- \bullet **Free-Running CLKA and CLKB Can Be Asynchronous or Coincident**
- \bullet **Clocked FIFO Buffering Data From Port A to Port B**
- \bullet **Memory Size: 1024** × **36**
- \bullet **Synchronous Read-Retransmit Capability**
- \bullet **Mailbox Register in Each Direction**
- \bullet **Programmable Almost-Full and Almost-Empty Flags**
- \bullet **Microprocessor Interface Control Logic**
- \bullet **Input-Ready and Almost-Full Flags Synchronized by CLKA**
- **Output-Ready and Almost-Empty Flags Synchronized by CLKB**
- \bullet **Low-Power 0.8-**µ**m Advanced CMOS Technology**
- \bullet **Supports Clock Frequencies up to 67 MHz**
- \bullet **Fast Access Times of 11 ns**
- \bullet **Pin-to-Pin Compatible With the SN74ACT3631 and SN74ACT3651**
- \bullet **Package Options Include 120-Pin Thin Quad Flat (PCB) and 132-Pin Plastic Quad Flat (PQ) Packages**

description

The SN74ACT3641 is a high-speed, low-power, CMOS clocked FIFO memory. It supports clock frequencies up to 67 MHz and has read access times as fast as 12 ns. The 1024 \times 36 dual-port SRAM FIFO buffers data from port A to port B. The FIFO memory has retransmit capability, which allows previously read data to be accessed again. The FIFO has flags to indicate empty and full conditions and two programmable flags (almost full and almost empty) to indicate when a selected number of words is stored in memory. Communication between each port takes place with two 36-bit mailbox registers. Each mailbox register has a flag to signal when new mail has been stored. Two or more devices are used in parallel to create wider datapaths. Expansion is also possible in word depth.

The SN74ACT3641 is a clocked FIFO, which means each port employs a synchronous interface. All data transfers through a port are gated to the low-to-high transition of a continuous (free-running) port clock by enable signals. The continuous clocks for each port are independent of one another and can be asynchronous or coincident. The enables for each port are arranged to provide a simple interface between microprocessors and/or buses with synchronous control.

The input-ready (IR) flag and almost-full (AF) flag of the FIFO are two-stage synchronized to CLKA. The output-ready (OR) flag and almost-empty (\overline{AE}) flag of the FIFO are two-stage synchronized to CLKB. Offset values for the \overline{AF} and \overline{AE} flags of the FIFO can be programmed from port A or through a serial input.

The SN74ACT3641 is characterized for operation from 0°C to 70°C.

For more information on this device family, see the following application reports:

- FIFO Patented Synchronous Retransmit: Programmable DSP-Interface Application for FIR Filtering (literature number SCAA009)
- FIFO Mailbox-Bypass Registers: Using Bypass Registers to Initialize DMA Control (literature number SCAA007)
- Metastability Performance of Clocked FIFOs (literature number SCZA004)

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**FS0/SD
FS1/SEN** RST
GNO SIN
GNO SIN E SOU BOILD
CONDIN
KONDIN
KONDIN CLKA ENA W/RA MBF2
MB GND CB
CN
CN
CN
CN EN C CSA MBA re R
En Ro ۳
MX $|\vec{<}|$ \Box 120 119 118 117 116 115 114 113 112 111 110 109 108 107 106 105 104 103 102 101 100 99 98 97 96 95 94 93 92 91 A₃₅ \Box 1 90 P B35 A34 2 89 P B34 $A33$ 3 88 D B33 A32 4 87 P B32 $V_{\rm CC}$ 86 \Box GND 5 A31 6 85 D B31 A30 7 84 P B30 GND □ 8 83 D B29 A29 □ 9 B28 82 A28 10 B27 81 A27 B26 11 80 A26 12 79 $V_{\rm CC}$ A25 13 78 B25 A24 14 77 B24 A23 □ 15 76 O GND $GND \sqsubseteq 16$ B23 75 A22 □ 17 B22 74 $\rm v_{\rm CC}$ 18 B21 73 A21 19 B20 72 A20 □ 20 71 D B19 A19 21 B18 70 A18 22 69 O GND $GND \sqcup 23$ 68 **□ B17** A17 24 67 **□** B16 A16 25 66 $\rm v_{\rm CC}$ A15 □ 26 B15 65 A14 27 B14 64 A13 □ 28 63 B13 $V_{\rm CC}$ 29 62 B12 A12 30 61 GND 2

2 POST OFFICE BOX 65538

2 POST OFFICE BOX 65303 • DALLAS, TEXAS

73256303 • DALLAS, TEXAS

2 P 6 5 5 5 5 5 5 5 5 6 6 6 7 A9 A8 GND A11 A10 A7 A6 A5 A4 A1 A0 B2 GND B0 B1 B5 GND B6 B7 B8 B9 A2 B4 VCC GND A3 B3 VCC B10 B11

PCB PACKAGE (TOP VIEW)

NC – No internal connection

1024 × **36 CLOCKED FIRST-IN, FIRST-OUT MEMORY**

SN74ACT3641

NC – No internal connection

† Uses Yamaichi socket IC51-1324-828

functional block diagram

Terminal Functions

SN74ACT3641 1024 × **36 CLOCKED FIRST-IN, FIRST-OUT MEMORY**

SCAS338C – JANUARY 1994 – REVISED OCTOBER 1997

Terminal Functions (Continued)

detailed description

reset

The SN74ACT3641 is reset by taking the reset (RST) input low for at least four port-A clock (CLKA) and four port-B clock (CLKB) low-to-high transitions. RST can switch asynchronously to the clocks. A reset initializes the memory read and write pointers and forces the IR flag low, the OR flag low, the \overline{AE} flag low, and the \overline{AF} flag high. Resetting the device also forces the mailbox flags (MBF1, MBF2) high. After a FIFO is reset, its flag is set high after at least two clock cycles to begin normal operation. A FIFO must be reset after power up before data is written to its memory.

almost-empty flag and almost-full flag offset programming

Two registers in the SN74ACT3641 are used to hold the offset values for the \overline{AE} and \overline{AF} flags. The \overline{AE} flag offset register is labeled X, and the \overline{AF} flag offset register is labeled Y. The offset registers can be loaded with a value in three ways: one of two preset values are loaded into the offset registers, parallel load from port A, or serial load. The offset register programming mode is chosen by the flag select (FS1, FS0) inputs during a low-to-high transition on RST (see Table 1).

FS ₁	FS ₀	RST	X AND Y REGISTERST		
н	н		Serial load		
Н			64		
	н				
			Parallel load from port A		
register holds the offset for AF. V register holds the					

Table 1. Flag Programming

† X register holds the offset for AE; Y register holds the offset for AF.

preset values

If a preset value of 8 or 64 is chosen by FS1 and FS0 at the time of a $\overline{\text{RST}}$ low-to-high transition according to Table 1, the preset value is automatically loaded into the X and Y registers. No other device initialization is necessary to begin normal operation, and the IR flag is set high after two low-to-high transitions on CLKA.

parallel load from port A

To program the X and Y registers from port A, the device is reset with FS0 and FS1 low during the low-to-high transition of RST. After this reset is complete, IR is set high after two low-to-high transitions on CLKA. The first two writes to the FIFO do not store data in its memory but load the offset registers in the order Y, X. Each offset register of the SN74ACT3641 uses port-A inputs (A9–A0). Data input A9 is used as the most-significant bit of the binary number. Each register value can be programmed from 1 to 1020. After both offset registers are programmed from port A, subsequent FIFO writes store data in the SRAM.

serial load

To program the X and Y registers serially, the device is reset with FS0/SD and FS1/SEN high during the low-to-high transition of RST. After this reset is complete, the X-and Y-register values are loaded bitwise through FS0/SD on each low-to-high transition of CLKA that FS1/SEN is low. Twenty bit writes are needed to complete the programming. The first bit write stores the most-significant bit of the Y register and the last bit write stores the least-significant bit of the the X register. Each register value can be programmed from 1 to 1020.

When the option to program the offset registers serially is chosen, the IR remains low until all 20 bits are written. IR is set high by the low-to-high transition of CLKA after the last bit is loaded to allow normal FIFO operation.

FIFO write/read operation

The state of the port-A data (A0–A35) outputs is controlled by the port-A chip select (CSA) and the port-A write/read select (W/RA). The A0-A35 outputs are in the high-impedance state when either CSA or W/RA is high. The A0–A35 outputs are active when both CSA and W/RA are low.

Data is loaded into the FIFO from the A0–A35 inputs on a low-to-high transition of CLKA when CSA and the port-A mailbox select (MBA) are low, W/RA, the port-A enable (ENA), and the IR flag are high (see Table 2). Writes to the FIFO are independent of any concurrent FIFO reads.

CSA	W/RA	ENA	MBA	CLKA	A0-A35 OUTPUTS	PORT FUNCTION	
н	X	X	X	X	In high-impedance state	None	
	н		X	X	In high-impedance state	None	
	н	н		个	In high-impedance state	FIFO write	
	н	н	Н	个	In high-impedance state	Mail1 write	
				X	Active, mail2 register	None	
		н		个	Active, mail2 register None		
			Н	X	Active, mail2 register None		
		н	н	个	Mail2 read (set MBF2 high) Active, mail2 register		

Table 2. Port-A Enable Function Table

The port-B control signals are identical to those of port A, with the exception that the port-B write/read select $\overline{\text{W/R}}$ B) is the inverse of W/RA. The state of the port-B data (B0–B35) outputs is controlled by the port-B chip select (CSB) and \overline{W}/RB . The B0–B35 outputs are in the high-impedance state when either CSB is high or \overline{W}/RB is low. The B0–B35 outputs are active when $\overline{\text{CSB}}$ is low and $\overline{\text{W}}$ /RB is high.

Data is read from the FIFO to its output register on a low-to-high transition of CLKB when CSB and the port-B mailbox select (MBB) are low, W/RB, the port-B enable (ENB), and the OR flag are high (see Table 3). Reads from the FIFO are independent of any concurrent FIFO writes.

FIFO write/read operation (continued)

CSB	W/RB	ENB	MBB	CLKB	B0-B35 OUTPUTS	PORT FUNCTION	
н	X	X	X	X	In high-impedance state	None	
			X	X	In high-impedance state None		
		н		↑	In high-impedance state None		
		н	Н	↑	In high-impedance state Mail ₂ write		
	н			X	Active, FIFO output register None		
	н	н		↑	Active, FIFO output register FIFO read		
	н		H	X	Active, mail1 register None		
	н	н	н	个	Mail1 read (set MBF1 high) Active, mail1 register		

Table 3. Port-B Enable Function Table

The setup- and hold-time constraints to the port clocks for the port-chip selects and write/read selects are only for enabling write and read operations and are not related to high-impedance control of the data outputs. If a port enable is low during a clock cycle, the port-chip select and write/read select can change states during the setup- and hold-time window of the cycle.

When the OR is low, the next data word is sent to the FIFO output register automatically by the CLKB low-to-high transition that sets OR high. When OR is high, an available data word is clocked to the FIFO output register only when a FIFO read is selected by CSB, W/RB, ENB, and MBB.

synchronized FIFO flags

Each FIFO flag is synchronized to its port clock through at least two flip-flop stages. This is done to improve the flag's reliability by reducing the probability of metastable events on their outputs when CLKA and CLKB operate asynchronously to one another. OR and \overline{AE} are synchronized to CLKB. IR and \overline{AF} are synchronized to CLKA. Table 4 shows the relationship of each flag to the number of words stored in memory.

NUMBER OF WORDS IN FIFO ₁		SYNCHRONIZED TO CLKB	SYNCHRONIZED TO CLKA	
	OR	AE	AF	IR
				н
1 to X	н		н	н
$(X + 1)$ to $[1024 - (Y + 1)]$	н	н	н	н
$(1024 - Y)$ to 1023	н	н		н
1024		н		

Table 4. FIFO Flag Operation

 \dagger X is the almost-empty offset for \overline{AE} . Y is the almost-full offset for \overline{AF} .

‡ When a word is present in the FIFO output register, its previous memory location is free.

output-ready flag (OR)

The OR flag of a FIFO is synchronized to the port clock that reads data from its array (CLKB). When the OR flag is high, new data is present in the FIFO output register. When the OR flag is low, the previous data word is present in the FIFO output register and attempted FIFO reads are ignored.

A FIFO read pointer is incremented each time a new word is clocked to its output register. From the time a word is written to a FIFO, it can be shifted to the FIFO output register in a minimum of three cycles of CLKB; therefore, an OR flag is low if a word in memory is the next data to be sent to the FIFO output register and three CLKB cycles have not elapsed since the time the word was written. The OR flag of the FIFO remains low until the third low-to-high transition of CLKB occurs, simultaneously forcing the OR flag high and shifting the word to the FIFO output register.

A low-to-high transition on CLKB begins the first synchronization cycle of a write if the clock transition occurs at time $t_{sk(1)}$, or greater, after the write. Otherwise, the subsequent CLKB cycle can be the first synchronization cycle (see Figure 6).

input-ready flag (IR)

The IR flag of a FIFO is synchronized to the port clock that writes data to its array (CLKA). When the IR flag is high, a memory location is free in the SRAM to write new data. No memory locations are free when the IR flag is low and attempted writes to the FIFO are ignored.

Each time a word is written to a FIFO, its write pointer is incremented. From the time a word is read from a FIFO, its previous memory location is ready to be written in a minimum of three cycles of CLKA; therefore, an IR flag is low if less than two cycles of CLKA have elapsed since the next memory write location has been read. The second low-to-high transition on CLKA after the read sets the IR flag high, and data can be written in the following cycle.

A low-to-high transition on CLKA begins the first synchronization cycle of a read if the clock transition occurs at time $t_{sk(1)}$, or greater, after the read. Otherwise, the subsequent CLKA cycle can be the first synchronization cycle (see Figure 7).

almost-empty flag (AE)

The \overline{AE} flag of a FIFO is synchronized to the port clock that reads data from its array (CLKB). The almost-empty state is defined by the contents of register X. This register is loaded with a preset value during a FIFO reset, programmed from port A, or programmed serially (see almost-empty flag and almost-full flag offset *programming*). The \overline{AE} flag is low when the FIFO contains X or fewer words and is high when the FIFO contains (X + 1) or more words. A data word present in the FIFO output register has been read from memory.

Two low-to-high transitions of CLKB are required after a FIFO write for the AE flag to reflect the new level of fill; therefore, the AE flag of a FIFO containing (X + 1) or more words remains low if two cycles of CLKB have not elapsed since the write that filled the memory to the (X + 1) level. An AE flag is set high by the second low-to-high transition of CLKB after the FIFO write that fills memory to the $(X + 1)$ level. A low-to-high transition of CLKB begins the first synchronization cycle if it occurs at time t_{sk(2)}, or greater, after the write that fills the FIFO to (X + 1) words. Otherwise, the subsequent CLKB cycle can be the first synchronization cycle (see Figure 8).

almost-full flag (AF)

The \overline{AF} flag of a FIFO is synchronized to the port clock that writes data to its array (CLKA). The almost-full state is defined by the contents of register Y. This register is loaded with a preset value during a FIFO reset, programmed from port A, or programmed serially (see almost-empty flag and almost-full flag offset programming). The \overline{AF} flag is low when the number of words in the FIFO is greater than or equal to (1024 – Y). The \overline{AF} flag is high when the number of words in the FIFO is less than or equal to [1024 – (Y + 1)]. A data word present in the FIFO output register has been read from memory.

Two low-to-high transitions of CLKA are required after a FIFO read for its AF flag to reflect the new level of fill. Therefore, the $\overline{\text{AF}}$ flag of a FIFO containing [1024 – (Y + 1)] or fewer words remains low if two cycles of CLKA have not elapsed since the read that reduced the number of words in memory to $[1024 - (Y + 1)]$. An \overline{AF} flag is set high by the second low-to-high transition of CLKA after the FIFO read that reduces the number of words in memory to $[1024 - (Y + 1)]$. A low-to-high transition of CLKA begins the first synchronization cycle if it occurs at time t_{sk(2)}, or greater, after the read that reduces the number of words in memory to [1024 – (Y + 1)]. Otherwise, the subsequent CLKA cycle can be the first synchronization cycle (see Figure 9).

synchronous retransmit

The synchronous retransmit feature of the SN74ACT3641 allows FIFO data to be read repeatedly starting at a user-selected position. The FIFO is first put into retransmit mode to select a beginning word and prevent ongoing FIFO write operations from destroying retransmit data. Data vectors with a minimum length of three words can retransmit repeatedly, starting at the selected word. The FIFO can be taken out of retransmit mode at any time and allow normal device operation.

The FIFO is put in retransmit mode by a low-to-high transition on CLKB when the retransmit mode (RTM) input is high and OR is high. This rising CLKB edge marks the data present in the FIFO output register as the first retransmit data. The FIFO remains in retransmit mode until a low-to-high transition occurs while RTM is low.

When two or more reads have been done past the initial retransmit word, a retransmit is initiated by a low-to-high transition on CLKB when the read-from-mark (RFM) input is high. This rising CLKB edge shifts the first retransmit word to the FIFO output register and subsequent reads can begin immediately. Retransmit loops can be done endlessly while the FIFO is in retransmit mode. RFM must be low during the CLKB rising edge that takes the FIFO out of retransmit mode.

When the FIFO is put into retransmit mode, it operates with two read pointers. The current read pointer operates normally, incrementing each time a new word is shifted to the FIFO output register and used by the OR and \overline{AE} flags. The shadow read pointer stores the SRAM location at the time the device is put into retransmit mode and does not change until the device is taken out of retransmit mode. The shadow read pointer is used by the IR and AF flags. Data writes can proceed while the FIFO is in retransmit mode, but AF is set low by the write that stores (1024 – Y) words after the first retransmit word. The IR flag is set low by the 1024th write after the first retransmit word.

When the FIFO is in retransmit mode and RFM is high, a rising CLKB edge loads the current read pointer with the shadow read-pointer value and the OR flag reflects the new level of fill immediately. If the retransmit changes the FIFO status out of the almost-empty range, up to two CLKB rising edges after the retransmit cycle are needed to switch \overline{AE} high (see Figure 11). The rising CLKB edge that takes the FIFO out of retransmit mode shifts the read pointer used by the IR and \overline{AF} flags from the shadow to the current read pointer. If the change of read pointer used by IR and \overline{AF} should cause one or both flags to transition high, at least two CLKA synchronizing cycles are needed before the flags reflect the change. A rising CLKA edge after the FIFO is taken out of retransmit mode is the first synchronizing cycle of IR if it occurs at time t_{sk(1)}, or greater, after the rising CLKB edge (see Figure 12). A rising CLKA edge after the FIFO is taken out of retransmit mode is the first synchronizing cycle of \overline{AF} if it occurs at time t_{sk(2)}, or greater, after the rising CLKB edge (see Figure 14).

mailbox registers

Two 36-bit bypass registers are on the SN74ACT3641 to pass command and control information between port A and port B. The mailbox-select (MBA, MBB) inputs choose between a mail register and a FIFO for a port data transfer operation. A low-to-high transition on CLKA writes A0-A35 data to the mail1 register when a port A write is selected by CSA, W/RA, and ENA with MBA high. A low-to-high transition on CLKB writes B0–B35 data to the mail2 register when a port-B write is selected by \overline{CSB} , \overline{W}/RB , and ENB with MBB high. Writing data to a mail register sets its corresponding flag (MBF1 or MBF2) low. Attempted writes to a mail register are ignored while its mail flag is low.

When the port-B data (B0–B35) outputs are active, the data on the bus comes from the FIFO output register when the port-B mailbox select (MBB) input is low and from the mail1 register when MBB is high. Mail2 data is always present on the port-A data (A0–A35) outputs when they are active. The mail1 register flag ($\overline{\text{MBF1}}$) is set high by a low-to-high transition on CLKB when a port-B read is selected by \overline{CSB} , \overline{W}/RB , and ENB with MBB high. The mail2 register flag (MBF2) is set high by a low-to-high transition on CLKA when a port-A read is selected by CSA, W/RA, and ENA with MBA high. The data in a mail register remains intact after it is read and changes only when new data is written to the register.

Figure 1. FIFO Reset Loading X and Y With a Preset Value of Eight

NOTE A: \overline{CSA} = L, W/RA = H, MBA = L. It is not necessary to program offset register on consecutive clock cycles.

NOTE A: It is not necessary to program offset register bits on consecutive clock cycles. FIFO write attempts are ignored until IR is set high.

Figure 3. Programming the AF Flag and AE Flag Offset Values Serially

Figure 4. FIFO Write-Cycle Timing

Figure 5. FIFO Read-Cycle Timing

 $t_{sk(1)}$ is the minimum time between a rising CLKA edge and a rising CLKB edge for OR to transition high and to clock the next word to the \overrightarrow{FIPO} output register in three CLKB cycles. If the time between the rising CLKA edge and rising CLKB edge is less than t_{SK(1)}, the transition of OR high and the first word load to the output register can occur one CLKB cycle later than shown.

Figure 6. OR-Flag Timing and First Data-Word Fall-Through When the FIFO Is Empty

 \dagger t_{Sk(1)} is the minimum time between a rising CLKB edge and a rising CLKA edge for IR to transition high in the next CLKA cycle. If the time between the rising CLKB edge and rising CLKA edge is less than t_{Sk(1)}, IR can transition high one CLKA cycle later than shown.

Figure 7. IR-Flag Timing and First Available Write When the FIFO Is Full

 \dagger t_{Sk(2)} is the minimum time between a rising CLKA edge and a rising CLK<u>B e</u>dge for $\overline{\sf AE}$ to transition high in the next CLKB cycle. If the time between the rising CLKA edge and rising CLKB edge is less than $t_{sk(2)}$, \overline{AE} can transition high one CLKB cycle later than shown. NOTE A: FIFO write $(\overline{CSA} = L, W/\overline{R}A = H, MBA = L)$, FIFO read $(\overline{CSB} = L, \overline{W}/RB = H, MBB = L)$

 \ddagger t_{Sk(2)} is the minimum time between a rising CLKA edge and a rising CLK<u>B e</u>dge for $\overline{\sf AF}$ to transition high in the next CLKA cycle. If the time between the rising CLKB edge and rising CLKA edge is less than $t_{sk(2)}$, \overline{AF} can transition high one CLKA cycle later than shown. NOTE A: FIFO write $(\overline{CSA} = \overline{L}, W/\overline{R}A = H, MBA = L)$, FIFO read $(\overline{CSB} = L, \overline{W}/RB = H, MBB = L)$

Figure 9. Timing for AF When FIFO Is Almost Full

NOTE A: \overline{CSB} = L, \overline{W}/RB = H, MBB = L. No input enables other than RTM and RFM are needed to control retransmit mode or begin a retransmit. Other enables are shown only to relate retransmit operations to the FIFO output register.

NOTE A: X is the value loaded in the \overline{AE} flag offset register.

Figure 11. AE Maximum Latency When Retransmit Increases the Number of Stored Words Above X

 \dagger t_{Sk(1)} is the minimum time between a rising CLKB edge and a rising CLKA edge for IR to transition high in the next CLKA cycle. If the time between the rising CLKB edge and rising CLKA edge is less than t_{Sk(1)}, IR can transition high one CLKA cycle later than shown.

Figure 12. IR Timing From the End of Retransmit Mode When One or More Write Locations Are Available

 \ddagger t_{Sk(2)} is the minimum time between a rising CLKB edge and a rising CLKA edge for $\overline{\sf AF}$ to transition high in the next CLKA cycle. If the time between the rising CLKB edge and ri<u>sing</u> CLKA edge is less than t_{SK(2)}, AF can transition high one CLKA cycle later than shown. NOTE A: Y is the value loaded in the AF flag offset register.

Figure 13. AF Timing From the End of Retransmit Mode When (Y + 1) or More Write Locations Are Available

Figure 14. Timing for Mail1 Register and MBF1 Flag

Figure 15. Timing for Mail2 Register and MBF2 Flag

absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

† Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. The input and output voltage ratings may be exceeded provided the input and output current ratings are observed.

2. The package thermal impedance is calculated in accordance with JESD 51.

recommended operating conditions

electrical characteristics over recommended operating free-air temperature range (unless otherwise noted)

 $\frac{1}{2}$ All typical values are at V_{CC} = 5 V, T_A = 25°C.

§ This is the supply current when each input is at one of the specified TTL voltage levels rather than 0 V or V_{CC}.

timing requirements over recommended ranges of supply voltage and operating free-air temperature (see Figures 1 through 16)

† Requirement to count the clock edge as one of at least four needed to reset a FIFO

‡ Applies only when serial load method is used to program flag-offset registers

§ Skew time is not a timing constraint for proper device operation and is included only to illustrate the timing relationship between CLKA cycle and CLKB cycle.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature, CL = 30 pF (see Figures 1 through 15)

† Writing data to the mail1 register when the B0–B35 outputs are active and MBB is high

‡ Writing data to the mail2 register when the A0–A35 outputs are active and MBA is high

PARAMETER MEASUREMENT INFORMATION

Figure 16. Load Circuit and Voltage Waveforms

SUPPLY CURRENT vs CLOCK FREQUENCY 250 fdata = 1/2 fclock $V_{CC} = 5.5 V$ $T_A = 25^\circ C$ **CL = 0 pF** I_{CC(f)} - Supply Current - mA **I – Supply Current – mA CC(f) 200** $V_{CC} = 5 V$ **150 VCC = 4.5 V 100 50 0 60 70 0 10 20 30 40 50 fclock – Clock Frequency – MHz**

TYPICAL CHARACTERISTICS

Figure 17

calculating power dissipation

The $I_{CC(f)}$ current in Figure 17 was taken while simultaneously reading and writing the FIFO on the SN74ACT3641 with CLKA and CLKB set to f_{clock}. All data inputs and data outputs change state during each clock cycle to consume the highest supply current. Data outputs are disconnected to normalize the graph to a zero-capacitance load. Once the capacitive load per data-output channel and the number of SN74ACT3641 inputs driven by TTL high levels are known, the power dissipation can be calculated with the equation below.

With $I_{CC(f)}$ taken from Figure 17, the maximum power dissipation (P_T) of the SN74ACT3641 can be calculated by:

$$
P_T = V_{CC} \times [I_{CC(f)} + (N \times \Delta I_{CC} \times dc)] + \Sigma (C_L \times V_{CC}^2 \times f_0)
$$

where:

When no reads or writes are occurring on the SN74ACT3641, the power dissipated by a single clock (CLKA or CLKB) input running at frequency f_{clock} is calculated by:

$$
P_T = V_{CC} \times f_{clock} \times 0.29 \text{ mA} / \text{MHz}
$$

JMENTS

PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details. **TBD:** The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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OTHER QUALIFIED VERSIONS OF SN74ACT3641 :

• Military: [SN54ACT3641](http://focus.ti.com/docs/prod/folders/print/sn54act3641.html)

NOTE: Qualified Version Definitions:

• Military - QML certified for Military and Defense Applications

MECHANICAL DATA

MBQF001A – NOVEMBER 1995

PQ (S-PQFP-G*) PLASTIC QUAD FLATPACK**

100 LEAD SHOWN

NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MO-069

MECHANICAL DATA

MHTQ004A – JANUARY 1995 – REVISED JANUARY 1998

PCB (S-PQFP-G120) PLASTIC QUAD FLATPACK (DIE DOWN)

NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Thermally enhanced molded plastic package with a heat slug (HSL)
- D. Falls within JEDEC MS-026

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