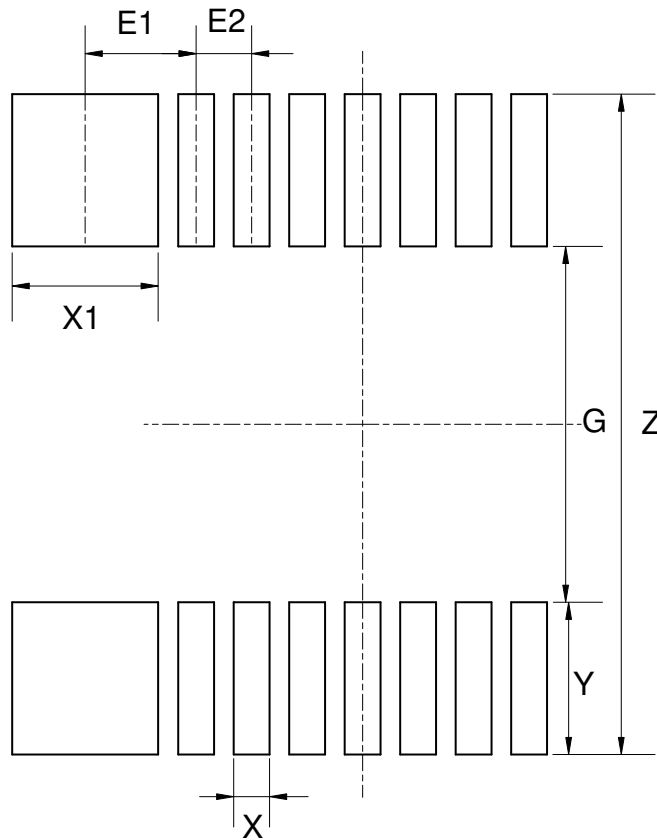


Dimensions	Z (mm)/(inch)	G (mm)/(inch)	X (mm)/(inch)	Y (mm)/(inch)	E (mm)/(inch)
Value	7.400/0.291	3.400/0.134	0.400/0.016	2.000/0.079	0.635/0.025

Suggested Pad Layout (continued)

Please see <http://www.diodes.com/package-outlines.html> for the latest version.

(2) Package Type: HTSSOP-14



Dimensions	Z (mm)/(inch)	G (mm)/(inch)	X (mm)/(inch)	X1 (mm)/(inch)
Value	7.720/0.304	4.160/0.164	0.420/0.017	1.710/0.067
Dimensions	Y (mm)/(inch)	E1 (mm)/(inch)	E2 (mm)/(inch)	—
Value	1.780/0.070	1.300/0.051	0.650/0.026	—

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