

HALOGEN

FREE

60 A VRPower[®] Integrated Power Stage

DESCRIPTION

The SiC620R and SiC620AR are integrated power stage solutions optimized for synchronous buck applications to offer high current, high efficiency, and high power density performance. Packaged in Vishay's proprietary 5 mm x 5 mm MLP package, SiC620R and SiC620AR enables voltage regulator designs to deliver up to 60 A continuous current per phase.

The internal power MOSFETs utilizes Vishay's state-of-the-art Gen IV TrenchFET[®] technology that delivers industry benchmark performance to significantly reduce switching and conduction losses.

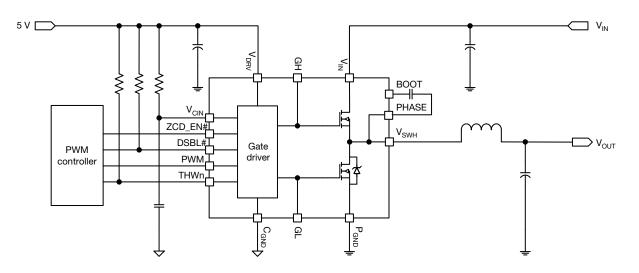
The SiC620R and SiC620AR incorporates an advanced MOSFET gate driver IC that features high current driving capability, adaptive dead-time control, an integrated bootstrap Schottky diode, a thermal warning (THWn) that alerts the system of excessive junction temperature, and zero current detect to improve light load efficiency. The drivers are also compatible with a wide range of PWM controllers and supports tri-state PWM, 3.3 V (SiC620AR) / 5 V (SiC620R) PWM logic.

FEATURES

- Thermally enhanced PowerPAK[®] MLP55-31L double cooling package
- double cooling package
 Vishay's Gen IV MOSFET technology and a low
- side MOSFET with integrated Schottky diode
- Delivers up to 60 A continuous current
- 95 % peak efficiency
- High frequency operation up to 1.5 MHz
- Power MOSFETs optimized for 12 V input stage
- 3.3 V (SiC620AR) / 5 V (SiC620R) PWM logic with tri-state and hold-off
- Zero current detect control for light load efficiency improvement
- Low PWM propagation delay (< 20 ns)
- Thermal monitor flag
- Under voltage lockout for V_{CIN}
- Material categorization: for definitions of compliance please see <u>www.vishay.com/doc?99912</u>

APPLICATIONS

• Multi-phase VRDs for CPU, GPU, and memory



TYPICAL APPLICATION DIAGRAM

Fig. 1 - SiC620R and SiC620AR Typical Application Diagram

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SiC620R, SiC620AR

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PINOUT CONFIGURATION

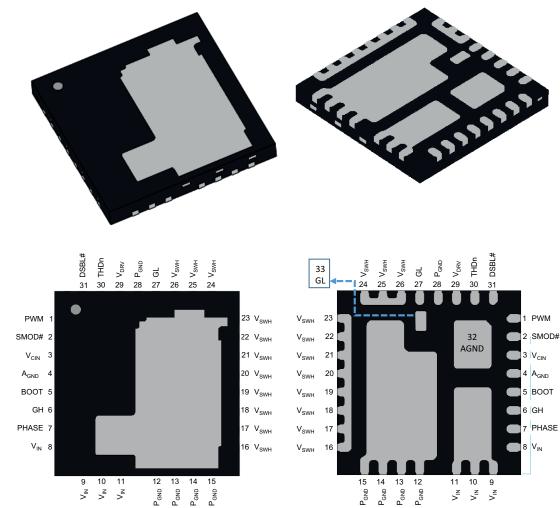


Fig. 2 - SiC620R and SiC620AR Pin Configuration

Bottom view

Top view

PIN CONFIG	URATION	
PIN NUMBER	NAME	FUNCTION
1	PWM	PWM control input
2	ZCD_EN#	ZCD control. Active low
3	V _{CIN}	Supply voltage for internal logic circuitry
4, 32	C _{GND}	Analog ground for the driver IC
5	BOOT	High side driver bootstrap voltage
6	GH	High side gate signal
7	PHASE	Return path of high side gate driver
8 to 11, 34	V _{IN}	Power stage input voltage. Drain of high side MOSFET
12 to 15, 28, 35	P _{GND}	Power ground
16 to 26	V _{SWH}	Switch node of the power stage
27, 33	GL	Low side gate signal
29	V _{DRV}	Supply voltage for internal gate driver
30	THWn	Thermal warning open drain output
31	DSBL#	Disable pin. Active low

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ORDERING INFORMATI	ORDERING INFORMATION					
PART NUMBER	PACKAGE	MARKING CODE	OPTION			
SiC620RCD-T1-GE3	PowerPAK MLP55-31L	620	5 V PWM optimized			
SiC620ARCD-T1-GE3	PowerPAK MLP55-31L	62 <u>0</u>	3.3 V PWM optimized			
SiC620RDB / SiC620ARDB		Reference board				

ABSOLUTE MAXIMUM RATIN	GS			
ELECTRICAL PARAMETER	CONDITIONS	LIMIT	UNIT	
Input voltage	V _{IN}	-0.3 to +25		
Control logic supply voltage	V _{CIN}	-0.3 to +7		
Drive supply voltage	V _{DRV}	-0.3 to +7		
Switch node (DC voltage)		-0.3 to +25		
Switch node (AC voltage) (1)	V _{SWH}	-7 to +30		
BOOT voltage (DC voltage)	N N	32	V	
BOOT voltage (AC voltage) (2)	V _{BOOT}	38		
BOOT to PHASE (DC voltage)		-0.3 to +7		
BOOT to PHASE (AC voltage) (3)	VBOOT-PHASE	-0.3 to +8	7	
All logic inputs and outputs (PWM, DSBL#, and THWn)		-0.3 to V _{CIN} +0.3		
Output ourrent L (4)	f _S = 300 kHz, V _{IN} = 12 V, V _{OUT} = 1.8 V	60	^	
Output current, I _{OUT(AV)} ⁽⁴⁾	$f_{S} = 1 \text{ MHz}, V_{IN} = 12 \text{ V}, V_{OUT} = 1.8 \text{ V}$	50	A	
Max. operating junction temperature	TJ	150		
Ambient temperature	T _A	-40 to +125		
Storage temperature	T _{stg}	-65 to +150		
Electrostatic discharge protection	Human body model, JESD22-A114	3000		
Electrostatic discharge protection	Charged device model, JESD22-C101	500	V	

Notes

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings
only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the
specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability

 $^{(1)}$ The specification values indicated "AC" is V_{SWH} to P_{GND} -8 V (< 20 ns, 10 µJ), min. and 30 V (< 50 ns), max.

⁽²⁾ The specification value indicates "AC voltage" is V_{BOOT} to P_{GND} , 38 V (< 50 ns) max.

 $^{(3)}$ The specification value indicates "AC voltage" is V_{BOOT} to V_{PHASE}, 8 V (< 20 ns) max.

⁽⁴⁾ Output current rated with testing evaluation board at $T_A = 25$ °C with natural convection cooling. The rating is limited by the peak evaluation board temperature, T_J

RECOMMENDED OPERATING RANGE						
ELECTRICAL PARAMETER	MINIMUM	TYPICAL	MAXIMUM	UNIT		
Input voltage (V _{IN})	4.5	-	18			
Drive supply voltage (V _{DRV})	4.5	5	5.5			
Control logic supply voltage (V _{CIN})	4.5	5	5.5	V		
Switch node (V _{SWH} , DC voltage)	-	-	18			
BOOT to PHASE (V _{BOOT-PHASE} , DC voltage)	4	4.5	5.5			
Thermal resistance from junction to ambient	-	10.6	-	°C/W		
Thermal resistance from junction to case	-	1.6	-	C/W		

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SiC620R, SiC620AR

	ELECTRICAL SPECIFICAT (DSBL# = ZCD_EN# = 5 V, V ₁		_{RV} and V _{CIN} = 5 V, T _A = 25 °C)				
POWER SUPPLY With TYP. MAX Min. TYP. MAX Control logic supply current Ivan Vosat_a = 5 V, no switching - 12 - 300 - IVan Ivan<				1	LIMITS		r
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
	POWER SUPPLY				1		
$ \begin{array}{ c c c c c c c } \hline V_{DSBLI} = 5 V, f_0 = 300 kHz, D = 0.1 & - & 380 & - & \\ \hline f_0 = 300 kHz, D = 0.1 & - & 55 & 0 & - & \\ \hline f_0 = 1 MHz, D = 0.1 & - & 65 & 0 & - & \\ \hline f_0 = 1 MHz, D = 0.1 & - & 65 & - & & \\ \hline V_{DSBLI} = 0 V, no switching & - & 25 & - & & \\ \hline V_{DSBLI} = 5 V, no switching & - & 60 & - & & \\ \hline V_{DSBLI} = 5 V, no switching & - & 60 & - & & \\ \hline V_{DSBLI} = 5 V, no switching & - & 60 & - & & \\ \hline V_{DSBLI} = 5 V, no switching & - & 60 & - & & \\ \hline V_{DSBLI} = 5 V, no switching & - & 60 & - & & \\ \hline WCONTROL INPUT (SICE2OH) & & & & & & & \\ \hline Hind threshold & V_{PL} PWM P & & & & & & & & \\ \hline Tri-state rising threshold & V_{PL} PWM P & & & & & & & & \\ \hline Tri-state rising threshold & V_{TRI, TR, FI} & & & & & & & & & \\ \hline Tri-state rising threshold & V_{TRI, TR, FI} & & & & & & & & & & \\ \hline Tri-state rising threshold & V_{TRI, TR, FI} & & & & & & & & & \\ \hline Tri-state rising threshold & V_{PVS, TRI, FI} & & & & & & & & & & \\ \hline Tri-state rising threshold & V_{PVS, TRI, FI} & & & & & & & & & & \\ \hline Tri-state rising threshold & V_{PVS, TRI, FI} & & & & & & & & & \\ \hline Tri-state rising threshold & V_{PVS, TRI, FI} & & & & & & & & & & & \\ \hline WM input current & & & & & & & & \\ \hline PWM ONTFOL INPUT (SICE2OH) & & & & & & & & \\ \hline Tri-state rising threshold & V_{PV, PVM, FI} & & & & & & & & \\ \hline Tri-state rising threshold & V_{PV, PVM, FI} & & & & & & & & \\ \hline Tri-state rising threshold & V_{PV, PVM, FI} & & & & & & & & \\ \hline Tri-state rising threshold & V_{PV, PVM, FI} & & & & & & & & \\ \hline WM input current & & & & & & & & & & \\ \hline PWM ONTFOL INPUT (SICE2OH) & & & & & & & & & \\ \hline Tri-state rising threshold & V_{PV, PVM, FI, FI} & & & & & & & & & \\ \hline Tri-state rising threshold & V_{PV, PVM, FI, FI} & & & & & & & & & \\ \hline Wing threshold & V_{PV, PVM, FI, FI} & & & & & & & & & \\ \hline WM input current & & & & & & & & & & \\ \hline WM input current & & & & & & & & & & & & & & & \\ \hline WM input current & & & & & & & & & & & & & & & \\ \hline WM input current & & & & & & & & & & & & & & & & & & &$			V _{DSBL#} = 0 V, no switching	-	12	-	
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Control logic supply current	I _{VCIN}	$V_{DSBL\#} = 5 V$, no switching, $V_{PWM} = FLOAT$	-	300	-	μA
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			V _{DSBL#} = 5 V, f _S = 300 kHz, D = 0.1	-	380	-	
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			f _S = 300 kHz, D = 0.1	-	15	25	
$\begin{tabular}{ c c c c c c } \hline V_{DSRL#} = 0 V, no switching & - & 25 & - & V_{DSRL#} = 5 V, no switching & - & 60 & - & V_{DSRL#} = 5 V, no switching & - & 60 & - & V_{DSRL#} = 5 V, no switching & - & 60 & - & V_{DSRL#} = 5 V, no switching & - & 60 & - & V_{DSRL#} = 5 V, no switching & - & 60 & - & V_{DSRL#} = 5 V, no switching & - & 60 & - & V_{DSRL#} = 5 V, no switching & - & 60 & - & V_{DSRL#} = 5 V, no switching & - & 60 & - & V_{DSRL#} = 0 V, no switching & - & 60 & - & V_{DSRL#} = 0 V, no switching & - & 60 & - & V_{DSRL#} = 0 V, no switching & - & 60 & - & V_{DSRL#} = 0 V, no switching & - & 60 & - & V_{DSRL#} = 0 V, no switching & - & 60 & - & V_{DSRL#} = 0 V, no switching & - & 0.4 & V_{DSRL#} = 0 V, no switching & - & 0.4 & V_{DSRL#} = 0 V, no switching & - & 0.5 & - & 0.5 & - & V_{DSRL#} = 0 V, no switching & - & 0.5 &$			f _S = 1 MHz, D = 0.1	-	50	-	mA
VDSRL# 5 V, no switching - 60 - - 60 - - 60 - - 60 - - 7 BOOTSTRAP SUPPLY Bootstrap diode forward voltage Vr. IF = 2 mA 0.4 V PWM CONTROL INPUT (SIC620R) VTRL PWM.F 0.72 0.9 1.2 - 2.3 - V - 2.3 - V - 2.3 - V Tri-state roing threshold VTRL PWM.F 0.9 1.15 1.38 - - 1.5 1.38 - - 2.3 - - 1.5 1.5 1.38 - - 1.5 1.38 - - 1.5 1.33 3.3 3.6 - - 3.50 - - - 3.50 - - - - 3.50 - - - 3.50 - - - - 3.50 - - - - - 3.50 - <td< td=""><td>Drive supply current</td><td>IVDRV</td><td>V_{DSBL#} = 0 V, no switching</td><td>-</td><td>25</td><td>-</td><td></td></td<>	Drive supply current	IVDRV	V _{DSBL#} = 0 V, no switching	-	25	-	
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$			$V_{DSBL\#} = 5 V$, no switching	-	60	-	μA
PWM CONTROL INPUT (SIG620R) VTH_PWM_R 3.4 3.8 4.2 Falling threshold VTH_PWM_R 0.72 0.9 1.2 Frailing threshold VTRI VPWM = FLOAT - 2.3 - Tri-state voltage VTRI VPWM = FLOAT 0.9 1.15 1.38 Tri-state rising threshold VTRI_TH_R 0.9 1.15 1.38 3.3 3.6 Tri-state rising threshold hysteresis VHX_TRI_R - 225 - m Tri-state falling threshold hysteresis VHX_TRI_R - 3255 - m PWM input current IpWM VPWM = 5 V - - 350 P PWM CONTROL INPUT (SIC620R) VTH_PWM_R 0.72 0.9 1.1 P Falling threshold VTH_PWM_R 0.72 0.9 1.1 P Tri-state rising threshold VTH_PWM_R 0.72 0.9 1.1 P Tri-state rising threshold VTH_PWM_R R 0.72 0.9 1.1 <td< td=""><td>BOOTSTRAP SUPPLY</td><td></td><td></td><td></td><td>•</td><td></td><td></td></td<>	BOOTSTRAP SUPPLY				•		
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Bootstrap diode forward voltage	V _F	$I_F = 2 \text{ mA}$			0.4	V
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	PWM CONTROL INPUT (SiC620R)				•		
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Rising threshold	V _{TH_PWM_R}		3.4	3.8	4.2	
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Falling threshold			0.72	0.9	1.2	
$\begin{array}{ c c c c c c c } \hline Tri-state rising threshold & V_{TRI_{TH_{.R}}} & 0.9 & 1.15 & 1.38 \\ \hline Tri-state falling threshold & V_{TRI_{TH_{.F}}} & 3 & 3.3 & 3.6 \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRI_{R}} & - & 225 & - & & Tri-state falling threshold hysteresis & V_{HYS_TRI_{R}} & - & 325 & - & & Tri-state falling threshold hysteresis & V_{HYS_TRI_{R}} & - & 325 & - & & Tri-state falling threshold hysteresis & V_{HYS_TRI_{R}} & - & 325 & - & & Tri-state falling threshold hysteresis & V_{HYS_TRI_{R}} & - & 325 & - & & Tri-state falling threshold & V_{TH_{PWM_{R}}} & V_{PWM} = 5 V & - & - & - & 350 & \\ \hline PWM control INPUT (SiC620AR) & & & & & & & & & \\ \hline Tri-state falling threshold & V_{TH_{PWM_{R}}} & & & & & & & & & & & & \\ \hline Tri-state voltage & V_{TRI} & V_{PWM_{R}} & V_{PWM} = FLOAT & - & 1.8 & - & & & & & & \\ \hline Tri-state rising threshold & V_{TRI_{TH_{.R}}} & & & & & & & & & & & & \\ \hline Tri-state rising threshold & V_{TRI_{TH_{.R}}} & & & & & & & & & & & & \\ \hline Tri-state rising threshold & V_{TRI_{TH_{.R}}} & & & & & & & & & & & & \\ \hline Tri-state falling threshold & V_{TRI_{TH_{.R}}} & & & & & & & & & & & & \\ \hline Tri-state falling threshold & V_{TRI_{TH_{.R}}} & & & & & & & & & & & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_{.TRI_{.R}}} & & & & & & & & & & & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_{.TRI_{.R}}} & & & & & & & & & & & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_{.TRI_{.R}}} & & & & & & & & & & & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_{.TRI_{.R}}} & & & & & & & & & & & & & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_{.TRI_{.R}}} & & & & & & & & & & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_{.TRI_{.R}}} & & & & & & & & & & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_{.TRI_{.R}}} & & & & & & & & & & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_{.TRI_{.R}} & & & & & & & & & & & & & \\ \hline Tri-state hold-off time & & & & & & & & & & & & & & & & & & &$			V _{PWM} = FLOAT	-	2.3	-	V
Tri-state failing threshold V _{FRI_TH_F} (1) (3) (1) (1) (1) (1) (1) (1) (1) (1) (1) (1) (1) (1) (1) (1)				0.9	1.15	1.38	
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Tri-state falling threshold			3	3.3	3.6	-
Tri-state failing threshold hysteresis V _{HYS_TRLF} - 325 - 1 PWM input current I _{PWM} V _{PWM} = 5 V - - 350 µ PWM control INPUT (Siceoar) V _{TLPWM,R} - - <td>Tri-state rising threshold hysteresis</td> <td></td> <td></td> <td>-</td> <td>225</td> <td>-</td> <td></td>	Tri-state rising threshold hysteresis			-	225	-	
$\begin{array}{ c c c c c c } \hline PWM input current & I_{PWM} & V_{PWM} = 5 V & - & - & 350 \\ \hline PWM CONTROL INPUT (SiG620AR) & & & & & & & & & & & & & & & & & & &$	Tri-state falling threshold hysteresis			-	325	-	mV
$\begin{array}{ c c c c c } \hline PWM input current & IPWM & VPWM = 0 V & - & - & -350 \\ \hline PWM CONTROL INPUT (SiG620AR) \\ \hline Pising threshold & V_{TH_PWM_F} & 0.72 & 0.9 & 1.1 \\ \hline Tri-state voltage & V_{TR} & V_{PWM} = FLOAT & - & 1.8 & - & V_{Tri-state voltage} & V_{TR} & V_{PWM} = FLOAT & - & 1.8 & - & V_{Tri-state voltage} & V_{TR} & 0.9 & 1.15 & 1.38 \\ \hline Tri-state voltage & V_{TR} & V_{PWM} = FLOAT & - & 1.8 & - & V_{Tri-state voltage} & V_{TR_1,TR} & 0.9 & 1.15 & 1.38 \\ \hline Tri-state rising threshold & V_{TR_1,TR} & 0.9 & 1.15 & 1.38 \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TR_1,R} & - & 250 & - & 0.50 & - & 0.50 & - & 0.50 & - & 0.50 & - & 0.50 & 0.50 & - & 0.50 & 0.50 & - & 0.50 & 0.50 & - & 0.50 & 0.50 & - & 0.50 & 0.50 & - & 0.50 & 0.50 & - & 0.50 & 0.50 & - & 0.50 & 0.50 & - & 0.50 & 0.50 & - &$			V _{PWM} = 5 V	-	-	350	
$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$	PWM input current	IPWM		-	-	-350	μA
$ \begin{array}{ c c c c c c } \hline Falling threshold & V_{TH_PWM_F} & 0.72 & 0.9 & 1.1 \\ \hline Tri-state voltage & V_{TRI} & V_{PWM} = FLOAT & - & 1.8 & - \\ \hline Tri-state voltage & V_{TRI} & V_{PWM} = FLOAT & - & 1.8 & - \\ \hline Tri-state rising threshold & V_{TRLTH_R} & 0.9 & 1.15 & 1.38 \\ \hline Tri-state rising threshold & V_{TRLTH_F} & 1.95 & 2.2 & 2.45 \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & - & 250 & - \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & - & 300 & - \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & - & 300 & - \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & - & 300 & - \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & V_{PWM} = 3.3 V & - & - & 225 \\ \hline Tri-state for GH/GL rising & t_{PD_TRLR} & V_{PWM} = 0 V & - & - & - & 225 \\ \hline Tri-state hold-off time & t_{TSHO} & & & & & & & & \\ \hline Tri-state hold-off time & t_{TSHO} & & & & & & & & & & & \\ \hline Tri-state hold-off time & t_{TSHO} & & & & & & & & & & & & \\ \hline GH - turn off propagation delay & t_{PD_OFF_GH} & & & & & & & & & & & & & & \\ GH - turn off propagation delay & t_{PD_OFF_GL} & & & & & & & & & & & & & & & & & & &$	PWM CONTROL INPUT (SiC620AR	k)			•		
$ \begin{split} \hline \begin{tabular}{ c c c c c } \hline Falling threshold & V_{TH_LPWM_F} & 0.72 & 0.9 & 1.1 \\ \hline Tri-state voltage & V_{TRI} & V_{PWM} = FLOAT & - & 1.8 & - \\ \hline Tri-state voltage & V_{TRI} & V_{PWM} = FLOAT & - & 1.8 & - \\ \hline Tri-state rising threshold & V_{TRL_TH_R} & 0.9 & 1.15 & 1.38 \\ \hline Tri-state rising threshold hysteresis & V_{HYS_TRLR} & - & 250 & - \\ \hline Tri-state rising threshold hysteresis & V_{HYS_TRLR} & - & 300 & - \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & - & 300 & - \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & - & 300 & - \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & - & 225 & - \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & V_{PWM} = 3.3 V & - & - & 225 \\ \hline Tri-state for GH/GL rising & t_{PD_TRLR} & V_{PWM} = 0 V & - & - & - & 225 \\ \hline Tri-state for GH/GL rising & t_{PD_TRLR} & & & & \\ \hline Tri-state hold-off time & t_{TSHO} & & & & \\ \hline Tri-state hold-off time & t_{TSHO} & & & & \\ \hline GH - turn off propagation delay & t_{PD_OFF_GH} & & & & \\ \hline GL - turn off propagation delay & t_{PD_OFF_GL} & & & \\ \hline GL - turn off propagation delay & t_{PD_OFF_GL} & & & \\ \hline GL - turn off propagation delay & t_{PD_ON_GL} & & & \\ \hline DSBL \mu Lo to GH/GL falling & t_{PD_ON_GL} & & & \\ \hline DSBL \mu Lo to GH/GL falling & t_{PD_ON_GL} & & & \\ \hline DSBL \mu Lo to GH/GL falling & t_{PD_ON_GL} & & & \\ \hline Tri-state hold-off delay & & \\ \hline Tri-DSBL \mu = F & Fig. 5 & - & \\ \hline Tri-state hold-off delay & & \\ \hline Tri-state hold-off delay & & \\ \hline Tri-state hold-off delay & & \\ \hline Tri-state hold-field falling & & \\ \hline Tri-state $	Rising threshold	V _{TH_PWM_R}		2.2	2.45	2.7	
$\begin{array}{ c c c c c } \hline Tri-state voltage & V_{TRI} & V_{PWM} = FLOAT & - & 1.8 & - & V_{TRI} \\ \hline Tri-state rising threshold & V_{TRI_TH_R} & 0.9 & 1.15 & 1.38 \\ \hline Tri-state rising threshold & V_{TRI_TH_F} & 1.95 & 2.2 & 2.45 \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRI_R} & - & 250 & - & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRI_R} & - & 300 & - & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRI_F} & - & 300 & - & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRI_F} & & & & & \\ \hline PWM input current & & & \\ \hline Tri-state fo GH/GL rising & & \\ \hline Tri-state fo GH/GL rising & & \\ \hline Tri-state hold-off time & & & \\ \hline CH - turn off propagation delay & & \\ \hline CH - turn off propagation delay & & \\ \hline CGL - turn off propagation delay & & \\ \hline CGL - turn off propagation delay & & \\ \hline TrD_ON_GH & & \\ \hline DSBL \# Lo to GH/GL falling & & \\ \hline TriD_ON_GH & & \\ \hline DSBL \# Lo to GH/GL falling & \\ \hline TroD_ON_GH & & \\ \hline TriD_ON_GH & & \\ \hline TriD_O$	Falling threshold			0.72	0.9	1.1	
$ \begin{array}{c c c c c c c } \hline Tri-state falling threshold & V_{TRLTH_F} & & & 1.95 & 2.2 & 2.45 \\ \hline Tri-state rising threshold hysteresis & V_{HYS_TRLR} & & & - & 250 & - & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLR} & & & - & 300 & - & & \\ \hline Tri-state falling threshold hysteresis & V_{HYS_TRLF} & & & & - & 300 & - & & \\ \hline PWM input current & I_{PWM} & V_{PWM} = 3.3 V & - & - & 225 & \mu \\ \hline PWM input current & I_{PWM} & V_{PWM} = 0 V & - & - & - & 225 & & \\ \hline Tri-state to GH/GL rising & t_{PD_TRLR} & & & & \\ \hline Tri-state hold-off time & t_{TSHO} & & & & \\ \hline GH - turn off propagation delay & t_{PD_OFF_GH} & & & & \\ \hline GH - turn off propagation delay & t_{PD_OFF_GH} & & & & \\ \hline GL - turn off propagation delay & t_{PD_OFF_GL} & & & \\ \hline GL - turn off propagation delay & t_{PD_OFF_GL} & & & \\ \hline GL - turn off propagation delay & t_{PD_ON_GH} & & & \\ \hline DSBL# Lo to GH/GL falling & t_{PD_DSBL#_F} & Fig. 5 & - & 15 & - \\ \hline \end{array}$	Tri-state voltage		V _{PWM} = FLOAT	-	1.8	-	V
$\begin{array}{c c c c c c c } \hline \mbox{Tri-state falling threshold hysteresis} & V_{HYS_TRLR} & & & & & & & & & & & & & & & & & & &$	Tri-state rising threshold	V _{TRI_TH_R}		0.9	1.15	1.38	
$\begin{array}{c c c c c c c }\hline Tri-state rising threshold hysteresis & V_{HYS_TRL_R} & & & & & & & & & & & & & & & & & & &$	Tri-state falling threshold			1.95	2.2	2.45	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Tri-state rising threshold hysteresis			-	250	-	
$\begin{array}{c c c c c c c } & V_{PWM} = 3.3 \ V & - & - & 225 \\ \hline V_{PWM} = 0 \ V & - & - & -225 \end{array} \\ \hline TriMING SPECIFICATIONS \\ \hline Tri-state to GH/GL rising \\ propagation delay & t_{PD_TRL_R} \\ \hline Tri-state hold-off time & t_{TSHO} \\ \hline GH - turn off propagation delay & t_{PD_OFF_GH} \\ \hline GH - turn off propagation delay & t_{PD_OFF_GH} \\ \hline GL - turn off propagation delay & t_{PD_OFF_GL} \\ \hline GL - turn off propagation delay & t_{PD_OFF_GL} \\ \hline GL - turn off propagation delay & t_{PD_OFF_GL} \\ \hline DSBL# Lo to GH/GL falling \\ propagation delay & t_{PD_OSBL#_F} \\ \hline \end{array} \begin{array}{c c c c c c c c c c c c c c c c c c c $	Tri-state falling threshold hysteresis			-	300	-	mV
PWM input currentIPWM $V_{PWM} = 0 V$ 225 μ TIMING SPECIFICATIONSTri-state to GH/GL rising propagation delay $t_{PD_TRL,R}$ -30Tri-state hold-off time t_{TSHO} -130GH - turn off propagation delay $t_{PD_OFF_GH}$ No load, see fig. 4-15-GH - turn off propagation delay $t_{PD_OFF_GH}$ -10GL - turn off propagation delay $t_{PD_OFF_GL}$ -10GL - turn off propagation delay (dead time falling) $t_{PD_ON_GL}$ Fig. 5-15-DSBL# Lo to GH/GL falling propagation delay $t_{PD_DSBL#_F}$ Fig. 5-15-			V _{PWM} = 3.3 V	-	-	225	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $		IPWM		-	-	-225	μA
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	TIMING SPECIFICATIONS					•	
GH - turn off propagation delay tpD_OFF_GH GH - turn on propagation delay tpD_OFF_GH GH - turn on propagation delay tpD_ON_GH GL - turn off propagation delay tpD_OFF_GL GL - turn off propagation delay tpD_OFF_GL GL - turn off propagation delay tpD_ON_GL GL - turn off propagation delay tpD_ON_GL DSBL# Lo to GH/GL falling tpD_DSBL#_F Fig. 5 -		t _{PD_TRI_R}		-	30	-	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Tri-state hold-off time	t _{TSHO}		-	130	-	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	GH - turn off propagation delay			-	15	-	
GL - turn off propagation delay tpD_OFF_GL GL - turn on propagation delay tpD_ON_GL GL - turn on propagation delay tpD_ON_GL DSBL# Lo to GH/GL falling propagation delay tpD_DSBL#_F Fig. 5 - 15 -			No load, see fig. 4	-	10	-	
GL - turn on propagation delay (dead time falling) tpD_ON_GL - 10 - DSBL# Lo to GH/GL falling propagation delay tpD_DSBL#_F Fig. 5 - 15 -		t _{PD OFF GL}		-	12	-	ns
DSBL# Lo to GH/GL falling propagation delay tPD_DSBL#_F Fig. 5 - 15 -	GL - turn on propagation delay			-	10	-	1
	DSBL# Lo to GH/GL falling	t _{PD_DSBL#_F}	Fig. 5	-	15	-	1
	PWM minimum on-time	t _{PWM_ON_MIN}		30	-	-	1

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PARAMETER	SYMBOL	TEST CONDITION		LIMITS				
PARAMETER	STNIBUL	TEST CONDITION	MIN.	TYP.	MAX.			
DSBL# ZCD_EN# INPUT								
	V _{IH_DSBL#}	Input logic high	2	-	-			
DSBL# logic input voltage	V _{IL_DSBL#}	Input logic low	-	-	0.8	v		
ZCD EN# logic input voltage	VIH_ZCD_EN#	Input logic high	2	-	-	v		
ZCD_EN# logic input voltage	V _{IL_ZCD_EN#}	Input logic low	-	-	0.8	1		
PROTECTION								
Linder veltage leekeut	V	V _{CIN} rising, on threshold	-	3.7	4.1	v		
Under voltage lockout	V _{UVLO}	V _{CIN} falling, off threshold	2.7	3.1	-	v		
Under voltage lockout hysteresis	V _{UVLO_HYST}		-	575	-	mV		
THWn flag set ⁽²⁾	T _{THWn_SET}		-	160	-			
THWn flag clear (2)	T _{THWn_CLEAR}		-	135	-	°C		
THWn flag hysteresis ⁽²⁾	T _{THWn_HYST}		-	25	-	1		
THWn output low	V _{OL THWn}	I _{THWn} = 2 mA	-	0.02	-	V		

Notes

⁽¹⁾ Typical limits are established by characterization and are not production tested

⁽²⁾ Guaranteed by design

DETAILED OPERATIONAL DESCRIPTION

PWM Input with Tri-State Function

The PWM input receives the PWM control signal from the VR controller IC. The PWM input is designed to be compatible with standard controllers using two state logic (H and L) and advanced controllers that incorporate tri-state logic (H, L and tri-state) on the PWM output. For two state logic, the PWM input operates as follows. When PWM is driven above $V_{\text{PWM TH R}}$ the low side is turned on and the high side is turned on. When PWM input is driven below VPWM TH F the high side is turned off and the low side is turned on. For tri-state logic, the PWM input operates as previously stated for driving the MOSFETs. However, there is an third state that is entered as the PWM output of tri-state compatible controller enters its high impedance state during shutdown. The high impedance state of the controller's PWM output allows the SiC620R and SiC620AR to pull the PWM input into the tri-state region (see PWM Timing Diagram). If the PWM input stays in this region for the tri-state hold-off period, t_{TSHO} , both high side and low side MOSFETs are turned off. This function allows the VR phase to be disabled without negative output voltage swing caused by inductor ringing and saves a Schottky diode clamp. The PWM and tri-state regions are separated by hysteresis to prevent false triggering. The SiC620AR incorporates PWM voltage thresholds that are compatible with 3.3 V logic and the SiC620R thresholds are compatible with 5 V logic.

Disable (DSBL#)

In the low state, the DSBL# pin shuts down the driver IC and disables both high side and low side MOSFETs. In this state, standby current is minimized. If DSBL# is left unconnected, an internal pull-down resistor will pull the pin to $C_{\rm GND}$ and shut down the IC.

Diode Emulation Mode (ZCD_EN#)

When ZCD_EN# pin is logic Low and PWM signal switches Low, GL is forced on (after normal BBM time). During this time, it is under control of the ZCD (zero crossing detect) comparator. If, after the internal blanking delay, the inductor current becomes zero, the low side is turned off. This improves light load efficiency by avoiding discharge of output capacitors. If PWM enters tri-state, then device will go into normal tri-state mode after tri-state delay. The GL output will be turned off regardless of Inductor current, this is an alternative method of improving light load efficiency by reducing switching losses.

Thermal Shutdown Warning (THWn)

The THWn pin is an open drain signal that flags the presence of excessive junction temperature. Connect with a maximum of 20 k Ω , to V_{CIN}. An internal temperature sensor detects the junction temperature. The temperature threshold is 160 °C. When this junction temperature is exceeded the THWn flag is set. When the junction temperature drops below 135 °C the device will clear the THWn signal. The SiC620R and SiC620AR do not stop operation when the flag is set. The decision to shutdown must be made by an external thermal control function.

Voltage Input (VIN)

This is the power input to the drain of the high side power MOSFET. This pin is connected to the high power intermediate BUS rail.

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Switch Node (V_{SWH} and PHASE)

The switch node, V_{SWH} , is the circuit power stage output. This is the output applied to the power inductor and output filter to deliver the output for the buck converter. The PHASE pin is internally connected to the switch node V_{SWH} . This pin is to be used exclusively as the return pin for the BOOT capacitor. A 20 k Ω resistor is connected between GH and PHASE to provide a discharge path for the HS MOSFET in the event that V_{CIN} goes to zero while V_{IN} is still applied.

Ground Connections (C_{GND} and P_{GND})

FUNCTIONAL BLOCK DIAGRAM

 $\mathsf{P}_{\mathsf{GND}}$ (power ground) should be externally connected to $\mathsf{C}_{\mathsf{GND}}$ (control signal ground). The layout of the printed circuit board should be such that the inductance separating $\mathsf{C}_{\mathsf{GND}}$ and $\mathsf{P}_{\mathsf{GND}}$ is minimized. Transient differences due to inductance effects between these two pins should not exceed 0.5 V

Control and Drive Supply Voltage Input (VDRV, VCIN)

 V_{CIN} is the bias supply for the gate drive control IC. V_{DRV} is the bias supply for the gate drivers. It is recommended to separate these pins through a resistor. This creates a low pass filtering effect to avoid coupling of high frequency gate drive noise into the IC.

Bootstrap Circuit (BOOT)

The internal bootstrap diode and an external bootstrap capacitor form a charge pump that supplies voltage to the BOOT pin. An integrated bootstrap diode is incorporated so that only an external capacitor is necessary to complete the bootstrap circuit. Connect a boot strap capacitor with one leg tied to BOOT pin and the other tied to PHASE pin.

Shoot-Through Protection and Adaptive Dead Time

The SiC620R and SiC620AR have an internal adaptive logic to avoid shoot through and optimize dead time. The shoot through protection ensures that both high side and low side MOSFETs are not turned on at the same time. The adaptive dead time control operates as follows. The HS and LS gate voltages are monitored to prevent the one turning on from tuning on until the other's gate voltage is sufficiently low (< 1 V). Built in delays also ensure that one power MOS is completely off, before the other can be turned on. This feature helps to adjust dead time as gate transitions change with respect to output current and temperature.

Under Voltage Lockout (UVLO)

During the start up cycle, the UVLO disables the gate drive holding high side and low side MOSFET gates low until the supply voltage rail has reached a point at which the logic circuitry can be safely activated. The SiC620R, SiC620AR also incorporates logic to clamp the gate drive signals to zero when the UVLO falling edge triggers the shutdown of the device. As an added precaution, a 20 k Ω resistor is connected between GH and PHASE to provide a discharge path for the HS MOSFET.

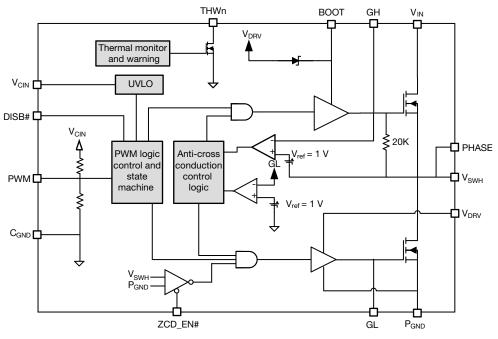


Fig. 3 - SiC620R and SiC620AR Functional Block Diagram

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DEVICE TRUTH T	ABLE			
DSBL#	ZCD_EN#	PWM	GH	GL
Open	Х	Х	L	L
L	Х	Х	L	L
н	L	L	L	H, I _L > 0 A L, I _L < 0 A
Н	L	Н	Н	L
н	L	Tri-state	L	L
Н	Н	L	L	Н
Н	Н	Н	Н	L
Н	Н	Tri-state	L	L

PWM TIMING DIAGRAM

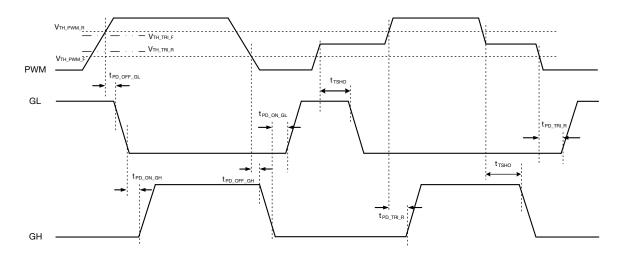


Fig. 4 - Definition of PWM Logic and Tri-state

DSBL# PROPAGATION DELAY PWM_______ DSBL# ______ DISable ______ DISable ______ GH ______ GH ______ GH ______ GL _____ DISABLE _____ GL _____ DISABLE ______ DISABLE _____ DISABLE ______ DISABLE _____ DISABLE ______ DISABLE _____ DISABLE ______ DISABLE _____

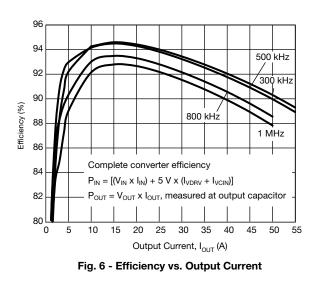
Fig. 5 - DSBL# Falling Propagation Delay

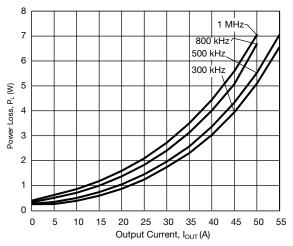
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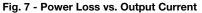
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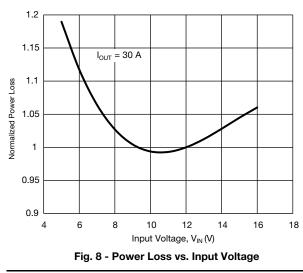
ELECTRICAL CHARACTERISTICS

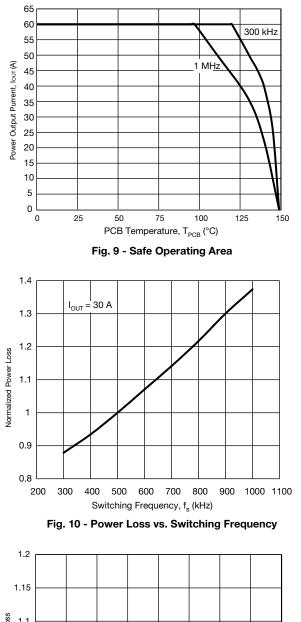
Test condition: $V_{IN} = 12 \text{ V}$, $V_{DRV} = V_{CIN} = 5 \text{ V}$, $ZCD_EN\# = 5 \text{ V}$, $V_{OUT} = 1.8 \text{ V}$, $L_{OUT} = 250 \text{ nH}$ (DCR = 0.32 m Ω), $T_A = 25 \text{ °C}$, natural convection cooling (All power loss and normalized power loss curves show SiC620R and SiC620AR losses only unless otherwise stated)

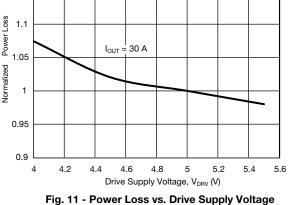












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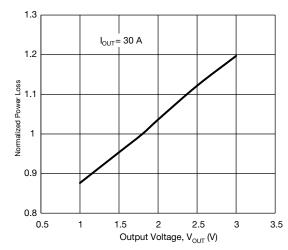


Fig. 12 - Power Loss vs. Output Voltage

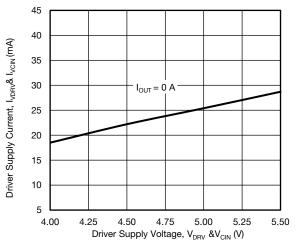


Fig. 13 - Driver Supply Current vs. Driver Supply Voltage

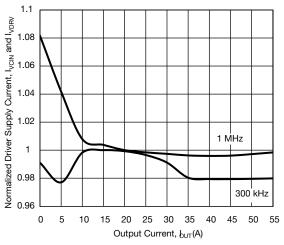


Fig. 14 - Driver Supply Current vs. Output Current

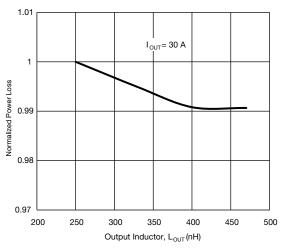


Fig. 15 - Power Loss vs. Output Inductor

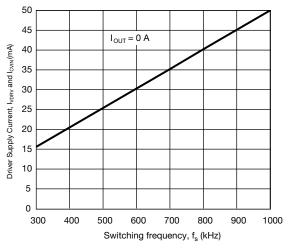


Fig. 16 - Driver Supply Current vs. Switching Frequency

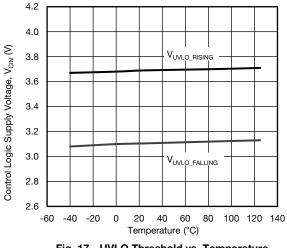


Fig. 17 - UVLO Threshold vs. Temperature

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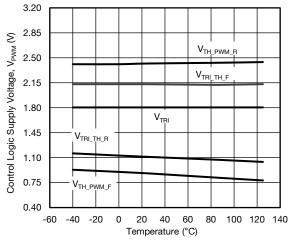


Fig. 18 - PWM Threshold vs. Temperature (SiC620AR)

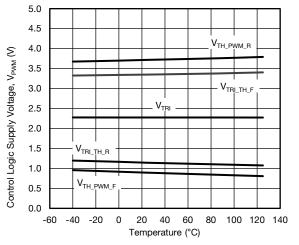


Fig. 19 - PWM Threshold vs. Temperature (SiC620R)

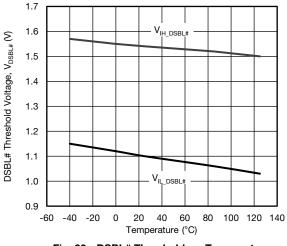


Fig. 20 - DSBL# Threshold vs. Temperature

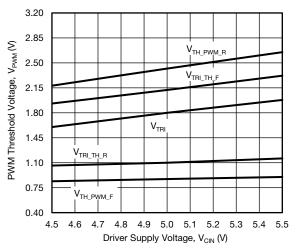


Fig. 21 - PWM Threshold vs. Driver Supply Voltage (SiC620AR)

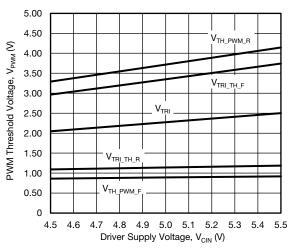


Fig. 22 - PWM Threshold vs. Driver Supply Voltage (SiC620R)

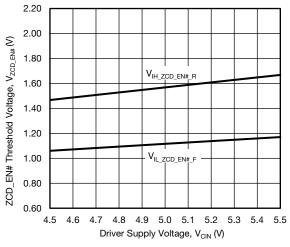


Fig. 23 - ZCD_EN# Threshold vs. Driver Supply Voltage

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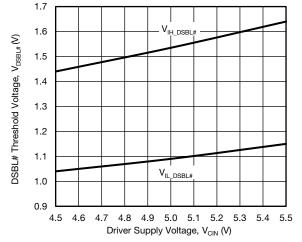


Fig. 24 - DSBL# vs. Driver Input Voltage

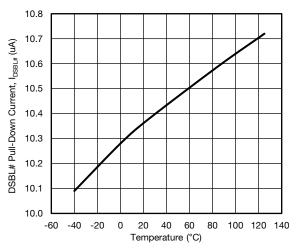


Fig. 25 - DSBL# Pull-Down Current vs. Temperature

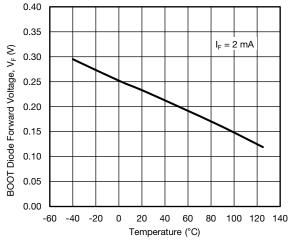


Fig. 26 - Boot Diode Forward Voltage vs. Temperature

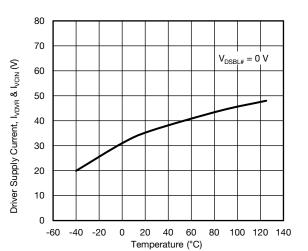


Fig. 27 - Driver Shutdown Current vs. Temperature

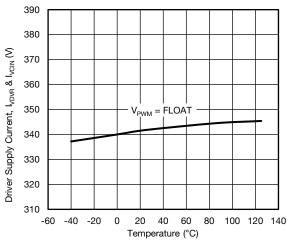


Fig. 28 - Driver Supply Current vs. Temperature

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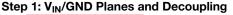
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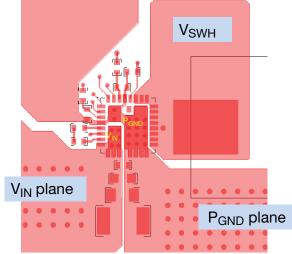
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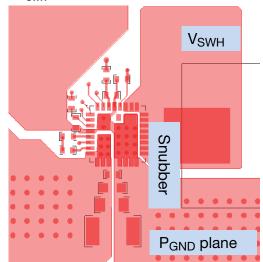
PCB LAYOUT RECOMMENDATIONS





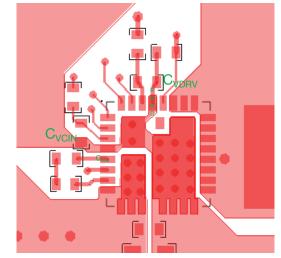
- 1. Layout V_{IN} and P_{GND} planes as shown above
- 2. Ceramic capacitors should be placed right between $V_{\rm IN}$ and $P_{\rm GND},$ and very close to the device for best decoupling effect
- 3. Difference values / packages of ceramic capacitors should be used to cover entire decoupling spectrum e.g. 1210, 0805, 0603 and 0402
- 4. Smaller capacitance value, closer to device V_{IN} pin(s) better high frequency noise absorbing

Step 2: V_{SWH} Plane



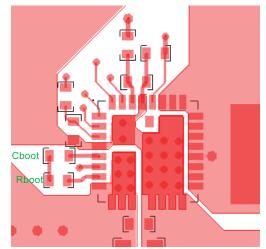
- 1. Connect output inductor to DrMOS with large plane to lower the resistance
- 2. If any snubber network is required, place the components as shown above and the network can be placed at bottom

Step 3: V_{CIN}/V_{DRV} Input Filter



- 1. The $V_{\text{CIN}}/V_{\text{DRV}}$ input filter ceramic cap should be placed very close to IC. It is recommended to connect two caps separately
- 2. C_{VCIN} cap should be placed between pin 3 and pin 4 (C_{GND} of driver IC) to achieve best noise filtering
- 3. $C_{\rm VDRV}$ cap should be placed between pin 28 ($\rm P_{GND}$ of driver IC) and pin 29 to provide maximum instantaneous driver current for low side MOSFET during switching cycle
- 4. For connecting C_{VCIN} analog ground, it is recommended to use large plane to reduce parasitic inductance

Step 4: BOOT Resistor and Capacitor Placement

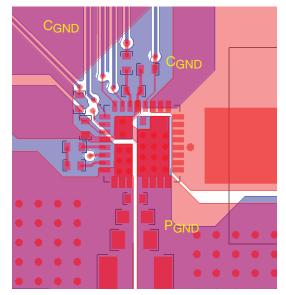


- 1. These components need to be placed very close to IC, right between PHASE (pin 7) and BOOT (pin 5)
- 2. To reduce parasitic inductance, chip size 0402 can be used

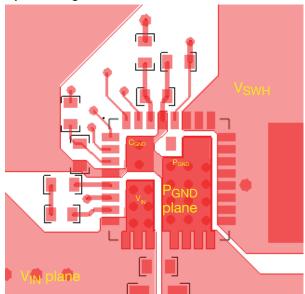
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Step 5: Signal Routing



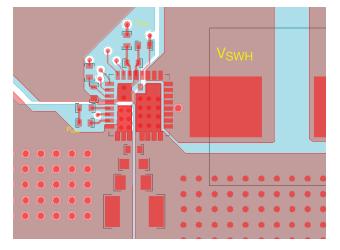
- 1. Route the PWM / ZCD_EN# / DSBL# / THWn signal traces out of the top left corner next DrMOS pin 1
- 2. PWM signal is very important signal, both signal and return traces need to pay special attention of not letting this trace cross any power nodes on any layer
- 3. It is best to "shield" traces form power switching nodes, e.g. V_{SWH} , to improve signal integrity
- 4. GL (pin 27) has been connected with GL pad internally and does not need to connect externally



Step 6: Adding Thermal Relief Vias

- 1. Thermal relief vias can be added on the $V_{\rm IN}$ and $P_{\rm GND}$ pads to utilize inner layers for high current and thermal dissipation
- 2. To achieve better thermal performance, additional vias can be put on $V_{\rm IN}$ plane and $P_{\rm GND}$ plane
- 3. V_{SWH} pad is a noise source and not recommended to put vias on this plane
- 4. 8 mil drill for pads and 10 mils drill for plane can be the optional via size. Vias on pad may drain solder during assembly and cause assembly issue. Please consult with the assembly house for guideline

Step 7: Ground Connection



- 1. It is recommended to make single connection between $C_{\mbox{GND}}$ and $P_{\mbox{GND}}$ and this connection can be done on top layer
- 2. It is recommended to make the whole inner 1 layer (next to top layer) ground plane and separate them into C_{GND} and P_{GND} plane
- 3. These ground planes provide shielding between noise source on top layer and signal trace on bottom layer



Multi-Phases VRPower PCB Layout

Following is an example for 6 phase layout. As can be seen, all the VRPower stages are lined in X-direction compactly with decoupling caps next to them. The inductors are placed as close as possible to the SiC620R and SiC620AR to minimize the PCB copper loss. Vias are applied on all PADs (V_{IN} , P_{GND} , C_{GND}) of the SiC620R and SiC620AR to ensure that both electrical and thermal performance are excellent. Large copper planes are used for all the high current loops, such as V_{IN} , V_{SWH} , V_{OUT} and P_{GND} . These copper planes are duplicated in other layers to minimize the inductance and resistance. All the control signals are routed from the SiC620R and SiC620AR to a controller placed to the north of the power stage through inner layers to avoid the overlap of high current loops. This achieves a compact design with the output from the inductors feeding a load located to the south of the design as shown in the figure.

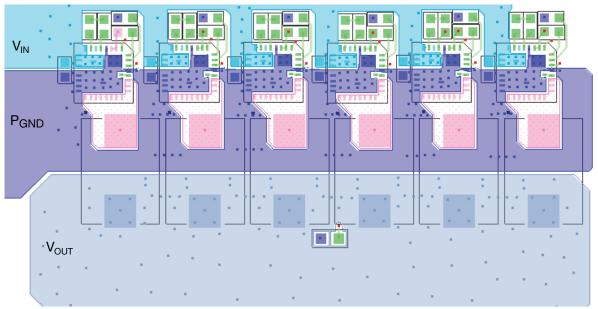


Fig. 29 - Multi-Phase VRPower Layout Top View

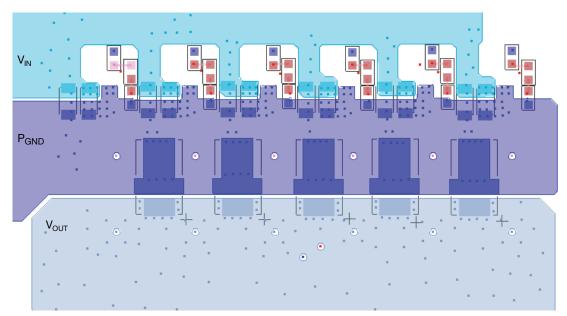


Fig. 30 - Multi-Phase VRPower Layout Bottom View

SiC620R, SiC620AR



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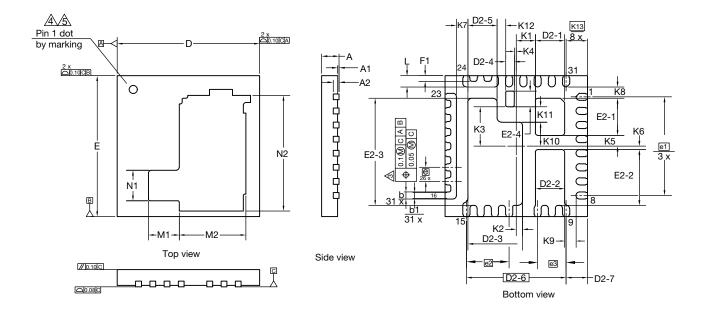
Document Number: 63589

PRODUCT SUMMARY		
Part number	SiC620R	SiC620AR
Description	60 A power stage, 4.5 V _{IN} to 18 V _{IN} , 5 V PWM with ZCD mode, dual side cooling	60 A power stage, 4.5 V_{IN} to 18 V_{IN} , 3.3 V PWM with ZCD mode, dual side cooling
Input voltage min. (V)	4.5	4.5
Input voltage max. (V)	18	18
Continuous current rating max. (A)	60	60
Switch frequency max. (kHz)	1500	1500
Enable (yes / no)	Yes	Yes
Monitoring features	-	-
Protection	UVLO, THDN	UVLO, THDN
Light load mode	ZCD	ZCD
Pulse-width modulation (V)	5	3.3
Package type	PowerPAK MLP55-31L double cooling	PowerPAK MLP55-31L double cooling
Package size (W, L, H) (mm)	5.0 x 5.0 x 0.60	5.0 x 5.0 x 0.60
Status code	2	2
Product type	VRPower (DrMOS)	VRPower (DrMOS)
Applications	Computer, industrial, networking	Computer, industrial, networking

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PowerPAK[®] MLP55-31L Double Cooling Case Outline (for SiC620R)



DIM.		MILLIMETERS			INCHES		
DINI.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	
A ⁽⁷⁾	0.56	0.61	0.66	0.022	0.024	0.026	
A1	0.00	-	0.05	0.000	-	0.002	
A2		0.20 ref.			0.008 ref.		
b ⁽³⁾	0.20	0.25	0.30	0.008	0.010	0.012	
b1	0.15	0.20	0.35	0.006	0.008	0.014	
D	4.90	5.00	5.10	0.193	0.197	0.201	
е		0.50 BSC			0.019 BSC		
E	4.90	5.00	5.10	0.193	0.197	0.200	
e1	3.50 BSC 0.138				0.138 BSC		
e2	1.50 BSC			0.059 BSC			
e3		1.00 BSC	0 BSC 0.039 BSC				
L	0.35	0.40	0.45	0.014	0.016	0.018	
D2-1	0.98	1.03	1.08	0.039	0.041	0.043	
D2-2	0.98	1.03	1.08	0.039	0.041	0.043	
D2-3	1.87	1.92	1.97	0.074	0.076	0.078	
D2-4	0.25	0.30	0.35	0.010	0.012	0.014	
D2-5	0.98	1.03	1.08	0.039	0.041	0.043	
D2-6		3.50 BSC			0.138 BSC		
D2-7	0.70	0.75	0.80	0.028	0.030	0.032	
E2-1	1.27	1.32	1.37	0.050	0.052	0.054	
E2-2	1.93	1.98	2.03	0.076	0.078	0.080	
E2-3	3.75	3.80	3.85	0.148	0.150	0.152	
E2-4	0.50	0.55	0.60	0.020	0.022	0.024	
F1	0.15	0.20	0.25	0.006	0.008	0.010	

Revision: 11-Dec-17

Document Number: 75766

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Package Information



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DIM		MILLIMETERS			INCHES		
DIM.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	
K1		0.67 ref.			0.026 ref.		
K2		0.22 ref.			0.009 ref.		
K3		1.40 ref.			0.006 ref.		
K4		0.07 ref.			0.003 ref.		
K5		0.38 ref.			0.015 ref.		
K6		0.12 ref.			0.005 ref.		
K7		0.40 ref.		0.016 ref.			
K8		0.40 ref.		0.016 ref.			
K9		0.40 ref.		0.016 ref.			
K10		0.85 ref.		0.033 ref.			
K11		0.55 ref.		0.022 ref.			
K12		0.30 ref.	of. 0.012 ref.				
K13		0.75 ref.			0.030 ref.		
M1	1.08 ref.				0.043 ref.		
M2	2.34 ref.		ef. 0.092 ref.				
N1	1.08 ref.				0.043 ref.		
N2	4.10 ref. 0.161 ref.						

DWG: 6060

Notes

1. Use millimeters as the primary measurement

2. Dimensioning and tolerances conform to ASME Y14.5M. - 1994

4. Dimension b applies to plated terminal and is measured between 0.20 mm and 0.25 mm from terminal tip

5. The pin #1 identifier must be existed on the top surface of the package by using indentation mark or other feature of package body

6. Exact shape and size of this feature is optional

7. Package warpage max. 0.08 mm

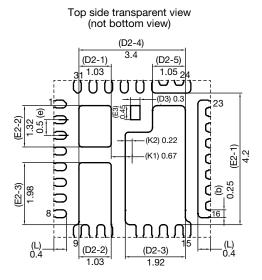
8. Applied only for terminals

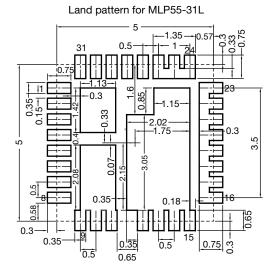


PAD Pattern

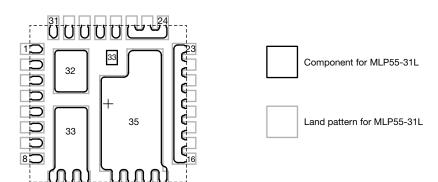
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Recommended Land Pattern PowerPAK[®] MLP55-31L





All dimensions in millimeters





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