

PN7120

NFC controller with integrated firmware, supporting all NFC Forum modes

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Product data sheet COMPANY PUBLIC

1 Introduction

This document describes the functionality and electrical specification of the NFC Controller PN7120.

Additional documents describing the product functionality further are available for designin support. Refer to the references listed in this document to get access to the full for full documentation provided by NXP.

In this document the term "MIFARE Classic card" refers to a MIFARE Classic IC-based contactless card.



NFC controller with integrated firmware, supporting all NFC Forum modes

2 General description

PN7120, the best plug'n play full NFC solution - easy integration into any OS environment, with integrated firmware and NCI interface designed for contactless communication at 13.56 MHz.

It is the ideal solution for rapidly integrating NFC technology in any application, especially those running OS environment like Linux and Android, reducing Bill of Material (BOM) size and cost, thanks to:

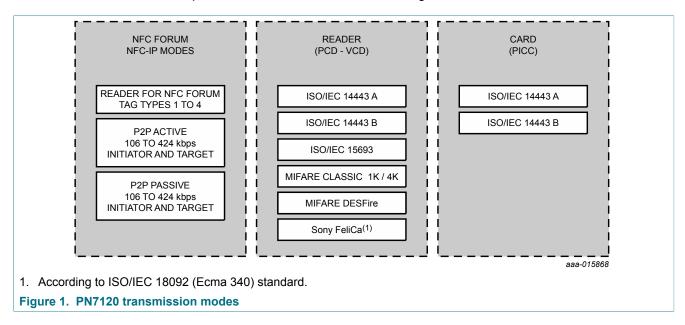
- full NFC forum compliancy (see [11]) with small form factor antenna
- embedded NFC firmware providing all NFC protocols as pre-integrated feature
- direct connection to the main host or microcontroller, by I²C-bus physical and NCI protocol
- ultra-low power consumption in polling loop mode
- Highly efficient integrated power management unit (PMU) allowing direct supply from a battery

PN7120 embeds a new generation RF contactless front-end supporting various transmission modes according to NFCIP-1 and NFCIP-2, ISO/IEC 14443, ISO/IEC 15693, ISO/IEC 18000-3, MIFARE Classic IC-based card and FeliCa card specifications. It embeds an ARM Cortex-M0 microcontroller core loaded with the integrated firmware supporting the NCI 1.0 host communication.

The contactless front-end design brings a major performance step-up with on one hand a higher sensitivity and on the other hand the capability to work in active load modulation communication enabling the support of small antenna form factor

Supported transmission modes are listed in <u>Figure 1</u>. For contactless card functionality, the PN7120 can act autonomously if previously configured by the host in such a manner.

PN7120 integrated firmware provides an easy integration and validation cycle as all the NFC real-time constraints, protocols and device discovery (polling loop) are being taken care internally. In few NCI commands, host SW can configure the PN7120 to notify for card or peer detection and start communicating with them.



PN7120

NFC controller with integrated firmware, supporting all NFC Forum modes

3 Features and benefits

- Includes NXP ISO/IEC 14443-A and Innovatron ISO/IEC 14443-B intellectual property licensing rights
- ARM Cortex-M0 microcontroller core
- · Highly integrated demodulator and decoder
- Buffered output drivers to connect an antenna with minimum number of external components
- Integrated RF level detector
- · Integrated Polling Loop for automatic device discovery
- RF protocols supported
 - NFCIP-1, NFCIP-2 protocol (see [7] and [10])
 - ISO/IEC 14443A, ISO/IEC 14443B PICC mode via host interface (see[2])
 - ISO/IEC 14443A, ISO/IEC 14443B PCD designed according to NFC Forum digital protocol T4T platform and ISO-DEP (see [11])
 - FeliCa PCD mode
 - MIFARE Classic PCD encryption mechanism (MIFARE Classic 1K/4K)
 - NFC Forum tag 1 to 4 (MIFARE Ultralight, Jewel, Open FeliCa tag, MIFARE DESFire) (see [11])
 - ISO/IEC 15693/ICODE VCD mode (see [8])
- Supported host interfaces
 - NCI protocol interface according to NFC Forum standardization (see [1])
 - I²C-bus High-speed mode (see[3])
- · Integrated power management unit
 - Direct connection to a battery (2.3 V to 5.5 V voltage supply range)
 - Support different Hard Power-Down/Standby states activated by firmware
 - Autonomous mode when host is shut down
- Automatic wake-up via RF field, internal timer and I²C-bus interface
- Integrated non-volatile memory to store data and executable code for customization

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4 Applications

- All devices requiring NFC functionality especially those running in an Android or Linux environment
- TVs, set-top boxes, Blu-ray decoders, audio devices
- · Home automation, gateways, wireless routers
- · Home appliances
- · Wearables, remote controls, healthcare, fitness
- Printers, IP phones, gaming consoles, accessories

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Quick reference data

Table 1. Quick reference data

| Symbol | Parameter | Conditions | | Min | Тур | Max | Unit |
|------------------------|--|---|------------|------|-----|------|------|
| V_{BAT} | battery supply voltage | Card Emulation and Passive Target; V _{SS} = 0 V | [1] [2] | 2.3 | - | 5.5 | V |
| | | Reader, Active Initiator and Active Target; V _{SS} = 0 V | [1] [2] | 2.7 | - | 5.5 | V |
| V_{DD} | supply voltage | internal supply voltage | | 1.65 | 1.8 | 1.95 | V |
| $V_{DD(PAD)}$ | V _{DD(PAD)} supply voltage | supply voltage for host interface | | | | | |
| | | 1.8 V host supply; V _{SS} = 0 V | [1] | 1.65 | 1.8 | 1.95 | V |
| | | 3.3 V host supply; V _{SS} = 0 V | [1] | 3.0 | - | 3.6 | V |
| I _{BAT} | battery supply current | in Hard Power Down state; V _{BAT} = 3.6 V; T = 25 °C | | - | 10 | 12 | μΑ |
| | | in Standby state; V _{BAT} = 3.6 V; T = 25 °C | | - | - | 20 | μΑ |
| | | in Monitor state; V _{BAT} = 2.75 V; T = 25 °C | | - | - | 12 | μΑ |
| | | in low-power polling loop; $V_{BAT} = 3.6 \text{ V}; T = 25 ^{\circ}\text{C};$ loop time = 500 ms | | - | 150 | - | μΑ |
| | | PCD mode at typical 3 V | [3] | - | - | 170 | mA |
| I _{O(VDDPAD)} | output current on pin $V_{\text{DD(PAD)}}$ | total current which can be pulled on V _{DD(PAD)} referenced outputs | | - | - | 15 | mA |
| $I_{th(Ilim)}$ | current limit threshold current | current limiter on $V_{DD(TX)}$ pin; $V_{DD(TX)} = 3.1 \text{ V}$ | [3][4] | - | 180 | - | mA |
| P _{tot} | total power dissipation | Reader; $I_{VDD(TX)} = 100 \text{ mA}$; $V_{BAT} = 5.5 \text{ V}$ | | - | - | 0.5 | W |
| T _{amb} | ambient temperature | JEDEC PCB-0.5 | | -30 | +25 | +85 | °C |

 V_{SS} represents V_{SS} , V_{SS1} , V_{SS2} , V_{SS3} , V_{SS4} , $V_{SS(PAD)}$ and $V_{SS(TX)}$. The antenna should be tuned not to exceed this current limit (the detuning effect when coupling with another device must

The antenna shall be tuned not to exceed the maximum of I_{VBAT} .

This is the threshold of a built-in protection done to limit the current out of $V_{DD(TX)}$ in case of any issue at antenna pins to avoid burning the device. It is not allowed in operational mode to have $I_{VDD(TX)}$ such that I_{VBAT} maximum value is exceeded.

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6 Ordering information

Table 2. Ordering information

| Type number | Package | | | | |
|-------------------|---------|--|-----------|--|--|
| | Name | Description | Version | | |
| PN7120A0EV/C1xxxx | VFBGA49 | plastic very thin fine-pitch ball grid array package; 49 balls | SOT1320-1 | | |

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7 Marking

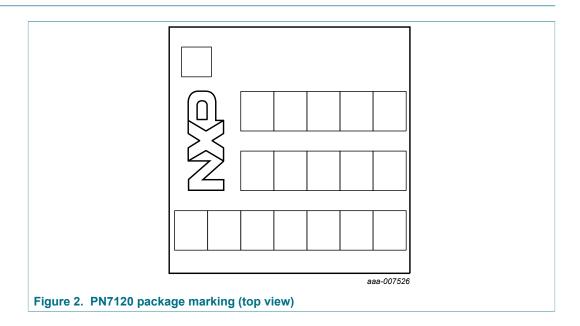
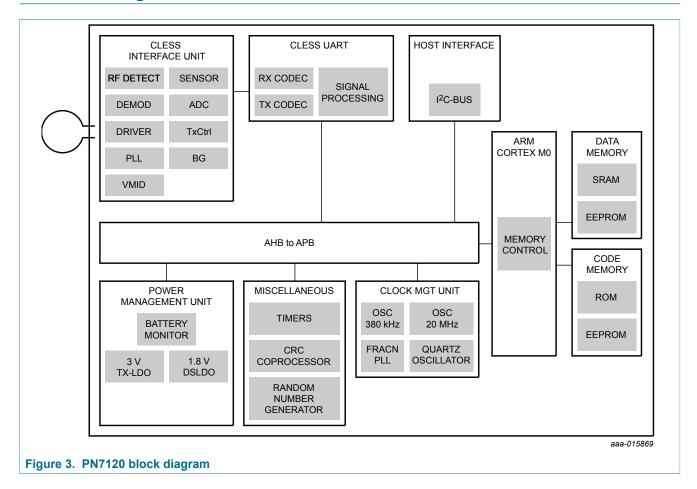


Table 3. Marking code

| Line number | Marking code |
|-------------|---|
| Line 1 | product version identification |
| Line 2 | diffusion batch sequence number |
| Line 3 | manufacturing code including: diffusion center code: — N: TSMC — s: Global Foundry assembly center code: — S: APK — X: ASEN RoHS compliancy indicator: — D: Dark Green; fully compliant RoHS and no halogen and antimony manufacturing year and week, 3 digits: — Y: year — WW: week code product life cycle status code: — X: means not qualified product nothing means released product |

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8 Block diagram



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9 Pinning information

9.1 Pinning

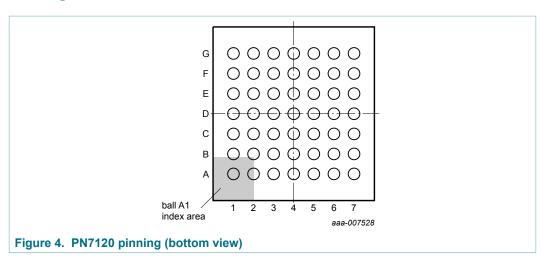


Table 4. PN7120 pin description

| Symbol | Pin | Type ^[1] | Refer | Description |
|----------------------|-----|---------------------|----------------------|---|
| i.c. | A1 | - | - | internally connected; must be connected to ground |
| CLK_REQ | A2 | 0 | $V_{DD(PAD)}$ | clock request pin |
| XTAL1 | А3 | I | V_{DD} | PLL clock input. Oscillator input |
| i.c. | A4 | - | - | internally connected; leave open |
| i.c. | A5 | - | - | internally connected; leave open |
| i.c. | A6 | - | - | internally connected; leave open |
| i.c. | A7 | - | - | internally connected; leave open |
| I2CSCL | B1 | I | V _{DD(PAD)} | I ² C-bus serial clock input |
| I2CADR0 | B2 | I | $V_{DD(PAD)}$ | I ² C-bus address bit 0 input |
| i.c. | В3 | - | - | internally connected; leave open |
| i.c. | B4 | - | - | internally connected; leave open |
| i.c. | B5 | - | - | internally connected; must be connected to ground |
| V _{SS1} | B6 | G | n/a | ground |
| i.c. | B7 | - | - | internally connected; leave open |
| I2CSDA | C1 | I/O | $V_{DD(PAD)}$ | I ² C-bus serial data |
| V _{SS(PAD)} | C2 | G | n/a | pad ground |
| XTAL2 | СЗ | 0 | V_{DD} | oscillator output |
| V _{SS} | C4 | G | n/a | ground |
| n.c. | C5 | - | - | not connected |

NFC controller with integrated firmware, supporting all NFC Forum modes

| Symbol | Pin | Type ^[1] | Refer | Description | |
|------------------------|-----|---------------------|---------------|---|--|
| V_{DD} | C6 | Р | n/a | LDO output supply voltage | |
| V _{BAT} | C7 | Р | n/a | battery supply voltage | |
| IRQ | D1 | 0 | $V_{DD(PAD)}$ | interrupt request output | |
| BOOST_CTRL | D2 | 0 | $V_{DD(PAD)}$ | booster control, see [5] | |
| $V_{DD(PAD)}$ | D3 | Р | n/a | pad supply voltage | |
| V _{SS2} | D4 | G | n/a | ground | |
| i.c. | D5 | - | - | internally connected; leave open | |
| V _{SS3} | D6 | G | n/a | ground | |
| i.c. | D7 | - | - | internally connected; leave open | |
| VEN | E1 | I | V_{BAT} | reset pin. Set the device in Hard Power Down | |
| V _{SS(DC_DC)} | E2 | G | n/a | ground | |
| n.c. | E3 | - | - | not connected | |
| n.c. | E4 | - | - | not connected | |
| n.c. | E5 | - | - | not connected | |
| n.c. | E6 | - | - | not connected | |
| $V_{DD(TX)}$ | E7 | Р | n/a | contactless transmitter output supply voltage for decoupling | |
| i.c. | F1 | - | - | internally connected; leave open | |
| i.c. | F2 | - | - | internally connected; leave open | |
| V _{SS4} | F3 | G | n/a | ground | |
| i.c. | F4 | - | - | internally connected; leave open | |
| RXN | F5 | I | V_{DD} | negative receiver input | |
| RXP | F6 | I | V_{DD} | positive receiver input | |
| $V_{\rm DD(MID)}$ | F7 | Р | n/a | receiver reference input supply voltage | |
| V _{BAT2} | G1 | Р | n/a | battery supply voltage; must be connected to V_{BAT} | |
| V _{BAT1} | G2 | Р | n/a | battery supply voltage; must be connected to V_{BAT} | |
| TX1 | G3 | 0 | $V_{DD(TX)}$ | antenna driver output | |
| V _{SS(TX)} | G4 | G | n/a | contactless transmitter ground | |
| TX2 | G5 | 0 | $V_{DD(TX)}$ | antenna driver output | |
| ANT2 | G6 | Р | n/a | antenna connection for Listen mode | |
| ANT1 | G7 | Р | n/a | antenna connection for Listen mode | |

^[1] P = power supply; G = ground; I = input, O = output; I/O = input/output.

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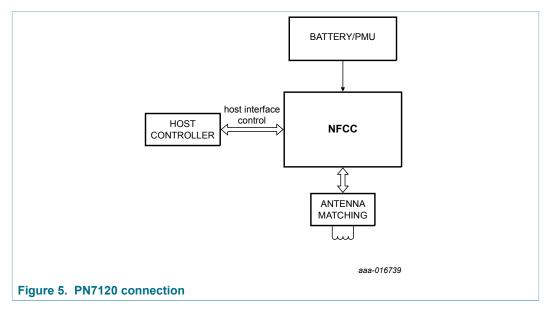
10 Functional description

PN7120 can be connected on a host controller through I²C-bus. The logical interface towards the host baseband is NCI-compliant [1] with additional command set for NXP-specific product features. This IC is fully user controllable by the firmware interface described in [4].

Moreover, PN7120 provides flexible and integrated power management unit in order to preserve energy supporting Power Off mode.

In the following chapters you will find also more details about PN7120 with references to very useful application note such as:

- PN7120 User Manual ([4]):
 User Manual describes the software interfaces (API) based on the NFC forum NCI standard. It does give full description of all the NXP NCI extensions coming in addition to NCI standard ([1]).
- PN7120 Hardware Design Guide ([5]):
 Hardware Design Guide provides an overview on the different hardware design options offered by the IC and provides guidelines on how to select the most appropriate ones for a given implementation. In particular, this document highlights the different chip power states and how to operate them in order to minimize the average NFC-related power consumption so to enhance the battery lifetime.
- PN7120 Antenna and Tuning Design Guide ([6]):
 Antenna and Tuning Design Guide provides some guidelines regarding the way to design an NFC antenna for the PN7120 chip.
 It also explains how to determine the tuning/matching network to place between this antenna and the PN7120.
 Standalone antenna performances evaluation and final RF system validation (PN7120 + tuning/matching network + NFC antenna within its final environment) are also covered by this document.
- PN7120 Low-Power Mode Configuration ([9]):
 Low-Power Mode Configuration documentation provides guidance on how PN7120 can be configured in order to reduce current consumption by using Low-power polling mode.



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10.1 System modes

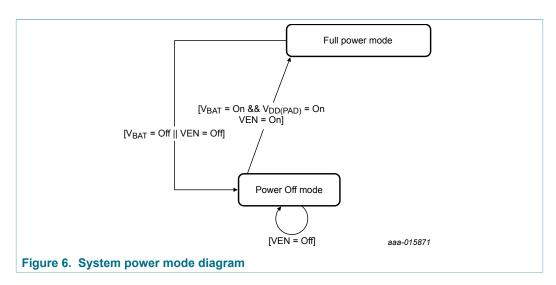
10.1.1 System power modes

PN7120 is designed in order to enable the different power modes from the system.

2 power modes are specified: Full power mode and Power Off mode.

Table 5. System power modes description

| System power mode | Description |
|-------------------|--|
| Full power mode | the main supply (V _{BAT}) as well as the host interface supply (V _{DD(PAD)}) is available, all use cases can be executed |
| Power Off mode | the system is kept Hard Power Down (HPD) |



<u>Table 6</u> summarizes the system power mode of the PN7120 depending on the status of the external supplies available in the system:

Table 6. System power modes configuration

| V _{BAT} | VEN | Power mode |
|------------------|-----|-----------------|
| Off | X | Power Off mode |
| On | Off | Power Off mode |
| On | On | Full power mode |

Depending on power modes, some application states are limited:

Table 7. System power modes description

| System power mode | Allowed communication modes |
|-------------------|--|
| Power Off mode | no communication mode available |
| Full power mode | Reader/Writer, Card Emulation, P2P modes |

PN7120

NFC controller with integrated firmware, supporting all NFC Forum modes

10.1.2 PN7120 power states

Next to system power modes defined by the status of the power supplies, the power states include the logical status of the system thus extend the power modes.

4 power states are specified: Monitor, Hard Power Down (HPD), Standby, Active.

Table 8. PN7120 power states

| Power state name | Description |
|------------------|---|
| Monitor | The PN7120 is supplied by V_{BAT} which voltage is below its programmable critical level, VEN voltage > 1.1 V and the Monitor state is enabled. The system power mode is Power Off mode. |
| Hard Power Down | The PN7120 is supplied by V_{BAT} which voltage is above its programmable critical level when Monitor state is enabled and PN7120 is kept in Hard Power Down (VEN voltage is kept low by host or SW programming) to have the minimum power consumption. The system power mode is in Power Off. |
| Standby | The PN7120 is supplied by V_{BAT} which voltage is above its programmable critical level when the Monitor state is enabled, VEN voltage is high (by host or SW programming) and minimum part of PN7120 is kept supplied to enable configured wake-up sources which allow to switch to Active state; RF field, Host interface. The system power mode is Full power mode. |
| Active | The PN7120 is supplied by V_{BAT} which voltage is above its programmable critical level when Monitor state is enabled, VEN voltage is high (by host or SW programming) and the PN7120 internal blocks are supplied. 3 functional modes are defined: Idle, Listener and Poller. The system power mode is Full power mode. |

At application level, the PN7120 will continuously switch between different states to optimize the current consumption (polling loop mode). Refer to <u>Table 1</u> for targeted current consumption in here described states.

The PN7120 is designed to allow the host controller to have full control over its functional states, thus of the power consumption of the PN7120 based NFC solution and possibility to restrict parts of the PN7120 functionality.

10.1.2.1 Monitor state

In Monitor state, the PN7120 will exit it only if the battery voltage recovers over the critical level. Battery voltage monitor thresholds show hysteresis behavior as defined in Table 26.

PN7120 will autonomously shut-down internal PMU supply to protect the battery from deep discharge.

10.1.2.2 Hard Power Down (HPD) state

The Hard Power Down state is entered when $V_{DD(PAD)}$ and V_{BAT} are high by setting VEN voltage < 0.4 V. As these signals are under host control, the PN7120 has no influence on entering or exiting this state.

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10.1.2.3 Standby state

Active state is PN7120's default state after boot sequence in order to allow a quick configuration of PN7120. It is recommended to change the default state to Standby state after first boot in order to save power. PN7120 can switch to Standby state autonomously (if configured by host).

In this state PN7120 most blocks including CPU are no more supplied. Number of wakeup sources exist to put PN7120 into Active state:

- I²C-bus interface wake-up event
- · Antenna RF level detector
- Internal timer event when using polling loop (380 kHz Low-power oscillator is enabled)

If wake-up event occurs, PN7120 will switch to Active state. Any further operation depends on software configuration and/or wake-up source.

10.1.2.4 Active state

Within the Active state, the system is acting as an NFC device. The device can be in 3 different functional modes: Idle, Poller and Target.

Table 9. Functional modes in active state

| Functional modes | Description |
|------------------|---|
| Idle | the PN7120 is active and host interface communication is on going. The RF interface is not activated. If Standby state is de-activated PN7120 stays in Idle mode even when no host communication. |
| Listener | the PN7120 is active and is listening to external device. The RF interface is activated. |
| Poller | the PN7120 is active and is in Poller mode. It polls external device. The RF interface is activated. |

Poller mode:

In this mode, PN7120 is acting as Reader/Writer or NFC Initiator, searching for or communicating with passive tags or NFC target. Once RF communication has ended, PN7120 will switch to Idle mode or Standby state to save energy. Poller mode shall be used with 2.7 V < V_{BAT} < 5.5 V and VEN voltage > 1.1 V. Poller mode shall not be used with V_{BAT} < 2.7 V. PV_{DD} is within its operational range (see <u>Table 1</u>).

Listener mode:

In this mode, PN7120 is acting as a card or as an NFC Target. Listener mode shall be used with 2.3 V < V_{BAT} < 5.5 V and VEN voltage > 1.1 V. Once RF communication has ended, PN7120 will switch to Idle mode or Standby state to save energy.

10.1.2.5 Polling loop

The polling loop will sequentially set PN7120 in different power states (Active or Standby). All RF technologies supported by PN7120 can be independently enabled within this polling loop.

There are 2 main phases in the polling loop:

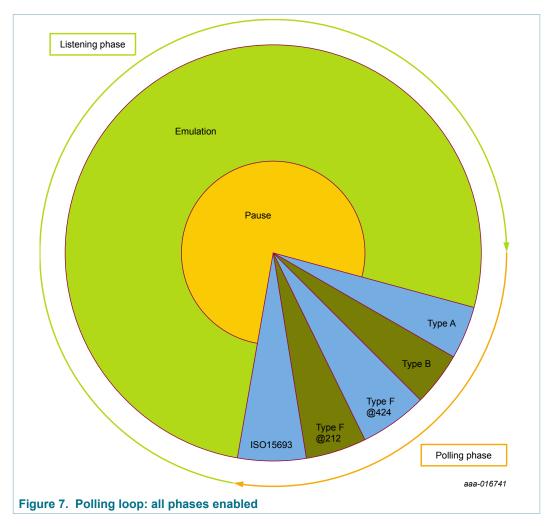
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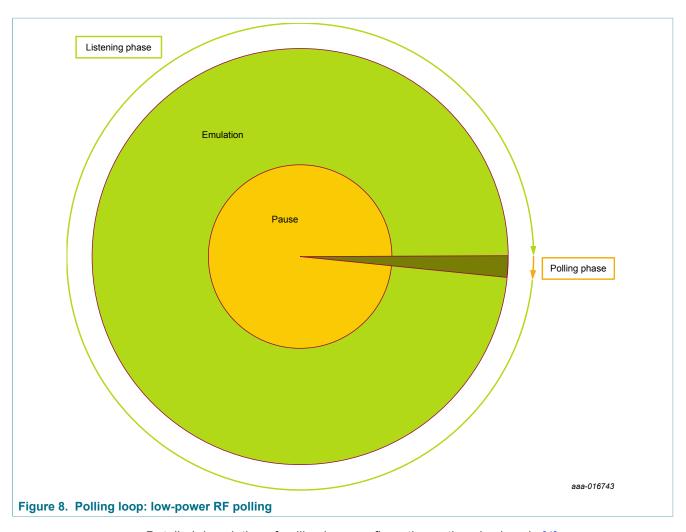
- Listening phase. The PN7120 can be in Standby power state or Listener mode
- Polling phase. The PN7120 is in Poller mode



Listening phase uses Standby power state (when no RF field) and PN7120 goes to Listener mode when RF field is detected. When in Polling phase, PN7120 goes to Poller mode.

To further decrease the power consumption when running the polling loop, PN7120 features a low-power RF polling. When PN7120 is in Polling phase instead of sending regularly RF command PN7120 senses with a short RF field duration if there is any NFC Target or card/tag present. If yes, then it goes back to standard polling loop. With 500 ms (configurable duration, see [4]) listening phase duration, the average power consumption is around 150 μA .

NFC controller with integrated firmware, supporting all NFC Forum modes



Detailed description of polling loop configuration options is given in [4].

10.2 Microcontroller

PN7120 is controlled via an embedded ARM Cortex-M0 microcontroller core.

PN7120 features integrated in firmware are referenced in [4]

10.3 Host interfaces

PN7120 provides the support of an I²C-bus Slave Interface, up to 3.4 MBaud.

The host interface is waken-up on I²C-bus address.

To enable and ensure data flow control between PN7120 and host controller, additionally a dedicated interrupt line IRQ is provided which Active state is programmable. See [4] for more information.

NFC controller with integrated firmware, supporting all NFC Forum modes

10.3.1 I²C-bus interface

The I²C-bus interface implements a slave I²C-bus interface with integrated shift register, shift timing generation and slave address recognition.

I²C-bus Standard mode (100 kHz SCL), Fast mode (400 kHz SCL) and High-speed mode (3.4 MHz SCL) are supported.

The mains hardware characteristics of the I²C-bus module are:

- Support slave I²C-bus
- · Standard, Fast and High-speed modes supported
- Wake-up of PN7120 on its address only
- Serial clock synchronization can be used by PN7120 as a handshake mechanism to suspend and resume serial transfer (clock stretching)

The I²C-bus interface module meets the I²C-bus specification [3] except General call, 10-bit addressing and Fast mode Plus (Fm+).

10.3.1.1 I²C-bus configuration

The I^2C -bus interface shares four pins with I^2C -bus interface also supported by PN7120. When I^2C -bus is configured in EEPROM settings, functionality of interface pins changes to one described in Table 10.

Table 10. Functionality for I²C-bus interface

| Pin name | Functionality |
|----------|---------------------------------|
| I2CADR0 | I ² C-bus address 0 |
| I2CSDA | I ² C-bus data line |
| I2CSCL | I ² C-bus clock line |

PN7120 supports 7-bit addressing mode. Selection of the I²C-bus address is done by 2-pin configurations on top of a fixed binary header: 0, 1, 0, 1, 0, 0, I2CADR0, R/W.

Table 11. I²C-bus interface addressing

| | I ² C-bus address (R/W = 0, write) | I ² C-bus address (R/W = 1, read) |
|---|--|---|
| 0 | 0x50 | 0x51 |
| 1 | 0x52 | 0x53 |

10.4 PN7120 clock concept

There are 4 different clock sources in PN7120:

- 27.12 MHz clock coming either/or from:
 - Internal oscillator for 27.12 MHz crystal connection
 - Integrated PLL unit which includes a 1 GHz VCO
- 13.56 MHz RF clock recovered from RF field
- Low-power oscillator 20 MHz
- Low-power oscillator 380 kHz

PN7120

NFC controller with integrated firmware, supporting all NFC Forum modes

10.4.1 27.12 MHz quartz oscillator

When enabled, the 27.12 MHz quartz oscillator applied to PN7120 is the time reference for the RF front end when PN7120 is behaving in Reader mode or NFCIP-1 initiator.

Therefore stability of the clock frequency is an important factor for reliable operation. It is recommended to adopt the circuit shown in Figure 9.

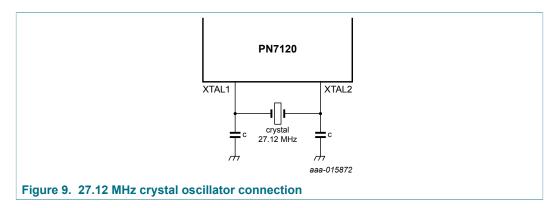


Table 12 describes the levels of accuracy and stability required on the crystal.

Table 12. Crystal requirements

| Symbol | Parameter | Conditions | | Min | Тур | Max | Unit |
|----------------------|------------------------------|--|-----|------|-------|------|------|
| f _{xtal} | crystal frequency | ISO/IEC and FCC compliancy | | - | 27.12 | - | MHz |
| Δf_{xtal} | crystal frequency accuracy | full operating range | [1] | -100 | - | +100 | ppm |
| | | all V _{BAT} range; T = 20 °C | [1] | -50 | - | +50 | ppm |
| | | all temperature range; V _{BAT} = 3.6 V | [1] | -50 | - | +50 | ppm |
| ESR | equivalent series resistance | | | - | 50 | 100 | Ω |
| C _L | load capacitance | | | - | 10 | - | pF |
| P _{o(xtal)} | crystal output power | | | - | - | 100 | μW |

^[1] This requirement is according to FCC regulations requirements. To meet only ISO/IEC 14443 and ISO/IEC 18092, then ± 14 kHz apply.

10.4.2 Integrated PLL to make use of external clock

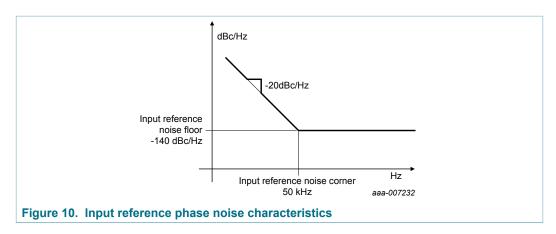
When enabled, the PLL is designed to generate a low noise 27.12 MHz for an input clock 13 MHz, 19.2 MHz, 24 MHz, 26 MHz, 38.4 MHz and 52 MHz.

The 27.12 MHz of the PLL is used as the time reference for the RF front end when PN7120 is behaving in Reader mode or NFC Initiator as well as in NFC Target when configured in Active communication mode.

The input clock on XTAL1 shall comply with the following phase noise requirements for the following input frequency: 13 MHz, 19.2 MHz, 24 MHz, 26 MHz, 38.4 MHz and 52 MHz:

PN7120

NFC controller with integrated firmware, supporting all NFC Forum modes



This phase noise is equivalent to an RMS jitter of 6.23 ps from 10 Hz to 1 MHz. For configuration of input frequency, refer to [8]. There are 6 pre programmed and validated frequencies for the PLL: 13 MHz, 19.2 MHz, 24 MHz, 26 MHz, 38.4 MHz and 52 MHz.

Table 13. PLL input requirements
Coupling: single-ended, AC coupling;

| Symbol | Parameter | Conditions | | Min | Тур | Max | Unit |
|------------------------|------------------------------------|--|-----|------|------|---------------|-----------|
| f _{clk} | clock frequency | ISO/IEC and FCC | | - | 13 | - | MHz |
| | | compliancy | | - | 19.2 | - | MHz |
| | | | | - | 24 | - | MHz |
| | | | | - | 26 | - | MHz |
| | | | | - | 38.4 | - | MHz |
| | | | | - | 52 | - | MHz |
| f _{i(ref)acc} | reference input frequency accuracy | full operating range; frequencies typical values: 13 MHz, 26 MHz and 52 MHz | [1] | -25 | - | +25 | ppm |
| | | full operating range; frequencies typical values: 19.2 MHz, 24 MHz and 38.4 MHz | [1] | -50 | - | +50 | ppm |
| φ _n | phase noise | input noise floor at 50 kHz | | -140 | - | - | dB/H z |
| Sinusoida | I shape | | | 1 | | | |
| $V_{i(p-p)}$ | peak-to-peak input voltage | | | 0.2 | - | 1.8 | V |
| V _{i(clk)} | clock input voltage | | | 0 | - | 1.8 | V |
| Square sh | ape | | | | | | |
| V _{i(clk)} | clock input voltage | | | 0 | - | 1.8 ± 10 % | V |

^[1] This requirement is according to FCC regulations requirements. To meet only ISO/IEC 14443 and ISO/IEC 18092, then ± 400 ppm limits apply.

For detailed description of clock request mechanisms, refer to [4] and [5].

PN7120

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10.4.3 Low-power 20 MHz oscillator

Low-power 20 MHz oscillator is used as system clock of the system.

10.4.4 Low-power 380 kHz oscillator

A Low Frequency Oscillator (LFO) is implemented to drive a counter (WUC) waking-up PN7120 from Standby state. This allows implementation of low-power reader polling loop at application level. Moreover, this 380 kHz is used as the reference clock for write access to EEPROM memory.

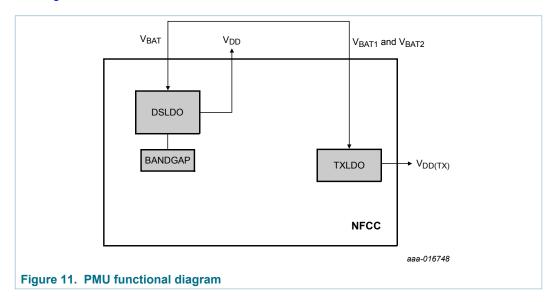
10.5 Power concept

10.5.1 PMU functional description

The Power Management Unit of PN7120 generates internal supplies required by PN7120 out of V_{BAT} input supply voltage:

- V_{DD}: internal supply voltage
- V_{DD(TX)}: output supply voltage for the RF transmitter

The Figure 11 describes the main blocks available in PMU:



10.5.2 DSLDO: Dual Supply LDO

The input pin of the DSLDO is V_{BAT}.

The Low drop-out regulator provides V_{DD} required in PN7120.

10.5.3 TXLDO

This is the LDO which generates the transmitter voltage.

The value of $V_{DD(TX)}$ is configured at 3.1 V ± 0.2 V.

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 $V_{\text{DD}(TX)}$ value is given according to the minimum targeted V_{BAT} value for which Reader mode shall work.

For V_{BAT} above 3.1 V, $V_{DD(TX)} = 3.1$ V:

$$V_{BAT} \ge 3.1V \Rightarrow V_{DD(TX)} = 3.1V$$

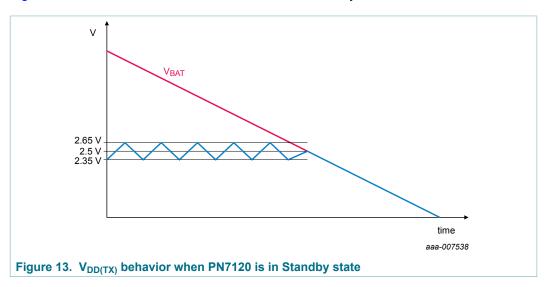
$$3.1V > V_{BAT} \ge 2.3V \Rightarrow V_{DD(TX)} = V_{BAT}$$

In Standby state, $V_{DD(TX)}$ is around 2.5 V with some ripples; it toggles between 2.35 V to 2.65 V with a period which depends on the capacitance and load on $V_{DD(TX)}$.

Figure 12 shows V_{DD(TX)} behavior for 3.1 V:



Figure 13 shows the case where the PN7120 is in Standby state:



NFC controller with integrated firmware, supporting all NFC Forum modes

10.5.3.1 TXLDO limiter

The TXLDO includes a current limiter to avoid too high current within TX1, TX2 when in reader or initiator modes.

The current limiter block compares an image of the TXLDO output current to a reference. Once the reference is reached, the output current gets limited which is equivalent to a typical output current of 220 mA whatever $V_{BAT} = 2.7 \text{ V}$ and 180 mA for $V_{BAT} = 3.1 \text{ V}$.

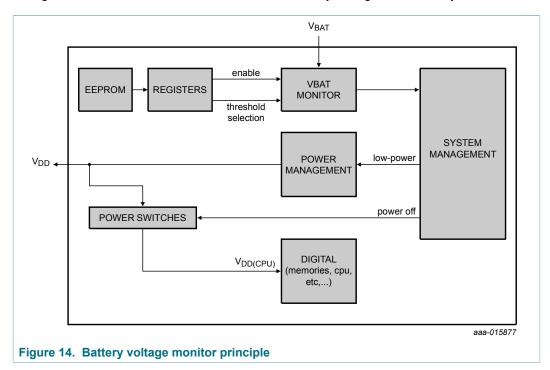
10.5.4 Battery voltage monitor

The PN7120 features low-power V_{BAT} voltage monitor which protects the host device battery from being discharged below critical levels. When V_{BAT} voltage goes below $V_{BAT critical}$ threshold, then the PN7120 goes in Monitor state. Refer to Figure 14 for principle schematic of the battery monitor.

The battery voltage monitor is enabled via an EEPROM setting.

The V_{BATcritical} threshold can be configured to 2.3 V or 2.75 V by an EEPROM setting.

At the first start-up, V_{BAT} voltage monitor functionality is OFF and then enabled if properly configured in EEPROM. The PN7120 monitors battery voltage continuously.



The value of the critical level can be configured to 2.3 V or 2.75 V by an EEPROM setting. This value has a typical hysteresis around 150 mV.

10.6 Reset concept

10.6.1 Resetting PN7120

To enter reset there are 2 ways:

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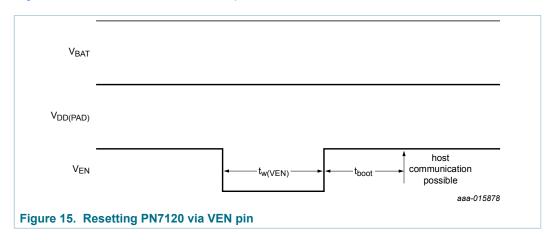
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- Pulling VEN voltage low (Hard Power Down state)
- if V_{BAT} monitor is enabled: lowering V_{BAT} below the monitor threshold (Monitor state, if VEN voltage is kept above 1.1 V)

Reset means resetting the embedded FW execution and the registers values to their default values. Part of these default values is defined from EEPROM data loaded values, others are hardware defined. See [4] to know which ones are accessible to tune PN7120 to the application environment.

To get out of reset:

Pulling VEN voltage high with V_{BAT} above V_{BAT} monitor threshold if enabled
 Figure 15 shows reset done via VEN pin.



See <u>Section 15.3.2</u> for the timings values.

10.6.2 Power-up sequences

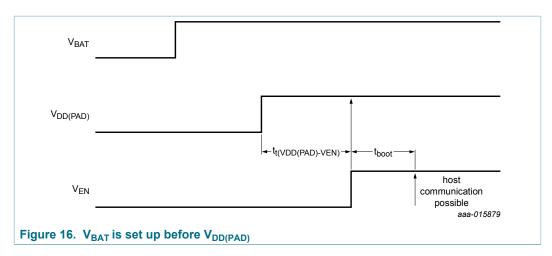
There are 2 different supplies for PN7120. PN7120 allows these supplies to be set up independently, therefore different power-up sequences have to be considered.

10.6.2.1 V_{BAT} is set up before V_{DD(PAD)}

This is at least the case when V_{BAT} pin is directly connected to the battery and when PN7120 V_{BAT} is always supplied as soon the system is supplied.

As VEN pin is referred to V_{BAT} pin, VEN voltage shall go high after V_{BAT} has been set.

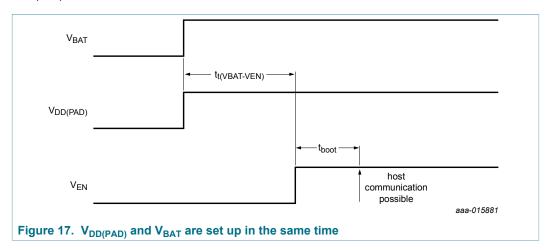
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See <u>Section 15.2.3</u> for the timings values.

10.6.2.2 $V_{DD(PAD)}$ and V_{BAT} are set up in the same time

It is at least the case when V_{BAT} pin is connected to a PMU/regulator which also supply $V_{DD(PAD)}$.



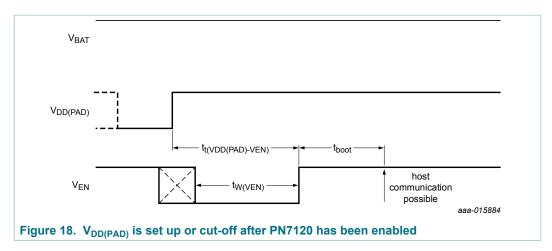
See <u>Section 15.2.3</u> for the timings values.

10.6.2.3 PN7120 has been enabled before $V_{DD(PAD)}$ is set up or before $V_{DD(PAD)}$ has been cut off

This can be the case when V_{BAT} pin is directly connected to the battery and when $V_{DD(PAD)}$ is generated from a PMU. When the battery voltage is too low, then the PMU might no more be able to generate $V_{DD(PAD)}$. When the device gets charged again, then $V_{DD(PAD)}$ is set up again.

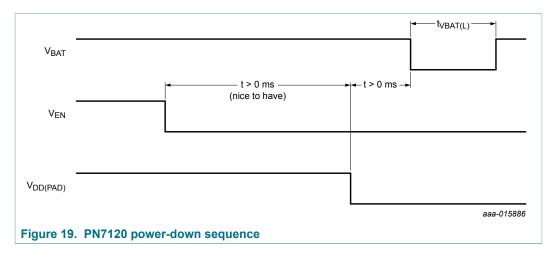
As the pins to select the interface are biased from $V_{DD(PAD)}$, when $V_{DD(PAD)}$ disappears the pins might not be correctly biased internally and the information might be lost. Therefore it is required to make the IC boot after $V_{DD(PAD)}$ is set up again.

NFC controller with integrated firmware, supporting all NFC Forum modes



See Section 15.2.3 for the timings values.

10.6.3 Power-down sequence



10.7 Contactless Interface Unit

PN7120 supports various communication modes at different transfer speeds and modulation schemes. The following chapters give more detailed overview of selected communication modes.

Remark: all indicated modulation index and modes in this chapter are system parameters. This means that beside the IC settings a suitable antenna tuning is required to achieve the optimum performance.

10.7.1 Reader/Writer communication modes

Generally 5 Reader/Writer communication modes are supported:

- PCD Reader/Writer for ISO/IEC 14443 type A and for MIFARE Classic
- PCD Reader/Writer for Jewel/Topaz
- PCD Reader/Writer for FeliCa
- PCD Reader/Writer for ISO/IEC 14443B

PN7120

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NFC controller with integrated firmware, supporting all NFC Forum modes

VCD Reader/Writer for ISO/IEC 15693/ICODE

10.7.1.1 Communication mode for ISO/IEC 14443 type A, MIFARE Classic and Jewel/Topaz PCD

The ISO/IEC 14443A/MIFARE Classic PCD communication mode is the general reader to card communication scheme according to the ISO/IEC 14443A specification. This modulation scheme is as well used for communications with Jewel/Topaz cards.

<u>Figure 20</u> describes the communication on a physical level, the communication table describes the physical parameters (the numbers take the antenna effect on modulation depth for higher data rates).

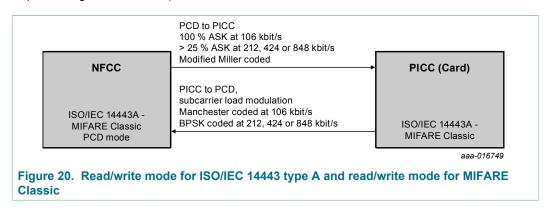


Table 14. Communication overview for ISO/IEC 14443 type A and read/write mode for MIFARE Classic

| Table 14. Communication | OVELVIEW IOI 130/ | ico 14443 type A a | iiu reau/Wille IIIU | UE IOI WIIFARE CI | a3316 | | |
|---------------------------------------|---|----------------------------|---------------------------------------|----------------------------|----------------------------|--|--|
| Communication direction | ISO/IEC 14443A/ MIFARE Classic/ Jewel/ Topaz | | ISO/IEC 14443A higher transfer speeds | | | | |
| | Transfer speed | 106 kbit/s | 212 kbit/s | 424 kbit/s | 848 kbit/s | | |
| | Bit length | (128/13.56) µs | (64/13.56) μs | (32/13.56) μs | (16/13.56) µs | | |
| PN7120 → PICC | | 1 | | | , | | |
| (data sent by PN7120 to a card) | modulation on PN7120 side | 100 % ASK | > 25 % ASK | > 25 % ASK | > 25 % ASK | | |
| | bit coding | Modified Miller | Modified Miller | Modified Miller | Modified Miller | | |
| PICC → PN7120 | | | | | | | |
| (data received by PN7120 from a card) | modulation on PICC side | subcarrier load modulation | subcarrier load modulation | subcarrier load modulation | subcarrier load modulation | | |
| | subcarrier frequency | 13.56 MHz/16 | 13.56 MHz/16 | 13.56 MHz/16 | 13.56 MHz/16 | | |
| | bit coding | Manchester | BPSK | BPSK | BPSK | | |

The contactless coprocessor and the on-chip CPU of PN7120 handle the complete ISO/ IEC 14443A/MIFARE Classic RF-protocol, nevertheless a dedicated external host has to handle the application layer communication.

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10.7.1.2 FeliCa PCD communication mode

The FeliCa communication mode is the general Reader/Writer to card communication scheme according to the FeliCa specification. <u>Figure 21</u> describes the communication on a physical level, the communication overview describes the physical parameters.

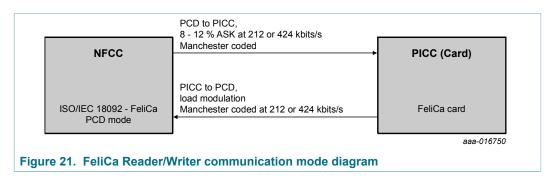


Table 15. Overview for FeliCa Reader/Writer communication mode

| Communication direction | | FeliCa | FeliCa higher transfer speeds |
|---------------------------------------|---------------------------------------|-----------------|-------------------------------|
| | Transfer speed | 212 kbit/s | 424 kbit/s |
| | Bit length (64/13.56) μs (32/13.56) μ | | (32/13.56) µs |
| PN7120 → PICC | | | |
| (data sent by PN7120 to a card) | modulation on PN7120 side | 8 % - 12 % ASK | 8 % - 12 % ASK |
| | bit coding | Manchester | Manchester |
| PICC → PN7120 | | | |
| (data received by PN7120 from a card) | modulation on PICC side | load modulation | load modulation |
| | subcarrier frequency | no subcarrier | no subcarrier |
| | bit coding | Manchester | Manchester |

The contactless coprocessor of PN7120 and the on-chip CPU handle the FeliCa protocol. Nevertheless a dedicated external host has to handle the application layer communication.

10.7.1.3 ISO/IEC 14443B PCD communication mode

The ISO/IEC 14443B PCD communication mode is the general reader to card communication scheme according to the ISO/IEC 14443B specification. Figure 22 describes the communication on a physical level, the communication table describes the physical parameters.

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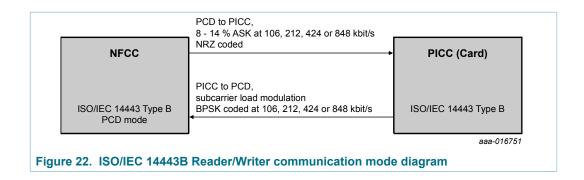


Table 16. Overview for ISO/IEC 14443B Reader/Writer communication mode

| Communication | | ISO/IEC 14443B | ISO/IEC 14443B | higher transfer sp | transfer speeds | | |
|---------------------------------------|---------------------------|----------------------------|----------------------------|----------------------------|----------------------------|--|--|
| direction | Transfer speed | 106 kbit/s | 212 kbit/s | 424 kbit/s | 848 kbit/s | | |
| | Bit length | (128/13.56) µs | (64/13.56) μs | (32/13.56) μs | (16/13.56) μs | | |
| PN7120 → PICC | | | | | | | |
| (data sent by PN7120 to a card) | modulation on PN7120 side | 8 % - 14 % ASK | | |
| | bit coding | NRZ | NRZ | NRZ | NRZ | | |
| PICC → PN7120 | | | | | | | |
| (data received by PN7120 from a card) | modulation on PICC side | subcarrier load modulation | subcarrier load modulation | subcarrier load modulation | subcarrier load modulation | | |
| | subcarrier frequency | 13.56 MHz/16 | 13.56 MHz/16 | 13.56 MHz/16 | 13.56 MHz/16 | | |
| | bit coding | BPSK | BPSK | BPSK | BPSK | | |

The contactless coprocessor and the on-chip CPU of PN7120 handles the complete ISO/IEC 14443B RF-protocol, nevertheless a dedicated external host has to handle the application layer communication.

10.7.1.4 R/W mode for NFC forum Type 5 Tag

The R/W mode for NFC forum Type 5 Tag (T5T) is the general reader to card communication scheme according to the ISO/IEC 15693 specification. PN7120 will communicate with VICC (Type 5 Tag) using only the 26.48 kbit/s with single subcarrier data rate of the VICC.

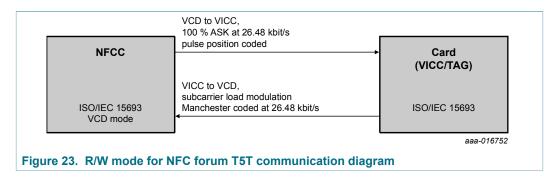


Figure 23 and Table 17 show the communication schemes used.

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Table 17. Communication overview for NFC forum T5T R/W mode

| Communication direction | | |
|--------------------------------------|---------------------------|---|
| PN7120 → VICC | | |
| (data sent by PN7120 to a tag) | transfer speed | 26.48 kbit/s |
| | bit length | (512/13.56) µs |
| | modulation on PN7120 side | 100 % ASK |
| | bit coding | pulse position modulation 1 out of 4 mode |
| VICC → PN7120 | | , |
| (data received by PN7120 from a tag) | transfer speed | 26.48 kbit/s |
| | bit length | (512/13.56) µs |
| | modulation on VICC side | subcarrier load modulation |
| | subcarrier frequency | single subcarrier |
| | bit coding | Manchester |

10.7.2 ISO/IEC 18092, Ecma 340 NFCIP-1 communication modes

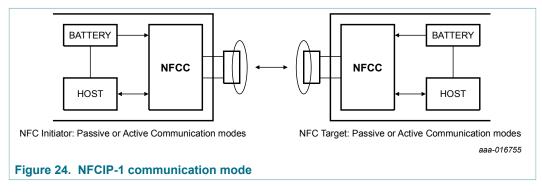
An NFCIP-1 communication takes place between 2 devices:

- NFC Initiator: generates RF field at 13.56 MHz and starts the NFCIP-1 communication.
- NFC Target: responds to NFC Initiator command either in a load modulation scheme in Passive communication mode or using a self-generated and self-modulated RF field for Active communication mode.

The NFCIP-1 communication differentiates between Active and Passive communication modes.

- Active communication mode means both the NFC Initiator and the NFC Target are using their own RF field to transmit data
- Passive communication mode means that the NFC Target answers to an NFC Initiator command in a load modulation scheme. The NFC Initiator is active in terms of generating the RF field.

PN7120 supports the Active Target, Active Initiator, Passive Target and Passive Initiator communication modes at the transfer speeds 106 kbit/s, 212 kbit/s and 424 kbit/s as defined in the NFCIP-1 standard.



Nevertheless a dedicated external host has to handle the application layer communication.

PN7120

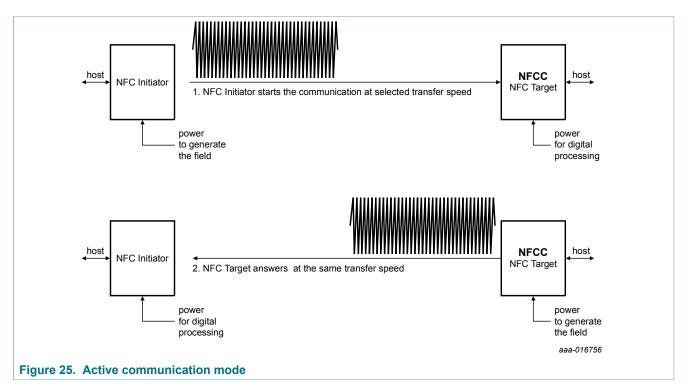
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10.7.2.1 ACTIVE communication mode

Active communication mode means both the NFC Initiator and the NFC Target are using their own RF field to transmit data.



The following table gives an overview of the Active communication modes:

Table 18. Overview for Active communication mode

| Communication direction | | ISO/IEC 18092, Ecma 340, NFCIP-1 | | | | |
|-----------------------------|------------|----------------------------------|-------------------------------|-------------------------------|--|--|
| | Baud rate | 106 kbit/s | 212 kbit/s | 424 kbit/s | | |
| | Bit length | (128/13.56) µs | (64/13.56) μs | (32/13.56) μs | | |
| NFC Initiator to NFC Target | | | | | | |
| | modulation | 100 % ASK | 8 % - 30 % ASK ^[1] | 8 % - 30 % ASK ^[1] | | |
| | bit coding | Modified Miller | Manchester | Manchester | | |
| NFC Target to NFC Initiator | | | | | | |
| | modulation | 100 % ASK | 8 % - 30 % ASK ^[1] | 8 % - 30 % ASK ^[1] | | |
| | bit coding | Miller | Manchester | Manchester | | |

^[1] This modulation index range is according to NFCIP-1 standard. It might be that some NFC forum type 3 cards does not withstand the full range as based on FeliCa range which is narrow (8 % to 14 % ASK). To adjust the index, see [6].

10.7.2.2 Passive communication mode

Passive communication mode means that the NFC Target answers to an NFC Initiator command in a load modulation scheme.

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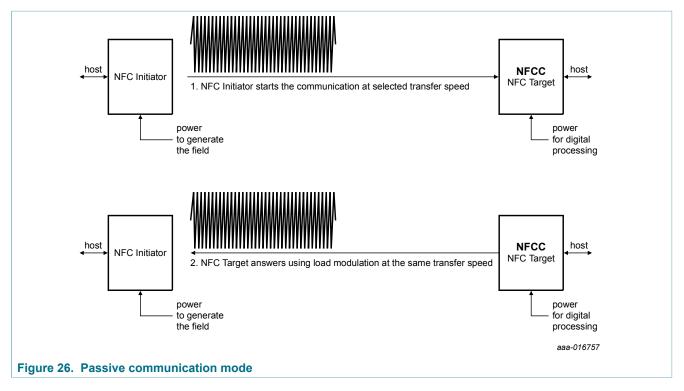


Table 19 gives an overview of the Passive communication modes:

Table 19. Overview for Passive communication mode

| Communication direction | | ISO/IEC 18092, Ed | cma 340, NFCIP-1 | |
|-----------------------------|----------------------|----------------------------|-------------------------------|-------------------------------|
| | Baud rate | 106 kbit/s | 212 kbit/s | 424 kbit/s |
| | Bit length | (128/13.56) µs | (64/13.56) μs | (32/13.56) μs |
| NFC Initiator to NFC Target | | | | |
| | modulation | 100 % ASK | 8 % - 30 % ASK ^[1] | 8 % - 30 % ASK ^[1] |
| | bit coding | Modified Miller | Manchester | Manchester |
| NFC Target to NFC Initiator | | | | ' |
| | modulation | subcarrier load modulation | load modulation | load modulation |
| | subcarrier frequency | 13.56 MHz/16 | no subcarrier | no subcarrier |
| | bit coding | Manchester | Manchester | Manchester |

^[1] This modulation index range is according to NFCIP-1 standard. It might be that some NFC forum type 3 cards does not withstand the full range as based on FeliCa range which is narrow (8 % to 14 % ASK). To adjust the index, see[6].

10.7.2.3 NFCIP-1 framing and coding

The NFCIP-1 framing and coding in Active and Passive communication modes are defined in the NFCIP-1 standard: ISO/IEC 18092 or Ecma 340.

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10.7.2.4 NFCIP-1 protocol support

The NFCIP-1 protocol is not completely described in this document. For detailed explanation of the protocol, refer to the ISO/IEC 18092 or Ecma 340 NFCIP-1 standard. However the datalink layer is according to the following policy:

- Transaction includes initialization, anticollision methods and data transfer. This sequence must not be interrupted by another transaction
- PSL shall be used to change the speed between the target selection and the data transfer, but the speed should not be changed during a data transfer

10.7.3 Card communication modes

PN7120 can be addressed as a ISO/IEC 14443A or ISO/IEC 14443B cards. This means that PN7120 can generate an answer in a load modulation scheme according to the ISO/IEC 14443A or ISO/IEC 14443B interface description.

Remark: PN7120 does not support a complete card protocol. This has to be handled by the host controller.

Table 20 and Table 21 describe the physical parameters.

10.7.3.1 ISO/IEC 14443A/MIFARE Classic card communication mode

Table 20. Overview for ISO/IEC 14443A/MIFARE Classic card communication mode

| Communication | | ISO/IEC 14443A | ISO/IEC 14443A higher transfer speed | | |
|---------------------------------------|---------------------------|----------------------------|--------------------------------------|----------------------------|--|
| direction | Transfer speed | 106 kbit/s | 212 kbit/s | 424 kbit/s | |
| | Bit length | (128/13.56) μs | (64/13.56) μs | (32/13.56) μs | |
| PCD → PN7120 | | | | | |
| (data received by PN7120 from a card) | modulation on PCD side | 100 % ASK | > 25 % ASK | > 25 % ASK | |
| | bit coding | Modified Miller | Modified Miller | Modified Miller | |
| PN7120 → PCD | | | | | |
| (data sent by PN7120 to a card) | modulation on PN7120 side | subcarrier load modulation | subcarrier load modulation | subcarrier load modulation | |
| | subcarrier frequency | 13.56 MHz/16 | 13.56 MHz/16 | 13.56 MHz/16 | |
| | bit coding | Manchester | BPSK | BPSK | |

NFC controller with integrated firmware, supporting all NFC Forum modes

10.7.3.2 ISO/IEC 14443B card communication mode

Table 21. Overview for ISO/IEC 14443B card communication mode

| Communication | | ISO/IEC 14443B | ISO/IEC 14443B hig | her transfer speeds |
|------------------------------------|---------------------------|----------------------------|----------------------------|----------------------------|
| direction | Transfer speed | 106 kbit/s | 212 kbit/s | 424 kbit/s |
| | Bit length | (128/13.56) μs | (64/13.56) μs | (32/13.56) μs |
| PCD → PN7120 | | | | |
| (data received by PN7120 from a | modulation on PCD side | 8 % - 14 % ASK | 8 % - 14 % ASK | 8 % - 14 % ASK |
| Reader) | bit coding | NRZ | NRZ | NRZ |
| PN7120 → PCD | | | | |
| (data sent by PN7120 to a Reader) | modulation on PN7120 side | subcarrier load modulation | subcarrier load modulation | subcarrier load modulation |
| | subcarrier frequency | 13.56 MHz/16 | 13.56 MHz/16 | 13.56 MHz/16 |
| | bit coding | BPSK | BPSK | BPSK |

10.7.4 Frequency interoperability

When in communication, PN7120 is generating some RF frequencies. PN7120 is also sensitive to some RF signals as it is looking from data in the field.

In order to avoid interference with others RF communication, it is required to tune the antenna and design the board according to [5].

Although ISO/IEC 14443 and ISO/IEC 18092/Ecma 340 allows an RF frequency of 13.56 MHz \pm 7 kHz, FCC regulation does not allow this wide spread and limits the dispersion to \pm 50 ppm, which is in line with PN7120 capability.

NFC controller with integrated firmware, supporting all NFC Forum modes

11 Application design-in information

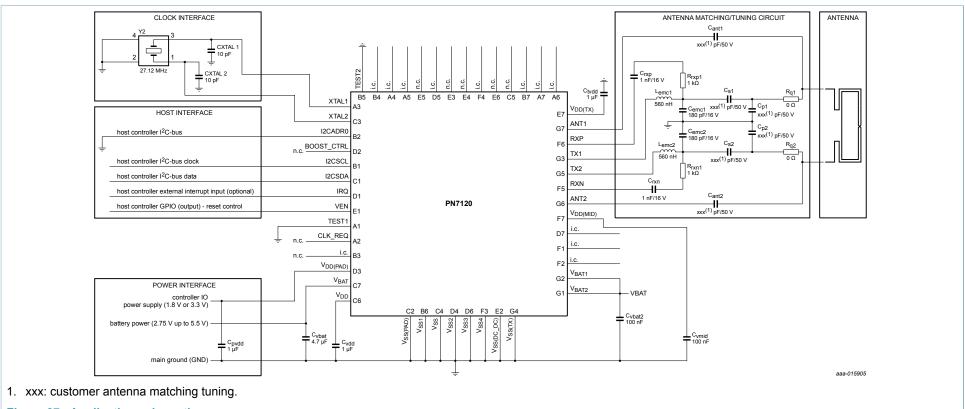


Figure 27. Application schematic

NFC controller with integrated firmware, supporting all NFC Forum modes

12 Limiting values

Table 22. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|------------------|-------------------------------------|--|-----|------|------|
| $V_{DD(PAD)}$ | V _{DD(PAD)} supply voltage | supply voltage for host interface | _ | 4.2 | V |
| V_{BAT} | battery supply voltage | | - | 6 | V |
| V _{ESD} | electrostatic discharge voltage | HBM; 1500 Ω, 100 pF; EIA/JESD22-A114-D | - | 1.5 | kV |
| | | CDM; field induced model; EIA/JESC22-C101-C | - | 500 | V |
| T _{stg} | storage temperature | | -55 | +150 | °C |
| P _{tot} | total power dissipation | all modes [1] | - | 0.55 | W |
| $V_{RXN(i)}$ | RXN input voltage | | 0 | 2.5 | V |
| $V_{RXP(i)}$ | RXP input voltage | | 0 | 2.5 | V |

^[1] The design of the solution shall be done so that for the different use cases targeted the power to be dissipated from the field or generated by PN7120 does not exceed this value.

NFC controller with integrated firmware, supporting all NFC Forum modes

13 Recommended operating conditions

Table 23. Operating conditions

| Symbol | Parameter | Conditions | | Min | Тур | Max | Uni |
|------------------------|---|---|-------|------------------|-----|------|-----|
| T _{amb} | ambient temperature | JEDEC PCB-0.5 | | -30 | +25 | +85 | °C |
| V_{BAT} | battery supply voltage | battery monitor enabled; V _{SS} = 0 V | [1] | 2.3 | - | 5.5 | V |
| | | Card Emulation and Passive Target; V _{SS} = 0 V | [1][2 | []] 2.3 | _ | 5.5 | V |
| | | Reader, Active Initiator and Active Target; V _{SS} = 0 V | [1][2 | []] 2.7 | - | 5.5 | V |
| V_{DD} | supply voltage | | | 1.65 | 1.8 | 1.95 | ٧ |
| $V_{DD(PAD)}$ | V _{DD(PAD)} supply voltage | supply voltage for host interface | | | | | |
| | | 1.8 V host supply; V _{SS} = 0 V | [1] | 1.65 | 1.8 | 1.95 | V |
| | | 3 V host supply; V _{SS} = 0 V | [1] | 3.0 | - | 3.6 | V |
| P _{tot} | total power dissipation | Reader; $I_{VDD(TX)} = 100$ mA; $V_{BAT} = 5.5 \text{ V}$ | | - | - | 0.5 | W |
| I _{O(VDDTX)} | output current on pin $V_{\text{DD(TX)}}$ | | [2] | - | - | 100 | mA |
| I _{BAT} | battery supply current | in Hard Power Down state; V _{BAT} = 3.6 V; T = 25 °C | | - | 10 | 12 | μA |
| | | in Standby state; V _{BAT} = 3.6 V; T = 25 °C | | - | - | 20 | μΑ |
| | | in Monitor state; V _{BAT} = 2.75 V; T = 25 °C | | - | - | 12 | μΑ |
| | | in low-power polling loop; V _{BAT} = 3.6 V; T = 25 °C; loop time = 500 ms | | - | 150 | - | μA |
| I _{VBAT(tot)} | total supply current on V_{BAT} | PCD mode at typical 3 V | [3] | | - | 170 | mA |
| I _{th(Ilim)} | current limit threshold current | current limiter on $V_{DD(TX)}$ pin; $V_{DD(TX)} = 3.1 \text{ V}$ | [3][4 |]_ | 180 | - | mA |

 V_{SS} represents V_{SS} , V_{SS1} , V_{SS2} , V_{SS3} , V_{SS4} , $V_{SS(PAD)}$ and $V_{SS(TX)}$. The antenna should be tuned not to exceed this current limit (the detuning effect when coupling with another device must be taken into account).

The antenna shall be tuned not to exceed the maximum of I_{VBAT}.

This is the threshold of a built-in protection done to limit the current out of V_{DD(TX)} in case of any issue at antenna pins to avoid burning the device. It is not allowed in operational mode to have I_{VDD(TX)} such that I_{VBAT} maximum value is exceeded.

NFC controller with integrated firmware, supporting all NFC Forum modes

14 Thermal characteristics

Table 24. Thermal characteristics

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|----------------------|---|--|-----|-----|-----|------|
| R _{th(j-a)} | thermal resistance from junction to ambient | in free air with exposed pad soldered on a 4 layer JEDEC PCB | - | 74 | - | K/W |

NFC controller with integrated firmware, supporting all NFC Forum modes

15 Characteristics

15.1 Current consumption characteristics

Table 25. Current consumption characteristics for operating ambient temperature range

| Symbol | Parameter | Conditions | | Min | Тур | Max | Unit |
|------------------------|--|---|------|-----|-----|-----|------|
| I _{BAT} | battery supply current | in Hard Power Down state; V _{BAT} = 3.6 V; VEN voltage = 0 V | | - | 10 | 18 | μΑ |
| | | in Standby state; V _{BAT} = 3.6 V; including emulation phase of polling loop | [1] | - | 20 | 35 | μΑ |
| | | in Idle and Target Active power states; V _{BAT} = 3.6 V | [2] | - | 6 | - | mA |
| | | in Initiator Active power state; $V_{BAT} = 3.6 \text{ V}$ | [2] | - | 13 | - | mA |
| | | in Monitor state; V _{BAT} = 2.75 V | [3] | - | 10 | 18 | μΑ |
| I _{O(VDDTX)} | output current on pin $V_{\text{DD(TX)}}$ | | [4][| 5] | 30 | 100 | mA |
| I _{O(VDDPAD)} | output current on pin $V_{\text{DD(PAD)}}$ | total current which can be pulled on $V_{\text{DD}(\text{PAD})}$ referenced outputs | | - | _ | 15 | mA |

^[1] Refer to Section 10.1.2.4 for the description of the power modes.

15.2 Functional block electrical characteristics

15.2.1 Battery voltage monitor characteristics

Table 26. Battery voltage monitor characteristics

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|------------------|--------------------|---------------|------|------|------|------|
| V _{th} | threshold voltage | set to 2.3 V | 2.2 | 2.3 | 2.4 | V |
| | | set to 2.75 V | 2.65 | 2.75 | 2.85 | V |
| V _{hys} | hysteresis voltage | | 100 | 150 | 200 | mV |

15.2.2 Reset via VEN

Table 27. Reset timing

| Table 21: 1000t tilling | | | | | | | | | |
|-------------------------|-----------------|------------|-----|-----|-----|------|--|--|--|
| Symbol | Parameter | Conditions | Min | Тур | Max | Unit | | | |
| t _{W(VEN)} | VEN pulse width | to reset | 3 | - | - | μs | | | |
| t _{boot} | boot time | | - | - | 2.5 | ms | | | |

PN7120

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^[2] Refer to <u>Section 10.1.2.5</u> for the description of the polling loop.

This is the same value for $V_{BAT} = 2.3 \text{ V}$ when the monitor threshold is set to 2.3 V.

^[4] I_{VDD(TX)} depends on V_{DD(TX)} and on the external circuitry connected to TX1 and TX2.

^[5] During operation with a typical circuitry as recommended by NXP in [6], the overall current is below 100 mA even when loaded by target/card/tag.

NFC controller with integrated firmware, supporting all NFC Forum modes

15.2.3 Power-up timings

Table 28. Power-up timings

| | <u> </u> | | | | | |
|-----------------------------|---|--|-----|-----|-----|------|
| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
| t _{t(VBAT-VEN)} | transition time from pin V_{BAT} to pin VEN | V _{BAT} , VEN voltage = HIGH | 0 | - | - | ms |
| t _{t(VDDPAD-VEN)} | transition time from pin $V_{DD(PAD)}$ to pin VEN | V _{DD(PAD)} , VEN voltage = HIGH | 0 | - | - | ms |
| t _{t(VBAT-VDDPAD)} | transition time from pin V_{BAT} to pin $V_{DD(PAD)}$ | V_{BAT} , $V_{DD(PAD)}$ = HIGH | 0 | - | - | ms |

15.2.4 Power-down timings

Table 29. Power-down timings

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|----------------------|---------------------------|------------|-----|-----|-----|------|
| t _{VBAT(L)} | time V _{BAT} LOW | | 20 | - | - | ms |

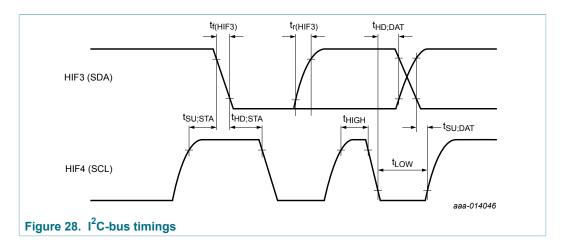
15.2.5 Thermal protection

Table 30. Thermal threshold

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-------------------------|---|------------|-----|-----|-----|------|
| T _{th(act)otp} | overtemperature protection activation threshold temperature | | 120 | 125 | 130 | °C |

15.2.6 I²C-bus timings

Here below are timings and frequency specifications.



NFC controller with integrated firmware, supporting all NFC Forum modes

Table 31. High-speed mode I²C-bus timings specification

| Symbol | Parameter | Conditions | Min | Max | Unit |
|--------------------------|--|--|-------------------------|-----|------|
| f _{clk(I2CSCL)} | clock frequency on pin I2CSCL | I^2 C-bus SCL; C _b < 100 pF | 0 | 3.4 | MHz |
| t _{SU;STA} | set-up time for a repeated START condition | C _b < 100 pF | 160 | - | ns |
| t _{HD;STA} | hold time (repeated) START condition | C _b < 100 pF | 160 | - | ns |
| t_{LOW} | LOW period of the SCL clock | C _b < 100 pF | 160 | - | ns |
| t _{HIGH} | HIGH period of the SCL clock | C _b < 100 pF | 60 | - | ns |
| t _{SU;DAT} | data set-up time | C _b < 100 pF | 10 | - | ns |
| t _{HD;DAT} | data hold time | C _b < 100 pF | 0 | - | ns |
| t _{r(I2CSDA)} | rise time on pin I2CSDA | I^2 C-bus SDA; C _b < 100 pF | 10 | 80 | ns |
| $t_{f(I2CSDA)}$ | fall time on pin I2CSDA | I^2 C-bus SDA; C _b < 100 pF | 10 | 80 | ns |
| V _{hys} | hysteresis voltage | Schmitt trigger inputs; C _b < 100 pF | 0.1V _{DD(PAD)} | - | V |

Table 32. Fast mode I²C-bus timings specification

| Symbol | Parameter | Conditions | Min | Max | Unit |
|--------------------------|--|--|-------------------------|-----|------|
| f _{clk(I2CSCL)} | clock frequency on pin I2CSCL | I^2 C-bus SCL; C _b < 400 pF | 0 | 400 | kHz |
| t _{SU;STA} | set-up time for a repeated START condition | C _b < 400 pF | 600 | _ | ns |
| t _{HD;STA} | hold time (repeated) START condition | C _b < 400 pF | 600 | _ | ns |
| t_{LOW} | LOW period of the SCL clock | C _b < 400 pF | 1.3 | - | μs |
| t _{HIGH} | HIGH period of the SCL clock | C _b < 400 pF | 600 | - | ns |
| t _{SU;DAT} | data set-up time | C _b < 400 pF | 100 | - | ns |
| t _{HD;DAT} | data hold time | C _b < 400 pF | 0 | 900 | ns |
| V _{hys} | hysteresis voltage | Schmitt trigger inputs; C _b < 400 pF | 0.1V _{DD(PAD)} | - | V |

NFC controller with integrated firmware, supporting all NFC Forum modes

15.3 Pin characteristics

15.3.1 XTAL1 and XTAL2 pins characteristics

Table 33. Input clock characteristics on XTAL1 when using PLL

| | • | | | | | | |
|--------------|----------------------------|------------|-----|-----|-----|------|--|
| Symbol | Parameter | Conditions | Min | Тур | Max | Unit | |
| $V_{i(p-p)}$ | peak-to-peak input voltage | | 0.2 | - | 1.8 | V | |
| δ | duty cycle | | 35 | - | 65 | % | |

Table 34. Pin characteristics for XTAL1 when PLL input

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-------------------|----------------------------------|----------------------|-----|-----|----------|------|
| I _{IH} | HIGH-level input current | $V_I = V_{DD}$ | - | - | 1 | μΑ |
| I _{IL} | LOW-level input current | V _I = 0 V | 1 | - | - | μΑ |
| Vi | input voltage | | - | - | V_{DD} | V |
| $V_{i(clk)(p-p)}$ | peak-to-peak clock input voltage | | 200 | - | - | mV |
| C _i | input capacitance | all power modes | - | 2 | - | pF |

Table 35. Pin characteristics for 27.12 MHz crystal oscillator

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit | | | |
|-----------------------|-------------------------|--|-----|-----|-----|------|--|--|--|
| C _{i(XTAL1)} | | $V_{DD} = 1.8 \text{ V}; V_{DC}$ = 0.65 V; $V_{AC} =$ 0.9 V(p-p) | - | 2 | - | pF | | | |
| C _{i(XTAL2)} | XTAL2 input capacitance | | - | 2 | - | pF | | | |

^[1] See the Figure 27 for example of appropriate connected components. The layout should ensure minimum distance between the pins and the components.

Table 36. PLL accuracy

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|---------------------|---------------------------|--|-----|-----|-----|------|
| f _{o(acc)} | output frequency accuracy | deviation added to XTAL1 frequency on RF frequency generated; worst case whatever input frequency | -50 | - | +50 | ppm |

15.3.2 VEN input pin characteristics

Table 37. VEN input pin characteristics

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-----------------|--------------------------|------------|-----|-----|-----------|------|
| V _{IH} | HIGH-level input voltage | | 1.1 | - | V_{BAT} | V |
| V_{IL} | LOW-level input voltage | | 0 | - | 0.4 | V |

PN7120

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NFC controller with integrated firmware, supporting all NFC Forum modes

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-----------------|--------------------------|--------------------------------|-----|-----|-----|------|
| I _{IH} | HIGH-level input current | VEN voltage = V _{BAT} | - | - | 1 | μΑ |
| I _{IL} | LOW-level input current | VEN voltage = 0 V | 1 | - | - | μΑ |
| C _i | input capacitance | | - | 5 | - | pF |

15.3.3 Pin characteristics for IRQ, CLK_REQ and BOOST_CTRL

Table 38. Pin characteristics for IRQ, CLK_REQ and BOOST_CTRL

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-----------------|---------------------------|----------------------------|----------------------------|-----|----------------------|------|
| V _{OH} | HIGH-level output voltage | I _{OH} < 3 mA | V _{DD(PAD)} - 0.4 | - | V _{DD(PAD)} | V |
| V _{OL} | LOW-level output voltage | I _{OL} < 3 mA | 0 | - | 0.4 | V |
| C _L | load capacitance | | - | - | 20 | pF |
| t _f | fall time | C _L = 12 pF max | | | | |
| | | high speed | 1 | - | 3.5 | ns |
| | | slow speed | 2 | - | 10 | ns |
| t _r | rise time | C _L = 12 pF max | | | | |
| | | high speed | 1 | - | 3.5 | ns |
| | | slow speed | 2 | - | 10 | ns |
| R _{pd} | pull-down resistance | [1] | 0.4 | - | 0.75 | МΩ |

^[1] Activated in HPD and Monitor states.

15.3.4 ANT1 and ANT2 pin characteristics

Table 39. Electrical characteristics of ANT1 and ANT2

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|---------------------------|---------------------------------------|---------------|-----|-----|-----|------|
| Z _{i(ANT1-ANT2)} | input impedance between ANT1 and ANT2 | low impedance | - | 10 | 17 | Ω |
| V _{th(ANT1)} | ANT1 threshold voltage | I = 10 mA | - | 3.3 | - | V |
| V _{th(ANT2)} | ANT2 threshold voltage | I = 10 mA | - | 3.3 | - | V |

15.3.5 Input pin characteristics for RXN and RXP

Table 40. Input pin characteristics for RXN and RXP

| Table 101 input pin onal actorication 101 1011 and 1011 | | | | | | | | | |
|---|-----------------------|------------|-----|-----|----------|------|--|--|--|
| Symbol | Parameter | Conditions | Min | Тур | Max | Unit | | | |
| $V_{RXN(i)}$ | RXN input voltage | | 0 | - | V_{DD} | V | | | |
| $V_{RXP(i)}$ | RXP input voltage | | 0 | - | V_{DD} | V | | | |
| C _{i(RXN)} | RXN input capacitance | | - | 12 | - | pF | | | |
| C _{i(RXP)} | RXP input capacitance | | - | 12 | - | pF | | | |

PN7120

NFC controller with integrated firmware, supporting all NFC Forum modes

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|--------------------------------|---|--|----------|-----|-----|---------|
| Z _{i(RXN-} VDDMID) | input impedance between RXN and $V_{\rm DD(MID)}$ | Reader, Card and P2P modes | 0 | - | 15 | kΩ |
| Z _{i(RXP-} VDDMID) | input impedance between RXP and $V_{\mathrm{DD}(\mathrm{MID})}$ | Reader, Card and P2P modes | 0 | - | 15 | kΩ |
| $V_{i(dyn)(RXN)}$ | RXN dynamic input voltage | Miller coded | | | | |
| | | 106 kbit/s | - | 150 | 200 | mV(p-p) |
| | | 212 to 424 kbit/ s | - | 150 | 200 | mV(p-p) |
| $V_{i(dyn)(RXP)}$ | RXP dynamic input voltage | Miller coded | | | | |
| | | 106 kbit/s | - | 150 | 200 | mV(p-p) |
| | | 212 to 424 kbit/ s | - | 150 | 200 | mV(p-p) |
| $V_{i(dyn)(RXN)}$ | RXN dynamic input voltage | Manchester, NRZ or BPSK coded; 106 to 848 kbit/s | - | 150 | 200 | mV(p-p) |
| $V_{i(dyn)(RXP)}$ | RXP dynamic input voltage | Manchester, NRZ or BPSK coded; 106 to 848 kbit/s | - | 150 | 200 | mV(p-p) |
| $V_{i(dyn)(RXN)}$ | RXN dynamic input voltage | All data coding; 106 kbit/s to 848 kbit/s | V_{DD} | - | - | V(p-p) |
| $V_{i(dyn)(RXP)}$ | RXP dynamic input voltage | All data coding; 106 kbit/s to 848 kbit/s | V_{DD} | - | - | V(p-p) |
| $V_{i(RF)}$ | RF input voltage | RF input voltage detected; Initiator modes | | 100 | - | mV(p-p) |

15.3.6 Output pin characteristics for TX1 and TX2

Table 41. Output pin characteristics for TX1 and TX2

| 145.5 111 0 | atput piii onaraotoi | ISTICS FOR TAX TUTIE TALE | | | | |
|-----------------|---------------------------|---|---------------------------|-----|-----|------|
| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
| V _{OH} | HIGH-level output voltage | $V_{DD(TX)}$ = 3.1 V and I_{OH} = 30 mA; PMOS driver fully on | V _{DD(TX)} - 150 | - | - | mV |
| V _{OL} | LOW-level output voltage | $V_{DD(TX)}$ = 3.1 V and I_{OL} = 30 mA; NMOS driver fully on | - | - | 200 | mV |

Table 42. Output resistance for TX1 and TX2

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-----------------|-----------------------------|--|-----|-----|-----|------|
| R _{OL} | LOW-level output resistance | V _{DD(TX)} - 100 mV; CWGsN = 01h | - | - | 80 | Ω |
| R _{OL} | LOW-level output resistance | V _{DD(TX)} - 100 mV; CWGsN = 0Fh | - | - | 5 | Ω |

PN7120

NFC controller with integrated firmware, supporting all NFC Forum modes

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-----------------|------------------------------|------------------------------|-----|-----|-----|------|
| R _{OH} | HIGH-level output resistance | V _{DD(TX)} - 100 mV | - | - | 4 | Ω |

15.3.7 Input pin characteristics for I2CADR0

Table 43. Input pin characteristics for I2CADR0

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-----------------|--------------------------|-------------------------------------|--------------------------|-----|--------------------------|------|
| V _{IH} | HIGH-level input voltage | | 0.65V _{DD(PAD)} | - | V _{DD(PAD)} | V |
| V _{IL} | LOW-level input voltage | | 0 | - | 0.35V _{DD(PAD)} | V |
| I _{IH} | HIGH-level input current | $V_I = V_{DD(PAD)};$ T = 125 °C | - | - | 1 | μΑ |
| I _{IL} | LOW-level input current | V _I = 0 V; T = 125 °C | -1 | - | - | μΑ |
| C _i | input capacitance | | - | 5 | - | pF |

15.3.8 Pin characteristics for I2CSDA and I2CSCL

Table 44. Pin characteristics for I2CSDA and I2CSCL

Below values are given for $V_{DD(PAD)}$ in the range of 1.8 V; unless specified.

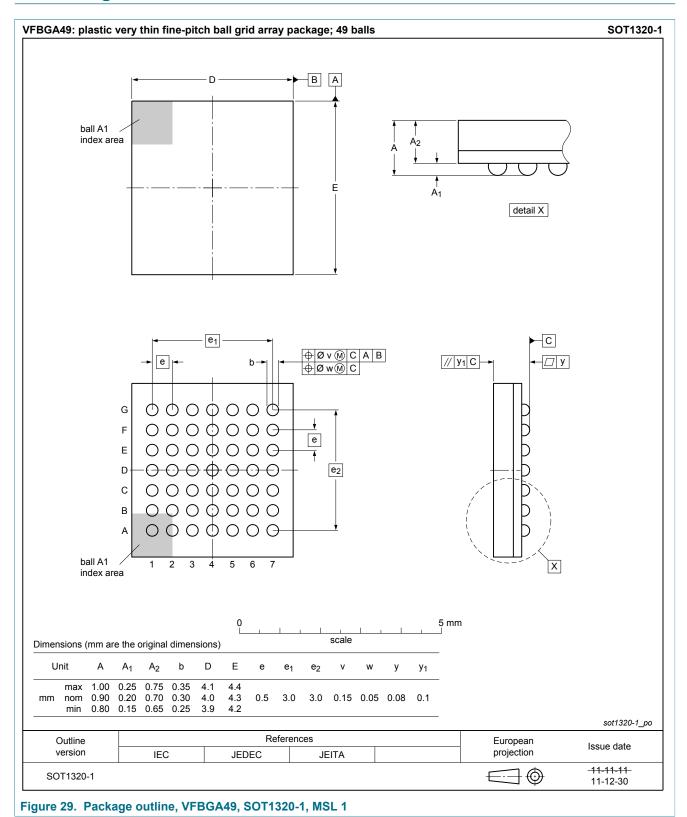
| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-----------------|--------------------------|--|-----|-----|-----|------|
| V _{OL} | LOW-level output voltage | I _{OL} < 3 mA | 0 | - | 0.4 | V |
| C _L | load capacitance | | - | - | 10 | pF |
| t _f | fall time | C_L = 100 pF; Rpull-up = 1.8 k Ω ; Standard and Fast mode | 30 | - | 250 | ns |
| | | C_L = 100 pF; $V_{DD(PAD)}$ = 3.3 V; Rpull- up = 3.3 k Ω ; Standard and Fast mode | 30 | - | 250 | ns |
| | | C_L = 100 pF; Rpull-up = 1 k Ω ; High-speed mode | 80 | - | 110 | ns |
| t _r | rise time | C_L = 100 pF; Rpull-up = 1.8 k Ω ; Standard and Fast mode | 30 | - | 250 | ns |

NFC controller with integrated firmware, supporting all NFC Forum modes

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-----------------|--------------------------|---|-------------------------|-----|-------------------------|------|
| | | C_L = 100 pF; $V_{DD(PAD)}$ = 3.3 V; Rpull-up = 3.3 k Ω ; Standard and Fast mode | 30 | - | 250 | ns |
| | | C_L = 100 pF; Rpull-up = 1 k Ω ; High-speed mode | 10 | - | 100 | ns |
| V _{IH} | HIGH-level input voltage | | 0.7V _{DD(PAD)} | - | $V_{DD(PAD)}$ | V |
| V _{IL} | LOW-level input voltage | | 0 | - | 0.3V _{DD(PAD)} | V |
| I _{IH} | HIGH-level input current | V _I = V _{DD(PAD)} ; high impedance | - | - | 1 | μA |
| I _{IL} | LOW-level input current | V _I = 0 V; high impedance | -1 | - | - | μA |
| C _i | input capacitance | | - | 5 | - | pF |

NFC controller with integrated firmware, supporting all NFC Forum modes

16 Package outline



NFC controller with integrated firmware, supporting all NFC Forum modes

17 Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

17.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

17.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- · Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than \sim 0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- · Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

17.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

PN7120

NFC controller with integrated firmware, supporting all NFC Forum modes

17.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see <u>Figure 30</u>) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board
 is heated to the peak temperature) and cooling down. It is imperative that the peak
 temperature is high enough for the solder to make reliable solder joints (a solder
 paste characteristic). In addition, the peak temperature must be low enough that the
 packages and/or boards are not damaged. The peak temperature of the package
 depends on package thickness and volume and is classified in accordance with
 Table 45 and Table 46

Table 45. SnPb eutectic process (from J-STD-020D)

| Package thickness (mm) | Package reflow temperature (°C) | | | |
|------------------------|---------------------------------|-------|--|--|
| | Volume (mm³) | | | |
| | < 350 | ≥ 350 | | |
| < 2.5 | 235 | 220 | | |
| ≥ 2.5 | 220 | 220 | | |

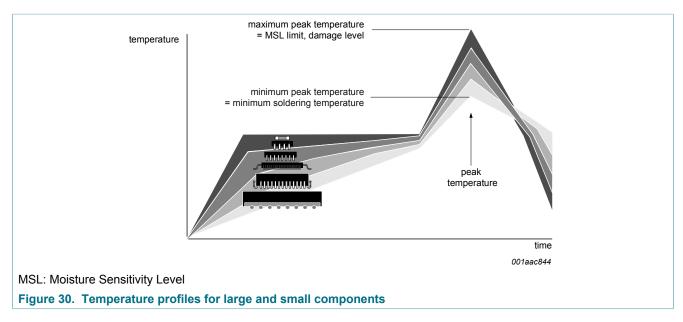
Table 46. Lead-free process (from J-STD-020D)

| Package thickness (mm) | Package reflow temperature (°C) Volume (mm³) | | _ |
|------------------------|---|--------------|---------|
| | | | |
| | < 350 | 350 to 2 000 | > 2 000 |
| < 1.6 | 260 | 260 | 260 |
| 1.6 to 2.5 | 260 | 250 | 245 |
| > 2.5 | 250 | 245 | 245 |

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 30.

NFC controller with integrated firmware, supporting all NFC Forum modes



For further information on temperature profiles, refer to Application Note *AN10365* "Surface mount reflow soldering description".

NFC controller with integrated firmware, supporting all NFC Forum modes

18 Abbreviations

Table 47. Abbreviations

| Acronym | Description |
|----------------------------|---|
| | · |
| API | Application Programming Interface |
| ASK | Amplitude Shift keying |
| ASK modulation index | The ASK modulation index is defined as the voltage ratio (Vmax - Vmin)/ (Vmax + Vmin) × 100 % |
| Automatic device discovery | Detect and recognize any NFC peer devices (initiator or target) like: NFC initiator or target, ISO/IEC 14443-3, -4 Type A&B PICC, MIFARE Classic and MIFARE Ultralight PICC, ISO/IEC 15693 VICC |
| BPSK | Bit Phase Shift Keying |
| Card Emulation | The IC is capable of handling a PICC emulation on the RF interface including part of the protocol management. The application handling is done by the host controller. |
| DEP | Data Exchange Protocol |
| DSLDO | Dual Supplied LDO |
| FW | FirmWare |
| HPD | Hard Power Down |
| LDO | Low Drop Out |
| LFO | Low Frequency Oscillator |
| MOSFET | Metal Oxide Semiconductor Field Effect Transistor |
| MSL | Moisture Sensitivity Level |
| NCI | NFC Controller Interface |
| NFC | Near Field Communication |
| NFCC | NFC Controller, PN7120 in this data sheet |
| NFC Initiator | Initiator as defined in ISO/IEC 18092 or ECma 340: NFCIP-1 communication |
| NFCIP | NFC Interface and Protocol |
| NFC Target | Target as defined in ISO/IEC 18092 or ECma 340: NFCIP-1 communication |
| NRZ | Non Return to Zero |
| P2P | Peer to Peer |
| PCD | Proximity Coupling Device. Definition for a Card reader/writer device according to the ISO/IEC 14443 specification or MIFARE Classic |
| PCD -> PICC | Communication flow between a PCD and a PICC according to the ISO/IEC 14443 specification or MIFARE Classic |
| PICC | Proximity Interface Coupling Card. Definition for a contactless Smart Card according to the ISO/IEC 14443 specification or MIFARE Classic |
| PICC-> PCD | Communication flow between a PICC and a PCD according to the ISO/IEC 14443 specification or MIFARE Classic |
| PMOS | P-channel MOSFET |
| PMU | Power Management Unit |
| PSL | Parameter SeLection |

NFC controller with integrated firmware, supporting all NFC Forum modes

| Acronym | Description |
|---------|--|
| TXLDO | Transmitter LDO |
| UM | User Manual |
| VCD | Vicinity Coupling Device. Definition for a reader/writer device according to the ISO/IEC 15693 specification |
| VCO | Voltage Controlled Oscillator |
| VICC | Vicinity Integrated Circuit Card |
| WUC | Wake-Up Counter |

NFC controller with integrated firmware, supporting all NFC Forum modes

19 References

| [1] | NFC Controller Interface (NCI) Technical Specification | _ | V1.0 |
|------|--|---|---|
| [2] | ISO/IEC 14443 | _ | parts 2: 2001 COR 1 2007 (01/11/2007), part 3: 2001 COR 1 2006 (01/09/2006) and part 4: 2nd edition 2008 (15/07/2008) |
| [3] | I ² C Specification | _ | I ² C Specification, UM10204 rev4 (13/02/2012) |
| [4] | PN7120 User Manual | _ | UM10819 PN7120 User Manual |
| [5] | PN7120 Hardware Design - Guide | _ | AN11565 PN7120 Hardware Design Guide |
| [6] | PN7120 Antenna and Tuning Design Guide | _ | AN11564 PN7120 Antenna and Tuning Design Guide |
| [7] | ISO/IEC 18092 (NFCIP-1) | _ | edition, 15/032013. This is similar to Ecma 340. |
| [8] | ISO/IEC 15693 | _ | part 2: 2nd edition (15/12/2006), part 3: 1st edition (01/04/2001) |
| [9] | PN7120 Low-Power Mode Configuration | _ | AN11562 PN7120 Low-Power Mode Configuration |
| [10] | ISO/IEC 21481 (NFCIP-2) | _ | edition, 01/07/2012. This is similar to Ecma 352. |
| [11] | NFC Forum Device Requirements | _ | V1.3 |

NFC controller with integrated firmware, supporting all NFC Forum modes

20 Revision history

Table 48. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|----------------|--|--------------------------------|-------------------|---------------|
| PN7120 v. 3.5 | 20180611 | Product data sheet | - | PN7120 v. 3.4 |
| Modifications: | Editorial updates | | | |
| PN7120 v. 3.4 | 20171018 | Product data sheet | - | PN7120 v3.3 |
| Modifications: | Table 17 (Communication | cation overview for NFC Forum | T5T R/W mode) upo | lated. |
| PN7120 v.3.3 | 20171005 | Product data sheet | - | PN7120 v.3.2 |
| Modifications: | Descriptive title upda <u>Section 2 "General of</u> MIFARE branding up | description": Figure 2 updated | | |
| PN7120 v.3.2 | 20160704 | Product data sheet | - | PN7120 v.3.1 |
| Modifications: | • <u>Section 10.7.1.4</u> : up | dated | | |
| PN7120 v.3.1 | 20151008 | Product data sheet | - | PN7120 v.3.0 |
| PN7120 v.3.0 | 20150727 | Product data sheet | - | PN7120 v.2 |
| PN7120 v.2 | 20150611 | Preliminary data sheet | - | PN7120 v.1 |
| PN7120 v.1 | 20150506 | Objective data sheet | - | - |

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21 Legal information

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| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
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NFC controller with integrated firmware, supporting all NFC Forum modes

Tables

| Tab. 1. | Quick reference data5 | Tab. 25. | Current consumption characteristics for | |
|----------|--|----------|--|----|
| Tab. 2. | Ordering information6 | | operating ambient temperature range | 38 |
| Tab. 3. | Marking code7 | Tab. 26. | Battery voltage monitor characteristics | 38 |
| Tab. 4. | PN7120 pin description9 | Tab. 27. | Reset timing | 38 |
| Tab. 5. | System power modes description 12 | Tab. 28. | Power-up timings | 39 |
| Tab. 6. | System power modes configuration 12 | Tab. 29. | Power-down timings | 39 |
| Tab. 7. | System power modes description 12 | Tab. 30. | Thermal threshold | 39 |
| Tab. 8. | PN7120 power states13 | Tab. 31. | High-speed mode I2C-bus timings | |
| Tab. 9. | Functional modes in active state14 | | specification | 40 |
| Tab. 10. | Functionality for I2C-bus interface17 | Tab. 32. | Fast mode I2C-bus timings specification | 40 |
| Tab. 11. | I2C-bus interface addressing 17 | Tab. 33. | Input clock characteristics on XTAL1 when | |
| Tab. 12. | Crystal requirements18 | | using PLL | 41 |
| Tab. 13. | PLL input requirements19 | Tab. 34. | Pin characteristics for XTAL1 when PLL | |
| Tab. 14. | Communication overview for ISO/IEC 14443 | | input | 41 |
| | type A and read/write mode for MIFARE | Tab. 35. | Pin characteristics for 27.12 MHz crystal | |
| | Classic | | oscillator | 41 |
| Tab. 15. | Overview for FeliCa Reader/Writer | Tab. 36. | PLL accuracy | 41 |
| | communication mode27 | Tab. 37. | VEN input pin characteristics | 41 |
| Tab. 16. | Overview for ISO/IEC 14443B Reader/ | Tab. 38. | Pin characteristics for IRQ, CLK_REQ and | |
| | Writer communication mode28 | | BOOST_CTRL | 42 |
| Tab. 17. | Communication overview for NFC forum | Tab. 39. | Electrical characteristics of ANT1 and ANT2. | 42 |
| | T5T R/W mode29 | Tab. 40. | Input pin characteristics for RXN and RXP | 42 |
| Tab. 18. | Overview for Active communication mode30 | Tab. 41. | Output pin characteristics for TX1 and TX2 | 43 |
| Tab. 19. | Overview for Passive communication mode 31 | Tab. 42. | Output resistance for TX1 and TX2 | 43 |
| Tab. 20. | Overview for ISO/IEC 14443A/MIFARE | Tab. 43. | Input pin characteristics for I2CADR0 | 44 |
| | Classic card communication mode32 | Tab. 44. | Pin characteristics for I2CSDA and I2CSCL | |
| Tab. 21. | Overview for ISO/IEC 14443B card | Tab. 45. | SnPb eutectic process (from J-STD-020D) | |
| | communication mode33 | Tab. 46. | Lead-free process (from J-STD-020D) | 48 |
| Tab. 22. | Limiting values35 | Tab. 47. | Abbreviations | |
| Tab. 23. | Operating conditions36 | Tab. 48. | Revision history | 53 |
| Tab. 24. | Thermal characteristics 37 | | | |

NFC controller with integrated firmware, supporting all NFC Forum modes

Figures

| PN7120 transmission modes | Fig. 18. | VDD(PAD) is set up or cut-off after PN7120 | 25 |
|--|---|--|-----------------------------------|
| | F:~ 10 | | |
| | | · | ∠5 |
| PN7120 pinning (bottom view)9 | Fig. 20. | · · | |
| PN7120 connection11 | | and read/write mode for MIFARE Classic | 26 |
| System power mode diagram 12 | Fig. 21. | FeliCa Reader/Writer communication mode | |
| Polling loop: all phases enabled15 | _ | diagram | 27 |
| Polling loop: low-power RF polling16 | Fig. 22. | ISO/IEC 14443B Reader/Writer | |
| 27.12 MHz crystal oscillator connection 18 | | communication mode diagram | 28 |
| Input reference phase noise characteristics 19 | Fig. 23. | R/W mode for NFC forum T5T | |
| PMU functional diagram20 | | communication diagram | 28 |
| VDD(TX) offset disabled behavior21 | Fig. 24. | NFCIP-1 communication mode | 29 |
| VDD(TX) behavior when PN7120 is in | Fig. 25. | Active communication mode | 30 |
| Standby state21 | Fig. 26. | Passive communication mode | 31 |
| Battery voltage monitor principle22 | Fig. 27. | Application schematic | 34 |
| Resetting PN7120 via VEN pin23 | Fig. 28. | I2C-bus timings | 39 |
| VBAT is set up before VDD(PAD)24 | Fig. 29. | Package outline, VFBGA49, SOT1320-1, | |
| VDD(PAD) and VBAT are set up in the same | · · | MSL 1 | 46 |
| time \(\tag{24} | Fig. 30. | Temperature profiles for large and small | |
| | - | components | 49 |
| | PN7120 package marking (top view) 7 PN7120 block diagram 8 PN7120 pinning (bottom view) 9 PN7120 connection 11 System power mode diagram 12 Polling loop: all phases enabled 15 Polling loop: low-power RF polling 16 27.12 MHz crystal oscillator connection 18 Input reference phase noise characteristics 19 PMU functional diagram 20 VDD(TX) offset disabled behavior 21 VDD(TX) behavior when PN7120 is in Standby state 21 Battery voltage monitor principle 22 Resetting PN7120 via VEN pin 23 VBAT is set up before VDD(PAD) 24 VDD(PAD) and VBAT are set up in the same | PN7120 package marking (top view) | PN7120 package marking (top view) |

NFC controller with integrated firmware, supporting all NFC Forum modes

Contents

| 1 | Introduction | 1 | 10.7.2 | ISO/IEC 18092, Ecma 340 NFCIP-1 | |
|----------|--|-----|----------|---|------|
| | General description | | 10.7.2 | communication modes | 20 |
| | Features and benefits | | 10.7.2.1 | | |
| | Applications | | 10.7.2.2 | | |
| | Quick reference data | | 10.7.2.3 | | |
| | Ordering information | | 10.7.2.4 | | |
| | Marking | | 10.7.3 | Card communication modes | |
| | Block diagram | | 10.7.3.1 | | 02 |
| | Pinning information | | 10.7.0.1 | communication mode | 32 |
| 9.1 | Pinning | | 10.7.3.2 | | |
| | Functional description | | 10.7.4 | Frequency interoperability | |
| 10.1 | System modes | | 11 | Application design-in information | |
| 10.1.1 | System power modes | | 12 | Limiting values | |
| 10.1.2 | PN7120 power states | | 13 | Recommended operating conditions | |
| 10.1.2.1 | | | 14 | Thermal characteristics | |
| 10.1.2.2 | | | 15 | Characteristics | |
| 10.1.2.3 | | | 15.1 | Current consumption characteristics | |
| 10.1.2.4 | • | | 15.2 | Functional block electrical characteristics | |
| 10.1.2.5 | | | 15.2.1 | Battery voltage monitor characteristics | |
| 10.2 | Microcontroller | | 15.2.2 | Reset via VEN | |
| 10.3 | Host interfaces | | 15.2.3 | Power-up timings | |
| 10.3.1 | I2C-bus interface | | 15.2.4 | Power-down timings | |
| 10.3.1.1 | I2C-bus configuration | | 15.2.5 | Thermal protection | |
| 10.4 | PN7120 clock concept | | 15.2.6 | I2C-bus timings | |
| 10.4.1 | 27.12 MHz quartz oscillator | | 15.3 | Pin characteristics | |
| 10.4.2 | Integrated PLL to make use of external clock . | | 15.3.1 | XTAL1 and XTAL2 pins characteristics | |
| 10.4.3 | Low-power 20 MHz oscillator | | 15.3.2 | VEN input pin characteristics | |
| 10.4.4 | Low-power 380 kHz oscillator | | 15.3.3 | Pin characteristics for IRQ, CLK_REQ and | |
| 10.5 | Power concept | | | BOOST CTRL | 42 |
| 10.5.1 | PMU functional description | 20 | 15.3.4 | ANT1 and ANT2 pin characteristics | 42 |
| 10.5.2 | DSLDO: Dual Supply LDO | 20 | 15.3.5 | Input pin characteristics for RXN and RXP | . 42 |
| 10.5.3 | TXLDO | | 15.3.6 | Output pin characteristics for TX1 and TX2 | . 43 |
| 10.5.3.1 | TXLDO limiter | 22 | 15.3.7 | Input pin characteristics for I2CADR0 | 44 |
| 10.5.4 | Battery voltage monitor | 22 | 15.3.8 | Pin characteristics for I2CSDA and I2CSCL | . 44 |
| 10.6 | Reset concept | 22 | 16 | Package outline | |
| 10.6.1 | Resetting PN7120 | | 17 | Soldering of SMD packages | |
| 10.6.2 | Power-up sequences | 23 | 17.1 | Introduction to soldering | |
| 10.6.2.1 | VBAT is set up before VDD(PAD) | 23 | 17.2 | Wave and reflow soldering | |
| 10.6.2.2 | VDD(PAD) and VBAT are set up in the same | | 17.3 | Wave soldering | |
| | time | 24 | 17.4 | Reflow soldering | |
| 10.6.2.3 | | | 18 | Abbreviations | |
| | VDD(PAD) is set up or before VDD(PAD) | | 19 | References | |
| | has been cut off | | 20 | Revision history | |
| 10.6.3 | Power-down sequence | | 21 | Legal information | 54 |
| 10.7 | Contactless Interface Unit | | | | |
| 10.7.1 | Reader/Writer communication modes | 25 | | | |
| 10.7.1.1 | | | | | |
| | type A, MIFARE Classic and Jewel/Topaz | 0.0 | | | |
| 40 = 4 = | PCD | | | | |
| 10.7.1.2 | | | | | |
| 10.7.1.3 | | | | | |
| 10.7.1.4 | R/W mode for NFC forum Type 5 Tag | 28 | | | |

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