# **Quick Start Guide** HMC3-M1616P



## Description:

HMC3-M1616P I/O expansion module with 16 digital bidirectional inputs and 16 PNP-type sourcing digital outputs.

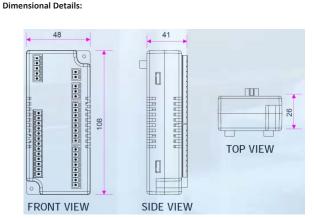
# Contents: 1 HMC3-1616P (in plastic bag)

Removable screw type terminal blocks\* Removable power supply connector\* Quick Start Guide

\*Note: Connector manufacturer may vary.

Programming software (MAPware-7000), cables, and power supply purchased separately.

| Specifications:               |  |
|-------------------------------|--|
| Power:                        | 12VDC from HMC3000 base  |
| Isolation:<br>Digital Inputs: | I/O optically isolated from internal circuit 16 bidirectional inputs |
| Rated Input Yoltene:          | 24VDC<br>up to 5mA (per contact)                                     |
| Input Impedance:              | 3ΚΩ  |
| Minimum ON voltage: 15        | VDC  |
| Maximum OFF voltage: 5        | VDC  |
| Turn ON/OFF time:             | 10 msec  |
| Special Input Functions:      |  |
| High Speed Channels:          | 2 inputs, X0 and X2  |
| Maximum Input Freq:           | 200KHz   |
| Maximum Input Count: 4        | ,294,967,295 (32-bit)  |
| Digital Outputs:              | 16 sourcing outputs (PNP-type)                                       |
| Output Current:               | 300mA maximum (per contact)  |
| Rated Load:                   | 300mA@24VDC  |
| Nominal Load:                 | 96Ω / 6W (Resistive) @ 24VDC   |
|                               | 6VA (Inductive, Unity Power Factor)                                  |
| Special Output Functions:     |  |
| High Speed Channels: 2        |  |
| Maximum Output Freq: 1        |  |
| PWM duty cycle:               | 0 to 100%  |
| Input Power Supply:           |  |
| Input Voltage:                | 24VDC +/- 15%  |
| Connection Method:            | Removable terminals (3.81 mm pitch)                                  |
| Operating Temp:               | 0 to 55° C   |
| Humidity:                     | 10% to 90% (non-condensing)  |
| Dimensions (WxHxD):           | 1.89 x 4.25 x 1.61 inches [48x108x41mm]                              |
| Doc. No. 1011-0304            |  |

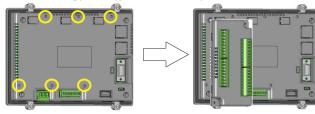


#### Mounting Module to HMC3000:

The HMC3 I/O module must be mounted onto the back of a HMC3000 Series unit

#### using one of the HMC expansion ports.

When locating equipment behind the HMC3000 ensure that AC power wiring, PLC output modules, contactors, starters, relay and any other source of electrical interference are located away from the HMC3000. Make sure that variable speed drives and switching power supplies are located away from the unit.



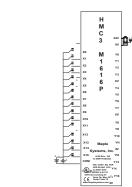
Step 1: Remove protective tab on HMC3000 expansion port to expose socket. Step 2: Align I/O module screws with screw holes, then carefully press down to establish contact between I/O interconnect plug on I/O module and the socket. Step 3: Tighten the two screws of the I/O module to the base (approx. 0.1Nm torque).

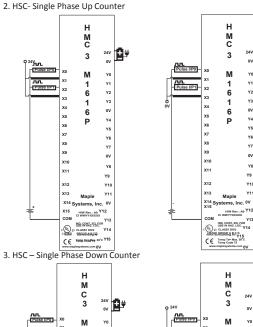
# Wiring I/O Expansion Modules:

The HMC3 I/O module has green block terminals that are used to wire the module to the digital input devices (i.e. switches, contacts, etc.). The block terminals can be physically removed from the module to facilitate connection (18-gauge wire recommended) Note: A 3/32" flat blade screwdriver should be used to tighten the screws of the terminal block.

Connecting to bidirectional inputs:

1. Normal





X4

X5

X6

X7

xa

x9

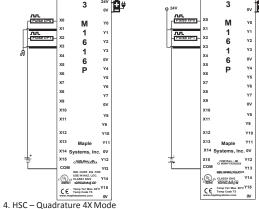
X10

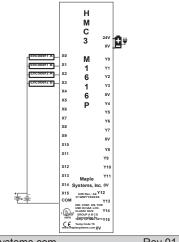
X11

X12

X13

X14





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Ð₩ 24V

YO Y1

Y2

Y3

ov

Y4

Y5

Y6

¥7

ov

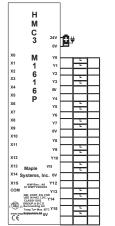
¥8

Y9 Y10

Y11

Y13

5. Connecting to PNP-type sourcing outputs:



#### Configuration:

Use MAPware-7000 to configure the expansion port, in which the module is installed, using the module's model number.

The input (X and XW), outputs (Y and YW), and configuration (M and MW) memory addresses are used to interact with the module. These addresses are created according to the slot location of the module, where nn refers to the slot number (ex. 01...05):

| Function                                 | Register            | Access   |
|--|---------------------|----------|
| X0-X15 Inputs                            | Xnn000-015 (XWnn00) | Rd Only  |
| Slot nn- CH1 Rate<br>Register            | XWnn01              | Rd Only  |
| Slot nn- CH2 Rate<br>Register            | XWnn03              | Rd Only  |
| Slot nn- CH1 Pulses<br>Per Scan Register | XWnn05              | Rd Only  |
| Slot nn- CH2 Pulses<br>Per Scan Register | XWnn07              | Rd Only  |
| Y0-Y15 Outputs                           | Ynn000-015 (YWnn00) | Rd/Write |

### High Speed Counter Configuration:

| Function        | HSC Channel 1 | HSC Channel 2 | Access   |
|-----------------|---------------|---------------|----------|
| Pulse Input Pin | XO            | X2            | Rd Only  |
| Direction Pin*  | X1            | X3            | Rd Only  |
| Reset HW Pin    | X4            | X5            | Rd Only  |
| Preset Reached  | Y2            | Y3            | Rd Only  |
| Pin             |               |               |          |
| Enable Counting | Mnn080        | Mnn176        | Rd/Write |
| Reset SW Bit    | Mnn081        | Mnn177        | Rd/Write |
| Preset Reached  | Mnn083        | Mnn179        | Rd Only  |
| Configuration   | MWnn00        | MWnn06        | Rd/Write |
| Register        |               |               |          |
| Current Value   | MWnn01        | MWnn07        | Rd Only  |
| Preset Value    | MWnn03        | MWnn09        | Rd/Write |

 $^{*-}$  X1 and X3 are used as Encoder pins 1B and 2B respectively when using Quadrature 4X mode.

#### Pulse Width Modulation (PWM) Configuration:

| Pulse Width     | PWM Channel 1 | PWM           |            |
|-----------------|---------------|---------------|------------|
| Modulation      |               | Channel 2     |            |
| Option          |               |               |            |
| PWM Output      | YO (terminal) | Y1 (terminal) | Rd/Write   |
| PWM             | MWnn24        | MWnn30        | Rd/Write   |
| Configuration   |               |               |            |
| Register        |               |               |            |
| PWM Frequency   | MWnn25        | MWnn31        | Rd/Write   |
| or Minimum      | MWnn26        | MWnn32        |            |
| Freq. Setting   |               |               |            |
| Register        |               |               |            |
| PWM ON Duty     | MWnn27        | MWnn33        | Rd/Write   |
| or Maximum      | MWnn28        | MWnn34        |            |
| Freq. Setting   |               |               |            |
| Register        |               |               |            |
| PWM             | MWnn37        | MWnn38        | Rd/Write   |
| Acceleration    |               |               |            |
| Time            |               |               |            |
| PWM             | MWnn39        | MWnn40        | Rd/Write   |
| Deceleration    |               |               |            |
| Time            |               |               |            |
| PWM Total       | MWnn41        | MWnn43        | Rd/Write   |
| Pulse           | MWnn42        | MWnn44        |            |
| PWM Elapsed     | MWnn45        | MWnn47        | Rd/Write   |
| Pulse           | MWnn46        | MWnn48        | ind, white |
| PWM             | MWnn50        | MWnn52        | Rd/Write   |
| Trapezoidal     | MWnn51        | MWnn53        | Ku/ White  |
| Minimum Pulse   | WWWIIIST      | 1414411133    |            |
| Count           |               |               |            |
| PWM ON Duty     | Mnn466        | Mnn471        | Rd/Write   |
| Setting Error   | WITH400       | 101111471     | Ku/ Write  |
| Flag            |               |               |            |
| *               | Mnn467        | Mnn472        | Rd/Write   |
| PWM Frequency   | Winn467       | IVINN472      | Kd/ write  |
| Setting Error   |               |               |            |
| Flag            | Mar 460       | h4== 472      | Del/Multa  |
| PWM             | Mnn468        | Mnn473        | Rd/Write   |
| Acceleration    |               |               |            |
| Time Setting    |               |               |            |
| Error Flag      |               |               |            |
| PWM             | Mnn469        | Mnn474        | Rd/Write   |
| Deceleration    |               |               |            |
| Time Setting    |               |               |            |
| Error Flag      |               |               | -          |
| PWM No of       | Mnn470        | Mnn475        | Rd/Write   |
| Total Pulses    |               |               |            |
| Setting Error   |               |               |            |
| Flag            |               |               |            |
| PWM Pulse       | Mnn576        | Mnn577        | Rd/Write   |
| Enable Flag     |               |               |            |
| PWM End of      | Mnn784        | Mnn785        | Rd/Write   |
| T TTIAL EIIG OF |               |               |            |

To implement High Speed Counter Operation:

- 1. Connect a device to X0 (Channel 1) or X5 (Channel 2) that will provide the high speed pulses to the expansion module.
- 2. Configure for HSC mode using the configuration register MWnn00 (Channel 1) or MWnn06 (Channel 2).
- 3. Write the HSC preset count value in MWnn03 (Channel 1) or MWnn09 (Channel 2).
- 4. Enable the HSC by setting the HSC Enable bit Mnn080 (Channel 1) or MWnn09 (Channel 2).

- HSC increments (starting from 0) the current value register in MWnn01 (Channel 1) or MWnn07 (Channel 2) until the preset value is reached. Then HSC sets Y1 (Channel 1) or Y6 (Channel 2).
- 6. Enable the HSC Reset Bit by setting Mnn081 (Channel1) ...
- To start the process again, simply reset (clear) the HSC Reset Bitand set the HSC Enable Bit. Note: if the HSC Enable Bit is still ON, you must reset (clear) this bit, and then set it again.

#### Additional Resources:

Detailed instructions on the operation and installation of the HMC3000 Series are available in the HMC3000 Programming Manual that is included with the MAPware-7000 configuration software. MAPware-7000 also includes help files that provide detailed information on using the configuration software.

This equipment is suitable for use in Class I, Division 2, Groups A, B, C, and D or non-hazardous locations only.

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▲ WARNING – EXPLOSION HAZARD – Do not disconnect equipment unless power has been removed or the area is known to be non-hazardous.

▲ WARNING – EXPLOSION HAZARD - Substitution of components may impair suitability for Class I, Division 2.

▲ WARNING - CAUTION, battery may explode if mistreated. Do not recharge, disassemble or dispose of in fire.

It is recommended that the user periodically inspect the sealed devices used, check for any degradation of properties, and replace as necessary.

#### For Technical Support:

Please contact Maple Systems if you have any questions regarding this product. We ask that you provide us with the unit serial number and firmware revision number written on the product label of the unit.

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