## LM53600MAEVM and LM53601MAEVM

# **User's Guide**



Literature Number: SNAU190 December 2015



## **Contents**

1	Intro	oduction	3	
2	Setup			
	2.1	Jumper Options	4	
	2.2	Test Points and Connectors	5	
	2.3	Changing Output Voltage	5	
	2.4	Quick Start	5	
3	Ope	rating Curves	6	
		<b>1</b>	7	
		out	8	
6	Schematic			



### Introduction

The LM53600/01 Evaluation Module helps a designer evaluate the operation and performance of the LM53600/01 wide input voltage automotive Buck regulator. This board enables the user to test external synchronization, RESET/Power Good output, precision enable, and operation in both Auto mode for high efficiency at light load and FPWM mode which maintains a constant frequency while lightly loaded. Both the EN and SYNC/MODE pins are rated for operation up to 36 V with excursions to 42 V. Please refer to the LM53600/01 datasheet for more information.

Note that there is a separate EVM for fixed output versions of the LM53600/01 which can be found at <a href="https://www.Tl.com/product/lm53601-q1">www.Tl.com/product/lm53601-q1</a>.

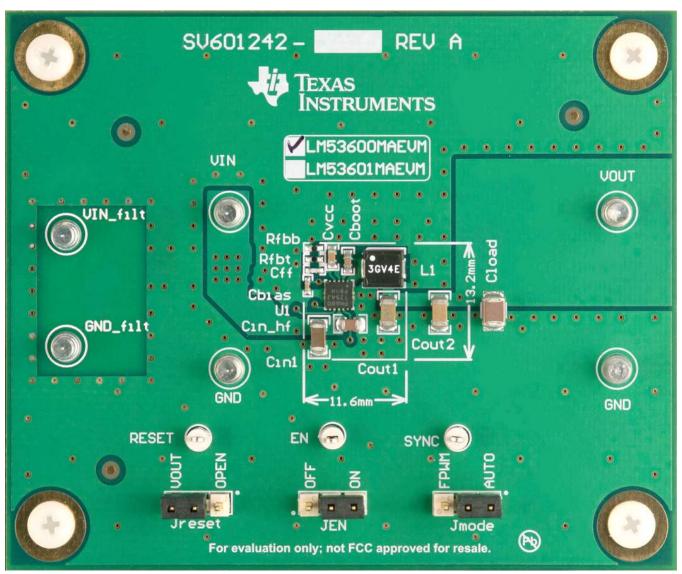


Figure 1-1. LM53600MAEVM



### Setup

Both the LM53600MAEVM and LM53601MAEVM are ready to operate. There are two sets of input terminals. The first pair, labeled VIN\_filt and GND\_filt, connects the power source to the LM53600/01 regulator through and EMI filter. The second set of terminals, labeled VIN and GND, connects the power source directly to the LM53600/01, bypassing the EMI filter. Output terminals are labeled VOUT and GND.

There are three connectors that are used in order to control the LM53600/01. A jumper can be connected on each of these connectors. Refer to the schematic in this document for details on the connection of these jumpers.

#### 2.1 Jumper Options

Designator	LM53600/01 Function	Jumper Position	Result
		VOUT	Pulls up RESET output to VOUT through a 100 kΩ resistor. Since RESET output is open drain, pull up is necessary to observe operation.
Jreset	RESET output	OPEN	RESET output pull-up disconnected: A user can connect to pull-up source of her/his choice (< 6 V) through RESET TP with a pull-up resistor in series limiting current when RESET pin goes low.
JEN	Enable	ON	Connects EN to VIN through a 100 k $\Omega$ resistor: Enables the part.
JLIN		OFF	Connects EN to GND through a 100 $k\Omega$ resistor: Disables the part.
		AUTO	Connects SYNC/MODE pin to ground through a 100 kΩ resistor activating Auto mode. During Auto mode, the part lowers frequency while lightly loaded to increase efficiency, diode emulation active.
Jmode	FPWM / Auto modes	FPWM	Connects SYNC/MODE pin to VIN through a 100 k $\Omega$ resistor activating FPWM mode. The part operates without diode emulation and does not reduce frequency under light load. Note that since there is also a 100 k $\Omega$ resistor to ground there will be leakage – remove Rsync to eliminate this leakage.



#### 2.2 Test Points and Connectors

Group	Purpose	Marking	Position
EMI filter power	Apply power here for testing that involves	VIN_filt	Turret type located on the left side of the board
input	filtered ripple testing such as conducted EMI testing	GND_filt	Turret type located on the left side of the board
Unfiltered power	Apply power here when testing only	VIN	Turret type located near the center of the board
input	concerns properties of the Buck regulator of theLM53600/01 on this board.	GND	Turret type located near the center of the board
Power output	This pair connects to the ouput of the	VOUT	Turret type located on the right side of the board
1 ower output	LM53600/01	GND	Turret type located on the right side of the board
Reset TP	Connects directly to the LM53600/01's RESET output. Use this TP to monitor the state of RESET. A user can connect to pull-up source of her/his choice (< 6 V) with a pull-up resistor in series limiting current when RESET pin goes low.	RESET	Loop type located on the lower left side of the board
Enable TP	Connects directly to the LM53600/01 EN input. Use this TP to monitor the voltage on EN or apply voltage to EN.	EN	Loop type located on the lower center of the board
Sync TP	Connects directly to the LM53600/01 SYNC/MODE input. Use this TP to monitor the voltage on SYNC/MODE or apply voltage to SYNC/MODE. Note that a when synchronizing the LM53600/01 to an external clock, the clock should be applied to this TP not at Jmode since the $100~k\Omega$ protection resistor, Rmode, will slow a clock signal applied through Jmode. Also note that this node has a $100~k\Omega$ pull down resistor, Rsync, making Auto mode this board's default. This resistor may be removed if a high value pull down is not desirable.	SYNC	Loop type located on the lower right side of the board

#### 2.3 Changing Output Voltage

Boards are initially set for 3.6 V output. If a different output voltage is desired, different feedback resistors are needed. Values for these resistors can be found as follows:

- 1. Choose RFBT: Normally a value close to 100 k $\Omega$  is chosen for RFBT. Boards come with 100 k $\Omega$  installed.
- 2. Find RFBB value: Use Equation 1.

$$R_{FBB} = \frac{R_{FBT} \times V_{REF}}{V_{OUT} - V_{REF}}$$
(1)

VREF is 1 V.

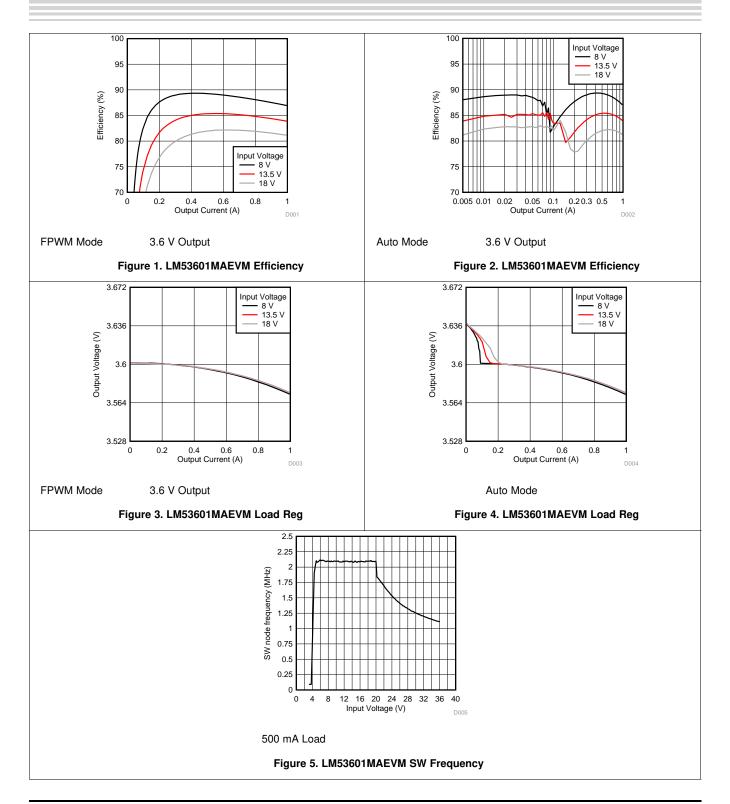
Note that if output voltage is greater than 4.2 V, L1 should be replaced with a 6.8  $\mu$ H inductor. Boards are shipped with a 4.7  $\mu$ H inductor. Also, if output voltage greater than 4.2 V is selected, output capacitance should be at least 30  $\mu$ F. Boards are shipped with 42  $\mu$ F of output capacitance.

#### 2.4 Quick Start

Connect the power supply to either the VIN\_filt, GND\_filt terminal pair or the VIN, GND terminal pair. The only jumper that need be installed is on JEN and should be in the ON position as marked on the board. The default mode of operation is normal or *Auto* mode (Light load mode enabled; see data sheet).



## **Operating Curves**





## **BOM**

Table 4-1. BOM for LM53600MAEVM

Designator	Qty	Value	Description	Part Number
Cbias 1 0.01 μF CAP, CERM, (		0.01 μF	CAP, CERM, 0.01 μF, 16 V, ±10%, X7R, 0402	C1005X7R1C103K050BA
Cboot 1 0.1 μF CAP, CERM, 0.1 μF,		CAP, CERM, 0.1 μF, 50 V, ±10%, X7R, 0603	GCM188R71H104KA57D	
		1 μF	CAP, CERM, 1 μF, 25 V, ±10%, X7R, AEC-Q200 Grade 1, 1206	GCM31MR71E105KA37L
Cff	1	100 pF	CAP, CERM, 100 pF, 25 V, ±5%, C0G/NP0, 0402	GCM31MR71E105KA37L
Cfilt, Cin_hf	2	0.1 μF	CAP, CERM, 0.1 μF, 100 V, ±10%, X7R, 0805	C2012X7R2A104K125AA
Cin1, Cin2	2	4.7 μF	CAP, CERM, 4.7 μF, 50 V, ±10%, X7R, 1206	GRM31CR71H475KA12L
Cload	1	22 μF	CAP, CERM, 22 μF, 16 V, ±20%, X7R, AEC-Q200 Grade 1, 1210	CGA6P1X7R1C226M250AC
Cout1, Cout2	2	10 μF	CAP, CERM, 10 μF, 16 V, ±10%, X7R, 1206	GRM31CR71C106KAC7L
Cvcc	1	1 μF	CAP, CERM, 1 μF, 16 V, ±10%, X7R, AEC-Q200 Grade 1, 0603	GCM188R71C105KA64D
H1, H2, H3, H4				NY PMS 440 0025 PH
H5, H6, H7, H8	4		Standoff, Hex, 0.5"L #4-40 Nylon	1902C
JEN, Jmode, Jreset	3		Header, 100 mil, 3x1, Gold, TH	HTSW-103-07-G-S
L1	1	4.7 μΗ	Inductor, Shielded, 4.7 μH, 2.3 A, 0.092 Ω, SMD	MPI4040R3-4R7-R
Lfilt	1	600 Ω	Ferrite Bead, 600 Ω @ 100 MHz, 3 A, 1210	FBMH3225HM601NT
Rd	1	4.99	RES, 4.99, 1%, 0.1 W, 0603	CRCW06034R99FKEA
REN, Rmode, Rreset, Rsync	4	100k	RES, 100 k, 1%, 0.1 W, 0603	CRCW0603100KFKEA
Rfbb	1	38.3k	RES, 38.3 k, 1%, 0.063 W, 0402	CRCW040238K3FKED
Rfbt	1	100k	RES, 100 k, 1%, 0.063 W, 0402	CRCW0402100KFKED
SH-J1, SH- J2, SH-J3	3	1x2	Shunt, 100 mil, Gold plated, Black	969102-0000-DA
TP1, TP2, TP3, TP4, TP5, TP6	6	Double	Terminal, Turret, TH, Double	1502-2
TP7, TP8, TP9	3	White	Test Point, Miniature, White, TH	5002
		Synchronous Buck Regulator for 650-mA Space Constraint Applications, DSX0010A, 3.3-V Output	LM53600MQDSXRQ1	

#### Table 4-2. LM53601MAEVM Differences from LM53600MAEVM

Designator	Qty	Value	Description	Part Number
U1	1		Synchronous Buck Regulator for 1000 mA Space Constraint Applications, DSX0010A, 5-V Output	LM53601MQDSXRQ1



## Layout

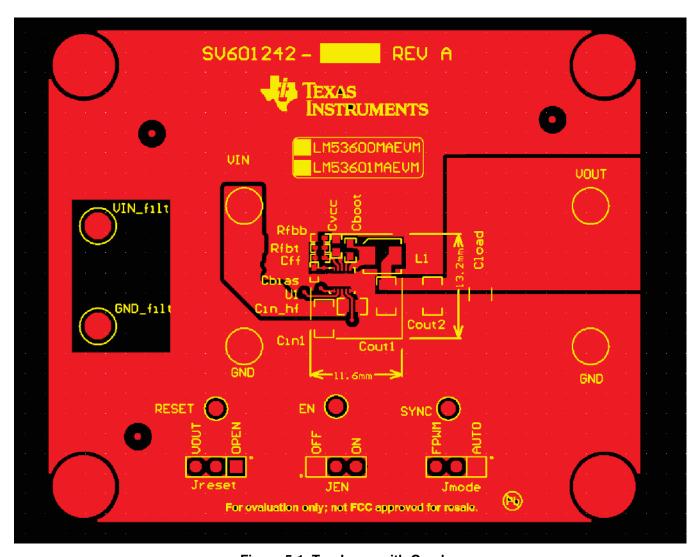


Figure 5-1. Top Layer with Overlay





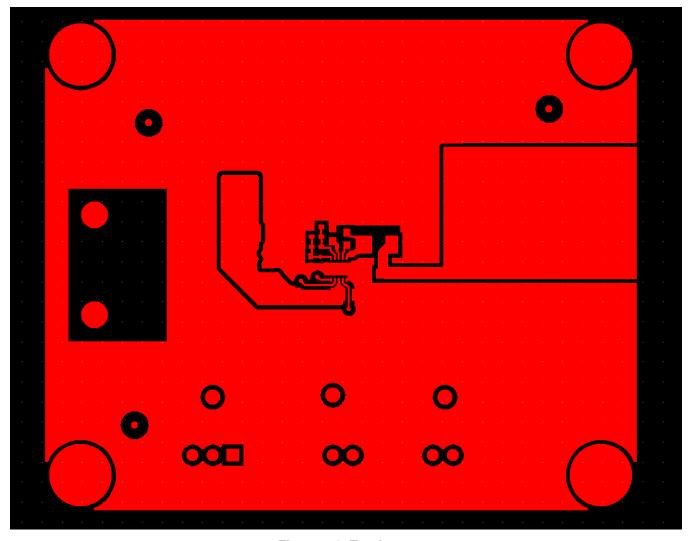


Figure 5-2. Top Layer



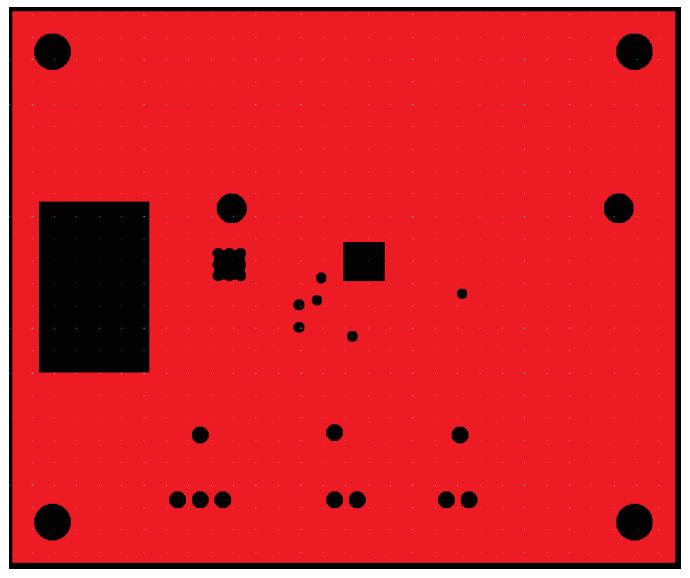


Figure 5-3. Ground Plane (Layer 2)





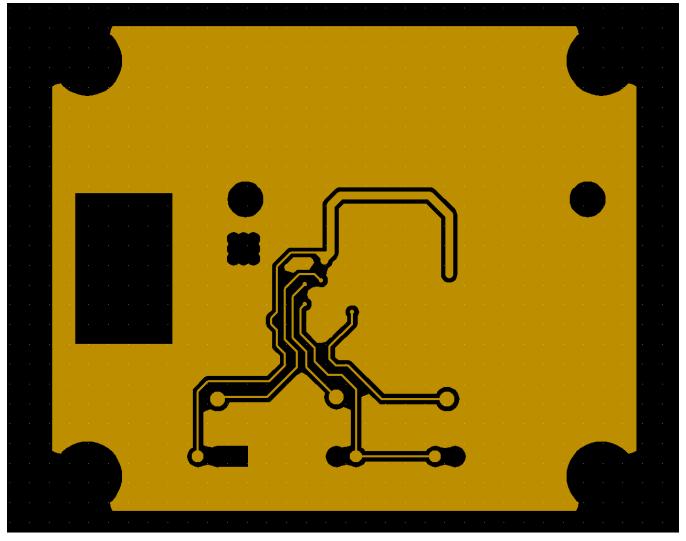


Figure 5-4. Mid Layer (Layer 3)



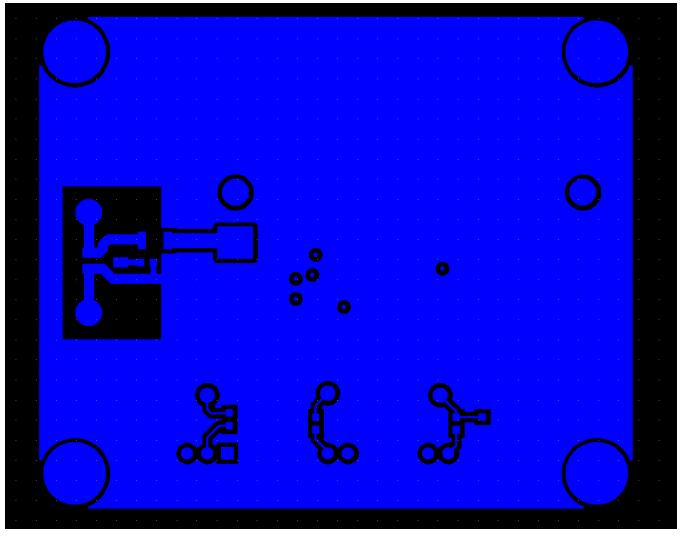


Figure 5-5. Bottom Layer (X-Ray)



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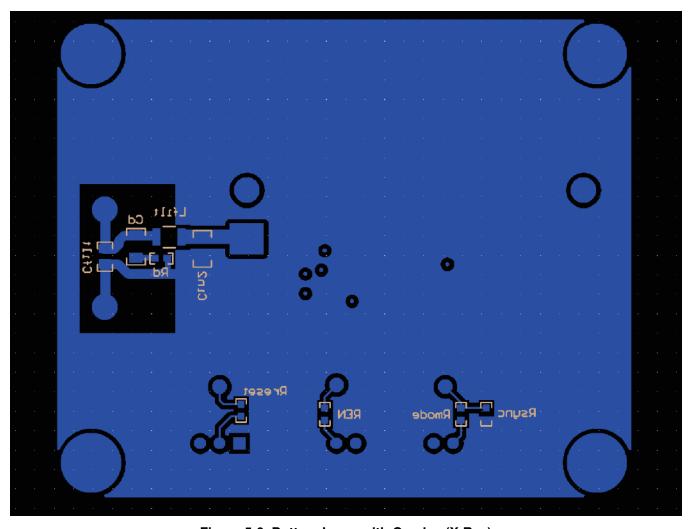
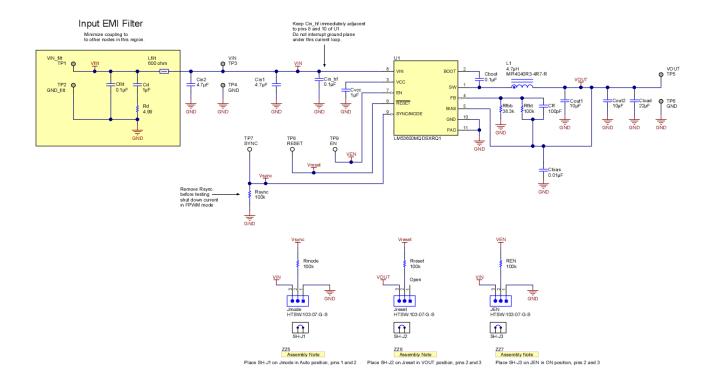


Figure 5-6. Bottom Layer with Overlay (X-Ray)



## Schematic



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This kit is designed to allow product developers to evaluate electronic components, circuitry, or software associated with the kit to determine whether to incorporate such items in a finished product and software developers to write software applications for use with the end product. This kit is not a finished product and when assembled may not be resold or otherwise marketed unless all required FCC equipment authorizations are first obtained. Operation is subject to the condition that this product not cause harmful interference to licensed radio stations and that this product accept harmful interference. Unless the assembled kit is designed to operate under part 15, part 18 or part 95 of this chapter, the operator of the kit must operate under the authority of an FCC license holder or must secure an experimental authorization under part 5 of this chapter.

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#### **CAUTION**

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

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- · Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- · Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

#### 3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210

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This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

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Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

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