











TPD12S015A

SLLSE74D -JUNE 2011-REVISED JULY 2016

# TPD12S015A HDMI Companion Chip With Step-Up DC-DC, I<sup>2</sup>C Level Shifter, and High-**Speed ESD Clamps**

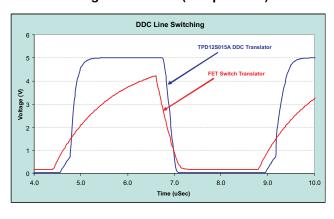
#### **Features**

- Conforms to HDMI Compliance Tests Without Any **External Components**
- Supports HDMI 1.3 and HDMI 1.4 Data Rate
- Match Class D and Class C Pin Mapping
- Excellent Matching Capacitance (0.05 pF) in Each Differential Signal Pair
- Internal Boost Converter to Generate 5 V From a 2.3-V to 5.5-V Battery Voltage
- Auto-Direction Sensing Level Shifting in the CEC, SDA, and SCL Paths
- IEC 61000-4-2 (Level 4) System Level ESD Compliance
- Improved Drop-In Replacement for the Industry Popular TPD12S015A
- Industrial Temperature Range: -40°C to 85°C

# **Applications**

- **Smart Phones**
- eBooks
- **Tablet PCs**
- Digital Camcorders
- Portable Game Consoles
- Digital Still Cameras

#### SCL B or SDA B Buffers of TPD12S015A Driving Long HDMI Cable (750-pF Load)



# 3 Description

The TPD12S015A device is an integrated HDMI companion chip solution. This device offers 8 low capacitance ESD clamps allowing HDMI 1.3/1.4 data rates. The 0.4-mm pitch DSBGA package pin mapping matches the HDMI Type D or Type C connectors. The integrated ESD clamps in monolithic silicon technology provide good matching between each differential signal pair. This provides an advantage over discrete ESD clamp solutions where variations between ESD clamps degrade the differential signal quality.

The TPD12S015A provides a regulated 5-V output (5VOUT) for sourcing the HDMI power line. The 5VOUT pin supplies minimum 55 mA to the HDMI receiver while meeting the HDMI specifications. The 5VOUT and the hot plug detect (HPD) circuitry are independent of the LS OE control signal; they are controlled by the CT\_CP\_HPD pin. This independent control enables the detection scheme (5VOUT + HPD) to be active before enabling the HDMI link. The HPD B port has a glitch filter to avoid false detection due to the bouncing while inserting the HDMI plug.

There are three noninverting bidirectional translation circuits for the SDA, SCL, and CEC lines; they are controlled by the LS OE control signal. Each have a common power rail (VCCA) on the A side from 1.1 V to 3.6 V. On the B side, the SCL B and SDA B each have an internal  $1.75-k\Omega$  pullup connected to the regulated 5-V rail (5VOUT). The SCL and SDA pins meet the I<sup>2</sup>C specifications, and drive at least 750-pF loads which exceeds the HDMI cable specification. An LDO generates a 3.3-V internal rail for the CEC line operation when LS OE = H & CT CP HPD = H. The CEC B pin has a  $26-k\Omega$  pullup to this internal 3.3-V rail.

The TPD12S015A provides IEC61000-4-2 (Level 4) ESD protection. This device is offered in a spacesaving 1.56-mm × 2.76-mm DSBGA package.

#### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)		
TPD12S015A	DSBGA (28)	1.56 mm × 2.76 mm		

(1) For all available packages, see the orderable addendum at the end of the data sheet.



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### 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

# Changes from Revision C (March 2013) to Revision D

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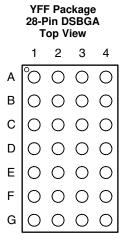
# Changes from Revision B (April 2012) to Revision C

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•	Changed Board Layout section	2



# 5 Pin Configuration and Functions



For package dimensions, see *Mechanical, Packaging, and Orderable Information* 

#### **Pin Functions**

PII	١		
NAME	NO.	TYPE	DESCRIPTION
5VOUT	F1	Power Out	DC-DC output. The 5-V power pin can supply 55 mA of regulated current to the HDMI receiver. Separate DC-DC converter control pin CT_CP_HPD disables the DC-DC converter when operating at low-power mode.
CEC_A	B2	I/O	System-side CEC bus I/O. This pin is bidirectional and referenced to V <sub>CCA</sub> .
CEC_B	D3	I/O	HDMI-side CEC bus I/O. This pin is bidirectional and referenced to the 3.3-V internal supply.
CLK-, CLK+	G4, F4	ESD	High-speed ESD clamp: provides ESD protection to the high-speed HDMI differential data lines
CT_CP_HPD	D1	Control	DC-DC Enable. Enables the DC-DC converter and HPD circuitry when CT_CP_HPD = H. The CT_CP_HPD is referenced to V <sub>CCA</sub> .
D0-, D0+, D1- , D1+, D2-, D2+	E4, D4, C4, B4, A4, A3	ESD	High-speed ESD clamp: provides ESD protection to the high-speed HDMI differential data lines
FB	E1	1	Feedback input. This pin is a feedback control pin for the DC-DC converter. It must be connected to 5VOUT.
GND	B3, C3, D2, E2	Ground	Device ground
HPD_A	C2	0	System-side output for the hot plug detect. This pin is unidirectional and is referenced to $V_{\text{CCA}}$ .
HPD_B	G3	1	HDMI-side input for the hot plug detect. This pin is unidirectional and is referenced to 5VOUT.
LS_OE	A1	Control	Level shifter enable. This pin is referenced to $V_{CCA}$ . Enables SCL, SDA, CEC level shifters, and LDO when LS_OE = H.
P <sub>GND</sub>	G1	Analog Ground	DC-DC converter ground. This pin must be tied externally to the system GND plane. See <i>Layout Guidelines</i> .
SCL_A	B1	I/O	System-side input and output for I <sup>2</sup> C bus. This pin is bidirectional and referenced to V <sub>CCA</sub> .
SCL_B	E3	I/O	HDMI-side input and output for I <sup>2</sup> C bus. This pin is bidirectional and referenced to 5VOUT.
SDA_A	C1	I/O	System-side input and output for I <sup>2</sup> C bus. This pin is bidirectional and referenced to V <sub>CCA</sub> .
SDA_B	F3	I/O	HDMI-side input and output for I <sup>2</sup> C bus. This pin is bidirectional and referenced to 5VOUT.
SW	F2	l	Switch input. This pin is the inductor input for the DC-DC converter.
$V_{BAT}$	G2	Supply	Battery supply. This voltage is typically 2.3 V to 5.5 V
V <sub>CCA</sub>	A2	Supply	System-side supply. this voltage is typically 1.2 V to 3.3 V from the core microcontroller.



# **Table 1. YFF Package Pin Mapping**

	1	2	3	4
Α	LS_OE	V <sub>CCA</sub>	D2+	D2-
В	SCL_A	CEC_A	GND	D1+
С	SDA_A	HPD_A	GND	D1-
D	CT_CP_HPD	GND	CEC_B	D0+
E	FB	GND	SCL_B	D0-
F	5VOUT	SW	SDA_B	CLK+
G	$P_GND$	$V_{BAT}$	HPD_B	CLK-



# 6 Specifications

#### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) (1)

			MIN	MAX	UNIT
$V_{CCA}$	Supply voltage			4	V
$V_{BAT}$	Supply voltage		-0.3	6	
VI	lanut valtaga	HPD_B, Dx, CLKx	-0.3	6	V
	Input voltage	CT_CP_HPD, LS_OE	-0.3	4	V
	Voltage range applied to any output in the high-impedance or power-off state (2)	SCL_A, SDA_A, CEC_A, HPD_A	-0.3	4	
V		SCL_B, SDA_B, CEC_B	-0.3	6	V
Vo	Voltage range applied to any output in the high or low state <sup>(3)</sup>	SCL_A, SDA_A, CEC_A, HPD_A	-0.3	$V_{CCA} + 0.3$	V
		SCL_B, SDA_B, CEC_B	-0.3	6	
$I_{IK}$	Input clamp current	V <sub>I</sub> < 0		-50	mA
lok	Output clamp current	V <sub>O</sub> < 0		-50	mA
I <sub>OUTMAX</sub>	Continuous current through 5VOUT or GND			±100	mA
T <sub>stg</sub>	Storage temperature		-65	150	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) The input and output voltage ratings may be exceeded if the input and output clamp-current ratings are observed.

#### 6.2 ESD Ratings

				VALUE	UNIT
	Electrostatic	Human bady model (HDM) new ANCI/ECDA/JEDEC JC	All pins except B1, C1, B2, D1, A1, and A2	±2500	
V <sub>(ESD)</sub>		Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 (1)	Pins E4, D4, B4, C4, D2+, D2-, F4, G4, E3, F3, D3, G3, F1, and E1	±15000	V
(===)		Charged-device model (CDM), per JEDEC specification JESD22-C101 (2)			
		IEC 61000-4-2 contact discharge	Pins D4, E4, B4, C4, A3, A4, F4, G4, E3, F3, D3, G3, F1, E1	±8000	

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

#### 6.3 Recommended Operating Conditions

over recommended operating free-air temperature range (unless otherwise noted)

			SUPPLY	MIN	NOM MAX	UNIT
$V_{CCA}$	Supply voltage			1.1	3.6	V
$V_{BAT}$	Supply voltage			2.3	5.5	V
	High-level input voltage	SCL_A, SDA_A, CEC_A	V <sub>CCA</sub> = 1.1 V to 3.6 V	0.7 × V <sub>CCA</sub>	$V_{CCA}$	
		CT_CP_HPD, LS_OE		1	3.6	
V <sub>IH</sub>		SCL_B, SDA_B	5VOUT = 5 V	0.7 × 5VOUT	5VOUT	V
		CEC_B		$0.7 \times 3.3$ (internal) <sup>(1)</sup>	3.3 (internal) <sup>(1)</sup>	
		HPD_B		2	5VOUT	

(1) '3.3V (internal)' is an internally generated voltage node for the CEC\_B output buffer supply reference. An LDO generates this 3.3 V from 5VOUT when LS OE = H & CT CP HPD = H.

<sup>(3)</sup> The package thermal impedance is calculated in accordance with JESD 51-7.

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



# **Recommended Operating Conditions (continued)**

over recommended operating free-air temperature range (unless otherwise noted)

		1 0 (	SUPPLY	MIN	NOM MAX	UNIT
		SCL_A, SDA_A, CEC_A	V <sub>CCA</sub> = 1.1 V to 3.6 V	0	0.082 × V <sub>CCA</sub>	
		CT_CP_HPD, LS_OE		0	0.4	
V <sub>IL</sub>	Low-level input voltage	SCL_B, SDA_B		0	0.3 × 5VOUT	V
		CEC_B	5VOUT = 5 V		$0.3 \times 3.3 \text{V}$ (internal) <sup>(1)</sup>	
		HPD_B		0	0.8	
$V_{ILC}$	Low-level input voltage (contention)	SCL_A, SDA_A, CEC_A	V <sub>CCA</sub> = 1.1 V to 3.6 V	0	0.065 × V <sub>CCA</sub>	٧
V <sub>OL</sub> – V <sub>ILC</sub>	Delta between $V_{OL}$ and $V_{ILC}$	SCL_A, SDA_A, CEC_A	V <sub>CCA</sub> = 1.1 V to 3.6 V		0.1 × V <sub>CCA</sub>	V
$T_A$	Operating free-air temperature			-40	85	°C

#### 6.4 Thermal Information

		TPD12S015A	
	THERMAL METRIC <sup>(1)</sup>	YFF (DSBGA)	UNIT
		28 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	63	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	0.4	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	9.2	°C/W
ΨЈТ	Junction-to-top characterization parameter	1.6	°C/W
ΨЈВ	Junction-to-board characterization parameter	9.1	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

# 6.5 Electrical Characteristics: I<sub>CC</sub>

	PARAMETER	PIN	TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Standby	V	I/O High			2	
ICCA	Active	V <sub>CCA</sub>	I/O = High			15	μΑ
	Standby	+	CT_CP_HPD=L, LS_OE=L, HPD_B=L		2		μΑ
loop	DC-DC and HPD active		CT_CP_HPD=H, LS_OE=L, HPD_B=L		30	50	
ICCB	DC-DC, HPD, DDC, CEC active	▼BA1	CT_CP_HPD=H LS_OE=H, HPD_B=L, I/O =H		225	300	

# 6.6 Electrical Characteristics: High-Speed ESD Lines: Dx, CLK

	<b>3</b> 1								
	PARAMETER	TI	EST CONDITIONS	MIN	TYP	MAX	UNIT		
I <sub>OFF</sub>	Current from IO port to supply pins	V <sub>CC</sub> = 0 V, V <sub>IO</sub> = 3.3 V			0.01	0.5	μΑ		
$V_{DL}$	Diode forward voltage	$I_D = 8 \text{ mA},$	Lower clamp diode		0.85	1	V		
$R_{DYN}$	Dynamic resistance	I = 1 A	D, CLK		1		Ω		
C <sub>IO</sub>	IO capacitance	$V_{CC} = 5 V$ $V_{IO} = 2.5 V$	D, CLK		1.3		pF		
$V_{BR}$	Break-down voltage	I <sub>IO</sub> = 1 mA		9		12	V		



## 6.7 Electrical Characteristics: DC-DC Converter

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>BAT</sub>	Input voltage range		2.3		5.5	V
5VOUT	Total DC output voltage	Includes voltage references, DC load / line regulations, process and temperature	4.9	5	5.13	V
TOVA	Total output voltage accuracy	Includes voltage references, DC load / line regulations, transient load / line regulations, ripple, process, and temperature	4.8	5	5.3	V
V <sub>O_Ripple</sub>	Output voltage ripple, loaded	I <sub>O</sub> = 65 mA			20	mVp-p
F_clk	Internal operating frequency	V <sub>BAT</sub> = 2.3 V to 5.5 V		3.5		MHz
t <sub>start</sub>	Start-up time	From CT_CP_HPD input to 5-V power output 90% point			300	μs
lo	Output current	V <sub>BAT</sub> = 2.3 V to 5.5 V	55			mA
	Reverse leakage current V <sub>O</sub>	CT_CP_HPD= L, V <sub>O</sub> = 5.5 V			2.5	μΑ
	Leakage current from battery to $V_{\rm O}$	CT_CP_HPD= L			5	μΑ
M	Linday of the sea lead to the the sea hald	Falling		2		V
$V_{BATUVT}$	Undervoltage lockout threshold	Rising		2.1		V
M	Out a must be an a local to the seal of	Falling		5.9		V
$V_{BATOVT}$	Overvoltage lockout threshold	Rising		6		V
	Line transient response	$V_{BAT}$ = 3.6 V, a pulse of 217-Hz 600 mVp-p square wave, $I_{O}$ = 20/65 mA		±25	±50	mVpk
	Load transient response	$V_{BAT} = 3.6 \text{ V}, \ I_{O} = 5 \text{ to } 65 \text{ mA}, \ \text{pulse of } 10 \ \mu\text{s}, \ t_{r}$ = $t_{f} = 0.1 \ \mu\text{s}$		50		mVpk
I <sub>DD (idle)</sub>	Power supply current from V <sub>BAT</sub> to DC-DC, enabled, unloaded	I <sub>O</sub> = 0 mA		30	50	μΑ
I <sub>DD</sub> (disabled)	Power supply current from V <sub>BAT</sub> , DC-DC Disabled, Unloaded	$V_{BAT}$ = 2.3 V to 5.5 V, $I_{O}$ = 0 mA, CT_CP_HPD Low			2	μΑ
I <sub>DD(system off)</sub>	Power supply current from V <sub>BAT</sub> , V <sub>CCA</sub> =0 V	V <sub>CCA</sub> = 0 V			5	μΑ
I_inrush (startup)	Inrush current, average over T_startup time	$V_{BAT} = 2.3 \text{ V to } 5.5 \text{ V}, I_{O} = 65 \text{ mA}$		100		mA
T <sub>SD</sub>	Thermal shutdown	Increasing junction temperature		140		°C
$\Delta T_{SD}$	Thermal shutdown hysteresis	Decreasing junction temperature		20		°C
I <sub>SC</sub>	Short-circuit current limit from output	$5$ - $\Omega$ short to GND			500	mA

## 6.8 Electrical Characteristics: Passive Components

	PARAMETER	TYP	UNIT
L <sub>IN</sub>	External inductor, 0805 footprint	1	μΗ
C <sub>IN</sub>	Input capacitor, 0603 footprint	4.7	μF
C <sub>OUT</sub>	Output capacitor, 0603 footprint	4.7	μF
C <sub>VCCA</sub>	Input capacitor, 0402 footprint	0.1	μF



## 6.9 Electrical Characteristics: Voltage Level Shifter: SCL, SDA Lines (x\_A/x\_B Ports)

 $T_A = -40$ °C to 85°C unless otherwise specified

PA	RAMETER	TES	T CONDITIONS	V <sub>CCA</sub>	MIN	TYP	MAX	UNIT
V <sub>OHA</sub>		$I_{OH} = -10 \mu A$ ,	$V_I = V_{IH}$	1.1 V to 3.6 V	V <sub>CCA</sub> × 0.8			V
V <sub>OLA</sub>		$I_{OL} = 10 \mu A$ ,	$V_I = V_{IL}$	1.1 V to 3.6 V		V <sub>CCA</sub> × 0.17		V
V <sub>OHB</sub>		$I_{OH} = -10 \mu A$ ,	$V_I = V_{IH}$		5VOUT × 0.9			V
V <sub>OLB</sub>		$I_{OL} = 3 \text{ mA},$	$V_I = V_{IL}$				0.4	V
$\Delta V_T$ hysteresis	SDx_A (V <sub>T+</sub> - V <sub>T-</sub> )			1.1 V to 3.6 V		40		mV
	$SDx\_B (V_{T+} - V_{T-})$			1.1 V to 3.6 V		400		IIIV
D	(Internal pullup)	SCL_A, SDA_A,	Internal pullup connected to V <sub>CCA</sub> rail			10		kΩ
R <sub>PU</sub>		SCL_B, SDA_B,	Internal pullup connected to 5-V rail			1.75		K22
I <sub>PULLUPAC</sub>	Transient boosted pullup current (rise time accelerator)	SCL_B, SDA_B,	Internal pullup connected to 5-V rail			15		mA
	A port	$V_{CCA} = 0 V, V_{I}$	or $V_O = 0$ to 3.6 V	0 V			±5	
l <sub>OFF</sub>	B port	5VOUT = 0 V,	$V_I$ or $V_O = 0$ to 5.5 V	0 V to 3.6 V			±5	μΑ
	B port	$V_O = V_{CCO}$ or $0$	GND	1.1 V to 3.6 V			±5	
l <sub>OZ</sub>	A port	V <sub>I</sub> = V <sub>CCI</sub> or GI	D	1.1 V to 3.6 V			±5	μΑ

# 6.10 Electrical Characteristics: Voltage Level Shifter: CEC Lines (x\_A/x\_B Ports)

 $T_A = -40$ °C to 85°C unless otherwise specified

PAR	AMETER	TE	ST CONDITIONS	V <sub>CCA</sub>	MIN	TYP	MAX	UNIT	
V <sub>OHA</sub>		$I_{OH} = -10 \mu A$ ,	$V_I = V_{IH}$	1.1 V to 3.6 V	V <sub>CCA</sub> × 0.8			V	
V <sub>OLA</sub>		$I_{OL} = 10 \mu A$ , $V_I = V_{IL}$		1.1 V to 3.6 V		V <sub>CCA</sub> × 0.17		V	
V <sub>OHB</sub>		$I_{OH} = -10 \mu A,$	$V_I = V_{IH}$		3.3V (internal) × 0.9 <sup>(1)</sup>			V	
V <sub>OLB</sub>		$I_{OL} = 3 \text{ mA},$	$V_I = V_{IL}$				0.4	٧	
AV_ hvetorosis	CEC_A (V <sub>T+</sub> - V <sub>T-</sub> )			1.1 V to 3.6 V		40		mV	
∆V <sub>T</sub> hysteresis	CEC_B (V <sub>T+</sub> - V <sub>T-</sub> )			1.1 V to 3.6 V		300			
В	(Internal pullup)	CEC_A	Internal pullup connected to V <sub>CCA</sub> rail			10		kΩ	
R <sub>PU</sub>	(Internal pullup)	CEC_B	Internal pullup connected to internal 3.3-V rail			26		K\$2	
	A port	$V_{CCA} = 0 V, V$	or $V_0 = 0$ to 3.6 V	0 V			±5		
I <sub>OFF</sub>	B port	5VOUT = 0 V,	$V_I$ or $V_O = 0$ to 5.5 $V$	0 V to 3.6 V			±1.8	μΑ	
l <sub>OZ</sub>	B port	V <sub>O</sub> = V <sub>CCO</sub> or	GND	1.1 V to 3.6 V			±5		
	A port	V <sub>I</sub> = V <sub>CCI</sub> or G	ND	1.1 V to 3.6 V			±5	μΑ	

<sup>(1) 3.3</sup> V (internal) is an internally generated voltage node for the CEC\_B output buffer supply reference. An LDO generates this 3.3 V from 5VOUT when LS\_OE = H & CT\_CP\_HPD = H

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# 6.11 Electrical Characteristics: Voltage Level Shifter: HPD Line (x\_A/x\_B Ports)

 $T_A = -40$ °C to 85°C unless otherwise specified

PARAMETER		TES	ST CONDITIONS	V <sub>CCA</sub>	MIN	TYP	MAX	UNIT
V <sub>OHA</sub>		$I_{OH} = -3 \text{ mA},$	$V_{I} = V_{IH}$	1.1 V to 3.6 V	$V_{CCA} \times 0.7$			V
V <sub>OLA</sub>		$I_{OL} = 3 \text{ mA},$	$V_I = V_{IL}$	1.1 V to 3.6 V			0.4	V
$\Delta V_T$ hysteresis	HPD_B (V <sub>T+</sub> – V <sub>T-</sub> )			1.1 V to 3.6 V		200		mV
R <sub>PD</sub>	(Internal pulldown)	HPD_B,	Internal pulldown connected to GND			11		kΩ
I <sub>OZ</sub>	A port	$V_I = V_{CCI}$ or G	ND	3.6 V			±5	μΑ

# 6.12 Electrical Characteristics: LS\_OE, CT\_CP\_HPD

 $T_A = -40$ °C to 85°C unless otherwise specified

PARAMETER	TEST CONDITIONS	V <sub>CCA</sub>	MIN	TYP	MAX	UNIT
I <sub>I</sub>	$V_I = V_{CCA}$ or GND	1.1 V to 3.6 V			±12	μΑ

### 6.13 Electrical Characteristics: I/O Capacitance

 $T_A = -40$ °C to 85°C unless otherwise specified

PA	RAMETER	TEST CONDITIONS	V <sub>CCA</sub>	MIN	TYP	MAX	UNIT
C <sub>I</sub>	Control inputs	V <sub>I</sub> = 1.89 V or GND, AC input = 30 mV(p-p); f = 10 MHz	1.1 V to 3.6 V		7.1		рF
C <sub>IO</sub>	A port	$V_O$ = 1.89 V or GND, AC input = 30 mV(p-p); f = 10 MHz, CT_CP_HPD = H, LS_OE = L	1.1 V to 3.6 V		8.3		рF
	B port	$V_O$ = 5 V or GND, AC input = 30 mV(p-p); f = 10 MHz, CT_CP_HPD = H, LS_OE = L	3.3 V		15		рF
	SCL_B, SDA_B	$V_{BAT} = 0 \text{ V}, V_{bias} = 2.5 \text{ V}; AC \text{ input} = 3.5 \text{ V(p-p)}; f = 100 \text{ kHz}$	0 V		20		рF
C <sub>IO</sub>	CEC B	$V_{BAT} = 0 \text{ V}, V_{bias} = 1.65 \text{ V}; AC input = 2.5 V(p-p); f = 100 kHz$	0 V		20		рF
	OLO_B	$V_{BAT} = 3.3 \text{ V}, V_{bias} = 1.65 \text{ V}; AC \text{ input} = 2.5 \text{ V}(p-p); f = 100 \text{ kHz}, CT\_CP\_HPD = H, LS\_OE = L$	3.3 V		20		pF

# 6.14 Switching Characteristics

	<u>_</u>					
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
_	Bus load capacitance (B side)				750	~F
CL	Bus load capacitance (A side)				15	ρг

# 6.15 Switching Characteristics: Voltage Level Shifter: SCL, SDA Lines ( $x_A & x_B ports$ ); $V_{CCA} = 1.2 V$

 $V_{CCA} = 1.2 \text{ V}$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP	MAX	UNIT	
+	Propagation doloy	A to B	DDC Channels Enabled	344		ns	
t <sub>PHL</sub>	Propagation delay	B to A	DDC Charnels Enabled	355		113	
	Propagation delay	A to B	DDC Channels Enabled	452		ns	
t <sub>PLH</sub>		B to A		178			
	A port fall time	A Port	DDC Channels Enabled	138		ns	
t <sub>f</sub>	B port fall time	B Port	DDC Channels Enabled	83			
	A port rise time	A Port	DDC Charrels Fredlad	194			
ι <sub>r</sub>	B port rise time	B Port	DDC Channels Enabled	92		ns	
f <sub>MAX</sub>	Maximum switching frequency		DDC Channels Enabled	400		kHz	



# 6.16 Switching Characteristics: Voltage Level Shifter: CEC Line (x\_A & x\_B ports); V<sub>CCA</sub> = 1.2 V

 $V_{CCA} = 1.2 \text{ V}$ 

OOA	PARAMETER	PINS	TEST CONDITIONS	MIN TYF	MAX	UNIT	
	TANAMETER	A to B	1201 CONDITIONS	445		Oitii	
$t_{PLH}$				337		ns	
t <sub>PLH</sub> Pro	Propagation delay	B to A	CEC Channels Enabled				
		A to B		13		μs	
		B to A		0.266	5		
t <sub>f</sub>	A port fall time	A Port	CEC Channels Enabled	140	)	ns	
ч	B port fall time	B Port	OLO GHAMINEIS ENADICO	96	3	113	
+	A port rise time	A Port	CEC Channels Enabled	202	2	ns	
t <sub>r</sub>	B port rise time	B Port	CEC Channels Enabled	15	5	μs	

# 6.17 Switching Characteristics: Voltage Level Shifter: HPD Line (x\_A & x\_B ports); V<sub>CCA</sub> = 1.2 V

 $V_{CCA} = 1.2 V$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP	MAX	UNIT	
t <sub>PLH</sub>	Dropogation dalay	B to A	CEC Channels Enabled	10			
t <sub>PLH</sub>	Propagation delay	B to A	GEC Channels Enabled	9		μs	
t <sub>f</sub>	A port fall time	A Port	CEC Channels Enabled	0.67		ns	
t <sub>r</sub>	A port rise time	A Port	CEC Channels Enabled	0.74		ns	

# 6.18 Switching Characteristics: Voltage Level Shifter: SCL, SDA Lines ( $x_A \& x_B ports$ ); $V_{CCA} = 1.5 V$

 $V_{CCA} = 1.5 \text{ V}$ 

- COA - 1-9 -									
	PARAMETER	PINS	TEST CONDITIONS	MIN TYP MAX	UNIT				
		A to B		335					
t <sub>PLH</sub>	Propagation delay	B to A	DDC Channels Enabled	265	200				
t <sub>PLH</sub>		A to B		438	ns				
		B to A		169					
	A port fall time	A Port	DDC Channels Fachlad	110	ns				
l <sub>f</sub>	B port fall time	B Port	DDC Channels Enabled	83					
	A port rise time	A Port	DDC Channels Enabled	190					
t <sub>r</sub>	B port rise time	B Port	DDC Channels Enabled	92	ns				
f <sub>MAX</sub>	Maximum switching frequency		DDC Channels Enabled	400	kHz				

# 6.19 Switching Characteristics: Voltage Level Shifter: CEC Line ( $x_A & x_B ports$ ); $V_{CCA} = 1.5 V$

 $V_{CCA} = 1.5 \text{ V}$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP	MAX	UNIT
+		A to B		437		no
t <sub>PLH</sub>	Duana antian dalau	B to A	CEC Channels Enabled	267		ns
	Propagation delay	A to B	CEC Channels Enabled	13		
t <sub>PLH</sub>		B to A		0.264		μs
	A port fall time	A Port	CEC Channels Enabled	110		20
ιf	B port fall time	B Port	CEC Channels Enabled	96		ns
	A port rise time	A Port	CEC Channala Fachlad	202		ns
τ <sub>r</sub>	B port rise time	B Port	CEC Channels Enabled	15		μs



# 6.20 Switching Characteristics: Voltage Level Shifter: HPD Line (x\_A & x\_B ports); V<sub>CCA</sub> = 1.5 V

 $V_{CCA} = 1.5 V$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{PLH}$	Drangation dolor	B to A	CEC Channels Enghlad		10		
$t_{PLH}$	Propagation delay	B to A	CEC Channels Enabled		9		μs
t <sub>f</sub>	A port fall time	A Port	CEC Channels Enabled		0.47		ns
t <sub>r</sub>	A port rise time	A Port	CEC Channels Enabled		0.51		ns

# 6.21 Switching Characteristics: Voltage Level Shifter: SCL, SDA Lines (x\_A & x\_B ports); V<sub>CCA</sub> = 1.8 V

 $V_{CCA} = 1.8 \text{ V}$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP MAX	UNIT
		A to B		334	
t <sub>PLH</sub>	Dranagation delay	B to A	DDC Channels Enabled	229	
	Propagation delay	A to B	DDC Charmers Enabled	431	ns
t <sub>PLH</sub>		B to A		169	
	A port fall time	A Port	DDC Channels Enabled	94	20
t <sub>f</sub>	B port fall time	B Port	DDC Charmers Enabled	83	ns
	A port rise time	A Port	DDC Channels Enabled	191	20
۱۲	B port rise time	B Port	DDC Charmers Enabled	92	ns
$f_{MAX}$	Maximum switching frequency		DDC Channels Enabled	400	kHz

# 6.22 Switching Characteristics: Voltage Level Shifter: CEC Line (x\_A & x\_B ports); V<sub>CCA</sub> = 1.8 V

 $V_{CCA} = 1.8 \text{ V}$ 

- TOA - 118 T							
	PARAMETER	PINS	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		A to B			441		
t <sub>PLH</sub>	Dranagation dalay	B to A	CEC Channels Enabled		231		ns
	Propagation delay	A to B	GEC Channels Enabled		13		
t <sub>PLH</sub>		B to A			0.26		μs
	A port fall time	A Port	OFO Chanada Frahlad		94		
ι <sub>f</sub>	B port fall time	B Port	CEC Channels Enabled		96		ns
	A port rise time	A Port	- CEC Channels Enabled		201		ns
t <sub>r</sub>	B port rise time	B Port			15		μs

# 6.23 Switching Characteristics: Voltage Level Shifter: HPD Line ( $x_A & x_B ports$ ); $V_{CCA} = 1.8 \text{ V}$

 $V_{CCA} = 1.8 V$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP N	IAX UNIT
t <sub>PLH</sub>	Dranagation dolor	B to A	CEC Channels Enabled	10	
t <sub>PLH</sub>	Propagation delay	B to A	GEC Channels Enabled	9	μs
t <sub>f</sub>	A port fall time	A Port	CEC Channels Enabled	0.41	ns
t <sub>r</sub>	A port rise time	A Port	CEC Channels Enabled	0.45	ns



# 6.24 Switching Characteristics: Voltage Level Shifter: SCL, SDA Lines (x\_A & x\_B ports); $V_{CCA} = 2.5 \text{ V}$

 $V_{CCA} = 2.5 \text{ V}$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP MAX	UNIT
		A to B		330	
t <sub>PLH</sub>	Dranagation delay	B to A	DDC Channels Enabled	182	
+	Propagation delay	A to B	DDC Channels Enabled	423	ns
t <sub>PLH</sub>		B to A		166	
	A port fall time	A Port	DDC Channels Enabled	79	200
Lf	B port fall time	B Port	DDC Charmers Enabled	83	ns
	A port rise time	A Port	DDC Channels Enabled	188	
l <sub>r</sub>	B port rise time	B Port	DDC Channels Enabled	92	ns
$f_{MAX}$	Maximum switching frequency	·	DDC Channels Enabled	400	kHz

# 6.25 Switching Characteristics: Voltage Level Shifter: CEC Line ( $x_A & x_B ports$ ); $V_{CCA} = 2.5 V$

 $V_{CCA} = 2.5 \text{ V}$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP	MAX	UNIT
		A to B		454		
t <sub>PLH</sub>	Dranagation dalay	B to A	CEC Channels Enabled	184		ns
	Propagation delay	A to B	CEC Channels Enabled	13		
t <sub>PLH</sub>		B to A		0.255		μs
	A port fall time	A Port	CEC Channels Enabled	79		20
t <sub>f</sub>	B port fall time	B Port	CEC Channels Enabled	96		ns
	A port rise time	A Port	CEC Channels Enabled	194		ns
۱۲	B port rise time	B Port	CEC Charmers Effabled	15		μs

# 6.26 Switching Characteristics: Voltage Level Shifter: HPD Line (x\_A & x\_B ports); V<sub>CCA</sub> = 2.5 V

 $V_{CCA} = 2.5 V$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP	MAX	UNIT
t <sub>PLH</sub>	Dropogation dalay	B to A	CEC Channels Enghlad	10		
t <sub>PLH</sub>	Propagation delay	B to A	CEC Channels Enabled	9		μs
t <sub>f</sub>	A port fall time	A Port	CEC Channels Enabled	0.37		ns
t <sub>r</sub>	A port rise time	A Port	CEC Channels Enabled	0.39		ns

# 6.27 Switching Characteristics: Voltage Level Shifter: SCL, SDA Lines ( $x_A \& x_B ports$ ); $V_{CCA} = 3.3 V$

 $V_{CCA} = 3.3 \text{ V}$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP MAX	UNIT
		A to B		323	
t <sub>PLH</sub>	Dranagation dolor	B to A	DDC channels enabled	158	
	Propagation delay	A to B	DDC channels enabled	421	ns
t <sub>PLH</sub>		B to A		162	
	A port fall time	A Port	DDC channels enabled	71	
t <sub>f</sub>	B port fall time	B Port	DDC channels enabled	84	ns
	A port rise time	A Port	DDC channels enabled	188	20
ι <sub>r</sub>	B port rise time	B Port	DDC channels enabled	92	ns
$f_{MAX}$	Maximum switching frequency		DDC channels enabled	400	kHz



# 6.28 Switching Characteristics: Voltage Level Shifter: CEC Line ( $x_A & x_B ports$ ); $V_{CCA} = 3.3 \text{ V}$

 $V_{CCA} = 3.3 \text{ V}$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP	MAX	UNIT	
		A to B		450		no	
t <sub>PLH</sub>	Propagation dalay	B to A	CEC channels enabled	160		ns	
	Propagation delay	A to B	CEC chamiles enabled	13			
t <sub>PLH</sub>		B to A		0.251		μs	
	A port fall time	A Port	CEC channels enabled	71		20	
t <sub>f</sub>	B port fall time	B Port	CEC channels enabled	96		ns	
	A port rise time	A Port	CEC channels enabled	194		ns	
۱۲	B port rise time	B Port	CEC charmers enabled	15		μs	

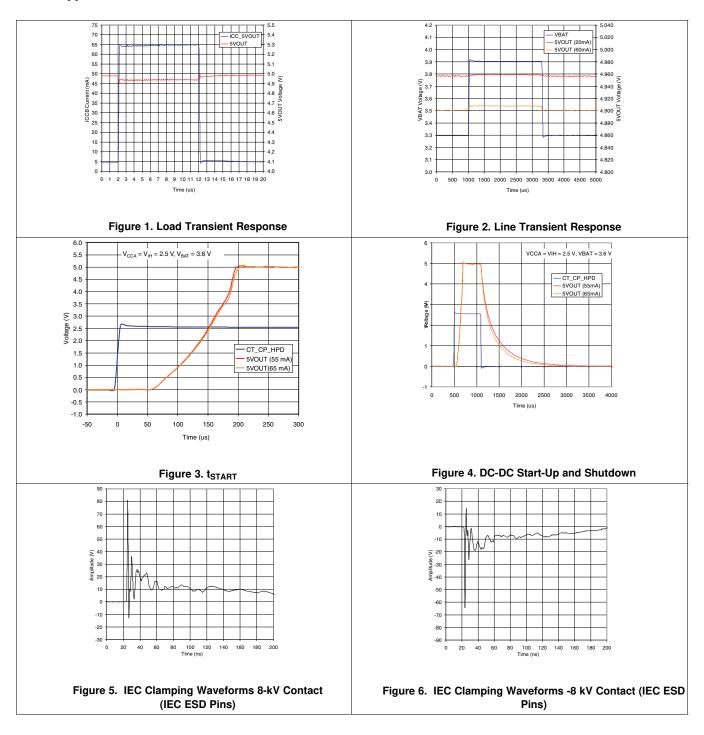
# 6.29 Switching Characteristics: Voltage Level Shifter: HPD Line ( $x_A & x_B ports$ ); $V_{CCA} = 3.3 \text{ V}$

 $V_{CCA} = 3.3 V$ 

	PARAMETER	PINS	TEST CONDITIONS	MIN TYP	MAX	UNIT
t <sub>PLH</sub>	Dropogation dalou	B to A	CEC channels enabled	10		
t <sub>PLH</sub>	Propagation delay	B to A	GEC channels enabled 9			μs
t <sub>f</sub>	A port fall time	A Port	CEC channels enabled	0.35		ns
t <sub>r</sub>	A port rise time	A Port	CEC channels enabled	0.37		ns

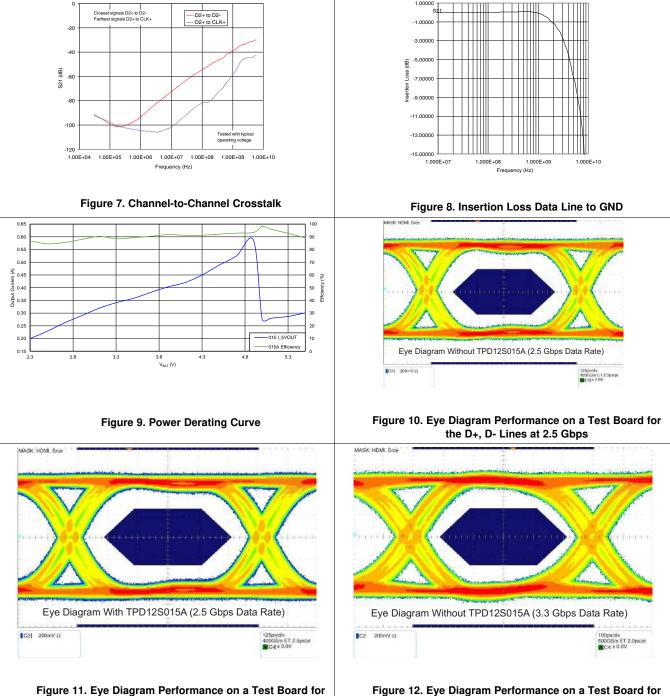


### 6.30 Typical Characteristics





### **Typical Characteristics (continued)**

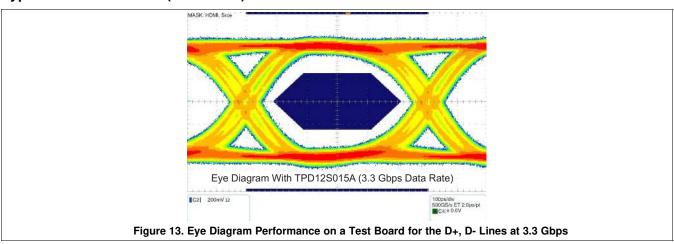


the D+, D- Lines at 3.3 Gbps

the D+, D- Lines at 2.5 Gbps



# **Typical Characteristics (continued)**

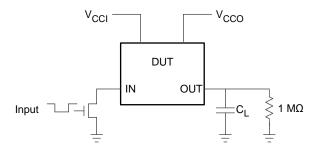


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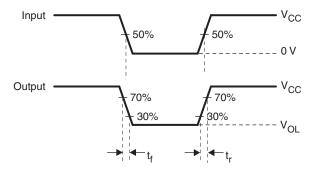


### 7 Parameter Measurement Information



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PIN	CL
DDC, CEC (A side	750 pF
DDC, CEC, HPD (E side)	3 15 pF



- A.  $R_T$  termination resistance must be equal to  $Z_{OUT}$  of pulse generators.
- B.  $C_L$  includes probe and jig capacitance.
- C. All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  10 MHz,  $Z_O = 50 \Omega$ , slew rate > 1 V/ns
- D. The outputs are measured one at a time, with one transition per measurement.
- E.  $t_{PLH}$  and  $t_{PHL}$  are the same as  $t_{pd}$ .

Figure 14. Test Circuit and Voltage Waveforms

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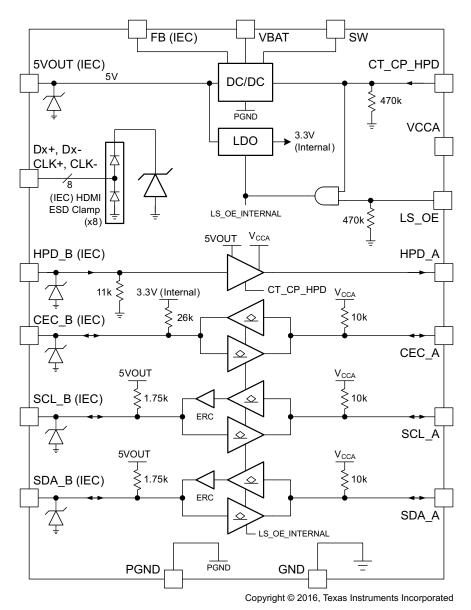


### 8 Detailed Description

#### 8.1 Overview

The TPD12S015A is an integrated interface solution for HDMI 1.3/1.4 interfaces, for both portable and non-portable electronics applications. It has a boost DC-DC converter that uses the 2.3-V to 5.5-V internal power supply and outputs regulated 5-V standard compliant power supply to the cable. This power supply output has current limit and short-circuit protection function. There are bidirectional level shifting and signal conditioning circuits on CEC, SCL, SDA with pullup resistors integrated to minimize the external passive discrete component use. There is also a unidirectional level shifter for HPD signal that translates the 5-V HPD down to  $V_{\rm CCA}$  level. The HPD\_B port has a glitch filter to avoid false detection due to the bouncing while inserting the HDMI plug. For the eight TMDS lines, there are high-speed ESD diodes on each line to make sure that the system pass 8-kV contact ESD.

#### 8.2 Functional Block Diagram



3.3 V (Internal) is an internally generated voltage node for the CEC\_B output buffer supply reference. An LDO generates this 3.3 V from 5VOUT when LS\_OE = H & CT\_CP\_HPD = H.

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#### 8.3 Feature Description

#### 8.3.1 Rise-Time Accelerators

The HDMI cable side of the DDC lines incorporates rise-time accelerators to support the high capacitive load on the HDMI cable side. The rise time accelerator boosts the cable side DDC signal independent of which side of the bus is releasing the signal.

#### 8.3.2 Internal Pullup Resistor

The TPD12S015A has incorporated all the required pullup and pulldown resistors at the interface pins. The system is designed to work properly with no external pullup resistors on the DDC, CEC, and HPD lines. For proper system operation, no external resistors must be placed at the A and B ports. If there is internal pullups at the host processor, they must be disabled.

#### 8.3.3 Undervoltage Lockout

The undervoltage lockout circuit prevents the DC-DC converter from malfunctioning at low input voltages and from excessive discharge of the battery. It disables the output stage of the converter once the falling  $V_{IN}$  trips the undervoltage lockout threshold  $V_{BATUV}$ . The undervoltage lockout threshold  $V_{BATUV}$  for falling  $V_{IN}$  is typically 2 V. The device starts operation once the rising  $V_{IN}$  trips undervoltage lockout threshold  $V_{BATUV}$  again at typical 2.1 V.

#### 8.3.4 Soft Start

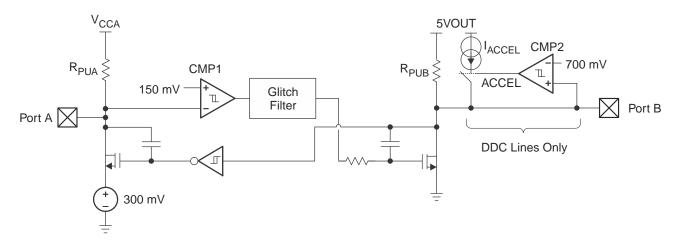
The DC-DC converter has an internal soft-start circuit that controls the ramp-up of the output voltage. The output voltage reaches its nominal value within  $t_{Start}$  of typically 250  $\mu s$  after CT\_CP\_HPD pin has been pulled to high level. The output voltage ramps up from 5% to its nominal value within  $t_{Ramp}$  of 300  $\mu s$ . This limits the inrush current in the converter during start-up, and prevents possible input voltage drops when a battery or high impedance power source is used. During soft start, the switch current limit is reduced to 300 mA until the output voltage reaches  $V_{IN}$ . Once the output voltage trips this threshold, the device operates with its nominal current limit ILIMF.

## 8.3.5 DDC/CEC Level Shifting Function

The TPD12S015A enables DDC translation from  $V_{CCA}$  (system side) voltage levels to 5-V (HDMI cable side) voltage levels without degradation of system performance. The TPD12S015A contains two bidirectional opendrain buffers specifically designed to support up-translation and down-translation between the low voltage,  $V_{CCA}$  side DDC-bus and the 5-V DDC-bus. The port B I/Os are overvoltage tolerant to 5.5 V even when the device is unpowered. After power up and with the LS\_OE and CT\_CP\_HPD pins high, a low level on port A (below approximately  $V_{ILC} = 0.08 \times V_{CCA}$  V) turns the corresponding port B driver (either SDA or SCL) on and drives port B down to  $V_{OLB}$  V. When port A rises above approximately  $0.10 \times V_{CCA}$  V, the port B pulldown driver is turned off, and the internal pullup resistor pulls the pin high. When port B falls first and goes below  $0.3 \times 5$ VOUT, a CMOS hysteresis input buffer detects the falling edge, turns on the port A driver, and pulls port A down to approximately  $V_{OLA} = 0.16 \times V_{CCA}$  V. The port B pulldown is not enabled unless the port A voltage goes below  $V_{ILC}$ . If the port A low voltage goes below  $V_{ILC}$ , the port B pulldown driver is enabled until port A rises above ( $V_{ILC} + \Delta V_{T-HYSTA}$ ); then port B, if not externally driven LOW, continues to rise being pulled up by the internal pullup resistor.



#### **Feature Description (continued)**



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Figure 15. DDC/CEC Level Shifter Block Diagram

#### 8.3.6 DDC/CEC Level Shifting Function When $V_{CCA} = 1.8 \text{ V}$

- The threshold of CMP1 is approximately 150 mV ± the 40 mV of total hysteresis.
- The comparator trips for a falling waveform at approximately 130 mV
- The comparator trips for a rising waveform at approximately 170 mV
- To be recognized as a zero, the level at Port A must first go below 130 mV (VILC in spec) and then stay below 170 mV (VILA in spec)
- To be recognized as a one, the level at A must first go above 170 mV and then stay above 130 mV
- VILC is set to 110 mV to give some margin to the 130 mV
- VILA is set to 140 mV to give some margin to the 170 mV
- VIHA is set to 70% of V<sub>CCA</sub> to be consistent with standard CMOS levels

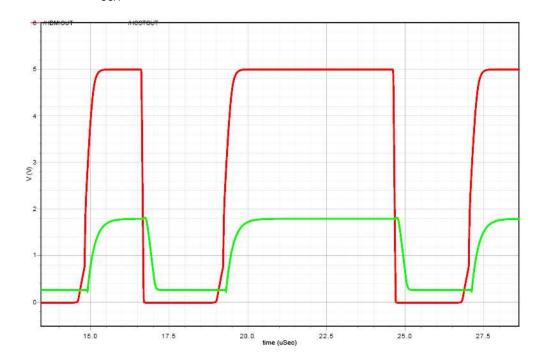


Figure 16. DDC/CEC Level Shifter Operation (B to A Direction)



#### **Feature Description (continued)**

#### 8.3.7 CEC Level Shifting Function

The CEC level shift function operates in the same manner as the DDC lines except that the CEC line does not need the rise time accelerator function.

#### 8.4 Device Functional Modes

#### 8.4.1 **Enable**

The DC-DC converter is enabled when the CT\_CP\_HPD is set to high. At first, the internal reference is activated and the internal analog circuits are settled. Afterwards, the soft start is activated and the output voltage is ramped up. The output voltage reaches its nominal value in typically 250  $\mu$ s after the device has been enabled. The CT\_CP\_HPD input can be used to control power sequencing in a system with various DC-DC converters. The CT\_CP\_HPD pin can be connected to the output of another converter, to drive the EN pin high and getting a sequencing of supply rails. With CT\_CP\_HPD = GND, the DC-DC enters shutdown mode.

#### 8.4.2 Power Save Mode

The TPD12S015A integrates a power save mode to improve efficiency at light load. In power save mode the converter only operates when the output voltage trips below a set threshold voltage. It ramps up the output voltage with several pulses and goes into power save mode once the output voltage exceeds the set threshold voltage. The PFM mode is left and PWM mode entered in case the output current can not longer be supported in PFM mode.

**Table 2. System Block Diagram Function Table** 

LS_OE	CT_CP_HPD	V <sub>CCA</sub>	VBAT	5VOUT	A-SIDE	DDC, B- SIDE	CEC, B- SIDE	CEC LDO	DC-DC &	DDC/CEC	ICC V <sub>CCA</sub>	ICC VBAT	COMMENT
					PULLUPS	PULLUPS	PULLUPS		пги	VLTs	TYP	TYP	
L	L	1.8 V	3.3 V	Off	Off	Off	Off	Off	Off	Off	1 μΑ	1 μΑ	Fully Disabled
L	н	1.8 V	3.3 V	On	On	On	Off	Off	On	Off	1 μΑ	30 μΑ	DC-DC on
н	L	1.8 V	3.3 V	Off	Off	Off	Off	Off	Off	Off	1 μΑ	1 μΑ	Not Valid State
Н	н	1.8 V	3.3 V	On	On	On	On	On	On	On	13 μΑ	255 μΑ	Fully On
х	x	0 V	0 V	Off	High-Z	High-Z	High-Z	Off	Off	Off	0	0	Power Down
х	x	1.8 V	0 V	Off	Low	High-Z	High-Z	Off	Off	Off	0	0	Power Down
х	х	0 V	3.3 V	Off	High-Z	High-Z	High-Z	Off	Off	Off	0	0	Power Down



# 9 Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers must validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

The TPD12S015A is an integrated solution for HDMI 1.3/1.4 interface. The device has a boost converter on the power supply, signal conditioning circuits on CEC, SCL, SDA, HPD lines, and ESD protection on the TMDS lines. To get the best performance, see *Design Requirements*, *Detailed Design Procedure*, and *Application Curves*.

### 9.2 Typical Applications

Some HDMI controller chips may have two GPIOs to control the HDMI interface chip. Figure 17 shows how TPD12S015A is used in this situation. Whereas some HDMI driver chips may have only one GPIO(CT\_CP\_HPD) available. In this situation, LE\_OE pin is tied to HPD\_A instead. Figure 18 shows how TPD12S015A is used in this situation.

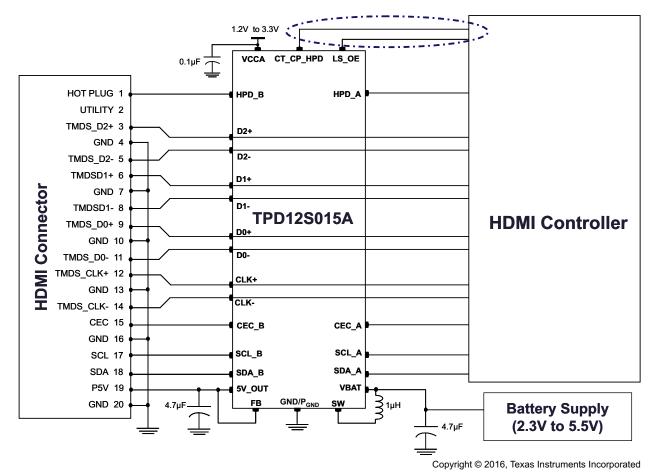


Figure 17. Application Schematics for HDMI Controllers With Two GPIOs for HDMI Interface Control



### **Typical Applications (continued)**

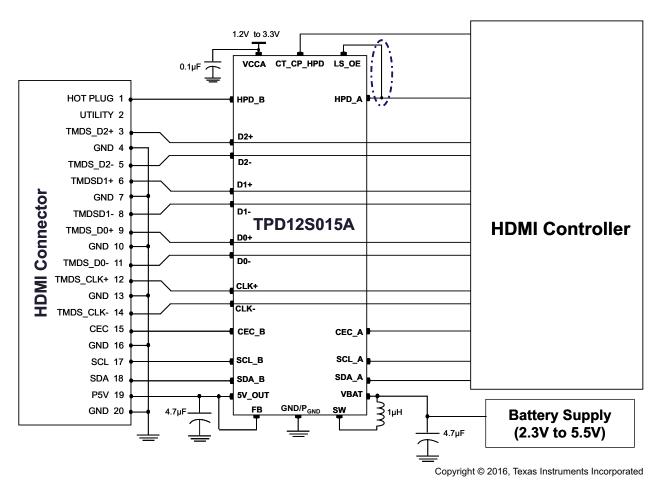


Figure 18. Application Schematics for HDMI Controllers With One GPIO for HDMI Interface Control

#### 9.2.1 Design Requirements

Table 3 lists the known system parameters for an HDMI 1.3/1.4 application.

**Table 3. Design Parameters** 

DESIGN PARAMETER	VALUE
5V_OUT DC current	55 mA
CEC_A, HPD_A, SCL_A, SDA_A voltage level	V <sub>CCA</sub>
HDMI data rate per TMDS signal pair	3.4 Gbps
Required IEC 61000-4-2 ESD Protection	±8-kV Contact

# 9.2.2 Detailed Design Procedure

#### 9.2.2.1 Inductor Selection

To make sure that the TPD12S015A devices can operate, an inductor must be connected between pin  $V_{BAT}$  and pin SW. A boost converter normally requires two main passive components for storing energy during the conversion. A boost inductor and a storage capacitor at the output are required. To select the boost inductor, TI recommends keeping the possible peak inductor current below the current limit threshold of the power switch in the chosen configuration. The highest peak current through the inductor and the switch depends on the output load, the input ( $V_{BAT}$ ), and the output voltage (5VOUT). Use Equation 1 to estimate the maximum average inductor current.



$$I_{L\_MAX} \approx I_{OUT} \times \frac{V_{OUT}}{\eta \times V_{IN}}$$
 (1)

For example, for an output current of 55 mA at 5VOUT, approximately 150 mA of average current flows through the inductor at a minimum input voltage of 2.3 V.

The second parameter for choosing the inductor is the desired current ripple in the inductor. Normally, it is advisable to work with a ripple of less than 20% of the average inductor current. A smaller ripple reduces the magnetic hysteresis losses in the inductor, as well as output voltage ripple and EMI. However, in the same way, regulation time at load changes rises. In addition, a larger inductor increases the total system size and cost. With these parameters, it is possible to calculate the value of the minimum inductance by using Equation 2.

$$L_{MIN} \approx \frac{V_{IN} \times (V_{out} - V_{IN})}{\Delta I_L \times f \times V_{out}}$$

where

- f is the switching frequency
- $\Delta I_1$  is the ripple current in the inductor, that is,  $20\% \times I_1$  (2)

With this calculated value and the calculated currents, it is possible to choose a suitable inductor. In typical applications, TI recommends 1- $\mu$ H inductance. The device has been optimized to operate with inductance values between 1  $\mu$ H and 1.3  $\mu$ H. TI recommends using at least 1- $\mu$ H inductance, even if Equation 2 yields something lower. Take care so that load transients and losses in the circuit can lead to higher currents as estimated in Equation 3. Also, the losses in the inductor caused by magnetic hysteresis losses and copper losses are a major parameter for total circuit efficiency.

With the chosen inductance value, the peak current for the inductor in steady state operation can be calculated. Equation 3 shows how to calculate the peak current I.

$$I_{L(peak)} = \frac{V_{IN} \times D}{2 \times f \times L} + \frac{I_{OUT}}{(1 - D) \times \eta}$$
where
$$D = \frac{V_{OUT} - V_{IN}}{V_{OUT}}$$
(3)

This would be the critical value for the current rating for selecting the inductor. It also must be considered that load transients and error conditions may cause higher inductor currents.

#### 9.2.2.2 Input Capacitor

Because of the nature of the boost converter having a pulsating input current, a low ESR input capacitor is required to prevent large voltage transients that can cause misbehavior of the device or interferences with other circuits in the system. TI recommends at least a 1.2- $\mu$ F input capacitor to improve transient behavior of the regulator and EMI behavior of the total power supply circuit. TI recommends placing a ceramic capacitor as close as possible to the  $V_{IN}$  and GND pins; to improve the input noise filter, it is better to use a 4.7- $\mu$ F capacitor.

### 9.2.2.3 Output Capacitor

For the output capacitor, TI recommends using small ceramic capacitors placed as close as possible to the  $V_{OUT}$  and GND pins of the IC. If, for any reason, the application requires the use of large capacitors, which cannot be placed close to the IC, TI recommends using a smaller ceramic capacitor in parallel to the large one. This small capacitor must be placed as close as possible to the  $V_{OUT}$  and GND pins of the IC. To get an estimate of the recommended minimum output capacitance, use Equation 4.

$$C_{\min} = \frac{I_{OUT} \times (V_{OUT} - V_{IN})}{f \times \Delta V \times V_{OUT}}$$

where

- f is the switching frequency
- ΔV is the maximum allowed ripple

(4)



With a chosen ripple voltage of 10 mV, a minimum effective capacitance of 2.7  $\mu$ F is needed. The total ripple is larger due to the ESR of the output capacitor. This additional component of the ripple can be calculated using Equation 5.

$$\Delta V_{ESR} = I_{OUT} \times R_{ESR} \tag{5}$$

A capacitor with a value in the range of the calculated minimum must be used. This is required to maintain control loop stability. There are no additional requirements regarding minimum ESR. There is no upper limit for the output capacitance value. Larger capacitors cause lower output voltage ripple as well as lower output voltage drop during load transients.

Note that ceramic capacitors have a DC Bias effect, which will have a strong influence on the final effective capacitance needed. Therefore, the right capacitor value must be chosen very carefully. Package size and voltage rating in combination with material are responsible for differences between the rated capacitor value and the effective capacitance. The minimum effective capacitance value must be 1.2  $\mu$ F, but the preferred value is about 4.7  $\mu$ F.

**Table 4. Passive Components: Recommended Minimum Effective Values** 

COMPONENT	MIN	TARGET	MAX	UNIT
C <sub>IN</sub>	1.2	4.7	6.5	μF
C <sub>OUT</sub>	1.2	4.7	10	μF
L <sub>IN</sub>	0.7	1	1.3	μΗ

### 9.2.2.4 CEC, HPD, SCL, SDA Level Shifting Function

To accommodate for the lower logic levels of some processors' control lines, level shifters are needed to translate the interface voltage down to  $V_{CCA}$ , the voltage level used by the processor. The TPD12S015A has bidirectional level shifters on CEC, SCL, SDA lines to support the two-way communication. The pullup resistors are integrated to minimize the number of external components. For HPD line, only one way of hot-plug indication is needed, the level shifter is unidirectional. There is a built-in HPD\_B pulldown resistor to keep the voltage level low on the connector side when nothing is attached. Apart from the signal level translation, the rise-time accelerators on the connector side increases the load driving capability.

#### 9.2.2.5 ESD

To get the best ESD performance on the interface side pins, high performance ESD diodes are needed. The TPD12S015A's ESD diodes on D0+, D0-, D1+, D1-, D2+, D2-, CLK+, CLK-, SCL\_B, SDA\_B, CEC\_B, HPD\_B, 5VOUT, FB ensure passing 8-kV contact IEC, the highest level ESD. Signal integrity on TMDS lines is also a design concern that needs to be evaluated to meet the HDMI 1.3/1.4 data rate. With the typical I/O capacitance of 1.3 pF and a bandwidth above 3 GHz, Figure 12 shows that TPD12S015A's ESD structure has enough margin to meet the data rate requirement of HDMI 1.3/1.4.

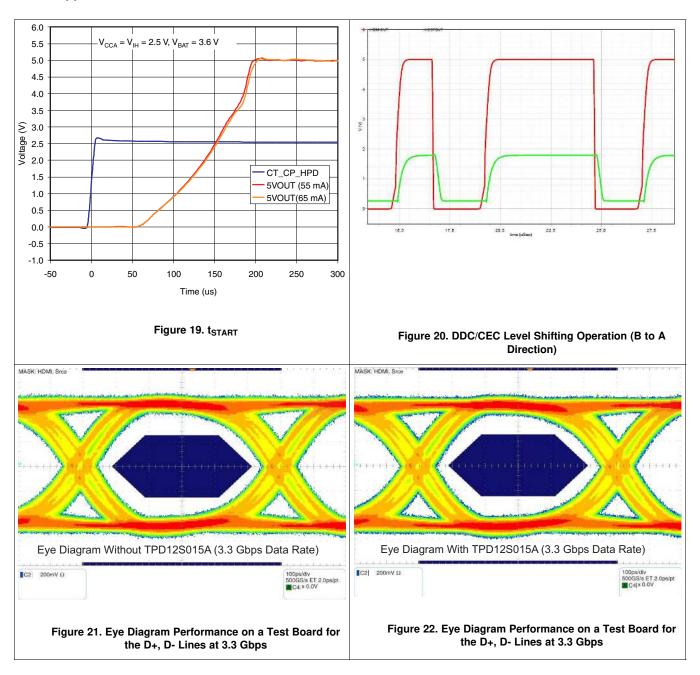
#### 9.2.2.6 Ground Offset Consideration

Ground offset between the TPD12S015A ground and the ground of devices on port A of the TPD12S015A must be avoided. The reason for this cautionary remark is that a CMOS/NMOS open-drain capable of sinking 3 mA of current at 0.4 V has an output resistance of 133  $\Omega$  or less. Such a driver shares enough current with the port A output pulldown of the TPD12S015A to be seen as a LOW as long as the ground offset is zero. If the ground offset is greater than 0 V, then the driver resistance must be less. Because VILC can be as low as 90 mV at cold temperatures and the low end of the current distribution, the maximum ground offset must not exceed 50 mV. Bus repeaters that use an output offset are not interoperable with the port A of the TPD12S015A as their output LOW levels are not recognized by the TPD12S015A as a LOW. If the TPD12S015A is placed in an application where the VIL of port A of the TPD12S015A does not go below its VILC, it pulls port B LOW initially when port A input transitions LOW but the port B returns HIGH, so it does not reproduce the port A input on port B. Such applications must be avoided. Port B is interoperable with all I $^2$ C bus slaves, masters, and repeaters.

Product Folder Links: TPD12S015A



#### 9.2.3 Application Curves





### 10 Power Supply Recommendations

See *Detailed Design Procedure* for detailed power supply recommendations.

### 11 Layout

#### 11.1 Layout Guidelines

For proper operation, follow these layout and design guidelines.

- Place the TPD12S015A as close to the connector as possible. This allows it to remove the energy associated with ESD strike before it reaches the internal circuitry of the system board.
- Place power line capacitors and inductors close to the pins with wide traces to allow enough current to flow through with less trace parasitics.
- Ensure that there is enough metallization for the GND pad. A sufficient current path enables safe discharge of all the energy associated with the ESD strike.
- The critical routing paths for HDMI interface are the high-speed TMDS lines. Make sure to match the lengths
  of the differential pair. Maintain constant trace width after to avoid impedance mismatches in the transmission
  lines. Maximize differential pair-to-pair spacing when possible.

#### 11.2 Layout Example

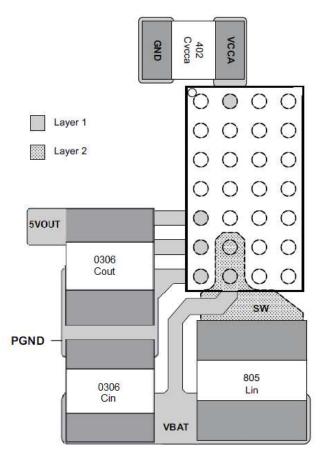


Figure 23. Board Layout (DC-DC Components) (Top View)

List of components:

- L<sub>IN</sub> = MURATA LQM21PN1R0MC0 (1 μH, 800 mA, 0805, Shielded)
- $C_{IN} = C_{OUT} = MURATA LLL31MR70J475MA01 (4.7 \mu F, Low ESL type, 6.3 V, 0306, X7R)$
- $C_{VCCA} = MURATA GRM155R60J475ME87D (0.1 \mu F, 6.3 V, 0402, X5R)$



# 12 Device and Documentation Support

### 12.1 Documentation Support

#### 12.1.1 Related Documentation

For related documentation see the following:

TPD12S015A EVM User's Guide (SLVU485)

#### 12.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 12.3 Community Resource

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

#### 12.4 Trademarks

E2E is a trademark of Texas Instruments.

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#### 12.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 12.6 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

# 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## PACKAGE OPTION ADDENDUM

10-Dec-2020

#### PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
							(6)				
TPD12S015AYFFR	ACTIVE	DSBGA	YFF	28	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-40 to 85	PN015A	Samples

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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# PACKAGE MATERIALS INFORMATION

www.ti.com 22-Sep-2020

## TAPE AND REEL INFORMATION





		Dimension designed to accommodate the component width
		Dimension designed to accommodate the component length
	K0	Dimension designed to accommodate the component thickness
	W	Overall width of the carrier tape
Ι	P1	Pitch between successive cavity centers

## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPD12S015AYFFR	DSBGA	YFF	28	3000	180.0	8.4	1.73	2.93	0.81	4.0	8.0	Q1

# **PACKAGE MATERIALS INFORMATION**

www.ti.com 22-Sep-2020

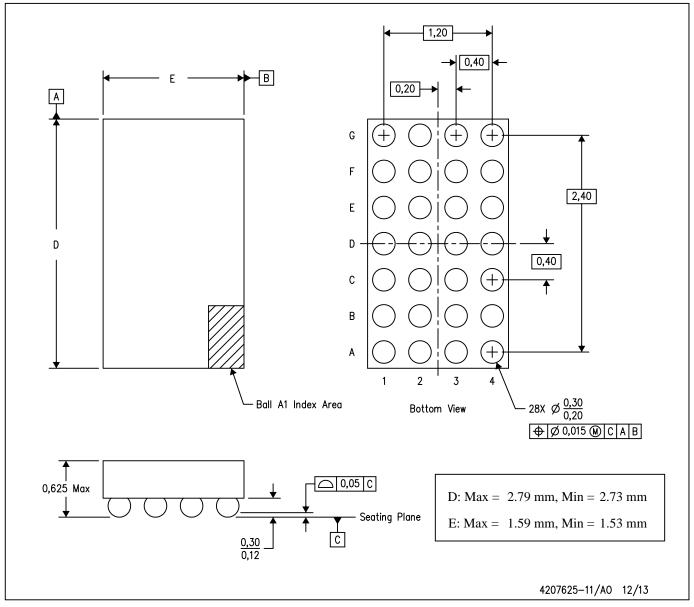


#### \*All dimensions are nominal

Device	Device Package Type		Pins SPQ		Length (mm)	Width (mm)	Height (mm)	
TPD12S015AYFFR	DSBGA	YFF	28	3000	182.0	182.0	20.0	

YFF (R-XBGA-N28)

DIE-SIZE BALL GRID ARRAY



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. NanoFree™ package configuration.

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