

Features

- 3.3 and 5 VDC voltage supply option
- PWM Absolute Position
- Bushing or servo mount

CMOS and TTL compatible

- Non-contacting magnetic technology
- Small size

- Resolution: 1024 states
- Long life
- High operating speed
- Highly repeatable
- Sealed option
- Magnetic technology

EMS22P - Non-Contacting PWM Encoder

Electrical Characteristics Electrical Travel **Output Voltage** Low Output Level Vss+0.4 V maximum **Output Current** Accuracy Nominal<u>+0</u>.7 ° or better Worst Case ±1.4 ° **Environmental Characteristics** Operating Temperature Range......-40 °C to +125 °C (-40 °F to +257 °F) HumidityMIL-STD-202, Method 103B, Condition B Rotational Life T & W Bushings (@1,000 rpm with 250 g side load)50,000,000 revolutions

Mechanical Characteristics

Mechanical Angle	
Torque	
Starting	
Running	
Mounting Torque	
Shaft End Play	
Shaft Radial Play	
Weight	
Terminals	Axial, radial or ribbon cable
Soldering Condition	
Manual Soldering	
-	370 °C (700 °F) max. for 3 seconds
Wave Soldering	
-	260 °C (500 °F) max. for 10 seconds
Wash processes	Not recommended
Marking	
Hardware	

IP Rating

Pin Configuration

Output Type	Pin 1	Pin 2	Pin 3	Pin 4	Pin 5	Pin 6
PWM	PWM Signal	GND	GND	GND	VCC*	CS**
* Can be 5 or 3.3 VD ** Active low chip sele			6 to GND.			
	Cancer and Re	productive Ha	rm - <u>www</u> .	P65Warnings.ca.go	V	
*RoHS Directive 2015/86	3, Mar 31, 2015 and	d Annex.				

Specifications are subject to change without notice.

Users should verify actual device performance in their specific applications.

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Applications

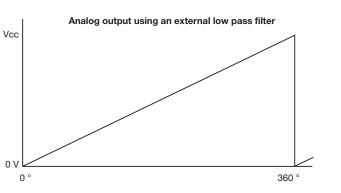
- Material handling equipment
- Brushless DC motor commutation
- Robotics
- Automotive
- Industrial automation
- Petroleum refinery

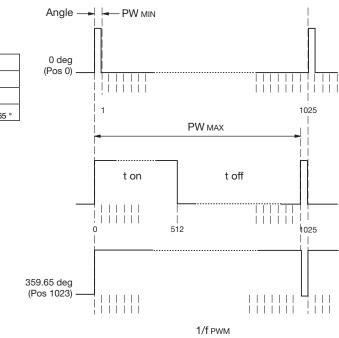
EMS22P - Non-Contacting PWM Encoder

Output Type Waveform and Variant Table

PWM Output

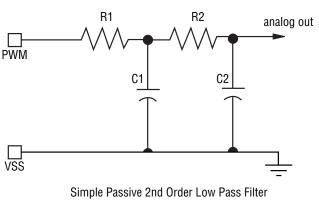
Parameter	Symbol	Type Uni		Note
PWM frequency	fPWM	0.9756	KHz	Signal period: 1025 µs
MIN pulse with	PWMIN	1	μs	Position 0 Angle 0 °
MAX pulse with	PWMAX	1024	μs	Position 1023 Angle 359.65 °





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Position = t on * 1025/(t on + t off) - 1



Recommended Filter

R1, R2 \ge 4.7K Ohms C1, C2 \ge 1 μ F / 6 V

R1 should be \ge 4.7K ohms to avoid loading of the PWM output. Larger values of Rx and Cx will provide better filtering and less ripple, but will also slow down the response time.

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- Medical (low/medium risk)*
- Office equipment
- Audio and broadcast equipment

Consult factory for options not shown, including:

- . Special shaft/bushing sizes and features
- Connectors

.

- .
- Non-standard resolutions •

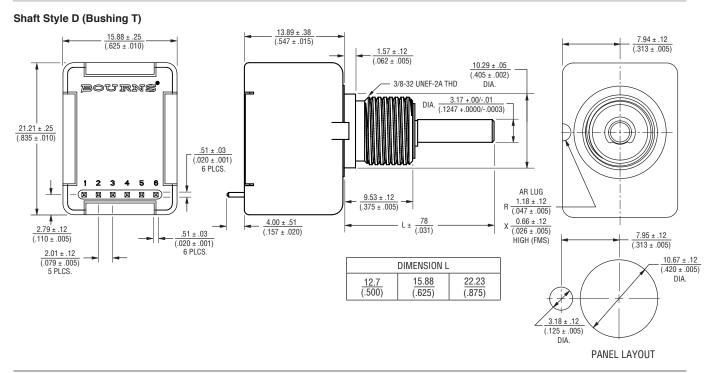
Wire lead or cable options

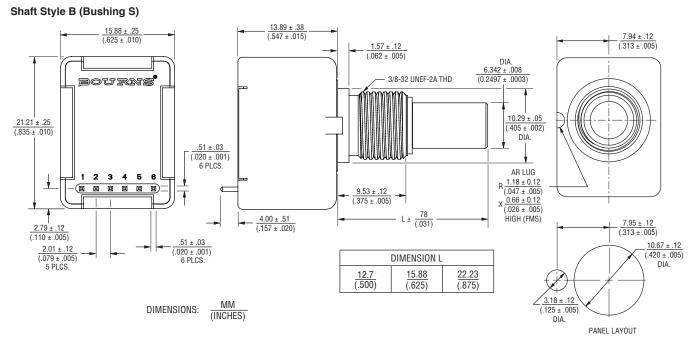
- Special performance characteristics
- PCB mounting bracket ٠

EMS22P - Non-Contacting PWM Encoder

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Product Dimensions





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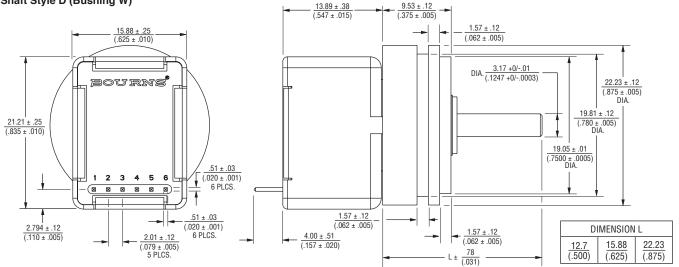
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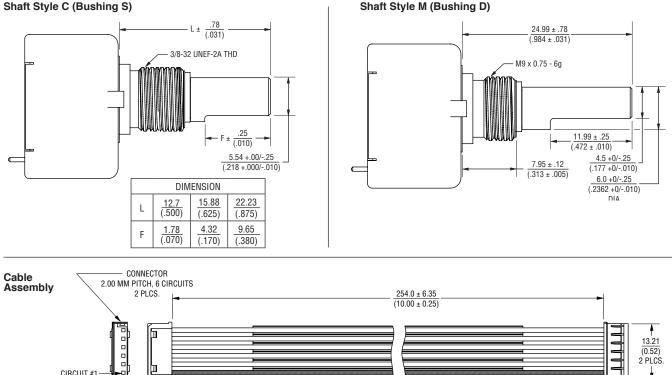
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Product Dimensions (Continued)

Shaft Style D (Bushing W)



Shaft Style C (Bushing S)



FLAT CABLE -2.0 MM PITCH ROUND CONDUCTOR 24 AWG (7X32) STRANDED, TOP COAT 6 CIRCUITS, P.V.C. INSULATION

18.0 (0.709) 2 PLCS.

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CIRCUIT #1

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PIN 1 IDENTIFICATION STRIPE $^{>}$

DIMENSIONS:

CIRCUIT #1

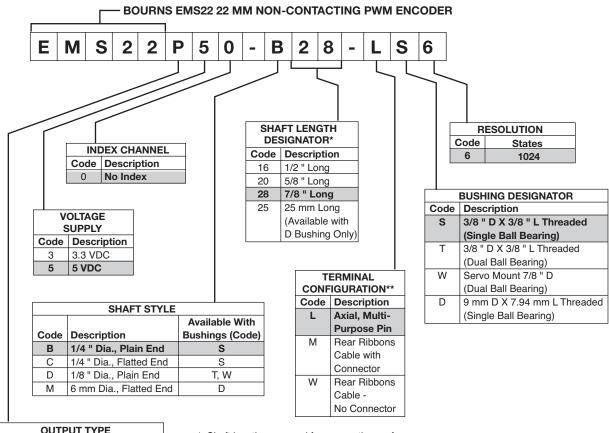
MM

(INCHES)

EMS22P - Non-Contacting PWM Encoder

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How To Order



OUTPUT TYPE					
Code	Description Notes				
Р	CW PWM	See Note 1			
R	CCW PWM	See Note 2			

* Shaft length measured from mounting surface.

** Standard ribbon cable is 10 inches long. Consult factory for other lengths. Note 1: (P) t on increases from 1 to 1025 with CW rotation of the shaft. Note 2: (R) t on increases from 1 to 1025 with CCW rotation of the shaft.

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