

Si3474 Data Sheet

Up to four 802.3bt or eight 802.3at Ethernet Port PoE PSE Controllers

The Si3474 is a fully programmable, 50 to 57 V power management controller for IEEE 802.3af, 802.3at, and 802.3bt compliant Power Sourcing Equipment (PSE). Designed for use in PSE endpoints (switches), the Si3474 integrates eight independent ports, each with the IEEE-required powered device (PD) detection and classification functionality. When used in 802.3af/802.3at (two-pair power) mode each PSE port supports one Ethernet connection, for a total of eight PoE Ethernet connections. 802.3bt operation (four-pair power) uses two PSE ports per Ethernet connection, for a total of four PoE Ethernet connections.

In addition, the Si3474 features a fully-programmable architecture that enables powered device (PD) disconnect using dc-sense algorithms, a robust multipoint detection algorithm, software configurable per-port current and voltage monitoring, and programmable current limits to support the IEEE 802.3af, 802.3at, and 802.3bt standards. Intelligent protection circuitry includes input undervoltage detection, output current limit, and short-circuit protection. The Si3474 operates autonomously or by host processor control through a two wire, I²C compatible serial interface. An interrupt pin is used to alert the host processor of various status and fault conditions.

Applications

- IEEE 802.3af, 802.3at, and 802.3bt Power Sourcing Equipment (PSE)
- Power over Ethernet Switches
- IP Phone Systems
- Smartgrid Switches
- Ruggedized and Industrial Switches

KEY FEATURES

- Octal-Port Power Sourcing Equipment (PSE) controller
- IEEE 802.3af, 802.3at, and 802.3bt compliant
- Autonomous or I²C host interface
- Emergency Shutdown support with port priority control
- Adds enhanced features for maximum design flexibility:
 - Per-port current and voltage monitoring
 - Multi-point detection
 - Programmable power MOSFET gate drive control
 - Configurable watchdog timer enables failsafe operation
- Maskable interrupt pin
- Comprehensive fault protection circuitry includes:
 - Power undervoltage lockout
 - Output current limit and short-circuit protection
 - Thermal overload detection
- Extended operating temp range: -40 to +85 °C
- 56-pin, 8 x 8 mm QFN package (RoHS-compliant)

1. Ordering Guide

Table 1.1. Si3474 Ordering Guide

| Ordering Part Number ¹ | Product Revision | Current Sense Resistor ² | Package | Temperature Range (Ambient) |
|-----------------------------------|------------------|-------------------------------------|--|-----------------------------|
| Si3474A-A01-IM | A01 | 255 mΩ | 56-pin, 8 x 8 mm QFN RoHS-compliant | –40 to 85 °C |
| Si3474B-A01-IM | A01 | 200 mΩ | 56-pin, 8 x 8 mm QFN RoHS-compliant | –40 to 85 °C |

Note:

1. Add an “R” to the end of the part number for tape and reel option (e.g., Si3474A or Si3474A-A01-IMR).
2. Options include industry-standard 255 mΩ or more thermally efficient 200 mΩ sense resistor.

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2. Functional Description

2.1 Overview

Integrating a high-performance microcontroller with high-resolution A/D and D/A capabilities, along with eight independent, high-voltage PSE port interfaces, the Si3474 enables an extremely flexible solution for virtually any PoE switch application. The Si3474 integrates all PSE controller functions needed for an octal-port PoE design.

The Si3474 includes many additional features that can be individually enabled or disabled by programming the extended register set appropriately.

- Per-port current / voltage monitoring and measurement
- Multipoint detection algorithms
- Programmable gate drive for external MOSFETs
- Watchdog timer (WDT)

2.2 Functional Block Diagram

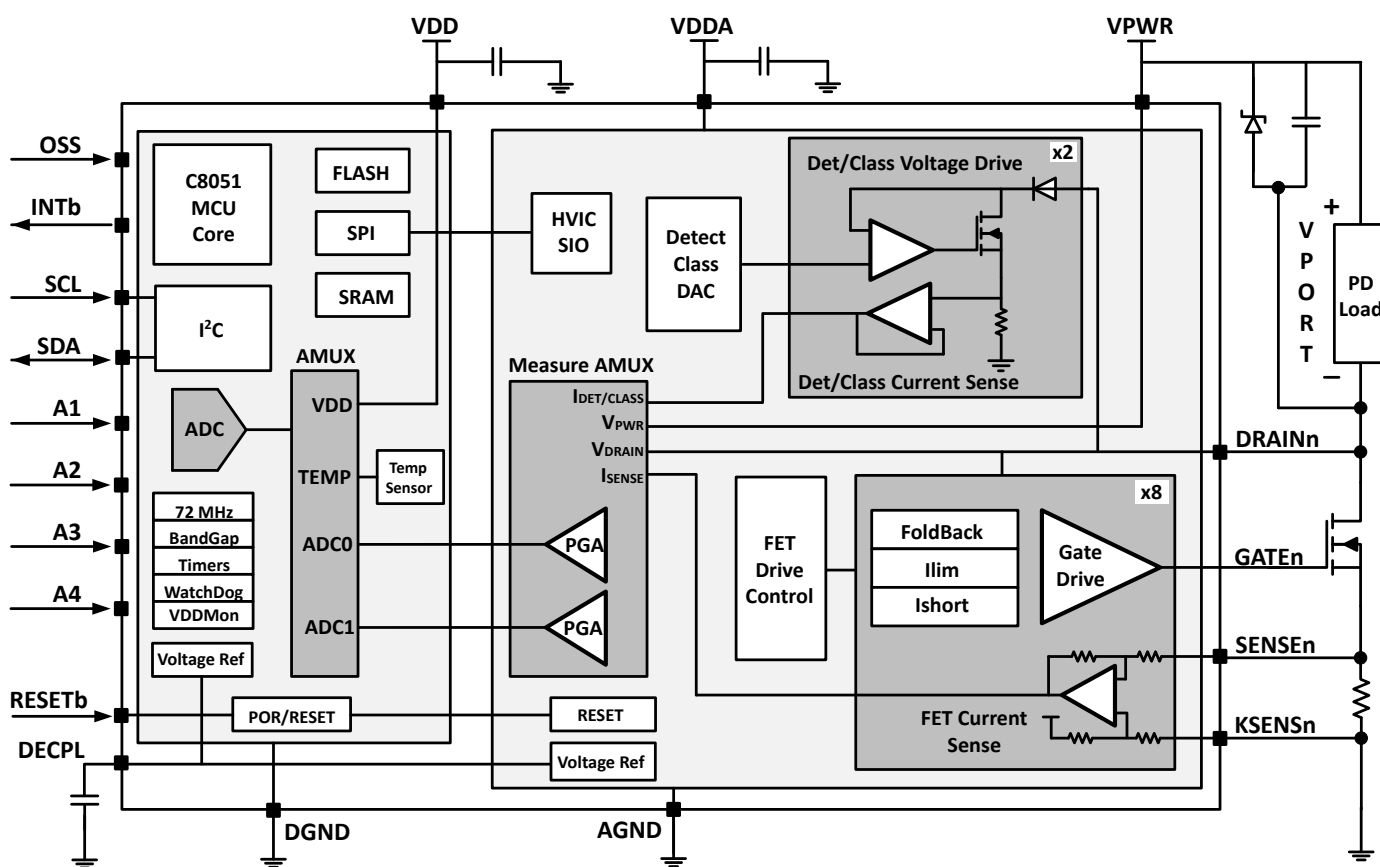


Figure 2.1. Si3474 Functional Block Diagram

2.3 Operational Modes

The Si3474 has three different operating modes: Autonomous, Semi-Autonomous, and Manual, plus one non-operating mode, Shut-down. The appropriate operating mode can be chosen depending on system requirements, such as whether the PSE system is power-constrained, whether the PSE system has a power manager host, or whether the PSE system must identify any power-non-conforming PD loads.

2.3.1 Autonomous Mode

Autonomous Mode should only be used in PSE systems where there is enough power to power all ports simultaneously to their total allocated power. In other words, Autonomous Mode can only be used in non-power constrained PSE systems. In Autonomous mode, the Si3474 will automatically detect, classify and power on ports that present a valid PD signature without any external host interaction.

There are two methods to place the Si3474 into Autonomous mode. One method is to configure the AUTO pin using an external voltage and power cycling the Si3474. The following types of systems are suitable for AUTO pin Autonomous Mode:

- Homogenous ports configuration. For each Si3474, all ports must be configured as either four-pair powered ports (4P) or all ports configured as two-pair powered ports (2P).
- Each port must have the same Power Allocation setting.
- PSE system must be able to supply sufficient VPWR current to all ports under maximum loading.

The second method is to an external host processor to configure and start the Autonomous Mode through the I²C registers. For systems whose ports are not homogenous or if the ports are to have different power allocations, use I²C Autonomous Mode instead of the AUTO pin. Whether Autonomous Mode is invoked by the AUTO pin or by the I²C interface, the I²C register interface remains active so an external host processor can poll the event registers, for example, to control indicator LEDs.

For more details on autonomous operation, refer to [2.10.1 AUTO Pin Autonomous Mode](#) and [2.10.2 I²C Autonomous Mode](#).

2.3.2 Semi-Autonomous Mode

In PSE systems with high port counts, rarely is there a PSE system power supply that is capable of powering all ports to their maximum load simultaneously. The Si3474 I²C register interface is designed to accommodate a host processor to act as a power manager that can choose or deny PD power requests as new PD loads are attached. In these systems, the Si3474 controller performs low level PoE protocols with the PD loads and provides real-time fault monitoring and power consumption measurements required by the external host processor to perform power management. For these hosted, power-constrained systems, the Si3474 operates in Semi-Autonomous mode.

2.3.3 Manual Mode

Manual mode is special case of Semi-Autonomous mode where the external host processor forces a condition on the port(s) that bypasses the low-level PoE protocol. For example, forcing a port to power on a PD load immediately without exercising detection and classification protocol. As such, manual mode should be used for diagnostic or debug purposes only.

2.4 Host Interface

The Si3474 communicates with the host processor through an I²C interface using:

- Registers
- Events
- Pushbuttons

In this data sheet, register names, fields and bits are listed in all capitals. Some have prefixes such as PORTn_ or PORTnm_. The PORTn_ describes attributes that are associated with 2P ports. The prefix PORTnm_ applies to attributes associated with 4P ports. Some registers are global to the entire Si3474. Some registers are associated with one set of four 2P ports (quad). The Si3474 has two quads and the second set of four 2P ports are accessed in the same register but through the alternate I²C address. Refer to [4. Register Map](#) for a complete listing of registers.

During operation, the Si3474 monitors global conditions such as temperature and supply voltage, and some conditions that are associated with the individual PoE ports. When an event occurs, the Si3474 will drive the INTb pin low. The host processor will then read the INTERRUPT register and decode what event has occurred. The Si3474 drives the INTb low until the appropriate Clear-on-Read (CoR) register is read by the host processor.

There are some events in which cause the Si3474 to take immediate action without instructions from the host, and there are some that are intended to be indicators to allow the host processor to take desired actions as its role being the PSE system power manager. Once the host receives notification of an event, it is expected to act upon that event. The details and mechanics of event handling is described in [2.9 Event Handling](#).

The host processor can instruct the Si3474 to take certain actions through a Pushbutton (PB) command. All write-only registers are Pushbutton registers. A register designated as Pushbutton will always return as zero when read. Some read-write registers can also act as pushbuttons depending on the context as described in .

Each Si3474 port can be in one of four operational modes, controlled by the PORT_MODE register. PORTn_PORT_MODE can be set to:

- SHUTDOWN
- MANUAL
- SEMI_AUTO
- AUTO

The AUTO mode is most applicable to a non-hosted PSE system. The MANUAL mode is used primarily for diagnostic and debug purposes. For hosted PSE systems, SHUTDOWN and SEMI_AUTO port modes are the most important. When PORTn_PORT_MODE is set to SHUTDOWN, that port is in an idle state, ready to be configured by the host.

A port enters SHUTDOWN by:

- A hard reset (power on reset or by deasserting RESETb pin)
- Setting RESET_QUAD in PB_RESET register sets all ports in that quad to SHUTDOWN
- Setting individual PORTn_RESET_PORT in PB_RESET register. Each port has a dedicated bit
- Any SUPPLY_EVENT sets all ports to SHUTDOWN
- An I²C WATCHDOG event is equivalent to a RESET_QUAD that sets all ports to SHUTDOWN

A port in SEMI_AUTO mode, when combined with PORTn_DETECT_CC_ENABLE and PORTn_CLASS_ENABLE, instructs the Si3474 to actively look for connected PDs on a port. In a power-managed, hosted PSE system, the figure below describes the key interactions and events between the power manager host and the PoE port conditions in the Si3474. The following sections describe the control flow of a Semi-Auto PSE.

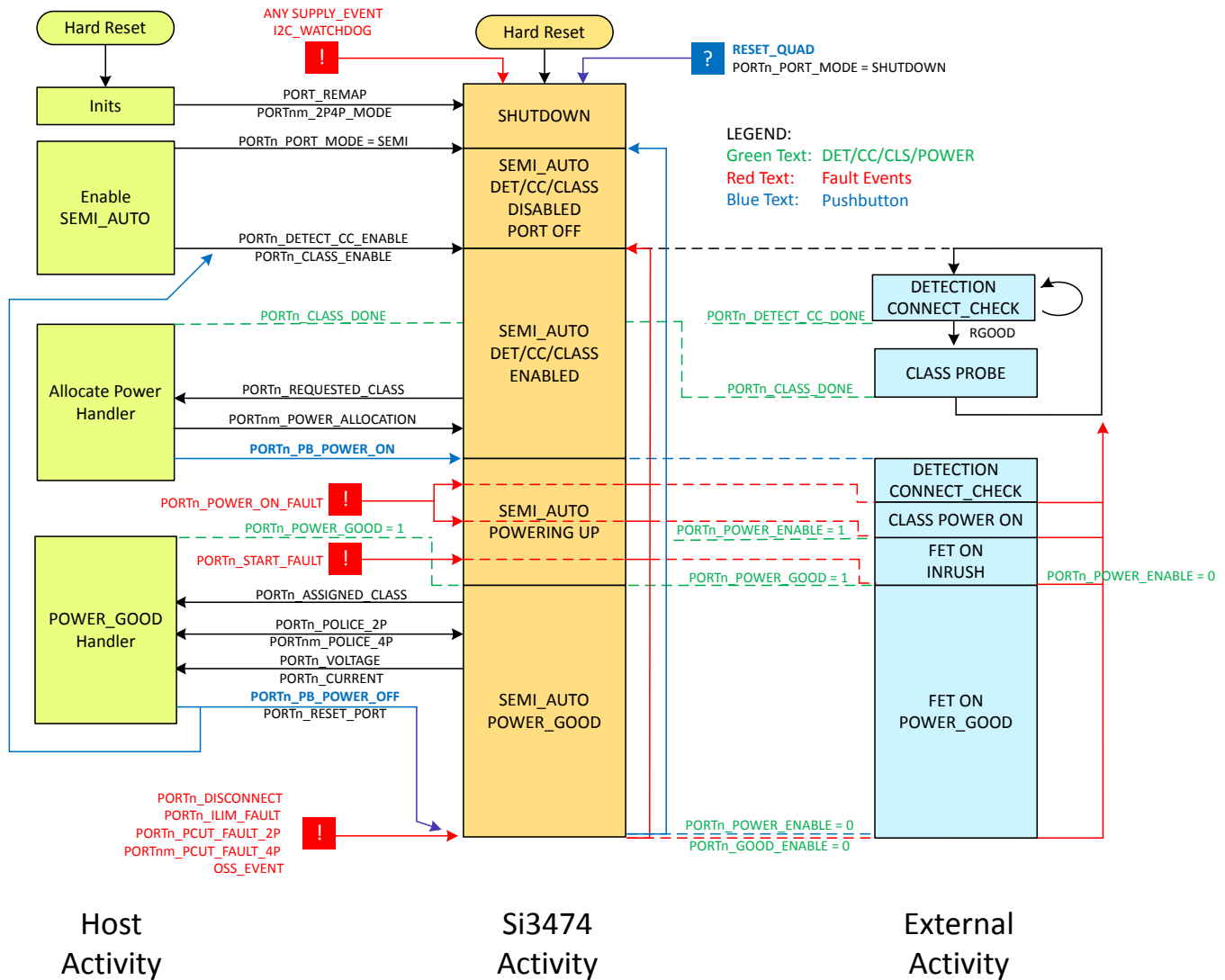


Figure 2.2. Semi-Auto System State Diagram

2.5 Reset and Initialization

Hard resets are invoked by either cycling power (Power on Reset or PoR) and/or deasserting RESEtb input. After a hard reset, all registers are set to default values. A PoR will always set all registers to default values. Invoking a hard reset by deasserting the RESEtb input will set all registers to default values except the upper nibble of SUPPLY_EVENT to default values. The upper nibble is sticky until the condition that is causing the global event is cleared. For specific information, refer to 4.8 SUPPLY_EVENT and SUPPLY_EVENT CoR (0x0A, 0x0B).

Immediately after a hard reset, the host must initialize at least two registers, the PORT_REMAP register and the PORTnm_2P4P_MODE field in POWER_ALLOCATION register. These registers must be set to match the hardware configuration, ex. how the ports are wired, of the PSE system. For specifics, refer 4.24 PORT_REMAP (0x26) and 4.26 POWER_ALLOCATION (0x29). These two registers once written to, are locked until a hard reset of the Si3474 to unlock them again.

During the initialization, the host can set other global registers as needed.

2.6 Semi-Auto Detection, Connection Check, and Class Probe

The host instructs the Si3474 to start detecting attached PDs by setting:

- `PORTn_PORT_MODE = SEMI_AUTO`
- `PORTn_DETECT_CC_ENABLE` and `PORTn_CLASS_ENABLE` in `DETECT_CLASS_ENABLE`

Prior to driving the detection waveform, the Si3474 performs a check that the port's external FET is properly off and is not damaged. The first test is a current measurement across the external sense resistor and the second test is a voltage measurement at the DRAINx pin. If excessive current detected or an unexpected drain voltage, `PORTn_DETECTION_STATUS` will indicate a `MOSFET_FAULT` and detection is aborted.

The Si3474 detects a PD by making a differential resistance measurement by driving 4 V to 8 V and back to 4 V on each enabled port through the DRAINx pin, while measuring current at each step. The results are used to calculate measured detection resistance, also known as the PD Signature Resistance, which is nominally 25 k Ω . The Si3474 reports the detection results in the `PORTn_DETECTION_STATUS` field of the `PORTn_DETECT_CLASS_STATUS` registers.

During detection the Si3474 monitors the voltage driven for evidence of a contention with another PSE driving the same line. If the measured voltage deviates significantly from the driven voltage, `PORTn_DETECTION_STATUS` will report a PSE to PSE fault. The Si3474 also uses the voltage/current measurements taken during the detection waveform to determine if the PD Signature Resistance measures too capacitive and reports in the `PORTn_DETECTION_STATUS`.

If the port is configured as a 2P port, a `DETECT_CC_DONE` event will be reported to the host after the detection sequence. If the detection result is `RGOOD`, the Si3474 begins a class probe to determine the PD's class signature. A class probe will always consist of three class fingers to determine the PD requested power followed by a class reset. The following figure shows the expected waveform for a 2-Pair powered PD.

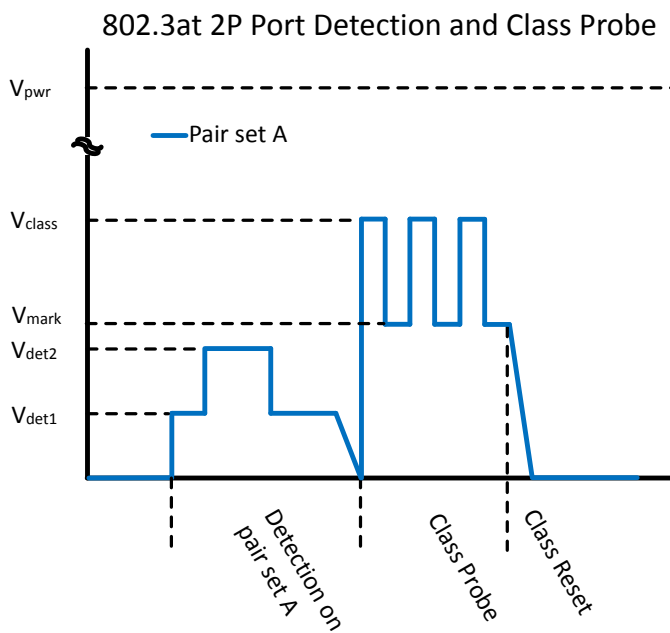


Figure 2.3. Semi-Auto DET/CLASS 2-Pair Waveform

The sequence changes if the port is configured to be a 4P port. After one of the two ports that comprise a 4P port detects a valid PD detection signature, a connection check (CC) is performed to determine if the attached PD is a single-signature PD or a dual signature PD. If the connection check indicates a single-signature PD, then Si3474 indicates a `DETECT_CC_DONE` and continues onto class probe on the primary pairset that detected the valid PD detection signature. The following figure shows the expected waveform for a 4-Pair powered single signature PD.

802.3bt Single Signature 4P Port Detection, Connection Check and Class Probe

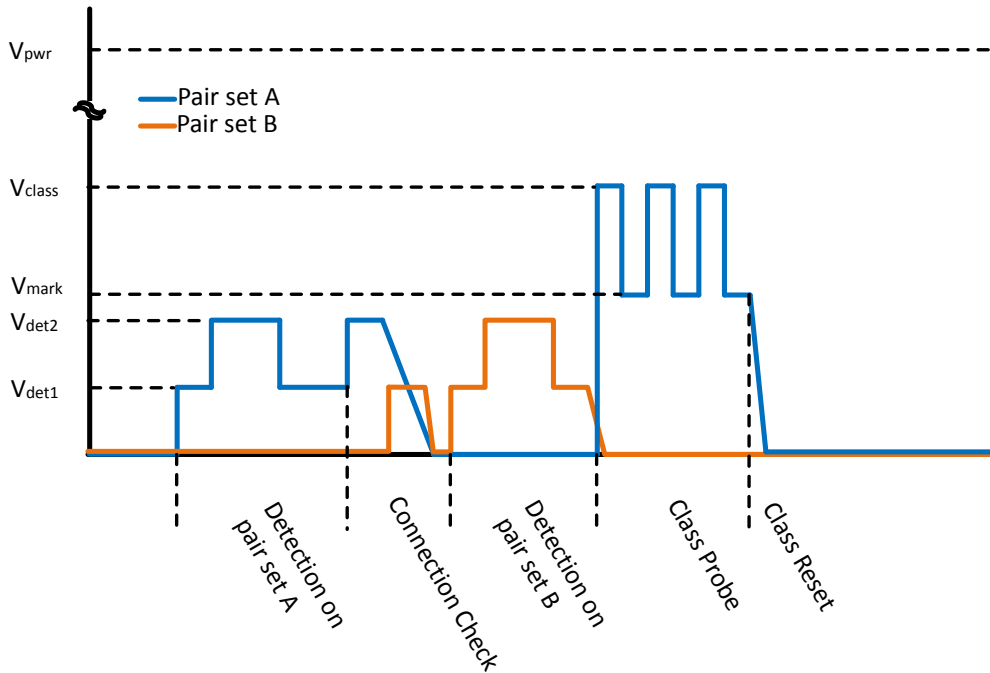


Figure 2.4. Semi-Auto DET/CC/CLASS 4-Pair Single-Signature Waveform

If the connection check indicates a dual-signature PD, the Si3474 detects and class probes on both the primary and secondary pairsets. The following figure shows the expected waveform for a 4-Pair powered dual-signature PD.

802.3bt Dual Signature 4P Port Detection, Connection Check and Class Probe

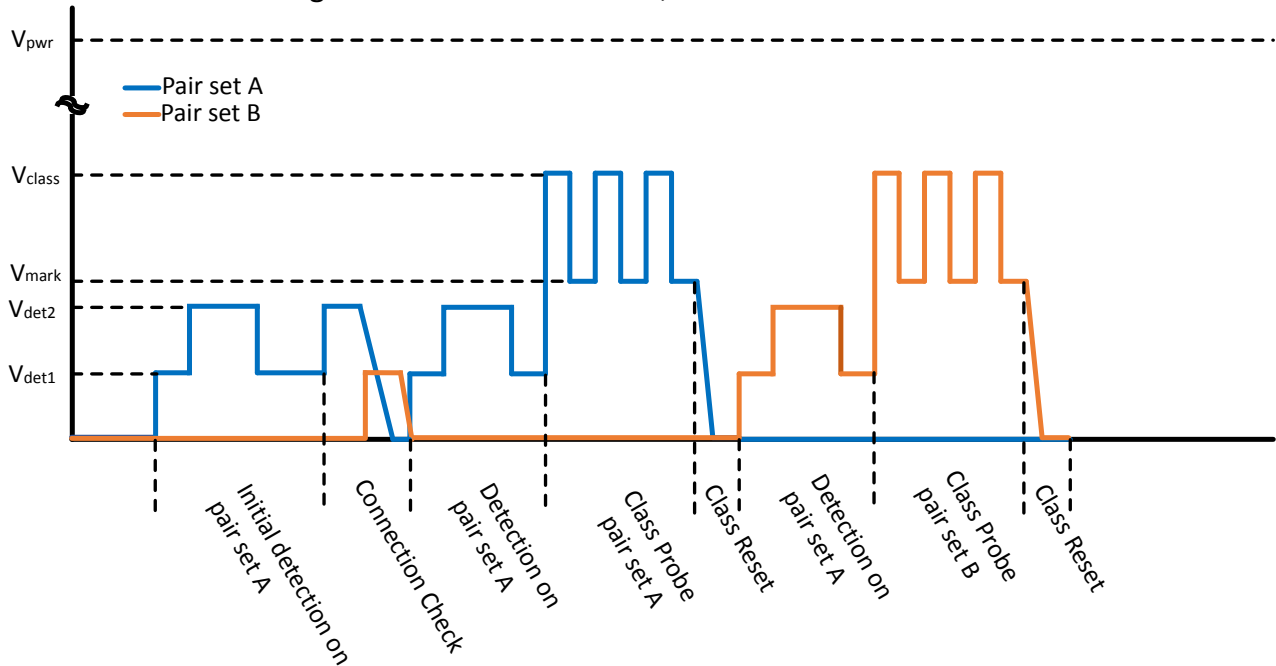


Figure 2.5. Semi-Auto DET/CC/CLASS 4-Pair Dual-Signature Waveform

Upon class probe completion, the Si3474 will report a `PORTn_CLASS_DONE` event and place the requested power in the `PORTn_CLASS_STATUS` field of the `PORTn_DETECT_CLASS_STATUS` register and in the `PORTn_REQUESTED_CLASS` field in the `PORTn_CLASS_RESULTS` register.

2.7 Powering Up

A port is ready to be powered on after the PORTn_CLASS_DONE event is reported. The host can examine the results of the PORTn_CLASS_STATUS to discover the PD's requested class. The host can then set or adjust the PORTnm_POWER_ALLOCATION as needed, followed by setting the PORTn_PB_POWER_ON for the port.

The Si3474 goes through the sequence of events described in the following subsections.

2.7.1 Power Demotion

Upon powering on a port, the host knows how much power the PD has requested by reading the PD's requested class. If the host determines that it has the requested power available, it will typically set PORTnm_POWER_ALLOCATION so that the PD receives the power it has requested. If the host knows it does not have the full power available, it can choose to set the PORTnm_POWER_ALLOCATION such that the assigned class will be less than the requested class; this is known as Power Demotion.

A power-demoted PD can request more power at any time through the Ethernet Link-Layer protocol (LLDP). Through LLDP, if the PD requests additional power (and if the PSE has more power to spare at that time), it can then grant the additional power. The host communicates the allowable additional power to the Si3474 by updating the PORTn_POLICE_2P or PORTnm_POLICE_4P registers without needing to put the port in SHUTDOWN and perform another PORTn_PB_POWER_ON sequence.

When putting a PD in Power Demotion, there are some considerations. There is a risk of encountering a PORTn_POWER_ON_FAULT "Insufficient Power Allocation" in a dual-signature 4P Port if one pair-set consumes all of the power in a way that prevents supplying additional power to the other pair-set. The other nuance is that, when a Class 4 to Class 8 PD is only provided Class 3 power, the PSE can only send one classification finger to the PD. In this case, the Si3474 will supply Class 3 power and communicate report "Class 4+ Type 1 Limited" in PORTn_CLASS_STATUS. PORTn_ASSIGNED_CLASS will show Class 3, and the PORTn_REQUESTED_CLASS shows the result of the Class Probe, which will show Class 4 to Class 8.

2.7.2 Final Detection, Connection Check, and Class Probe

When PORTn_PB_POWER_ON is received by the Si3474, it is likely that it is performing a DET/CC/CLASS PD discovery sequence that is unrelated to the port receiving the PB_POWER_ON pushbutton. The Si3474 allows those started sequences to complete before executing the Pushbutton command for the specified port. PB_POWER_ON consists of a final set of Detection, Connection Check (for 4P Ports), and Class Power On for the ports that the host wants to power on.

The PB_POWER_ON detection sequence is similar to that performed by Semi-Auto Detection, Connection Check and Class Probe, with some slight differences. If the detection results are anything other than RGOOD for the ports being powered up, the PORTn_POWER_ON_FAULT event is set to *Invalid Detection*. If the PB_POWER_ON is issued to a 4P Port, a connection check will be performed the same way. The Si3474 then performs another Class Probe to reconfirm the PD's requested class followed by a Class Reset.

2.7.3 Class Power On

Unlike Class Probe, Class Power On intends to power on the PD afterwards. The other important factor to consider is that, with Class Power On, the number of classification fingers is significant as the PD will count them so as to learn what power it has been allocated by the Si3474. For example, a Class 4 PD learns it has been power demoted and is allocated only 15.5 W of power if the PSE presents a single classification finger. But, a Class 4 PD learns it may draw the full 30 W if the PSE presents it with two fingers during the Class Power On.

If, during Class Power On, an overcurrent or an invalid classification occurs, the `PORTn_POWER_ON_FAULT` event is set to *Classification Error*. Another error that will trigger a `PORTn_POWER_ON_FAULT` event is *Insufficient power allocation*. This can occur when a one pair-set of a dual-signature PD consumes the remaining power allocation and, therefore, there is no power available for the other pair-set. *Insufficient power allocation* is also reported if the host issues a `PB_POWER_ON` to only one pair-set of a Single Signature port and the attached PD requested Class 5 or higher power.

Class Power On results are stored in `PORTn_ASSIGNED_CLASS`. However, `PORTn_CLASS_STATUS` can contain additional information. In the case of a Power Demotion where a Class 4 or higher PD is demoted to Class 3, `PORTn_CLASS_STATUS` will report *Class 4+ Type 1 Limited*, whereas the `PORTn_ASSIGNED_CLASS` will report Class 3. Refer to [Table 4.2 Classification Event Timing on page 67](#) in [4.36 CLASS_RESULTS \(0x4C – 0x4F\)](#) for a comprehensive list of class codes and when they are updated.

The Si3474 sends out a long class pulse on the first finger during Class Power On for two purposes. First, a long first classification finger communicates to the PD that the Si3474 supports Short Maintain Power Signature (MPS) to save more power when in standby. Second, with the initial long class pulse, it is possible to detect if the PD supports Autoclass. Refer to [2.8.4 Autoclass](#) for details.

After Class Power On has completed, the FET is turned on, and the Inrush period begins. The following figure show the entire expected waveforms for a `PORTn_PB_POWER_ON` for 2P, 4P Single Signature, and 4P Dual Signature PDs.

802.3at 2P Port Detection, Class Probe, Class Power On and Power Up

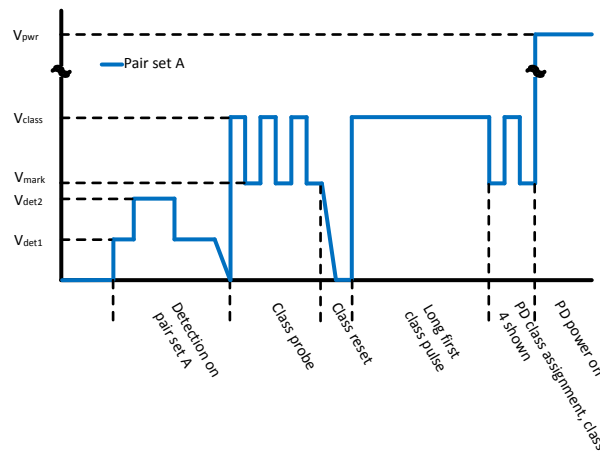


Figure 2.6. 2P Port Detection Waveform

802.3bt Single Signature 4P Port Detection, Connection Check, Class Probe, Class Power On and Power Up

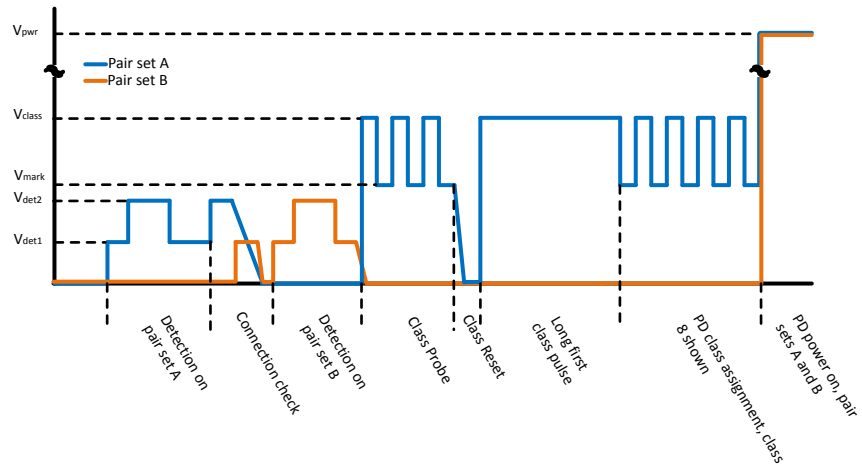


Figure 2.7. 4P Single-Signature Port Detection Waveform

802.3bt Dual Signature 4P Port Detection, Connection Check, Class Probe, Class Power On and Power Up

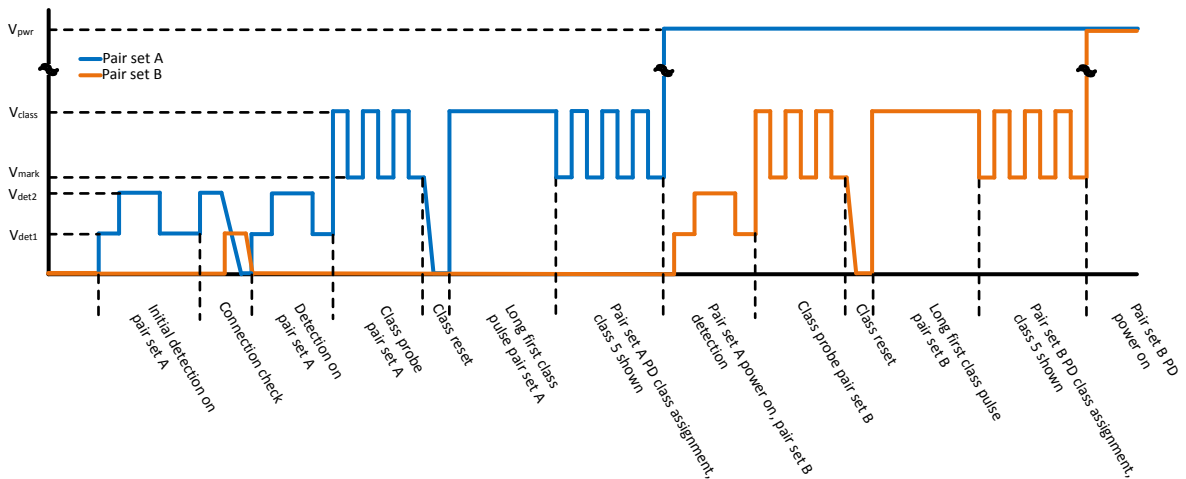


Figure 2.8. 4P Dual-Signature Port Detection Waveform

2.8 Powered States

There are two states for which the FET is ON:

1. Inrush Period
2. Power Good State

2.8.1 FET On Status

Each pair set has the PORTn_POWER_ENABLE and PORTn_POWER_GOOD status information suitable for tracking the general state of the Si3474 after a PORTn_PB_POWER_ON.

| PORTn_POWER_ENABLE | PORTn_POWER_GOOD | FET State | After PORTn_PB_POWER_ON |
|--------------------|------------------|-----------|---|
| 0 | 0 | OFF | Final Detection Connection Check Class Probe Class Power |
| 1 | 0 | ON | Inrush Period |
| 1 | 1 | ON | Power Good |
| 0 | 1 | — | Invalid |

The corresponding events PORTn_POWER_ENABLE_CHANGE and PORT_POWER_GOOD_CHANGE events in the POWER_EVENT register track the changes in the POWER_ENABLE and the POWER_GOOD fields in the POWER_STATUS register.

Changes to PORTn_POWER_GOOD and PORTn_POWER_ENABLE affects the corresponding events PORTn_POWER_GOOD_CHANGE and PORTn_POWER_ENABLE_CHANGE. These events can be used by the host to check the POWER_STATUS register to check the most up-to-date port status.

PORTn_POWER_GOOD and PORTn_POWER_ENABLE elicit changes to the PORTn_POWER_GOOD_CHANGE and PORTn_POWER_ENABLE_CHANGE event bits. Once set, the PORTn_POWER_GOOD_CHANGE and PORTn_POWER_ENABLE_CHANGE bits are typically cleared by reading the POWER_CHANGE CoR register. In addition, PORTn_POWER_GOOD_CHANGE and PORTn_POWER_ENABLE_CHANGE events are cleared when PORTn_RESET_PORT is set, PORTn_PB_POWER_OFF is set, and when a port is turned off as a result of an OSS Event.

2.8.2 Inrush Period

Immediately after the FET is turned on, the Si3474 enters the Inrush Period. The Inrush Period is a fixed time period defined by t_{INRUSH} . During the Inrush Period, the Si3474 performs a voltage-foldback function for currents higher than 425 mA in order to limit the current drawn from the VPWR rail. The Si3474 also has a proprietary short-circuit FET protection circuit intended to protect the FET from damage.

The terms “start” and “inrush” are used interchangeably in this document. The Inrush Period is the initial part of a power-on in which the PSE is expected to supply current to the PD’s bulk capacitors. As is normal with any capacitor, if permitted, it will consume as much current as the PSE can supply. During the Inrush Period, a port implements a 425 mA current limit, with a 30 V Foldback, during a t_{START} or t_{INRUSH} time period.

After t_{INRUSH} , the port should no longer be in a current-limited state. If the port is still in a current-limited state, the port is powered off, and the PORTn_START_FAULT event is raised. Otherwise, the port reaches a POWER_GOOD state, and the Si3474 begins monitoring the port.

See [2.8.5 Current Limit and Voltage Foldback](#) for an illustration of how current limiting and voltage foldback work.

2.8.3 Power Good State

When a port is in a POWER_GOOD state, three things are monitored:

1. Disconnection
2. ILIM / Current Limit
3. PCUT / Power Overload

Of these three things monitored, the Disconnection monitoring is to check if the PD is drawing too little current.

For the next two items, the Si3474 is monitoring for “too much current”. The difference between these two over-current monitors is the speed of the action taken.

For ILIM / Current Limit events are considered to be fast, high current events. As such, Si3474 circuits aim to limit the current by reducing port voltage. Under extremely high current conditions, the Si3474 shuts off the port completely to protect the FET from damage.

On the other hand, a PCUT does not involve FETs operating in current-limited state. But rather, the Si3474 is monitoring the port voltage and port current, then comparing them against the POLICE register limits.

2.8.3.1 Disconnection

While in the POWER_GOOD state, the Si3474 checks whether or not the PD is still connected to the port. A connected PD is obligated to draw a minimum amount of current. To keep the PSE from declaring a disconnection, the PD must meet a “Maintain Power Signature” for time duration of t_{MPDO} . If the PD does not meet these MPS requirements, the PSE may choose to power down the port.

When the Si3474 determines that the PD is no longer present, it sets the PORT_n_DISCONNECTION event.

2.8.3.2 ILIM / Current Limit

Depending on the PD Class, the Si3474 chooses a current-limit template designed to allow normal PD currents to flow, while also setting a peak current threshold to begin a voltage foldback. Ostensibly, the Si3474 implements a number of current limit templates. The current limit template is a 2-dimensional function that defines a current limit against the drain voltage. At low drain voltages, the current limit is set at its maximum.

Whenever the measured port current exceeds these current limits, a feedback circuit then adjusts the gate voltage of the FET to fold-back the voltage. The speed at which the gate voltage is adjusted is a function of the difference between the current limit threshold at the drain voltage against the sensed port current.

The foldback mechanism is done automatically, while the drain voltage is monitored to check for evidence of a current-limited state. The device implements a counter that counts up by 1 whenever the FET is in an over-current state. For every subsequent non-overcurrent event is encountered, the counter is then decreased by 1/16. This allows current limited events to self-clear if it is a transient event. This prevents nuisance disconnections while also allowing disconnecting a port based on the severity of the event.

As a simple example, if the device continuously detects overcurrent for time t_{LIM} time periods, it will be considered an ILIM fault and remove power from the port.

In addition to the programmable current-limit foldback voltage templates, the Si3474 also implements a separate short circuit monitor so that if the difference between the measured current and the current limit is very large, the FET is turned off. In a certain sense, turning off a FET is a form of “extreme foldback”. This is implemented this way as it intends to protect the FET in the case of an unexpected short-circuit.

Current Limit faults are reported through the PORT_n_ILIM_FAULT in the ILIM_START_FAULT register.

[2.8.5 Current Limit and Voltage Foldback](#) shows an illustration of how current limiting and voltage foldback works.

2.8.3.3 PCUT Faults

After the Class Power On, both the PSE and PD would have a mutual understanding of the power that the PSE is obligated to supply, as well as an understanding by the PD on how much power it is entitled to receive. Once the Port has reached a POWER_GOOD state, the Si3474 enforces this mutual power agreement through the various police registers.

The power values represented in the various police registers represents the power level consistent with what the PSE is obligated to supply, at the very minimum. Based on these values, the actual police limits internal to the Si3474 are slightly higher, to err on the side of supplying power to the PD.

There are generally two kinds of police registers PORTn_POLICE_2P and PORTnm_POLICE_4P.

The PORTn_POLICE_2P defines the power limits for each pair set, independently of each other. PORTnm_POLICE_4P is used also for 4P Ports. The PORTnm_POLICE_4P takes the total power of the two pair sets forming the 4P Port and compares against the power thresholds implied by the PORTnm_POLICE_4P.

At the completion of the Class Power On, the Assigned Class is determined based on the value of PORTnm_POWER_ALLOCATION, PORTnm_2P4P_MODE, PORTnm_CONNECTION_CHECK_RESULTS and the PORTn_REQUESTED_CLASS. For each pair set, the PORTn_ASSIGNED_CLASS is converted into a minimum power threshold and is stored in the applicable PORTn_POLICE_2P. For 4P Ports, there are two PORTn_POLICE_2P registers that are initialized, and in addition, the PORTnm_POLICE_4P.

For Single Signature 4P Ports, Autoclass can be enabled in the Si3474, and if the PD also supports Autoclass, then the PD will draw its expected maximum power during the first two to three seconds of being powered, allowing the Si3474 to know exactly how much power the PD would use. As such, the various police registers are initialized based on the Autoclass results, rather than using the Assigned Classification. Autoclass is discussed separately in [2.8.4 Autoclass](#).

In summary, the Si3474, upon reaching the POWER_GOOD state will have an initialized police register set. These police registers are the basis of checking for PCUT events. The Si3474 implements an algorithm that monitors compliance against the police registers.

After the initialization of the police registers, the host can make adjustments to the various police registers once it has more accurately determined the actual usage either through long term checking of the pertinent PORTn_VOLTAGE and PORTn_CURRENT, or through LLDP link-layer messaging.

PCUT faults are reported in PORTn_PCUT_FAULT_2P if the fault is associated with the PORTn_POLICE_2P. PORTnm_PCUT_FAULT_4P events are reported in the case where the PCUT faults are associated with PORTnm_POLICE_4P.

2.8.4 Autoclass

Autoclass is a protocol that only affects Single Signature 4P Ports. When automatic Autoclass is enabled, the Si3474 monitors the first long class finger of the Class Power On to detect if the PD is Autoclass-capable. If the Si3474 detects the PD acknowledgement, the PORTn_AUTOCLASS_DETECTED bit is set on that pair set. The Si3474 then takes voltage and current measurements when the pair sets reach POWER_GOOD state. Both the two PORTn_POLICE_2P registers and the PORTnm_POLICE_4P registers will be initialized based on measured power plus margin. If PORTn_AUTO_AUTOCLASS is set, the corresponding PORTn_POLICE_2P and/or PORTnm_POLICE_4P are updated using the information in PORTn_AUTOCLASS_POWER information, plus some power margin.

The host may also initiate a Manual Autoclass by setting PORTn_MANUAL_AUTOCLASS (both pair sets must be set) in the AUTOCLASS_CONTROL register. The manual autoclass feature is typically used in conjunction with the LLDP-initiated autoclass procedure. As such, the host is expected to initiate a Manual Autoclass when the PD is drawing its maximum power. The Si3474 stores the computed Autoclass power results in the PORTn_AUTOCLASS_POWER (one for each pair set). Once the results are written into PORTn_AUTOCLASS_POWER fields, the Si3474 clears the PORTn_MANUAL_AUTOCLASS bits. When both PORTn_MANUAL_AUTOCLASS bits are cleared, the host can use this as an indication that the information is ready. The host may then overwrite the results of the police registers based on the power information supplied by the two PORTn_AUTOCLASS_POWER registers.

2.8.5 Current Limit and Voltage Foldback

The figure below illustrates how current limiting works. Consider an initial condition where the FET is ON, with the PD appearing like 167 Ω load. Let's say that suddenly, the load changes from 167 Ω to 62.5 Ω. The initial point condition is below the Green Line, which represents an ILIM Threshold vs VDRAIN template that the Si3474 is maintaining. Any difference between the actual current and this threshold results in whether or not current is flowing into the gate of the FET, or if it is flowing into the gate. The magnitude of the gate current is proportional to the difference between where the actual current through the sense resistor, relative to the set point.

When the load initially changes from 167 Ω to 62.5 Ω, the sensed current is higher than the ILIM Threshold at that VDRAIN voltage, and as such, the current is removed from the gate, leading to the FET shutting down slightly, leading to the VDRAIN increasing.

Eventually, the VDRAIN will increase high enough so that it meets the 62.5 Ω, where the gate drive becomes zero since the sensed current is at the green line. In this example, when the PD Load decreases from 167 Ω to 62.5 Ω, the port voltage folds back from 50 V down to around 22 V.

Note that the example does not show the intermediate steps, only the starting points and end points. This is a feedback circuit and this illustration cannot show the speed by which the VDRAIN increases is in proportion to the magnitude difference between the sensed current and the ILIM curve.

Some things to note include:

1. The FET power in the current limited state is $28\text{ V} \times 350\text{ mA} = 9.8\text{ W}$. To prevent damage, the Si3474 limits the time the FET spends in this condition.
2. The DRAIN Voltage is high. The Si3474 can measure this, and magnitude of the DRAIN Voltage, when taking the ILIM Template into account, is a good clue of the power level being experienced by the FET.

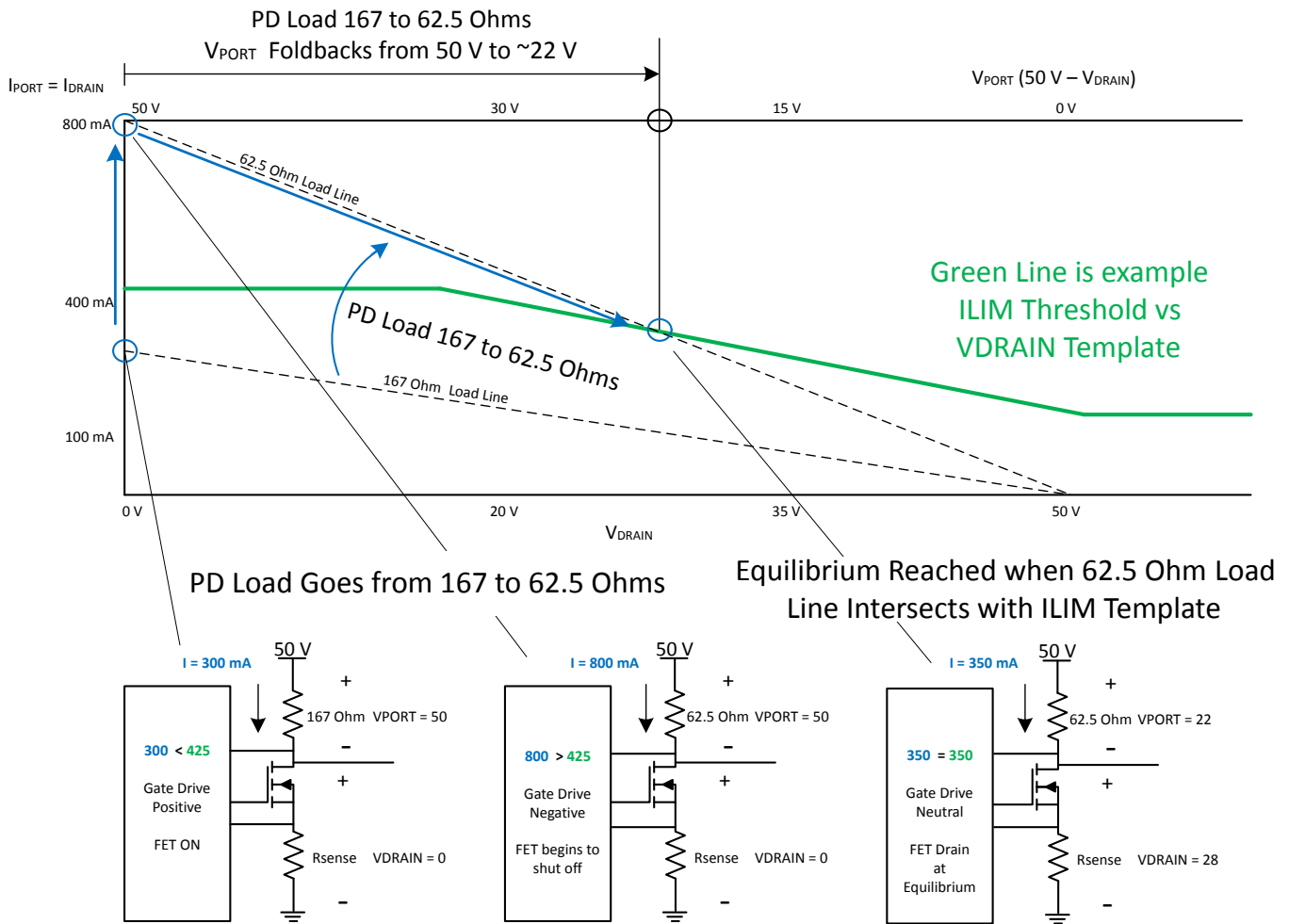


Figure 2.9. Current Limiting and Voltage Feedback

2.9 Event Handling

The host can communicate with the Si3474 at any time since the host is an I²C Master. For the Si3474 to communicate vital information to the host, it can only do so by asserting the INTb pin, and wait for the host to service the Si3474. However, it is not known when the host will service the Si3474. Therefore, there needs to be a way to have a way of communicating information without losing any of it if the host does not service the Si3474 immediately.

When the Si3474 wants attention from the host, it does so by setting an event in the event register map. The event bits map into a corresponding bit in the INTERRUPT register. If the corresponding INTERRUPT_MASK bit is also set, then this will cause INTb to assert.

Whenever the host receives an interrupt, the host should first read the INTERRUPT register from every I²C address. If there is a bit set, the host should then check the fields associated with that interrupt.

Refer to the figure below. The events are color-coded to have the same color as the associated bits in the INTERRUPT register. For example, when the host reads INTERRUPT, it sees the DISCONNECT_BIT set only. Note the color coding of DISCONNECT. The DISCONNECTION field and the OSS_EVENT fields are of the same color. In this case, the host would know to read DISCONNECT_Pcut_FAULT register SUPPLY_EVENT register as those are where the DISCONNECTION field and OSS_EVENT fields are located at.

Once the DISCONNECT_Pcut_FAULT_COR (0x07) and SUPPLY_EVENT_COR (0x0B) are read, the Si3474 will clear the DISCONNECT_BIT in the INTERRUPT register. If the DISCONNECT_BIT is the only bit that is set, then the INTb pin will negate.

It is important to note that each Si3474 contains two Quads. So, INTb will assert whenever there is an unserved interrupt in either Quad.

It is also important to note that if the host reads all the COR registers, it is not a guarantee that the INTb would negate. The reason being that a new event may have occurred after the COR register was read to clear the event. The host should take care to only service the events that it reads from the COR register as this is how the Si3474 knows that the host has picked up the event and had cleared it by reading the COR register.

It is important to note that PORTn_POWER_ON_FAULT is slightly different from the other event registers. When a PORTn_POWER_ON_FAULT event is reported, the corresponding PORTn_START_FAULT is also set. To service a PORTn_POWER_ON_FAULT, both the ILIM_START_FAULT CoR register and the POWER_ON_FAULT CoR register must be read to clear the START_EVENT_BIT in the INTERRUPT Register.

| Address | Name | Access | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|-----------------------|--------|----------------------|---------------|----------------------|------------|----------------------|------------|----------------------|---------------------|
| INTERRUPT REGISTERS | | | | | | | | | | |
| 0x00 | INTERRUPT | RO | SUPPLY_EVENT | START_EVENT | P_I_FAULT | CLASS_DONE | DETECT_CC_DONE | DISCONNECT | POWER_GOOD_CHANGE | POWER_ENABLE_CHANGE |
| 0x01 | INTERRUPT_MASK | R/W | | | | | | | | |
| EVENT REGISTER BITS ASSOCIATED WITH INTERRUPT REGISTER | | | | | | | | | | |
| 0x02 | POWER_EVENT | RO | POWER_GOOD_CHANGE | | | | POWER_ENABLE_CHANGE | | | |
| 0x03 | | CoR | | | | | | | | |
| 0x04 | CLASS_DETECT_EVENT | RO | CLASS_DONE | | | | DETECT_CC_DONE | | | |
| 0x05 | | CoR | | | | | | | | |
| 0x06 | DISCONNECT_Pcut_FAULT | RO | DISCONNECTION | | | | PCUT_FAULT_2P | | | |
| 0x07 | | CoR | | | | | | | | |
| 0x08 | ILIM_START_FAULT | RO | ILIM_FAULT | | | | START_FAULT | | | |
| 0x09 | | CoR | | | | | | | | |
| 0x0A | SUPPLY_EVENT | RO | OVER_TEMP | VDD_UVLO_FAIL | VDD_UVLO_WARN | VPWR_UVLO | PORTnm_Pcut_FAULT_4P | | OSS_EVENT | -- |
| 0x0B | | CoR | | | | | | | | |
| 0x24 | POWER_ON_FAULT | RO | PORT4_POWER_ON_FAULT | | PORT3_POWER_ON_FAULT | | PORT2_POWER_ON_FAULT | | PORT1_POWER_ON_FAULT | |
| 0x25 | | CoR | | | | | | | | |

2.10 Autonomous Operation

If it can be assumed that the total PD load can be supplied by the system VPWR, then it is suitable to use one of the two autonomous operations.

The two autonomous modes will be described as "virtual register settings", so as to leverage much of the prior discussion with typical use case when using Semi Auto and Pushbutton Power On.

2.10.1 AUTO Pin Autonomous Mode

A voltage divider is needed on the AUTO pin. A 15 kΩ resistor is needed from VDD to the AUTO pin, and the following resistors can be populated from the AUTO pin to GND.

| Lower Resistor | 2P / 4P Port | Class | Power | Equivalent Register Setting POWER_ALLOCATION |
|----------------|-----------------------------------|----------------------------------|-------|---|
| None | Hosted I ² C Operation | | | |
| 124 kΩ | 2P | Class 3 | 15 W | 0x00 |
| 61.9 kΩ | 2P | Class 4 | 30 W | 0x33 |
| 35.7 kΩ | 4P | SS Class 4, DS Class 3 + Class 3 | 30 W | 0xBB |
| 22.6 kΩ | 4P | SS Class 5, DS Class 4 + Class 3 | 45 W | 0xCC |
| 15.8 kΩ | 4P | SS Class 6, DS Class 4 + Class 4 | 60 W | 0xDD |
| 11 kΩ | 4P | SS Class 7, DS Class 5 + Class 4 | 75 W | 0xEE |
| 7.68 kΩ | 4P | SS Class 8, DS Class 5 + Class 5 | 90 W | 0xFF |

The operation of AUTO Pin Autonomous Mode is identical to setting the following in both Quads:

1. PORT_REMAP = 0xE4 (no remapping)
2. POWER_ALLOCATION = AS_SHOWN_ABOVE
3. INTERRUPT_MASK = 0xE4 (faults enabled)
4. PORT_MODE = 0xFF (all ports in AUTO Mode)
5. PORT_DETECT_CLASS_ENABLE = 0xFF (all ports DETECT_CC_ENABLE = 1 and CLASS_ENABLE = 1)

2.10.2 I²C Autonomous Mode

When the PORTn_MODE is set to AUTO instead of SEMI_AUTO, as long as the PORTn_DETECT_CC_ENABLE and PORTn_CLASS_ENABLE is also set, then the operation is similar to SEMI_AUTO.

The main difference between SEMI_AUTO and AUTO is that when a PD successfully classifies, in SEMI_AUTO, the Si3474 keeps repeating Detection/Connection Check/Class Probe, whereas in AUTO Mode, the Si3474 acts as though it immediately received a PORTn_PB_POWER_ON, and proceeds with a Final Detection, Connection Check and Class Power On before powering up the port.

If a fault were to occur at any time, the Si3474 will go back into Continuous Detection / Connection Check / Class Probe and repeats the process over again. In summary, the Si3474 will simply "keep trying".

Placing the Si3474 in I²C Autonomous Mode requires the following register settings to both Quads:

1. PORT_REMAP = 0xE4 (no remapping)
2. POWER_ALLOCATION = This depends on your system
3. INTERRUPT_MASK = 0xE4 (faults enabled)
4. PORT_MODE = 0xFF (all ports in AUTO Mode)
5. PORT_DETECT_CLASS_ENABLE = 0xFF (all ports DETECT_CC_ENABLE = 1 and CLASS_ENABLE = 1)

The setting of the POWER_ALLOCATION consists of setting the PORTnm_2P4P_MODE as well as the PORTnm_POWER_ALLOCATION registers. Refer to [4.26 POWER_ALLOCATION \(0x29\)](#) for more details.

2.11 OSS Operation

2.11.1 Emergency Shutdown Feature

The Si3474 supports two kinds of Emergency Shutdown procedures, both of which are controlled by the host via the OSS pin (pin 36). If `MULTIBIT_PRIORITY_ENABLE = 0` (in MISC register), then [2.11.1.1 1-Bit Shutdown Priority](#) describes the Emergency Shutdown behavior. Otherwise, if `MULTIBIT_PRIORITY_ENABLE = 1` (in MISC register), then [2.11.1.2 Multi-Bit Shutdown Priority](#) describes the Emergency Shutdown behavior.

2.11.1.1 1-Bit Shutdown Priority

If `MULTIBIT_PRIORITY_ENABLE = 0`, then `PORTn_PORT_POWER_PRIORITY` bit in each port defines the port Shutdown priority. `PORTn_PORT_POWER_PRIORITY` bits are found in the `POWER_PRIORITY_PCUT_DISABLE` register. If `PORTn_PORT_POWER_PRIORITY` is set, then the associated port is tagged as a "Low Priority" ports. "High Priority" ports are unaffected by an OSS event.

A positive-going edge on pin 36 (OSS), will shut down powered lower priority ports. All powered lower priority ports will be shut down within 50 μ s. Refer to the `PORTn_PB_POWER_OFF` description for all event and register bits that are cleared. Since `PORTn_CLASS_ENABLE` and `PORTn_DETECT_CC_ENABLE` are among one of the many bits that are cleared, no detection, connection check, or classification activity will occur until the `PORTn_CLASS_ENABLE` and `PORTn_DETECT_CC_ENABLE` are set again. As such, all events and associated measurement data are cleared. For as long as OSS is asserted high, low priority ports cannot be powered on.

2.11.1.2 Multi-Bit Shutdown Priority

If `MULTIBIT_PRIORITY_ENABLE` is set, then `PORTn_MULTIBIT_PRIORITY` defines the port priority and OSS action.

The figure below shows the operation and timing diagram of the OSS pin in multi-bit mode.

- The priority of each port is defined by a 3-bit value in `PORTn_MULTIBIT_PRIORITY` for each port.
- A port whose priority setting is "000" has the highest priority; priority setting of "111" has the lowest priority.
- When the host system wants certain priority ports to be shut down, it will transmit the "Shutdown code" over the OSS pin.
- Ports whose port priority settings are greater than or equal to the received Shutdown code will be turned off.
- For example, a received OSS Shutdown code of "101" will shut down ports whose port priority settings are "101", "110" or "111".

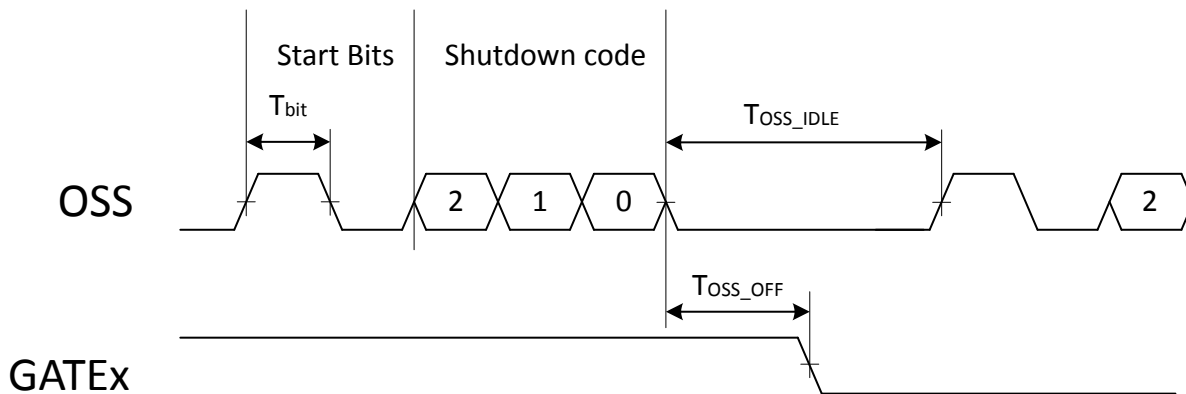


Figure 2.10. OSS Pin in Multi-Bit Mode

The following table describes the timing parameters associated with the OSS pin in multi-priority bit mode.

Table 2.1. Description of Timing Parameters Associated with the OSS Pin In Multi-Bit Mode

| Parameter | Description | Min | Typ | Max | Units |
|-----------------|---|-----|-----|-----|---------|
| T_{bit} | Bit Period | 24 | 25 | 26 | μ s |
| T_{OSS_OFF} | Maximum time between receiving Shutdown code and shutting down of the ports | — | — | 50 | μ s |
| T_{OSS_IDLE} | Idle time between consecutive Shutdown code transmission in multi-bit mode | 125 | — | — | μ s |

2.12 I²C Interface

2.12.1 I²C Protocol

Communicating with the Si3474 is accomplished through a 2-wire I²C compatible serial interface. An I²C transaction begins with a START condition and concludes with a STOP condition. Technically speaking, the interface to the Si3474 is better described as SMBus instead of I²C. SMBus transactions consist of I²C accesses in a manner that resembles a register map. The Si3474 registers are described in [Table 4.1 Si3474 Registers¹ on page 27](#). Note that the Register Map describes the operation of a quad (four ports). Each Si3474 has two quads. As such the Si3474 responds to two I²C Addresses, one for each quad.

2.12.1.1 Slave Address

The I²C Slave Addresses, for which the Si3474 responds to, are dependent on the following:

- A1, A2, A3 and A4 pin strapping
- Quad

As mentioned previously, each Si3474 responds to two I²C Addresses since there are two quads in each Si3474.

The 7-bit Slave Address is effectively constructed as this bit pattern:

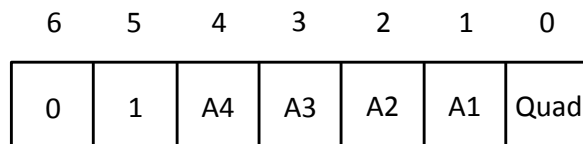


Figure 2.11. 7-bit I²C Address Bit Pattern

The following table outlines the I²C Addresses that the Si3474 will respond to, based on the A1, A2, A3 and A4 pin strapping as well as which quad the host intends to access:

Table 2.2. Si3474 I²C Slave Address

| A4 | A3 | A2 | A1 | Quad 0 I ² C Address | Quad 1 I ² C Address |
|----|----|----|----|---------------------------------|---------------------------------|
| 0 | 0 | 0 | 0 | 0x20 | 0x21 |
| 0 | 0 | 0 | 1 | 0x22 | 0x23 |
| 0 | 0 | 1 | 0 | 0x24 | 0x25 |
| 0 | 0 | 1 | 1 | 0x26 | 0x27 |
| 0 | 1 | 0 | 0 | 0x28 | 0x29 |
| 0 | 1 | 0 | 1 | 0x2A | 0x2B |
| 0 | 1 | 1 | 0 | 0x2C | 0x2D |
| 0 | 1 | 1 | 1 | 0x2E | 0x2F |
| 1 | 0 | 0 | 0 | 0x30 | 0x31 |
| 1 | 0 | 0 | 1 | 0x32 | 0x33 |
| 1 | 0 | 1 | 0 | 0x34 | 0x35 |
| 1 | 0 | 1 | 1 | 0x36 | 0x37 |
| 1 | 1 | 0 | 0 | 0x38 | 0x39 |
| 1 | 1 | 0 | 1 | 0x3A | 0x3B |
| 1 | 1 | 1 | 0 | 0x3C | 0x3D |
| 1 | 1 | 1 | 1 | 0x3E | 0x3F |

2.12.1.2 Available I²C Transfer Types

All Si3474 registers are accessible using 8-bit Writes and 8-bit Reads.

In addition, 16-bit Port Parametric Measurement Registers must be read using a 16-bit Read address in order to guarantee that the MSB and LSB of the Voltage or Current measurement belong to each other. The 16-bit Read Register Address should be pointing to the least significant byte so that the burst-read will end with the MSB.

Legend

- S Start Bit
- Sr Repeated Start Bit
- P Stop Bit
- A1...A4 Si3474 A1, A2, A3, A4 pin strapping
- Q Si3474 Quad Selection (virtual 'A0')
- R0...R7 Si3474 Register Address
- D0...D7 Si3474 Register Data LSB
- D8...D15 Si3474 Register Data MSB
- Wr Write Bit
- Rd Read Bit
- A ACK bit
- N No ACK bit

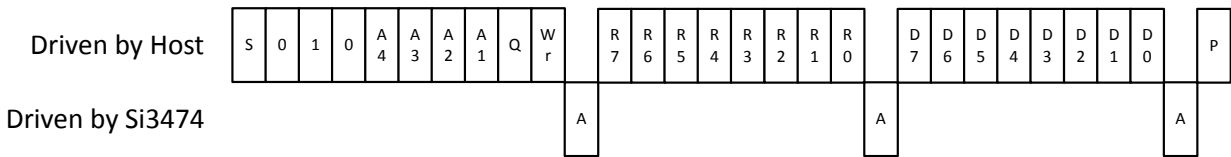


Figure 2.12. 8-Bit Write

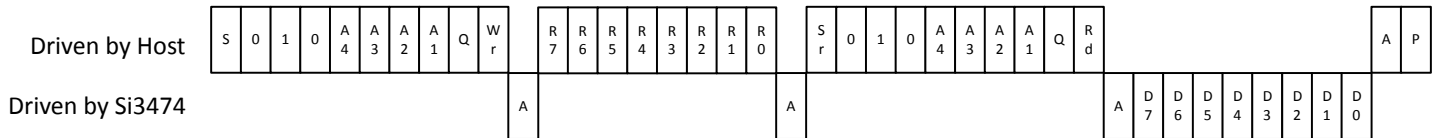


Figure 2.13. 8-Bit Read

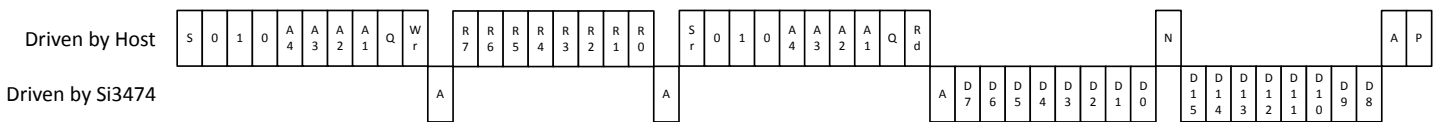


Figure 2.14. 16-Bit Read

2.13 Bootloader

2.13.1 Updating Si3474 Flash

The Si3474 Firmware can be updated through the I²C interface. The Si3474 firmware is roughly separated into the 'Application' firmware and a 'Bootloader' firmware. To ensure that the flash loading process never results in a non-communicating device, only the 'Application' part of the firmware is capable of being updated; the Bootloader cannot be updated.

The registers FLASH_CONTROL, FLASH_ERASE_KEY_FLASH_ADDRESS_LSB, FLASH_ADDRESS_MSB, FLASH_DATA work together to implement the flash update process. The figure above illustrates the flash loading sequence.

As a general rule, the flash update must always begin with checking the FIRMWARE_REVISION to see if a flash update is necessary or not. It is recommended to double-check that the Si3474 does not already have the latest firmware and that it does not need to be reflashed.

Once it has been determined that the device is to be updated, start the flash update procedure with a device reset.

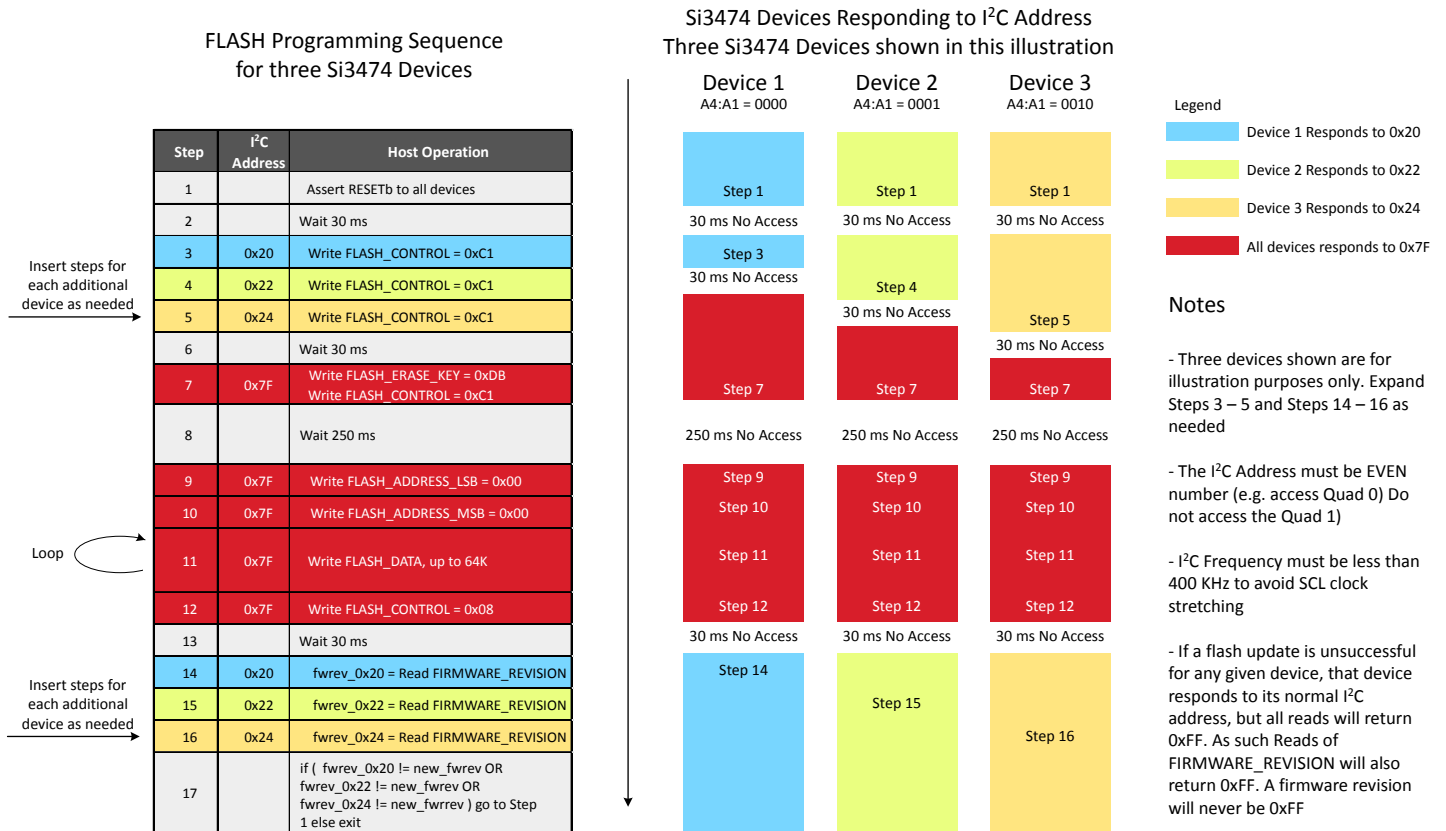


Figure 2.15. Flash Loading Sequence

The chip reset is illustrated in Step 1. After a RESET, wait 30 ms before starting communication, as the device is booting. After the 30 ms wait period, the devices should be able to communicate through I²C, via the standard I²C Address based on the A1-A4 pin strapping.

In Step 3, Step 4 and Step 5, the host will individually command each device to enter its bootload state (FLASH_CONTROL=0xC1). Note that the host must access each device individually through its normal I²C address. It is also important to note that the host must access only the Quad 0. Quad 0 of each device has an even I²C Address. After each device receives its FLASH_CONTROL=0xC1 command, each device will reset into a special state where the device will now respond to the Global Address 0x7F.

Once the host has send FLASH_CONTROL=0xC1 through each individual I²C Address it should delay an additional 30 ms in order to allow the last device to be ready. This 30 ms delay is illustrated in Step 6. After this final delay, the host can then proceed to Step 7, where the host would send another FLASH_CONTROL=0xC1 command. However, this time, the host will use the Global Address 0x7F. In addition, FLASH_ERASE_KEY=0xDB is sent prior to the FLASH_CONTROL=0xC1. This is illustrated on Step 7.

Upon receiving the FLASH_ERASE_KEY=0xDB and FLASH_CONTROL=0xC1 in Step 7, each device will begin to erase the Application FLASH area. This process takes 250 ms, and the host should not initiate communication during this time. This is illustrated on Step 8.

After the 250 ms delay, the host should then write 0x00 to both the FLASH_ADDRESS_LSB and FLASH_ADDRESS_MSB registers to indicate the starting address. This is illustrated in Steps 9 and 10.

The host then sends the contents of the new firmware by writing to the FLASH_DATA continuously. For accessing FLASH_DATA, in addition to the standard I²C Register Byte Write method, the Si3474 also supports burst writes in order to increase the throughput of the flash update. The burst write is illustrated in the figure below:

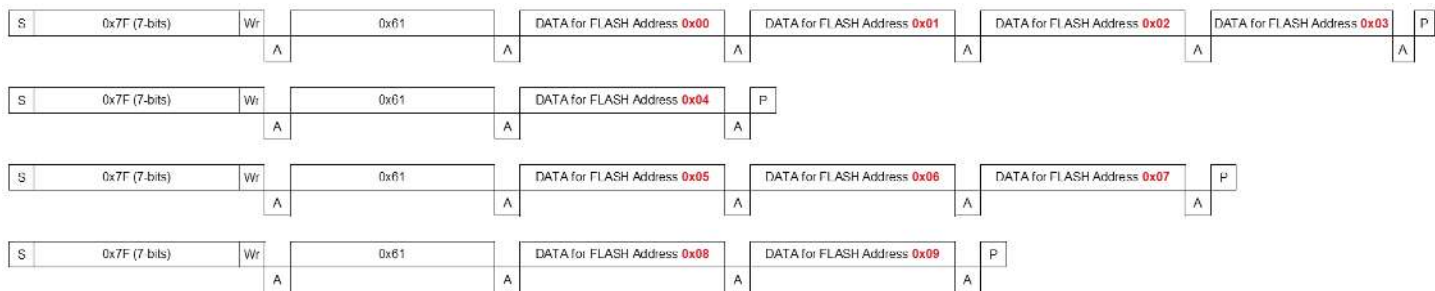


Figure 2.16. Burst Write

To complete the flash update, the host then writes FLASH_CONTROL=0x08 using the Global Address 0x7F. This is illustrated in Step 12. When each Si3474 device receives the FLASH_CONTROL=0x08 command, it completes the flash update process and computes the Flash CRC. Normally, the Si3474 reboots, and the FIRMWARE_REVISION Register can be checked using the normal non-global addresses to make sure that the firmware revision has been updated.

As previously mentioned, there is a separate Bootloader from the 'Application' firmware. As such, the Bootloader doesn't know what the FIRMWARE_REVISION is, that's why the check for the proper firmware revision needs to be done using the normal, non-global I²C Addresses.

If in the event something goes wrong with the flash update, the host will receive a response of 0xFF response to a FIRMWARE_REVISION read. The host will receive 0xFF for all registers if the firmware update procedure fails. If this happens, the host should simply restart the entire process from the very beginning.

3. Typical Application Example

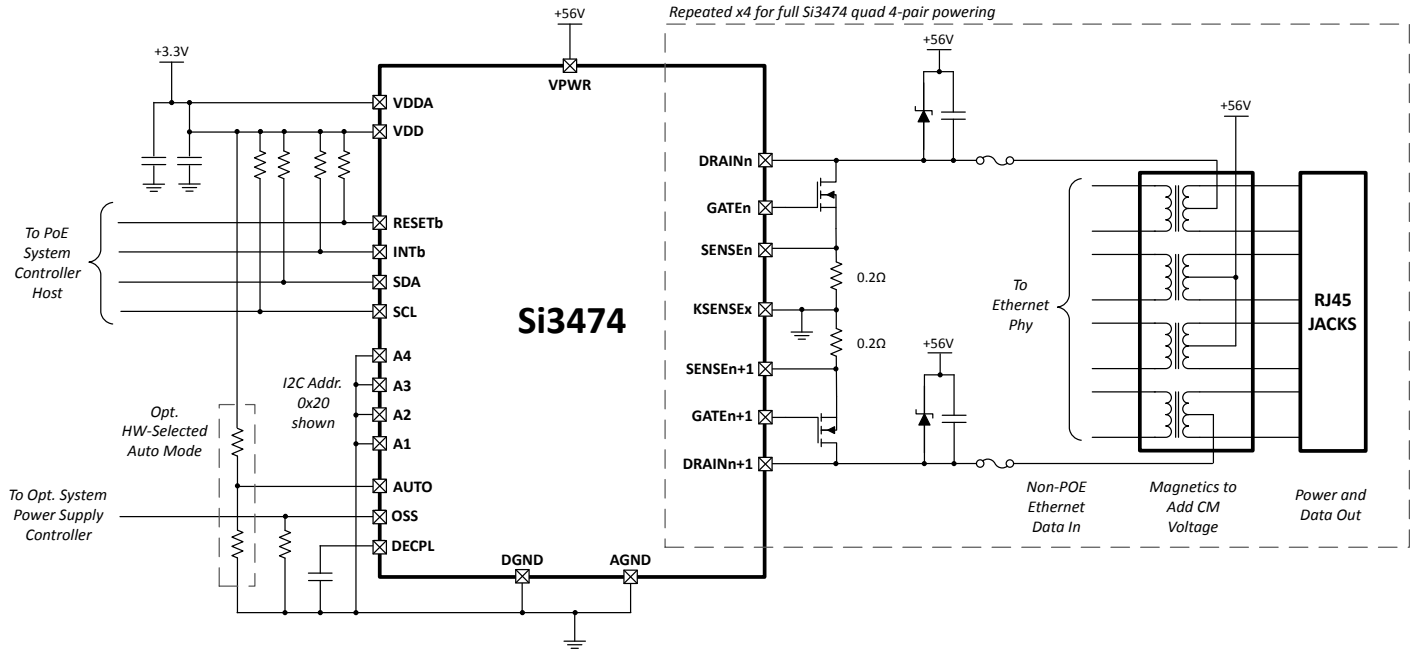


Figure 3.1. Si3474 Typical Application Circuit

4. Register Map

Table 4.1. Si3474 Registers¹

| Addr | Name | Access | Reset State | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------------------------|---------------------------|--------|-------------|----------------------|---------------|---------------|------------|----------------------|------------|-------------------|---------------------|
| Interrupt Registers | | | | | | | | | | | |
| 0x00 | INTERRUPT | RO | 1000 0000 | SUPPLY_EVENT | START_EVENT | P_IL_FAULT | CLASS_DONE | DETECT_CC_DONE | DISCONNECT | POWER_GOOD_CHANGE | POWER_ENABLE_CHANGE |
| 0x01 | INTERRUPT_MASK | R/W | 1000 0000 | | | | | | | | |
| Event Registers | | | | | | | | | | | |
| 0x02 | POWER_EVENT | RO | 0000 0000 | POWER_GOOD_CHANGE | | | | | | | |
| 0x03 | | CoR | | | | | | | | | |
| 0x04 | CLASS_DETECT_EVENT | RO | 0000 0000 | CLASS_DONE | | | | | | | |
| 0x05 | | CoR | | | | | | | | | |
| 0x06 | DISCONNECT_PCUT_FAULT | RO | 0000 0000 | DISCONNECTION | | | | | | | |
| 0x07 | | CoR | | | | | | | | | |
| 0x08 | ILIM_START_FAULT | RO | 0000 0000 | ILIM_FAULT | | | | | | | |
| 0x09 | | CoR | | | | | | | | | |
| 0x0A | SUPPLY_EVENT | RO | 0??? 0000 | OVER_TEMP | VDD_UVLO_FAIL | VDD_UVLO_WARN | VPWR_UVLO | PORTnm_PCUT_FAULT_4P | OSS_EVENT | — | |
| 0x0B | | CoR | | | | | | | | | |
| 0x24 | POWER_ON_FAULT | RO | 0000 0000 | PORT4_POWER_ON_FAULT | | | | | | | |
| 0x25 | | CoR | | | | | | | | | |
| Main Status Registers | | | | | | | | | | | |
| 0x0C | PORT1_CLASS_DETECT_STATUS | RO | 0000 0000 | PORT1_CLASS_STATUS | | | | | | | |
| 0x0D | PORT2_CLASS_DETECT_STATUS | RO | 0000 0000 | PORT2_CLASS_STATUS | | | | | | | |
| 0x0E | PORT3_CLASS_DETECT_STATUS | RO | 0000 0000 | PORT3_CLASS_STATUS | | | | | | | |
| 0x0F | PORT4_CLASS_DETECT_STATUS | RO | 0000 0000 | PORT4_CLASS_STATUS | | | | | | | |

| Addr | Name | Access | Reset State | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------------------|-----------------------------|--------|-------------|-----------------|---------------------|-----------------|---------------------------|--------------|-------------------|---|-------|
| 0x10 | POWER_STATUS | RO | 0000 0000 | | POWER_GOOD | | | | POWER_ENABLE | | |
| 0x11 | PIN_STATUS | RO | 0aaa aq00 | — | PIN_A4 | PIN_A3 | PIN_A2 | PIN_A1 | QUAD | — | — |
| Main Configuration Registers | | | | | | | | | | | |
| 0x12 | PORT_MODE | R/W | 0000 0000 | PORT4_PORT_MODE | PORT3_PORT_MODE | PORT2_PORT_MODE | PORT1_PORT_MODE | | | | |
| 0x13 | DISCONNECT_ENABLE | R/W | 0000 1111 | — | | | | | DISCONNECT_ENABLE | | |
| 0x14 | DETECT_CLASS_ENABLE | R/W | 0000 0000 | | CLASS_ENABLE | | | | DETECT_CC_ENABLE | | |
| 0x15 | POWER_PRIORITY_PCUT_DISABLE | R/W | 0000 0000 | | PORT_POWER_PRIORITY | | | | DISABLE_PCUT | | |
| 0x16 | TIMING_CONFIG | R/W | 0000 0000 | TLIM | | TSTART | TOVLD | | | | TMPDO |
| 0x17 | MISC | R/W | 1000 0000 | INT_PIN_ENABLE | CAP_MEAS_ENABLE | — | MULTI-BIT PRIORITY_ENABLE | CLASS_CHANGE | DETECT_CHANGE | — | — |
| Pushbuttons | | | | | | | | | | | |
| 0x18 | PB_DETECT_CLASS | WO | 0000 0000 | | RESTART_CLASS | | | | RESTART_DETECT | | |
| 0x19 | PB_POWER_ENABLE | WO | 0000 0000 | | PB_POWER_OFF | | | | PB_POWER_ON | | |
| 0x1A | PB_RESET | WO | 0000 0000 | CLEAR_ALL_INTS | CLEAR_INT_PIN | — | RESET_QUAD | | RESET_PORT | | |

| Addr | Name | Access | Reset State | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | |
|----------------------|--------------------------------|--------|-------------|--------------------|-------------------------|-------------|-------------------------|--------------------------|---|---|---|--|--|
| Miscellaneous | | | | | | | | | | | | | |
| 0x1B | VENDOR_ID | RO | 0100 0101 | MANUFACTURER_ID | | | | IC_ID | | | | | |
| 0x1C | AUTOCLASS_CONNECTION_CHECK | RO | 0000 0000 | AUTOCLASS_DETECTED | | | | CONNECTION_CHECK_RESULTS | | | | | |
| 0x1D | Reserved | R/W | 0000 0000 | Reserved | | | | | | | | | |
| 0x1E | PORT1_POLICE_2P | R/W | 1111 1111 | PORT1_POLICE_2P | | | | | | | | | |
| 0x1F | PORT2_POLICE_2P | R/W | 1111 1111 | PORT2_POLICE_2P | | | | | | | | | |
| 0x20 | PORT3_POLICE_2P | R/W | 1111 1111 | PORT3_POLICE_2P | | | | | | | | | |
| 0x21 | PORT4_POLICE_2P | R/W | 1111 1111 | PORT4_POLICE_2P | | | | | | | | | |
| 0x22-0x23 | Reserved | R/W | 0000 0000 | — | | | | | | | | | |
| 0x26 | PORT_REMAP | R/W | 1110 0100 | PORT4_REMAP | PORT3_REMAP | PORT2_REMAP | PORT1_REMAP | | | | | | |
| 0x27 | PORT1_PORT2_MULTIBIT_PRIORITY | R/W | 0000 0000 | — | PORT2_MULTIBIT_PRIORITY | — | PORT1_MULTIBIT_PRIORITY | | | | | | |
| 0x28 | PORT3_PORT_4_MULTIBIT_PRIORITY | R/W | 0000 0000 | — | PORT4_MULTIBIT_PRIORITY | — | PORT3_MULTIBIT_PRIORITY | | | | | | |
| 0x29 | POWER_ALLOCATION | R/W | 0000 0000 | — | PORT34_POWER_ALLOCATION | — | PORT12_POWER_ALLOCATION | | | | | | |
| 0x2A | PORT12_POLICE_4P | R/W | 1111 1111 | PORT12_POLICE_4P | | | | | | | | | |
| 0x2B | PORT34_POLICE_4P | R/W | 1111 1111 | PORT34_POLICE_4P | | | | | | | | | |
| 0x2C | TEMPERATURE | RO | ??? | TEMPERATURE | | | | | | | | | |
| 0x2D | ILIM_PCUT_DISCONNECT_4P | R/W | 0000 1100 | ILIM_BEHAVIOR | PCUT_BEHAVIOR | PCUT_ENABLE | DISCON-NECT_THRESH | | | | | | |

| Addr | Name | Access | Reset State | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--|---------------|--------|--------------|---|---|---|-----|-----|---|---|---|
| Must Use 16-BIT SMBUS Reads for Parametric Measurements | | | | | | | | | | | |
| 0x2E | VPWR | RO | ???? ???? | | | | LSB | | | | |
| — | | RO | 00?? ???? | — | | | | MSB | | | |
| 0x30 | PORT1_CURRENT | RO | 0000 0000 | | | | LSB | | | | |
| — | | RO | 0000 0000 | — | | | | MSB | | | |
| 0x32 | PORT1_VOLTAGE | RO | 0000 0000 | | | | LSB | | | | |
| — | | RO | 0000 0000 | — | | | | MSB | | | |
| 0x34 | PORT2_CURRENT | RO | 0000 0000 | | | | LSB | | | | |
| — | | RO | 0000 0000 | — | | | | MSB | | | |
| 0x36 | PORT2_VOLTAGE | RO | 0000 0000 | | | | LSB | | | | |
| — | | RO | 0000 0000 | — | | | | MSB | | | |
| 0x38 | PORT3_CURRENT | RO | 0000 0000 | | | | LSB | | | | |
| — | | RO | 0000 0000 | — | | | | MSB | | | |
| 0x3A | PORT3_VOLTAGE | RO | 0000 0000 | | | | LSB | | | | |
| — | | RO | 0000 0000 | — | | | | MSB | | | |
| 0x3C | PORT4_CURRENT | RO | 0000 0000 | | | | LSB | | | | |
| — | | RO | 0000 0000 | — | | | | MSB | | | |
| 0x3E | PORT4_VOLTAGE | RO | 0000 0000 | | | | LSB | | | | |
| — | | RO | 0000 0000 | — | | | | MSB | | | |

| Addr | Name | Access | Reset State | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--|--------------------------|--------|--------------|---|----------------|---|--------------------------|---|---|---|--------------------------|
| Firmware Revision And Chip Revision | | | | | | | | | | | |
| 0x40 | MAX_ILIM_MANUAL_POLICE | RW | 0000 0000 | | MAX_ILIM | | MANUAL_POLICE | | | | |
| 0x41 | FIRMWARE_REVISION | RO | ???? ???? | | MAJOR_REVISION | | MINOR_REVISION | | | | |
| 0x42 | I2C_WATCHDOG | RW | 0001 0110 | 0 | 0 | 0 | WATCHDOG_DISABLE | | | | WATCH- DOG_STA TUS |
| 0x43 | CHIP_REVISION | RO | ???? ??? | | | | CHIP_REVISION | | | | |
| Detection Resistance Results | | | | | | | | | | | |
| 0x44 | PORT1_DETECT_RESISTANCE | RO | 0000 0000 | | | | PORT1_DETECT_RESISTANCE | | | | |
| 0x45 | PORT2_DETECT_RESISTANCE | RO | 0000 0000 | | | | PORT2_DETECT_RESISTANCE | | | | |
| 0x46 | PORT3_DETECT_RESISTANCE | RO | 0000 0000 | | | | PORT3_DETECT_RESISTANCE | | | | |
| 0x47 | PORT4_DETECT_RESISTANCE | RO | 0000 0000 | | | | PORT4_DETECT_RESISTANCE | | | | |
| 0x48 | PORT1_DETECT_CAPACITANCE | RO | 0000 0000 | | | | PORT1_DETECT_CAPACITANCE | | | | |
| 0x49 | PORT2_DETECT_CAPACITANCE | RO | 0000 0000 | | | | PORT2_DETECT_CAPACITANCE | | | | |
| 0x4A | PORT3_DETECT_CAPACITANCE | RO | 0000 0000 | | | | PORT3_DETECT_CAPACITANCE | | | | |
| 0x4B | PORT4_DETECT_CAPACITANCE | RO | 0000 0000 | | | | PORT4_DETECT_CAPACITANCE | | | | |

| Addr | Name | Access | Reset State | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--|-------------------------|--------|-------------|---|----------------------|---|-----------------------|---|---|---|---|
| Assigned Class and Requested Class | | | | | | | | | | | |
| 0x4C | PORT1_CLASS_RESULTS | RO | 0000 0000 | | PORT1_ASSIGNED_CLASS | | PORT1_REQUESTED_CLASS | | | | |
| 0x4D | PORT2_CLASS_RESULTS | RO | 0000 0000 | | PORT2_ASSIGNED_CLASS | | PORT2_REQUESTED_CLASS | | | | |
| 0x4E | PORT3_CLASS_RESULTS | RO | 0000 0000 | | PORT3_ASSIGNED_CLASS | | PORT3_REQUESTED_CLASS | | | | |
| 0x4F | PORT4_CLASS_RESULTS | RO | 0000 0000 | | PORT4_ASSIGNED_CLASS | | PORT4_REQUESTED_CLASS | | | | |
| Autoclass Configuration and Results | | | | | | | | | | | |
| 0x50 | AUTOCLASS_CONTROL | R/W | 0000 0000 | | MANUAL_AUTOCLASS | | AUTO_AUTOCLASS | | | | |
| 0x51 | PORT1_AUTOCLASS_RESULTS | R/W | 0000 0000 | 0 | | | PORT1_AUTOCLASS_POWER | | | | |
| 0x52 | PORT2_AUTOCLASS_RESULTS | R/W | 0000 0000 | 0 | | | PORT2_AUTOCLASS_POWER | | | | |
| 0x53 | PORT3_AUTOCLASS_RESULTS | R/W | 0000 0000 | 0 | | | PORT3_AUTOCLASS_POWER | | | | |
| 0x54 | PORT4_AUTOCLASS_RESULTS | R/W | 0000 0000 | 0 | | | PORT4_AUTOCLASS_POWER | | | | |
| Miscellaneous | | | | | | | | | | | |
| 0x55 | ALTERNATIVE_FOLDBACK | R/W | 0000 0000 | | PGOOD_FOLDBACK | | INRUSH_850MA | | | | |
| 0x56 - 0x5E | Reserved | R/W | 0000 0000 | | | | | | | | |

| Addr | Name | Access | Reset State | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | |
|---|-------------------|--------|-------------|-------------------|-----------|---|---|--------------|---|---|---------------|--|--|
| Flash Control | | | | | | | | | | | | | |
| 0x5F | FLASH_ERASE_KEY | R/W | 0000 0000 | FLASH_ERASE_KEY | | | | | | | | | |
| 0x60 | FLASH_CONTROL | R/W | 0000 0000 | START_FLASHING | RESET_CPU | 0 | 0 | END_FLASHING | 0 | 0 | CLEAR_POINTER | | |
| 0x61 | FLASH_DATA | R/W | 0000 0000 | FLASH_DATA | | | | | | | | | |
| 0x62 | FLASH_ADDRESS_LSB | R/W | 0000 0000 | FLASH_ADDRESS_LSB | | | | | | | | | |
| 0x63 | FLASH_ADDRESS_MSB | R/W | 0000 0000 | FLASH_ADDRESS_MSB | | | | | | | | | |
| 0x64-0xFF | Reserved | R/W | 0000 0000 | — | | | | | | | | | |
| Note: | | | | | | | | | | | | | |
| 1. A firmware FLASH update is required to use PORTn_DETECT_CAPACITANCE, TLIM, and PORTn_MAX_ILIM. Contact Skyworks for details. | | | | | | | | | | | | | |

4.1 INTERRUPT Register (Address 0x00)

| | | | | | | | |
|------------------------|-----------------|---------------|----------------|--------------------|----------------|-----------------------|-------------------------|
| INTERRUPT | | | | | | | |
| Register Address: 0x00 | | | | | | | |
| Access Type: Read Only | | | | | | | |
| Reset: 1000 0000 | | | | | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| SUPPLY_EVENT_BIT | START_EVENT_BIT | P_I_FAULT_BIT | CLASS_DONE_BIT | DETECT_CC_DONE_BIT | DISCONNECT_BIT | POWER_GOOD_CHANGE_BIT | POWER_ENABLE_CHANGE_BIT |

| Bit | Name | Description |
|-----|-------------------------|--|
| 7 | SUPPLY_EVENT_BIT | VDD, VPWR or Temperature failed 0 = No Events 1 = At least one event in OVER_TEMP, VDD_UVLO_FAIL, VDD_UVLO_WARN, VPWR_UVLO in SUPPLY_EVENT |
| 6 | START_EVENT_BIT | Fault occurred after PORTn_PB_POWER_ON but before achieving PORTn_POWER_GOOD 0 = No Events 1 = At least one event bit in START_FAULT in ILIM_START_FAULT |
| 5 | P_I_FAULT_BIT | A port previously reached POWER_GOOD state is now unpowered due to a PCUT or ILIM event 0 = No Events 1 = At least one event bit in ILIM_FAULT in ILIM_START_FAULT, PCUT_FAULT_2P in DISCONNECT_PCUT_FAULT, PORTnm_PCUT_FAULT_4P in SUPPLY_EVENT |
| 4 | CLASS_DONE_BIT | Class Probe completed successfully 0 = No Events 1 = At least one event in CLASS_DONE in CLASS_DETECT_EVENT |
| 3 | DETECT_CC_DONE_BIT | Detection and Connection check completed 0 = No Events 1 = At least one event in DETECT_CC_DONE in CLASS_DETECT_EVENT |
| 2 | DISCONNECT_BIT | A port previously reached POWER_GOOD state is now unpowered because of PD disconnection or OSS_EVENT 0 = No Events 1 = At least one event bit in DISCONNECTION in DISCONNECT_PCUT_FAULT, OSS_EVENT in SUPPLY_EVENT |
| 1 | POWER_GOOD_CHANGE_BIT | POWER_GOOD in POWER_STATUS changed 0 = No Events 1 = At least one event in POWER_GOOD_CHANGE in POWER_EVENT |
| 0 | POWER_ENABLE_CHANGE_BIT | POWER_ENABLE in POWER_STATUS changed 0 = No Events 1 = At least one event in the POWER_ENABLE_CHANGE in POWER_EVENT |

4.2 INTERRUPT_MASK Register (Address 0x01)

| | | | | | | | |
|--------------------------------|--------------------------|------------------------|-------------------------|--------------------------------------|------------------------------|---|---------------------------------------|
| INTERRUPT_MASK | | | | | | | |
| Register Address: 0x01 | | | | | | | |
| Access Type: Read / Write | | | | | | | |
| Reset: 1000 0000 | | | | | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| SUP- PLY_EVENT_ MASK_BIT | START_EVEN T_MASK_BIT | P_I_FAULT_M ASK_BIT | CLASS_DONE _MASK_BIT | DE- TECT_CC_DO NE_MASK_BI T | DISCON- NECT_MASK_ BIT | POW- ER_GOOD_C HANGE_MAS K_BIT | POWER_ENA- BLE_CHANGE _MASK_BIT |

| Bit | Name | Description |
|-----|-------------------------------------|--|
| 7 | SUPPLY_EVENT_MASK_BIT | Masks SUPPLY_EVENT_BIT in the INTERRUPT register 0 = SUPPLY_EVENT_BIT not can assert INTb 1 = SUPPLY_EVENT_BIT can assert INTb |
| 6 | START_EVENT_MASK_BIT | Masks START_EVENT_BIT in the INTERRUPT register 0 = START_EVENT_BIT cannot assert INTb 1 = START_EVENT_BIT can assert INTb |
| 5 | P_I_FAULT_MASK_BIT | Masks the P_I_FAULT_BIT in the INTERRUPT register 0 = P_I_FAULT_BIT cannot assert INTb 1 = P_I_FAULT_BIT can assert INTb |
| 4 | CLASS_DONE_MASK_BIT | Masks the CLASS_DONE_BIT in the INTERRUPT register 0 = CLASS_DONE_BIT cannot assert INTb 1 = CLASS_DONE_BIT can assert INTb |
| 3 | DE- TECT_CC_DONE_MASK_BIT | Masks the DETECT_CC_DONE_BIT in the INTERRUPT register 0 = DETECT_CC_DONE_BIT cannot assert INTb 1 = DETECT_CC_DONE_BIT can assert INTb |
| 2 | DISCONNECT_MASK_BIT | Masks DISCONNECT_BIT in the INTERRUPT register 0 = DISCONNECT_BIT cannot assert INTb 1 = DISCONNECT_BIT can assert INTb |
| 1 | POW- ER_GOOD_CHANGE_MASK_ BIT | Masks POWER_GOOD_CHANGE_BIT in the INTERRUPT register 0 = POWER_GOOD_CHANGE_BIT cannot assert INTb 1 = POWER_GOOD_CHANGE_BIT can assert INTb |
| 0 | POWER_ENA- BLE_CHANGE_MASK_BIT | Masks POWER_ENABLE_CHANGE_BIT in the INTERRUPT register 0 = POWER_ENABLE_CHANGE_BIT cannot assert INTb 1 = POWER_ENABLE_CHANGE_BIT can assert INTb |

The INTERRUPT and INTERRUPT_MASK registers work together to influence the INTb pin logic for any given Quad. Each Si3474 has two Quads, and either Quad can assert the INTb pin independently of each other.

Quad_0_INT = INTERRUPT_{Q0} AND INTERRUPT_MASK_{Q0}

Quad_1_INT = INTERRUPT_{Q1} AND INTERRUPT_MASK_{Q1}

INTb = NOT (Quad_0_INT OR Quad_1_INT)

Bits in the INTERRUPT register can be cleared by a number of actions:

1. Reading CoR EVENT registers
2. Setting PORTn_PORT_MODE to SHUTDOWN
3. Setting PORTn_PB_POWER_OFF
4. Setting RESET_QUAD
5. Setting PORTn_RESET_PORT
6. Set CLEAR_ALL_INTS
7. OSS Emergency Shutdown

It is also possible to negate the INTb pin directly using the CLEAR_INT_PIN. This method does not clear any event register bits, nor does it clear bits in the INTERRUPT register.

4.3 Event Registers

These registers provide event status information. For these event registers, there is an RO register and a separate COR register. The COR version of an event register will clear those events when they are read. Consequently, by clearing the event, the INTERRUPT register bit corresponding to the event register may get cleared as a result. The graphic shows how the various event registers map into the INTERRUPT register bits.

For example, The DISCONNECT_BIT in INTERRUPT sets when either OSS_EVENT in SUPPLY_EVENT is set, or if one or more DISCONNECTION bits are set in the DISCONNECT_PCUT_FAULT. All of these bits are color-coded to illustrate their relationship.

If the SUPPLY_EVENT COR is read, the OSS_EVENT may clear, but if there are still set DISCONNECTION bits in DISCONNECT_PCUT_FAULT, the DISCONNECT_BIT in INTERRUPT will remain asserted. The DISCONNECT_BIT in INTERRUPT will only clear if all event bits, shown in the same color, are all zeroes.

Once the DISCONNECT_BIT in INTERRUPT is cleared, and if there are no other set bits in INTERRUPT on BOTH QUADS, then the INTb is negated.

In addition to reading of the CoR register, PORTn_CLASS_DONE, PORTn_DETECT_CC_DONE, PORTn_DISCONNECTION, PORTn_PCUT_FAULT_2P, PORTn_ILIM_FAULT, PORTn_START_FAULT, PORTnm_PCUT_FAULT_4P can also be cleared by the following:

1. Set PORTn_PORT_MODE to SHUTDOWN
2. Set PORTn_PB_POWER_OFF in PB_POWER_ENABLE
3. Set PORTn_RESET_PORT in PB_RESET
4. OSS_EVENT in SUPPLY_EVENT as a result of an emergency shutdown
5. Set RESET_QUAD
6. Set CLEAR_ALL_INTS

Consequently, INTb may also negate as a result of these event bits being cleared when the COR register is read.

| Address | Name | Access | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|-----------------------|--------|----------------------|---------------|----------------------|------------|----------------------|------------|----------------------|---------------------|
| INTERRUPT REGISTERS | | | | | | | | | | |
| 0x00 | INTERRUPT | RO | SUPPLY_EVENT | START_EVENT | P_I_FAULT | CLASS_DONE | DETECT_CC_DONE | DISCONNECT | POWER_GOOD_CHANGE | POWER_ENABLE_CHANGE |
| 0x01 | INTERRUPT_MASK | R/W | | | | | | | | |
| EVENT REGISTER BITS ASSOCIATED WITH INTERRUPT REGISTER | | | | | | | | | | |
| 0x02 | POWER_EVENT | RO | POWER_GOOD_CHANGE | | | | POWER_ENABLE_CHANGE | | | |
| 0x03 | | CoR | | | | | | | | |
| 0x04 | CLASS_DETECT_EVENT | RO | CLASS_DONE | | | | DETECT_CC_DONE | | | |
| 0x05 | | CoR | | | | | | | | |
| 0x06 | DISCONNECT_PCUT_FAULT | RO | DISCONNECTION | | | | PCUT_FAULT_2P | | | |
| 0x07 | | CoR | | | | | | | | |
| 0x08 | ILIM_START_FAULT | RO | ILIM_FAULT | | | | START_FAULT | | | |
| 0x09 | | CoR | | | | | | | | |
| 0x0A | SUPPLY_EVENT | RO | OVER_TEMP | VDD_UVLO_FAIL | VDD_UVLO_WARN | VPWR_UVLO | PORTnm_PCUT_FAULT_4P | OSS_EVENT | -- | |
| 0x0B | | CoR | | | | | | | | |
| 0x24 | POWER_ON_FAULT | RO | PORT4_POWER_ON_FAULT | | PORT3_POWER_ON_FAULT | | PORT2_POWER_ON_FAULT | | PORT1_POWER_ON_FAULT | |
| 0x25 | | CoR | | | | | | | | |

4.4 POWER Event and POWER Event CoR (Address 0x02, 0x03)

| | | | | | | | |
|--------------------|-------|-------|-------|------------------------|----------------------------|-------|-------|
| POWER_EVENT | | | | Register Address: 0x02 | Register Address: 0x03 | | |
| | | | | Access Type: Read Only | Access Type: Clear on Read | | |
| | | | | Reset: 0000 0000 | Reset: 0000 0000 | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| POWER_GOOD_CHANGE | | | | POWER_ENABLE_CHANGE | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |

| Bit | Name | Description |
|-----|---------------------------|---|
| 7 | PORT4_POWER_GOOD_CHANGE | PORTn_POWER_GOOD_CHANGE PORTn_POWER_GOOD in POWER_STATUS register changed 0 = PORTn_POWER_GOOD did not change 1 = PORTn_POWER_GOOD changed |
| 6 | PORT3_POWER_GOOD_CHANGE | |
| 5 | PORT2_POWER_GOOD_CHANGE | |
| 4 | PORT1_POWER_GOOD_CHANGE | |
| 3 | PORT4_POWER_ENABLE_CHANGE | PORTn_POWER_ENABLE_CHANGE PORTn_POWER_ENABLE in POWER_STATUS register changed 0 = PORTn_POWER_ENABLE did not change 1 = PORTn_POWER_ENABLE changed |
| 2 | PORT3_POWER_ENABLE_CHANGE | |
| 1 | PORT2_POWER_ENABLE_CHANGE | |
| 0 | PORT1_POWER_ENABLE_CHANGE | |

For a description of what POWER_GOOD and POWER_ENABLE means, refer to the description in the POWER_STATUS register.

PORTn_POWER_GOOD_CHANGE indicates that PORTn_POWER_GOOD in the POWER_STATUS register has changed. Any set PORTn_POWER_GOOD_CHANGE bit will also set the POWER_GOOD_CHANGE_BIT in the INTERRUPT register.

PORTn_POWER_ENABLE_CHANGE indicates that PORTn_POWER_ENABLE in the POWER_STATUS register has changed. Any set PORTn_POWER_ENABLE_CHANGE bit will also set the POWER_ENABLE_CHANGE_BIT in the INTERRUPT register.

4.5 CLASS_DETECT_EVENT and CLASS_DETECT_EVENT CoR (0x04, 0x05)

| | | | | | | | |
|---------------------------|-------|-------|-------|------------------------|-------|----------------------------|-------|
| CLASS_DETECT_EVENT | | | | Register Address: 0x04 | | Register Address: 0x05 | |
| | | | | Access Type: Read Only | | Access Type: Clear on Read | |
| | | | | Reset: 0000 0000 | | Reset: 0000 0000 | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| CLASS_DONE | | | | DETECT_CC_DONE | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |

| Bit | Name | Description |
|-----|----------------------|--|
| 7 | PORT4_CLASS_DONE | PORTn_CLASS_DONE PORTn_CLASS_STATUS in PORTn_CLASS_DETECT_STATUS register was updated or changed (see also CLASS_CHANGE in 4.17 MISC (0x17)). 0 = PORTn_CLASS_STATUS was not updated nor changed. 1 = PORTn_CLASS_STATUS was updated or changed. |
| 6 | PORT3_CLASS_DONE | |
| 5 | PORT2_CLASS_DONE | |
| 4 | PORT1_CLASS_DONE | |
| 3 | PORT4_DETECT_CC_DONE | PORTn_DETECT_CC_DONE PORTn_DETECTION_STATUS in PORTn_CLASS_DETECT_STATUS register was updated or changed (see also DETECT_CHANGE in 4.17 MISC (0x17)). 0 = PORTn_DETECTION_STATUS was not updated nor changed. 1 = PORTn_DETECTION_STATUS was updated or changed. |
| 2 | PORT3_DETECT_CC_DONE | |
| 1 | PORT2_DETECT_CC_DONE | |
| 0 | PORT1_DETECT_CC_DONE | |

PORTn_DETECT_CC_DONE indicates whether the PORTn_DETECTION_STATUS in PORTn_CLASS_DETECT_STATUS has valid results. The PORTnm_CONNECTION_CHECK_RESULTS in the AUTOCLASS_CONNECTION_CHECK register also have useful information for 4P Ports. Any set bits in the DETECT_CC_DONE field sets the DETECT_CC_DONE_BIT in the INTERRUPT register.

One common usability issue with enabling the DETECT_CC_DONE_BIT interrupt is that there tends to be a lot of detection events. One good way of reducing the number of interrupts is by also setting the DETECT_CHANGE bit in the MISC register. When this bit is set, the PORTn_DETECT_CC_DONE is only updated whenever there is a change in PORTn_DETECTION_STATUS, thereby reducing the number of interrupts to the system.

PORTn_CLASS_DONE indicates whether PORTn_CLASS_STATUS in PORTn_CLASS_DETECT_STATUS register has valid results. The PORTn_CLASS_DETECT_STATUS will always indicate RGOOD as Class Probe does not occur without RGOOD. PORTnm_CONNECTION_CHECK_RESULTS also will be updated for 4P Ports. Any set PORTn_CLASS_DONE bits also sets CLASS_DONE_BIT in the INTERRUPT register.

4.6 DISCONNECT_PCUT_FAULT and DISCONNECT_PCUT_FAULT CoR (0x06, 0x07)

| | | | | | | | |
|------------------------------|-------|-------|-------|------------------------|-------|----------------------------|-------|
| DISCONNECT_PCUT_FAULT | | | | Register Address: 0x06 | | Register Address: 0x07 | |
| | | | | Access Type: Read Only | | Access Type: Clear on Read | |
| | | | | Reset: 0000 0000 | | Reset: 0000 0000 | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| DISCONNECTION | | | | PCUT_FAULT_2P | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |

| Bit | Name | Description |
|-----|---------------------|--|
| 7 | PORT4_DISCONNECTION | PORTn_DISCONNECTION A PORTn in POWER_GOOD, did not detect sufficient current to meet MPS requirements, leading to a disconnection. 0 = PORTn did not disconnect. 1 = PORTn disconnected. |
| 6 | PORT3_DISCONNECTION | |
| 5 | PORT2_DISCONNECTION | |
| 4 | PORT1_DISCONNECTION | |
| 3 | PORT4_PCUT_FAULT_2P | PORTn_PCUT_FAULT_2P PORTn in POWER_GOOD state, was powered off because it exceeded the power threshold defined by the pertinent PORTn_POLICE_2P register. 0 = PORTn did not encounter a PCUT fault. 1 = PORTn encountered a PCUT fault. |
| 2 | PORT3_PCUT_FAULT_2P | |
| 1 | PORT2_PCUT_FAULT_2P | |
| 0 | PORT1_PCUT_FAULT_2P | |

PORTn_DISCONNECTION indicates a powered port was formerly in a POWER_GOOD state is now unpowered because the PD drew sufficient current. Any set PORTn_DISCONNECTION bits also set the DISCONNECT_BIT in the INTERRUPT register.

PORTn_PCUT_FAULT_2P indicates a powered port, formerly in a POWER_GOOD state, is now unpowered because the PD exceeded the power limits specified by the various POLICE registers. Any set PORTn_PCUT_FAULT_2P bits will set the P_I_FAULT_BIT in the INTERRUPT register.

4.7 ILIM_START_FAULT and ILIM_START_FAULT CoR (0x08, 0x09)

| | | | | | | | |
|-------------------------|-------|-------|-------|------------------------|-------|----------------------------|-------|
| ILIM_START_FAULT | | | | Register Address: 0x08 | | Register Address: 0x09 | |
| | | | | Access Type: Read Only | | Access Type: Clear on Read | |
| | | | | Reset: 0000 0000 | | Reset: 0000 0000 | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| ILIM_FAULT | | | | START_FAULT | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |

| Bit | Name | Description |
|-----|-------------------|--|
| 7 | PORT4_ILIM_FAULT | PORTn_ILIM_FAULT PORTn previously in POWER_GOOD state, encountered an overcurrent event, for longer than tLIM, leading to the port being powered down. 0 = PORTn did not encounter an ILIM fault. 1 = PORTn encountered an ILIM fault. |
| 6 | PORT3_ILIM_FAULT | |
| 5 | PORT2_ILIM_FAULT | |
| 4 | PORT1_ILIM_FAULT | |
| 3 | PORT4_START_FAULT | PORTn_START_FAULT PORTn was still powering up encountered an overcurrent condition, for longer than the tINRUSH. PORTn never achieved a POWER_GOOD status and is not powered. 0 = PORTn did not encounter a start fault. 1 = PORTn encountered a start fault. |
| 2 | PORT3_START_FAULT | |
| 1 | PORT2_START_FAULT | |
| 0 | PORT1_START_FAULT | |

PORTn_ILIM_FAULT indicates that a powered port in POWER_GOOD state is now unpowered because the port was in a current-limited state for longer than the tLIM time limit. Any set PORTn_ILIM_FAULT bits will set the P_I_FAULT_BIT in the INTERRUPT register.

PORTn_START_FAULT indicates that a powering port (POWER_ENABLE is set but POWER_GOOD is not set) did not reach POWER_GOOD because PORTn was in a current-limited state for longer than the tINRUSH time limit. Any set PORTn_START_FAULT bits will set the START_FAULT_BIT in the INTERRUPT register.

4.8 SUPPLY_EVENT and SUPPLY_EVENT CoR (0x0A, 0x0B)

| | | | | | | | |
|---------------------|--------------------|--------------------|-----------|------------------------|----------------------------|-----------|---|
| SUPPLY_EVENT | | | | Register Address: 0x0A | Register Address: 0x0B | | |
| | | | | Access Type: Read Only | Access Type: Clear on Read | | |
| | | | | Reset: 0001 0000 | Reset: 0001 0000 | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| OVER_TEMP | VDD_UV- LO_FAIL | VDD_UV- LO_WARN | VPWR_UVLO | PCUT_FAULT_4P | | OSS_EVENT | — |
| — | — | — | — | PORT34 | PORT12 | — | — |

| Bit | Name | Description |
|-----|----------------------|--|
| 7 | OVER_TEMP | Device temperature monitoring indicator 0 = Normal temperature. 1 = Device case temperature exceeded 125 °C. |
| 6 | VDD_UVLO_FAIL | VDD UVLO Failure Status 0 = VDD is greater than 2.25 V. 1 = VDD was measured to be under 2.25 V. Upon entering this condition, VDD needs to be higher than 2.6 V to exit this condition. |
| 5 | VDD_UVLO_WARN | VDD UVLO Warning Status 0 = VDD is greater than 2.8 V. 1 = VDD was measured under 2.8 V. Upon entering this condition, VDD needs to be higher than 3.1 V to exit this condition. |
| 4 | VPWR_UVLO | VPWR UVLO Status 0 = VPWR is greater than 28 V. 1 = VPWR was measured to be less than 28 V. Upon entering this condition, VPWR needs to be higher than 31 V to exit this condition. |
| 3 | PORT34_PCUT_FAULT_4P | The 4PP PD connected to PORT3 and PORT4 exceeded the power threshold defined by PORT34_POLICE_4P register, leading to a disconnection. 0 = PORT34 did not disconnect. 1 = PORT34 encountered a PCUT fault. |
| 2 | PORT12_PCUT_FAULT_4P | The 4PP PD connected to PORT1 and PORT2 exceeded the power threshold defined by PORT12_POLICE_4P register, leading to a disconnection. 0 = PORT12 did not disconnect. 1 = PORT12 encountered a PCUT fault. |
| 1 | OSS_EVENT | Emergency shutdown affected one of the ports in the quad. 0 = No emergency shutdown event. 1 = At least one low priority port was shut down. |

When one of OVER_TEMP, VDD_UVLO_FAIL, VDD_UVLO_WARN, and VPWR_UVLO are set, SUPPLY_EVENT_BIT in the INTERRUPT register is also set. Ports are powered off; no Detection, Classification and Power can occur while these events persist.

When either PORTnm_PCUT_FAULT_4P is set, the P_I_FAULT_BIT in the INTERRUPT register is also set.

When then the OSS_EVENT bit is set, the DISCONNECT_BIT in the INTERRUPT register is also set.

4.9 POWER_ON_FAULT and POWER_ON_FAULT CoR (0x24, 0x25)

| | | | | | | | |
|-----------------------|---|----------------|---|------------------------|---|----------------------------|---|
| POWER_ON_FAULT | | | | Register Address: 0x24 | | Register Address: 0x25 | |
| | | | | Access Type: Read Only | | Access Type: Clear on Read | |
| | | | | Reset: 0000 0000 | | Reset: 0000 0000 | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| POWER_ON_FAULT | | POWER_ON_FAULT | | POWER_ON_FAULT | | POWER_ON_FAULT | |
| PORT4 | | PORT3 | | PORT2 | | PORT1 | |

| Bit | Name | Description |
|-----|----------------------|--|
| 7-6 | PORT4_POWER_ON_FAULT | PORTn_POWER_ON_FAULT While attempting to turn on a port, a fault occurred even before turning on the FET. 00 = No Event. 01 = Invalid Detection. 10 = Classification Error. 11 = Insufficient power allocation. |
| 5-4 | PORT3_POWER_ON_FAULT | |
| 3-2 | PORT2_POWER_ON_FAULT | |
| 1-0 | PORT1_POWER_ON_FAULT | |

When PORTn_POWER_ON_FAULT is set, START_FAULT_BIT in INTERRUPT register is also set.

4.10 CLASS_DETECT_STATUS Registers (0x0C–0x0F)

| PORTn_CLASS_DETECT_STATUS Register | | | | Register Address: 0x0C/0x0D/0x0E/0x0F; Port 1/2/3/4 respectively | | | |
|---|--------------------------------------|---|---|--|-------------------------|---|---|
| | | | | Access Type: Read Only | | | |
| | | | | Reset: 0000 0000 for each PORTn_CLASS_DETECT_STATUS | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| PORTn_CLASS_STATUS | | | | PORTn_DETECTION_STATUS | | | |
| Code | PORTn_CLASS_STATUS | | | Code | PORTn_DETECTION_STATUS | | |
| 0000 | UNKNOWN | | | 0000 | UNKNOWN | | |
| 0001 | Class 1 | | | 0001 | Short circuit | | |
| 0010 | Class 2 | | | 0010 | Capacitive ¹ | | |
| 0011 | Class 3 | | | 0011 | RLOW | | |
| 0100 | Class 4 | | | 0100 | RGOOD | | |
| 0101 | — | | | 0101 | RHIGH | | |
| 0110 | Class 0 | | | 0110 | Open circuit | | |
| 0111 | Overcurrent | | | 0111 | PSE to PSE ² | | |
| 1000 | Class 5 4P SS | | | 1000 | — | | |
| 1001 | Class 6 4P SS | | | 1001 | — | | |
| 1010 | Class 7 4P SS | | | 1010 | — | | |
| 1011 | Class 8 4P SS | | | 1011 | — | | |
| 1100 | Class 4+ Type 1 Limited ¹ | | | 1100 | — | | |
| 1101 | Class 5 DS | | | 1101 | — | | |
| 1110 | — | | | 1110 | — | | |
| 1111 | Class Mismatch ² | | | 1111 | MOSFET_FAULT | | |
| Note: | | | | Note: | | | |
| <ol style="list-style-type: none"> Class 4+ Type 1 Limited is not emitted in Semi Auto Class Probe. It may occur during a Class Power On as a result of PB_POWER_ON The Si3474 automatically performs a Class Reset and repeats classification. | | | | <ol style="list-style-type: none"> Capacitive status is reported when the load capacitance is bigger than 1.5 μF (Cpd > 1.5 μF). The Si3474 is capable of detecting whether it is cross-connected to another PSE controller of a different type. In this case, the PSE to PSE Status is reported. Detection of another PSE is based on verifying the voltage level on the output (DRAINn pin) during detection. | | | |

In SEMI_AUTO mode, the classification process is not initiated unless RGOOD is reported. When reading PORTn_CLASS_STATUS outside of an event handler servicing the PORTn_CLASS_DONE, the classification status can be unknown, or it can be the last classification status after the last RGOOD.

It is generally recommended to only read PORTn_CLASS_STATUS only when PORTn_CLASS_DONE indicates that there is useful information available.

4.11 PORT_POWER_STATUS Register (0x10)

| PORT_POWER_STATUS | | | | Register Address: 0x10 | | | |
|--------------------------|--------------------|--|-------|------------------------|-------|-------|-------|
| | | | | Access Type: Read Only | | | |
| | | | | Reset: 0000 0000 | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| POWER_GOOD | | | | POWER_ENABLE | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |
| Bit | Name | Description | | | | | |
| 7 | PORT4_POWER_GOOD | PORTn has passed through the initial inrush period and has successfully powered up the port 0 = OFF 1 = PORTn is in POWER_GOOD state PORTn is in POWER_GOOD state after the initial t_{INRUSH} and that the PORTn Drain is within 2 V of the Si3474 ground reference. | | | | | |
| 6 | PORT3_POWER_GOOD | | | | | | |
| 5 | PORT2_POWER_GOOD | | | | | | |
| 4 | PORT1_POWER_GOOD | | | | | | |
| 3 | PORT4_POWER_ENABLE | PORTn_POWER_ENABLE correlates to PORTn FET ON / OFF Status. | | | | | |
| 2 | PORT3_POWER_ENABLE | 0 = FET is turned OFF. | | | | | |
| 1 | PORT2_POWER_ENABLE | 1 = FET is turned ON. | | | | | |
| 0 | PORT1_POWER_ENABLE | After a PORTn_PB_POWER_ON, the PORTn_POWER_ENABLE is set after the Detection, Connection Check and Class Power On. | | | | | |

The main difference between the POWER_ENABLE and POWER_GOOD concepts is rooted in time delays.

Assume for a moment that both PORTn_POWER_ENABLE and PORTn_POWER_GOOD are both OFF, as an initial condition of this illustration.

When a PORTn_PB_POWER_ON is set, there is typically a delay from that pushbutton setting to when the Si3474 starts drives the GATE of the FET to turn it on. However, between PORTn_PB_POWER_ON and the GATE drive, the Si3474 may need to complete servicing other ports before starting to service the PORTn_PB_POWER_ON. Even if the Si3474 began servicing the PORTn_PB_POWER_ON, the port will still need to go through Detection, Connection Check and Class Power On before turning on the FET.

At the time then the Si3474 drives the FET, this is when PORTn_POWER_ENABLE is declared.

At this point, PORTn_POWER_ENABLE is ON, but PORTn_POWER_GOOD is still OFF. This effectively defines an initial start-up period where the port is allowed to current-limit for short t_{INRUSH} duration in order to charge up the PD capacitors. During this time, it is possible that the FET DRAIN would be folded-back to enforce this start-up current limit. Once the t_{INRUSH} period is over, if the DRAIN voltage is less than 2 V, this is when POWER_GOOD state is declared, and that in the POWER_GOOD state, both PORTn_POWER_ENABLE and PORTn_POWER_GOOD are both ON.

Once in POWER_GOOD state, the port is then monitored for ILIM, PCUT and DISCONNECTION events. Throughout this document, POWER_GOOD state is sometimes used to distinguish between the initial t_{INRUSH} period and the long-term port monitoring of these events.

When a port is turned off, PORTn_POWER_ENABLE and PORTn_POWER_GOOD bits both changes to OFF simultaneously.

The POWER_ENABLE_CHANGE and POWER_GOOD_CHANGE is used to mark the transition time, as these transition times are what marks the status of both the FET, and the actions the Si3474 is performing as part of servicing that port.

4.12 PORT_MODE (0x12)

| | | | | | | | | |
|------------------|---|-----------|---|-----------|---|-----------|---|---------------------------|
| PORT_MODE | | | | | | | | Register Address: 0x12 |
| | | | | | | | | Access Type: Read / Write |
| | | | | | | | | Reset: 0000 0000 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| PORT_MODE | | PORT_MODE | | PORT_MODE | | PORT_MODE | | |
| PORT4 | | PORT3 | | PORT2 | | PORT1 | | |

| Bit | Name | Description |
|-----|-----------------|---|
| 7-6 | PORT4_PORT_MODE | PORTn_PORT_MODE Sets the main port operating mode. SEMI_AUTO is used in managed power use case. AUTO mode is used in unmanaged power use case. MANUAL mode is used generally for debug only. 00 = Set PORTn to SHUTDOWN Mode. 01 = Set PORTn to MANUAL Mode. 10 = Set PORTn to SEMI_AUTO Mode. 11 = Set PORTn to AUTO Mode. See 4.14 DETECT_CLASS_ENABLE (0x14) and 4.19 PB_POWER_ENABLE (0x19) . |
| 5-4 | PORT3_PORT_MODE | |
| 3-2 | PORT2_PORT_MODE | |
| 1-0 | PORT1_PORT_MODE | |

Setting PORTn_PORT_MODE to SHUTDOWN clears numerous port registers, and possibly the associated INTERRUPT bits. Refer to description of PORTn_PB_POWER_OFF in PB_POWER_ENABLE for this list.

Outside of the host setting PORTn_PORT_MODE, PORTn_PORT_MODE can be set to SHUTDOWN when RESET_QUAD is set.

After setting SEMI_AUTO in PORTn_PORT_MODE, PORTn_CLASS_ENABLE and PORTn_DETECT_CC_ENABLE in DETECT_CC_ENABLE should also be set to begin continuous Detection, Connection Check and Class Probe. Refer to DETECT_CLASS_ENABLE register.

4.13 DISCONNECT_ENABLE (0x13)

| | | | | | | | | |
|--------------------------|---|---|---|-------------------|-------|-------|-------|---------------------------|
| DISCONNECT_ENABLE | | | | | | | | Register Address: 0x13 |
| | | | | | | | | Access Type: Read / Write |
| | | | | | | | | Reset: 0000 1111 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| | | | | DISCONNECT_ENABLE | | | | |
| | | | | PORT4 | PORT3 | PORT2 | PORT1 | |

| Bit | Name | Description |
|-----|-------------------------|---|
| 3 | PORT4_DISCONNECT_ENABLE | PORTn_DISCONNECT_ENABLE Defines operation of a port in POWER GOOD state, whether or not to allow disconnection if the PD does not draw sufficient current and does not meet MPS requirements. Overcurrent and PCUT faults will still result in a disconnection. 0 = Keep port power even if PD current too low. 1 = Normal Disconnection Monitoring. |
| 2 | PORT3_DISCONNECT_ENABLE | |
| 1 | PORT2_DISCONNECT_ENABLE | |
| 0 | PORT1_DISCONNECT_ENABLE | |

4.14 DETECT_CLASS_ENABLE (0x14)

| | | | | | | | | |
|----------------------------|-------|-------|-------|------------------|-------|-------|-------|---------------------------|
| DETECT_CLASS_ENABLE | | | | | | | | Register Address: 0x14 |
| | | | | | | | | Access Type: Read / Write |
| | | | | | | | | Reset: 0000 0000 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| CLASS_ENABLE | | | | DETECT_CC_ENABLE | | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 | |

| Bit | PORTn_CLASS_ENABLE | PORTn_DETECT_CC_ENABLE | Description |
|-------|--------------------|------------------------|--|
| 7 / 3 | PORT4_CLASS_ENABLE | PORT4_DETECT_CC_ENABLE | PORTn_CLASS_ENABLE / PORTn_DETECT_CC_ENABLE |
| 6 / 2 | PORT3_CLASS_ENABLE | PORT3_DETECT_CC_ENABLE | It is more useful to describe CLASS_ENABLE and DETECT_CC_ENABLE together. CLASS_ENABLE is shown on the left; DETECT_CC_ENABLE shown on the right. |
| 5 / 1 | PORT2_CLASS_ENABLE | PORT2_DETECT_CC_ENABLE | |
| 4 / 0 | PORT1_CLASS_ENABLE | PORT1_DETECT_CC_ENABLE | |
| | | | <p>If PORTn_MODE in SEMI_AUTO</p> <p>00 = No Operation</p> <p>01 = Continuous Detection and Connection Check</p> <p>10 = Not supported</p> <p>11 = Continuous Detection, Connection Check and Class Probe</p> <p>If PORTn_MODE in AUTO</p> <p>00 = No Operation</p> <p>01 = Not supported</p> <p>10 = Not supported</p> <p>11 = Continuous Detection, Connection Check and Class Probe until a PD is detected. When a PD is detected, a Class Power On is initiated, followed by a turning on the port. In effect, it is as though the Si3474 received a PORTn_PB_POWER_ON.</p> <p>If PORTn_MODE in MANUAL</p> <p>Use PB_DETECT_CLASS instead</p> <p>If PORTn_MODE in SHUTDOWN</p> <p>Set up PORTn_PORT_MODE first</p> |

PORTn_CLASS_ENABLE and PORTn_DETECT_CC_ENABLE are cleared when the following occur:

1. PORTn_PORT_MODE set to SHUTDOWN.
2. PORTn_PB_POWER_OFF in PB_POWER_ENABLE is set.
3. PORTn_RESET_PORT in PB_RESET is set.
4. OSS_EVENT in SUPPLY_EVENT is set as a result of an emergency shutdown.
5. RESET_QUAD is set.

The DETECT_CLASS_ENABLE register is intended for use when PORTn_PORT_MODE is either in SEMI_AUTO or AUTO only.

If PORTn_PORT_MODE is MANUAL, the corresponding bits in PB_DETECT_CLASS are set; refer to PB_DETECT_CLASS for additional operational description.

If PORTn_PORT_MODE is SHUTDOWN, PORTn_PORT_MODE must be initialized first as this is an invalid operation.

4.15 POWER_PRIORITY_P CUT_DISABLE (0x15)

| | | | | | | | |
|------------------------------------|-------|-------|-------|---------------------------|-------|-------|-------|
| PORT_PRIORITY_P CUT_DISABLE | | | | Register Address: 0x15 | | | |
| | | | | Access Type: Read / Write | | | |
| | | | | Reset: 0000 0000 | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| PORT_POWER_PRIORITY | | | | DISABLE_P CUT | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |

| Bit | Name | Description |
|-----|----------------------|--|
| 7 | PORT4_POWER_PRIORITY | PORTn_PORT_POWER_PRIORITY Defines the Port Power Priority for use when MULTIBIT_PRIORITY_ENABLE = 0. 0 = OSS event does not shut down PORTn. 1 = OSS event shuts down PORTn |
| 6 | PORT3_POWER_PRIORITY | |
| 5 | PORT2_POWER_PRIORITY | |
| 4 | PORT1_POWER_PRIORITY | PORTn_PORT_POWER_PRIORITY is cleared when RESET_QUAD is set. An OSS event occurs when the OSS pin goes high. Every lower priority port experiences a PORTn_PB_POWER_OFF. Refer to PORTn_PB_POWER_OFF for additional details of what registers are cleared, |
| 3 | PORT4_DISABLE_P CUT | PORTn_DISABLE_P CUT Defines operation of a port in POWER GOOD state, whether or not to power down PORTn if the PD exceeds port power limits defined in PORTn_POLICE_2P or PORTnm_POLICE_4P. For additional 4P behavior, refer to See also 4.28 ILIM_P CUT_DISCONNECT_4P (0x2D) . Overcurrent faults and PD Disconnection will still result in a disconnection. |
| 2 | PORT3_DISABLE_P CUT | |
| 1 | PORT2_DISABLE_P CUT | |
| 0 | PORT1_DISABLE_P CUT | 0 = Normal P CUT Monitoring. 1 = Keep port power even if PD exceeds POLICE register limits Although the port power is not removed, PORTn_P CUT_FAULT_2P or PORTnm_P CUT_FAULT_4P events are reported, leading to an interrupt. The interrupt may be cleared by increasing the related PORTn_POLICE_2P or PORTnm_POLICE_4P registers. |

4.16 TIMING_CONFIG (0x16)

| | | | | | | | | |
|----------------|---|----------------|---|----------------|---|----------------|---|---------------------------|
| TLIM | | | | | | | | Register Address: 0x16 |
| | | | | | | | | Access Type: Read / Write |
| | | | | | | | | Reset: 0000 0000 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| TLIM | | TSTART | | TOVLD | | TMPDO | | |
| PORT1 to PORT4 | | PORT1 to PORT4 | | PORT1 to PORT4 | | PORT1 to PORT4 | | |

| Bit | Name | Description |
|-----|--------|---|
| 7-6 | TLIM | <p>ILIM FAULT Timing</p> <p>Specifies minimum t_{LIM} when $PORTn_MAX_ILIM$ is set. This setting defines the minimum period for which an overcurrent event is tolerated without turning off the port. This setting applies for all ports in the quad.</p> <p>00 = 60 ms 01 = 15 ms 10 = 10 ms 11 = 6 ms</p> <p>When using the Si3474A-A01 or Si3470B-A01, a FLASH Update is required for TLIM to operate as documented. Contact Skyworks for details.</p> |
| 5-4 | TSTART | <p>START FAULT Timing</p> <p>When the port is powering up, if the port is still current limiting after the t_{INRUSH} period, the port is shut off. This setting applies for all ports in the quad</p> <p>00 = 60 ms 01 = 30 ms 10 = 120 ms 11 = Reserved</p> |
| 3-2 | TOVLD | <p>PCUT FAULT Timing</p> <p>A PD drawing power that exceeds the policing power limits for longer than t_{OVLD} will result in the port shut off. This setting applies for all ports in the quad.</p> <p>00 = 60 ms 01 = 30 ms 10 = 120 ms 11 = 240 ms</p> |
| 1-0 | TMPDO | <p>DISCONNECTION Delay Timing</p> <p>A PD drawing too little current for longer than the t_{MPDO} will result in a disconnection. This setting applies to all ports in the quad.</p> <p>00 = 360 ms 01 = 90 ms 10 = 180 ms 11 = 720 ms</p> |

4.17 MISC (0x17)

| | | | | | | | |
|-------------------------------|---------------------|---|------------------------------------|------------------|------------------------|---|---|
| MISC | | | | | | | |
| Register Address: 0x17 | | | | | | | |
| Access Type: Read / Write | | | | | | | |
| Reset: 1000 0000 | | | | | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| INTER- RUPT_PIN_E NABLE | CAP_MEAS_E NABLE | — | MULTI- BIT_PRIORI- TY_ENABLE | CLASS_CHAN GE | DE- TECT_CHAN GE | — | — |

| Bit | Name | Description |
|-----|--------------------------|---|
| 7 | INTERRUPT_PIN_ENABLE | Enables INTb pin output drive. 0 = Enable 1 = Disable |
| 6 | CAP_MEAS_ENABLE | Enables Capacitance Measurement on PORTn_DETECT_CAPACITANCE. 0 = Enable 1 = Disable When using the Si3474A-A01 or Si3474B-A01, a FLASH Update is needed for Capacitive Measurement to function as documented. Contact Skyworks for more details. |
| 4 | MULTIBIT_PRIORITY_ENABLE | Enables Multibit Port Priority. 0 = Single Bit Port Priority. See also PORTn_PORT_POWER_PRIORITY. 1 = Multibit Port Priority. See also PORTn_MULTIBIT_PRIORITY. |
| 3 | CLASS_CHANGE | Defines whether CLASS_DONE events in CLASS_DETECT_STATUS register are set whenever the PORTn_CLASS_STATUS is updated, or only when it changes. 0 = Report CLASS_DONE when CLASS_STATUS is updated. 1 = Report CLASS_DONE when CLASS_STATUS changes. |
| 2 | DETECT_CHANGE | Defines whether the DETECT_CC_DONE events in CLASS_DETECT_STATUS register are set whenever the PORTn_DETECTION_STATUS is updated, or only if it changes. 0 = Report DETECT_CC_DONE when DETECTION_STATUS is updated. 1 = Report DETECT_CC_DONE when DETECTION_STATUS changes. |

4.18 PB_DETECT_CLASS (0x18)

| | | | | | | | |
|------------------------|-------|-------|-------|-------------------------|-------|-------|-------|
| PB_DETECT_CLASS | | | | Register Address: 0x18 | | | |
| | | | | Access Type: Write Only | | | |
| | | | | Reset: 0000 0000 | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| RESTART_CLASS | | | | RESTART_DETECT | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |

| Bit | PORT _n _RE- START_CLASS | PORT _n _RE- START_DETECT | Description |
|-------|---------------------------------------|--|---|
| 7 / 3 | PORT4_RE- START_CLASS | PORT4_RE- START_DETECT | PORT _n _RESTART_CLASS / PORT _n _RESTART_DETECT It is best to view these RESTART_CLASS and RESTART_DETECT together. As a shortcut, RESTART_CLASS will be shown below as the 'left bit', while RESTART_DETECT is shown as the 'right' bit. The intended use case of this register is in MANUAL mode. By definition, MANUAL mode is used for debug only. 00 - No operation 01 - Single Detection and Connection Check 10 - Invalid Setting 11 - Single Detection, Connection Check and Classification without powering the port (e.g., Class Probe). |
| 6 / 2 | PORT3_RE- START_CLASS | PORT3_RE- START_DETECT | |
| 5 / 1 | PORT2_RE- START_CLASS | PORT2_RE- START_DETECT | |
| 4 / 0 | PORT1_RE- START_CLASS | PORT1_RE- START_DETECT | |

PB_DETECT_CLASS is intended for use when PORT_n_PORT_MODE is MANUAL and is not intended for use in SEMI_AUTO or AUTO.

However, if PB_DETECT_CLASS is used while the PORT_n_PORT_MODE is SEMI_AUTO or AUTO, the respective bits are transferred over to the DETECT_CLASS_ENABLE.

4.19 PB_POWER_ENABLE (0x19)

| PB_POWER_ENABLE | | | | Register Address: 0x19 | | | |
|------------------------|--------------------|---------------------------|-------|-------------------------|-------|-------|-------|
| | | | | Access Type: Write Only | | | |
| | | | | Reset: 0000 0000 | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| PB_POWER_OFF | | | | PB_POWER_ON | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |
| Bit | Name | Description | | | | | |
| 7 | PORT4_PB_POWER_OFF | PORTn_PB_POWER_OFF | | | | | |
| 6 | PORT3_PB_POWER_OFF | Initiates Pushbutton OFF. | | | | | |
| 5 | PORT2_PB_POWER_OFF | 0 = Do Nothing | | | | | |
| 4 | PORT1_PB_POWER_OFF | 1 = Power OFF PORT n | | | | | |
| 3 | PORT4_PB_POWER_ON | PORTn_PB_POWER_ON | | | | | |
| 2 | PORT3_PB_POWER_ON | Initiates Pushbutton ON. | | | | | |
| 1 | PORT2_PB_POWER_ON | 0 = Do Nothing | | | | | |
| 0 | PORT1_PB_POWER_ON | 1 = Power ON PORT n | | | | | |

When a PORTn_PB_POWER_OFF is set, all bits associated with the PORTn being Powered OFF are set to its default reset values, which are mostly cleared with a few exceptions. This list also applies to OSS_EVENT, PORTn_RESET_PORT. This list also applies to OSS_EVENT, PORTn_RESET_PORT and when PORTn_PORT_MODE is set to SHUTDOWN.

- PORTn_POWER_ENABLE
- PORTn_POWER_GOOD
- PORTn_CLASS_DONE
- PORTn_DETECT_CC_DONE
- PORTn_DISCONNECTION
- PORTn_PCUT_FAULT_2P
- PORTnm_PCUT_FAULT_4P
- PORTn_ILIM_FAULT
- PORTn_START_FAULT
- PORTn_CLASS_STATUS
- PORTn_DETECTION_STATUS
- PORTn_CLASS_ENABLE
- PORTn_DETECT_CC_ENABLE
- PORTnm_CONNECTION_CHECK_RESULTS
- PORTn_POWER_ON_FAULT
- PORTnm_ILIM_BEHAVIOR
- PORTnm_PCUT_BEHAVIOR
- PORTnm_DISCONNECT_THRESH
- PORTnm_PCUT_ENABLE
- PORTn_CURRENT
- PORTn_VOLTAGE
- PORTn_PGOOD_FOLDBACK
- PORTn_INRUSH_FOLDBACK
- PORTn_DETECT_RESISTANCE
- PORTn_DETECT_CAPACITANCE
- PORTn_ASSIGNED_CLASS
- PORTn_REQUESTED_CLASS

- PORTn_AUTOCLASS_POWER
- PORTn_POLICE_2P
- PORTnm_POLICE_4P

If the host sets a PORTn_PB_POWER_ON, the PORTn_PORT_MODE is in SEMI_AUTO, it is expected that the PORTnm_PORT_ALLOCATION, PORTn_CLASS_ENABLE, and PORTn_DETECT_CC_ENABLE are already initialized.

Prior Detection, Connection Check and Class Probes that has already started are allowed to complete first. A new Detection, Connection Check and Classification are performed before the FET is finally turned on. If any faults occurred prior to the FET turn on, these are reported as PORTn_POWER_ON_FAULT events.

Once the FET is turned on, the PORTn_POWER_ENABLE is set. There is a short tINRUSH period to allow the PD to charge up their capacitors. After the tINRUSH if the PORTn DRAIN voltage does not settle to under 2V, the port is disconnected and a PORTn_START_FAULT is issued.

On the other hand, if the DRAIN voltage is under 2V, PORTn_POWER_GOOD is issued and the port has reaches POWER_GOOD state.

PORTn_POLICE_2P and PORTnm_POLICE_4P are initialized automatically based on PORTn_ASSIGNED_CLASS these registers are used later to check if the PD is exceeding its power budget. If the PD exceeds the negotiated power thresholds dictated by the various PORTn_PCUT_FAULT_2P, PORTnm_PCUT_FAULT_4P events would occur.

If PORTn_AUTO_AUTOCLASS is set and if the PD is Autoclass-capable, the PORTn_POLICE_2P and PORTnm_POLICE_4P are updated based on PORTn_AUTOCLASS_POWER. At any time after the Si3474 updates the PORTn_POLICE_2P and PORTnm_POLICE_4P registers, the host can choose to manage power by overwriting these police registers. The host can compute actual PD power by monitoring PORTn_CURRENT and PORTn_VOLTAGE and may choose to increase or decrease port power as part of power management.

If the host chooses to decrease police registers, it may choose to also set the PORTn_PCUT_DISABLE so that it can be informed that a PD exceeded the police register thresholds without turning off power to the PD.

In addition, the Si3474 also monitors for disconnections (PORTn_DISCONNECTION), current limit events (PORTn_ILIM_FAULT).

Typically, it is expected that PORTn_PB_POWER_ON to be set with both the PORTn_CLASS_ENABLE and the PORTn_DETECT_CC_ENABLE both set also. However, there is a special use case in MANUAL mode that would allow Detection, Connection Check and Classification to be skipped. If the host sets PORTn_PB_POWER_ON with the PORTn_PORT_MODE is in MANUAL Mode, and if PORTn_CLASS_ENABLE = 0 and PORTn_DETECT_CC_ENABLE = 0, Detection, Connection Check and Classification are all skipped and the port is powered on immediately. The PORTn_POLICE_2P and PORTnm_POLICE_4P are initialized based on PORTnm_POWER_ALLOCATION instead of PORTn_ASSIGNED_CLASS.

4.20 PB_RESET (0x1A)

| | | | | | | | | |
|-----------------|---------------|---|----------------|------------|-------|-------|-------|-------------------------|
| PB_RESET | | | | | | | | Register Address: 0x1A |
| | | | | | | | | Access Type: Write Only |
| | | | | | | | | Reset: 0000 0000 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| CLEAR_ALL_INTS | CLEAR_INT_PIN | | RESET_QUAD | RESET_PORT | | | | |
| EIGHT PORTS | NONE | | PORT1 to PORT4 | PORT4 | PORT3 | PORT2 | PORT1 | |

| Bit | Name | Description |
|-----|------------------|---|
| 7 | CLEAR_ALL_INTS | Clears the INTb pin by clearing all events on both Quads. 0 = Do Nothing 1 = Clear all events in all ports (both Quads) and negate INTb |
| 6 | CLEAR_INT_PIN | Clears the INTb pin directly in hardware without affecting any event bits. 0 = Do Nothing 1 = Clear INTb pin |
| 4 | RESET_QUAD | Registers in the current quad are initialized to Reset defaults. Registers in the other quad are unaffected. 0 = Do Nothing 1 = Reset registers in the Quad to reset defaults |
| 3 | PORT4_RESET_PORT | PORTn_RESET_PORT Initiates Port Reset 0 = Do Nothing 1 = Associated PORTn Registers are set to Reset Default values Refer to PORTn_PB_POWER_OFF for a list of registers initialized to Reset Default Values. If the port is powered, it will be shut off. |
| 2 | PORT3_RESET_PORT | |
| 1 | PORT2_RESET_PORT | |
| 0 | PORT1_RESET_PORT | |

PORTn_RESET_PORT clears event register similar to that of PORTn_PB_POWER_OFF. If PORTn is powered, the port will be shut off. Refer to PORTn_PB_POWER_OFF for the list of register that are set to Reset default values. The main difference between PORTn_RESET_PORT and PORTn_PB_POWER_OFF is that PORTn_RESET_PORT may be used regardless of what the PORTn_PORT_MODE is.

4.21 VENDOR_ID (0x1B), FIRMWARE_REVISION (0x41), CHIP_REVISION (0x43)

| | | | | | | | |
|------------------|---|---|---|--|---|---|---|
| VENDOR_ID | | | | Register Address: 0x1B Access Type: Read Only | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| MANUFACTURER_ID | | | | IC_ID | | | |
| 0 | 1 | 0 | 0 | 0 | 1 | 0 | 1 |

| | | | | | | | |
|--------------------------|---|---|---|--|---|---|---|
| FIRMWARE_REVISION | | | | Register Address: 0x41 Access Type: Read Only | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| MAJOR_REVISION | | | | MINOR_REVISION | | | |
| ? | ? | ? | ? | ? | ? | ? | ? |

| | | | | | | | |
|----------------------|---|---|---|--|---|---|---|
| CHIP_REVISION | | | | Register Address: 0x43 Access Type: Read Only | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| CHIP_REVISION | | | | | | | |
| ? | ? | ? | ? | ? | ? | ? | ? |

The purpose of MANUFACTURER_ID in the VENDOR_ID register is to allow the host to determine the manufacturer of the device in the presence of a multi-source design. This allows the host to make adjustments to the software to make adjustments to system software due to chip behavior across different vendors. The CHIP_ID effectively defines the product as an Si347x-Class device. Together, the MANUFACTURER_ID and the CHIP_ID is an overall identifier of a class of chips that may be similar to competitive offerings.

The VENDOR_ID is therefore static and does not change across revisions in either hardware or firmware.

The CHIP_REVISION tracks Si3474 hardware revisions.

The FIRMWARE_REVISION tracks firmware revisions. The upper nibble is a "major" revision, while the lower nibble is a "minor" revision.

| Ordering Part Number | Chip Revision |
|----------------------|---------------|
| Si3474A-A01-IM | 0x01 |
| Si3474B-A01-IM | 0x00 |

4.22 AUTOCLASS_CONNECTION_CHECK (0x1C)

| | | | | | | | |
|-----------------------------------|-------|-------|-------|---------------------------|---|--------|---|
| AUTOCLASS_CONNECTION_CHECK | | | | Register Address: 0x1C | | | |
| | | | | Access Type: Read / Write | | | |
| | | | | Reset: 0000 0000 | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| AUTOCLASS_DETECTED | | | | CONNECTION_CHECK_RESULTS | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT34 | | PORT12 | |

| Bit | Name | Description |
|-----|---------------------------------|--|
| 7 | PORT4_AUTOCLASS_DETECTED | PORTn_AUTOCLASS_DETECTED Indicates that the PD is Autoclass-capable and that the classification occurred on PORTn of a 4P Port 0 = PD not Autoclass-capable 1 = PD is Autoclass-capable |
| 6 | PORT3_AUTOCLASS_DETECTED | |
| 5 | PORT2_AUTOCLASS_DETECTED | |
| 4 | PORT1_AUTOCLASS_DETECTED | |
| 3 | PORT34_CONNECTION_CHECK_RESULTS | PORTnm_CONNECTION_CHECK_RESULTS PORTnm Connection Check Results 00 = UNKNOWN 01 = Single Signature 10 = Dual Signature 11 = Invalid Available when PORTn_DETECT_CC_DONE event is set. But since there is no interrupt for this, PORTn_CLASS_DONE can be used instead |
| 2 | | |
| 1 | | |
| 0 | | |

The AUTOCLASS_CONNECTION_CHECK is set to Reset default values when these occur:

1. PORTn_PORT_MODE = SHUTDOWN
2. PORTn_PB_POWER_OFF = 1
3. PORTn_RESET_PORT = 1
4. OSS_EVENT
5. RESET_QUAD = 1

4.23 PORT1_POLICE_2P to PORT4_POLICE_2P, PORT12_POLICE_4P, PORT34_POLICE_4P (0x1E – 0x21, 0x2A, 0x2B)

| Name | Address | Access Type | Reset | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------------|---------|-------------|-----------|--|---|---|---|---|---|---|---|
| PORT1_POLICE_2P | 0x1E | R/W | 1111 1111 | PORTn_POLICE_2P Minimum 2P PCUT Threshold (Watts) = PORTn_POLICE_2P * 0.5 W | | | | | | | |
| PORT2_POLICE_2P | 0x1F | R/W | 1111 1111 | | | | | | | | |
| PORT3_POLICE_2P | 0x20 | R/W | 1111 1111 | | | | | | | | |
| PORT4_POLICE_2P | 0x21 | R/W | 1111 1111 | | | | | | | | |
| PORT12_POLICE_4P | 0x2A | R/W | 1111 1111 | PORTnm_POLICE_4P Minimum 4P PCUT Threshold (Watts) = PORTnm_POLICE_4P * 0.5 W | | | | | | | |
| PORT34_POLICE_4P | 0x2B | R/W | 1111 1111 | | | | | | | | |

PORTn_POLICE_2P and PORTnm_POLICE_4P are registers that are initialized by the Si3474 as part of PORTn_PB_POWER_ON. The PORTnm_POWER_ALLOCATION, in conjunction with the PD Requested Class will negotiate to an ASSIGNED_CLASS. The PCUT thresholds are then set by the Si3474.

For 4PP Ports, the PCUT thresholds are evaluated for individual 2P Ports against the PORTn_POLICE_2P thresholds, then the power from the two 2P ports are then added and evaluated against the PORTnm_POLICE_4P thresholds.

Any of these police registers can be adjusted based on the actual power used by the port. Once the port has achieved a POWER_GOOD state, the police registers can be written and the Si3474 will then evaluate power thresholds as set by these police registers.

It is important to note that the power values represented in the police register interfaces are MINIMUM threshold. The actual internal thresholds are increased by 5%.

PORTn_POLICE_2P are set to Reset Default Values when:

1. Setting PORTn_PORT_MODE = SHUTDOWN
2. Setting PORTn_PB_POWER_OFF
3. Setting PORTn_RESET_PORT
4. Setting RESET_QUAD
5. OSS Event

4.24 PORT_REMAP (0x26)

| | | | | | | | | |
|-------------------|---|-------|---|-------|---|-------|---|---------------------------|
| PORT_REMAP | | | | | | | | Register Address: 0x26 |
| | | | | | | | | Access Type: Read / Write |
| | | | | | | | | Reset: 11 10 01 00 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| REMAP | | REMAP | | REMAP | | REMAP | | |
| PORT4 | | PORT3 | | PORT2 | | PORT1 | | |

| Bit | Name | Description |
|-----|-------------|--|
| 7-6 | PORT4_REMAP | PORTn_REMAP PORTn_REMAP defines the physical pins used when referencing the logical concept called "PORTn" |
| 5-4 | PORT3_REMAP | |
| 3-2 | PORT2_REMAP | |
| 1-0 | PORT1_REMAP | 00 = Use physical pins GATE1, DRAIN1, SENSE1 01 = Use physical pins GATE2, DRAIN2, SENSE2 10 = Use physical pins GATE3, DRAIN3, SENSE3 11 = Use physical pins GATE4, DRAIN4, SENSE4 PORTnm_2P4P_MODE must be written, using a single write, immediately after reset along with PORTnm_2P4P_MODE in POWER_ALLOCATION. For example, the concept called "PORT4", by default, uses DRAIN4. The PORT4_REMAP field is therefore '11'. |

The port remapping feature allows the host to rearrange the sequencing of the Si3474 ports so that it better aligns to the end product's port alignment.

There are some restrictions to be aware of:

1. A Physical Port must appear, and may only appear in one Logical Port.
2. If two 2P Ports form a 4P Port, the two 2P Ports must both be listed on the same PORT_REMAP Nibble (e.g., both on upper nibble or both on lower nibble).

[Figure 4.1 RJ45 Example Layouts on page 59](#) shows a graphic illustration of how to create a logical-to-physical mapping by first starting with a sketch of where the DRAIN pins would line up to where your RJ45 jacks would be.

If the same physical pin code is assigned to more than one PORTn_REMAP field, the Si3474 rejects the setting. It is best to confirm if the Si3474 accepted the remap setting by reading back PORT_REMAP register.

The PORT_REMAP register is one of two registers that must be written once immediately after reset. Even if the intention is to use the default PORT_REMAP, PORT_REMAP must be written with 0xE4. Without this, the Si3474 will not function.

Once PORT_REMAP is written, ONLY a hardware reset can be used to allow PORT_REMAP to be written again.

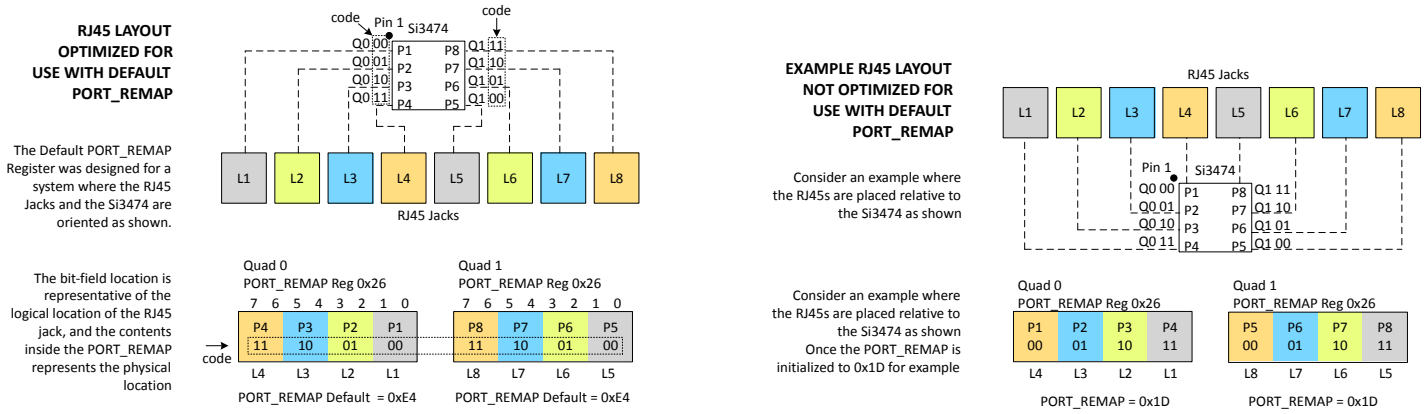


Figure 4.1. RJ45 Example Layouts

4.25 PORTn_MULTIBIT_PRIORITY (0x27, 0x28)

| Name | Address | Access Type | Reset | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------------|---------|-------------|-----------|-------------------------|---|---|---|-------------------------|---|---|---|
| PORT1_PORT2_MULTIBIT_PRIORITY | 0x27 | R/W | 0000 0000 | PORT2_MULTIBIT_PRIORITY | | | | PORT1_MULTIBIT_PRIORITY | | | |
| PORT3_PORT4_MULTIBIT_PRIORITY | 0x28 | R/W | 0000 0000 | PORT4_MULTIBIT_PRIORITY | | | | PORT3_MULTIBIT_PRIORITY | | | |

| Address | Bit | Name | Description |
|---------|-----|-------------------------|--|
| 0x27 | 6-4 | PORT2_MULTIBIT_PRIORITY | PORTn_MULTIBIT_PRIORITY |
| 0x27 | 2-0 | PORT1_MULTIBIT_PRIORITY | |
| 0x28 | 6-4 | PORT4_MULTIBIT_PRIORITY | |
| 0x28 | 2-0 | PORT3_MULTIBIT_PRIORITY | 111 = Receiving OSS Code 111 or lower shuts down PORTn (lowest priority). 110 = Receiving OSS Code 110 or lower shuts down PORTn. 101 = Receiving OSS Code 101 or lower shuts down PORTn. 100 = Receiving OSS Code 100 or lower shuts down PORTn. 011 = Receiving OSS Code 011 or lower shuts down PORTn. 010 = Receiving OSS Code 010 or lower shuts down PORTn. 001 = Receiving OSS Code 001 or lower shuts down PORTn. 000 = Receiving OSS Code 000 shuts down the port (highest priority). Note that the higher the PORTn_MULTIBIT_PRIORITY setting, the more OSS Codes that can shut it down. As such, the lower the PORTn_MULTIBIT_PRIORITY is, the higher the priority of the port. |

If MULTIBIT_PRIORITY_ENABLE = 1, then PORT1_PORT2_MULTIBIT_PRIORITY and PORT3_PORT4_MULTIBIT_PRIORITY defines port power priority and governs OSS action. See 2.7.3 Class Power On for figures showing the operation and timing diagram of the OSS pin in multi-bit mode. The most significant bit is sent first. The priority for PORTn is defined by a 3-bit specified by PORTn_MULTIBIT_PRIORITY. A port whose priority setting is '000' has the highest priority; priority setting of '111' has the lowest priority. When the host system wants certain priority ports be shut down, it will transmit the "shutdown code" over the OSS pin. Ports whose port priority settings are greater than or equal to the received shutdown code will be turned off. For example, a received OSS shutdown code of '101' will shut down ports whose port priority settings are '101', '110' or '111'.

4.26 POWER_ALLOCATION (0x29)

| | | | | | | | | |
|-------------------------|------------------|---|---|-----------|------------------|---|---|---------------------------|
| POWER_ALLOCATION | | | | | | | | Register Address: 0x29 |
| | | | | | | | | Access Type: Read / Write |
| | | | | | | | | Reset: 0000 0000 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| 2P4P_MODE | POWER_ALLOCATION | | | 2P4P_MODE | POWER_ALLOCATION | | | |
| PORT34 | | | | PORT12 | | | | |

| Bit | Name | Description |
|-----|-------------------------|---|
| 7 | PORT34_2P4P_MODE | PORTnm_2P4P_MODE |
| 3 | PORT12_2P4P_MODE | Assigns whether if PORTn and PORTm should be treated as separate 2P Ports, or should be combined into a single PORTnm 4PP 0 = PORTn and PORTm are separate 2P Ports 1 = PORTn and PORTm combine as PORTnm 4PP PORTnm_2P4P_MODE must be initialized immediately after reset, using a single write, along with PORTn_REMAP |
| 6-4 | PORT34_POWER_ALLOCATION | PORTnm_POWER_ALLOCATION |
| 2-0 | PORT12_POWER_ALLOCATION | |

| PORTnm_2P4P_MODE | PORTnm_POWER_ALLOCATION | | | 4PP Port Single Signature | 4PP Port Dual Signature | 2PP Port |
|------------------|-------------------------|-------|-------|---------------------------|-----------------------------|-----------------------------|
| | Bit 2 | Bit 1 | Bit 0 | | | |
| 0 | 0 | 0 | 0 | | | 15 W Class 3 + 15 W Class 3 |
| 0 | 0 | 1 | 1 | | | 30 W Class 4 + 30 W Class 4 |
| 0 | 1 | X | X | | | |
| 1 | 0 | 0 | 0 | 15 W Class 3 | 7 W Class 2 + 7 W Class 2 | |
| 1 | 0 | 0 | 1 | | | |
| 1 | 0 | 1 | 0 | | | |
| 1 | 0 | 1 | 1 | 30 W Class 4 | 15 W Class 3 + 15 W Class 3 | |
| 1 | 1 | 0 | 0 | 45 W Class 5 | 30 W Class 4 + 15 W Class 3 | |
| 1 | 1 | 0 | 1 | 60 W Class 6 | 30 W Class 4 + 30 W Class 4 | |
| 1 | 1 | 1 | 0 | 75 W Class 7 | 45 W Class 5 + 30 W Class 4 | |
| 1 | 1 | 1 | 1 | 90 W Class 8 | 45 W Class 5 + 45 W Class 5 | |

4.27 TEMPERATURE (0x2C)

| | | | | | | | | |
|---|---|---|---|---|---|---|---|------------------------|
| TEMPERATURE | | | | | | | | Register Address: 0x2C |
| | | | | | | | | Access Type: Read Only |
| | | | | | | | | Reset: ???? |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| TEMPERATURE | | | | | | | | |
| Approximate Chip Temperature in Centigrade is (TEMPERATURE * 0.652) – 20 | | | | | | | | |

4.28 ILIM_PCUT_DISCONNECT_4P (0x2D)

| | | | | | | | |
|---|--------|---------------|--------|-------------|--------|-------------------|--------|
| ILIM_PCUT_DISCONNECT_4P | | | | | | | |
| Register Address: 0x2D | | | | | | | |
| Access Type: Read/Write* | | | | | | | |
| *The upper nibble of this register is read/write while the lower nibble is read-only. | | | | | | | |
| Reset: 00 00 11 00 | | | | | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| ILIM_BEHAVIOR | | PCUT_BEHAVIOR | | PCUT_ENABLE | | DISCONNECT_THRESH | |
| PORT34 | PORT12 | PORT34 | PORT12 | PORT34 | PORT12 | PORT34 | PORT12 |

| Bit | Name | Description |
|-----|--------------------------|--|
| 7 | PORT34_ILIM_BEHAVIOR | PORTnm_ILIM_BEHAVIOR |
| 6 | PORT12_ILIM_BEHAVIOR | Defines 4PP ILIM Behavior when an ILIM fault occurs on one of the 2PP ports 0 = Only the faulting port is turned off 1 = Both ports are turned off |
| 5 | PORT34_PCUT_BEHAVIOR | PORTnm_PCUT_BEHAVIOR |
| 4 | PORT12_PCUT_BEHAVIOR | Defines 4PP ILIM Behavior when a PCUT fault occurs on one of the 2PP ports 0 = Only the faulting port is turned off 1 = Both ports are turned off |
| 3 | PORT34_PCUT_ENABLE | PORTnm_PCUT_ENABLE |
| 2 | PORT12_PCUT_ENABLE | Defines 4PP PCUT Enable 0 = 4PP PCUT is disabled 1 = 4PP PCUT is enabled |
| 1 | PORT34_DISCONNECT_THRESH | PORTnm_DISCONNECT_THRESH |
| 0 | PORT12_DISCONNECT_THRESH | Status of which 4PP Disconnection Threshold the Si3474 chose 0 = Si3474 chose disconnection threshold for SS Class 0-4 1 = Si3474 chose disconnection threshold for SS Class 5-8 |

ILIM_PCUT_DISCONNECT_4P is initialized to Reset default behavior when the following occurs:

1. PORTn_PORT_MODE = SHUTDOWN
2. PORTn_PB_POWER_OFF = 1
3. PORTn_RESET_PORT = 1
4. OSS_EVENT
5. RESET_QUAD = 1

4.29 Parametric Measurement Registers (0x2E – 0x3F)

VPWR, PORTn_VOLTAGE and PORTn_CURRENT are each 14-bit registers straddled across two bytes.

The host must use an SMBus Burst Read of 16-bits so for proper the proper LSB / MSB pairing. An improper LSB / MSB pairing will result in a 256 code error if the measurement happens to be near a multiple of 256.

All of the 16-bit registers begin at an even byte. The SMBus Burst Read should therefore have an even Register Address. The first byte returned from the SMBus Read would be the LSB, followed by the MSB.

VPWR can be read at any time.

PORTn_VOLTAGE and PORTn_CURRENT can be read as long as the port is in POWER_GOOD state. PORTn_VOLTAGE and PORTn_CURRENT are cleared when the following occurs:

1. PORTn_PORT_MODE = SHUTDOWN
2. PORTn_PB_POWER_OFF = 1
3. PORTn_RESET_PORT = 1
4. OSS_EVENT
5. RESET_QUAD = 1

4.30 VPWR, PORT1_VOLTAGE, PORT2_VOLTAGE, PORT3_VOLTAGE, PORT4_VOLTAGE (0x2E/0x2F, 0x32/0x33, 0x36/0x37, 0x3A/0x3B, 0x3E/0x3F)

| Name | Address | Access Type | Reset | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------|---------|-------------|-----------|--|---|---|---|---|---|---|---|
| VPWR_LSB | 0x2E | RO | ???? ???? | VPWR Voltage (in volts) = $60 * ((VPWR_MSB \ll 8) + VPWR_LSB) / 16384$ | | | | | | | |
| VPWR_MSB | 0x2F | RO | 00?? ???? | | | | | | | | |
| PORT1_VOLTAGE_LSB | 0x32 | RO | 0000 0000 | PORTn Voltage (in volts) = $60 * ((PORTn_VOLTAGE_MSB \ll 8) + PORTn_VOLTAGE_LSB) / 16384$ | | | | | | | |
| PORT1_VOLTAGE_MSB | 0x33 | RO | 0000 0000 | | | | | | | | |
| PORT2_VOLTAGE_LSB | 0x36 | RO | 0000 0000 | | | | | | | | |
| PORT2_VOLTAGE_MSB | 0x37 | RO | 0000 0000 | | | | | | | | |
| PORT3_VOLTAGE_LSB | 0x3A | RO | 0000 0000 | | | | | | | | |
| PORT3_VOLTAGE_MSB | 0x3B | RO | 0000 0000 | | | | | | | | |
| PORT4_VOLTAGE_LSB | 0x3E | RO | 0000 0000 | | | | | | | | |
| PORT4_VOLTAGE_MSB | 0x3F | RO | 0000 0000 | | | | | | | | |

4.31 PORT1_CURRENT, PORT2_CURRENT, PORT3_CURRENT, PORT4_CURRENT (0x30/0x31, 0x34/0x35, 0x38/0x39, 0x3C/0x3D)

| Name | Address | Access Type | Reset | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------|---------|-------------|-----------|--|---|---|---|---|---|---|---|
| PORT1_CURRENT_LSB | 0x30 | RO | 0000 0000 | PORTn Current (in mA) = $1000 * ((PORTn_CURRENT_MSB \ll 8) + PORTn_CURRENT_LSB) / 16384$ | | | | | | | |
| PORT1_CURRENT_MSB | 0x31 | RO | 0000 0000 | | | | | | | | |
| PORT2_CURRENT_LSB | 0x34 | RO | 0000 0000 | | | | | | | | |
| PORT2_CURRENT_MSB | 0x35 | RO | 0000 0000 | | | | | | | | |
| PORT3_CURRENT_LSB | 0x38 | RO | 0000 0000 | | | | | | | | |
| PORT3_CURRENT_MSB | 0x39 | RO | 0000 0000 | | | | | | | | |
| PORT4_CURRENT_LSB | 0x3C | RO | 0000 0000 | | | | | | | | |
| PORT4_CURRENT_MSB | 0x3D | RO | 0000 0000 | | | | | | | | |

4.32 MAX_ILIM_MANUAL_POLICE (0x40)

| MAX_ILIM | | | | MANUAL_POLICE | | | |
|-----------------|-------|-------|-------|----------------------|-------|-------|-------|
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| MAX_ILIM | | | | MANUAL_POLICE | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |

| Bit | Name | Description |
|-----|---------------------|--|
| 7 | PORT4_MAX_ILIM | PORTn_MAX_ILIM Allows increasing of the port's current limit setting to the maximum possible setting allowed by the Si3474 |
| 6 | PORT3_MAX_ILIM | |
| 5 | PORT2_MAX_ILIM | |
| 4 | PORT1_MAX_ILIM | 0 = Port Current Limit not yet maximized 1 = Max Port Current Limit When the port is powered up to POWER_GOOD state, the PORTn_MAX_ILIM is set by the device if the highest 1275 mA current limit setting is used. For the ports whose PORTn_MAX_ILIM is zero, the host can set it to 1 to maximize the current limit to 1275 mA. When set, the PORTn_TLIM setting is enforced. The PORTn_PGOOD_FOLDBACK is also used. When using the Si3474A-A01 or Si3474B-A01, a FLASH Update is needed for PORTn_MAX_ILIM to function as documented. Contact Skyworks for more details. |
| 3 | PORT4_MANUAL_POLICE | PORTn_MANUAL_POLICE Defines ports for which the police register settings are manually set 0 = The police registers are updated automatically based on PD Assigned Class 1 = The police registers are initialized by the host before PORTn_PB_POWER_ON. The host is responsible for maintaining the police registers |
| 2 | PORT3_MANUAL_POLICE | |
| 1 | PORT2_MANUAL_POLICE | |
| 0 | PORT1_MANUAL_POLICE | |

4.33 I2C_WATCHDOG (0x42)

| I2C_WATCHDOG | | | | | | | | Register Address: 0x42 |
|---------------------|---|---|------------------|---|---|---|-----------------|---------------------------|
| | | | | | | | | Access Type: Read / Write |
| | | | | | | | | Reset: 000 1011 0 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| 0 | 0 | 0 | WATCHDOG_DISABLE | | | | WATCHDOG_STATUS | |

| Bit | Name | Description |
|-----|------------------|--|
| 4-1 | WATCHDOG_DISABLE | WATCHDOG_DISABLE Enables the I ² C Watchdog 1011 = Disable the I ² C Watchdog NOT 1011 = Enable the I ² C Watchdog |
| 0 | WATCHDOG_STATUS | 0 = I ² C Watchdog did not occur 1 = I ² C Watchdog occurred |

The Si3474 implements an I²C transaction watchdog. The I²C transaction watchdog is disabled by default and can be enabled by setting WATCHDOG_DISABLE to any bit pattern except 0xB. When WATCHDOG_DISABLE bit is set, the transaction watchdog will begin a 50 ms timer whenever an I²C Start Bit is detected. If an I²C Stop Bit is not detected within the 50 ms time period, the Si3474 restarts the I²C subsystem and performs an action equivalent to RESET_QUAD. This results in all ports being shut off.

Once the WATCHDOG_STATUS bit is set, it remains set until the host sets it to 0.

The main benefit of enabling the I²C WATCHDOG feature is to allow recovery if an I²C miscommunication results in the Si3474 in a stuck state, continuously asserting the SDA pin.

Consider this condition as an example of how the Si3474 could end up asserting the SDA continuously:

Let's say that during an SMBUS Read during which the Si3474 is driving SDA to supply data to the host. Let's say that for some reason, the Si3474 somehow misses an SCL clock transition. If this occurs, the Si3474 may be expecting more SCL transitions as it believes that it needs to send more data bits. So, it drives the SDA pin believing that there would be additional SCL clocks. The Si3474 in this case could be driving the SDA low, thereby hanging the I²C Bus. By enabling the I²C WATCHDOG feature, the I²C Bus is unlocked, and all ports are effectively placed in a reset state so that the host has a known starting point to begin again.

Although an I²C fault would lead to powering down ports all I²Cs, it places the Si3474 in a known state, ready for the host to reinitialize and start anew.

4.34 DETECT_RESISTANCE (0x44 – 0x47)

| Name | Address | Access Type | Reset | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|---------|-------------|-----------|---|---|---|---|---|---|---|---|
| PORT1_DETECT_RESISTANCE | 0x44 | RO | 0000 0000 | PORTn PD RESISTANCE (in kΩ) = (50/256) * PORTn_DETECT_RESISTANCE Updated when PORTn_DETECT_CC_DONE event is set. | | | | | | | |
| PORT2_DETECT_RESISTANCE | 0x45 | RO | 0000 0000 | | | | | | | | |
| PORT3_DETECT_RESISTANCE | 0x46 | RO | 0000 0000 | | | | | | | | |
| PORT4_DETECT_RESISTANCE | 0x47 | RO | 0000 0000 | | | | | | | | |

4.35 DETECT_CAPACITANCE (0x48 – 0x4B)

| Name | Address | Access Type | Reset | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------------------------|---------|-------------|-----------|--|---|---|---|---|---|---|---|
| PORT1_DETECT_CAPACITANCE | 0x48 | RO | 0000 0000 | PORTn PD Capacitance (in uF) = PORTn_DETECT_CAPACITANCE * 0.05 CAP_MEAS_ENABLE must be set for these registers to be updated. Capacitance Measurement is initiated when the detection result is 'Capacitive'. PORTn_DETECT_CAPACITANCE is ready once PORTn_DETECT_CC_DONE event is set. | | | | | | | |
| PORT2_DETEEC_CAPACITANCE | 0x49 | RO | 0000 0000 | | | | | | | | |
| PORT3_DETECT_CAPACITANCE | 0x4A | RO | 0000 0000 | | | | | | | | |
| PORT4_DETECT_CAPACITANCE | 0x4B | RO | 0000 0000 | | | | | | | | |

When using the Si3474A-A01 or Si3474B-A01, a FLASH Update is needed for this register to function as documented. Contact Skyworks for more details.

4.36 CLASS_RESULTS (0x4C – 0x4F)

| Name | Address | Access Type | Reset | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------|-------------|-----------|----------------|---|---|---|-----------------|---|---|---|
| PORT1_CLASS_RESULTS | 0x4C | RO | 0000 0000 | ASSIGNED_CLASS | | | | REQUESTED_CLASS | | | |
| PORT2_CLASS_RESULTS | 0x4D | RO | 0000 0000 | ASSIGNED_CLASS | | | | REQUESTED_CLASS | | | |
| PORT3_CLASS_RESULTS | 0x4E | RO | 0000 0000 | ASSIGNED_CLASS | | | | REQUESTED_CLASS | | | |
| PORT4_CLASS_RESULTS | 0x4F | RO | 0000 0000 | ASSIGNED_CLASS | | | | REQUESTED_CLASS | | | |

| Address | Bit | Name | Description |
|---------|-------|-----------------------|---|
| 0x4C | 7 - 4 | PORT1_ASSIGNED_CLASS | PORTn_ASSIGNED_CLASS The assigned class represents the result of Class Power On initiated by a PORTn_PB_POWER_ON |
| 0x4D | 7 - 4 | PORT2_ASSIGNED_CLASS | |
| 0x4E | 7 - 4 | PORT3_ASSIGNED_CLASS | |
| 0x4F | 7 - 4 | PORT4_ASSIGNED_CLASS | |
| 0x4C | 3 - 0 | PORT1_REQUESTED_CLASS | PORTn_REQUESTED_CLASS When a PORTn_PB_POWER_ON is issued, the most recent Class Probe results are stored here. The Class Probe is effectively the requested class. |
| 0x4D | 3 - 0 | PORT2_REQUESTED_CLASS | |
| 0x4E | 3 - 0 | PORT3_REQUESTED_CLASS | |
| 0x4F | 3 - 0 | PORT4_REQUESTED_CLASS | |

The following table aims to provide a summary of when to expect values in the various fields that may contain Classification information.

Table 4.2. Classification Event Timing

| Classification Code | PORTn_CLASS_STATUS | PORTn_REQUESTED_CLASS | PORTn_ASSIGNED_CLASS | Comments |
|---------------------|-------------------------|-----------------------|----------------------|--|
| 0000 | UNKNOWN | UNKNOWN | UNKNOWN | |
| 0001 | Class 1 | Class 1 | Class 1 | |
| 0010 | Class 2 | Class 2 | Class 2 | |
| 0011 | Class 3 | Class 3 | Class 3 | |
| 0100 | Class 4 | Class 4 | Class 4 | |
| 0101 | | | | |
| 0110 | Class 0 | Class 0 | | If a Class 0 is requested, it is converted to Class 3 |
| 0111 | Overcurrent | | | |
| 1000 | Class 5 - 4P SS | Class 5 - 4P SS | Class 5 - 4P SS | |
| 1001 | Class 6 - 4P SS | Class 6 - 4P SS | Class 6 - 4P SS | |
| 1010 | Class 7 - 4P SS | Class 7 - 4P SS | Class 7 - 4P SS | |
| 1011 | Class 8 - 4P DS | Class 8 - 4P DS | Class 8 - 4P DS | |
| 1100 | Class 4+ Type 1 limited | | | Requested Class \geq CLASS_4, demoted to CLASS_3 |
| 1101 | Class 5 - 4P DS | Class 5 - 4P DS | Class 5 - 4P DS | |
| 1110 | — | — | — | |
| 1111 | Class mismatch | | | This is temporary status setting as the classification is repeated |

Note:

1. Red Text: Possible if unsuccessful Class Power On (PORTn_POWER_ON_FAULT in POWER_ON_FAULT register).
2. Green Text: Updated during Class Probe (PORTn_CLASS_DONE in CLASS_DETECT_STATUS).
3. Blue Text: Updated during Class Power On (PORTn_POWER_GOOD in POWER_STATUS register).
4. All Initialized to UNKNOWN:
 - PORTn_PORT_MODE = SHUTDOWN
 - PORTn_PB_POWER_OFF = 1
 - PORTn_RESET_PORT = 1
 - OSS_EVENT
 - RESET_QUAD = 1

4.37 AUTOCLASS_CONTROL (0x50)

| AUTOCLASS_CONTROL | | | | Register Address: 0x50 | | | |
|--------------------------|------------------------|--|-------|---------------------------|-------|-------|-------|
| | | | | Access Type: Read / Write | | | |
| | | | | Reset: 0000 0000 | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| MANUAL_AUTOCLASS | | | | AUTO_AUTOCLASS | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | PORT4 | PORT3 | PORT2 | PORT1 |
| Bit | Name | Description | | | | | |
| 7 | PORT4_MANUAL_AUTOCLASS | PORTn_MANUAL_AUTOCLASS Initiate an autotclass measurement. 0 = No Action 1 = Manually initiate an Autoclass power measurement. | | | | | |
| 6 | PORT3_MANUAL_AUTOCLASS | | | | | | |
| 5 | PORT2_MANUAL_AUTOCLASS | | | | | | |
| 4 | PORT1_MANUAL_AUTOCLASS | Once set, PORTn_MANUAL_AUTOCLASS clears itself once the results in PORTn_AUTOCLASS_POWER is ready. It is recommended that the host makes use of this auto-clearing behavior to determine that PORTn_AUTOCLASS_POWER is ready to be read. Once the PORTn_AUTOCLASS_POWER is updated, the host may then add some margin, then update the related PORTn_POLICE_2P and/or PORTnm_POLICE_4P registers. | | | | | |
| 3 | PORT4_AUTO_AUTOCLASS | PORTn_AUTO_AUTOCLASS PORTn_AUTO_AUTOCLASS Enable 0 = Disable AUTO Autoclass 1 = Enables AUTO Autoclass | | | | | |
| 2 | PORT3_AUTO_AUTOCLASS | | | | | | |
| 1 | PORT2_AUTO_AUTOCLASS | | | | | | |
| 0 | PORT1_AUTO_AUTOCLASS | Must be initialized before initiating PORTn_PB_POWER_ON In the presence of an autotclass-capable PD, the related PORTn_POLICE_2P and/or PORTnm_POLICE_4P registers are updated based on some margin in addition to the measurement stored in PORTn_AUTOCLASS_POWER. | | | | | |

PORTn_AUTO_AUTOCLASS must be set prior to a PORTn_PB_POWER_ON.

An Autoclass procedure is performed during the Class Power On that occurs due to a PORTn_PB_POWER_ON. If the Si3474 detects an Autoclass request from a PD, the PORTn_AUTOCLASS_DETECTED is set.

Once the PORT has reached POWER_GOOD, the PD is expected to draw its maximum power during the first few seconds after powering up. The Si3474 automatically measures the PD power and updates the police registers based on the measured power.

In the 802.3bt standard, it is possible to negotiate a manual autotclass procedure between the PSE and PD through Data Link Layer messaging. The host can set the PORTn_MANUAL_AUTOCLASS at the time when the PD is expected to be drawing full power as part of this Data Link Layer Autotclass protocol. Once PORTn_MANUAL_AUTOCLASS is set, the Si3474 performs a power measurement. Once the power measurement is ready, the PORTn_MANUAL_AUTOCLASS is cleared as an indicator to the host that the PORTn_AUTOCLASS_POWER is ready.

In a MANUAL AUTOCLASS measurement is made, the police registers are not updated, and it is the host's responsibility to set up the various police registers based on the PORTn_AUTOCLASS_POWER results.

4.38 PORT1_AUTOCLASS_RESULTS, PORT2_AUTOCLASS_RESULTS, PORT3_AUTOCLASS_RESULTS, PORT4_AUTOCLASS_RESULTS (0x51 – 0x54)

| Name | Addr | Access Type | Reset | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|------|-------------|-----------|---|-----------------|---|---|---|---|---|---|
| PORT1_AUTOCLASS_RESULTS | 0x51 | RO | 0000 0000 | 0 | AUTOCLASS_POWER | | | | | | |
| PORT2_AUTOCLASS_RESULTS | 0x52 | RO | 0000 0000 | 0 | AUTOCLASS_POWER | | | | | | |
| PORT3_AUTOCLASS_RESULTS | 0x53 | RO | 0000 0000 | 0 | AUTOCLASS_POWER | | | | | | |
| PORT4_AUTOCLASS_RESULTS | 0x54 | RO | 0000 0000 | 0 | AUTOCLASS_POWER | | | | | | |

| Addr | Bit | Name | Description |
|------|-------|-----------------------|--|
| 0x51 | 6 - 0 | PORT1_AUTOCLASS_POWER | PORTn_AUTOCLASS_POWER Holds the AUTOCLASS_POWER information Power (in Watts) = PORTn_AUTOCLASS_POWER * 0.5 |
| 0x52 | 6 - 0 | PORT2_AUTOCLASS_POWER | |
| 0x53 | 6 - 0 | PORT3_AUTOCLASS_POWER | |
| 0x54 | 6 - 0 | PORT4_AUTOCLASS_POWER | |

4.39 ALTERNATIVE_FOLDBACK (0x55)

| ALTERNATIVE_FOLDBACK | | | | | | | | Register Address: 0x50 | | | |
|-----------------------------|----------------------|-------|-------|---|---|---|---|---------------------------|--|--|--|
| | | | | | | | | Access Type: Read / Write | | | |
| | | | | | | | | Reset: 0000 0000 | | | |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | | |
| PGOOD_FOLDBACK | | | | — | | | | | | | |
| PORT4 | PORT3 | PORT2 | PORT1 | | | | | | | | |
| Bit | Name | | | Description | | | | | | | |
| 7 | PORT4_PGOOD_FOLDBACK | | | PORTn_PGOOD_FOLDBACK | | | | | | | |
| 6 | PORT3_PGOOD_FOLDBACK | | | When PORTn is in POWER_GOOD state and the PD momentarily increases its current draw, setting this bit decreases the level at which the PORTn fold-backs the port voltage so the current can be supplied at a higher port voltage, thereby increasing the maximum power delivery to the PD | | | | | | | |
| 5 | PORT2_PGOOD_FOLDBACK | | | | | | | | | | |
| 4 | PORT1_PGOOD_FOLDBACK | | | | | | | | | | |
| | | | | 0 = Normal Voltage Foldback for port in POWER_GOOD state 1 = Decrease level of Port Voltage Foldback | | | | | | | |

4.40 FLASH REGISTERS (0x5F – 0x63)

Refer to 2.13.1 Updating Si3474 Flash for information on the use of these registers.

5. Electrical Characteristics Si3474

Table 5.1. Recommended Operating Conditions¹

| Parameter | Symbol | Test Condition/Note | Min | Typ | Max | Unit |
|--|----------------------|-----------------------------|-----|-----|-----|------|
| VPWR Input Supply Voltage | V _{PWR} | IEEE Type 3 when port is ON | 50 | — | 57 | V |
| | | IEEE Type 4 when port is ON | 52 | — | 57 | V |
| VPWR Slew Rate | V _{PWRSLEW} | | — | — | 1 | V/μs |
| VDD Supply Voltage | V _{DD} | | 3.0 | 3.3 | 3.6 | V |
| Operating Ambient Temperature ² | T _{AMB} | | −40 | — | 85 | °C |

Note:

- All specification voltages are referenced with respect to DGND. These specifications apply over the recommended operating voltage and temperature ranges of the device unless noted otherwise.
- The Si3474 includes internal thermal shutdown above 125 °C.

Table 5.2. Electrical Specifications

These specifications apply over the recommended operating voltage and temperature ranges of the device specified in [Table 5.1 Recommended Operating Conditions¹ on page 70](#) unless otherwise noted. Typical performance is for T_A = 25 °C, V_{DD} = AGND + 3.3 V, AGND and DGND = 0 V, and VPWR at 54 V. V_{PORTn}, V_{CLASS}, and V_{MARK} voltages are referenced with respect to V_{DRAIN}. All other voltages are referenced with respect to GND.

| Parameter | Symbol | Test Condition/Note | Min | Typ | Max | Unit |
|--|---------------------------|---|-----|------|-----|------|
| Power Supply Voltages | | | | | | |
| VPWR Under Voltage Lock Out | V _{PWR_UVLO} | Level below which chip is not operational | 25 | 31 | 34 | V |
| VPWR UVLO Input Voltage (to turn on) | V _{UVLO_ON} | | 25 | 28 | — | V |
| VPWR UVLO Input Voltage (to turn off) | V _{UVLO_OFF} | | — | 31 | 34 | V |
| VDD UVLO Warning Voltage | V _{DD_UVLO_WARN} | Digital interface still responds, but VDD_UVLO bit will be set as an indication of an imminent problem. | 2.6 | 2.8 | 3.0 | V |
| VDD UVLO Failure Voltage | V _{DD_UVLO_FAIL} | Level below which digital parts of the chip will not respond | 2.1 | 2.25 | 2.4 | V |
| Hardware Reset Voltage | V _{RESET} | V _{DD} voltage causing reset | — | 1.8 | — | V |
| Power Supply Currents¹ | | | | | | |
| VPWR Supply Current | I _{VPWR} | During normal operation | — | 2 | 5 | mA |
| | | V _{PWR} = 8 V, V _{DD} = 0 V | — | — | 100 | μA |
| VDD Supply Current | I _{DD} | During normal operation | — | 17 | 25 | mA |
| MOSFET Fault Specifications | | | | | | |
| MOSFET Fault Threshold | V _{PORT} | When FET is driven OFF, if either condition is met, a MOSFET fault is reported. | — | 15 | — | V |
| | I _{FET} | | — | 2.5 | — | mA |

| Parameter | Symbol | Test Condition/Note | Min | Typ | Max | Unit |
|--|---------------------|---|------|-----|------|---------------|
| Detection Specifications | | | | | | |
| Detection Short Circuit Current | I_{DET_SC} | Measured when V_{drain} is shorted to V_{PWR} | — | 3.0 | 4.9 | mA |
| Detection voltage when $R_{DET} = 25.5\text{ k}\Omega$ | V_{PORTn} | Primary detection voltage | 2.8 | 4.0 | — | V |
| | | Secondary detection voltage | — | 8.0 | 10.0 | V |
| Signature Resistance | R_{GOOD} | | — | 25 | — | k Ω |
| Minimum Signature Resistance @ PD | R_{DET_MIN} | | 15 | 17 | 19 | k Ω |
| Maximum Signature Resistance @ PD | R_{DET_MAX} | | 26.5 | 30 | 33 | k Ω |
| Reject Signature Capacitance | C_{REJECT} | | — | — | 10 | μF |
| Open Port Threshold | R_{OPEN_PORT} | Threshold between R_HIGH and R_OPEN | 100 | — | 400 | k Ω |
| Shorted Port Threshold | R_{SHORT} | | 150 | — | 400 | Ω |
| High Detection Signature Resistance | R_{HIGH} | | 33 | — | 100 | k Ω |
| Low Detection Signature Resistance | R_{LOW} | | 0.4 | — | 15 | k Ω |
| Classification Specifications | | | | | | |
| Class Event Voltage | V_{CLASS} | $0\text{ mA} < I_{CLASS} < 51\text{ mA}$ | 15.5 | — | 20.5 | V |
| Classification Short Circuit Current | I_{CLASS_SC} | Measured when V_{drain} is shorted to V_{PWR} | 55 | — | 95 | mA |
| Classification Current Region | I_{CLASS_REGION} | Class Signature 0 | 0 | — | 5 | mA |
| | | Threshold between Class Signature 0 or 1 | 5 | — | 8 | mA |
| | | Class Signature 1 | 8 | — | 13 | mA |
| | | Threshold between Class Signature 1 or 2 | 13 | — | 16 | mA |
| | | Class Signature 2 | 16 | — | 21 | mA |
| | | Threshold between Class Signature 2 or 3 | 21 | — | 25 | mA |
| | | Class Signature 3 | 25 | — | 31 | mA |
| | | Threshold between Class Signature 3 or 4 | 31 | — | 35 | mA |
| | | Class Signature 4 | 35 | — | 45 | mA |
| Threshold between Class Signature 4 or invalid class | 45 | — | 51 | mA | | |
| Classification Mark Specifications | | | | | | |
| Mark Event Voltage | V_{MARK} | Mark current between 0 and 5 mA | 7 | — | 10 | V |
| Mark Event Current Limitation | I_{MARK_LIM} | | 5 | — | 100 | mA |
| Output Voltage | | | | | | |
| Threshold Voltage for Power Good Sense | V_{PGOOD} | Measured at V_{DRAINn} to AGND | 1 | 2 | 3 | V |
| Bias Current of DRAINn Pin | I_{DRAINn} | $V_{DRAINn} = 0\text{ V}$ | — | -25 | — | μA |

| Parameter | Symbol | Test Condition/Note | Min | Typ | Max | Unit |
|---|---------------------|---|-----|--------|------|---------|
| Current Limit Detection Threshold | V_{DRAIN_ILIM} | Measured at V_{DRAIN} with respect to AGND | — | — | 3.00 | V |
| Resistance from DRAIN to AGND | R_{DRAIN} | | — | 2.5 | — | MΩ |
| Current Sense² | | | | | | |
| Power Limit | P_{CUT} | Class 0, 2-pair power, 15.4 W nominal | — | 16.275 | — | W |
| | | Class 1, 2-pair power, 4 W nominal | — | 4.2 | — | W |
| | | Class 2, 2-pair power, 7 W nominal | — | 7.35 | — | W |
| | | Class 3, 2-pair power, 15.4 W nominal | — | 16.275 | — | W |
| | | Class 4, 2 or 4-pair power ³ , 30 W nominal ⁴ | — | 31.5 | — | W |
| | | Class 5, dual signature, 2 pair power, 45 W nominal ⁵ | — | 47.25 | — | W |
| | | Class 5, single signature, 4 pair power ³ , 45 W nominal | — | 47.25 | — | W |
| | | Class 6, 4-pair power ³ , 60 W nominal | — | 63 | — | W |
| | | Class 7, 4-pair power ³ , 75 W nominal | — | 78.75 | — | W |
| | | Class 8, 4-pair power ³ , 90 W nominal | — | 94.5 | — | W |
| PCUT Tolerance | P_{CUT} | Policy settings < 15 W | 0 | 5 | 10 | % |
| | | Policy settings \geq 15 W | 0 | 2.5 | 5 | % |
| Current Limit ⁶ | I_{LIM} | Inrush, all assigned PD classes, $V_{port} > 30$ V | 400 | 425 | 450 | mA |
| | | Power-on, assigned PD Class 0, 1, 2, 3, 4+ Type 1 limited | — | 425 | — | mA |
| | | Power-on, assigned PD Class 4, 5, 6 ⁷ | — | 850 | — | mA |
| | | Power-on, assigned PD Class 7, 8 ⁷ | — | 1275 | — | mA |
| | | Power-on, assigned dual-signature PD Class 1, 2, 3 | — | 425 | — | mA |
| | | Power-on, assigned dual-signature PD Class 4 | — | 850 | — | mA |
| | | Power-on, assigned dual-signature PD Class 5 | — | 1275 | — | mA |
| Disconnect with power provided over two pairs ⁸ | $I_{PORT_DIS_2P}$ | Current per pairset | — | 6.5 | — | mA |
| Disconnect with power provided over four pairs ⁸ | $I_{PORT_DIS_4P}$ | Current per pairset. While powering over four pairs, if either pairset current is above this threshold, the PD is considered to be presenting the MPS signal. | — | 3.5 | — | mA |
| MOSFET Gate Drive⁹ | | | | | | |
| Drive Current from GATEn Pin (Active) | | GATEn pin active $V_{GATEn} = AGND$ | -70 | -50 | -20 | μ A |
| Drive Current from GATEn Pin (Off) | | GATEn pin shut off $V_{GATEn} = AGND + 5$ V | — | 50 | — | mA |

| Parameter | Symbol | Test Condition/Note | Min | Typ | Max | Unit |
|---|--------|------------------------|-----|------|-----|------|
| Voltage Difference Between any GATE _n and AGND Pin | | $I_{GATEn} = -1 \mu A$ | 10 | 11.5 | 13 | V |

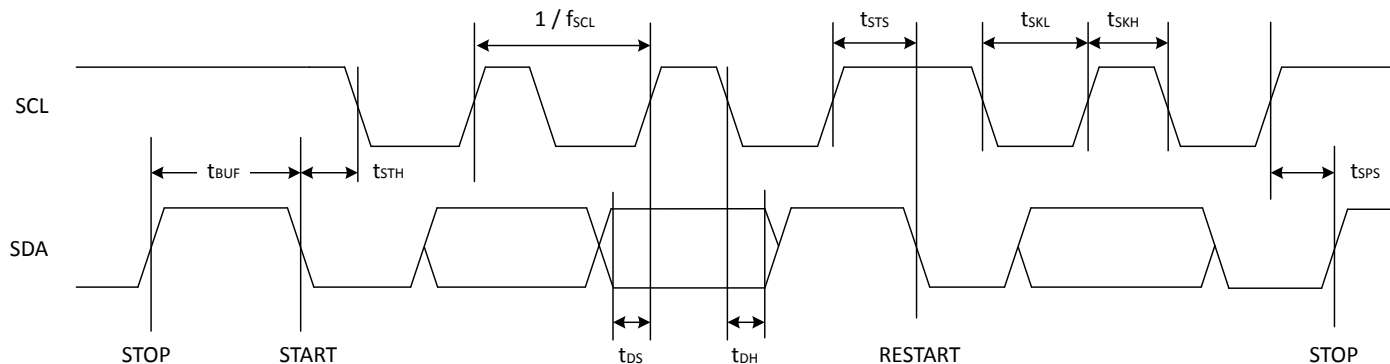
Note:

1. Positive values indicate currents flowing into the device. Negative currents indicate current flowing out of the device.
2. Current sense resistor, R_{SENSE} , has a value of 0.255 Ω .
3. P_{CUT} is within 802.3bt specified unbalance limits.
4. Class 4 can be powered over either 4-pair or 2-pair power. When powered over 4-pair, the total current across both alternatives is used for P_{CUT} measurements, when powered over a single pair P_{CUT} is taken from the lone alternative.
5. Class 5 dual signature is on a per-alternative basis. The summed P_{CUT} of both alternatives are held to Class 8 Single Signature power levels.
6. Setting applies to each active alternative.
7. When powered in 4-pair mode, the ILIM value applies to each alternative; so, the total ILIM for the load is effectively doubled.
8. An MPS signal is considered present on an alternative when the current on that alternative is above these thresholds.
9. See "AN1228: FET Selection Guide for Si347x PSE Families" for detailed information on FET selection.

Table 5.3. I²C Bus Timing Specifications^{1, 2, 3, 4}

| Parameter | Symbol | Test Condition | Min | Typ | Max | Unit |
|--|-------------|---|-----|-----|-----|------|
| Serial Bus Clock Frequency | f_{SCL} | See Figure 5.1 I²C Bus Interface Timing on page 74. | 0 | — | 800 | kHz |
| SCL High Time | t_{SKH} | See Figure 5.1 I²C Bus Interface Timing on page 74. | 300 | — | — | ns |
| SCL Low Time | t_{SKL} | See Figure 5.1 I²C Bus Interface Timing on page 74. | 650 | — | — | ns |
| Bus Free Time | t_{BUF} | Between STOP and START conditions. See Figure 5.1 I²C Bus Interface Timing on page 74. | 650 | — | — | ns |
| Start Hold Time | t_{STH} | Between START and first low SCL. See Figure 5.1 I²C Bus Interface Timing on page 74. | 300 | — | — | ns |
| Repeated Start Setup Time | t_{STS} | Between SCL high and START condition. See Figure 5.1 I²C Bus Interface Timing on page 74. | 300 | — | — | ns |
| Stop Setup Time | t_{SPS} | Between SCL high and STOP condition. See Figure 5.1 I²C Bus Interface Timing on page 74. | 300 | — | — | ns |
| Data Hold Time | t_{DH} | See Figure 5.1 I²C Bus Interface Timing on page 74. | 75 | — | — | ns |
| Data Setup Time | t_{DS} | See Figure 5.1 I²C Bus Interface Timing on page 74. | 100 | — | — | ns |
| Time from Hardware or Software Reset until Start of I ² C Traffic | t_{RESET} | Reset to start condition | 5 | — | — | ms |

| Parameter | Symbol | Test Condition | Min | Typ | Max | Unit |
|--|--------|----------------|-----|-----|-----|------|
| Note: | | | | | | |
| 1. All specification voltages are referenced with respect to AGND and DGND at ground. | | | | | | |
| 2. Not production tested (guaranteed by design). | | | | | | |
| 3. All timing references measured at V_{IL} and V_{IH} . | | | | | | |
| 4. SCL and SDA rise and fall times depend on bus pull-up resistance and bus capacitance. | | | | | | |

Figure 5.1. I²C Bus Interface TimingTable 5.4. Digital Pin Recommended Operating Conditions¹

| Parameter | Symbol | Test Condition | Pins | Min | Typ | Max | Unit |
|--|----------|---|----------------------------------|-----------|-----|---------------------|---------------|
| Input Low Voltage | V_{IL} | | A1-A4, SCL, SDA, RESETb, OSS | — | — | 0.3 x VDD | V |
| Input High Voltage | V_{IH} | | A1-A4, SCL, SDA, RESETb, OSS | 0.7 x VDD | — | — | V |
| Output Low Voltage | V_{OL} | $I_{OL} = 13.5 \text{ mA}$, $V_{DD} > 3.0$ $I_{OL} = 3.6 \text{ mA}$, $1.71 < V_{DD} < 2.2$ V | SDA, INTb | | | $V_{DD} \times 0.2$ | V |
| Input Leakage | I_{LK} | $V_{DD} < V_{pin} < V_{DD} + 2.5 \text{ V}$ | A1-A4, SCL, SDA, RESETb, OSS | 0 | 5 | 150 | μA |
| Pullup Current to VDD | I_{PU} | | RESET, OSS, INT, SCL, SDA, A1-A4 | — | -20 | — | μA |
| Pulse Width of spikes which must be suppressed by input filter | t_{SP} | | SCL, SDA | 0 | — | 10 | ns |

Note:

1. All specification voltages are referenced with respect to DGND. These specifications apply over the recommended operating voltage and temperature ranges of the device unless noted otherwise.
2. SDA and INTb are open drain outputs. Tie each pin to VDD with a 1 k Ω resistor for normal operation
3. Note that V_{IL} and V_{IH} are shown as fractions of VDD. This is intended to allow the I²C interface to operate with CMOS levels. These values will be higher than the standard TTL interface.

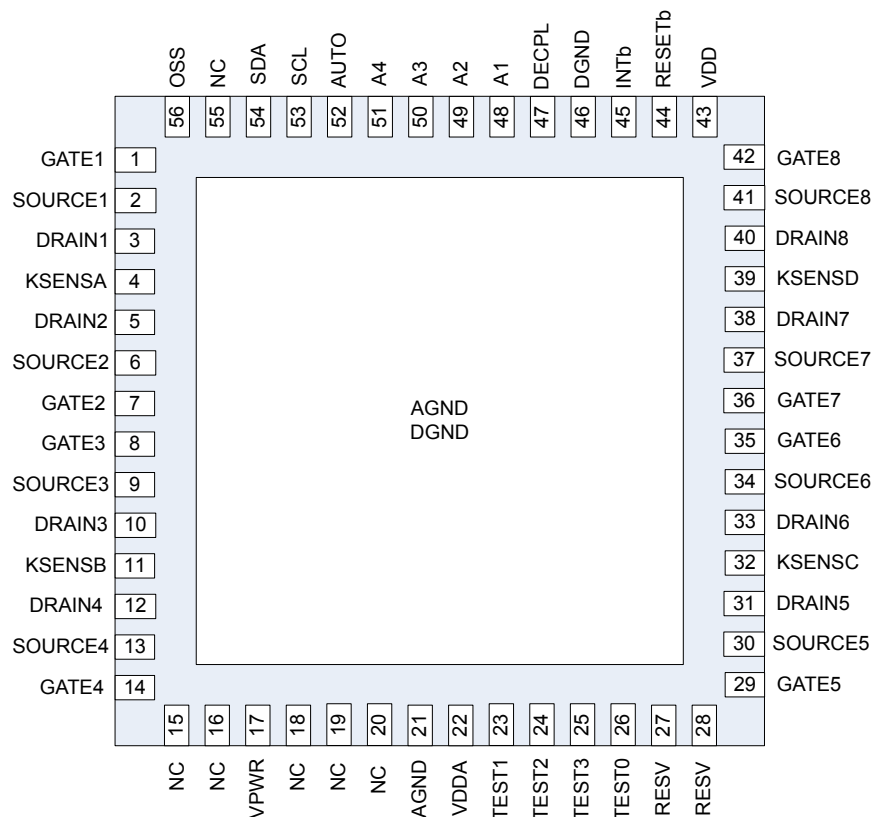
Table 5.5. Absolute Maximum Ratings¹

| Parameter | Range | Unit |
|-----------------------------|--------------|------|
| Supply Voltage | | |
| VDD | –0.3 to 4.0 | V |
| VPWR | –0.3 to 80.0 | V |
| DGND with Respect to AGND | 0 | V |
| Digital Signals | | |
| All | –0.3 to 3.6 | V |
| Analog Signals | | |
| GATEn with Respect to AGND | –0.3 to 20.0 | V |
| SENSEn with Respect to AGND | –0.3 to 3.0 | V |
| DRAINn with Respect to AGND | –3 to 80 | V |
| Temperature | | |
| Junction | +150 | °C |
| Storage | –55 to +150 | °C |

Note:

1. Permanent device damage may occur if the maximum ratings are exceeded. Functional operation should be restricted to those conditions specified in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may adversely affect device reliability.

6. Pin Descriptions



| Pin # | Name | Type | Description |
|----------------|----------------|--|--|
| 44 | RESETb | Digital input with 20 μ A pull-up to VDD | Active low device reset input. Generally, RESETb is used at initial power up. If RESETb is asserted (pulled to DGND), the MCU is disabled, all internal registers of the device are set to their default (power-up) state, and all output ports are shut off. Valid RESETb timing pulses must be >10 μ s. If RESETb is not used, RESETb should either be tied directly to VDD or through a 10 k Ω resistor to VDD. |
| 45 | INTb | Digital output (open drain) | Interrupt output. This open drain output pin is asserted low (to DGND) if a fault condition occurs on any of the four ports. The state of INTb is updated for use by the host controller between valid I ² C commands. Refer to the “Interrupts” section of for more information. Tie INTb to VDD through a 10 k Ω resistor for normal operation. |
| 53 | SCL | Digital input | Serial clock input. Should be tied directly to the SCL (clock) connection on the I ² C bus. |
| 54 | SDA | I ² C input/output | Bidirectional I ² C input/output. |
| 51, 50, 49, 48 | A4, A3, A2, A1 | Digital input with 20 μ A pull-up to VDD | I ² C address input. Used to set the base I ² C address for the Si3474 in the following (binary) format: 010[A4][A3][A2][A1]b. The three MSB bits of the address are set to 010. Address values are latched after the deassertion of RESETb or when VDD ramps and VPWR exceeds the UVLO threshold voltage. Each address pin should be tied to either VDD or DGND. |
| 46, ePAD | DGND | Digital ground | Ground connection for 3.3 V digital supply (VDD). DGND and AGND are tied together inside the Si3474 package. |

| Pin # | Name | Type | Description |
|----------|--------|--|--|
| 21, ePAD | AGND | Analog ground | Ground connection for VPWR supply. DGND and AGND are tied together inside the Si3474 package |
| 43 | VDD | Digital power | 3.3 V digital supply (relative to DGND). Bypass VDD with a 0.1 μ F capacitor to DGND as close as possible to the Si3474 power supply pins; tied with VDDA. |
| 22 | VDDA | Analog power | 3.3 V supply to the analog side; tied with VDD at the PCB level. |
| 17 | VPWR | Analog power | Positive PoE voltage (+44 to +56 V) relative to AGND. |
| 41 | SENSE8 | Analog input | Current sense inputs for external MOSFETs. The SENSE _n pin measures current through an external sense resistor tied between the AGND supply rail and the SENSE _n input. If the I _{CUT} limit (the overcurrent limit) is exceeded, the current limit fault timer is incremented. If the voltage across the sense resistor subsequently triggers (the overcurrent limit), the voltage driven onto the GATE _n pin is modulated to provide constant current through the external MOSFET. Tie the SENSE _n pin to AGND when the port is not used. To accommodate 802.3at (PoE Plus) classification, both the I _{CUT} and I _{lim} values can be scaled. See 4.24 PORT_REMAP (0x26) for more information. |
| 37 | SENSE7 | | |
| 34 | SENSE6 | | |
| 30 | SENSE5 | | |
| 13 | SENSE4 | | |
| 9 | SENSE3 | | |
| 6 | SENSE2 | | |
| 2 | SENSE1 | | |
| 42 | GATE8 | Analog output | Gate drive outputs to external MOSFETs. Connect the GATE _n outputs to the external MOSFET gate node gate. A 50 μ A pull-up source is used to turn on the external MOSFET. When a current limit is detected, the GATE _n voltage is reduced to maintain constant current through the external MOSFET. If the fault timer limit is reached, GATE _n pulls down, shutting off the external MOSFET. GATE _n will clamp to 11.5 V (typical) above AGND. If the port is unused, leave the GATE _n pin disconnected or tie to AGND. |
| 36 | GATE7 | | |
| 35 | GATE6 | | |
| 29 | GATE5 | | |
| 14 | GATE4 | | |
| 8 | GATE3 | | |
| 7 | GATE2 | | |
| 1 | GATE1 | | |
| 40 | DRAIN8 | Analog input with 25 μ A pull-up to VPWR | MOSFET drain output voltage sense. The Power Good bit is set on each port when the voltage between DRAIN _n and AGND drops below 2 V (typical). See 4.4 POWER Event and POWER Event CoR (Address 0x02, 0x03) for further information. DRAIN _n pins should be left floating if the port is unused. |
| 38 | DRAIN7 | | |
| 33 | DRAIN6 | | |
| 31 | DRAIN5 | | |
| 12 | DRAIN4 | | |
| 10 | DRAIN3 | | |
| 5 | DRAIN2 | | |
| 3 | DRAIN1 | | |
| 56 | OSS | Over supply signal | A positive going edge on this pin shuts down ports that have been identified as low priority by setting Register 0x15. This pin has a 20 μ A pull-up. Do not leave this pin unconnected. |
| 4 | KSENSA | Input | Kelvin points for accurate measurement of voltage across the sense resistor for ports 1 and 2. |
| 11 | KSENSB | Input | Kelvin points for accurate measurement of voltage across the sense resistor for ports 3 and 4. |
| 32 | KSENSC | Input | Kelvin points for accurate measurement of voltage across the sense resistor for ports 5 and 6. |

| Pin # | Name | Type | Description |
|---------------------------|-----------|--------------|--|
| 39 | KSENSD | Input | Kelvin points for accurate measurement of voltage across the sense resistor for ports 7 and 8. |
| 26 | TEST4 | Input/Output | Test pin for internal use by Skyworks. Leave floating. |
| 25 | TEST3 | | |
| 24 | TEST2 | | |
| 23 | TEST1 | | |
| 47 | DECPL | Decoupling | Place a 0.1 μ F capacitor between DECPL and GND. |
| 52 | AUTO-MODE | Automode | Enables Automode. Refer to 2.10.1 AUTO Pin Autonomous Mode . |
| 28, 27 | RESV | Reserved | Reserved for future use. Leave floating. |
| 19, 18, 16, 15, 55, 20 | NC | No Connect | No connections or nets allowed. Leave floating. |

7. Package Outline: 56-Pin QFN

The figure below illustrates the package details for the Si3474. The table lists the values for the dimensions shown in the illustration. The Si3474 is packaged in an industry-standard, RoHS-compliant, 56-pin QFN package.

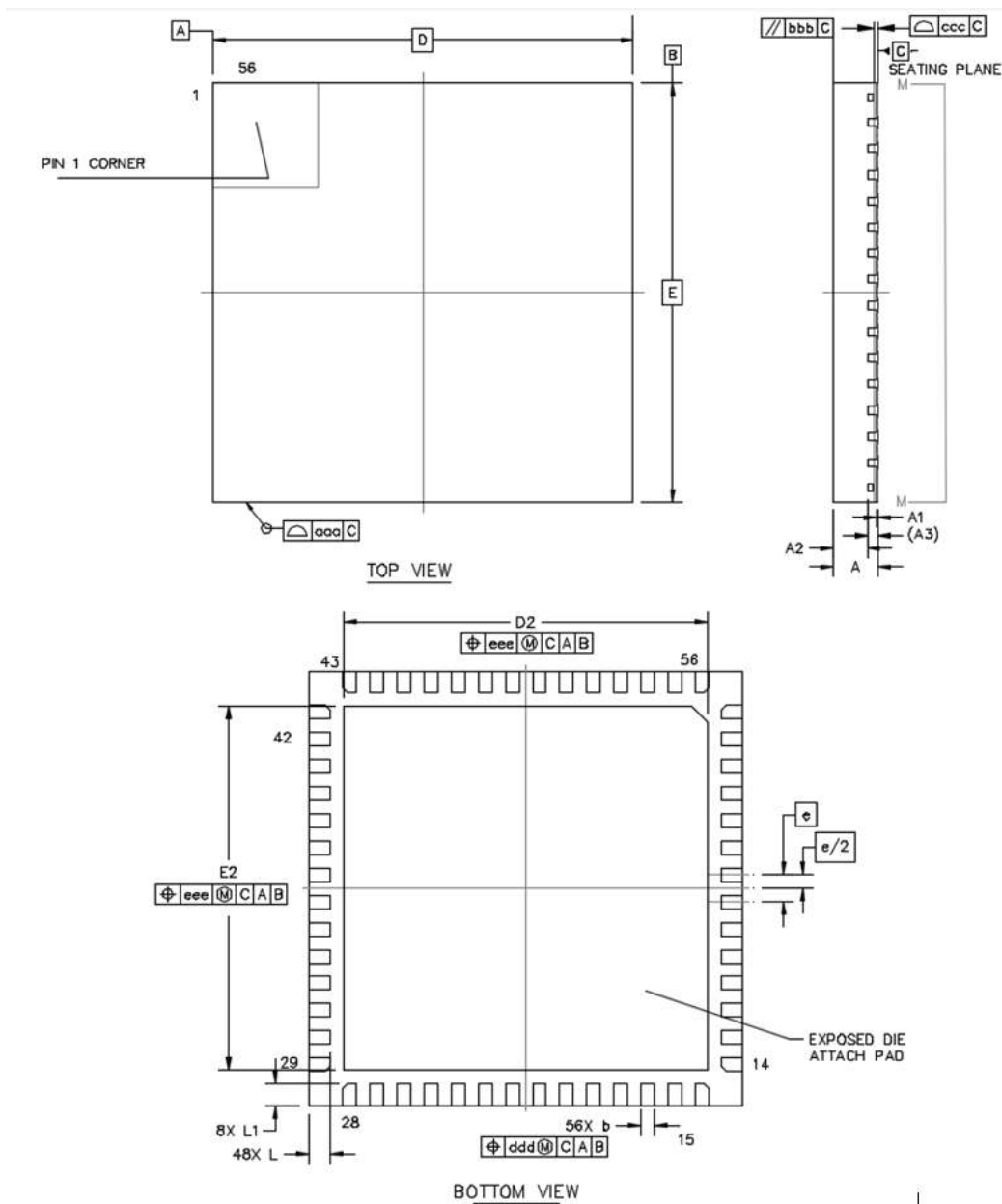


Figure 7.1. 56-Pin QFN Package

Table 7.1. Package Diagram Dimensions

| Dimension | Min | Nom | Max |
|-----------|-----------|-------|------|
| A | 0.80 | 0.85 | 0.90 |
| A1 | 0.00 | 0.035 | 0.05 |
| A3 | 0.203 REF | | |
| b | 0.20 | 0.25 | 0.30 |
| D | 7.90 | 8.00 | 8.10 |
| E | 7.90 | 8.00 | 8.10 |
| D2 | 6.60 | 6.70 | 6.80 |
| E2 | 6.60 | 6.70 | 6.80 |
| e | 0.50 BSC | | |
| L | 0.35 | 0.40 | 0.45 |
| L1 | 0.30 | 0.40 | 0.45 |
| aaa | 0.10 | | |
| bbb | 0.10 | | |
| ccc | 0.08 | | |
| ddd | 0.10 | | |
| eee | 0.10 | | |

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. This drawing conforms to the JEDEC Solid State Outline MO-220, Variation VLLD-5.
4. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

8. Land Pattern

The following figure illustrates the land pattern details for the Si3474. The table lists the values for the dimensions shown in the illustration. The stencil design and notes are shared as recommendations only. A customer or user may find it necessary to use different parameters and fine-tune their SMT process as required for their application and tooling.

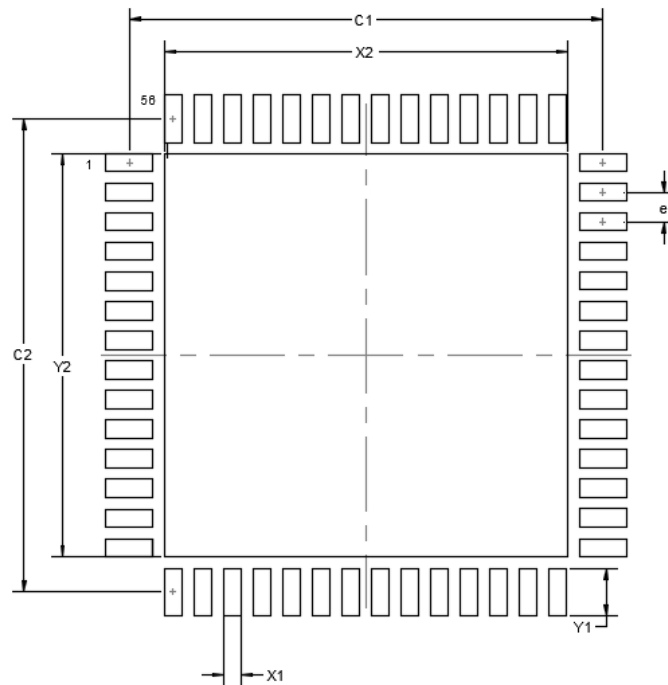


Figure 8.1. Si3474 Recommended Land Pattern

Table 8.1. PCB Land Pattern Dimensions

| Symbol | mm |
|--------|------|
| C1 | 8.00 |
| C2 | 8.00 |
| e | 0.50 |
| X1 | 0.30 |
| Y1 | 0.80 |
| X2 | 6.80 |
| Y2 | 6.80 |

| Symbol | mm |
|--|----|
| <p>Notes:</p> <p>General</p> <ol style="list-style-type: none">1. All dimensions shown are at Maximum Material Condition (MMC). Least Material Condition (LMC) is calculated based on a Fabrication Allowance of 0.05 mm.2. This Land Pattern Design is based on the IPC-7351 guidelines. <p>Solder Mask Design</p> <ol style="list-style-type: none">1. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 µm minimum, all the way around the pad. <p>Stencil Design</p> <ol style="list-style-type: none">1. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.2. The stencil thickness should be 0.125 mm (5 mils).3. The ratio of stencil aperture to land pad size should be 1:1 for all perimeter pins.4. A 3 x 3 array of 1.50 mm square openings on a 2.1 mm pitch should be used for the center ground pad. <p>Card Assembly</p> <ol style="list-style-type: none">1. A No-Clean, Type-3 solder paste is recommended.2. The recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components. | |

9. Top Marking

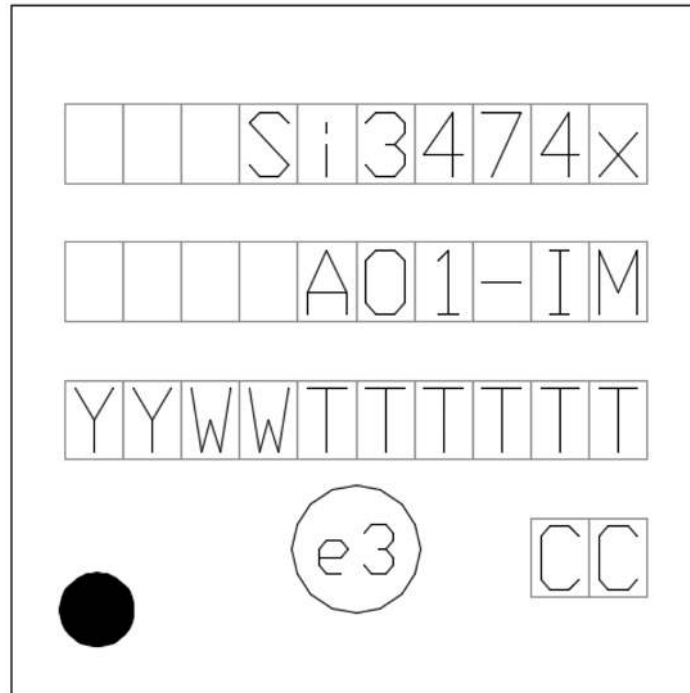


Figure 9.1. Si3474 Top Marking (QFN)

Table 9.1. Top Marking Explanation

| | | |
|----------------------------|--|---|
| Mark Method: | Laser | |
| Pin 1 Mark: | Bottom-Left-Justified | |
| Line 1 Mark Format: | Device Part Number | Si3474x x = A (255 mΩ sense resistor) x = B (200 mΩ sense resistor) |
| Line 2 Mark Format: | Device Revision Package Type | A01 IM |
| Line 3 Mark Format: | YY = Year WW = Work Week TTTTTT = Mfg Code | Year and Work Week of Assembly Manufacturing Code |
| Line 4 Mark Format: | Circle = 1.3 mm Diameter Country of Origin | “e3” Pb-Free Symbol TW = Taiwan |

10. Revision History

Revision 0.5

May, 2020

- Initial release.



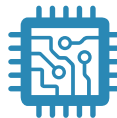
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