

CY7B9930V/CY7B9940V RoboClock II™ Junior

High-Speed Multi-frequency PLL Clock Buffer

Features

- 12-100 MHz (CY7B9930V), or 24-200 MHz (CY7B9940V) input/output operation
- Matched pair output skew < 200 ps
- Zero input-to-output delay
- 10 LVTTL 50% duty-cycle outputs capable of driving 50 Ω terminated lines
- Commercial temperature range with eight outputs at 200 MHz
- Industrial temperature range with eight outputs at 200 MHz
- 3.3 V LVTTL/LV differential (LVPECL), fault-tolerant and hot insertable reference inputs
- \blacksquare Multiply ratios of (1–6, 8, 10, 12)
- Operation up to 12x input frequency
- Individual output bank disable for aggressive power management and EMI reduction
- Output high impedance option for testing purposes
- Fully integrated PLL with lock indicator
- Low cycle-to-cycle jitter (<100 ps peak-peak)
- Single $3.3 \vee \pm 10\%$ supply
- 44-pin TQFP package

Logic Block Diagram

Functional Description

The CY7B9930V and CY7B9940V High-Speed Multi-frequency PLL Clock Buffers offer user-selectable control over system clock functions. This multiple output clock driver provides the system integrator with functions necessary to optimize the timing of high performance computer or communication systems.

Ten configurable outputs can each drive terminated transmission lines with impedances as low as 50 Ω while delivering minimal and specified output skews at LVTTL levels. The outputs are arranged in three banks. The FB feedback bank consists of two outputs, which allows divide-by functionality from 1 to 12. Any one of these ten outputs can be connected to the feedback input as well as driving other inputs.

Selectable reference input is a fault tolerance feature that allows smooth change over to secondary clock source, when the primary clock source is not in operation. The reference inputs are configurable to accommodate both LVTTL or differential (LVPECL) inputs. The completely integrated PLL reduces jitter and simplifies board layout.

For a complete list of related documentation, [click here](http://www.cypress.com/?rID=13822).

Contents

Logic Block Diagram Description

Phase Frequency Detector and Filter

These two blocks accept signals from the REF inputs (REFA+, REFA-, REFB+ or REFB-) and the FB input (FBKA). Correction information is then generated to control the frequency of the Voltage Controlled Oscillator (VCO). These two blocks, along with the VCO, form a Phase-Locked Loop (PLL) that tracks the incoming REF signal.

The RoboClockII[™] Junior has a flexible REF input scheme. These inputs allow the use of either differential LVPECL or single ended LVTTL inputs. To configure as single ended LVTTL inputs, leave the complementary pin to 1.5V), then use the other input pin as an LVTTL input. The REF inputs are also tolerant to hot insertion.

The REF inputs can be changed dynamically. When changing from one reference input to the other reference input of the same frequency, the PLL is optimized to ensure that the clock outputs period is not less than the calculated system budget $(t_{MIN} = t_{REF}$ (nominal reference clock period) – t_{CCJ} (cycle-to-cycle jitter) – t_{PDEV} (max. period deviation)) while reacquiring lock.

VCO, Control Logic, and Divide Generator

The VCO accepts analog control inputs from the PLL filter block. The FS control pin setting determines the nominal operational frequency range of the divide by one output (f_{NOM}) of the device. f_{NOM} is directly related to the VCO frequency. There are two versions of the RoboClockII Junior, a low speed device (CY7B9930V) where f_{NOM} ranges from 12 MHz to 100 MHz, and a high speed device (CY7B9940V), which ranges from 24 MHz to 200 MHz. The FS setting for each device is shown in [Table 1](#page-2-6). The f_{NOM} frequency is seen on "divide-by-one" outputs.

Table 1. Frequency Range Select

Divide Matrix

The Divide Matrix is comprised of three independent banks: two banks of clock outputs and one bank for feedback. Each clock output bank has two pairs of low-skew, high fanout output buffers $([1:2]Q[A:B][0:1])$, and an output disable $(DIS[1:2])$.

The feedback bank has one pair of low-skew, high fanout output buffers (QFA[0:1]). One of these outputs may connect to the selected feedback input (FBKA+). This feedback bank also has two divider function selects FBDS[0:1].

The divide capabilities for each bank are shown in [Table 2](#page-2-7)*.*

Output Disable Description

The outputs of Bank 1 and Bank 2 can be independently put into a HOLD OFF or high impedance state. The combination of the Output_Mode and DIS[1:2] inputs determines the clock outputs' state for each bank. When the DIS[1:2] is LOW, the outputs of the corresponding bank are enabled. When the DIS[1:2] is HIGH, the outputs for that bank are disabled to a high impedance (HI-Z) or HOLD OFF state depending on the Output Mode input. [Table 3](#page-2-8) defines the disabled output functions.

The HOLD OFF state is designed as a power saving feature. An output bank is disabled to the HOLD OFF state in a maximum of six output clock cycles from the time when the disable input (DIS[1:2]) is HIGH. When disabled to the HOLD OFF state, outputs are driven to a logic LOW state on its falling edge. This ensures the output clocks are stopped without glitch. When a bank of outputs is disabled to HI-Z state, the respective bank of outputs go HI-Z immediately.

Table 3. DIS[1:2] Pin Functionality

Notes

2. The maximum output frequency is 200 MHz.

^{1.} The level to be set on FS is determined by the "nominal" operating frequency (f_{NOM}) of the V_{CO}. f_{NOM} always appears on an output when the output is operating in the undivided.
the undivided mode. The REF and FB a

Lock Detect Output Description

The LOCK detect output indicates the lock condition of the integrated PLL. Lock detection is accomplished by comparing the phase difference between the reference and feedback inputs. Phase error is declared when the phase difference between the two inputs is greater than the specified device propagation delay limit (t_{PD}) .

When in the locked state, after four or more consecutive feedback clock cycles with phase errors, the LOCK output is forced LOW to indicate out-of-lock state.

When in the out-of-lock state, 32 consecutive phase errorless feedback clock cycles are required to allow the LOCK output to indicate lock condition (LOCK = HIGH).

If the feedback clock is removed after LOCK has gone HIGH, a Watchdog circuit is implemented to indicate the out-of-lock condition after a timeout period by deasserting LOCK LOW. This timeout period is based upon a divided down reference clock.

This assumes that there is activity on the selected REF input. If there is no activity on the selected REF input then the LOCK detect pin may not accurately reflect the state of the internal PLL.

Factory Test Mode Description

The device enters factory test mode when the OUTPUT_MODE is driven to MID. In factory test mode, the device operates with its internal PLL disconnected; the input level supplied to the reference input is used in place of the PLL output. In TEST mode the selected FB input must be tied LOW. All functions of the device remain operational in factory test mode except the internal PLL and output bank disables. The OUTPUT_MODE input is designed as a static input. Dynamically toggling this input from LOW to HIGH may temporarily cause the device to go into factory test mode (when passing through the MID state).

Factory Test Reset

When in factory test mode (OUTPUT_MODE = MID), the device is reset to a deterministic state by driving the DIS2 input HIGH. When the DIS2 input is driven HIGH in factory test mode, all clock outputs go to HI-Z; after the selected reference clock pin has five positive transitions, all the internal finite state machines (FSM) are set to a deterministic state. The deterministic state of the state machines depends on the configurations of the divide selects and frequency select input. All clock outputs stay in high impedance mode and all FSMs stay in the deterministic state until DIS2 is deasserted. When DIS2 is deasserted (with OUTPUT_MODE still at MID), the device reenters factory test mode.

Pin Configuration

Pin Definitions

Note
3. For all tri-state inputs, HIGH indicates a connection to V_{CC}, LOW indicates a connection to GND, and MID indicates an open connection. Internal termination circuitry
holds an unconnected input to V_{CC}/2.

Absolute Maximum Conditions

Exceeding the maximum ratings may impair the useful life of the device. These user guidelines are not tested.

Static discharge voltage (MIL-STD-883, Method 3015) >2000 V Latch up current .. >±200 mA

Operating Range

Electrical Characteristics

Over the Operating Range

Note

^{4.} These inputs are normally wired to V_{CC}, GND, or left unconnected (actual threshold voltages vary as a percentage of V_{CC}). Internal termination resistors hold the
unconnected inputs are switched, the function and ti

Electrical Characteristics (continued)

Over the Operating Range

Notes
5. I_{CCI} measurement is performed with Bank1 and FB Bank configured to run at maximum frequency (f_{NOM} = 100 MHz for CY7B9930V, f_{NOM} = 200 MHz for CY7B9940V),
and all other clock output banks to run at hal

Capacitance

Thermal Resistance

AC Test Loads and Waveforms

(a) LVTTL AC Test Load

Notes

- 7. These parameters are guaranteed by design and are not tested.
- 8. These figures are for illustration only. The actual ATE loads may vary.

Switching Characteristics

Over the Operating Range [[9,](#page-9-1) [10,](#page-9-2) [11](#page-9-3), [12](#page-9-4), [13](#page-9-5)]

Notes

- 9. This is for non-three level inputs.
- 10. Assumes 25 pF Max. Load Capacitance up to 185 Mhz. At 200 MHz the max load is 10 pF.
- 11. Both outputs of pair must be terminated, even if only one is being used.
- 12. Each package must be properly decoupled.
- 13. AC parameters are measured at 1.5V, unless otherwise indicated.
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- 14. Test Load C_L= 25 pF, terminated to V_{CC}/2 with 50Ω.
15. SKEW is defined as the time between the earliest and the latest output transition among all outputs for which the same phase delay has been selected when all

- 16. Guaranteed by statistical correlation. Tested initially and after any design or process changes that may affect these parameters.
- 17. Tested initially and after any design or process changes that may affect these parameters.
- 18. Rise and fall times are measured between 2.0V and 0.8V.
- 19. f_{NOM} must be within the frequency range defined by the same FS state.
- 20. t_{PWH} is measured at 2.0V. t_{PWL} is measured at 0.8V.
- 21. UI = Unit Interval. Examples: 1 UI is a full period. 0.1 UI is 10% of period.
- 22. Measured at 0.5V deviation from starting voltage.
- 23. For t_{OZA} minimum, C_L = 0 pF. For t_{OZA} maximum, C_L= 25 pF to 18 MHz, 10 pF from 185 to 200 MHz.

AC Timing Diagrams

Ordering Information

Ordering Code Definitions

Package Diagram

Figure 4. 44-pin TQFP (10 × 10 × 1.4 mm) A44S Package Outline, 51-85064

NOTE:

- 1. JEDEC STD REF MS-026 2. BODY LENGTH DIMENSION DOES NOT INCLUDE MOLD PROTRUSION/END FLASH
- MOLD PROTRUSION/END FLASH SHALL NOT EXCEED 0.0098 in (0.25 mm) PER SIDE BODY LENGTH DIMENSIONS ARE MAX PLASTIC BODY SIZE INCLUDING MOLD MISMATCH
- 3. DIMENSIONS IN MILLIMETERS

51-85064 *G

Acronyms

Document Conventions

Units of Measure

Document History Page

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