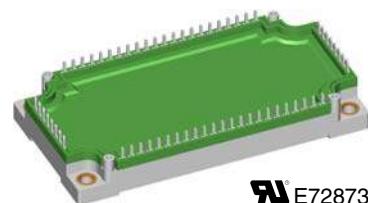
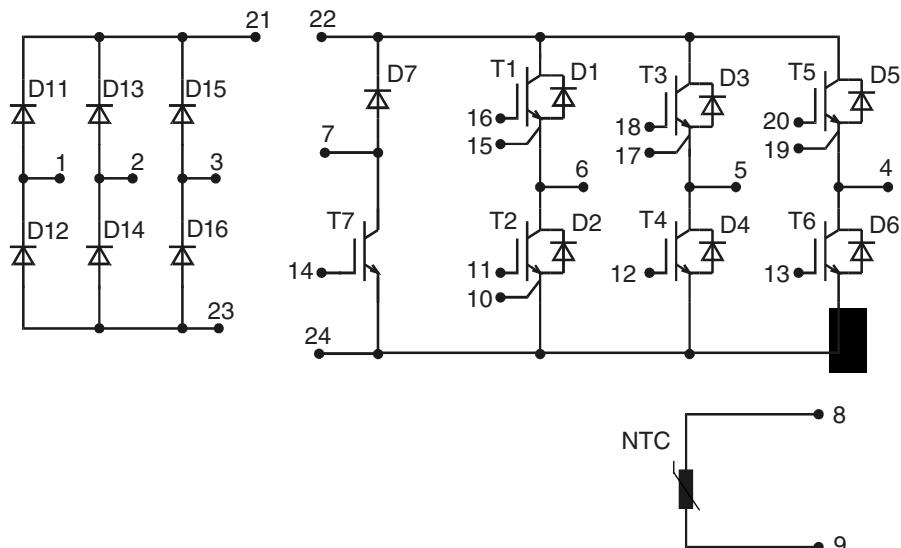


## Converter - Brake - Inverter Module (CBI3)



See outline drawing for pin arrangement

E72873

Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600 \text{ V}$	$V_{CES} = 1200 \text{ V}$	$V_{CES} = 1200 \text{ V}$
$I_{FAV} = 42 \text{ A}$	$I_{C25} = 35 \text{ A}$	$I_{C25} = 50 \text{ A}$
$I_{FSM} = 300 \text{ A}$	$V_{CE(sat)} = 2.3 \text{ V}$	$V_{CE(sat)} = 2.5 \text{ V}$

### Input Rectifier D11 - D16

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$		1600		V
$I_{FAV}$	$T_c = 80^\circ\text{C}$ ; sine 180°	30		A
$I_{DAVM}$	$T_c = 80^\circ\text{C}$ ; rectangular; $d = 1/3$ ; bridge	80		A
$I_{FSM}$	$T_{VJ} = 25^\circ\text{C}$ ; $t = 10 \text{ ms}$ ; sine 50 Hz	300		A
$P_{tot}$	$T_c = 25^\circ\text{C}$	100		W

### Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

### Features

- High level of integration - only one power semiconductor module required for the whole drive
- NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

Symbol	Conditions	Characteristic Values			
		( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)	min.	typ.	max.
$V_F$	$I_F = 35 \text{ A}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.2	1.4	V
			1.2	1.2	V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.02	0.4	mA
			0.02	0.4	mA
$R_{thJC}$	(per diode)			1.3	K/W

**Output Inverter T1 - T6**

<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1200		V
$V_{GES}$	Continuous	$\pm 20$		V
$I_{C25}$	$T_C = 25^\circ\text{C}$	50		A
$I_{C80}$	$T_C = 80^\circ\text{C}$	35		A
<b>RBSOA</b>	$V_{GE} = \pm 15 \text{ V}$ ; $R_G = 47 \Omega$ ; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 70$ $V_{CEK} \leq V_{CES}$		A
<b>t<sub>sc</sub> (SCSOA)</b>	$V_{CE} = V_{CES}$ ; $V_{GE} = \pm 15 \text{ V}$ ; $R_G = 47 \Omega$ ; $T_{VJ} = 125^\circ\text{C}$ non-repetitive	10	$\mu\text{s}$	
<b>P<sub>tot</sub></b>	$T_C = 25^\circ\text{C}$	225		W

<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>		
		( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)	<b>min.</b>	<b>typ.</b>
$V_{CE(sat)}$	$I_C = 35 \text{ A}$ ; $V_{GE} = 15 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		2.5 2.9	3.1 V V
$V_{GE(th)}$	$I_C = 1 \text{ mA}$ ; $V_{GE} = V_{CE}$	4.5		6.5 V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.0	1.1 mA mA
$I_{GES}$	$V_{CE} = 0 \text{ V}$ ; $V_{GE} = \pm 20 \text{ V}$		200	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 600 \text{ V}$ ; $I_C = 35 \text{ A}$ $V_{GE} = \pm 15 \text{ V}$ ; $R_G = 47 \Omega$		100 70 500 70 5.3 3.9	ns ns ns ns mJ mJ
$C_{ies}$		1.65		nF
$Q_{Gon}$		120		nC
$R_{thJC}$			0.55	K/W

**Output Inverter D1 - D6**

<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>		
$I_{F25}$	$T_C = 25^\circ\text{C}$	50		A
$I_{F80}$	$T_C = 80^\circ\text{C}$	35		A

<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>		
		<b>min.</b>	<b>typ.</b>	<b>max.</b>
$V_F$	$I_F = 35 \text{ A}$ ; $V_{GE} = 0 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	2.4 1.8	2.8 V V	
$t_{rr}$	$I_F = 30 \text{ A}$ ; $dI_F/dt = -500 \text{ A}/\mu\text{s}$ ; $T_{VJ} = 125^\circ\text{C}$ $V_R = 600 \text{ V}$ ; $V_{GE} = 0 \text{ V}$	27 150		A ns
$R_{thJC}$	(per diode)		1.19	K/W

## Brake Chopper T7

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_{VJ} = 25^\circ C$ to $150^\circ C$	1200		V
$V_{GES}$	Continuous	$\pm 20$		V
$I_{C25}$	$T_C = 25^\circ C$	35		A
$I_{C80}$	$T_C = 80^\circ C$	25		A
<b>RBSOA</b>	$V_{GE} = \pm 15 V$ ; $R_G = 82 \Omega$ ; $T_{VJ} = 125^\circ C$ Clamped inductive load; $L = 100 \mu H$	$I_{CM} = 35$ $V_{CEK} \leq V_{CES}$		A
<b>t<sub>sc</sub> (SCSOA)</b>	$V_{CE} = V_{CES}$ ; $V_{GE} = \pm 15 V$ ; $R_G = 82 \Omega$ ; $T_{VJ} = 125^\circ C$ non-repetitive	10	$\mu s$	
$P_{tot}$	$T_C = 25^\circ C$	180		W

Symbol	Conditions	Characteristic Values		
		( $T_{VJ} = 25^\circ C$ , unless otherwise specified)	min.	typ.
$V_{CE(sat)}$	$I_C = 20 A$ ; $V_{GE} = 15 V$ ; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		2.3 2.6	3.0 V V
$V_{GE(th)}$	$I_C = 0.6 mA$ ; $V_{GE} = V_{CE}$	4.5		6.5 V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0 V$ ; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		0.8	0.8 mA mA
$I_{GES}$	$V_{CE} = 0 V$ ; $V_{GE} = \pm 20 V$		200	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ C$ $V_{CE} = 600 V$ ; $I_C = 20 A$ $V_{GE} = \pm 15 V$ ; $R_G = 82 \Omega$		100 75 500 70 3.1 2.4	ns ns ns ns mJ mJ
$C_{ies}$			1	nF
$Q_{Gon}$			70	nC
$R_{thJC}$			0.7	K/W

## Brake Chopper D7

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$	$T_{VJ} = 25^\circ C$ to $150^\circ C$	1200		V
$I_{F25}$	$T_C = 25^\circ C$	16		A
$I_{F80}$	$T_C = 80^\circ C$	11		A
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 20 A$ ; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		3.2 2.5	3.6 V V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		0.06 0.07	mA mA
$I_{RM}$ $t_{rr}$	$I_F = 10 A$ ; $di_F/dt = -400 A/\mu s$ ; $T_{VJ} = 125^\circ C$ $V_R = 600 V$		13 110	A ns
$R_{thJC}$			3.2	K/W

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## Temperature Sensor NTC

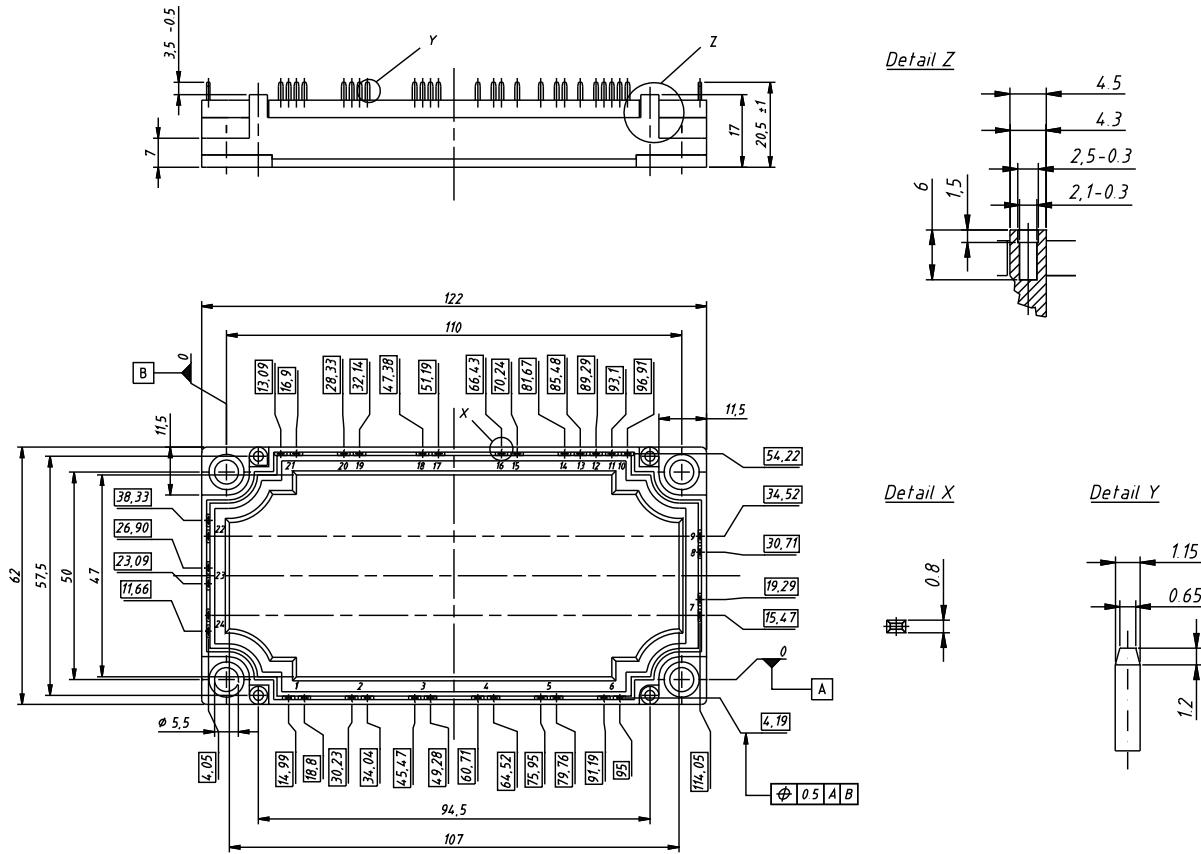
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$ $B_{25/50}$	$T = 25^\circ\text{C}$	4.75	5.0 3375	5.25 k $\Omega$ K

## Module

Symbol	Conditions	Maximum Ratings		
		-	-	-
$T_{VJ}$	operating	-40...+125	°C	
$T_{JM}$		+150	°C	
$T_{stg}$		-40...+125	°C	
$V_{ISOL}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~	
$M_d$	Mounting torque (M5)	3 - 6	Nm	

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$		5	m $\Omega$	
$d_s$	Creepage distance on surface	6	mm	
$d_A$	Strike distance in air	6	mm	
$R_{thCH}$	with heatsink compound	0.01	K/W	
Weight		300	g	

Dimensions in mm (1 mm = 0.0394")



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## Input Rectifier Bridge D11 - D16

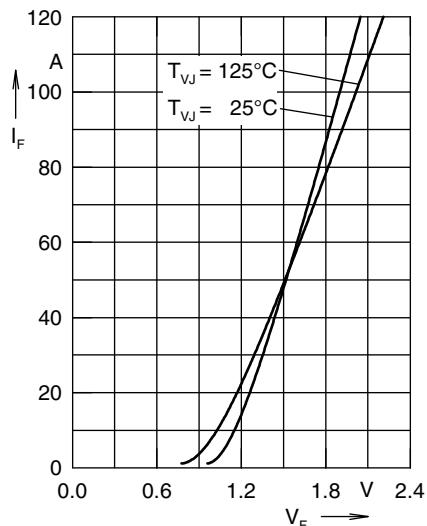


Fig. 1 Forward current versus voltage drop per diode

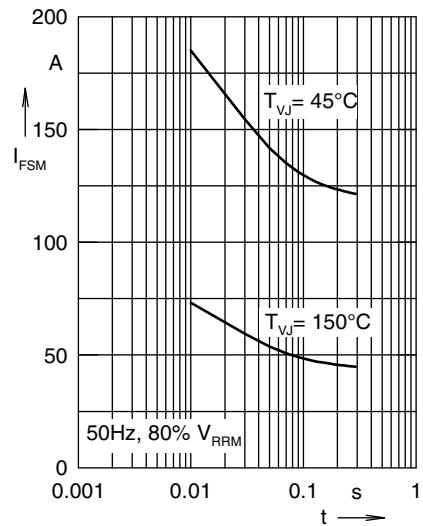


Fig. 2 Surge overload current

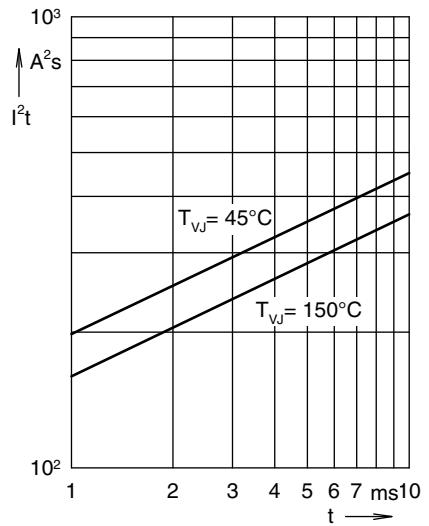
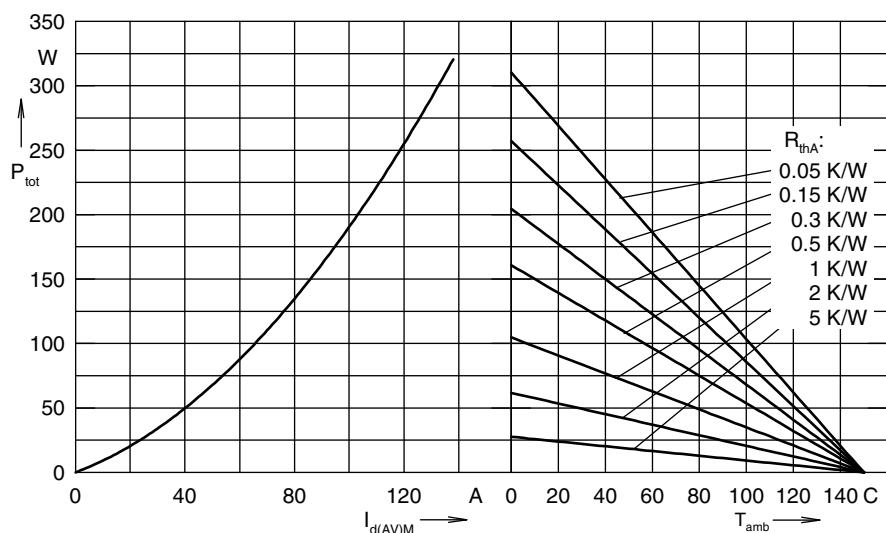
Fig. 3  $I^2t$  versus time per diode

Fig. 4 Power dissipation versus direct output current and ambient temperature, sin 180°

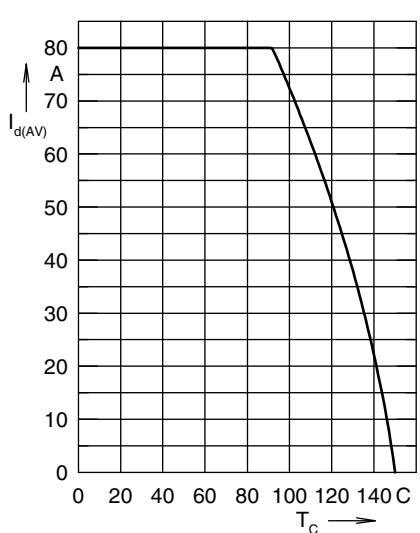


Fig. 5 Max. forward current versus case temperature

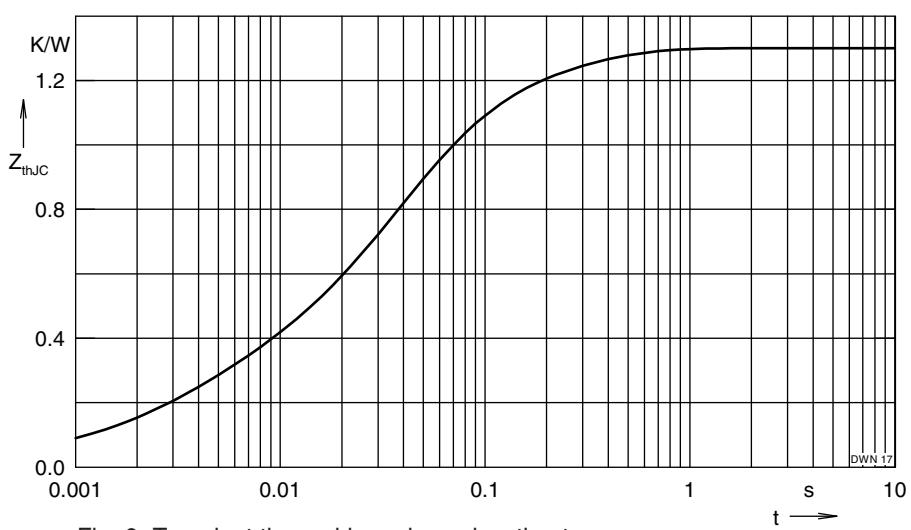


Fig. 6 Transient thermal impedance junction to case

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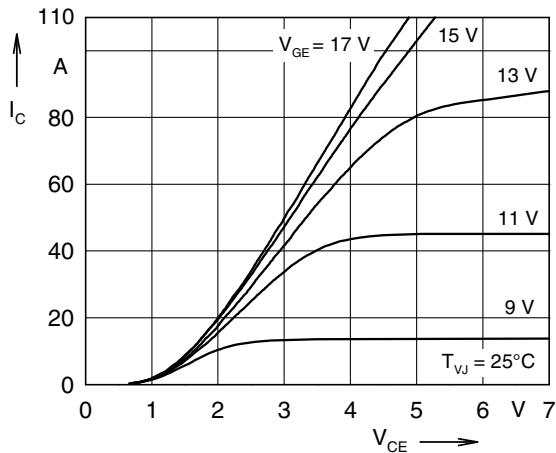
**Output Inverter T1 - T6 / D1 - D6**


Fig. 7 Typ. output characteristics

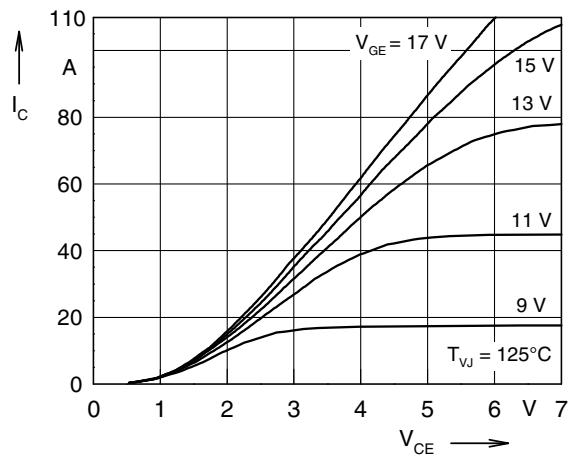


Fig. 8 Typ. output characteristics

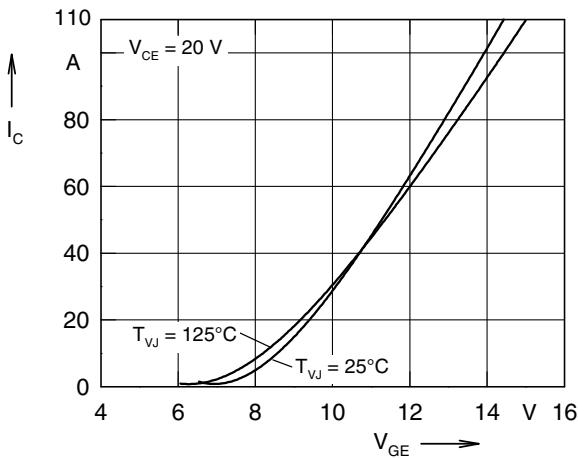


Fig. 9 Typ. transfer characteristics

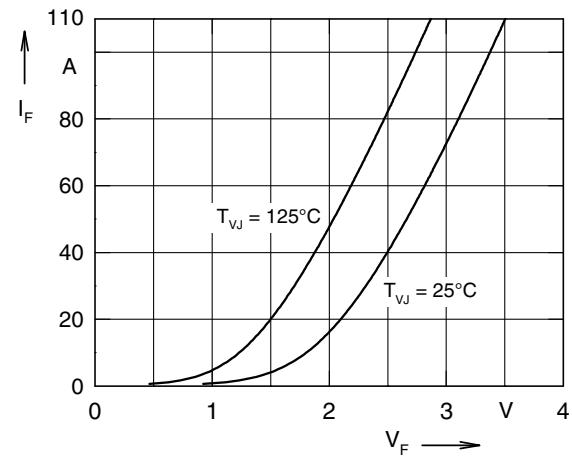
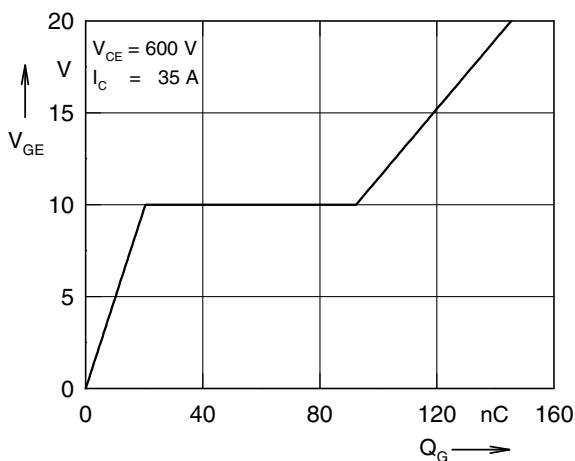
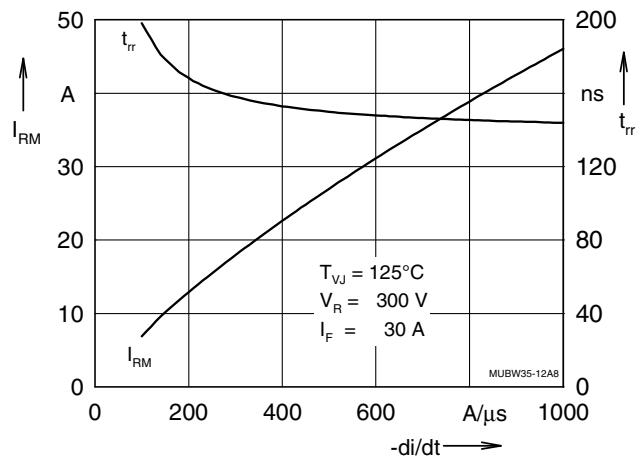

 Fig. 10 Typ. forward characteristics  
of free wheeling diode


Fig. 11 Typ. turn on gate charge


 Fig. 12 Typ. turn off characteristics  
of free wheeling diode

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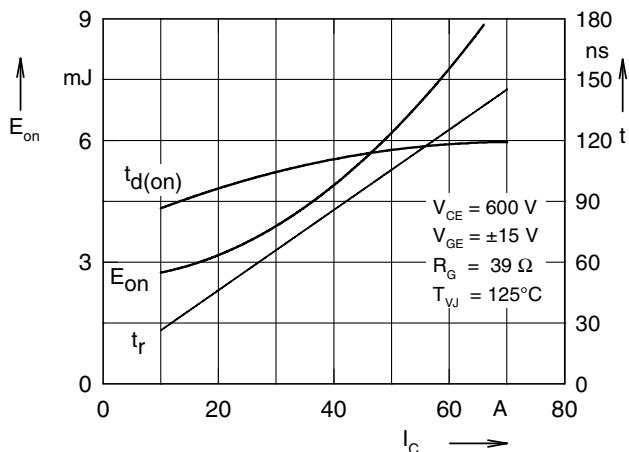
**Output Inverter T1 - T6 / D1 - D6**


Fig. 13 Typ. turn on energy and switching times versus collector current

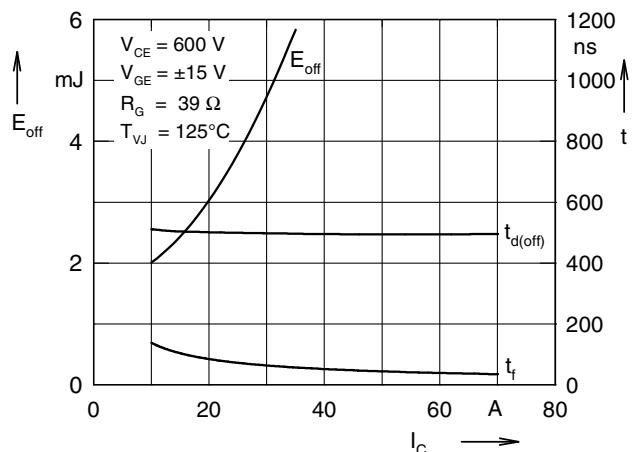


Fig. 14 Typ. turn off energy and switching times versus collector current

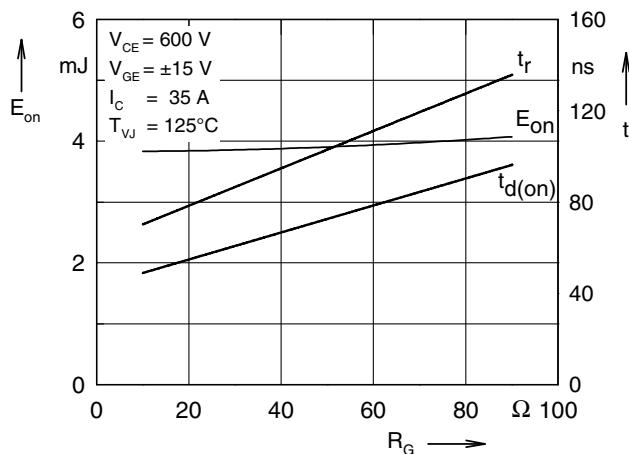


Fig. 15 Typ. turn on energy and switching times versus gate resistor

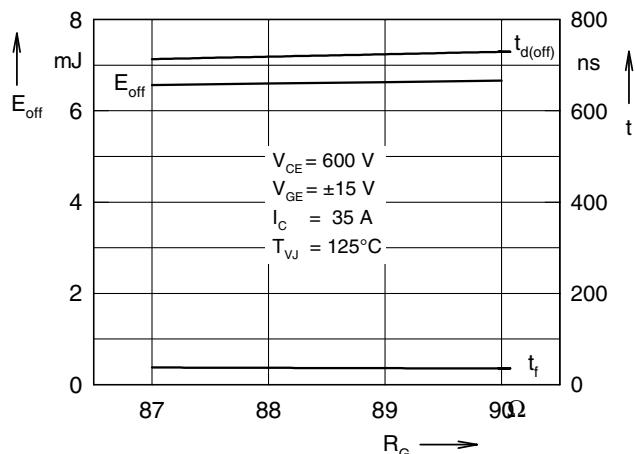


Fig. 16 Typ. turn off energy and switching times versus gate resistor

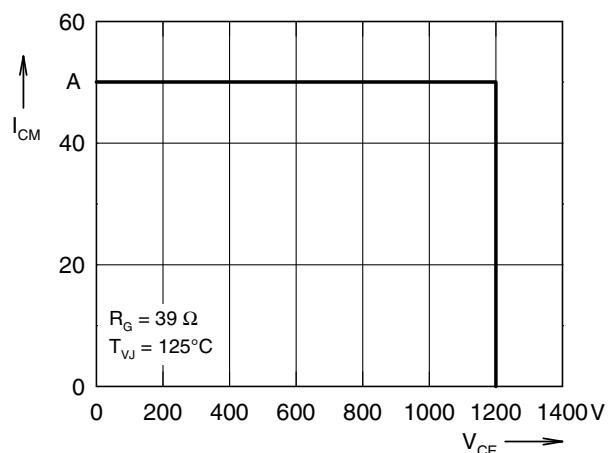


Fig. 17 Reverse biased safe operating area RBSOA

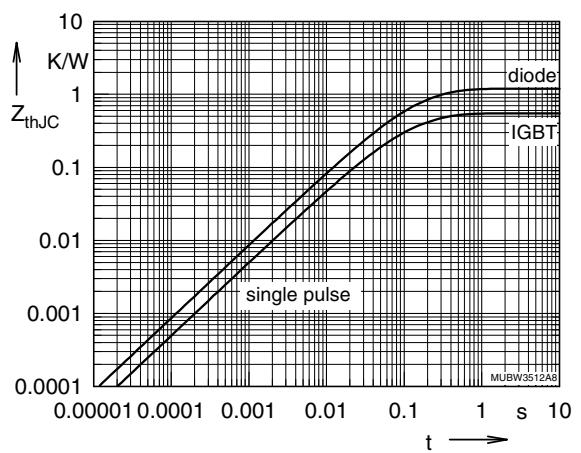
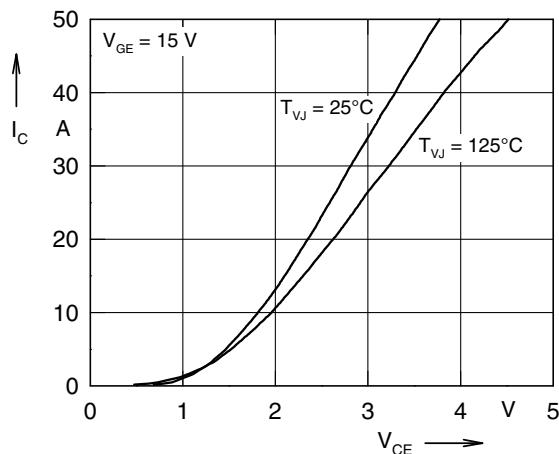
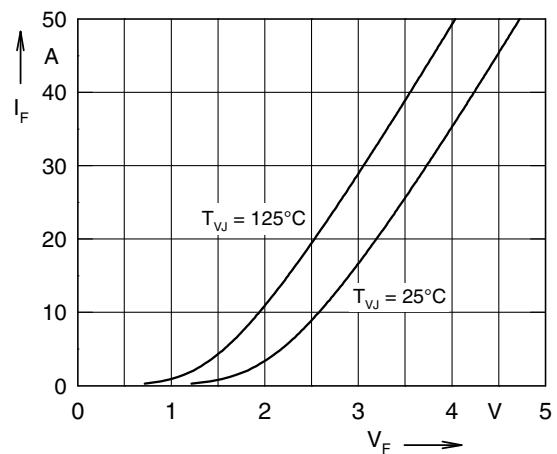
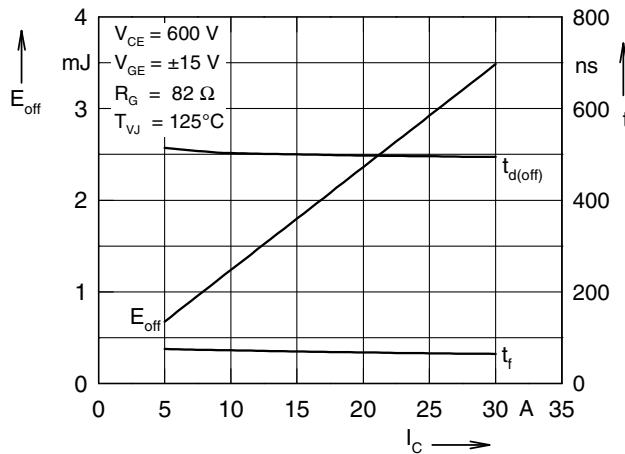
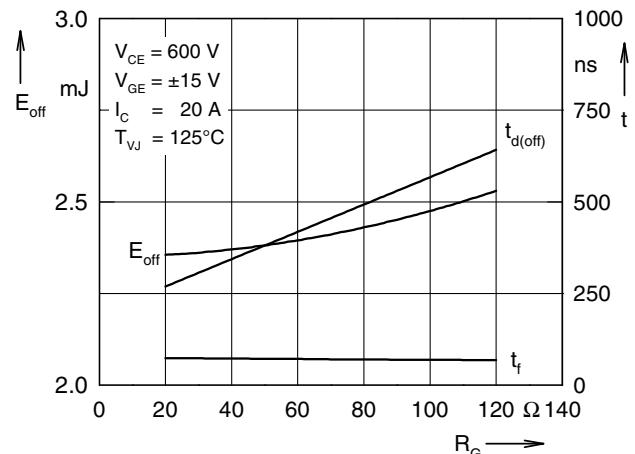
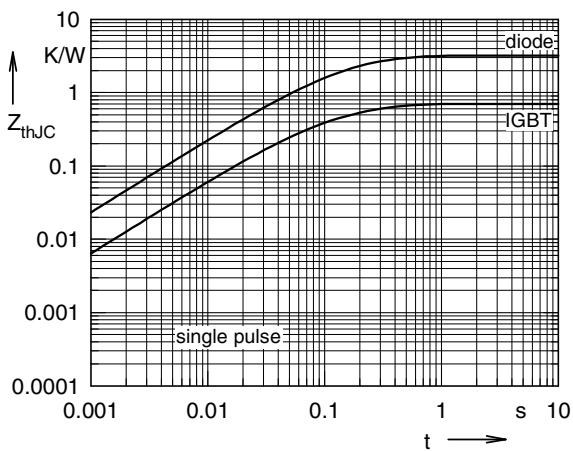
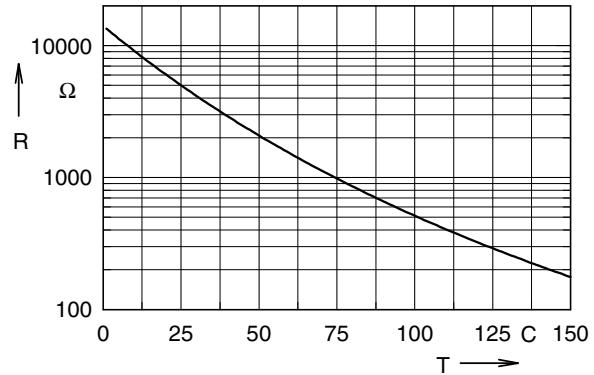


Fig. 18 Typ. transient thermal impedance

**Brake Chopper T7 / D7**

**Fig. 19** Typ. output characteristics

**Fig. 20** Typ. forward characteristics  
of free wheeling diode

**Fig. 21** Typ. turn off energy and switching times versus collector current

**Fig. 22** Typ. turn off energy and switching times versus gate resistor

**Temperature Sensor NTC**

**Fig. 23** Typ. transient thermal impedance

**Fig. 24** Typ. thermistor resistance  
versus temperature