MTi-G-710

- Movella's high-performance product line
- 0.2 deg in roll/pitch, 0.8 deg in heading accuracy
- Complete SDK and development kits available

The MTi-G-710 features vibration-rejecting gyroscopes, and offers high-quality position, velocity, acceleration, and orientation, even in challenging environments.

With Xsens technology inside, the all-in-one sensor system supports optimized temperature calibration, high-frequency position and orientation output, and has configurable output settings for synchronization with any third-party device.

The MTi-G-710 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms.

Sensor fusion performance		м
Roll, Pitch	0.2 deg RMS	IP
Yaw/Heading	-	0
Position	1.0 m (1σ STD)	Ca
Velocity	0.05 m/s (1σ STD)	M
Gyroscope		Di
Standard full range	450 deg/s	Co
In-run bias stability	10 deg/h	W
Bandwidth (-3dB)	415 Hz	Ce
Noise Density	0.01 º/s/√Hz	E
g-sensitivity (calibr.)	0.003 °/s/g	In
Accelerometer		Po
Standard full range	20 g	I
In-run bias stability	15 µg	In
Bandwidth (-3dB)	375 Hz	S
Noise Density	60 µg/√Hz	Pr
Magnetometer		CI
Standard full range	+/- 8 G	0
Total RMS noise	0.5 110	B
Non-linearity	0.2%	S
Resolution	0.25 mG	G
GNSS Receiver		
Brand	u-blox	SI
Model	MAX-M8	
RTCM input port	n/a	D
Barometer		Si
Standard full range	300-1100 hPa	
Total RMS noise	3.6 Pa	
Resolution	~0.08m	
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- White label and OEM integration options available
- 3D models available on request

This document is informational and not binding. Complete and detailed specifications are available at **mtidocs.movella.com**

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Mechanical	
IP-rating	IP67
Operating Temperature	-40 to 85 °C
Casing material	Aluminum
	No restriction, full 360° in all axes
Dimensions	57x41.90x23.60 mm
Connector	
Weight	58 g
Certifications	CE, FCC, RoHS, MIL-STD-202
Electrical	
Input voltage	3V3, 4.5V-34V
Power consumption (typ)	660 mW
Interfaces / IO	
Interfaces	USB, RS232, RS422, UART
Sync Options	SyncIn, SyncOut, ClockSync
Protocols	Xbus, ASCII (NMEA)
Clock drift	1 ppm
Output Frequency	Up to 2kHz
Built-in-self test	Gyr, Acc, Mag
Software Suite	
GUI (Windows/Linux)	MT Manager, Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab, Nucleo, public source code
Drivers	LabVIEW, ROS, GO
Support	Online manuals, community and
Sabbold	knowledge base

