

# VND10B DOUBLE CHANNEL HIGH SIDE SMART POWER SOLID STATE RELAY

#### **Table 1. General Features**

Туре	V <sub>DSS</sub>	R <sub>DS(on)</sub>	In <sup>(1)</sup>	Vcc
VND10B	40 V	0.1 Ω	3.4 A	26 V

Note: 1. In= Nominal current according to ISO definition for high side automotive switch. The Nominal Current is the current at  $T_c = 85$  °C for battery voltage of 13V which produces a voltage drop of 0.5 V.

- OUTPUT CURRENT (CONTINUOUS): 14 A @ T<sub>c</sub>=85°C PER CHANNEL
- 5V LOGIC LEVEL COMPATIBLE INPUT
- THERMAL SHUT-DOWN
- UNDER VOLTAGE PROTECTION
- OPEN DRAIN DIAGNOSTIC OUTPUT
- INDUCTIVE LOAD FAST DEMAGNETIZATION
- VERY LOW STAND-BY POWER DISSIPATION

#### DESCRIPTION

The VND10B is a monolithic device made using STMicroelectronics V.Power Technology, intended for driving resistive or inductive loads with one side grounded. This device has two channels, and a common diagnostic. Built-in thermal shut down protects the chip from over temperature and short circuit.

The s atus output provides an indication of open load in on state, open load in off state, overtemperature conditions and stuck-on to  $V_{CC}$ .

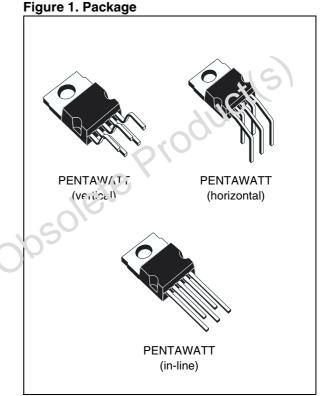
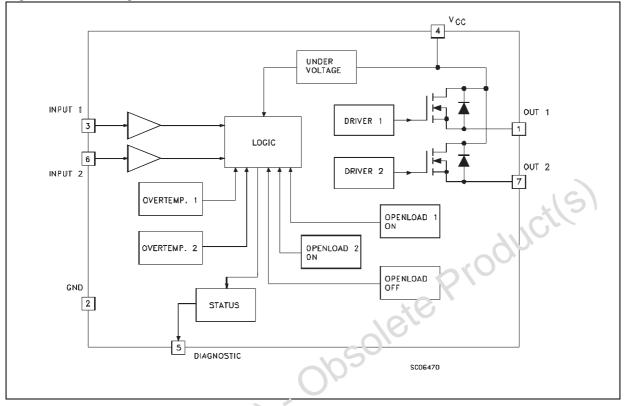


Table 2. Order Codes	Table	2.	Order	Codes
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Package	Tube	Tape and Reel
PENTAWATT Vert.	VND10B	-
PENTAWATT Hor.	VND10B(011Y)	-
PENTAWATT In line	VND10B(012Y)	_

# Figure 2. Block Diagram



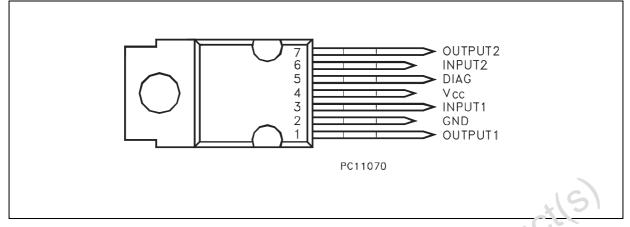
# Table 3. Absolute Maximum Ratings 🕤

Symbol	Parameter	Value	Unit
V <sub>(BR)DSS</sub>	Drain-Source Brackdown Voltage	40	V
lout	Output Cu rent (cont.) at T <sub>c</sub> = 85 °C	14	A
I <sub>OUT</sub> (RMS)	RMS Cutput Current at T <sub>c</sub> = 85 °C	14	А
I <sub>R</sub>	F. averse Output Current at T <sub>c</sub> = 85 °C	-14	A
Lin	Input Current	±10	mA
- /cc	Reverse Supply Voltage	-4	V
ISTAT	Status Current	±10	mA
V <sub>ESD</sub>	Electrostatic Discharge (1.5 kΩ; 100 pF)	2000	V
P <sub>tot</sub>	Power Dissipation at $T_c = 25 \ ^{\circ}C$	75	W
Тj	Junction Operating Temperature	-40 to 150	°C
T <sub>stg</sub>	Storage Temperature	-55 to 150	°C

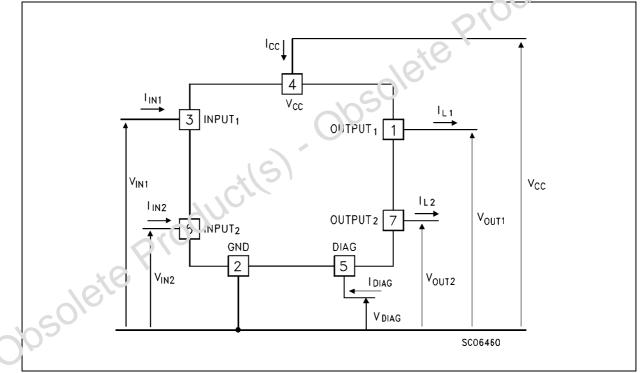
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57

# Figure 3. Connection Diagram



# Figure 4. Current and Voltage Conventions



## Table 4. Thermal Data

Symbol	Parameter		Value	Unit
R <sub>thj-case</sub>	Thermal Resistance Junction-case	Max	1.65	°C/W
R <sub>thj-amb</sub>	Thermal Resistance Junction-ambient	Max	60	°C/W

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#### **ELECTRICAL CHARACTERISTICS**

(8 < V\_{CC} < 16 V; -40  $\leq$  T\_j  $\leq$  125 °C unless otherwise specified)

### Table 5. Power

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
V <sub>CC</sub>	Supply Voltage		6	13	26	V
In <sup>(2)</sup>	Nominal Current	$T_{c} = 85 \ ^{\circ}C; \ V_{DS(on)} \leq 0.5; \ V_{CC} = 13 \ V$	3.4		5.2	А
Ron	On State Resistance	$I_{OUT} = I_n; V_{CC} = 13 V; T_j = 25 \ ^{\circ}C$	0.065		0.1	Ω
I <sub>S</sub>	Supply Current	Off State; $T_j = 25 \text{ °C}$ ; $V_{CC} = 13 \text{ V}$		35	100	μA
V <sub>DS(MAX)</sub>	Maximum Voltage Drop	$I_{OUT} = 13 \text{ A}; T_j = 85 \text{ °C}; V_{CC} = 13 \text{ V}$	1.2		2	<b>&gt;</b>
Ri	Output to GND internal Impedance	T <sub>j</sub> = 25 °C	5	10	20	δ KΩ

Note: 2. In= Nominal current according to ISO definition for high side automotive switch. The Nominal Current is the current at T<sub>c</sub> = 85 °C for battery voltage of 13V which produces a voltage drop of 0.5 V.

24

57

#### Table 6. Switching

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
$t_{d(on)}^{(3)}$	Turn-on Delay Time Of Output Current	R <sub>OUT</sub> = 2.7 Ω	5	35	200	μs
$t_r^{(3)}$	Rise Time Of Output Current	R <sub>OUT</sub> = 2.7 Ω	28	110	360	μs
$t_{d(off)}^{(3)}$	Turn-off Delay Time Of Output Current	R <sub>OUT</sub> = 2.7 Ω	10	140	500	μs
t <sub>f</sub> <sup>(3)</sup>	Fall Time Of Output Current	Rou : - 2.7 Ω	28	75	360	μs
(di/dt) <sub>on</sub>	Turn-on Current Slope	R <sub>OUT</sub> = 2.7 Ω	0.003		0.1	A/µs
(di/dt) <sub>off</sub>	Turn-off Current הארוה	R <sub>OUT</sub> = 2.7 Ω	0.005		0.1	A/µs

Note: 3. See Switching Time Woveforms.

#### Table 7. Logic input

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
<u> </u>	Input Low Level Voltage				1.5	V
VIH	Input High Level Voltage		3.5		Note 4	V
V <sub>I(hyst)</sub>	Input Hysteresis Voltage		0.2	0.9	1.5	V
l <sub>IN</sub>	Input Current	$V_{IN} = 5 V; T_j = 25 °C$		30	100	μA
VICL	Input Clamp Voltage	I <sub>IN</sub> = 10 mA I <sub>IN</sub> = -10 mA	5	6 –0.7	7	V V

Note: 4. The V<sub>IH</sub> is internally clamped at 6V about. It is possible to connect this pin to an higher voltage via an external resistor calculated to not exceed 10 mA at the input pin.

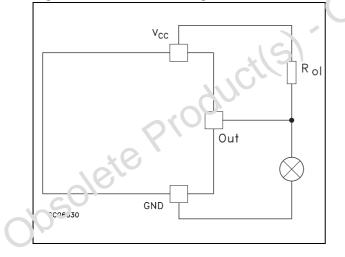
## ELECTRICAL CHARACTERISTICS (cont'd)

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
V <sub>STAT</sub>	Status Voltage Output Low	I <sub>STAT</sub> = 1.6 mA			0.4	V
V <sub>USD</sub>	Under Voltage Shut Down		3.5	4.5	6	V
V <sub>SCL</sub>	Status Clamp Voltage	I <sub>STAT</sub> = 10 mA I <sub>STAT</sub> = -10 mA	5	6 0.7	7	V V
T <sub>TSD</sub>	Thermal Shut-down Temperature		140	160	180	°C
T <sub>SD(hyst.)</sub>	Thermal Shut-down Hysteresis				50	°C
T <sub>R</sub>	Reset Temperature		125		10	°,
V <sub>OL</sub> <sup>(5)</sup>	Open Voltage Level	Off-State	2.5	4	5	V
I <sub>OL</sub>	Open Load Current Level		0.6	0.9	1.4	А
t <sub>povl</sub> (6)	Status Delay		20	5	10	μs
t <sub>pol</sub> <sup>(6)</sup>	Status Delay	× 01	50	500	2500	μs
	$f_{ff} = (V_{CC} - V_{OL})/R_{OL}$ (see figure 5) $t_{pol}$ : ISO definition (see figure 6).	1610	<u>.</u>	•	-	-

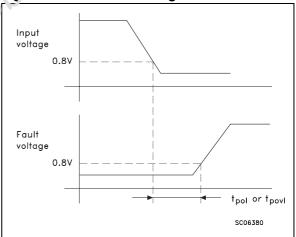
#### **Table 8. Protection and Diagnostics**

Note: 5.  $I_{OL(off)} = (V_{CC} - V_{OL})/R_{OL}$  (see figure 5) 6.  $t_{povl} t_{pol}$ : ISO definition (see figure 6).

## Figure 5. Note 5 relevant figure

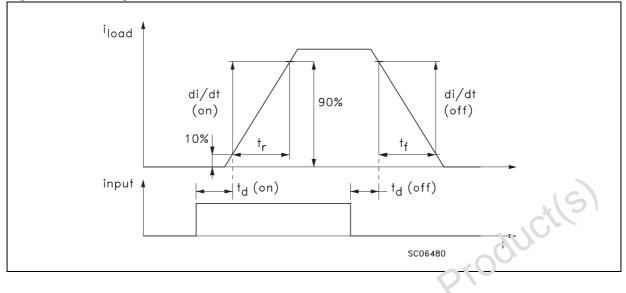


## Figure 6. Note 6 relevant figure



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#### Figure 7. Switching Time Waveforms



#### FUNCTIONAL DESCRIPTION

The device has a common diagnostic output for both channels which indicates open load in onstate, open load in off-state, over temperature conditions and stuck-on to  $V_{CC}$ .

From the falling edge of the input signal, the status output, initially low to signal a fault condition (overtemperature or open load on-state), vil go back to a high state with a different aplay in case of overtemperature (tpov) and in case of open open load (tpol) respectively. היוב feature allows to discriminate the nature citie detected fault. To protect the device against short circuit and over current condition, the thermal protection turns the integrated Power MOS off at a minimum junction temperature of 140 °C. When this temperature returns to 125 °C the switch is automatically turned on again in short circuit the protection reacts with virtualy no delay, the sensor (one for each channel) being located inside each of the two Power MOS areas. This positioning allows the device to operate with one channel in automatic thermal cycling and the other one on a normal load. An internal function of the devices ensures the fast demagnetization of inductive loads with a typical voltage (V<sub>demag</sub>) of -18V. This function allows to greatly reduces the power dissipation according to the formula:

 $P_{dem} = 0.5 \bullet L_{load} \bullet (I_{load})^2 \bullet [(V_{CC} + V_{demag}) / V_{demag}] \bullet f$ 

where f = switching frequency and

V<sub>demag</sub> = demagnetization voltage

The maximum inductance which causes the chip temperature to reach the shut-down temperature in a specified thermal environment is a function of the load current for a fixed  $V_{CC}$ ,  $V_{demag}$  and f according to the above formula. In this device if the GND pin is disconnected, with  $V_{CC}$  not exceeding 16V, both channel will switch off.

# PROTECTING THE DEVICE AGAINST REVERSE BATTERY

The simplest way to protect the device against a continuous reverse battery voltage (-26V) is to insert a Schottky diode between pin 1(GND) and ground, as shown in the typical application circuit (Figure 9).

The consequences of the voltage drop across this diode are as follows:

- If the input is pulled to power GND, a negative voltage of -V<sub>f</sub> is seen by the device. (V<sub>IL</sub>, V<sub>IH</sub> thresholds and V<sub>STAT</sub> are increased by V<sub>f</sub> with respect to power GND).
- The undervoltage shutdown level is increased by  $V_{f}$ .

If there is no need for the control unit to handle external analog signals referred to the power GND, the best approach is to connect the reference potential of the control unit to node [1] (see application circuit in Figure 10), which becomes the common signal GND for the whole control board avoiding shift of  $V_{IH}$ ,  $V_{IL}$  and  $V_{STAT}$ . This solution allows the use of a standard diode.

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## Table 9. Truth Table

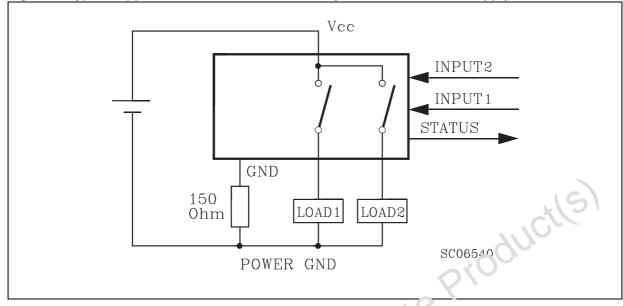
		Input 1	Input 2	Output 1	Output 2	Diagnostic	
Normal Operation			L H H L	L H L H	L H H L	H H H H	
Under voltage		Х	Х	L	L	Н	
Thermal Shutdown	Channel 1	Н	Х	L	Х	L	
	Channel 2	Х	Н	Х	L	L	
Open Load	Channel 1	H L	X L	H L	X L	L L <sup>(7)</sup>	
	Channel 2	X L	H L	X L	H		
Output Shorted to V <sub>CC</sub>	Channel 1	H L	X L	H H	, OČ	L	
	Channel 2	X L	H L	X L	Н	L	
Note: 7. With additional external resistor. Figure 8. Waveforms							
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# Figure 8. Waveforms

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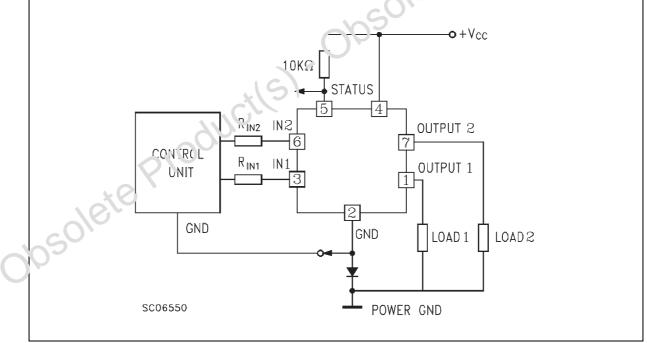
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	INPUT	NOR MAL OPERATION	INPUT STATUS SWITCH On Off		OPEN LOAD
C	INPUT	UNDER VOLTAGE	INPUT STATUS SWITCH <sup>On</sup> <sup>I</sup> OUT		THERMAL SHUTDOWN - 140 <sup>o</sup> C - 125 <sup>o</sup> C
	INPUT LOAD CURRENT DIAG SWITCH On Off	OUTPUT SHOR TO V <sub>CC</sub>	TED	SC06590	









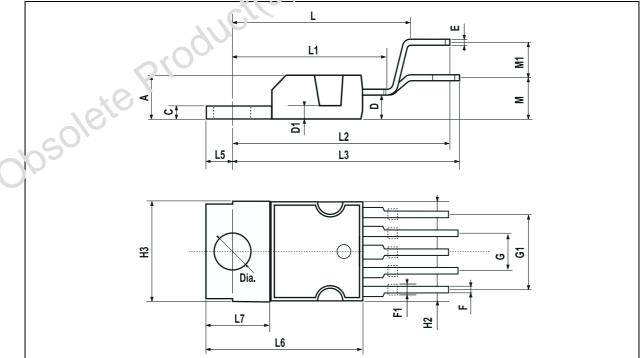
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## PACKAGE MECHANICAL

Symbol	millimeters			
	Min	Тур	Мах	
А			4.8	
С			1.37	
D	2.4		2.8	
D1	1.2		1.35	
E	0.35		0.55	
F	0.8		1.05	
F1	1		1.4	
G	3.2	3.4	Ĵ.t	
G1	6.6	6.8	7	
H2			10.4	
H3	10.05		10.4	
L2	23.05	23.4	23.8	
L3	25.3	25.65	26.1	
L5	2.6		3	
L6	15.1	S	15.8	
L7	6	70-	6.6	
Dia.	3.65		3.85	

# Table 10. PENTAWATT (vertical) Mechanical Data

## Figure 11. PENTAWATT (vertical) Pacing Dimensions

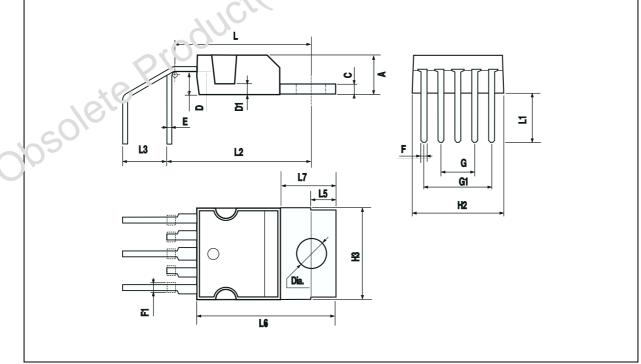


Note: Drawing is not to scale.

Symbol	millimeters		
	Min	Тур	Мах
А			4.8
С			1.37
D	2.4		2.8
D1	1.2		1.35
E	0.35		0.55
F	0.8		1.05
F1	1		1.4
G	3.2	3.4	3.6
G1	6.6	6.8	215
H2			10.4
H3			10.4
L	14.2	14.2 15	
L1	5.7		6.2
L2	14.6		15.2
L3	3.5		4.1
L5	2.6		3
L6	15.1	5	15.8
L7	6	NP.	6.6
Dia.	3.65		3.85

## Table 11. PENTAWATT (horizontal) Mechanical Data

# Figure 12. PENTAWATT (horizontal) Package Dimensions

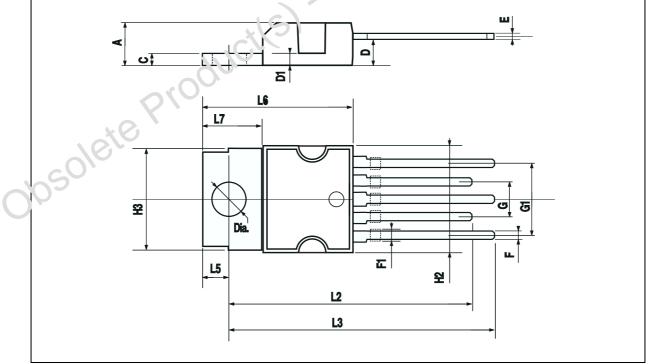


Note: Drawing is not to scale.

Symbol	millimeters			
	Min	Тур	Max	
A			4.8	
С			1.37	
D	2.4		2.8	
D1	1.2		1.35	
E	0.35		0.55	
F	0.8		1.05	
F1	1		1.4	
G	3.2	3.4	3.6	
G1	6.6	6.8	7.5	
H2			10.4	
H3	10.05		10.4	
L2	23.05	23.4	23.8	
L3	25.3	25.65	26.1	
L5	2.6		3	
L6	15.1	1010	15.8	
L7	6		6.6	
Dia.	3.65	5	3.85	

Table 12. PENTAWATT (in-line) Mechanical Data

## Figure 13. PENTAWATT (in-line) Package Dimensions



Note: Drawing is not to scale.



### **REVISION HISTORY**

#### Table 13. Revision History

Date	Revision	Description of Changes
September-1994	1	First Issue
18-June-2004	2	Stylesheet update. No content change.

obsolete Product(s). Obsolete Product(s)

57

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