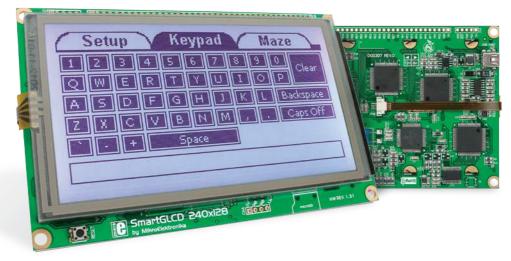
SmartGLCD 240x128







TO OUR VALUED CUSTOMERS

I want to express my thanks to you for being interested in our products and for having confidence in MikroElektronika.

The primary aim of our company is to design and produce high quality electronic products and to constantly improve the performance thereof in order to better suit your needs.

Nebojsa Matic General Manager

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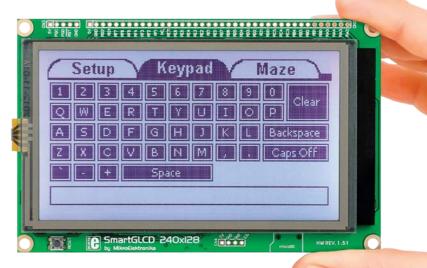
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What is the SmartGLCD 240x128?

The SmartGLCD 240x128 is a compact smart display, with many on-board peripherals. It's designed to become a control interface of your device. Main part of the board is a large 240x128 pixel graphical LCD with a 4-wire resistive touch screen. It features RGB backlight, which can greatly improve user experience, but can also be used as a signaling feature. The heart of the board is PIC18F87K22, an 8-bit microcontroller delivering 12MIPS of processing power. Other modules like USB UART, piezo buzzer, microSD slot and connection pads can be found on board as well. The board is preprogrammed with UART bootloader. We have also provided a nice example which will give you a great out-of-thebox experience.





Package Contains



1. Key Features

0 GLCD 240x128 display

2 RESET button



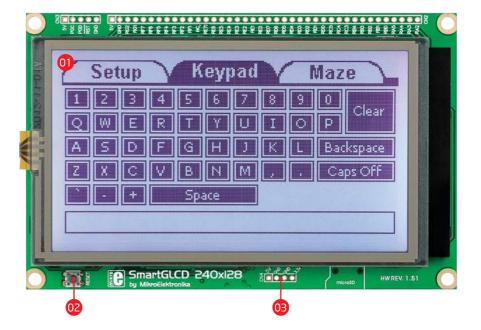
- Power supply pads
- 04 I/O pads
- 05 Pads for mikroProg programmer
- 06 USB connector

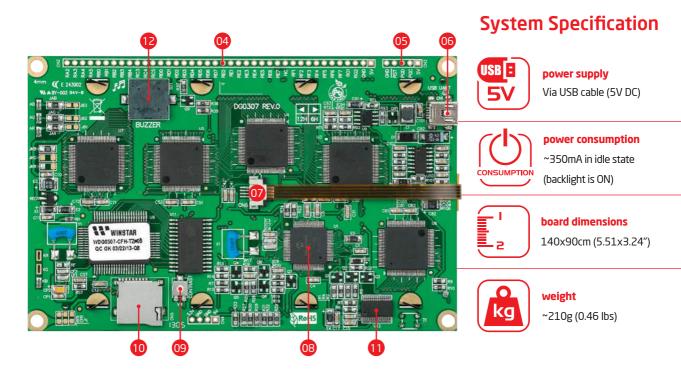


- Touch panel connector
- 08 PIC18F87K22 microcontroler
- 9 Contrast potentiometer
- 10 microSD card slot



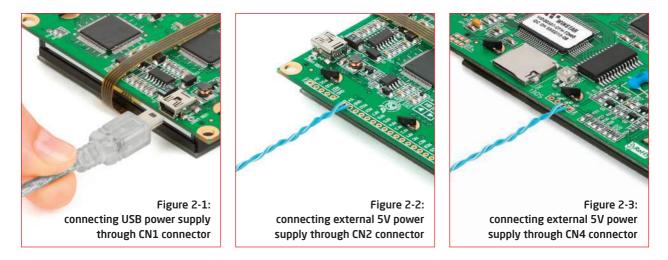
12 Buzzer





2. Power supply

The SmartGLCD board can be powered in two different ways: via USB connector **(CN1)** using MINI-B USB cable provided with the board **(Figure 2-1)**, or via side headers **(CN2** or **CN4)** using external 5V power supply (**Figure 2-2** and **Figure 2-3**).



When the board is powered up the GLCD display will be automatically turned on. The USB connection can provide up to 500mA of current which is more than enough for the operation of all on-board modules and the microcontroller as well.

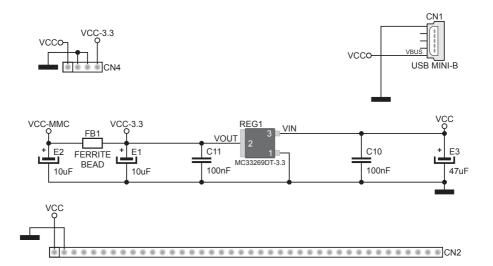


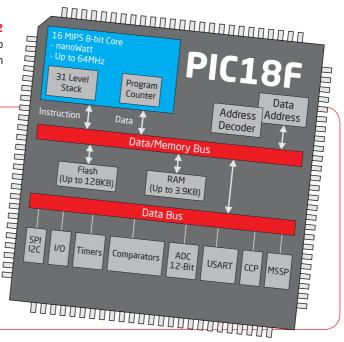
Figure 2-4: Power supply schematic

3. PIC18F87K22 microcontroller

The SmartGLCD development tool comes with the **PIC18F87K22** microcontroller. This 8-bit microcontroller is rich with on-chip peripherals and features 128KB of Flash and 4KB of RAM. It can easily handle demanding graphical applications.

Key microcontroller features

- Up to 12 MIPS Operation;
- 8-bit architecture;
- 128KB of Flash memory;
- 3,862 bytes of RAM;
- 1024 bytes of EEPROM;
- 80 pin TQFP;
- 24 ch, 12-bit ADC;
- UART, SPI, I²C; etc.



4. Programming the microcontroller



Figure 4-1: PIC18F87K22 microcontroller

The microcontroller can be programmed in two ways:



Using USB UART mikroBootloader

Using external mikroProg[™] for PIC, dsPIC, PIC32 programmer

5. Programming with bootloader

Microcontroller is preprogrammed with USB UART Bootloader, which can be used to upload new device firmware. To transfer firmware .HEX file from a PC to MCU you need to use mikro-Bootloader USB UART application, which can be downloaded from:



http://www.mikroe.com/smartglcd/

Upon download, unzip it to desired location and start the mikroBootloader application:



mikroBootloader software

Before starting mikroBootloader software, connect SmartGLCD to a PC using a USB cable provided with the package.

1 Setup COM port Daud	Port: COM1 Rate: 19200	Change Settings	Signals	Conn	Rx @	T)
2 Connect	Connect	History Win				_
to HCU		Setup: Port CO!	11.			
3 Choose HEX file	Browse tor HEX					
4 Start bootloader	Begin					

Figure 5-1: mikroBootloader window



When you start mikroBootloader software a window should appear, as shown in the image above.

Identifying device COM port

step 1 - Choosing COM port

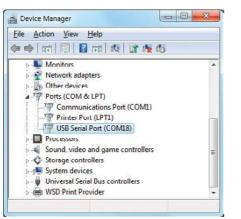


Figure 5-2: Identifying COM port



mikroBoot	loade	Select MCI	J PIC	18 •
1 Setup COM Port: port Daud Rate		Change Settings	-01 Conn	Rx Tx
2 to MCU	Connect	Settings Port	COM 18	
	Browse for HEX	Baud rate Data bits	115200 8	•
4 Start bootloader	Begin ploading	Stop bits Parity	1 None	•
Bootloading progress bar		Flow control	Software	•

Figure 5-3: Choosing COM port



Click the **Change Settings** button.

From the drop down list, select appropriate **Port** (in this case it is COM18) and **Baud rate** (115200).

Click OK.

step 2 - Establishing Connection

Setup COM	Port: COM18	Change	als	Conn	Rx	Tx
	Rate: 115200	Settings	Signals	0	•	0
2 Connect to MCU	Connect	on story Wind	1.			
3 Choose HEX file	Browse for HEX	Setup: Port COM	18.			
4 Start bootloader	Begin uploading					

Figure 5-4: Connecting with mikroBootloader

01	Press the Reset button on SmartGLCD board and click
	Connect within 5s, otherwise the existing microcontroller
	program will run. If connected, the button's caption will be
	changed to Disconnect .

step 3 - Browsing for .HEX file

1 Setup COM P port Baud R	ort: COM18 ate: 115200	Change Settings	Signals	Conn	Rx O	Tx O
2 Connect to MCU 3 Choose HEX file	Disconnect Browse for HEX	History Win Setup: Port CO Setup: Port CO Walting MCU re Uninected.	ndow M1. M18.			1
4 Start bootloader	Begin uploading					

Figure 5-5: Browse for HEX



Click the **Browse for HEX** button and from a pop-up window (Figure 5-6) choose a .HEX file to be uploaded in MCU memory.

step 4 - Selecting .hex file

Organize 🔻 New fold	er			二	0
🖈 Favorites	Name	Date modified	Туре	Size	
Desktop	SmartGLCD.hex	28.3.2013 16:20	HEX File		16 KB
	01				
Ubraries Documents Music Pictures Videos	U	,			
Documents Music Pictures	U	,			

Figure 5-6: Locating and selecting .hex file



Select .HEX file from the **Open dialog** window.

Click the **Open** button.

step 5 - Uploading .hex file

mikroBootloade	Select MCU	PIC18
1 Setup COM Port: COM18 Baud Rate: 115200	Change Settings	Conn Rx Tx
2 Connect Disconnect	History Window	
to MCU	Setup: Port COM1. Setup: Port COM18.	1
3 Choose Browse HEX file for HEX	Waiting MCU response Connected. Opened: C:\Project\SmartG	LCD.hex
4 Start Begin bootloader uploading	-01	
Bootloading		Show Activit

Figure 5-7: Begin uploading



In order to upload .HEX file click the **Begin** uploading button.

step 6 - Progress bar

1 Setup port	COM Port: Baud Rate:		Change Settings	Signals	Conn	Rx @	Τx
2 Connect	t Loi	connect	History Wir	dow			
3 Choose HEX file	B	irowse or HEX	Setup: Port COI Waiting MCU re Connected. Opened: C: (Pro Uploading	sponse	GLCD.ht	ex	
4 Start	ader up	Stop					

Figure 5-8: Progress bar

Progress bar enables you to monitor .HEX file uploading.

step 7 - Finishing upload

Setup port	Success		
2 Connector MCU	Reset MCU. Uploading program	n has finished.	0
3 Choose HEX file	Show details		ОК
4 Start	Begin C der uploading	ompleted successfully.	

Figure 5-9: Restarting MCU

finished.

OI Click **OK** button after the uploading process has been

02 Press Reset button on SmartGLCD board and wait for 5 seconds. Your program will run automatically.

Tips and Tricks: Speed-up UART data transfer

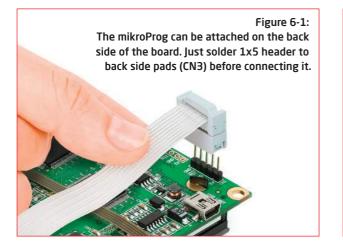
🚔 Device Manager	USB Serial Port (COM18) Properties	Advanced Settings for COM18
File Action View Help	USS Serial Port (COM18) Properties	Advanced Settings for COM18 COM Bort Number: COM18 USB Transfer Sizes Select lower settings to correct performance. Receive (Byten): 4095 Transmit (Byten): 4095 BM Options BM Options Select lower settings to correct response problem Select lower settings to correct response problem Latency Timer (msec):
Image: Second	OK Cancel	

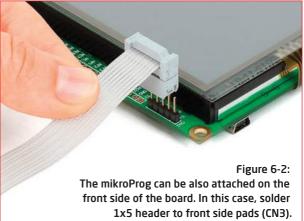
note If .HEX file transfer from your PC to MCU is too slow, it's possible to speed up data transfer by setting latency time of COM port to 1 ms. This is done in Device Manager:

- 01 02 04
 - Right click on the USB Serial Port (COM18) item and then select Properties.
 - Select Port Settings tab.
 - Click the **Advanced...** button.
 - Set Latency Timer to 1 and click OK.

6. Programming with mikroProg[™] programmer

The microcontroller can be programmed with the external **mikroProg**[™] programmer which can be connected to the board via **CN3** connector. Before establishing this connection it is necessary to solder 1x5 male header to **CN3** connection pads. This can be done in both ways: on the bottom, or the top side, as shown in **Figures 6-1** and **6-2**.





note If bootloader program is accidently erased you can upload it again through mikroProg programmer. Program Bootloader18F87K22.hex can be found under Firmware folder (page 12).

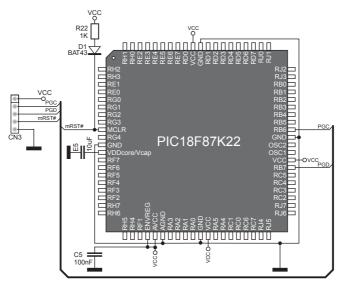


Figure 6-3: mikroProg[™] connection schematic



Make sure to use only the front row of mikroProg's IDC10 connector (side with a knob and incision) when connecting it to 1x5 header on your SmartGLCD board.



7. mikroProg Suite[™] for PIC[®] Software



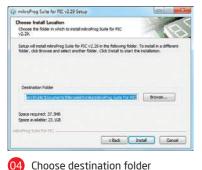
The **mikroProg**^{TD} programmer requires special programming software called mikroProg Suite^{TT} for PIC[®]. It can be used for programming all Microchip® microcontroller families, including PIC10[®], PIC12°, PIC16°, PIC18°, dsPIC30/33°, PIC24[®] and PIC32[®]. The software has intuitive interface and SingleClick[™] programming technology. Just download the latest version of mikroProg Suite^T and your programmer is ready to program new devices. mikroProg **Suite**Th is updated regularly, at least four times a year, so your programmer will be more and more powerful with each new release

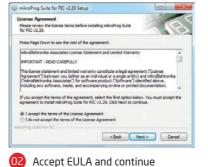


Figure 7-1: Main window of mikroProg Suite[™] for PIC[®] programming software

Software Installation Wizard



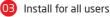




Indiverfrag Suite For 192
 Indiverfrag Suite For 192

Installation in progress









Finish installation

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8. microSD Card Slot

Figure 8-1: microSD card slot

There is a built-in microSD card slot provided on-board. It enables the expansion of available memory space using microSD cards. Communication between the microcontroller and the card is done through Serial Peripheral Interface (**SPI**).

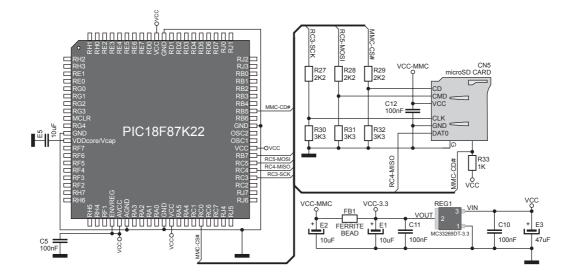
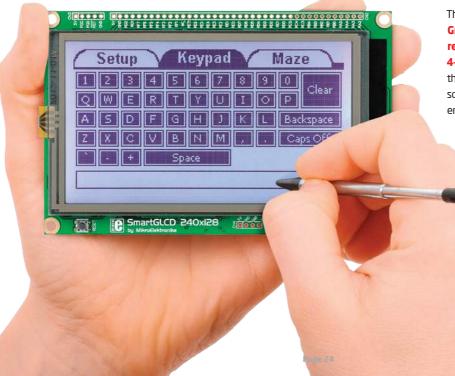


Figure 8-2: microSD Card Slot module connection schematic

9. Touch Screen



The development system features a **Graphical LCD in 240x128 pixel resolution.** Display is covered with a **4-wire resistive** touch panel. Together they form a functional unit called a touch screen, **Figure 9-1.** It enables data to be entered and displayed at the same time.

Figure 9-1: Touch Screen

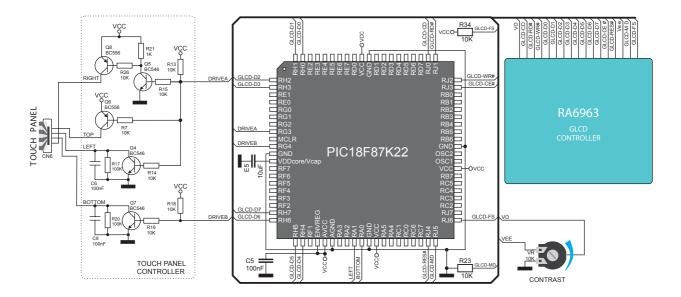
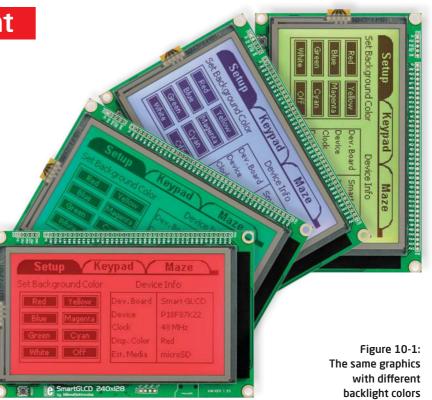


Figure 9-2: Touch Screen connection schematic

10. RGB backlight

Graphical LCDs are only capable of showing monochromatic pixel but not color content. The color of the pixel is determined by the color of the backlight which illuminates the display. SmartGLCD has **the RGB color backlight** - a very useful feature which can give your graphical user interfaces an astonishing look.

Display's backlight module consists of three LEDs: red, green and blue, which can shine simoutaneously. LED can be driven by PWM signals coming from three separate microcontroller pins. Duty ratio of the PWM signal determines the intensity of color (or brightness) of each LED. Combined together they can create more than 16 milion different backlight colors.



11. Contrast potentiometer

On the backside of the board there is a small potentiometer which can be used to change contrast of the GLCD. The brighter the backlight, the less contrast you will need to properly display the graphical content.

Figure 11-1: Constrast potentiometer

12. USB UART

Figure 12-1: Connecting USB cable to SmartGLCD board



Fast on-board **FTDI*** **chip** allows you to communicate with a PC or other UART devices using USB UART connection. Before connecting the board to a PC, make sure that you have the appropriate **FTDI drivers** installed on your operating system. Drivers can be found on the **Product DVD**:

DVD://download/eng/software/development-tools/universal/ftdi/vcp_drivers.zip

USB-B connector (**CN1**) is used for connecting the USB cable, which is delivered with the board package. Plug it in as shown in **Figure 12-1**.

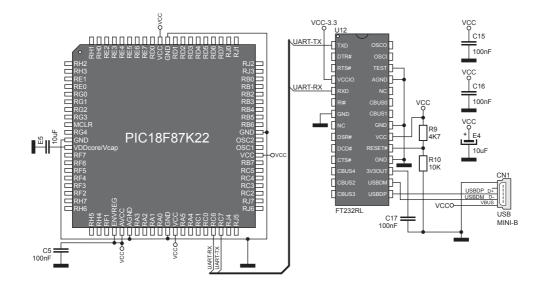


Figure 12-2: USB UART module connection schematic



Figure 13-1: Buzzer module

BUZZER

The board is also equipped with piezo buzzer. It is an electric component which can be used to create sound when provided with electrical signal. This is usually a PWM signal coming from a microcontroller pin. Before entering the buzzer itself, the signal is amplified by the on-board buzzer driver circuit. Frequency of the signal determines the pitch of the sound and duty cycle of the signal can be used to increase or decrease the volume.

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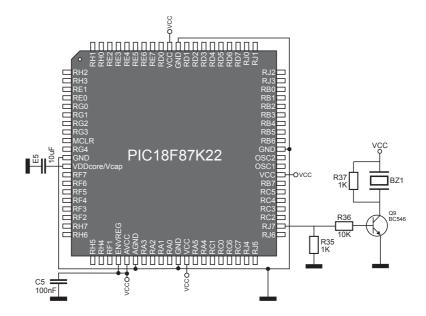
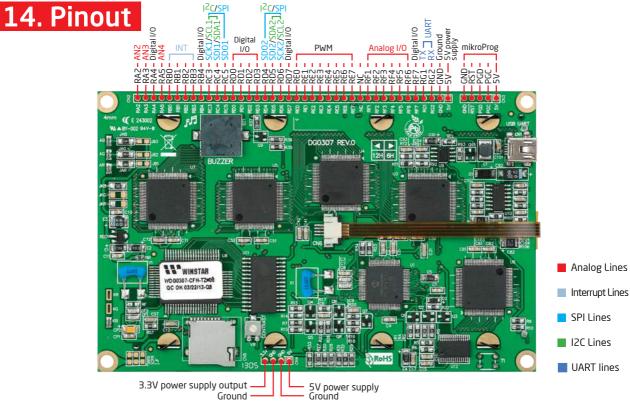


Figure 13-2: Buzzer module schematic



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15. Dimensions

Legend

mm

Mounting hole size Ø 4 mm

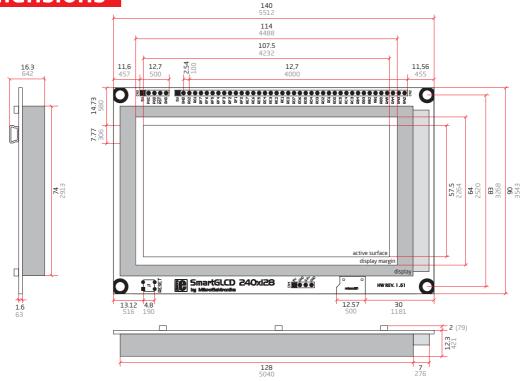
Tolerance +/- 0.5mm

mils

Pad hole size

Ø 1.14 mm Ø 45 mils

ø 157 mils



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What's next?

Your journey through each and every feature of SmartGLCD board ends here. You got to know it's modules and organization. Now you are ready to use it. We are suggesting several steps which are probably the best way to begin with. We invite you to join the users of SmartGLCD brand. You will find very useful projects and tutorials and can get help from a large ecosystem of users. Welcome!

Compiler

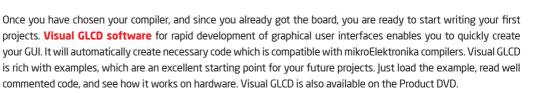
SOFTWARE

You still don't have an appropriate compiler? Locate PIC[®] compiler that suits you best on the Product DVD provided with the package:

DVD://download/eng/software/compilers/

Projects

Choose between mikroC[™], mikroBasic[™] and mikroPascal[™] and download fully functional demo version, so you can begin building your first applications.





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