



Order





Instruments

SN75DP139

SLLS977F - APRIL 2009-REVISED JULY 2017

SN75DP139 DisplayPort to TMDS Level-Shifting Re-Driver

Features 1

Fexas

- DisplayPort Physical Layer Input Port to TMDS Physical Layer Output Port
- Integrated TMDS Level-Shifting Re-driver With **Receiver Equalization**
- Supports Data Rates up to 3.4 Gbps
- Achieves HDMI 1.4b Compliance
- 3D HDMI Support With TMDS Clock Rates up to 340 MHz
- 4k × 2k Operation (30 Hz, 24bpp)
- Deep Color Supporting 36bpp
- Integrated I²C Logic Block for DVI/HDMI **Connector Recognition**
- Integrated Active I²C Buffer
- Enhanced ESD: 10 kV on All Pins
- Enhanced Commercial Temperature Range: 0°C to 85°C
- 48-Pin 7-mm × 7-mm VQFN (RGZ) Package
- 40-Pin 5-mm × 5-mm WQFN (RSB) Package

2 Applications

- Personal Computer Market
 - **DP/TMDS** Dongle
 - Desktop PC
 - Notebook PC
 - **Docking Station**
 - Stand-Alone Video Card

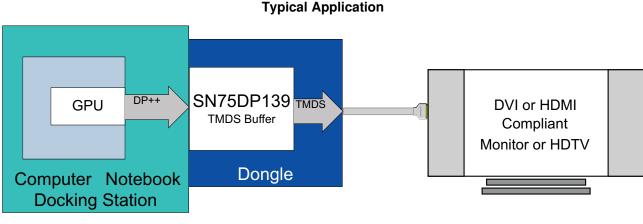
3 Description

The SN75DP139 is a dual-mode DisplayPort input to Transition-Minimized Differential Signaling (TMDS) output. The TMDS output has a built-in level-shifting re-driver supporting Digital Video Interface (DVI) 1.0 and High Definition Multimedia Interface (HDMI) 1.4b standards. The SN75DP139 is specified up to a maximum data rate of 3.4 Gbps, supporting resolutions greater then 1920 × 1200 or HDTV 12-bit color depth at 1080p (progressive scan). The SN75DP139 is compliant with the HDMI 1.4b specifications and supports optional protocol enhancements such as 3D graphics at resolutions demanding a pixel rate up to 340 MHz.

Device Information⁽¹⁾

| PART NUMBER | R PACKAGE BODY SIZE (NO | |
|-------------|-------------------------|-------------------|
| SN75DP139 | VQFN (48) | 7.00 mm x 7.00 mm |
| SIN/SDP 139 | WQFN (40) | 5.00 mm x 5.00 mm |

(1) For all available packages, see the orderable addendum at the end of the datasheet.



GPU - Graphics Processing Unit DP++ - Dual-Mode DisplayPort TMDS - Transition-Minimized Differential Signaling **DVI - Digital Visual Interface**

HDMI - High Definition Multimedia Interface



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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

| CI | hanges from Revision E (September 2014) to Revision F | Page |
|----|--|------|
| • | Added Note 1 to the Pin Functions table | 5 |
| | 7 | |
| CI | hanges from Revision D (July 2013) to Revision E | Page |
| • | Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and Mechanical, Packaging, and Orderable Information | 1 |
| CI | hanges from Revision C (December 2012) to Revision D | Page |
| • | Changed title and Feature bullet from "TMDS Translator" to "TMDS Level Shifting Re-driver" | 1 |
| • | Changed second sentence text string in Description section from "built in level translator" to "built in level shifting re-driver" | 1 |

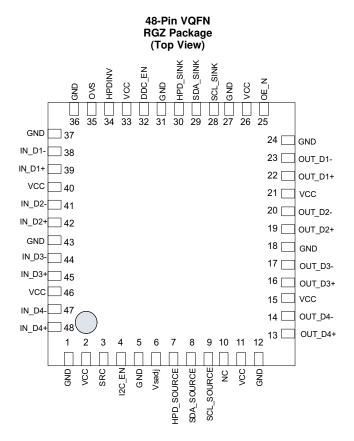


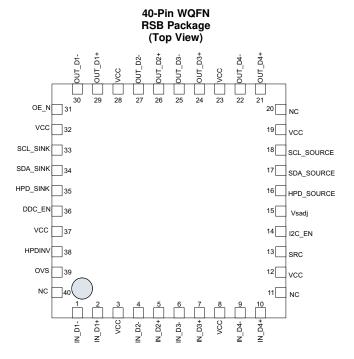
Page

Changes from Revision A (July 2010) to Revision B

| • | Added to FEATURES "40 Pin 5 x 5 QFN (RSB) Package" | . 1 |
|---|--|-----|
| • | Added RSB package drawing | . 4 |
| | Changed Pin Functions to include RSB package pins | |
| • | Added RSB package to ORDERING INFORMATION table | . 6 |
| | Changed voltage range section of Absolute Maximum Ratings | |
| • | Changed input voltages within the Recommended Operating Conditions | . 7 |
| • | Changed thermal resistance info and enable voltages to 3.6V | . 8 |
| • | Changed enable voltages from 5 V to 3.6 V | . 9 |
| • | Changed V _{IH(AUX}) max from 5.5 V to 3.6 V | . 9 |
| | Changed OUT_Dx terminal connections | |

5 Pin Configuration and Functions







| Pin Functions | | | | | |
|---------------------------|---|--------------------------------|-----|--|--|
| | PIN | | | | |
| SIGNAL | NO |). | I/O | DESCRIPTION | |
| SIGNAL | RGZ | RSB | | | |
| MAIN LINK INPU | T PINS | | | | |
| IN_D1 | 38, 39 | 1, 2 | Ι | DisplayPort Main Link Channel 0 Differential Input | |
| IN_D2 | 41, 42 | 4, 5 | Ι | DisplayPort Main Link Channel 1 Differential Input | |
| IN_D3 | 44, 45 | 6, 7 | Ι | DisplayPort Main Link Channel 2 Differential Input | |
| IN_D4 | 47, 48 | 9, 10 | Ι | DisplayPort Main Link Channel 3 Differential Input | |
| MAIN LINK POR | T B OUTPUT PINS | | | | |
| OUT_D1 | 23, 22 | 30, 29 | 0 | TMDS Data 2 Differential Output | |
| OUT_D2 | 20, 19 | 27, 26 | 0 | TMDS Data 1 Differential Output | |
| OUT_D3 | 17, 16 | 25, 24 | 0 | TMDS Data 0 Differential Output | |
| OUT_D4 | 14, 13 | 22, 21 | 0 | TMDS Data Clock Differential Output | |
| HOT PLUG DETE | ECT PINS | | | | |
| HPD_SOURCE | HPD_SOURCE 7 16 O Hot Plug Detect Output | | | | |
| HPD_SINK | 30 | 35 | Ι | Hot Plug Detect Input | |
| AUXILIARY DAT | A PINS | | | | |
| SDA_SOURCE, SCL_SOURCE | 8, 9 | 17, 18 | I/O | Source Side Bidirectional DisplayPort Auxiliary Data Line | |
| SDA_SINK, SCL_SINK | 29, 28 | 34, 33 | I/O | TMDS Port Bidirectional DDC Data Lines | |
| CONTROL PINS | | | | | |
| OE_N | 25 | 31 | Ι | Output Enable and power saving function for High Speed Differential level shifter path. | |
| NC | 10 | 11, 20, 40 | | No Connect | |
| OVS | 35 | 39 | Ι | DDC I2C buffer offset select | |
| DDC_EN | 32 | 36 | Ι | Enables or Disables the DDC I2C buffer | |
| HPDINV | 34 | 38 | Ι | HPD_SOURCE Logic and Level Select | |
| VSadj | 6 | 15 | Ι | TMDS Compliant Voltage Swing Control | |
| SRC | 3 | 13 | Ι | TMDS outputs rise and fall time select | |
| I2C_EN | 4 | 14 | Ι | Internal I ² C register enable, used for HDMI / DVI connector differentiation | |
| SUPPLY AND G | ROUND PINS | | | | |
| VCC | 2, 11, 15, 21, 26, 33, 40, 46 | 3, 8, 12, 19, 23 28, 32, 37 | | 3.3 V Supply | |
| GND | 1, 5, 12, 18, 24, 27, 31, 36, 37, 43 ⁽¹⁾ | Thermal Pad | | Ground | |

(1) Connect the Thermal Pad to GND

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| SIGNAL | LEVEL ⁽¹⁾ | STATE | DESCRIPTION | | |
|---------------------|----------------------|--------------------------------|---|--|--|
| OE_N | Н | Power Saving Mode | Main Link is disabled. IN_Dx termination = 50 Ω with common mode voltage set to 0V. OUT_Dx outputs = high impedance | | |
| | L | Normal Mode | IN_Dx termination = 50 Ω OUT_Dx outputs = active | | |
| I ² C_EN | Н | HDMI | The Internal I2C register is active and readable when the TMDS port is selected indicating that the connector being used is HDMI. This mode selects the fastest rise and fall time for the TMDS differential output signals | | |
| | L | DVI | The Internal I2C register is disabled and not readable when the TMDS port is selected indicating that the connector being used is DVI. This mode selects a slower rise and fall time for the TMDS differential output signals See <i>Application Information</i> . | | |
| VSadj | 4.02 kΩ ±5% | Output Voltage Swing Contol | iver output voltage swing precision control to aid with system compliance | | |
| HPDINV | Н | HPD Inversion | HPD_SOURCE VOH =0.9V (typical) and HPD logic is inverted | | |
| | L | HPD non- inversion | HPD_SOURCE VOH =3.2V (typical) and HPD logic is non-inverted | | |
| SRC | Н | Edge Rate: Slowest | SRC helps to slow down the rise and fall time. SRC =High adds ~60ps to the rise and fall time of the TMDS differential output signals in addition to the I2C_EN pin selection (recommended setting) | | |
| | L | Edge Rate: Slow | SRC helps to slow down the rise and fall time. SRC =Low adds \sim 30ps to the rise and fall time of the TMDS differential output signals in addition to the I ² C_EN pin selection | | |
| | Hi-Z | Edge Rate | Leaving the SRC pin High Z, will keep the default rise and fall time of the TMDS differential output signals as selected by the l^2C_EN pin. It is recommended that an external resistor-divider (less than 100 k Ω) is used so that voltage on this pin = VCC/2, if Hi-Z logic level is intended on this pin. | | |
| OVS | Н | Offset 1 | DDC source side VOL and VIL offset range 1 | | |
| | L | Offset 2 | DDC source side VOL and VIL offset range 2 | | |
| | Hi-Z | Offset 3 | DDC source side VOL and VIL offset range 3 It is recommended that an external resistor-divider (less than 100 k Ω) is used so that voltage on this pin = VCC/2, if Hi-Z logic level is intended on this pin. | | |
| DDC_EN | Н | DDC Buffer enabled | DDC Buffer is enabled | | |
| | L | DDC buffer disabled | DDC Buffer is disabled | | |

(1) (H) Logic High; (L) Logic Low; (Z) High Z



6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

| | | MIN | MAX | UNIT |
|---|--|------|-----------|------|
| Supply voltage range ⁽²⁾ | VCC | -0.3 | 3.6 | V |
| | Main Link Input (IN_Dx) differential voltage | -0.3 | VCC + 0.3 | V |
| | TMDS Outputs (OUT_Dx) | -0.3 | VCC + 0.3 | |
| Voltage range | HPD_SOURCE, SDA_SOURCE, SCL_SOURCE, OVS, DDC_EN, VSadj, SRC, I ² C_EN | -0.3 | VCC + 0.3 | |
| | HPD_SINK, SDA_SINK, SCL_SINK, OE_EN, HPDINV | -0.3 | 5.5 | |
| Storage temperature range, T _{stg} | | -55 | 150 | °C |

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values, except differential voltages, are with respect to network ground terminal.

6.2 ESD Ratings

| | | | VALUE | UNIT |
|--------------------|-------------------------|-------------------------------------|--------|------|
| | | Human body model ⁽¹⁾ | ±10000 | V |
| V _(ESD) | Electrostatic discharge | Charged-device model ⁽²⁾ | ±1500 | V |
| | | Machine model ⁽³⁾ | ±200 | V |

(1) Tested in accordance with JEDEC Standard 22, Test Method A114-B

(2) Tested in accordance with JEDEC Standard 22, Test Method C101-A

(3) Tested in accordance with JEDEC Standard 22, Test Method A115-A

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

| | | м | IN | NOM | MAX | UNIT |
|-----------------------------|--|--------------------|----|------|-----|------|
| V _{CC} | Supply Voltage | | 3 | 3.3 | 3.6 | ٧ |
| T _A | Operating free-air temperature | | 0 | | 85 | °C |
| MAIN LINK DIF | FERENTIAL INPUT PINS | | | | | |
| V _{ID_PP} | Peak-to-peak AC input differential voltage | 0. | 15 | | 1.2 | V |
| -J | RGZ paci | kage 0.2 | 25 | | 3.4 | Chas |
| d _R Data rate | | kage 0.2 | 25 | | 3.4 | Gbps |
| t _{rise fall time} | Input Signal Rise and Fall time (20%-80%) | | 75 | | | ps |
| V _{PRE} | Pre-emphasis on the Input Signal at IN_Dx pins | | 0 | 0 | 0 | db |
| TMDS DIFFER | ENTIAL OUTPUT PINS | | | | | |
| AV _{CC} | TMDS output termination voltage | | 3 | 3.3 | 3.6 | V |
| .1 | RGZ pac | kage 0.2 | 25 | | 3.4 | 01 |
| d _R | Data rate RSB pack | kage 0.2 | 25 | | 3.4 | Gbps |
| R _T | Termination resistance | | 45 | 50 | 55 | Ω |
| R _{Vsadj} | TMDS output swing voltage bias resistor ⁽¹⁾ | 3. | 65 | 4.02 | | kΩ |
| AUXILIARY AN | ID I2C PINS | L | | | | |
| | SDA_SIN | SDA_SINK, SCL_SINK | | | 5.5 | |
| VI | Input voltage | URCE, SCL_SOURCE | | | 3.6 | V |
| d _{R(I2C)} | I ² C data rate | | | | 100 | kHz |

(1) R_{Vsadj} resistor controls the SN75DP139 Driver output voltage swing and thus helps in meeting system compliance. It is recommended that R_{Vsadj} resistor should be above the MIN value as indicated in the RECOMMENDED OPERATING CONDITIONS table, however for NOM and MAX value, Figure 19 could be used as reference. It is important to note that system level losses, AV_{CC} and R_T variation affect R_{Vsadj} resistor selection. Worse case variation on system level losses, AV_{CC}, R_T could make R_{Vsadj} resistor value of 4.02 kΩ ±5% result in non-compliant TMDS output voltage swing. In such cases Figure 19 could be used as reference.

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Recommended Operating Conditions (continued)

over operating free-air temperature range (unless otherwise noted)

| | MIN NO | M MAX | UNIT |
|--------------------------|--|---|--|
| NV, OE_N | | | |
| High-level input voltage | 2 | 5.5 | V |
| Low-level input voltage | 0 | 0.8 | V |
| | | | |
| High-level input voltage | 2 | 3.6 | V |
| Low-level input voltage | 0 | 0.8 | V |
| | | | |
| High-level input voltage | 3 | 3.6 | V |
| Low-level input voltage | 0 | 0.5 | V |
| | High-level input voltage Low-level input voltage High-level input voltage Low-level input voltage High-level input voltage | NV, OE_N 2 High-level input voltage 0 High-level input voltage 0 High-level input voltage 0 High-level input voltage 0 High-level input voltage 3 | NV, OE_N High-level input voltage 2 5.5 Low-level input voltage 0 0.8 High-level input voltage 2 3.6 Low-level input voltage 0 0.8 High-level input voltage 2 3.6 High-level input voltage 3 3.6 |

6.4 Thermal Information

over operating free-air temperature range (unless otherwise noted)

| | PARAMETER | TEST CONDITION | IS | MIN TYP | MAX ⁽¹⁾ | UNIT |
|------------------|--|---|-------------|---------|--------------------|------|
| 0 | Junction-to-board thermal | | RGZ package | 10.9 | | °C/W |
| θ_{JB} | resistance | | RSB package | 10.8 | | 0/10 |
| ۵ | Junction-to-case-top thermal | | RGZ package | 22.5 | | °C/W |
| θ _{JCT} | resistance | | RSB package | 24.4 | | 0/11 |
| N/ .= | Junction-to-board thermal | High-K board ⁽²⁾ | RGZ package | 10.9 | | °C/W |
| ΨJB | resistance metric | | RSB package | | | 0/11 |
|)// . — | Junction-to-top thermal resistance | High-K board ⁽²⁾ | RGZ package | 0.5 | | °C/W |
| ΨJT | metric | Thigh-R board | RSB package | 0.4 | | 0/11 |
| P _{D1} | Device power dissipation ⁽³⁾ | HDMI Mode: OE_N = 0V, DDC_EN = 3.6' ML: VID_PP = 1200mV, 3Gbps TMDS pail AUX: V _I = 3.3V, 100 kHz PRBS HPD: HPD_SINK = 5V, 12C_EN = 3.6V, S | tern | 270+146 | 396+146 | mW |
| P _{D2} | Device power dissipation ⁽³⁾ | $eq:started_st$ | tern | 214+146 | 306+146 | mW |
| P _{SD1} | Device power dissipation under low power with HPDINV = LOW | OE_N = 5V, DDC_EN = 0V, HPDINV = 0V HPD_SINK = 0V | Ι, | 18 | 54 | μW |
| P _{SD2} | Device power dissipation under low power with HPDINV =HIGH | OE_N = 5V, DDC_EN = 0V, HPDINV = 5\ | / | 1.7 | 3 | mW |
| P _{SD3} | Device power dissipation under low power with DDC enabled with HPDINV = HIGH | OE_N = 5V, DDC_EN = 3.6V, HPDINV = | 5V | 16.5 | 29 | mW |
| P _{SD4} | Device power dissipation under low power with DDC enabled with HPDINV = LOW | OE_N = 5V, DDC_EN = 3.6V, HPDINV = | υv | 15 | 26 | mW |

The maximum rating is simulated under 3.6V V_{CC} unless otherwise noted. (1)

(2)

Test conditions for ψ_{JB} and ψ_{JT} are clarified in TI document *Semiconductpr and IC Package Thermal Metrics*, . Power dissipation is the sum of the power consumption from the VCC pins, plus the 146 mW of power from the AVCC (HDMI/DVI (3) Receiver Termination Supply).



6.5 Electrical Characteristics (Device Power)

over operating free-air temperature range (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|------------------|--|--|-----|-----|-----|------|
| I _{CC1} | Supply current (HDMI Mode) | $\label{eq:homoscience} \begin{array}{l} \mbox{HDMI Mode: } OE_N = 0V, \mbox{ DDC}_EN = 3.6 \ V, \\ V_{CC} = 3.6 \ V, \\ \mbox{ML: } VID_PP = 1200 \ mV, 3 \ Gbps \ TMDS \ pattern \\ \mbox{AUX: } V_I = 3.3 \ V, \ 100 \ kHz \ PRBS \\ \mbox{HPD: } HPD_SINK = 5 \ V, \ I2C_EN = 3.6 \ V, \ SRC = \ Hi-Z \end{array}$ | | 82 | 110 | mA |
| I _{CC2} | Supply Current (DVI Mode) | $\label{eq:vector} \begin{array}{l} \mbox{DVI Mode:} OE_N = 0V, \mbox{DDC}_EN = 3.6 \ V, \\ V_{CC} = 3.6 \ V, \\ \mbox{ML: VID}_PP = 1200 \ mV, \ 3 \ Gbps \ TMDS \ pattern \\ \mbox{AUX: VI} = 3.3 \ V, \ 100 \ kHz \ PRBS \\ \mbox{HPD: HPD}_SINK= 5 \ V, \ 12C_EN = 0 \ V, \ SRC = Hi-Z \end{array}$ | | 65 | 85 | mA |
| I _{SD1} | Shutdown current with HPDINV = LOW | $OE_N = 5 V$, $DDC_EN = 0 V$, $HPDINV = 0 V$, $HPD_SINK = 0 V$ | | 5.5 | 15 | μA |
| I _{SD2} | Shutdown current with HPDINV = HIGH | OE_N = 5 V, DDC_EN = 0 V, HPDINV = 5 V | | 0.5 | 0.8 | mA |
| I _{SD3} | Shutdown current with DDC enabled with HPDINV = HIGH | OE_N = 5 V, DDC_EN = 3.6 V, HPDINV = 5 V | | 5 | 8 | mA |
| I _{SD4} | Shutdown current with DDC enabled with HPDINV = LOW | OE_N = 5 V, DDC_EN = 3.6 V, HPDINV = 0 V | | 4.5 | 7.2 | mA |

6.6 Electrical Characteristics (Hot Plug Detect)

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--------------------|---|--|-----|-----|-----|------------|
| V _{OH3.3} | High-level output voltage | $\label{eq:IOH} \begin{array}{l} I_{OH} = -100 \ \mu\text{A}, \ V_{CC} = 3.3 \ V \ \pm 10\%, \\ \text{HPDINV} = \text{LOW} \end{array}$ | 2.8 | | 3.6 | V |
| V _{OH1.1} | High-level output voltage | $\label{eq:IOH} \begin{array}{l} I_{OH} = -100 \ \mu\text{A}, \ V_{CC} = 3.3 \ V \ \pm 10\%, \\ \text{HPDINV} = \text{HIGH} \end{array}$ | 0.8 | | 1.1 | V |
| V _{OL} | Low-level output voltage | I _{OH} = 100 μA | 0 | | 0.1 | V |
| I _{IH} | High-level input current | $V_{IH} = 2.0 \text{ V}, V_{CC} = 3.6 \text{ V}$ | -30 | | 30 | μA |
| IIL | Low-level input current | $V_{IL} = 0.8 V, V_{CC} = 3.6 V$ | -30 | | 30 | μ A |
| RINTHPD | Input pull down on HPD_SINK (HPD Input) | | 110 | 130 | 160 | kΩ |

6.7 Electrical Characteristics (Aux / I²C Pins)

| | PARAMETER | | TEST CONDITIONS | MIN | TYP MAX | UNIT |
|-----------------------|--------------------------|--|--|------|---------|------|
| ΙL | Low input current | | $V_{CC} = 3.6 V, V_1 = 0 V$ | -10 | 10 | μA |
| I _{lkg(AUX)} | Input leakage current | AUX_I ² C pins (SCL_SOURCE, SDA_SOURCE) | $V_{CC} = 3.6V, V_1 = 3.6 V$ | -10 | 10 | μA |
| C _{IO(AUX)} | Input/Output capacitance | AUX_I ² C pins (SCL_SOURCE, SDA_SOURCE) | DC bias = 1.65 V, AC = 2.1Vp-p, f = 100 kHz | | 15 | pF |
| V _{IH(AUX)} | High-level input voltage | AUX_I ² C pins (SCL_SOURCE, SDA_SOURCE) | | 1.6 | 3.6 | V |
| V _{IL1(AUX)} | Low-level input voltage | AUX_I ² C pins (SCL_SOURCE, SDA_SOURCE) | OVS = HIGH | -0.2 | 0.36 | V |
| V _{OL1(AUX)} | Low-level output voltage | AUX_I ² C pins (SCL_SOURCE, SDA_SOURCE) | I _O = 3 mA, OVS = HIGH | 0.6 | 0.7 | V |

Electrical Characteristics (Aux / I²C Pins) (continued)

over recommended operating conditions (unless otherwise noted)

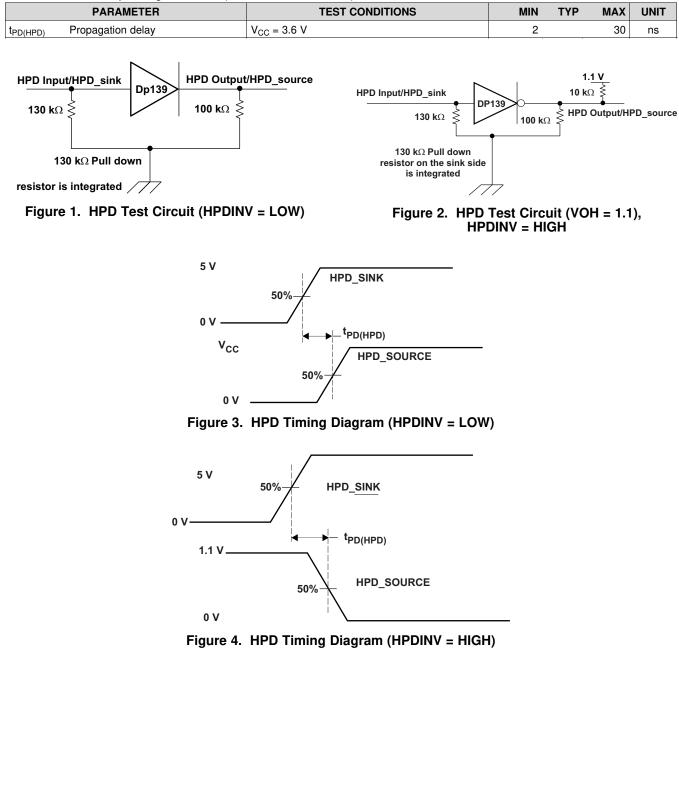
| PARAMETER | | | TEST CONDITIONS | MIN | ΤΥΡ ΜΑΧ | UNIT |
|---|---|--|--|------|---------|------|
| V _{IL2(AUX)} | Low-level input voltage | AUX_I ² C pins (SCL_SOURCE, SDA_SOURCE) | OVS = Hi-Z | -0.2 | 0.36 | V |
| $V_{OL2(AUX)}$ Low-level output voltage AUX_I ² C pins (SCL_SOURCE, SDA_SOURCE) $I_O = 3 \text{ mA}$ | | I _O = 3 mA, OVS = Hi-Z | 0.5 | 0.6 | V | |
| V _{IL3(AUX)} | | | OVS = Low | -0.2 | 0.27 | V |
| V _{OL3(AUX)} | $\begin{array}{c c} & & & \\ \hline x_{i} & & Low-level \mbox{ output voltage } & & AUX_{i}^{2}C \mbox{ pins } \\ & & (SCL_SOURCE, \\ & & SDA_SOURCE) \end{array} I_{O} = 3 \mbox{ mA, OVS = Low } \\ \end{array}$ | | 0.4 | 0.5 | V | |
| I _{lkg(I2C)} | Input leakage current | I ² C SDA/SCL pins (SCL_SINK, SDA_SINK) | V _{CC} = 3.6 V, V _I = 4.95 V | -10 | 10 | μA |
| C _{IO(I2C)} | Input/Output capacitance | I ² C SDA/SCL pins (SCL_SINK, SDA_SINK) | DC bias = 2.5 V, AC = 3.5Vp-p, f = 100 kHz | | 15 | pF |
| V _{IH(I2C)} | High-level input voltage | I ² C SDA/SCL pins (SCL_SINK, SDA_SINK) | | 2.1 | 5.5 | V |
| V _{IL(I2C)} | Low-level input voltage | I ² C SDA/SCL pins (SCL_SINK, SDA_SINK) | | -0.2 | 1.5 | V |
| V _{OL(I2C)} | Low-level output voltage | I ² C SDA/SCL pins (SCL_SINK, SDA_SINK) | I _O = 3mA | | 0.2 | V |

6.8 Electrical Characteristics (TMDS and Main Link Pins)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---------------------|---|--|----------|-----|----------|------|
| V _{OH} | Single-ended HIGH level output voltage | AVCC = 3.3 V, $R_T = 50 \Omega$, | AVCC-10 | | AVCC+10 | mV |
| V _{OL} | Single-ended LOW level output voltage | | AVCC-600 | | AVCC-400 | mV |
| V _{SWING} | Single-ended output voltage swing | | 400 | | 600 | mV |
| V _{OC(SS)} | Change in steady-state common-mode output voltage between logic states | | -5 | | 5 | mV |
| V _{OD(PP)} | Peak-to-Peak output differential voltage | | 800 | | 1200 | mV |
| V _{(O)SBY} | Single-ended standby output voltage | AVCC = 3.3 V, R_T = 50 Ω , OE_N = High | AVCC-10 | | AVCC+10 | mV |
| I _{(O)OFF} | Single-ended power down output current | $\begin{array}{l} 0V\leqVCC\leq1.5\;V,\;AVCC=3.3\;V,\\ R_{T}=50\Omega \end{array}$ | -10 | | 10 | μA |
| I _{OS} | Short circuit output current | See Figure 14 | -15 | | 15 | mA |
| R _{INT} | Input termination impedance | | 40 | 50 | 60 | Ω |
| V _{term} | Input termination voltage | | 1 | | 2 | V |



6.9 Switching Characteristics (Hot Plug Detect)



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6.10 Switching Characteristics (Aux / I²C Pins)

| | PARAMETER | TEST CONDITIONS | MIN | ΤΥΡ Ν | ИАХ | UNIT |
|--------------------|--|-----------------|-----|-------|-----|------|
| t _{PLH1} | Propagation delay time, low to high | Source to Sink | 204 | | 600 | ns |
| t _{PHL1} | Propagation delay time, high to low | Source to Sink | 35 | | 200 | ns |
| t _{PLH2} | Propagation delay time, low to high | Sink to Source | 80 | | 251 | ns |
| t _{PHL2} | Propagation delay time, high to low | Sink to Source | 35 | | 200 | ns |
| t _{f1} | Output signal fall time | Sink Side | 20 | | 72 | ns |
| t _{f2} | Output signal fall time | Source Side | 20 | | 72 | ns |
| f _{SCL} | SCL clock frequency for internal register | Source Side | | | 100 | kHz |
| t _{W(L)} | Clock LOW period for I ² C register | Source Side | 4.7 | | | μS |
| t _{W(H)} | Clock HIGH period for internal register | Source Side | 4.0 | | | μS |
| t _{SU1} | Internal register setup time, SDA to SCL | Source Side | 250 | | | ns |
| t _{h(1)} | Internal register hold time, SCL to SDA | Source Side | 0 | | | μS |
| T _(buf) | Internal register bus free time between STOP and START | Source Side | 4.7 | | | μS |
| t _{su(2)} | Internal register setup time, SCL to START | Source Side | 4.7 | | | μS |
| t _{h(2)} | Internal register hold time, START to SCL | Source Side | 4.0 | | | μS |
| t _{su(3)} | Internal register hold time, SCL to STOP | Source Side | 4.0 | | | μS |

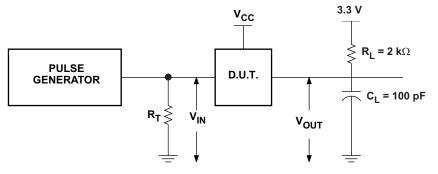


Figure 5. Source Side Test Circuit (SCL_SOURCE, SDA_SOURCE)

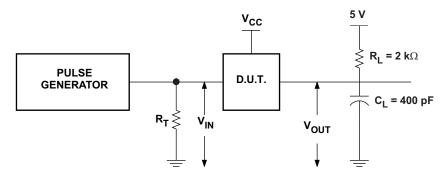


Figure 6. Sink Side Test Circuit (SCL_SINK,SDA_SINK)



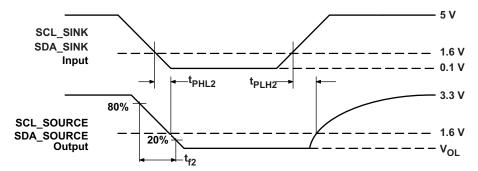


Figure 7. Source Side Output AC Measurements

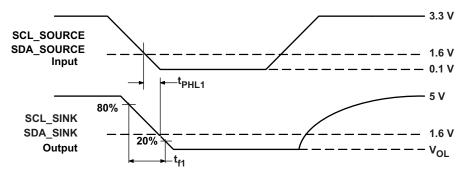


Figure 8. Sink Side Output AC Measurements

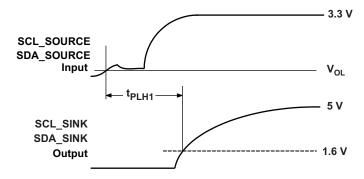


Figure 9. Sink Side Output AC Measurements Continued

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6.11 Switching Characteristics (TMDS and Main Link Pins)

| | PARAMETER | TEST CONDITIONS | MIN | ΤΥΡ | MAX | UNIT |
|-----------------------|---|--|-----|-----|-----|------|
| t _{PLH} | Propagation delay time | | 250 | 350 | 600 | ps |
| t _{PHL} | Propagation delay time | | 250 | 350 | 600 | ps |
| t _{R1} | Rise Time (I2C_EN = HI, SRC = Hi-Z) | | 60 | 85 | 120 | ps |
| t _{F1} | Fall Time (I2C_EN = HI, SRC = Hi-Z) | | 60 | 85 | 120 | ps |
| t _{R2} | Rise Time (I2C_EN = Low, SRC = Hi-Z) | | | 115 | 150 | ps |
| t _{F2} | Fall Time (I2C_EN = Low, SRC = Hi-Z) | | | 115 | 150 | ps |
| t _{R3} | Rise Time (I2C_EN = HI, SRC = HI) | | | 150 | 180 | ps |
| t _{F3} | Fall Time (I2C_EN = HI, SRC = HI) | | | 150 | 180 | ps |
| t _{R4} | Rise Time (I2C_EN = HI, SRC = Low) | AVCC=3.3 V, R _T = 50 Ω, f = 1MHz, R _{Vsadj} = 4.02 kΩ | | 115 | 150 | ps |
| t _{F4} | Fall Time (I2C_EN = HI, SRC = Low) | - 11Vsadj - 4.02 102 | | 115 | 150 | ps |
| t _{R5} | Rise Time (I2C_EN = Low, SRC = HI) | | | 175 | 220 | ps |
| t _{F5} | Fall Time (I2C_EN = Low, SRC = HI) | | | 175 | 220 | ps |
| t _{R6} | Rise Time (I2C_EN = Low, SRC = Low) | | | 150 | 180 | ps |
| t _{F6} | Fall Time (I2C_EN = Low, SRC = Low) | | | 150 | 180 | ps |
| t _{SK(P)} | Pulse skew | | | 8 | 15 | ps |
| t _{SK(D)} | Intra-pair skew | | | 20 | 65 | ps |
| t _{SK(O)} | Inter-pair skew | | | 20 | 100 | ps |
| t _{JITD(PP)} | Peak-to-peak output residual data jitter | $\begin{array}{l} \mbox{AVCC} = 3.3 \mbox{ V}, R_T = 50 \Omega, dR = 3 \mbox{Gbps}, \\ \mbox{TMDS} \mbox{ output slew rate (default).} \\ R_{Vsadj} = 4.02 \kappa \Omega \mbox{ (refer to Figure 13)} \end{array}$ | | 14 | 50 | ps |
| t _{JITC(PP)} | Peak-to-peak output residual clock jitter | AVCC = 3.3 V , $R_T = 50\Omega$, $f = 300 \text{ MHz}$ TMDS output slew rate (default). R_{Vsadi} = 4.02 k Ω (refer to Figure 13) | | 8 | 30 | ps |

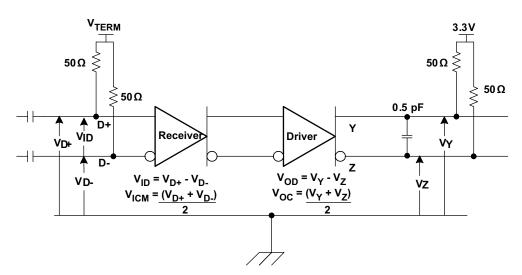


Figure 10. TMDS Main Link Test Circuit



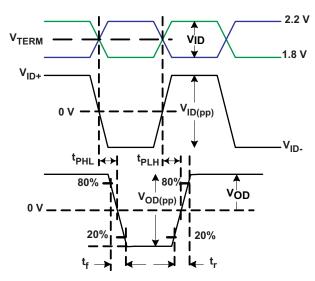


Figure 11. TMDS Main Link Timing Measurements

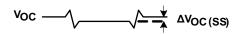
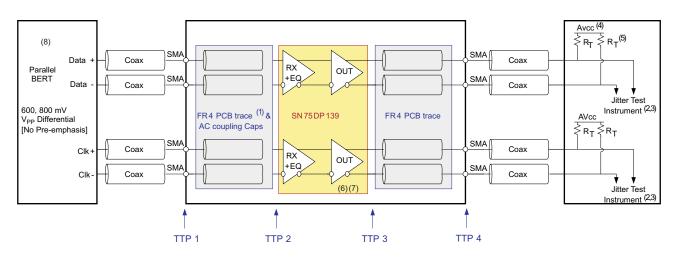


Figure 12. TMDS Main Link Common Mode Measurements



1. The FR4 trace between TTP1 and TTP2 is designed to emulate 1-8" of FR4, AC coupling cap, connector and another 1-8" of FR4. Trace width - 4 mils.

All Jitter is measured at a BER of 10°
Residual jitter reflects the total jitter measured at TTP4 minus the jitter measured at TTP1

4. AVCC = 3.3V 5. RT = 50Ω,

6. Jitter data is taken with SN75DP139 configured in the fastest slew rate setting(default) 7. Rvsadj = $4.02k\Omega$

8. The input signal from parallel BERT does not have any pre-emphasis. Refer to recommended operating conditions

Figure 13. TMDS Jitter Measurements



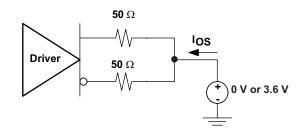
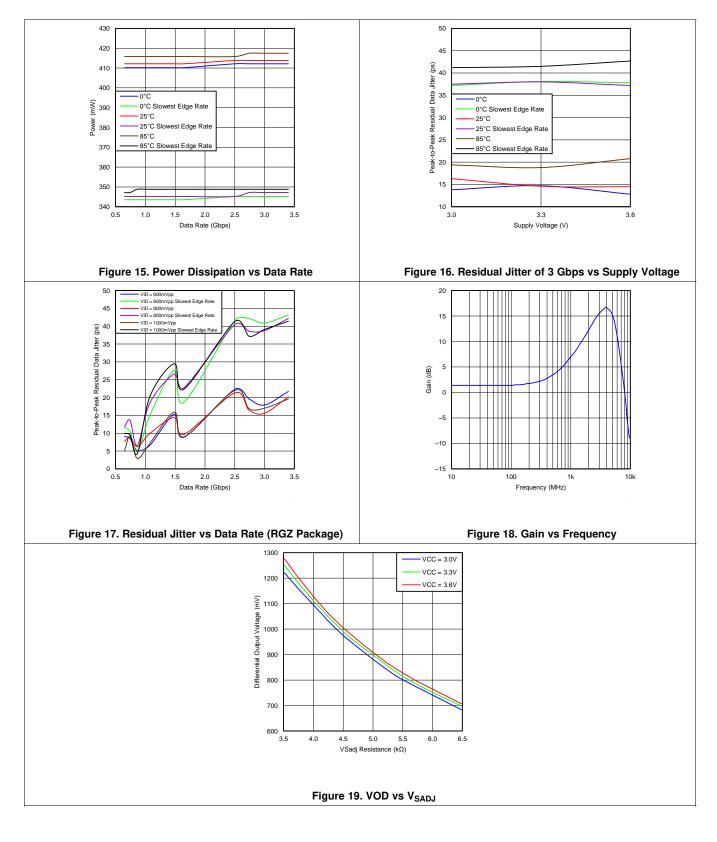


Figure 14. TMDS Main Link Short Circuit Output Circuit



6.12 Typical Characteristics

AVCC = 3.3 V, R_T = 50 Ω



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7 Detailed Description

7.1 Overview

The SN75DP139 is a Dual-Mode DisplayPort input to Transition-Minimized Differential Signaling (TMDS) output. The TMDS output has a built in level shifting re-driver supporting Digital Video Interface (DVI) 1.0 and High Definition Multimedia Interface (HDMI) 1.4b standards.

An integrated Active I2C buffer isolates the capacitive loading of the source system from that of the sink and interconnecting cable. This isolation improves overall signal integrity of the system and allows for considerable design margin within the source system for DVI / HDMI compliance testing.

A logic block was designed into the SN75DP139 in order to assist with TMDS connector identification. Through the use of the I2C_EN pin, this logic block can be enabled to indicate the translated port is an HDMI port; therefore legally supporting HDMI content.

7.2 Functional Block Diagram

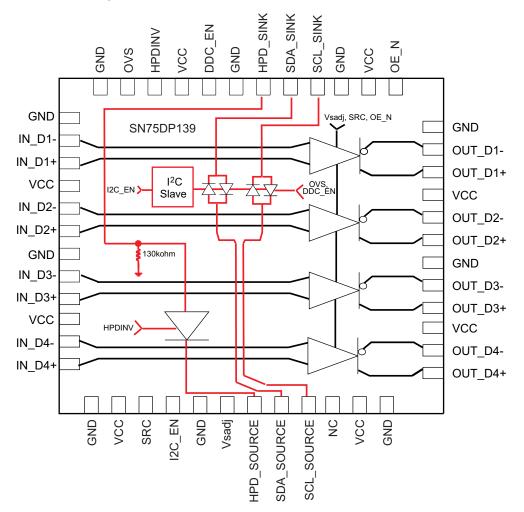


Figure 20. Data Flow Block Diagram



7.3 Feature Description

The SN75DP139 is designed to operate off of one supply voltage VCC.

The SN75DP139 offers features to enable or disable different functionality based on the status of the output enable (OE_N) and DDC Enable (DDC_EN) inputs.

- OE_N affects only the High Speed Differential channels (Main Link/TMDS link). OE_N has no influence on the HPD_SINK input, HPD_SOURCE output, or the DDC buffer.
- DDC_EN affects only the DDC channel. The DDC_EN should never change state during the I2C operation. Disabling DDC_EN during a bus operation will hang the bus, while enabling the DDC_EN during bus traffic will corrupt the I2C bus operation. DDC_EN should only be toggled while the bus is idle.
- TMDS output edge rate control has impact on the SN75DP139 Active power. See Figure 15. TMDS output edge rate can be controlled by SRC pin. Slower output Edge Rate Setting helps in reducing the Active power consumption.

| HPD_SINK | HPDINV | OE_N | DDC_EN | IN_Dx | OUT_Dx | DDC | HPD_SOURCE | MODE |
|----------------|--------|------|--------|---|--------------------|--------------------|--|--|
| Input = H or L | L | L | L | 50 Ω termination active | Enabled | High- impedance | Output = non inverted, follows HPD_SINK | Active |
| Input = H or L | L | L | н | 50 Ω termination active | Enabled | enabled | Output = non inverted, follows HPD_SINK | Active |
| Input = H or L | L | Н | L | 50Ω termination active: Terminations connected to common Mode Voltage = 0V. | High- impedance | High- impedance | Output = non inverted, follows HPD_SINK | Low Power |
| Input = H or L | L | Н | Н | 50Ω termination active: Terminations connected to common Mode Voltage = 0V. | High- impedance | enabled | Output = non inverted, follows HPD_SINK | Low Power with DDC channel enabled |
| Input = H or L | н | L | L | 50 Ω termination active | Enabled | High- impedance | Output = inverted, follows HPD_SINK | Active |
| Input = H or L | н | L | н | 50 Ω termination active | Enabled | enabled | Output = inverted, follows HPD_SINK | Active |
| Input = H or L | Н | Н | L | 50Ω termination active: Terminations connected to common Mode Voltage = 0V. | High- impedance | High- impedance | Output = inverted, follows HPD_SINK | Low Power |
| Input = H or L | Н | Н | Н | 50 Ω termination active: Terminations connected to common Mode Voltage = 0V. | High- impedance | enabled | Output = inverted, follows HPD_SINK | Low Power with DDC channel enabled |

Table 2. Packaging Options

7.3.1 Hot Plug Detect

The SN75DP139 has a built in level shifter for the HPD outputs. The output voltage level of the HPD pin is defined by the voltage level of the VCC pin. The HPD input or HPD_SINK side has 130kohm of pull down resistor integrated.

The logic of the HPD_SOURCE output always follows the logic state of the HPD_SINK input based on the HPDINV pin logic, regardless of whether the device is in Active or Low Power Mode

7.3.2 Aux / I²C Pins

The SN75DP139 utilizes an active I²C repeater. The repeater is designed to isolate the parasitic effects of the system in order to aid with system level compliance.

In addition to the I^2C repeater, the SN75DP139 also supports the connector detection I^2C register. This register is enabled via the I^2C_EN pin. When active an internal memory register is readable via the AUX_I²C I/O. The functionality of this register block is described in the *Programming* section.



7.3.3 TMDS and Main Link Pins

The main link inputs are designed to support DisplayPort 1.1 specification. The TMDS outputs of the SN75DP139 are designed to support the Digital Video Interface (DVI) 1.0 and High Definition Multimedia Interface (HDMI) 1.4b specifications. The differential output voltage swing can be fine tuned with the R_{Vsadj} resistor.

The DP++ (dual-mode) input of the SN75DP139 is designed to accommodate the standard DP level ac coupled signal with no pre-emphasis with up to 16 inches of trace (4 mil 100 Ω differential stripline).

7.3.4 Input/Output Equivalent Circuits

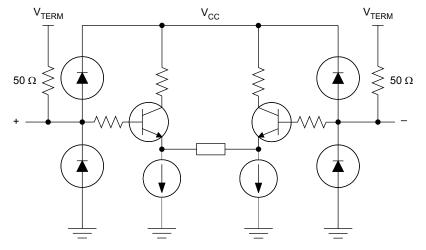


Figure 21. DisplayPort Input Stage

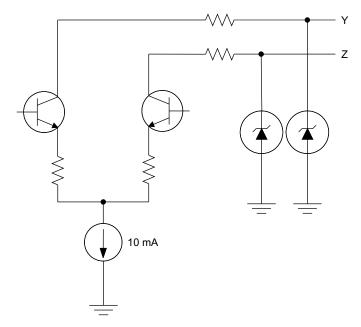
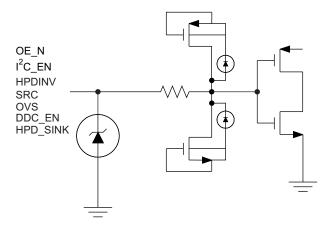
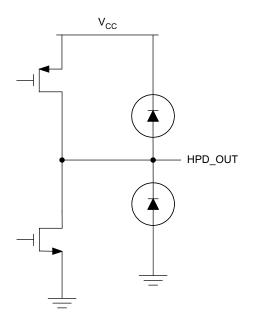


Figure 22. TMDS Output Stage

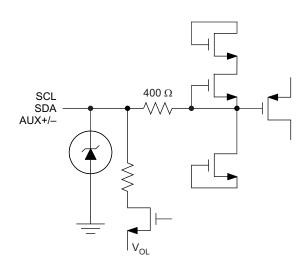
















7.4 Device Functional Modes

7.4.1 Active

The SN75DP139 activates the main link channel and thus is able to transmit the TMDS content.

7.4.2 Low Power With DDC Channel Enabled

The SN75DP139 is in low power but keeps its DDC channel active, this allows the device to configure its internal I2C registers.

7.4.3 Low Power

The SN75DP139 is in the lowest power mode, with no activity on the DDC or main link channels.

7.5 Programming

7.5.1 I²C Interface Notes

The I²C interface can be used to access the internal memory of the SN75DP139. I²C is a two-wire serial interface developed by Philips Semiconductor (see I²C-Bus Specification, Version 2.1, January 2000). The bus consists of a data line (SDA) and a clock line (SCL) with pull-up structures. When the bus is *idle*, both SDA and SCL lines are pulled high. All the I²C compatible devices connect to the I²C bus through open drain I/O pins, SDA and SCL. A *master* device, usually a microcontroller or a digital signal processor, controls the bus. The master is responsible for generating the SCL signal and device addresses. The master also generates specific conditions that indicate the START and STOP of data transfer. A *slave* device receives and/or transmits data on the bus under control of the master device. The SN75DP139 works as a slave and supports the standard mode transfer (100 kbps) as defined in the I²C-Bus Specification.

The basic I²C start and stop access cycles are shown in Figure 26.

The basic access cycle consists of the following:

- A start condition
- A slave address cycle
- Any number of data cycles
- A stop condition

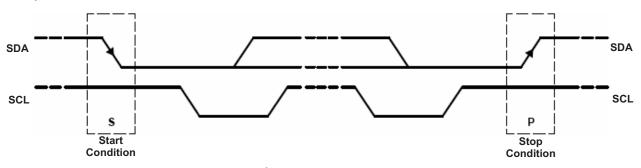


Figure 26. I²C Start And Stop Conditions

7.5.2 General I²C Protocol

- The master initiates data transfer by generating a start condition. The start condition is when a high-to-low transition occurs on the SDA line while SCL is high, as shown in Figure 28. All I²C-compatible devices should recognize a start condition.
- The master then generates the SCL pulses and transmits the 7-bit address and the *read/write direction bit* R/W on the SDA line. During all transmissions, the master ensures that data is *valid*. A *valid data condition* requires the SDA line to be stable during the entire high period of the clock pulse (see Figure 27). All devices recognize the address sent by the master and compare it to their internal fixed addresses. Only the slave device with a matching address generates an *acknowledge* (see Figure 28) by pulling the SDA line low during the entire high period of the ninth SCL cycle. On detecting this acknowledge, the master knows that a communication link with a slave has been established.



Programming (continued)

- The master generates further SCL cycles to either *transmit* data to the slave (R/W bit 0) or *receive* data from the slave (R/W bit 1). In either case, the receiver needs to acknowledge the data sent by the *transmitter*. So an acknowledge signal can either be generated by the master or by the slave, depending on which one is the receiver. The 9-bit valid data sequences consisting of 8-bit data and 1-bit acknowledge can continue as long as necessary (See Figure 29).
- To signal the end of the data transfer, the master generates a *stop condition* by pulling the SDA line from low to high while the SCL line is high (see Figure 29). This releases the bus and stops the communication link with the addressed slave. All I²C compatible devices must recognize the stop condition. Upon the receipt of a *stop condition*, all devices know that the bus is released, and they wait for a *start condition* followed by a matching address.

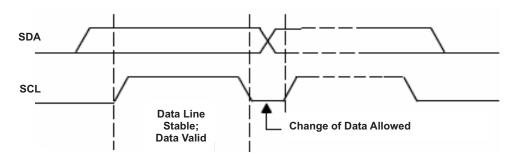


Figure 27. I²C Bit Transfer

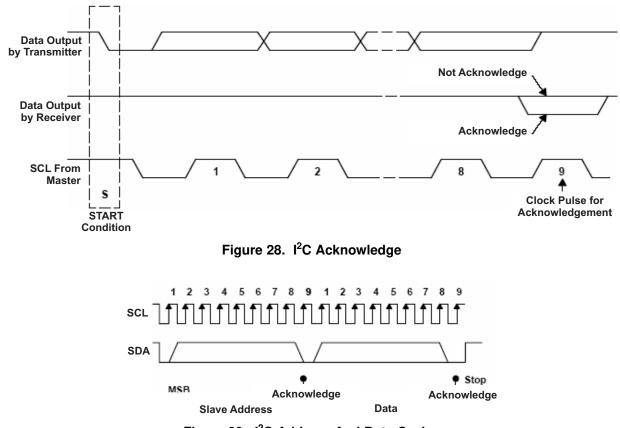


Figure 29. I²C Address And Data Cycles



Programming (continued)

During a read cycle, the slave receiver will acknowledge the initial address byte if it decodes the address as its address. Following this initial acknowledge by the slave, the master device becomes a receiver and acknowledges data bytes sent by the slave. When the master has received all of the requested data bytes from the slave, the not acknowledge (A) condition is initiated by the master by keeping the SDA signal high just before it asserts the stop (P) condition. This sequence terminates a read cycle as shown in Figure 30 and Figure 31. See Example – Reading from the SN75DP139 section for more information.

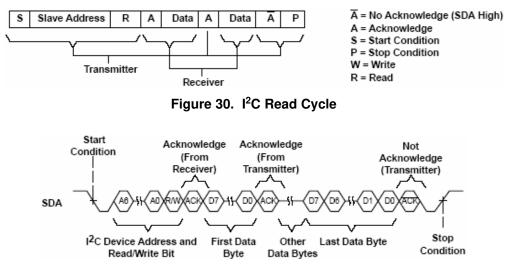


Figure 31. Multiple Byte Read Transfer

7.5.3 Slave Address

Both SDA and SCL must be connected to a positive supply voltage via a pull-up resistor. These resistors should comply with the I^2C specification that ranges from $2k\Omega$ to $19k\Omega$. When the bus is free, both lines are high. The address byte is the first byte received following the START condition from the master device. The 7-bit address is factory preset to 1000000. Table 3 lists the calls that the SN75DP139 will respond to.

| | Fixed Address | | | | | | | | |
|----------------|---------------|---|---|---|---|---|----------------|--|--|
| Bit 7 (MSB) | | | | | | | Bit 0 (R/W) | | |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | | |

7.5.3.1 Sink Port Selection Register And Source Plug-In Status Register Description (Sub-Address)

The SN75DP139 operates using a multiple byte transfer protocol similar to Figure 31. The internal memory of the SN75DP139 contains the phrase "DP-HDMI ADAPTOR<EOT>" converted to ASCII characters. The internal memory address registers and the value of each can be found in Table 4.

During a read cycle, the SN75DP139 will send the data in its selected sub-address in a single transfer to the master device requesting the information. See the *Example – Reading from the SN75DP139* section of this document for the proper procedure on reading from the SN75DP139.

| Address | 0x00 | 0x01 | 0x02 | 0x03 | 0x04 | 0x05 | 0x06 | 0x07 | 0x08 | 0x09 | 0x0A | 0x0B | 0x0C | 0x0D | 0x0E | 0x0F | 0x10 |
|---------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| Data | 44 | 50 | 2D | 48 | 44 | 4D | 49 | 20 | 41 | 44 | 41 | 50 | 54 | 4F | 52 | 04 | FF |



7.5.3.2 Example – Reading From The SN75DP139:

The read operation consists of several steps. The I²C master begins the communication with the transmission of the start sequence followed by the slave address of the SN75DP139 and logic address of 00h. The SN75DP139 will acknowledge it's presence to the master and begin to transmit the contents of the memory registers. After each byte is transferred the SN75DP139 will wait for either an acknowledge (ACK) or a not-acknowledge (NACK) from the master. If an ACK is received the next byte of data will be transmitted. If a NACK is received the data transmission sequence is expected to end and the master should send the stop command.

The SN75DP139 will continue to send data as long as the master continues to acknowledge each byte transmission. If an ACK is received after the transmission of byte 0x0F the SN75DP139 will transmit byte 0x10 and continue to transmit byte 0x10 for all further ACK's until a NACK is received.

The SN75DP139 also supports an accelerated read mode where steps 1–6 can be skipped.

SN75DP139 Read Phase

| | | - | | | | | | |
|---|------|-------|------|------|------|------|------|------|
| Step 1 | 0 | _ | | | | | | |
| I ² C Start (Master) | S | | | | | | | |
| | | | | 1 | | | | |
| Step 2 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| I ² C General Address Write (Master) | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | | П | | | | | | |
| Step 3 | 9 | _ | | | | | | |
| I ² C Acknowledge (Slave) | A | | | | | | | |
| Step 4 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| I ² C Logic Address (Master) | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | T. | _ | | | | | | |
| Step 5 | 9 | | | | | | | |
| I ² C Acknowledge (Slave) | A | | | | | | | |
| | | Т | | | | | | |
| Step 6 | 0 | _ | | | | | | |
| I ² C Stop (Master) | P | | | | | | | |
| Step 7 | 0 | 1 | | | | | | |
| I ² C Start (Master) | S | 1 | | | | | | |
| | | → | | | | | | |
| Step 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| I ² C General Address Read (Master) | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| | | 7 | | | | | | |
| Step 9 | 9 | _ | | | | | | |
| I ² C Acknowledge (Slave) | A | | | | | | | |
| Step 10 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| I ² C Read Data (Slave) | Data | Data | Data | Data | Data | Data | Data | Data |
| | Duid | Duiu | Duiu | Duiu | Duiu | Dulu | Duiu | Dulu |

Where Data is determined by the Logic values Contained in the Sink Port Register

| Step 11 | 9 |
|---|---|
| I ² C Not-Acknowledge (Master) | Х |

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Where X is an A (Acknowledge) or \overline{A} (Not-Acknowledge) An A causes the pointer to increment and step 10 is repeated. An \overline{A} causes the slave to stop transmitting and proceeds to step 12.

| Step 12 | 0 |
|--------------------------------|---|
| I ² C Stop (Master) | Р |



8 Application and Implementation

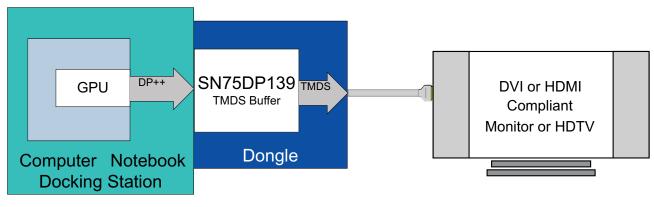
NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The typical application for the SN75DP139 is to translate from DP++ to TMDS, and thus expand the connectivity for any DP++ source to HDMI 1.4b and DVI sinks. This can be clearly explained when you have the SN75DP139 in a dongle connected to the DP++ source.

8.2 Typical Application



GPU - Graphics Processing Unit DP++ - Dual-Mode DisplayPort TMDS - Transition-Minimized Differential Signaling DVI - Digital Visual Interface

HDMI - High Definition Multimedia Interface

Figure 32. Typical Application

8.2.1 Design Requirements

| DESIGN PARAMETERS | VALUE |
|--|----------------|
| VDD Main Power Supply | 3.0 - 3.6 V |
| Main Link Peak-to-Peak AC Input Differential Voltage | 0.15 - 1.2 V |
| TMDS Output Termination Voltage | 3.0 - 3.6 V |
| TMDS Output Swing Voltage Bias Resistor | 3.65 - 4.02 kΩ |

8.2.2 Detailed Design Procedure

8.2.2.1 DVI Application

In DVI application case, it is recommended that between the SN75DP139 TMDS outputs (OUT_Dx) and a through hole DVI connector that a series resistor placeholder is incorporated. This could help in case if there are signal integrity issues as well as help pass system level compliance.

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8.2.3 Application Curve

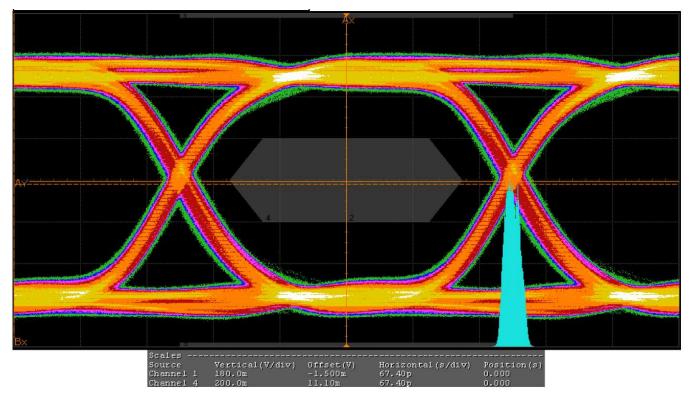


Figure 33. Data Jitter



9 Power Supply Recommendations

Use a VCC power rail able to supply 110 mA for the SN75DP139, Place four 1 uF, two 0.1 uF and two 0.01 uF capacitors under the SN75DP139 and close to the VCC pins, all connecter in parallel between VCC and GND.

10 Layout

10.1 Layout Guidelines

10.1.1 Layer Stack

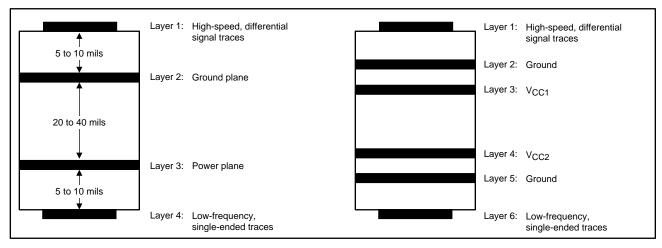


Figure 34. Recommended 4- or 6- Layer (0.062") Stack for a Receiver PCB Design

Routing the high-speed differential signal traces on the top layer avoids the use of vias (and the introduction of their inductances) and allows for clean interconnects from the DisplayPort connectors to the repeater inputs and from the repeater output to the subsequent receiver circuit.

Placing a solid ground plane next to the high-speed signal layer establishes controlled impedance for transmission line interconnects and provides an excellent low-inductance path for the return current flow.

Placing the power plane next to the ground plane creates additional high-frequency bypass capacitance.

Routing the fast-edged control signals on the bottom layer by prevents them from cross-talking into the high-speed signal traces and minimizes EMI.

If the receiver requires a supply voltage different from the one of the repeater, add a second power/ground plane system to the stack to keep it symmetrical. This makes the stack mechanically stable and prevents it from warping. Also, the power and ground plane of each power system can be placed closer together, thus increasing the high-frequency bypass capacitance significantly. Finally, a second power/ground system provides added isolation between the signal layers.

10.1.2 Differential Traces

Guidelines for routing PCB traces are necessary when trying to maintain signal integrity and lower EMI. Although there seems to be an endless number of precautions to be taken, this section provides only a few main recommendations as layout guidance.

- 1. Reduce intra-pair skew in a differential trace by introducing small meandering corrections at the point of mismatch.
- Reduce inter-pair skew, caused by component placement and IC pinouts, by making larger meandering correction along the signal path. Use chamfered corners with a length-to-trace width ratio of between 3 and 5. The distance between bends should be 8 to 10 times the trace width.
- 3. Use 45 degree bends (chamfered corners), instead of right-angle (90°) bends. Right-angle bends increase the effective trace width, which changes the differential trace impedance creating large discontinuities. A 450

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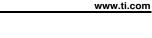
Layout Guidelines (continued)

bends is seen as a smaller discontinuity.

- 4. When routing around an object, route both trace of a pair in parallel. Splitting the traces changes the line-toline spacing, thus causing the differential impedance to change and discontinuities to occur.
- 5. Place passive components within the signal path, such as source-matching resistors or ac-coupling capacitors, next to each other. Routing as in case a) creates wider trace spacing than in b), the resulting discontinuity, however, is limited to a far narrower area.
- 6. When routing traces next to a via or between an array of vias, make sure that the via clearance section does not interrupt the path of the return current on the ground plane below.
- 7. Avoid metal layers and traces underneath or between the pads off the DisplayPort connectors for better impedance matching. Otherwise they will cause the differential impedance to drop below 75 Ω and fail the board during TDR testing.
- 8. Use the smallest size possible for signal trace vias and DisplayPort connector pads as they have less impact on the 100 Ω differential impedance. Large vias and pads can cause the impedance to drop below 85 Ω .
- 9. Use solid power and ground planes for 100 Ω impedance control and minimum power noise.
- 10. For 100 Ω differential impedance, use the smallest trace spacing possible, which is usually specified by the PCB vendor.
- 11. Keep the trace length between the DisplayPort connector and the DisplayPort device as short as possible to minimize attenuation.
- 12. Use good DisplayPort connectors whose impedances meet the specifications.
- 13. Place bulk capacitors (for example, 10 μ F) close to power sources, such as voltage regulators or where the power is supplied to the PCB.
- 14. Place smaller 0.1 μF or 0.01 μF capacitors at the device.

10.2 Layout Example







Layout Example (continued)

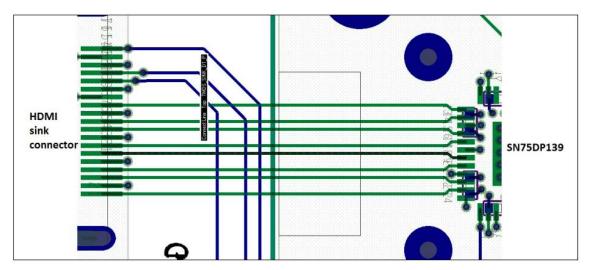


Figure 36. Sink Side Layout Example

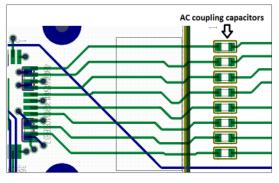


Figure 37. AC Capacitors Placement and Routing Example

11 Device and Documentation Support

11.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E[™] Online Community *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.3 Trademarks

E2E is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

11.4 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.5 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



PACKAGING INFORMATION

| Orderable Device | | Package Type | | Pins | - | | Lead finish/ Ball material | MSL Peak Temp | Op Temp (°C) | Device Marking | Samples |
|------------------|--------|--------------|---------|------|------|--------------|-------------------------------|---------------------|--------------|----------------|---------|
| | (1) | | Drawing | | Qty | (2) | (6) | (3) | | (4/5) | |
| SN75DP139RGZR | ACTIVE | VQFN | RGZ | 48 | 2500 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | 0 to 85 | DP139 | Samples |
| SN75DP139RGZT | ACTIVE | VQFN | RGZ | 48 | 250 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | 0 to 85 | DP139 | Samples |
| SN75DP139RSBR | ACTIVE | WQFN | RSB | 40 | 3000 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | 0 to 85 | DP139 | Samples |
| SN75DP139RSBT | ACTIVE | WQFN | RSB | 40 | 250 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | 0 to 85 | DP139 | Samples |

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

⁽³⁾ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

⁽⁴⁾ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

⁽⁵⁾ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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10-Dec-2020

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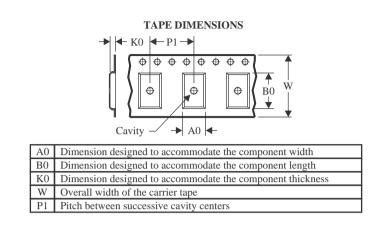


Texas

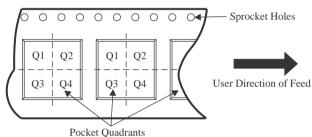
STRUMENTS

TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



| *All dimensions are nominal | | | | | | | | | | | | |
|-----------------------------|------|--------------------|----|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| Device | - | Package Drawing | | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
| SN75DP139RGZR | VQFN | RGZ | 48 | 2500 | 330.0 | 16.4 | 7.3 | 7.3 | 1.1 | 12.0 | 16.0 | Q2 |
| SN75DP139RGZT | VQFN | RGZ | 48 | 250 | 180.0 | 16.4 | 7.3 | 7.3 | 1.1 | 12.0 | 16.0 | Q2 |
| SN75DP139RSBR | WQFN | RSB | 40 | 3000 | 330.0 | 12.4 | 5.3 | 5.3 | 1.1 | 8.0 | 12.0 | Q2 |
| SN75DP139RSBT | WQFN | RSB | 40 | 250 | 180.0 | 12.4 | 5.3 | 5.3 | 1.1 | 8.0 | 12.0 | Q2 |



PACKAGE MATERIALS INFORMATION

20-Apr-2023



*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|---------------|--------------|-----------------|------|------|-------------|------------|-------------|
| SN75DP139RGZR | VQFN | RGZ | 48 | 2500 | 367.0 | 367.0 | 38.0 |
| SN75DP139RGZT | VQFN | RGZ | 48 | 250 | 210.0 | 185.0 | 35.0 |
| SN75DP139RSBR | WQFN | RSB | 40 | 3000 | 346.0 | 346.0 | 33.0 |
| SN75DP139RSBT | WQFN | RSB | 40 | 250 | 210.0 | 185.0 | 35.0 |

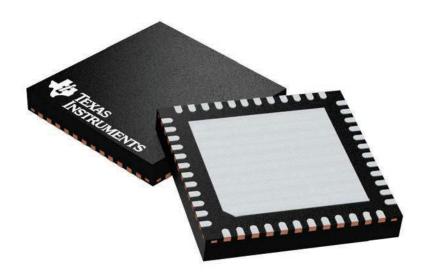
RGZ 48

7 x 7, 0.5 mm pitch

GENERIC PACKAGE VIEW

VQFN - 1 mm max height

PLASTIC QUADFLAT PACK- NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



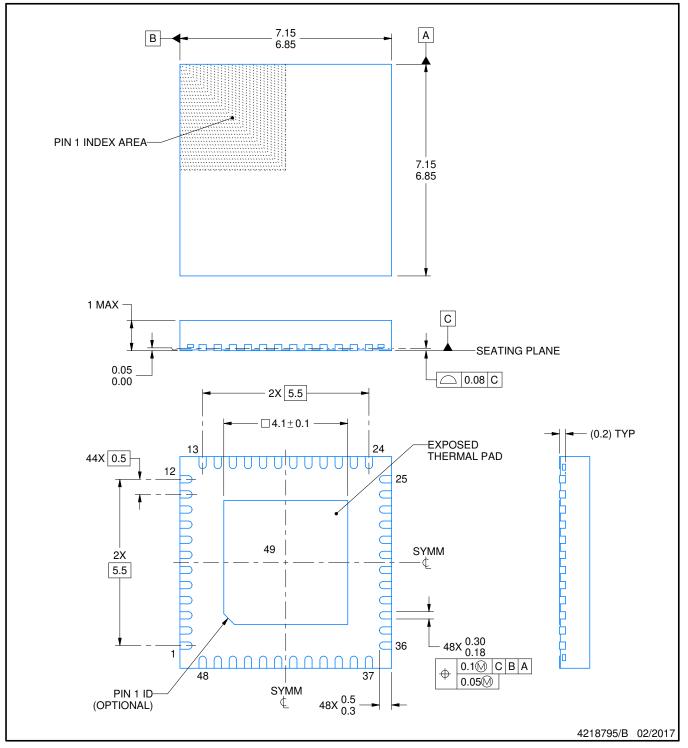
RGZ0048B



PACKAGE OUTLINE

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

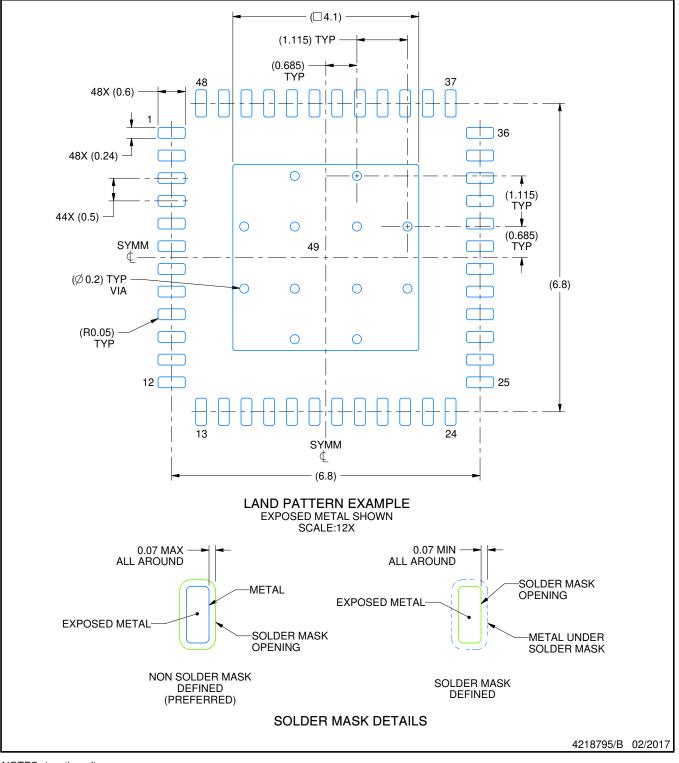


RGZ0048B

EXAMPLE BOARD LAYOUT

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

 This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

 Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

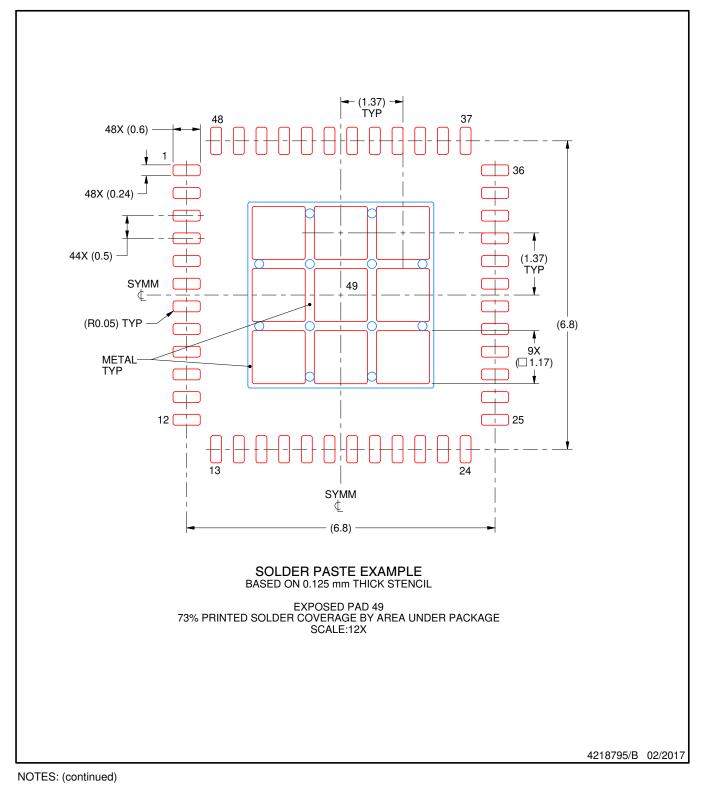


RGZ0048B

EXAMPLE STENCIL DESIGN

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

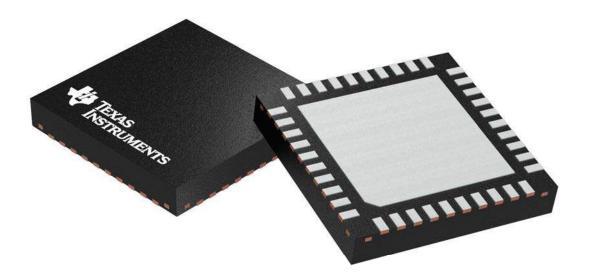


RSB 40

5 x 5 mm, 0.4 mm pitch

GENERIC PACKAGE VIEW

WQFN - 0.8 mm max height PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



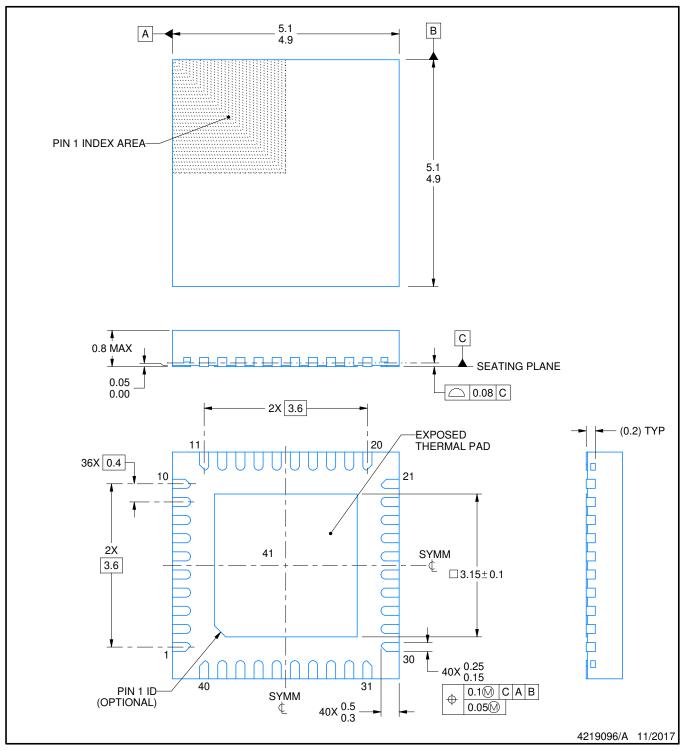
RSB0040E



PACKAGE OUTLINE

WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

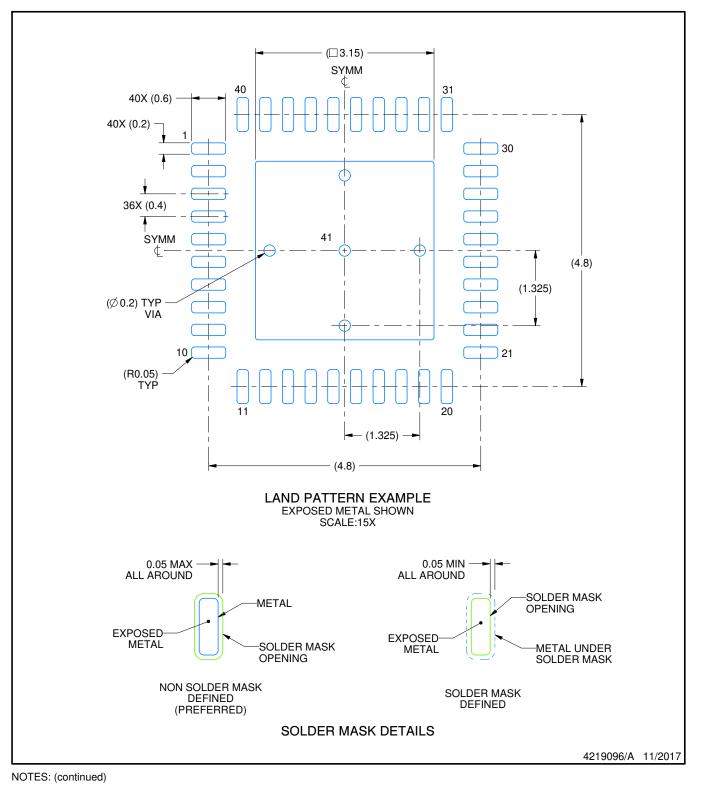


RSB0040E

EXAMPLE BOARD LAYOUT

WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



 This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

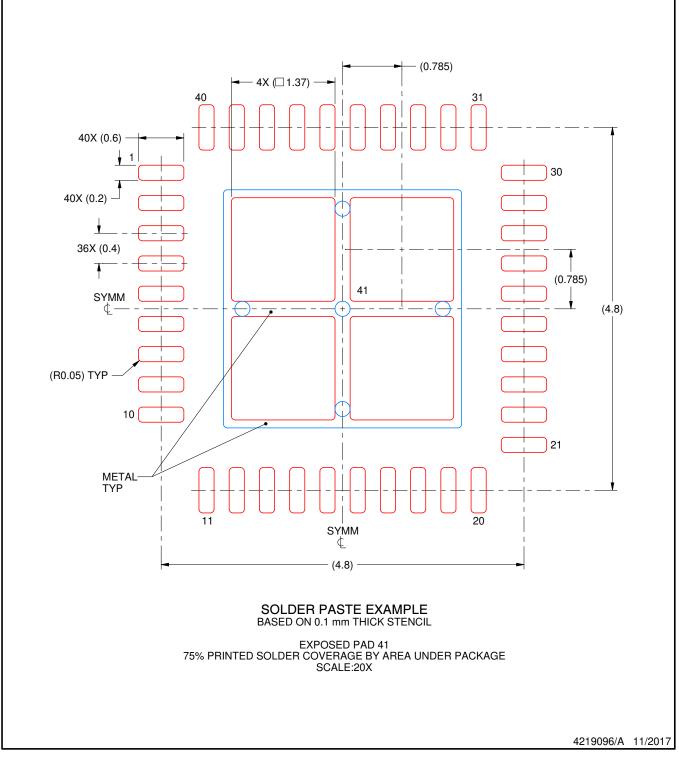


RSB0040E

EXAMPLE STENCIL DESIGN

WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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