

Critical Conduction Mode PFC Control IC SSC2016S

Data Sheet

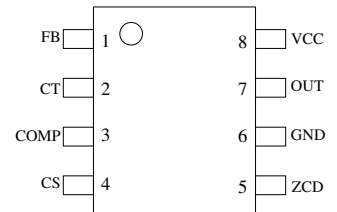
Description

SSC2016S is a Critical Conduction Mode (CRM) control IC for power factor correction (PFC).

Since no input voltage sensing is required, the IC allows the realization of low standby power and the low number of external components. The product achieves high cost-performance and high efficiency PFC converter system.

Package

SOIC8



Not to Scale

Features

- Low Standby Power
(No input voltage sensing required)
- Maximum Switching Frequency Limitation Function
- Minimum On-time Limitation Function
- Restart Function
- Protection Functions
 - Overcurrent Protection 1 (OCP1): Pulse-by-pulse
 - Overcurrent Protection 2 (OCP2): Latched shutdown
 - Overvoltage Protection (OVP): Auto-restart
 - FB Pin Undervoltage Protection (FB_UVP): Auto-restart
 - Thermal Shutdown Protection with hysteresis (TSD): Auto-restart

Electrical Characteristics

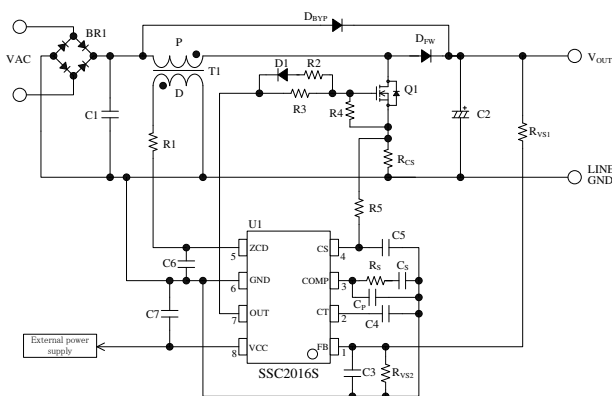
- VCC Pin Absolute Maximum Ratings, $V_{CC} = 28\text{ V}$
- OUT Pin Source Current, $I_{OUT(SRC)} = -500\text{ mA}$
- OUT Pin Sink Current, $I_{OUT(SNK)} = 1000\text{ mA}$

Application

PFC circuit up to 200 W of output power such as:

- AC/DC Power Supply
- Digital Appliances (large size LCD television and so forth).
- OA Equipment (Computer, Server, Monitor, and so forth).
- Communication Facilities
- Other Switching Mode Power Supply, SMPS

Typical Application



TC_SSC2016S_1_R2

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1. Absolute Maximum Ratings

Current polarities are defined as follows: a current flow going into the IC (sinking) is positive current (+); and a current flow coming out of the IC (sourcing) is negative current (-).

Unless specifically noted $T_A = 25\text{ }^\circ\text{C}$.

Parameter	Symbol	Conditions	Pins	Rating	Unit	Remarks
FB Pin Voltage	V_{FB}		1 – 6	- 0.3 to 5	V	
CT Pin Voltage	V_{CT}		2 – 6	- 0.3 to 5	V	
COMP Pin Voltage	V_{COMP}		3 – 6	- 0.3 to 5	V	
COMP Pin Current	I_{COMP}		3 – 6	- 100 to 100	μA	
CS Pin Voltage (DC)	$V_{CS(DC)}$		4 – 6	- 0.3 to 5	V	
CS Pin Voltage (Pulse)	$V_{CS(PULSE)}$	Pulse with $\tau = 1\mu\text{s}$	4 – 6	- 2 to 5	V	
ZCD Pin Voltage	V_{ZCD}		5 – 6	- 10 to 10	V	
ZCD Pin Current	I_{ZCD}		5 – 6	- 10 to 10	mA	
OUT Pin Voltage	V_{OUT}		7 – 6	- 0.3 to $V_{CC} + 0.3$	V	
OUT Pin Source Current	$I_{OUT(SRC)}$		7 – 6	- 500	mA	
OUT Pin Sink Current	$I_{OUT(SNK)}$		7 – 6	1000	mA	
VCC Pin Voltage	V_{CC}		8 – 6	28	V	
Allowable Power Dissipation	P_D		-	0.5	W	
Operating Ambient Temperature	T_{OP}		-	-40 to 110	$^\circ\text{C}$	
Storage Temperature	T_{stg}		-	-40 to 150	$^\circ\text{C}$	
Junction Temperature	T_j		-	150	$^\circ\text{C}$	

2. Electrical Characteristics

Current polarities are defined as follows: a current flow going into the IC (sinking) is positive current (+); and a current flow coming out of the IC (sourcing) is negative current (-).

Unless specifically noted, $T_A = 25\text{ }^\circ\text{C}$, $V_{CC} = 14\text{ V}$.

Parameter	Symbol	Conditions	Pins	Min.	Typ.	Max.	Unit
Power Supply Operation							
Operation Start Voltage	$V_{CC(ON)}$		8 – 6	7.5	8.5	9.5	V
Operation Stop Voltage	$V_{CC(OFF)}$		8 – 6	6.5	7.5	8.5	V
Operation Voltage Hysteresis	$V_{CC(HYS)}$		8 – 6	0.5	1.0	1.5	V
Circuit Current in Operation	$I_{CC(ON)}$		8 – 6	1.2	2.1	3.2	mA
Circuit Current in Non-Operation	$I_{CC(OFF)}$	$V_{CC} = 7\text{ V}$	8 – 6	–	50	100	μA
Frequency Control							
FB Pin Sink Current	I_{FB}		1 – 6	0.3	0.7	1.1	μA
Feedback Voltage Reference	V_{REF}		1 – 6	2.475	2.500	2.525	V
V_{REF} Line Regulation	$V_{REF(LR)}$	$V_{CC} = 11.5\text{ V}$ $\sim 28\text{ V}$	1 – 6	– 8.0	1.0	12.0	mV
COMP Pin Source Current 1	$I_{COMP(SRC)1}$	$V_{FB} = 2.4\text{ V}$	3 – 6	– 22	– 11	– 1	μA
COMP Pin Sink Current 1	$I_{COMP(SNK)1}$	$V_{FB} = 2.6\text{ V}$	3 – 6	1	11	22	μA
COMP Pin Sink Current 2	$I_{COMP(SNK)2}$	$V_{FB} = 2.7\text{ V}$	3 – 6	15	35	55	μA
Error Amplifier Transconductance Gain	gm		1 – 6 3 – 6	60	100	140	μS
Zero Duty COMP Voltage	$V_{COMP(ZD)}$		3 – 6	0.50	0.65	0.90	V
Restart Time	t_{RS}		7 – 6	140	220	300	μs
ON Time in Restart Operation	$t_{ON(RS)}$		7 – 6	0.5	1.7	2.9	μs
CT Pin Source Current	I_{CT}		2 – 6	– 165	– 150	– 135	μA
CT Pin Threshold Voltage	$V_{CT(OFF)}$	$V_{COMP} = 4.5\text{ V}$	2 – 6	2.60	2.75	2.90	V
CT Pin Delay Time of Control	$t_{DLY(PWM)}$	$V_{COMP} = 2.2\text{ V}$	2 – 6	–	120	220	ns
Maximum Switching Frequency ⁽¹⁾	f_{MAX}		7 – 6	–	300	400	kHz
Drive Output							
Output Voltage (High)	V_{OH}	$I_{OUT} = -100\text{ mA}$	7 – 6	10.0	12.0	13.5	V
Output Voltage (low)	V_{OL}	$I_{OUT} = 200\text{ mA}$	7 – 6	0.40	0.75	1.25	V
Output Rise Time ⁽²⁾	t_r	$C_{OUT} = 1000\text{ pF}$	7 – 6	–	60	120	ns
Output Fall Time ⁽²⁾	t_f	$C_{OUT} = 1000\text{ pF}$	7 – 6	–	20	70	ns
Zero Current Detection							

⁽¹⁾ Design assurance item

⁽²⁾ Shown in Figure 3-1

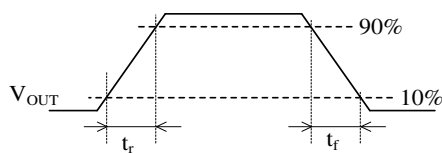


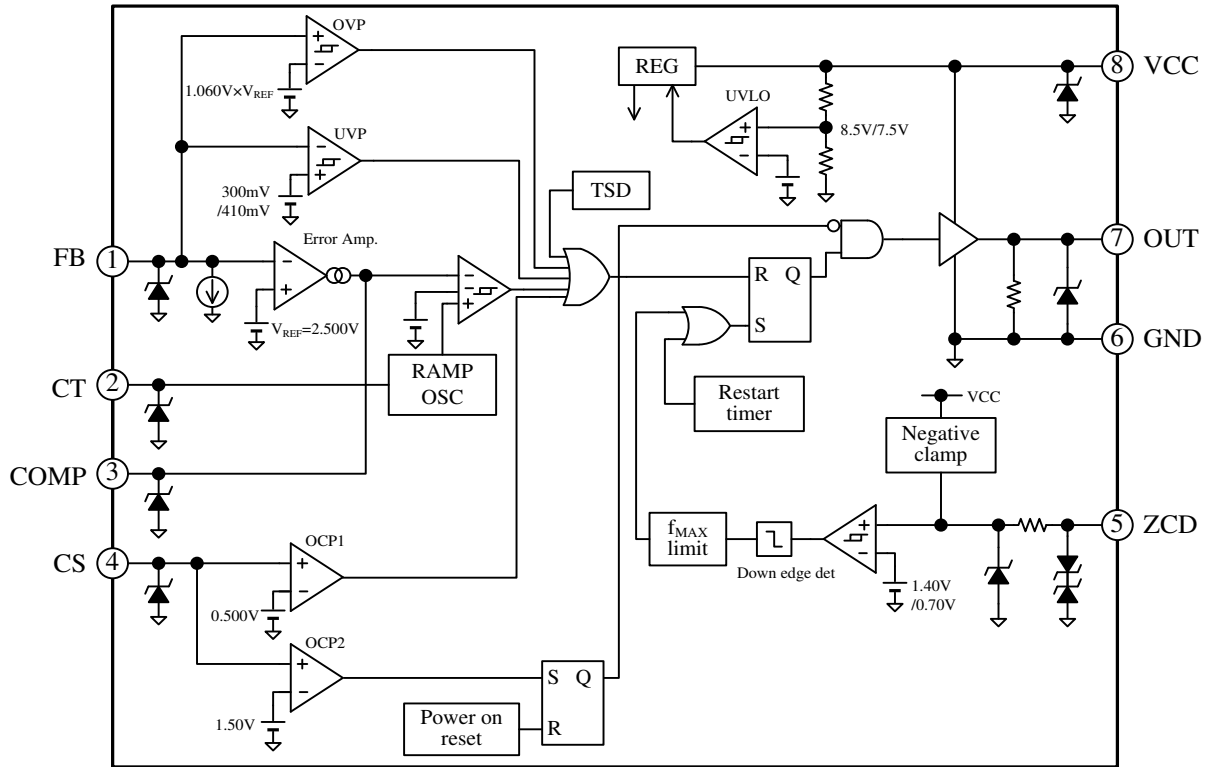
Figure 3-1 Switching time

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Parameter	Symbol	Conditions	Pins	Min.	Typ.	Max.	Unit
Zero Current Detection Threshold Voltage (High)	$V_{ZCD(H)}$		5 – 6	1.25	1.40	1.55	V
Zero Current Detection Threshold Voltage (Low)	$V_{ZCD(L)}$		5 – 6	0.60	0.70	0.80	V
Zero Current Detection Delay Time ⁽¹⁾	$t_{DLY(ZCD)}$		5 – 6	–	70	160	ns
ZCD Pin Clamp Voltage	$V_{ZCD(CL)}$	$I_{ZCD}=3mA$	5 – 6	6.5	7.7	9.0	V
Overcurrent Protection Function							
Overcurrent Protection Threshold Voltage 1	$V_{CS(OC1)}$		4 – 6	0.475	0.500	0.525	V
Overcurrent Protection Threshold Voltage 2	$V_{CS(OC2)}$		4 – 6	1.35	1.50	1.65	V
Overcurrent Protection Delay Time	$t_{DLY(OC)}$		4 – 6	90	215	340	ns
CS Pin Source Current	I_{CS}		4 – 6	– 40	– 20	– 10	μA
FB Pin Protection Function							
Overvoltage Protection Threshold Voltage	V_{OVP}		1 – 6	$1.040 \times V_{REF}$	$1.060 \times V_{REF}$	$1.080 \times V_{REF}$	V
Overvoltage Protection Hysteresis	$V_{OVP(HYS)}$		1 – 6	40	60	80	mV
Undervoltage Protection Threshold Voltage	V_{UVP}		1 – 6	200	300	400	mV
Undervoltage Protection Hysteresis	$V_{UVP(HYS)}$		1 – 6	70	110	150	mV
Thermal Shutdown Protection							
Thermal Shutdown Threshold ⁽¹⁾	$T_{j(TSD)}$		–	135	150	–	°C
Thermal Shutdown Hysteresis ⁽¹⁾	$T_{j(TSDHYS)}$		–	–	10	–	°C
Thermal Resistance							
Junction to Ambient Resistance ⁽¹⁾	θ_{j-A}		–	–	–	180	°C/W

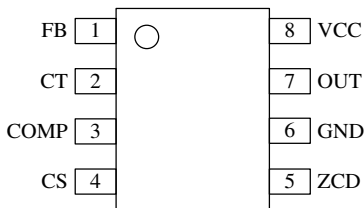
⁽¹⁾ Design assurance item

3. Block Diagram



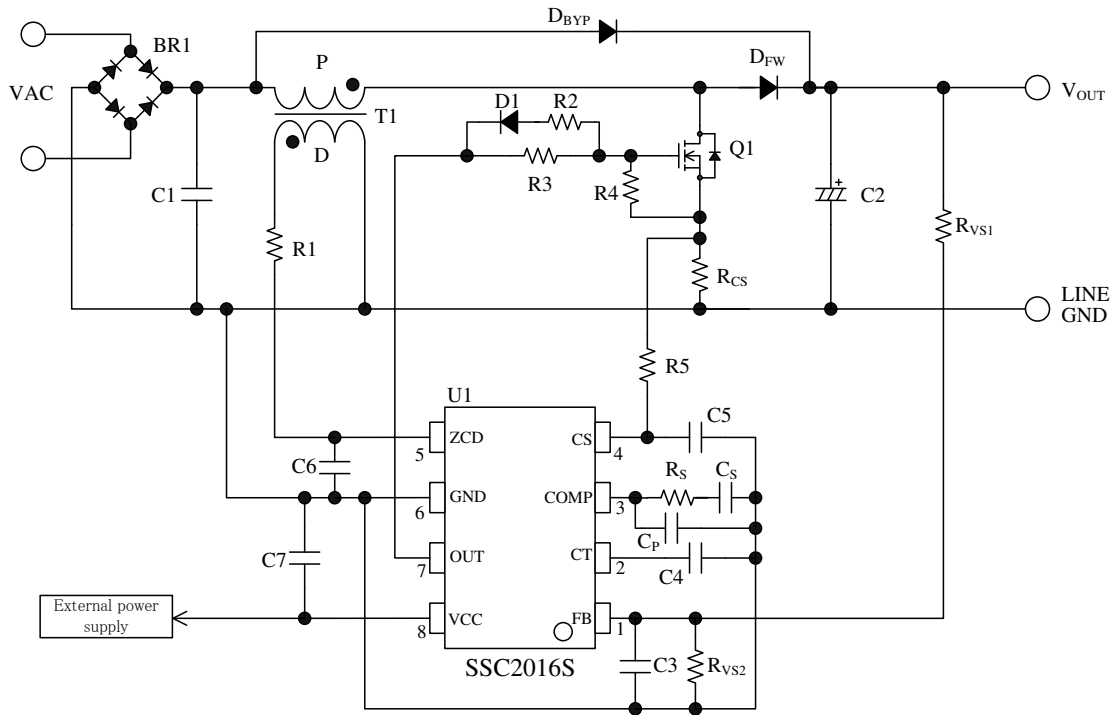
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4. Pin Configuration Definitions



Number	Name	Function
1	FB	Feedback signal input, Overvoltage Protection signal input and FB pin Undervoltage Protection signal input
2	CT	Timing capacitor connection
3	COMP	Phase compensation
4	CS	Overcurrent Protection signal input
5	ZCD	Zero current detection signal input and bottom-on-timing adjustment
6	GND	Ground
7	OUT	Gate drive output
8	VCC	Power supply input for control circuit

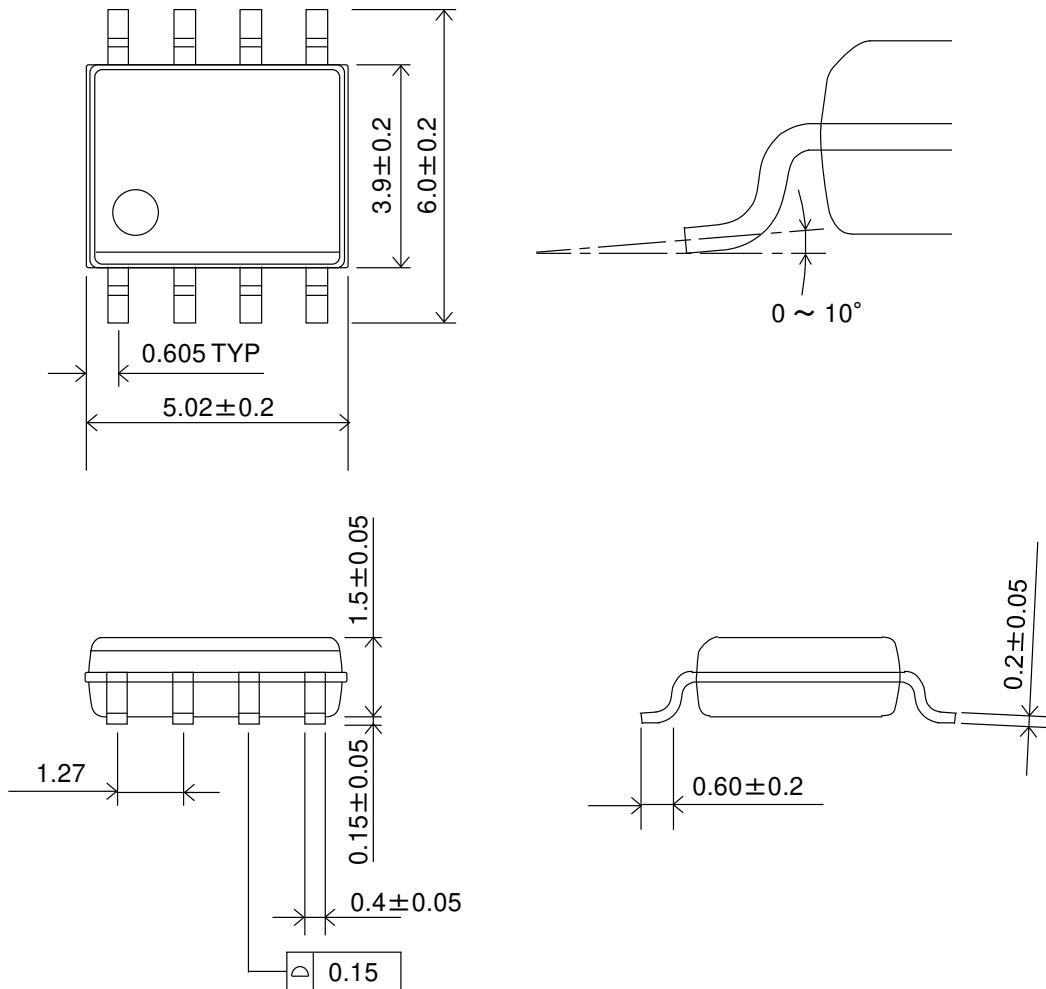
5. Typical Application



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6. External Dimensions

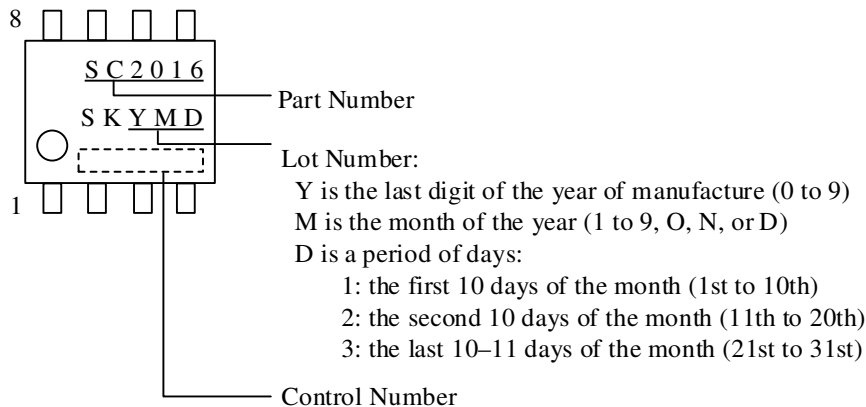
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NOTES:

- All linear dimensions are in millimeters
- Pb-free. Device composition compliant with the RoHS directive.

7. Marking Diagram



8. Operational Description

All of the parameter values used in these descriptions are typical values, unless they are specified as minimum or maximum.

Current polarities are defined as follows: a current flow going into the IC (sinking) is positive current (+); and a current flow coming out of the IC (sourcing) is negative current (-).

8.1 Critical Conduction Mode: CRM

Figure 8-1 and Figure 8-2 show the PFC circuit and CRM operation waveform. The IC performs the on/off operation of switching device Q1 in critical mode (the inductor current is zero). Thus, the low drain current variation di/dt of power MOSFET is accomplished. Also, adjusting the turn-on timing at the bottom point of V_{DS} free oscillation waveform (quasi-resonant operation), low noise and high efficiency PFC circuit is realized.

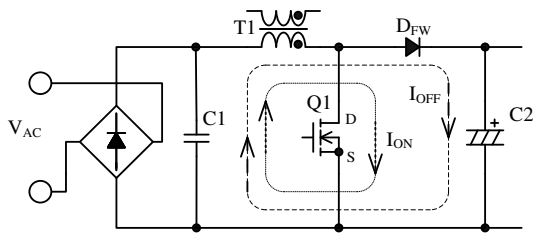


Figure 8-1. PFC Circuit

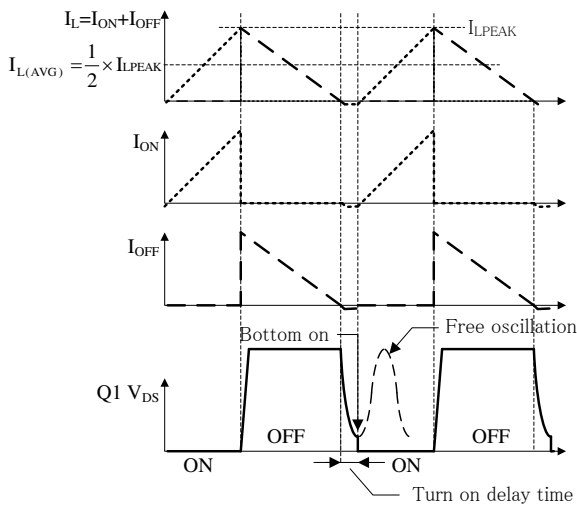


Figure 8-2. CRM Operation and Bottom On Operation

Figure 8-3 shows the internal CRM control circuit.

The power MOSFET Q1 starts switching operation by self-oscillation.

The on-time control is as follows: the detection

voltage R_{VS2} is compared with the Feedback Voltage Reference $V_{REF} = 2.500 \text{ V}$ by using error amplifier (Error AMP) connected to FB pin. The output of the Error AMP is averaged and the phase is compensated. This signal V_{COMP} is compared with the ramp signal V_{OSC} to achieve the on-time control. The on-time becomes almost constant in commercial cycle by setting V_{COMP} to respond below 20 Hz (Figure 8-4). This is achieved by tuning the capacitor connected to COMP pin.

The off-time is set by detecting the zero current signal of boost winding P. The zero current is detected by auxiliary winding D and ZCD pin.

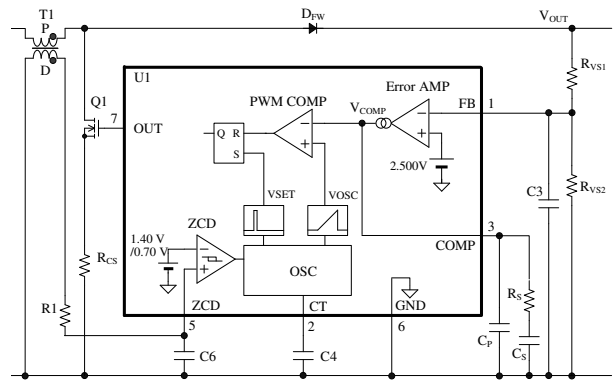


Figure 8-3. CRM Control Circuit

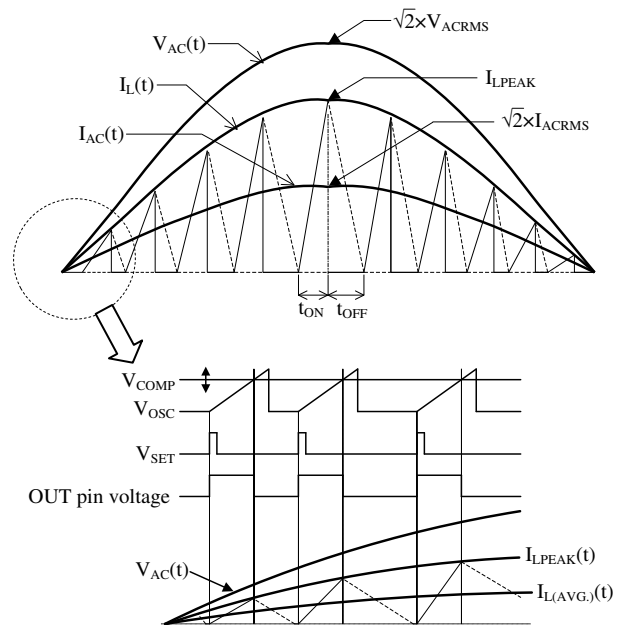


Figure 8-4 CRM Operation Waveforms

The off duty D_{OFF} of boost converter in CRM mode have the relation of $D_{OFF}(t) = V_{AC}(t)/V_{OUT}$ and is proportional to input voltage, where $V_{AC}(t)$ is the input

voltage of AC line as a function of time.

As a result of aforementioned control shown in Figure 8-4, the peak current I_{LPEAK} of the inductance current I_L becomes sinusoidal. Since the averaged input current become similar to AC input voltage waveform by Low Pass Filter at input stage, high power factor is achieved.

8.2 Startup Operation

Figure 8-5 and Figure 8-7 show the VCC pin peripheral circuit. Figure 8-5 shows how to use an external power supply. Figure 8-7 shows how to use an auxiliary winding.

8.2.1 To Use an External Power Supply

When an external power supply shown in Figure 8-5 is used, the startup operation is as follows.

As shown in Figure 8-6, when VCC pin voltage rises to the Operation Start Voltage $V_{CC(ON)} = 8.5\text{ V}$, the control circuit starts operation and the COMP pin voltage increases. The COMP pin voltage increases to the Zero Duty COMP Voltage $V_{COMP(ZD)} = 0.65\text{ V}$, switching operation starts.

When the VCC pin voltage decreases to $V_{CC(OFF)} = 7.5\text{ V}$, the control circuit stops operation by Undervoltage Lockout (UVLO) circuit, and reverts to the state before startup.

Since the COMP pin voltage rises from zero during startup period, the V_{COMP} signal shown in Figure 8-3 gradually rises from low voltage. The on-width gradually increased to restrict the rise of output power by the Softstart Function. Thus, the stress of the peripheral component is reduced.

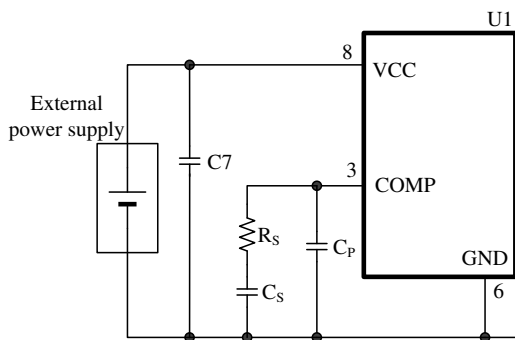


Figure 8-5. VCC Pin Peripheral Circuit (Power supply from external power supply)

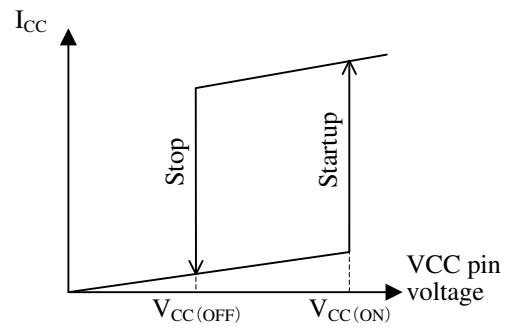


Figure 8-6. Relationship between VCC Pin Voltage and I_{CC}

8.2.2 To Use an Auxiliary Winding

When an auxiliary winding is used as shown in Figure 8-7, C_{VCC} is charged through R_{ST} at startup. When VCC pin voltage rises to $V_{CC(ON)} = 8.5\text{ V}$, the control circuit starts operation.

Figure 8-8 shows the VCC pin voltage behavior during startup period.

When the VCC pin voltage reaches $V_{CC(ON)}$, the control circuit starts operation. Then the circuit current increases and the VCC pin voltage decreases. At the same time, the auxiliary winding voltage V_D increases in proportion to the output voltage. These are all balanced to produce VCC pin voltage.

The value of C_{VCC} , the turns ratio of boost winding P and auxiliary winding D should be set so that VCC pin voltage is maintained higher than $V_{CC(OFF)}$ (See Section 9.1.2).

If the values of R_{ST} and C_{VCC} are large, the startup time becomes longer. Adjustment is necessary in actual operation.

When the COMP pin voltage increases to the Zero Duty COMP Voltage $V_{COMP(ZD)} = 0.65\text{ V}$ after the control circuit starts operation, switching operation starts and the circuit current is supplied from auxiliary winding D as follows.

V_B and V_D are the voltage of auxiliary winding during Q1 on and off, respectively.

When Q1 is on, C_{CP} is charged by V_B . When Q1 is off, the capacitor connected to VCC pin, C_{VCC} , is charged by $V_D + V_B (=V_{CCP})$.

V_B is calculated using Equation (1).

$$V_B = V_{IN} \times \frac{N_D}{N_P} \quad (1)$$

Where

V_{IN} : C1 voltage (V)

N_P : Number of turns of boost winding P (turns)

N_D : Number of turns of auxiliary winding D (turns)

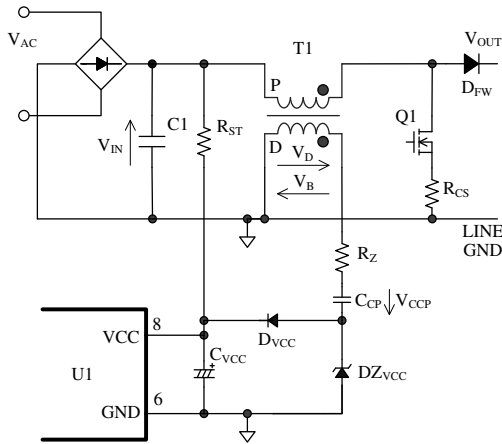


Figure 8-7. VCC Pin Peripheral Circuit (Power supply from auxiliary winding)

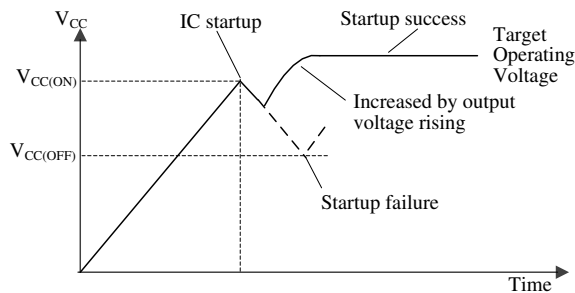


Figure 8-8. VCC During Startup Period

8.3 Restart Circuit

The IC is self-oscillation type. The off-time of OUT pin is set by the detecting zero current signal at ZCD pin.

When the off-time of OUT pin is maintained for $t_{RS} = 220 \mu s$ or more, the restart circuit is activated and OUT pin turns on. The ON time of the OUT pin is $t_{ON(RS)} = 1.7 \mu s$ in the restart operation.

At intermittent oscillation period in startup and light load, the restart circuit is activated and the switching operation is stabilized.

Since $t_{RS} = 220 \mu s$ corresponds to the operational frequency of 6.25 kHz, the minimum frequency should be set to higher than 20 kHz (above audible frequency) at the inductance value design.

8.4 Maximum On-time Setting

In order to reduce audible noise of transformer at transient state, the Maximum on-time, $t_{ON(MAX)}$, should be set. The $t_{ON(MAX)}$ depends on the value of C4 connected to CT pin. Section 9.1 shows about $t_{ON(MAX)}$ setting.

8.5 Zero Current Detection and Bottom-on Timing Setting

Figure 8-9 shows the peripheral circuit of ZCD pin, Figure 8-10 shows the zero current detection waveform.

The off-time is determined by detecting the zero current of the boost winding P via the auxiliary winding D and ZCD pin

The polarity of winding P and winding D of transformer T1 are shown in Figure 8-9.

When the OUT pin voltage becomes low and the power MOSFET turns off, the ZCD pin voltage becomes the voltage of auxiliary winding D as shown in Figure 8-10. After the turning off of the power MOSFET, when ZCD pin voltage is above $V_{ZCD(H)} = 1.40 V$, OUT pin voltage is kept to be Low. When ZCD pin voltage becomes below $V_{ZCD(L)} = 0.70 V$, OUT pin voltage becomes High and power MOSFET turns on.

After the turning off of the power MOSFET, when the current in boost winding become zero, V_{DS} waveform starts free oscillation based on the inductance L_P , the output capacitance of power MOSFET C_{OSS} and the parasitic capacitance. The bottom point of V_{DS} is calculated as follows:

$$t_{HFP} \approx \pi \sqrt{L_P \times C_V} \quad (2)$$

where

t_{HFP} : Half cycle of free oscillation (s)

L_P : Inductance of boost winding (H)

C_V : Combined output capacitance of power MOSFET C_{OSS} and parasitic capacitance (F)

In order to set the timing of turn on to the bottom point of V_{DS} as shown in Figure 8-11, adjust the turn on delay time t_{HFP} by using C6 and R1 in actual operation condition as shown in Figure 8-9. Since R1 have a role as the current limiting resistor of ZCD pin, adjust the C6 value if R1 value exceeds the range of limiting.

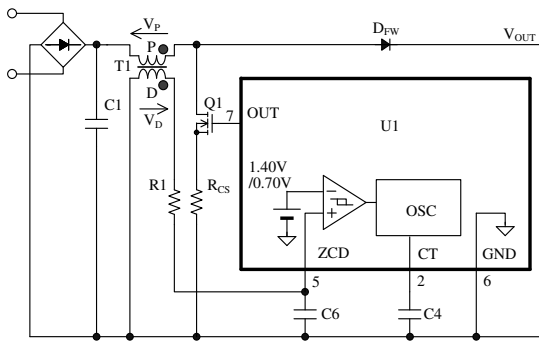


Figure 8-9. ZCD Pin Peripheral Circuit

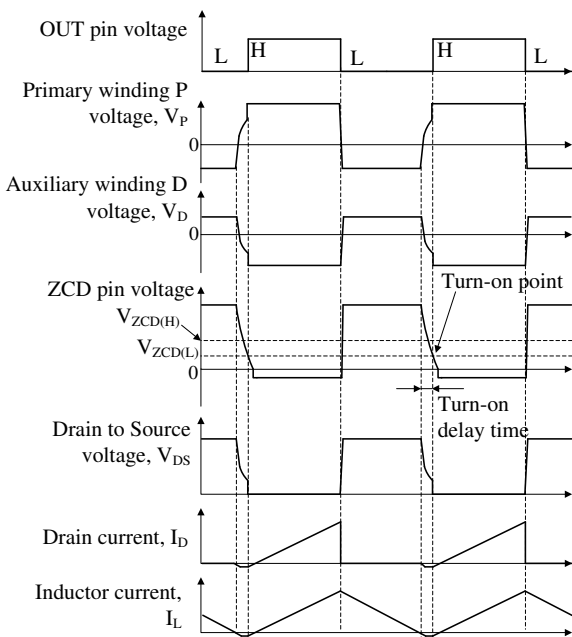


Figure 8-10. Zero Current Detection Waveform

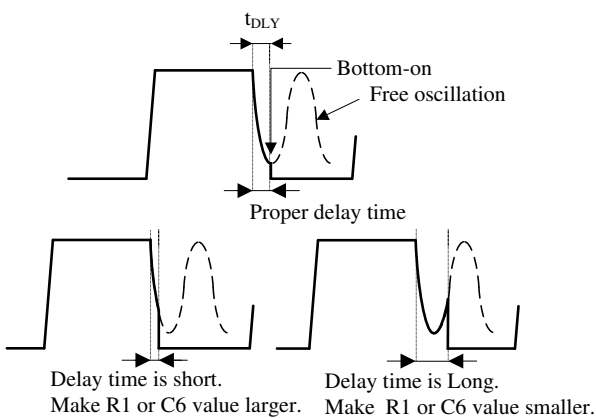


Figure 8-11. V_{DS} Turn On Timing

8.6 Maximum Switching Frequency Limitation Function

In the CRM operation, the switching frequency of a power MOSFET is varied in a period of sinusoidal AC input voltage. The switching frequency is lowest in the peak of AC input voltage and is high as getting close to the bottom of it. In addition, when output load decreases, the switching frequency increases entirely. In order to reduce the switching loss, the IC has the Maximum Switching Frequency Limitation Function that limits the switching frequency to f_{MAX} of 300 kHz.

8.7 Overcurrent Protection (OCP)

Figure 8-12 shows the CS pin peripheral circuit and internal circuit. The inductor current, I_L is detected by the detection resistor, R_{CS} . The detection voltage, V_{RCS} , is fed into CS pin. As shown in Figure 8-12, the CS pin is connected to capacitor-resistor filter ($R5$ and $C5$).

The IC has two Overcurrent Protection (OCP) threshold voltages.

- **OCP1**

When V_{RCS} increases $V_{CS(OCP1)} = 0.500$ V or more, the output of the OUT pin becomes Low by pulse-by-pulse.

- **OCP2**

OCP2 is activated by malfunctions such as the short of a boost diode, D_{FW} . If the instantaneous large current flows to a power MOSFET and the CS pin voltage increases to $V_{CS(OSP2)} = 1.50$ V or more and this operation continues seven times, the output of OUT pin is latched to low level.

Releasing the latched state is done by turning off the input voltage and by dropping VCC pin voltage below $V_{CC(OFF)}$.

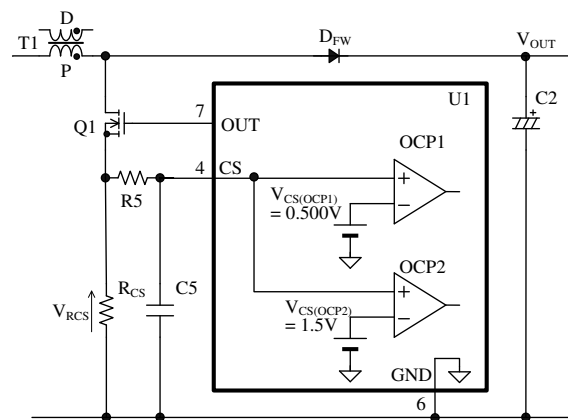


Figure 8-12. The CS Pin Peripheral Circuit and Internal Circuit.

8.8 Overvoltage Protection (OVP)

Figure 8-13 shows the waveforms of Overvoltage Protection (OVP) operation. When the FB pin voltage increase to Overvoltage Protection Threshold Voltage, V_{OVP} , OUT pin voltage become Low immediately and the switching operation stops. As a result, the rise of output voltage is prevented. V_{OVP} is 1.060 times the Feedback Voltage Reference, $V_{REF} = 2.500\text{ V}$. When the cause of the overvoltage is removed and FB pin voltage decreases to $V_{OVP} - V_{OVP(HYS)}$ the switching operation restarts.

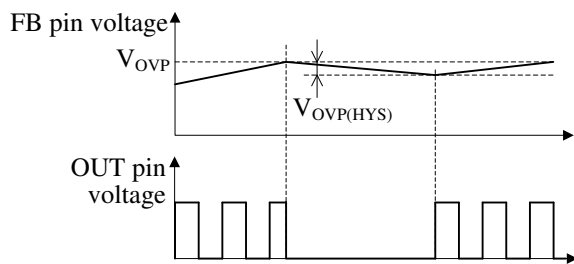


Figure 8-13. OVP Waveforms

8.9 FB Pin Under Voltage Protection (FB_UVP)

FB pin Under Voltage Protection (FB_UVP) is activated when the FB pin voltage is decreased by the malfunctions in feedback loop such as the open of R_{VS1} , the short of R_{VS2} , or the open of FB pin.

Figure 8-14 shows the FB pin peripheral circuit and internal circuit. When the FB pin voltage is decreased to $V_{UVP} = 300\text{ mV}$ or less, the OUT pin output is turned-off immediately and switching operation stops. This prevents the rise of output voltage. When the cause of malfunction is removed and the FB pin voltage rises to $V_{UVP} + V_{UVP(HYS)}$, the switching operation restarts.

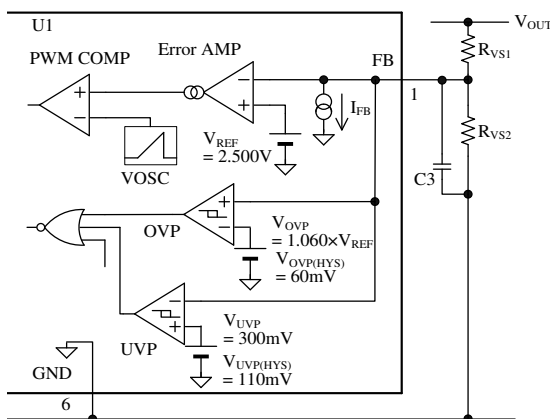


Figure 8-14. The FB Pin Peripheral Circuit and Internal Circuit.

8.10 Thermal Shutdown (TSD)

< Using External Power Supply >

When the temperature of control circuit increases to $T_{j(TSD)} = 150\text{ }^\circ\text{C}$ or more, Thermal Shutdown (TSD) is activated and the IC stops switching operation.

When the fault condition is removed and the temperature decreases to less than $T_{j(TSD)} - T_{j(TSDHYS)}$, the IC returns to normal operation automatically.

< Using Auxiliary Winding D for VCC supply >

When TSD is activated and the IC stops switching operation, VCC pin voltage decreases to $V_{CC(OFF)}$ and the control circuit stops operation. After that, the IC reverts to the initial state by UVLO circuit, and the IC starts operation when VCC pin voltage increases to $V_{CC(ON)}$ by startup current. Thus the intermittent operation by UVLO is repeated in TSD state.

When the fault condition is removed and the temperature decreases to less than $T_{j(TSD)} - T_{j(TSDHYS)}$, the IC returns to normal operation automatically.

9. Design Notes

9.1 Inductor Design

Inductor T1 consists of a boost winding P and auxiliary winding D. The winding P is used for boosting the voltage and winding D is used for off-timing detection.

The calculation methods of winding P and winding D are as shown below. Since the following calculating formulas are approximated, the peak current and the frequency of operational waveforms may be different from the setting value at calculating. Eventually, the inductance value should be adjusted in actual operation.

Apply proper design margin to temperature rise by core loss and copper loss.

9.1.1 Boost winding, P

Inductance L_P of PFC in CRM mode is calculated as follows:

1) Output Voltage, V_{OUT}

The output voltage V_{OUT} of boost-converter should be set higher than peak value of input voltage as following equation:

$$V_{OUT} \geq \sqrt{2} \times V_{ACRMS(MAX)} \times V_{DIF} \quad (3)$$

where

$V_{ACRMS(MAX)}$: Maximum AC input voltage rms value (V)

V_{DIF} : Boost voltage (about 10V) (V)

2) Operational Frequency, $f_{SW(SET)}$

Determine $f_{SW(SET)}$ that is minimum operational frequency at the peak of the AC line waveform. The frequency becomes higher with lowering the input voltage. The frequency at the peak of the AC line waveform, $f_{SW(SET)}$ should be set more than the audible frequency (20 kHz).

3) Inductance, L_P

Substituting both minimum and maximum of AC input voltage to V_{ACRMS} , choose a smaller one as L_P value. L_P is calculated as follows:

$$L_P = \frac{\eta \times V_{ACRMS}^2 \times (V_{OUT} - \sqrt{2} \times V_{ACRMS})}{2 \times P_{OUT} \times f_{SW(SET)} \times V_{OUT}} \quad (H) \quad (4)$$

where

V_{ACRMS} : Maximum or minimum AC input voltage rms value (V)

P_{OUT} : Output Power (W)

$f_{SW(SET)}$: Minimum operational frequency at the peak of the AC line waveform (kHz)

(The operational frequency becomes lowest at the peak of the AC line waveform. $f_{SW(SET)}$ should be set above frequency of 20 kHz.)

η : Efficiency of PFC

(In general, the range of η is 0.90 to 0.97, depending on on-resistance of power MOSFET $R_{DS(ON)}$ and forward voltage drop of rectifier diode V_F .)

4) Inductor peak current, I_{LP}

I_{LP} is peak current at the minimum of AC input voltage waveform. I_{LP} calculated as follows:

$$I_{LP} = \frac{2\sqrt{2} \times P_{OUT}}{\eta \times V_{ACRMS(MIN)}} \quad (A) \quad (5)$$

where,

P_{OUT} : Output power (W)

$V_{ACRMS(MIN)}$: Minimum AC input voltage rms value (V)

η : Efficiency of PFC (About 0.90 to 0.97)

5) Maximum On-time, $t_{ON(SET)MAX}$

$t_{ON(MAX)_OP}$ is calculated by Equation (6) with results of Equation (4) and Equation (5). $t_{ON(MAX)_OP}$ is the maximum on time of the peak voltage of the minimum AC input voltage.

$$t_{ON(MAX)_OP} = \frac{L_P \times I_P}{\sqrt{2} \times V_{ACRMS(MIN)}} \quad (s) \quad (6)$$

where,

L_P : Inductance value of the result of Equation (4)

$V_{ACRMS(MIN)}$: Minimum AC input voltage rms value (V)

Equation (7) shows the relationship between maximum on time, $t_{ON(MAX)}$, and CT pin capacitor, C4

(see Section 8.4). C4 should be set so as $t_{ON(MAX)}$ is larger than $t_{ON(MAX)_OP}$ that is calculated by Equation (6). The value of C4 is about 330 pF to 1500 pF

$$t_{ON(MAX)} = \frac{C4 \times V_{CT(OFF)}}{|I_{CT}|} \quad (s) \quad (7)$$

where

C4: Capacitance of capacitor connected to CT pin (μF)

$V_{CT(OFF)}$: CT Pin Threshold Voltage (V)

I_{CT} : CT Pin Source Current (μA)

9.1.2 Auxiliary Winding, D

Figure 9-1 shows the polarity of boost winding P and auxiliary winding D.

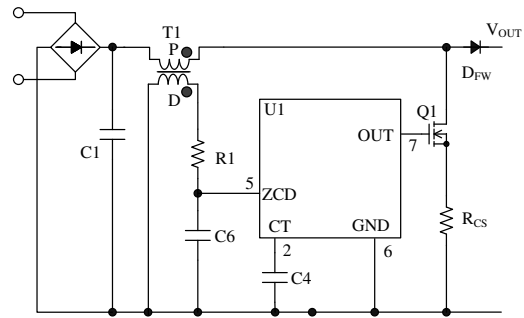


Figure 9-1. ZCD Peripheral Circuit

Given the number of windings of each winding as N_P and N_D , the turn ratio N_D/N_P is set satisfying following conditions.

The condition of N_D/N_P making ZCD pin voltage above $V_{ZCD(H)} = 1.40 V$ after power MOSFET turns off is expressed as follows:

$$\frac{N_D}{N_P} > \frac{V_{ZCD(H)}}{V_{OUT} - \sqrt{2} \times V_{ACRMS(MAX)}} \quad (8)$$

where

N_P : The number of turns of boost winding P (turns)

N_D : The number of turns of auxiliary winding D (turns)

V_{OUT} : Output voltage (V)

$V_{ACRMS(MAX)}$: Maximum AC input voltage rms value (turns)

When power supply of VCC pin is supplied from auxiliary winding as shown in Figure 9-2, the condition of N_D/N_P is set to larger rate of Equation (8) or Equation (9).

The maximum VCC pin input voltage is limited by the zener voltage of DZ_{VCC} . The minimum VCC pin input voltage must be set higher than the maximum

R_{CS} is calculated using the following Equation (11), where Overcurrent Protection Threshold Voltage $V_{CS(OC)}$ is 0.500 V and I_{LP} is calculated using Equation (5).

$$R_{CS} \leq \frac{|V_{CS(OC)}|}{I_{LP}} (\Omega) \quad (11)$$

The loss P_{RCS} at R_{CS} is calculated by Equation (13) using Equation (12).

$$I_{DRMS} = \frac{2\sqrt{2} \times P_{OUT}}{\eta \times V_{ACRMS(MIN)}} \times \sqrt{\frac{1}{6} - \frac{4\sqrt{2} \times V_{ACRMS(MIN)}}{9 \times \pi \times V_{OUT}}} (A) \quad (12)$$

$$P_{RCS} = I_{DRMS}^2 \times R_{CS} (W) \quad (13)$$

Where

I_{DRMS} : RMS Drain current (A)
 $V_{ACRMS(MIN)}$: Minimum AC input voltage rms value (V)
 V_{OUT} : Output voltage (V)
 P_{OUT} : Output power (W)
 η : Efficiency of PFC

The CR filter (R5 and C5) is connected to CS pin.

CR filter (R5 and C5) prevents IC from responding to the drain current surge at MOSFET turn-on and avoids the unstable operation of the IC.

R5 value of approximately 47 Ω is recommended, since the CS Pin Source Current affects the accuracy of OCP detection.

C5 value is recommended to be calculated by using following formula in which cut-off frequency of CR filter (C5 and R5) is approximately 0.5 MHz to 3.0MHz.

$$C5 = \frac{1}{2\pi \times 1 \times 10^6 \times R5} (F) \quad (14)$$

If R5 value is 47 Ω , C5 value is approximately 1000 pF to 6800 pF. C5 value should adjust based on actual operation in application.

9.2.5 ZCD Pin Peripheral Circuit, R1 and C6

R1 is for the limiting of the input and output current to ZCD pin. The value of resistor R1 is determined so that the ZCD pin current is smaller than the absolute maximum rating. The recommended value of ZCD pin current is less than 3 mA.

The R1 value is chosen to satisfy both Equation (15) and Equation (16). In addition, the bottom-on timing is set by C6 and R1 (See Section 8.5).

1) Limiting of ZCD pin source current (at Q1 ON state)

$$R1 > \frac{\sqrt{2} \times V_{ACRMS(MAX)} \times \frac{N_D}{N_P}}{3 \times 10^{-3}(A)} (\Omega) \quad (15)$$

Where

$V_{ACRMS(MAX)}$: Maximum AC input voltage rms value (V)

N_P : The number of turns of boost winding P (turns)

N_D : The number of turns of auxiliary winding D (turns)

2) Limiting of ZCD pin sink current (at Q1 OFF state)

$$R1 > \frac{V_{OUT} \times \frac{N_D}{N_P}}{3 \times 10^{-3}(A)} (\Omega) \quad (16)$$

Where

V_{OUT} : Output voltage (V)

N_P : The number of turns of boost winding P (turns)

N_D : The number of turns of auxiliary winding D (turns)

9.2.6 OUT Pin Peripheral Circuit (Gate Drive Circuit)

The OUT pin is the gate drive output that can drive the external power MOSFET directly.

The maximum output voltage of OUT pin is the VCC pin voltage. The maximum current is -500 mA for source and 1000 mA for sink, respectively.

R3 is for source current limiting. Both R2 and D1 are for sink current limiting. The values of these components are adjusted to decrease the ringing of Gate pin voltage and the EMI noise. The reference value is several ohms to several dozen ohms.

R4 is used to prevent malfunctions due to steep dv/dt at turn-off of the power MOSFET, and the resistor is connected near the MOSFET, between the gate and source. The reference value of R4 is from 10 k Ω to 100 k Ω . R2, R3, D1 and R4 are affected by the printed circuit board trace layout and the power MOSFET capacitance. Thus, the optimal values should be adjusted under actual operation of the application.

9.2.7 VCC Pin Peripheral Circuit

< Using External Power Supply >

Figure 9-4 shows the VCC pin peripheral circuit. The value of capacitor C7 is set approximately 1000 pF, in order to reduce the switching noise.

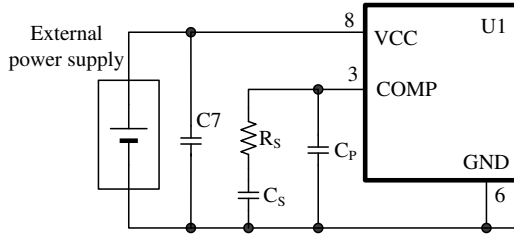


Figure 9-4. VCC Pin Peripheral Circuit (Power supply from external power supply)

< Using Auxiliary Winding D for VCC supply >

Figure 9-5 shows the VCC pin peripheral circuit when VCC pin is supplied from auxiliary winding.

- **R_{ST}**

The value of startup resistor, R_{ST} is selected so that the current more than I_{CC(OFF)} = 100 μA (max.) can be supplied to VCC pin at startup. R_{ST} is expressed as follows:

$$R_{ST} < \frac{\sqrt{2} \times V_{ACRMS(MIN)} - V_{CC(ON)max.}}{I_{CC(OFF)max.}} (\Omega) \quad (17)$$

Where, V_{ACRMS(MIN)} is Minimum AC input voltage rms value (V)

When the specification of AC input voltage is 100 V or Universal, the value of R_{ST} is approximately 100 kΩ to 220 kΩ. When the specification of AC input voltage is 230 V, the value of R_{ST} is approximately 180 kΩ to 330 kΩ.

The rating of R_{ST} is chosen taking into account the loss of R_{ST} at maximum input voltage. Since the high voltage is applied to resistor, choose a resistor designed against electromigration or use a series combination of resistors.

- **C_{VCC}**

The approximate startup time is determined by the value of C_{VCC}. It is calculated as follows where the initial voltage of VCC pin is zero.

$$t_{START} \approx \frac{C7 \times V_{CC(ON)}}{\frac{\sqrt{2} \times V_{ACRMS} - V_{CC(ON)}}{R_{ST}} - I_{CC(OFF)}} (s) \quad (18)$$

In general, power supply applications, C_{VCC}, is approximately 22 μF to 47 μF.

- **R_Z, C_{CP} and DZ_{VCC}**

The circuit consists of R_Z, C_{CP} and R_Z is the boost circuit of VCC pin.

R_Z is the limiting resistor for the breakdown current of DZ_{VCC}. The R_Z value is approximately 150 Ω.

C_{CP} is charged when Q1 is in ON state. The C_{CP} value is approximately 22 nF.

Since the absolute maximum rating value of VCC pin is 28 V, the zener voltage of DZ_{VCC} is chosen to be less than it.

- **C7**

If CVCC and the VCC pin are distant from each other, a capacitor C7 should be placed as close as possible to the VCC pin. C7 is approximately 1000 pF, in order to reduce the switching noise.

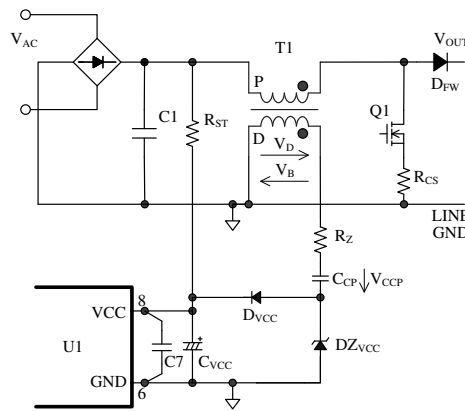


Figure 9-5. VCC Pin Peripheral Circuit (Power supply from auxiliary winding)

9.2.8 Power MOSFET, Q1

Choose a power MOSFET having proper margin of V_{DSS} against output voltage, V_{OUT}. The size of heat sink is chosen taking into account some loss by switching and ON resistance of MOSFET.

The loss P_{RDS(ON)} by on-resistance, R_{DS(ON)} of power MOSFET is calculated using I_{DRMS} of the result of Equation (12) as follows:

$$P_{RDS(ON)} = I_{DRMS}^2 \times R_{DS(ON)125^\circ C} (W) \quad (19)$$

Where

R_{DS(ON)125°C}: ON resistance of MOSFET at T_{ch} = 125 °C (Ω)

9.2.9 Boost Diode, D_{FW}

Choose a boost diode having proper margin of a peak reverse voltage V_{RSM} against output voltage V_{OUT} .

A fast recovery diode is recommended to reduce the switching noise and loss. Please ask our staff about our lineup. The size of heat sink is chosen taking into account some loss by V_F and recovery current of boost diode.

The loss of V_F , P_{DFW} is expressed as follows:

$$P_{DFW} = V_F \times I_{OUT} \quad (W) \quad (20)$$

Where

V_F : Forward voltage of boost diode (V)

I_{OUT} : Out put current (A)

9.2.10 Bypass Diode, D_{BYP}

Bypass diode protects the boost diode from a large current such as an inrush current. A high surge current tolerance diode is recommended. Please ask our staff about our lineup.

9.2.11 Output Capacitor, C_2

Apply proper design margin to accommodate the ripple current, the ripple voltage and the temperature rise. Use of high ripple current and low impedance types, designed for switch-mode power supplies, is recommended, depending on their purposes.

In order to obtain C_2 value C_O , calculate both Equation (21) and (23) described in following and select a larger value.

1) Ripple voltage considered

$$C_2 = \frac{I_{OUT}}{2\pi \times f_{LINE} \times V_{OUT(RI)}} \quad (F) \quad (21)$$

Where

$V_{OUT(RIPPLE)}$: C_2 ripple voltage (10 V_{PP} for example)

f_{LINE} : Line frequency (Hz)

I_{OUT} : Output current (A)

The C_2 voltage is expressed Equation (22).

When the output ripple is high, the V_{C_2} voltage may reach to Overvoltage Protection voltage, V_{OVP} in near the maximum value of V_{C_2} , or input current waveform may be distorted due to the stop of the boost operation in near the minimum value of V_{C_2} . It is necessary to select large C_O value or change the setting of output voltage (boost voltage).

$$V_{C_2} = V_{OUT} \pm \frac{V_{OUT(RI)}}{2} \quad (V) \quad (22)$$

2) Output hold time considered

$$C_2 > \frac{2 \times P_{OUT} \times t_{HOLD}}{V_{OUT}^2 - V_{OUT(MIN)}^2} \quad (F) \quad (23)$$

Where

t_{HOLD} : Output hold time (s)

$V_{OUT(MIN)}$: Minmum output voltage of C_2 during output hold (V)

If $t_{HOLD} = 20$ ms, $P_O = 200$ W, $\eta = 90$ % and the output voltage = 330 V to 390 V, C_2 value is derived as 205 μ F. Thus, C_2 value of approximately 220 μ F is connected.

9.3 PCB Trace Layout and Component Placement

Since the PCB traces design and the component layout significantly affects operation, EMI noise, and power dissipation, the high frequency PCB trace should be low impedance with small loop and wide trace.

In addition, the ground traces affect radiated EMI noise, and wide, short traces should be taken into account.

Figure 9-6 shows the circuit design example.

1) Main Circuit Trace

This is the main trace containing switching currents, and thus it should be as wide trace and small loop as possible.

2) Control Ground Trace Layout

Since the operation of IC may be affected from the large current of the main trace that flows in control ground trace, the control ground trace should be separated from main trace and connected at a single point grounding of point A in Figure 9-6 as close to the R_{CS} pin as possible.

3) R_{CS} Trace Layout

R_{CS} should be placed as close as possible to the Source pin and the CS pin. The peripheral components of CS pin should be connected by dedicated pattern from root of R_{CS} .

The connection between the power ground of the main trace and the IC ground should be at a single point ground which is close to the base of R_{CS} .

4) Peripheral Component of IC

The components for control connected to the IC should be placed as close as possible to the IC, and should be connected as short as possible to the each pin.

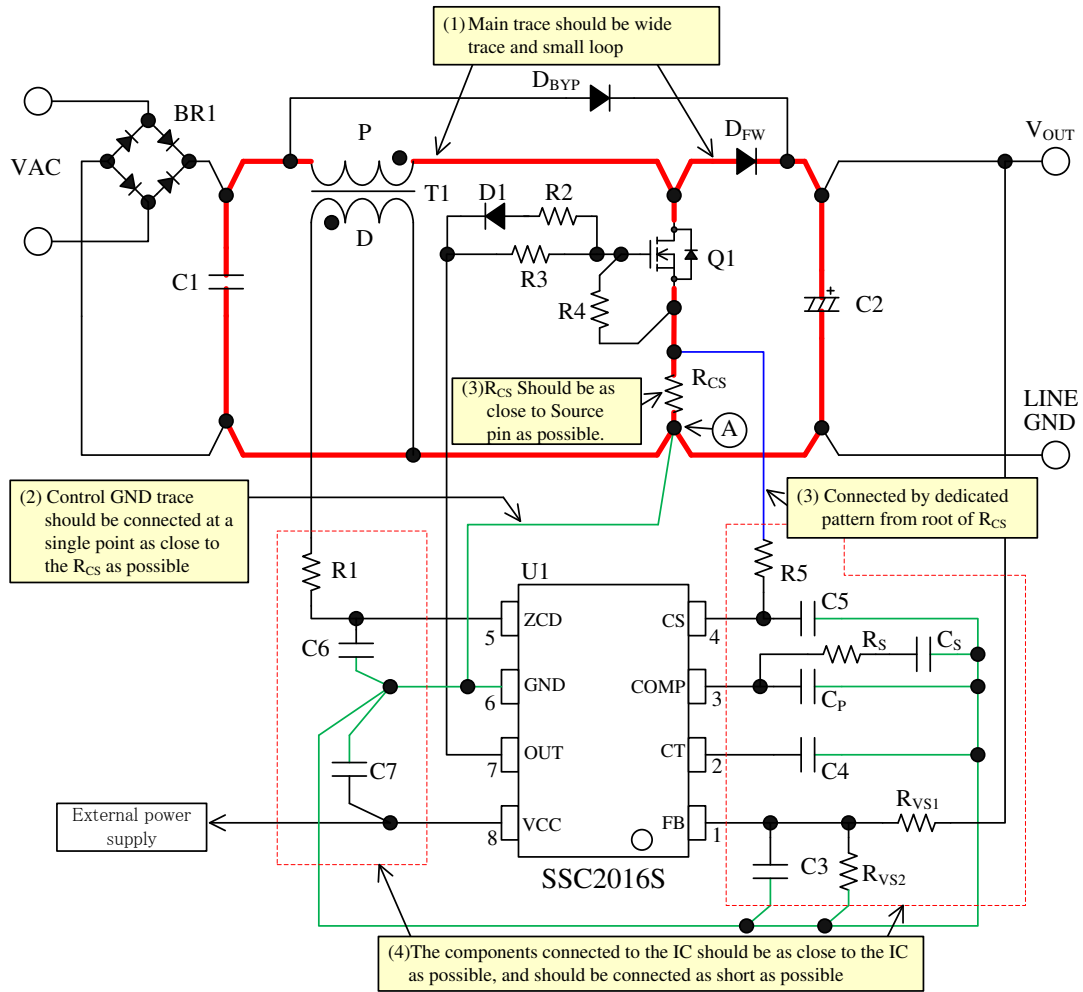


Figure 9-6. Example of Connection of Peripheral Component

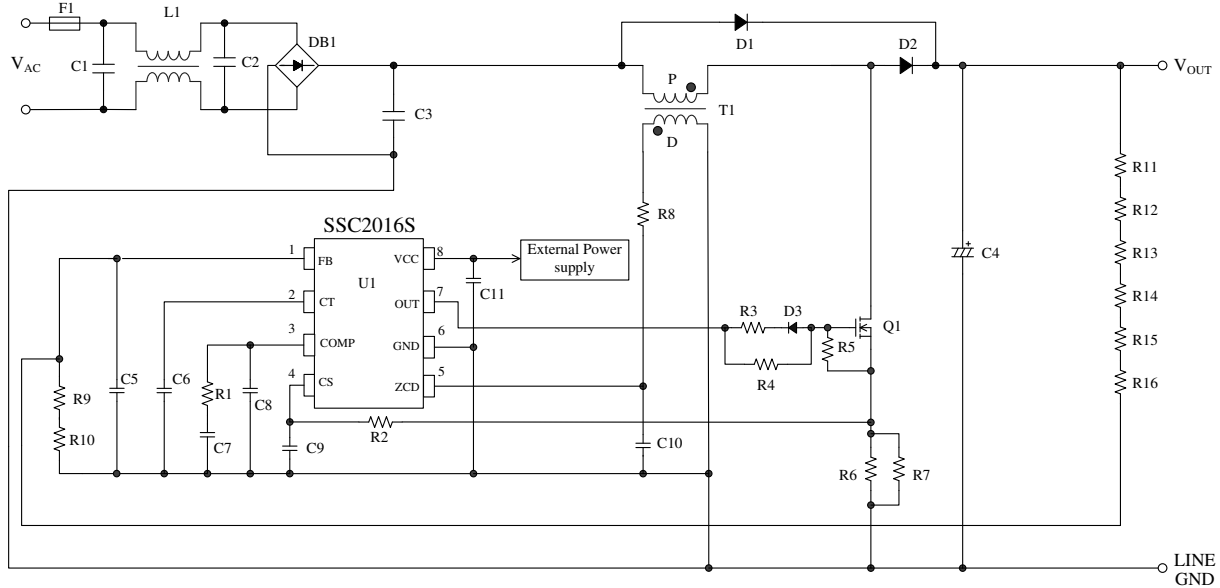
10. Reference Design of Power Supply

As an example, the following show the power supply specification, the circuit schematic, the bill of materials, and the transformer specification.

• Power Supply Specifications

IC	SSC2016S
Input Voltage	85V AC to 265VAC
Output Power	100 W (390V, 0.256 A)
Minimum Frequency	45 kHz

• Circuit Schematic



• Bill of Materials

Symbol	Ratings ⁽¹⁾	Recommended Sanken Parts	Symbol	Ratings ⁽¹⁾	Recommended Sanken Parts
F1	Fuse, AC250 V, 4 A		R1	68 kΩ	
L1	CM inductor, 12 mH		R2	47 Ω	
DB1	Bridge diode, 600 V, 4 A		R3	10 Ω	
D1	600 V, 3 A	RM 4A	R4	100 Ω	
D2	Fast recovery, 600 V, 5 A	FMX-G16S	R5	10 kΩ	
D3	Schottky, 40 V, 1 A	AK 04	R6	0.24 Ω, 1 W	
C1	Film, 0.22 μF, 310 V		R7	0.24 Ω, 1 W	
C2	Film, 0.22 μF, 310 V		R8	47 kΩ	
C3	Ceramic, 0.82 μF, 450V		R9	22 kΩ, ± 1 %	
C4	Electrolytic, 120 μF, 450 V		R10	2 kΩ, ± 1 %	
C5	Ceramic, 0.01 μF		R11	750 kΩ, ± 1 %	
C6	Ceramic, 1000 pF		R12	750 kΩ, ± 1 %	
C7	Ceramic, 0.47 μF		R13	750 kΩ, ± 1 %	
C8	Ceramic, 1 μF		R14	750 kΩ, ± 1 %	
C9	Ceramic, 3300 pF		R15	750 kΩ, ± 1 %	
C10	Ceramic, Open		R16	30 kΩ, ± 1 %	
C11	Ceramic, Open		T1	See the specification	
Q1	Power MOSFET, 600 V, 10A, < 0.75 Ω		U1	IC	SSC2016S

⁽¹⁾ Unless otherwise specified, the voltage rating of capacitor is 50 V or less and the power rating of resistor is 1/8 W or less.

⁽²⁾ It is necessary to be adjusted based on actual operation in the application.

⁽³⁾ Resistors applied high DC voltage and of high resistance are recommended to select resistors designed against electromigration or use combinations of resistors in series for that to reduce each applied voltage, according to the requirement of the application.

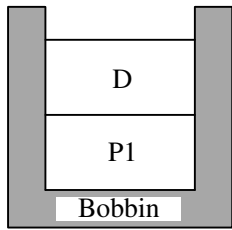
SSC2016S

- Transformer Specification

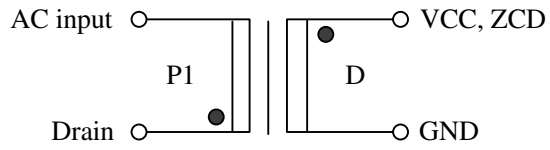
Primary Inductance : 290 μ H
 Core Size : EER28
 AL-Value : 92.5 nH/N²
 Gap Length : 1.2 mm (center gap)

Winding Specification

Location	Symbol	Number of Turns (turns)	Wire (mm)	Configuration	Note
Primary Winding	P1	56	ϕ 0.20 \times 10	Solenoid winding	Litz wire
Auxiliary Winding	D	8	ϕ 0.32	Solenoid winding	



Cross-section view



● mark shows the start point of winding

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