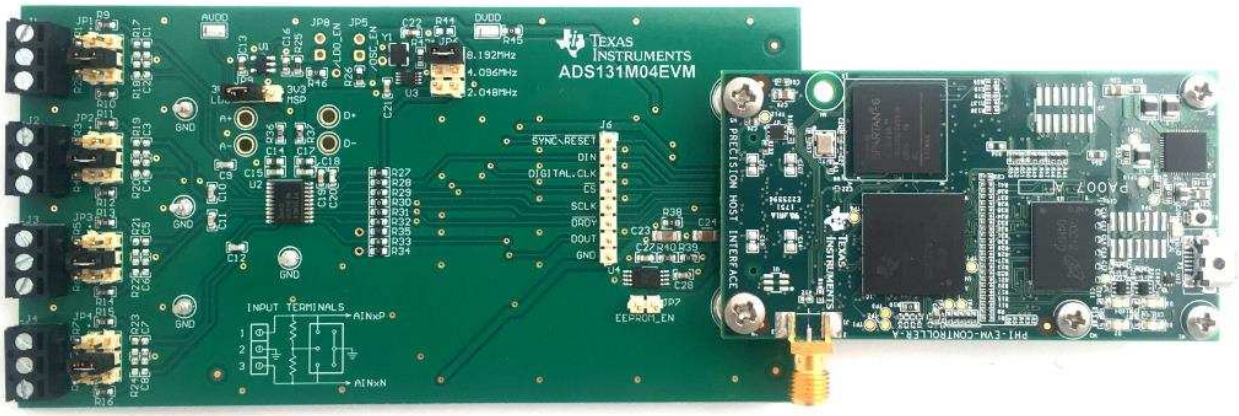
ADS131M04 Evaluation Module



This user's guide describes the characteristics, operation, and use of the ADS131M04 evaluation module (EVM). This kit is an evaluation platform for the ADS131M04, which is a 4-channel, simultaneously-sampling, 24-bit, delta-sigma (ΔΣ) analog-to-digital converter (ADC). The ADS131M04 offers wide dynamic range and internal calibration features, making the device excellent for energy metering, power quality, protection relay, and circuit breaker applications.

The ADS131M04EVM eases the evaluation of the device with hardware, software, and computer connectivity through the universal serial bus (USB) interface. This user's guide includes complete circuit descriptions, schematic diagrams, and a bill of materials. Throughout this document, the abbreviation *EVM* and the term *evaluation module* are synonymous with the ADS131M04EVM. The following related documents are available through the Texas Instruments web site at www.ti.com.

Table 1. Related Documentation

Device	Literature Number
ADS131M04	SBAS890

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1 EVM Overview

The ADS131M04EVM is a platform for evaluating the performance of the ADS131M04, which is a 4-channel, simultaneously-sampling, 24-bit, ΔΣ ADC. The evaluation kit includes the ADS131M04EVM board and the precision host interface (PHI) controller board that enables the accompanying computer software to communicate with the ADC over the USB for data capture and analysis.

The ADS131M04EVM board includes the ADS131M04 ADC and all the peripheral analog circuits and components required to extract optimum performance from the ADC.

The PHI board primarily serves three functions:

- Provides a communication interface from the EVM to the computer through a USB port
- Provides the digital input and output signals necessary to communicate with the ADS131M04
- Supplies power to all active circuitry on the ADS131M04EVM board

1.1 ADS131M04EVM Kit

The ADS131M04 evaluation module kit includes the following features:

- Hardware and software required for diagnostic testing as well as accurate performance evaluation of the ADS131M04 ADC
- USB powered—no external power supply is required
- The PHI controller that provides a convenient communication interface to the ADS131M04 ADC over USB 2.0 (or higher) for power delivery as well as digital input and output
- Easy-to-use evaluation software for 64-bit Microsoft Windows® 7, Windows 8, and Windows 10 operating systems
- The software suite includes graphical tools for data capture, histogram analysis, and spectral analysis. This suite also has a provision for exporting data to a text file for post-processing.

Figure 1 illustrates an example system setup for evaluation.

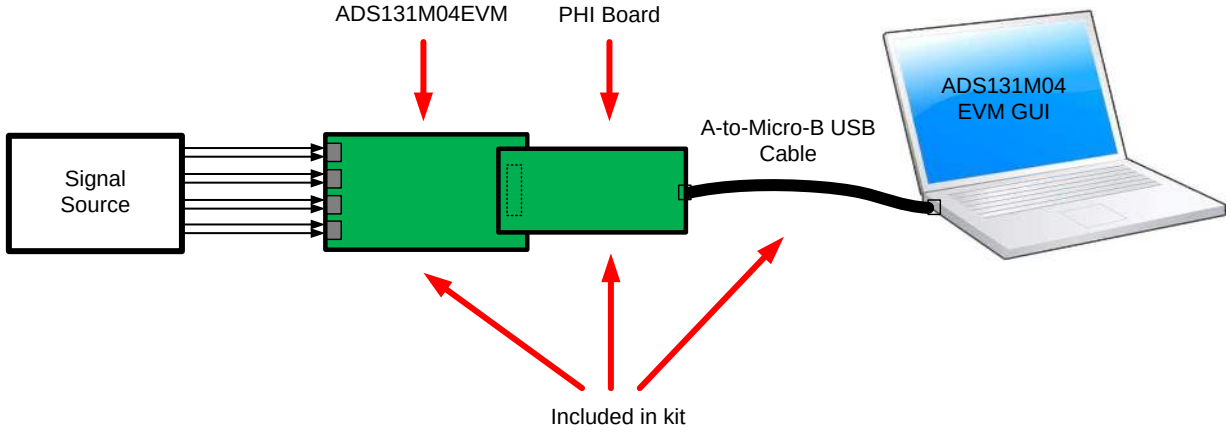

Figure 1. System Connection for Evaluation

1.2 ADS131M04EVM Board

The ADS131M04EVM board includes the following features:

- External signal source from differential pair headers
- Options to use external analog and digital power supplies
- Serial interface header for easy connection to the PHI controller
- Pin connections to monitor digital signals with a logic analyzer
- Onboard ultra-low noise low-dropout (LDO) regulator for excellent 3.3-V, single-supply regulation of all analog circuits

2 EVM Analog Interface

The ADS131M04EVM is designed for easy interfacing with analog sources. This section covers the details of the front-end circuit including jumper configuration for different input test signals and board connectors for signal sources.

2.1 ADC Analog Input Signal Path

Analog inputs to the EVM can be connected to either the terminal blocks or to the header pins associated with each ADC channel. The 3x2 100-mil headers for each channel allow the user to configure the inputs differentially depending on the signal to be measured. The screw terminal blocks can interface directly with the leads of an external sensor input. Figure 2 shows the signal chain used for all four input channels on the EVM and is used to describe the supported input options in Figure 3, Table 2, and Table 3.

External voltage inputs can be applied to J1 pins 1 and 3. For single-ended inputs, install a jumper on either JP1[1-2] or JP1[5-6] to connect an input to the EVM ground. If the external voltage is applied through a series resistor, R1 or R2 can be used to form a resistor divider by installing JP1[3-4] to support higher voltage measurements. Input jumper connections are described in Table 2. Similarly, R17 and R18 can be installed to form a resistor divider with the series 49.9-Ω resistors on each input. An input must not be applied such that the voltage on the input pins of the ADS131M04 exceeds the absolute maximum ratings. See the ADS131M04 data sheet for details.

R1 and R2 also present a 2-kΩ differential load when all jumpers on JP1 are uninstalled. This load acts as a burden resistor for a current transformer (CT) input. For single-ended measurements, the unused end of the transformer secondary side can be tied to ground by installing the appropriate jumper on JP1.

R9, R10, and C9 form a differential low-pass filter with a –3-dB cutoff frequency of 1.594 MHz. The series impedance is kept relatively low in order to maintain adequate total harmonic distortion (THD) performance.

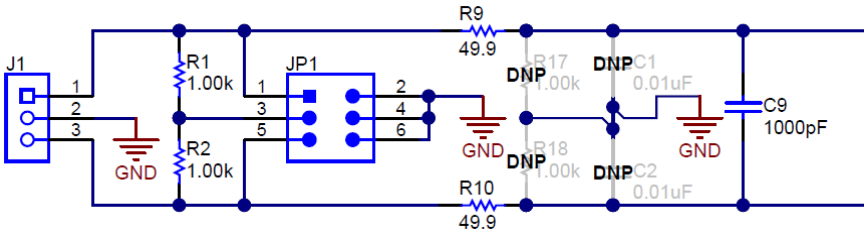

Figure 2. Input Terminal Blocks and Headers (Schematic)

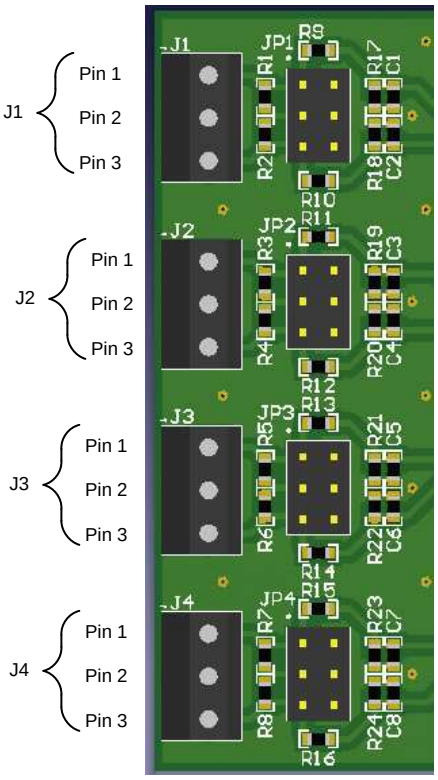

Figure 3. Input Terminal Blocks and Headers (PCB)

Table 2. Analog Input Terminal Blocks, J1–J4

Terminal Block	Pin	Function	ADS131M04 Input Pin
J1	1	Channel 0 positive input	AIN0P
	2	EVM ground	AGND and DGND
	3	Channel 0 negative input	AIN0N
J2	1	Channel 1 positive input	AIN1P
	2	EVM ground	AGND and DGND
	3	Channel 1 negative input	AIN1N
J3	1	Channel 2 positive input	AIN2P
	2	EVM ground	AGND and DGND
	3	Channel 2 negative input	AIN2N
J4	1	Channel 3 positive input	AIN3P
	2	EVM ground	AGND and DGND
	3	Channel 3 negative input	AIN3N

Table 3. Analog Input Jumper Connection, JP1–JP4

Jumper	Position	Description
JP1	Connection for channel 0 analog inputs	
	[1-2]	Short positive input to ground
	[3-4]	Connect both inputs to ground via 1-kΩ resistors (default)
	[5-6]	Short negative input to ground
JP2	Connection for channel 1 analog inputs	
	[1-2]	Short positive input to ground
	[3-4]	Connect both inputs to ground via 1-kΩ resistors (default)
	[5-6]	Short negative input to ground
JP3	Connection for channel 2 analog inputs	
	[1-2]	Short positive input to ground
	[3-4]	Connect both inputs to ground via 1-kΩ resistors (default)
	[5-6]	Short negative input to ground
JP4	Connection for channel 3 analog inputs	
	[1-2]	Short positive input to ground
	[3-4]	Connect both inputs to ground via 1-kΩ resistors (default)
	[5-6]	Short negative input to ground

2.2 ADC External Clock (CLKIN) Options

The ADS131M04 requires a continuous, free-running external master clock at the CLKIN pin for normal operation. The onboard complementary metal oxide semiconductor (CMOS) crystal oscillator (Y1) provides the nominal 8.192-MHz clock frequency used in the high-resolution (HR) mode of the device. Two D flip-flops (U3) divide the Y1 clock output to produce clock frequencies of 4.096 MHz and 2.048 MHz to support the low-power (LP) mode and very-low-power (VLP) mode, respectively.

Install a jumper in the appropriate position on the JP6 header shown in Figure 4 to provide selectable clock frequency options. An external clock frequency can also be provided to any even-numbered pin on JP6 when the jumper is uninstalled. TI also recommends powering down Y1 by installing JP5 when providing an external clock. When using an external clock, ground must be shared between the external clock source and the EVM ground. The external clock must adhere to the frequency and amplitude limits outlined in the ADS131M04 data sheet. Table 4 lists the JP6 jumper settings for the clock input selections.

In addition to jumper settings, each of the power modes requires configuration register settings outlined in Section 6.1.

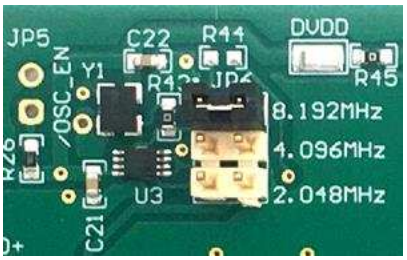

Figure 4. CLKIN External Clock (PCB)

Table 4. CLKIN External Clock Options

J13 Jumper Setting	Clock Frequency	Description
[1-2]	8.192 MHz	Nominal clock for high-resolution mode (default)
[3-4]	4.096 MHz	Nominal clock for low-power mode
[5-6]	2.048 MHz	Nominal clock for very-low-power mode

3 Digital Interface

As noted in Section 1, the EVM interfaces with the PHI and communicates with the computer over the USB. There are two devices on the EVM with which the PHI communicates: the ADS131M04 ADC (over SPI) and the EEPROM (over I^2C). The EEPROM comes pre-programmed with the information required to configure and initialize the ADS131M04EVM platform. When the hardware is initialized, the EEPROM is no longer used.

3.1 SPI Communication

The ADS131M04EVM supports limited interface modes as detailed in the ADS131M04 data sheet. The ADS131M04 uses an SPI-compatible interface to configure the device and retrieve conversion data. SPI communication on the ADS131M04 is performed in frames. Each SPI communication frame consists of several words. The word size is configurable as either 16 bits, 24 bits (default), or 32 bits by programming the WLENGTH[1:0] bits in the MODE register.

Additionally, the $\overline{\text{DRDY}}$ pin indicates when conversion data are available to be read by the master. The DRDY_SEL[1:0] bits, DRDY_HIZ bit, and the DRDY_FMT bit in the MODE register control the behavior of the $\overline{\text{DRDY}}$ pin.

For this EVM not all modes and functions for this SPI communication are supported. Functions not supported are disabled in the EVM GUI software. For more information about the SPI communication, see the ADS131M04 data sheet.

3.2 Connection to the PHI

The ADS131M04EVM board communicates with the PHI through a shrouded, 60-pin connector, J5. There are two round standoffs next to J5 with Phillips-head screws. To connect the PHI to the EVM, remove the screws, attach the PHI to the EVM, and replace the screws into the standoffs. The screws secure the EVM to the PHI and ensures the connection between the boards.

Table 5 lists the different PHI connection and their functions.

Table 5. PHI Connector Pin Functions

PHI Connector Pin Name	PHI Connector Pin	Function
EVM_RAW_5V	J5[2]	Power-supply source for the analog section of the EVM
GND	J5[3]	Ground
SYNC/$\overline{\text{RESET}}$	J5[10]	Conversion synchronization or system reset for the ADS131M04; active low
DIN	J5[18]	Serial data input for the ADS131M04
CLK	J5[20]	Master clock input for the ADS131M04
$\overline{\text{CS}}$	J5[22]	Chip select for the ADS131M04; active low
SCLK	J5[24]	Serial data clock for the ADS131M04
SCLK	J5[28]	Serial data clock for the ADS131M04
$\overline{\text{DRDY}}$	J5[30]	Data ready for the ADS131M04; active low
DOUT	J5[36]	Serial data output for the ADS131M04
EVM_DVDD	J5[50]	Power-supply source for the digital section of the EVM
SDA	J5[56]	I^2C serial data for the EEPROM used to identify the EVM
SCL	J5[58]	I^2C serial clock for the EEPROM used to identify the EVM
EVM_ID_PWR	J5[59]	Power-supply source for the EEPROM used to identify the EVM
GND	J5[60]	Ground

3.3 Digital Header

In addition to the PHI, the EVM has a header connected to the digital lines that can be used to connect a logic analyzer or oscilloscope. This placement allows for easy access to the digital communications. Header J6 is connected to the digital lines between the ADS131M04 and the PHI connector. Table 6 describes the digital header pins.

Table 6. Digital Header Pins

ADS131M04 Pin Name	Digital Header Pin
SYNC/$\overline{\text{RESET}}$	J6[1]
DIN	J6[2]
CLK	J6[3]
$\overline{\text{CS}}$	J6[4]
SCLK	J6[5]
$\overline{\text{DRDY}}$	J6[6]
DOUT	J6[7]
GND	J6[8]

3.4 LaunchPad™ Connectors

On the bottom side of the ADS131M04EVM board is a set of unpopulated surface-mount connectors (J7 and J8). When populated, these devices can be used to connect to a TI LaunchPad™ directly as a typical BoosterPack™ plug-in module.

Connectors J7 and J8 are a set of 10x2, 100 mil connectors. As shown in Table 7, the pin numbers for J7 and J8 map to the pin numbers for a standard 40-pin LaunchPad™ connector.

Table 7. LaunchPad™ Pin Functions

ADS131M04EVM Connection	ADS131M04EVM (J7, J8)	LaunchPad™ Connection
+3.3V	J8[1]	Pin 1
SCLK	J8[7]	Pin 7
DOUT	J7[14]	Pin 14
DIN	J7[12]	Pin 15
GND	J7[2]	Pin 20
+5V	J8[2]	Pin 21
GND	J8[4]	Pin 22
$\overline{\text{DRDY}}$	J7[7]	Pin 37
$\overline{\text{CS}}$	J7[5]	Pin 38
SYNC/$\overline{\text{RESET}}$	J7[3]	Pin 39
CLK	J7[1]	Pin 40

4 Power Supplies

The PHI provides multiple power-supply options for the EVM, derived from the USB supply of the computer.

The EEPROM on the ADS131M04EVM uses a 3.3-V power supply generated directly by the PHI. The analog supply of the ADC is powered by the LP5907 onboard the EVM, which is a low-noise linear regulator that uses the 5-V supply on the PHI to generate a cleaner 3.3-V output. The 3.3-V supply to the digital section of the ADC is provided directly by an LDO on the PHI.

The power supply for each active component on the EVM is bypassed with a ceramic capacitor placed close to that component. Additionally, the EVM layout uses thick traces or large copper fill areas, where possible, between bypass capacitors and their loads to minimize inductance along the load current path.

As mentioned previously in Section 1, power to the EVM is supplied by the PHI through connector J5. For information about PHI pins and the power connections, see Table 5.

With modifications, the user may use external supplies for either AVDD or DVDD. AVDD can be driven externally by moving the jumper on JP9 to the left. This placement disconnects 3V3_LDO from AVDD. Power can then be applied through the AVDD test point at TP2 or through 3V3_LP if connector J8 is installed. DVDD can be driven externally from the DVDD test point at TP1 if R45 is removed from the EVM.

5 ADS131M04EVM Initial Setup

This section explains the initial hardware and software setup procedure that must be completed for properly operating the ADS131M04EVM.

5.1 Default Jumper Settings

After unpacking, the EVM is already configured with the default jumper settings. Figure 5 shows the locations for the default jumpers.

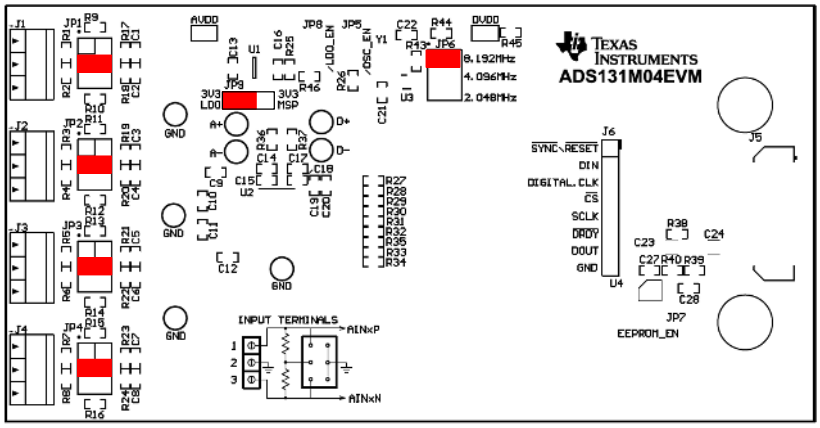

Figure 5. ADS131M04EVM Jumper Default Settings

The default position of the JP6 jumper is across [1-2] at the top. JP6 sets the onboard oscillator frequency to 8.192 MHz, used for the ADS131M04 in high-resolution mode. The default connection for JP9 is to the left, so that the linear regulator is powering the system using 5 V from the PHI controller.

The default settings, as listed in Table 8, includes no jumpers installed at JP5, JP7, and JP8. When installed, JP5 disables the onboard oscillator, JP7 enables the EEPROM for write, and JP8 disables the linear regulator.

Table 8. Default Settings

Jumper	Position	Function
JP1, JP2, JP3, JP4	[3-4]	Sets common-mode to ground for device inputs
JP5	Not installed	Disables on-board oscillator
JP6	[1-2]	Oscillator frequency select, 8.192MHz
JP7	Open	Disables write for EEPROM
JP8	Not installed	Disables linear regulator power
JP9	[1-2]	Selects device power from linear regulator

5.2 EVM Graphical User Interface (GUI) Software Installation

Download the latest version of the EVM GUI installer from the *Tools and Software* folder of the ADS131M04EVM and run the GUI installer to install the EVM GUI software on your computer.

CAUTION

Manually disable any antivirus software running on the computer before downloading the EVM GUI installer onto the local hard disk. Depending on the antivirus settings, an error message may appear or the installer. The exe file can be deleted.

Accept the license agreements and follow the on-screen instructions shown in Figure 6 to complete the installation.

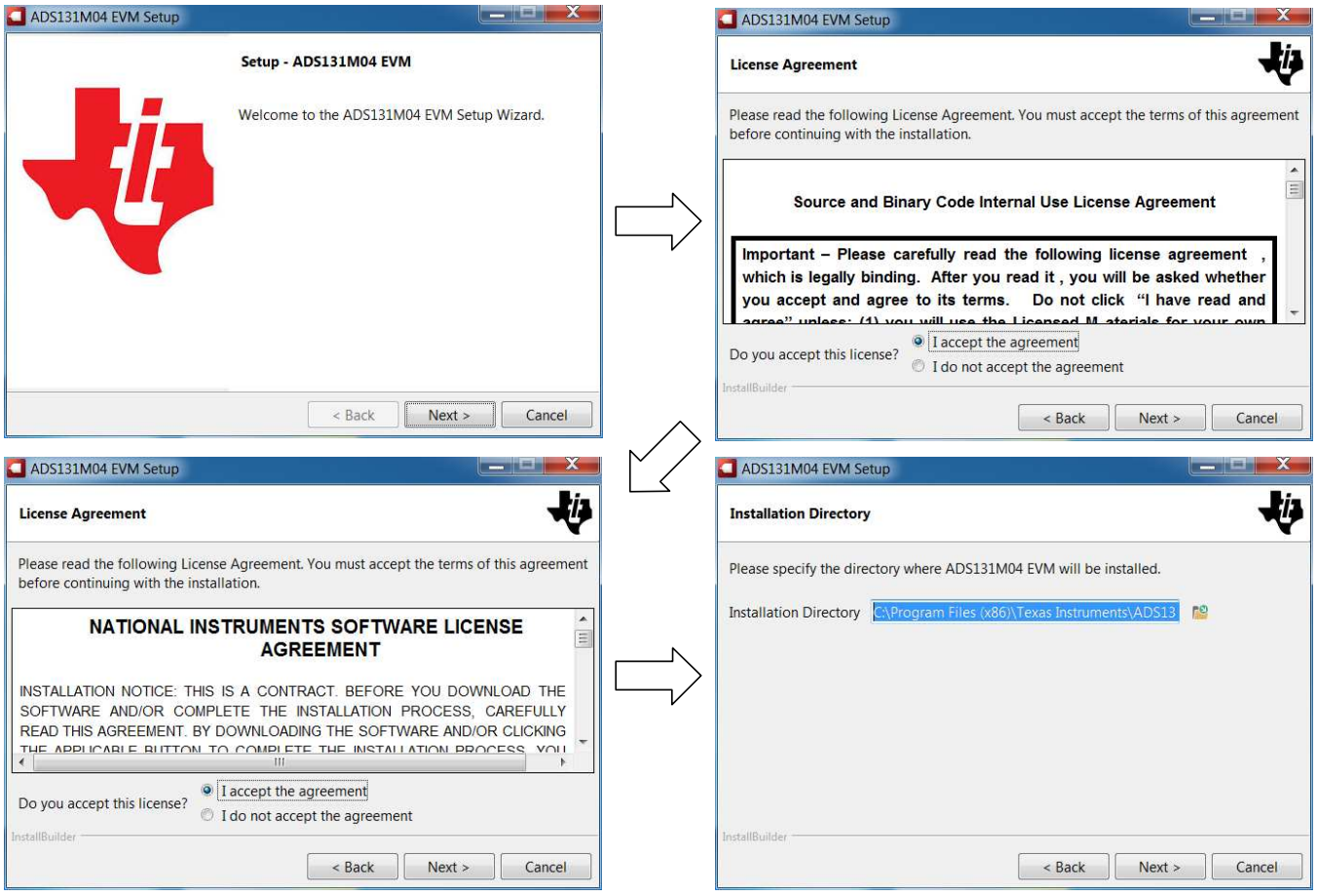

Figure 6. ADS131M04 Software Installation Prompts

As a part of the ADS131M04EVM GUI installation, a prompt with a Device Driver Installation (as shown in Figure 7) appears on the screen. Click *Next* to proceed.

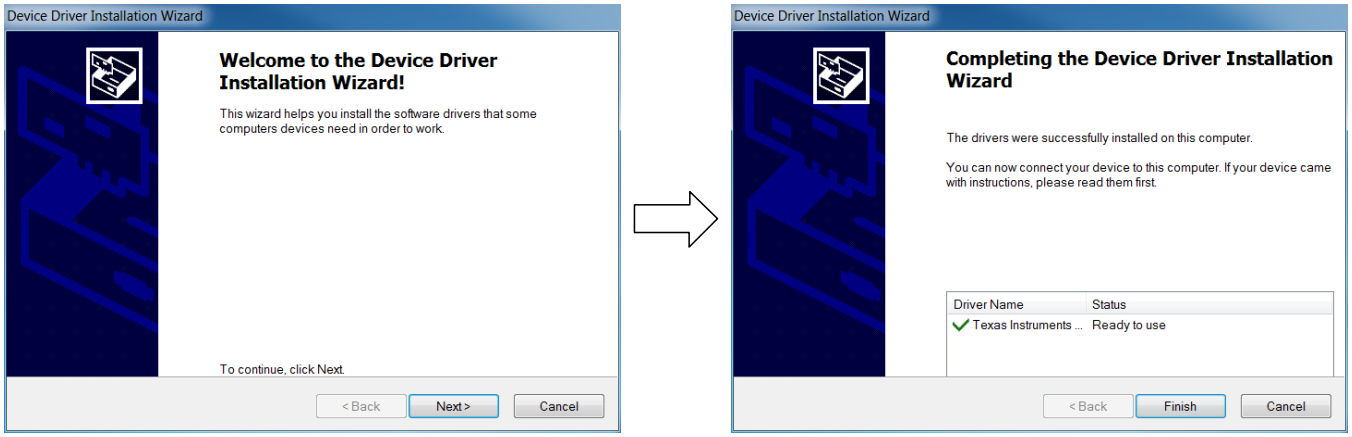

Figure 7. Device Driver Installation Wizard Prompts

NOTE: A notice may appear on the screen stating that Windows cannot verify the publisher of this driver software. Select *Install this driver software anyway*.

The ADS131M04EVM requires the LabVIEW™ run-time engine and may prompt for the installation of this software, as shown in Figure 8, if not already installed.

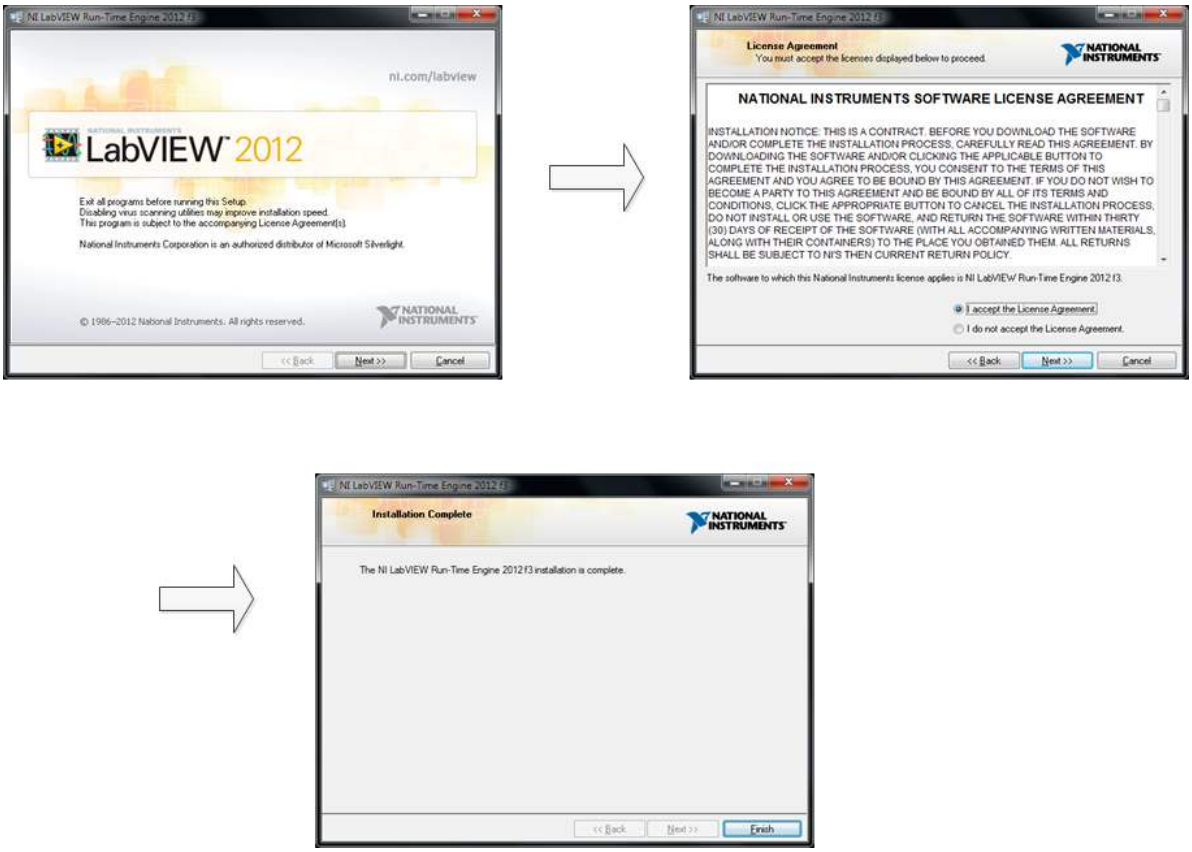

Figure 8. LabVIEW Run-Time Engine Installation

Verify that *C:\Program Files (x86)\Texas Instruments\ADS131M04EVM* is as shown in Figure 9 after these installations.

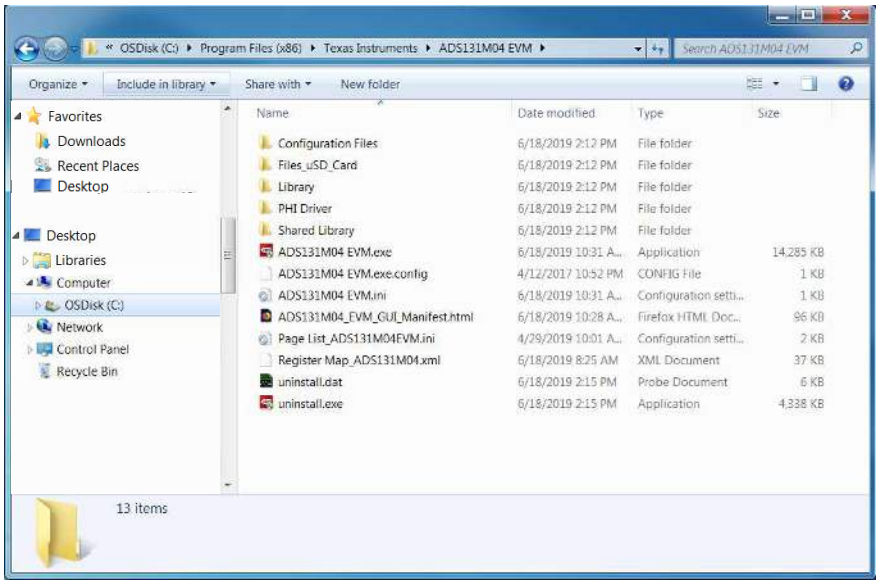

Figure 9. ADS131M04EVM GUI Folder Post-Installation

6 ADS131M04EVM Operation

The following instructions are a step-by-step guide to connecting the ADS131M04EVM to the computer and evaluating the performance of the ADS131M04:

1. Connect the ADS131M04EVM to the PHI. Install the two screws as indicated in Figure 10.
2. Use the provided USB cable to connect the PHI to the computer.
   - LED D5 on the PHI lights up, indicating that the PHI is powered up
   - LEDs D1 and D2 on the PHI start blinking to indicate that the PHI is booted up and communicating with the PC; Figure 10 shows the resulting LED indicators

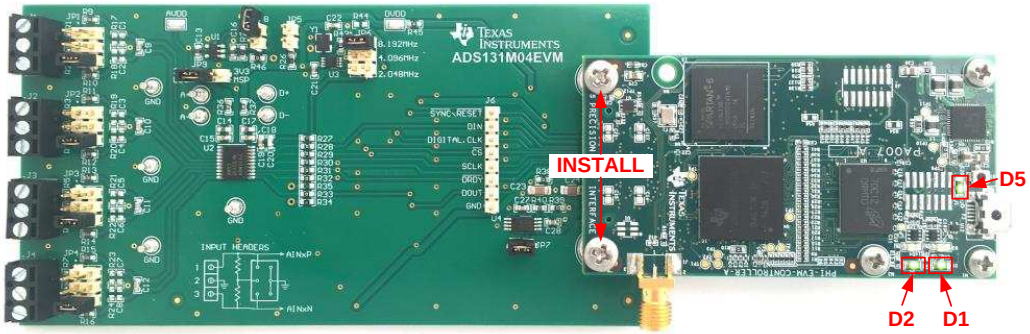

Figure 10. ADS131M04EVM Hardware Setup and LED Indicators

3. Figure 11 shows how to launch the ADS131M04EVM GUI software.

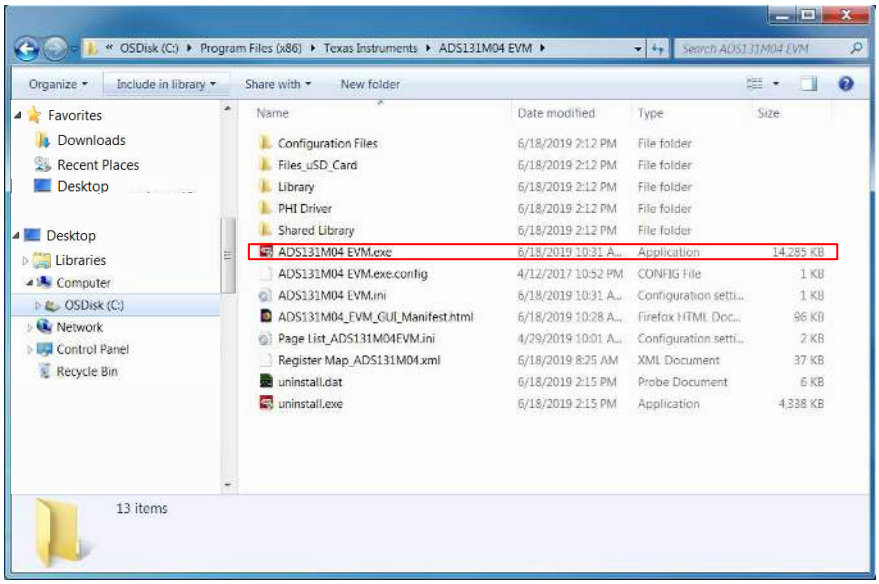

Figure 11. Launch the EVM GUI Software

6.1 EVM GUI Global Settings for ADC Control

Although the EVM GUI does not allow direct access to the levels and timing configuration of the ADC digital interface, the EVM GUI does give users high-level control over virtually all functions of the ADS131M04 including interface modes, sampling rate, and number of samples to be captured. Figure 12 identifies the input parameters of the GUI (as well as their default values) through which the various functions of the ADS131M04 can be exercised.

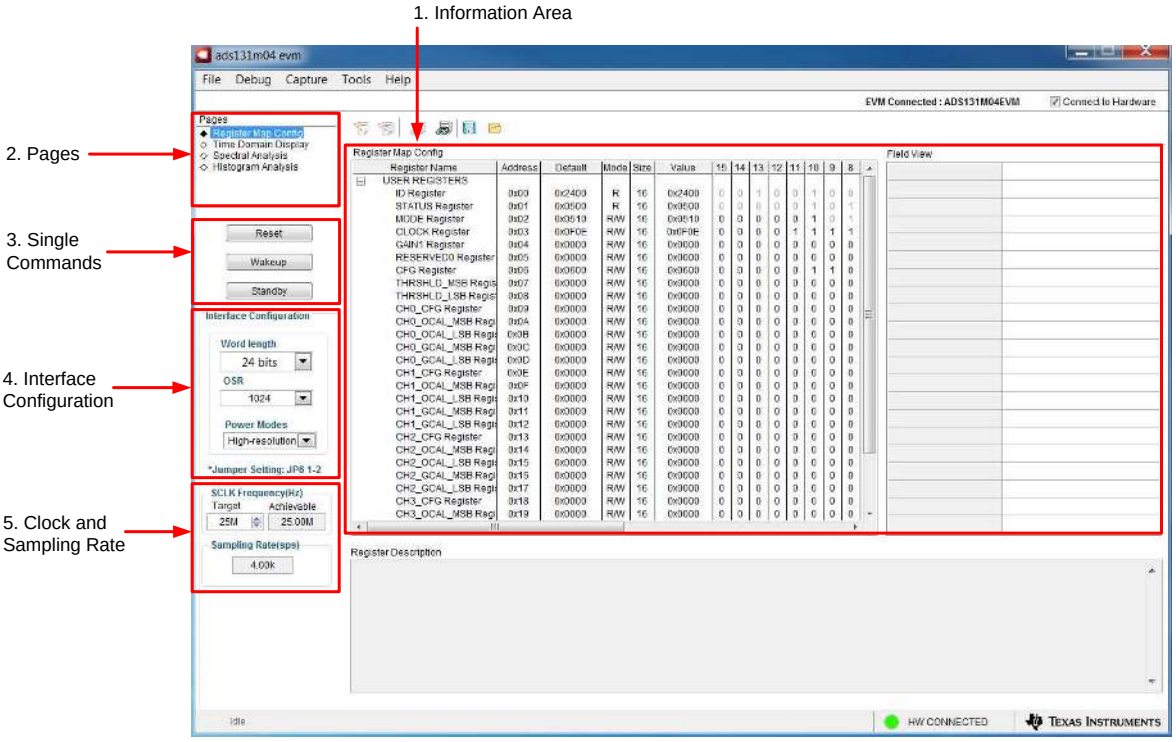

Figure 12. EVM GUI Global Input Parameters

There are four pages available in the ADS131M04EVM GUI. The information area displays the results of each of the pages. Each of these pages display a different control or measurement of the device. The Register Map Config page is used to read and write to the registers of the device. The Time Domain Display page is used to collect a set of data from the device and display the result. The Spectral Analysis page can determine the FFT of the collected data, and the Histogram Analysis page shows a histogram of the collected data and displays basic statistics of the result.

The Single Commands section allows for direct control of the device for three basic functions. First the *Reset* button sends a signal to the SYNC/RESET pin to reset the device. The *Standby* button puts the device into a low-power state in which all channels are disabled, and the reference and other non-essential circuitry are powered down. The *Wakeup* button exits the standby mode.

The Interface Configuration options in this pane allows the user to choose from different frame word sizes available on the ADS131M04. This section also sets the data rate by setting the oversampling ratio (OSR) in the ADC. Finally, this section may used to set the power modes in the registers. The ADS131M04 can be set to high-resolution, low power, and very-low power modes in conjunction with the jumper settings of JP6 for the CLKIN pin, as outlined in Table 4. This information is also discussed in Section 2.2.

The Clock and Sampling Rate section allows the user to specify a target SCLK frequency (in Hz) and the GUI tries to match this frequency as closely as possible by changing the PHI PLL settings, but the achievable frequency may differ from the target value entered. This section also displays the sampling rate of the ADC as controlled by the OCR.

The GUI is switched between hardware mode and simulation mode by checking and unchecking the *Connected to Hardware* box in the top right area of the screen at any time.

6.2 Register Map Configuration Tool

The register map configuration tool allows the user to view and modify the registers of the ADS131M04. This tool can be selected, as indicated in Figure 13, by clicking on the *Register Map Config* radio button at the Pages section of the left pane. On power-up, the values on this page correspond to the Host Configuration Settings that enable ADC sampling at the maximum sampling rate specified for the ADC. The register values can be edited by double-clicking the corresponding value field. If interface mode settings are affected by the change in register values, this change reflects on the left pane immediately. The changes in the register value reflect on the AD131M04 device on the ADS131M04EVM based on the Update Mode selection, as described in Section 6.1.

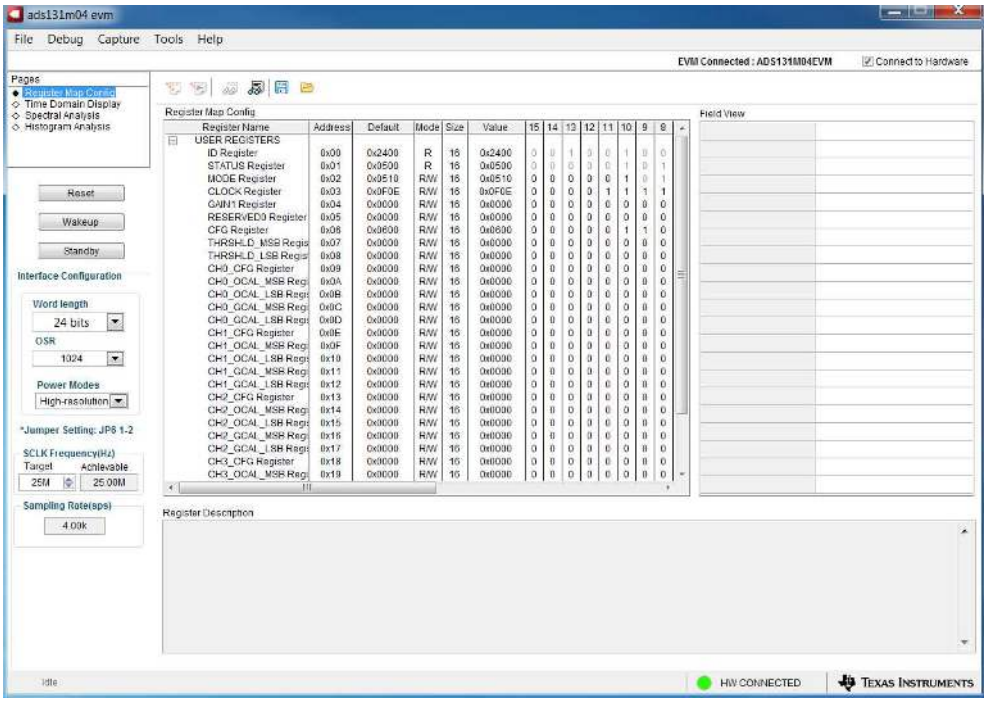

Figure 13. Register Map Configuration

Section 6.3 through Section 6.5 describe the data collection and analysis features of the ADS131M04EVM GUI.

6.3 Time Domain Display Tool

The time domain display tool allows visualization of the ADC response to a given input signal. This tool is useful for both studying the behavior and debugging any gross problems with the ADC or drive circuits.

The user can trigger a capture of the data of the selected number of samples from the ADS131M04EVM, as per the current interface mode settings indicated in Figure 14 by using the *Capture* button. The sample indices are on the x-axis and there are two y-axes showing the corresponding output codes as well as the equivalent analog voltages based on the specified reference voltage. Switching pages to any of the Analysis tools described in the subsequent sections causes calculations to be performed on the same set of data.

Figure 14. Time Domain Display Tool Options

6.4 Spectral Analysis Tool

The spectral analysis tool, shown in Figure 15, is intended to evaluate the dynamic performance (SNR, THD, SFDR, SINAD, and ENOB) of the ADS131M04 ADC through single-tone sinusoidal signal FFT analysis using the *7-term Blackman-Harris* window setting.

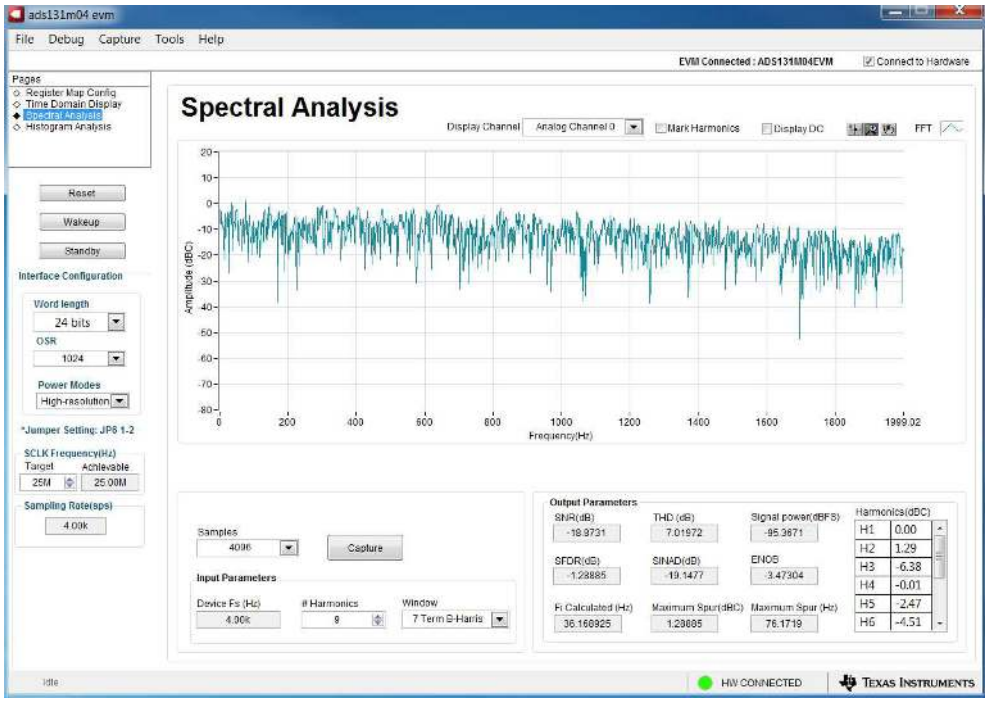

Figure 15. Spectral Analysis Tool

The FFT tool includes windowing options that are required to mitigate the effects of non-coherent sampling (this discussion is beyond the scope of this document). The *7-Term Blackman Harris* window is the default option and has sufficient dynamic range to resolve the frequency components of up to a 24-bit ADC. The *None* option corresponds to not using a window (or using a rectangular window) and is not recommended.

6.5 Histogram Tool

Noise degrades ADC resolution and the histogram tool can be used to estimate effective resolution, which is an indicator of the number of bits of ADC resolution losses resulting from noise generated by the various sources connected to the ADC when measuring a DC signal. The cumulative effect of noise coupling to the ADC output from sources such as the input drive circuits, the reference drive circuit, the ADC power supply, and the ADC itself is reflected in the standard deviation of the ADC output code histogram that is obtained by performing multiple conversions of a DC input applied to a given channel.

As shown in Figure 16, the histogram corresponding to a DC input is displayed on clicking the *Capture* button.

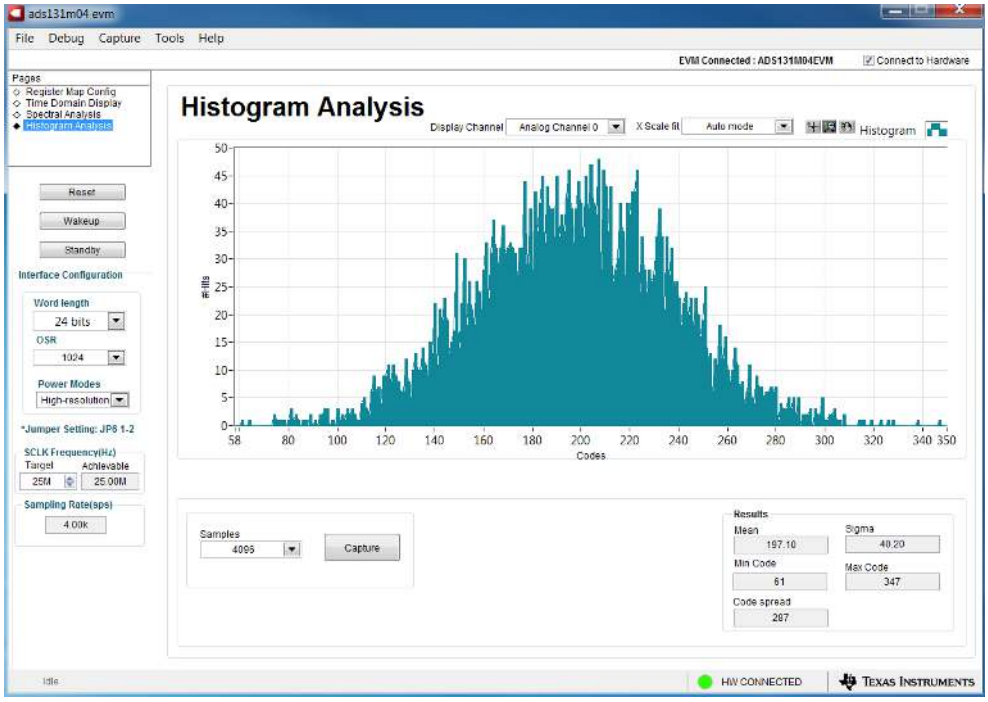

Figure 16. Histogram Analysis Tool

7 ADS131M04EVM Bill of Materials, PCB Layout, and Schematic

7.1 Bill of Materials

Table 9 lists the ADS131M04EVM bill of materials.

Table 9. ADS131M04EVM Bill of Materials

Designator	Quantity	Value	Description	Package Reference	Part Number	Manufacturer
C9, C10, C11, C12	4	1000pF	CAP, CERM, 1000 pF, 25 V, +/- 5%, C0G/NP0, 0603	0603	GRM1885C1E102JA01D	MuRata
C13, C14, C16, C17	4	1uF	CAP, CERM, 1 uF, 25 V, +/- 10%, X7R, 0603	0603	C0603C105K3RACTU	Kemet
C15, C18, C19, C21, C22, C27, C28	7	0.1uF	CAP, CERM, 0.1 uF, 25 V, +/- 5%, X7R, 0603	0603	C0603C104J3RAC	Kemet
C20	1	10pF	CAP, CERM, 10 pF, 50 V, +/- 5%, C0G/NP0, 0603	0603	C0603C100J5GACTU	Kemet
C23, C24	2	10uF	CAP, CERM, 10 uF, 25 V, +/- 10%, X7R, 1206_190	1206_190	C1206C106K3RACTU	Kemet
H1, H2	2		Machine Screw Pan PHILLIPS M3		RM3X4MM 2701	APM HEXSEAL
H3, H4	2		ROUND STANDOFF M3 STEEL 5MM		9774050360R	Wurth Elektronik
H5, H6, H7, H8	4		Bumpon, Hemisphere, 0.44 X 0.20, Clear	Transparent Bumpon	SJ-5303 (CLEAR)	3M
H9	1		Cable, USB-A to micro USB-B, 1 m - Kitting item		102-1092-BL-00100	CnC Tech
H10	1		PHI-EVM Controller Kitting item Edge# 6591636		PA007	Texas Instruments
J1, J2, J3, J4	4		Terminal Block, 3.5mm Pitch, 3x1, TH	10.5x8.2x6.5mm	ED555/3DS	On-Shore Technology
J5	1		Header(Shrouded), 19.7mil, 30x2, Gold, SMT	Header (Shrouded), 19.7mil, 30x2, SMT	QTH-030-01-L-D-A	Samtec
J6	1		Header, 100mil, 8x1, Gold, TH	8x1 Header	TSW-108-07-G-S	Samtec
JP1, JP2, JP3, JP4, JP6	5		Header, 100mil, 3x2, Gold, TH	3x2 Header	TSW-103-07-G-D	Samtec
JP7	1		Header, 100mil, 2x1, Gold, TH	2x1 Header	TSW-102-07-G-S	Samtec
JP9	1		Header, 100mil, 3x1, Gold, TH	3x1 Header	TSW-103-07-G-S	Samtec
R1, R2, R3, R4, R5, R6, R7, R8	8	1.00k	RES, 1.00 k, 1%, 0.1 W, AEC-Q200 Grade 0, 0603	0603	CRCW06031K00FKEA	Vishay-Dale
R9, R10, R11, R12, R13, R14, R15, R16	8	49.9	RES, 49.9, 1%, 0.1 W, AEC-Q200 Grade 0, 0603	0603	CRCW060349R9FKEA	Vishay-Dale

Table 9. ADS131M04EVM Bill of Materials (continued)

Designator	Quantity	Value	Description	Package Reference	Part Number	Manufacturer
R25, R26, R34, R35	4	100k	RES, 100 k, 1%, 0.1 W, AEC-Q200 Grade 0, 0603	0603	CRCW0603100KFKEA	Vishay-Dale
R27	1	10.0	RES, 10.0, 1%, 0.25 W, AEC-Q200 Grade 0, 0603	0603	CRCW060310R0FKEAHP	Vishay-Dale
R28, R29, R30, R31, R32, R33, R38, R39, R43, R45, R46	11	0	RES, 0, 5%, 0.1 W, 0603	0603	RC0603JR-070RL	Yageo
R36, R37	2	0.1	RES, 0.1, 1%, 0.1 W, AEC-Q200 Grade 1, 0603	0603	ERJ-L03KF10CV	Panasonic
R40	1	10k	RES, 10 k, 5%, 0.1 W, 0603	0603	RC1608J103CS	Samsung Electro-Mechanics
SH-J1, SH-J2, SH-J3, SH-J4, SH-J5, SH-J6	6	1x2	Shunt, 100mil, Flash Gold, Black	Closed Top 100mil Shunt	SPC02SYAN	Sullins Connector Solutions
TP1, TP2	2		Test Point, Miniature, SMT	Testpoint Keystone Miniature	5015	Keystone
TP3, TP4, TP5, TP6	4		Terminal, Turret, TH, Double	Keystone1573-2	1573-2	Keystone
U1	1		250-mA Ultra-Low-Noise, Low-IQ LDO, DBV0005A (SOT-23-5)	DBV0005A	LP5907MFX-3.3/NOPB	Texas Instruments
U2	1		4-Channel, 24-Bit, Simultaneously-Sampling, Delta-Sigma ADC, PW0020A (TSSOP-20)	PW0020A	ADS131M04IPWT	Texas Instruments
U3	1		Low-Power Dual Positive-Edge-Triggered D-Type Flip-Flop, DCU0008A (VSSOP-8)	DCU0008A	SN74AUP2G80DCUR	Texas Instruments
U4	1		I2C BUS EEPROM (2-Wire), TSSOP-B8	TSSOP-8	BR24G32FVT-3AGE2	Rohm
Y1	1		Oscillator, 8.192 MHz, 15 pF, AEC-Q200 Grade 1, SMD	3.2x2.5mm	SIT8924BA-22-33E-8.192000G	SiTime
C1, C2, C3, C4, C5, C6, C7, C8	0	0.01uF	CAP, CERM, 0.01 uF, 25 V, +/- 5%, C0G/NP0, 0603	0603	C0603H103J3GACTU	Kemet
C25, C26	0	10uF	CAP, CERM, 10 uF, 25 V, +/- 10%, X7R, 1206_190	1206_190	C1206C106K3RACTU	Kemet
FID1, FID2, FID3	0		Fiducial mark. There is nothing to buy or mount.	N/A	N/A	N/A
J7, J8	0		Connector, Receptacle, 100mil, 10x2, Gold plated, SMD	10x2 Receptacle	SSW-110-22-F-D-VS-K	Samtec
JP5, JP8	0		Header, 100mil, 2x1, Gold, TH	2x1 Header	TSW-102-07-G-S	Samtec

Table 9. ADS131M04EVM Bill of Materials (continued)

Designator	Quantity	Value	Description	Package Reference	Part Number	Manufacturer
R17, R18, R19, R20, R21, R22, R23, R24	0	1.00k	RES, 1.00 k, 1%, 0.1 W, AEC-Q200 Grade 0, 0603	0603	CRCW06031K00FKEA	Vishay-Dale
R41, R42, R44	0	0	RES, 0, 5%, 0.1 W, 0603	0603	RC0603JR-070RL	Yageo
TP7, TP8, TP9, TP10	0		Terminal, Turret, TH, Double	Keystone1573-2	1573-2	Keystone

7.2 PCB Layout

Figure 17 through Figure 22 illustrate the ADS131M04EVM PCB layout.

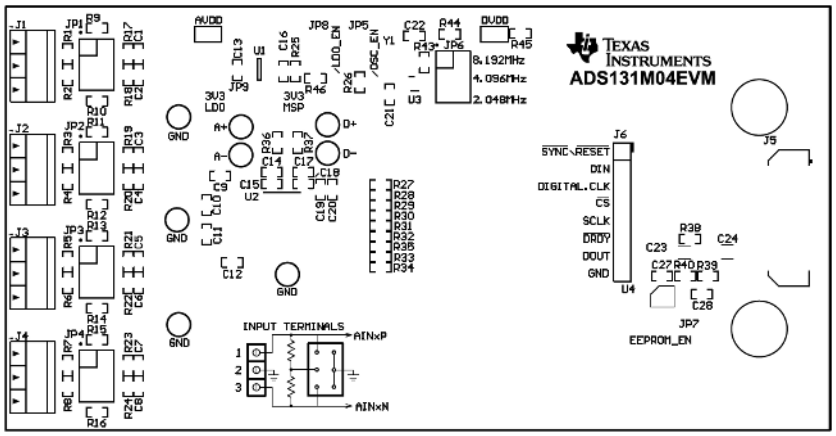

Figure 17. Top Silkscreen

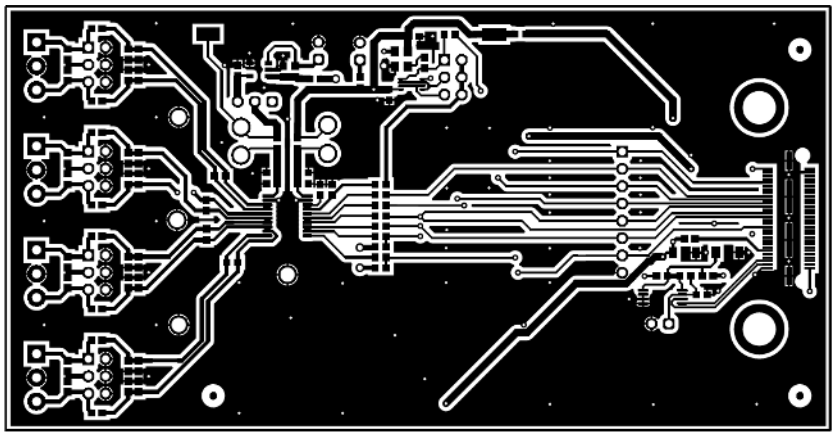

Figure 18. Top Layer

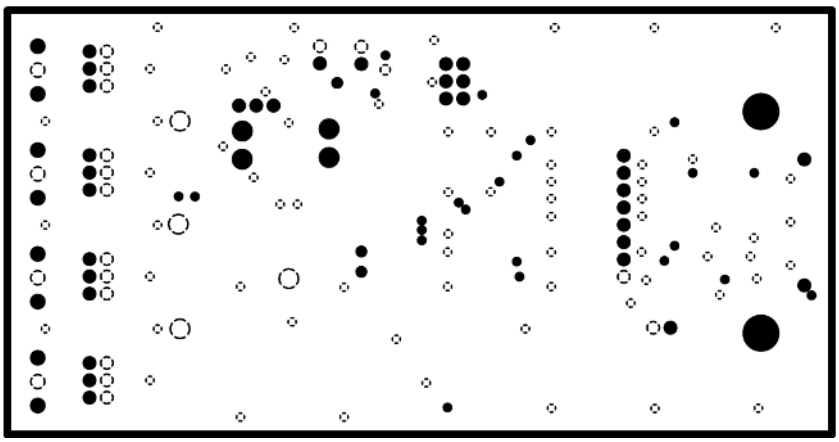

Figure 19. Ground Layer 1

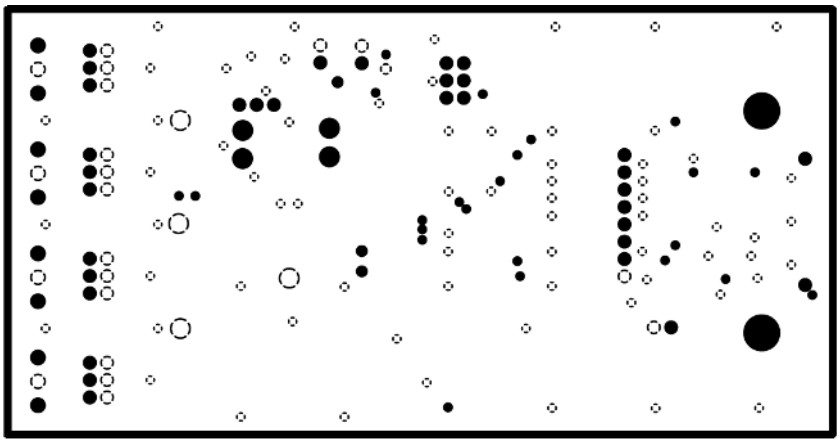

Figure 20. Ground Layer 2

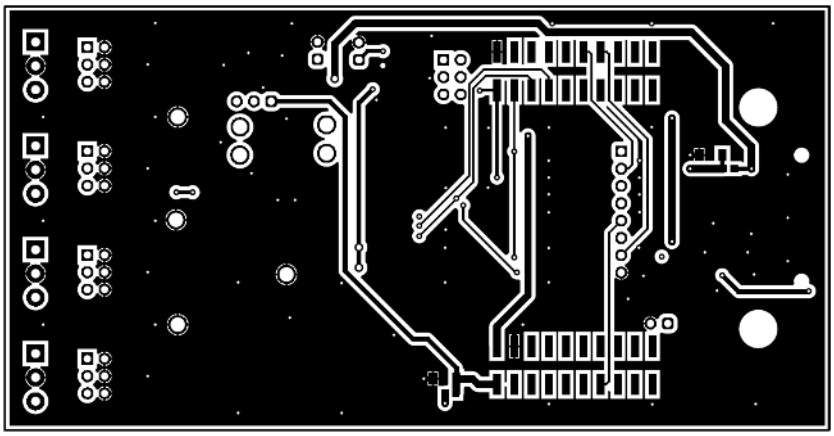

Figure 21. Bottom Layer

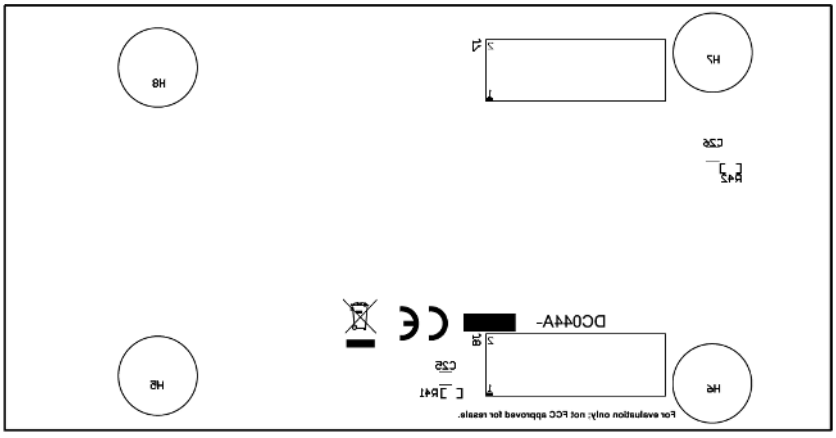

Figure 22. Bottom Silkscreen

7.3 Schematic

Figure 23 and Figure 24 illustrate the ADS131M04EVM schematics.

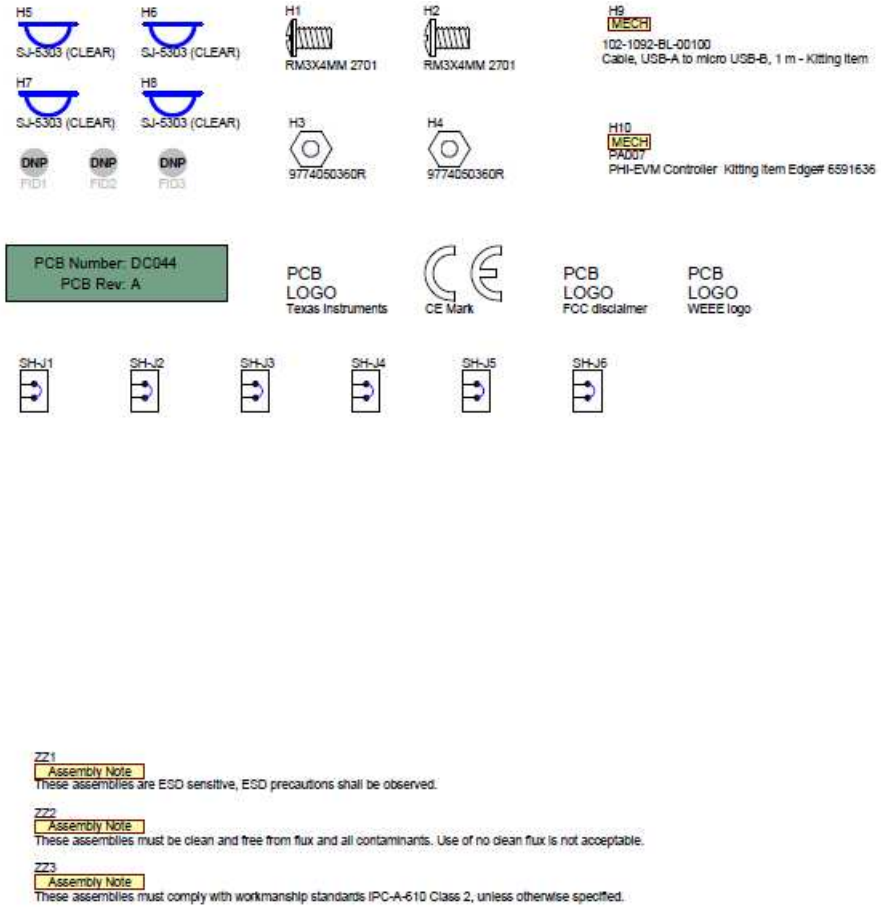

Figure 23. ADS131M04EVM Hardware Schematic

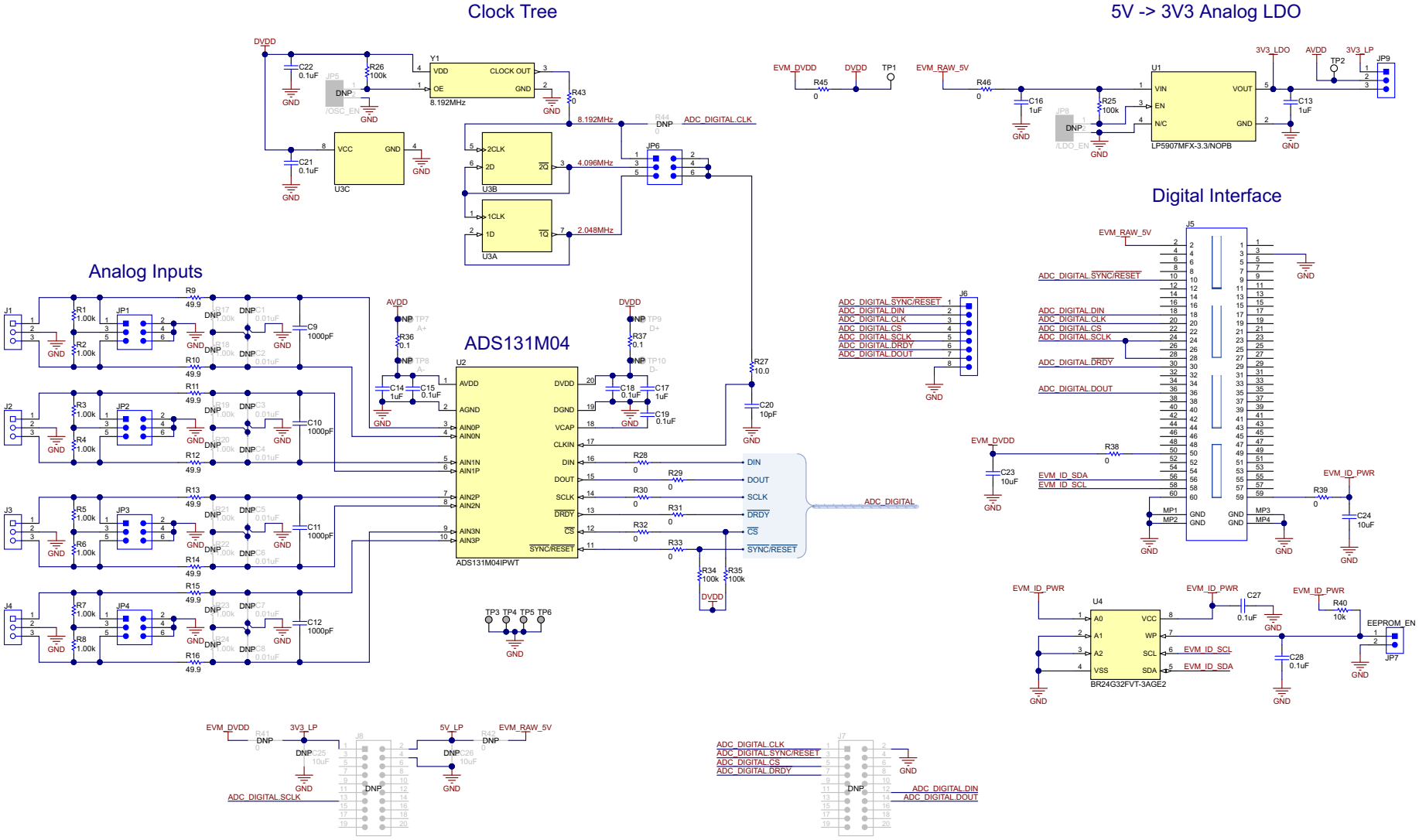

Figure 24. ADS131M04EVM Main Schematic

Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Original (March 2019) to A Revision	Page
• Changed document to align with new evaluation module	1

STANDARD TERMS FOR EVALUATION MODULES

1. *Delivery:* TI delivers TI evaluation boards, kits, or modules, including any accompanying demonstration software, components, and/or documentation which may be provided together or separately (collectively, an “EVM” or “EVMs”) to the User (“User”) in accordance with the terms set forth herein. User's acceptance of the EVM is expressly subject to the following terms.

   1.1 EVMs are intended solely for product or software developers for use in a research and development setting to facilitate feasibility evaluation, experimentation, or scientific analysis of TI semiconductors products. EVMs have no direct function and are not finished products. EVMs shall not be directly or indirectly assembled as a part or subassembly in any finished product. For clarification, any software or software tools provided with the EVM (“Software”) shall not be subject to the terms and conditions set forth herein but rather shall be subject to the applicable terms that accompany such Software

   1.2 EVMs are not intended for consumer or household use. EVMs may not be sold, sublicensed, leased, rented, loaned, assigned, or otherwise distributed for commercial purposes by Users, in whole or in part, or used in any finished product or production system.

2 *Limited Warranty and Related Remedies/Disclaimers*:

   2.1 These terms do not apply to Software. The warranty, if any, for Software is covered in the applicable Software License Agreement.

   2.2 TI warrants that the TI EVM will conform to TI's published specifications for ninety (90) days after the date TI delivers such EVM to User. Notwithstanding the foregoing, TI shall not be liable for a nonconforming EVM if (a) the nonconformity was caused by neglect, misuse or mistreatment by an entity other than TI, including improper installation or testing, or for any EVMs that have been altered or modified in any way by an entity other than TI, (b) the nonconformity resulted from User's design, specifications or instructions for such EVMs or improper system design, or (c) User has not paid on time. Testing and other quality control techniques are used to the extent TI deems necessary. TI does not test all parameters of each EVM. User's claims against TI under this Section 2 are void if User fails to notify TI of any apparent defects in the EVMs within ten (10) business days after delivery, or of any hidden defects with ten (10) business days after the defect has been detected.

   2.3 TI's sole liability shall be at its option to repair or replace EVMs that fail to conform to the warranty set forth above, or credit User's account for such EVM. TI's liability under this warranty shall be limited to EVMs that are returned during the warranty period to the address designated by TI and that are determined by TI not to conform to such warranty. If TI elects to repair or replace such EVM, TI shall have a reasonable time to repair such EVM or provide replacements. Repaired EVMs shall be warranted for the remainder of the original warranty period. Replaced EVMs shall be warranted for a new full ninety (90) day warranty period.

WARNING

Evaluation Kits are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems.

User shall operate the Evaluation Kit within TI’s recommended guidelines and any applicable legal or environmental requirements as well as reasonable and customary safeguards. Failure to set up and/or operate the Evaluation Kit within TI’s recommended guidelines may result in personal injury or death or property damage. Proper set up entails following TI’s instructions for electrical ratings of interface circuits such as input, output and electrical loads.

NOTE:

EXPOSURE TO ELECTROSTATIC DISCHARGE (ESD) MAY CAUSE DEGREDATION OR FAILURE OF THE EVALUATION KIT; TI RECOMMENDS STORAGE OF THE EVALUATION KIT IN A PROTECTIVE ESD BAG.

3 *Regulatory Notices:*

3.1 *United States*

3.1.1 *Notice applicable to EVMs not FCC-Approved:*

FCC NOTICE: This kit is designed to allow product developers to evaluate electronic components, circuitry, or software associated with the kit to determine whether to incorporate such items in a finished product and software developers to write software applications for use with the end product. This kit is not a finished product and when assembled may not be resold or otherwise marketed unless all required FCC equipment authorizations are first obtained. Operation is subject to the condition that this product not cause harmful interference to licensed radio stations and that this product accept harmful interference. Unless the assembled kit is designed to operate under part 15, part 18 or part 95 of this chapter, the operator of the kit must operate under the authority of an FCC license holder or must secure an experimental authorization under part 5 of this chapter.

3.1.2 *For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant:*

CAUTION

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

FCC Interference Statement for Class A EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- *Reorient or relocate the receiving antenna.*
- *Increase the separation between the equipment and receiver.*
- *Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.*
- *Consult the dealer or an experienced radio/TV technician for help.*

3.2 *Canada*

3.2.1 *For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210 or RSS-247*

Concerning EVMs Including Radio Transmitters:

This device complies with Industry Canada license-exempt RSSs. Operation is subject to the following two conditions:

(1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Concerning EVMs Including Detachable Antennas:

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur

3.3 *Japan*

3.3.1 *Notice for EVMs delivered in Japan:* Please see http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_01.page 日本国内に輸入される評価用キット、ボードについては、次のところをご覧ください。
http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_01.page

3.3.2 *Notice for Users of EVMs Considered "Radio Frequency Products" in Japan:* EVMs entering Japan may not be certified by TI as conforming to Technical Regulations of Radio Law of Japan.

If User uses EVMs in Japan, not certified to Technical Regulations of Radio Law of Japan, User is required to follow the instructions set forth by Radio Law of Japan, which includes, but is not limited to, the instructions below with respect to EVMs (which for the avoidance of doubt are stated strictly for convenience and should be verified by User):

1. Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

【無線電波を送信する製品の開発キットをお使いになる際の注意事項】 開発キットの中には技術基準適合証明を受けていないものがあります。 技術適合証明を受けていないもののご使用に際しては、電波法遵守のため、以下のいずれかの措置を取っていただく必要がありますのでご注意ください。

1. 電波法施行規則第6条第1項第1号に基づく平成18年3月28日総務省告示第173号で定められた電波暗室等の試験設備でご使用いただく。
2. 実験局の免許を取得後ご使用いただく。
3. 技術基準適合証明を取得後ご使用いただく。

なお、本製品は、上記の「ご使用にあたっての注意」を譲渡先、移転先に通知しない限り、譲渡、移転できないものとします。
上記を遵守頂けない場合は、電波法の罰則が適用される可能性があることをご留意ください。 日本テキサス・インスツルメンツ株式会社
東京都新宿区西新宿 6 丁目 2 4 番 1 号
西新宿三井ビル

3.3.3 *Notice for EVMs for Power Line Communication:* Please see http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_02.page
電力線搬送波通信についての開発キットをお使いになる際の注意事項については、次のところをご覧ください。http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_02.page

3.4 *European Union*

3.4.1 *For EVMs subject to EU Directive 2014/30/EU (Electromagnetic Compatibility Directive)*:

This is a class A product intended for use in environments other than domestic environments that are connected to a low-voltage power-supply network that supplies buildings used for domestic purposes. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

4 *EVM Use Restrictions and Warnings:*

4.1 EVMS ARE NOT FOR USE IN FUNCTIONAL SAFETY AND/OR SAFETY CRITICAL EVALUATIONS, INCLUDING BUT NOT LIMITED TO EVALUATIONS OF LIFE SUPPORT APPLICATIONS.

4.2 User must read and apply the user guide and other available documentation provided by TI regarding the EVM prior to handling or using the EVM, including without limitation any warning or restriction notices. The notices contain important safety information related to, for example, temperatures and voltages.

4.3 *Safety-Related Warnings and Restrictions:*

4.3.1 User shall operate the EVM within TI's recommended specifications and environmental considerations stated in the user guide, other available documentation provided by TI, and any other applicable requirements and employ reasonable and customary safeguards. Exceeding the specified performance ratings and specifications (including but not limited to input and output voltage, current, power, and environmental ranges) for the EVM may cause personal injury or death, or property damage. If there are questions concerning performance ratings and specifications, User should contact a TI field representative prior to connecting interface electronics including input power and intended loads. Any loads applied outside of the specified output range may also result in unintended and/or inaccurate operation and/or possible permanent damage to the EVM and/or interface electronics. Please consult the EVM user guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative. During normal operation, even with the inputs and outputs kept within the specified allowable ranges, some circuit components may have elevated case temperatures. These components include but are not limited to linear regulators, switching transistors, pass transistors, current sense resistors, and heat sinks, which can be identified using the information in the associated documentation. When working with the EVM, please be aware that the EVM may become very warm.

4.3.2 EVMs are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems. User assumes all responsibility and liability for proper and safe handling and use of the EVM by User or its employees, affiliates, contractors or designees. User assumes all responsibility and liability to ensure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard. User assumes all responsibility and liability for any improper or unsafe handling or use of the EVM by User or its employees, affiliates, contractors or designees.

4.4 User assumes all responsibility and liability to determine whether the EVM is subject to any applicable international, federal, state, or local laws and regulations related to User's handling and use of the EVM and, if applicable, User assumes all responsibility and liability for compliance in all respects with such laws and regulations. User assumes all responsibility and liability for proper disposal and recycling of the EVM consistent with all applicable international, federal, state, and local requirements.

5. *Accuracy of Information:* To the extent TI provides information on the availability and function of EVMs, TI attempts to be as accurate as possible. However, TI does not warrant the accuracy of EVM descriptions, EVM availability or other information on its websites as accurate, complete, reliable, current, or error-free.

6. *Disclaimers:*

6.1 EXCEPT AS SET FORTH ABOVE, EVMS AND ANY MATERIALS PROVIDED WITH THE EVM (INCLUDING, BUT NOT LIMITED TO, REFERENCE DESIGNS AND THE DESIGN OF THE EVM ITSELF) ARE PROVIDED "AS IS" AND "WITH ALL FAULTS." TI DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED, REGARDING SUCH ITEMS, INCLUDING BUT NOT LIMITED TO ANY EPIDEMIC FAILURE WARRANTY OR IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF ANY THIRD PARTY PATENTS, COPYRIGHTS, TRADE SECRETS OR OTHER INTELLECTUAL PROPERTY RIGHTS.

6.2 EXCEPT FOR THE LIMITED RIGHT TO USE THE EVM SET FORTH HEREIN, NOTHING IN THESE TERMS SHALL BE CONSTRUED AS GRANTING OR CONFERRING ANY RIGHTS BY LICENSE, PATENT, OR ANY OTHER INDUSTRIAL OR INTELLECTUAL PROPERTY RIGHT OF TI, ITS SUPPLIERS/LICENSORS OR ANY OTHER THIRD PARTY, TO USE THE EVM IN ANY FINISHED END-USER OR READY-TO-USE FINAL PRODUCT, OR FOR ANY INVENTION, DISCOVERY OR IMPROVEMENT, REGARDLESS OF WHEN MADE, CONCEIVED OR ACQUIRED.

7. *USER'S INDEMNITY OBLIGATIONS AND REPRESENTATIONS.* USER WILL DEFEND, INDEMNIFY AND HOLD TI, ITS LICENSORS AND THEIR REPRESENTATIVES HARMLESS FROM AND AGAINST ANY AND ALL CLAIMS, DAMAGES, LOSSES, EXPENSES, COSTS AND LIABILITIES (COLLECTIVELY, "CLAIMS") ARISING OUT OF OR IN CONNECTION WITH ANY HANDLING OR USE OF THE EVM THAT IS NOT IN ACCORDANCE WITH THESE TERMS. THIS OBLIGATION SHALL APPLY WHETHER CLAIMS ARISE UNDER STATUTE, REGULATION, OR THE LAW OF TORT, CONTRACT OR ANY OTHER LEGAL THEORY, AND EVEN IF THE EVM FAILS TO PERFORM AS DESCRIBED OR EXPECTED.

8. *Limitations on Damages and Liability:*

   8.1 *General Limitations*. IN NO EVENT SHALL TI BE LIABLE FOR ANY SPECIAL, COLLATERAL, INDIRECT, PUNITIVE, INCIDENTAL, CONSEQUENTIAL, OR EXEMPLARY DAMAGES IN CONNECTION WITH OR ARISING OUT OF THESE TERMS OR THE USE OF THE EVMS , REGARDLESS OF WHETHER TI HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. EXCLUDED DAMAGES INCLUDE, BUT ARE NOT LIMITED TO, COST OF REMOVAL OR REINSTALLATION, ANCILLARY COSTS TO THE PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES, RETESTING, OUTSIDE COMPUTER TIME, LABOR COSTS, LOSS OF GOODWILL, LOSS OF PROFITS, LOSS OF SAVINGS, LOSS OF USE, LOSS OF DATA, OR BUSINESS INTERRUPTION. NO CLAIM, SUIT OR ACTION SHALL BE BROUGHT AGAINST TI MORE THAN TWELVE (12) MONTHS AFTER THE EVENT THAT GAVE RISE TO THE CAUSE OF ACTION HAS OCCURRED.

   8.2 *Specific Limitations.* IN NO EVENT SHALL TI'S AGGREGATE LIABILITY FROM ANY USE OF AN EVM PROVIDED HEREUNDER, INCLUDING FROM ANY WARRANTY, INDEMITY OR OTHER OBLIGATION ARISING OUT OF OR IN CONNECTION WITH THESE TERMS, , EXCEED THE TOTAL AMOUNT PAID TO TI BY USER FOR THE PARTICULAR EVM(S) AT ISSUE DURING THE PRIOR TWELVE (12) MONTHS WITH RESPECT TO WHICH LOSSES OR DAMAGES ARE CLAIMED. THE EXISTENCE OF MORE THAN ONE CLAIM SHALL NOT ENLARGE OR EXTEND THIS LIMIT.

9. *Return Policy.* Except as otherwise provided, TI does not offer any refunds, returns, or exchanges. Furthermore, no return of EVM(s) will be accepted if the package has been opened and no return of the EVM(s) will be accepted if they are damaged or otherwise not in a resalable condition. If User feels it has been incorrectly charged for the EVM(s) it ordered or that delivery violates the applicable order, User should contact TI. All refunds will be made in full within thirty (30) working days from the return of the components(s), excluding any postage or packaging costs.

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