



## **DAC716**

# 16-Bit DIGITAL-TO-ANALOG CONVERTER with Serial Data Interface

## **FEATURES:**

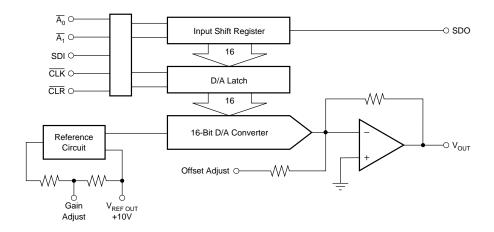
- SERIAL DIGITAL INTERFACE
- VOLTAGE OUTPUT: 0 to +10V
- ±2 LSB INTEGRAL LINEARITY
- PRECISION INTERNAL REFERENCE
- LOW NOISE: 120nV/√Hz Including Reference
- 16-LEAD PLASTIC SKINNY DIP AND PLASTIC SOIC PACKAGES

### DESCRIPTION

The DAC716 is a complete monolithic D/A converter including a +10V temperature compensated voltage reference, current-to-voltage amplifier, a high-speed synchronous serial interface, a serial output which allows cascading multiple converters, and an asynchronous clear function which immediately sets the output voltage to zero.

The output voltage range is 0 to +10 V while operating from  $\pm 12 \text{V}$  to  $\pm 15 \text{V}$  supplies, and the gain and bipolar offset adjustments are designed so that they can be set via external potentiometers or external D/A converters. The output amplifier is protected against short-circuiting to ground.

The 16-pin DAC716 is available in a plastic 0.3" DIP and a wide-body plastic SOIC package. The DAC716P, U, PB, and UB are specified over the -40°C to +85°C range while the DAC716UK and PK are specified over the 0°C to +70°C range.



International Airport Industrial Park • Mailing Address: PO Box 11400, Tucson, AZ 85734 • Street Address: 6730 S. Tucson Blvd., Tucson, AZ 85706 • Tel: (520) 746-1111 • Twx: 910-952-1111 Internet: http://www.burr-brown.com/ • FAXLine: (800) 548-6133 (US/Canada Only) • Cable: BBRCORP • Telex: 066-6491 • FAX: (520) 889-1510 • Immediate Product Info: (800) 548-6132

## **SPECIFICATIONS**

At  $T_A = +25$ °C,  $+V_{CC} = +15$ V,  $-V_{CC} = -15$ V, unless otherwise noted.

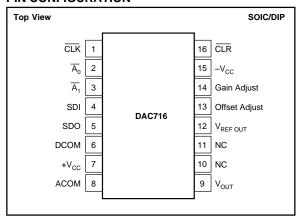
		DAC716PB, UB		В	DAC716PK, UK					
PARAMETER	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	UNITS
TRANSFER CHARACTERISTICS										
ACCURACY										
Linearity Error			±4			±2			±2	LSB
•										
T <sub>MIN</sub> to T <sub>MAX</sub>			±8			±4			±2	LSB
Differential Linearity Error			±4			±2			±2	LSB
T <sub>MIN</sub> to T <sub>MAX</sub>			±8			±4			±2	LSB
Monotonicity	14			15			15			Bits
Monotonicity Over Spec Temp Range	13			14			15			Bits
Gain Error <sup>(3)</sup>			±0.1			*			*	%
T <sub>MIN</sub> to T <sub>MAX</sub>			±0.25			*			*	%
Unipolar Zero Error <sup>(3)</sup>			±0.1			*			*	% of FSR(2
T <sub>MIN</sub> to T <sub>MAX</sub>			±0.2			*			*	% of FSR
Power Supply Sensitivity of Gain			±0.003			*			*	%FSR/%V <sub>c</sub>
one: cappi, consum, or cam			±30			*			*	ppm FSR/%\
DYNAMIC PERFORMANCE	+									
Settling Time										
(to ±0.003%FSR, 5kW    500pF Load)(4)										
20V Output Step	1	6	10		*	*		*	*	
	1		10			*			*	μs
1LSB Output Step <sup>(5)</sup>	1	4			*			*		μs
Output Slew Rate	1	10			*			*		V/µs
Total Harmonic Distortion	1									
0dB, 1001Hz, $f_S = 100kHz$	1	0.005			*			*		%
$-20$ dB, 1001Hz, $f_S = 100$ kHz	1	0.03			*			*		%
$-60$ dB, $1001$ Hz, $f_S = 100$ kHz	1	3.0			*			*		%
SINAD: 1001Hz, f <sub>S</sub> = 100kHz	1	87			*			*		dB
Digital Feedthrough <sup>(5)</sup>		2			*			*		nV-s
Digital-to-Analog Glitch Impulse <sup>(5)</sup>		15			*			*		nV-s
Output Noise Voltage (includes reference)		120			*			*		nV/√ <del>Hz</del>
ANALOG OUTPUT		120						,		1177 1112
Output Voltage Range										
+V <sub>CC</sub> , -V <sub>CC</sub> = ±11.4V	+10			*			*			V
	±5			*			*			
Output Current	ΞĐ			*			*			mA
Output Impedance		0.1			*			*		W
Short Circuit to ACOM Duration		Indefinite			*			*		ļ
REFERENCE VOLTAGE	.0.075	.40.000	.40.005	.,		.,	,	.,	.,	.,,
Voltage	+9.975	+10.000	+10.025	*	*	*	*	*	*	V
T <sub>MIN</sub> to T <sub>MAX</sub>	+9.960		+10.040	*		*	*		*	V
Output Resistance		1			*			*		W
Source Current	2			*			*			mA
Short Circuit to ACOM Duration		Indefinite			*			*		
INTERFACE										
RESOLUTION		16			*			*		Bits
DIGITAL INPUTS										
Serial Data Input Code										
Logic Levels <sup>(1)</sup>					Straight Binary	7	_			
V <sub>IH</sub>	+2.0		(V <sub>CC</sub> -1.4)	*		*	*		*	V
V <sub>IL</sub>	0		+0.8	*		*	*		*	V
I <sub>IH</sub> (V <sub>I</sub> = +2.7V)	1		±10			*			*	μА
I <sub>IL</sub> (V <sub>I</sub> = +0.4V)	+		±10			*			*	μА
<b>DIGITAL OUTPUT</b> Serial Data	1									
	1 ^		.0.4	<b>V</b> -		J.	y.		v.	V
V <sub>OL</sub> (I <sub>SINK</sub> = 1.6mA)	0		+0.4	*		*	*		*	
$V_{OH}$ ( $I_{SOURCE} = 500\mu A$ ), $T_{MIN}$ to $T_{MAX}$	+2.4		+5	*		*	*		*	V
POWER SUPPLY REQUIREMENTS										1
Voltage	1									
+V <sub>CC</sub>	+11.4	+15	+16.5	*	*	*	*	*	*	V
-V <sub>CC</sub>	-11.4	-15	-16.5	*	*	*	*	*	*	V
Current (No Load, ±15V Supplies)(6)	1									
+V <sub>CC</sub>	1	13	16		*	*		*	*	mA
-V <sub>CC</sub>	1	22	26		*	*		*	*	mA
Power Dissipation <sup>(7)</sup>	1		625		"	*			*	mW
· · · · · · · · · · · · · · · · · · ·	1									
IEMPERATURE RANGES	1				1	I			1	1
TEMPERATURE RANGES Specification										
Specification	-40		+85	*		*	0		+70	°C
	-40 -60		+85 +150	* *		*	0 *		+70 *	°C °C

 $<sup>\</sup>ensuremath{\mbox{\ensuremath{\$}}}$  Specifications are the same as the grade to the left.

NOTES: (1) Digital inputs are TTL and +5V CMOS compatible over the specification temperature range. (2) FSR means Full Scale Range. For example, for 0 to +10V output, FSR = 10V. (3) Errors externally adjustable to zero. (4) Maximum represents the 3d limit. Not 100% tested for this parameter. (5) For the worst-case Straight Binary code changes: 7FFF to 8000 and 8000 to 7FFF. (6) During power supply turn on, the transient supply current may approach 3x the maximum quiescent specification. (7) Typical (i.e. rated) supply voltages times maximum currents.



#### **PIN CONFIGURATION**



## ELECTROSTATIC DISCHARGE SENSITIVITY

Electrostatic discharge can cause damage ranging from performance degradation to complete device failure. Burr-Brown Corporation recommends that all integrated circuits be handled and stored using appropriate ESD protection methods.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet published specifications.

#### ABSOLUTE MAXIMUM RATINGS(1)

+V <sub>CC</sub> to Common	0V to +17V
-V <sub>CC</sub> to Common	0V to –17V
+V <sub>CC</sub> to -V <sub>CC</sub>	34V
ACOM to DCOM	±0.5V
Digital Inputs to Common	1V to (V <sub>CC</sub> -0.7V)
External Voltage Applied to BPO and Ra	ange Resistors ±V <sub>CC</sub>
V <sub>REF OUT</sub>	Indefinite Short to Common
V <sub>OUT</sub>	
SDO	Indefinite Short to Common
Power Dissipation	750mW
Storage Temperature	60°C to +150°C
Lead Temperature (soldering, 10s)	

NOTE: (1) Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. Exposure to absolute maximum conditions for extended periods may affect device reliability.

#### **PIN DESCRIPTIONS**

PIN	LABEL	DESCRIPTION
1	CLK	Serial Data Clock
2	$\overline{A_0}$	Enable for Input Register (Active Low)
3	$\overline{A_1}$	Enable for D/A Latch (Active Low)
4	SDI	Serial Data Input
5	SDO	Serial Data Output
6	DCOM	Digital Supply Ground
7	+V <sub>CC</sub>	Positive Power Supply
8	ACOM	Analog Supply Ground
9	V <sub>OUT</sub>	D/A Output
10	NC	No Connection
11	NC	No Connection
12	V <sub>REF OUT</sub>	Voltage Reference Output
13	Offset Adjust	Offset Adjust
14	Gain Adjust	Gain Adjust
15	-V <sub>CC</sub>	Negative Power Supply
16	CLR	Clear

#### ORDERING INFORMATION

PRODUCT	PACKAGE	DIFFERENTIAL LINEARITY ERROR T <sub>MIN</sub> to T <sub>MAX</sub>	TEMPERATURE RANGE	
DAC716P	Plastic DIP	±8 LSB	-40°C to +85°C	
DAC716U	Plastic SOIC	±8 LSB	-40°C to +85°C	
DAC716PB	Plastic DIP	±4 LSB	-40°C to +85°C	
DAC716UB	Plastic SOIC	±4 LSB	-40°C to +85°C	
DAC716PK	Plastic DIP	±2 LSB	0°C to +70°C	
DAC716UK	Plastic SOIC	±2 LSB	0°C to +70°C	

#### **PACKAGE INFORMATION**

PRODUCT	PACKAGE	PACKAGE DRAWING NUMBER <sup>(1)</sup>
DAC716P	Plastic DIP	180
DAC716U	Plastic SOIC	211

NOTE: (1) For detailed drawing and dimension table, please see end of data sheet, or Appendix C of Burr-Brown IC Data Book.

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#### **TIMING SPECIFICATIONS**

 $T_A = -40^{\circ}C$  to +85°C, +V<sub>CC</sub> = +15V, -V<sub>CC</sub> = -15V.

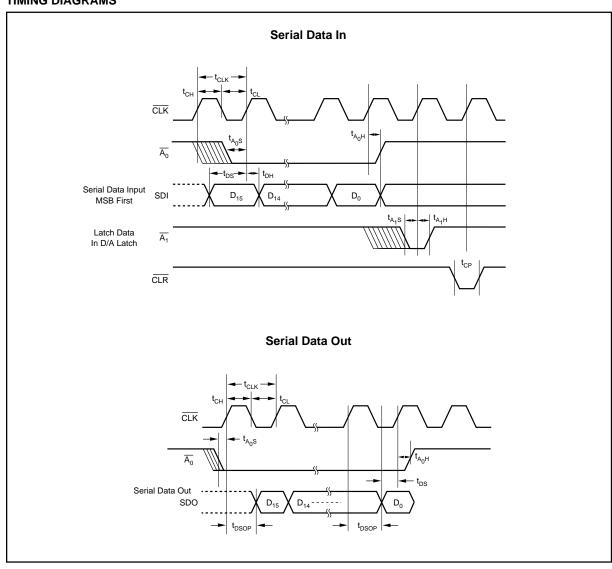
SYMBOL	PARAMETER	MIN	MAX	UNITS
t <sub>CLK</sub>	Data Clock Period	100		ns
t <sub>CL</sub>	Clock LOW	50		ns
t <sub>CH</sub>	Clock HIGH	50		ns
t <sub>AOS</sub>	Setup Time for $\overline{A_0}$	50		ns
t <sub>A1S</sub>	Setup Time for $\overline{A_1}$	50		ns
t <sub>AOH</sub>	Hold Time for $\overline{A_0}$	10		ns
t <sub>A1H</sub>	Hold Time for $\overline{A_1}$	10		ns
t <sub>DS</sub>	Setup Time for DATA	50		ns
t <sub>DH</sub>	Hold Time for DATA	10		ns
t <sub>DSOP</sub>	Output Propagation Delay	140		ns
t <sub>CP</sub>	Clear Pulsewidth	200		ns

#### **TRUTH TABLE**

$\overline{A_0}$	A <sub>1</sub>	CLK	CLR	DESCRIPTION
0	1	$1 \rightarrow 0 \rightarrow 1$	1	Shift Serial Data into SDI
1	0	$1 \rightarrow 0 \rightarrow 1$	1	Load D/A Latch
1	1	$1 \rightarrow 0 \rightarrow 1$	1	No Change
0	0	$1 \rightarrow 0 \rightarrow 1$	1	Two Wire Operation <sup>(1)</sup>
Х	Х	1	1	No Change
Х	Х	Х	0	Reset D/A Latch

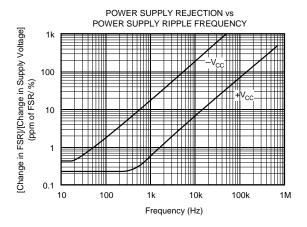
NOTES: X = Don't Care. (1) All digital input changes will appear at the D/A output.

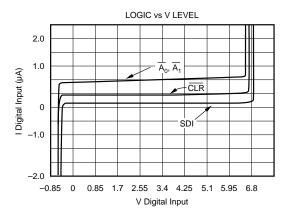
#### **TIMING DIAGRAMS**

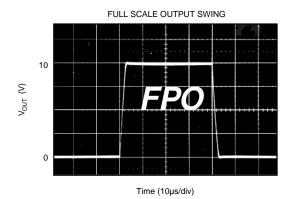


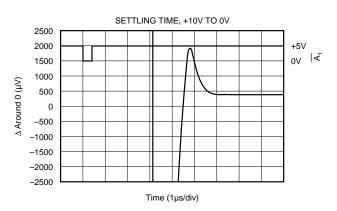
## TYPICAL PERFORMANCE CURVES

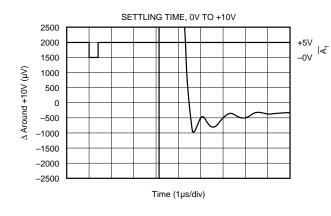
At  $T_A = +25$ °C,  $V_{CC} = \pm 15$ V, unless otherwise noted.

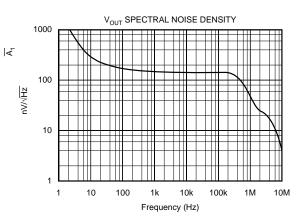












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## DISCUSSION OF SPECIFICATIONS

#### LINEARITY ERROR

Linearity error is defined as the deviation of the analog output from a straight line drawn between the end points of the transfer characteristic.

#### **DIFFERENTIAL LINEARITY ERROR**

Differential linearity error (DLE) is the deviation from 1LSB of an output change from one adjacent state to the next. A DLE specification of  $\pm 1/2$ LSB means that the output step size can range from 1/2LSB to 3/2LSB when the digital input code changes from one code word to the adjacent code word. If the DLE is more positive than -1LSB, the D/A is said to be monotonic.

#### MONOTONICITY

A D/A converter is monotonic if the output either increases or remains the same for increasing digital input values. Monotonicity of the K grade is guaranteed over the specification temperature range to 15 bits.

#### **SETTLING TIME**

Settling time is the total time (including slew time) for the D/A output to settle to within an error band around its final value after a change in input. Settling times are specified to within ±0.003% of Full Scale Range (FSR) for an output step change of 10V and 1LSB. The 1LSB change is measured at the Major Carry (7FFF to 8000, and 8000 to 7FFF: Straight Binary codes), the input transition at which worst-case settling time occurs.

#### **TOTAL HARMONIC DISTORTION + NOISE**

Total harmonic distortion + noise is defined as the ratio of the square root of the sum of the squares of the values of the harmonics and noise to the value of the fundamental frequency. It is expressed in % of the fundamental frequency amplitude at sampling rate  $f_S$ .

#### SIGNAL-TO-NOISE AND DISTORTION RATIO (SINAD)

SINAD includes all the harmonic and outstanding spurious components in the definition of output noise power in addition to quantizing and internal random noise power. SINAD is expressed in dB at a specified input frequency and sampling rate,  $f_{\rm S}$ .

#### **DIGITAL-TO-ANALOG GLITCH IMPULSE**

The amount of charge injected into the analog output from the digital inputs when the inputs change state. It is measured at half scale at the input codes where as many as possible switches change state—from 8000 to 7FFF.

#### **DIGITAL FEEDTHROUGH**

When the A/D is not selected, high frequency logic activity on the digital inputs is coupled through the device and shows up as output noise. This noise is digital feedthrough.

### **OPERATION**

The DAC716 is a monolithic integrated-circuit 16-bit D/A converter complete with 16-bit D/A switches and ladder network, voltage reference, output amplifier and a serial interface.

#### **INTERFACE LOGIC**

The DAC716 has double-buffered data latches. The input data latch holds a 16-bit data word before loading it into the second latch, the D/A latch. This double-buffered organization permits simultaneous update of several D/A converters. All digital control inputs are active low. Refer to block diagram of Figure 1.

All latches are level-triggered. Data present when the enable inputs are logic "0" will enter the latch. When the enable inputs return to logic "1", the data is latched.

The CLR input resets both the input latch and the D/A latch to give an output voltage of 0V (code 0000).

#### LOGIC INPUT COMPATIBILITY

DAC716 digital inputs are TTL compatible (1.4V switching level) with low leakage, high impedance inputs. Thus the inputs are suitable for being driven by any type of 5V logic such as 5V CMOS logic. An equivalent circuit of a digital input is shown in Figure 2.

Data inputs will float to logic "0" and control inputs will float to logic "0" if left unconnected. It is recommended that any unused inputs be connected to DCOM to improve noise immunity.

Digital inputs remain high impedance when power is off.

#### **INPUT CODING**

The DAC716 is designed to accept Straight Binary (SB) input codes. The serial input format is MSB first.

#### INTERNAL REFERENCE

DAC716 contains a +10V reference.

The reference output may be used to drive external loads, sourcing up to 2mA. The load current should be constant, otherwise the gain and unipolar offset of the converter will vary.

#### **OUTPUT VOLTAGE SWING**

The output amplifier of DAC716 is designed to achieve a +10V output range. DAC716 will provide a +10V output swing while operating on  $\pm 11.4V$  or higher voltage supplies.



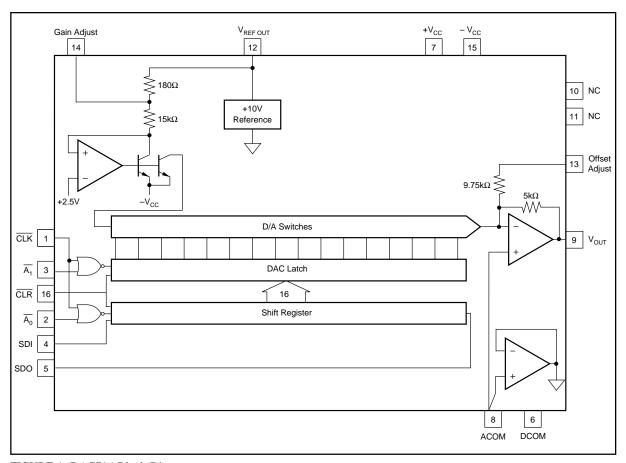


FIGURE 1. DAC716 Block Diagram.

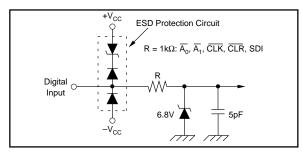


FIGURE 2. Equivalent Circuit of Digital Inputs.

#### **GAIN AND OFFSET ADJUSTMENTS**

Figure 3 illustrates the relationship of offset and gain adjustments for a unipolar connected D/A converter. Offset should be adjusted first to avoid interaction of adjustments. See Table I for calibration values and codes. These adjustments have a minimum range of  $\pm 0.3\%$ .

#### **Offset Adjustment**

Apply the digital input code, 0000, that produces 0V and adjust the offset potentiometer or the offset adjust D/A converter for 0V.

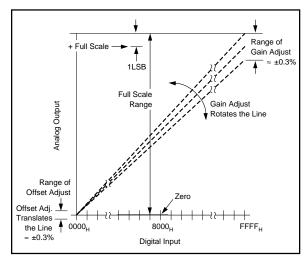


FIGURE 3. Relationship of Offset and Gain Adjustments.

### **Gain Adjustment**

Apply the digital input that gives the maximum positive voltage output. Adjust the gain potentiometer or the gain adjust D/A converter for this positive full scale voltage.

DAC716 CALIBRATION VALUES 1 LEAST SIGNIFICANT BIT = $152\mu V$							
DIGITAL INPUT CODE	DIGITAL INPUT CODE ANALOG OUTPUT (V)						
STRAIGHT BINARY	UNIPOLAR 10V RANGE	DESCRIPTION					
FFFF <sub>H</sub>	+9.999695	+ Full Scale -1LSB					
8000 <sub>H</sub>	+5.000000	Half Scale					
0000 <sub>H</sub>	0.000000	Unipolar Zero					

TABLE I. Digital Input and Analog Output Voltage Calibration Values.

## **INSTALLATION**

#### **GENERAL CONSIDERATIONS**

Due to the high precision of these D/A converters, system design problems such as grounding and contact resistance become very important. A 16-bit converter with a 10V full-scale range has a 1LSB value of 152 $\mu$ V. With a load current of 5mA, series wiring and connector resistance of only  $60m\Omega$  will cause a voltage drop of  $300\mu$ V. To understand what this means in terms of a system layout, the resistivity of a typical 1 ounce copper-clad printed circuit board is 1/2  $m\Omega$  per square. For a 5mA load, a 0.1 inch wide printed circuit conductor 0.6 inches long will result in a voltage drop of  $150\mu$ V.

The analog output of DAC716 has an LSB size of  $152\mu V$  (–96dB). The rms noise floor of the D/A should remain below this level in the frequency range of interest. The DAC716's output noise spectral density (which includes the noise contributed by the internal reference) is shown in the Typical Performance Curves section.

Wiring to high-resolution D/A converters should be routed to provide optimum isolation from sources of RFI and EMI. The key to elimination of RF radiation or pickup is small loop area. Signal leads and their return conductors should be kept close together such that they present a small capture cross-section for any external field. Wire-wrap construction is not recommended.

## POWER SUPPLY AND REFERENCE CONNECTIONS

Power supply decoupling capacitors should be added as shown in Figure 4. Best performance occurs using a 1 to  $10\mu F$  tantalum capacitor at  $-V_{CC}.$  Applications with less critical settling time may be able to use  $0.01\mu F$  at  $-V_{CC}$  as well as at  $+V_{CC}.$  The capacitors should be located close to the package.

The DAC716 has separate ANALOG COMMON and DIGITAL COMMON pins. The current through DCOM is mostly switching transients and are up to 1mA peak in amplitude. The current through ACOM is typically  $5\mu$ A for all codes.

Use separate analog and digital ground planes with a single interconnection point to minimize ground loops. The analog

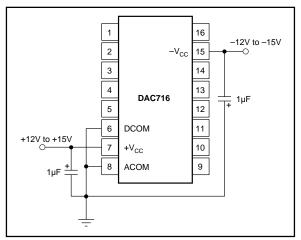


FIGURE 4. Power Supply Connections.

pins are located adjacent to each other to help isolate analog from digital signals. Analog signals should be routed as far as possible from digital signals and should cross them at right angles. A solid analog ground plane around the D/A package, as well as under it in the vicinity of the analog and power supply pins, will isolate the D/A from switching currents. It is recommended that DCOM and ACOM be connected directly to the ground planes under the package.

If several DAC716s are used or if the DAC716 shares supplies with other components, connecting the ACOM and DCOM lines together at the power supplies only rather than at each chip, may give better results.

#### **LOAD CONNECTIONS**

Since the reference point for  $V_{OUT}$  and  $V_{REF\ OUT}$  is the ACOM pin, it is important to connect the D/A converter load directly to the ACOM pin. Refer to Figure 5.

Lead and contact resistances are represented by  $R_1$  through  $R_3$ . As long as the load resistance  $R_L$  is constant,  $R_1$  simply introduces a gain error and can be removed by gain adjustment of the D/A or system-wide gain calibration.  $R_2$  is part of  $R_L$  if the output voltage is sensed at ACOM.

In some applications it is impractical to return the load to the ACOM pin of the D/A converter. Sensing the output voltage at the SYSTEM GROUND point is reasonable, because there is no change in DAC716 ACOM current, provided that  $R_3$  is a low-resistance ground plane or conductor. In this case you may wish to connect DCOM to SYSTEM GROUND as well.

#### **GAIN AND OFFSET ADJUST**

#### **Connections Using Potentiometers**

GAIN and OFFSET adjust pins provide for trim using external potentiometers. 15-turn potentiometers provide sufficient resolution. Range of adjustment of these trims is at least  $\pm 0.3\%$  of Full Scale Range. Refer to Figure 6.



#### **Using D/A Converters**

The GAIN ADJUST and OFFSET ADJUST circuits of DAC716 have been arranged so that these points may be easily driven by external D/A converters. Refer to Figure 7. 12-bit D/A converters provide a nominal OFFSET adjust and GAIN adjust resolution of  $25\mu V$  and  $15\mu V$  per LSB step, respectively.

Nominal values of GAIN and OFFSET occur when the D/A converters outputs are at approximately half scale, 0V.

#### **OUTPUT VOLTAGE RANGE CONNECTIONS**

The DAC716 output amplifier is connected internally for 10V output range.

## **DIGITAL INTERFACE**

#### **SERIAL INTERFACE**

The DAC716 has a serial interface with two data buffers which can be used for either synchronous or asynchronous updating of multiple D/A converters.  $\overline{A0}$  is the enable control for the Data Input Latch.  $\overline{A1}$  is the enable for the D/A Latch.  $\overline{CLK}$  is used to strobe data into the latches enabled by  $\overline{A0}$  and  $\overline{A1}$ . A  $\overline{CLR}$  function is also provided and when enabled it sets both the Data Latch and the D/A Latch to all zeros .

Multiple DAC716s can be connected to the same  $\overline{\text{CLK}}$  and data lines in two ways. The output of the serial loaded data latch is available as SDO so that any number of DAC716s can be cascaded on the same input bit stream as shown in Figure 8 and 9. This configuration allows all D/A converters to be updated simultaneously and requires a minimum number of control signal inputs. These configurations do require  $16N\ \overline{\text{CLK}}$  cycles to load any given D/A converter, where N is the number of D/A converters.

The DAC716 can also be connected in parallel as shown in Figure 10. This configuration allows any D/A converter in the system to be updated in a maximum of  $16\ \overline{\text{CLK}}$  cycles.

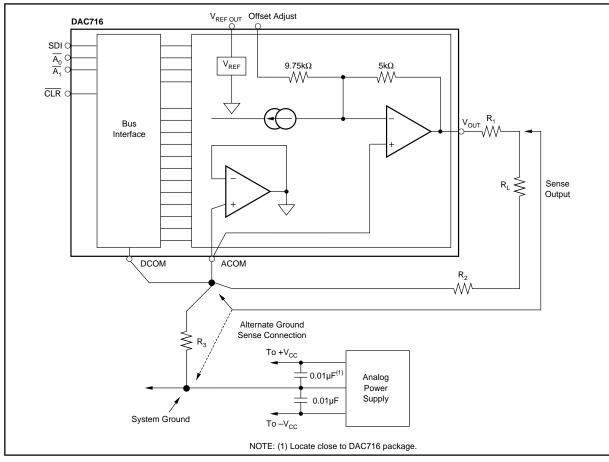


FIGURE 5. System Ground Considerations for High-Resolution D/A Converters.



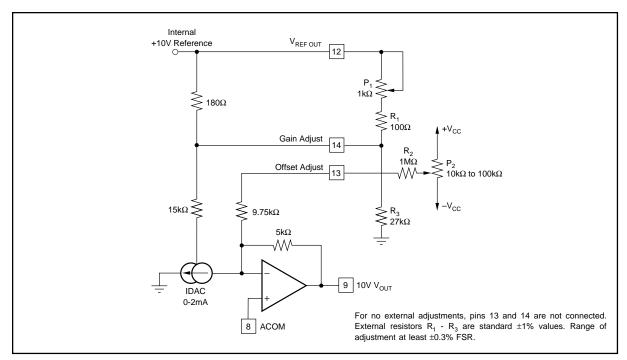


FIGURE 6. Manual Offset and Gain Adjust Circuits.

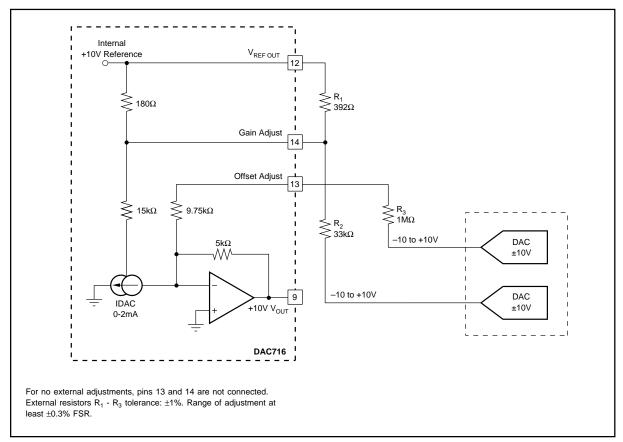


FIGURE 7. Gain and Offset Adjustment Using D/A Converters.



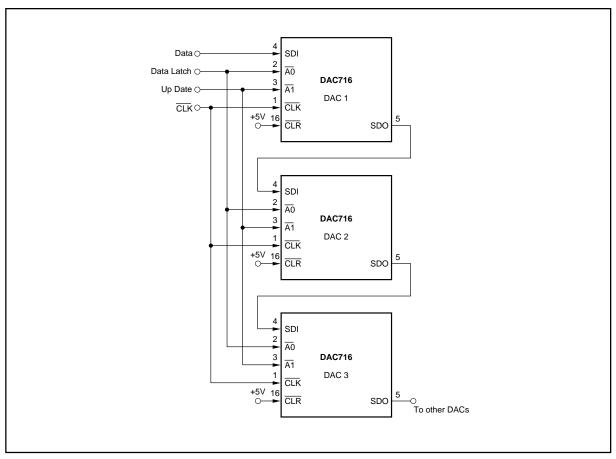


FIGURE 8a. Cascaded Serial Bus Connection with Synchronous Update.

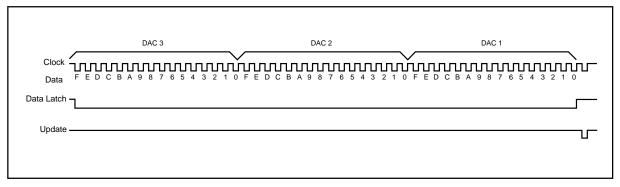


FIGURE 8b. Timing Diagram For Figure 8a.

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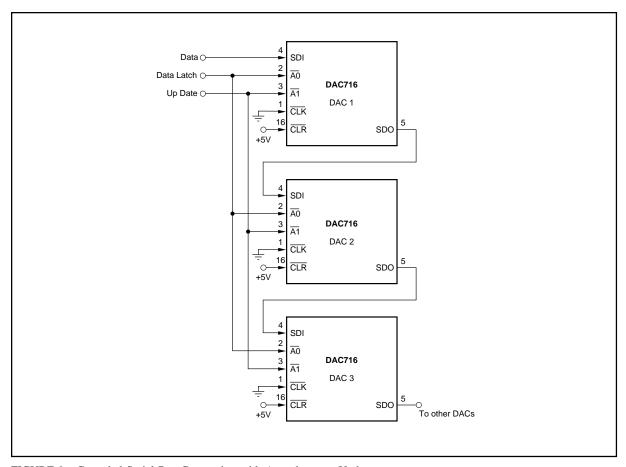


FIGURE 9a. Cascaded Serial Bus Connection with Asynchronous Update.

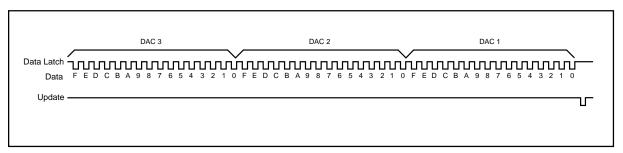


FIGURE 9b. Timing Diagram For Figure 9a.

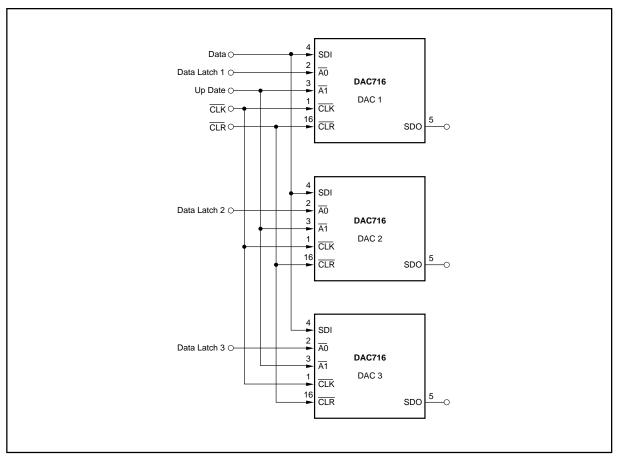
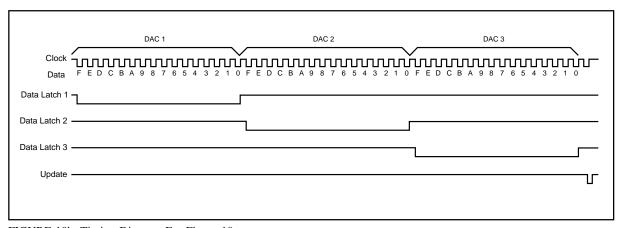


FIGURE 10a. Parallel Bus Connection.



 $FIGURE\ 10b.\ Timing\ Diagram\ For\ Figure\ 10a.$ 

#### PACKAGE OPTION ADDENDUM

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#### PACKAGING INFORMATION

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	e Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
DAC716P	NRND	PDIP	N	16	25	Green (RoHS & no Sb/Br)	CU NIPDAU	N / A for Pkg Type
DAC716PB	NRND	PDIP	N	16	25	Green (RoHS & no Sb/Br)	CU NIPDAU	N / A for Pkg Type
DAC716PBG4	NRND	PDIP	N	16	25	Green (RoHS & no Sb/Br)	CU NIPDAU	N / A for Pkg Type
DAC716PG4	NRND	PDIP	N	16	25	Green (RoHS & no Sb/Br)	CU NIPDAU	N / A for Pkg Type
DAC716PK	NRND	PDIP	N	16	25	Green (RoHS & no Sb/Br)	CU NIPDAU	N / A for Pkg Type
DAC716PKG4	NRND	PDIP	N	16	25	Green (RoHS & no Sb/Br)	CU NIPDAU	N / A for Pkg Type
DAC716U	ACTIVE	SOIC	DW	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
DAC716UB	ACTIVE	SOIC	DW	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
DAC716UBG4	ACTIVE	SOIC	DW	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
DAC716UG4	ACTIVE	SOIC	DW	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
DAC716UK	ACTIVE	SOIC	DW	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
DAC716UKG4	ACTIVE	SOIC	DW	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND**: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

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**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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