

# **FSCM0465R Green Mode Fairchild Power Switch (FPS™)**

### **Features**

- Internal Avalanche Rugged SenseFET
- Low Start-up Current (max. 40µA)
- Low Power Consumption; under 1W at 240VAC and 0.4W Load
- Precise Fixed Operating Frequency (66kHz)
- **Frequency Modulation for Low EMI**
- Pulse-by-Pulse Current Limiting (Adjustable)
- Over-Voltage Protection (OVP)
- Overload Protection (OLP)
- Thermal Shutdown Function (TSD)
- Auto-Restart Mode
- Under-Voltage Lock Out (UVLO) with Hysteresis
- Built-in Soft-Start (15ms)

# **Applications**

- SMPS for VCR, SVR, STB, DVD, and DVCD
- Adaptor
- SMPS for LCD Monitor

# **Related Application Notes**

- AN-4137: Design Guidelines for Off-line Flyback Converters Using Fairchild Power Switch (FPS)
- **AN-4140**: Transformer Design Consideration for Off-line Flyback Converters using Fairchild Power Switch
- **AN-4141**: Troubleshooting and Design Tips for Fairchild Power Switch Flyback Applications
- AN-4148: Audible Noise Reduction Techniques for FPS Applications

# **Description**

The FSCM0465R is an integrated Pulse-Width Modulator (PWM) and SenseFET specifically designed for high-performance offline Switch Mode Power Supplies (SMPS) with minimal external components. This device is an integrated high-voltage powerswitching regulator that combines an avalanche rugged SenseFET with a current mode PWM control block. The PWM controller includes an integrated fixed-frequency oscillator, under-voltage lockout, leading edge blanking (LEB), optimized gate driver, internal soft-start, temperature-compensated precise current sources for a loop compensation, and self-protection circuitry. Compared with a discrete MOSFET and PWM controller solution, it can reduce total cost, component count, size, and weight while simultaneously increasing efficiency, productivity, and system reliability. This device is a basic platform well suited for cost-effective designs of flyback converters.



**Ordering Information**

#### **Note:**

1. WDTU: Forming Type

FPSTM is a trademark of Fairchild Semiconductor Corporation.

# **Typical Circuit**



**Figure 1. Typical Flyback Application**

# **Output Power Table**



#### **Notes:**

1. Typical continuous power in a non-ventilated enclosed adapter measured at 50°C ambient

2. Maximum practical continuous power in an open-frame design at 50°C ambient

3. 230 VAC or 100/115 VAC with doubler





6 | Ilimit

ming. By using a resistor to GND on this pin, the current limit level can be

changed. If this pin is left floating, the typical current limit is 2.0A.

# **Absolute Maximum Ratings**

The "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. The device should not be operated at these limits. The parametric values defined in the Electrical Characteristics tables are not guaranteed at the absolute maximum ratings.



 $T_A = 25^{\circ}$ C unless otherwise specified.

#### **Notes:**

1. T<sub>j</sub> = 25°C to 150°C

2. Repetitive rating: Pulse-width limited by maximum junction temperature

3.  ${\sf T}_{\sf C}$ : Case back surface temperature with infinite heat sink

# **Electrical Characteristics**

 $T_A = 25^{\circ}$ C unless otherwise specified.



**Notes:**

1. Pulse Test: Pulse width  $\leq 300 \mu S$ , duty  $\leq 2\%$ 

2. These parameters, although guaranteed at the design, are not tested in mass production.

3. These parameters indicate the inductor current. Where packages are I2PAK or D2PAK, this should be decreased to 2.0A by external resistor.

4. MOSFET switching time is essentially independent of operating temperature.

# **Comparison Between FSDM0465RB and FSCM0465R**



FSCM0465R Green Mode Fairchild Power Switch (FPST<sup>M</sup>) **FSCM0465R Green Mode Fairchild Power Switch (FPS™)**

# **Typical Performance Characteristics**

These characteristic graphs are normalized at  ${\sf T}_{\sf A}$ = 25°C.















Figure 4. Startup Current vs. Temp. **Figure 5. Stop Threshold voltage vs. Temp.** 







#### © 2006 Fairchild Semiconductor Corporation www.fairchildsemi.com FSCM0465R Rev. 1.0.1

FSCM0465R Green Mode Fairchild Power Switch (FPST<sup>M</sup>) **FSCM0465R Green Mode Fairchild Power Switch (FPS™)**

## **Typical Performance Characteristics** (Continued)

These characteristic graphs are normalized at  ${\sf T}_{\sf A}$ = 25°C.











-50 -25 0 25 50 75 100 125 Junction Temperature [°C]

0.80

0.88 0.96

1.04 1.12 1.20

Burst Mode Enable Voltage (Normalized to 25°C)

Burst Mode Enable Voltage (Normalized to 25°C)



Figure 12. Maximum Drain Current vs. Temp. **Figure 13. Shutdown Delay Current vs. Temp.** 





#### **Functional Description**

**1. Startup**: Figure 16 shows the typical startup circuit and transformer auxiliary winding for the FSCM0465R application. Before the FSCM0465R begins switching, it consumes only startup current (typically 20µA) and the current supplied from the DC link supply current consumed by the FPS  $(I_{CC})$  and charges the external capacitor (C<sub>a</sub>) connected to the V<sub>CC</sub> pin. When V<sub>CC</sub> reaches start voltage of 12V ( $V<sub>STAT</sub>$ ), the FSCM0465R begins switching and the current consumed by the FSCM0465R increases to 2.5mA. Then the FSCM0465R continues its normal switching operation and the power required for this device is supplied from the transformer auxiliary winding, unless  $V_{CC}$  drops below the stop voltage of 8V ( $V<sub>STOP</sub>$ ). To guarantee the stable operation of the control IC,  $V_{CC}$  has under-voltage lockout (UVLO) with 4V hysteresis. Figure 17 shows the relationship between the current consumed by the FPS  $(I_{CC})$  and the supply voltage  $(V_{CC})$ .







The minimum current supplied through the startup resistor is given by:

$$
I_{\text{sup}}^{min} = \left(\sqrt{2} \cdot V_{\text{line}}^{min} - V_{\text{start}}\right) \cdot \frac{1}{R_{\text{str}}} \tag{1}
$$

where *Vline min* is the minimum input voltage, *Vstart* is the start voltage (12V) and *Rstr* is the startup resistor. The startup resistor should be chosen so that *Isup min* is larger than the maximum startup current (40 $\mu$ A). If not, V<sub>CC</sub> can not be charged to the start voltage and FPS fails to start.

**2. Feedback Control**: The FSCM0465R employs current mode control, as shown in Figure 18. An optocoupler (such as the H11A817A) and a shunt regulator (such as the KA431) are typically used to implement the feedback network. Comparing the feedback voltage with the voltage across the Rsense resistor makes it possible to control the switching duty cycle. When the reference pin voltage of the KA431 exceeds the internal reference voltage of 2.5V, the H11A817A LED current increases , pulling down the feedback voltage and reducing the duty cycle. This event typically happens when the input voltage is increased or the output load is decreased .

**2.1 Pulse-by-pulse Current Limit**: Because current mode control is employed, the peak current through the SenseFET is determined by the inverting input of th e PWM comparator (Vfb\*) as shown in Figure 18. When the current through the opto-transistor is zero and the current limit pin (#5) is left floating, the feedback current source  $(I_{FB})$  of 0.9mA flows only through the internal resistor (R+2.5R=2.8k). In this case, the cathode voltage of diode D2 and the peak drain current have maximum values of 2.5V and 2.5A, respectively. The pulse-by pulse current limit can be adjusted using a resistor to GND on the current limit pin (#5). The current limit level using an external resistor  $(R_{LIM})$  is given by:

$$
I_{LIM} = \frac{R_{LIM} \cdot 2.5A}{2.8K\Omega + R_{LIM}}
$$
 (2)





**2.2 Constant Power Limit Circuit**: Due to the circuit delay of FPS, the pulse-by-pulse limit current increases a little bit when the input voltage increases. This means unwanted excessive power is delivered to the secondary side. To compensate, the auxiliary power compensation network in Figure 19 can be used.  $R_{LIM}$  can adjust pulseby-pulse current by absorbing internal current source  $(I_{FB}:$  typical value is 0.9mA), depending on the ratio between resistors. With the suggested compensation circuit, additional current from  $I_{FR}$  is absorbed more proportionally to the input voltage  $(V_{DC})$  and achieves constant power in wide input range. Choose  $R<sub>LIM</sub>$  for proper current to the application, then check the pulseby-pulse current difference between minimum and maximum input voltage. To eliminate the difference (to gain constant power), R<sub>y</sub> can be calculated by:

$$
R_{y} \cong \frac{I_{\lim\_spec} \times V_{dc} \times \frac{N_{a}}{N_{p}}}{I_{tb} \times \Delta I_{\lim\_comp}}
$$
(3)

where, *I lim*\_spec is the limit current stated on the specification;  $N_{\sf a}$  and  $N_{\sf p}$  are the number of turns for  $\sf V_{CC}$ and primary side, respectively; *I fb* is the internal current source at feedback pin with a typical value of 0.9mA; and Δ*I lim\_comp* is the current difference which must be eliminated. In case of capacitor in the circuit 1µF, 100V is good choice for all applications.



**Figure 19. Constant power limit circuit**

**2.3 Leading Edge Blanking (LEB)**: At the instant the internal SenseFET is turned on, a high-current spik e through the SenseFET usually occurs, caused by primary-side capacitance and secondary-side rectifier reverse recovery. Excessive voltage across the Rsense resistor can lead to incorrect feedback operation in the current mode PWM control. To counter this effect, th e FSCM0465R employs a leading edge blanking (LEB) circuit. This circuit inhibits the PWM comparator for a short time after the SenseFET is turned on.

**3. Protection Circuit**: The FSCM0465R has several self-protective functions, such as overload protection (OLP), over-voltage protection (OVP) and thermal shutdown (TSD). Because these protection circuits are fully integrated into the IC without external components, the reliability is improved without increasing cost. Once the fault condition occurs, switching is terminated and the SenseFET remains off. This causes  $V_{CC}$  to fall. When  $V_{CC}$  reaches the UVLO stop voltage of 8V, the current consumed by the FSCM0465R decreases to the startup current (typically 20µA) and the current supplied from the DC link charges the external capacitor  $(C_{\mathsf{a}})$ connected to the  $V_{CC}$  pin. When  $V_{CC}$  reaches the start voltage of 12V, the FSCM0465R resumes normal operation. In this manner, the auto-restart can alternately enable and disable the switching of the power SenseFET until the fault condition is eliminated (see Figure 20).



**Figure 20. Auto Restart Operation**

**3.1 Overload Protection (OLP)** : Overload is defined as the load current exceeding a preset level due to an unexpected event. In this situation, the protection circuit should be activated to protect the SMPS. However, even when the SMPS is in the normal operation, the overload protection circuit can be activated during the load transition. To avoid this undesired operation, the overload protection circuit is designed to be activated after a specified time to determine whether it is a transient situation or an overload situation. Because of the pulse-by-pulse current limit capability, the maximum peak current through the SenseFET is limited and th e maximum input power is restricted with a given inpu t voltage. If the output consumes beyond this maximum power, the output voltage  $(\mathsf{V}_\mathsf{O})$  decreases below the set voltage. This reduces the current through the optocoupler LED, which also reduces the opto-coupler transistor current, increasing the feedback voltage (Vfb). If Vfb exceeds 2.5V, D1 is blocked and the 5.3µA current source (I<sub>delay</sub>) starts to charge C<sub>B</sub> slowly up to V<sub>CC</sub>. In this condition, Vfb continues increasing until it reaches 6V, when the switching operation is terminated as shown in Figure 21. The delay time for shutdown is the tim e required to charge  $C_B$  from 2.5V to 6.0V with 5.3 $\mu$ A ( $I_{\text{delay}}$ ). A 10 ~ 50ms delay time is typical for most applications.



**Figure 21. Overload Protection**

**3.2 Over-Voltage Protection (OVP)**: If the secondaryside feedback circuit were to malfunction or a solder defect causes an opening in the feedback path, the current through the opto-coupler transistor becomes almost zero. In this case, Vfb climbs up in a similar manner to the overload situation, forcing the preset maximum current to be supplied to the SMPS until th e overload protection is activated. Because more energy than required is provided to the output, the output voltage may exceed the rated voltage before the overload protection is activated, resulting in the breakdown of the devices in the secondary side. To prevent this situation, an over- voltage protection (OVP) circuit is employed. In general,  $V_{CC}$  is proportional to the output voltage and the FSCM0465R uses  $V_{CC}$  instead of directly monitoring the output voltage. If  $V_{CC}$  exceeds 19V, an OVP circuit is activated, resulting in the termination of the switching operation. To avoid undesired activation of OVP during normal operation , V<sub>CC</sub> should be designed to be below 19V.

**3.3 Thermal Shutdown (TSD)**: The SenseFET and the control IC are built in one package. This makes it easy for the control IC to detect the heat generation from the SenseFET. When the temperature exceeds approximately 145°C, the thermal protection is triggered, resulting in shutdown of the FPS.

**4. Frequency Modulation**: EMI reduction can be accomplished by modulating the switching frequency of a switched power supply. Frequency modulation can reduce EMI by spreading the energy over a wider frequency range than the bandwidth measured by the EMI test equipment. The amount of EMI reduction is directly related to the depth of the reference frequency. As can be seen in Figure 22, the frequency changes from 63KHz to 69KHz in 4ms.





**5. Soft-Start**: The FSCM0465R has an internal soft-start circuit that increases PWM comparator inverting input voltage, together with the SenseFET current, slowly after it starts up. The typical soft-start time is15ms. The pulse width to the power switching device is progressivel y increased to establish the correct working conditions for transformers, rectifier diodes, and capacitors. The voltage on the output capacitors is progressively increased with the intention of smoothly establishing the required output voltage. Preventing transformer saturation and reducing stress on the secondary diode during startup is also helpful.

**6. Burst Operation**: To minimize power dissipation in standby mode, the FSCM0465R enters into burst-mode operation at light load condition. As the load decreases, the feedback voltage decreases. As shown in Figure 23, the device automatically enters burst mode when the feedback voltage drops below  $V_{BURL}$  (300mV). At this point, switching stops and the output voltages start to drop at a rate dependent on standby current load. This causes the feedback voltage to rise. Once it passes  $V_{\text{BURH}}$  (500mV), switching resumes. The feedback voltage then falls and the process repeats. Burst mode operation alternately enables and disables switching of the power SenseFET, thereby reducing switching loss in standby mode.



**Figure 23. Waveforms of Burst Operation** 

# **Typical Application Circuit**



#### **Features**

- High efficiency (>81% at 85Vac input)
- Low standby mode power consumption (<1W at 240Vac input and 0.4W load)
- **Low component count**
- Enhanced system reliability through various protection functions
- Low EMI through frequency modulation
- Internal soft-start (15ms)

#### **Key Design Notes**

- Resistors R107 and R108 are employed to prevent startup at low input voltage
- The delay time for overload protection is designed to be about 50ms with C106 of 100nF. If a faster triggering of OLP is required, C106 can be reduced to 22nF.

#### **1. Schematic**



#### **2. Transformer**



**Figure 25. Transformer Schematic Diagram**

#### **3. Winding Specification**



#### **4. Electrical Characteristics**



#### **5. Core & Bobbin**

- Core: EER 3016
- Bobbin: EER3016
- $\blacksquare$  Ae(mm<sup>2</sup>): 96

#### **6. Demo Circuit Part List**



# **Package Dimensions**

#### **D2-PAK-6L**

Dimensions are in millimeters unless otherwise specified.



# FSCM0465R Green Mode Fairchild Power Switch (FPST<sup>M</sup>) **FSCM0465R Green Mode Fairchild Power Switch (FPS™)**

**18.50<br>17.90** 

 $(7.15)$ 

# **Package Dimensions (Continued)**

#### **I2-PAK-6L (Forming)**

Dimensions are in millimeters unless otherwise specified.



# **Package Dimensions (Continued)**

#### **TO-220-6L (Forming)**

Dimensions are in millimeters unless otherwise specified.





(NOTE)

- 1. THESE DIMENSIONS DO NOT INCLUDE MOLD PROTRUSION.
- 2.  $($  ) IS REFERENCE
- 3. ( ) IS ASS'Y OUT QUALITY

#### **TRADEMARKS**

The following are registered and unregistered trademarks Fairchild Semiconductor owns or is authorized to use and is not intended to be an exhaustive list of all such trademarks.



#### **DISCLAIMER**

FAIRCHILD SEMICONDUCTOR RESERVES THE RIGHT TO MAKE CHANGES WITHOUT FURTHER NOTICE TO ANY PRODUCTS HEREIN TO IMPROVE RELIABILITY, FUNCTION, OR DESIGN. FAIRCHILD DOES NOT ASSUME ANY LIABILITY ARISING OUT OF THE APPLICATION OR USE OF ANY PRODUCT OR CIRCUIT DESCRIBED HEREIN; NEITHER DOES IT CONVEY ANY LICENSE UNDER ITS PATENT RIGHTS, NOR THE RIGHTS OF OTHERS. THESE SPECIFICATIONS DO NOT EXPAND THE TERMS OF FAIRCHILD'S WORLDWIDE TERMS AND CONDITIONS, SPECIFICALLY THE WARRANTY THEREIN, WHICH COVERS THESE PRODUCTS.

#### **LIFE SUPPORT POLICY**

FAIRCHILD'S PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS WITHOUT THE EXPRESS WRITTEN APPROVAL OF FAIRCHILD SEMICONDUCTOR CORPORATION.

#### As used herein:

- 1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, or (c) whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in significant injury to the user.
- 2. A critical component is any component of a life support device or system whose failure to perform can be reasonabl y expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

#### **PRODUCT STATUS DEFINITIONS**

Definition of Terms



Rev. I19