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[TPS62095](http://www.ti.com/product/tps62095?qgpn=tps62095)

SLVSBD8A –APRIL 2014–REVISED MAY 2014

TPS62095 4A, High Efficiency Step Down Converter with DCS-Control™ and Low Profile Solution

Technical [Documents](http://www.ti.com/product/TPS62095?dcmp=dsproject&hqs=td&#doctype2)

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- Adjustable Soft Startup
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- Hard Disk Drives
-
- **Battery Powered Applications**

1.8V Output Application

1 Features 3 Description

Tools & **[Software](http://www.ti.com/product/TPS62095?dcmp=dsproject&hqs=sw&#desKit)**

DCS-Control™ Topology

The TPS62095 device is a high frequency

synchronous step down converter optimized for small Pin-to-Pin Compatible with TPS62090

• Synchronous step down converter optimized for battery

• Supports 1.2mm Height Total Solution

• Nowered applications. To maximize efficiency, the powered applications. To maximize efficiency, the 95% Converter Efficiency

²⁰¹⁴ Converter operates in PWM mode with a nominal

²⁰¹⁴ Charating Quisseant Current

²⁰¹⁴ Charating Cuisseant Current Switching frequency of 1.4MHz and automatically 1.2MHz and automatically 1.4MHz and automatically enters Power Save Mode operation at light load
2.5V to 5.5V Input Voltage Range enters Power Save Mode operation at light l currents. When used in distributed power supplies • Power Save Mode **and point of load regulation, the device allows voltage and point of load regulation**, the device allows voltage Two Level Short Circuit Protection
tracking to other voltage rails and tolerates output
capacitors up to 150µF and beyond. Using the DCS-The 150% Duty Cycle for Lowest Dropout
Control™ topology, the device achieves excellent
Output Discharge Function
In the Using the Marian Control™ topology, the device achieves excellent load transient performance and accurate output
voltage regulation.

Support & **[Community](http://www.ti.com/product/TPS62095?dcmp=dsproject&hqs=support&#community)**

으리

Output Voltage Tracking The Summan The output voltage startup ramp is controlled by the 0.8V to V_{IN} Adjustable Output Voltage soft startup pin, which allows operation as either a Interval Adjustable Output Voltage standalone power supply or in tracking configurations. Standalone power supply or in tracking computations.
Power sequencing is also possible by configuring the
EN and PG pins. In Power Save Mode, the device EN and PG pins. In Power Save Mode, the device **2 Applications** operates with typically 20µA quiescent current. Power • Notebooks, Computers Save Mode is entered automatically and seamlessly Solid State Drives **Fig. 2018 maintaining high efficiency over the entire load • Solid State Drives current range.**

Processor Supply Device Information⁽¹⁾

(1) For all available packages, see the orderable addendum at the end of the datasheet.

1.8V Output Application Efficiency

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Table of Contents

4 Revision History

Changes from Original (April 2014) to Revision A Page

• Changed status from Product Preview to Production Data - removed Product Preview banner .. [1](#page-0-2)

2 Applications ... [1](#page-0-1) **8 Application and Implementation** [11](#page-10-0) **3 Description** ... [1](#page-0-0) 8.1 Application Information.. [11](#page-10-1) 8.2 Typical Applications .. [11](#page-10-2) **4 Revision History**... [2](#page-1-0) **Power Supply Recommendations...................... [17](#page-16-0)**

5 Pin Configuration and Functions

Pin Functions

6 Specifications

6.1 Absolute Maximum Ratings(1)

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground pin.

6.2 Handling Ratings

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommend Operating Conditions

Over operating free-air temperature range, unless otherwise noted.

6.4 Thermal Information

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, [SPRA953](http://www.ti.com/lit/pdf/spra953)

6.5 Electrical Characteristics

 V_{IN} = 3.6V, T_A = -40°C to 85°C, typical values are at T_A = 25°C (unless otherwise noted)

(1) Conditions: $L = 1 \mu H$, $C_{\text{OUT}} = 2 \times 22 \mu F$.

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NSTRUMENTS

Texas

6.6 Typical Characteristics

7 Detailed Description

7.1 Overview

The TPS62095 synchronous step down converter is based on DCS-Control™ (Direct Control with Seamless transition into Power Save Mode). This is an advanced regulation topology that combines the advantages of hysteretic and voltage mode control.

The DCS-Control™ topology operates in PWM (Pulse Width Modulation) mode for medium to heavy load conditions and in Power Save Mode at light load currents. In PWM, the converter operates with its nominal switching frequency of 1.4 MHz having a controlled frequency variation over the input voltage range. As the load current decreases, the converter enters Power Save Mode, reducing the switching frequency and minimizing the IC's quiescent current to achieve high efficiency over the entire load current range. DCS-Control™ supports both operation modes using a single building block and therefore has a seamless transition from PWM to Power Save Mode without effects on the output voltage. The TPS62095 offers excellent DC voltage regulation and load transient regulation, combined with low output voltage ripple, minimizing interference with RF circuits.

7.2 Functional Block Diagram

7.3 Feature Description

7.3.1 PWM Operation

In PWM mode, the device operates with a fixed ON-time switching pulse at medium to heavy load currents. A quasi fixed switching frequency of typical 1.4MHz over the input and output voltage range is achieved by using an input feed forward. The ON-time is calculated as shown in [Equation 2](#page-7-2). As the load current decreases, the converter enters Power Save Mode operation reducing its switching frequency. The device enters Power Save Mode at the boundary to discontinuous conduction mode (DCM).

7.3.2 Low Dropout Operation (100% Duty Cycle)

The device offers low input to output voltage difference by entering 100% duty cycle mode. In this mode the high side MOSFET switch is constantly turned on. This is particularly useful in battery powered applications to achieve longest operation time by taking full advantage of the whole battery voltage range. The minimum input voltage where the output voltage falls below set point is given by:

$$
V_{IN(min)} = V_{OUT(min)} + I_{OUT} \times (R_{DS(on)} + R_L)
$$

Where

 $R_{DS(on)}$ = High side FET on-resistance

 R_L = DC resistance of the inductor

 $V_{\text{OUT}(min)}$ = Minimum output voltage the load can accept

7.3.3 Power Save Mode Operation

As the load current decreases, the converter enters Power Save Mode operation. During Power Save Mode, the converter operates with reduced switching frequency and with a minimum quiescent current to maintain high efficiency. The Power Save Mode is based on a fixed on-time architecture following [Equation 2](#page-7-2).

$$
\tan = \frac{V_{OUT}}{V_{IN}} \times 360 \text{ns} \times 2
$$
\n
$$
f = \frac{2 \times I_{OUT}}{\tan^2 \left(1 + \frac{V_{IN} - V_{OUT}}{V_{OUT}}\right) \times \frac{V_{IN} - V_{OUT}}{L}}
$$

In Power Save Mode, the output voltage rises slightly above the nominal output voltage in PWM mode. This effect is reduced by increasing the output capacitance or the inductor value. This effect is also reduced by programming the output voltage of the TPS62095 lower than the target value. As an example, if the target output voltage is 3.3V, then the TPS62095 can be programmed to 3.3V - 0.3%. As a result, the output voltage accuracy is now -1.7% to +1.7% instead of -1.4% to 2%. The output voltage accuracy in PFM operation is reflected in the electrical specification table and given for a 2 x 22µF output capacitance.

7.4 Device Functional Modes

7.4.1 Soft Startup

To minimize inrush current during startup, the device has an adjustable startup time depending on the capacitor value connected to the SS pin. The device charges the SS capacitor with a constant current of typically 7.5µA. The feedback voltage follows this voltage divided by 1.56, until the internal reference voltage of 0.8V is reached. The soft startup operation is completed once the voltage at the SS capacitor has reached typically 1.25V. The soft startup time is calculated using [Equation 3](#page-7-3). The larger the SS capacitor, the longer the soft startup time. The relation between the SS pin voltage and the FB pin voltage is estimated using [Equation 4.](#page-7-4) Leaving the SS pin floating sets the minimum startup time.

$$
t_{SS} = C_{SS} \times \frac{1.25V}{7.5\mu A}
$$
\n
$$
V_{FB} = \frac{V_{SS}}{1.56}
$$
\n(3)

(2)

Device Functional Modes (continued)

During startup the switch current limit is reduced to 1/3 of its typical current limit of 5.5A when the output voltage is less than 0.6V. Once the output voltage exceeds typically 0.6V, the switch current limit is released to its nominal value. Thus, the device provides a reduced load current of 1.8A when the output voltage is below 0.6V. A small or no soft startup time may trigger this reduced switch current limit during startup, especially for larger output capacitor applications. This is avoided by using a larger soft start up capacitance which extends the soft startup time. See Short Circuit Protection (Hiccup-Mode) for details of the reduced current limit during startup.

7.4.2 Voltage Tracking

The SS pin can also be used to implement output voltage tracking with other supply rails, as shown in [Figure 5](#page-8-0).

In voltage tracking applications, the resistance R4 should be set properly to achieve accurate voltage tracking by taking 7.5μA soft startup current into account. 4.3kΩ is a sufficient value for R4. The relationship between V1 and V2 is shown in [Equation 5](#page-8-1). To achieve V1 startup leading V2, as shown in [Figure 6,](#page-8-2) [Equation 5](#page-8-1) should be less than 1. To achieve simultaneous tracking, [Equation 5](#page-8-1) should equal to 1.

Device Functional Modes (continued)

7.4.3 Short Circuit Protection (Hiccup-Mode)

The device is protected against hard short circuits to GND and over-current events. This is implemented by a two level short circuit protection. During start-up and when the output is shorted to GND, the switch current limit is reduced to 1/3 of its typical current limit of 5.5A. Once the output voltage exceeds typically 0.6V the current limit is released to its nominal value. The full current limit is implemented as a hiccup current limit. Once the internal current limit is triggered 32 times, the device stops switching and starts a new start-up sequence after a typical delay time of 66µS passed by. The device repeats these cycles until the high current condition is released.

7.4.4 Output Discharge Function

To make sure the device starts up under defined conditions, the output gets discharged via the VOS pin with a typical discharge resistor of 200Ω whenever the device shuts down. This happens when the device is disabled or if thermal shutdown, undervoltage lockout or short circuit hiccup-mode is triggered.

7.4.5 Power Good Output

The power good output is low when the output voltage is below its nominal value. The power good becomes high impedance once the output is within 5% of regulation. The PG pin is an open drain output and is specified to sink up to 1mA. This output requires a pull-up resistor to be monitored properly. The pull-up resistor cannot be connected to any voltage higher than the input voltage of the device.

7.4.6 Undervoltage Lockout

To avoid mis-operation of the device at low input voltages, an undervoltage lockout is included. UVLO shuts down the device at input voltages lower than typically 2.2V with a 200mV hysteresis.

7.4.7 Thermal Shutdown

The device goes into thermal shutdown once the junction temperature exceeds typically 150°C with a 20°C hysteresis.

8 Application and Implementation

8.1 Application Information

The TPS62095 is a synchronous step down converter based on DCS-Control™ topology whose output voltage can be adjusted by component selection. The following section discusses the design of the external components to complete the power supply design for several input and output voltage options by using typical applications as a reference.

8.2 Typical Applications

8.2.1 2.5V to 5.5V Input, 1.8V Output Converter

Figure 7. 1.8-V Output Application

8.2.1.1 Design Requirements

For this design example, use the following as the input parameters.

8.2.1.2.1 Output Filter

8.2.1.2 Detailed Design Procedure

inductor and capacitor value combinations.

[TPS62095](http://www.ti.com/product/tps62095?qgpn=tps62095)

2.2 (1) Inductor tolerance and current de-rating is anticipated. The effective inductance can vary by +20% and –30%.

The first step is the selection of the output filter components. To simplify this process, [Table 2](#page-11-0) outlines possible

Table 2. Output Filter Selection

OUTPUT CAPACITOR VALUE [µF](2)

10 22 2 x 22 100 150

(3) √ √

(2) Capacitance tolerance and bias voltage de-rating is anticipated. The effective capacitance can vary by +20% and –50%.

(3) Typical application configuration. Other check mark indicates alternative filter combinations

1.0 √

8.2.1.2.2 Inductor Selection

The inductor selection is affected by several parameters like inductor ripple current, output voltage ripple, transition point into Power Save Mode, and efficiency. See [Table 3](#page-11-1) for typical inductors.

Table 3. Inductor Selection(1)

(1) See [Third-Party Products Disclaimer.](#page-18-1)

In addition, the inductor has to be rated for the appropriate saturation current and DC resistance (DCR). The inductor needs to be rated for a saturation current as high as the typical switch current limit of 5.5A or according to [Equation 6](#page-11-2) and [Equation 7](#page-11-3). [Equation 6](#page-11-2) and [Equation 7](#page-11-3) calculate the maximum inductor current under static load conditions. The formula takes the converter efficiency into account. The converter efficiency can be taken from the data sheet graphs or 80% can be used as a conservative approach. The calculation must be done for the maximum input voltage where the peak switch current is highest.

$$
I_{L} = I_{OUT} + \frac{\Delta I_{L}}{2}
$$
\n
$$
I_{L} = I_{OUT} + \frac{\frac{V_{OUT}}{n} \times \left(1 - \frac{V_{OUT}}{V_{IN} \times n}\right)}{2 \times f \times L}
$$
\n(7)

where

 $f =$ Converter switching frequency (typically 1.4MHz)

 $L = Inductor value$

 η = Estimated converter efficiency (use the number from the efficiency curves or 0.80 as a conservative assumption)

Note: The calculation must be done for the maximum input voltage of the application

Calculating the maximum inductor current using the actual operating conditions gives the minimum saturation current. A margin of 20% should be added to cover for load transients during operation.

8.2.1.2.3 Input and Output Capacitor Selection

For best output and input voltage filtering, low ESR ceramic capacitors are recommended. The input capacitor minimizes input voltage ripple, suppresses input voltage spikes and provides a stable system rail for the device. A 22µF or larger input capacitor is required. The output capacitor value can range from 2x22µF up to 150µF. The recommended typical output capacitor value is 2x22µF and can vary over a wide range as outline in the output filter selection table.

8.2.1.2.4 Setting the Output Voltage

The output voltage is set by an external resistor divider according to the following equations:

$$
V_{OUT} = V_{FB} \times \left(1 + \frac{R1}{R2}\right) = 0.8 \text{ V} \times \left(1 + \frac{R1}{R2}\right)
$$

$$
R2 = \frac{V_{FB}}{R2} = \frac{0.8 \text{ V}}{R2} \approx 160 \text{ k}\Omega
$$
 (8)

$$
R2 = \frac{v_{FB}}{l_{FB}} = \frac{0.6 \text{ V}}{5 \text{ }\mu\text{A}} \approx 160 \text{ k}\Omega
$$
 (9)

$$
R1 = R2 \times \left(\frac{V_{OUT}}{V_{FB}} - 1\right) = R2 \times \left(\frac{V_{OUT}}{0.8V} - 1\right)
$$
\n(10)

When sizing R2, in order to achieve low quiescent current and acceptable noise sensitivity, use a minimum of 5μ A for the feedback current I_{FB}. Larger currents through R2 improve noise sensitivity and output voltage accuracy.

8.2.1.3 Application Performance Curves

 $T_A = 25^{\circ}$ C, V_{IN} = 3.6V, VOUT = 1.8V, L1 = 1µH (XAL4020-102), C2 = 2x22µF, unless otherwise noted.

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NSTRUMENTS

Texas

8.2.2 2.5V to 5.5V Input, 1.2V Output Converter

8.2.3 3.0V to 5.5V Input, 2.6V Output Converter

8.2.4 5V Input, 3.3V Output Converter

9 Power Supply Recommendations

The devices are designed to operate from an input voltage supply range between 2.5V and 5.5V. If the input supply is located more than a few inches from the device, an additional bulk capacitance may be required in addition to the ceramic bypass capacitors. An electrolytic capacitor with a value of 47µF is a typical choice.

The average input current of the TPS62095 is calculated as:

$$
I_{IN} = \frac{1}{\eta} \times \frac{V_{OUT} \times I_{OUT}}{V_{IN}}
$$
(11)

10 Layout

10.1 Layout Guidelines

- It is recommended to place all components as close as possible to the IC. Specially, the input capacitor placement is closest to the PVIN and PGND pins of the device.
- Use wide and short traces for the main current paths to reduce the parasitic inductance and resistance, like the SW node.
- The VOS pin is noise sensitive and needs to be routed as short and directly to the output pin of the inductor and the output capacitor. This minimizes switch node jitter.
- The exposed thermal pad of the package, the AGND and the PGND should have a single joint connection at the exposed thermal pad of the package. To enhance heat dissipation of the device, the exposed thermal pad should be connected to bottom or internal layer ground planes using vias.
- The charge pump capacitor connected to CP and CN should be placed close to the IC to minimize coupling of switching waveforms into other traces and circuits.
- The capacitor on the SS pin and the FB resistors divider network should be placed close to the IC and connected directly to those pins and the AGND pin.
- Refer to [Figure 26](#page-16-4) for an example of component placement, routing and thermal design.

10.2 Layout Example

Figure 26. TPS62095 PCB Layout

10.3 Thermal Consideration

Implementation of integrated circuits in low-profile and fine-pitch surface-mount packages typically requires special attention to power dissipation. Many system-dependent issues such as thermal coupling, airflow, added heat sinks and convection surfaces, and the presence of other heat-generating components affect the powerdissipation limits of a given component. The Thermal Information table provides the thermal metric of the device and its package based on JEDEC standard. For more details on how to use the thermal parameters in real applications, see the application notes: [SZZA017](http://www.ti.com/lit/pdf/szza017) and [SPRA953](http://www.ti.com/lit/pdf/spra953).

11 Device and Documentation Support

11.1 Device Support

11.1.1 Third-Party Products Disclaimer

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11.2 Trademarks

DCS-Control is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

11.3 Electrostatic Discharge Caution

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.4 Glossary

[SLYZ022](http://www.ti.com/lit/pdf/SLYZ022) — *TI Glossary*.

This glossary lists and explains terms, acronyms and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures. "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PACKAGE OPTION ADDENDUM

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TEXAS

TAPE AND REEL INFORMATION

ISTRUMENTS

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

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PACKAGE MATERIALS INFORMATION

www.ti.com 20-Apr-2023

*All dimensions are nominal

TEXAS INSTRUMENTS

www.ti.com

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TUBE

B - Alignment groove width

*All dimensions are nominal

GENERIC PACKAGE VIEW

VQFN - 1 mm max height
PLASTIC QUAD FLATPACK - NO LEAD

Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

PACKAGE OUTLINE

RGT0016C VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD

NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

EXAMPLE BOARD LAYOUT

RGT0016C VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

EXAMPLE STENCIL DESIGN

RGT0016C VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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