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FEATURES AND BENEFITS

- Integrated boost MOSFET, current sensing, and compensation
- Stable with low-profile ceramic boost capacitors
- Configurable output settings to meet global requirements
- A8303-1 includes 11.667 V setting to meet Japanese market requirements
- Adjustable LNB output current limit from 250 to 950 mA \Box Covers wide array of application requirements
	- \Box Minimizes component sizing to fit each application
	- \Box For startup, reconfiguration, and continuous output (maximum value depends on PCB thermal design)
- Boost peak current limit scales with LNB current limit setting
- 8 programmable LNB output voltage (DAC) levels
- LNB overcurrent limiter with shutdown timer
- Static LNB current limit reliably starts a wide range of loads
- Tracking boost converter minimizes power dissipation
- LNB transition times configurable by external capacitor

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PACKAGE:

 $4 \text{ mm} \times 4 \text{ mm} \times 0.75 \text{ mm}$

DESCRIPTION

Intended for analog and digital satellite receivers, these single low noise block converter regulator (LNBR) are monolithic linear and switching voltage regulators, specifically designed to provide the power and the interface signals to an LNB down converter via coaxial cable. The A8303 and A8303-1 require few external components, with the boost switch and compensation circuitry integrated inside of the devices. A high switching frequency is chosen to minimize the size of the passive filtering components, further assisting in cost reduction. The high levels of component integration ensure extremely low noise and ripple figures.

The A8303 and A8303-1 have been designed for high efficiency, using the Allegro™ advanced BCD process. The integrated boost switch has been optimized to minimize both switching and static losses. To further enhance efficiency, the voltage drop across the tracking regulator has been minimized.

For DiSEqC™ communications, a tone control pin is provided to gate the internally generated 22 kHz tone on-and-off.

A comprehensive set of fault registers are provided, which comply with all the common standards, including: overcurrent, thermal shutdown, undervoltage, and power not good.

Furthermore, design methodology and structure ensure the highest level of robustness against transients and component failures. The devices use a 2-wire bidirectional serial interface, compatible with the I²CTM standard, that operates up to 400 kHz.

The A8303 and A8303-1 are supplied in a lead (Pb) free package.

Functional Block Diagram

FEATURES AND BENEFITS (continued)

- Push-pull LNB output stage maintains 13→18 V and 18→13 V transition times, even with highly capacitive loads
- Built-in 22 kHz tone oscillator facilitates DiSEqC™ tone encoding, even at no-load
- Tone generation does not require additional external components
- Diagnostic features: PNG, TDET
- Dynamic tone detect amplitude and frequency transmit/ receive thresholds
- Extensive protection features: UVLO, OCP, TSD, CPOK
- 2-wire I2C-compatible interface

SELECTION GUIDE

[1] Contact Allegro for additional packing options.

[2] Leadframe plating 100% matte tin.

ABSOLUTE MAXIMUM RATINGS

[3] Output current rating may be limited by duty cycle, ambient temperature, and heat sinking. Under any set of conditions, do not exceed the specified current ratings, or a junction temperature, ${\sf T}_{\sf J}$, of 150°C.

[4] See application schematics 3 and 4 on pages 24 and 25.

THERMAL CHARACTERISTICS

[5] Additional thermal information available on the Allegro website.

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Pinout Diagram

Terminal List Table

ELECTRICAL CHARACTERISTICS [1]: Valid at TA = 25°C, VIN = 10 to 16 V, as noted [2], unless noted otherwise

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ELECTRICAL CHARACTERISTICS [1] (continued): Valid at TA = 25°C, VIN = 10 to 16 V, as noted [2], unless noted otherwise

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ELECTRICAL CHARACTERISTICS [1] (continued): Valid at TA = 25°C, VIN = 10 to 16 V, as noted [2], unless noted otherwise

[1] Operation at 16 V may be limited by power loss in the linear regulator.

 $^{[2]}$ Indicates specifications guaranteed from 0 ≤ T $_{\textrm{\scriptsize{J}}}$ ≤ 125°C $_{\textrm{\scriptsize{MIN}}}$.

[3] Guaranteed by worst case process simulations and system characterization. Not production tested.

[4] LNB output ripple and noise are dependent on component selection and PCB layout. Refer to the Application Schematic and PCB layout recommendations. Not production tested.

[5] Current from the LNB output may be limited by the choice of Boost components.

FUNCTIONAL DESCRIPTION

Protection

The A8303 and A8303-1 have a wide range of protection features and fault diagnostics which are detailed in the Status Register section.

Boost Converter/Linear Regulator

The A8303 and A8303-1 solution contains a tracking currentmode boost converter and linear regulator. The boost converter tracks the requested LNB voltage to within 800 mV, to minimize power dissipation. Under conditions where the input voltage, V_{BOOST} , is greater than the output voltage, V_{LNB} , the linear regulator must drop the differential voltage. When operating in these conditions, care must be taken to ensure that the safe operating temperature range of the A8303 and A8303-1 is not exceeded.

The boost converter operates at 352 kHz typical: 16 times the internal 22 kHz tone frequency. All the loop compensation, current sensing, and slope compensation functions are provided internally.

The A8303 and A8303-1 have internal pulse-by-pulse current limiting on the boost converter and DC current limiting on the LNB output to protect the IC against short circuits. When the LNB output is shorted, the LNB output current is limited, and if the overcurrent condition lasts for more than 45 ms, the LNB output will be disabled. If this occurs, the A8303 and A8303-1 output must be reenabled for normal operation. The system should provide sufficient time between successive restarts to limit internal power dissipation; 1 to 2 seconds is recommended

At extremely light load or no load, if the BOOST voltage tries to exceed the BOOST target voltage, the boost converter operates with minimum on time. BOOST settling voltage depends on supply voltage, boost inductance, minimum on time, switching frequency, output power and power loss in boost inductor, capacitor and A8303 and A8303-1. If the BOOST voltage settles below pulse skipping threshold (23.7 V), the boost converter continues to operate with minimum on time. If BOOST voltage tries to exceed 23.7 V, pulse skipping occurs, and pulse skipping stops when the BOOST voltage drops to 23.4 V.

In the case that two or more set top box LNB outputs are connected together by the customer (e.g., with a splitter), it is possible that one output could be programmed at a higher voltage than the other. This would cause a voltage on one output that is higher than its programmed voltage (e.g., 19 V on the output of a 13 V programmed voltage). The output with the highest voltage will effectively turn off the other outputs. As soon as this voltage is reduced below the value of the other outputs, the A8303 and A8303-1 output will auto-recover to their programmed levels.

Charge Pump. Generates a supply voltage above the internal tracking regulator output to drive the linear regulator control.

LNB and BOOST Current Limits. The LNB output current limit, $I_{\text{OUT} (MAX)}$ can be set by connecting a resistor (RSET) from the ISET pin to GND as shown in the applications schematic. The LNB current limit can be set from 300 to 800 mA, corresponding to an R_{SET} value of 100 to 37.4 kΩ, respectively. If the LNB current limit is exceeded for more than the Overcurrent Disable Time (t_{DIS}) then the A8303 and A8303-1 will be shut down and the OCP bit set, as shown in figure 1. The LNB output current limit can be set as high as 950 mA (R_{SET} = 31.6 kΩ) but care should be taken not to exceed the thermal limit of the package or thermal shutdown (TSD) will occur. The typical LNB output current limit can be set according to the following equation:

 $I_{\text{OUT} (MAX)} = 29,925 / R_{\text{SET}}$,

where $I_{\text{OUT}(MAX)}$ is in mA and R_{SET} is in kΩ. If the voltage at the ISET pin is 0 V (that is, shorted to GND), $I_{\text{OUT}(MAX)}$ will be clamped to a moderately high value (approximately 1.5 A). Care should be taken to ensure that ISET is not inadvertently grounded. If no resistor is connected to the ISET pin (that is, if ISET is open-circuit), $I_{\text{OUT}(MAX)}$ will be set to approximately 0 A and the A8303 and A8303-1 will not support any load (OCP will occur prematurely).

The BOOST pulse-by-pulse current limit, $I_{\text{BOOST}(MAX)}$, is automatically scaled along with the LNB output current limit. The typical BOOST current limit is set according to the following equation:

$$
I_{\text{BOOST(MAX)}} = 4.7 \times I_{\text{OUT(MAX)}} + 270 \text{ mA} ,
$$

where both $I_{\text{BOOST}(MAX)}$ and $I_{\text{OUT}(MAX)}$ are in mA.

Automatically scaling the BOOST current limit allows the designer to choose the lowest possible saturation current of the boost inductor, reducing its physical size and PCB area, thus minimizing cost.

Slew Rate Control. During either start-up, or when the output voltage at the LNB pin is transitioning, the output voltage rise and fall times can be set by the value of the capacitor connected from the TCAP pin to GND (C12 in the Applications Schematic). Note that during start-up, the BOOST pin is pre-charged to the input voltage minus a diode voltage drop. As a result, the slew rate control for the BOOST pin occurs from this voltage.

The value of C12 can be calculated using the following formula:

$$
C_{12} = (I_{\text{TCAP}} \times 6) / SR ,
$$

where SR is the required slew rate of the LNB output voltage, in V/s , and I_{TCAP} is the TCAP pin current specified in the Electrical Characteristics table. The recommended value for C_{12} , 100 nF, should provide satisfactory operation for most applications.

The minimum value of C_{12} is 10 nF. There is no theoretical maximum value of C_{12} however too large a value will probably cause the voltage transition specification to be exceeded. Tone generation is unaffected by the value of C_{12} .

Pull-Down Rate Control. In applications that have to operate at very light loads and that require large load capacitances (in the order of tens to hundreds of microfarads), the output linear stage provides approximately 45 mA of pull-down capability. This ensures that the LNB output voltage is ramped from 18 to 13 V in a reasonable amount of time. When the tone is on $(TONECTRL = 1)$, the output linear stage must increase its pull-down capability to approximately 100 mA. This ensures that the tone signal meets all specifications, even with no load on the on the LNB output.

ODT (Overcurrent Disable Time)

If the LNB output current exceeds the set output current, for more than 45 ms, then the LNB output will be disabled and the OCP bit will be set. See figure 1.

Short Circuit Handling

If the LNB output is shorted to ground, the LNB output current will be clamped to $I_{\text{OUT}(MAX)}$. If the short circuit condition lasts for more than 45 ms, the A8303 and A8303-1 will be disabled and the OCP bit will be set.

Auto-Restart

After a short circuit condition occurs, the host controller should periodically reenable the A8303 and A8303-1 to check if the short circuit has been removed. Consecutive startup attempts should allow 1 to 2 seconds of delay between restarts.

Figure 1. Startup, Reconfiguration, and Short Circuit operation using R_{SET} = 37.4 kΩ, and a capacitive load

In-Rush Current

At start-up or during an LNB reconfiguration event, a transient surge current above the normal DC operating level can be provided by the A8303 and A8303-1. This current increase can be as high as the set output current, for as long as required, up to a maximum of 45 ms.

Tone Generation

A 22 kHz tone is generated internally, and can be controlled on and off via the TONECTRL pin as shown in figure 2. Note this tone can be generated under no-load conditions, and does not require the use of an external DiSEqC filter.

Tone Detection

A 22 kHz tone detector is provided in the A8303 and A8303-1. The detector extracts the 22 kHz signal from the AC-coupled TDI pin and provides it as an open-drain logic output at the TDO pin. Also, when a tone is present, the TDET bit in the Status register is set high and can be seen via the I2C interface. The tone detection delay is typically shorter than 1.5 cycles.

The tone detector dynamically adjusts its amplitude and frequency thresholds depending on whether the A8303 and A8303-1 are transmitting or receiving a tone signal. If TONECTRL is a logic high, the A8303 and A8303-1 are transmitting and the tone detect amplitude threshold is relatively high and the acceptable frequency range is tight. This guarantees a high quality tone signal is always generated by the A8303 and A8303-1. On the other hand, if TONECTRL is a logic low, the A8303 and A8303-1 are receiving and the tone detect amplitude threshold is reduced and the acceptable frequency range is increased slightly. This guarantees the A8303 and A8303-1 have maximum sensitivity to remotely generated tone signals that may be degraded by long lengths of coaxial cable. The Electrical Characteristics table of this datasheet documents the guaranteed specifications of the tone detector and how they are adjusted by TONECTRL. To help in the understanding, typical tone detector operation is shown graphically in figures 3a and 3b. The shaded areas in figure 3a indicate the accept range of the detector when TONECTRL is a logic high (transmit) and a logic low (receive). The shaded areas in figure 3b indicate the reject range of the detector when TONECTRL is a logic high (transmit) and a logic low (receive).

Figure 2. Internal tone, gated by TONECTRL pin

Figure 3a. Accept Ranges of Tone Detection feature

Component Selection

BOOST INDUCTOR

The A8303 and A8303-1 are designed to operate with a boost inductor value of 15 μ H +30%/-40% with a DCR less than 75 mΩ. The error amplifier loop compensation, current sense gain, and PWM slope compensation were chosen for this value of inductor. The boost inductor must be able to support the peak currents required to maintain the maximum LNB output current without saturating. Figure 4 can be used to determine the peak current in the inductor given the LNB load current. The "typical" curve uses $V_{IN} = 12$ V, $V_{OUT} = 19$ V, L = 15 µH, and f = 352 kHz, while the "maximum" curve assumes $V_{IN} = 9 V$, $V_{OUT} = 20 V$, $L = 12 \mu H$, and $f = 282 \text{ kHz}$.

The system will have reduced gain and phase margins, if the boost inductor is higher than 22 µH. Figure 6 shows a Bode plot of the boost loop with $3 \times 10 \mu$ F of boost capacitance and 33, 22, 18, 15, and 10 µH of boost inductance. Although this plot assumes many of the system variables are "worst case" (10.8

Figure 4. Boost inductor peak current versus I_{LNB}

 V_{IN} , 20 V_{OUT} , +2% DAC tolerance, 1V of ΔV_{REG} , 1.1 A load, and 320 kHz), these conditions could certainly occur in an application. This plot shows that, as the boost inductance increases, the 0 dB crossover frequency remains relatively constant but the phase and gain margins are reduced. With 22 µH, the phase margin is 32° and with 33 μ H the phase margin is only 10°.

Figure 6. Gain and Phase Margin of the boost loop at various inductance levels

BOOST CAPACITORS

The A8303 and A8303-1 are designed to operate with two or three, high-quality ceramic capacitors on the boost node. Allegro recommends capacitors that are rated at least 35 V, $\pm 10\%$, X7R, 1210 size. Physically smaller capacitors, like 0603 and 0805, with lower temperature ratings, like X5R and Z5U, should be avoided. Figure 5 can be used to determine the necessary rms current rating of the boost capacitor given the LNB load current. The "typical" curve uses $V_{IN} = 12$ V, $V_{OUT} = 19$ V, $L = 15$ μ H, and $f = 352$ kHz while the "maximum" curve assumes $V_{IN} = 9$ V, V_{OUT} = 20 V, L = 12 µH, and f = 282 kHz.

The nominal boost capacitance should total 18.8 to 30 µF. Allegro recommends either four 4.7 μ F or three 10 μ F capacitors, with the characteristics shown in table 1. If tolerance, temperature, and DC bias effects are considered, the capacitance must total at least 13 µF. The DC bias effect is very significant on ceramic capacitors with lower voltage ratings, smaller packages, or wider temperature characteristics. For example, a 10 µF, 25 V, 1206, X5R capacitor can lose 85% of its value at 20 VDC bias. If the total boost capacitance becomes less than 12μ F, the converter will have reduced gain and phase margins. If the total boost

capacitance becomes less than 7.5μ F, then the converter will very likely be unstable.

Figure 7 shows a Bode plot of the boost loop with 15 µH of boost inductance and 20, 15, 10, 7.5, and 5 µF of boost capacitance. Although this plot assumes many of the system variables are "worst case" (10.8 V_{IN} , 20 V_{OUT} , +2% DAC tolerance, 1 V of ΔV_{REG} , 1.1 A load, and 320 kHz), these conditions could certainly occur in an application. This plot shows that, as the boost capacitance decreases, the 0 dB crossover frequency increases and the phase and gain margins are reduced. At 7.5 µF the phase margin is only 6° and at 5 μ F this system is unstable.

Two possible ceramic based capacitor solutions have been presented. Other capacitor combinations are certainly possible, such as a very low ESR electrolytic capacitor in parallel with several microfarads of ceramic capacitance. However, there are two critical requirements that must be satisfied: 1) the zero formed by the electrolytic capacitor and its ESR should be at least 1 decade higher than the 0 dB crossover of the boost loop (typically around 25 kHz), and 2) the ceramic capacitors must eliminate the high frequency switching spikes/edges in the boost voltage, or the LNB output noise will be too high.

Figure 5. Boost capacitor rms current versus I_{LNB}

Figure 7. Gain and Phase Margin of the boost loop at various capacitance values

BOOST FILTERING AND LNB NOISE

The LNB output noise depends on the amount of high-frequency noise at the BOOST pin. To minimize the high-frequency noise at the BOOST pin, the ceramic capacitors should be placed as close as possible to the BOOST pin.

SURGE COMPONENTS

The circuit shown in schematic 1 includes external diodes for surge protection. The Applications Information section includes D2, D3, and D4 component recommendations in table 6. This configuration and these components have successfully passed surge tests up to ± 1000 V/500 A, with a 1.2/50 μ s – 8/20 μ s combination wave.

Recently, set-top box suppliers have increased their surge specifications to require "surge to failure of the TVS" or ± 4000 V, whichever occurs first. These increased surge voltages produce significantly more current in the both the external circuitry and the A8303 and A8303-1. Allegro surge testing has shown that the SMDJ20A and LNBTVS6-221 usually fail at approximately 43 V, so all the LNBR output components (ceramic capacitors, diodes, etc.) should support at least 50 V.

To protect at these higher voltage/current levels three modifications must be made:

- For increased positive surge, the shunting diode from the LNB pin to the BOOST pin (D3, 3 A/40 V) will no longer be able to protect the body diode of the output stage. This diode must be increased to a 3 A/50 V device and be located so that it is in series with the BOOST pin as shown in schematics 3 and 4. In this position D3 will block surge current to the majority of the boost capacitance, but the 1μ F ceramic capacitor will still filter the high frequency switching noise.
- For increased negative surge, the relatively small clamping diode (D2) from LNB to ground will no longer be sufficient. This diode must be increased from a 1 A/40 V, SOD123 to a 3 A/50 V, SMA device.
- For a DiSEqC 1.0 application, a 0.47 $\Omega/1\%/0.25$ W series resistor also must be added as shown in the application drawings. The 0.47 Ω resistor could be reduced if there is enough equivalent resistance in any series output components such as jumpers, inductors, or PCB traces.

Every application will have its own surge requirements and the surge solution can be changed. However, Allegro strongly recommends incorporating a form of surge protection to prevent any pin of the A8303 and A8303-1 from exceeding its Absolute Maximum voltage ratings shown in this datasheet.

I 2C™-Compatible Interface

The I²C™ interface is used to access the internal Control and Status registers of the A8303 and A8303-1. This is a serial interface that uses two lines, serial clock (SCL) and serial data (SDA), connected to a positive supply voltage via a current source or a pull-up resistor. Data is exchanged between a microcontroller (master) and the A8303 and A8303-1 (slave). The master always generates the SCL signal. Either the master or the slave can generate the SDA signal. The SDA and SCL lines from the A8303 and A8303-1 are open-drain signals so multiple devices may be connected to the I2C**™** bus. When the bus is free, both the SDA and the SCL lines are high.

SDA and SCL Signals. SDA can only be changed while SCL is low. SDA must be stable while SCL is high. However, an exception is made when the I^2C^{TM} Start or Stop condition is encountered. See the I2C™ Communication section for further details.

Acknowledge (AK) Bit. The Acknowledge (AK) bit indicates a "good transmission" and can be used two ways. First, if the slave has successfully received eight bits of either an address or control data, it will pull the SDA line low $(AK = 0)$ for the ninth SCL pulse to signal "good transmission" to the master. Second, if the master has successfully received eight bits of status data from the A8303 and A8303-1, it will pull the SDA line low for the

ninth SCL pulse to signal "good transmission" to the slave. The receiver (either the master or the slave) should set the AK bit high $(AK = 1 \text{ or } NAK)$ for the ninth SCL pulse if eight bits of data are not received successfully.

AK Bit During a Write Sequence. When the master sends control data (writes) to the A8303 and A8303-1 there are three instances where AK bits are toggled by the A8303 and A8303-1. First, the A8303 and A8303-1 use the AK bit to indicate reception of a valid seven-bit chip address plus a read/write bit $(R/W=0$ for write). Second, the A8303 and A8303-1 use the AK bit to indicate reception of a valid eight-bit Control register address. Third, the A8303 and A8303-1 use the AK bit to indicate reception of eight bits of control data. This protocol is shown in figure 8(A).

AK Bit During a Read Sequence. When the master reads status data from the A8303 and A8303-1 there are four instances where AK bits are sent–three sent by the A8303 and A8303-1 and one sent by the master. First, the A8303 and A8303-1 use the AK bit to indicate reception of a valid seven-bit chip address plus a read/write bit ($R/W = 0$ for write). Second, the A8303 and A8303-1 use the AK bit to indicate reception of a valid eight-bit status register address. Third, the A8303 and A8303-1 use the AK bit to indicate reception of a valid seven-bit chip address plus a read/write bit ($R/W = 1$ for read). Finally, the master uses the AK bit to indicate receiving eight bits of status data from the A8303 and A8303-1. This protocol is shown in figure 8(B).

Figure 8. I2C™ Interface Read and Write Sequences. (A) for the I2C™ Write cycle and (B) for the I2C™ Read cycle

I 2C™ Communications

I 2C™ Start and Stop Conditions. The I 2C™ Start condition is defined by a negative edge on the SDA line while SCL is highConversely, the Stop condition is defined by a positive edge on the SDA line while SCL is high. The Start and Stop conditions are shown in figure 8. It is possible for the Start or Stop condition to occur at any time during a data transfer. If either a Start or Stop condition is encountered during a data transfer, the A8303 and A8303-1 will respond by resetting the data transfer sequence.

I 2C™ Write Cycle Description. Writing to the A8303 and A8303-1 Control register requires transmission of a total of 27 bits–three 8-bit bytes of data plus an Acknowledge bit after each byte. Writing to the A8303 and A8303-1 Control register is shown in figure 8(A). Writing to the A8303 and A8303-1 Control register requires a chip address with $R/W = 0$, a Control register address, and the control data, as follows:

- The Chip Address cycle consists of a total of nine bits seven bits of chip address (A6 to A0) plus one read/write bit $(R/W=0)$ to indicate a write from the master followed by an Acknowledge bit $(AK = 0$ for reception of a valid chip address) from the slave. The chip address must be transmitted MSB (A6) first. The first five bits of the A8303 and A8303-1 chip address (A6 to A2) are fixed as 00010. The remaining two bits (A1 and A0) are used to select one of four possible A8303 and A8303-1 chip addresses. The DC voltage on the ADD pin programs the chip address. See the Electrical Characteristics table for the ADD pin voltages and the corresponding chip addresses.
- The Control Register Address cycle consists of a total of nine bits—eight bits of control register address (RC7 to RC0) from the master followed by an Acknowledge bit from the slave. The Control register address must be transmitted MSB (RC7) first. The A8303 and A8303-1 only have one Control register each, so the Control register address is fixed as 00000000.
- The Control Data cycle consists of a total of nine bits—eight bits of control data (D7 to D0) from the master followed by

an Acknowledge bit from the slave. The control data must be transmitted MSB first (D7). The Control register bits are identified in the Control Registers section of this datasheet.

I 2C™ Read Cycle Description. Reading from the A8303 and A8303-1 Status register requires transmission of a total of 36 bits–four 8-bit bytes of data plus an Acknowledge bit after each byte. Reading the A8303 and A8303-1 Status register requires a chip address with $R/W=0$, a Status register address, an I²CTM Stop condition, an I2C™ Start condition, a "repeated" chip address with R/W=1, and finally the status data from the A8303 and A8303-1. Reading from the A8303 and A8303-1 Status register is shown in figure 8(B).

- This 9-bit Chip Address cycle is identical to the Chip Address cycle previously described for the Write Control register sequence. It consists of A6 to A0, plus one read/write bit $(R/W=0)$ from the master, followed by an Acknowledge bit from the slave and finally an I^2C^{TM} Stop condition.
- The Status Register Address cycle consists of a total of nine bits–eight bits of Status register address (RS7 to RS0) from the master, followed by an Acknowledge bit from the slave. The Status register address must be transmitted MSB (RS7) first. The A8303 and A8303-1 only have one Status register, so the Status register address is fixed at 00000000.
- The "Repeated" Chip Address cycle begins with an I^2C^{TM} Start condition followed by a 9-bit cycle identical to the Chip Address cycle previously described for the Write Control Register sequence. It consists of A6 to A0, plus one read/write bit $(R/W=1)$ from the master, followed by an Acknowledge bit from the slave.
- The Status Data cycle consists of a total of nine bits–eight bits of status data (RD7 to RD0) from the slave, followed by an Acknowledge bit from the master. The status data is transmitted MSB (RD7) first. The Status register bits are identified in the Status Register section of this data sheet.

Interrupt (IRQ) and Fault Clearing

The A8303 and A8303-1 provide an interrupt request pin (IRQ), which is an open-drain, active low output. This output may be connected to a common IRQ line with a suitable external pull-up resistor and can be used with other I ²C™ compatible devices to request attention from the master controller.

The IRQ output becomes active (logic low) when the A8303 and A8303-1 recognize a fault condition. The fault conditions that will force IRQ active include undervoltage lockout (UVLO), overcurrent protection (OCP), and thermal shutdown (TSD). The UVLO, OCP, and TSD faults are latched in the Status register and will not be unlatched until the A8303 and A8303-1 Status register is successfully transmitted to the master controller (an AK bit must be received from the master). See the description in the Status Register section and figure 9 for further details.

The A8303 and A8303-1 IRQ response to $V_{IN(UVLO)}$ is controlled by the I2C address setting. The A8303 and A8303-1 have two methods to control the IRQ for UVLO fault:

The first method uses the I²C address setting (Address 2, Address 3, or Address 4). In this method while V_{IN} is below 8.70 V (typ), the A8303 and A8303-1 are disabled and the I²C port is inactive. After V_{IN} rises above 8.70 V (typ), the I 2C port becomes active and the IRQ pin is pulled low. An I 2C Read cycle is required to report and clear the UVLO fault and set the IRQ pin to a logic high before the A8303 and A8303-1 can be enabled. If a brown-out occurs, such that V_{IN} drops below 8.35 V (typ), the A8303 and A8303-1 will be disabled and the I2C port will become inactive (note that the IRQ pin will remain high during this time because the

A8303 and A8303-1 are disabled). After V_{IN} rises above 8.70 V (typ) the I2C port reactivates and the IRQ pin is pulled low to report that a brown-out had occurred. An I2C Read cycle is required to report and clear the UVLO fault before the A8303 and A8303-1 can be re-enabled. A detailed timing diagram is shown in figure $10(A)$.

The second method uses I²C address setting (Address 1). In this method the I²C port is active when V_{IN} is above the I²C UVLO (6 V when V_{IN} is rising). IRQ transitions low when V_{IN} goes above I²C UVLO (6 V, V_{IN} rising), and the I²C Read cycle resets IRQ to logic high even if V_{IN} is below UVLO. Even though IRQ is cleared below UVLO, one more Read cycle is required after V_{IN} goes above UVLO, to re-enable the A8303 and A8303-1. While V_{IN} is falling, IRQ transitions low when V_{IN} goes below UVLO, and the I²C Read cycle resets IRQ to logic high. A detailed timing diagram is shown in figure $10(B)$.

When the master device receives an interrupt, it should address all slaves connected to the interrupt line in sequence and read the status register of each to determine which device is requesting attention. As shown in figure 9, the A8303 and A8303-1 latch all conditions in the Status register and set the IRQ to logic low when a UVLO, OCP, or TSD event occurs. The IRQ bit is reset to logic high and the Status register is unlatched when the master acknowledges the status data from the A8303 and A8303-1 (an AK bit must be received from the master).

The disable (DIS) and Power Not Good (PNG) conditions do not cause an interrupt and are not latched in the Status register.

Figure 9. Fault, IRQ, and Status Register Timing. When a UVLO, OCP, or TSD event occurs, the IRQ bit is set low and the Status register is latched. The IRQ bit is reset to high when the $A8303$ and $A8303$ -1 acknowledges it is being read. The Status register is unlatched when the master acknowledges the status data from the A8303 and A8303-1.

10(A). IRQ and Fault Clearing in Response to Undervoltage at VIN (UVLO), with I2C address set to (Address 2, Address 3, or Address 4). In this method, while V_{IN} is below 8.70 V (typ), the A8303 and A8303-1 are disabled and the I²C port is inactive. After V_{IN} rises above 8.70 V (typ), the I2C port becomes active and the IRQ pin is pulled low. An I2C Read cycle is required, to report and clear the UVLO fault and set the IRQ pin to a logic high, before the A8303 and A8303-1 can be enabled. If a brown-out occurs, such that V_{IN} drops below 8.35 V (typ), the A8303 and A8303-1 will be disabled and the I²C port will become inactive (note that the IRQ pin will remain high during this time because the A8303 and A8303-1 are disabled). After V_{IN} rises above 8.70 V (typ) the I²C port reactivates and the IRQ pin is pulled low to report that a brown-out had occurred. An I2C Read cycle is required to report and clear the UVLO fault before the A8303 and A8303-1 can be re-enabled.

10(B). IRQ and Fault Clearing in Response to Undervoltage at VIN (UVLO), with I2C address set to (Address 1). In this method, the I2C port is active when V_{IN} is above I²C UVLO (6 V when V_{IN} is rising). IRQ transitions low when V_{IN} goes above I²C UVLO (6 V, V_{IN} rising), and the I²C Read cycle resets IRQ to logic high even if V_{IN} is below UVLO. Even though IRQ is cleared below UVLO, one more Read cycle is required after V_{IN} goes above UVLO, to re-enable the A8303 and A8303-1. While V_{IN} is falling, IRQ transitions low when V_{IN} goes below UVLO, and the I 2C Read cycle resets IRQ to logic high.

Figure 10. IRQ and Fault Clearing in Response to Undervoltage at VIN (UVLO), showing the alternate methods, set by selection of I2C address

Figure 11. IRQ and Fault Clearing in Response to Overcurrent (OCP). If the LNB output is grounded for more than 45 ms, the LNB output will be shut off, an overcurrent fault (OCP) will be latched in the Status Register, and the IRQ pin will transition low. After an OCP fault, the LNB output does not respond to the Enable (ENB) bit until an I2C Read cycle is executed to report and clear the OCP fault. After a successful I2C Read, the IRQ pin transitions high and the A8303 and A8303-1 can be re-enabled, provided the LNB output is no longer grounded.

Figure 12. IRQ and Fault Clearing in Response to Thermal Shutdown (TSD). If the LNB junction temperature rises above 165°C (typ), the LNB output will be shut off, a thermal shutdown fault (TSD) will be latched in the Status Register, and the IRQ pin will transition low. After a TSD fault, the LNB output does not respond to the Enable (ENB) bit until an I2C Read cycle is executed to report and clear the TSD fault. After a successful I2C Read, the IRQ pin transitions high and the A8303 and A8303-1 can be reenabled, provided the junction temperature is below 145°C (typ).

I 2C™-Compatible Interface Timing Diagram

I 2C™-Compatible Timing Requirements

 * For t_{HD:DAT}(min), the master device must provide a hold time of at least 300 ns for the SDA signal in order to bridge the undefined region of the SCL signal falling edge.

Control Registers (I2C™-Compatible Write Register)

All main functions of the A8303 and A8303-1 are controlled through the I2C™ compatible interface via the 8-bit Control register. Table 2 shows the functionality and bit definitions of the Control register. At power-up, the Control register is initialized to all 0s.

Table 2. Control Register Definition

Table 3a. A8303 Output Voltage Selection

Table 3b. A8303-1 Output Voltage Selection

Status Registers (I2C™-Compatible Read Register)

The main fault conditions: overcurrent (OCP), and thermal shutdown (TSD) are all indicated by setting the relevant bits in the Status register. For these two fault cases, after the bit is set, it remains latched until the I2C™ master has successfully read the A8303 and A8303-1, assuming the fault has been resolved.

The undervoltage lockout (UVLO) bit indicates either V_{IN} is below V_{UVLO} , or V_{REG} is out of regulation. UVLO disables the LNB output and forces IRQ low. UVLO is a latched fault, and can only be cleared by performing an I2C™ READ cycle.

The Disable bit (DIS) indicates the status of the LNB output. The DIS is set when either a fault occurs (UVLO, OCP, TSD, or CPOK) or when the LNB output is turned off using the Enable bit (ENB) via the I2C™ interface. The DIS bit is latched and is only

reset when there are no faults and the A8303 and A8303-1 output is turned back on using the Enable (ENB) bit via the I^2C^{TM} interface.

The Power Not Good (PNG), Charge Pump OK (CPOK), and Tone Detect (TDET) bits are set based on the conditions sensed at the LNB output, VCP, and Tone Detect Input (TDI) pins, respectively. These bits are not latched and, unlike the other fault bits, may become reset without an I²C[™] read sequence. The PNG, CPOK, and TDET bits are continuously updated.

There are three methods to detect when the Status register changes: responding to the interrupt request (IRQ) pin going low, continuously polling the Status register via the I2C™ interface, or detecting a fault condition external to the A8303 and A8303-1 and performing a diagnostic poll of the A8303 and A8303-1. In any case, the master should read and re-read the Status register until the status changes.

Table 4. Status Register Description and IRQ Operation

APPLICATION INFORMATION

See next page for bill of materials

Schematic 1. DiSEqC 2.0 Applications, 12 V_{IN} ±10%, 700 mA I_{OUT} , surge of ±1000 V, 2 Ω , 1.2/50 µs – 8/20 µs combination wave

Table 6. Component Selection Table

Schematic 2. DiSEqC 1.0 Applications, 12 V_{IN} ±10%, 700 mA I_{OUT} , surge of ±1000 V, 2 Ω , 1.2/50 µs – 8/20 µs combination wave

Schematic 3. DiSEqC 2.0 Applications for increased surge requirements ±1000 V, 2 Ω, 1.2/50 µs – 8/20 µs combination wave, and "stress to TVS failure" (or ±4000 V) test

Schematic 4. DiSEqC 1.0 Applications for increased surge requirements ±1000 V, 2 Ω, 1.2/50 µs – 8/20 µs combination wave, and "stress to TVS failure" (or ±4000 V) test

PACKAGE OUTLINE DRAWING

Package ES 20-Pin MLP/QFN

Revision History

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