

### FEATURES

- Dual Measurement Channels**
- Precision Four-Quadrant-Per-Pin V/I Source**
- Programmable Current Force Ranges**  
 $\pm 204.8 \mu\text{A}$  and  $\pm 2.048 \text{ mA}$
- Five Current Measurement Ranges**  
 $204.8 \text{ nA}$  to  $\pm 2.048 \text{ mA}$
- Output Voltage Range:  $-4 \text{ V}$  to  $+9 \text{ V}$**
- Power Supplies:  $+15 \text{ V}$ ,  $+5 \text{ V}$ , and  $-10 \text{ V}$**
- 44-Lead Plastic J-Leaded Chip Carrier Package**

### APPLICATIONS

- Can Be Used with the AD53032 DCL to Extend Current Force Range to  $35 \text{ mA}$**

### GENERAL DESCRIPTION

The AD53508 is a custom dual-channel parametric measurement circuit for use in semiconductor automatic test equipment. It contains programmable modes to force a pin voltage and measure its current or to integrate and hold a current value. Alternatively, a current can be forced and the compliance voltage measured.

The device provides a remote force/sense capability to ensure accuracy at the tester pin. A guard output is available to drive the shield of a force/sense pair.

Two input references per channel permit controlled switching to different voltage or current levels. The forced voltage or current levels can be switched back to the measurement system to read back the analog levels for system calibration.

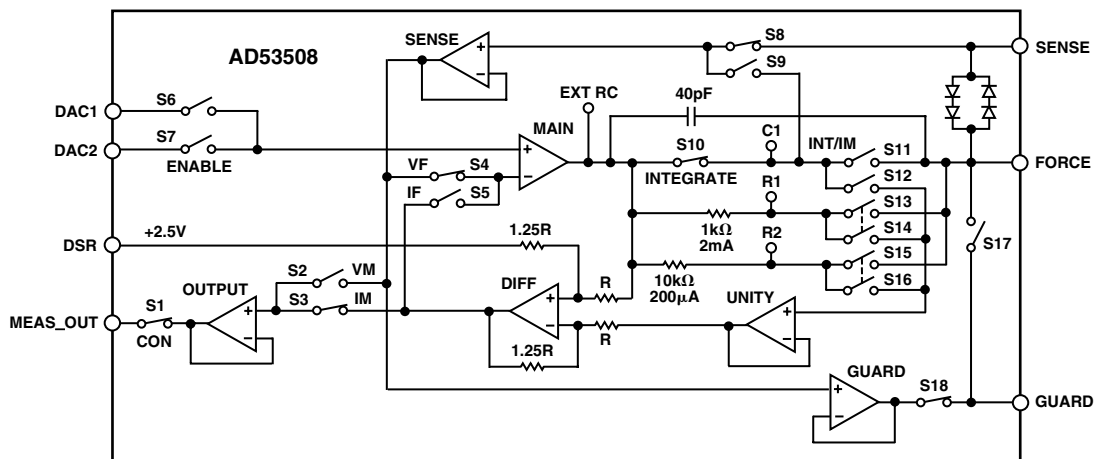
The circuit is powered by  $+15 \text{ V}$ ,  $+5 \text{ V}$ , and  $-10 \text{ V}$  supplies and dissipates  $230 \text{ mW}$  nominally.

### Recommended Use of the PPMU with AD53032 DCL

The PPMU can be used with the AD53032 DCL to extend the Current Force Range beyond  $2 \text{ mA}$ . VCOM can be set to the maximum spec allowance of  $8 \text{ V}$ , which would allow the maximum Current Force of IOL of  $35 \text{ mA}$ . The combination of the PPMU and the DCL would have a few benefits including:

1. Accurately measuring low currents.
2. Can take parallel measurements by using one PMU per pin.

### FUNCTIONAL BLOCK DIAGRAM



### REV. A

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# AD53508—SPECIFICATIONS (T<sub>A</sub> = 25°C, rated power supplies unless otherwise noted.)

Parameter	Condition	Min	Typ	Max	Unit <sup>1</sup>
VOLTAGE FORCE/MEASURE MODE Voltage Swing, ±2 mA Range ±2 mA Drive ±100 μA Drive		-4 -5		+9 +12	V V
ACCURACY Gain (±0.1% Tolerance) Offset Error Gain Nonlinearity (Relative to Endpoints) Current Measure CMRR (at MEAS_OUT)		0.999		1.001 ±15 ±0.02 ±0.31	V/V mV % of Span mV/V
DRIFT Gain Error Temperature Coefficient  Offset Drift				±20  ±100	ppm (PV or MV)/°C  μV/°C
CURRENT FORCE/MEASURE MODE RANGES 0 (High) 1 (Low)			±2.0 ±200		mA μA
ACCURACY—HIGH RANGE Transconductance (±3% Tolerance) Transresistance (±3% Tolerance) Offset Error Gain Nonlinearity (Relative to Endpoints) Output Compliance Voltage-Induced Transconductance/Error	Force Mode Measure Mode   Force Mode	0.776 1.21	0.8 1.25	0.824 1.29 ±40 ±0.05 +0.4	mA/V V/mA μA % of Span μA/V
DRIFT—HIGH RANGE Gain Error Temperature Coefficient  Offset Drift				+10/-60  ±400	ppm (PV or MV)/°C  nA/°C
ACCURACY—LOW RANGE Transconductance (±3% Tolerance) Transresistance (±3% Tolerance) Offset Error Gain Nonlinearity (Relative to Endpoints) Output Compliance Voltage-Induced Transconductance/Error	Force Mode Measure Mode   Force Mode	77.6 12.1	80 12.5	82.4 12.9 ±4 ±0.05 +0.04	μA/V V/mA μA % of Span μA/V
DRIFT—LOW RANGE Gain Error Temperature Coefficient  Offset Drift				+10/-60  ±40	ppm (PV or MV)/°C  nA/°C
CURRENT MEASURE INTEGRATE MODE RANGES High Medium Low			±20.0 ±2.0 ±200		μA μA nA
ACCURACY—HIGH RANGE Transresistance Error (±3% Tolerance) Offset Error Gain Nonlinearity (Relative to Endpoints) Output Compliance Voltage-Induced Transresistance Error		0.121	0.125	0.129 ±400 ±0.05 ±2.5	V/μA nA % of Span nA/V of Output
DRIFT—HIGH RANGE Gain Error Temperature Coefficient Offset Drift				±20 ±2	ppm MV/°C nA/°C
ACCURACY—MEDIUM RANGE Transresistance Error (±3% Tolerance) Offset Error Gain Nonlinearity (Relative to Endpoints) Output Compliance Voltage-Induced Transresistance Error		1.21	1.25	1.29 ±40 ±0.05 ±0.25	V/μA nA % of Span nA/V of Output
DRIFT—MEDIUM RANGE Gain Error Temperature Coefficient Offset Drift				±20 ±250	ppm MV/°C pA/°C

Parameter	Condition	Min	Typ	Max	Unit <sup>1</sup>
ACCURACY—LOW RANGE					
Transresistance Error ( $\pm 3\%$ Tolerance)		0.0121	0.0125	0.0129	V/nA
Offset Error				$\pm 4$	nA
Gain Nonlinearity (Relative to Endpoints)				$\pm 0.05$	% of Span
Output Compliance Voltage-Induced Transresistance Error				$\pm 0.025$	nA/V of Output
DRIFT—LOW RANGE					
Gain Error Temperature Coefficient				$\pm 20$	ppm MV/°C
Offset Drift				$\pm 70$	pA/°C
DISABLE MODE <sup>2</sup>					
Voltage Swing, $\pm 2$ mA Range					V
$\pm 2$ mA Drive		-4		+9	V
$\pm 100$ $\mu$ A Drive		-5		+12	V
ACCURACY					
Gain ( $\pm 0.1\%$ Tolerance)		0.999		1.001	V/V
Offset Error				$\pm 15$	mV
Gain Nonlinearity (Relative to Endpoints)				$\pm 0.02$	% of Span
Current Measure CMRR (at MEAS_OUT)				$\pm 0.31$	mV/V
DRIFT					
Gain Error Temperature Coefficient				$\pm 20$	ppm (PV or MV)/°C
Offset Drift				$\pm 100$	$\mu$ V/°C
OTHER SPECIFICATIONS					
Power Supply Rejection Ratio	$f < 40$ Hz, $V_{CC}$	70			dB
	$f < 40$ Hz, $V_{EE}$	60			dB
	$f = 40$ kHz, $V_{CC}$	35			dB
	$f = 40$ kHz, $V_{EE}$	25			dB
CURRENT MEASURE HOLD MODE LEAKAGE	$T_{AMB} = 70^\circ\text{C}$			$\pm 1.2$	nA
CROSSTALK <sup>3</sup>				$\pm 0.02$	% of Span
SETTLING TIMES TO 0.01%					
Voltage Force and Guard Voltage	$C_{LOAD} = 100$ pF			20	$\mu$ s
	$C_{LOAD} = 2000$ pF			2	ms
Current Force (200 $\mu$ A Range)	$Z_{LOAD} = 100$ pF  50 k $\Omega$			50	$\mu$ s
MEAS_OUT Pin	$C_{LOAD} = 20$ pF			2	$\mu$ s
SHORT CIRCUIT CURRENT LIMIT MAGNITUDE	Any Output Except Guards	8.5		20	mA
GUARD SCC LIMIT MAGNITUDE		2.5		10	mA
GUARD OFFSET (FROM SENSE INPUT PIN)		-65	-25	0	mV
$I_B$ (DAC1, DAC2) CURRENT				$\pm 1.0$	$\mu$ A
DIGITAL INPUTS					
$V_{IH}$		2.4			V
$V_{IL}$				0.8	V
$I_{IN}$ (Input leakage current)				10	$\mu$ A
POWER SUPPLIES					
$V_{CC}$ (Positive Analog Supply Voltage)		14.0	15.0	15.75	V
$V_{EE}$ (Negative Analog Supply Voltage)		-10.5	-10.0	-9.0	V
$V_{DD}$ (Logic Supply Voltage)		4.75	5.0	5.25	V
$I_{CC}$ (Positive Analog Supply Current)		5		15	mA
$I_{EE}$ (Negative Analog Supply Current)		-15		-5	mA
$I_{DD}$ (Logic Supply Current Is 0 with Inputs at Rails, Worst Case @ 2.4 $V_{IN}$ )				8	mA

## NOTES

<sup>1</sup>PV = Programmed Value, MV = Measured Value, FSR = Full-Scale Range = span.

<sup>2</sup>Output connected: DAC2 and 2 mA range selected, unconditionally.

<sup>3</sup> $f < 40$  Hz, both channels in current force mode; other channel output voltage swinging rail to rail.

Specifications subject to change without notice.

# AD53508

## ABSOLUTE MAXIMUM RATINGS\*

(T<sub>A</sub> = 25°C unless otherwise noted)

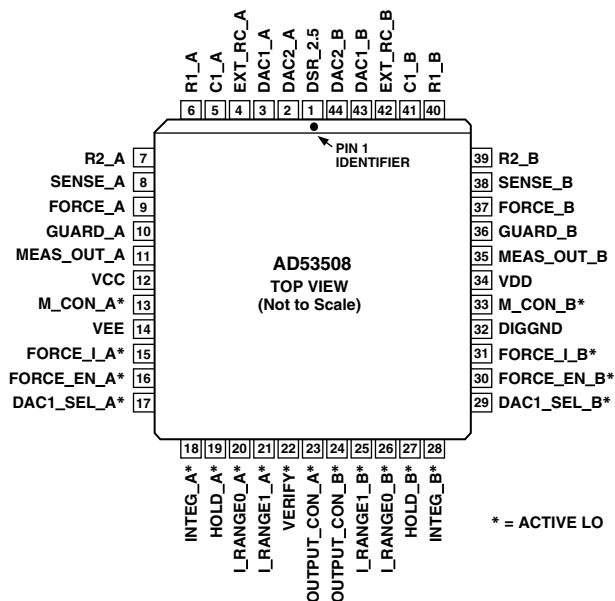
	Min	Max	Unit	Condition
VDD to VEE	-0.3	+26.4	V	T <sub>A</sub> ≤ 75°C
VCC to VEE	-0.3	+26.4	V	
VDD to DGND	-0.3	+6	V	
Digital Inputs to DGND	-0.3	VCC+0.3	V	
Power Dissipation		700	mW	
Operating Temperature Range	25	70	°C	
Storage Temperature	-60	+125	°C	
Lead Temperature		300	°C	
Force/Sense Outputs	VEE-0.8	VCC+0.8	V	

\*Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only; functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ORDERING GUIDE

Model	Temperature Range	Package Description	Package Option
AD53508JP	25°C to 70°C	Plastic Leaded Chip Carrier	P-44A

## PIN CONFIGURATION



## PIN FUNCTION DESCRIPTIONS

Pin	Name	Description
1	DSR_2.5	2.5 V Reference Input
2	DAC2_A	First of Two Switchable Inputs
3	DAC1_A	Second of Two Switchable Inputs
4	EXT_RC_A	External R <sub>S</sub> and C Common
5	C1_A	External Capacitor
6	R1_A	External Resistor
7	R2_A	External Resistor
8	SENSE_A	Sense Input
9	FORCE_A	Force Output
10	GUARD_A	Guard Drive Output
11	MEAS_OUT_A	Measurement Output
12	VCC	+15 V Analog Supply
13	M_CON_A*	Connect Measure Output to Bus
14	VEE	-10 V Analog Supply
15	FORCE_I_A*	Force V (When Hi) or I (When Lo)
16	FORCE_EN_A*	Control Input
17	DAC1_SEL_A*	Select DAC1 (When Lo) or DAC2
18	INTEG_A*	Control Input
19	HOLD_A*	Control Input
20	I_RANGE0_A*	Select 2 mA Range (Active Lo)
21	I_RANGE1_A*	Select 200 µA Range (Active Lo)
22	VERIFY*	Measure Forced Voltage or Current
23	OUTPUT_CON_A*	Connect Pin Drive (Active Lo)
24	OUTPUT_CON_B*	Connect Pin Drive (Active Lo)
25	I_RANGE1_B*	Select 200 µA Range (Active Lo)
26	I_RANGE0_B*	Select 2 mA Range (Active Lo)
27	HOLD_B*	Control Input
28	INTEG_B*	Control Input
29	DAC1_SEL_B*	Select DAC1 (When Lo) or DAC2
30	FORCE_EN_B*	Control Input
31	FORCE_I_B*	Force V (When Hi) or I (When Lo)
32	DIGGND	Digital Ground
33	M_CON_B*	Connect Measure Output to Bus
34	VDD	+5 V Digital Supply
35	MEAS_OUT_B	Measurement Output
36	GUARD_B	Guard Drive Output
37	FORCE_B	Force Output
38	SENSE_B	Sense Input
39	R2_B	External Resistor
40	R1_B	External Resistor
41	C1_B	External Capacitor
42	EXT_RC_B	External R <sub>S</sub> and C Common
43	DAC1_B	Second of Two Switchable Inputs
44	DAC2_B	First of Two Switchable Inputs

\* = Active Lo

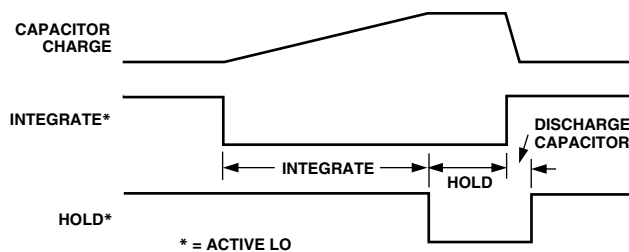
## CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD53508 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high-energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



**Table I. Data Table**

Data Latch Bits			S4	S5	S6	S7	S9	S17	S8	S10	S13, S14	S15, S16	S11	S12	S18
S1	S2	S3													
Voltage Force/Current Measure															
Range 0			On	Off	On	Off	On	Off	On	On	On	Off	Off	Off	On
Range 1			On	Off	On	Off	On	Off	On	On	Off	On	Off	Off	On
Integrate Range			On	Off	On	Off	On	Off	On	On	Off	Off	On	On	On
Integrate			On	Off	On	Off	On	Off	On	Off	Off	Off	On	On	On
Hold/Measure			On	Off	On	Off	On	Off	On	Off	Off	Off	On	On	On
Current Force/Voltage Measure															
Range 0			On	On	Off	Off	On	On	On	On	On	Off	Off	Off	On
Range 1			On	On	Off	Off	On	On	On	On	Off	On	Off	Off	On
Disable Mode: Output Connected			X	X	X	On	Off	Off	On	X	On	Off	Off	Off	On
Verify/Voltage Force			On	On	Off	On	Off	Off	Off	On	On	Off	Off	Off	On
Verify/Current Force			On	Off	On	Off	On	Off	Off	On	On	Off	Off	Off	On
Disconnect			X	X	X	On	Off	X	X	On	Off	Off	Off	On	Off
DAC2 Select: Enabled			X	X	X	X	X	Off	On	X	X	X	X	X	X



*Figure 1. Integrate/Current Measure Timing Diagram*

**Table II. Truth Table**

* = Active LO	FV/MI 2 mA		FV/MI 200 mA		FV/MI Integrate DAC1			FV/MI Integrate DAC 2			FI/MV 2 mA		FI/MV 200 µA		FV/Verify		FI/Verify		Disconnect	Disable	
Control Input	DAC1	DAC2	DAC1	DAC2	Voltage Settle	Integrate	Hold	Voltage Settle	Integrate	Hold	DAC1	DAC2	DAC1	DAC2	DAC1	DAC2	DAC1	DAC2		Output Connected	
M_CON*	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	X	X
VERIFY*	HI	HI	HI	HI	HI	HI	HI	HI	HI	HI	HI	HI	HI	HI	LO	LO	LO	LO	LO	X	X
FORCE_I*	HI	HI	HI	HI	HI	HI	HI	HI	HI	HI	LO	LO	LO	LO	HI	HI	LO	LO	X	X	X
FORCE_EN*	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	X	HI
DAC1_SEL*	LO	HI	LO	HI	LO	LO	LO	HI	HI	HI	LO	HI	LO	HI	LO	HI	LO	HI	X	X	X
INTEG*	HI	HI	HI	HI	HI	LO	LO	HI	LO	LO	HI	HI	HI	HI	HI	HI	HI	HI	X	X	X
HOLD*	HI	HI	HI	HI	HI	HI	LO	HI	HI	LO	HI	HI	HI	HI	HI	HI	HI	HI	X	X	X
L_RANGE0*	LO	LO	HI	HI	HI	HI	HI	HI	HI	HI	LO	LO	HI	HI	X	X	X	X	X	X	X
L_RANGE1*	HI	HI	LO	LO	HI	HI	HI	HI	HI	HI	HI	HI	LO	LO	X	X	X	X	X	X	X
OUTPUT_CON*	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	LO	HI	LO

# AD53508

## PPMU APPLICATION NOTES

The PPMU can be used in two modes: 1. VOLTAGE FORCE with CURRENT MEASURE or VERIFY CURRENT FORCE; 2. CURRENT FORCE with VOLTAGE MEASURE or VERIFY VOLTAGE FORCE. In both modes the following setup is recommended:

1. The value of the external integrate capacitor (EXT\_RC to C1) is 10 nF.
2. MEAS\_OUT pin is loaded with 1 MΩ to ground.
3.  $V_{CC} = 15.0\text{ V}$ ,  $V_{DD} = 4.5\text{ V}$ ,  $DIGGND = 0.0\text{ V}$ ,  $V_{EE} = -10\text{ V}$ ,  $DSR = 2.5\text{ V}$  unless otherwise stated.
4. A 10 Ω resistor in series with the FORCE pin.
5. A 1 kΩ resistor in series with the SENSE pin.

## IN VOLTAGE FORCE WITH CURRENT MEASURE OR VERIFY CURRENT FORCE

To measure the leakage in the current measure and hold mode, the PPMU has to be into the Force Voltage/Measure Current Integrate mode.

1. The FORCE\_A (Force Output) pin has to be programmed to 9 V.
2. The PPMU has to be programmed to INTEGRATE mode.
3. The PPMU has to be programmed to HOLD mode.
4. Sample MEAS\_OUT.
5. Wait 100 ms.
6. Sample MEAS\_OUT again.
7. The difference between 2 and 4 must be less than 15 mV.

The linearity tests for forcing voltage are as follows (at the FORCE pin):

1. The four ranges of CURRENT MEASURE ranges (200 nA, 20 μA, 200 μA, and 2 mA) correspond to F1, F2, F3, and F4.
2. The endpoints of the linearity curve are determined by -full scale (or LOW), and the +full scale (or HIGH) readings at the same FORCE pin current.
3. Using these endpoints, gain nonlinearity is computed and tested at the 1/4 scale, 1/2 scale, and 3/4 scale points.

4. Computations for F1 are:  
 $F1 \times 0.25 = \text{LOW} + 1 \times (\text{HIGH} - \text{LOW})/4$   
 $F1 \times 0.50 = \text{LOW} + 2 \times (\text{HIGH} - \text{LOW})/4$   
 $F1 \times 0.75 = \text{LOW} + 3 \times (\text{HIGH} - \text{LOW})/4$

Where LOW = -Full Scale and HIGH = +Full Scale.

The linearity tests for measuring current are as follows (at the MEAS\_OUT pin):

1. The voltage is constant for these measurements.
2. The four ranges (M1, M2, M3, M4) correspond to CURRENT MEASURE ranges (200 nA, 20 μA, 200 μA, and 2 mA respectively).
3. The endpoints of the linearity curve are determined by the -full scale (or LOW), and the +full scale (or HIGH) readings at the same FORCE pin voltage.
4. Using these endpoints, gain nonlinearity is computed and tested at the 1/4 scale, 1/2 scale, and 3/4 scale points.
5. Computations for M1 are:  
 $M1 \times 0.25 = \text{LOW} + 1 \times (\text{HIGH} - \text{LOW})/4$   
 $M1 \times 0.50 = \text{LOW} + 2 \times (\text{HIGH} - \text{LOW})/4$   
 $M1 \times 0.75 = \text{LOW} + 3 \times (\text{HIGH} - \text{LOW})/4$

Where LOW = -Full Scale, and HIGH = +Full Scale.

The M\_CON pin can be used for disconnecting the MEAS\_OUT pin by:

1. Raising M\_CON to 2.4 V.
2. Measuring MEAS\_OUT (which is loaded with 100 kΩ).
3. MEAS\_OUT should ideally be 0 V.

The OUTPUT\_CON pin can be used for disconnecting the DUT by:

1. Disabling the SENSE pin (OUTPUT\_CON = 2.4 V).
2. Loading FORCE\_OUT with 2 kΩ to ground.
3. Programming the DAC1 input to +FS (+9 V) and measuring the FORCE\_OUT voltage (FV1).
4. Programming the DAC1 input to -FS (-4 V) and measuring the FORCE\_OUT voltage (FV2).
5.  $FV1 - FV2 < 1.3\text{ mV}$ .
6. A change of 1.3 mV implies a switch off-resistance of 20 MΩ.

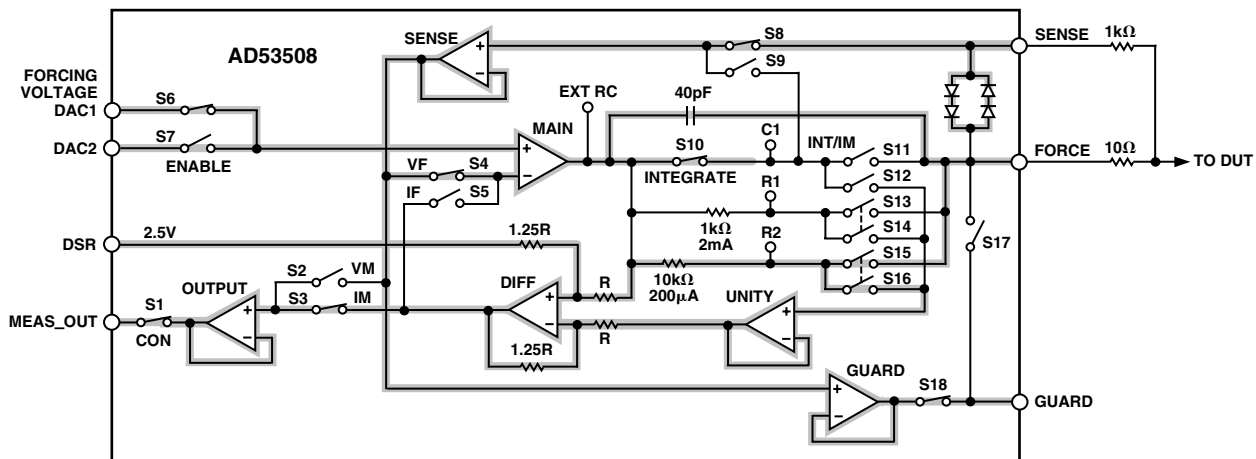


Figure 2. Guarded Voltage Force/Current Measure,  $I_{\text{RANGE } 1}: I \leq 2\text{ mA}$

### IN CURRENT FORCE WITH VOLTAGE MEASURE OR VERIFY CURRENT FORCE

The linearity tests for forcing current at the FORCE pin:

1. The FORCE pin is loaded with a voltage source.
2. The two ranges of CURRENT FORCE ranges (2 mA and 200  $\mu$ A) correspond to F1 and F2. The endpoints of the linearity curve are determined by full scale (or LOW), and the full scale (or HIGH) readings at the same FORCE pin voltage.
3. Using these endpoints, gain nonlinearity is computed and tested at the 1/4 scale, 1/2 scale, and 3/4 scale points.
4. Computations for F1 are:  
 $F1 \times 0.25 = LOW + 1 \times (HIGH - LOW)/4$   
 $F1 \times 0.50 = LOW + 2 \times (HIGH - LOW)/4$   
 $F1 \times 0.75 = LOW + 3 \times (HIGH - LOW)/4$

Where LOW = -Full Scale and HIGH = +Full Scale.

The linearity test for measuring voltage is as follows (at the MEAS\_OUT pin):

1. The endpoints of the linearity curve are determined by the -full scale (or LOW), and the +full scale (or HIGH) readings.
  2. Using these endpoints, gain nonlinearity is computed and tested at the 1/4 scale, 1/2 scale, and 3/4 scale points.
  3. Computations for M1 are:  
 $M1 \times 0.25 = LOW + 1 \times (HIGH - LOW)/4$   
 $M1 \times 0.50 = LOW + 2 \times (HIGH - LOW)/4$   
 $M1 \times 0.75 = LOW + 3 \times (HIGH - LOW)/4$
- Where LOW = -Full Scale, and HIGH = +Full Scale.

### CURRENT FORCE WITH VOLTAGE MEASURE (2 mA RANGE)

1. DAC1 = 5 V.
2. FORCE pin loaded with 9 V source.
3. Measure current at FORCE.
4. Measure voltage at MEAS\_OUT.
5.  $V_{CC} = 15$  V.
6. Measure current at FORCE and compare to 3.

7. Measure voltage at MEAS\_OUT and compare to 4.
8.  $V_{CC} = 15$  V.
9. DAC1 = 0 V.
10. FORCE pin loaded with -4 V source.
11. Measure current at FORCE.
12. Measure voltage at MEAS\_OUT.
13.  $V_{EE} = -9.5$  V.
14. Measure current at FORCE and compare to 11.
15. Measure voltage at MEAS\_OUT and compare to 12.
16.  $V_{EE} = -10$  V.

### VOLTAGE FORCE WITH CURRENT MEASURE (2 mA RANGE)

1. DAC1 = 9 V.
2. FORCE pin loaded with 2 mA current source.
3. Measure voltage at FORCE.
4. Measure current at MEAS\_OUT.
5.  $V_{CC} = 14.25$  V.
6. Measure voltage at FORCE and compare to 3:  
Limit =  $\pm 237$   $\mu$ V.
7. Measure current at MEAS\_OUT and compare to 4:  
Limit =  $\pm 237$   $\mu$ V.
8.  $V_{CC} = 15$  V.
9. DAC1 = -4 V.
10. FORCE pin loaded with 2 mA current sink.
11. Measure voltage at FORCE.
12. Measure current at MEAS\_OUT.
13.  $V_{EE} = -9.5$  V.
14. Measure voltage at FORCE and compare to 11:  
Limit =  $\pm 474$   $\mu$ V.
15. Measure current at MEAS\_OUT and compare to 12.
16.  $V_{EE} = -10$  V.

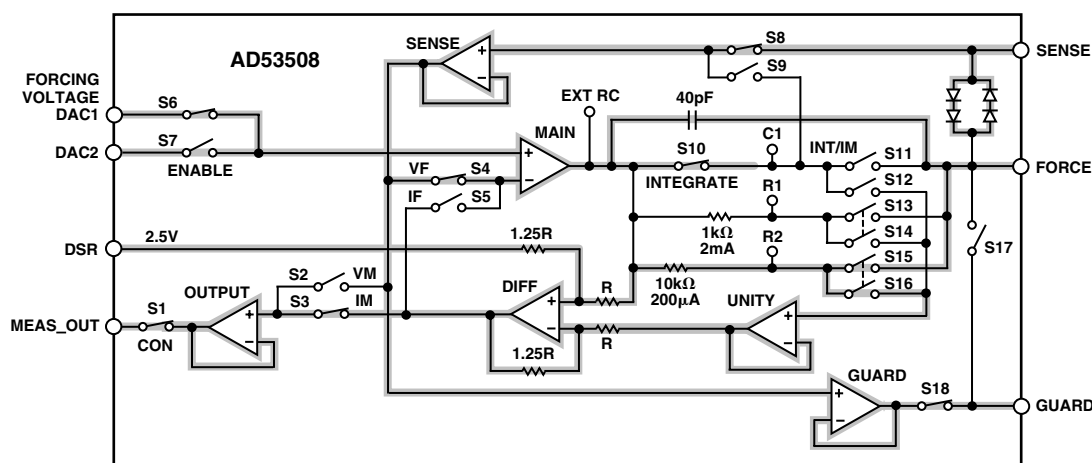


Figure 3. Guarded Current Force/Voltage Measure,  $I_{RANGE 1}: I \leq 2$  mA

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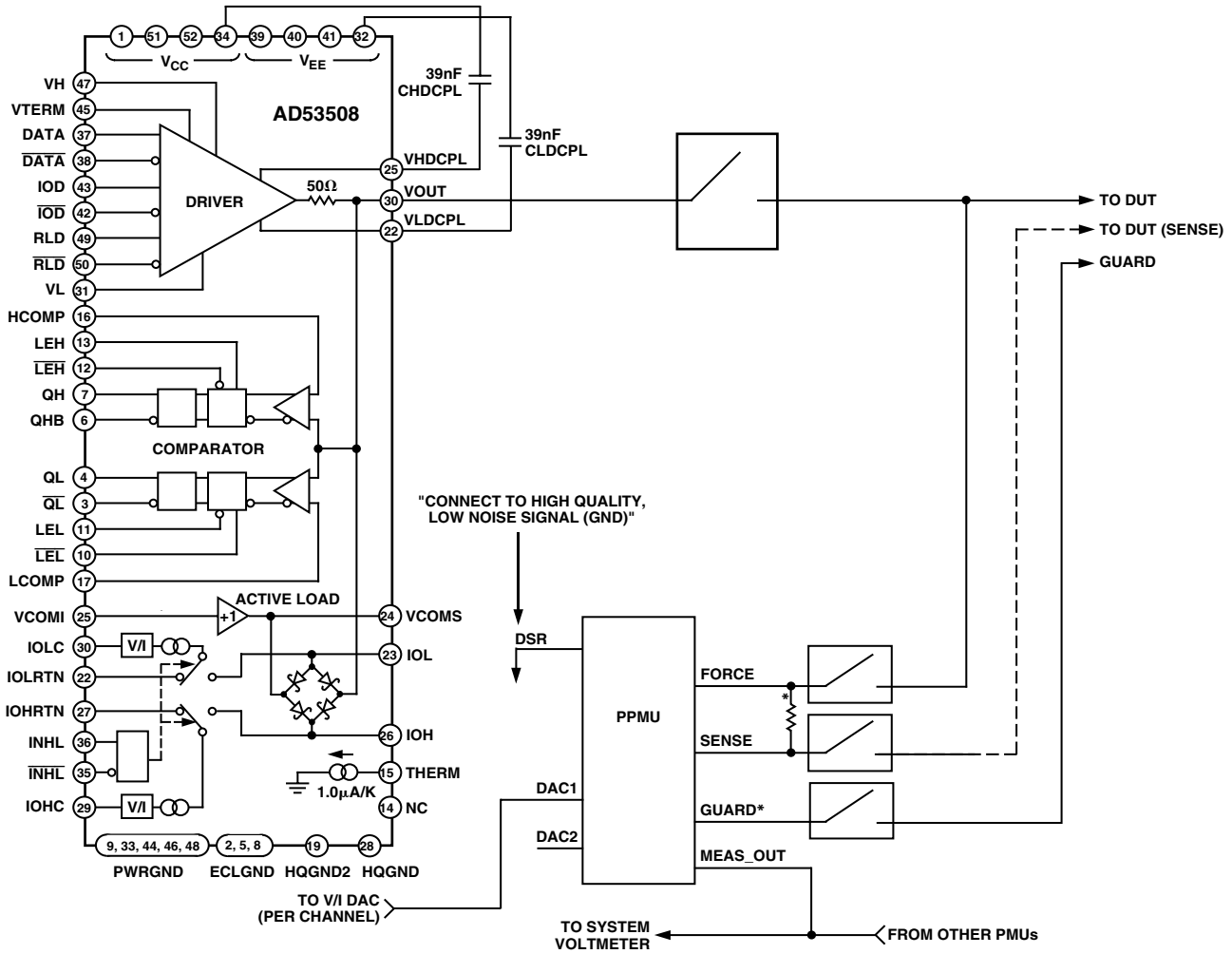


Figure 4. Recommended Use of the PPMU with a DCL

## OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).

### 44-Lead Plastic Leaded Chip Carrier (PLCC) (P-44A)

