

LMC6442 Dual Micropower Rail-to-Rail Output Single Supply Operational Amplifier

Check for Samples: [LMC6442](http://www.ti.com/product/lmc6442#samples)

- **•** (Typical, $V_s = 2.2V$)
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- **Low Supply Current 0.95 µA/Amplifier**
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¹FEATURES DESCRIPTION

The LMC6442 is ideal for battery powered systems, where very low supply current (less than one **• Output Swing to Within 30 mV of Supply Rail** microamp per amplifier) and Rail-to-Rail output swing is required. It is characterized for 2.2V to 10V Gain Bandwidth Product 9.5 KHz **• Cain Bandwidth Product 9.5 KHz • Cancel Product 9.5 KHz • Case Registed** Product 9.5 KHz **Finsured for: 2.2V, 5V, 10V • The State of State of Single (Li-Ion)** or two cell (NiCad or alkaline) **•** battery systems.

The LMC6442 is designed for battery powered **• Input Voltage Range [−]0.3V to V⁺ Input voltage Range -0.3V to v -0.9V** systems that require long service life through low
2.1 **µW/Amplifier Power Consumption** supply current, such as smoke and gas detectors. supply current, such as smoke and gas detectors, **Stable for A_V ≥ +2 or A_V ≤ −1** \blacksquare **and pager or personal communications systems.**

Operation from single supply is enhanced by the wide **APPLICATIONS** common mode input voltage range which includes the **Portable Instruments • Portable Instruments • Portable Instruments • Portable Instruments • Portable Instruments** applications. Very low (5 fA, typical) input bias current
 Smoke/Gas/CO/Fire Detectors
 • Pagers/Cell Phones and near constant supply current over supply voltage

enhance the LMC6442's performance near the endenhance the LMC6442's performance near the end-**Instrumentation • Instrumentation • Instrumentation • Instrumentation**

• Thermostats • Thermostats *•* **Thermostats ***•* Designed for closed loop gains of greater than plus **Occupancy Sensors**
 Commus one), the amplifier has typically 9.5
 Commus Occupancy Sensors
 Commus Occupancy Sensors
 Commus Occupancy Sensors Cameras Cameras Cameras Fig. Cameras be used with a simple compensation circuit, which **Active Badges Active Badges Product Active Badges Product Active Badges Product Active Badges Product Active Badges • Active Badges** also allows capacitive loads of up to 300 pF to be driven, as described in the [Application Information](#page-11-0) section.

Connection Diagram

Top View \mathbf{v}^+ OILT A OUT B $-1N$ R \overline{N} R

Figure 1. 8-Pin SOIC / PDIP Package See Package Numbers D0008A, P0008E

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

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Absolute Maximum Ratings (1)(2)

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.

- If Military/Aerospace specified devices are required, please contact the TI Sales Office/ Distributors for availability and specifications.
- (3) Human body model, 1.5 k Ω in series with 100 pF.
- (4) Limiting input pin current is only necessary for input voltages that exceed absolute maximum input voltage ratings.
- (5) Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C. Output currents in excess of ±30 mA over long term may adversely affect reliability.
- (6) Do not short circuit output to V⁺, when V⁺ is greater than 13V or reliability will be adversely affected.
- (7) The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} , and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D=$ (T_{J(MAX)} - T_A)/ θ_{JA} . All numbers apply for packages soldered directly into a PC board.

Operating Ratings (1)

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.

2.2V Electrical Characteristics

Unless otherwise specified, all limits ensured for T_J = 25°C, V⁺ = 2.2V, V⁻ = 0V, V_{CM} = V_O = V ⁺/2, and R_L = 1 MΩ to V⁺/2. **Boldface** limits apply at the temperature extremes.

(1) Typical Values represent the most likely parametric norm.

All limits are specified by testing or statistical analysis unless otherwise specified.

(3) Limits specified by design.

2.2V Electrical Characteristics (continued)

Unless otherwise specified, all limits ensured for T_J = 25°C, V⁺ = 2.2V, V⁻ = 0V, V_{CM} = V_O = V ⁺/2, and R_L = 1 MΩ to V⁺/2. **Boldface** limits apply at the temperature extremes.

(4) R_L connected to V⁺/2. For Sourcing Test, V_O > V⁺/2. For Sinking tests, V_O < V⁺/2.

 (5) V_{ID} is differential input voltage referenced to inverting input.

(6) Output shorted to ground for sourcing, and shorted to V+ for sinking short circuit current test.

(7) Slew rate is the slower of the rising and falling slew rates.

(8) See the [Typical Performance Characteristics](#page-5-0) and [Applications Information](#page-11-0) sections for more details.

5V Electrical Characteristics

Unless otherwise specified, all limits ensured for T_J = 25°C, V⁺ = 5V, V⁻ = 0V, V_{CM} = V_O = V ⁺/2, and R_L = 1 MΩ to V⁺/2. **Boldface** limits apply at the temperature extremes.

(1) Typical Values represent the most likely parametric norm.

(2) All limits are specified by testing or statistical analysis unless otherwise specified.

(3) Limits specified by design.

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5V Electrical Characteristics (continued)

Unless otherwise specified, all limits ensured for T_J = 25°C, V⁺ = 5V, V⁻ = 0V, V_{CM} = V_O = V ⁺/2, and R_L = 1 MΩ to V⁺/2. **Boldface** limits apply at the temperature extremes.

(4) R_L connected to V⁺/2. For Sourcing Test, V_O > V⁺/2. For Sinking tests, V_O < V⁺/2.

(5) V_{ID} is differential input voltage referenced to inverting input.

(6) Output shorted to ground for sourcing, and shorted to V+ for sinking short circuit current test.

(7) Slew rate is the slower of the rising and falling slew rates.

(8) See the [Typical Performance Characteristics](#page-5-0) and [Applications Information](#page-11-0) sections for more details.

10V Electrical Characteristics

Unless otherwise specified, all limits ensured for T_J = 25°C, V⁺ = 10V, V⁻ = 0V, V_{CM} = V_O = V ⁺/2, and R_L = 1 MΩ to V⁺/2. **Boldface** limits apply at the temperature extremes.

(1) Typical Values represent the most likely parametric norm. (2) All limits are specified by testing or statistical analysis unless otherwise specified.

Limits specified by design.

10V Electrical Characteristics (continued)

Unless otherwise specified, all limits ensured for T_J = 25°C, V⁺ = 10V, V⁻ = 0V, V_{CM} = V_O = V ⁺/2, and R_L = 1 MΩ to V⁺/2. **Boldface** limits apply at the temperature extremes.

(4) R_L connected to V⁺/2. For Sourcing Test, V_O > V⁺/2. For Sinking tests, V_O < V⁺/2.

(5) V_{ID} is differential input voltage referenced to inverting input.
(6) Output shorted to ground for sourcing, and shorted to V+ for sinking short circuit current test.

(7) Slew rate is the slower of the rising and falling slew rates.

(8) See the [Typical Performance Characteristics](#page-5-0) and [Applications Information](#page-11-0) sections for more details.
(9) Input referred, V⁺ = 10V and R_L = 10 MΩ connected to 5V. Each amp excited in turn with 1 KHz to produce about

NSTRUMENTS

Texas

Supply Voltage (V)

 $10k$

 1_k

100

 10

Ibias (A)

pply voltage (v) **Figure 4.** Fermetage of the set of the

Typical Performance Characteristics (continued)

$V_S = 5V$, Single Supply, $T_A = 25^{\circ}C$ unless otherwise specified

 $I_{SINK}(\mu A)$

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Output Voltage Referenced to GND (V)

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Typical Performance Characteristics (continued)

 $V_S = 5V$, Single Supply, $T_A = 25^{\circ}C$ unless otherwise specified

 $R_L = 100k$ $\overline{3}$ $\overline{4}$ $\sqrt{5}$ $\,6\,$ 78 9 10 11 12 Supply Voltage (V)

GBWP (kHz)

 $\boldsymbol{6}$

 $\boldsymbol{\Lambda}$

 $\sqrt{2}$

Typical Performance Characteristics (continued)

 $V_S = 5V$, Single Supply, $T_A = 25^{\circ}$ C unless otherwise specified

10 MΩ to GND

 $10k$

 $1k$

Source Channel Output Load =

 $\| \cdot \|$

100

Frequency (Hz)

 10

 $\overline{0}$

 $\mathbf{1}$

 $$

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5

Typical Performance Characteristics (continued) $V_S = 5V$, Single Supply, $T_A = 25^{\circ}C$ unless otherwise specified **Input Voltage Noise**
 VS.
 VS. vs. vs. Frequency

Frequency Frequency

Here the contract of the con $10k$ V_S $= \pm 5$ '= ±5V 160 150 140 V_{n} (nV/ \sqrt{Hz}) 130 $R_{\text{OUT}}(k\Omega)$ 120 1^k 110 100 90 80 70 100 60 0.01 0.1 $10\,$ 100 1_k 10 100 1_k $10k$ $\overline{1}$ Frequency (Hz) Frequency (Hz) **Figure 25. Figure 26. THD+N THD+N vs. vs. Frequency Amplitude** 20 $=1V_{PP}$ $f = 100$ Hz v_{out} 10 10 $±2.5V$ $= \pm 2.5V$ $\sqrt{2}$ A_{V} $= +2$ $A_V = +2$ ≒ 10м† $= 10M$ R THD+N $(%)$ $\mathbf{1}$ 0.1 0.1 0.01 0.01 20 100 1^k $10k$ 10_m 100m $\overline{1}$ Frequency (Hz) Output (V_{PP}) **Figure 27. Figure 28. Maximum Output Swing vs. Small Signal Step Response Frequency (A^V = +2) (C^L = 12 pF, 100 pF)** 10 Output $V_{\rm S}$ \top \top \top A_{V} 100 pF $\overline{9}$ †††∣тно+л` $\overline{\epsilon}$ $1%$ Output $= 10M\Omega$ to $\boldsymbol{8}$ R_{\parallel} V Inpu $\overline{7}$ $V_{OUT} (V_{PP})$ 50 mV/Div $\sqrt{6}$ $\frac{5}{2}$ 5 $\overline{4}$ $\overline{3}$ Ш $\boldsymbol{2}$ $C_{L} = 12 pF$ 2λ ٬s $\overline{1}$ $C_{L} = 100 pF$ रु $\pmb{0}$ 200 μ s/Div 10 100 $1k$ $10k$ Frequency (Hz)
Figure 29. Figure 30.

Typical Performance Characteristics (continued)

 $V_S = 5V$, Single Supply, $T_A = 25^{\circ}C$ unless otherwise specified

APPLICATIONS INFORMATION

USING LMC6442 IN UNITY GAIN APPLICATIONS

LMC6442 is optimized for maximum bandwidth and minimal external components when operating at a minimum closed loop gain of +2 (or −1). However, it is also possible to operate the device in a unity gain configuration by adding external compensation as shown in [Figure 35:](#page-11-1)

Figure 35. $A_V = +1$ Operation by adding C_C and R_C

Using this compensation technique it is possible to drive capacitive loads of up to 300 pF without causing oscillations (see the [Typical Performance Characteristics](#page-5-0) for step response plots). This compensation can also be used with other gain settings in order to improve stability, especially when driving capacitive loads (for optimum performance, R_C and C_C may need to be adjusted).

USING "T" NETWORK

Compromises need to be made whenever high gain inverting stages need to achieve a high input impedance as well. This is especially important in low current applications which tend to deal with high resistance values. Using a traditional inverting amplifier, gain is inversely proportional to the resistor value tied between the inverting terminal and input while the input impedance is equal to this value. For example, in order to build an inverting amplifier with an input impedance of 10MΩ and a gain of 100, one needs to come up with a feedback resistor of 1000 MΩ -an expensive task.

An alternate solution is to use a "T" Network in the feedback path, as shown in [Figure 36](#page-11-2).

Closed loop gain, A_V is given by:

$$
A_{V} = -\frac{R^{2}}{R^{2}} \cdot \left(\frac{2}{R} + \frac{1}{R^{1}}\right)
$$
\n
$$
V_{IN} \underbrace{\bigodot}_{10M} \underbrace{R^{2}}_{10M} \underbrace{\bigodot}_{10M} \underbrace{R^{2}}_{10M} \underbrace{\bigodot}_{10M} \underbrace{R^{2}}_{10M}
$$
\n
$$
V_{OUT}
$$
\n(1)

Figure 36. "T" Network Used to Replace High Value Resistor

It must be noted, however, that using this scheme, the realizable bandwidth would be less than the theoretical maximum. With feedback factor, β, defined as:

$$
\beta \approx \frac{R2}{R2 + R} \cdot \frac{R1}{R1 + R} \quad \text{for } R2 \gg R1
$$
\n
$$
BW(-3 dB) \approx GBWP \cdot \beta
$$
\n(2)

In this case, assuming a GBWP of about 10 KHz, the expected BW would be around 50 Hz (vs. 100 Hz with the conventional inverting amplifier).

(4)

Looking at the problem from a different view, with R_F defined by $A_V \bullet R$ in, one could select a value for R in the "T" Network and then determine R1 based on this selection:

$$
R 1 = \frac{R^2}{R_F - 2R}
$$

Figure 37. "T" Network Values for Various Values of R

For convenience, [Figure 37](#page-12-0) shows R1 vs. R_F for different values of R.

DESIGN CONSIDERATIONS FOR CAPACITIVE LOADS

As with many other opamps, the LMC6442 is more stable at higher closed loop gains when driving a capacitive load. [Figure 38](#page-13-0) shows minimum closed loop gain versus load capacitance, to achieve less than 10% overshoot in the output small signal response. In addition, the LMC6442 is more stable when it provides more output current to the load and when its output voltage does not swing close to V[−] .

The LMC6442 is more tolerant to capacitive loads when the equivalent output load resistance is lowered or when output voltage is 1V or greater from the V⁻ supply. The capacitive load drive capability is also improved by adding an isolating resistor in series with the load and the output of the device. [Figure 39](#page-13-1) shows the value of this resistor for various capacitive loads ($A_V = -1$), while limiting the output to less than 10 % overshoot.

Referring to the Typical Performance Characteristics plot of Phase Margin (Worst Case) vs. Supply Voltage, note that Phase Margin increases as the equivalent output load resistance is lowered. This plot shows the expected Phase Margin when the device output is very close to V⁻, which is the least stable condition of operation. Comparing this Phase Margin value to the one read off the Open Loop Gain/Phase vs. Frequency plot, one can predict the improvement in Phase Margin if the output does not swing close to V[−] . This dependence of Phase Margin on output voltage is minimized as long as the output load, R_L , is about 1M Ω or less.

Output Phase Reversal: The LMC6442 is immune against this behavior even when the input voltages exceed the common mode voltage range.

Output Time Delay: Due to the ultra low power consumption of the device, there could be as long as 2.5 ms of time delay from when power is applied to when the device output reaches its final value.

Figure 38. Minimum Operating Gain vs. Capacitive Load

Figure 39. Isolating Resistor Value vs Capacitive Load

Application Circuits

STRUMENTS

EXAS

 V^+ = 5V: I_S < 10 μ A, f/V_C = 4.3 (Hz/V)

$$
R1 \cong 4R4
$$

 $R2 = 2R3$ $f(Hz) = \frac{V_C}{3R_1C_1V^+ \left[\frac{R6}{R5+R6} - \frac{(R6||R7)}{(R6||R7)+R5}\right]}\approx \frac{V_C(R5+R6)}{3R_1C_1V^+(R6-R7)}$ for R5 >> R6 and R6 >> R7

Figure 40. Micropower Single Supply Voltage to Frequency Converter

Figure 41. Gain Stage with Current Boosting

PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check<http://www.ti.com/productcontent>for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

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Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

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(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

PACKAGE OPTION ADDENDUM

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⁽⁶⁾ Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

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PACKAGE MATERIALS INFORMATION

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*All dimensions are nominal

 $P (R-PDIP-T8)$

PLASTIC DUAL-IN-LINE PACKAGE

- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MS-001 variation BA.

 $D (R-PDSO-G8)$

PLASTIC SMALL OUTLINE

NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- 6 Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AA.

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