Microprocessor Monitor

The NCP1232 is a fully-integrated processor supervisor. It provides three important functions to safeguard processor functionality: precision power on/off reset control, watchdog timer and external reset override.

On power-up, the NCP1232 holds the processor in the reset state for a minimum of 250 msec after V_{CC} is within tolerance to ensure a stable system start-up.

Microprocessor functionality is monitored by the on-board watchdog circuit. The microprocessor must provide a periodic low-going signal on the \overline{ST} input. Should the processor fail to supply this signal within the selected time-out period (150 msec, 600 msec or 1200 msec), an out-of-control processor is indicated and the NCP1232 issues a processor reset as a result.

The outputs of the NCP1232 are immediately driven active when the PB input is brought low by an external push-button switch or other electronic signal. When connected to a push-button switch, the NCP1232 provides contact debounce.

The NCP1232 is packaged in a space-saving 8-pin plastic SOIC package and requires no external components.

Features

- Precision Voltage Monitor (Adjustable +4.5 V or +4.75 V)
- Reset Pulse Width (250 msec Min)
- No External Components
- Adjustable Watchdog Timer (150 msec, 600 msec or 1.2 sec)
- Debounced Manual Reset Input for External Override

Applications

- Computers
- Controllers
- Intelligent Instruments
- Automotive Systems
- Critical μP Power Monitoring



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MARKING DIAGRAM



SO-8 D SUFFIX CASE 751



YY, Y WW X YearWork Week

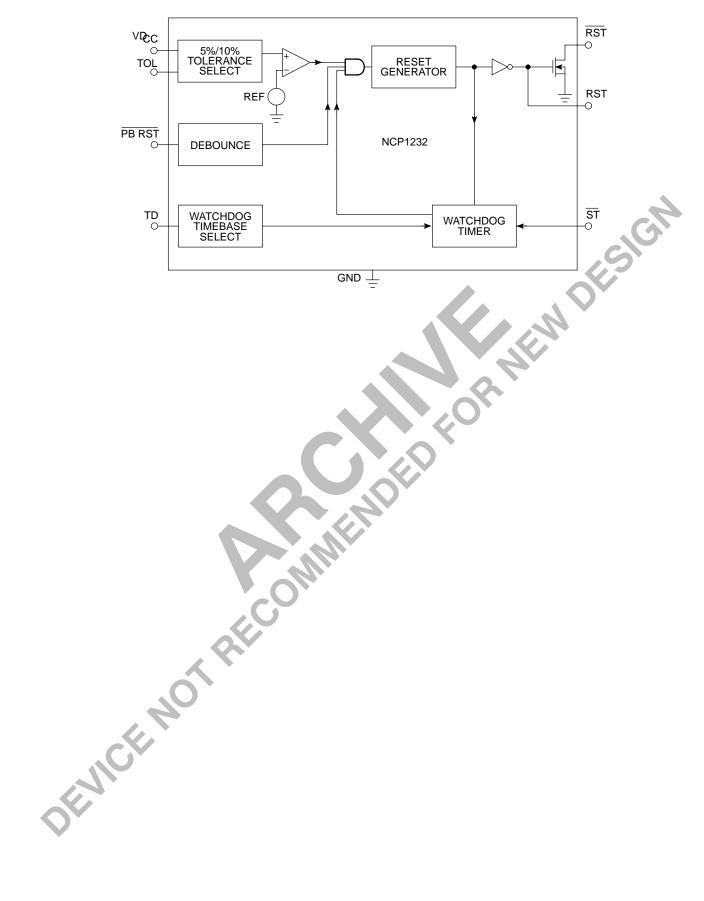
= Assembly ID Code = Subcontractor ID Code

PIN CONNECTIONS

ORDERING INFORMATION

Device	Package	Shipping		
NCP1232DR2	SO-8	2500 Tape & Reel		

FUNCTIONAL BLOCK DIAGRAM



PIN DESCRIPTION

1
2
3
4
5
6
7
8
OFNIC

ABSOLUTE MAXIMUM RATINGS* Voltage on any pin (with respect to GND) -0.3 V to +5.8 V

Rating	Value	Unit
Operating Temperature Range	-40 to +85	°C
Storage Temperature Range, T _{stg}	-65 to +150	°C
Lead Temperature (Soldering, 10 sec)	+300	°C

^{*}Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS ($T_A = T_{MIN}$ to T_{MAX} ; $V_{CC} = +4.5$ V to 5.5 V, unless otherwise specified.)

Characteristic	Symbol	Test Conditions	Min	Тур	Max	Unit
Supply Voltage	V _{CC}	-	4.5	5.0	5.5	V
ST and PB RST Input High Level	V _{IH}	Note 1	2.0	-	V _{CC} +0.3	V
ST and PB RST Input Low Level	V _{IL}	-	-0.3	-	+0.8	V
Input Leakage ST, TOL	IL	-	-1.0	-	+1.0	μΑ
Output Current RST	I _{OH}	V _{OH} = 2.4 V	-1.0	-12	1,50	mA
Current RST, RST	I _{OL}	V _{OL} = 0.4 V	2.0	10		mA
Operating Current	I _{CC}	Note 2	-	50	200	μΑ
V _{CC} 5% Trip Point (Note 3)	V _{CCTP}	TOL = GND	4.50	4.62	4.74	V
V _{CC} 10% Trip Point (Note 3)	V _{CCTP}	TOL = V _{CC}	4.25	4.37	4.49	V

CAPACITANCE (Note 4) $(T_A = +25^{\circ}C)$

Characteristic	Symbol	Test Conditions Min	Тур	Max	Unit
Input Capacitance ST, TOL	C _{IN}	4 / A Y / () ·	-	5.0	pF
Output Capacitance RST, RST	C _{OUT}	-	-	7.0	pF

AC ELECTRICAL CHARACTERISTICS ($T_A = T_{MIN}$ to T_{MAX} ; $V_{CC} = +5.0$ V to $\pm 10\%$, unless otherwise specified.)

Characteristic	Symbol	Test Conditions	Min	Тур	Max	Unit
PB RST (Note 5)	t _{PB}	Figure 3	20	-	-	msec
PB RST Delay	t _{PBD}	Figure 3	1.0	4.0	20	msec
Reset Active Time	t _{RST}	-	250	610	1000	msec
ST Pulse Width	t _{ST}	Figure 4	20	-	-	nsec
ST Time-out Period	tπρ	Figure 4 TD Pin = 0 V TD Pin = Open TD Pin = V _{CC}	62.5 250 500	150 600 1200	250 1000 2000	msec
V _{CC} Fall Time (Note 4)	t _F	Figure 5	10	-	-	μsec
V _{CC} Rise Time (Note 4)	t _R	Figure 6	0	-	-	μsec
V _{CC} Detect to RST High and RST Low	t _{RPD}	Figure 7, V _{CC} Falling	-	-	100	nsec
V _{CC} Detect to RST High and RST Open (Note 6)	t _{RPU}	Figure 8, V _{CC} Rising	250	610	1000	msec

- 1. \overline{PB} RST is internally pulled up to V_{CC} with an internal impedance of typically 40 k Ω .
- 2. Measured with outputs open.
- 3. All voltages references to GND.
- 4. Guaranteed by design.
- 5. PB RST must be held low for a minimum of 20 msec to guarantee a reset.
- 6. $t_R = 5 \mu sec.$

Power Monitor

The NCP1232 detects out-of-tolerance power supply conditions and warns a processor-based system of an impending power failure. When V_{CC} is detected as below the preset level defined by TOL, the V_{CC} comparator outputs the signals RST and \overline{RST} . If TOL is connected to ground, the RST and \overline{RST} signals become active as V_{CC} falls below 4.75 volts. If TOL is connected to V_{CC} , the RST and \overline{RST} become active as V_{CC} falls below 4.5 volts. Because the processing is stopped at the last possible moment of valid V_{CC} , the RST and \overline{RST} are excellent control signals for a μP . The reset outputs will remain in their active states until V_{CC} has been continuously in-tolerance for a minimum of 250 msec allowing the power supply and μP to stabilize before \overline{RST} is released.

Push-button Reset Input

The debounced manual reset input ($\overline{PB~RST}$) manually forces the reset outputs into their active states. Once $\overline{PB~RST}$ has been low for a time, t_{PBD} , the push-button delay time, the reset outputs go active. The reset outputs remain in their active states for a minimum of 250 msec after $\overline{PB~RST}$ rises above V_{IH} (Figure 3).

A mechanical push-button or active logic signal can drive the $\overline{PB~RST}$ input. The debounced input ignores input pulses less than 1 msec and is guaranteed to recognize pulses of 20 msec or greater. No external pull-up resistor is required because the $\overline{PB~RST}$ input has an internal pull-up to V_{CC} of approximately $100~\mu A$.

Watchdog Timer

When the \overline{ST} input is not stimulated for a preset time period, the watchdog timer function forces RST and \overline{RST} signals to the active state. The preset time period is determined by the \overline{TD} inputs to be 150 msec with TD connected to ground, 600 msec with TD open, or 1200 msec with TD connected to V_{CC} , typical. The watchdog timer starts timing out from the set time period as soon as RST and \overline{RST} are inactive. If a high-to-low transition occurs on the ST input pin prior to time-out, the watchdog timer is reset and begins to time-out again. If the watchdog timer is allowed to time-out, then the RST and \overline{RST} signals are driven to the active state for 250 msec minimum (Figure 2).

The software routine that strobes \overline{ST} is critical. The code must be in a section of software that is executed regularly so the time between toggles is less than the watchdog time-out period. One common technique controls the μP I/O line from two sections of the program. The software might set the I/O

line high while operating in the foreground mode and set it low while in the background or interrupt mode. If both modes do not execute correctly, the watchdog timer issues reset pulses.

Supply Monitor Noise Sensitivity

The NCP1232 is optimized for fast response to negative-going changes in $V_{DD}.$ Systems with an inordinate amount of electrical noise on V_{DD} (such as systems using relays), may require a 0.01 μF or 0.1 μF bypass capacitor to reduce detection sensitivity. This capacitor should be installed as close to the NCP1232 as possible to keep the capacitor lead length short.

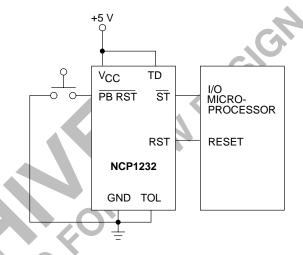


Figure 1. Push-button Reset

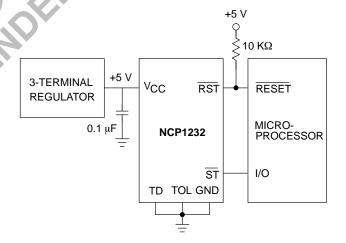


Figure 2. Watchdog Timer

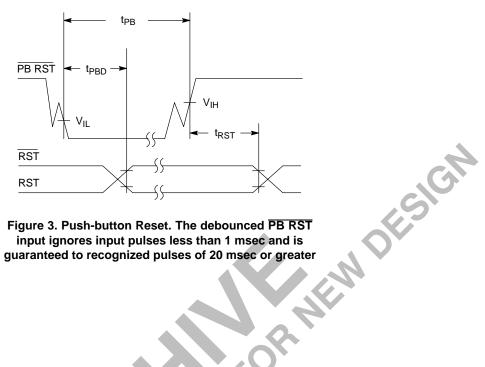


Figure 3. Push-button Reset. The debounced PB RST input ignores input pulses less than 1 msec and is guaranteed to recognized pulses of 20 msec or greater

PUSH-BUTT ON RESET

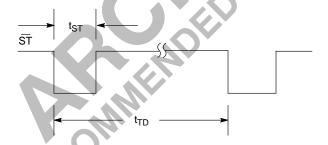
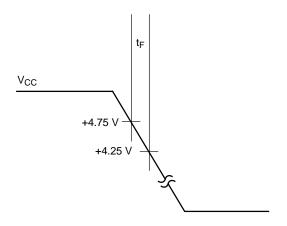


Figure 4. Strobe Input

	NOTE: t _{TD} is the maxin transistions (ST keep the watchd for a time of t _{RST} as tabulated bel	is activated by f log timer from for t _{TD} is a function	alling edges onl	y) which will utputs active
	CONDITION	MIN	^t TD TYP	MAX
OEVICE	TD PIN = 0 V 62.5 msec TD PIN = OPEN TD PIN = V _{CC} 500 msec	150 msec 250 msec 1200 msec	250 msec 600 msec 2000 msec	1000 msec



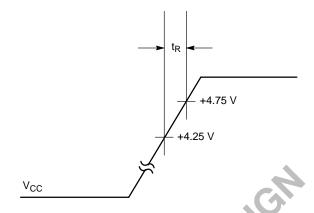
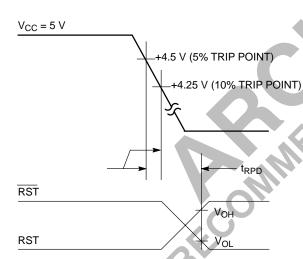


Figure 5. Power-Down Slew Rate

Figure 6. Power-Down Slew Rate



 V_{CC} , SLEW RATE = 1.66mV/ μ sec (0.5 V/300 μ sec)

Figure 7. V_{CC} Detect Reset Output Delay (Power-Down)

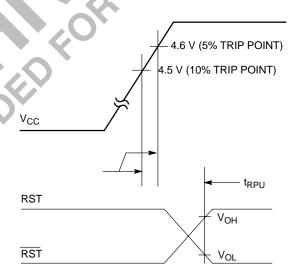
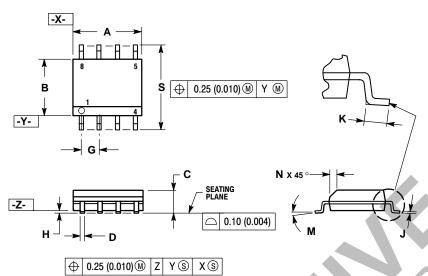


Figure 8. V_{CC} Detect Reset Output Delay (Power-Up)

PACKAGE DIMENSIONS

SO-8 D SUFFIX CASE 751-07 **ISSUE AA**



NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: MILLIMETER.
 DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION
- MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.

 5. DIMENSION D DOES NOT INCLUDE DAMBAR
- PROTRUSION. ALLOWABLE DAMBAR
 PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.
- 751-01 THRU 751-06 ARE OBSOLETE. NEW STANDARD IS 751-07.

MILLIN	IETERS	INCHES		
MIN	MAX	MIN	MAX	
4.80	5.00	0.189	0.197	
3.80	4.00	0.150	0.157	
1.35	1.75	0.053	0.069	
0.33	0.51	0.013	0.020	
1.27	1.27 BSC		0 BSC	
0.10	0.25	0.004	0.010	
0.19	0.25	0.007	0.010	
0.40	1.27	0.016	0.050	
0 °	8 °	0 °	8 °	
0.25	0.50	0.010	0.020	
5.80	6.20	0.228	0.244	
	MIN 4.80 3.80 1.35 0.33 1.27 0.10 0.19 0.40 0 ° 0.25	4.80 5.00 3.80 4.00 1.35 1.75 0.33 0.51 1.27 BSC 0.10 0.25 0.19 0.25 0.40 1.27 0 ° 8 ° 0.25 0.50	MIN MAX MIN 4.80 5.00 0.189 3.80 4.00 0.150 1.35 1.75 0.053 0.33 0.51 0.013 1.27 BSC 0.05 0.004 0.19 0.25 0.007 0.40 1.27 0.016 0 ° 8 ° 0 ° 0.25 0.50 0.010	

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