

The S-93C86B is a high speed, low current consumption, 3-wire serial E<sup>2</sup>PROM with a wide operating voltage range. The S-93C86B has the capacity of 16 K-bit, and the organization is 1024-word × 16 bit. It is capable of sequential read, at which time addresses are automatically incremented in 16-bit blocks.

The communication method is by the Microwire bus.

## ■ Features

- Operating voltage range:           Read           1.8 V to 5.5 V  
  Write           2.7 V to 5.5 V
- Operation frequency:           2.0 MHz (V<sub>CC</sub> = 4.5 V to 5.5 V)
- Write time:                        4.0 ms max.
- Sequential read capable
- Write protect function during the low power supply voltage
- Function to protect against write due to erroneous instruction recognition
- Endurance:                        10<sup>6</sup> cycles / word\*<sup>1</sup> (Ta = +85°C)
- Data retention:                   100 years (Ta = +25°C)  
  20 years (Ta = +85°C)
- Memory capacity:                16 K-bit
- Initial delivery state:           FFFFh
- Operation temperature range:   Ta = -40°C to +85°C
- Lead-free, Sn 100%, halogen-free\*<sup>2</sup>

\*1. For each address (Word: 16-bit)

\*2. Refer to "■ Product Name Structure" for details.

## ■ Packages

- 8-Pin SOP (JEDEC)
- 8-Pin TSSOP

**Caution** This product is intended to use in general electronic devices such as consumer electronics, office equipment, and communications devices. Before using the product in medical equipment or automobile equipment including car audio, keyless entry and engine control unit, contact to ABLIC Inc. is indispensable.

■ Pin Configurations

1. 8-Pin SOP (JEDEC)

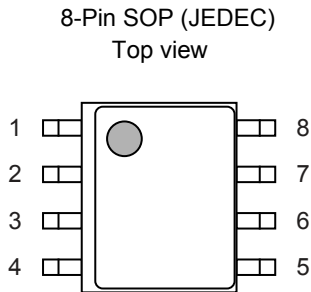


Figure 1

S-93C86BD4I-J8T1x

Table 1

Pin No.	Symbol	Description
1	CS	Chip select input
2	SK	Serial clock input
3	DI	Serial data input
4	DO	Serial data output
5	GND	Ground
6	TEST* <sup>1</sup>	Test
7	NC	No connection
8	VCC	Power supply

\*1. Connect to GND or V<sub>CC</sub>.

Even if this pin is not connected, performance is not affected so long as the absolute maximum rating is not exceeded.

2. 8-Pin TSSOP

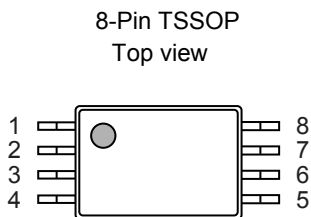


Figure 2

S-93C86BD4I-T8T1x

Table 2

Pin No.	Symbol	Description
1	CS	Chip select input
2	SK	Serial clock input
3	DI	Serial data input
4	DO	Serial data output
5	GND	Ground
6	TEST* <sup>1</sup>	Test
7	NC	No connection
8	VCC	Power supply

\*1. Connect to GND or V<sub>CC</sub>.

Even if this pin is not connected, performance is not affected so long as the absolute maximum rating is not exceeded.

**Remark 1.** Refer to the “package drawings” for the details.

**2.** x: G or U

**3.** Please select products of environmental code = U for Sn 100%, halogen-free products.

■ Block Diagram

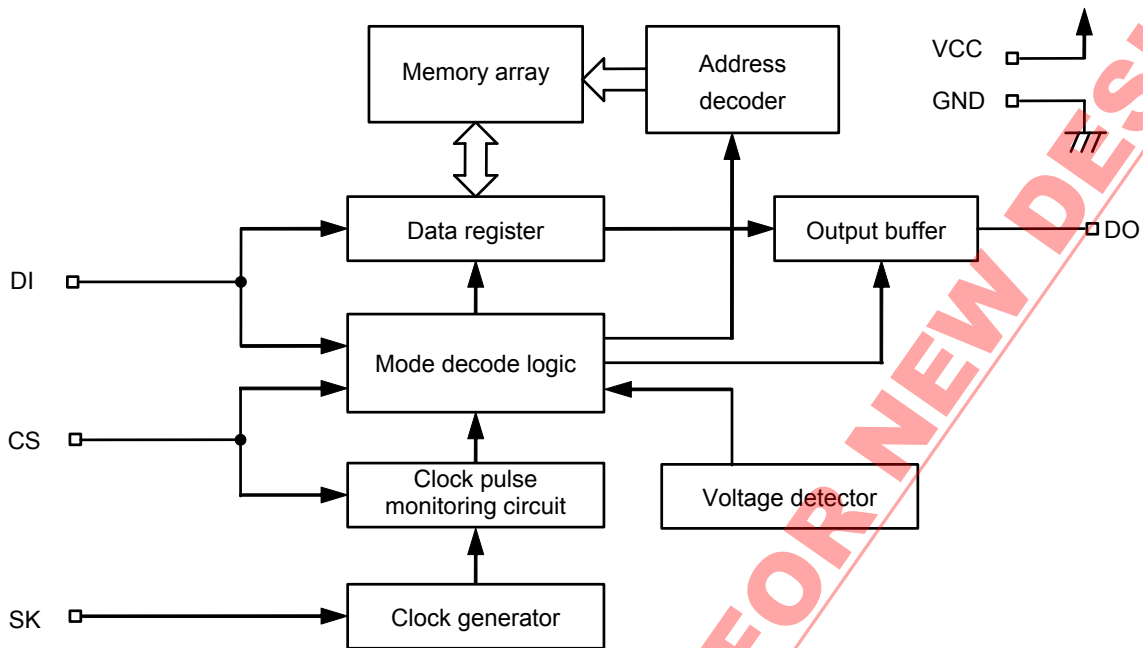


Figure 3

**NOT RECOMMENDED FOR NEW DESIGN**

■ Instruction Sets

Table 3

Instruction	Start Bit	Operation Code		Address										Data	
		2	3	4	5	6	7	8	9	10	11	12	13	14 to 29	
SK input clock	1														
READ (Read data)	1	1	0	A9	A8	A7	A6	A5	A4	A3	A2	A1	A0	D15 to D0 Output <sup>*1</sup>	
WRITE (Write data)	1	0	1	A9	A8	A7	A6	A5	A4	A3	A2	A1	A0	D15 to D0 Input	
ERASE (Erase data)	1	1	1	A9	A8	A7	A6	A5	A4	A3	A2	A1	A0	—	
WRAL (Write all)	1	0	0	0	1	x	x	x	x	x	x	x	x	D15 to D0 Input	
ERAL (Erase all)	1	0	0	1	0	x	x	x	x	x	x	x	x	—	
EWEN (Write enable)	1	0	0	1	1	x	x	x	x	x	x	x	x	—	
EWDS (Write disable)	1	0	0	0	0	x	x	x	x	x	x	x	x	—	

\*1. When the 16-bit data in the specified address has been output, the data in the next address is output.

Remark x: Don't care



## ■ Absolute Maximum Ratings

Table 4

Item	Symbol	Ratings	Unit
Power supply voltage	$V_{CC}$	-0.3 to +7.0	V
Input voltage	$V_{IN}$	-0.3 to $V_{CC} + 0.3$	V
Output voltage	$V_{OUT}$	-0.3 to $V_{CC}$	V
Operation ambient temperature	$T_{opr}$	-40 to +105	°C
Storage temperature	$T_{stg}$	-65 to +150	°C

**Caution** The absolute maximum ratings are rated values exceeding which the product could suffer physical damage. These values must therefore not be exceeded under any conditions.

## ■ Recommended Operating Conditions

Table 5

Item	Symbol	Conditions	$T_a = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$		Unit
			Min.	Max.	
Power supply voltage	$V_{CC}$	READ, EWDS	1.8	5.5	V
		WRITE, ERASE, WRAL, ERAL, EWEN	2.7	5.5	V
High level input voltage	$V_{IH}$	$V_{CC} = 4.5\text{ V to }5.5\text{ V}$	2.0	$V_{CC}$	V
		$V_{CC} = 2.7\text{ V to }4.5\text{ V}$	$0.8 \times V_{CC}$	$V_{CC}$	V
		$V_{CC} = 1.8\text{ V to }2.7\text{ V}$	$0.8 \times V_{CC}$	$V_{CC}$	V
Low level input voltage	$V_{IL}$	$V_{CC} = 4.5\text{ V to }5.5\text{ V}$	0.0	0.8	V
		$V_{CC} = 2.7\text{ V to }4.5\text{ V}$	0.0	$0.2 \times V_{CC}$	V
		$V_{CC} = 1.8\text{ V to }2.7\text{ V}$	0.0	$0.15 \times V_{CC}$	V

## ■ Pin Capacitance

Table 6

( $T_a = +25^{\circ}\text{C}$ ,  $f = 1.0\text{ MHz}$ ,  $V_{CC} = 5.0\text{ V}$ )

Item	Symbol	Conditions	Min.	Max.	Unit
Input Capacitance	$C_{IN}$	$V_{IN} = 0\text{ V}$	—	8	pF
Output Capacitance	$C_{OUT}$	$V_{OUT} = 0\text{ V}$	—	10	pF

## ■ Endurance

Table 7

Item	Symbol	Operation Ambient Temperature	Min.	Max.	Unit
Endurance	$N_w$	$T_a = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$	$10^6$	—	Cycles / word*1

\*1. For each address (Word: 16-bit)

## ■ Data Retention

Table 8

Item	Symbol	Operation Ambient Temperature	Min.	Max.	Unit
Data retention	—	$T_a = +25^{\circ}\text{C}$	100	—	year
		$T_a = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$	20	—	year

■ DC Electrical Characteristics

Table 9

Item	Symbol	Conditions	Ta = -40°C to +85°C						Unit
			V <sub>CC</sub> = 4.5 V to 5.5 V		V <sub>CC</sub> = 2.5 V to 4.5 V		V <sub>CC</sub> = 1.8 V to 2.5 V		
			Min.	Max.	Min.	Max.	Min.	Max.	
Current consumption (READ)	I <sub>CC1</sub>	DO no load	—	0.8	—	0.5	—	0.4	mA

Table 10

Item	Symbol	Conditions	Ta = -40°C to +85°C				Unit
			V <sub>CC</sub> = 4.5 V to 5.5 V		V <sub>CC</sub> = 2.7 V to 4.5 V		
			Min.	Max.	Min.	Max.	
Current consumption (WRITE)	I <sub>CC2</sub>	DO no load	—	2.0	—	1.5	mA

Table 11

Item	Symbol	Conditions	Ta = -40°C to +85°C						Unit
			V <sub>CC</sub> = 4.5 V to 5.5 V		V <sub>CC</sub> = 2.5 V to 4.5 V		V <sub>CC</sub> = 1.8 V to 2.5 V		
			Min.	Max.	Min.	Max.	Min.	Max.	
Standby current consumption	I <sub>SB</sub>	CS = GND, DO = Open, Other inputs to V <sub>CC</sub> or GND	—	1.5	—	1.5	—	1.5	μA
Input leakage current	I <sub>LI</sub>	V <sub>IN</sub> = GND to V <sub>CC</sub>	—	1.0	—	1.0	—	1.0	μA
Output leakage current	I <sub>LO</sub>	V <sub>OUT</sub> = GND to V <sub>CC</sub>	—	1.0	—	1.0	—	1.0	μA
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.1 mA	—	0.4	—	—	—	—	V
		I <sub>OL</sub> = 100 μA	—	0.1	—	0.1	—	0.1	V
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -400 μA	2.4	—	—	—	—	—	V
		I <sub>OH</sub> = -100 μA	V <sub>CC</sub> - 0.3	—	V <sub>CC</sub> - 0.3	—	—	—	V
		I <sub>OH</sub> = -10 μA	V <sub>CC</sub> - 0.2	—	V <sub>CC</sub> - 0.2	—	V <sub>CC</sub> - 0.2	—	V
Data hold voltage of write enable latch	V <sub>DH</sub>	Only program disable mode	1.5	—	1.5	—	1.5	—	V

NOT RECOMMENDED FOR NEW DESIGN

## ■ AC Electrical Characteristics

Table 12 Measurement Conditions

Input pulse voltage	$0.1 \times V_{CC}$ to $0.9 \times V_{CC}$
Output reference voltage	$0.5 \times V_{CC}$
Output load	100 pF

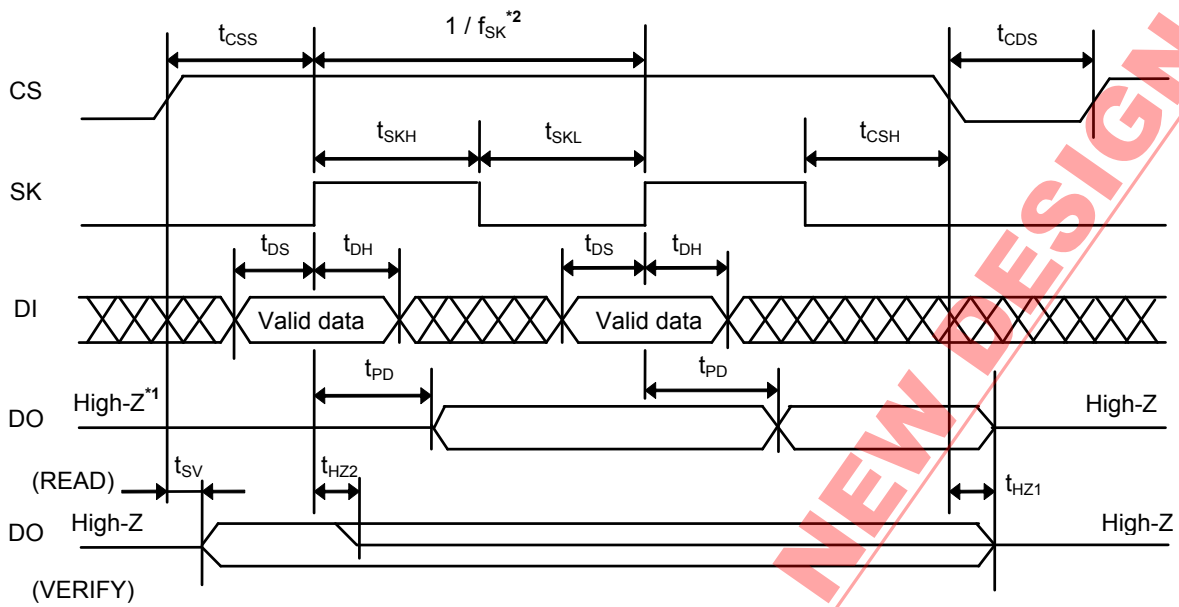
Table 13

Item	Symbol	Ta = -40°C to +85°C						Unit
		V <sub>CC</sub> = 4.5 V to 5.5 V		V <sub>CC</sub> = 2.5 V to 4.5 V		V <sub>CC</sub> = 1.8 V to 2.5 V		
		Min.	Max.	Min.	Max.	Min.	Max.	
CS setup time	t <sub>CSS</sub>	0.2	—	0.4	—	1.0	—	μs
CS hold time	t <sub>CSH</sub>	0	—	0	—	0	—	μs
CS deselect time	t <sub>CDS</sub>	0.2	—	0.2	—	0.4	—	μs
Data setup time	t <sub>DS</sub>	0.1	—	0.2	—	0.4	—	μs
Data hold time	t <sub>DH</sub>	0.1	—	0.2	—	0.4	—	μs
Output delay time	t <sub>PD</sub>	—	0.4	—	0.8	—	2.0	μs
Clock frequency*1	f <sub>SK</sub>	0	2.0	0	0.5	0	0.25	MHz
SK clock time "L"*1	t <sub>SKL</sub>	0.1	—	0.5	—	1.0	—	μs
SK clock time "H"*1	t <sub>SKH</sub>	0.1	—	0.5	—	1.0	—	μs
Output disable time	t <sub>HZ1</sub> , t <sub>HZ2</sub>	0	0.15	0	0.5	0	1.0	μs
Output enable time	t <sub>SV</sub>	0	0.15	0	0.5	0	1.0	μs

\*1. The clock cycle of the SK clock (frequency: f<sub>SK</sub>) is 1 / f<sub>SK</sub> μs. This clock cycle is determined by a combination of several AC characteristics, so be aware that even if the SK clock cycle time is minimized, the clock cycle (1 / f<sub>SK</sub>) cannot be made to equal t<sub>SKL</sub> (min.) + t<sub>SKH</sub> (min.).

Table 14

Item	Symbol	Ta = -40°C to +85°C			Unit
		V <sub>CC</sub> = 2.7 V to 5.5 V			
		Min.	Typ.	Max.	
Write time	t <sub>PR</sub>	—	2.0	4.0	ms



\*1. Indicates high impedance.

\*2.  $1/f_{SK}$  is the SK clock cycle. This clock cycle is determined by a combination of several AC characteristics, so be aware that even if the SK clock cycle time is minimized, the clock cycle ( $1/f_{SK}$ ) cannot be made to equal  $t_{SKL}(\text{min.}) + t_{SKH}(\text{min.})$ .

Figure 4 Timing Chart

NOT RECOMMENDED FOR NEW DESIGN



## ■ Initial Delivery State

Initial delivery state of all addresses is “FFFFh”.

## ■ Operation

All instructions are executed by inputting DI in synchronization with the rising edge of SK after CS goes high. An instruction set is input in the order of start bit, instruction, address, and data.

Instruction input finishes when CS goes low. A low level must be input to CS between commands during  $t_{\text{CDS}}$ . While a low level is being input to CS, the S-93C86B is in standby mode, so the SK and DI inputs are invalid and no instructions are allowed.

## ■ Start Bit

A start bit is recognized when the DI pin goes high at the rise of SK after CS goes high. After CS goes high, a start bit is not recognized even if the SK pulse is input as long as the DI pin is low.

### 1. Dummy clock

SK clocks input while the DI pin is low before a start bit is input are called dummy clocks. Dummy clocks are effective when aligning the number of instruction sets (clocks) sent by the CPU with those required for serial memory operation. For example, when a CPU instruction set is 16 bits, the number of instruction set clocks can be adjusted by inserting a 3-bit dummy clock for the S-93C86B.

### 2. Start bit input failure

- When the output status of the DO pin is high during the verify period after a write operation, if a high level is input to the DI pin at the rising edge of SK, the S-93C86B recognizes that a start bit has been input. To prevent this failure, input a low level to the DI pin during the verify operation period (refer to “4.1 Verify operation”).
- When a 3-wire interface is configured by connecting the DI input pin and DO output pin, a period in which the data output from the CPU and the serial memory collide may be generated, preventing successful input of the start bit. Take the measures described in “■ 3-Wire Interface (Direct Connection between DI and DO)”.

**3. Reading (READ)**

The READ instruction reads data from a specified address.

After CS has gone high, input an instruction in the order of the start bit, read instruction, and address. Since the last input address ( $A_0$ ) has been latched, the output status of the DO pin changes from high impedance (High-Z) to low, which is held until the next rise of SK. 16-bit data starts to be output in synchronization with the next rise of SK.

**3.1 Sequential read**

After the 16-bit data at the specified address has been output, inputting SK while CS is high automatically increments the address, and causes the 16-bit data at the next address to be output sequentially. The above method makes it possible to read the data in the whole memory space. The last address ( $A_9 \dots A_1 A_0 = 1 \dots 1 1$ ) rolls over to the top address ( $A_9 \dots A_1 A_0 = 0 \dots 0 0$ ).

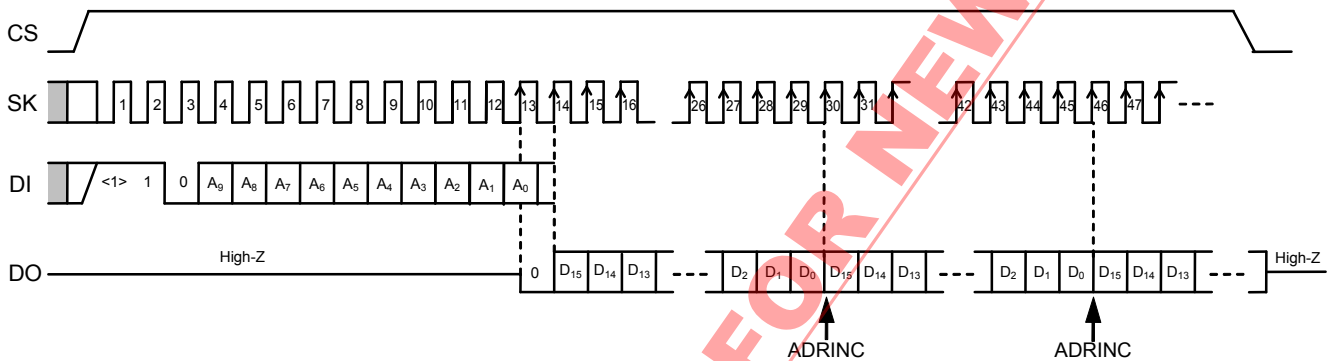


Figure 5 Read Timing

NOT RECOMMENDED FOR NEW DESIGN

#### 4. Writing (WRITE, ERASE, WRAL, ERAL)

A write operation includes four write instructions: data write (WRITE), data erase (ERASE), chip write (WRAL), and chip erase (ERAL).

A write instruction (WRITE, ERASE, WRAL, ERAL) starts a write operation to the memory cell when a low level is input to CS after a specified number of clocks have been input. The SK and DI inputs are invalid during the write period, so do not input an instruction.

Input an instruction while the output status of the DO pin is high or high impedance (High-Z).

A write operation is valid only in program enable mode (refer to "5. Write enable (EWEN) and write disable (EWDS)").

##### 4.1 Verify operation

A write operation executed by any instruction is completed within 4 ms (write time  $t_{PR}$ : typically 2 ms), so if the completion of the write operation is recognized, the write cycle can be minimized. A sequential operation to confirm the status of a write operation is called a verify operation.

##### 4.1.1 Operation

After the write operation has started (CS = low), the status of the write operation can be verified by confirming the output status of the DO pin by inputting a high level to CS again. This sequence is called a verify operation, and the period that a high level is input to the CS pin after the write operation has started is called the verify operation period.

The relationship between the output status of the DO pin and the write operation during the verify operation period is as follows.

- DO pin = low: Writing in progress (busy)
- DO pin = high: Writing completed (ready)

##### 4.1.2 Operation example

There are two methods to perform a verify operation: Waiting for a change in the output status of the DO pin while keeping CS high, or suspending the verify operation (CS = low) once and then performing it again to verify the output status of the DO pin. The latter method allows the CPU to perform other processing during the wait period, allowing an efficient system to be designed.

- Caution**
1. Input a low level to the DI pin during a verify operation.
  2. If a high level is input to the DI pin at the rise of SK when the output status of the DO pin is high, the S-93C86B latches the instruction assuming that a start bit has been input. In this case, note that the DO pin immediately enters a high-impedance (High-Z) state.

4.2 Writing data (WRITE)

To write 16-bit data to a specified address, change CS to high and then input the WRITE instruction, address, and 16-bit data following the start bit. The write operation starts when CS goes low. There is no need to set the data to 1 before writing. When the clocks more than the specified number have been input, the clock pulse monitoring circuit cancels the WRITE instruction. For details of the clock pulse monitoring circuit, refer to “■ Function to Protect Against Write due to Erroneous Instruction Recognition”.

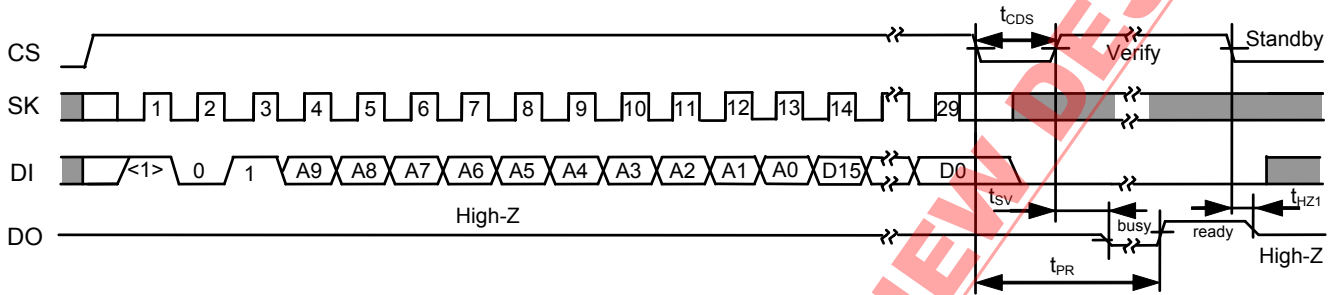


Figure 6 Data Write Timing

4.3 Erasing data (ERASE)

To erase 16-bit data at a specified address, set all 16 bits of the data to 1, change CS to high, and then input the ERASE instruction and address following the start bit. There is no need to input data. The data erase operation starts when CS goes low. When the clocks more than the specified number have been input, the clock pulse monitoring circuit cancels the ERASE instruction. For details of the clock pulse monitoring circuit, refer to “■ Function to Protect Against Write due to Erroneous Instruction Recognition”.

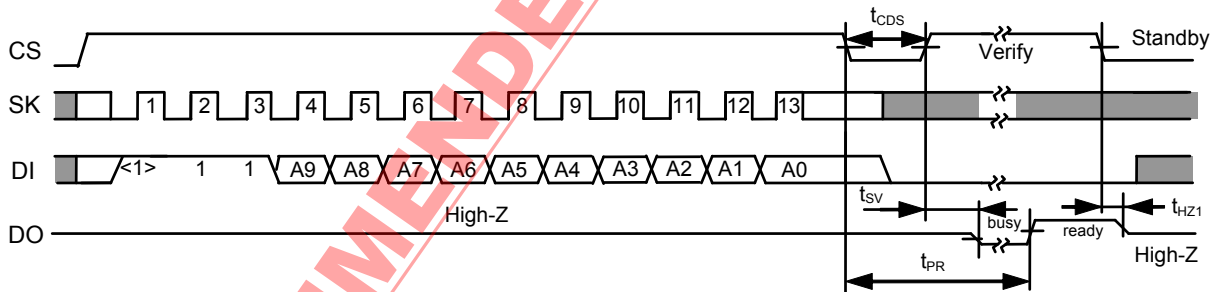


Figure 7 Data Erase Timing

**4.4 Writing to chip (WRAL)**

To write the same 16-bit data to the entire memory address space, change CS to high, and then input the WRAL instruction, an address, and 16-bit data following the start bit. Any address can be input. The write operation starts when CS goes low. There is no need to set the data to 1 before writing. When the clocks more than the specified number been input, the clock pulse monitoring circuit cancels the WRAL instruction. For details of the clock pulse monitoring circuit, refer to “**Function to Protect Against Write due to Erroneous Instruction Recognition**”.

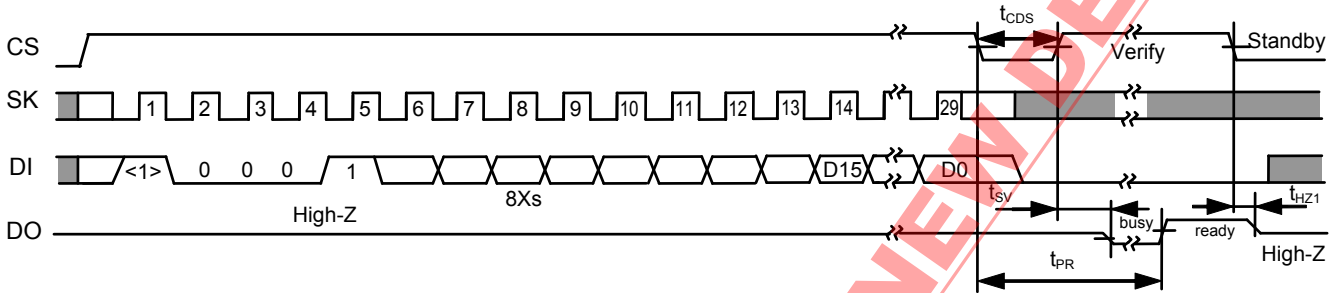


Figure 8 Chip Write Timing

**4.5 Erasing chip (ERAL)**

To erase the data of the entire memory address space, set all the data to 1, change CS to high, and then input the ERAL instruction and an address following the start bit. Any address can be input. There is no need to input data. The chips erase operation starts when CS goes low. When the clocks more than the specified number have been input, the clock pulse monitoring circuit cancels the ERAL instruction. For details of the clock pulse monitoring circuit, refer to “**Function to Protect Against Write due to Erroneous Instruction Recognition**”.

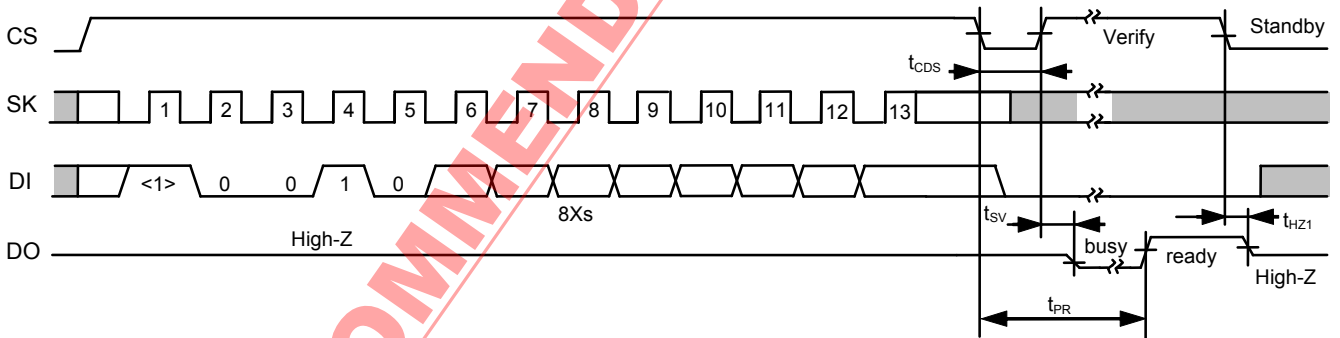


Figure 9 Chip Erase Timing

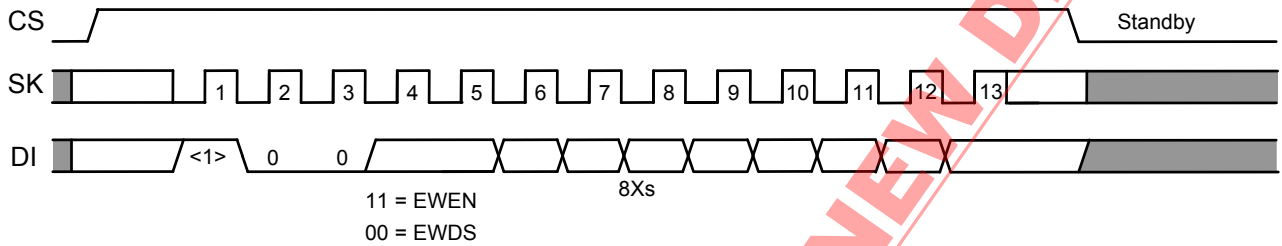
NOT RECOMMENDED FOR NEW DESIGNS

**5. Write enable (EWEN) and write disable (EWDS)**

The EWEN instruction is an instruction that enables a write operation. The status in which a write operation is enabled is called the program enable mode.

The EWDS instruction is an instruction that disables a write operation. The status in which a write operation is disabled is called the program disable mode.

After CS goes high, input an instruction in the order of the start bit, EWEN or EWDS instruction, and address (optional). Each mode becomes valid by inputting a low level to CS after the last address (optional) has been input.



**Figure 10 Write Enable/Disable Timing**

**5.1 Recommendation for write operation disable instruction**

It is recommended to implement a design that prevents an incorrect write operation when a write instruction is erroneously recognized by executing the write operation disable instruction when executing instructions other than write instruction, and immediately after power-on and before power off.

NOT RECOMMENDED FOR NEW DESIGN

### ■ Write Protect Function during the Low Power Supply Voltage

The S-93C86B provides a built-in detector. When the power supply voltage is low or at power application, the write instructions (WRITE, ERASE, WRAL, and ERAL) are cancelled, and the write disable state (EWDS) is automatically set. The detection voltage is 1.75 V typ., the release voltage is 2.05 V typ., and there is a hysteresis of about 0.3 V (refer to **Figure 11**). Therefore, when a write operation is performed after the power supply voltage has dropped and then risen again up to the level at which writing is possible, a write enable instruction (EWEN) must be sent before a write instruction (WRITE, ERASE, WRAL, or ERAL) is executed.

When the power supply voltage drops during a write operation, the data being written to an address at that time is not guaranteed.

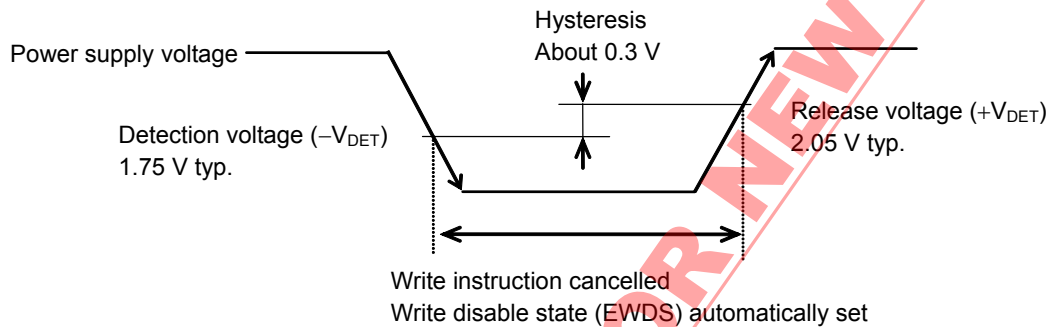


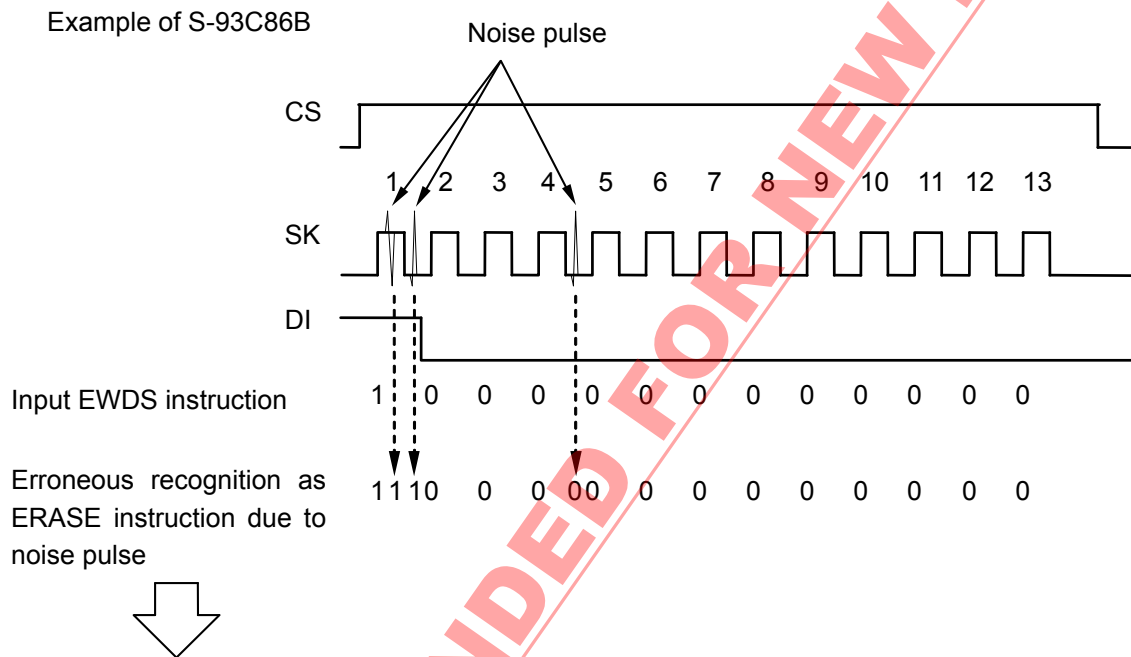
Figure 11 Operation during Low Power Supply Voltage

NOT RECOMMENDED FOR NEW DESIGN

■ Function to Protect Against Write due to Erroneous Instruction Recognition

The S-93C86B provides a built-in clock pulse monitoring circuit which is used to prevent an erroneous write operation by canceling write instructions (WRITE, ERASE, WRAL, and ERAL) recognized erroneously due to an erroneous clock count caused by the application of noise pulses or double counting of clocks. Instructions are cancelled if a clock pulse whose count other than the one specified for each write instruction (WRITE, ERASE, WRAL, or ERAL) is detected.

<Example> Erroneous recognition of program disable instruction (EWDS) as erase instruction (ERASE)



In products that do not incorporate a clock pulse monitoring circuit, FFFFh is mistakenly written to address 00h. However the S-93C86B detects the over count and cancels the instruction without performing a write operation.

Figure 12 Example of Clock Pulse Monitoring Circuit Operation



### ■ 3-Wire Interface (Direct Connection between DI and DO)

There are two types of serial interface configurations: a 4-wire interface configured using the CS, SK, DI, and DO pins, and a 3-wire interface that connects the DI input pin and DO output pin.

When the 3-wire interface is employed, a period in which the data output from the CPU and the data output from the serial memory collide may occur, causing a malfunction. To prevent such a malfunction, connect the DI and DO pins of the S-93C86B via a resistor (10 kΩ to 100 kΩ) so that the data output from the CPU takes precedence in being input to the DI pin (refer to "Figure 13 Connection of 3-Wire Interface").

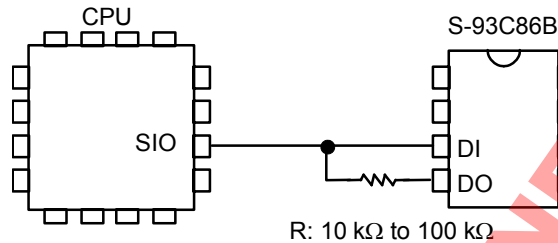


Figure 13 Connection of 3-Wire Interface

### ■ Input Pin and Output Pin

#### 1. Connection of input pins

All the input pins of the S-93C86B employ a CMOS structure, so design the equipment so that high impedance will not be input while the S-93C86B is operating. Especially, deselect the CS input (a low level) when turning on / off power and during standby. When the CS pin is deselected (a low level), incorrect data writing will not occur. Connect the CS pin to GND via a resistor (10 kΩ to 100 kΩ pull-down resistor). To prevent malfunction, it is recommended to use equivalent pull-down resistors for pins other than the CS pin.

#### 2. Equivalent circuit of input pin and output pin

The following shows the equivalent circuits of input pins of the S-93C86B. None of the input pins incorporate pull-up and pull-down elements, so special care must be taken when designing to prevent a floating status.

Output pins are high-level / low-level / high-impedance tri-state outputs. The TEST pin is disconnected from the internal circuit by a switching transistor during normal operation. As long as the absolute maximum rating is satisfied, the TEST pin and internal circuit will never be connected.

2.1 Input pin

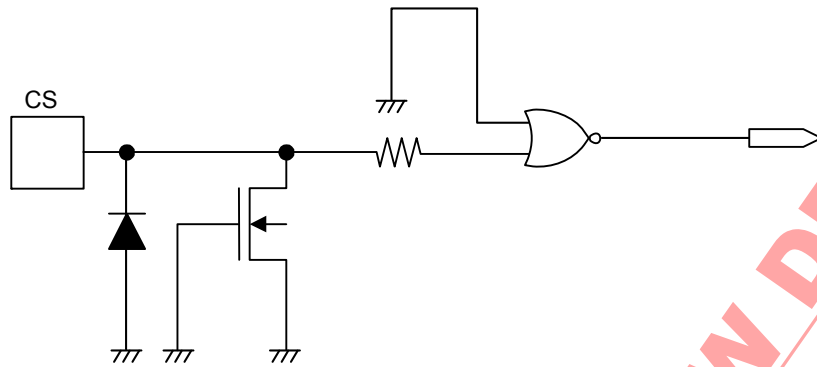


Figure 14 CS Pin

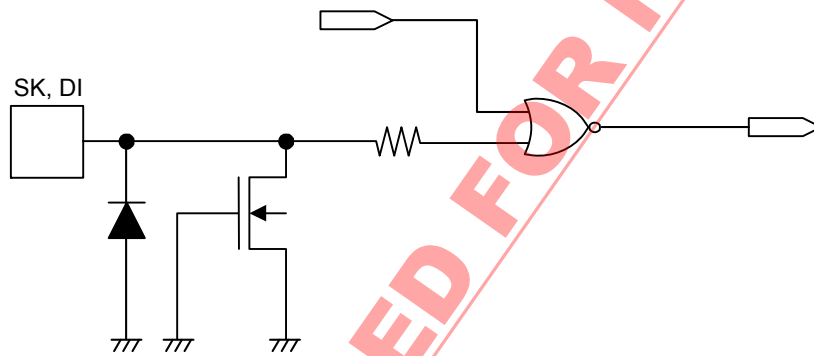


Figure 15 SK, DI Pin

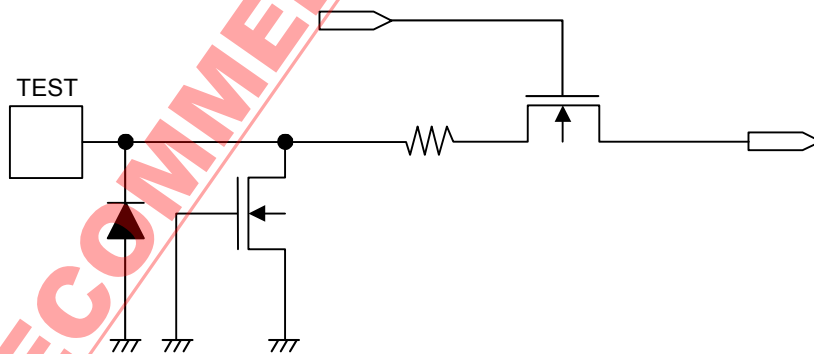


Figure 16 TEST Pin

NOT RECOMMENDED FOR NEW DESIGN

## 2.2 Output pin

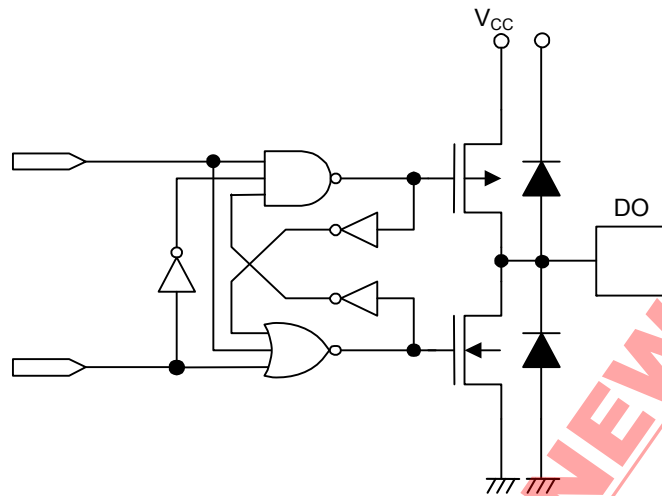


Figure 17 DO Pin

## 3. Input pin noise elimination time

The S-93C86B includes a built-in low-pass filter to eliminate noise at the SK, DI, and CS pins. This means that if the supply voltage is 5.0 V (at room temperature), noise with a pulse width of 20 ns or less can be eliminated.

Note, therefore, that noise with a pulse width of more than 20 ns will be recognized as a pulse if the voltage exceeds  $V_{IH} / V_{IL}$ .

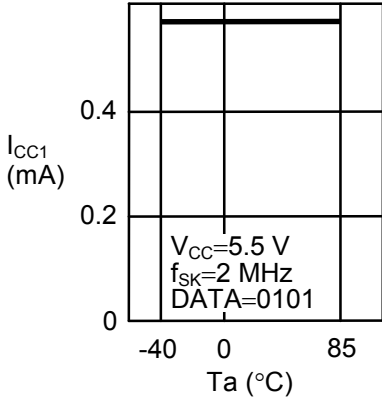
### ■ Precaution

- Do not apply an electrostatic discharge to this IC that exceeds the performance ratings of the built-in electrostatic protection circuit.
- ABLIC Inc. claims no responsibility for any and all disputes arising out of or in connection with any infringement of the products including this IC upon patents owned by a third party.

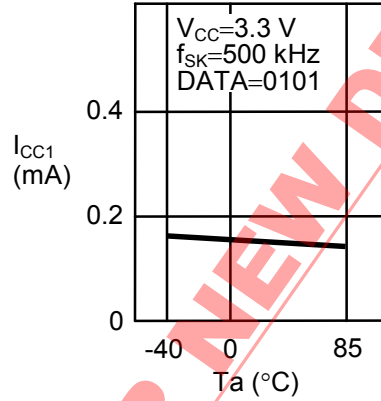
■ Characteristics (Typical Data)

1. DC Characteristics

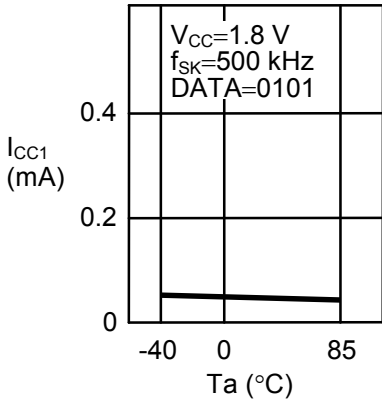
1.1 Current consumption (READ)  $I_{CC1}$  vs. ambient temperature  $T_a$



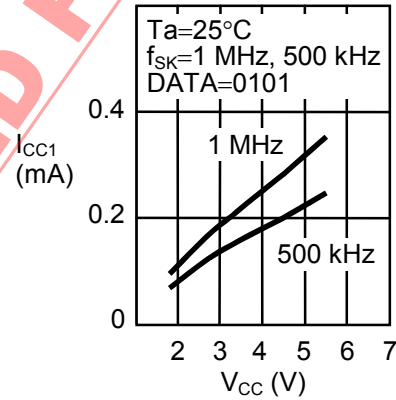
1.2 Current consumption (READ)  $I_{CC1}$  vs. ambient temperature  $T_a$



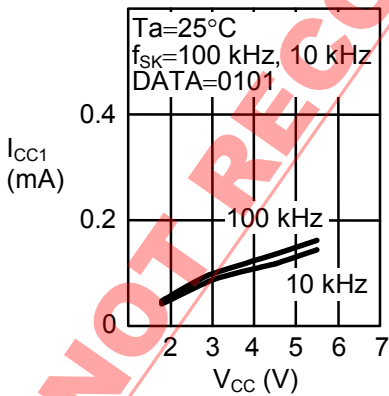
1.3 Current consumption (READ)  $I_{CC1}$  vs. ambient temperature  $T_a$



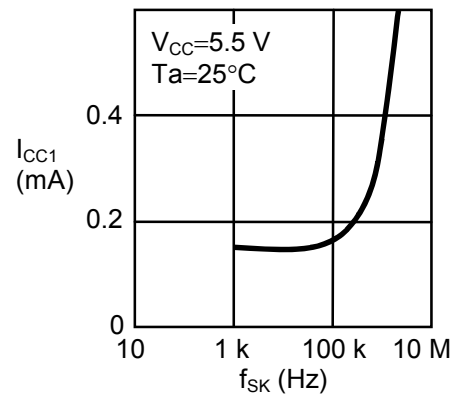
1.4 Current consumption (READ)  $I_{CC1}$  vs. power supply voltage  $V_{CC}$



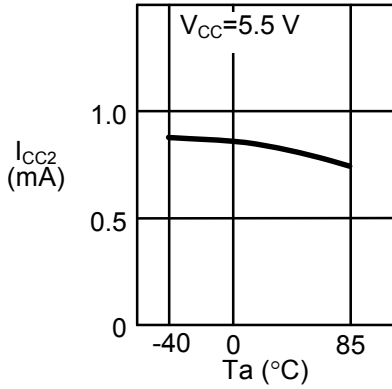
1.5 Current consumption (READ)  $I_{CC1}$  vs. power supply voltage  $V_{CC}$



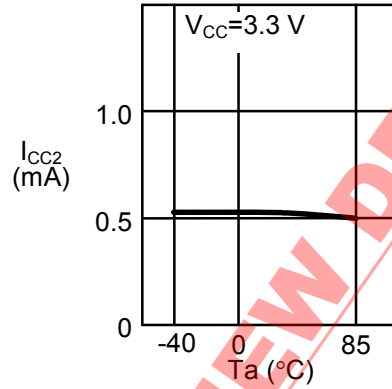
1.6 Current consumption (READ)  $I_{CC1}$  vs. Clock frequency  $f_{SK}$



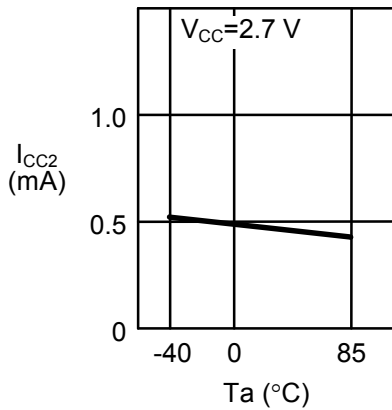
1. 7 Current consumption (WRITE)  $I_{CC2}$   
vs. ambient temperature  $T_a$



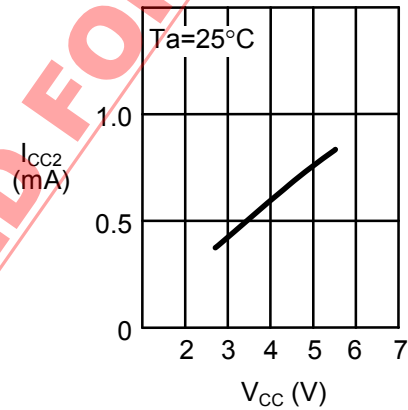
1. 8 Current consumption (WRITE)  $I_{CC2}$   
vs. ambient temperature  $T_a$



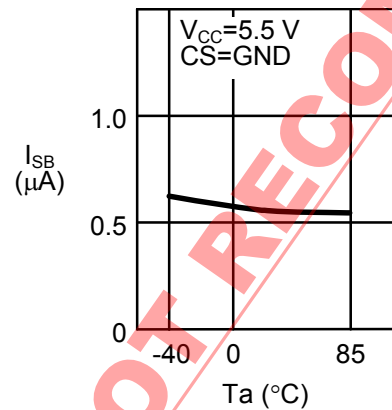
1. 9 Current consumption (WRITE)  $I_{CC2}$   
vs. ambient temperature  $T_a$



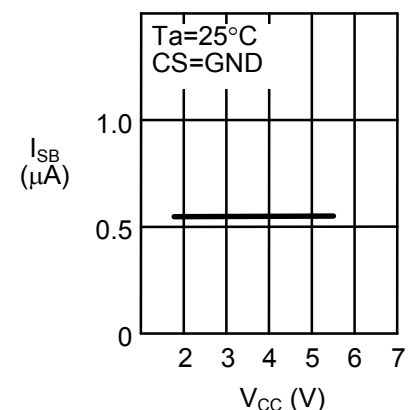
1. 10 Current consumption (WRITE)  $I_{CC2}$   
vs. power supply voltage  $V_{CC}$



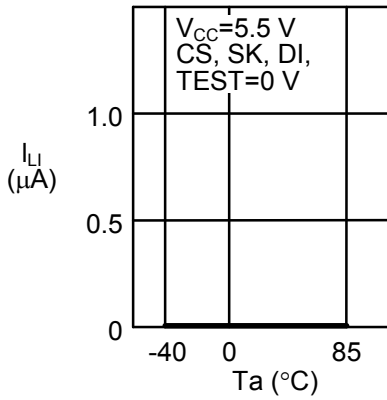
1. 11 Current consumption in standby mode  $I_{SB}$   
vs. ambient temperature  $T_a$



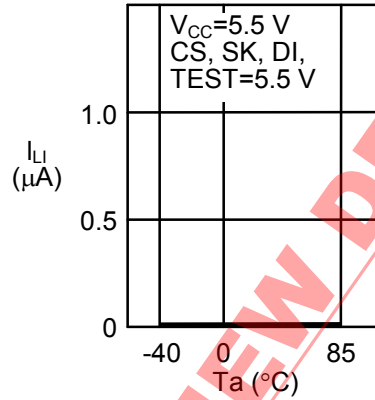
1. 12 Current consumption in standby mode  $I_{SB}$   
vs. power supply voltage  $V_{CC}$



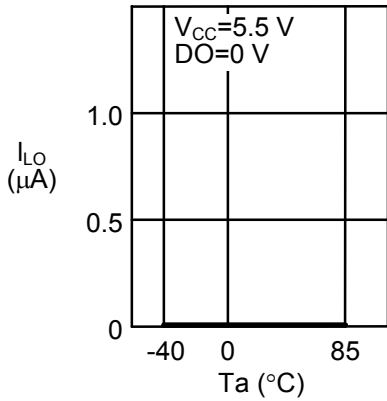
1. 13 Input leakage current  $I_{LI}$   
vs. ambient temperature  $T_a$



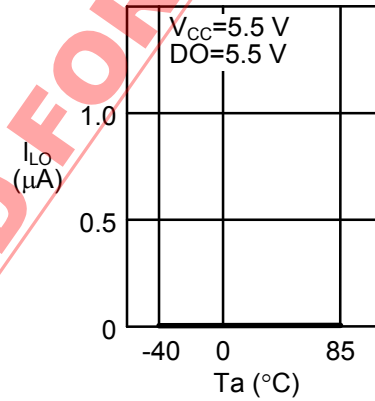
1. 14 Input leakage current  $I_{LI}$   
vs. ambient temperature  $T_a$



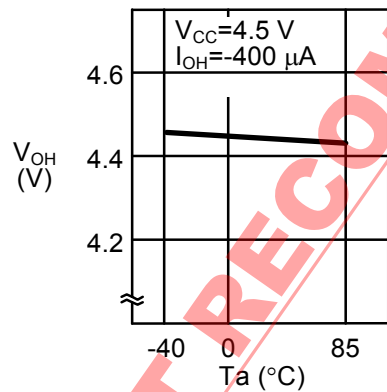
1. 15 Output leakage current  $I_{LO}$   
vs. ambient temperature  $T_a$



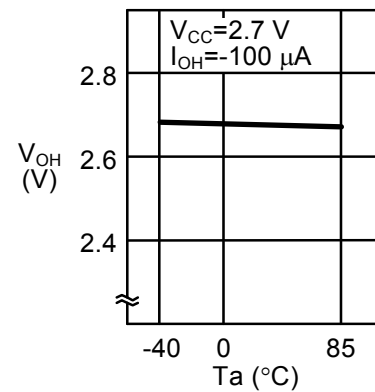
1. 16 Output leakage current  $I_{LO}$   
vs. ambient temperature  $T_a$



1. 17 High-level output voltage  $V_{OH}$   
vs. ambient temperature  $T_a$

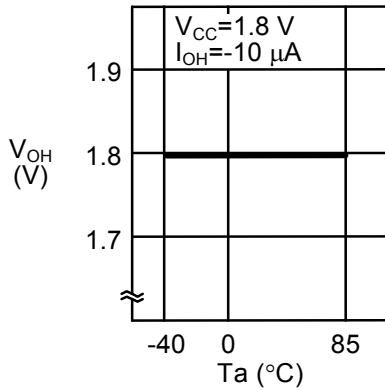


1. 18 High-level output voltage  $V_{OH}$   
vs. ambient temperature  $T_a$

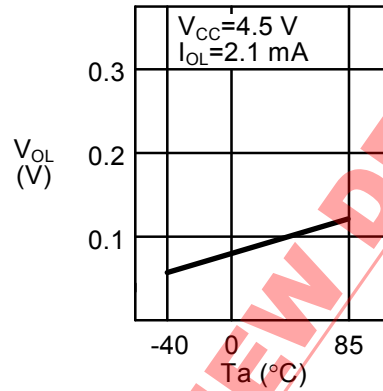


NOT RECOMMENDED FOR NEW DESIGN

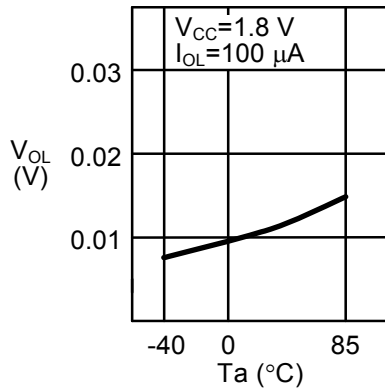
1. 19 High-level output voltage  $V_{OH}$  vs. ambient temperature  $T_a$



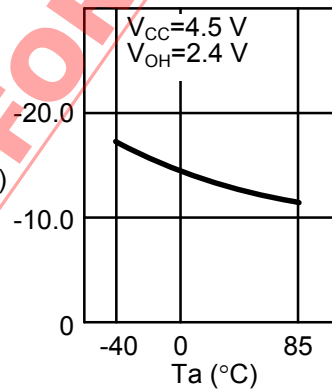
1. 20 Low-level output voltage  $V_{OL}$  vs. ambient temperature  $T_a$



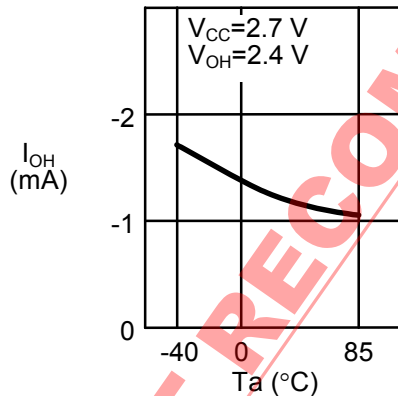
1. 21 Low-level output voltage  $V_{OL}$  vs. ambient temperature  $T_a$



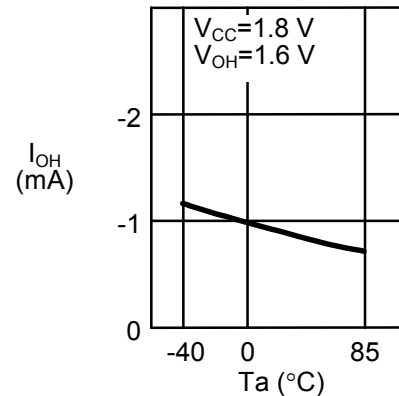
1. 22 High-level output current  $I_{OH}$  vs. ambient temperature  $T_a$



1. 23 High-level output current  $I_{OH}$  vs. ambient temperature  $T_a$

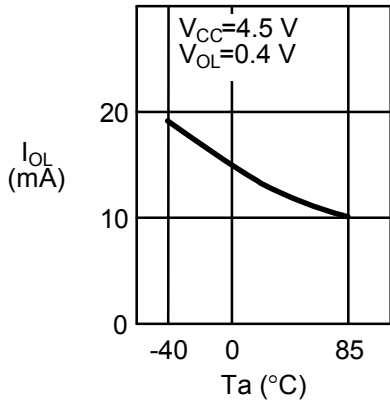


1. 24 High-level output current  $I_{OH}$  vs. ambient temperature  $T_a$

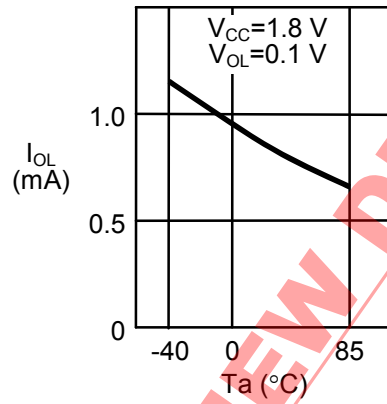


NOT RECOMMENDED FOR NEW DESIGN

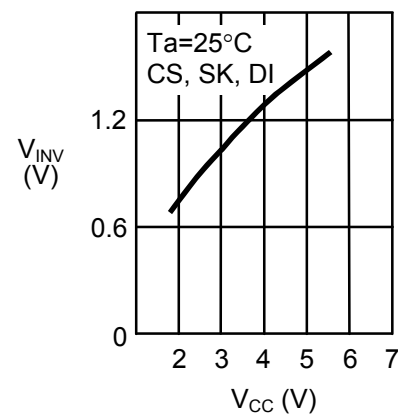
1. 25 Low-level output current  $I_{OL}$   
vs. ambient temperature  $T_a$



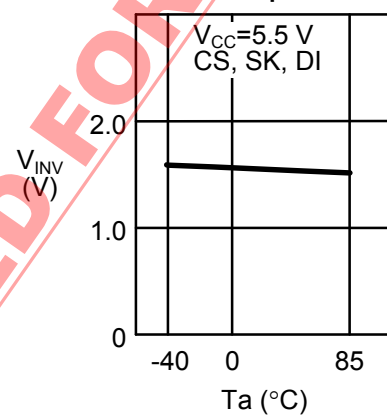
1. 26 Low-level output current  $I_{OL}$   
vs. ambient temperature  $T_a$



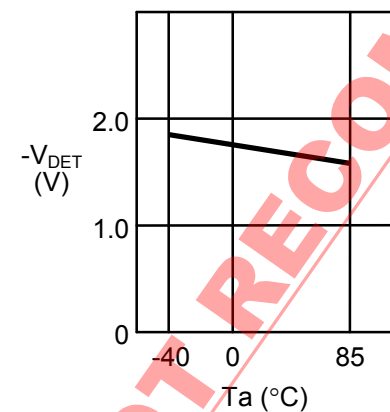
1. 27 Input inverted voltage  $V_{INV}$   
vs. power supply voltage  $V_{CC}$



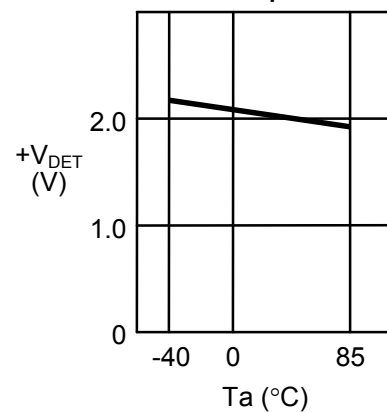
1. 28 Input inverted voltage  $V_{INV}$   
vs. ambient temperature  $T_a$



1. 29 Low supply voltage detection voltage  $-V_{DET}$   
vs. ambient temperature  $T_a$



1. 30 Low supply voltage release voltage  $+V_{DET}$   
vs. ambient temperature  $T_a$

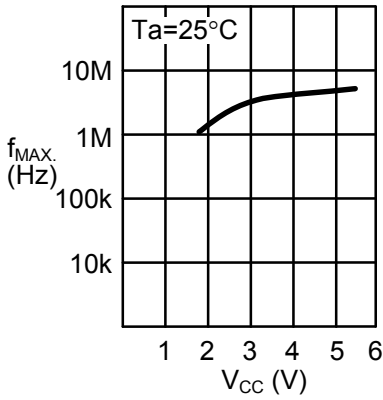


NOT RECOMMENDED FOR NEW DESIGN

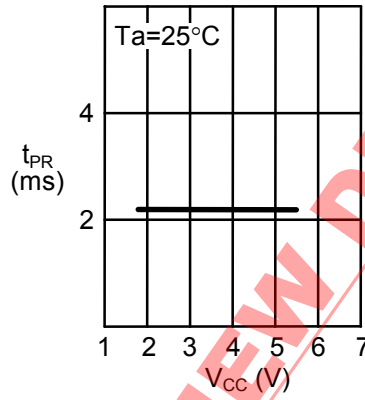


2. AC Characteristics

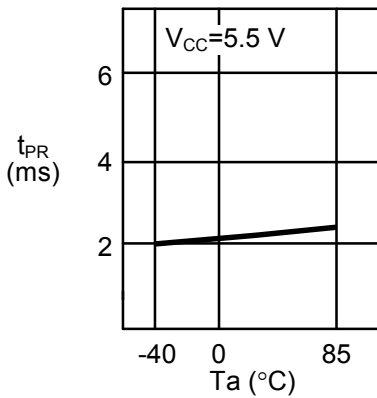
2.1 Maximum operating frequency  $f_{MAX}$ .  
vs. power supply voltage  $V_{CC}$



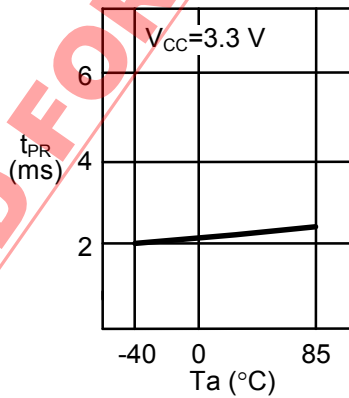
2.2 Write time  $t_{PR}$   
vs. power supply voltage  $V_{CC}$



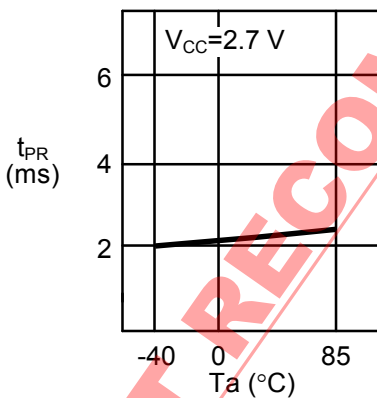
2.3 Write time  $t_{PR}$   
vs. ambient temperature  $T_a$



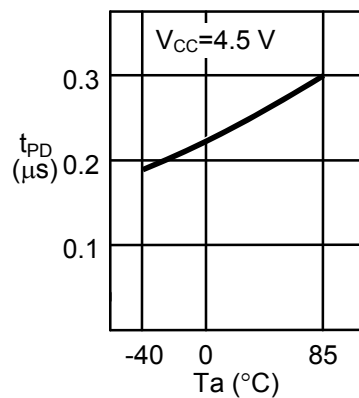
2.4 Write time  $t_{PR}$   
vs. ambient temperature  $T_a$



2.5 Write time  $t_{PR}$   
vs. ambient temperature  $T_a$

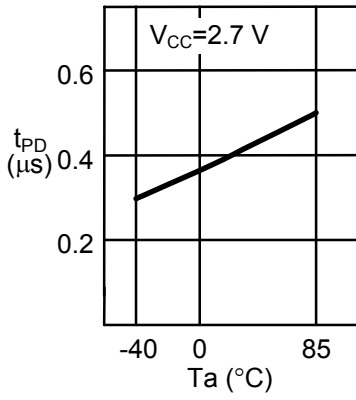


2.6 Data output delay time  $t_{PD}$   
vs. ambient temperature  $T_a$

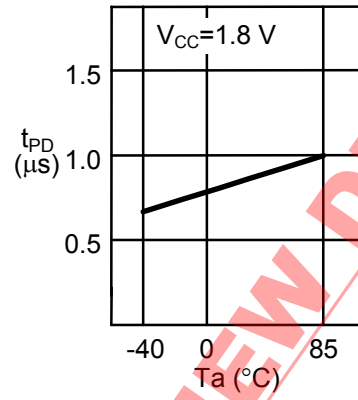


NOT RECOMMENDED FOR NEW DESIGN

2.7 Data output delay time  $t_{PD}$   
vs. ambient temperature  $T_a$



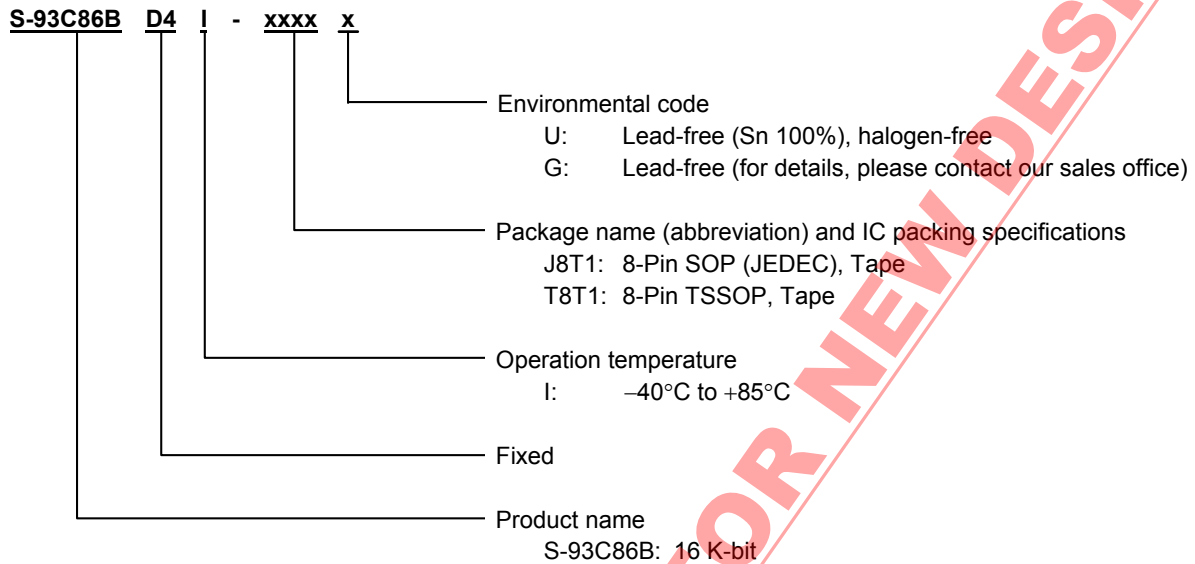
2.8 Data output delay time  $t_{PD}$   
vs. ambient temperature  $T_a$



**NOT RECOMMENDED FOR NEW DESIGN**

■ Product Name Structure

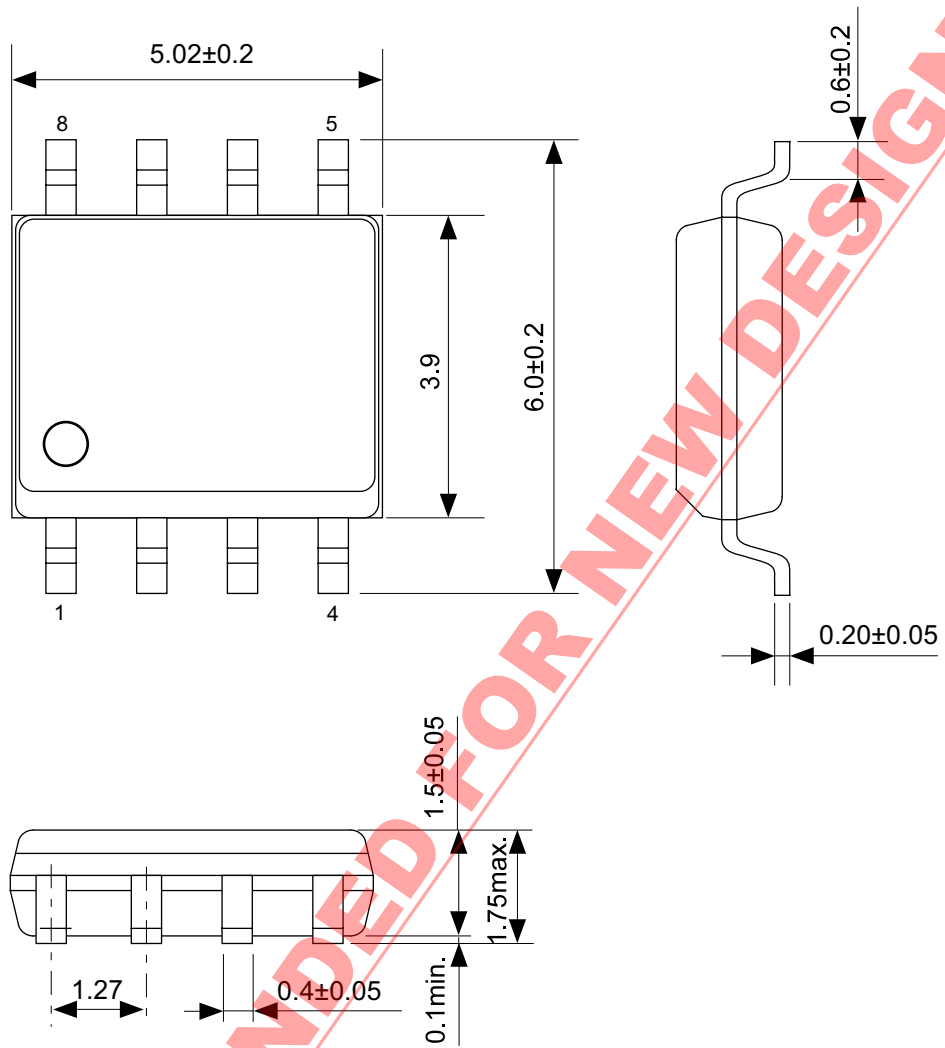
1. Product name



2. Packages

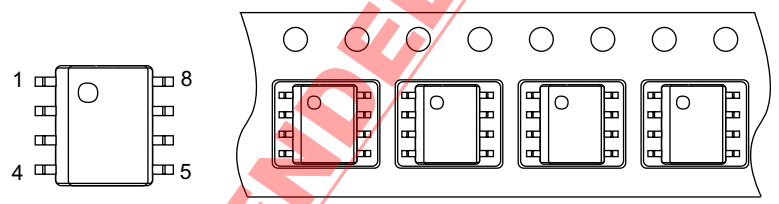
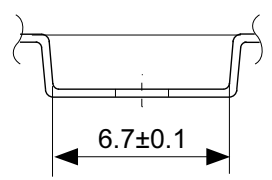
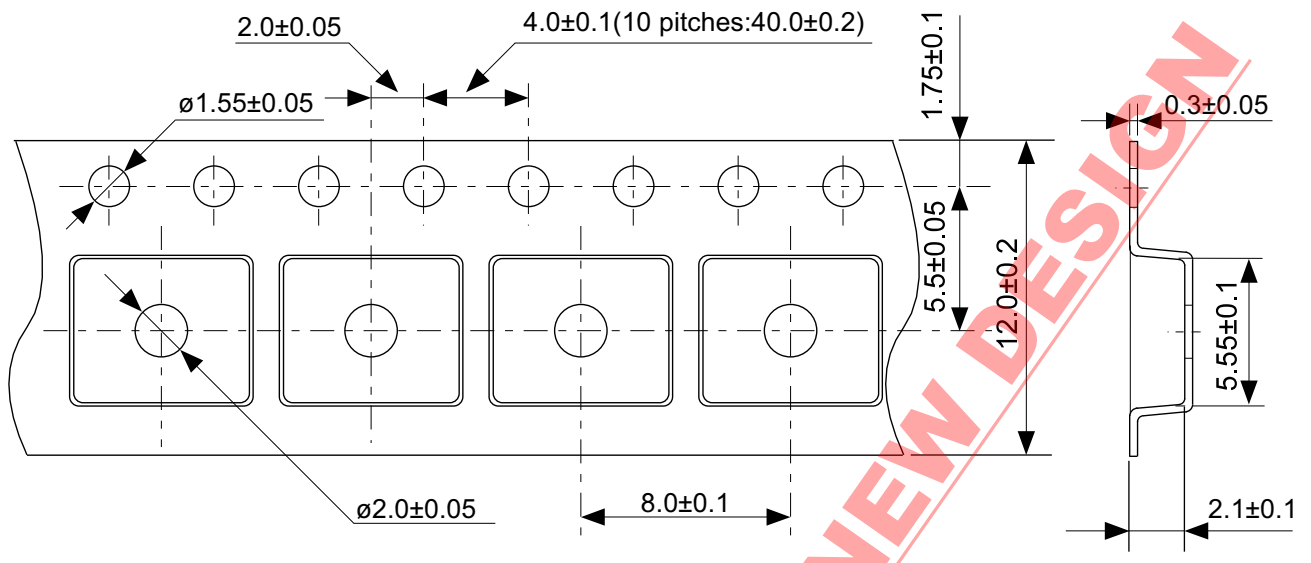
Package Name		Drawing Code		
		Package	Tape	Reel
8-Pin SOP (JEDEC)	Environmental code = G	FJ008-A-P-SD	FJ008-D-C-SD	FJ008-D-R-SD
	Environmental code = U	FJ008-A-P-SD	FJ008-D-C-SD	FJ008-D-R-S1
8-Pin TSSOP	Environmental code = G	FT008-A-P-SD	FT008-E-C-SD	FT008-E-R-SD
	Environmental code = U	FT008-A-P-SD	FT008-E-C-SD	FT008-E-R-S1

NOT RECOMMENDED FOR NEW DESIGN



No. FJ008-A-P-SD-2.2

TITLE	SOP8J-D-PKG Dimensions
No.	FJ008-A-P-SD-2.2
ANGLE	
UNIT	mm
<b>ABLIC Inc.</b>	



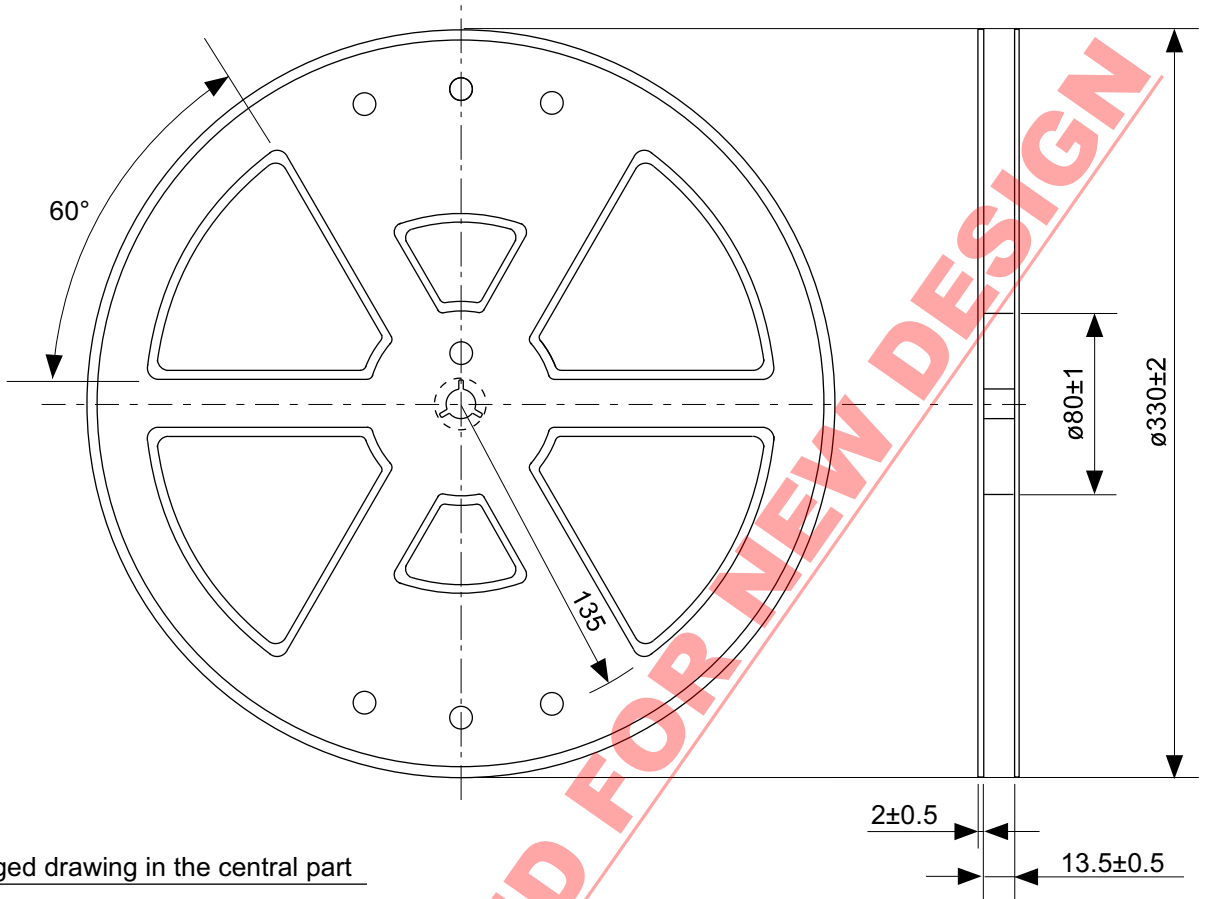
→  
Feed direction

No. FJ008-D-C-SD-1.1

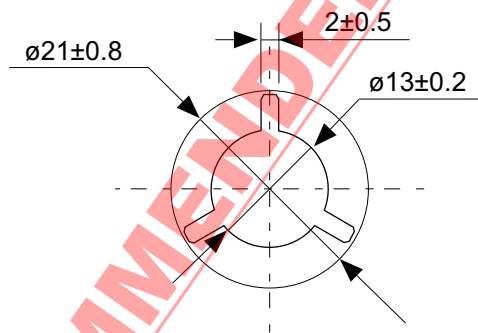
NOT RECOMMENDED FOR NEW DESIGN

TITLE	SOP8J-D-Carrier Tape
No.	FJ008-D-C-SD-1.1
ANGLE	
UNIT	mm

**ABLIC Inc.**



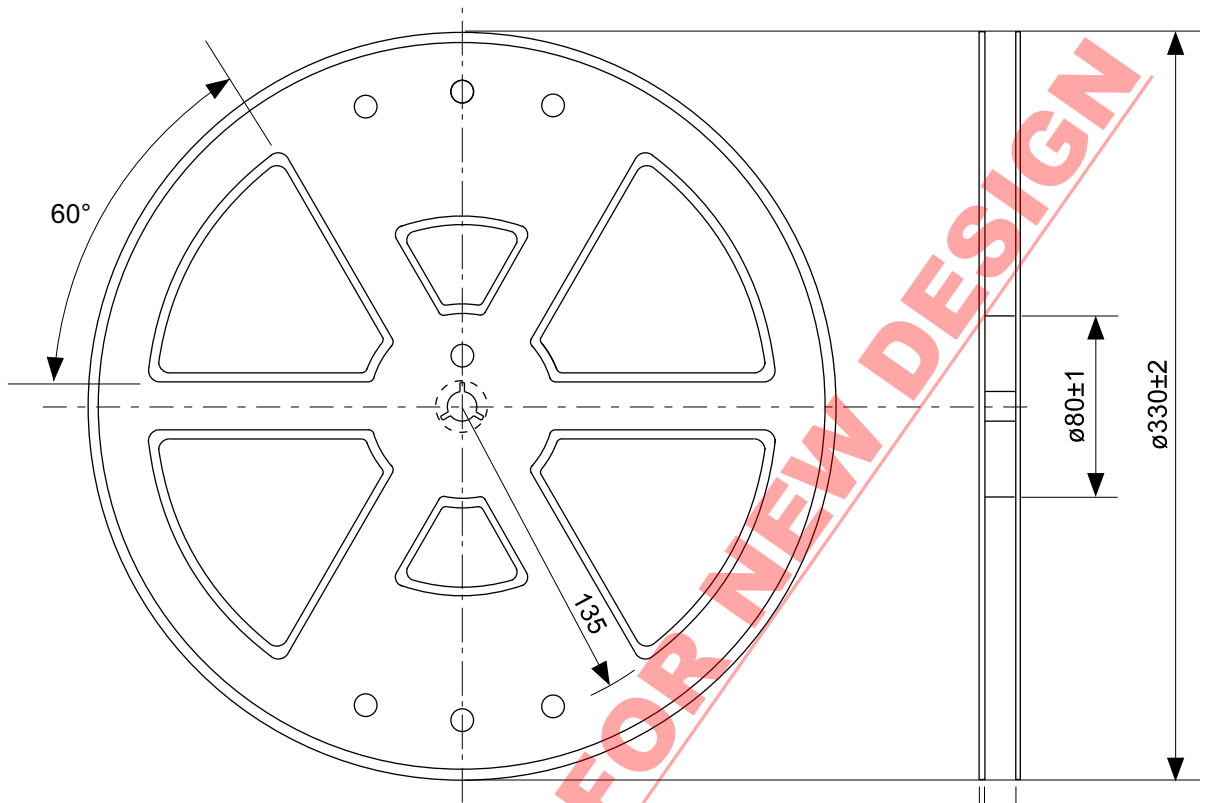
Enlarged drawing in the central part



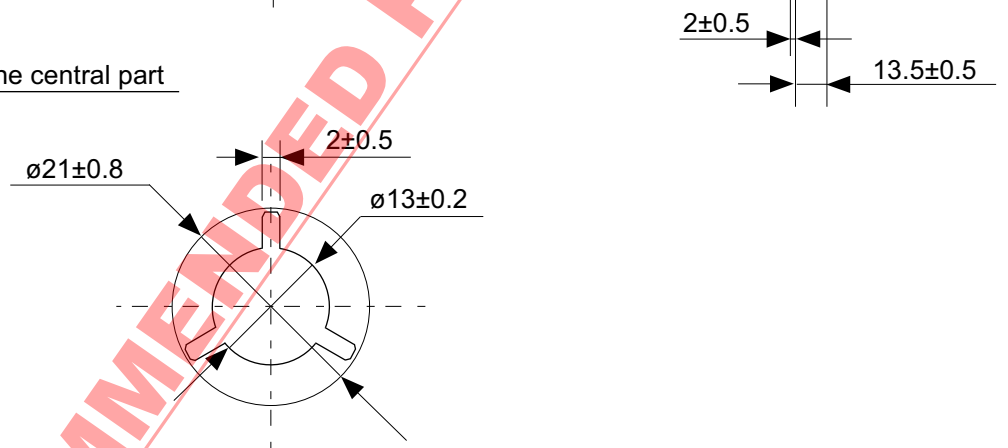
No. FJ008-D-R-SD-1.1

TITLE	SOP8J-D-Reel		
No.	FJ008-D-R-SD-1.1		
ANGLE		QTY.	2,000
UNIT	mm		
<b>ABLIC Inc.</b>			

NOT RECOMMENDED FOR NEW DESIGN



Enlarged drawing in the central part

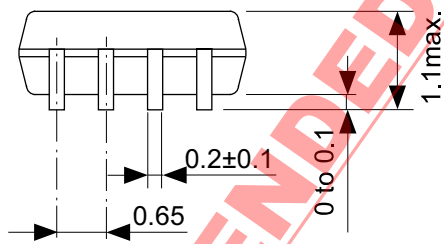
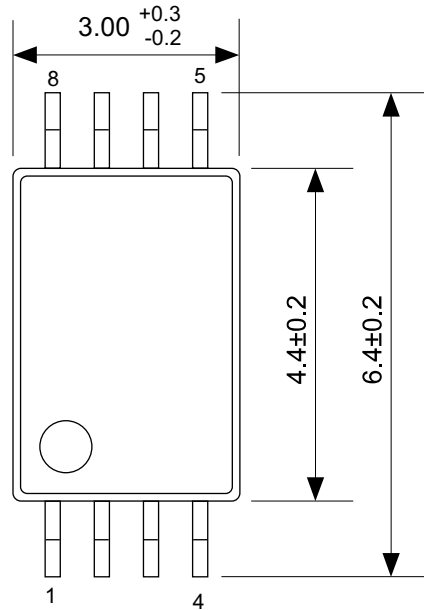


No. FJ008-D-R-S1-1.0

TITLE	SOP8J-D-Reel		
No.	FJ008-D-R-S1-1.0		
ANGLE		QTY.	4,000
UNIT	mm		
<b>ABLIC Inc.</b>			

**NOT RECOMMENDED FOR NEW DESIGN**

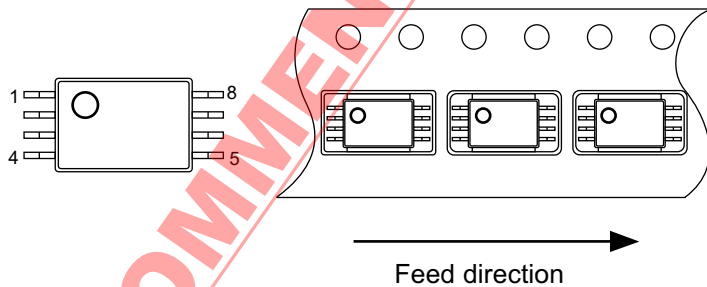
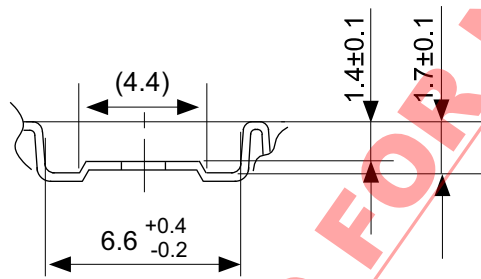
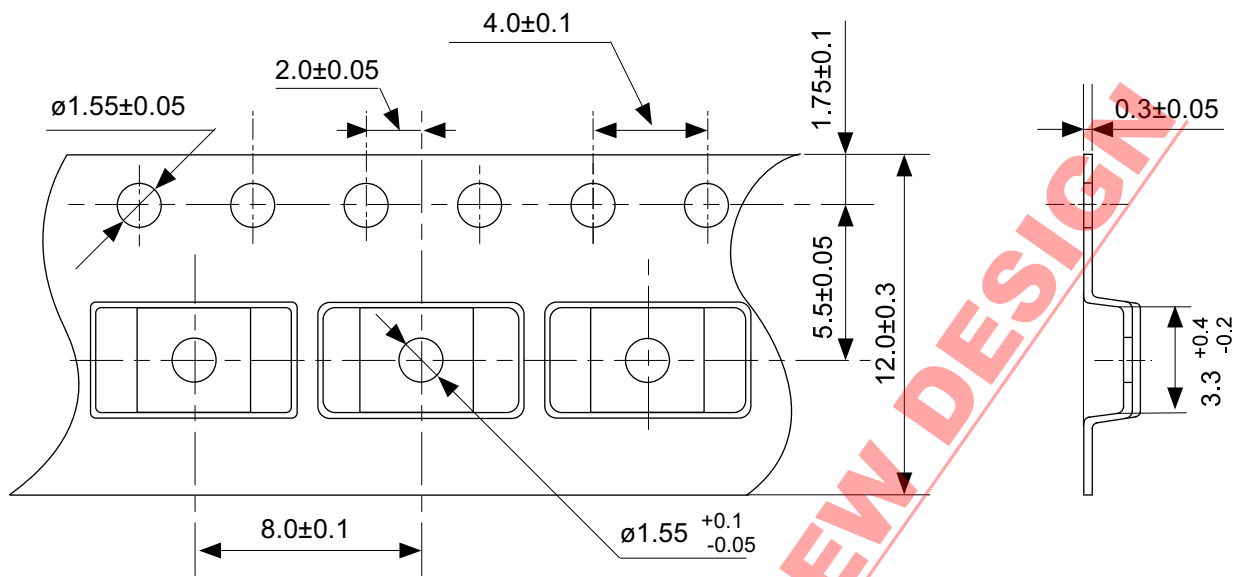
**NOT RECOMMENDED FOR NEW DESIGN**



No. FT008-A-P-SD-1.2

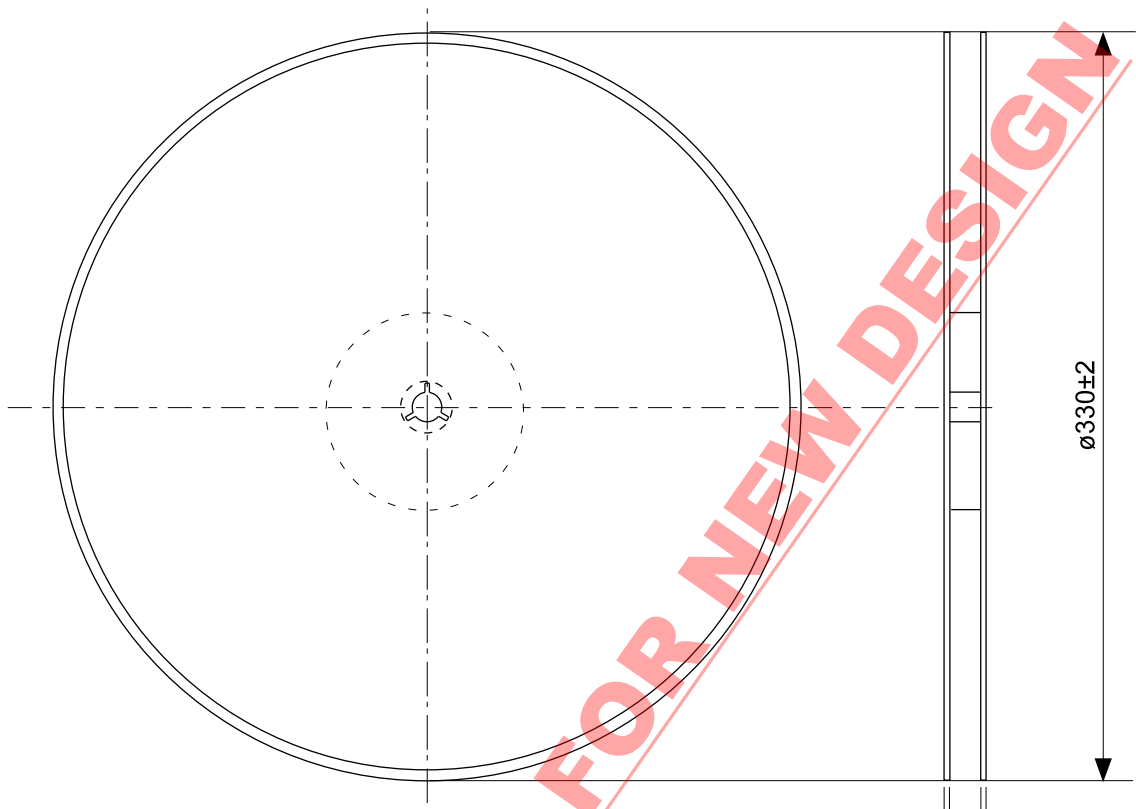
TITLE	TSSOP8-E-PKG Dimensions
No.	FT008-A-P-SD-1.2
ANGLE	
UNIT	mm
<b>ABLIC Inc.</b>	



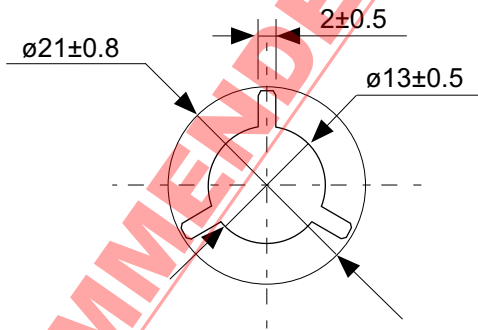


No. FT008-E-C-SD-1.0

TITLE	TSSOP8-E-Carrier Tape
No.	FT008-E-C-SD-1.0
ANGLE	
UNIT	mm
<b>ABLIC Inc.</b>	



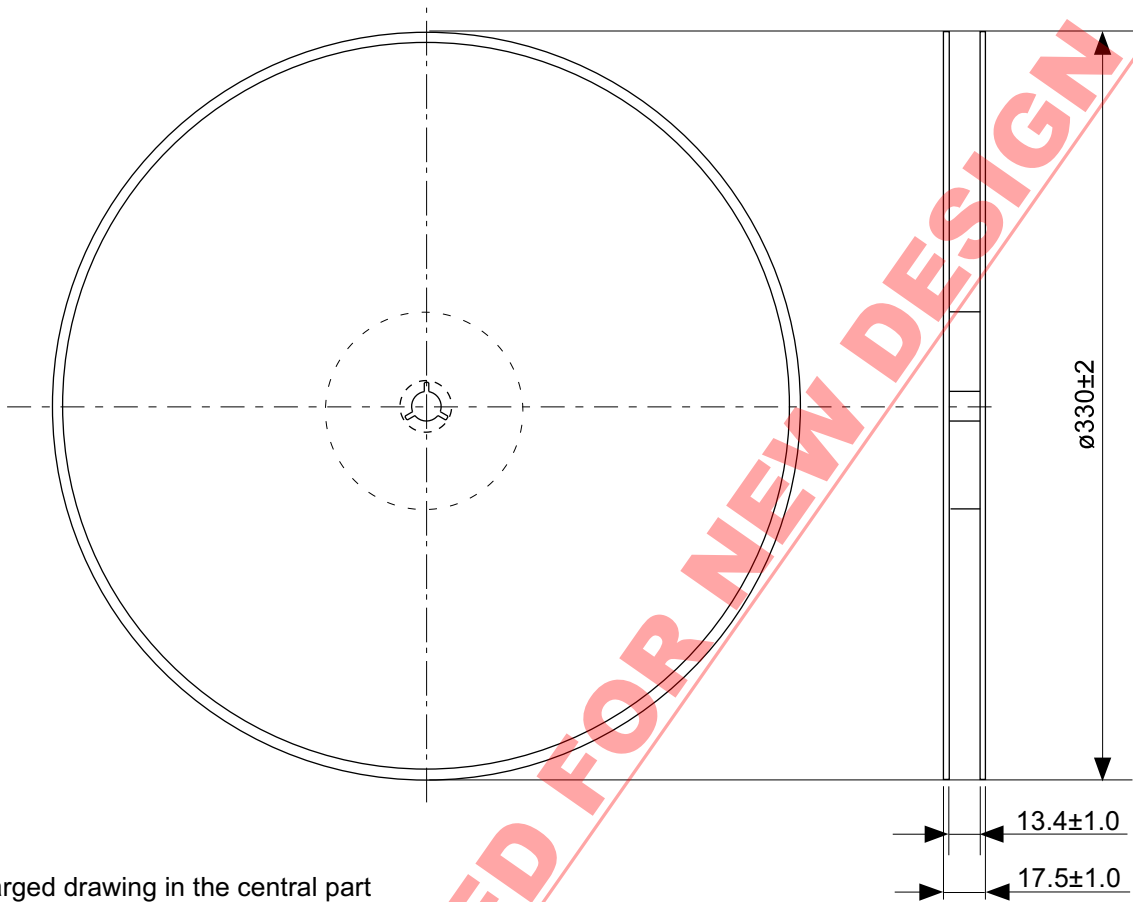
Enlarged drawing in the central part



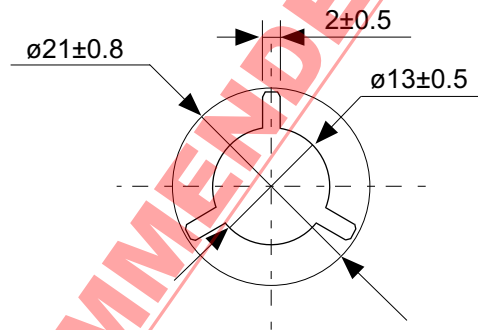
No. FT008-E-R-SD-1.0

TITLE	TSSOP8-E-Reel		
No.	FT008-E-R-SD-1.0		
ANGLE		QTY.	3,000
UNIT	mm		
<b>ABLIC Inc.</b>			

NOT RECOMMENDED FOR NEW DESIGN



Enlarged drawing in the central part



No. FT008-E-R-S1-1.0

TITLE	TSSOP8-E-Reel		
No.	FT008-E-R-S1-1.0		
ANGLE		QTY.	4,000
UNIT	mm		
<b>ABLIC Inc.</b>			

NOT RECOMMENDED FOR NEW DESIGN

## Disclaimers (Handling Precautions)

1. All the information described herein (product data, specifications, figures, tables, programs, algorithms and application circuit examples, etc.) is current as of publishing date of this document and is subject to change without notice.
2. The circuit examples and the usages described herein are for reference only, and do not guarantee the success of any specific mass-production design.  
ABLIC Inc. is not responsible for damages caused by the reasons other than the products described herein (hereinafter "the products") or infringement of third-party intellectual property right and any other right due to the use of the information described herein.
3. ABLIC Inc. is not responsible for damages caused by the incorrect information described herein.
4. Be careful to use the products within their specified ranges. Pay special attention to the absolute maximum ratings, operation voltage range and electrical characteristics, etc.  
ABLIC Inc. is not responsible for damages caused by failures and / or accidents, etc. that occur due to the use of the products outside their specified ranges.
5. When using the products, confirm their applications, and the laws and regulations of the region or country where they are used and verify suitability, safety and other factors for the intended use.
6. When exporting the products, comply with the Foreign Exchange and Foreign Trade Act and all other export-related laws, and follow the required procedures.
7. The products must not be used or provided (exported) for the purposes of the development of weapons of mass destruction or military use. ABLIC Inc. is not responsible for any provision (export) to those whose purpose is to develop, manufacture, use or store nuclear, biological or chemical weapons, missiles, or other military use.
8. The products are not designed to be used as part of any device or equipment that may affect the human body, human life, or assets (such as medical equipment, disaster prevention systems, security systems, combustion control systems, infrastructure control systems, vehicle equipment, traffic systems, in-vehicle equipment, aviation equipment, aerospace equipment, and nuclear-related equipment), excluding when specified for in-vehicle use or other uses. Do not apply the products to the above listed devices and equipments without prior written permission by ABLIC Inc. Especially, the products cannot be used for life support devices, devices implanted in the human body and devices that directly affect human life, etc.  
Prior consultation with our sales office is required when considering the above uses.  
ABLIC Inc. is not responsible for damages caused by unauthorized or unspecified use of our products.
9. Semiconductor products may fail or malfunction with some probability.  
The user of the products should therefore take responsibility to give thorough consideration to safety design including redundancy, fire spread prevention measures, and malfunction prevention to prevent accidents causing injury or death, fires and social damage, etc. that may ensue from the products' failure or malfunction.  
The entire system must be sufficiently evaluated and applied on customer's own responsibility.
10. The products are not designed to be radiation-proof. The necessary radiation measures should be taken in the product design by the customer depending on the intended use.
11. The products do not affect human health under normal use. However, they contain chemical substances and heavy metals and should therefore not be put in the mouth. The fracture surfaces of wafers and chips may be sharp. Be careful when handling these with the bare hands to prevent injuries, etc.
12. When disposing of the products, comply with the laws and ordinances of the country or region where they are used.
13. The information described herein contains copyright information and know-how of ABLIC Inc.  
The information described herein does not convey any license under any intellectual property rights or any other rights belonging to ABLIC Inc. or a third party. Reproduction or copying of the information from this document or any part of this document described herein for the purpose of disclosing it to a third-party without the express permission of ABLIC Inc. is strictly prohibited.
14. For more details on the information described herein, contact our sales office.

2.0-2018.01