PrimeSTACK™

## 2PS13512E43W39689



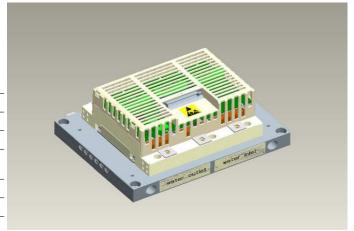
### **Preliminary data**

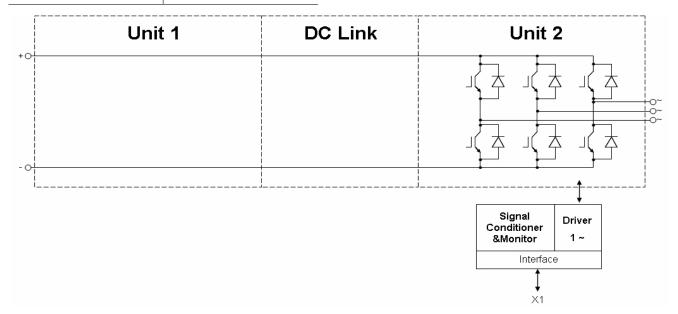
### **General information**

### IGBT Stack for typical voltages of up to 400 $V_{\text{RMS}}$ Rated output current 900 A<sub>RMS</sub>

- · Solar power · Motor drives
- · High power converter
- $\begin{array}{l} \cdot \ 62mm \ power \ module \\ \cdot \ Trenchstop^{\text{TM}} \ IGBT4 \end{array}$

Topology	1/2 B2I
Application	Inverter
Load type	resitive, indutive
Semiconductor (Inverter Section)	3x FF450R12KE4
Heatsink	water cooled
Implemented sensors	current, voltage, temperature
Driver signals IGBT	Electrical
Design standards	EN 50178
Approvals	UL 508C
Sales - name	2PS13512E43W39689
SP - No.	SP001132612





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### **Preliminary data**

### Absolute maximum rated values

Collector-emitter voltage	IGBT; T <sub>vj</sub> = 25°C	V <sub>CES</sub>	1200	V
Repetitive peak reverse voltage	Diode; T <sub>vj</sub> = 25°C	V <sub>RRM</sub>	1200	V
Insulation management	according to installation height of 2000 m	V <sub>line</sub>	500	V <sub>RMS</sub>
Insulation test voltage	according to EN50178, f = 50 Hz, t = 1 s	V <sub>ISOL</sub>	2.5	kV <sub>RMS</sub>
Switching frequency inverter section		f <sub>sw2</sub>	8	kHz

#### Notes

Further maximum ratings are specified in the following dedicated sections

### **Characteristic values**

DC Link		min.	typ.	max.	
Rated voltage	$V_{DC}$		650	850	V

### Notes

The over voltage shutdown level is above the max.rated DC voltage. Therefore this function can not be used

nverter Section				typ.	max.	
Rated continuous current	$\begin{array}{l} V_{DC} = 650 \text{ V},  V_{AC} = 400 \text{ V}_{RMS},  cos(\phi) = 0.85, \\ f_{AC \text{ sine}} = 50 \text{ Hz},  f_{sw} = 5000 \text{ Hz},  T_{inlet} = 40^{\circ}C,  T_{j} \leq 125  ^{\circ}C \end{array}$	I <sub>AC</sub>			900	A <sub>RMS</sub>
Continuous current at low frequency	$\begin{aligned} V_{DC} &= 650 \text{ V}, \cos(\phi) = 0.85, f_{AC \text{ sine}} = 0 \text{ Hz}, f_{sw} = 5000 \text{ Hz}, \\ T_{inlet} &= 40 \text{ °C}, T_j \leq 125 \text{ °C} \end{aligned}$	I <sub>AC low</sub>			540	A <sub>RMS</sub>
Rated continuous current for 150% overload capability	$I_{AC\ 150\%}$ = 1080 $A_{RMS}$ , $t_{on\ over}$ = 60 s, $t_{recovery}$ = 600 s, $T_{j} \le 125\ ^{\circ}C$	I <sub>AC over1</sub>			720	A <sub>RMS</sub>
Over current shutdown	within 15 μs	I <sub>AC OC</sub>			1860	A <sub>peak</sub>
Power losses	$ \begin{vmatrix} I_{AC} = 900 \text{ A}, \ V_{DC} = 650 \text{ V}, \ V_{AC} = 400 \ V_{RMS}, \ cos(\phi) = 0.85, \\ f_{AC \text{ sine}} = 50 \text{ Hz}, \ f_{sw} = 5000 \text{ Hz}, \ T_{inlet} = 40 \ ^{\circ}C, \ T_{j} \leq 125 \ ^{\circ}C \\ \end{vmatrix} $	P <sub>loss</sub>			2940	W

#### Notes

Maximum junction temperature limited to 125°C under all operating conditions

### **Controller interface**

Driver and interface board	ref. to separate Application Note			DR240		
			min.	typ.	max.	
Auxiliary voltage		V <sub>aux</sub>	18	24	40	V
Auxiliary power requirement	V <sub>aux</sub> = 24 V	Paux			40	W
Digital input level	resistor to GND 10 kΩ, capacitor to GND 1 nF	V <sub>in low</sub>	0		4	V
		V <sub>in high</sub>	11		15	V
Digital output level	open collector, logic low = no fault, max. 15 mA	V <sub>out low</sub>	0		1.5	V
		V <sub>out high</sub>		15		V
Analog current sensor output inverter section	load max 5 mA, @ 900 A <sub>RMS</sub>	V <sub>IU</sub> ana2 V <sub>IV</sub> ana2 V <sub>IW</sub> ana2	4.8	4.9	5	٧
Analog DC link voltage sensor output	load max 5 mA, @ 800 V	V <sub>DC</sub> ana	5.5	5.7	5.8	V
Analog temperature sensor output inverter section (Simulated)	load max 5 mA, @T <sub>NTC</sub> = 55 °C, corresponds to T <sub>j</sub> = 125 °C at rated conditions	V <sub>Theta sim2</sub>		4.5		٧
Over temperature shutdown inverter section	@T <sub>NTC</sub> = 81 °C	V <sub>Error OT2</sub>		10		V

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### **Preliminary data**

System data				min.	typ.	max.	
EMC robustness	according to IEC 61800-3 at named	power	$V_{\text{Burst}}$	2			kV
Livio robuotilogo	interfaces	control	V <sub>Burst</sub>		1		kV
		aux (24V)	V <sub>surge</sub>		1		kV
Storage temperature		·	T <sub>stor</sub>	-40		80	°C
Operational ambient temperature	PCB, DC link capacitor, bus bar, excludi medium	PCB, DC link capacitor, bus bar, excluding cooling medium Top amb		-25		55	°C
Cooling air velocity	PCB, DC link capacitor, bus bar, standard atmosphere		Vair	0.3			m/s
Humidity	no condensation	no condensation		0		85	%
Vibration	according to IEC 60721	according to IEC 60721				5	m/s²
Shock	according to IEC 60721					40	m/s²
Protection degree					IP00	•	
Pollution degree					2		
Dimensions	width x depth x height			260	280	120	mm
Weight					7.7		kg

Heatsink water cooled			min.	typ.	max.	
Water flow	according to coolant specification from Infineon	ΔV/Δt	10			dm³/min
Water pressure				30		bar
Water pressure drop		Δр			8	mbar
Coolant inlet temperature		T <sub>inlet</sub>	-40		70	°C
Cooling channel material			Α	luminiu	m	

**Notes**Conditions are standard Infineon characterization for heatsinks.

Overview of optional components	Unit 1	Inverter Section	Unit 3
Parallel interface board			
Optical interface board			
Chopper controller			
Voltage sensor		×	
Current sensor		×	
Temperature sensor		×	
DC link capacitors			

Setting of Active Clamping TVS-Diodes: Vz = 824 V

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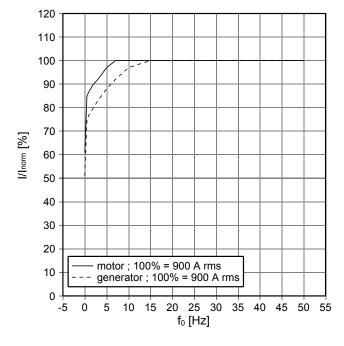
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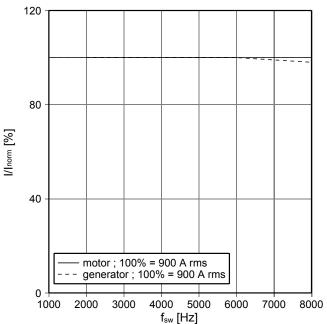


### **Preliminary data**

fo - derating curve IGBT (motor), Diode (generator)  $\cos(\text{phi}) = \pm \ 0.85 \\ T_{\text{cool medium}} = 40^{\circ}\text{C}$ 

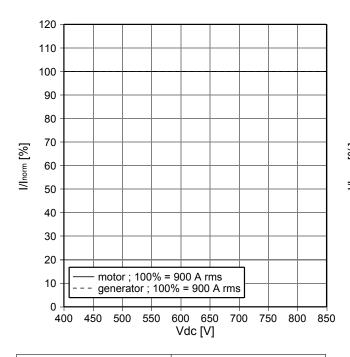
fsw - derating curve IGBT (motor), Diode (generator)  $\cos(phi) = \pm 0.85 \\ T_{\text{cool medium}} = 40^{\circ}\text{C}$ 

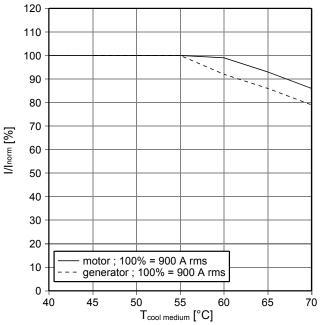




Continuous current derating curves vs. dc link voltage  $cos(phi) = \pm 0.85$   $T_{cool\ medium} = 40^{\circ}C$ 

Continuous current derating curves vs. Toool medium  $cos(phi) = \pm 0.85$ 





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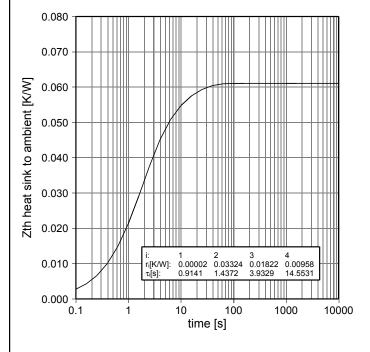
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### **Preliminary data**

Zth heat sink to ambient per switch



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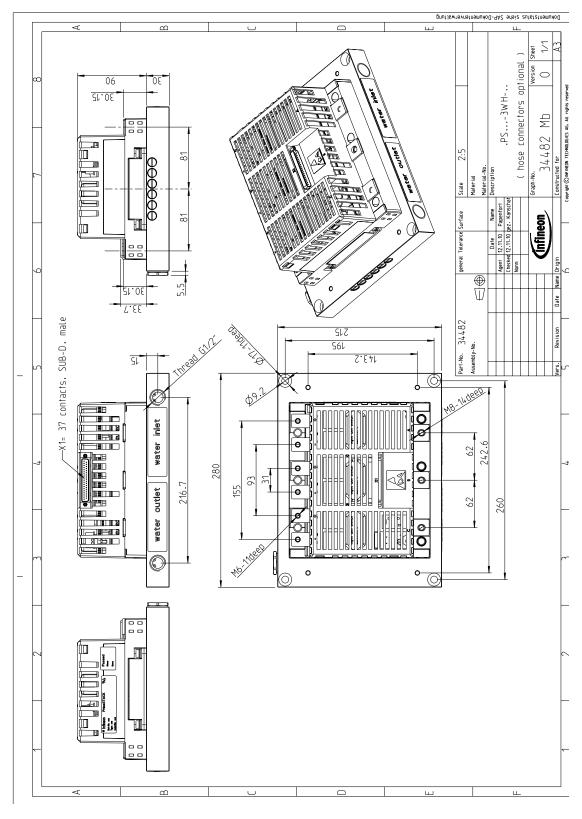
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### **Preliminary data**

### **Mechanical drawing**



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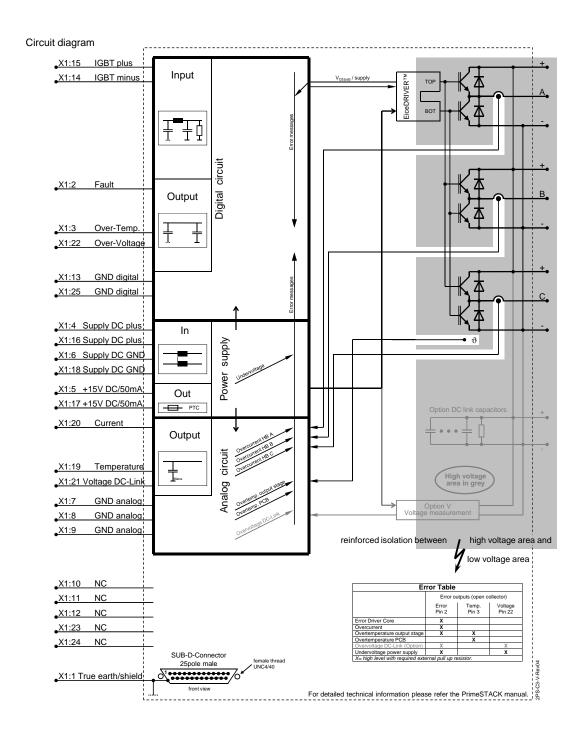
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### **Preliminary data**

### Circuit diagram



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### **Preliminary data**

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- the conclusion of Quality Agreements;
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### **Safety Instructions**

Prior to installation and operation, all safety notices and warnings and all warning signs attached to the equipment have to be carefully read. Make sure that all warning signs remain in a legible condition and that missing or damaged signs are replaced. To installation and operation, all safety notices and warnings and all warning signs attached to the equipment have to be carefully read. Make sure that all warning signs remain in a legible condition and that missing or damaged signs are replaced.

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