

SANYO Semiconductors DATA SHEET

An ON Semiconductor Company



BI-CMOS LSI For DSC, and Cell Phone Camera Modules H-Bridge × 4-channel Motor Driver

Overview

The LV8416CB is an H-bridge×4-channel motor driver IC and is able to control 4 modes of forward, reverse, brake and standby.

This IC housed in a wafer level package (WLP) is optimum for use in a stepping motor driving system for DSC or a camera module of cell phones.

Functions

- Saturation drive H-bridge: 4-channels
- Various protection circuits (thermal protection, low voltage malfunction protection)

Specifications

Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Power supply voltage	V _{CC} max		6.0	V
Output peak current	I _O peak	Channels 1 to 4, t \leq 10msec, ON-duty \leq 20%	600	mA
Output continuous current	I _O max	Channels 1 to 4	400	mA
Allowable power dissipation	Pd max	Mounted on a circuit board*	1000	mW
Operating temperature	Topr		-30 to +85	°C
Storage temperature	Tstg		-55 to +150	°C

• Specified circuit board : 60mm × 60mm × 1.7mm, glass epoxy two-layer board.

Recommended Operating Conditions at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Power supply voltage range	V _{CC} op		2.5 to 5.5	V
Logic input voltage range	V _{IN}		0 to V _{CC} +0.3	V
Input frequency	fIN	IN1 to 8	to 100	kHz

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Electrical Characteristics at $Ta = 25^{\circ}C$, $V_{CC} = 5V$

Parameter	Symbol	Symbol Conditions		Ratings		
Farameter	Symbol	Conditions	min	typ	max	Unit
Standby mode current drain	lst	IN1 to IN8 = "L"			1.0	μA
V _{CC} current drain	ICC1	$V_{CC}=V_{IN}1 = 3.3V$	40	80	160	μA
	I _{CC} 2	$V_{CC} = V_{IN} 1 = 5.0 V$	50	100	200	μA
V _{CC} low-voltage cutoff voltage	VthV _{CC}		2.0	2.25	2.5	V
Low-voltage hysteresis voltage	VthHIS		100	150	200	mV
Thermal shutdown temperature	TSD	Design guarantee value *	160	180	200	°C
Thermal hysteresis width	ΔTSD	Design guarantee value *	10	30	50	°C
Input pin						
Logic pin input current	linL	V _{IN} = 0V, IN1 to IN8			1.0	μA
	linH	V _{IN} = 3.3V, IN1 to IN8	8.3	16.5	33	μA
Logic input high-level voltage	Vinh	IN1 to IN8	0.5×V _{CC}			V
Logic input low-level voltage	Vinl	IN1 to IN8			0.2×V _{CC}	V
Input circuit current consumption	ICCin	$V_{IN} = 3.3V$, power hit of IN1 to IN8 *1	30	80	250	μA
Motor driver						
Output on-resistance	Ronu	I _O = 100mA, upper ON resistance		0.5	0.75	Ω
	Rond	I _O = 100mA, lower ON resistance		0.3	0.55	Ω
Output leakage current	l _O leak				1.0	μA
Diode forward voltage	VD	ID = -100mA	0.4	0.75	1.2	V
Turn-on time	Ton	Time of Input 50% \rightarrow Output 50% *2		0.10	0.50	μsec
Turn-off time	Toff	Time of Input 50% \rightarrow Output 50%		0.15	0.55	μsec
At the rise time	Tr	Time of Output $10\% \rightarrow 90\%$		0.05	0.20	μsec
Standing fall time	Tf	Time of Output 90% \rightarrow 10%		0.05	0.20	μseo

*1: The input circuit current consumption in CMOS circuit composition of the input steps is generated though it is unquestionable for IC operation when impressing it to V_{IN} voltage that is lower than the V_{CC} voltage.

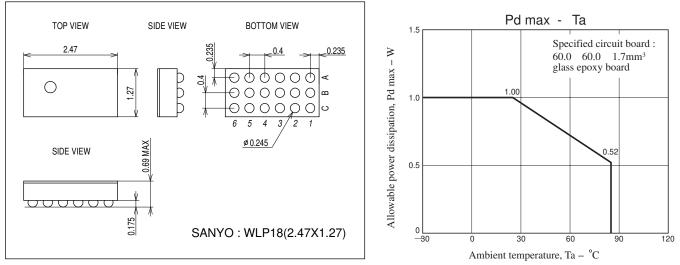
*2: Time from change edge to change edge (0.5×VCC) of control input at output level.

It doesn't have an enable pin, and as for this IC, either in the input pin begins and the internal logic begins operation of "High". Therefore, the turn-on time becomes about three microseconds only at the initial motion work of the input terminal "High".

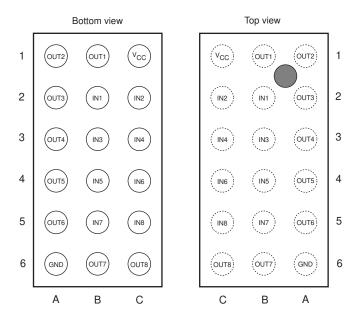
Package Dimensions

unit : mm (typ)

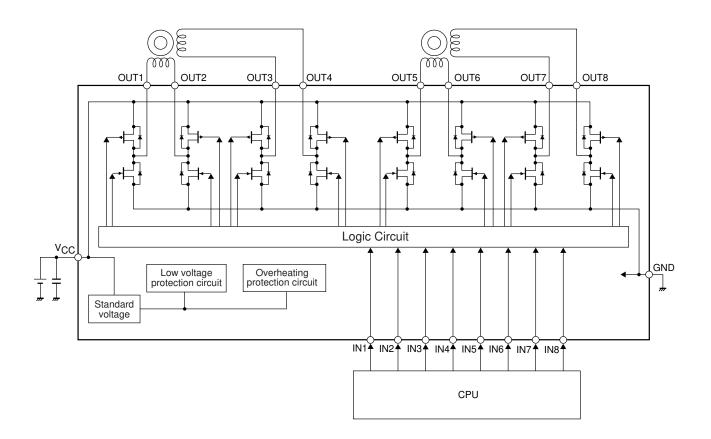
3401



Pin Assignment



Block Diagram



Pin Fu	nctions		
Pin No.	Pin name	Pin Function	Equivalent Circuit
B2 C2 B3 C3 B4 C4 B5 C5	IN1 IN2 IN3 IN4 IN5 IN6 IN7 IN8	Control signal input pin Control signal input pin	V _{CC}
B1 A1 A2 A3 A4 A5 B6 C6	OUT1 OUT2 OUT3 OUT4 OUT5 OUT6 OUT7 OUT8	Motor driver output pin Motor driver output pin	
			GND
C1	V _{CC}	Logic system power supply connection pin	
A6	GND	Signal ground	

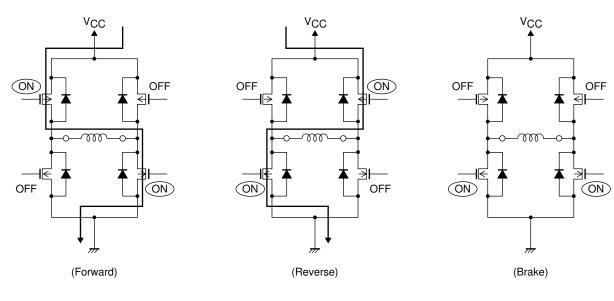
Logic input specifications

- Common channels 1 to 4
 - ch1:IN1 to IN2, OUT1 to OUT2
 - ch2:IN3 to IN4, OUT3 to OUT4
 - ch3:IN5 to IN6, OUT5 to OUT6

ch4 : IN7 to IN8, OUT7 to OUT8

Input		Output		On eventions are ada
IN1	IN2	OUT1	OUT2	Operation mode
L	L	OFF	OFF	Standby
н	L	Н	L	CW (forward)
L	н	L	н	CCW (reverse)
н	н	L	L	Brake

• Output stage transistor function



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