

# 3A, 30V, Host-Controlled Single-Input, Single Cell Switchmode Li-Ion Battery Charger with Power Path Management and USB-OTG Support

Check for Samples: bq24260, bq24261, bq24262A

## FEATURES

- Charge Time Optimizer (Enhanced CC/CV Transition) for Faster Charging
- Integrated FETs for Up to 3A Charge Rate at 5% Accuracy and 93% Peak Efficiency
- Boost Capability to Supply 5V at 1A at IN for USB OTG Supply
- Integrated 17mΩ Power Path MOSFET and optional BGATE control to Maximize Battery Life and Instantly Startup From a Deeply Discharged Battery or No Battery
- 30V Input Rating with Over-Voltage Protection Supports 5V USB2.0/3.0 and 12V USB Power Delivery (bq24261)
- Small Solution Size In a 2.4mm x 2.4mm 36ball WCSP or 4mm x 4mm QFN-24 Package
  - Total Charging Solution Can be 50mm<sup>2</sup> or less with WCSP
- Safe and Accurate Battery Management Functions Programmed Using I<sup>2</sup>C Interface
  - Charge Voltage, Current, Termination Threshold, Input Current Limit, V<sub>IN\_DPM</sub> Threshold
  - Voltage-based, JEITA Compatible NTC Monitoring Input

**Application Schematic** 



- Thermal Shutdown and Protection

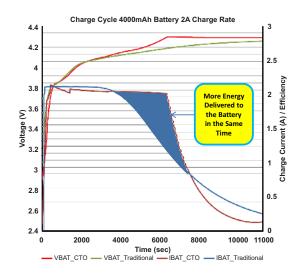
## **APPLICATIONS**

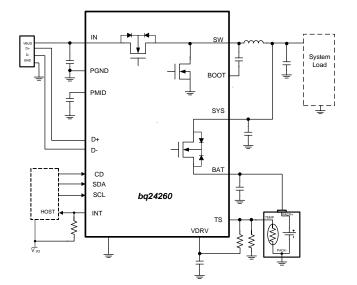
- Smartphone and Tablets
- Handheld Products
- Power Banks and External Battery Packs
- Small Power Tools
- Portable Media Players and Gaming

## DESCRIPTION

The bq24260/bq24261/bq24262A are highly integrated single cell Li-lon battery charger and system power path management devices targeted for space-limited, portable applications with high capacity batteries. The single cell charger has a single input that supports operation from either a USB port or wall adapter supply for a versatile solution. (Continued on page 2)

## **Charge Time Optimizer Effect**





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## **DESCRIPTION (CONTINUED)**

The power path management feature allows the bq2426x to power the system from a high efficiency DC to DC converter while simultaneously and independently charging the battery. The charger monitors the battery current at all times and reduces the charge current when the system load requires current above the input current limit or the adapter cannot support the required load, causing the adapter voltage to fall ( $V_{IN\_DPM}$ ). This allows for proper charge termination and timer operation. The system voltage is regulated to the battery voltage but will not drop below 3.5V ( $V_{MINSYS}$ ). This minimum system voltage support enables the system to run with a defective or absent battery pack and enables instant system turn-on even with a totally discharged battery or no battery. The power-path management architecture also permits the battery to supplement the system current requirements when the adapter cannot deliver the peak system currents. The power-path feature coupled with  $V_{IN}$ -DPM, enables the use of many adapters with no hardware change. The charge parameters are programmable using the I2C interface. To Support USB OTG applications, the bq2426x is configurable to boost the battery voltage to 5V at the input. In this mode, the bq2426x supplies up to 1A and operates with battery voltages down to 3.3V.

The battery is charged using a standard Li-Ion charge profile with three phases: precharge, constant current and constant voltage. In all charge phases, an internal control loop monitors the IC junction temperature and reduces the input current to prevent the junction temperature from rising above 125°C. Additionally, a voltage-based, JEITA compatible battery pack thermistor monitoring input (TS) is included that monitors battery temperature and automatically changes charge parameters to prevent the battery from charging outside of its safe temperature range.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

PART NUMBER	OVP	CE BIT DEFAULT	D+/D- DETECTION	TIMERS (SAFETY and WATCHDOG)	NTC MONITORING	OTG BOOST	I2C ADDRESS			
bq24260	10.5	0 (Charge Enabled)	YES	YES	JEITA	YES	6B			
bq24261	14	1 (Charge Disabled)	NO	YES	JEITA	YES	6B			
bq24262A	6.5	0 (Charge Enabled)	NO	NO	JEITA	YES	6B			

### Available Options

#### **Ordering Information**

PART NUMBER	IC MARKING	PACKAGE	ORDERABLE NUMBER	QUANTITY
		DSBGA - YFF (PREVIEW)	bq24260YFFR	3000
h=04000	h=04000	DSBGA - YFF (PREVIEW)	bq24260YFFT	250
bq24260	bq24260	QFN – RGE (PREVIEW)	bq24260RGER	3000
		QFN – RGE (PREVIEW)	bq24260RGET	250
	bq24261	DSBGA - YFF	bq24261YFFR	3000
h=04001		DSBGA - YFF	bq24261YFFT	250
bq24261		QFN – RGE	bq24261RGER	3000
		QFN – RGE	bq24261RGET	250
h=040004	h=040004	DSBGA - YFF (PREVIEW)	bq24262AYFFR	3000
bq24262A	bq24262A	DSBGA - YFF (PREVIEW)	bq24262AYFFT	250



## Absolute Maximum Ratings<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

		VAL	VALUE		
		MIN	UNIT		
	IN	-1.3	30		
	BOOT, PMID	-0.3	30		
Pin Voltage Range (with respect to PGND)	SW	-0.7	20	V	
,	BAT, BGATE, CD, D+, D-, DRV, INT, PSEL, SDA, SCL, STAT, SYS, TS	-0.3	5	-	
BOOT to SW		-0.3	5	V	
	SW		4.5		
Output Current (Continuous)	SYS, BAT (charging/ discharging)		3.5	A	
Input Current (Continuous)			2.75	Α	
Output Sink Current	STAT, INT		10	mA	
Operating free-air temperature rai	-40	85	- °C		
Junction temperature, T <sub>J</sub> -40 125				Ů	
Storage temperature, T <sub>STG</sub> 300					

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability. All voltage values are with respect to the network ground terminal unless otherwise noted.

## THERMAL INFORMATION

	THERMAL METRIC <sup>(1)</sup>	bq2	bq2426x				
		YFF (36 PINS)	RGE (24 PINS)	UNITS			
$\theta_{JA}$	Junction-to-ambient thermal resistance	55.8	32.6				
θ <sub>JCtop</sub>	Junction-to-case (top) thermal resistance	0.5	30.5				
$\theta_{JB}$	Junction-to-board thermal resistance	10	3.3	°C/W			
$\Psi_{JT}$	Junction-to-top characterization parameter	2.6	0.4	°C/W			
$\Psi_{JB}$	Junction-to-board characterization parameter	9.9	9.3				
θ <sub>JCbot</sub>	Junction-to-case (bottom) thermal resistance	N/A	2.6				

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

### **Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
	IN voltage range	4.2		28 <sup>(1)</sup>	
V	IN operating voltage range (bq24260)	4.2		10	V
V <sub>IN</sub>	IN operating voltage range (bq24261)	4.2		13.2	v
	IN operating voltage range (bq24262A)	4.2		6.0	
I <sub>IN</sub>	Input current, IN input			2.5	А
I <sub>SW</sub>	Output Current from SW, DC			3	А
I <sub>BAT</sub> , I <sub>SYS</sub>	Charging			3	٨
	Discharging, using internal battery FET			3	A
TJ	Operating junction temperature range	0		125	°C

(1) The inherent switching noise voltage spikes should not exceed the absolute maximum rating on either the BOOT or SW pins. A *tight* layout minimizes switching noise.

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## **ELECTRICAL CHARACTERISTICS**

Circuit of Figure 1,  $V_{UVLO} < V_{IN} < V_{OVP}$  AND  $V_{IN} > V_{BAT} + V_{SLP}$ ,  $T_J = -40^{\circ}C$  to 125°C and  $T_J = 25^{\circ}C$  for typical values (unless otherwise noted)

	PARAMETER	TEST CONDITION	ONS	MIN	TYP	MAX	UNIT
INPUT CURF	ENTS						
		$V_{UVLO} < V_{IN} < V_{OVP}$ and $V_{IN} {>} V_{BAT} {+} V_{SLP}$ PWM switching			15		
I <sub>IN</sub>	Supply current for control	YFF Package: $V_{\rm UVLO} < V_{\rm IN} < V_{\rm OVP}$ and PWM NOT switching			6.5	mA	
		RGE Package: $V_{UVLO} < V_{IN} < V_{OVP}$ and PWM NOT switching	VIN>VBAT+VSLP			6.65	
		$0^{\circ}C < T_{J} < 85^{\circ}C, V_{IN} = 5V, High-Z Mode$	1			250	μA
		$\begin{array}{l} 0^{\circ}C<{}T_{J}<85^{\circ}C,V_{BAT}=4.2V,V_{IN}=5V,\\ SCL,SDA=0Vor1.8V,High\text{-}ZMode \end{array}$				15	
I <sub>BAT_HIZ</sub>	Battery discharge current in High Impedance mode, (BAT, SW, SYS)	YFF Package: 0°C< $T_{\rm J}$ < 85°C, $V_{\rm BAT}$ = SCL, SDA = 0V or 1.8V	4.2 V, $V_{IN} = 0V$ ,			77	μA
	(2, 0, 0.0)	RGE Package: $0^{\circ}C < T_{J} < 85^{\circ}C, V_{BAT} =$ SCL, SDA = 0V or 1.8V	4.2 V, $V_{IN} = 0V$ ,			80	
POWER-PAT	H MANAGEMENT	•					
V <sub>SYSREG(LO)</sub>	System Regulation Voltage	V <sub>BAT</sub> < V <sub>MINSYS</sub>		V <sub>MINSYS</sub> + 80mV	V <sub>MINSYS</sub> + 100mV	V <sub>MINSYS</sub> + 120mV	V
V <sub>SYSREG(HI)</sub>	System Regulation Voltage	Battery FET turned off, no charging, $V_{BAT} > 3.5 V \label{eq:vbarger}$		V <sub>BATREG</sub> +2.2%	V <sub>BATREG</sub> +2.5%	V <sub>BATREG</sub> +2.77%	V
V <sub>MINSYS</sub>	Minimum System Voltage Regulation Threshold	$V_{BAT} + V_{DO(SYS\_BAT)} < 3.5V$		3.44	3.5	3.55	V
t <sub>DGL(MINSYS_C</sub> MP)	Deglitch time, VMINSYS comparator rising				8		ms
V <sub>BSUP1</sub>	Enter supplement mode threshold	V <sub>BAT</sub> > V <sub>BUVLO</sub>			V <sub>BAT</sub> – 20mV		V
V <sub>BSUP2</sub>	Exit supplement mode threshold	V <sub>BAT</sub> > V <sub>BUVLO</sub>		V <sub>BAT</sub> – 5mV		V	
I <sub>LIM(DISCH)</sub>	Current Limit, Discharge or Supplement Mode	$V_{\text{LIM}(\text{BGATE})} = V_{\text{BAT}} - V_{\text{SYS}}$	4	6		А	
t <sub>DGL(SC1)</sub>	Deglitch Time, OUT Short Circuit during Discharge or Supplement Mode	Measured from I <sub>BAT</sub> = 7A to FET off		250		μs	
t <sub>REC(SC1)</sub>	Recovery time, OUT Short Circuit during Discharge or Supplement Mode				2		S
	Battery Range for BGATE Operation			2.5		4.5	V
BATTERY CI	HARGER					1 1	
R <sub>ON(BAT-SYS)</sub>	Internal battery charger	Measured from BAT to SYS,	YFF		17	25	mΩ
- ON(BAT-313)	MOSFET on-resistance	$V_{BAT} = 4.2V$ , High-Z mode	RGE		32	47	
	Charge Voltage	Operating in voltage regulation, Program	mmable Range	3.5		4.44	V
	RGE Package Voltage Regulation Accuracy	$T_J = 0^{\circ}C$ to $50^{\circ}C$		-0.5%		0.5%	
VBATREG	RGE Package Voltage Regulation Accuracy	$T_J = 0^{\circ}C$ to $85^{\circ}C$		-0.7%		0.7%	
	RGE Package Voltage Regulation Accuracy	$T_J = 0^{\circ}C$ to 125°C	-1.0%		1.0%		
	YFF Package Voltage Regulation Accuracy	$T_{\rm J} = 0^{\circ}$ C to 125°C		-1.7%		0.8%	
	Fast Charge Current Range	$V_{BATSHRT} \le V_{BAT} < V_{BAT(REG)}$		500		3000	mA
I <sub>CHARGE</sub>	Fast Charge Current	500 mA $\leq$ I <sub>CHARGE</sub> $\leq$ 1A		-10%		10%	
	Accuracy	I <sub>CHARGE</sub> > 1000 mA		-5%		5%	
VBATSHRT	Battery short circuit threshold			1.9	2	2.1	V
V <sub>BATSHRT_HY</sub> s	Hysteresis for $V_{\text{BATSHRT}}$	Battery voltage falling			100		mV



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## **ELECTRICAL CHARACTERISTICS (continued)**

Circuit of Figure 1,  $V_{UVLO} < V_{IN} < V_{OVP}$  AND  $V_{IN} > V_{BAT} + V_{SLP}$ ,  $T_J = -40^{\circ}C$  to 125°C and  $T_J = 25^{\circ}C$  for typical values (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
	Deglitch time for battery short to fastcharge transition	V <sub>BAT</sub> rising or falling		1		ms	
IBATSHRT	Battery short circuit charge current	V <sub>BAT</sub> < V <sub>BATSHRT</sub>		33.5	50	66.5	mA
		I <sub>TERM</sub> ≤ 50 mA		-30%		30%	
I <sub>TERM</sub>	Termination charge current	50 mA < <sub>ITERM</sub> < 200 mA		-15%		15%	
		I <sub>TERM</sub> ≥ 200 mA		-15%		10%	
t <sub>DGL(TERM)</sub>	Deglitch time for charge termination	Both rising and falling, 2-mV over-drive, t <sub>BISE</sub> , t <sub>FALL</sub> =100ns			32		ms
V <sub>RCH</sub>	Recharge threshold voltage	Below V <sub>BATREG</sub>		100	120	150	mV
t <sub>DGL(RCH)</sub>	Deglitch time	V <sub>BAT</sub> falling below V <sub>RCH</sub> , t <sub>FALL</sub> =100ns			32		ms
V <sub>DET(SRC1)</sub>	Battery detection voltage threshold (TE = 1)	During current source (Turn I <sub>BATSHRT off</sub> )			V <sub>RCH</sub>		V
V <sub>DET(SRC2)</sub>		During current source (Turn I <sub>BATSHRT on</sub> )			V <sub>RCH</sub> – 200mV		V
V <sub>DET(SNK)</sub>		During current sink			VBATSHRT		V
I <sub>DETECT</sub>	Battery detection current before charge done (sink current)	Termination enabled (TE = 1)			7		mA
t <sub>DETECT(SRC)</sub>	Battery detection time (sourcing current)	Termination enabled (TE = 1)			2		s
t <sub>DETECT(SNK)</sub>	Battery detection time (sinking current)	Termination enabled (TE = 1)			250		ms
INPUT CURI	RENT LIMITING						
			I <sub>INLIM</sub> =USB100	90	95	100	
			I <sub>INLIM</sub> =USB500	450	475	500	
			I <sub>INLIM</sub> =USB150	125	140	150	
			I <sub>INLIM</sub> =USB900	800	850	900	
			I <sub>INLIM</sub> =1.5A	1425	1500	1575	
I <sub>INLIM</sub>	Input current limiting threshold	USB charge mode, $V_{IN} = 5V$ , Current pulled from SW	I <sub>INLIM</sub> =2A, YFF Package	1850	2000	2150	mA
			I <sub>INLIM</sub> =2A, RGE Package	1850	2000	2200	
			I <sub>INLIM</sub> =2.5A, YFF Package	2300	2500	2700	
			I <sub>INLIM</sub> =2.5A, RGE Package	2225	2500	2825	
V <sub>IN_DPM</sub>	Input based DPM threshold range	Charge mode, programmable via I <sup>2</sup> C		4.2		11.6	V
	$V_{\text{IN\_DPM}}$ threshold Accuracy			-3%		3%	
V <sub>DRV</sub> BIAS R	REGULATOR				1		
V <sub>DRV</sub>	Internal bias regulator voltage	V <sub>IN</sub> >5V		4.3	4.8	5.3	v
I <sub>DRV</sub>	DRV Output Current			0		10	mA
V <sub>DO_DRV</sub>	DRV Dropout Voltage (V <sub>IN - VDRV</sub> )	$I_{IN} = 1A, V_{IN} = 4.2V, I_{DRV} = 10mA$			450	mV	
STATUS OU	ITPUT (STAT, INT)	•			*		+
V <sub>OL</sub>	Low-level output saturation voltage	I <sub>O</sub> = 10 mA, sink current				0.4	v
I <sub>IH</sub>	High-level leakage current	V <sub>STAT</sub> = V <sub>INT</sub> = 5V			1	μA	
	(CD, PSEL)				1		<u> </u>
V <sub>IL</sub>	Input low threshold					0.4	V
V <sub>IH</sub>	Input high threshold			1.4			V
R <sub>PULLDOWN</sub>	CD pull-down resistance	CD Only		100		kΩ	

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## **ELECTRICAL CHARACTERISTICS (continued)**

Circuit of Figure 1,  $V_{UVLO} < V_{IN} < V_{OVP}$  AND  $V_{IN} > V_{BAT} + V_{SLP}$ ,  $T_J = -40^{\circ}C$  to 125°C and  $T_J = 25^{\circ}C$  for typical values (unless otherwise noted)

	PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT	
	Deglitch for CD and PSEL	CD or PSEL rising/falling		100		μs	
PROTECTIO	N				P	<b>1</b>	
V <sub>UVLO</sub>	IC active threshold voltage	V <sub>IN</sub> rising	3.2	3.3	3.4	V	
V <sub>UVLO_HYS</sub>	IC active hysteresis	$V_{\text{IN}}$ falling from above $V_{\text{UVLO}}$			300		mV
V <sub>BATUVLO</sub>	Battery Undervoltage Lockout threshold	V <sub>BAT</sub> falling, 100mV Hysteresis			2.4	2.6	V
V <sub>SLP</sub>	Sleep-mode entry threshold, $V_{IN}$ - $V_{BAT}$	2.0 V < $V_{BAT}$ < $V_{BATREG}$ , $V_{IN}$ falling		0	40	120	mV
t <sub>DGL(BAT)</sub>	Deglitch time, BAT above $V_{\text{BATUVLO}}$ before SYS starts to rise				1.2		ms
$V_{SLP_HYS}$	Sleep-mode exit hysteresis	$V_{\text{IN}}$ rising above $V_{\text{SLP}}$		40	100	190	mV
t <sub>DGL(VSLP)</sub>	Deglitch time for supply rising above $V_{SLP} + V_{SLP\_HYS}$	Rising voltage, 2-mV over drive, t <sub>RISE</sub> =100	Ins		30		ms
			bq24260	10.1	10.5	10.9	
V <sub>OVP</sub>	Input supply OVP threshold voltage	IN rising, 100mV hysteresis	bq24261	13.6	14	14.4	V
			bq24262	6.25	6.5	6.75	
V <sub>BATGD</sub>	Good Battery Monitor Threshold (BQ24260/1 only)	V <sub>IN</sub> Rising		3.51	3.7	3.89	V
t <sub>DGL(BUCK_OV</sub> P)	Deglitch time, VIN OVP in Buck Mode	IN falling below V <sub>OVP</sub>			30		ms
V <sub>BOVP</sub>	Battery OVP threshold voltage	$V_{\text{BAT}}$ threshold over $V_{\text{OREG}}$ to turn off charge	ger during charge	1.03 × V <sub>BATREG</sub>	1.05 × V <sub>BATREG</sub>	1.07 × V <sub>BATREG</sub>	v
V <sub>BOVP_HYS</sub>	V <sub>BOVP</sub> hysteresis	Lower limit for $V_{\text{BAT}}$ falling from above $V_{\text{BC}}$	Lower limit for $V_{\text{BAT}}$ falling from above $V_{\text{BOVP}}$				% of V <sub>BATREG</sub>
t <sub>DGL(BOVP)</sub>	BOVP Deglitch	Battery entering/exiting BOVP	Battery entering/exiting BOVP				ms
ICBCLIMIT	Cycle-by-cycle current limit	V <sub>SYS</sub> shorted		4.1	4.5	4.9	А
T <sub>SHTDWN</sub>	Thermal trip				150		°C
	Thermal hysteresis				10		
T <sub>REG</sub>	Thermal regulation threshold	Input current begins to cut off			125		°C
	Safety Timer Accuracy			-20%		20%	
PWM	T						
R <sub>DSON Q1</sub>	Internal top MOSFET on-	YFF Package: Measured from IN to SW			75	120	mΩ
- D30N_Q1	resistance	RGE Package: Measured from IN to SW			80	135	mΩ
R <sub>DSON_Q2</sub>	Internal bottom N-channel	YFF Package: Measured from SW to PGN	1D		75	115	mΩ
· -D30N_Q2	MOSFET on-resistance	RGE Package: Measured from SW to PGI	ND		80	135	mΩ
f <sub>OSC</sub>	Oscillator frequency			1.35	1.5	1.65	MHz
D <sub>MAX</sub>	Maximum duty cycle				95		%
D <sub>MIN</sub>	Minimum duty cycle			0			
	ACK NTC MONITOR (1)					T	1
V <sub>HOT</sub>	High temperature threshold	V <sub>TS</sub> falling, 2% V <sub>DRV</sub> Hysteresis		27.3	30	32.6	%V <sub>DRV</sub>
V <sub>WARM</sub>	Warm temperature threshold	V <sub>TS</sub> falling, 2% V <sub>DRV</sub> Hysteresis		36.0	38.3	41.2	%V <sub>DRV</sub>
V <sub>COOL</sub>	Cool temperature threshold	V <sub>TS</sub> rising, 2% V <sub>DRV</sub> Hysteresis		54.7	56.4	58.1	%V <sub>DRV</sub>
V <sub>COLD</sub>	Low temperature threshold	V <sub>TS</sub> rising, 2% V <sub>DRV</sub> Hysteresis	58.2	60	61.8	%V <sub>DRV</sub>	
TSOFF	TS Disable threshold	V <sub>TS</sub> rising, 4% V <sub>DRV</sub> Hysteresis	80		85	%V <sub>DRV</sub>	
t <sub>DGL(TS)</sub>	Deglitch time on TS change	Applies to $V_{\text{HOT}},V_{\text{WARM}},V_{\text{COOL}}$ and $V_{\text{COLD}}$			50		ms
							1
V <sub>IH</sub>	Input low threshold level	V <sub>PULL-UP</sub> =1.8V, SDA and SCL		1.3			V
V <sub>IL</sub>	Input low threshold level	V <sub>PULL-UP</sub> =1.8V, SDA and SCL				0.4	V
V <sub>OL</sub>	Output low threshold level	IL=5mA, sink current				0.4	V
I <sub>BIAS</sub>	High-Level leakage current	V <sub>PULL-UP</sub> =1.8V, SDA and SCL				1	μA
t <sub>WATCHDOG</sub>				30	50		S



## **ELECTRICAL CHARACTERISTICS (continued)**

Circuit of Figure 1,  $V_{UVLO} < V_{IN} < V_{OVP}$  AND  $V_{IN} > V_{BAT} + V_{SLP}$ ,  $T_J = -40^{\circ}C$  to 125°C and  $T_J = 25^{\circ}C$  for typical values (unless otherwise noted)

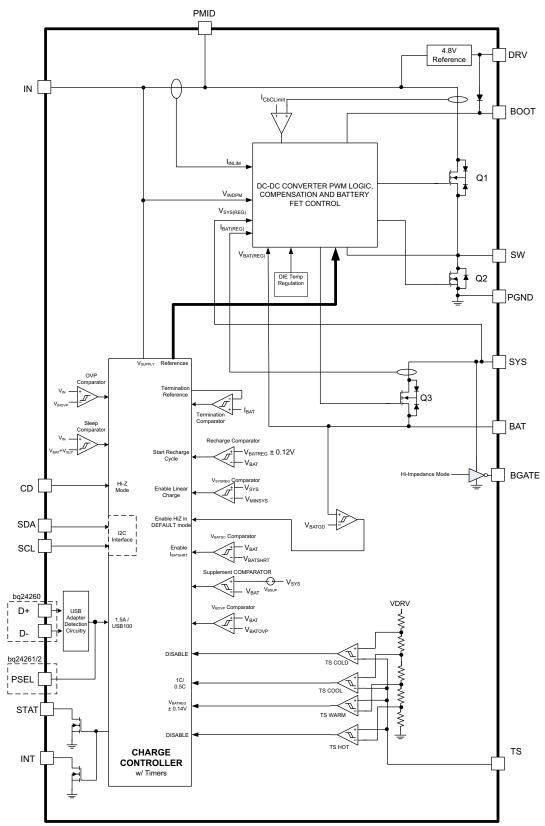
	PARAMETER	TEST CONDITIONS			TYP	MAX	UNIT
t <sub>I2CRESET</sub>					700		ms
OTG BOOST	SUPPLY						-
I <sub>QBAT_ BOOST</sub>	Quiescent current during boost mode (BAT pin)	3.3V <v<sub>BAT&lt;4.5V, no switching</v<sub>				100	μA
	Battery voltage range for specified boost operation	VBAT falling		3.3		4.5	v
V <sub>IN_BOOST</sub>	Boost output voltage (to pin VBUS)	3.3V <v<sub>BAT&lt;4.5V over line and load</v<sub>		4.95	5.05	5.2	v
1	Maximum output current for	3.3V <v<sub>BAT&lt;4.5V</v<sub>	BOOST_ILIM = 1	1000			mA
BO	boost	3.3V <vbat<4.3v boost_il<="" td=""><td>BOOST_ILIM = 0</td><td>500</td><td></td><td></td><td>IIIA</td></vbat<4.3v>	BOOST_ILIM = 0	500			IIIA
	Cycle by cycle current limit		BOOST_ILIM = 1		4		
I <sub>BLIMIT</sub>	for boost (measured at low- side FET)	3.3V <v<sub>BAT&lt;4.5V</v<sub>	BOOST_ILIM = 0		2		A
VBOOSTOVP	Over voltage protection threshold for boost (IN pin)	Signals fault and exits boost mode		5.8	6	6.2	v
t <sub>DGL(BOOST_O</sub> VP)	Deglitch Time, VIN OVP in Boost Mode				170		μs
V <sub>BURST(ENT)</sub>	Upper V <sub>IN</sub> voltage threshold to enter burst mode (stop switching)			5.1	5.2	5.3	v
V <sub>BURST(EXIT)</sub>	Lower V <sub>BUS</sub> voltage threshold to exit burst mode (start switching)			4.9	5	5.1	v

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### **Block Diagrams**





8



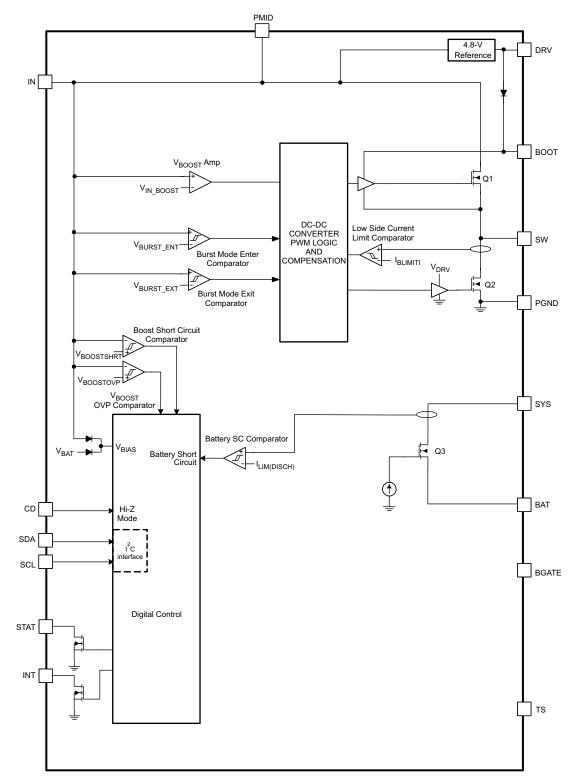
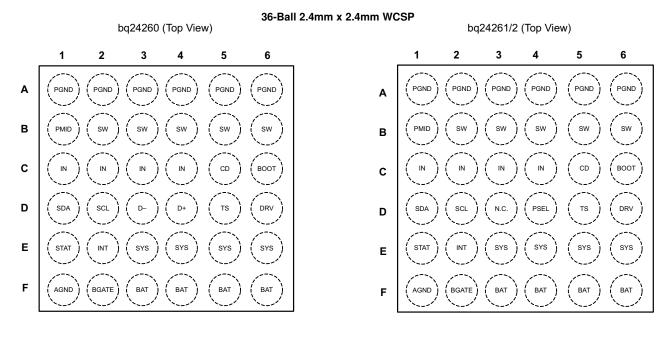


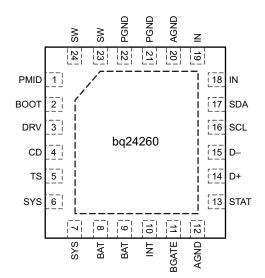
Figure 2. Block Diagram in Boost Mode

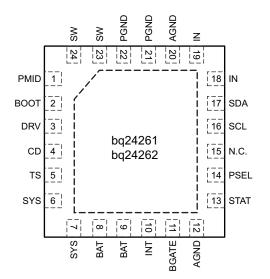


## **PIN CONFIGURATION**



24-Pin 4mm × 4mm QFN (Top View)







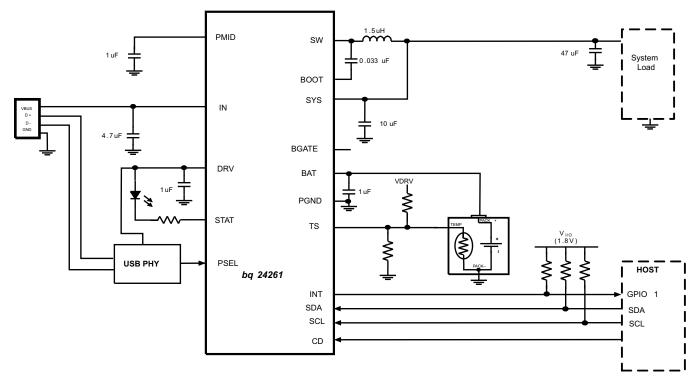
## **Pin Configurations**

PIN		UMBER 24260		JMBER 261/2	I/O	DESCRIPTION
NAME	YFF	RGE	YFF	RGE		
AGND	F1	12, 20	F1	12, 20		Analog Ground. Connect to the thermal pad (for QFN only) and the ground plane of the circuit.
BAT	F3-F6	8, 9	F3-F6	8, 9	I/O	Battery Connection. Connect to the positive terminal of the battery. Bypass BAT to GND with at least 1µF of ceramic capacitance. See Applicaton section for additional details.
BGATE	F2	11	F2	11	0	External Discharge MOSFET Gate Connection. BGATE drives an external P-Channel MOSFET to provide a very low resistance discharge path. Connect BGATE to the gate of the external MOSFET. BGATE is low during high impedance mode or when no input is connected. If no external FET is required, leave BGATE disconnected. Do not connect BGATE to GND.
BOOT	C6	2	C6	2	I	High Side MOSFET Gate Driver Supply. Connect 0.033µF of ceramic capacitance (voltage rating > 10V) from BOOT to SW to supply the gate drive for the high side MOSFET.
CD	C5	4	C5	4	I	IC Hardware Disable Input. Drive CD high to place the bq24260 in high-z mode. Drive CD low for normal operation. CD is pulled low internally with $100k\Omega$
D+	D4	14	-	-	I	D+ and D- Connections for USB Input Adapter Detection. When a source is initially connected
D-	D3	15	-	-	I	to the input during DEFAULT mode, and a short is detected between D+ and D-, the input current limit is set to 1.5A. If a short is not detected, the USB100 mode is selected.
DRV	D6	3	D6	3	0	Gate Drive Supply. DRV is the bias supply for the gate drive of the internal MOSFETs. Bypass DRV to PGND with at least 1µF of ceramic capacitance. DRV may be used to drive external loads up to 10mA. DRV is active whenever the input is connected and $V_{IN} > V_{UVLO}$ and $V_{IN} > (V_{BAT} + V_{SLP})$ .
IN	C1-C4	19	C1-C4	19	I	DC Input Power Supply. IN is connected to the external DC supply (AC adapter or USB port). Bypass IN to PGND with at least a $4.7\mu$ F of ceramic capacitance.
INT	E2	10	E2	10	0	Status Output. INT is an open-drain output that signals charging status and fault interrupts. INT pulls low during charging. INT is high impedance when charging is complete, disabled or the charger is in high impedance mode. When a fault occurs, a 128µs pulse is sent out as an interrupt for the host. INT is enabled /disabled using the EN_STAT bit in the control register. Connect INT to a logic rail through a 100k $\Omega$ resistor to communicate with the host processor.
PGND	A1-A6	21,22	A1-A6	21,22	-	Ground terminal. Connect to the thermal pad (for QFN only) and the ground plane of the circuit.
PMID	B1	1	B1	1	I	High Side Bypass Connection. Connect at least 1µF of ceramic capacitance from PMID to PGND as close to the PMID and PGND pins as possible.
PSEL	-	-	D4	14	I	Hardware Input Current Limit. In DEFAULT mode, PSEL selects the input current limit. Drive PSEL high to select USB100 (bq24261) or USB500 (bq24262A) mode, drive PSEL low to select 1.5A mode.
SCL	D2	16	D2	16	I	$I^2C$ Interface Clock. Connect SCL to the logic rail through a $10k\Omega$ resistor.
SDA	D1	17	D1	17	I/O	$I^2C$ Interface Data. Connect SDA to the logic rail through a $10k\Omega$ resistor.
STAT	E1	13	E1	13	0	Status Output. STAT is an open-drain output that signals charging status and fault interrupts. STAT pulls low during charging. STAT is high impedance when charging is complete, disabled or the charger is high impedance mode. When a fault occurs, a 128µs pulse is sent out as an interrupt for the host. STAT is enabled /disabled using the EN_STAT bit in the control register. Connect STAT to a logic rail using an LED for visual indication or through a 100k $\Omega$ resistor to communicate with the host processor.
SW	B2-B6	23, 24	B2-B6	23, 24	0	Inductor Connection. Connect to the switched side of the external inductor. The inductance must be between 1.5 $\mu$ H and 2.2 $\mu$ H.
SYS	E3-E6	6, 7	E3-E6	6, 7	I	System Voltage Sense and Charger FET Connection. Connect SYS to the system output at the output bulk capacitors. Bypass SYS locally with at least $10\mu F$ of ceramic capacitance. The SYS rail must have at least $20\mu F$ of total capacitance for stable operation. See Application section for additional details.
TS	D5	5	D5	5	I	Battery Pack NTC Monitor. Connect TS to the center tap of a resistor divider from DRV to GND. The NTC is connected from TS to GND. The TS function provides 4 thresholds for JEITA compatibility. TS faults are reported by the $l^2$ C interface. Pull TS high to V <sub>DRV</sub> to disable the TS function if unused. See the <i>NTC Monitor</i> section for more details on operation and selecting the resistor values.
Thermal PAD	_	-	_	-	-	There is an internal electrical connection between the exposed thermal pad and the PGND pin of the device. The thermal pad must be connected to the same potential as the PGND pin on the printed circuit board. Do not use the thermal pad as the primary ground input for the device. PGND pin must be connected to ground at all times.

TEXAS INSTRUMENTS

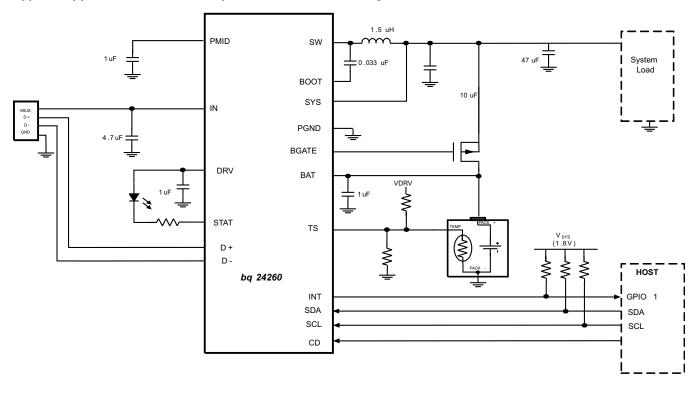
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## **Typical Application Circuit**



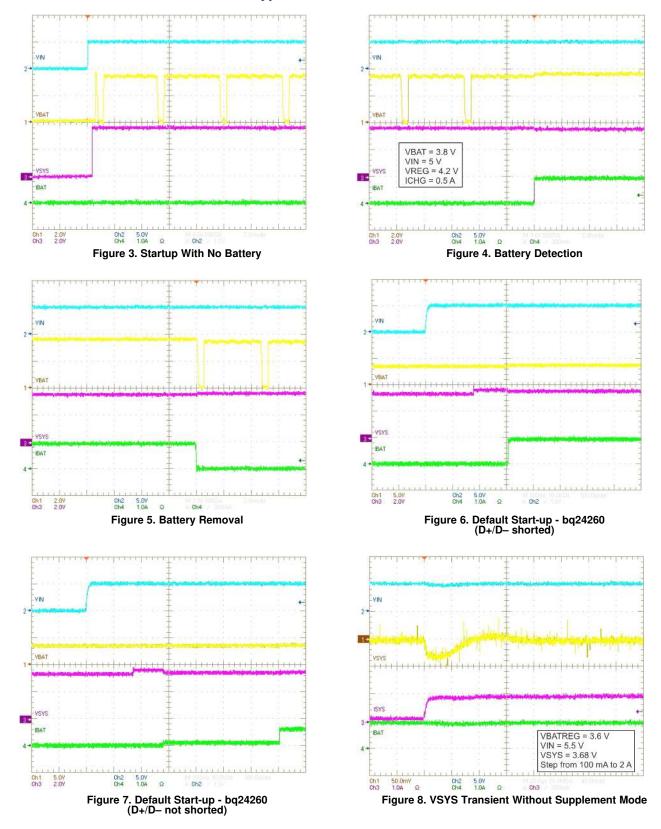
Typical Application Circuit 1 – bq24261, No External Discharge FET

Typical Application Circuit 2 – bq24260, External Discharge FET





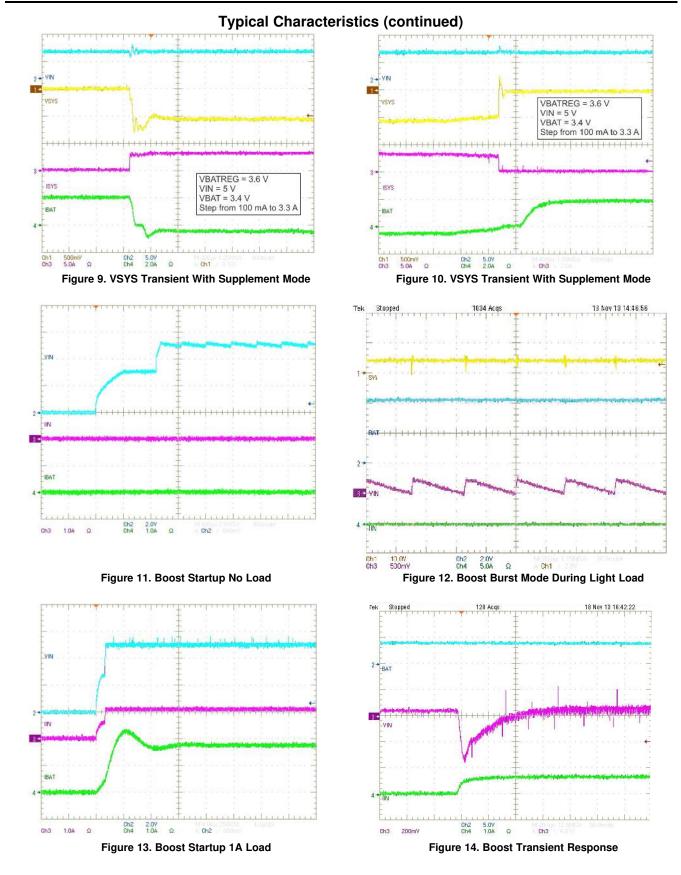
**Typical Characteristics** 



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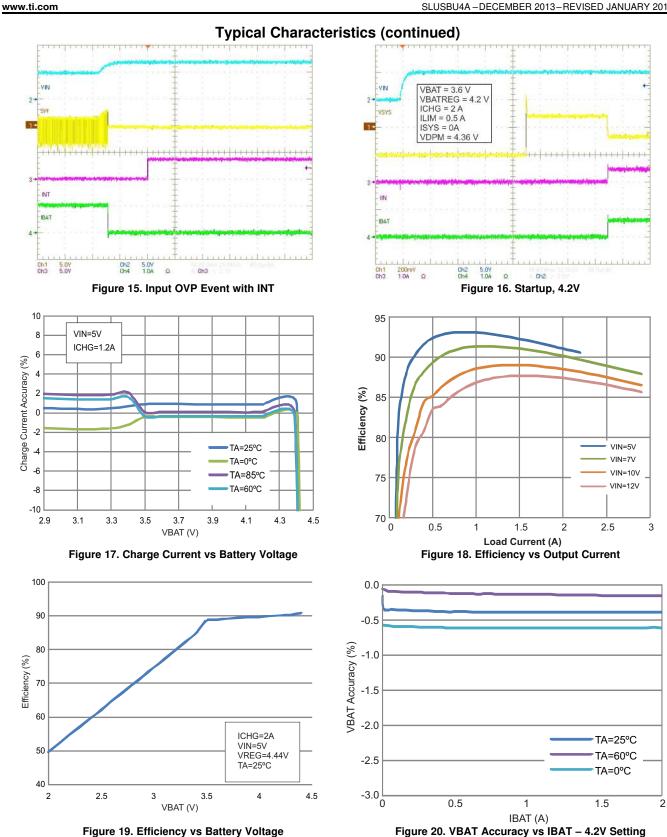
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## bq24260 bq24261 bq24262A SLUSBU4A – DECEMBER 2013 – REVISED JANUARY 2014

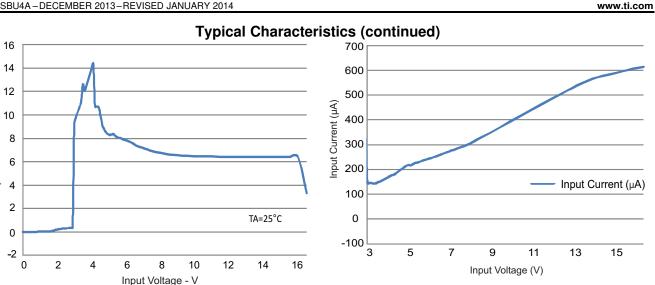


Figure 22. Input IQ with Hi-Z Enabled

**EXAS** 

INSTRUMENTS

## **Detailed Description**

Figure 21. Input IQ - No Battery, No System

Input Current - mA

#### **High Impedance Mode**

High Impedance mode (Hi-Z mode) is the low quiescent current state for the bq2426x. During Hi-Z mode, the buck converter is off, and the battery FET and BGATE are on. SYS is powered by BAT. The bq2426x is in Hi-Z mode when  $V_{IN} < V_{UVLO}$ , the HZ\_MODE bit in the I<sup>2</sup>C is '1' or the CD pin is driven high. Hi-Z mode resets the safety timer.

The bq2426x contains a CD input that is used to disable the IC and place the bq2426x into high-impedance mode. Drive CD low to enable the bq2426x and enter normal operation. Drive CD high to disable charge and place the bq2426x into high-impedance mode. CD is internally pulled down to PGND with a  $100k\Omega$  resistor. When exiting Hi-Z mode, charging resumes in approximately 110ms.

#### **Battery Only Connected**

When the battery is connected with no input source, the battery FET is turned on. After the battery rises above  $V_{BATUVLO}$  and the deglitch time,  $t_{DGL(BAT)}$ , the SYS output starts to rise. In this mode, the current is not regulated; however, there is a short circuit current limit. If the short circuit limit ( $I_{LIM(DISCHG)}$ ) is reached for the deglitch time ( $t_{DGL(SC)}$ ), the battery FET is turned off for the recovery time ( $t_{REC(SC)}$ ). After the recovery time, the battery FET is turned on to test and see if the short has been removed. If it has not, the FET turns off and the process repeats until the short is removed. This process protects the internal FET from over current. If an external FET is used for discharge, the body diode prevents the load on SYS from being disconnected from the battery and  $t_{DGL(BAT)}$  is not applicable.

#### Input Connected

#### Input Voltage Protection in Charge Mode

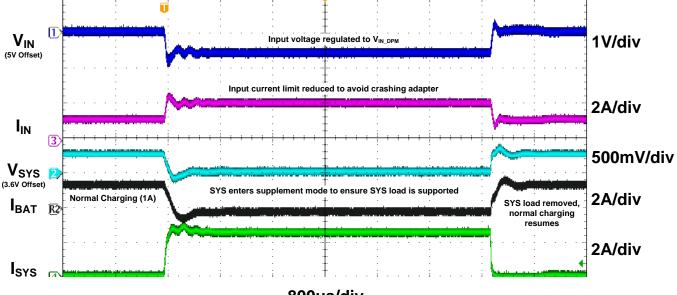
#### Sleep Mode

The bq2426x enters the low-power sleep mode if the voltage on V<sub>IN</sub> falls below sleep-mode entry threshold, V<sub>BAT</sub>+V<sub>SLP</sub>, and V<sub>IN</sub> is higher than the undervoltage lockout threshold, V<sub>UVLO</sub>. In sleep mode, the input is isolated from the battery. This feature prevents draining the battery during the absence of V<sub>IN</sub>. When V<sub>IN</sub> < V<sub>BAT</sub>+ V<sub>SLP</sub>, the bq2426x turns off the PWM converter, turns the battery FET and BGATE on, sends a single 128µs pulse on the STAT and INT outputs and the STATx and FAULT\_x bits of the status registers are updated in the l<sup>2</sup>C. Once V<sub>IN</sub> > V<sub>BAT</sub>+ V<sub>SLP</sub>, the STATx bits are cleared and the device initiates a new charge cycle. The FAULT\_x bits are not cleared until they are read in the l<sup>2</sup>C and the sleep condition no longer exists.

#### Input Voltage Based Dynamic Power Management (V<sub>IN</sub>-DPM)



During normal charging process, if the input power source is not able to support the programmed or default charging current, the supply voltage deceases. Once the supply drops to  $V_{IN\_DPM}$  (default 4.2V), the charge current limit is reduced to prevent the further drop of the supply. When the IC enters this mode, the charge current is lower than the set value and the DPM\_STATUS bit is set. This feature ensures IC compatibility with adapters with different current capabilities without a hardware change. Figure 23 shows the  $V_{IN}$ -DPM behavior to a current limited source. In this figure the input source has a 2A current limit and the device is charging at 1A. A 2.5A load transient then occurs on  $V_{SYS}$  causing the adapter to hit its current limit and collapse, while  $V_{SYS}$  goes from  $V_{SYSREG(LO)}$  to  $V_{MINSYS}$ . If the 2X timer is set, the safety timer is extended while  $V_{IN}$ -DPM is active. Additionally, termination is disabled.



## 800us/div

Figure 23. bq24260 V<sub>IN</sub>-DPM

#### Input Over-Voltage Protection

The built-in input over-voltage protection protects the bq2426x and downstream components connected to SYS and/or BAT against damage from overvoltage on the input supply (Voltage from V<sub>IN</sub> to PGND). When V<sub>IN</sub> > V<sub>OVP</sub>, the bq2426x turns off the PWM converter immediately. After the deglitch time t<sub>DGL(BUCK\_OVP</sub>), an OVP fault is determined to exist. During the OVP fault, the bq2426x turns the battery FET and BGATE on, sends a single 128µs pulse is sent on the STAT and INT outputs and the STATx and FAULT\_x bits are updated in the l<sup>2</sup>C. Once the OVP fault is removed, the STATx bits are cleared and the device returns to normal operation. The FAULT\_x bits are not cleared until they are read in the l<sup>2</sup>C after the OVP condition no longer exists.

The OVP threshold for the bq24260 is 10.5V for operation from standard adapters while the bq24261 is set to 14V to enable operation from 12V sources. The bq24262A OVP is set to 6.5V to operate from standard USB sources.

### Charge Profile

When a valid input source is connected ( $V_{IN} > V_{UVLO}$  and  $V_{BAT} + V_{SLP} < V_{IN} < V_{OVP}$ ), the  $\overline{CE}$  bit in the control register determines whether a charge cycle is initiated. By default, the bq24260 and bq24262A enable the charge cycle when a valid input source is connected while the bq24261 does not ( $\overline{CE}$ =1 by default). When the  $\overline{CE}$  bit is 1 and a valid input source is connected, the battery  $\underline{FET}$  is turned off and the SYS output is regulated to VSYSREG(HI). A charge cycle is initiated when the  $\overline{CE}$  bit is written to a 0.





The bq2426x supports a precision Li-Ion or Li-Polymer charging system for single-cell applications. Charging is done through the internal battery MOSFET. There are 6 loops that influence the charge current; constant current loop (CC), constant voltage loop (CV), thermal regulation loop, minimum system voltage loop (MINSYS), input current limit and  $V_{IN}$ -DPM. During the charging process, all six loops are enabled and the one that is dominant takes control. The minimum system output feature regulates the system voltage to  $V_{SYSREG(LO)}$ , so that startup is enabled even for a missing or deeply discharged battery. Figure 24 shows a typical charge profile including the minimum system output voltage feature.

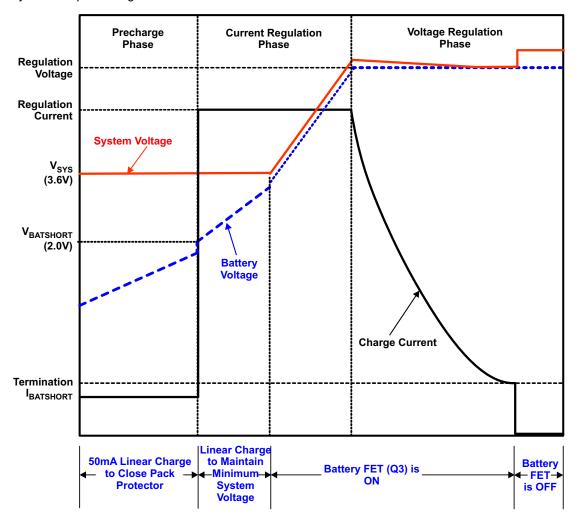


Figure 24. Typical Charging Profile of bq2426x with Termination Enabled

### **Battery Charging Process**

When the battery is deeply discharged or shorted, the bq2426x applies a  $I_{BATSHRT}$  current to close the battery protector switch and bring the battery voltage up to acceptable charging levels. During this time, the battery FET is off and the system output is regulated to  $V_{SYSREG(LO)}$ . Once the battery rises above  $V_{BATSHRT}$ , the charge current is regulated to the value set in the  $I^2C$  register. The battery FET is linearly regulated to maintain the system voltage at  $V_{SYSREG(LO)}$ . Under normal conditions, the time spent in this region is a very short percentage of the total charging time, so the linear regulation of the charge current does not affect the overall charging efficiency for very long. If the die temperature does heat up, the thermal regulation loop reduces the input current to maintain a die temperature at 125°C. If the current limit for the SYS output is reached (limited by the input current limit,  $V_{IN}$ -DPM, or 100% duty cycle), the SYS output drops to the  $V_{MINSYS}$  output voltage. When this happens, the charge current is reduced to ensure the system is supplied with all the current that is needed while maintaining the minimum system voltage. If the charge current is reduced to 0mA, pulling further current from SYS causes the output to fall to the battery voltage and enter supplement mode (see the "Dynamic Power Path Management" section for more details).



Once the battery is charged enough that the system voltage rises above  $V_{SYSREG(LO)}$  (approximately 3.5V), the battery FET is turned on fully and the battery is charged with the full programmed charge current set by the I<sup>2</sup>C interface, I<sub>CHARGE</sub>. The charge current is regulated to I<sub>CHARGE</sub> until the voltage between BAT and PGND reaches the regulation voltage. The voltage between BAT and PGND is regulated to V<sub>BATREG</sub> (CV mode) while the charge current naturally tapers down as shown in Figure 24. During CV mode, the SYS output remains connected to the battery. The impedance of the battery FET is increased to 4x of the fully on value when IBAT falls below ~350mA to provide increased accuracy during termination. This will show a small rise in the SYS voltage when the R<sub>DSON</sub> increases below ~350mA.

When termination is enabled (TE bit is '1'), the bq2426x monitors the charging current during the CV mode. Once the charge current tapers down to the termination threshold,  $I_{TERM}$ , and the battery voltage is above the recharge threshold, the bq2426x terminates charge, turns off the battery charging FET and enters battery detection (see Battery Detection section for more details). The system output is regulated to the V<sub>SYSREG(HI)</sub> and supports the full current available from the input. The battery supplement mode is available to supply any SYS load that cannot be supported by the input source (see the "Dynamic Power Path Management" section for more details). The termination current level is programmable. To disable the charge current termination, the host sets the charge termination bit (TE) of charge control register to 0. Refer to  $I^2C$  section for details. When termination is disabled,  $V_{BAT}$  is continuously regulated to  $V_{BATREG}$ . Termination is also disabled when any loop is active other than CC or CV. This includes  $V_{INDPM}$ , input current limit, or thermal regulation. Termination is also disabled during TS warm/cool conditions and when the LOW\_CHG bit is set to '1'.

A charge cycle is initiated when one of the following conditions is detected:

- 1. The battery voltage falls below the  $V_{BATREG}$ - $V_{RCH}$  threshold.
- 2. IN Power-on reset (POR)
- 3. CE bit toggle or RESET bit is set (Host controlled)
- 4. CD pin is toggled

### Charge Time Optimizer

The CC to CV transition is enhanced in the bq2426x architecture. The "knee" between CC and CV is very sharp. This enables the charger to remain in CC mode as long as possible before beginning to taper the charge current (CV mode). This provides a decrease in charge time as compared to older topologies.

#### **Battery Detection**

When termination conditions are met, a battery detection cycle is started. During battery detection,  $I_{DETECT}$  is pulled from  $V_{BAT}$  for  $t_{DETECT(SNK)}$  to verify there is a battery. If the battery voltage remains above  $V_{DETECT}$  for the full duration of  $t_{DETECT(SNK)}$ , a battery is determined to present and the IC enters "Charge Done". If  $V_{BAT}$  falls below  $V_{DETECT}$ , a "Battery Not Present" fault is signaled, the charge parameters are reset ( $V_{BATREG}$ ,  $I_{CHARGE}$  and  $I_{TERM}$ ) and battery detection continues. The next cycle of battery detection, the bq2426x turns on  $I_{BATSHRT}$  for  $t_{DETECT(SRC)}$ . If  $V_{BAT}$  rises to  $V_{DET(SRC1)}$ , the current source is turned off and a "No Battery" condition is registered. In order to keep VBAT high enough to close the battery protector, the current source turns on if  $V_{BAT}$  falls to  $V_{DET(SRC2)}$ . The source cycle continues for  $t_{DETECT(SRC)}$ . After  $t_{DETECT(SRC)}$ , the battery detection continues through another current sink cycle. Battery detection continues until charge is disabled, the bq2426x enters high-z mode or a battery is detected. Once a battery is detected, the fault status clears and a new charge cycle begins. With no battery connected, the BAT output will transition from VRCH to PGND with a high period of  $t_{DETECT(SRC)}$  and a low period of  $t_{DETECT(SNK)}$ . See Figure 4 in the Typical Operating Characteristics. Battery detection is not performed when termination is disabled.

#### Battery Overvoltage Protection (BOVP)

If the battery is ever above the battery OVP threshold ( $V_{BOVP}$ ), the battery OVP circuit shuts the PWM converter off and the battery FET is turned on to discharge the battery to safe operating levels. A battery OVP most commonly occurs when the bq2426x returns to DEFAULT mode after a watchdog timer expiration or RESET bit written to '1'. In this condition, the  $V_{BATREG}$  is reset and may be below the battery voltage. Other conditions may be when the input is initially plugged in before I<sup>2</sup>C communication is established or TS WARM conditions or when writing the  $V_{BATREG}$  to less than the battery voltage. The battery OVP condition is cleared when the battery

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voltage falls below the hysteresis of  $V_{BOVP}$  either by the battery discharging or writing the  $V_{BATREG}$  to a higher value. When a battery OVP event exists for  $t_{DGL(BOVP)}$ , the bq2426x turns the battery FET and BGATE on, sends a single 128µs pulse on the STAT / INT outputs and the STATx and FAULT\_x bits are updated in the I<sup>2</sup>C. Once the BOVP fault is removed, the STATx bits are cleared and the device returns to normal operation. The FAULT\_x bits are not cleared until they are read in the I<sup>2</sup>C after the BOVP condition no longer exists.

### Dynamic Power Path Management

The bq2426x features a SYS output that powers the external system load connected to the battery. This output is active whenever a valid source is connected to IN or BAT. When  $V_{SYS} > V_{SYSREG(LO)}$ , the SYS output is connected to  $V_{BAT}$ . If the battery voltage falls to  $V_{MINSYS}$ ,  $V_{SYS}$  is regulated to the  $V_{SYSREG(LO)}$  threshold to maintain the system output even with a deeply discharged or absent battery. In this mode, the SYS output voltage is regulated by the buck converter and the battery FET is linearly regulated to regulate the charge current into the battery. The current from the supply is shared between charging the battery and powering the system load at SYS. The dynamic power path management (DPPM) circuitry of the bq2426x monitors the current limits continuously and if the SYS voltage falls to the  $V_{MINSYS}$  threshold, it adjusts charge current to maintain the minimum system voltage and supply the load on SYS. If the charge current is reduced to zero and the load increases further, the bq2426x enters battery supplement mode. During supplement mode, the battery FET is turned on and  $V_{BAT} = V_{SYS}$  while the battery supplements the system load.

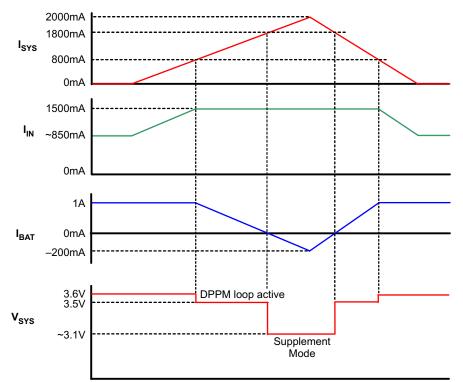


Figure 25. Example DPPM Response (V<sub>Supply</sub>=5V, V<sub>BAT</sub> = 3.1V, 1.5A Input current limit)

### Battery Discharge FET (BGATE)

The bq2426x contains a MOSFET driver to drive an external discharge FET between the battery and the system output. This external FET provides a low impedance path for supplying the system from the battery. Connect BGATE to the gate of the external discharge P-channel MOSFET. BGATE is on (low) under the following conditions:

- 1. No input supply connected.
- 2. HZ\_MODE = 1
- 3. CD pin = 1



ba24262/

DEFAULT mode is used when I2C communication is not available. DEFAULT mode is entered in the following situations:

- 1. When the charger is enabled and  $V_{BAT} < V_{BATGD}$  before I<sup>2</sup>C communication is established
- 2. When the watchdog timer expires without a reset from the I<sup>2</sup>C interface
- 3. The RESET bit is written in the  $I^2C$  register

In DEFAULT mode, the I<sup>2</sup>C registers are reset to the default values. The 2 minute safety timer is reset and starts when DEFAULT mode is entered if a charge cycle is underway. The default value for  $V_{BATREG}$  is 3.6V for the BQ24260/1 and 4.2V for the bq24262A. The default value for  $I_{CHARGE}$  is 1A. For the bq24260, the input current limit is determined by the D+/D- detection (See *D*+/*D*- *Based Adapter Detection* section). For the bq24261 and bq24262A, the input current limit in DEFAULT mode is set by PSEL. (See *Power Source Selector Input* section) DEFAULT mode is exited by writing to the I<sup>2</sup>C interface. Note that if termination is enabled and charging has terminated, a new charge cycle is NOT initiated when entering DEFAULT mode.

### Good Battery Monitor

The bq2426x contains a good battery monitor circuit that places the bq2426x into high-z mode if the battery voltage is above the  $V_{BATGD}$  threshold while in DEFAULT mode. This function is used to enable compliance to the battery charging standard that prevents charging from an un-enumerated USB host while the battery is above the good battery threshold. If the bq2426x is in HOST mode, it is assumed that USB host has been enumerated and the good battery circuit has no effect on charging. Any write to the i2c places the bq2426x in HOST mode and clears the high-impedance mode condition. The HZ\_MODE bit is not updated during this condition.

### D+/D- Based Adapter Detection (D+/D-, bq24260 only)

The bq24260 contains a D+/D- based adapter detection circuit that is used to program the input current limit for the input during DEFAULT mode. D+/D- is only performed in DEFAULT mode unless forced by the D+/D-\_EN bit in host mode.

By default the input current limit is set to 100mA. During DEFAULT mode, when the input source is connected, the bq24260 performs an adapter detection to determine if it is connected to a USB port or dedicated charger. The adapter detection starts with a connection detection as described in the USB Battery Charging Specification ver 1.2 (BC1.2). Once a connection is detected, the adapter detection is performed. If a connection is not detected within 500ms, the adapter detection begins. The adapter detection runs as described in BC1.2. If a CDP/DCP is detected, the input current limit is increased to 1.5A. If an SDP is detected, the current limit remains at 100mA, until changed in the I<sup>2</sup>C.

D+/D- is initiated at any time by the host by setting the D+/D- EN bit in the  $l^2C$  to 1. After detection is complete the D+/D- EN bit is automatically reset to 0 and the detection circuitry is disconnected from the D+ D- pins to avoid interference with USB data transfer. When a command is written to change the input current limit in the  $l^2C$ , this overrides the current limit selected by D+/D- detection.

#### Power Source Selector Input (PSEL, bq24261/2 only)

The bq24261/2 contains a PSEL input that is used to program the input current limit during DEFAULT mode. Drive PSEL high to indicate a USB source is connected to the input and program the 100mA (bq24261) or 500mA (bq24262A) current limit for IN. Drive PSEL low to indicate that an AC Adapter is connected to the input. When PSEL is low, the IC starts up with a 1.5A input current limit. Once an I<sup>2</sup>C write is done and the device is in HOST mode, the PSEL has no effect on the input current limit until the watchdog timer expires and returns the bq2426x to DEFAULT mode.

#### Safety Timer and Watchdog Timer in Charge Mode (bq24260/1 only)

At the beginning of charging process, the bq24260/1 starts the safety timer. This timer is active during the entire charging process. If charging has not terminated before the safety timer expires, the IC enters suspend mode where charging is disabled. When a safety timer fault occurs, a single 128µs pulse is sent on the STAT and INT outputs and the STATx and FAULT\_x bits of the status registers are updated in the I2C. The CE bit, Hi-Z mode, or power must be toggled in order to clear the safety timer fault. The safety timer duration is selectable using the TMR\_X bits in the Safety Timer Register/ NTC Monitor register. When the safety timer is active, changing the

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safety timer duration resets the safety timer. The bq2426x also contains a 2X\_TIMER bit that enables the 2x timer function to prevent premature safety timer expiration when the charge current is reduced by a load on SYS or a NTC condition. When 2X\_TIMER is enabled, the timer runs at half speed when any loop is active other than CC or CV. This includes V<sub>INDPM</sub>, input current limit, or thermal regulation. The timer also runs at half speed during TS warm/cool conditions and when the LOW CHG bit is set to '1'.

In addition to the safety timer, the bq24260/1 contains a 30-second ( $t_{WATCHDOG}$ ) watchdog timer that monitors the host through the l<sup>2</sup>C interface. Once a write is performed on the l<sup>2</sup>C interface, a watchdog timer is started. The watchdog timer is reset by the host using the l<sup>2</sup>C interface. This is done by writing a "1" to the reset bit (TMR\_RST) in the control register. The TMR\_RST bit is automatically set to "0" when the watchdog timer is reset. This process must continue as long as the input is connected in order to maintain the register contents. If the watchdog timer expires, the IC enters DEFAULT mode where the default register values are loaded, the safety timer restarts at 2 minutes once charging continues. The l<sup>2</sup>C may be accessed again to reinitialize the desired values and restart the watchdog timer. The watchdog timer flow chart is shown in Figure 26.

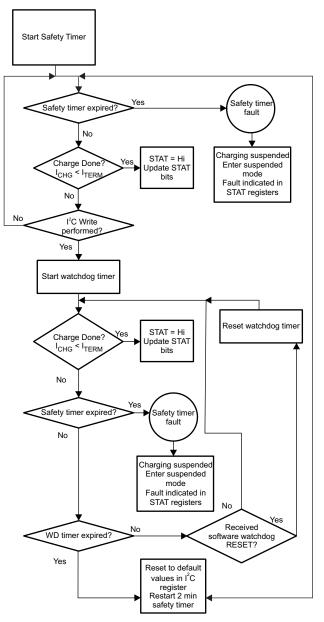


Figure 26. The Watchdog Timer Flow Chart for bq24260



## LDO Output (DRV)

The bq24260 contains a linear regulator (DRV) that is used to supply the internal MOSFET drivers and other circuitry. Additionally, DRV supplies up to 10mA external loads to power the STAT LED or the USB transceiver circuitry. The maximum value of the DRV output is 5.3V so it ideal to protect voltage sensitive USB circuits. The LDO is on whenever a supply is connected to the input of the bq24260. The DRV is disabled under the following conditions:

- 1.  $V_{SUPPLY} < UVLO$
- 2.  $V_{SUPPLY} < V_{BAT} + V_{SLP}$
- 3. Thermal Shutdown

## External NTC Monitoring (TS)

The I<sup>2</sup>C interface allows the user to easily implement the JEITA standard for systems where the battery pack thermistor is monitored by the host. Additionally, the bq24260 provides a flexible, voltage based TS input for monitoring the battery pack NTC thermistor. The voltage at TS is monitored to determine that the battery is at a safe temperature during charging. The JEITA specification is shown in Figure 27.

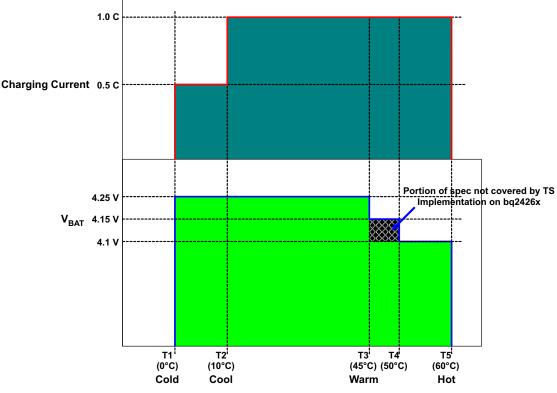


Figure 27. Charge Current During TS Conditions

To satisfy the JEITA requirements, four temperature thresholds are monitored; the cold battery threshold ( $T_{NTC} < 0^{\circ}C$ ), the cool battery threshold ( $0^{\circ}C < T_{NTC} < 10^{\circ}C$ ), the warm battery threshold ( $45^{\circ}C < T_{NTC} < 60^{\circ}C$ ) and the hot battery threshold ( $T_{NTC} > 60^{\circ}C$ ). These temperatures correspond to the V<sub>COLD</sub>, V<sub>COOL</sub>, V<sub>WARM</sub>, and V<sub>HOT</sub> thresholds in the EC table. Charging is suspended and timers are suspended when V<sub>TS</sub> < V<sub>HOT</sub> or V<sub>TS</sub> > V<sub>COLD</sub>. When V<sub>COOL</sub> < V<sub>TS</sub> < V<sub>COLD</sub>, the charging current is reduced to half of the programmed charge current. When V<sub>HOT</sub> < V<sub>TS</sub> < V<sub>WARM</sub>, the battery regulation voltage is reduced by 140mV from the programmed regulation threshold. The TS function is disabled by connecting TS directly to DRV (V<sub>TS</sub> > V<sub>TSOFF</sub>).

The TS function is voltage based for maximum flexibility. Connect a resistor divider from DRV to GND with TS connected to the center tap to set the threshold. The connections are shown in Figure 28. The resistor values are calculated using the following equations:

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**NSTRUMENTS** 

(1)

(2)

**FEXAS** 

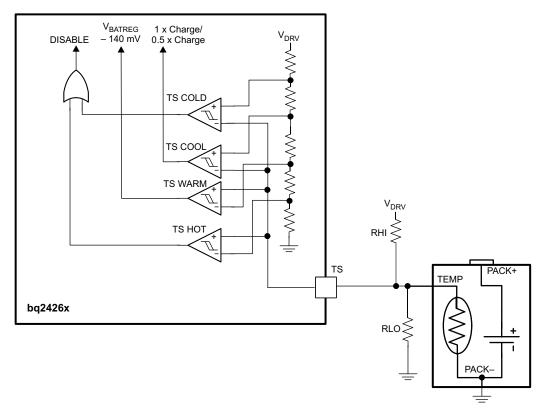
$$RLO = \frac{V_{DRV} \times RCOLD \times RHOT \times \left[\frac{1}{V_{COLD}} - \frac{1}{V_{HOT}}\right]}{RHOT \times \left[\frac{V_{DRV}}{V_{HOT}} - 1\right] - RCOLD \times \left[\frac{V_{DRV}}{V_{COLD}} - 1\right]}$$
$$RHI = \frac{\frac{V_{DRV}}{V_{COLD}} - 1}{\frac{1}{RLO} + \frac{1}{RCOLD}}$$

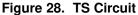
Where:

 $V_{COLD} = 0.60 \times V_{DRV}$  $V_{HOT} = 0.30 \times V_{DRV}$ RLO×RHI×0.564  $\mathsf{RCOOL} = \frac{1}{\mathsf{RLO} - \mathsf{RLO} \times 0.564 - \mathsf{RHI} \times 0.564}$ (3) RLO×RHI×0.383  $RWARM = \frac{1}{RLO - RLO \times 0.383 - RHI \times 0.383}$ (4)

Where RHOT is the NTC resistance at the hot temperature and RCOLD is the NTC resistance at cold temperature.

The WARM and COOL thresholds are not independently programmable. The COOL and WARM NTC resistances for a selected resistor divider are calculated using Equation 3 and Equation 4.







#### **Thermal Regulation and Protection**

During the charging process, to prevent overheating in the chip, bq2426x monitors the junction temperature,  $T_J$ , of the die and reduces the input current once  $T_J$  reaches the thermal regulation threshold,  $T_{REG}$ . The input current is reduced to zero when the junction temperature increases about 10°C above  $T_{REG}$ . Once the input current is reduced to 0, the system current is reduced while the battery supplements the load to supply the system. When the input current is completely reduced to 0 and  $T_J>125$ °C, this is may cause a thermal shutdown of the bq2426x if the die temperature rises too high. At any state, if  $T_J$  exceeds  $T_{SHTDWN}$ , bq24260 stops charging and disables the buck converter. During thermal shutdown mode, PWM is turned off, all timers are suspended, and a single 128µs pulse is sent on the STAT and INT outputs and the STATx and FAULT\_x bits of the status registers are updated in the l<sup>2</sup>C. The charge cycle resumes when  $T_J$  falls below  $T_{SHTDWN}$  by approximately 10°C.

### Charge Status Outputs (STAT, INT)

The STAT/INT output is used to indicate operation conditions for bq2426x. STAT/INT is pulled low during charging when EN\_STAT bit in the control register is set to "1". When charge is complete or disabled, STAT/INT is high impedance. When a fault occurs, a 128-µs pulse (interrupt) is sent out to notify the host. The status of STAT/INT during different operation conditions is summarized in Table 1. STAT/INT drives an LED for visual indication or can be connected to the logic rail for host communication. The EN\_STAT bit in the control register is used to enable/disable the charge status for STAT/INT. The interrupt pulses are unaffected by EN\_STAT and will always be shown.

CHARGE STATE	STAT and INT BEHAVIOR
Charge in progress and EN_STAT=1	Low
Other normal conditions	High-Impedance
Charge mode faults: Timer faults, sleep mode, VIN over voltage, VIN < UVLO or Sleep mode, BOVP, thermal shutdown, No Battery and Battery Temperature faults	128-µs pulse, then High Impedance

#### Table 1. STAT Pin Summary

### **Boost Mode Operation**

In HOST mode, when the operation mode bit (BOOST\_EN) in the control register is set to 1, bq2426x operates in boost mode and delivers 5V to IN to supply USB OTG devices connected to the USB connector. Boost operation can start with VBAT between 3.45V to 4.5V, and will maintain boost output until VBAT falls to 3.3V. IN supplies up to 1A to power these devices. It is not recommended to operate boost mode when the battery voltage is less than 3.3V. Proper operation is not guaranteed.

#### Chip Disable Input During Boost Mode (CD)

The bq2426x contains a CD input that is used to disable the IC and place the bq2426x into high-impedance mode. CD must be low to enter boost mode. Driving CD high during boost mode places the bq2426x into high-z mode and resets the BOOST\_EN bit in the I<sup>2</sup>C. When CD is high, the buck converter is off, and the battery FET and BGATE are turned on. CD is internally pulled down to GND with a 100k $\Omega$  resistor.

#### PWM Controller in Boost Mode

Similar to charge mode operation, in boost mode the IC switches at 1.5MHz to regulate the voltage at IN to 5V. The voltage control loop is internally compensated to provide enough phase margin for stable operation with the full battery voltage range and up to 1A.

In boost mode, the cycle-by-cycle current limit is set to 4A or 2A (depending on the  $I^2C$  setting) to provide protection against short circuit conditions. If the cycle-by-cycle current limit is active for 8ms, an overload condition is detected and the device exits boost mode, and signals an over-current fault. Additionally, discharge current limit ( $I_{LIM(DISCHG)}$ ) is active to protect the battery from overload. Synchronous operation and burst mode are used to maximize efficiency over the full load range.

The bq2426x will not enter boost mode unless the IN voltage is less than the UVLO. When the boost function is enabled, the bq2426x enters a linear mode to bring IN up to the battery voltage. Once  $V_{IN} > (V_{BAT} - 1V)$ , the bq2426x begins switching and regulates IN up to 5V. If  $V_{IN}$  does not rise to within 1V of  $V_{BAT}$  within 8ms, an over-current event is detected and boost mode is exited and a boost mode over-current event is announced, the BOOST\_EN bit is reset to '0' and the STAT\_x and FAULT\_x bits in the Status/ Control register are updated.

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#### **Burst Mode during Light Load**

In boost mode, the IC operates using burst mode to improve light load efficiency and reduce power loss. During boost mode, the PWM converter is turned off when the device reaches minimum duty cycle and the output voltage rises to  $V_{BURST(ENT)}$  threshold. This corresponds to approximately a 75mA inductor current. The converter then restarts when  $V_{IN}$  falls to  $V_{BURST(EXT)}$ . See Figure TBD in the Typical Operating Characteristics for an example waveform.

#### Watchdog Timer in Boost Mode

During boost mode, the watchdog timer is active. The watchdog timer works the same as in charge mode. Write a "1" to the TMR\_RST reset bit in the control register. If the watchdog timer expires, the IC resets the EN\_BOOST bit to 0, signals the fault pulse on the STAT and INT pins. The FAULT\_x bits read "Low Supply Fault" as this is a higher priority fault than the WD timer.

#### STAT/ INT During Boost Mode

During boost mode, the STAT and INT outputs are high impedance. Under fault conditions, a 128µs pulse is sent out to notify the host of the error condition.

#### Protection in Boost Mode

#### **Output Over-Voltage Protection**

The bq2426x contains integrated over-voltage protection on the IN pin. During boost mode, if an over-voltage condition is detected ( $V_{IN} > V_{BOOSTOVP}$ ), after deglitch  $t_{DGL(BOOST_OVP)}$ , the IC turns off the PWM converter, resets EN\_BOOST bit to 0, sets fault status bits and sends out a fault pulse on STAT and INT. The converter does not restart when VIN drops to the normal level until the EN\_BOOST bit is reset to 1.

#### **Output Over-Current Protection**

The bq2426x contains over current protection to prevent the device and battery damage when IN is overloaded. When an over-current condition occurs, the cycle-by-cycle current limit limits the current from the battery to the load. If the overload condition lasts for 8ms, the overload fault is detected. When an overload condition is detected, the bq2426x turns off the PWM converter, resets EN\_BOOST bit to 0, sets the fault status bits and sends out the fault pulse on STAT and INT. The boost operation starts only after the fault is cleared and the EN\_BOOST bit is reset to 1 using the I<sup>2</sup>C.

#### **Battery Voltage Protection**

During boost mode, when the battery voltage is below the minimum battery voltage threshold,  $V_{BATUVLO}$ , the IC turns off the PWM converter, resets EN\_BOOST bit to 0, sets fault status bits and sends out a fault pulse on STAT and INT. Once the battery voltage returns to the acceptable level, the boost starts only after the EN\_BOOST bit is set to 1. Proper operation below 3.3V down to the  $V_{BATUVLO}$  is not guaranteed.

#### Serial Interface Description

The bq24260 uses an I<sup>2</sup>C compatible interface to program charge parameters. I<sup>2</sup>C TM is a 2-wire serial interface developed by NXP (formerly Philips Semiconductor, see I<sup>2</sup>C-Bus Specification, Version 5, October 2012). The bus consists of a data line (SDA) and a clock line (SCL) with pull-up structures. When the bus is idle, both SDA and SCL lines are pulled high. All the I<sup>2</sup>C compatible devices connect to the I<sup>2</sup>C bus through open drain I/O pins, SDA and SCL. A master device, usually a microcontroller or a digital signal processor, controls the bus. The master is responsible for generating the SCL signal and device addresses. The master also generates specific conditions that indicate the START and STOP of data transfer. A slave device receives and/or transmits data on the bus under control of the master device.

The bq2426x device works as a slave and supports the following data transfer modes, as defined in the  $l^2C$  Bus<sup>TM</sup> Specification: standard mode (100 kbps) and fast mode (400 kbps). The interface adds flexibility to the battery charge solution, enabling most functions to be programmed to new values depending on the instantaneous application requirements. The  $l^2C$  circuitry is powered from IN when a supply is connected. If the IN supply is not connected, the  $l^2C$  circuitry is powered from the battery through BAT. The battery voltage must stay above  $V_{BATUVLO}$  with no input connected in order to maintain proper operation.



The data transfer protocol for standard and fast modes is exactly the same; therefore, they are referred to as the F/S-mode in this document. The bq24260/1/2 device only supports 7-bit addressing. The device 7-bit address is defined as '1101011' (0x6Bh).

To avoid  $I^2C$  hang-ups, a timer ( $t_{I2CRESET}$ ) runs during I2C transactions. If the transaction takes longer than  $t_{I2CRESET}$ , any additional commands are ignored and the I2C engine is reset. The timeout is reset with START and repeated START conditions and stops when a valid STOP condition is sent.

#### F/S Mode Protocol

The master initiates data transfer by generating a start condition. The start condition is when a high-to-low transition occurs on the SDA line while SCL is high, as shown in Figure 29. All  $I^2C$  -compatible devices should recognize a start condition.

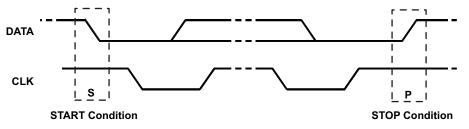


Figure 29. START and STOP Condition

The master then generates the SCL pulses, and transmits the 8-bit address and the read/write direction bit R/W on the SDA line. During all transmissions, the master ensures that data is valid. A valid data condition requires the SDA line to be stable during the entire high period of the clock pulse (see Figure 30). All devices recognize the address sent by the master and compare it to their internal fixed addresses. Only the slave device with a matching address generates an acknowledge (see Figure 31Figure 11) by pulling the SDA line low during the entire high period of the ninth SCL cycle. Upon detecting this acknowledge, the master knows that communication link with a slave has been established.

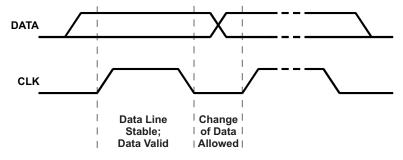
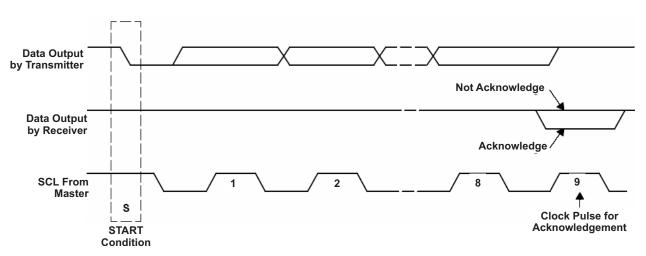


Figure 30. Bit Transfer on the Serial Interface

The master generates further SCL cycles to either transmit data to the slave (R/W bit 0) or receive data from the slave (R/W bit 1. In either case, the receiver needs to acknowledge the data sent by the transmitter. So an acknowledge signal can either be generated by the master or by the slave, depending on which one is the receiver. The 9-bit valid data sequences consisting of 8-bit data and 1-bit acknowledge can continue as long as necessary. To signal the end of the data transfer, the master generates a stop condition by pulling the SDA line from low to high while the SCL line is high (see Figure 29). This releases the bus and stops the communication link with the addressed slave. All I2C compatible devices must recognize the stop condition. Upon the receipt of a stop condition, all devices know that the bus is released, and wait for a start condition followed by a matching address. If a transaction is terminated prematurely, the master needs to send a STOP condition to prevent the slave I2C logic from remaining in a incorrect state. Attempting to read data from register addresses not listed in this section will result in 0xFFh being read out.

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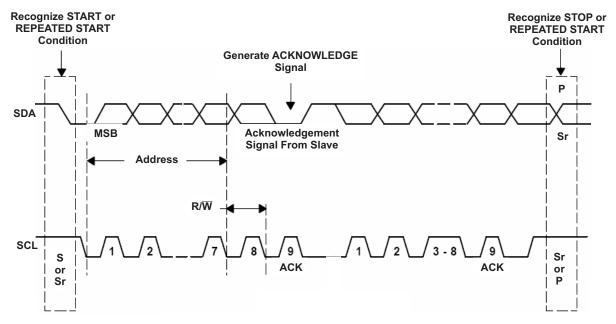


Figure 32. Bus Protocol



## **Register Description**

## Status/Control Register (READ/WRITE)

Memory location: 00, Reset state: 00xx 0xxx

BIT	NAME	<b>READ/WRITE</b>	FUNCTION
B7(MSB)	TMR_RST	Read/Write	Write: TMR_RST function, write "1" to reset the watchdog timer (auto clear) Read: Always 0 (bq24260/1 only)
B6	EN_BOOST	Read/Write	0-Charger Mode 1-Boost Mode (default 0)
B5	STAT_1	Read only	00-Ready
B4	STAT_0	Read only	01-Charge in progress 10-Charge done 11-Fault
B3	EN_SHIPMODE	Read/Write	0-Normal Operation 1-Ship Mode Enabled (default 0)
B2	FAULT_2	Read only	000-Normal
B1	FAULT_1	Read only	001-VIN > VOVP or Boost Mode OVP
B0(LSB)	FAULT_0	Read only	<ul> <li>010- Low Supply connected (VIN<vuvlo boost="" li="" mode="" or="" overcurrent<="" vin<vslp)=""> <li>011- Thermal Shutdown</li> <li>100-Battery Temperature Fault</li> <li>101- Timer Fault (watchdog or safety timer)</li> <li>110-Battery OVP</li> <li>111-No Battery connected</li> </vuvlo></li></ul>

### EN\_BOOST Bit (Operation Mode)

The EN\_BOOST bit selects the operation mode for the bq2426x. Write a "1" to enable boost mode and regulate IN to 5V to supply OTG peripherals. See "Boost Mode Operation" section for more details.

### **EN\_SHIPMODE Bit**

Writing the EN\_SHIPMODE bit to a "1" latches off the IC, battery FET and BGATE until a high to low transition on UVLO occurs. This means that if EN\_SHIPMODE is written to a "1" while the input is connected, it must first be removed and then replaced before the battery FET turns on. This allows the end product with no load on the battery and the end user will enable the device by plugging it into the adapter. The EN\_SHIPMODE bit can be cleared using the I<sup>2</sup>C interface as well.



## Control Register (READ/WRITE)

Memory location: 01, Reset state: 1xxx 1100 (bq24260/2), 1xxx 1110 (bq24261)

BIT	NAME	<b>READ/WRITE</b>	FUNCTION
B7(MSB)	RESET	Write only	Write: 1-Reset all registers to default values 0-No effect Read: always get "1"
B6	IN_LIMIT_2	Read/Write	000-USB2.0 host with 100mA current limit
B5	IN_LIMIT_1	Read/Write	001-USB3.0 host with 150mA current limit
В4	IN_LIMIT_0	Read/Write	<ul> <li>010 – USB2.0 host with 500mA current limit</li> <li>011 – USB3.0 host/charger with 900mA current limit</li> <li>100 – Charger with 1500mA current limit</li> <li>101—Charger with 1950mA current limit</li> <li>110 – Charger with 2500mA current limit</li> <li>111- Charger with 2000mA current limit (default 000<sup>(1)</sup>)</li> </ul>
B3	EN_STAT	Read/Write	0-Disable STAT function (STAT only shows faults) 1-Enable STAT function (default 1)
B2	TE	Read/Write	0-Disable charge current termination 1-Enable charge current termination (default 1)
B1	CE	Read/Write	0-Charger enabled 1-Charger is disabled (default 0-bq24260 / 2, 1-bq24261)
B0(LSB)	HZ_MODE	Read/Write	0-Not high impedance mode 1-High impedance mode (default 0)

(1) When in DEFAULT mode, the PSEL (bq24261/2) determine the default input current limit.

#### RESET Bit

The RESET bit in the control register (0x01h) is used to reset all the charge parameters. Write "1" to RESET bit to reset all the registers to default values and place the bq2426x into DEFAULT mode and turn off the watchdog timer. The RESET bit is automatically cleared to zero once the bq2426x enters DEFAULT mode.

### **CE** Bit (Charge Enable)

The  $\overline{CE}$  bit is used to disable or enable the charge process. A low logic level (0) on this bit enables the charge and a high logic level (1) disables the charge. When charge is disabled, the SYS output regulates to  $V_{SYS(REG)}$  and battery is disconnected from the SYS. Supplement mode is available if the system load demands cannot be met by the supply.

### HZ\_MODE Bit (High Impedance Mode Enable)

The HZ\_MODE bit is used to disable or enable the high impedance mode. A low logic level (0) on this bit enables the IC and a high logic level (1) puts the IC in a low quiescent current state called high impedance mode. When in high impedance mode, the converter is off and the battery FET and BGATE are on. The load on SYS is supplied by the battery. BGATE is low (external FET turned on) while in high impedance mode.



## Control/Battery Voltage Register (READ/WRITE)

Memory location: 02, Reset state: 0001 0100 (BQ24260/1), 1000 1100 (bq24262A)

BIT	NAME	READ/WRITE	FUNCTION
B7(MSB)	V <sub>BREG5</sub>	Read/Write	Battery Regulation Voltage: 640mV (default 0)
B6	V <sub>BREG4</sub>	Read/Write	Battery Regulation Voltage: 320mV (default 0)
B5	V <sub>BREG3</sub>	Read/Write	Battery Regulation Voltage: 160mV (default 0)
B4	V <sub>BREG2</sub>	Read/Write	Battery Regulation Voltage: 80mV (default 1)
B3	V <sub>BREG1</sub>	Read/Write	Battery Regulation Voltage: 40mV (default 0)
B2	V <sub>BREG0</sub>	Read/Write	Battery Regulation Voltage: 20mV (default 1)
B1	MOD_FREQ1	Read/Write	Modify Switching Frequency Target –
B0(LSB)	MOD_FREQ0	Read/Write	00 – No Change to Nominal Frequency Target 01 – +10% Change to Nominal Frequency 10 – -10% Change to Nominal Frequency 11 – NA (default 00)

## V<sub>BREG</sub> Bits (Battery Regulation Threshold setting)

Use  $V_{BREG}$  bits to set the battery regulation threshold. The VBATREG is calculated using the following equation:

 $V_{BATREG} = 3.5 V + V_{BREG}CODE \times 20 mV$ 

The charge voltage range is 3.5V to 4.44V with the offset of 3.5V and step of 20mV. The default setting is 3.6V for the BQ24260 and BQ24261. The default setting is 4.2V for the bq24262A. If a value greater than 4.44V is written, the setting goes to 4.44V. It is recommended to set  $V_{\text{BATREG}}$  above  $V_{\text{MINSYS}}$ .

## MOD\_FREQx Bits (Frequency Modification)

The MOD\_FREQx bits are used to change the switching frequency by  $\pm 10\%$ . This is used for applications where the 1.5MHz switching frequency noise interferes with other device operation. The frequency may be modified by  $\pm 10\%$  of the nominal frequency.

## Vender/Part/Revision Register (READ only)

Memory location: 03, Reset state: 0100 0010 (bq24262A), 0100 0110 (BQ24260/1)

BIT	NAME	<b>READ/WRITE</b>	FUNCTION
B7(MSB)	Vendor2	Read only	Vender Code: bit 2 (default 0)
B6	Vendor1	Read only	Vender Code: bit 1 (default 1)
B5	Vendor0	Read only	Vender Code: bit 0 (default 0)
B4	PN1	Read only	For I <sup>2</sup> C Address 6Bh: 00 – bq24260
B3	PN0	Read only	
B2	NA	Read only	NA
B1	NA	Read only	NA
B0(LSB)	NA	Read only	NA



## Battery Termination/Fast Charge Current Register (READ/WRITE)

Memory location: 04, Reset state: 0010 1010

BIT	NAME	<b>READ/WRITE</b>	FUNCTION
B7(MSB)	I <sub>CHRG4</sub>	Read/Write	Charge current 1600mA – (default 0)
B6	I <sub>CHRG3</sub>	Read/Write	Charge current: 800mA — (default 0)
B5	I <sub>CHRG2</sub>	Read/Write	Charge current: 400mA —(default 1)
B4	I <sub>CHRG1</sub>	Read/Write	Charge current: 200mA — (default 0)
B3	I <sub>CHRG0</sub>	Read/Write	Charge current: 100mA (default 1)
B2	I <sub>TERM2</sub>	Read/Write	Termination current sense: 200mA (default 0)
B1	I <sub>TERM1</sub>	Read/Write	Termination current sense voltage: 100mA (default 1)
B0(LSB)	I <sub>TERM0</sub>	Read/Write	Termination current sense voltage: 50mA (default 0)

## I<sub>CHRG</sub> Bits (Charge Current Regulation Threshold setting)

Use  $I_{CHRG}$  bits to set the charge current regulation threshold. The charge current is programmable from 500mA to 3A in 100mA steps. The default is 1A. The  $I_{CHARGE}$  is calculated using the following equation:

 $I_{CHARGE} = 500 \text{ mA} + I_{CHRG}CODE \times 100 \text{ mA}$ 

Any setting programmed above 3A selects the 3A setting.

## I<sub>TERM</sub> Bits (Charge Current Termination Threshold setting)

Use  $I_{\text{TERM}}$  bits to set the charge current termination threshold. The termination threshold is programmable from 50mA to 300mA in 50mA steps. The default is 150mA. The  $I_{\text{TERM}}$  is calculated using the following equation:

 $I_{\text{TERM}} = 50 \text{ mA} + I_{\text{TERM}} \text{CODE} \times 50 \text{ mA}$ 

Any setting programmed above 300mA selects the 300mA setting.



## VIN-DPM Voltage/ MINSYS Status Register

Memory location: 05, Reset state: xx00 x000

BIT	NAME	<b>READ/WRITE</b>	FUNCTION			
B7(MSB)	MINSYS_STATUS	Read only	0 – Minimum System Voltage mode is not active 1 – Minimum System Voltage mode is active (low battery			
B6	VINDPM_STATUS	Read only	0 – VIN-DPM mode is not active 1 – VIN-DPM mode is active			
B5	LOW_CHG	Read/Write	0 – Normal charge current set by 04h 1 – Low charge current setting 300mA (default 0)			
B4	D+/D– EN	Read/Write	0 – Bit returns to 0 after D+/D- detection is performed 1 – Force D+/D- detection (bq24260 only, default 0)			
B3	CD_STATUS	Read Only	0 – CD low, IC enabled 1 – CD high, IC disabled			
B2	V <sub>INDPM2</sub>	Read/Write	Input V <sub>IN-DPM</sub> voltage: V <sub>DPMOFF</sub> + 8% (default 0)			
B1	V <sub>INDPM1</sub>	Read/Write	Input V <sub>IN-DPM</sub> voltage: V <sub>DPMOFF</sub> + 4% (default 0)			
B0(LSB)	V <sub>INDPM0</sub>	Read/Write	Input V <sub>IN-DPM</sub> voltage: V <sub>DPMOFF</sub> + 2% (default 0)			

V<sub>IN-DPM</sub> voltage offset is programmable using the VINDPM\_OFF bit (bit 0 of register 0x06) and default V<sub>IN-DPM</sub> threshold is 4.2V.

## LOW\_CHG Bit (Low Charge Mode Enable)

The LOW\_CHG bit is used to reduce the charge current to a minimum current. This feature is used by systems where battery NTC is monitored by the host and requires a reduced charge current setting or by systems that need a "preconditioning" current for low battery voltages. Write a "1" to this bit to charge at 300mA. Write a "0" to this bit to charge at the programmed charge current.

## VINDPM Bits (VINDPM Threshold setting)

Use  $V_{INDPM}$  bits to set the  $V_{INDPM}$  regulation threshold. The  $V_{INDPM}$  threshold is calculated using the following equation:

 $V_{INDPM} = V_{INDPM_OFF} + V_{INDPM}CODE \times 2\% \times V_{INDPM_OFF}$ 

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## Safety Timer/ NTC Monitor Register (READ/WRITE)

Memory location: 06, Reset state: 1001 1xx0

BIT	NAME	<b>READ/WRITE</b>	FUNCTION
B7(MSB)	2XTMR_EN	Read/Write	0 – Timer not slowed at any time 1 – Timer slowed by 2x when in thermal regulation, $V_{IN\_DPM}$ or input current limit (default 1)
B6	TMR_1	Read/Write	Safety Timer Time Limit –
B5	TMR_2	Read/Write	00 – 1.25 minute fast charge 01 – 6 hour fast charge 10 – 9 hour fast charge 11 – Disable safety timers (default 00) (bq24260/1 only)
B4	BOOST_ILIM	Read/Write	0 – 500mA 1 – 1A (Default 1)
B3	TS_EN	Read/Write	0 – TS function disabled 1 – TS function enabled (default 1)
B2	TS_FAULT1	Read only	TS Fault Mode:
B1	TS_FAULT0	Read only	00 - Normal, No TS fault $01 - TS temp < T_{COLD}$ or TS temp > T <sub>HOT</sub> (Charging suspended) $10 - T_{COOL}$ > TS temp > T <sub>COLD</sub> (Charge current reduced by half) $11 - T_{WARM}$ < TS temp < T <sub>HOT</sub> (Charge voltage reduced by 100mV)
B0(LSB)	VINDPM_OFF	Read/Write	0 - 4.2V 1 - 10.1V (Default 0)

### BOOST\_ILIM Bit (Boost current limit setting)

The BOOST\_ILIM bit programs the cycle by cycle current limit threshold for boost operation. The 1A setting sets the low side cycle by cycle current limit to 4A (typ). This ensures that at least 1A can be supplied from the boost converter over the entire battery range. The 500mA setting sets the current limit to 2A(typ) to ensure at least 500mA available from the boost converter. See the boost mode over-current section for more details.

### VINDPM\_OFF Bit (VINDPM offset setting)

The VINDPM\_OFF bit programs the offset for the VINDPM function. The 4.2V setting is intended to work with a standard 5V output adapter. The 10.1V setting supports 12V adapters and the 12V output for the new USB Power Delivery specification (USB PD).



## **APPLICATION INFORMATION**

### **Output Inductor and Capacitor Selection Guidelines**

When selecting an inductor, several attributes must be examined to find the right part for the application. First, the inductance value should be selected. The bq2426x is designed to work with 1.5 $\mu$ H to 2.2 $\mu$ H inductors. The chosen value will have an effect on efficiency and package size. Due to the smaller current ripple, some efficiency gain is reached using the 2.2 $\mu$ H inductor, however, due to the physical size of the inductor, this may not be a viable option. The 1.5 $\mu$ H inductor provides a good tradeoff between size and efficiency.

Once the inductance has been selected, the peak current must be calculated in order to choose the current rating of the inductor. Use Equation 5 to calculate the peak current.

$$I_{\text{PEAK}} = I_{\text{LOAD}(\text{MAX})} \times \left(1 + \frac{\%_{\text{RIPPPLE}}}{2}\right)$$

(5)

The inductor selected must have a saturation current rating greater than or equal to the calculated  $I_{PEAK}$ . Due to the high currents possible with the bq2426x, a thermal analysis must also be done for the inductor. Many inductors have 40°C temperature rise rating. This is the DC current that will cause a 40°C temperature rise above the ambient temperature in the inductor. For this analysis, the typical load current may be used adjusted for the duty cycle of the load transients. For example, if the application requires a 1.5A DC load with peaks at 2.5A 20% of the time, a  $\Delta$ 40°C temperature rise current must be greater than 1.7A:

$$I_{\text{TEMPRISE}} = I_{\text{LOAD}} + D \times (I_{\text{PEAK}} - I_{\text{LOAD}}) = 1.5 \text{ A} + 0.2 \times (2.5 \text{ A} - 1.5 \text{ A}) = 1.7 \text{ A}$$

The bq2426x's internal loop compensation is designed to be stable with  $10\mu$ F to  $150\mu$ F of local capacitance but requires at least  $20\mu$ F total capacitance on the SYS rail ( $10\mu$ F local +  $\geq 10\mu$ F distributed). The capacitance on the SYS rail can be higher than  $150\mu$ F if distributed amongst the rail. To reduce the output voltage ripple, a ceramic capacitor with the capacitance between  $10\mu$ F and  $47\mu$ F is recommended for local bypass to SYS. If greater than  $100\mu$ F effective capacitance is on the SYS rail, place at least  $10\mu$ F bypass on the BAT pin. Pay special attention to the DC bias characteristics of ceramic capacitors. For small case sizes, the capacitance can be derated as high as 70% at workable voltages. All capacitances specified in this datasheet are effective capacitance, not capacitor value.



## **PCB Layout Guidelines**

It is important to pay special attention to the PCB layout. Figure 33 provides a sample layout for the high current paths of the bq2426xYFF. Figure 34 provides a sample layout for the high current paths of the bq2426xRGE.

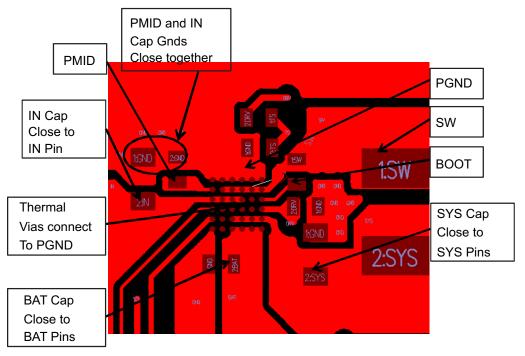


Figure 33. Recommended bq2426x PCB Layout for WCSP Package

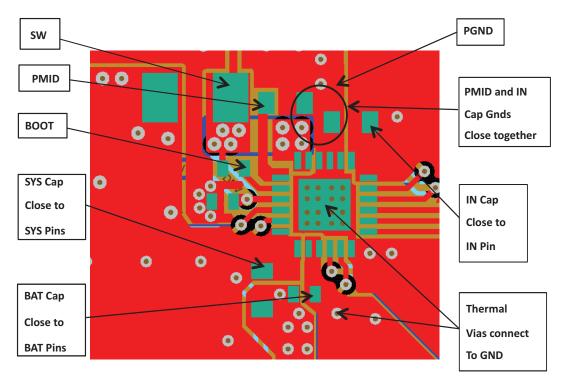


Figure 34. Recommended bq2426x PCB Layout for QFN Package



The following provides some guidelines:

- Place 1µF input capacitor as close to PMID pin and PGND pin as possible to make high frequency current loop area as small as possible.
- Connect the GND of the PMID and IN caps as close as possible.
- Place 4.7µF input capacitor as close to IN pin and PGND pin as possible to make high frequency current loop area as small as possible.
- The local bypass capacitor from SYS to GND should be connected between the SYS pin and PGND of the IC. The intent is to minimize the current path loop area from the SW pin through the LC filter and back to the PGND pin.
- Place all decoupling capacitors close to their respective IC pin and as close as to PGND as possible. Do not
  place components such that routing interrupts power stage currents. All small control signals should be routed
  away from the high current paths.
- The PCB should have a ground plane (return) connected directly to the return of all components through vias. Two vias per capacitor for power-stage capacitors and one via per capacitor for small-signal components. It is also recommended to put vias inside the PGND pads for the IC, if possible. A star ground design approach is typically used to keep circuit block currents isolated (high-power/low-power small-signal) which reduces noisecoupling and ground-bounce issues. A single ground plane for this design gives good results.
- The high-current charge paths into IN, BAT, SYS and from the SW pins must be sized appropriately for the maximum charge current in order to avoid voltage drops in these traces. The PGND pins should be connected to the ground plane to return current through the internal low-side FET.
- For high-current applications, the balls for the power paths should be connected to as much copper in the board as possible. This allows better thermal performance as the board pulls heat away from the IC.

## **REVISION HISTORY**

#### Changes from Original (December 2013) to Revision A

•	Deleted "PREVIEW" from the bq24261RGE device in the Ordering Info table.	2
•	Added specifications to Electrical Characteristics table pertaining to RGE package.	4
•	Added separate lines for I <sub>INLIM</sub> current for YFF and RGE packages.	5
•	Changed V <sub>DO_DRV</sub> spec MAX voltage from "500 mV" to "450 mV"	5
•	Changed VIN to VIN in the Input Over-Voltage Protection section.	17
•	Changed text string in Battery Charging Process section from " IBATSHORT" to " IBATSHRT" for clarification.	18
•	Changed several device references from "bq24260" to "bq2426x" in the Detailed Description section.	20
•	Changed the wording of the Safety Timer description for clarification.	22
•	Changed text in the F/S Mode Protocol section from "to either transmit data to the slave (R/W bit 1) or receive data from the slave (R/W bit 0" to "to either transmit data to the slave (R/W bit 0) or receive data from the slave (R/W bit 1" for clarification.	27

ba24262/

Page

SLUSBU4A - DECEMBER 2013 - REVISED JANUARY 2014



12-Feb-2014

## PACKAGING INFORMATION

Orderable Device	Status	Package Type	-	Pins	-	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
BQ24260SYFFR	PREVIEW	DSBGA	YFF	36		Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ24260S	
BQ24260SYFFT	PREVIEW	DSBGA	YFF	36		Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ24260S	
BQ24261RGER	ACTIVE	VQFN	RGE	24	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85		Samples
BQ24261RGET	ACTIVE	VQFN	RGE	24	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85		Samples
BQ24261YFFR	ACTIVE	DSBGA	YFF	36	3000	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ24261	Samples
BQ24261YFFT	ACTIVE	DSBGA	YFF	36	250	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ24261	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.



# PACKAGE OPTION ADDENDUM

12-Feb-2014

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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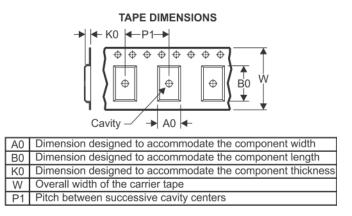
# PACKAGE MATERIALS INFORMATION

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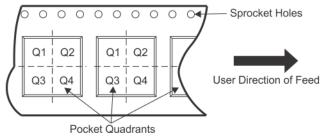
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## TAPE AND REEL INFORMATION





## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal												
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ24260SYFFR	DSBGA	YFF	36	0	180.0	8.4	2.54	2.54	0.76	4.0	8.0	Q1
BQ24260SYFFT	DSBGA	YFF	36	0	180.0	8.4	2.54	2.54	0.76	4.0	8.0	Q1
BQ24261RGER	VQFN	RGE	24	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
BQ24261RGET	VQFN	RGE	24	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
BQ24261YFFR	DSBGA	YFF	36	3000	180.0	8.4	2.54	2.54	0.76	4.0	8.0	Q1
BQ24261YFFT	DSBGA	YFF	36	250	180.0	8.4	2.54	2.54	0.76	4.0	8.0	Q1

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# PACKAGE MATERIALS INFORMATION

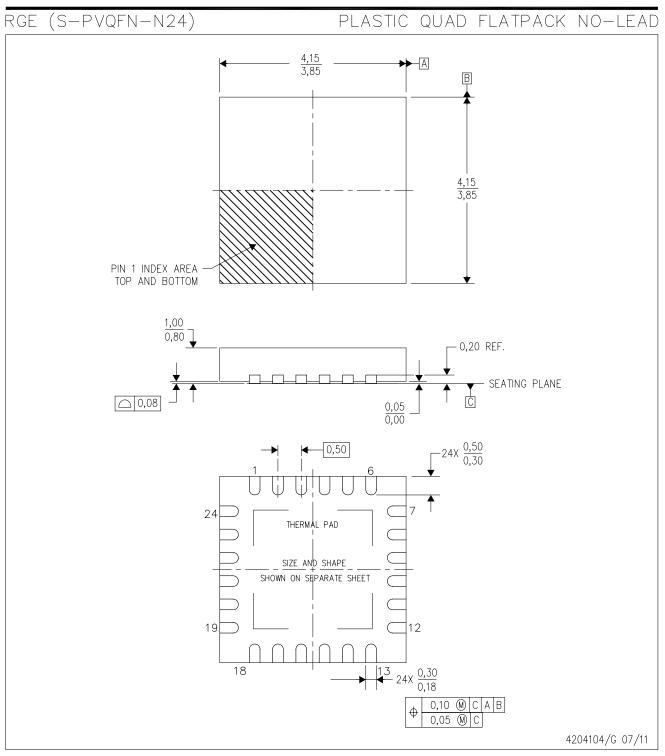
13-Feb-2014



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ24260SYFFR	DSBGA	YFF	36	0	210.0	185.0	35.0
BQ24260SYFFT	DSBGA	YFF	36	0	210.0	185.0	35.0
BQ24261RGER	VQFN	RGE	24	3000	367.0	367.0	35.0
BQ24261RGET	VQFN	RGE	24	250	210.0	185.0	35.0
BQ24261YFFR	DSBGA	YFF	36	3000	182.0	182.0	17.0
BQ24261YFFT	DSBGA	YFF	36	250	182.0	182.0	17.0

# **MECHANICAL DATA**



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Quad Flatpack, No-Leads (QFN) package configuration.
- D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions. F. Falls within JEDEC MO-220.
  - TEXAS INSTRUMENTS www.ti.com

## RGE (S-PVQFN-N24)

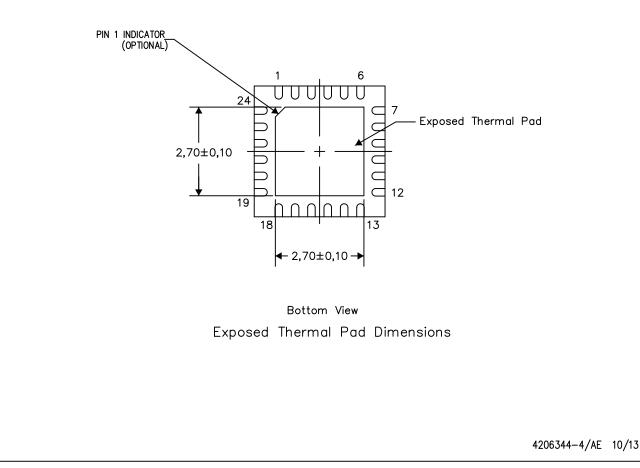
## PLASTIC QUAD FLATPACK NO-LEAD

### THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

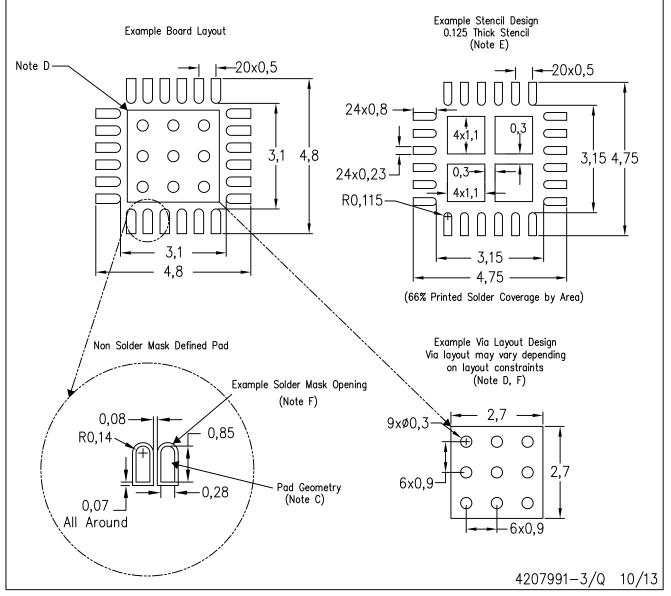


#### NOTES: A. All linear dimensions are in millimeters



RGE (S-PVQFN-N24)

PLASTIC QUAD FLATPACK NO-LEAD



NOTES:

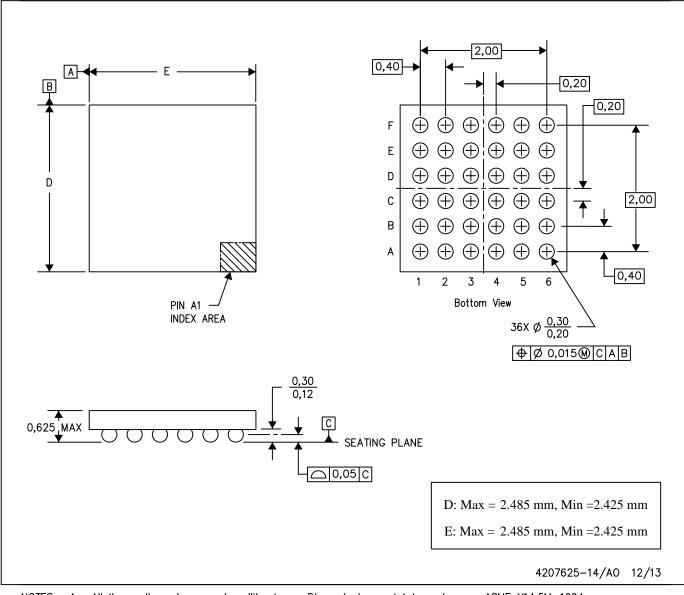
A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.



YFF (S-XBGA-N36)

DIE-SIZE BALL GRID ARRAY



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994. B. This drawing is subject to change without notice.

C. NanoFree™ package configuration.

NanoFree is a trademark of Texas Instruments.



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