# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to1.5Vdc output; 120A Output Current

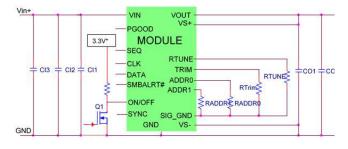




### **RoHS Compliant**

### **Applications**

- Networking equipment
- Telecommunications equipment
- Servers and storage applications
- Distributed power architectures
- Intermediate bus voltage applications
- Industrial equipment



#### **Features**

- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863
- Compliant to IPC-9592 (September 2008), Category 2
- Compatible in a Pb-free or SnPb reflow environment (Z versions)
- Compliant to REACH Directive (EC) No 1907/2006
- Wide Input voltage range (7Vdc-14 Vdc)
- Output voltage programmable from 0.6Vdc to 1.5Vdc via external resistor or PMBus™# commands
- Digital interface through the PMBus protocol
- Digital sequencing
- Fast digital loop control
- Power Good signal
- Fixed switching frequency with capability of external synchronization
- Output overcurrent protection (non-latching)
- Output overvoltage protection
- Over temperature protection
- Remote On/Off
- Ability to sink and source current
- Cost efficient open frame design
- Small size: 53.8 x 31.7 x 13.3 mm [ 2.118" x 1.248" x 0.524"]
- Wide operating temperature range [-40°C to 85°C]
- ANSI/UL\* 62368-1 and CAN/CSA† C22.2 No. 62368-1 Recognized, DIN VDE‡ 0868-1/A11:2017 (EN62368-1:2014/A11:2017)
- ISO\*\* 9001 and ISO 14001 certified manufacturing facilities

### **Description**

The 120A Digital TeraDLynx™ power modules are non-isolated dc-dc converters that can deliver up to 120A of output current. These modules operate over a 7 to 14Vdc input range and provide a precisely regulated output voltage from 0.6 to 1.5Vdc. The output voltage is programmable via an external resistor and/or PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, Power Good signal and overcurrent, overvoltage and overtemperature protection. The PMBus interface supports a range of commands to both control and monitor the module. The module also includes a real time compensation loop that allows optimizing the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.

- \* UL is a registered trademark of Underwriters Laboratories, Inc.
- \* CSA is a registered trademark of Canadian Standards Association.
- VDF is a trademark of Verband Deutscher Elektrotechniker e.V.
- \*\* ISO is a registered trademark of the International Organization of Standards
- # The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)



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### **Absolute Maximum Ratings**

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are only absolute stress ratings, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the technical requirements. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage - Continuous	All	V <sub>IN</sub>	-0.3	15	V
SEQ, ADDR0, ADDR1, RTUNE, RTRIM, SYNC, VS+, ON/OFF	All		-0.3	3.6	V
CLK, DATA, SMBALERT#	All		-0.3	3.6	V
Operating Ambient Temperature	All	T <sub>A</sub>	-40	85	°C
(see Thermal Considerations section)					
Storage Temperature	All	$T_{stg}$	-55	125	°C

### **Electrical Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	Vin	7	_	14	Vdc
Maximum Input Current	All	I <sub>IN,max</sub>			29	Adc
(V <sub>IN</sub> =7V to 14V, I <sub>O</sub> =I <sub>O, max</sub> )						
Input No Load Current	V <sub>O,set</sub> = 0.6 Vdc	I <sub>IN,No load</sub>		160		mA
$(V_{IN} = 12Vdc, I_0 = 0, module enabled)$	V <sub>O,set</sub> = 1.5Vdc	I <sub>IN1No load</sub>		200		mA
Input Stand-by Current (V <sub>IN</sub> = 12Vdc, module disabled)	All	I <sub>IN,stand-by</sub>		62		mA
Inrush Transient	All	l²t		1		A <sup>2</sup> s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, $1\mu$ H source impedance; $V_{IN}$ =0 to 14V, $I_{O}$ = $I_{Omax}$ ; See Test Configurations)	All			5		mAp-p
Input Ripple Rejection (120Hz)	All			-54		dB
Output Voltage Set-point Tolerance over output voltage range from 0.5 to 1.5V						
0 to 85ºC	All	$V_{O,  set}$	-0.7		+0.7	% V <sub>O, set</sub>
-40 to 85ºC	All	$V_{O,set}$	-1.0		+1.0	% V <sub>O, set</sub>
Voltage Regulation <sup>1</sup>						
Line Regulation	(V <sub>IN</sub> =V <sub>IN, min</sub> to V <sub>IN, max</sub> )			2		mV
	(12V <sub>IN</sub> ±20%)			1		mV
Load (I <sub>O</sub> =I <sub>O, min</sub> to I <sub>O, max</sub> ) Regulation	All			4		mV

 $<sup>^{1}</sup>$ Worst case Line and load regulation data, all temperatures, from design verification testing as per IPC9592.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

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### **Electrical Specifications** (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Adjustment Range (selected by an external resistor)	All	$V_{OUT}$	0.6		1.5	Vdc
PMBus Adjustable Output Voltage Range	All	V <sub>OUT</sub>	0.6		1.5	Vdc
PMBus Output Voltage Adjustment Step Size	All			61 <sup>2</sup>		μV
Remote Sense Range	All				0.3	Vdc
Output Ripple and Noise on nominal output $ (V_{IN} = V_{IN,nom} \text{ and } I_O = I_{O,min} \text{ to } I_{O,max} \text{ Co} = 1500 \ \mu\text{F} $						
Peak-to-Peak (Full bandwidth)					30	$mV_{\text{pk-pk}}$
RMS (Full bandwidth)	All				12	$mV_{\text{rms}}$
External Capacitance <sup>3</sup>						
Minimum output capacitance	All	$C_{O,min}$	1500		_	μF
Maximum output capacitance	All	Co, max	_	_	40000	μF
Output Current (in either sink or source mode)	All	I <sub>o</sub>	0.005 *		120	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	Io, lim		110		% I <sub>o,max</sub>
Output Short-Circuit Current	All	l <sub>O1, s/c</sub> , l <sub>O1, s/c</sub>		40		Arms
(Vo≤250mV) (Hiccup Mode)						
Efficiency	$V_{O,set} = 0.6Vdc$	η		88.2		%
	$V_{O, set} = 0.8 Vdc$	η		90.9		%
V <sub>IN</sub> = 12Vdc, T <sub>A</sub> =25°C	$V_{O,set} = 1.0Vdc$	η		92.1		%
$I_O=I_{O, max}$ , $V_O=V_{O, set}$	V <sub>O,set</sub> = 1.2Vdc	η		93.0		%
	V <sub>O, set</sub> = 1.5Vdc	η		94.0		%
Switching Frequency	All	$f_{sw}$	-	400	-	kHz
Frequency Synchronization	All					
Synchronization Frequency Range	All		-15		+15	%
High-Level Input Voltage	All	V <sub>IH,SYNC</sub>	2.5			V
Low-Level Input Voltage	All	V <sub>IL,SYNC</sub>			1.1	V
Minimum Pulse Width, SYNC	All	tsync	256			ns

<sup>\*</sup> Minimum load on module should be 5mA

<sup>&</sup>lt;sup>2</sup> this must be supported by an appropriate PMBus tool capable of writing at that resolution

<sup>&</sup>lt;sup>3</sup> External capacitors may require using the new Tunable Loop<sup>™</sup> feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop<sup>™</sup> section for details.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

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### **General Specifications**

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (I <sub>O</sub> =0.8I <sub>O, max</sub> , T <sub>A</sub> =40°C) Telecordia Issue 2 Method 1 Case 3	All		11,556,226		Hours
Weight - Module with SMT Pins			57 (2.01)		g (oz.)
Module with Through Hole Pins			59 (2.08)		g (oz.)

### **Feature Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface						
(V <sub>IN</sub> =V <sub>IN, min</sub> to V <sub>IN, max</sub> ; open collector or equivalent,						
Signal referenced to GND)						
Device Code with no suffix - Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
,						
Logic High (Module OFF)						
Input High Current	All	Іін	_	_	1	mA
Input High Voltage	All	ViH	2	_	3.6*	Vdc
Logic Low (Module ON)						
Input low Current	All	lıL	_	_	10	μΑ
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Device Code with suffix "4" - Positive Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module ON)						
					40	
Input High Current	All	Іін	_	_	10	μΑ
Input High Voltage	All	ViH	2	_	3.6*	Vdc
Logic Low (Module OFF)						
Input low Current	All	lıL	_	_	10	μΑ
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Turn-On Delay and Rise Times						
(V <sub>IN</sub> =V <sub>IN, nom</sub> , I <sub>O</sub> =I <sub>O, max</sub> , V <sub>O</sub> to within ±1% of steady state)						
Case 1: On/Off input is enabled and then input power is						
applied (delay from instant at which $V_{IN} = V_{IN, min}$ until $V_0 =$	All	Tdelay	_	30	_	ms
10% of Vo, set)						
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at	All	Tdelay		15	_	ms
which Von/Off is enabled until Vo = 10% of Vo, set)	All	Tuelay		13		1113
Output voltage Rise time (time for Vo to rise from	All	Trise	_	10	_	msec
10% of Vo, set to 90% of Vo, set)						
Output voltage overshoot ( $T_A = 25^{\circ}C$ $V_{IN} = V_{IN, min}$ to $V_{IN, max}$ , $I_O = I_{O, min}$ to $I_{O, max}$ )		Output			3.0	% V <sub>O, set</sub>
With or without maximum external capacitance		2 2 3 4 5 5 5				, 0, sec
Over Temperature Protection	All	$T_{ref}$		135		°C
(See Thermal Considerations section)	All	I ret		133		, , ,
PMBus Over Temperature Warning Threshold	All	Twarn		125		°C

<sup>\*</sup>Use external resistive voltage divider to step down higher logic voltages

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## **Feature Specifications (cont.)**

Parameter	Device	Symbol	Min	Тур	Max	Units
Tracking Accuracy (Power-Up: 0.5V/ms)	All	Vseq –Vo			100	mV
(Power-Down: 0.5V/ms)	All	Vseq –Vo			100	mV
(V <sub>IN, min</sub> to V <sub>IN, max</sub> ; I <sub>O, min</sub> to I <sub>O, max</sub> VSEQ < V <sub>O</sub> )						
Input Undervoltage Lockout						
Turn-on Threshold	All				7	Vdc
Turn-off Threshold			6.75			Vdc
Hysteresis	All			0.25		Vdc
PMBus Adjustable Input Under Voltage Lockout Thresholds	All		7		14	Vdc
Resolution of Adjustable Input Under Voltage Threshold	All				5.8	mV
PGOOD (Power Good) for output voltages set with Rtrim**						
Signal Interface Open Drain, V <sub>supply</sub> ≤ 5VDC						
Overvoltage threshold for PGOOD ON	All			112.5		%V <sub>O, set</sub>
Undervoltage threshold for PGOOD OFF	All			87.5		%V <sub>O, set</sub>
Pulldown resistance of PGOOD pin	All				2	Ω
Sink current capability into PGOOD pin	All				50	mA

<sup>\*\*</sup>If output voltage is set using VOUT COMMAND(21h) then PGOOD ON and PGOOD OFF thresholds should be manually set through PMBus commands 5E and 5F

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## **Digital Interface Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics						•
Input High Voltage (CLK, DATA)		VIH	2.1			V
Input Low Voltage (CLK, DATA)		VIL			1.1	V
Input high level current (CLK, DATA)		I <sub>IH</sub>			0.5	μΑ
Input low level current (CLK, DATA)		I <sub>IL</sub>			4	mA
Output Low Voltage (CLK, DATA, SMBALERT#)	I <sub>OUT</sub> =4mA	Vol			0.25	V
Output high level open drain leakage current (DATA, SMBALERT#)	V <sub>OUT</sub> =3.6V	Іон	5		55	nA
Pin capacitance		Со			10	pF
PMBus Operating frequency range	Slave Mode	FРMВ	10		1000	kHz
Data hold time		thd:dat		0		ns
Data setup time		<b>t</b> su:dat		100		ns
Measurement System Characteristics						
Read delay time		tdly		110		μs
Output current measurement range		I <sub>RNG</sub>	0		135	А
Output current measurement resolution		Ires		250		mA
Output current measurement accuracy	-40°C to +85°C	I <sub>ACC</sub>			±5	% of Io,max
V <sub>OUT</sub> measurement range		V <sub>OUT</sub>	0		2.0	V
V <sub>OUT</sub> measurement accuracy		V <sub>OUT(gain)</sub>		±1		% of Vo,max
V <sub>OUT</sub> measurement resolution		V <sub>OUT(res)</sub>		0.61		mV
V <sub>IN</sub> measurement range		V <sub>IN</sub>	0		16	V
V <sub>IN</sub> measurement accuracy		V <sub>IN(gain)</sub>		±2		%
V <sub>IN</sub> measurement resolution		V <sub>IN(res)</sub>		5.8		mV
Temperature measurement range		T <sub>MEAS</sub>	-25		150	°C
Temperature measurement accuracy		T <sub>MEAS(gain)</sub>	-8		8	°C
Temperature measurement resolution		T <sub>MEAS(res)</sub>		0.08		°C

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#### **Characteristic Curves**

The following figures provide typical characteristics for the 120A Digital TeraDLynx™ at 0.6Vo and 25°C.

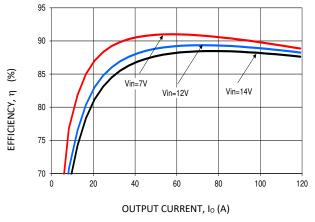


Figure 1. Converter Efficiency versus Output Current.

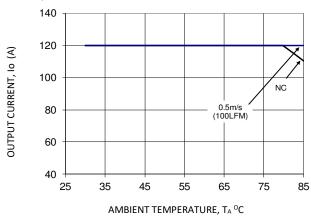
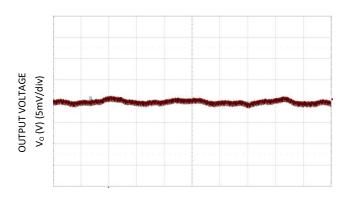
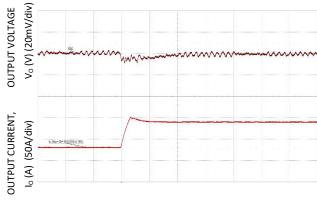


Figure 2. Derating Output Current versus Ambient Temperature and Airflow.

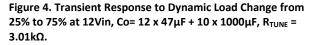


TIME, t (50μs/div)



TIME, t (200µs /div)

Figure 3. Typical output ripple and noise ( $C_0=12x47\mu F$  ceramic +  $10x470\mu F$  polymer,  $V_{IN}=12V$ ,  $I_0=I_{0,max_s}$ ).



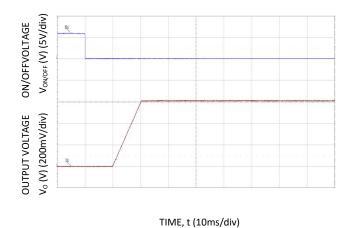


Figure 5. Typical Start-up Using On/Off Voltage (Io = Io, max).



TIME, t (10ms/div)

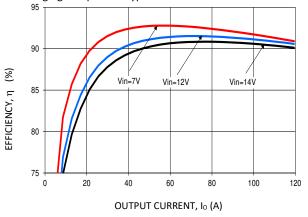
Figure 6. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{0,max}$ ).

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#### **Characteristic Curves**

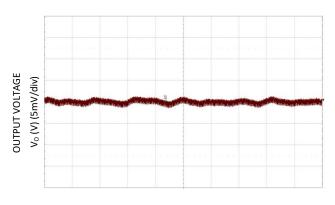
The following figures provide typical characteristics for the 120A TeraDLynx™ at 0.8Vo and 25°C



1m/s (200LFM) 120 OUTPUT CURRENT, Io (A) 100 NC 80 0.5m/s (100LFM) 60 40 25 35 55 65 75 85 AMBIENT TEMPERATURE, TA °C

Figure 7. Converter Efficiency versus Output Current.

Figure 8. Derating Output Current versus Ambient Temperature and Airflow.



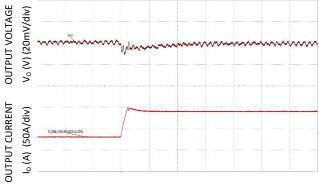
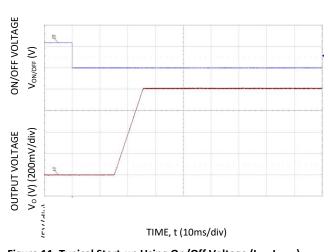


Figure 9. Typical output ripple and noise ( $C_0$ =12x47 $\mu$ F ceramic + 10x470 $\mu$ F polymer,  $V_{IN}$  = 12V,  $I_0$  =  $I_{0,max}$ )

TIME, t (50µs/div)

Figure 10. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47 $\mu$ F + 10 x 1000 $\mu$ F, R<sub>TUNE</sub> = 3.01k $\Omega$ .

TIME, t (200µs /div)



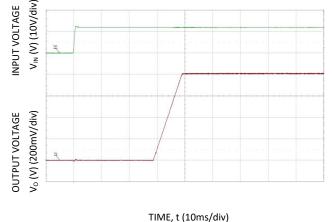


Figure 11. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

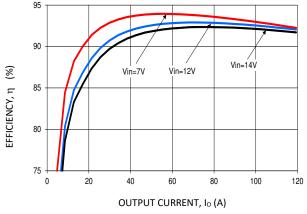
Figure 12. Typical Start-up Using Input Voltage ( $V_{IN}$  = 12V,  $I_0$  =  $I_{o,max}$ ).

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#### **Characteristic Curves**

The following figures provide typical characteristics for the 120A Digital TeraDLynx™ at 1.0Vo and 25°C.



140 1m/s (200LFM) 120 OUTPUT CURRENT, Io (A) 100 80 0.5m/s (100LFM) 60 25 35 45 55 65 75 85 AMBIENT TEMPERATURE, TA OC

Figure 13. Converter Efficiency versus Output Current.

Figure 14. Derating Output Current versus Ambient Temperature and Airflow.

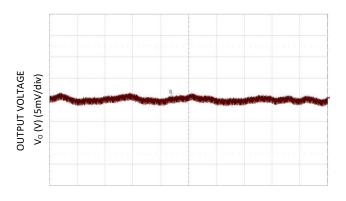


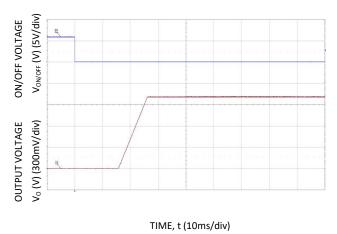


Figure 15. Typical output ripple and noise ( $C_0=12x47\mu F$  ceramic +  $10x470\mu F$  polymer,  $V_{IN}=12V$ ,  $I_0=I_{O,max}$ ,)

TIME, t (50µs/div)

Figure 16. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47 $\mu$ F + 10 x 1000 $\mu$ F, R<sub>TUNE</sub> = 3.01k $\Omega$ .

TIME, t (200µs /div)



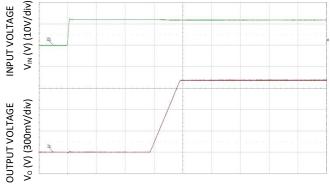


Figure 17. Typical Start-up Using On/Off Voltage (Io = Io,max).

Figure 18. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{0,max}$ ).

TIME, t (10ms/div)

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#### **Characteristic Curves**

The following figures provide typical characteristics for the 120A Digital TeraDLynx™ at 1.2Vo and 25°C.

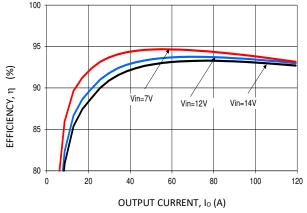


Figure 19. Converter Efficiency versus Output Current.

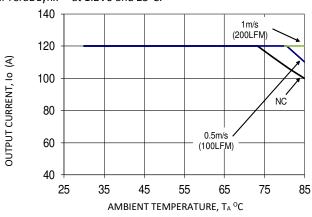
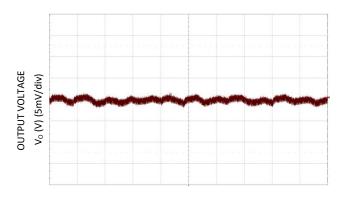
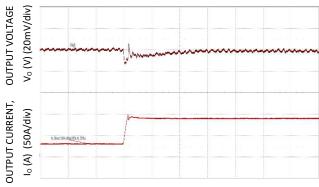


Figure 20. Derating Output Current versus Ambient Temperature and Airflow.

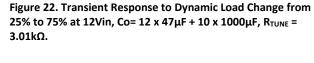


TIME, t (50µs/div)



TIME, t (200µs /div)

Figure 21. Typical output ripple and noise ( $C_0=12x47\mu F$  ceramic +  $10x470\mu F$  polymer,  $V_{IN}=12V$ ,  $I_0=I_{O,max}$ ,)



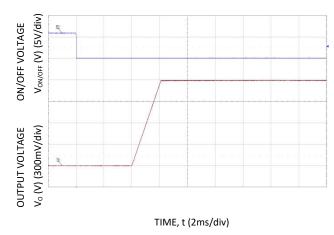
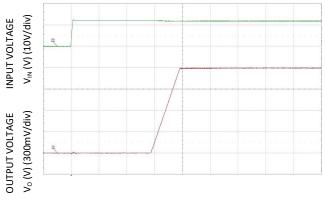


Figure 23. Typical Start-up Using On/Off Voltage (Io = Io,max).



TIME, t (10ms/div)

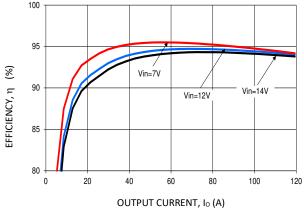
Figure 24. Typical Start-up Using Input Voltage ( $V_{IN}$  = 12V,  $I_0$  =  $I_{O,max}$ ).

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#### **Characteristic Curves**

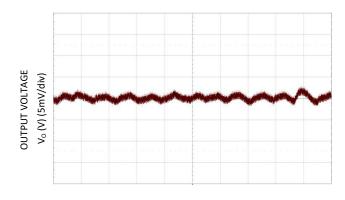
The following figures provide typical characteristics for the 120A Digital TeraDLynx™ at 1.5Vo and 25°C.

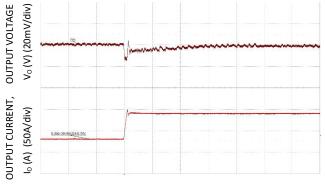


1m/s (200LFM) 120 OUTPUT CURRENT, Io (A) 100 80 NC 0.5m/s 60 (100LFM) 40 75 25 35 45 55 65 85 AMBIENT TEMPERATURE, TA °C

Figure 25. Converter Efficiency versus Output Current.

Figure 26. Derating Output Current versus Ambient Temperature and Airflow.

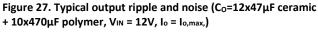




TIME, t (50µs/div)

Figure 28. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47 $\mu$ F + 10 x 1000 $\mu$ F, R<sub>TUNE</sub> = 3.01k $\Omega$ .

TIME, t (200µs /div)



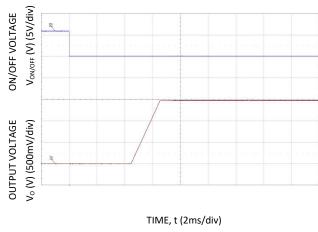




Figure 20 Typical Start\_un Heing On/Off Voltage (L. - L. ....)

Figure 20 Typical Start\_un Heine Innut Voltage (Visi = 12V Is =

TIME, t (2ms/div)

## 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### **Design Considerations**

#### **Input Filtering**

The 120A TeraDLynx™ module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pins of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 31 shows the input ripple voltage for various output voltages at 120A of load current with  $4x470 + 12x22 + 12x4.7 \, \mu F$  and  $2x470 + 6x22 + 12x4.7 \, \mu F$  input capacitor combinations.

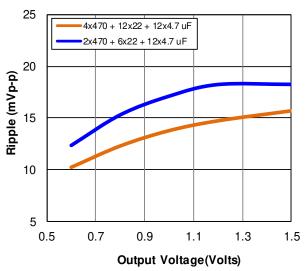


Figure 31. Input ripple voltage for various output voltages with two input capacitor combinations at 120A load. Input voltage is 12V.

#### **Output Filtering**

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with minimum of 12 x 22  $\mu\text{F}$  ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 32 provides output ripple information for capacitance of ~3574uF (47µF (1210 ceramic) x 12 + 10µF (0805 ceramic) + 0.1µF (0402) x4 + 1000µF (polymer) x 3) at various Vo and a full load current of 120A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can

be achieved by using the Tunable Loop  $^{\text{TM}}$  feature described later in this data sheet.

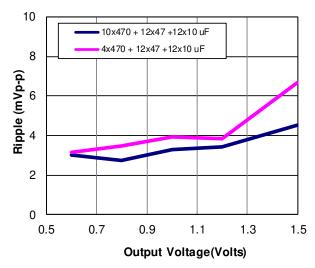


Figure 32. Peak to peak output ripple voltage for various output voltages with external capacitors at the output (120A load). Input voltage is 12V.

#### **Safety Considerations**

For safety agency approval the power module must be For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL ANSI/UL\* 62368-1 and CAN/CSA+ C22.2 No. 62368-1 Recognized, DIN VDE 0868-1/A11:2017 (EN62368-1:2014/A11:2017)

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV) or ES1, the input must meet SELV/ES1 requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a slow-blow fuse. When the input voltage is  $\leq$  8V, the recommendation is to use two 25A Littelfuse 456 series or equivalent fuses in parallel. For input voltages > 8V, a single 40A Littelfuse series 456 or equivalent fuse is recommended.

## 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

### **Analog Feature Descriptions**

#### Remote On/Off

The TeraDLynx 120A module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the ON/OFF input:

- Module ON/OFF can controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF can controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF can be controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

#### **Analog On/Off**

The 120A Digital TeraDLynx™ power modules feature an On/Off pin for remote On/Off operation. With the Negative Logic On/Off option, (see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. Leaving the On/Off pin disconnected will turn the module ON when input voltage is present. With the positive logic on/off option, the module turns ON during logic high and OFF during logic low.

#### **Digital On/Off**

Please see the Digital Feature Descriptions section.

#### **Monotonic Start-up and Shutdown**

The module has monotonic start-up and shutdown behavior on the output for any combination of rated input voltage, output current and operating temperature range.

#### **Startup into Pre-biased Output**

The module will start into a pre biased output on output as long as the pre bias voltage is 0.5V less than the set output voltage.

#### **Analog Output Voltage Programming**

The output voltage of the module is programmable to any voltage from 0.6 to 1.5Vdc, as shown in Table 1, by connecting a resistor between the Trim and SIG\_GND pins of the module as shown in Fig 33.

Without an external resistor between the Trim pin and SIG\_GND pins, the output of the module will be 0.1 Vdc. The

value of the trim resistor,  $R_{Trim}$  for a desired output voltage, should be selected as shown in Table 1.

The trim resistor is only determined during module initialization and hence cannot be used for dynamic output voltage adjustment

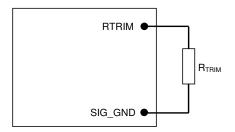


Figure 33. Circuit configuration for programming output voltage using an external resistor.

Table 1

V <sub>O, set</sub>	Rtrim (Ω)	V <sub>O, set</sub> (V)	Rtrim (Ω)	V <sub>O, set</sub> (V)	Rtrim (Ω)			
0.600	1090	1.000	2870	1.400	18900			
0.620	1140	1.020	3050	1.420	23200			
0.640	1180	1.040	3240	1.440	29800			
0.660	1230	1.060	3480	1.460	40200			
0.680	1290	1.080	3700	1.480	60400			
0.700	1330	1.100	3920	1.500	115000			
0.720	1380	1.120	4220					
0.740	1470	1.140	4530					
0.760	1560	1.160	4990					
0.780	1640	1.180	5360					
0.800	1740	1.200	5900					
0.820	1820	1.220	6420					
0.840	1930	1.240	6980					
0.860	2030	1.260	7680					
0.880	2130	1.280	8450					
0.900	2230	1.300	9420					
0.920	2340	1.320	10400					
0.940	2460	1.340	11700					
0.960	2610	1.360	13500					
0.980	2710	1.380	15800					

### **Digital Output Voltage Adjustment**

Please see the Digital Feature Descriptions section.

### **Remote Sense**

The power module has a differential Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-) for the output. The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.3V.

#### **Digital Output Voltage Margining**

## 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### Please see the Digital Feature Descriptions section.

#### **Output Voltage Sequencing**

The power module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

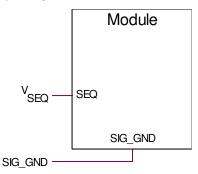


Figure 34. Circuit showing connection of the sequencing signal to the SEQ pin.

When the sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5V/msec during power-up or power-down.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their set-point voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

#### **Digital Sequencing**

The module can support digital sequencing by allowing control of the turn-on delay and rise times as well as turn-off and fall times.

#### **Digital Output Voltage Margining**

Please see the Digital Feature Descriptions section.

### **Overcurrent Protection (OCP)**

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry on output and can endure current limiting continuously. The module overcurrent response is non-latching shutdown with automatic recovery. OCP response time is programmable through manufacturer specific commands. The unit operates normally once the output current is brought back into its specified range.

#### **Digital Adjustable Overcurrent Warning**

#### Please see the Digital Feature Descriptions section.

#### **Overtemperature Protection**

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 135 °C (typ) is exceeded at the thermal reference point  $T_{\rm ref}$ . Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

#### **Digital Adjustable Overcurrent Warning/Shutdown**

Please see the Digital Feature Descriptions section.

#### **Digital Temperature Status via PMBus**

Please see the Digital Feature Descriptions section.

# Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.

#### **Input Undervoltage Lockout**

At input voltages below the input undervoltage lockout limit, module operation for the associated output is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

#### **Digitally Adjustable Input Undervoltage Lockout**

Please see the Digital Feature Descriptions section.

#### **Digitally Adjustable Power Good Thresholds**

Please see the Digital Feature Descriptions section.

#### Synchronization

The module switching frequency is capable of being synchronized to an external signal frequency within a specified range. Synchronization is done by using the external signal applied to the SYNC pin of the module as shown in Fig. 35, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency.

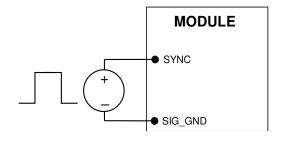


Figure 35. External source connections to synchronize switching frequency of the module.

Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

## 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### **Digital Compensator**

The TJT120 module uses digital control to regulate the output voltage. As with all POL modules, external capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The TJT120 comes with default compensation values programmed into the non-volatile memory of the module. These digital compensation values can be adjusted externally to optimize transient response and also ensure stability for a wide range of external capacitance, as well as with different types of output capacitance. This can be done by two different methods.

- By allowing the user to select among several pre-tuned compensation choices to select the one most suited to the transient response needs of the load. This selection is made via a resistor RTune connected between the RTUNE and SIG\_GND pins as shown in Fig. 35. Table 2 shows various pre-tuned compensation combinations recommended for various external capacitor combinations.
- Using PMBus to change compensation parameters in the module.

Note that during initial startup of the module, compensation values that are stored in non-volatile memory are used. If a resistor RTune is connected to the module, then the compensation values are changed to ones that correspond to the value of RTUNE. If RTUNE is open however, no change in compensation values is made. Finally, if the user chooses to do so, they can overwrite the compensation values via PMBus commands.

Recommended values of  $R_{\text{TUNE}}$  for different output capacitor combinations are given in Table 2. If no RTUNE is used, the default compensation values are used.

The TJT120 pre-tuned compensation can be divided into three different banks (COMP1, COMP2, COMP3) that are available to the user to compensate the control loop for various values and combinations of output capacitance and to obtain reliable and stable performance under different conditions. Each bank consists of 20 different sets of compensation coefficients precalculated for different values of output capacitance. The three banks are set up as follows:

 COMP1: Recommended for the case where all of the output capacitance is composed of only ceramic

- capacitors. The range of external output capacitance is from 1470  $\mu F$  to a maximum value of 17640  $\mu F$ )
- COMP2: For the most commonly used mix of ceramic and polymer type capacitors that have higher output capacitance in a smaller size. The range of output capacitance is from 2564  $\mu$ F to a maximum of 30564  $\mu$ F. This is the combination of output capacitance and compensation that can achieve the best transient response at lowest cost and smallest size. For example, with the maximum output capacitance of 12 x 47 $\mu$ F ceramics + 25 x 1000  $\mu$ F polymer capacitors, and selecting RTUNE = 5.36k $\Omega$ , transient deviation can be as low as 25 mV, for a 50% load step (0 to 85A).
- COMP3: Suitable for a mix of ceramic and higher ESR polymers or electrolytic capacitors, with output capacitance ranging from a minimum of 2204 μF to a maximum of 30084 μF.

Selecting  $R_{\text{TUNE}}$  according to Table 2 will ensure stable operation of the module with sufficient stability margin as well as yield optimal transient response.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of  $R_{\text{TUNE}}$  in order to meet 2% output voltage deviation limits for some common output voltages in the presence of an 60A to 120A step change (50% of full load), with an input voltage of 12V.

Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external RTUNE to tune the module for best transient performance and stable operation for other output capacitance values. Simulation models are also available via the GE Power Module Wizard to predict stability characteristics and transient response.

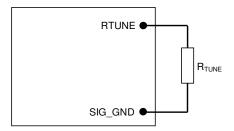


Figure 36. Circuit diagram showing connection of  $R_{\text{TUNE}}$  to tune the control loop of the module.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Table 2. Recommended  $R_{\text{TUNE}}$  Compensation.

<b>Output Capacitance</b>	Number of Output	Total Output	R <sub>TUNE</sub>	R <sub>TUNE</sub>			1/0	
Туре	Capacitors**	Capacitance (μF)**	resistor (Ω)	Index	KD	KI	KP	AP
C	Default Compensation Value	S	OPEN		375	2	37	150
Ceramic	10 x 47μF + 10 x 100μF	1398	29.1	0	375	2	37	150
Ceramic	12 x 47μF + 12 x 100μF	1644	88.7	1	441	3	44	150
Ceramic	14 x 47μF + 14 x 100μF	1890	150	2	506	3	51	150
Ceramic	16 x 47μF + 16 x 100μF	2136	213	3	572	3	57	150
Ceramic	19 x 47μF + 19 x 100μF	2505	280	4	671	3	67	150
Ceramic	22 x 47μF + 22 x 100μF	2874	348	5	770	4	77	150
Ceramic	25 x 47μF + 25 x 100μF	3243	417	6	869	4	87	150
Ceramic	28 x 47μF + 28 x 100μF	3612	493	7	968	4	97	150
Ceramic	31 x 47μF + 31 x 100μF	3981	569	8	1067	4	107	150
Ceramic	34 x 47μF + 34 x 100μF	4350	642	9	1166	4	117	150
Ceramic	38 x 47μF + 38 x 100μF	4842	723	10	1297	5	130	150
Ceramic	42 x 47μF + 42 x 100μF	5334	806	11	1429	5	143	150
Ceramic	48 x 47μF + 48 x 100μF	6072	898	12	1627	5	163	150
Ceramic	55 x 47μF + 55 x 100μF	6933	938	13	1858	5	186	150
Ceramic	63 x 47μF + 63 x 100μF	7917	1090	14	2121	6	212	150
Ceramic	72 x 47μF + 72 x 100μF	9024	1180	15	2418	6	242	150
Ceramic	82 x 47μF + 82 x 100μF	10254	1290	16	2748	7	275	150
Ceramic	93 x 47μF + 93 x 100μF	11607	1400	17	3110	7	311	150
Ceramic	105 x 47μF + 105 x 100μF	13083	1520	18	3506	7	351	150
Ceramic	120 x 47μF + 120 x 100μF	14928	1640	19	4000	8	400	150
Ceramic + Polymer	12 x 47μF + 2 x 1000μF	2672	1760	20	501	3	300	220
Ceramic + Polymer	12 x 47μF + 3 x 1000μF	3672	1890	21	688	3	413	220
Ceramic + Polymer	12 x 47μF + 4 x 1000μF	4672	2030	22	876	3	525	220
Ceramic + Polymer	12 x 47μF + 5 x 1000μF	5672	2150	23	1063	4	638	220
Ceramic + Polymer	12 x 47μF + 6 x 1000μF	6672	2320	24	1250	4	750	220
Ceramic + Polymer	12 x 47μF + 7 x 1000μF	7672	2460	25	1438	4	860	220
Ceramic + Polymer	12 x 47μF + 8 x 1000μF	8672	2640	26	1625	5	975	220
Ceramic + Polymer	12 x 47μF + 9 x 1000μF	9672	2840	27	1813	5	1088	220
Ceramic + Polymer	12 x 47μF + 10 x 1000μF	10672	3010	28	2000	5	1200	220
Ceramic + Polymer	12 x 47μF + 11 x 1000μF	11672	3200	29	2187	5	1312	220
Ceramic + Polymer	12 x 47μF + 12 x 1000μF	12672	3400	30	2375	5	1425	220
Ceramic + Polymer	12 x 47μF + 13 x 1000μF	13672	3650	31	2562	6	1537	220
Ceramic + Polymer	12 x 47μF + 15 x 1000μF	15672	3880	32	2937	6	1762	220
Ceramic + Polymer	12 x 47μF + 17 x 1000μF	17672	4120	33	3312	6	1987	220
Ceramic + Polymer	12 x 47μF + 19 x 1000μF	19672	4420	34	3687	7	2212	220
Ceramic + Polymer	12 x 47μF + 21 x 1000μF	21672	4700	35	4061	7	2437	220
Ceramic + Polymer	12 x 47μF + 23 x 1000μF	23672	5050	36	4436	7	2662	220
Ceramic + Polymer	12 x 47μF + 25 x 1000μF	25672	5360	37	4811	8	2887	220
Ceramic + Polymer	12 x 47μF + 27 x 1000μF	27672	5760	38	5186	8	3112	220
Ceramic + Polymer	12 x 47μF + 30 x 1000μF	30672	6120	39	5748	8	3449	220

<sup>\*\*</sup> Total output capacitance includes the capacitance inside the module is  $4 \times 47 \mu F$  (3m $\Omega$  ESR). Effective capacitance of 47uF cap taken as 42uF, 100uF cap taken as 81uF. Polymers taken at rated values of 100uF and 820uF

Note: The capacitors used in the digital compensation Loop tables are  $47\mu F/3 \, m\Omega$  ESR ceramic,  $100uF/3.2m\Omega$  ceramic,  $1000 \, \mu F/6m\Omega$  ESR polymer capacitor and  $820uF/19m\Omega$  ESR Polymer capacitor.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Table 2 (continued). R<sub>TUNE</sub> compensation table

Output Capacitance Type	Number of Output Capacitors**	Total Output Capacitance (μF)**	$R_{TUNE}$ resistor $(\Omega)$	R <sub>TUNE</sub> Index	KD	KI	КР	AP
Ceramic + Electrolytic	12 x 47μF + 2 x 820μF	2312	6570	40	176	2	176	220
Ceramic + Electrolytic	12 x 47μF + 3 x 820μF	3312	7060	41	238	3	238	220
Ceramic + Electrolytic	12 x 47μF + 4 x 820μF	3952	7590	42	301	3	301	220
Ceramic + Electrolytic	12 x 47μF + 5 x 820μF	4772	8160	43	363	3	363	220
Ceramic + Electrolytic	12 x 47μF + 6 x 820μF	5592	8870	44	426	4	426	220
Ceramic + Electrolytic	12 x 47μF + 7 x 820μF	6412	9530	45	488	4	488	220
Ceramic + Electrolytic	12 x 47μF + 8 x 820μF	7312	10400	46	550	4	550	220
Ceramic + Electrolytic	12 x 47μF + 9 x 820μF	8052	11300	47	613	4	613	220
Ceramic + Electrolytic	12 x 47μF + 10 x 820μF	8872	12400	48	675	5	675	220
Ceramic + Electrolytic	12 x 47μF + 11 x 820μF	9692	13700	49	738	5	738	220
Ceramic + Electrolytic	12 x 47μF + 12 x 820μF	10512	15000	50	800	5	800	220
Ceramic + Electrolytic	12 x 47μF + 14 x 820μF	12152	16700	51	925	5	925	220
Ceramic + Electrolytic	12 x 47μF + 16 x 820μF	13792	18700	52	1050	6	1050	220
Ceramic + Electrolytic	12 x 47μF + 18 x 820μF	15432	21000	53	1174	6	1174	220
Ceramic + Electrolytic	12 x 47μF + 20 x 820μF	17072	24000	54	1299	6	1299	220
Ceramic + Electrolytic	12 x 47μF + 23 x 820μF	19532	28000	55	1486	7	1486	220
Ceramic + Electrolytic	12 x 47μF + 26 x 820μF	21992	33000	56	1674	7	1674	220
Ceramic + Electrolytic	12 x 47μF + 29 x 820μF	24452	40200	57	1861	8	1861	220
Ceramic + Electrolytic	12 x 47μF + 32 x 820μF	26912	50500	58	2048	8	2048	220
Ceramic + Electrolytic	12 x 47μF + 36 x 820μF	30192	68000	59	2298	8	2298	220

<sup>\*\*</sup> Total output capacitance includes the capacitance inside the module is  $4 \times 47 \mu F$  ( $3 m\Omega$  ESR). Effective capacitance of 47uF cap taken as 42uF, 100uF cap taken as 81uF. Polymers taken at rated values of 100uF and 820uF

Note: The capacitors used in the digital compensation Loop tables are  $47\mu F/3 m\Omega$  ESR ceramic,  $100uF/3.2m\Omega$  ceramic,  $1000 \mu F/6m\Omega$  ESR polymer capacitor and  $820uF/19m\Omega$  ESR Electrolytic capacitor.

#### **Power Module Wizard**

GE offers a free web based easy to use tool that helps users simulate the Tunable Loop performance of the TJT120. Go to <a href="http://ge.transim.com/pmd/Home">http://ge.transim.com/pmd/Home</a> and sign up for a free account and use the module selector tool. The tool also offers downloadable Simplis/Simetrix models that can be used to assess transient performance, module stability, etc.

#### Bin 'a' and Bin 'b' settings using the models available through Power Module Wizard

The TJT120 module has a built-in non-linear compensation adjustment to speed up its transient response to dynamic loading conditions. When the module senses a load transition in progress, it automatically adjusts the KD, KI, KP settings to higher values and then reverts to the values set before the transient conditions. The adjustment of the PID coefficients is as follows:

Steady State			Transient Condition			
Bin 'a' – User set values based on RTUNE or programmed			Bin 'b' – Controller adjusted values for duration of transient			
KD	KI	KP	KD KI KP			
Α	В	Х	1.5 x A 2 x B 2 x C			

For determining the voltage response to a current load transient, it is more accurate to use the Bin 'b' settings corresponding to the selected KD, KI, KP values. For Loop Stability Simulations, the selected PID values corresponding to Bin 'a' should be used.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### **Digital Feature Descriptions**

#### **PMBus Interface Capability**

The 120A TeraDLynx power modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from <a href="https://www.pmbus.org">www.pmbus.org</a>. The modules support a subset of version 1.1 of the specification (see Table 4 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use

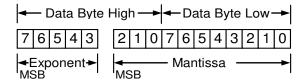
Communication over the module PMBus interface supports the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module.

The module also supports the SMBALERT# response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 4 for which command parameters can be saved to non-volatile storage).

#### **PMBus Data Format**

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two-byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by  $Value = Mantissa \times 2^{Exponent}$ 

#### **PMBus Addressing**

The power module is addressed through the PMBus using a device address. The module supports 128 possible addresses (0 to 127 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG\_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specification and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 3 (E96 series resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

The user must know which I<sup>2</sup>C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the

Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, <a href="mailto:smbus.org">smbus.org</a>.

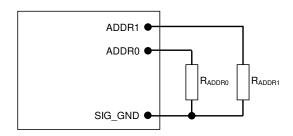


Figure 37. Circuit showing connection of resistors used to set the PMBus address of the module.

т.	_	۱.	-
Ιd	D	ıe	- 5

		ADDR1 Resistor Values									
ADDR0 Resistor Values	4.99K	15.4k	27.4K	41.2K	54.9K	71.5K	90.9K	110K	137K	162K	191K
4.99K	1	13	25	37	49	61	73	85	97	109	121
15.4K	2	14	26	38	50	62	74	86	98	110	122
27.4K	3	15	27	39	51	63	75	87	99	111	123
41.2K	4	16	28	40	52	64	76	88	100	112	124
54.9K	5	17	29	41	53	65	77	89	101	113	125
71.5K	6	18	30	42	54	66	78	90	102	114	126
90.9K	7	19	31	43	55	67	79	91	103	115	127
110K	8	20	32	44	56	68	80	92	104	116	64
137K	9	21	33	45	57	69	81	93	105	117	64
162K	10	22	34	46	58	70	82	94	106	118	64
191K	11	23	35	47	59	71	83	95	107	119	64
232K	12	24	©2 <b>%</b> 97 Ge	ner <del>4</del> 8Elec	tric 60mp	anv. 7A1 rig	hts Reserv	ed. 96	108	120	64

## 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### Operation (01h)

This is a paged register. The OPERATION command can be used to turn the module on or off in conjunction with the ON/OFF pin input. It is also used to margin up or margin down the output voltage

#### **PMBus Enabled On/Off**

The module can also be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON\_OFF\_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

0 : Output is disabled1 : Output is enabled

This module uses the lower five bits of the ON\_OFF\_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r	r
Function	PU	CMD	CPR	Х	CPA
Default Value	1	0	1	х	1

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Value	Action
0	Module ignores the ON bit in the OPERATION
U	command
1	Module responds to the ON bit in the
1	OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

Bit Value	Action
	Module ignores the analog ON/OFF pin, i.e.
0	ON/OFF is only controlled through the
	PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to
1	be asserted to start the unit

CPA: Sets the action of the analog ON/OFF pin when turning the controller OFF. This bit is internally read and cannot be modified by the user

#### **PMBus Adjustable Soft Start Rise Time**

The soft start rise time of module output is adjustable in the module via PMBus. The TON\_RISE command can set the rise time in ms, and allows choosing soft start times between 1 and 1000ms. Rise time below 10msec may cause the module it overshoot its voltage setpoint during startup

#### **Output Voltage Adjustment Using the PMBus**

Two PMBus commands are available to change the output voltage setting. The first, VOUT\_COMMAND can set the output voltage directly. The second, VOUT\_TRIM is used to apply an offset to the commanded output voltage.

Since the output voltage can be set using an external RTrim resistor as well, an additional PMBus command MFR\_VOUT\_SET\_MODE is used to tell the module whether the VOUT\_COMMAND is used to directly set output voltage or whether RTrim is to be used. If MFR\_VOUT\_SET\_MODE is set to where bit position 7 is set at 1, then VOUT\_COMMAND is ignored and output voltage is set solely by RTrim. If bit 7 of MFR\_VOUT\_SET\_MODE is set to 0, then output voltage is set using VOUT\_COMMAND, and the value of RTrim is only used at startup to set the output voltage.

The second output voltage adjustment command VOUT\_TRIM works in either case to provide a fixed offset to the output voltage. This allows PMBus adjustment of the output voltage irrespective of how MFR\_VOUT\_SET\_MODE is set and allows digital adjustment of the output voltage setting even when RTrim is used.

For all digital commands used to set or adjust the output voltage via PMBus, the resolution is  $98\mu V$ .

#### **Output Voltage Margining Using the PMBus**

The output voltage of the module can be margined via PMBus between 0.6 and 1.5V. The margining voltage can be adjusted in  $98\mu V$  steps.

#### **PMBus Adjustable Overcurrent Warning**

The module can provide an overcurrent warning via the PMBus. The threshold for the overcurrent warning can be set using the parameter IOUT\_OC\_WARN\_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The value of the IOUT\_OC\_WARN\_LIMIT can be stored to non-volatile memory using the STORE\_DEFAULT\_ALL command.

#### **Temperature Status via PMBus**

The module provides information related to temperature of the module through standardized PMBus commands. Commands READ\_TEMPERATURE1, READ\_TEMPERATURE\_2 are mapped to module temperature and internal temperature of the PWM controller, respectively. The temperature readings are returned in °C and in two bytes.

## 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### PMBus Adjustable Output Over, Under Voltage Protection

The module has output over and under voltage protection capability. The PMBus command VOUT\_OV\_FAULT\_LIMIT is used to set the output over voltage threshold. The default value is configured to be 112.5% of the commanded output. The command VOUT\_UV\_FAULT\_LIMIT sets the threshold that detects an output under voltage fault. The default values are 87.5% of the commanded output voltage. Both commands use two data bytes formatted in the Linear format.

#### **PMBus Adjustable Input Undervoltage Lockout**

The module allows adjustment of the input under voltage lockout and hysteresis. The command VIN\_ON allows setting the input voltage turn on threshold, while the VIN\_OFF command sets the input voltage turn off threshold. For the VIN\_ON command possible values are 7 to 14V and for the VIN\_OFF command, possible values are 6.75V to 14V. Both VIN\_ON and VIN\_OFF commands use the "Linear" format with two data bytes.

# Measurement of Output Current, Output Voltage and Input Voltage

The module can measure key module parameters such as output current, output voltage and input voltage and provide this information through the PMBus interface.

#### **Measuring Output Current Using the PMBus**

The module measures output current by using a signal derived from the switching FET currents. The current gain factor is accessed using the IOUT\_CAL\_GAIN command, and consists of two bytes in the Linear data format. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT\_CAL\_OFFSET command is used to store and read the current offset. The READ\_IOUT command provides module average output current information. This command only supports positive output current, i.e. current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ\_IOUT command returns two bytes of data in the Linear data format.

### **Measuring Output Voltage Using the PMBus**

The module provides output voltage information using the READ\_VOUT command. The command returns two bytes of data in Linear format.

#### **Measuring Input Voltage Using the PMBus**

The module provides input voltage information using the READ\_VIN command. The command returns two bytes of data in the Linear format.

#### Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. A 1 in the bit position indicates the fault that is flagged.

STATUS\_BYTE: Returns one byte of information with a summary of the most critical device faults.

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS\_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

#### Low Byte

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

#### **High Byte**

Bit Position	Flag	Default Value
7	VOUT fault or warning	0
6	IOUT fault or warning	0
5	X	0
4	X	0
3	POWER_GOOD# (is negated)	0
2	X	0
1	X	0
0	X	0

STATUS\_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	VOUT_OV_WARNING	0
5	VOUT_UV_WARNING	0
4	VOUT UV Fault	0
3	X	0
2	X	0
1	X	0
0	X	0

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

STATUS\_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	X	0
5	IOUT OC Warning	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS\_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	X	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS\_CML: Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Data	0
5	Packet Error Check Failed	0
4	Memory Fault Detected	0
3	X	0
2	X	0
1	Other Communication Fault	0
0	X	0

MFR\_SPECIFIC\_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (001101 corresponds to the TJT120 series of module), while bits [7:3] in the high byte indicate the revision number of the module.

L	ow	Byte

Bit Position	Flag	Default Value
7:2	Module Name	001101

1:0	Reserved	10

#### **High Byte**

Bit Position	Flag	Default Value
7:3	Module Revision Number	None
2:0	Reserved	000

#### **User-Programmable Compensation Coefficients**

The output voltage control compensation coefficients can be changed by the user via PMBus commands. On startup, the module uses stored values of the four compensation parameters KD, KI, KP and ALPHA. If the module detects a valid value of RTUNE connected to the module, the values of KD, KI, KP and ALPHA are then changed to the appropriate values. Beyond this, the user can use the PMBus commands listed below to overwrite the values of KD, KP, KI and ALPHA.

MFR\_SPECIFIC\_KP: Allows the user to program the value of the KP compensation coefficient. The allowed range is -32768 to 32767. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, the maximum allowed value is 10922

MFR\_SPECIFIC\_KI: Allows the user to program the value of the KI compensation coefficient. The allowed range is -32768 to 32767. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, the maximum allowed value is 10922

MFR\_SPECIFIC\_KD: Allows the user to program the value of the KD compensation coefficient. The allowed range is -32768 to 32767. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, the maximum allowed value is 10922

MFR\_SPECIFIC\_ALPHA: Allows the user to program the value of the ALPHA compensation coefficient. The allowed range is -256 to 256. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, use positive values only as suggested with the maximum allowed value being 256.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

## **Summary of Supported PMBus Commands**

Please refer to the PMBus 1.1 specification for more details of these commands. For the registers where a range is specified, any value outside the range is ignored and the module continues to use the previous value.

Table 4

Hove			Non Volatile									
Hex Code	Command				Brief D	escripti	on					Non-Volatile Memory Storage
		Turn Module on or	off. Also	used to	margin	the out	put volt	age				
		Format				Unsigne	d Binary	/			1	
01	ODEDATION	Bit Position	7	6	5	4	3	2	1	0		VEC
01	OPERATION	Access	r/w	r	r/w	r/w	r/w	r/w	r	r		YES
		Function	On	Х	,	Ma	rgin		Х	Х		
		Default Value	1	0	0	0	0	0	Х	Х		
		Configures the ON/O	OFF fund	ctionalit		mbinat	ion of a	nalog Ol	l	<u> </u>	PMBus	
		Format				Unsigne	d Binary	/				
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0		YES
		Access	r	r	r	r/w	r/w	r/w	r	r		
		Function	Χ	Х	Х	pu	cmd	cpr	Х	сра		
		Default Value	0	0	0	1	0	1	х	1		
03	CLEAR_FAULTS	device has been ass	ear any fault bits that may have been set, also releases the SMBALERT# signal if the evice has been asserting it.									
		Used to control writ	-						_		-	
		the module whose of			matche	the val	ue in th	e data b	yte into	non-vo	latile	
		memory (EEPROM)	on the r	nodule			-l D'				1	
		Format					d Binary			1 0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	X	X	X	X	X		
		Function	bit7	bit6	bit5	X	X	X	X	X		
10	WRITE_PROTECT	Default Value Bit5: 0 – Enables all	0	0	0	X	X	Χ	Х	X		YES
		1 – Disables all and ON_OFI Bit 6: 0 – Enables all OPERATION Bit7: 0 – Enables all 1 – Disables all (bit5 and bit	e_CONF writes a writes a writes a writes e 6 must	IG (bit 6 as perm except for ands (bit as permi except for be 0)	and bit itted in or the W t5 and b tted in b or the W	7 must k bit5 or k /RITE_P it7 musi bit5 or b RITE_PF	oe 0) oit7 ROTECT t be 0) it6 ROTECT	and comma	nd			
11	STORE_DEFAULT_ALL	Copies all current re the module. Takes a							memor	y (EEPRC	DM) on	
13	DECTORE DESAULT ALL	Restores all current							the mod	dule non	-volatile	
12	RESTORE_DEFAULT_ALL	memory (EEPROM)										
		The module has MC changed	1	1	ı	ponent	set to -1	1	e values	cannot	be	
20	VOUT_MODE	Bit Position	7	6	5	4	3	2	1	0		
_		Access	r	r	r	r	r	r	r	r		
		Function		Mode	1		's comp					
		Default Value	0	0	0	1	0	0	1	0	]	
		Set desired output voltage. Only 16-bit unsigned mantissa – implied exponent of -14 per VOUT_MODE command. Valid range is 0.6 to 1.5V.  Format Unsigned Mantissa										
		Bit Position	15	14	13	12	11	10	9	8	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
21	VOUT_COMMAND	Function			•	•	tissa			•	1	YES
	_	Default Value				Vari	able				1	
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function			•	Man	tissa			•	1	
		Default Value					able				1	
		I									4	

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Apply a fixed offset voltage to the set output voltage from either the RTrim resist VOUT COMMAND. Implied exponent of -14 per VOUT MODE command.		Memory Storage
Allowed range is ±300mV.		
Format Linear, two's complement binary		
Bit Position         15         14         13         12         11         10         9         8		
22 VOUT_TRIM  Access r/w		YES
- Function Mantissa		11.3
Default Value   0   0   0   0   0   0   0		
Bit Position         7         6         5         4         3         2         1         0	_	
Access r/w r/w r/w r/w r/w r/w r/w r/w r/w	_	
Function   Mantissa     Default Value   0   0   0   0   0   0   0   0   0	-	
Applies an offset to the commanded output voltage to calibrate out errors in se	ting modulo	
output voltage (between -100mV and +100mV) and when output voltage is set v	•	
command VOUT_COMMAND (21). Implied exponent of -14 per VOUT_MODE or		
Format Linear, two's complement binary	7	
Bit Position         15         14         13         12         11         10         9         8	1	
Access r/w r r r r r r r	1	VEC
23 VOUT_CAL_OFFSET Function Mantissa		YES
Default Value Variable based on factory calibration		
Bit Position         7         6         5         4         3         2         1         0		
Access   r   r/w   r/w   r/w   r/w   r/w   r/w   r/w   r/w		
Function Mantissa	_	
Default Value Variable based on factory calibration	) (OUT 14005	
Sets the target voltage for margining the output high. Implied exponent of -14 p command. Allowed range is 0.6 to 1.5V	er VOUT_MODE	
Format Linear, two's complement binary	¬	
	-	
Access r/w r/w r/w r/w r/w r/w r/w r/w r/w	1	
25 VOUT_MARGIN_HIGH Function Mantissa	1	YES
Default Value Variable		. 20
Bit Position         7         6         5         4         3         2         1         0	1	
Access r/w r/w r/w r/w r/w r/w r/w r/w		
Function Mantissa		
Default Value Variable		
Sets the target voltage for margining the output low. Implied exponent of -14 pe	r VOUT_MODE	
command. Allowed range is 0.6 to 1.5V.	_	
Format Linear, two's complement binary		
Bit Position         15         14         13         12         11         10         9         8		
Access   r/w   r	_	
26 VOUT_MARGIN_LOW Function Mantissa	_	YES
Default Value   Variable	-	
Access r/w r/w r/w r/w r/w r/w r/w r/w r/w	-	
Function Mantissa	-	
Default Value Variable	┥	
	+ C Allower	
Sets the value of input voltage at which the module turns on. Exponent is fixed a range is 7 to 14V.	t -o. Allowed	
Format Linear, two's complement binary	7	
Bit Position   15   14   13   12   11   10   9   8	<b>-</b>	
Access r r r r r r r r/w r/w	┥ !	
35 VIN_ON Function Exponent Mantissa	╡	YES
Default Value         1         1         0         1         0         0         0         1	]	
Bit Position         7         6         5         4         3         2         1         0		
Access r/w r/w r/w r/w r/w r/w r/w r/w r/w	_	
Function Mantissa	_	
Default Value   1   1   0   0   0   0   0		

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Sets the value of input voltage at which the module turns off. Exponent is fixed at -6. Allowed range is 6.75 to 14V.   Format	Code	Command			Non-Volatile								
Tange is 6.75 to 14V.   Format	1		Coto the value of the	- دا مینید	go st.		Descrip		ff [	mon+:- 1	ناموا - ا	C Allamas	Memory Storage
Format			-		ige at w	nich the	module	turns o	тт. Ехро	nent is i	ixed at -	-6. Allowed	
Bit Position				i		inoar t	vo's con	anlamai	at hinan	.,			
Access			-	1 5							0		
Function   Exponent				<del>                                     </del>		15							
Default Value	26	VIN OFF		'		vnonon		1					VEC
Bit Position   7   6   5   4   3   2   1   0     Access   r/w     Function	30	VIIN_OFF		1		· —		0					163
Access													
Function			-										
Default Value				1, 00	1,700	17 00			1, 00	17 00	1, **		
Applies a gain correction to the READ_IOUT command results to calibrate out gain errors in module measurements of the output current. The number in this register is divided by 8192 to generate the correction factor. Allowed range is 6553 to 9830.  Format Linear, two's complement binary  Bit Position 15 14 13 12 11 10 9 8  Access r r r r r r r r r r r r r r r r r r				1	0	1			0	0	0		
module measurements of the output current. The number in this register is divided by 8192 to generate the correction factor. Allowed range is 6553 to 9830.    Format												errors in	
Togenerate the correction factor. Allowed range is 6553 to 9830.   Format   Linear, two's complement binary													
Format										cBister i	o aiviae	a by 0132	
Bit Position   15   14   13   12   11   10   9   8										v			
Access				15							8		
Function   Integer													
Default Value	38	IOUT_CAL_GAIN	Function				Inte	ger			,		YES
Bit Position   7   6   5   4   3   2   1   0			Default Value		Va	riable ba			calibrati	ion			
Function   Integer   Default Value   Variable based on factory calibration    Returns the value of the offset correction term used to correct the measured output current. The exponent is fixed at -2. The allowed range is -50 to +50A.    Format			Bit Position	7							0		
Default Value   Variable based on factory calibration			Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
Default Value   Variable based on factory calibration			Function				Inte	ger	•		,		
The exponent is fixed at -2. The allowed range is -50 to +50A.    Format			Default Value		Va	riable ba			calibrati	ion			
The exponent is fixed at -2. The allowed range is -50 to +50A.    Format			Returns the value of	f the off	set corre	ection te	erm used	d to corr	ect the	measur	ed outp	ut current.	
Bit Position   15   14   13   12   11   10   9   8													
Bit Position   15   14   13   12   11   10   9   8			Format		L	inear. tv	vo's con	nplemei	nt binar	v			
Second   S			-	15							8		
Second   Function   Exponent   Mantissa   Part			Access	r	r	r	r	r	r/w	r	r		
Bit Position         7         6         5         4         3         2         1         0           Access         r         r         r/w	39	IOUT_CAL_OFFSET			E	xponen	t		ľ	Mantissa	ı		YES
Access r r r/w r/w r/w r/w r/w r/w r/w  Function Mantissa  Default Value Variable based on factory calibration			Default Value	1	1	1	1	0	,	Variable			
Function Mantissa Default Value Variable based on factory calibration			Bit Position	7	6	5	4	3	2	1	0		
Default Value Variable based on factory calibration			Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
, , , , , , , , , , , , , , , , , , ,			Function		•		Man	tissa					
			Default Value		Va	riable ba	ased on	factory	calibrati	ion			
Sets the voltage level for an output overvoltage fault. Implied exponent of -14 per			Sets the voltage leve	el for an	output	overvol	tage fau	lt. Impl	ied expo	onent of	-14 per	•	
VOUT_MODE command. Allowed range is 0.6 to 2V. Triggers SMBALERT.			VOUT_MODE comm	and. All								_	
Format Linear, two's compliment binary			Format			Linear, t	wo's co	mplime	nt binar	у			
Bit Position         15         14         13         12         11         10         9         8			Bit Position	15	14	13	12	11	10	9	8		
Access r/w r/w r/w r/w r/w r/w r/w r/w			Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
40 VOUT_OV_FAULT_LIMIT Function Mantissa YES	40	VOUT_OV_FAULT_LIMIT	Function				Man	tissa					YES
Default Value Variable			Default Value				Vari	able					
Bit Position         7         6         5         4         3         2         1         0			Bit Position	7	6	5	4	3	2	1	0		
Access   r/w   r/w   r/w   r/w   r/w   r/w   r/w   r/w   r/w			Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
Function Mantissa							Man	tissa					
Default Value Variable			Default Value				Vari	able					
Instructs the module on what action to take in response to an output overvoltage fault													
Format Unsigned Binary			Format				Unsigne	d Binary				]	
Bit Position         7         6         5         4         3         2         1         0			Bit Position	7	6		4		2	1	0	]	
41   VOUT_OV_FAULT_RESPONSE	41 V	41 VOUT_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r	]	YES
Function         RSP [1]         RSP [0]         RS[1]         RS[0]         X         X         X						RS[2]	RS[1]	RS[0]	Х	Х	Х		
Default Value         1         0         1         1         0         0         0			Default Value	1	0	1	1	1	0	0	0	]	

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command		Brief Description											
		Sets the value of ou	tput vol	tage at	which th	ne modu	ıle gene	rates wa	rning fo	or over-	voltage.			
		Exponent is fixed at	-14. All	owed ra	nge is 0	.6 to 2V	. Trigger	rs SMBA	LERT.		_			
		Format		l	inear, t	wo's co	mpleme	nt binar	У					
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r/w	r/w	r/w				
42	VOUT_OV_WARN_LIMIT	Function			Exponen	t		1	Mantissa	a		YES		
		Default Value				Vari	able							
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function					itissa							
		Default Value				Vari	able							
		Sets the value of ou	tput vol	tage at	which th	ne modu	ıle gene	rates wa	arning fo	or under	-voltage.			
		Exponent is fixed at	-14. All	owed ra	nge is 0	.05 to 1	.5V. Trig	gers SM	BALERT		1			
		Format			inear, t	wo's co	npleme	nt binar						
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r/w	r/w	r/w				
43	VOUT_UV_WARN_LIMIT	Function			Exponen			ı	Mantissa	a		YES		
		Default Value		1			able	1	1	1				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function					itissa							
		Default Value					able							
		Sets the voltage leve				oltage f	ault. Exp	ponent i	s fixed a	it -14. <i>F</i>	Allowed			
		range is 0.05 to 2V.	1											
		Format	15					nt binar	y 9	0				
		Bit Position Access	15	14 r	13	12 r	11	10 r/w	r/w	8 r/w				
44	VOUT_UV_FAULT_LIMIT	Function	r	L	r Exponen	l	r		Mantissa Mantissa			YES		
44	VOOT_UV_FAULT_LIMIT	Default Value			-хропен		able		viaiitisse	<u> </u>		TES		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function	.,	.,	.,		itissa	.,	.,	.,				
		Default Value					able							
		Instructs the modul	o on wh	at actio	n to take	in rocr	onse to	an outr	ut unde	rvoltag	a fault			
		Format	I	at actio			d Binary		at anac	rvoitag				
		Bit Position	7	6	5	4	3	2	1	0				
45	VOUT_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES		
			RSP	RSP			,					. = -		
		Function	[1]	[0]	RS[2]	RS[1]	RS[0]	Х	Х	Х				
		Default Value	1	0	1	1	1	0	0	0				
		Sets the current leve	el for an	output	overcur	rent fau	ılt (can d	only be l	owered	below t	the			
		maximum of 140A).												
		Format		1	inear t	۷0's ۲۰۱	nnleme	nt binar	v		]			
		Bit Position	15	14	13	12	11	10	y 9	8				
		Access	r	r	r	r	r	r	r/w	r/w				
46	IOUT_OC_FAULT_LIMIT	Function		L	xponen	l	<u> </u>		Mantissa			YES		
		Default Value	1	1	1	1	0	0	1	0				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function					itissa							
		Default Value	0	0	0	0	1	0	0	0				
		1		•	•	•	•	•			•	l		

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex					(COIIIII							Non-Volatile
Code	Command				Brie	Descri	otion					Memory Storage
		Sets the value of cu	rrent lev	el at wl	nich the	module	generat	tes warr	ning for	overcur	rent.	
		Allowed range is 0 t	o 140A.	The exp	onent i	s fixed a	t -2. Trig	gers SN	/IBALER1	ī	•	
		Format					mpleme		-			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r	r/w		
4A	IOUT_OC_WARN_LIMIT	Function		1	xponen				Mantissa			YES
		Default Value	1	1	1	1	0	0	1	0		
		Bit Position Access	7	6 r/w	5	4	3 r/w	2 r/w	1	0		
		Function	r/w	1/W	r/w	r/w	•	1/W	r/w	r/w		
		Default Value	1	0	1	0	itissa 1	0	0	0		
		Sets the temperatur				_	_				nga is 35 to	
		140°C. The expone						iauit oc	curs. An	oweura	ilige is 33 to	
		Format	THE IS TIME				npleme	nt binar	v			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r/w	r	r		
4F	OT_FAULT_LIMIT	Function		· I	xponen	t	•		Mantissa	3		YES
		Default Value	0	0	0	0	0	0	0	0		-
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	itissa					
		Default Value	1	0	0	0	1	0	1	0		
		Configures the over	temper	ature fa	ult resp	onse						
		Format										
		Bit Position	7	6	5	4	3	2	1	0		
50	OT_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Х		
		Default Value	1	0	1	1	1	0	0	0		
		Sets the over temper fixed at 0. Triggers S			level in	°C. Allo	wed rar	nge is 30	to 130°	C. The 6	exponent is	
		Format			inear. t	wo's co	mpleme	nt binar	V			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r	r		
51	OT_WARN_LIMIT	Function	Ė		Exponer		1		Mantissa			YES
		Default Value	0	0	0	0	0	0	0	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Mar	itissa					
		Default Value	0	1	1	1	1	1	0	1		
		Sets the input overv Triggers SMBALERT	oltage f	ault lim	it. Expo	nent is f	fixed at -	-6. Allow	ved rang	ge is 6.7	5 to 15V.	
		Format		L	inear, t	vo's cor	nplemei	nt binar	у.			
		Bit Position	15	14	13	12tr	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
55	VIN_OV_FAULT_LIMIT	Function			Exponer	t		ا	Mantissa	9		YES
		Default Value	1	1	0	1	0	0	1	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					ntissa	1				
		Default Value	1	0	1	0	0	0	0	0		

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex	Command				Brief	f Descrip	ation					Non-Volatile
Code	Command			•		•	JUIOII					Memory Storage
		Configures the VIN of	overvolt	age fau			d D:				1	
		Format			1	Unsigne						
F.C	VIN OV FALIET DECDONCE	Bit Position	7	6	5	4	3	2	1	0		VEC
56	VIN_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Х		
		Default Value	1	0	0	0	0	0	0	0		
		Sets the value of the			_	_		-	_	-	at fixed at	
		6. Allowed range is						e iow w	arriirig.	Exponei	it lixeu at -	
		Format	3.73 (0 .			wo's cor		nt hinar	3/			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
57	VIN_OV_WARN_LIMIT	Function			Exponer				Mantiss			YES
,	VII.4_0 V_VV/II.II.4_EIIVII.1	Default Value	1	1	0	1	0	0	1	1		123
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa	· · · · · ·				
		Default Value	1	0	0	0	0	0	0	0		
		Sets the value of the	e input v	oltage t	that cau	ses innu	t voltaø	e low w	arning	Exponer	nt fixed at -	
		6. Allowed range is !	•	_		•		**				
		Format				wo's cor	npleme	nt binar	γ			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
58	VIN_UV_WARN_LIMIT	Function			Exponer	nt			Mantiss	a		YES
		Default Value	1	1	0	1	0	0	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa	1				
		Default Value	1	0	1	0	0	0	0	0		
		Sets the value of the					nput und	dervolta	ge fault	. Expone	ent fixed at -	
		6. Allowed range is !	5 to 14V								•	
		Format				wo's cor	mpleme					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r/w	r/w		
59	VIN_UV_FAULT_LIMIT	Function			Exponer	1			Mantiss			YES
		Default Value	1	1	0	1	0	0	0	1		
		Bit Position	7	6 r/w	5 r/w	4 r/w	3 r/w	2 r/w	1 r/w	0 r/w		
		Access Function	r/w	1 / VV	1 / VV		tissa	1 / W	1 / VV	1 / W		
		Default Value	1	0	1	0	0	0	0	0		
		Instructs the module	e on wh	at actio					it under	voltage	fault.	
		Format	_	<u> </u>		Unsigne						
ΕA	VIN UV FAULT DECDONICE	Bit Position	7	6	5	4	3	2	1	0		VEC
5A	VIN_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Х		
		Default Value	1	0	1	1	1	0	0	0		
			l				I					
		Sets the output volt							ıgn. Im	piied exp	oonent of -	
		14 per VOUT_MODE	Comm			wo's cor			7/			
		Bit Position	15	14	13	12	11	10	y 9	8		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
5E	POWER_GOOD_ON	Function	<u> </u>	., **	., **		itissa	., **	., **	1 1 / 44		YES
"		Default Value					able					1.23
		Bit Position	7	6	5	4	3	2	1	0		
	-	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa	· · · · · ·				
		Default Value				Vari	able					
		II h	•									

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex	Command					of Door	intinu					Non-Volatile
Code	Command					ef Desci	-					Memory Storage
		Sets the output volt							ed low.	Implied ex	rponent of -	
		14 per VOUT_MODI	E comm	and. All							1	
		Format					mplem			1	_	
		Bit Position	15	14	13	12	11	10	9	8	4	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	4	
5F	POWER_GOOD_OFF	Function					ntissa				4	YES
		Default Value	_		-	1	riable	_			4	
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	4	
		Function Default Value					ntissa riable				-	
		LL.						Alla		: . 0 + .	1000	
		Sets the delay time	in ms of	tne out	tput voit	tage dur	ing star	tup. Alic	owed rai	nge is u to	1000ms.	
		Format			Linear,	two's co	omplem	ent bina	ary		]	
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
60	TON_DELAY	Function		1	Exponen	1			Mantis		1	YES
	_	Default Value	0	0	0	0	0	0	0	0		
		Bit Position	7	6	5	4	3	2	1	0	_	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	_	
		Function					ntissa	1		1	4	
		Default Value	0	0	0	0	0	0	1	0		
		Sets the rise time in		he outp	ut volta	ge durin	ig startu	p. The e	exponen	t is fixed a	t 0. Allowed	
		range is 1 to 1000m	S.								7	
		Format					mplem				4	
		Bit Position	7	6	5	4	3	2	1	0	4	
64	TON 0105	Access	r	r	R	r	r	r	r/w	r/w	1	\/F6
61	TON_RISE	Function Default Value	0	0	Exponen		0	_	Mantis		-	YES
		Default Value	7		5	0	3	0	0	0	4	
		Bit Position Access	r/w	6 r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function	17 VV	1 / VV	1 / VV		ntissa	1 / W	1 / VV	1 / VV	1	
		Default Value	0	0	0	0	0	1	0	1	-	
		Sets the delay time									d at O	
		Allowed range is 0 t			tput voit	lage uui	ing turn	-011. 111	e expon	CIIL IS IIAC	u at o.	
		Format	3 10001		Linear	two's ro	omplem	ent hina	arv		1	
		Bit Position	15	14	13	12	11	10	9	8	1	
		Access	r	r	R	r	r	r	r/w	r/w	1	
64	TOFF_DELAY	Function			Exponen		· · · ·		Mantis		1	YES
		Default Value	0	0	0	0	0	0	0	0	1	. 20
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function				•	ntissa			•	1	
		Default Value	0	0	0	0	0	0	1	0	1	
		Sets the fall time in	ms of th	ne outpu	ut voltag	ge durin	g turn-o	ff. Expo	nent is f	ixed at 0.	Allowed	
		range is 0 to 1000m	S.								=	
		Format			Linear,	two's co	omplem	ent bina	ary		]	
		Bit Position	15	14	13	12	11	10	9	8	]	
		Access	r	r	R	r	r	r	r/w	r/w		
65	TOFF_FALL	Function			Exponen	nt			Mantis	sa	1	YES
		Default Value	0	0	0	0	0	0	0	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function					ntissa				1	
		Default Value	0	0	0	0	0	1	0	1		

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex						milinu									Non-Volatile
Code	Command				В	rief De	scriptio	n							Memory Storage
		Returns one byte of	informa	ation w	ith a si					al mod	lule f	aults		1	
		Format		_	1 _		nsigned	1		_					
		Bit Position	7	6	5		4	+	3	2	1	_	0		
78	STATUS_BYTE	Access	r	r	F		r		r	r	r		r		
		Flag	Х	OFF	VOU		OUT_OC	VIN	1_UV	TEMP	CN	1L O	THER		
		Default Value		l			Varia	ble							
		Returns two bytes o	of inform	nation v	with a :	summa	rv of the	e mo	dule's	fault/	warni	ng co	nditio	ns	
		Format					Unsigne								
		Bit Position	15	14		13	12		11	. :	10	9	8		
		Access	r	r		R	r		r		r	r	r		
		Flag	VOUT	IOUT	oc ı	NPUT	Х		PGO	OD	Х	Х	Х		
79	STATUS_WORD	Default Value		_	•		Vari	iable							
		Bit Position	7	6		5	4		3		2	1	0		
		Access	r	r		R	r		r		r	r	r		
								00							
		Flag	Х	OFF	- VC	)U [_0\	/ IOUT_			UV TE	:MP	CML	OTH	ĿК	
		Default Value					Vari	iable							
		Returns one byte of	informa	ation w	ith the	status	of the n	nodu	ıle's o	utput v	oltag/	e rela	ited fa	ults	
		Format					Unsign	ed Bi	nary						
		Bit Position	7		6		5		4		3	2	1	0	
7A	STATUS_VOUT	Access	r		r		r		r		r	r	r	r	
		Flag	VOUT_	ov V	OUT_O		OUT_U\	′_   ·	VOUT.	_UV	Х	Х	х	Х	
		Default Value		Variable											
		Returns one byte of	e of information with the status of the module's output current related faults												
		Format					gned Bi						1		
	CT 4 T 1 C 1 C 1 T	Bit Position	7		6 5			3		2	1	0			
7B	STATUS_IOUT	Access	r		r r	r		r		r	r	r			
		Flag	IOUT	_OC	ХХ	Х	IOUT_	0C_۱	NARN	Х	Х	Χ			
		Default Value					Variable								
		Returns one	oyte of i	nforma	ition w	ith the	status c	of the	mod	ule's ir	put r	elated	d fault	S	
		Format					Unsigne	ed Bi	nary						
		Bit Position		7		6		5		4	3	2	1	0	
7C	STATUS_INPUT	Access		r		r		r		r	r	r	r	r	
		Flag	VIN_O	V_FAU		1_0V_V				N_UV	Χ	Х	Х	Х	
		<b>.</b>			Α	RNING	WAR			AULT					
		Default Value	]				Var	iable	!						
		Datum	:		tala (1	-1	-611		.1-1				-d 6-		
		Returns one byte of	Intorma	ation w	ith the				iie's te	empera	iture	relate	ed faul	TS	
		Format Bit Position	7	,		Unsig 6	ned Bin		3	2	1	0			
7D	STATUS_TEMPERATURE	Bit Position					5 r	4 r				_			
		Access Flag	OT_F			r WARN	r X	r X	r X	r X	r X	r X			
		Default Value	01_1/	, OLI	<u> </u>		ariable	^	^	^	^	^			
<u> </u>			1												
		Returns one byte of	informa	ation w	ith the	status	of the r	nodu	ıle's co	<u>om</u> mu	<u>nic</u> atio	on rel	ated f	aults	
		Format					Unsigne	ed Bi	nary						
		Bit Position													
7E	STATUS_CML	Access	r		r	r	r	r	r		r			r	
	_	Flag	Inva		Invalid		x	Х	Х	Othe	r Com	ım Fa	ult	x	
			Comm	nand	Data	Fail				Julie	2011	1 0	-11		
		Default Value					Var	iable	!						
<b></b>															1

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command	Brief Description										Volatile ry Storage					
Code		Poturns the value of	f tha inn	ut volta	go anni	iad ta th	o modu	ulo				Memor	y Storage				
		Returns the value of	i the inp								İ						
		Format	4.5				npleme										
		Bit Position	15	14	13	12	11	10	9	8							
		Access	r	r	r	r	r	r	r	r							
88	READ_VIN	Function		Exponent Mantissa													
	_	Default Value															
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r	r	r	r	r	r	r	r							
		Function				Man											
		Default Value	efault Value Variable														
		Returns the value of	f the ou	tput vol	tage of	the mod	lule. Exp	onent is	s fixed a	nt -14	_						
		Format		L	inear, t	wo's cor	npleme	nt binar	у								
		Bit Position	15	14	13	12	11	10	9	8							
		Access	r	r	r	r	r	r	r	r							
		Function		•	•	Man	tissa			•							
8B	READ_VOUT	Default Value	i				able										
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r	r	r	r	r	r	r	r							
		Function				L	tissa										
		Default Value					able										
			f +b = ===	tout our	ront of												
			f the output current of the module.  Linear, two's complement binary							İ							
	READ_IOUT	Format	4.5														
		Bit Position	15	14	13	12	11	10	9	8							
		Access	r	r	r	r	r	r	r	r							
8C		Function	Exponent Mantissa Variable														
		Default Value	_							_							
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r	r	r	r	r	r	r	r							
		Function					itissa										
		Default Value				Vari	able										
		Returns a module F	ET packa	age tem	peratur	e in ºC.											
		Format		L	inear, t	wo's cor	npleme	nt binar	у								
		Bit Position	15	14	13	12	11	10	9	8							
		Access	r	r	r	r	r	r	r	r							
	DEAD TEMPERATURE :	Function			xponen	it	•	1	Mantiss	a							
8D	READ_TEMPERATURE_1	Default Value	İ				able	•									
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r	r	r	r	r	r	r	r							
		Function					tissa	1	ı	1							
		Default Value					able										
		Returns the module	PWM c	ontrolle	r tempe												
		Format		L	inear, t	wo's cor	npleme	nt binar	У								
		Bit Position	15	14	13	12	11	10	9	8							
		Access	r	r	r	r	r	r	r	r							
		Function	<u> </u>		xponen	L			 Mantiss	I							
8E	READ_TEMPERATURE_2	Default Value	1		porici		able	<u>'</u>	.10111133								
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r	r	r	r	r	r	r								
		Function	<del>- '</del>	_ '	_ '		itissa	<u>'</u>	_ '	r							
			-														
		Default Value	<u> </u>			vari	able										

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Setup	Hex Code	Command	Brief Description									Non-Volatile Memory Storage	
Format	Code												Welliory Storage
Bit Position   15   14   13   12   11   10   0   8   8     Access   7   7   7   7   7   7   7     Function			I	g of two									
Access													
Function							_						
Default Value	05	DEAD EDECLIENCY		r	r	r			r	r	r		
Bit Position	95	READ_FREQUENCY		_	١ ٥	Ι ο	1	· -		0	1		
Access   r   r   r   r   r   r   r   r   r													
Pinction						-	1						
Default Value													
Returns one byte indicating the module is compliant to PMBus Spec 1.1				1	0	0			0	0	0		
PMBUS_REVISION			Returns one byte in	dicating	the mo	dule is	compliar	nt to PM	Bus Spe	c. 1.1			
Second				Ι									
Default Value	98	PMBUS_REVISION	Bit Position	7	6					1	0		YES
Value used to program specific proportional coefficient of the PID compensation Block. Do not use value higher than 10922			Access	r	r	r	r	r	r	r	r		
Do not use value higher than 10922			Default Value	0	0	0	1	0	0	0	1		
Bit							al coeffic	cient of	the PID	comper	sation B	lock.	
Bit Position   15				her tha									
Access													
Function											_		
Default Value   Sariable   Bit Position   7   6   5   4   3   2   1   0   0				r/w	r/w	r/w			r/w	r/w	r/w		
Bit Position   7   6   5   4   3   2   1   0     Access   r/w   r/w   r/w   r/w   r/w   r/w   r/w   r/w   r/w     Function	В0	MFR_SPECIFIC_KP						_					YES
Access   r/w   r				-		T -	1		_	1			
Function   Integer   Variable   Value used to program specific integral coefficient of the PID compensation Block.													
Default Value				1/W	I/W	1/W			1/W	I/W	1/W		
Value used to program specific integral coefficient of the PID compensation Block.   Do not use value higher than 10922.   Format   Linear, two's complement binary   Bit Position   15   14   13   12   11   10   9   8     Access   r/w   r/				ÿ									
Bit Position   15   14   13   12   11   10   9   8				am sneo	rific into	aral coe			ID comr	onsatio	n Block		
Bit Position   15   14   13   12   11   10   9   8							inclent	or the r	ib comp	)CIISatic	III DIOCK.		
Bit Position   15													
Function				15							8		
Default Value			Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
Default Value   Survival   Surv	D1	MED CDECIFIC KI									VEC		
Access   r/w   r	PI	MFR_SPECIFIC_KI	5								163		
Function			Bit Position	7	6	5	4		2	1	0		
Default Value			Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
Value used to program specific differential coefficient of the PID compensation. Do not use value higher than 10922   Format								_					
Bit Position   15   14   13   12   11   10   9   8			Default Value				Vari	able					
Bit Position   15   14   13   12   11   10   9   8			Value used to press	am cno	ific diff	arential	coefficia	ant of th	DID or	mnono	ation D	o not	
Bit Position   15				-		erential	COEITICIE	ent of th	וכ רוט ל(	nipens	ation. D	o not	
Bit Position   15   14   13   12   11   10   9   8				1052		Linear. t	wo's cor	npleme	nt binar	V			
MFR_SPECIFIC_KD				15							8		
B2													
Bit Position   7   6   5   4   3   2   1   0	B2	MFR_SPECIFIC_KD				•		•					VEC
Access   r/w   r		_	Default Value				Vari	able					155
Function   Integer   Variable			Bit Position										
Default Value				r/w	r/w	r/w		•	r/w	r/w	r/w		
Value used to program specific alpha value of the PID compensation block     Format								_					
Format   Linear, two's complement binary					:::: ! ·!	L U				انتامان			
Bit Position   15   14   13   12   11   10   9   8			value used to progr	am spec	citic alph	na value	of the P	וי comן	pensatio	n block			
Bit Position   15   14   13   12   11   10   9   8			Format		-	Linear. t	wo's cor	npleme	nt binar	v			
Access   r/w   r				15							8		
Function   Integer   YES											_		
Default Value	В3	MFR SPECIFIC ALPHA				, ,							YES
Bit Position         7         6         5         4         3         2         1         0           Access         r/w         r/w         r/w         r/w         r/w         r/w         r/w         r/w           Function         Integer								_					
Function Integer				7	6	5			2	1	0		
Function Integer			Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
Default Value Variable			Function				Inte	eger					
			Default Value				Vari	able	-				

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex			ı a	516 <del>1</del>		inuea)						Non-Volatile
Code	Command											Memory Storage
		Returns module name information (read only)										
		Format				Unsigne	d Binary	/	_			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r	r		
	145D 0050:5:0 00	Function				Rese	rved					\/F5
D0	MFR_SPECIFIC_00	Default Value	0	0	0	0	0	0	0	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function				e Name	•			served		
		Default Value	0	0	1	1	0	1	0	0		
		Delault Value	U	U		1		1	U	U		
		Applies an offset to	the READ	_vou	Γ comm	and res	ults to c	alibrate	out of	fset error	s in module	
		neasurements of the output voltage (between -125mV and +124mV). Exponent is fixed at -14.										
		Format				wo's cor						
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
D4	MFR_READ_VOUT_CAL_OF	Function			•	Man	tissa			1 -		YES
-	FSET	Default Value		Var	riable h	ased on		calibrat	ion			. 20
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	.,	٠, ••	., **		itissa	., **	., ••	, , vv		
		Default Value		Var	riahla h	ased on		calibrat	ion			
		Delault Value	<u> </u>	vai	. מאוכ ט		. actor y	Junioral	.011		<u> </u>	
		Applies a gain correc	ction to t	he REA	D_VOU	T comm	and res	ults to c	alibrat	e out gair	n errors in	
		module measureme	nts of the	e outpu	ıt volta	ge. The	number	in this r	egiste	r is divide	d by 8192 to	
		generate the correct	tion facto	or.								
	MFR_READ_VOUT_CAL_GA IN	Format		L	inear, t	wo's cor	npleme	nt binar	У			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
D5		Function	- 1		•		eger					YES
		Default Value		Var	riable h	ased on		calibrat	ion			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	.,	.,	.,		eger	., **	., ••	., ••		
		Default Value		\/aı	riahle h	ased on		calibrat	ion			
<del></del>		Applies an offset to	the com							rs in setti	ı ng module	
		output voltage (bety				_					•	
		14.		uill		.,	3311B 1		J. C. I.	ponent	ut	
		Format		1	inear t	wo's cor	nnleme	nt hinar	v			
		Bit Position	15	14	13	12	11	10	y 9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
D7	MFR_VOUT_CAL_OFFSET	Function	1 / VV	1 / VV	1 / W		tissa	1 / VV	1 / VV	1 / W		YES
				1/6	ا ماطونا			calibest	ion			
		Default Value	-, T	-		ased on				1 ^		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa	19	•			
<u> </u>		Default Value				ased on						VEC
		Bit 7 used to determ			-	_		-		_		YES
		Bit 7: 1 – Output vo	U	olely se	et by R1	rım valı	ue and c	an be a	ajuste	a from set	value using	
		the VOUT_TRIM co		-1.1		S.I. =				at		
		Bit 7: 0 – Output vo	_	•	•	OU I_CO	IVIMANI	and ca	in be a	ajusted fr	om set	
1		value using the VOI	_								0.0.1055	
		Bit 0: Used to indica			_						-	
		levels, margin level				_		-				
D8	MFR VOUT SET MODE	more of the values	nave cha	inged f	rom the	e detault	. If this	oit is 0,	tnen t	ne detault	values are	
-		used.										
		Format				Uns	igned B	inary				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/v	_		r/w		r/w	r/w	,	
			VOUT_	SF						-		
		Flag	T MOI	. x	Х	Х	X	Х	Х	USER_CH	ANGES	
		Dofoult Value	_	0	0	0	0	0	0	^		
		Default Value	1	U	U	U	U	U	U	0		

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### Table 4 (Continued)

Volatile ry Storage
/ES
/ES
/ES
/ES

### SMBALERT# is also triggered:

- when an invalid/unrecognized PMBus command (write or read) is issued
- By invalid PMBus data (write)
- By PEC Failure (when used)
- By Enable OFF (when used)
- Module is out of Power Good Range

### **Digital Power Insight (DPI)**

GE offers a software tool that set helps users evaluate and simulate the PMBus performance of the TJT120A modules without the need to write software.

The software can be downloaded for free at <a href="http://go.ge-energy.com/DigitalPowerInsight.html">http://go.ge-energy.com/DigitalPowerInsight.html</a>. A GE USB to I2C adapter and associated cable set are required for proper functioning of the software suite. For first time users, the GE DPI Evaluation Kit can be purchased from leading distributors at a nominal price and can be used across the entire range of GE Digital POL Modules.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### **Thermal Considerations**

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 37. The preferred airflow direction for the module is in Figure 38.

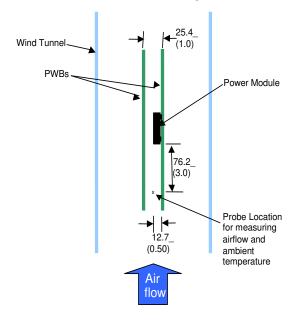


Figure 37. Thermal Test Setup.

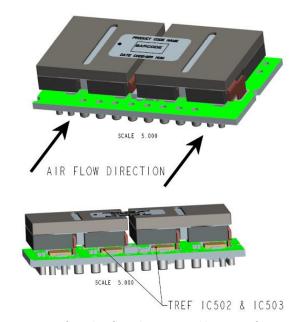


Figure 38. Preferred airflow direction and location of hotspots of the module (Tref).

The thermal reference points,  $T_{ref}$  used in the specifications are also shown in Figure 38. For reliable operation the temperatures at these points should not exceed 120°C. The output power of the module should not exceed the rated power of the module (Vo,set x Io,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### **Example Application Circuit**

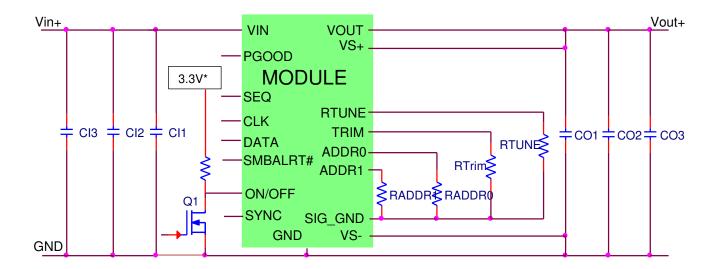
#### **Requirements:**

Vin: 12V Vout: 1.2V

lout: 120A max., worst case load transient is from 60A to 90A, 10A/usec

ΔVout: 25mV for worst case load transient

Vin, ripple 2% of Vin (240mV p-p)



 $3.3V^*$  can be derived from Vin through a suitable voltage divider network

CI1 4 x 0.047 µF (high-frequency decoupling ceramic capacitor)

CI2 12 x 22 µF Ceramic

CI3  $4 \times 470 \mu F$  (polymer or electrolytic)

CO1 4 x 0.047 μF (high-frequency decoupling ceramiccapacitor)

CO2 12 x 47 μF, Ceramic CO3 7 x 1000 μF RTune 2460 $\Omega$ , RTrim 5.9K $\Omega$ 

Note: The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the PMBus master controller will have pull-up resistors as well as provide the driving source for these signals.

If running the simulation at ge.transim.com remember to use bin 'a' parameters to determine the Loop Stability, and bin 'b' parameters to determine the transient response.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

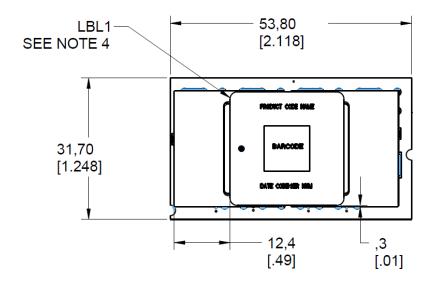
4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

### **Mechanical Outline (SMT)**

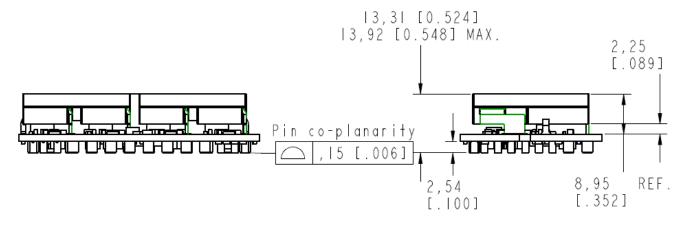
Dimensions are in millimeters and (inches).

Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]

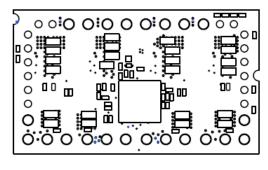
x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)



**TOP VIEW** 



FRONT VIEW SIDE VIEW



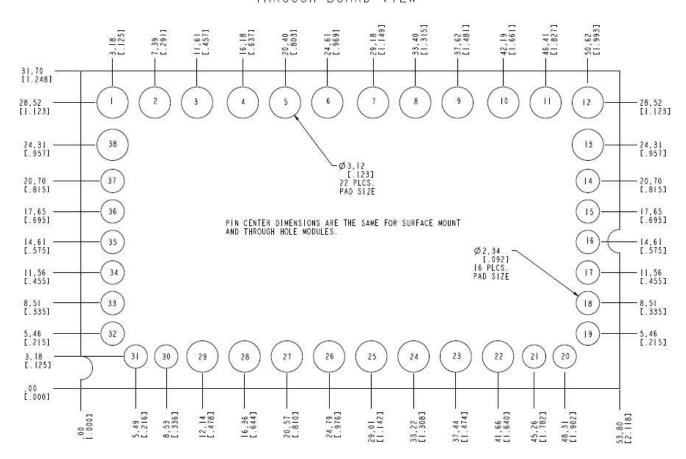
**BOTTOM VIEW** 

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

### **Recommended SMT Pad Layout**

# RECOMMENDED SMT FOOTPRINT -THROUGH BOARD VIEW -



PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	VOUT	15	PWR_GOOD	29	VIN
2	VOUT	16	RTUNE	30	N/A
3	GND	17	TRIM	31	SHARE/NC
4	VOUT	18	SEQ	32	ON/OFF
5	VOUT	19	SIG_GND	33	SMBALERT#
6	GND	20	VS+	34	DATA
7	VOUT	21	VS-	35	CLK
8	VOUT	22	GND	36	ADDR0
9	GND	23	VIN	37	ADDR1
10	VOUT	24	GND	38	GND
11	VOUT	25	VIN		
12	GND	26	GND		
13	GND	27	VIN		
14	SYNC	28	GND		

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

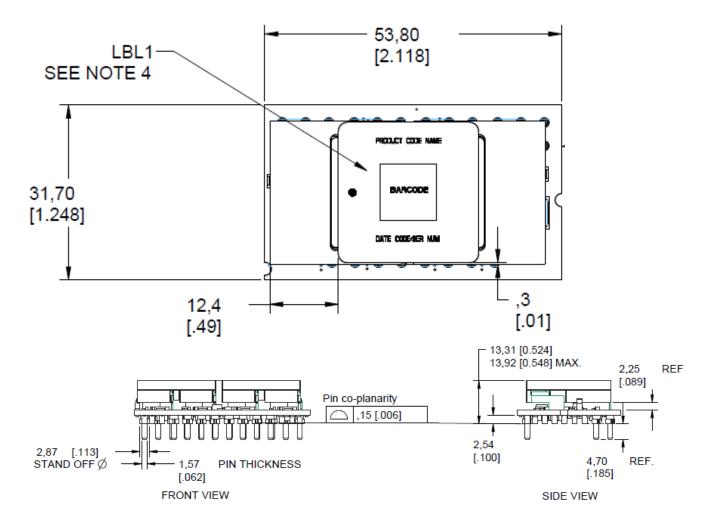
4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

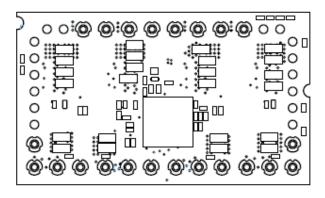
### **Mechanical Outline (Through hole)**

Dimensions are in millimeters and (inches).

Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]

x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)



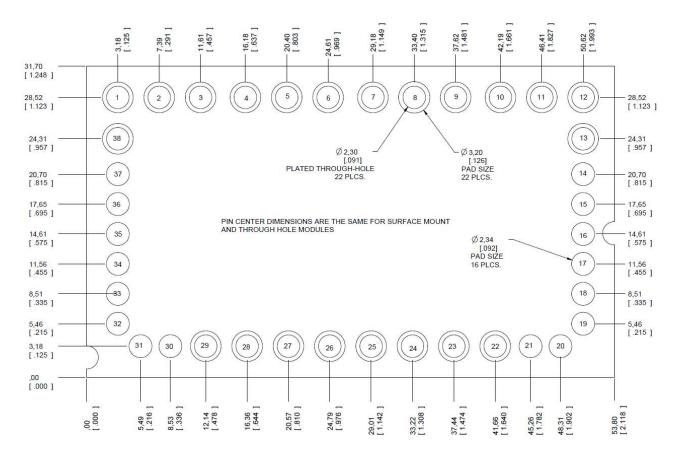


**BOTTOM VIEW** 

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

### **Recommended Through-hole Layout**



Note: In the Through-Hole version of the TJT120, pins 1-13, 22-29 and 38 are Through-Hole pins, pins 14-21, 30-37 are SMT pins. The drawing above shows the recommended layout as a combination of holes in the PWB to accommodate the Through-Hole pins and pads on the top layer to accommodate the SMT pins.

PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	VOUT	15	PWR_GOOD	29	VIN
2	VOUT	16	RTUNE	30	N/A
3	GND	17	TRIM	31	SHARE/NC
4	VOUT	18	SEQ	32	ON/OFF
5	VOUT	19	SIG_GND*	33	SMBALERT#
6	GND	20	VS+	34	DATA
7	VOUT	21	VS-	35	CLK
8	VOUT	22	GND	36	ADDR0
9	GND	23	VIN	37	ADDR1
10	VOUT	24	GND	38	GND
11	VOUT	25	VIN		
12	GND	26	GND		
13	GND	27	VIN		
14	SYNC	28	GND		

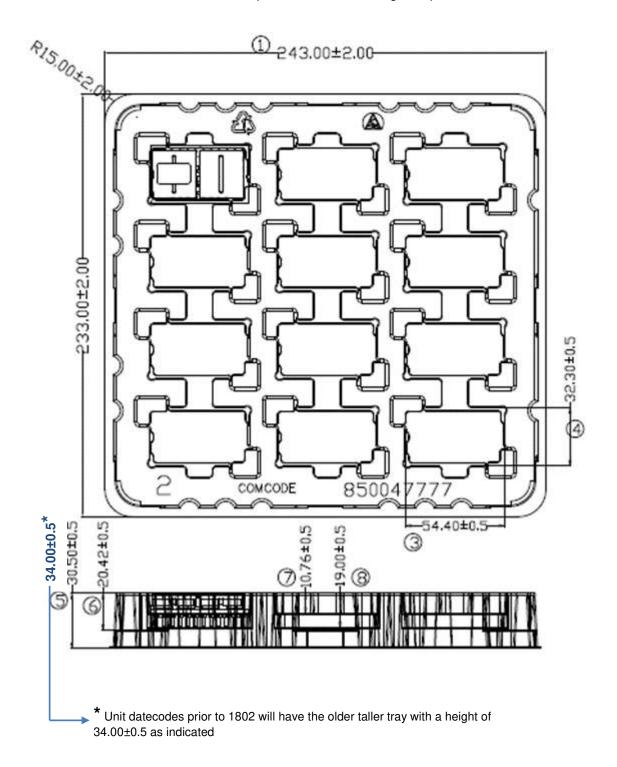
<sup>\*</sup>Do not connect SIG\_GND to any other GND paths. It needs to be kept separate from other grounds on the board external to the module

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

### **Packaging Details**

The 120A TeraDLynx<sup>™</sup> modules are supplied in trays. Modules are shipped in quantities of 12 modules per layer, 24 per box. All Dimensions are in millimeters. All radius unspecified are R2.0mm. All angles unspecified are 5°.



## 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### **Surface Mount Information**

#### **Pick and Place**

The 120A TeraDLynx™ modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

#### **Nozzle Recommendations**

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 15mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 22 mm.

#### **Bottom Side / First Side Assembly**

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

#### **Lead Free Soldering**

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

#### **Pb-free Reflow Profile**

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 40. Soldering outside of the recommended profile requires testing to verify results and performance.

#### **MSL Rating**

The 120A TeraDLynx<sup>™</sup> modules have a MSL rating of 3.

#### **Storage and Handling**

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is

broken, the floor life of the product at conditions of  $\leq 30^{\circ}$ C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions:  $< 40^{\circ}$  C, < 90% relative humidity.

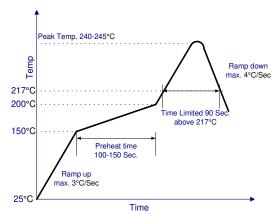


Figure 39. Recommended linear reflow profile using Sn/Ag/Cu solder.

#### **Post Solder Cleaning and Drying Considerations**

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to *Board Mounted Power Modules: Soldering and Cleaning* Application Note (ANO4-001).

#### **Through Hole Information**

The 120A TeraDLynx<sup>TM</sup> modules are lead-free (Pb-free) and RoHS compliant and fully compatible in an Pb-free soldering process. For the through-hole application, it is recommended that the modules are assembled in the pin and paste reflow process, not in the wave solder process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

# 120A TeraDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

#### **Ordering Information**

Please contact your GE Sales Representative for pricing, availability and optional features.

**Table 5. Device Codes** 

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Interconnect	Comcodes
TJT120A0X3Z#	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Negative	TH	150043982
TJT120A0X43Z#	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Positive	TH	150049601
TJT120A0X3-SZ#	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Negative	SMT	150041745
TJT120A0X43-SZ#	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Positive	SMT	150049603

<sup>-</sup>Z refers to RoHS compliant parts

\*TJT120A0X3-SZ, TJT120A0X3Z, TJT120A0X43-SZ, and TJT120A0X43Z are End of Life (EOL). Last Time Buy September 30, 2020. Orders after September 30, 2020 will continue to be accepted until supplies last.

**Table 6. Coding Scheme** 

Package Identifier	Family	Sequencing Option	Output current	Output voltage	On/Off logic	Remote Sense	Options		ROHS Compliance
T	J	Т	120A0	Х		3	-SR	+	Z
P=Pico U=Micro M=Mega G=Giga T=Tera	J = DLynx II	T=with EZ Sequence X=without sequencing	120A	X = programm able output	4 = positive No entry = negative	3 = Remote Sense	S = Surface Mount R = Tape & Reel No entry = Through hole	Extra Ground Pins	Z = ROHS6

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