

# SPI Interface, Octal SPST Switches, 13.5 $\Omega$ R<sub>on</sub>, ±20 V/+36 V, Mux

### **Data Sheet**

#### FEATURES

SPI interface with error detection Includes CRC, invalid read/write address, and SCLK count error detection Supports burst and daisy-chain mode Industry-standard SPI Mode 0 and Mode 3 interfacecompatible
Guaranteed break-before-make switching, allowing external wiring of switches to deliver multiplexer configurations
V<sub>SS</sub> to V<sub>DD</sub> analog signal range Fully specified at ±15 V, ±20 V, +12 V, and +36 V 9 V to 40 V single-supply operation (V<sub>DD</sub>) ±9 V to ±22 V dual-supply operation (V<sub>DD</sub>/V<sub>SS</sub>)
8 kV HBM ESD rating Low on resistance
1.8 V logic compatibility with 2.7 V ≤ V<sub>L</sub> ≤ 3.3 V

#### **APPLICATIONS**

Relay replacement Automatic test equipment Data acquisition Instrumentation Avionics Audio and video switching Communication systems

#### **GENERAL DESCRIPTION**

The ADGS5414 contains eight independent single-pole/singlethrow (SPST) switches. An SPI interface controls the switches and has robust error detection features, including cyclic redundancy check (CRC) error detection, invalid read/write address error detection, and SCLK count error detection.

It is possible to daisy-chain multiple ADGS5414 devices together. This enables the configuration of multiple devices with a minimal amount of digital lines. The ADGS5414 can also operate in burst mode to decrease the time between SPI commands.

Each switch conducts equally well in both directions when on, and each switch has an input signal range that extends to the supplies. In the off condition, signal levels up to the supplies are blocked.

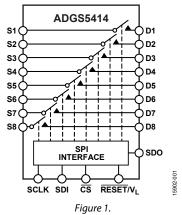
The on-resistance profile is flat over the full analog input range, ensuring ideal linearity and low distortion when switching audio signals. The ADGS5414 exhibits break-before-make switching action, allowing the use of the device in multiplexer applications with external wiring.

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# **ADGS5414**

#### FUNCTIONAL BLOCK DIAGRAM



#### **PRODUCT HIGHLIGHTS**

- 1. The SPI interface removes the need for parallel conversion, logic traces, and reduces the general-purpose input/output (GPIO) channel count.
- 2. Daisy-chain mode removes the need for additional logic traces when using multiple devices.
- 3. CRC error detection, invalid read/write address error detenction, and SCLK count error detection ensures a robust digital interface.
- 4. CRC and error detection capabilities allow the use of the ADGS5414 in safety critical systems.
- 5. Break-before-make switching allows external wiring of the switches to deliver multiplexer configurations.
- 6. The trench isolation analog switch section guards against latch-up. A dielectric trench separates the positive and negative channel transistors, preventing latch-up even under severe overvoltage conditions.

## TABLE OF CONTENTS

Features 1
Applications1
Functional Block Diagram 1
General Description 1
Product Highlights 1
Revision History 1
Specifications
±15 V Dual Supply3
±20 V Dual Supply5
12 V Single Supply7
36 V Single Supply9
Continuous Current per Channel, Sx or Dx Pins 11
Timing Characteristics11
Absolute Maximum Ratings
Thermal Resistance
ESD Caution13
Pin Configurations and Function Descriptions14
Typical Performance Characteristics
Test Circuits
Terminology
Theory of Operation
Address Mode

### Register Summary ...... 27

#### **REVISION HISTORY**

10/2017—Revision 0: Initial Version

### **SPECIFICATIONS**

### ±15 V DUAL SUPPLY

Digital logic voltage ( $V_{DD}$ ) = +15 V ± 10%, negative supply voltage ( $V_{SS}$ ) = -15 V ± 10%, positive supply voltage ( $V_L$ ) = 2.7 V to 5.5 V, GND = 0 V, unless otherwise noted.

#### Table 1.

Parameter	+25°C	-40°C to +85°C	-40°C to +125°C	Unit	Test Conditions/Comments
ANALOG SWITCH					
Analog Signal Range			V <sub>DD</sub> to V <sub>SS</sub>	V	
On Resistance, R <sub>ON</sub>	13.5			Ωtyp	Source voltage (V <sub>s</sub> ) = $\pm 10$ V, I <sub>s</sub> = $-10$ mA; see Figure 29
	15	18	22	Ωmax	$V_{DD} = +13.5 V, V_{SS} = -13.5 V$
On-Resistance Match Between Channels, $\Delta R_{ON}$	0.3			Ωtyp	$V_s = \pm 10 V$ , source current $(I_s) = -10 mA$
	0.8	1.3	1.4	Ωmax	
On-Resistance Flatness, RFLAT (ON)	1.8			Ωtyp	$V_s = \pm 10 V$ , $I_s = -10 mA$
	2.2	2.6	3	Ωmax	
LEAKAGE CURRENTS					$V_{DD} = +16.5 V, V_{SS} = -16.5 V$
Source Off Leakage, Is (Off)	±0.1			nA typ	$V_s = \pm 10 V$ , $V_D = \pm 10 V$ ; see Figure 32
	±0.25	±1	±7	nA max	
Drain Off Leakage, I <sub>D</sub> (Off)	±0.1			nA typ	$V_s = \pm 10 \text{ V}, V_D = \pm 10 \text{ V};$ see Figure 32
	±0.25	±1	±7	nA max	
Channel On Leakage, $I_D$ (On), $I_S$ (On)	±0.15			nA typ	$V_s = V_D = \pm 10 V$ ; see Figure 28
	±0.4	±2	±14	nA max	
DIGITAL OUTPUT					
Output Voltage					
Low, V <sub>OL</sub>			0.4	V max	Sink current ( $I_{SINK}$ ) = 5 mA
			0.2	V max	$I_{SINK} = 1 \text{ mA}$
Output Current, Low (I_{OL}) or High (I_{OH})	0.001			μA typ	Output voltage ( $V_{OUT}$ ) = ground voltage ( $V_{GND}$ ) or $V_L$
			±0.1	μA max	
Digital Output Capacitance, Cout	4			pF typ	
DIGITAL INPUTS					
Input Voltage					
High, V <sub>INH</sub>			2	V min	$3.3 \text{ V} < \text{V}_{L} \le 5.5 \text{ V}$
			1.35	V min	$2.7~V \leq V_L \leq 3.3~V$
Low, V <sub>INL</sub>			0.8	V max	$3.3 \text{ V} < \text{V}_{L} \le 5.5 \text{ V}$
			0.8	V max	$2.7~V \leq V_L \leq 3.3~V$
Input Current, Low (I <sub>INL</sub> ) or High (I <sub>INH</sub> )	0.001			μA typ	$V_{IN} = V_{GND} \text{ or } V_L$
			±0.1	µA max	
Digital Input Capacitance, C <sub>IN</sub>	4			pF typ	
DYNAMIC CHARACTERISTICS					
ton	410			ns typ	Load resistance ( $R_L$ ) = 300 $\Omega$ , load capacitance ( $C_L$ ) = 35 pF
	420	515	515	ns max	$V_s = 10 V$ ; see Figure 37
t <sub>OFF</sub>	135			ns typ	$R_L = 300 \Omega, C_L = 35 pF$
	140	185	195	ns max	$V_s = 10 V$ ; see Figure 37
Break-Before-Make Time Delay, t₀	260			ns typ	$R_L = 300 \Omega, C_L = 35 pF$
<b>*</b> *	250		210	ns min	$V_{s1} = V_{s2} = 10 V$ ; see Figure 36
Charge Injection, Q <sub>INJ</sub>	125			pC typ	$V_s = 0 V$ , $R_s = 0 \Omega$ , $C_L = 1 nF$ ; see Figure 38

Parameter	+25°C	-40°C to +85°C	-40°C to +125°C	Unit	<b>Test Conditions/Comments</b>
Off Isolation	-60			dB typ	$R_L = 50 \Omega, C_L = 5 pF,$ frequency (f) = 1 MHz; see
					Figure 32
Channel to Channel Crosstalk	-75			dB typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ , $f = 1 MHz$ ; see Figure 30
Total Harmonic Distortion + Noise (THD + N)	0.01			% typ	$R_L = 1 k\Omega$ , 15 V p-p, f = 20 Hz to 20 kHz; see Figure 33
–3 dB Bandwidth	200			MHz typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ ; see Figure 34
Insertion Loss	-0.9			dB typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ , $f = 1 MHz$ ; see Figure 34
Source Capacitance (C <sub>s</sub> ) (Off)	11			pF typ	$V_{s} = 0 V, f = 1 MHz$
Drain Capacitance(C <sub>D</sub> ) (Off)	11			pF typ	$V_{s} = 0 V, f = 1 MHz$
$C_D$ (On), $C_s$ (On)	30			pF typ	$V_{s} = 0 V, f = 1 MHz$
POWER REQUIREMENTS				P: 9P	$V_{DD} = +16.5 \text{ V}, \text{ V}_{SS} = -16.5 \text{ V}$
Positive Supply Current (IDD)	45			μA typ	All switches open
rositive Supply Current (IDD)	45		70	μA typ μA max	All switches open
	45		70		All switches closed, $V_L = 5.5 V$
	45		70	μA typ	
	210		70	µA max	All switches closed, $V_L = 5.5 V$
	310			μA typ	All switches closed, $V_L = 2.7 V$
			430	μA max	All switches closed, $V_L = 2.7 V$
l.					
Inactive	6.3			μA typ	Digital inputs = $0 V \text{ or } V_L$
			8.0	μA max	l
SCLK = 1 MHz	14			μA typ	$\overline{CS}$ and $SDI = 0 V$ or $V_L, V_L = 5$ V
	7			μA typ	$\overline{\text{CS}}$ and $\text{SDI} = 0 \text{ V or } V_L, V_L = 3 \text{ V}$
SCLK = 50 MHz	390			μA typ	$\overline{CS} = V_L \text{ and } SDI = 0 \text{ V or } V_L,$ $V_L = 5 \text{ V}$
	210			μA typ	$\overline{CS} = V_L$ and $SDI = 0 V$ or $V_L$ , $V_L = 3 V$
SDI = 1 MHz	15			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 5 V
	7.5			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 3 V
SDI = 25 MHz	230			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 5 V
	120			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 3 V
Active at 50 MHz	1.8			mA typ	Digital inputs toggle between 0 V and $V_L$ , $V_L = 5.5 V$
		2	2.1	mA max	
	0.7	_		mA typ	Digital inputs toggle between 0 V and $V_L$ , $V_L$ = 2.7 V
			1.0	mA max	
Negative Supply Current (Iss)	0.05			μA typ	Digital inputs = $0 \text{ V}$ or $V_{L}$
James and his content (13)	0.05		1.0	μA max	
Dual-Supply Operation (V <sub>DD</sub> /V <sub>ss</sub> )			±9	Vmin	GND = 0 V
Sau supply operation (VUU VSS)			±22	V max	GND = 0V GND = 0V

#### ±20 V DUAL SUPPLY

 $V_{\text{DD}}$  = +20 V  $\pm$  10%,  $V_{\text{SS}}$  = -20 V  $\pm$  10%,  $V_{\text{L}}$  = 2.7 V to 5.5 V, GND = 0 V, unless otherwise noted.

#### Table 2. Parameter +25°C -40°C to +85°C -40°C to +125°C Unit **Test Conditions/Comments** ANALOG SWITCH **Analog Signal Range** V<sub>DD</sub> to V<sub>SS</sub> ٧ $V_s = \pm 15 V$ , $I_s = -10 mA$ ; On Resistance, RON 12.5 Ωtyp see Figure 29 14 17 21 $\Omega$ max $V_{DD} = +18 V, V_{SS} = -18 V$ **On-Resistance Match Between** 0.3 Ωtyp $V_s = \pm 15 V$ , $I_s = -10 mA$ Channels, ΔRON 0.8 1.3 1.4 $\Omega$ max On-Resistance Flatness, RFLAT (ON) 2.3 Ωtyp $V_s = \pm 15 V$ , $I_s = -10 mA$ 2.7 3.5 3.1 Ωmax LEAKAGE CURRENTS $V_{DD} = +22 V, V_{SS} = -22 V$ Source Off Leakage, Is (Off) $V_{s} = \pm 15 V, V_{D} = \pm 15 V;$ ±0.1 nA typ see Figure 32 ±0.25 ±7 nA max +1Drain Off Leakage, I<sub>D</sub> (Off) ±0.1 nA typ $V_{\rm S} = \pm 15 \, \rm V, \, V_{\rm D} = \pm 15 \, \rm V;$ see Figure 32 ±0.25 ±1 ±7 nA max Channel On Leakage, I<sub>D</sub> (On), I<sub>S</sub> (On) ±0.15 nA typ $V_{\rm S} = V_{\rm D} = \pm 15$ V; see Figure 28 ±0.4 ±2 ±14 nA max DIGITAL OUTPUT **Output Voltage** Low, VOL 0.4 V max $I_{SINK} = 5 \text{ mA}$ 0.2 V max $I_{SINK} = 1 \text{ mA}$ Output Current, IoL or IOH 0.001 $V_{OUT} = V_{GND} \text{ or } V_L$ µA typ ±0.1 µA max Digital Output Capacitance, COUT 4 pF typ **DIGITAL INPUTS** Input Voltage V min $3.3 \text{ V} < \text{V}_{L} \le 5.5 \text{ V}$ High, VINH 2 1.35 V min $2.7~V \leq V_L \leq 3.3~V$ Low, VINL 0.8 V max $3.3 \text{ V} < \text{V}_{\text{L}} \le 5.5 \text{ V}$ $2.7~V \leq V_L \leq 3.3~V$ 0.8 V max 0.001 Input Current, IINL or IINH µA typ $V_{IN} = V_{GND} \text{ or } V_L$ ±0.1 µA max Digital Input Capacitance, C<sub>IN</sub> 4 pF typ DYNAMIC CHARACTERISTICS 410 $R_L = 300 \Omega, C_L = 35 pF$ ton ns typ 418 485 495 ns max $V_s = 10 V$ ; see Figure 37 135 $R_L = 300 \Omega, C_L = 35 pF$ ns typ toff 144 185 195 $V_s = 10 V$ ; see Figure 37 ns max Break-Before-Make Time Delay, t<sub>D</sub> 255 $R_L = 300 \Omega, C_L = 35 pF$ ns typ 245 205 $V_{S1} = V_{S2} = 10 V$ ; see Figure 36 ns min 160 $V_{s} = 0 V, R_{s} = 0 \Omega, C_{L} = 1 nF;$ Charge Injection, QINJ pC typ see Figure 38 Off Isolation -60 dB typ $R_L = 50 \Omega$ , $C_L = 5 pF$ , f = 1 MHz; see Figure 34 Channel to Channel Crosstalk -75 dB typ $R_L = 50 \Omega, C_L = 5 pF, f = 1 MHz;$ see Figure 30 (THD + N)0.012 $R_{\text{L}}=1~\text{k}\Omega,\,20~\text{V}~\text{p-p},\,f=20~\text{Hz}$ to % typ 20 kHz; see Figure 33

Parameter	+25°C	-40°C to +85°C	-40°C to +125°C	Unit	Test Conditions/Comments
–3 dB Bandwidth	200			MHz typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ ; see Figure 34
Insertion Loss	-0.8			dB typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ , $f = 1 MHz$ ; see Figure 34
C <sub>s</sub> (Off)	11			pF typ	$V_{s} = 0 V, f = 1 MHz$
C <sub>D</sub> (Off)	11			pF typ	$V_{s} = 0 V, f = 1 MHz$
C <sub>D</sub> (On), C <sub>s</sub> (On)	30			pF typ	$V_{s} = 0 V, f = 1 MHz$
POWER REQUIREMENTS					$V_{DD} = +22 V, V_{SS} = -22 V$
IDD	50			μA typ	All switches open
			110	μA max	All switches open
	50			μA typ	All switches closed, $V_L = 5.5 V$
			110	μA max	All switches closed, $V_L = 5.5 V$
	320			μA typ	All switches closed, $V_L = 2.7 V$
			450	μA max	All switches closed, $V_L = 2.7 V$
l∟ Inactive	6.3			μA typ	Digital inputs = 0 V or V <sub>L</sub>
mactive	0.5		8.0	μA typ μA max	
SCLK = 1 MHz	14		0.0	μA typ	$\overline{\text{CS}}$ and $\text{SDI} = 0 \text{ V}$ or $V_L, V_L = 5 \text{ V}$
	7			μA typ	$\overline{\text{CS}}$ and $\overline{\text{SDI}} = 0 \text{ V or } V_L, V_L = 3 \text{ V}$
SCLK = 50 MHz	390			μA typ	$\frac{1}{CS} = V_L \text{ and } SDI = 0 \text{ V or } V_L,$ $V_L = 5 \text{ V}$
	210			μA typ	$\overline{CS} = V_L$ and $SDI = 0 V \text{ or } V_L$ , $V_L = 3 V$
SDI = 1 MHz	15			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 5 V
	7.5			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 3 V
SDI = 25 MHz	230			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 5 V
	120			µA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 3 V
Active at 50 MHz	1.8			mA typ	Digital inputs toggle between $0 V$ and $V_L$ , $V_L = 5.5 V$
		2	2.1	mA max	
	0.7			mA typ	Digital inputs toggle between $0 V$ and $V_L$ , $V_L = 2.7 V$
			1.0	mA max	
lss	0.05			μA typ	Digital inputs = $0 V \text{ or } V_{L}$
			1.0	µA max	
Dual-Supply Operation (V <sub>DD</sub> /V <sub>SS</sub> )			±9	V min	GND = 0 V
			±22	V max	GND = 0 V

### **12 V SINGLE SUPPLY**

 $V_{\text{DD}}$  = 12 V  $\pm$  10%,  $V_{\text{SS}}$  = 0 V,  $V_{\text{L}}$  = 2.7 V to 5.5 V, GND = 0 V, unless otherwise noted.

#### Table 3.

Parameter	+25°C	–40°C to +85°C	–40°C to +125°C	Unit	Test Conditions/Comments
ANALOG SWITCH					
Analog Signal Range			$0 V to V_{DD}$	V	
On Resistance, R <sub>ON</sub>	26			Ωtyp	$V_s = 0 V$ to $10 V$ , $I_s = -10 mA$ ; see Figure 29
	30	36	42	Ωmax	$V_{DD} = 10.8 V, V_{SS} = 0 V$
On-Resistance Match Between Channels, $\Delta R_{\text{ON}}$	0.3			Ωtyp	$V_{s} = 0 V$ to 10 V, $I_{s} = -10 \text{ mA}$
	1	1.5	1.6	Ωmax	
On-Resistance Flatness, R <sub>FLAT (ON)</sub>	5.5			Ωtyp	$V_s = 0 V$ to 10 V, $I_s = -10 mA$
	6.5	8	12	Ωmax	
LEAKAGE CURRENTS					$V_{DD} = 13.2 V, V_{SS} = 0 V$
Source Off Leakage, Is (Off)	±0.1			nA typ	$V_{s} = 1 \text{ V}/10 \text{ V}, V_{D} = 10 \text{ V}/1 \text{ V};$ see Figure 32
	±0.25	±1	±7	nA max	
Drain Off Leakage, I <sub>D</sub> (Off)	±0.1			nA typ	$V_{s} = 1 \text{ V}/10 \text{ V}, V_{D} = 10 \text{ V}/1 \text{ V};$ see Figure 32
	±0.25	±1	±7	nA max	
Channel On Leakage, I <sub>D</sub> (On), I <sub>s</sub> (On)	±0.15			nA typ	$V_s = V_D = 1 \text{ V}/10 \text{ V}$ ; see Figure 28
	±0.4	±2	±14	nA max	
DIGITAL OUTPUT					
Output Voltage					
Low, V <sub>OL</sub>			0.4	V max	$I_{SINK} = 5 \text{ mA}$
			0.2	V max	$I_{SINK} = 1 \text{ mA}$
Output Current, I <sub>OL</sub> or I <sub>OH</sub>	0.001			μA typ	$V_{OUT} = V_{GND} \text{ or } V_L$
			±0.1	μA max	
Digital Output Capacitance, Cout	4			pF typ	
DIGITAL INPUTS					
Input Voltage					
High, V <sub>INH</sub>			2	V min	$3.3~V < V_L \leq 5.5~V$
			1.35	V min	$2.7~V \leq V_L \leq 3.3~V$
Low, V <sub>INL</sub>			0.8	V max	$3.3~V < V_L \leq 5.5~V$
			0.8	V max	$2.7~V \leq V_L \leq 3.3~V$
Input Current, I <sub>INL</sub> or I <sub>INH</sub>	0.001			μA typ	$V_{IN} = V_{GND} \text{ or } V_L$
			±0.1	μA max	
Digital Input Capacitance, C <sub>IN</sub>	4			pF typ	
DYNAMIC CHARACTERISTICS					
t <sub>on</sub>	450			ns typ	$R_L = 300 \Omega, C_L = 35 pF$
	455	555	575	ns max	$V_s = 8 V$ ; see Figure 37
toff	135			ns typ	$R_L = 300 \Omega, C_L = 35 pF$
	141	195	205	ns max	$V_s = 8 V$ ; see Figure 37
Break-Before-Make Time Delay, t <sub>D</sub>	285			ns typ	$R_L = 300 \Omega, C_L = 35 pF$
-	275		225	ns min	$V_{s1} = V_{s2} = 8 V$ ; see Figure 36
Charge Injection, Q <sub>INJ</sub>	55			pC typ	$V_s = 6 V, R_s = 0 \Omega, C_L = 1 nF;$ see Figure 38
Off Isolation	-60			dB typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ , $f = 1 MHz$ ; see Figure 31
Channel to Channel Crosstalk	-75			dB typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ , $f = 1 MHz$ ; see Figure 30

Parameter	+25°C	-40°C to +85°C	-40°C to +125°C	Unit	<b>Test Conditions/Comments</b>
THD +N	0.1			% typ	$R_L = 1 \text{ k}\Omega$ , 6 V p-p, f = 20 Hz to 20 kHz; see Figure 33
–3 dB Bandwidth	220			MHz typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ ; see Figure 34
Insertion Loss	-1.55			dB typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ , $f = 1 MHz$ ; see Figure 34
Cs (Off)	12			pF typ	$V_s = 6V, f = 1 MHz$
C <sub>D</sub> (Off)	12			pF typ	$V_{s} = 6 V, f = 1 MHz$
C <sub>D</sub> (On), C <sub>s</sub> (On)	30			pF typ	$V_{s} = 6 V, f = 1 MHz$
POWER REQUIREMENTS					V <sub>DD</sub> = 13.2 V
I <sub>DD</sub>	40			μA typ	All switches open
			65	μA max	All switches open
	40			μA typ	All switches closed, $V_L = 5.5 V$
			65	μA max	All switches closed, $V_L = 5.5 V$
	300			µA typ	All switches closed, $V_L = 2.7 V$
			420	µA max	All switches closed, $V_L = 2.7 V$
ΙL					
Inactive	6.3			μA typ	Digital inputs = $0 \text{ V}$ or $V_{L}$
			8.0	µA max	
SCLK = 1 MHz	14			μA typ	$\overline{CS}$ and $SDI = 0 V$ or $V_L, V_L = 5 V$
	7			µA typ	$\overline{CS}$ and SDI = 0 V or V <sub>L</sub> , V <sub>L</sub> = 3 V
SCLK = 50 MHz	390			µA typ	$\overline{CS} = V_L$ and $SDI = 0 V$ or $V_L$ ,
				F	$V_L = 5 V$
	210			μA typ	$\overline{CS} = V_L$ and $SDI = 0 V$ or $V_L$ , $V_L = 3 V$
SDI = 1 MHz	15			μA typ	$\overline{CS}$ and $SCLK = 0 V \text{ or } V_L, V_L = 5 V$
	7.5			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> =
SDI = 25 MHz	230			μA typ	$\frac{3 \text{ V}}{\text{CS}}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> =
	120			μA typ	$\frac{5 \text{ V}}{\text{CS}}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 3 V
Active at 50 MHz	1.8			mA typ	Digital inputs toggle between 0 V and $V_L$ , $V_L = 5.5 V$
		2	2.1	mA max	
	0.7			mA typ	Digital inputs toggle between 0 V and $V_L$ , $V_L = 2.7$ V
			1.0	mA max	
Single-Supply Operation (VDD)			9	V min	$GND = 0 V, V_{ss} = 0 V$
			40	V max	$GND = 0 V, V_{ss} = 0 V$

### **36 V SINGLE SUPPLY**

 $V_{\text{DD}}$  = 36 V  $\pm$  10%,  $V_{\text{SS}}$  = 0 V,  $V_{\text{L}}$  = 2.7 V to 5.5 V, GND = 0 V, unless otherwise noted.

#### Table 4.

Parameter	+25°C	–40°C to +85°C	-40°C to +125°C	Unit	<b>Test Conditions/Comments</b>
ANALOG SWITCH					
Analog Signal Range			0 V to V <sub>DD</sub>	V	
On Resistance, R <sub>ON</sub>	14.5			Ωtyp	$V_s = 0 V$ to 30 V, $I_s = -10 mA$ ; see Figure 29
	16	19	23	Ωmax	$V_{DD} = 32.4 V, V_{SS} = 0 V$
On-Resistance Match Between Channels, $\Delta R_{ON}$	0.3			Ωtyp	$V_s = 0 V$ to 30 V, $I_s = -10 mA$
	0.8	1.3	1.4	Ωmax	
On-Resistance Flatness, R <sub>FLAT(ON)</sub>	3.5			Ωtyp	$V_{s} = 0 V$ to 30 V, $I_{s} = -10 \text{ mA}$
	4.3	5.5	6.5	Ωmax	
LEAKAGE CURRENTS					$V_{DD} = 39.6 V, V_{SS} = 0 V$
Source Off Leakage, Is (Off)	±0.1			nA typ	$V_s = 1 \text{ V}/30 \text{ V}, V_D = 30 \text{ V}/1 \text{ V};$ see Figure 32
	±0.25	±1	±7	nA max	
Drain Off Leakage, I <sub>D</sub> (Off)	±0.1			nA typ	$V_{s} = 1 \text{ V}/30 \text{ V}, V_{D} = 30 \text{ V}/1 \text{ V};$ see Figure 32
	±0.25	±1	±7	nA max	
Channel On Leakage, $I_D$ (On), $I_S$ (On)	±0.15			nA typ	$V_s = V_D = 1 \text{ V}/30 \text{ V}; \text{ see}$ Figure 28
	±0.4	±2	±14	nA max	
DIGITAL OUTPUT					
Output Voltage					
Low, V <sub>OL</sub>			0.4	V max	$I_{SINK} = 5 \text{ mA}$
			0.2	V max	$I_{SINK} = 1 \text{ mA}$
Output Current, I <sub>OL</sub> or I <sub>OH</sub>	0.001			μA typ	$V_{OUT} = V_{GND} \text{ or } V_L$
			±0.1	μA max	
Digital Output Capacitance, Cout	4			pF typ	
DIGITAL INPUTS					
Input Voltage					
High, V <sub>INH</sub>			2	V min	$3.3 V < V_L \le 5.5 V$
			1.35	V min	$2.7~V \leq V_L \leq 3.3~V$
Low, V <sub>INL</sub>			0.8	V max	$3.3 V < V_L \le 5.5 V$
			0.8	V max	$2.7~V \leq V_L \leq 3.3~V$
Input Current, IINL or IINH	0.001			μA typ	$V_{IN} = V_{GND} \text{ or } V_L$
			±0.1	μA max	
Digital Input Capacitance, C <sub>IN</sub>	4			pF typ	
DYNAMIC CHARACTERISTICS					
t <sub>on</sub>	425			ns typ	$R_L = 300 \Omega, C_L = 35 pF$
	435	515	515	ns max	V <sub>s</sub> = 18 V; see Figure 37
toff	145			ns typ	$R_L = 300 \ \Omega, \ C_L = 35 \ pF$
	151	195	195	ns max	V <sub>s</sub> = 18 V; see Figure 37
Break-Before-Make Time Delay, t <sub>D</sub>	260			ns typ	$R_L = 300 \ \Omega, \ C_L = 35 \ pF$
	245		205	ns min	$V_{51} = V_{52} = 18$ V; see Figure 36
Charge Injection, Q <sub>INJ</sub>	145			pC typ	$V_{s} = 18 \text{ V},  \text{R}_{s} = 0  \Omega,  \text{C}_{\text{L}} = 1  \text{nF};$ see Figure 38
Off Isolation	-60			dB typ	$\label{eq:RL} \begin{array}{l} R_{L} = 50 \; \Omega,  C_{L} = 5 \; pF,  f = 1 \; MHz; \\ \text{see Figure 31} \end{array}$
Channel to Channel Crosstalk	-75			dB typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ , $f = 1$ MHz; Figure 30

Parameter	+25°C	-40°C to +85°C	-40°C to +125°C	Unit	<b>Test Conditions/Comments</b>
THD + N	0.04			% typ	$R_L = 1 \ k\Omega$ , 18 V p-p, f = 20 Hz
					to 20 kHz; see Figure 33
–3 dB Bandwidth	200			MHz typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ ; see Figure 34
Insertion Loss	-0.85			dB typ	$R_L = 50 \Omega$ , $C_L = 5 pF$ , $f = 1$ MHz; see Figure 34
C <sub>s</sub> (Off)	11			pF typ	$V_s = 18 V, f = 1 MHz$
$C_{D}$ (Off)	11			pF typ	$V_{s} = 18 V, f = 1 MHz$
$C_{D}$ (On), $C_{s}$ (On)	26			pF typ	$V_{s} = 18 V, f = 1 MHz$
POWER REQUIREMENTS	-			r 9r	$V_{DD} = 39.6 V$
I <sub>DD</sub>	80			μA typ	All switches open
			130	µA max	All switches open
	80			μA typ	All switches closed, $V_{L} = 5.5 V$
			130	µA max	All switches closed, $V_L = 5.5 V$
	330			μA typ	All switches closed, $V_L = 2.7 V$
			490	µA max	All switches closed, $V_L = 2.7 V$
ار				F	· ····································
Inactive	6.3			μA typ	Digital inputs = $0 V \text{ or } V_{L}$
			8.0	µA max	
SCLK = 1 MHz	14			µA typ	$\overline{CS}$ and SDI = 0 V or V <sub>L</sub> , V <sub>L</sub> = 5 V
	7			μA typ	$\overline{CS}$ and SDI = 0 V or V <sub>L</sub> , V <sub>L</sub> = 3
SCLK = 50 MHz	390			μA typ	$\frac{1}{CS} = V_L$ and SDI = 0 V or $V_L$ , $V_L = 5 V$
	210			μA typ	$\overline{CS} = V_L$ and $SDI = 0 V$ or $V_L$ , $V_L = 3 V$
SDI = 1 MHz	15			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 5 V
	7.5			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 3 V
SDI = 25 MHz	230			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 5 V
	120			μA typ	$\overline{CS}$ and SCLK = 0 V or V <sub>L</sub> , V <sub>L</sub> = 3 V
Active at 50 MHz	1.8			mA typ	Digital inputs toggle between 0 V and $V_L$ , $V_L$ = 5.5 V
		2	2.1	mA max	
	0.7			mA typ	Digital inputs toggle between 0 V and V <sub>L</sub> , $V_L = 2.7$ V
			1.0	mA max	
Single-Supply Operation ( $V_{DD}$ )			9	V min	$GND = 0 V, V_{SS} = 0 V$
			40	V max	$GND = 0 V, V_{SS} = 0 V$

#### **CONTINUOUS CURRENT PER CHANNEL, Sx OR Dx Pins**

#### Table 5. Eight Channels On

Parameter	25°C	85°C	125°C	Unit
CONTINUOUS CURRENT, Sx OR Dx PINS				
$V_{DD} = +15 \text{ V}, V_{SS} = -15 \text{ V} (\theta_{JA} = 50^{\circ}\text{C/W})$	82	61	38	mA maximum
$V_{DD} = +20 \text{ V}, V_{SS} = -20 \text{ V} (\theta_{JA} = 50^{\circ}\text{C/W})$	86	63	41	mA maximum
$V_{DD} = 12 V, V_{SS} = 0 V (\theta_{JA} = 50^{\circ}C/W)$	63	47	29	mA maximum
$V_{DD} = 36 \text{ V}, V_{SS} = 0 \text{ V} (\theta_{JA} = 50^{\circ}\text{C/W})$	85	62	40	mA maximum

#### Table 6. One Channel On

Parameter	25°C	85°C	125°C	Unit
CONTINUOUS CURRENT, Sx OR Dx PINS				
$V_{DD} = +15 \text{ V}, V_{SS} = -15 \text{ V} (\theta_{JA} = 50^{\circ}\text{C/W})$	199	124	75	mA maximum
$V_{DD} = +20 \text{ V}, V_{SS} = -20 \text{ V} (\theta_{JA} = 50^{\circ}\text{C/W})$	210	129	77	mA maximum
$V_{DD} = 12 \text{ V}, V_{SS} = 0 \text{ V} (\theta_{JA} = 50^{\circ}\text{C/W})$	157	104	68	mA maximum
$V_{DD} = 36 \text{ V}, V_{SS} = 0 \text{ V} (\theta_{JA} = 50^{\circ}\text{C/W})$	206	127	76	mA maximum

#### TIMING SPECIFICATIONS

 $V_{\rm L}$  = 2.7 V to 5.5 V; GND = 0 V; all specifications  $T_{\text{MIN}}$  to  $T_{\text{MAX}}$  , unless otherwise noted.

Table 7.	1	11	
Parameter	Limit	Unit	Test Conditions/Comments
TIMING CHARACTRISTICS			
t1	20	ns min	SCLK period
<b>t</b> <sub>2</sub>	8	ns min	SCLK high pulse width
t <sub>3</sub>	8	ns min	SCLK low pulse width
t4	10	ns min	CS falling edge to SCLK active edge
t <sub>5</sub>	6	ns min	Data setup time
t <sub>6</sub>	8	ns min	Data hold time
t <sub>7</sub>	10	ns min	SCLK active edge to $\overline{CS}$ rising edge
t <sub>8</sub>	20	ns max	CS falling edge to SDO data available
t9 <sup>1</sup>	20	ns max	SCLK falling edge to SDO data available
t <sub>10</sub>	20	ns max	CS rising edge to SDO returns to high impedance
t11	20	ns min	CS high time between SPI commands
t <sub>12</sub>	8	ns min	CS falling edge to SCLK becomes stable
<b>t</b> <sub>13</sub>	8	ns min	CS rising edge to SCLK becomes stable

 $^{1}$  Measured with the 1 k $\Omega$  pull-up resistor to V<sub>L</sub> and a 20 pF load. t<sub>9</sub> determines the maximum SCLK frequency when using SDO.

#### **Timing Diagrams**

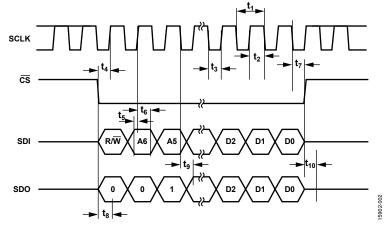


Figure 2. Addressable Mode Timing Diagram

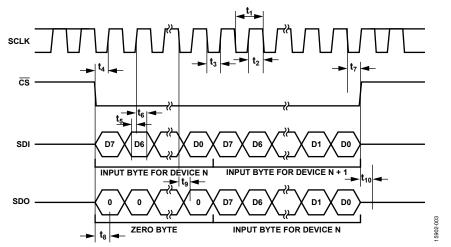


Figure 3. Daisy Chain Timing Diagram

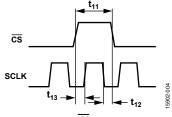


Figure 4. SCLK/CS Timing Diagram

### **ABSOLUTE MAXIMUM RATINGS**

 $T_A = 25^{\circ}C$ , unless otherwise noted.

#### Table 8.

Parameter	Rating
V <sub>DD</sub> to V <sub>ss</sub>	48 V
V <sub>DD</sub> to GND	–0.3 V to +48 V
V <sub>ss</sub> to GND	+0.3 V to -48 V
V <sub>L</sub> to GND	–0.3 V to +5.75 V
Analog Inputs <sup>1</sup>	V <sub>ss</sub> – 0.3 V to V <sub>DD</sub> + 0.3 V or 30 mA, whichever occurs first
Digital Inputs <sup>1</sup>	–0.3 V to +5.75 V
Peak Current, Sx or Dx Pins	422 mA (pulsed at 1 ms, 10% duty cycle maximum)
Continuous Current, Sx or Dx Pins <sup>2</sup>	Data (see Table 5 and Table 6) + 15%
Operating Temperature Range	-40°C to +125°C
Storage Temperature Range	–65°C to +150°C
Junction Temperature	150°C
Reflow Soldering Peak Temperature, Pb Free	260(+0 or -5)°C
Human Body Model (HBM) Electrostatic Discharge (ESD)	8 kV

<sup>1</sup> Overvoltages at the Sx and Dx pins are clamped by internal diodes. Limit current to the maximum ratings given.

<sup>2</sup> See Table 5 and Table 6.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

Only one absolute maximum rating can be applied at any one time.

#### THERMAL RESISTANCE

Thermal performance is directly linked to printed circuit board (PCB) design and operating environment. Close attention to PCB thermal design is required.

 $\theta_{JA} \text{ is the natural convection junction to ambient thermal resistance measured in a one cubic foot sealed enclosure. } \theta_{JC} \text{ is the junction to case thermal resistance.}$ 

#### Table 9. Thermal Resistance

Package Type	Αιθ	θ」c²	Unit
CP-24-17 <sup>1</sup>	50	3.28	°C/W

<sup>1</sup> Thermal impedance simulated values are based on a JEDEC 2S2P thermal test board. See JEDEC JESD51.

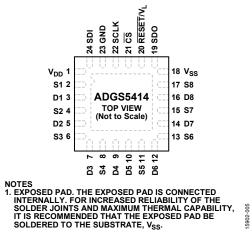
 $^2\,\theta_{\text{JCB}}$  is the junction to the bottom of the case value.

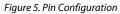
#### ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

### PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS





#### **Table 8. Pin Function Descriptions**

Pin No.	Mnemonic	Description
1	V <sub>DD</sub>	Most Positive Power Supply Potential.
2	S1	Source Terminal 1. This pin can be an input or output.
3	D1	Drain Terminal 1. This pin can be an input or output.
4	S2	Source Terminal 2. This pin can be an input or output.
5	D2	Drain Terminal 2. This pin can be an input or output.
6	S3	Source Terminal 3. This pin can be an input or output.
7	D3	Drain Terminal 3. This pin can be an input or output.
8	S4	Source Terminal 4. This pin can be an input or output.
9	D4	Drain Terminal 4. This pin can be an input or output.
10	D5	Drain Terminal 5. This pin can be an input or output.
11	S5	Source Terminal 5. This pin can be an input or output.
12	D6	Drain Terminal 6. This pin can be an input or output.
13	S6	Source Terminal 6. This pin can be an input or output.
14	D7	Drain Terminal 7. This pin can be an input or output.
15	S7	Source Terminal 7. This pin can be an input or output.
16	D8	Drain Terminal 8. This pin can be an input or output.
17	S8	Source Terminal 8. This pin can be an input or output.
18	Vss	Most Negative Power Supply Potential. In single-supply applications, tie this pin to ground.
19	SDO	Serial Data Output. This pin can daisy-chain a numeral ADGS5414 devices together or for reading back the data stored in a register for diagnostic purposes. The serial data is propagated on the falling edge of SCLK. Pull this open-drain output to V <sub>L</sub> with an external resistor.
20	RESET/VL	RESET/Logic Power Supply Input (V <sub>L</sub> ). Under normal operation, drive the RESET/V <sub>L</sub> pin with a 2.7 V to 5.5 V supply. Pull the pin low to complete a hardware reset. All switches are opened, and the appropriate registers are set to their default.
21		Active Low Control Input. This is the frame synchronization signal for the input data. When $\overline{CS}$ goes low, it powers on the SCLK buffers and enables the input shift register. Data is transferred in on the falling edges of the following clocks. Taking $\overline{CS}$ high updates the switch condition.
22	SCLK	Serial Clock Input. Data is captured on the positive edge of SCLK . Data can be transferred at rates of up to 50 MHz.
23	GND	Ground (0 V) Reference.
24	SDI	Serial Data Input. Data is captured on the positive edge of the serial clock input.
	Exposed Pad	The exposed pad is connected internally. For increased reliability of the solder joints and maximum thermal capability, it is recommended that the pad be soldered to the substrate, V <sub>ss</sub> .

### **TYPICAL PERFORMANCE CHARACTERISTICS**

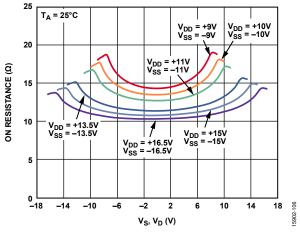


Figure 6. Row as a Function of  $V_S$  and  $V_D$  (Dual Supply)

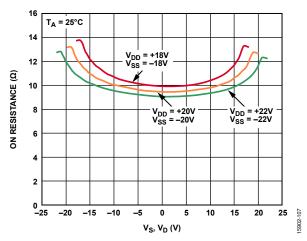


Figure 7. Row as a Function of Vs and VD (Dual Supply)

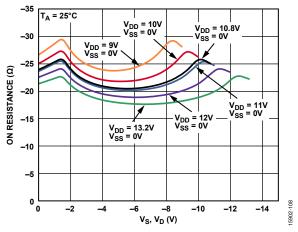
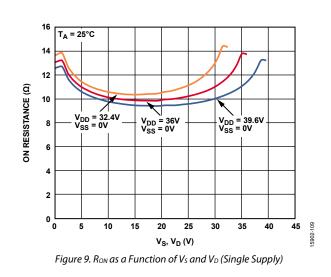


Figure 8.  $R_{ON}$  as a Function of  $V_s$  and  $V_D$  (Single Supply)



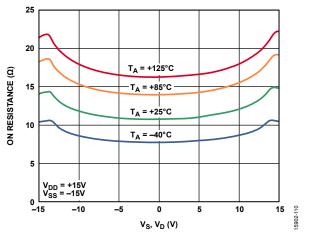


Figure 10.  $R_{\text{ON}}$  as a Function of  $V_{\text{S}}$  and  $V_{\text{D}}$  for Different Temperatures,  $\pm 15$  V Dual Supply

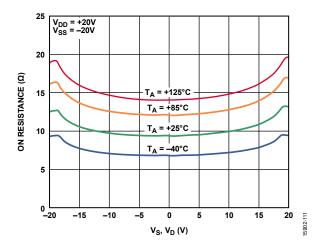


Figure 11. R<sub>ON</sub> as a Function of V<sub>S</sub> and V<sub>D</sub> for Different Temperatures,  $\pm 20$  V Dual Supply

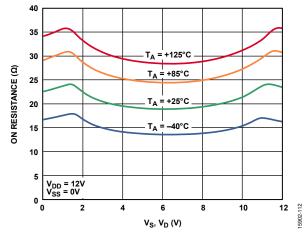


Figure 12.  $R_{ON}$  as a Function of  $V_s$  and  $V_D$  for Different Temperatures, 12 V Single Supply

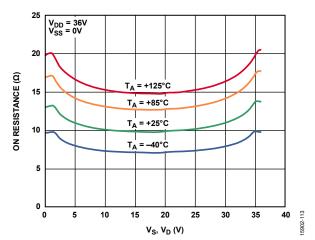


Figure 13.  $R_{ON}$  as a Function of  $V_S$  and  $V_D$  for Different Temperatures, 36 V Single Supply

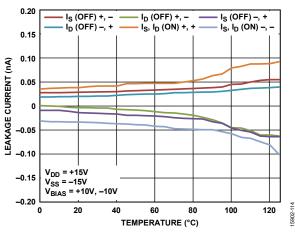


Figure 14. Leakage Currents vs. Temperature, ±15 V Dual Supply

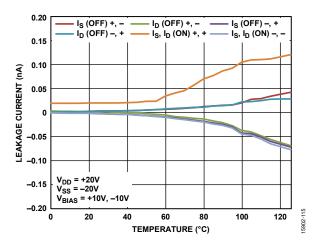
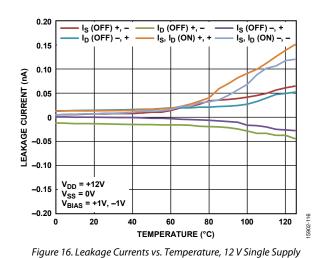


Figure 15. Leakage Currents vs. Temperature, ±20 V Dual Supply



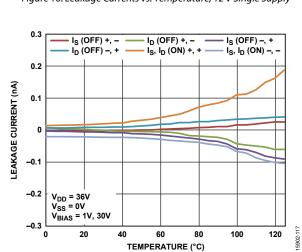


Figure 17. Leakage Currents vs. Temperature, 36 V Single Supply

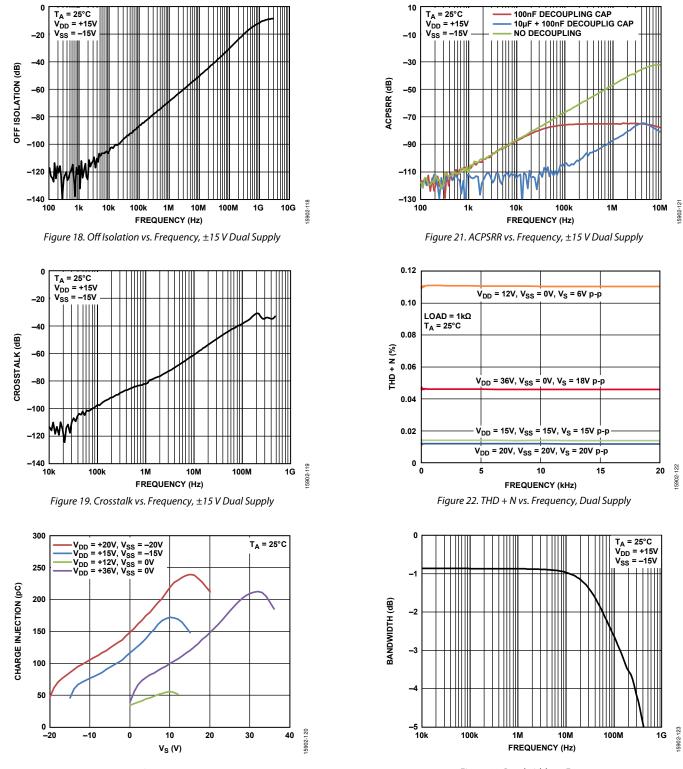


Figure 20. Charge Injection vs. Vs

Figure 23. Bandwidth vs. Frequency

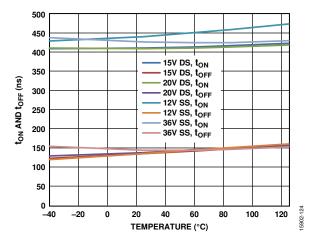


Figure 24. ton and toFF Times vs. Temperature

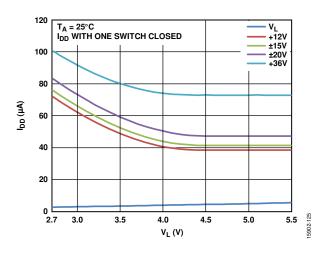
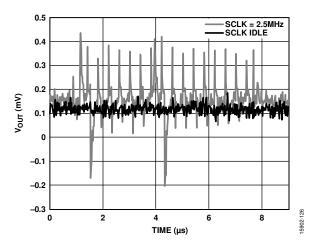
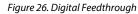


Figure 25. IDD vs. VL





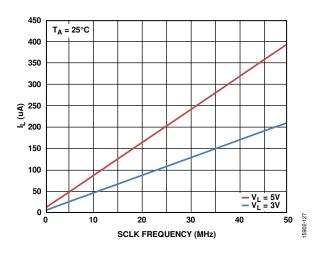
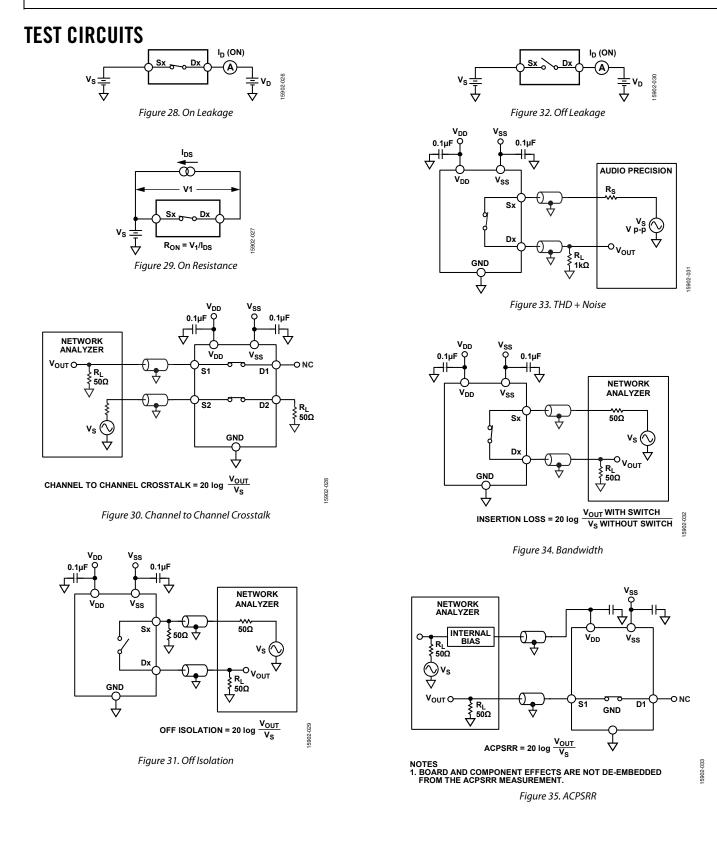
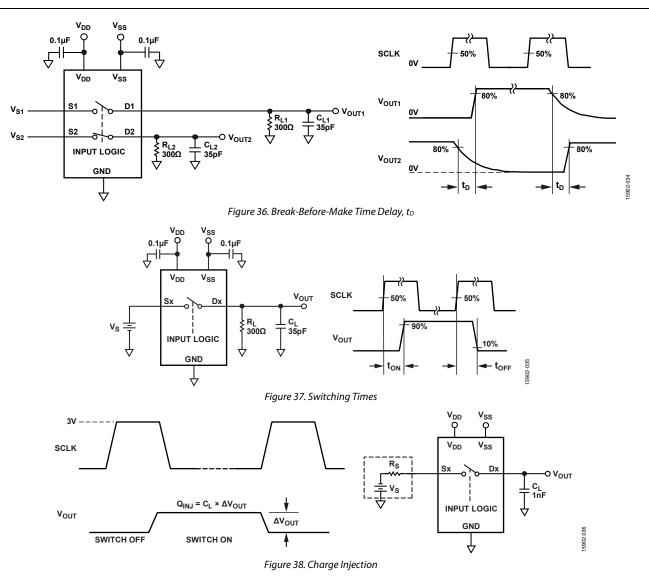


Figure 27. I<sub>L</sub> vs. SCLK Frequency when  $\overline{CS}$  is High

### **Data Sheet**





### TERMINOLOGY

#### Idd

I<sub>DD</sub> is the positive supply current.

#### Iss

Iss is the negative supply current.

#### VD, Vs

 $V_{\rm D}$  and  $V_{\rm S}$  are the analog voltages on Terminal D and Terminal S, respectively.

#### Ron

 $R_{\mbox{\scriptsize ON}}$  represents the ohmic resistance between Terminal D and Terminal S.

#### $\Delta R_{ON}$

 $\Delta R_{\rm ON}$  is the difference between the  $R_{\rm ON}$  of any two channels.

#### R<sub>FLAT(ON)</sub>

 $R_{\rm FLAT(ON)}$  is defined as the difference between the maximum and minimum value of on resistance measured over the specified analog signal range.

#### Is (Off)

Is (Off) is the source leakage current with the switch off.

#### I<sub>D</sub> (Off)

 $I_{\rm D}$  (Off) is the drain leakage current with the switch off.

#### $I_{D}$ (On), $I_{S}$ (On)

 $I_{\rm D}$  (On) and  $I_{\rm S}$  (On) are the channel leakage currents with the switch on.

#### VINL

 $V_{\mbox{\scriptsize INL}}$  is the maximum input voltage for Logic 0.

#### VINH

 $V_{\ensuremath{\text{INH}}}$  is the minimum input voltage for Logic 1.

#### IINL, IINH

 $I_{\rm INL}$  and  $I_{\rm INH}$  are the low and high input currents of the digital inputs.

#### C<sub>D</sub> (Off)

 $C_{\text{D}}$  (Off) is the off switch drain capacitance, which is measured with reference to GND.

#### C<sub>s</sub> (Off)

 $C_{s}$  (Off) is the off switch source capacitance, which is measured with reference to GND.

#### $C_D$ (On), $C_S$ (On)

 $C_{\text{D}}$  (On) and  $C_{\text{S}}$  (On) are the on switch capacitances, which are measured with reference to GND.

#### Cin

C<sub>IN</sub> is the digital input capacitance.

#### ton

 $t_{\rm ON}$  is the delay between applying the digital control input and the output switching on.

#### toff

 $t_{\text{OFF}}$  is the delay between applying the digital control input and the output switching off.

#### t<sub>D</sub>

 $t_{\rm D}$  is the off time measured between the 80% point of both switches when switching from one address state to another.

#### **Off Isolation**

Off isolation is a measure of unwanted signal coupling through an off switch.

#### **Charge Injection**

Charge injection is a measure of the glitch impulse transferred from the digital input to the analog output during switching.

#### Crosstalk

Crosstalk is a measure of unwanted signal that is coupled through from one channel to another as a result of parasitic capacitance.

#### Bandwidth

Bandwidth is the frequency at which the output is attenuated by 3 dB.

#### On Response

On response is the frequency response of the on switch.

### Insertion Loss

Insertion loss is the loss due to the on resistance of the switch.

#### Total Harmonic Distortion + Noise (THD + N)

The ratio of the harmonic amplitude plus noise of the signal to the fundamental.

#### AC Power Supply Rejection Ratio (ACPSRR)

ACPSRR is the ratio of the amplitude of signal on the output to the amplitude of the modulation. ACPSRR is a measure of the ability of the device to avoid coupling noise and spurious signals that appear on the supply voltage pin to the output of the switch. The dc voltage on the device is modulated by a sine wave of 0.62 V p-p.

### THEORY OF OPERATION

The ADGS5414 is a set of SPI controlled, octal SPST switches with error detection features. SPI Mode 0 and Mode 3 can be used with the device, and it operates with SCLK frequencies up to 50 MHz. The default mode for the ADGS5414 is address mode in which the registers of the device are accessed by a 16-bit SPI command that is bounded by CS. The SPI command becomes 24 bits long if the user enables CRC error detection. Other error detection features include SCLK count error detection and invalid read/write error detection. If any of these SPI interface errors occur, they are detectable by reading the error flags register. The ADGS5414 can also operate in two other modes: burst mode and daisy-chain mode.

The interface pins of the ADGS5414 are  $\overline{CS}$ , SCLK, SDI, and SDO. Hold  $\overline{CS}$  low when using the SPI interface. Data is captured on SDI on the rising edge of SCLK, and data is propagated out on SDO on the falling edge of SCLK. SDO has an open-drain output; thus, connect a pull-up to this output. When not pulled low by the ADGS5414, SDO is in a high impedance state.

### ADDRESS MODE

Address mode is the default mode for the ADGS5414 upon power-up. A single SPI frame in address mode is bounded by a  $\overline{\text{CS}}$  falling edge and the succeeding  $\overline{\text{CS}}$  rising edge. The SPI frame is comprised of 16 SCLK cycles. The timing diagram for address mode is shown in Figure 39. The first SDI bit indicates if the SPI command is a read or write command. When the first bit is set to 0, a write command is issued, and if the first bit is set to 1, a read command is issued. The next seven bits determine the target register address. The remaining eight bits provide the data to the addressed register. The last eight bits are ignored during a read command, because, during these clock cycles, SDO propagates out the data contained in the addressed register.

The target register address of an SPI command is determined on the eighth SCLK rising edge. Data from this register propagates out on SDO from the ninth to the 16th SCLK falling edge during SPI reads.

A register write occurs on the 16th SCLK rising edge during SPI writes.

During any SPI command, SDO sends out eight alignment bits on the first eight SCLK falling edges. The alignment bits observed at SDO are 0x25.

#### **ERROR DETECTION FEATURES**

Protocol and communication errors on the SPI interface are detectable. There are three detectable errors: incorrect SCLK error detection, invalid read and write address error detection, and CRC error detection. Each of these errors has a corresponding enable bit in the error configuration register. In addition, there is an error flag bit for each of these errors in the error flags register.

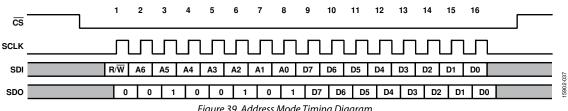
#### **CRC Error Detection**

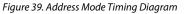
The CRC error detection feature extends a valid SPI frame by eight SCLK cycles. These eight extra cycles send the CRC byte for that SPI frame. The CRC byte is calculated by the SPI block using the 16-bit payload: the  $R/\overline{W}$  bit, a selected register address, Bits[6:0], and selected Register Data Bits[7:0]. The CRC polynomial used in the SPI block is  $x^8 + x^2 + x^1 + 1$  with a seed value of 0. For a timing diagram with CRC enabled, see Figure 40. Register writes occur at the 24th SCLK rising edge with CRC error checking enabled.

During an SPI write, the microcontroller or computer processing unit (CPU) provides the CRC byte through SDI. The SPI block checks the CRC byte just before the 24th SCLK rising edge. On this same edge, the register write is prevented if an incorrect CRC byte is received by the SPI interface. The CRC error flag is asserted in the error flags register in the case of the incorrect CRC byte being detected.

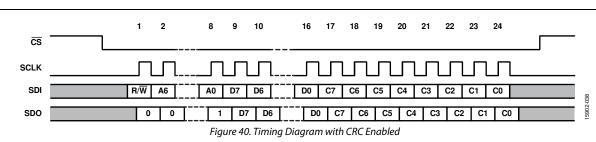
During an SPI read, the CRC byte is provided to the microcontroller through SDO.

The CRC error detection feature is disabled by default and can be configured by the user through the error configuration register.





### **Data Sheet**



#### SCLK Count Error Detection

SCLK count error detection allows the user to detect if an incorrect number of SCLK cycles are sent by the microcontroller or CPU. When in address mode, with CRC disabled, 16 SCLK cycles are expected. If 16 SCLK cycles are not detected, the SCLK count error flag asserts in the error flags register. When less than 16 SCLK cycles are received by the device, a write to the register map does not occur. When the ADGS5414 receives more than 16 SCLK cycles, a write to the memory map still occurs at the 16<sup>th</sup> SCLK rising edge, and the flag asserts in the error flags register. With CRC enabled, the expected number of SCLK cycles becomes 24. SCLK count error detection is enabled by default and can be configured by the user through the error configuration register.

#### Invalid Read/Write Address Error

An invalid read/write address error detects when a nonexistent register address is a target for a read or write. In addition, this error asserts when a write to a read only register is attempted. The invalid read/write address error flag asserts in the error flags register when an invalid read/write address error occurs. The invalid read/write address error is detected on the ninth SCLK rising edge, which means a write to the register does not occur when an invalid address is targeted. Invalid read/write address error detection is enabled by default and can be disabled by the user through the error configuration register.

#### **CLEARING THE ERROR FLAGS REGISTER**

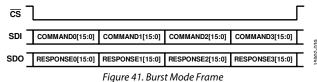
To clear the error flags register, write the 16-bit SPI frame (not included in the register map), 0x6CA9, to the device. This SPI command does not trigger the invalid  $R/\overline{W}$  address error. When CRC is enabled, the user must send the correct CRC byte for a successful error clear command. At the 16<sup>th</sup> or 24<sup>th</sup> SCLK rising edge, the error flags register resets to zero.

#### **BURST MODE**

The SPI interface can accept consecutive SPI commands without the need to deassert the  $\overline{\text{CS}}$  line, which is called burst mode. Burst mode is enabled through the burst enable register (Address 0x05). This mode uses the same 16-bit command to communicate with the device. In addition, the response of the device at SDO is still aligned with the corresponding SPI command. Figure 41 shows an example of SDI and SDO during burst mode.

ADGS5414

The invalid read/write address and CRC error checking functions operate similarly during burst mode as they do during address mode. However, SCLK count error detection operates in a slightly different manner. The total number of SCLK cycles within a given  $\overline{\text{CS}}$  frame is counted, and if the total is not a multiple of 16, or a multiple of 24 when CRC is enabled, the SCLK count error flag asserts.

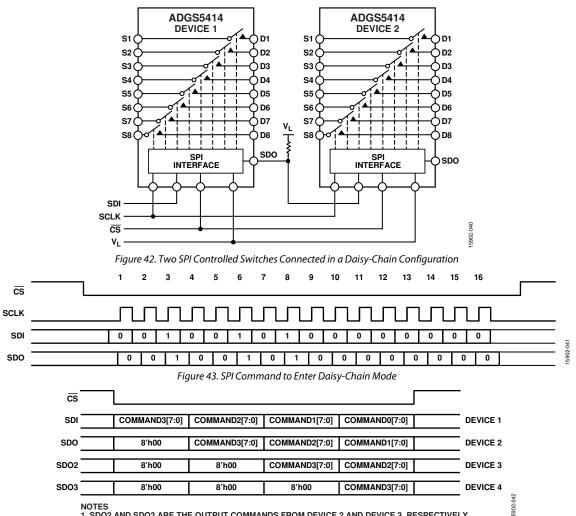


#### SOFTWARE RESET

When in address mode, the user can initiate a software reset. To do so, write two consecutive SPI commands, namely 0xA3 followed by 0x05, to Register 0x0B. After a software reset, all register values are set to default.

#### **DAISY-CHAIN MODE**

The connection of several ADGS5414 devices in a daisy-chain configuration is possible, and Figure 42 shows this setup. All devices share the same  $\overline{CS}$  and SCLK line, whereas the SDO of a device forms a connection to the SDI of the next device, creating a shift register. In daisy-chain mode, SDO is an eight cycle delayed version of SDI. When in daisy-chain mode, all commands target the switch data register (SW\_DATA). Therefore, it is not possible to make configuration changes while in daisy-chain mode.



1. SDO2 AND SDO3 ARE THE OUTPUT COMMANDS FROM DEVICE 2 AND DEVICE 3, RESPECTIVELY. Figure 44. Example of an SPI Frame when Four ADGS5414 Devices are Connected in Daisy-Chain Mode

The ADGS5414 can only enter daisy-chain mode when in address mode by sending the 16-bit SPI command, 0x2500 (see Figure 43). When the ADGS5414 receives this command, the SDO of the device sends out the same command because the alignment bits at SDO are 0x25, which allows multiple daisy-connected devices to enter daisy-chain mode in a single SPI frame. A hardware reset is required to exit daisy-chain mode.

For the timing diagram of a typical daisy-chain SPI frame, see Figure 44. For example, when  $\overline{CS}$  goes high, Device 1 writes Command 0, SW\_DATA, Bits[7:0] to its switch data register, Device 2 writes Command 1, SW\_DATA, Bits[7:0] to its switches. The SPI block uses the last eight bits it receives through SDI to update the switches. After entering daisy-chain mode, the first eight bits sent out by SDO on each device in the chain are 0x00. When  $\overline{CS}$  goes high, the internal shift register value does not reset back to zero. An SCLK rising edge reads in data on SDI while data is propagated out on SDO on an SCLK falling edge. The expected number of SCLK cycles must be a multiple of eight before  $\overline{CS}$ goes high. If this is not the case, the SPI interface sends the last eight bits received to the switch data register.

#### **POWER-ON RESET**

The digital section of the ADGS5414 goes through an initialization phase during  $V_L$  power-up. This initialization also occurs after a hardware or software reset. After  $V_L$  power-up or a reset, ensure a minimum of 120  $\mu$ s from the time of power-up or reset before any SPI command is issued. Ensure  $V_L$  does not drop out during the 120  $\mu$ s initialization phase because it can result in the incorrect operation of the ADGS5414.

#### **BREAK-BEFORE-MAKE SWITCHING**

The ADGS5414 exhibits break-before-make switching action, which allows the use of the device in multiplexer applications. A multiplexer function can be achieved by externally hardwiring the device in the required mux configuration, as shown in Figure 45.

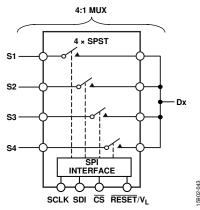


Figure 45. An SPI Controlled Switch Configured in a 4:1 Mux

#### **TRENCH ISOLATION**

In the analog switch section of the ADGS5414, an insulating oxide layer (trench) is placed between the N-type metal-oxide semiconductor (NMOS) and the P-type metal-oxide semiconductor (PMOS) transistors of each complementary metal-oxide semiconductor CMOS switch. Parasitic junctions, which occur between the transistors in junction isolated switches, are eliminated, and the result is a completely latch-up proof switch. In junction isolation, the P-well and N-well of the PMOS and NMOS transistors form a diode that is reverse-biased under normal operation. However, during overvoltage conditions, this diode can become forward-biased. A silicon controlled rectifier (SCR) circuit is formed by the two transistors, causing a significant amplification of the current that, in turn, leads to latch-up. With trench isolation, this diode is removed, and the result is a latchup proof switch.

The Analog Devices, Inc., high voltage latch-up proof family of switches and multiplexers provides a robust olution for instrumentation, industrial, aerospace, and other harsh environments that are prone to latch-up, which is an undesirable high current state that can lead to device failure and persists until the power supply is turned off. The ADGS5414 high voltage switches allow single-supply operation from 9 V to 40 V and dual-supply operation from  $\pm 9$  V to  $\pm 22$  V.

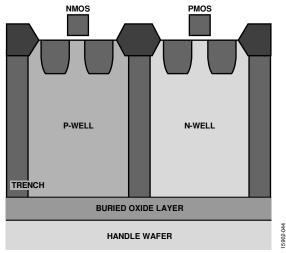


Figure 46. Trench Isolation

### **APPLICATIONS INFORMATION**

### POWER SUPPLY RAILS

To guarantee correct operation of the ADGS5414, 0.1  $\mu F$  decoupling capacitors are required.

The ADGS5414 can operate with bipolar supplies between  $\pm 9$  V and  $\pm 22$  V. The supplies on V<sub>DD</sub> and V<sub>SS</sub> do not need to be symmetrical; however, the V<sub>DD</sub> to V<sub>SS</sub> range must not exceed 44 V. The ADGS5414 can also operate with single supplies between 9 V and 40 V with V<sub>SS</sub> connected to GND.

The voltage range that can be supplied to  $V_{\rm L}$  is from 2.7 V to 5.5 V.

The device is fully specified at  $\pm 15$  V,  $\pm 20$  V,  $\pm 12$  V, and  $\pm 36$  V, analog supply voltage ranges.

#### POWER SUPPLY RECOMMENDATIONS

Analog Devices has a wide range of power management products that meet the requirements of most high performance signal chains.

An example of a bipolar power solution is shown in Figure 47. The ADP5070 dual switching regulator generates a positive and negative supply rail for the ADGS5414, an amplifier, and/or a precision converter in a typical signal chain.

Figure 47 also shows two optional low dropout regulators (LDOs), ADP7118 and ADP7182, positive and negative LDOs respectively, that can reduce the output ripple of the ADP5070 in ultralow noise sensitive applications.

The ADM7160 can be used to generate the  $V_L$  voltage that is required to power the digital circuitry within the ADGS5414.

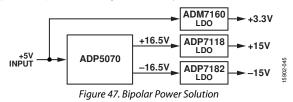


Table 10. Recommended Power Management Devices

	0
Product	Description
ADP5070	1 A/0.6 A, dc-to-dc switching regulator with independent positive and negative outputs
ADM7160	
ADP7118	20 V, 200 mA, low noise, CMOS LDO linear regulator
ADP7182	–28 V, –200 mA, low noise, LDO linear regulator

# **REGISTER SUMMARY**

### Table 11. Register Summary

Reg.	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2		Bit 1		Bit 0	1	Default	RW
0x01	SW_DATA	SW8_EN	SW7_EN	SW6_EN	SW5_EN	SW4_EN	SW3_EN		SW2_E	N	SW1	_EN	0x00	R/W
0x02	ERR_CONFIG		Reserved RW_ERR_EN SCLK_ERR_EN				CRC	_ERR_EN	0x06	R/W				
0x03	ERR_FLAGS		Reserved RW_ERR_FLAG SCLK_ERR_FLAG					CRC	_ERR_FLAG	0x00	R			
0x05	BURST_EN		Reserved BURST_MODI						ST_MODE_EN	0x00	R/W			
0x0B	SOFT_RESETB					SOFT	RESETB						0x00	R/W

### **REGISTER DETAILS**

#### SWITCH DATA REGISTER

#### SW\_DATA, Address 0x01, Reset: 0x00

The switch data register controls the status of the eight switches of the ADGS5414.

Bit	Bit Name	Setting	Description	Default	Access	
7	SW8_EN		Enable bit for Switch 8.	0x0	R/W	
		0	Switch 8 open.			
		1	Switch 8 closed.			
6	SW7_EN		Enable bit for Switch 7.	0x0	R/W	
		0	Switch 7 open.			
		1	Switch 7 closed.			
5	SW6_EN		Enable bit for Switch 6.	0x0	R/W	
		0	Switch 6 open.			
		1	Switch 6 closed.			
4	SW5_EN		Enable bit for Switch 5.	0x0	R/W	
		0	Switch 5 open.			
		1	Switch 5 closed.			
3	SW4_EN		Enable bit for Switch 4.	0x0	R/W	
		0	Switch 4 open.			
		1	Switch 4 closed.			
2	SW3_EN		Enable bit for Switch 3.	0x0	R/W	
		0	Switch 3 open.			
		1	Switch 3 closed.			
1	SW2_EN		Enable bit for Switch 2.	0x0	R/W	
		0	Switch 2 open.			
		1	Switch 2 closed.			
0	SW1_EN		Enable bit for Switch 1.	0x0	R/W	
		0	Switch 1 open.			
		1	Switch 1 closed.			

#### Table 12. Bit Descriptions for SW\_DATA

### ERROR CONFIGURATION REGISTER

#### ERR\_CONFIG, Address 0x02, Reset: 0x06

The error configuration register allows the user to enable or disable the relevant error features as required.

Bit	Bit Name	Setting	Description	Default	Access
[7:3]	Reserved		These bits are reserved; set these bits to 0.	0x0	R
2	RW_ERR_EN		Enable bit for detecting an invalid read/write address.	0x1	R/W
		0	Disabled.		
		1	Enabled.		
1	SCLK_ERR_EN	0	Enable bit for detecting the correct number of SCLK cycles in an SPI frame. 16 SCLK cycles are expected when CRC is disabled and burst mode is disabled. 24 SCLK cycles are expected when CRC is enabled and burst mode is disabled. A multiple of 16 SCLK cycles is expected when CRC is disabled and burst mode is enabled. A multiple of 24 SCLK cycles is expected when CRC is enabled and burst mode is enabled. Disabled.	0x1	R/W
		1	Enabled.		
0	CRC_ERR_EN		Enable bit for CRC error detection. SPI frames must be 24 bits wide when enabled.	0x0	R/W
		0	Disabled.		
		1	Enabled.		

#### Table 13. Bit Descriptions for ERR\_CONFIG

#### **ERROR FLAGS REGISTER**

#### ERR\_FLAGS, Address 0x03, Reset: 0x00,

The error flags register allows the user to determine if an error occurs. To clear the error flags register, write the special 16-bit SPI command, 0x6CA9, to the device. This SPI command does not trigger the invalid R/W address error. When CRC is enabled, the user must include the correct CRC byte during the SPI write for the clear Error Flags Register command to be successful.

Bit	Bit Name	Setting	Description		Access
[7:3]	RESERVED		These bits are reserved and are set to 0.	0x0	R
2	RW_ERR_FLAG		Error flag for invalid read/write address. The error flag asserts during an SPI read if the target address does not exist. The error flag also asserts when the target address of a SPI write is does not exist or is read only.		R
		0	No Error.		
		1	Error.		
1	SCLK_ERR_FLAG		Error flag for the detection of the correct number of SCLK cycles in an SPI frame.	0x0	R
		0	No Error.		
		1	Error.		
0	CRC_ERR_FLAG		Error Flag that determines if a CRC error occurs during a register write.	0x0	R
		0	No Error.		
		1	Error.		

#### Table 14. Bit Descriptions for ERR\_FLAGS

#### **BURST ENABLE REGISTER**

#### BURST\_EN, Address 0x05, Reset: 0x00

The burst enable register allows the user to enable/disable the burst mode. When enabled, the user can send multiple consecutive SPI commands without deasserting  $\overline{CS}$ .

#### Table 15. Bit Descriptions for BURST\_EN

Bits	Bit Name	Settings	Description	Default	Access
[7:1]	Reserved		These bits are reserved; set these bits to 0.	0x0	R
0	BURST_MODE_EN		Burst mode enable bit.	0x0	R/W
		0	Disabled.		
		1	Enabled.		

#### SOFTWARE RESET REGISTER

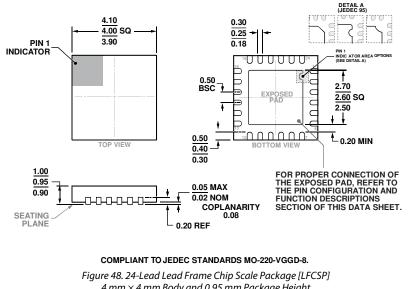
#### SOFT\_RESETB, Address 0x0B, Reset: 0x00

This register performs a software reset. Consecutively, write 0xA3 and 0x05 to this register and to reset the device registers to their default state.

#### Table 15. Bit Descriptions for SOFT\_RESETB

Bits	Bit Name	Settings	Description	Default	Access
[7:0]	SOFT_RESETB		To Perform a Software Reset, consecutively write 0xA3 followed by 0x05 to this register.	0x0	R

### **OUTLINE DIMENSIONS**



4 mm × 4 mm Body and 0.95 mm Package Height (CP-24-17)

Dimensions shown in millimeters

#### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range	Package Description	Package Option
ADGS5414BCPZ	-40°C to +125°C	24-Lead Lead Frame Chip Scale Package [LFCSP]	CP-24-17
ADGS5414BCPZ-RL7	-40°C to +125°C	24-Lead Lead Frame Chip Scale Package [LFCSP]	CP-24-17
EVAL-ADGS5414SDZ		Evaluation Board	

 $^{1}$  Z = RoHS Compliant Part.



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