



## PRIMARY-SIDE PUSH-PULL OSCILLATOR WITH DEAD-TIME CONTROL

#### FEATURES

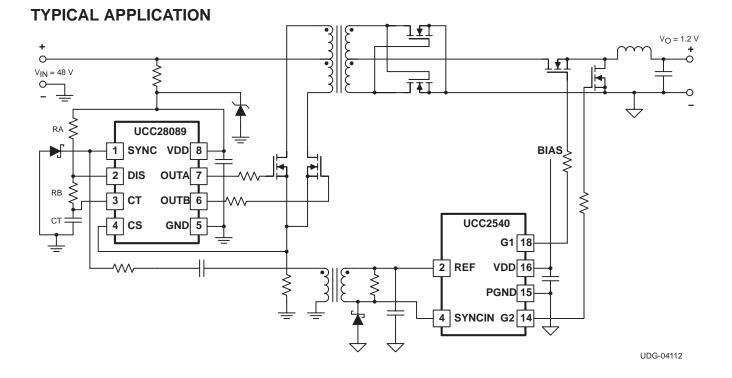
- Push-Pull Oscillator With Programmable Deadtime
- High-Current Totem-Pole Dual Output Stage Drives Push-Pull Configuration with 1-A Sink and 0.5-A Source Capability
- Can be Used in Push-Pull, Half-Bridge, or Full-Bridge Topologies
- Oscillator Synchronization Output
- Low Start-Up Current of 130 μA and 1.4-mA Typical Run Current
- Over-Current Shutdown
- Digitally Controlled Over-Current/Retry Feature
- Undervoltage Lockout With Hysteresis

#### APPLICATIONS

- High Efficiency Cascaded Converters
- Inverters
- Electronic Ballasts
- Uninterruptable Power Supplies (UPS)
- AC or DC Links

## DESCRIPTION

The UCC28089 is a versatile BiCMOS controller for dc-to-dc or off-line fixed-frequency switching power supplies. The UCC28089 has dual alternating output stages in dual-alternating push-pull configuration. Both outputs switch at half the oscillator frequency using a toggle flip-flop and duty cycle is limited to less than 50%.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

 $\overline{\mathbf{A}}$ 



#### **DESCRIPTION (CONTINUED)**

The UCC28089 is optimized for use as the primary-side companion controller for a cascaded converter that has secondary-side control. The device incorporates dead-time programming. The synchronization output also provides dead-time information. The retry and soft-start duration scales with the oscillator clock frequency for high performance fault recovery.

The UCC28089 also provides primary side under-voltage protection (UVLO), and over-current protection. Both the soft start and retry after fault durations scale with oscillator frequency for high performance. The turn-on/off UVLO thresholds are 10.5 V/8.0 V.

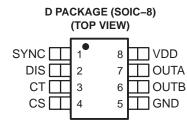
#### **ORDERING INFORMATION**

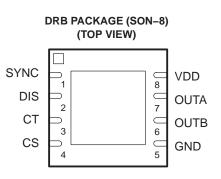
| TEMPERATURE RANGE | PACKAGED DEVICES |             |  |
|-------------------|------------------|-------------|--|
| $T_A = T_J$       | SOIC-8 (D)       | SON-8 (DRB) |  |
| –40°C to 105°C    | UCC28089D        | UCC28089DRB |  |

NOTE: D (SOIC-8) and DRB (SON-8) packages are available taped and reeled. Add R suffix to device type (e.g. UCC28089DR or UCC28089DRBR) to order quantities of 2,500 devices per reel (for D), and 1,000 devices per reel (for DRB).

NOTE: Contact factory through TI sales for the availability of this package.

#### **CONNECTION DIAGRAM**







#### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature (unless otherwise noted)<sup>†‡</sup>

| PARAMETER  | SYMBOL           | RATING   | UNITS |  |
|--|------------------|--|-------|--|
| Supply voltage (I <sub>DD</sub> < 10 mA)               | V <sub>DD</sub>  | 15   | V     |  |
| Supply current   | IDD              | 20   | mA    |  |
| OUTA/OUTB sink current (peak)                          | IOUT(sink)       | 1.0  |       |  |
| OUTA/OUTB source current (peak)                        | IOUT(source)     | -0.5   | A     |  |
| SYNC sink current (peak)                               |                  | 50   |       |  |
| SYNC source current (peak)                             |                  | -50  | mA    |  |
| Analog inputs (DIS, CT, CS)                            |                  | -0.3 to V <sub>DD</sub> + 0.3, not to exceed 5 | V     |  |
| Power dissipation at $T_A = 25^{\circ}C$ (D package)   |                  | 650  |       |  |
| Power dissipation at $T_A = 25^{\circ}C$ (DRB package) |                  | TBD  | mW    |  |
| Junction operating temperature                         | Тј               | –55 to 150                                     |       |  |
| Storage temperature                                    | T <sub>stg</sub> | -65 to 150                                     | oC    |  |
| Lead temperature (soldering, 10 sec.)                  | T <sub>sol</sub> | +300   |       |  |

<sup>†</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute–maximum–rated conditions for extended periods may affect device reliability.

<sup>‡</sup> All voltages are with respect to GND. Currents are positive into, negative out of the specified terminal. Consult Packaging Section of the Databook for thermal limitations and considerations of packages.

#### **RECOMMENDED OPERATION CONDITIONS**

| Parameter                                | Symbol          | MIN | TYP | MAX     | UNITS |
|--|-----------------|-----|-----|---------|-------|
| Supply voltage (I <sub>DD</sub> < 10 mA) | V <sub>DD</sub> | 8.5 |     | 14      | V     |
| SYNC sink current (peak)                 |                 | 0   | 10  | 25      |       |
| SYNC source current (peak)               |                 | -25 | -10 | 0       | mA    |
| Analog inputs (DIS, CT, CS)              |                 | 0   |     | 4       | V     |
| Timing capacitor range                   | СТ              | 100 |     | 100,000 | pF    |
| Timing charge resistor range             | RA              | 32  |     | 750     |       |
| Discharge resistor range                 | RB              | 0   |     | 250     | kΩ    |
| Timing charge current                    | ICHG(RA+RB)     | 10  |     | 300     | mA    |
| Switching Frequency                      | fSW             |     |     | 1000    | kHz   |
| Junction temperature                     | ТJ              | -40 |     | 105     | °C    |



#### ELECTRICAL CHARACTERISTICS:

 $T_A = -40^{\circ}C$  to 105°C for UCC28089,  $V_{DD} = 9 V$  (see Note 1), 1  $\mu$ F capacitor from VDD to GND, RA = 110 k $\Omega$ , RB = 182  $\Omega$ , CT = 220 pF,  $T_A = T_J$ , (unless otherwise noted).

| PARAMETER                             | TEST CONDITION  | MIN   | ТҮР   | MAX   | UNITS  |  |
|---------------------------------------|---|-------|-------|-------|--------|--|
| Overall Section                       |   | •     | •     | •     | •      |  |
| Startup current                       | VDD < UVLO start threshold (see Note 2)                                   |       | 130   | 260   | μΑ     |  |
| Operating supply current              | CS = 0 V, (see Note 1, Note 2)  |       | 1.4   | 2.0   | mA     |  |
| Undervoltage Lockout                  |   | •     | •     | •     | •      |  |
| Start threshold                       | See Note 1  | 9.5   | 10.5  | 11.5  |        |  |
| Minimum operating voltage after start |   | 7.4   | 8.0   | 8.4   | V      |  |
| Hysteresis                            |   | 2.1   | 2.5   | 2.9   |        |  |
| Oscillator                            |   | •     | •     | •     | •      |  |
| Oscillator frequency                  | 2 x OUTx frequency, Measured at output(s)                                 | 180   | 200   | 220   | kHz    |  |
| Current Sense                         |   | •     | •     | •     | •      |  |
| Current Shutdown threshold            | Resetting current limit   | 0.650 | 0.725 | 0.800 | V      |  |
| CS to output delay                    | CS from 0 mV to 900 mV  |       | 45    | 100   | ns     |  |
| Output                                |   | •     | •     | •     | •      |  |
|                                       | Measured at OUTA or OUTB  | 90    | 100   | 110   |        |  |
| Dead Time                             | Over temperature  | 80    |       | 125   | ns     |  |
| Minimum duty cycle                    | CS = 0.9 V  |       |       | 0     | %      |  |
| VOL (OUTA or OUTB)                    | I <sub>OUT</sub> = 75 mA  |       | 0.5   | 1     |        |  |
| VOH (OUTA or OUTB)                    | I <sub>OUT</sub> = -35 mA, (VDD – VOUT)                                   |       | 1.0   | 1.3   | V      |  |
| Output resistance high                | $T_A = 25^{\circ}C I_{OUT} = -1 \text{ mA} \text{ (see Note 4)}$          | 70    | 80    | 90    |        |  |
|                                       | $T_A = $ full range $I_{OUT} = -1$ mA (see Note 4)                        | 40    | 80    | 135   |        |  |
| Output resistance low                 | $T_A = 25^{\circ}C I_{OUT} = 1 mA$ (see Note 4)                           | 6.5   | 7.5   | 8.5   | Ω      |  |
|                                       | $T_A = $ full range I <sub>OUT</sub> = 1 mA (see Note 4)                  | 4     | 7.5   | 14    |        |  |
| tr, Rise Time                         | C <sub>LOAD</sub> = 1 nF  |       | 28    | 50    |        |  |
| tf, Fall Time                         | C <sub>LOAD</sub> = 1 nF  |       | 13    | 30    | ns     |  |
| SYNC                                  |   | •     | •     | •     | •      |  |
| SYNC duration                         | Measured at SYNC pin  | 75    | 95    | 115   |        |  |
| tr, delay                             | Rising SYNC until falling OUTA or OUTB                                    | 0     | 8.5   | 30    | ns     |  |
| tf, delay                             | Falling SYNC until rising OUTA or OUTB                                    | 0     | 14    | 50    |        |  |
| SYNC VOH                              | I <sub>SYNC</sub> = -5 mA (VDD - VSYNC)                                   |       | 0.3   | 1     |        |  |
| SYNC VOL                              | I <sub>SYNC</sub> = 5 mA  |       | 0.3   | 1     | V      |  |
| tr, Rise Time                         | C <sub>LOAD</sub> = 100 pF  |       | 15    | 30    |        |  |
| tf, Fall Time                         | $C_{LOAD} = 100  \text{pF}$   |       | 15    | 30    | ns     |  |
| Soft Start & Fault                    |   | •     |       | •     | •      |  |
| OUTA/OUTB start delay time            | Cycles as measured at CT pin  | 57    | 59    | 62    |        |  |
| OUTA/OUTB soft start duration         | First output stage cycle to first full output stage cycle, $CS \le 0.6 V$ | 4     | 5     | 7     | cycles |  |

NOTES: 1. Set VDD above the start threshold before setting at 9V.

2. Does not include current of the external oscillator network.

3. Ensured by design. Not 100% tested in production.

4. The pullup / pulldown circuits of the driver are bipolar and MOSFET transistors in parallel. The output resisstance is the RDS(ON) of the MOSFET transistor when the voltage of the driver output is less than the saturation voltage of the bipolar transistor.



UDG-04101

#### UCC28089 VDD L SYNC 1 OSCILLATOR DIS 2 UVLO 1 8 VDD VDD = 10.5/8.0 V СК VDD/5 -S Q VDD/19.6 Q R CT 3 VDD SOFT-START & FAULT OUTPUT LOGIC $\sim$ 56 STEP START DELAY 7 OUTA VDD/5 GO REF SS LATCH GO SQ OVER CURRENT COMP 7 STEP SOFT-+| 6 OUTB START RAMP SS COMP RQ 0.2V R CS 4 Q т -d ą 0.725 V 5 GND

#### FUNCTIONAL BLOCK DIAGRAM

| PIN # | NAME | I/O | FUNCTION  |
|-------|------|-----|---|
| 1     | SYNC | 0   | Active when OUTA and OUTB are active, logic LO at all other times such as during under-voltage lock-out and over-current shutdown. When active, SYNC is logic HI (VDD) during the discharge time of the oscillator and logic LO (GND) at all other times. The pulse occur during the dead time. |
| 2     | DIS  | Ι   | Separate oscillator timing capacitor discharge pin that allows the dead time to be externally programmed.   |
| 3     | СТ   | Ι   | Oscillator timing capacitor connection.   |
| 4     | CS   | I   | Current sense pin. An over current shutdown event is triggered when the voltage of this pin rises above 0.75 V.   |
| 5     | GND  | -   | Ground pin. Analog and digital signals reference this pin and output drivers return current through this pin  |
| 6     | OUTB | 0   | Driver output, capable of sinking 1 A and sourcing 0.5 A. OUTB signal alternates with OUTA.   |
| 7     | OUTA | 0   | Driver output, capable of sinking 1 A and sourcing 0.5 A. OUTA signal alternates with OUTB.   |
| 8     | VDD  | I   | Power input connection for this device.   |



#### **APPLICATION INFORMATION**

UCC28089 is an alternating dual-driver output oscillator with over-current and under-voltage fault protection. This feature set is ideal as a start-up controller for isolated power systems where the majority of control functions are performed on the secondary side. This device is especially useful for dc link for topologies such as the cascaded buck converter [1], ac link inverter topologies [2], and inexpensive modified square wave inverters. The UCC28089 has a brief 5 to 7 cycle leading-edge modulated soft-start cycle so that it will not interfere with secondary-side controlled soft start. Both systems with off-line self bias and auxiliary bias supplies are more fault tolerant with the UCC28089 because it consistently responds to a fault with a delay of at least 56 oscillator cycles before retry.

#### **Detailed Functional Description**

**VDD:** Power input connection for this device. Although quiescent VDD current is very low, total supply current is higher, depending on OUTA and OUTB current and the programmed oscillator frequency. During fault response, the current drops to a lower level because the oscillator is disabled.

In order to avoid noise problems, position a  $1-\mu F$  ceramic bypass capacitor, connected from VDD to GND, as close to the chip as possible. The ceramic bypass capacitor is in addition to any energy storage capacitance that would be used to hold up the VDD voltage during start-up transients.

**GND:** Ground pin. Analog signals reference this pin and output drivers return current through this pin. For best results, use this pin as a local ground point in a star ground configuration.

**OUTA and OUTB:** Output drivers capable of sinking 1 A and sourcing 0.5 A. The output pulse alternates between OUTA and OUTB. In addition, a T latch forces the output pulses to alternate in order to reduce flux build up in a transformer during low duty ratio operation. Each output is capable of driving the gate of a power MOSFET.

**CT and DIS:** Oscillator timing capacitor pin and timing capacitor discharge pin. The UCC28089 oscillator tracks VDD and GND internally in order to minimize oscillator frequency changes due to variations in the voltage of VDD. Figure 1 shows the oscillator block diagram.

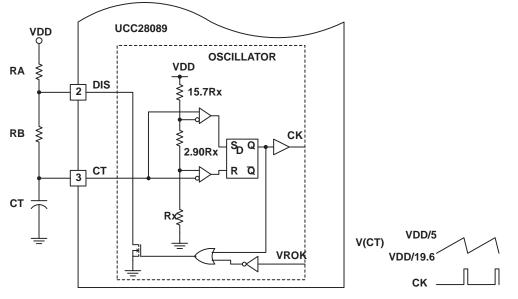


Figure 1. Block Diagram for Oscillator



## **APPLICATION INFORMATION**

The recommended oscillator frequency range is up to 1 MHz. In order to avoid noise issues,  $R_A$  and  $R_B$  should be small enough for the oscillator to have at least 10  $\mu$ A of current. There are two sets of oscillator programming equations that model the oscillator over its wide programming range. Measure the charge and the discharge times at the SYNC pin in order to avoid affecting the oscillator with probe impedances or output driver delays.

The approximate first order equations in the table are adequate for switching frequencies below 50 kHz and/or discharge times that are greater than 1  $\mu$ s. The specific requirements for using the first order equations versus the second order equations are related to the timing capacitor size and the discharge resistor. Keep in mind that the 1st order equations and 2nd order equations are merely approximations that are typically within +/–20% of the actual operating point. The frequency, charge and discharge times are relatively insensitive to temperature but larger values of C<sub>T</sub> and R<sub>B</sub> exhibit the least sensitivity to temperature. Incidentally, the second order equations that are in the Electrical Characteristics table. The oscillator frequency is set according to the following equations:

|            | 1 <sup>ST</sup> ORDER EQUATIONS                   | 2 <sup>ND</sup> ORDER EQUATIONS                |
|------------|---|--|
| Condition  | $R_A > 300 \Omega AND C_T > 300 pF$               | 100 Ω < $R_A$ < 300 Ω OR 100pF < $C_T$ < 300pF |
| TCHARGE    | $0.169 \left( R_{A} + R_{B} \right) C_{T}$        | $0.175 (R_A + R_B) (C_T + 40 \ pF) + 20 \ ns$  |
| TDISCHARGE | 1.36 R <sub>B</sub> C <sub>T</sub>                | $(1.37)(R_B + 44)(C_T + 14  pF) + 20  ns$      |
| fosc       | $\frac{5.9}{\left(R_{A} + 8.0 R_{B}\right)C_{T}}$ | $\frac{1}{T_{CHARGE} + T_{DISCHARGE}}$         |

Where R<sub>A</sub> and R<sub>B</sub> are in Ohms; C<sub>T</sub> is in Farads; f<sub>OSC</sub> is in Hz; t<sub>CHARGE</sub> and t<sub>DISCHARGE</sub> are in seconds.

The oscillator is optimized for a C<sub>T</sub> timing capacitor range from 100 pF to 1000 nF and R<sub>B</sub> more than 100  $\Omega$ . If the shortest discharge time possible is desired, it is permissible to short DIS to C<sub>T</sub> for all recommended C<sub>T</sub> values (100 pF to 0.100  $\mu$ F).

**SYNC:** This SYNC pin produces an output pulse from 0 to VDD that can be used to synchronize a secondary side-buck controller to the free running isolating power stage. The proper timing of this signal enables zero voltage switching on the primary side MOSFETs. The clean signal also solves a problem of getting a synchronization signal from the secondary side of the transformer, which can have leakage inductance voltage spikes that may cause false triggering. The SYNC pulse width is the oscillator discharge time, which is approximately equal to the dead time. Pulse frequency is the oscillator frequency. During fault conditions, the SYNC pulses are terminated and the SYNC output is held low for at least 56 oscillator cycles. During soft start, SYNC precedes the first output pulse by at least one oscillator cycle.

CS: Connect the current sense device to this pin. A voltage threshold of 0.725 V triggers a shutdown sequence.

An over-current fault triggers an immediate shutdown. After the fault clears, a total of 64 oscillator cycles are required for an entire soft start sequence to occur. First, the outputs and SYNC are kept OFF for at least 56 oscillator cycles. Next, after one or two SYNC pulses, the soft start progressively increases the output duty ratio over the next five to seven oscillator cycles.



#### APPLICATION INFORMATION

# Using the UCC28089 as the Primary-Side start-up Controller in a Cascaded Push-Pull Buck Two-Stage Converter

The cascaded push-pull topology is ideal for converting from moderate bus voltages, such as 48-V telecom buses, to sub 2-V output voltages. The general topology is shown in Figure 2 using the UCC28089 as the primary-side start-up controller and the UCC2540 as the secondary-side regulator [3].

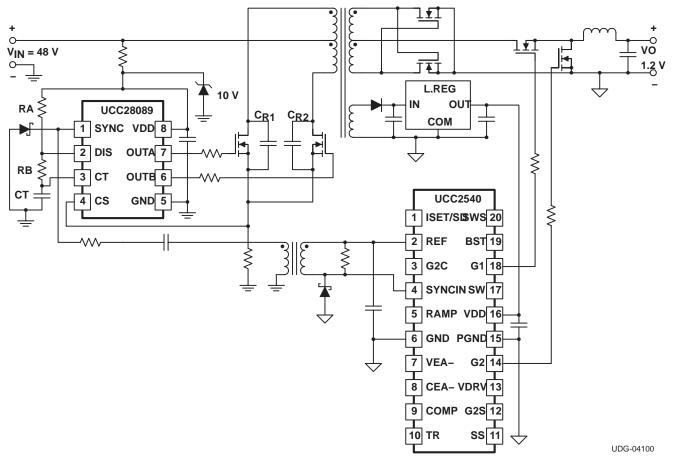


Figure 2. Cascaded Push-Pull Buck Two-Stage Converter

#### **APPLICATION INFORMATION**

Program the oscillator frequency of the UCC28089 to equal the desired switching frequency of the output post regulator. The secondary-side controller may also need corresponding switching frequency programming, such as RAMP and G2C capacitor values for the UCC2540. Program the dead time to be approximately 1/4 of the resonant period of the equivalent parasitic L–C circuit that is established by the primary leakage inductance of the transformer and the total drain-source capacitance of the primary-side power MOSFET transistors ( $C_{OSS}$  + stray capacitances). Remember that  $C_{OSS}$  predictably varies over input line voltage. If the variation is too great and/or 1/4 the resonant period is less than 100 ns, connect additional capacitance ( $C_{R1}$  and  $C_{R2}$  in Figure 2) between the drain and source of the primary transistors, which stabilizes the capacitance and raise the total capacitance value.

If the secondary-side controller is compatible with pulse edges, the pulse edge transformer circuit in Figure 3 can provide an isolated pulse edge signal on the secondary side using a transformer core that is 6-mm diameter or less. The recommended transformer (COEV #MGBBT–0001101) is compatible with all switching frequencies and it is smaller than many opto-isolators.

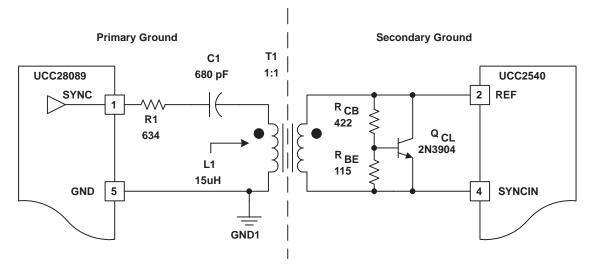


Figure 3. Isolation and clamping the SYNC signal for Cascaded Buck Converters

Notice that the peak-pulse voltage is proportional to the UCC28089 bias voltage. The circuit in Figure 3 is well suited to the full VDD bias voltage range of the UCC28089 bias voltage because it has a clamp circuit. The clamp circuit in Figure 3 ( $R_{CB}$ ,  $R_{BE}$  and  $Q_{CL}$ ) is a  $V_{BE}$  clamp rather than a Zener diode. A  $V_{BE}$  clamp is used here because it has much lower capacitance than typical Zener diodes so that the clamp does not affect the narrow 50-ns pulse width. The clamp may be replaced by a single resistor in applications, as in Figure 2, where the VDD bias voltage of the UCC28089 is regulated within a +/–5% window.



#### **APPLICATION INFORMATION**

#### Synchronization of Multiple UCC28089 Controllers to an External Signal

In systems where multiple UCC28089 parts need to be synchronized to a common clock, a 3.3-V logic-level signal can be directly applied to the CT pin (the SYNC pin on UCC28089 only provides output sync signals). As shown in Figure 4, the externally supplied sync pulse width determines the frequency and the dead time between OUT A and OUT B. In this configuration, the discharge pin DIS should be grounded since it is not used. The external sync signal should exceed the oscillator trip level of  $V_{DD}/5$  when high, and pull CT below  $V_{DD}/20$  when low.

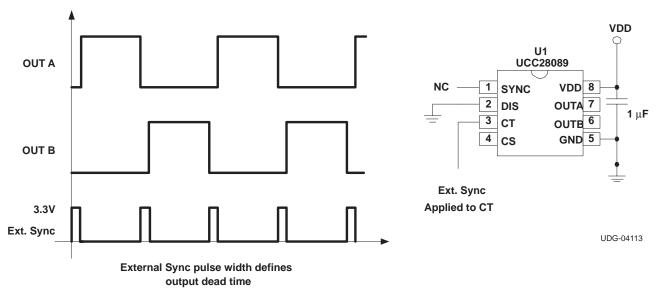


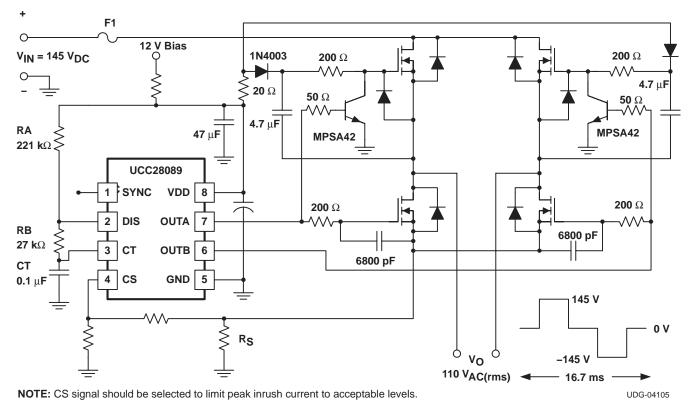
Figure 4. Synchronizing the UCC28089 to an External Signal



#### **APPLICATION INFORMATION**

#### Using the UCC28089 as a Modified Square Wave Inverter

Remote or dc-only power systems often require a limited amount of 60-Hz ac line power to supply small appliances. Compatible loads include universal motors, incandescent lamps, and other electronic devices with switched mode power supplies to convert the  $110-V_{AC}$  to lower dc voltages. Many of these devices do not require a perfect sinusoidal line voltage, and acceptable performance can be obtained with a modified square wave voltage. Using the circuit in Figure 5, the UCC28089 can provide the appropriate waveform along with primary side over-current protection. Components RA, RB, and CT are selected to program the desired modified square waveform with the appropriate dead time.



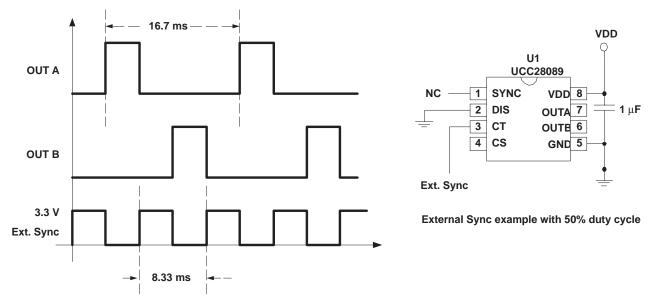
#### Figure 5. Modified Square Wave Inverter

The high-side gate drives of the inverter in Figure 5 are suitable for low frequency applications with relatively constant duty ratio. The NPN transistors and the charge pump diodes on the high-side gate drives must be rated for high voltage (at least 145 V + VDD). The gates are protected from excessive negative voltage by the diodes shown from gate to source.



#### **APPLICATION INFORMATION**

If desired, the 60-Hz modified square wave inverter frequency could be programmed using an external sync signal that might originate from a separate oscillator or digital controller. The following diagram in Figure 6 shows a 50% duty cycle square wave fed into the CT pin, with a frequency of 120 Hz, and the resulting OUTA/OUTB wave shapes.



#### Figure 6. External Synchronization Example with 50% Duty Cycle Square Wave

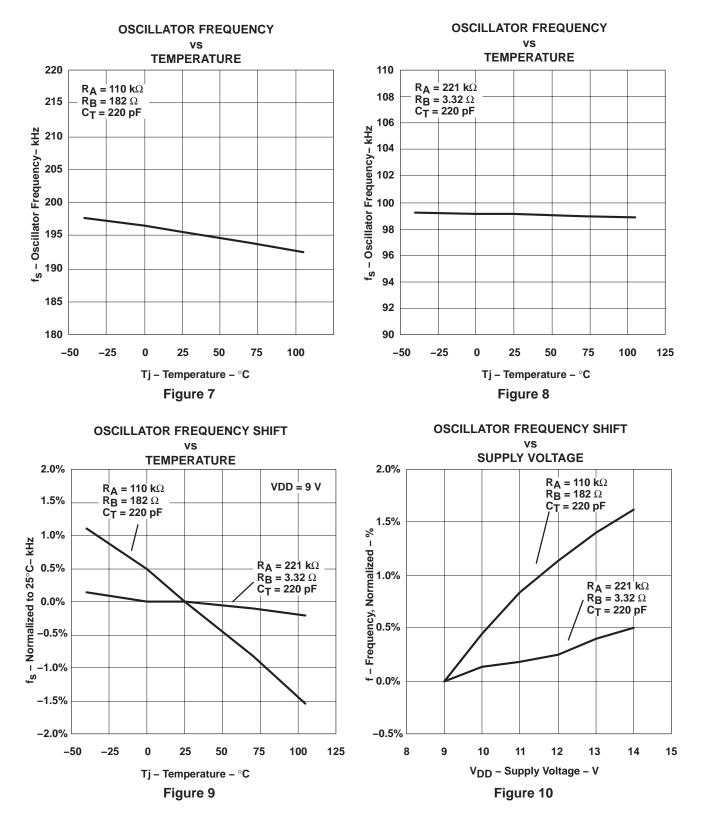
#### **RELATED PRODUCTS**

| DEVICE  | DESCRIPTION  |
|---------|--|
| UCC2540 | High-Efficiency Secondary-Side Synchronous-Buck PWM Controller |



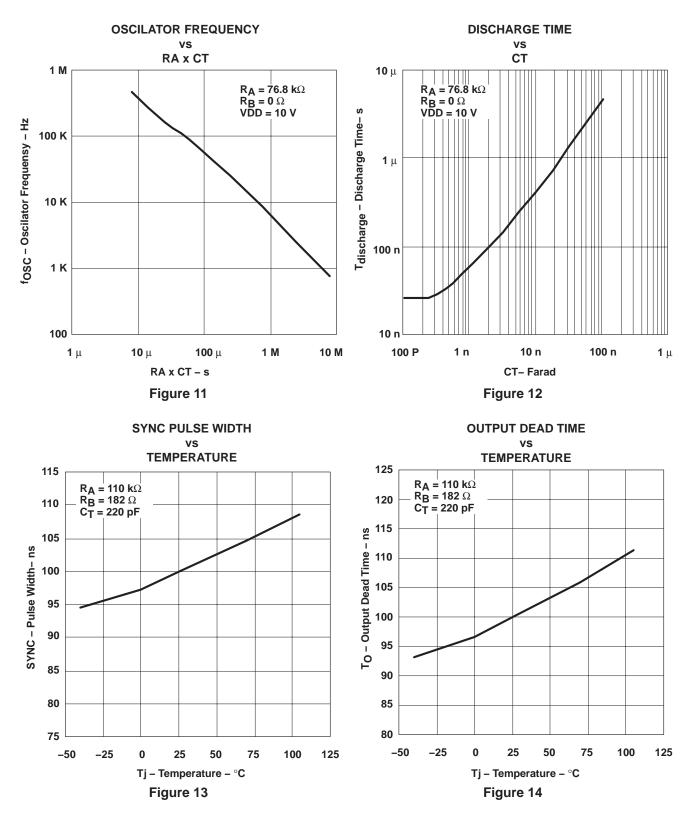
SLUS623 - SEPTEMBER 2004

#### **TYPICAL CHARACTERISTICS**



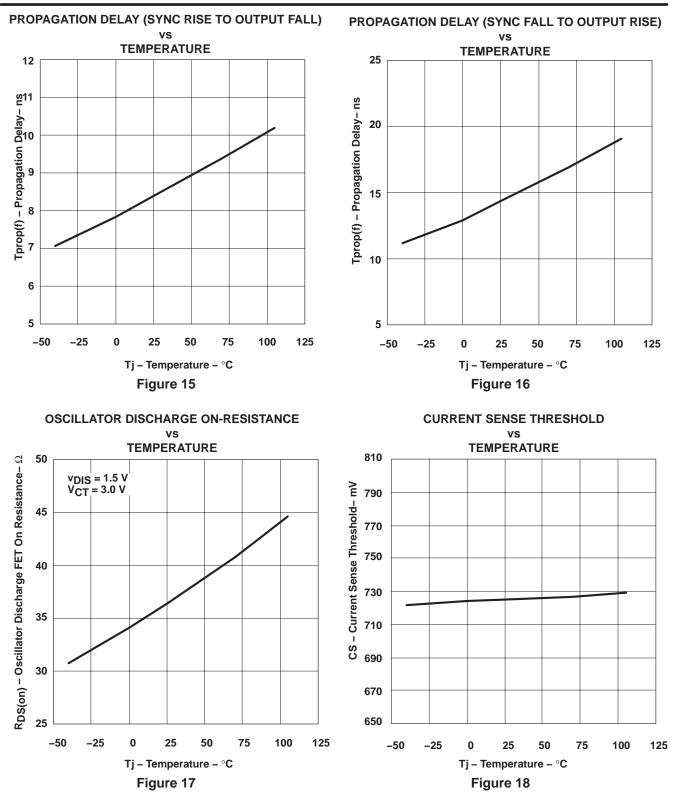


#### **TYPICAL CHARACTERISTICS**



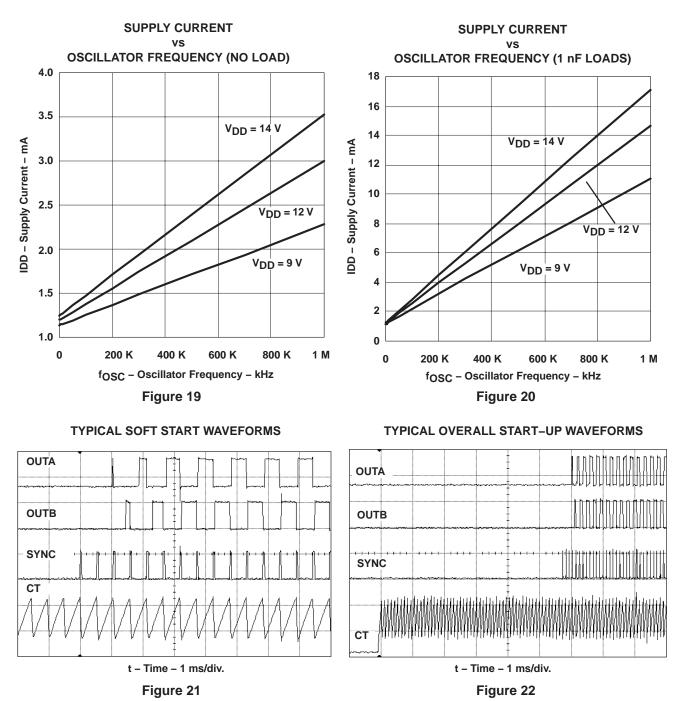


SLUS623 - SEPTEMBER 2004







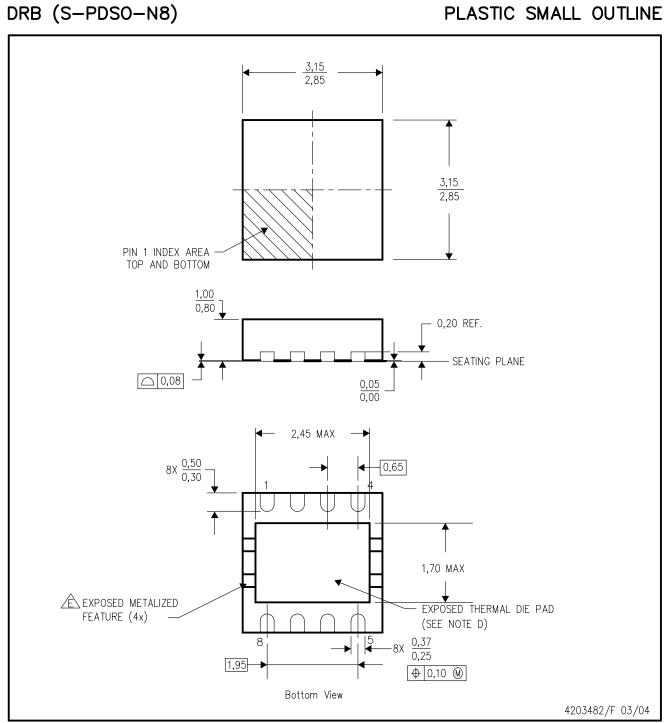


#### REFERENCES

- Power Supply Seminar SEM–1300 Topic 1: Unique Cascaded Power Converter Topology for High Current Low Output Voltage Applications, by L. Balogh, C. Bridge and B. Andreycak, Texas Instruments Literature No. SLUP133
- 2. Low Cost Inverter Suitable for Medium-Power Fuel Cell Sources, by P.T. Krein and R Balog, IEEE Power Electronics Specialists Conference Proceedings, 2002, vol. 1, pp. 321–326.
- 3. Datasheet, UCC2540 *High-Efficiency Secondary-Side Synchronous-Buck PWM Controller*, Texas Instruments Literature No. SLUS539



PLASTIC SMALL OUTLINE



NOTES: Α. All linear dimensions are in millimeters.

- Β. This drawing is subject to change without notice.
- Small Outline No-Lead (SON) package configuration. C.

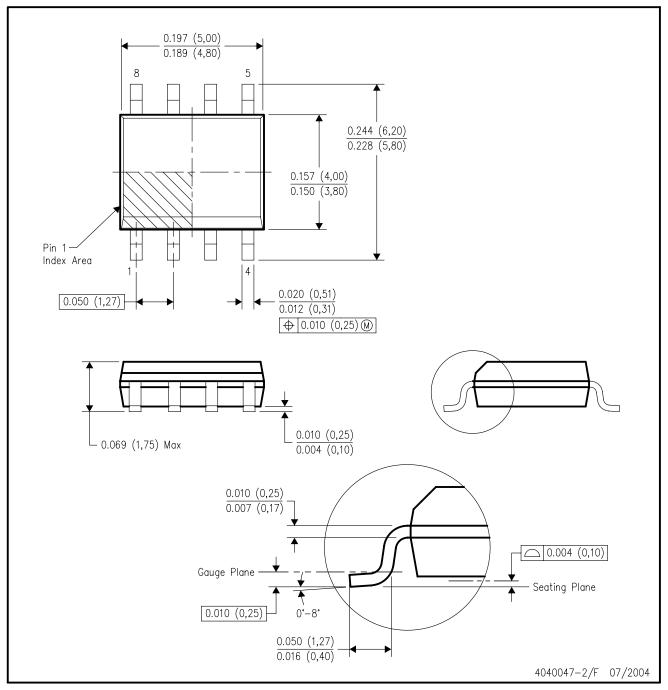
D. The package thermal performance may be enhanced by bonding the thermal die pad to an external thermal plane.

Æ. Metalized features are supplier options and may not be on the package.



D (R-PDSO-G8)

PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).

D. Falls within JEDEC MS-012 variation AA.



#### **IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

| Products         |                        | Applications       |                           |
|------------------|------------------------|--------------------|---------------------------|
| Amplifiers       | amplifier.ti.com       | Audio              | www.ti.com/audio          |
| Data Converters  | dataconverter.ti.com   | Automotive         | www.ti.com/automotive     |
| DSP              | dsp.ti.com             | Broadband          | www.ti.com/broadband      |
| Interface        | interface.ti.com       | Digital Control    | www.ti.com/digitalcontrol |
| Logic            | logic.ti.com           | Military           | www.ti.com/military       |
| Power Mgmt       | power.ti.com           | Optical Networking | www.ti.com/opticalnetwork |
| Microcontrollers | microcontroller.ti.com | Security           | www.ti.com/security       |
|                  |                        | Telephony          | www.ti.com/telephony      |
|                  |                        | Video & Imaging    | www.ti.com/video          |
|                  |                        | Wireless           | www.ti.com/wireless       |

Mailing Address:

Texas Instruments

Post Office Box 655303 Dallas, Texas 75265

Copyright © 2004, Texas Instruments Incorporated