

## **General Description**

The MAX5407 SOT-PoT™ is a logarithmic taper digital potentiometer with 32 tap points that has 1dB steps between taps. This device is ideal for audio applications, such as volume control and fading/balancing audio signals.

The MAX5407 consists of a resistor string and CMOS switches that are digitally controlled through a simple 2wire serial interface. This device performs the same function as a mechanical potentiometer. The device has a fixed end-to-end resistance of  $20k\Omega$  and features zero-crossing detection to minimize the audible noise generated by the wiper transitions.

This device has nominal resistor temperature coefficients of 35ppm/°C end-to-end and 5ppm/°C ratiometric. The MAX5407 is available in a space saving 8-pin SOT23 package and is guaranteed from -40°C to +85°C.

## **Applications**

Audio Volume Control Fading/Balancing Audio Signals Mechanical Potentiometer Replacement

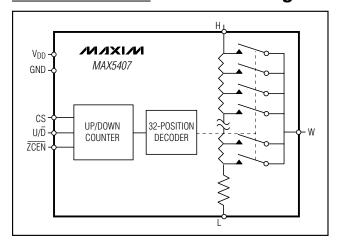
#### **Features**

- ♦ Miniature 3mm x 3mm 8-Pin SOT23 Package
- ♦ Logarithmic Taper with 1dB Steps Between Taps
- ♦ 32 Tap Positions
- ♦ Low 0.35µA Supply Current
- ♦ +2.7V to +5.5V Single-Supply Operation
- **♦** Zero-Crossing Detection to Minimize Audible **Clicks During Wiper Transitions**
- ♦ Simple Up/Down 2-Wire Serial Data Interface
- ♦ Power-On Reset **Wiper Goes To Maximum Attenuation** (Lowest Tap Position)
- ♦ 20kΩ End-to-End Resistance

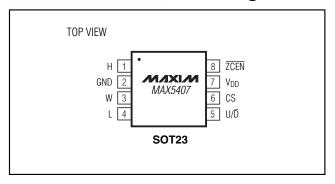
# **Ordering Information**

| PART       | TEMP. RANGE    | PIN-<br>PACKAGE | TOP MARK |  |
|------------|----------------|-----------------|----------|--|
| MAX5407EKA | -40°C to +85°C | 8 SOT23         | AAID     |  |

## Functional Diagram



# **Pin Configuration**



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## **ABSOLUTE MAXIMUM RATINGS**

| V <sub>DD</sub> to GND0.3V to +   | ·6V |
|---|-----|
| H, W, L, CS, $\overline{ZCEN}$ , and U/ $\overline{D}$ to GND0.3V to (V <sub>DD</sub> + 0.3 | 3V) |
| Input and Output Latchup Immunity±200r  | mΑ  |
| Maximum Continuous Current into H, L, and W±500   | μΑ  |
| Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )                                       |     |
| 8-Pin SOT23-8 (derate 8.9mW/°C above +70°C)714n   | nW  |

| Operating Temperature Range            | 40°C to +85°C  |
|--|----------------|
| Junction Temperature                   | +150°C         |
| Storage Temperature Range              | 65°C to +150°C |
| Soldering Temperature (soldering, 10s) | +300°C         |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## **ELECTRICAL CHARACTERISTICS**

 $(V_{DD} = +2.7V \text{ to } +5.5V, V_H = V_{DD}, V_L = 0, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5V \text{ and } T_A = +25^{\circ}C.)$  (Note 1)

| PARAMETER                                      | SYMBOL          | CONDITIONS  | MIN | TYP   | MAX  | UNITS  |
|--|-----------------|---|-----|-------|------|--------|
| Number of Resistor Taps                        |                 |   | 32  |       |      | Taps   |
| End-to-End Resistance                          |                 |   | 15  | 20    | 25   | kΩ     |
| Bandwidth (Note 2)                             |                 | (Notes 3, 4)  |     | 500   |      | kHz    |
| Absolute Tolerance (Note 5)                    |                 | (Note 3)  |     | ±0.25 | ±1   | dB     |
| Tap-to-Tap Tolerance (Note 6)                  |                 | (Note 3)  |     | ±0.05 | ±0.1 | dB     |
| Total Harmonic Distortion + Noise              | THD + N         | $V_{IN} = 1V_{RMS}$ , $f = 1kHz$ ,<br>Tap = -6dB (Notes 3, 4) |     | 0.002 |      | %      |
| Power-Supply Rejection Ratio                   | PSRR            |   |     | -80   |      | dB     |
| End-to-End Resistance Temperature Coefficient  | TCR             |   |     | 35    |      | ppm/°C |
| Ratiometric Resistance Temperature Coefficient |                 |   |     | 5     |      | ppm/°C |
| Wiper Resistance                               | Rw              | $V_{DD} = 2.7V$   |     | 400   | 1700 | Ω      |
| DIGITAL INPUTS                                 |                 |   |     |       |      |        |
| Input High Voltage                             | V <sub>IH</sub> |   | 2.4 |       |      | V      |
| Input Low Voltage                              | V <sub>IL</sub> |   |     |       | 0.8  | V      |
| Input Leakage Current                          |                 |   |     |       | ±1   | μΑ     |
| Input Capacitance                              |                 |   |     | 5     |      | рF     |
| TIMING CHARACTERISTICS (Fig                    | gures 1, 2)     |   |     |       |      |        |
| U/D Mode to CS Setup                           | tcu             |   | 25  |       |      | ns     |
| CS to U/D Step Setup                           | tcı             |   | 25  |       |      | ns     |
| CS to U/D Step Hold                            | tIC             |   | 25  |       |      | ns     |
| U/D Step Low Period                            | tıL             |   | 25  |       |      | ns     |
| U/D Step High Period                           | tıH             |   | 25  |       |      | ns     |
| Up/Down Toggle Rate                            | fTOGGLE         |   |     |       | 7    | MHz    |
| Wiper Switching Time                           | t <sub>IW</sub> | Zero-crossing detection disabled (Note 4)                     |     | 0.1   | _    | μs     |
| Zero-Crossing Timeout                          |                 |   |     | 50    |      | ms     |

## **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = +2.7V \text{ to } +5.5V, V_{H} = V_{DD}, V_{L} = 0, T_{A} = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5V \text{ and } T_{A} = +25^{\circ}\text{C.})$  (Note 1)

| PARAMETER      | SYMBOL          | MBOL CONDITIONS   |                  | MIN | TYP  | MAX | UNITS |
|----------------|-----------------|---|------------------|-----|------|-----|-------|
| POWER SUPPLIES |                 |   |                  |     |      |     |       |
| Supply Voltage | V <sub>DD</sub> |   |                  | 2.7 |      | 5.5 | V     |
| Supply Current | I <sub>DD</sub> | All digital inputs are set to 0 Active (Note 7)  Standby (Note 8) |                  | 100 |      |     |       |
|                |                 |   | Standby (Note 8) |     | 0.35 | 1   | - μA  |

Note 1: All devices are 100% production tested at  $T_A = +25^{\circ}C$  and guaranteed by design for  $T_A = T_{MIN}$  to  $T_{MAX}$ .

Note 2: Bandwidth is measured from H to W at the -6dB wiper tap position (see Typical Operating Characteristics).

Note 3: These specifications are only valid for ly less than 100nA of continuous wiper current.

Note 4: Measured with 20pF load capacitor.

Note 5: Absolute tolerance is defined as the variation of the attenuation for any given tap from its expected value.

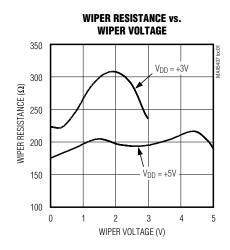
Note 6: Tap-to-tap tolerance is defined as the variation between any two adjacent taps from the typical value of 1dB.

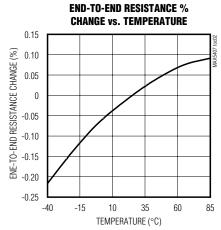
**Note 7:** Supply current when f<sub>TOGGLE</sub> = 2MHz.

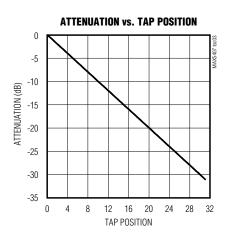
Note 8: Supply current when wiper position is not changing.

# Typical Operating Characteristics

 $(V_{DD} = +5V, T_A = +25^{\circ}C, unless otherwise noted.)$ 

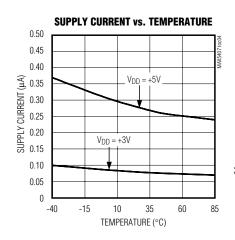


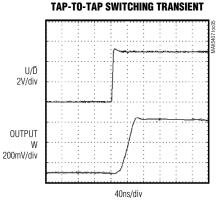


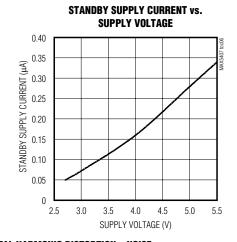


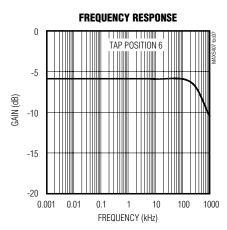
# **Typical Operating Characteristics (continued)**

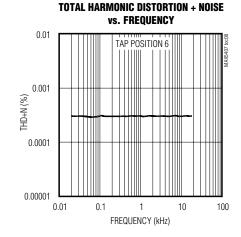
 $(V_{DD} = +5V, T_A = +25^{\circ}C, unless otherwise noted.)$ 











# **Pin Description**

| PIN | NAME     | FUNCTION   |  |  |  |
|-----|----------|--|--|--|--|
| 1   | Н        | High Terminal of Resistor  |  |  |  |
| 2   | GND      | Ground   |  |  |  |
| 3   | W        | Wiper Terminal of Resistor   |  |  |  |
| 4   | L        | Low Terminal of Resistor   |  |  |  |
| 5   | U/D      | Up/Down Control Input. With CS high, a low-to-high transition increments or decrements the wiper position, depending on the mode.                |  |  |  |
| 6   | CS       | Chip-Select Input. A low-to-high CS transition determines the mode: increment if $U/\overline{D}$ is high, decrement if $U/\overline{D}$ is low. |  |  |  |
| 7   | $V_{DD}$ | Power Supply   |  |  |  |
| 8   | ZCEN     | Zero-Crossing Detection Enable Input. Set to low to enable zero-crossing detection.  |  |  |  |

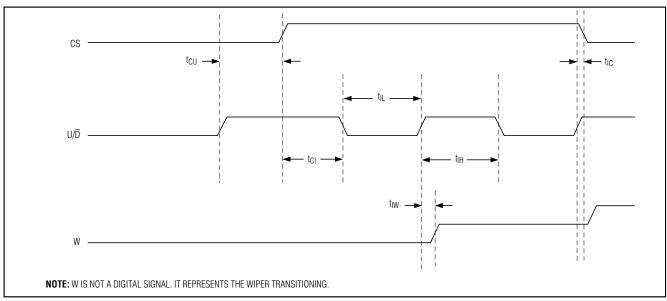


Figure 1. Serial Interface Timing Diagram, Increment Mode

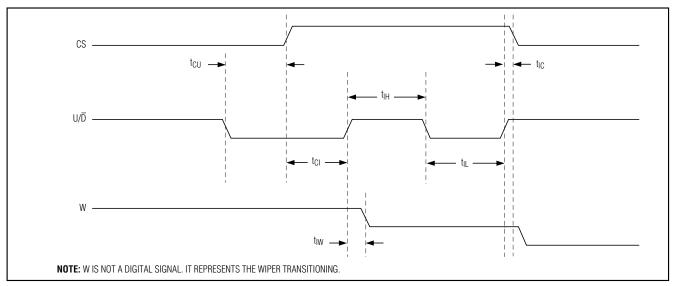


Figure 2. Serial Interface Timing Diagram, Decrement Mode

# \_Detailed Description

#### **Digital Interface Operation**

The MAX5407 has two modes of operation when the serial interface is active: increment and decrement mode. The serial interface is only active when CS is high.

The CS and  $U/\overline{D}$  inputs control the position of the wiper along the resistor array. When CS transitions from low to high, the part will go into increment mode if  $U/\overline{D}$  is

high and into decrement mode if  $U/\overline{D}$  is low. Once the mode is set, the device will remain in that mode until CS goes low again. A low-to-high transition at the  $U/\overline{D}$  pin will increment or decrement the wiper position depending on the mode (Figures 1 and 2).

When the CS input transitions to low (serial interface inactive), the value of the counter is stored and the wiper position is maintained.

#### **Power-On Reset**

The power-on reset feature sets the wiper to the maximum attenuation (tap position 31, -31dB) at power-up. If CS is initially high, the MAX5407 is in the increment mode by default.

#### **Zero-Crossing Detection**

When the  $\overline{\text{ZCEN}}$  input is low, the zero-crossing detect feature is enabled. This feature reduces the audible noise ("clicks and pops") that result from wiper transitions. When zero-crossing detection is enabled, the wiper changes position only when the voltage at L is the same as the voltage at H. If no zero crossing is detected after 50ms, the device will timeout and change the wiper position.

#### **Digital Logic Inputs**

The MAX5407 can interface to +3V logic as well as +5V logic, while using a +3V to +5V power supply. In order to minimize the supply current, set all digital inputs low while the part is inactive.

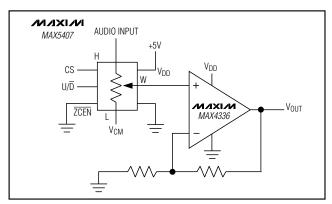


Figure 3. Volume Control Circuit

# MAX5407 SIGNAL INPUT CS U/D VDD VDD VDD VOUT MAX4336 VOUT

Figure 4. Signal Attenuator Circuit

# **Applications Information**

The MAX5407 is intended for circuits requiring digitally controlled adjustable voltage or adjustable gain, such as applications involving volume control.

#### **Volume Control**

The zero-crossing feature of the MAX5407 makes it ideal for applications involving volume control. Figure 3 shows a typical application circuit, where the MAX5407 is followed by an op amp for output buffering and gain. VCM represents the common voltage around which the audio signal swings.

#### Signal Attenuator

Figure 4 shows a typical signal attenuator. Use an op amp to provide buffering and gain to the output of the MAX5407. Connect the MAX5407 to the positive input of a noninverting op amp to select the level of attenuation of the input signal, by digitally controlling the wiper terminal.

#### Adjustable Gain

Figure 5 shows how to use the MAX5407 to digitally adjust the gain of a noninverting op amp configuration. The MAX5407 has a low 5ppm/°C ratiometric tempco that allows for a very stable adjustable gain configuration over temperature.

## Chip Information

TRANSISTOR COUNT: 1942

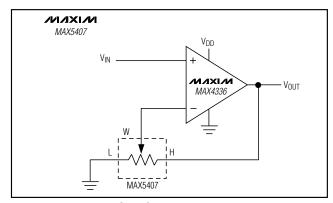
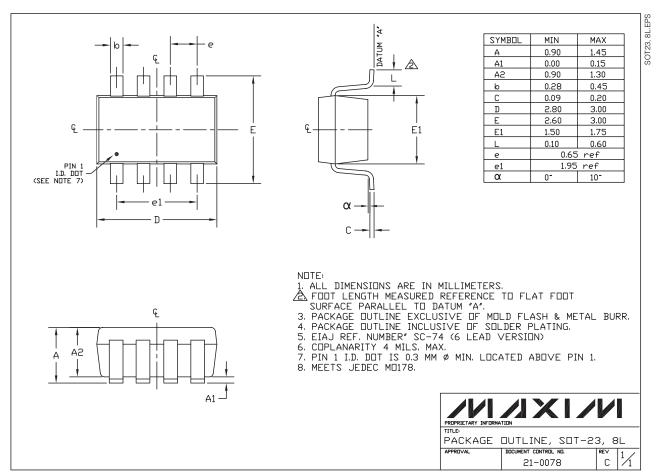


Figure 5. Adjustable Gain Circuit

# **Package Information**



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