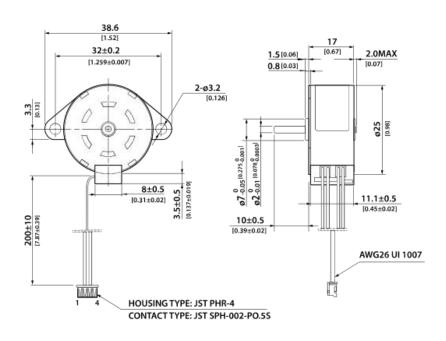




### **MOTOR SPECIFICATIONS**

Part Number	PM25L-075-032
Rate Voltage	12
Constant Current	0.35A/Phase
Phase Number	2
Step Angle	7.5°
Excitation Method	Bipolar Full-Step
Insulation Class	Class B
Resistance per Phase	14Ω ± 10%
Inductance per Phase A/B	13± 20%
Holding Torque	270g-cm Min
Detent Torque	45 g-cm Max
Insulation Resistance	100MΩ min.

# **DIMENSIONS**



CONNECTOR PIN LOCATION							
PIN NO.	COLOR	CCW CW PHASE (Seen from flange side)					
1	BLACK	ON			ON	ON	Α
2	BROWN		ON	ON			A
3	ORANGE	ON	ON			ON	В
4	YELLOW			ON	ON		В

### **PERFORMANCE CURVE**

#### PM25L-075-032 12VDC, 0.35 Amps Peak, Bipolar Series, Full Stepping 250 → PULL-OUT → PULL-IN Pull-in & Pull-out Torque (g-cm) 200 150 100 50 n 1000 1400 200 600 1200 Pulse Rate (pps)

### **OPERATING CONDITIONS**

Operating Temperature	-20C - +50C
Operating Humidity	15 - 85% RH
Storage Temperature	-30C - +70
Storage Humidity	15 - 85% RH

# **MECHANICAL SPECIFICATIONS**

Radial Shaft Loading	5N Max
Axial Shaft Loading	1N Max
Radial Shaft Play	0.05 mm Max
Axial Shaft Play	0.6 mm Max
Mass	Approximate 39g
Rotor Inertia	Approximate 0.85 g-cm <sup>2</sup>

# **OPERATION & USAGE TIPS**



Do not disassemble motors; a significant reduction in motor performance will occur.



Do not machine shafts; this will have a negative effect on shaft run out and perpendicularity.



Do not disconnect motor from drive while in operation.



Do not use holding torque/detent torque of motor as a fail safe brake.



Do not hold motor by lead wires.



Do not exceed the rated current; this wil burn the motor.

FAILURE TO COMPLY WITH THESE RECOMMENDATIONS WILL VOID ALL WARRANTY TERMS

## **RECOMMENDED**



Microstepping Driver R208



Single Axis Controller + Driver **R256-RO** 

# Motion Control, Solved.

**MOTOR ENGINEERING & MANUFACTURING** 







Small Batch to OEM Volume Production

