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LMP2231 Single

Micropower, 1.6V, Precision Operational Amplifier with CMOS Inputs

General Description

The LMP2231 is a single micropower precision amplifier designed for battery powered applications. The 1.6V to 5.5V operating supply voltage range and quiescent power consumption of only 16 μW extend the battery life in portable battery operated systems. The LMP2231 is part of the LMP® precision amplifier family. The high impedance CMOS input makes it ideal for instrumentation and other sensor interface applications.

The LMP2231 has a maximum offset of 150 μV and maximum offset voltage drift of only 0.4 $\mu V/^\circ C$ along with low bias current of only ±20 fA. These precise specifications make the LMP2231 a great choice for maintaining system accuracy and long term stability.

The LMP2231 has a rail-to-rail output that swings 15 mV from the supply voltage, which increases system dynamic range. The common mode input voltage range extends 200 mV below the negative supply, thus the LMP2231 is ideal for use in single supply applications with ground sensing.

The LMP2231 is offered in 5-Pin SOT23 and 8-pin SOIC packages.

The dual and quad versions of this product are also available. The dual, LMP2232 is offered in 8-pin SOIC and MSOP. The quad, LMP2234 is offered in 14-pin SOIC and TSSOP.

Features

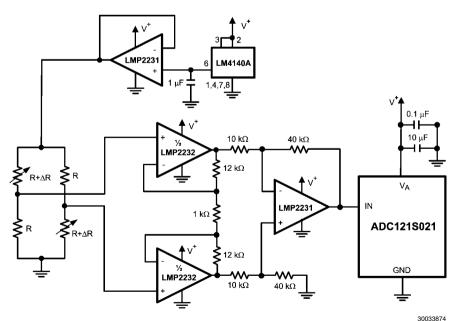
(For $V_S = 5V$, $T_A = 25^{\circ}C$, Typical unless otherwise noted)

Supply current -10 µA -Operating voltage range 1.6V to 5.5V $\pm 0.4 \ \mu V/^{\circ}C$ (max) TCV_{OS} (LMP2231A) TCV_{OS} (LMP2231B) $\pm 2.5 \mu V/^{\circ}C$ (max) ±150 µV (max) Vos Input bias current 20 fA PSRR 120 dB CMRR 97 dB Open loop gain 120 dB Gain bandwidth product 130 kHz Slew rate 58 V/ms Input voltage noise, f = 1 kHz 60 nV/√Hz Temperature range -40°C to 125°C

Applications

- Precision instrumentation amplifiers
- Battery powered medical instrumentation
 - High Impedance Sensors
 - Strain gauge bridge amplifier
 - Thermocouple amplifiers





Strain Gauge Bridge Amplifier

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Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for

Distributors for availability and specifications.		
ESD Tolerance (Note 2)		C
Human Body Model	2000V	
Machine Model	100V	Op
Differential Input Voltage	±300 mV	Sı

Differential Input Voltage	±300 mV
Supply Voltage ($V_S = V^+ - V^-$)	6V
Voltage on Input/Output Pins	V+ + 0.3V, V 0.3V
Storage Temperature Range	–65°C to 150°C

Junction Temperature (Note 3) For soldering specifications:

see product folder at www.national.com and www.national.com/ms/MS/MS-SOLDERING.pdf

Operating Ratings (Note 1)

Operating Temperature Range (Note 3)	–40°C to 125°C
Supply Voltage (V _S = V ⁺ - V ⁻)	1.6V to 5.5V
Package Thermal Resistance (θ_{JA}) (Note 3)	
5-Pin SOT23	160.6 °C/W
8-Pin SOIC	116.2 °C/W

5V DC Electrical Characteristics (Note 4) Unless otherwise specified, all limits guaranteed for $T_A = 25^{\circ}$ C, $V_{+} = 5V$, $V_{-} = 0V$, $V_{-} = V_{+}/2$ and $R_{-} > 1$ MO **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
V _{OS}	Input Offset Voltage			±10	±150 ±230	μV
TCV _{OS}	Input Offset Voltage Drift	LMP2231A		±0.3	±0.4	
		LMP2231B		±0.3	±2.5	μV/°C
I _{BIAS}	Input Bias Current			0.02	±1 ±50	pА
I _{OS}	Input Offset Current			5		fA
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 4V$	81 80	97		dB
PSRR	Power Supply Rejection Ratio	$1.6V \le V_{+} \le 5.5V$ $V^{-} = 0V, V_{CM} = 0V$	83 83	120		dB
CMVR	Common Mode Voltage Range	CMRR ≥ 80 dB CMRR ≥ 79 dB	-0.2 - 0.2		4.2 4.2	v
A _{VOL}	Large Signal Voltage Gain	$V_{O} = 0.3V \text{ to } 4.7V$ $R_{L} = 10 \text{ k}\Omega \text{ to } V^{+}/2$	110 108	120		dB
Vo	Output Swing High	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ $V_{IN}(diff) = 100 \text{ mV}$		17	50 50	mV
	Output Swing Low	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ $V_{IN}(diff) = -100 \text{ mV}$		17	50 50	from eithe rail
I _O	Output Current (Note 7)	Sourcing, V _O to V ⁻ V _{IN} (diff) = 100 mV	27 19	30		
		Sinking, V_O to V ⁺ V_{IN} (diff) = -100 mV	17 12	22		mA
I _S	Supply Current			10	16 18	μΑ

5V AC Electrical Characteristics (Note 4) Unless otherwise specified, all limits guaranteed for $T_A = 25^{\circ}C$, $V^+ = 5V$, $V^- = 0V$, $V_{CM} = V_O = V^+/2$, and $R_L > 1 \text{ M}\Omega$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions		Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
GBW	Gain-Bandwidth Product	C _L = 20 pF, R _L	= 10 kΩ		130		kHz
SR	Slew Rate	A _V = +1	Falling Edge	33 32	58		V/ms
			Rising Edge	33 32	48		v/ms
θ _m	Phase Margin	C _L = 20 pF, R _L	= 10 kΩ		78		deg
G _m	Gain Margin	C _L = 20 pF, R _L	$C_{L} = 20 \text{ pF}, \text{ R}_{L} = 10 \text{ k}\Omega$		27		dB

THD+N 3.3V E $T_A = 25^{\circ}C$ Symbol V_{OS}	Input-Referred Voltage Noise Densit Input-Referred Voltage Noise Input-Referred Current Noise Total Harmonic Distortion + Noise OC Electrical Characte C, V+ = $3.3V$, V- = $0V$, V _{CM} = V ₀ = V+ Parameter Input Offset Voltage Input Offset Voltage Drift	0.1 Hz to 10 Hz f = 1 kHz $f = 100 \text{ Hz}, \text{ R}_{L} = 10 \text{ k}\Omega$ ristics (Note 4) Unless of		60 2.3 10 0.002 d, all limits gr	Jaranteed fo	$\frac{nV/\sqrt{Hz}}{\mu V_{PP}}$ $\frac{fA/\sqrt{Hz}}{\%}$ or Units
i_n THD+N 3.3V $T_A = 25^{\circ}C$ Symbol V_{OS}	Input-Referred Voltage Noise Input-Referred Current Noise Total Harmonic Distortion + Noise OC Electrical Characte C, V+ = 3.3V, V ⁻ = 0V, V _{CM} = V ₀ = V+ Parameter Input Offset Voltage	0.1 Hz to 10 Hz f = 1 kHz $f = 100 \text{ Hz}, \text{ R}_{\text{L}} = 10 \text{ k}\Omega$ ristics (Note 4) Unless of /2, and R _L > 1 MΩ. Boldface I Conditions	limits apply at the Min	2.3 10 0.002 d, all limits gr temperature Typ (Note 5)	extremes. Max	µV _{PP} fA/√Hz %
THD+N 3.3V E $T_A = 25^{\circ}C$ Symbol V_{OS}	Input-Referred Current Noise Total Harmonic Distortion + Noise C Electrical Characte C, V+ = $3.3V$, V- = $0V$, V _{CM} = V ₀ = V+ Parameter Input Offset Voltage	$f = 1 \text{ kHz}$ $f = 100 \text{ Hz}, R_L = 10 \text{ k}\Omega$ $ristics (Note 4) Unless of a constraint of a constraint$	limits apply at the Min	10 0.002 d, all limits gr temperature Typ (Note 5)	extremes. Max	fA/√Hz %
THD+N 3.3V E $T_A = 25^{\circ}C$ Symbol V_{OS}	Total Harmonic Distortion + Noise DC Electrical Characte D, V+ = 3.3V, V- = 0V, V _{CM} = V ₀ = V+ Parameter Input Offset Voltage	$f = 100 \text{ Hz}, \text{ R}_{\text{L}} = 10 \text{ k}\Omega$ ristics (Note 4) Unless of 2, and $\text{R}_{\text{L}} > 1 \text{ M}\Omega$. Boldface 1 Conditions	limits apply at the Min	0.002 d, all limits gr temperature Typ (Note 5)	extremes. Max	or
3.3V C $T_A = 25^{\circ}C$ Symbol V_{OS}	DC Electrical Characte 5, V ⁺ = 3.3V, V ⁻ = 0V, V _{CM} = V ₀ = V ⁺ Parameter Input Offset Voltage	ristics (Note 4) Unless of 2, and $R_L > 1 M\Omega$. Boldface Conditions	limits apply at the Min	d, all limits gr temperature Typ (Note 5)	extremes. Max	pr
T _A = 25°C Symbol V _{OS}	$V_{CM} = 3.3V, V_{-} = 0V, V_{CM} = V_{O} = V_{+}$ Parameter Input Offset Voltage	/2, and R _L > 1 MΩ. Boldface I Conditions	limits apply at the Min	temperature Typ (Note 5)	extremes. Max	
V _{os}	Input Offset Voltage			(Note 5)		Units
		LMP2231A	(Note 6)		(Note 6)	Į
		LMP2231A		±10		l
TOV	Input Offset Voltage Drift	LMP2231A			±160 ±250	μV
TCV _{OS}				±0.3	±0.4	
		LMP2231B		±0.3	±2.5	µV/°C
I _{BIAS}	Input Bias Current			0.02	±1 ±50	pА
I _{os}	Input Offset Current			5		fA
	Common Mode Rejection Ratio	$0V \le V_{CM} \le 2.3V$	79 77	92		dB
PSRR	Power Supply Rejection Ratio	1.6V ≤ V+ ≤ 5.5V	83	120		
		$V^- = 0V, V_{CM} = 0V$	83			dB
CMVR	Common Mode Voltage Range	CMRR ≥ 78 dB	-0.2		2.5	
		CMRR ≥ 77 dB	-0.2		2.5	V
A _{VOL}	Large Signal Voltage Gain	V _O = 0.3V to 3V	108	120		
		$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$	107			dB
V _o	Output Swing High	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$		14	50	[
		$V_{IN}(diff) = 100 \text{ mV}$			50	mV
Ī	Output Swing Low	$R_L = 10 \text{ k}\Omega \text{ to V}$ +/2		14	50	from eithe rail
		$V_{IN}(diff) = -100 \text{ mV}$			50	ran
I _o	Output Current (Note 7)	Sourcing, V _O to V-	11	14		
		V _{IN} (diff) = 100 mV	8			mA
		Sinking, V _O to V ⁺	8	11		
		$V_{IN}(diff) = -100 \text{ mV}$	5			
I _S	Supply Current			10	15 16	μA
	C Electrical Characte 5, V ⁺ = 3.3V, V ⁻ = 0V, V _{CM} = V _O = V ⁺ /					for
Symbol	Parameter	Conditions	Min (Note 6	(Note 5)	Max (Note 6)	Units
GBW	Gain-Bandwidth Product	C _L = 20 pF, R _L = 10 kΩ		128	/	kHz

16AC Electrical Characteristics (Note 4) Unless otherwise is specified, all limits guaranteed forC, V+ = 3.3V, V- = 0V, $V_{CM} = V_0 = V^+/2$, and $R_L > 1 M\Omega$. Boldface limits apply at the temperature extremes.ParameterConditionsMin (Note 6)Typ (Note 5)Max (Note 6)UGain-Bandwidth Product $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 128HSlew Rate $A_V = +1, C_L = 20 \text{ pF}$ $R_L = 10 \text{ k}\Omega$ Falling Edge58 Rising EdgeVPhase Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 760	S	inking, V _O to V+		8	11		
ACElectrical Characteristics(Note 4)Unless otherwise is specified, all limits guaranteed for C, V+ = 3.3V, V- = 0V, V_{CM} = V_0 = V+/2, and R_L > 1 M\Omega. Boldface limits apply at the temperature extremes.ParameterConditionsMin (Note 6)Typ (Note 5)Max (Note 6)U (Note 6)Gain-Bandwidth Product $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 12848Slew Rate $A_V = +1, C_L = 20 \text{ pF}$ $R_L = 10 \text{ k}\Omega$ Falling Edge58V V Rising EdgePhase Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 760Gain Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 260	V	$_{\rm IN}({\rm diff}) = -100 ~{\rm mV}$		5			
16AC Electrical Characteristics (Note 4) Unless otherwise is specified, all limits guaranteed for C, V+ = 3.3V, V ⁻ = 0V, V _{CM} = V ₀ = V+/2, and R _L > 1 MΩ. Boldface limits apply at the temperature extremes.ParameterConditionsMin (Note 6)Typ (Note 5)Max (Note 6)UGain-Bandwidth Product $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 128HSlew Rate $A_V = +1, C_L = 20 \text{ pF}$ $R_L = 10 \text{ k}\Omega$ Falling Edge58 Rising EdgeVPhase Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 760Gain Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 260	Supply Current				10	15	
C, V+ = 3.3V, V- = 0V, V _{CM} = V _O = V+/2, and R _L > 1 MΩ. Boldface limits apply at the temperature extremes. Min Typ Max U Parameter Conditions Min Typ Max U Gain-Bandwidth Product $C_L = 20 \text{ pF}, \text{ R}_L = 10 \text{ k}\Omega$ 128 4 Slew Rate $A_V = +1, C_L = 20 \text{ pF}$ Falling Edge 58 4 Phase Margin $C_L = 20 \text{ pF}, \text{ R}_L = 10 \text{ k}\Omega$ 76 0 Gain Margin $C_L = 20 \text{ pF}, \text{ R}_L = 10 \text{ k}\Omega$ 26 0						16	μA
Gain-Bandwidth Product $C_L = 20 \text{ pF}, \text{R}_L = 10 \text{ k}\Omega$ (Note 6)(Note 5)(Note 6)Slew Rate $A_V = +1, C_L = 20 \text{ pF}, \text{R}_L = 10 \text{ k}\Omega$ Falling Edge586 $R_L = 10 \text{ k}\Omega$ Rising Edge4867676Phase Margin $C_L = 20 \text{ pF}, \text{R}_L = 10 \text{ k}\Omega$ Component of the term of t							for
	Parameter	Conditio	ons	Min	Тур	Max	Units
Slew Rate $A_V = +1, C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ Falling Edge58 V Phase Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 76 $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$							
$R_L = 10 \text{ k}\Omega$ Rising Edge48VPhase Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 760Gain Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 260				(Note 6)	(Note 5)	(Note 6)	
$R_L = 10 \text{ k}\Omega$ Rising Edge48Phase Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 760Gain Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 260	Gain-Bandwidth Product	C _L = 20 pF, R _L = 10 l	kΩ	(Note 6)	· · · ·	(Note 6)	kHz
Gain Margin $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$ 26			1	(Note 6)	128	(Note 6)	
		$A_V = +1, C_L = 20 \text{ pF}$	Falling Edge	(Note 6)	128 58	(Note 6)	kHz V/ms
Input-Referred Voltage Noise Density f = 1 kHz 60 nv	Slew Rate	$A_{V} = +1, C_{L} = 20 \text{ pF}$ $R_{L} = 10 \text{ k}\Omega$	Falling Edge Rising Edge	(Note 6)	128 58 48	(Note 6)	
	Slew Rate Phase Margin	$A_V = +1, C_L = 20 \text{ pF}$ $R_L = 10 \text{ k}\Omega$ $C_L = 20 \text{ pF}, R_L = 10 \text{ H}$	Falling Edge Rising Edge kΩ	(Note 6)	128 58 48 76	(Note 6)	V/ms

2.4

10

0.003

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 μV_{PP}

fA/√Hz

%

f = 100 Hz, $R_L = 10 \text{ k}\Omega$

0.1 Hz to 10 Hz

f = 1 kHz

Input-Referred Voltage Noise

Input-Referred Current Noise

Total Harmonic Distortion + Noise

SR

 θ_{m}

G_m

en

i_n

THD+N

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
V _{OS}	Input Offset Voltage	Voltage		±10	±190 ±275	μV
TCV _{OS}	Input Offset Voltage Drift	LMP2231A LMP2231B		±0.3 ±0.3	±0.4 ±2.5	μV/°C
I _{BIAS}	Input Bias Current			0.02	±1.0 ±50	pА
I _{os}	Input Offset Current			5		fA
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 1.5V$	77 76	91		dB
PSRR	Power Supply Rejection Ratio	$1.6V \le V^+ \le 5.5V$ V ⁻ = 0V, V _{CM} = 0V	83 83	120		dB
CMVR	Common Mode Voltage Range	CMRR ≥ 77 dB CMRR ≥ 76 dB	-0.2 - 0.2		1.7 1.7	v
A _{VOL}	Large Signal Voltage Gain	$V_{O} = 0.3V$ to 2.2V R _L = 10 k Ω to V+/2	104 104	120		dB
Vo	Output Swing High	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ $V_{IN}(\text{diff}) = 100 \text{ mV}$		12	50 50	mV
	Output Swing Low	$R_L = 10 k\Omega$ to V+/2 V _{IN} (diff) = -100 mV		13	50 50	from either rail
Io	Output Current (Note 7)	Sourcing, V _O to V- V _{IN} (diff) = 100 mV	5 4	8		
		Sinking, V _O to V+ V _{IN} (diff) = -100 mV	3.5 2.5	7		- mA
I _S	Supply Current			10	14 15	μA

2.5V AC Electrical Characteristics (Note 4) Unless otherwise specified, all limits guaranteed for $T_A = 25^{\circ}C$, $V^+ = 2.5V$, $V^- = 0V$, $V_{CM} = V_0 = V^{+}/2$, and $R_L > 1M\Omega$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions		Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
GBW	Gain-Bandwidth Product	$C_{L} = 20 \text{ pF}, R_{L} = 10 \text{ kg}$	ß		128		kHz
SR	Slew Rate	$A_V = +1, C_L = 20 \text{ pF}$	Falling Edge		58		\//
		$R_L = 10 \ k\Omega$	Rising Edge		48		V/ms
θ _m	Phase Margin	$C_{L} = 20 \text{ pF}, R_{L} = 10 \text{ k}\Omega$			74		deg
G _m	Gain Margin	$C_{L} = 20 \text{ pF}, R_{L} = 10 \text{ kg}$	Ω		26		dB
e _n	Input-Referred Voltage Noise Density	f = 1 kHz			60		nV/√Hz
	Input-Referred Voltage Noise	0.1 Hz to 10 Hz			2.5		μV _{PP}
i _n	Input-Referred Current Noise	f = 1 kHz			10		fA/√Hz
THD+N	Total Harmonic Distortion + Noise	f = 100 Hz, R ₁ = 10 kΩ	2		0.005		%

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
V _{OS}	Input Offset Voltage			±10	±230 ±325	μV
TCV _{OS}	Input Offset Voltage Drift	LMP2231A LMP2231B		±0.3 ±0.3	±0.4 ±2.5	μV/°C
I _{BIAS}	Input Bias Current			0.02	±1.0 ±50	рА
I _{os}	Input Offset Current			5		fA
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 0.8V$	76 75	92		dB
PSRR	Power Supply Rejection Ratio	$1.6V \le V^+ \le 5.5V$ $V^- = 0V, V_{CM} = 0V$	83 83	120		dB
CMVR	Common Mode Voltage Rang	$CMRR \ge 76 dB$ $CMRR \ge 75 dB$	-0.2 0		1.0 1.0	v
A _{VOL}	Large Signal Voltage Gain	$V_0 = 0.3V$ to 1.5V $R_L = 10 \text{ k}\Omega$ to V+/2	103 103	120		dB
Vo	Output Swing High	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ $V_{IN}(diff) = 100 \text{ mV}$		12	50 50	mV
	Output Swing Low	$R_L = 10 \text{ k}\Omega \text{ to V+/2}$ $V_{IN}(diff) = -100 \text{ mV}$		13	50 50	from either rail
I _O	Output Current (Note 7)	Sourcing, V _O to V- V _{IN} (diff) = 100 mV	2.5 2	5		
		Sinking, V_O to V ⁺ V_{IN} (diff) = -100 mV	2 1.5	5		- mA
I _S	Supply Current			10	14 15	μA

1.8V AC Electrical Characteristics (Note 4) Unless otherwise is specified, all limits guaranteed for $T_A = 25^{\circ}$ C, V⁺ = 1.8V, V⁻ = 0V, V_{CM} = V_O = V⁺/2, and R_L > 1 M Ω . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions		Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
GBW	Gain-Bandwidth Product				127	(Note 6)	kHz
GBW	Gain-bandwidth Product	$C_{L} = 20 \text{ pF}, R_{L} = 10$	KΩ		127		КПД
SR	Slew Rate	$A_V = +1, C_L = 20 \text{ pF}$	Falling Edge		58		V/ms
		$R_L = 10 \text{ k}\Omega$	Rising Edge		48		v/1115
θ _m	Phase Margin	$C_{L} = 20 \text{ pF}, R_{L} = 10$	kΩ		70		deg
G _m	Gain Margin	$C_{L} = 20 \text{ pF}, R_{L} = 10$	kΩ		25		dB
e _n	Input-Referred Voltage Noise Density	f = 1 kHz			60		nV/√Hz
	Input-Referred Voltage Noise	0.1 Hz to 10 Hz			2.4		μV_{PP}
i _n	Input-Referred Current Noise	f = 1 kHz			10		fA/√Hz
THD+N	Total Harmonic Distortion + Noise	f = 100 Hz, R ₁ = 10	kΩ		0.005		%

Note 1: Absolute Maximum Ratings indicate limits beyond which damage may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and test conditions, see the Electrical Characteristics.

Note 2: Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).

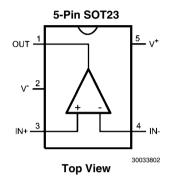
Note 3: The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$. All numbers apply for packages soldered directly onto a PC Board.

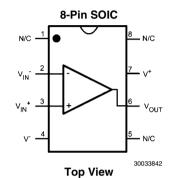
Note 4: Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that $T_J = T_A$. No guarantee of parametric performance is indicated in the electrical tables under conditions of internal self-heating where $T_J > T_A$. Absolute Maximum Ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically. **Note 5:** Typical values represent the most likely parametric norm at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.

Note 6: All limits are guaranteed by testing, statistical analysis or design.

Note 7: The short circuit test is a momentary open loop test.

Connection Diagrams

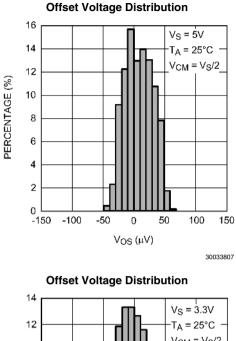


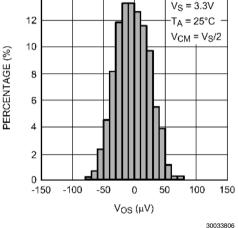


Ordering Information

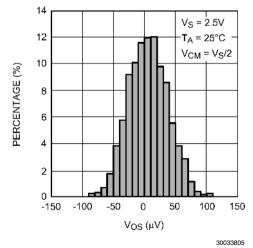
Package	Part Number	Temperature Range	Package Marking	Transport Media	NSC Drawing
	LMP2231AMF			1k Units Tape and Reel	
	LMP2231AMFE		AL5A	250 Units Tape and Reel	
5-Pin SOT23	LMP2231AMFX		Ī	3k Units Tape and Reel	
5-PIN 50123	LMP2231BMF			1k Units Tape and Reel	MF05A
	LMP2231BMFE	1	AL5B	250 Units Tape and Reel	
	LMP2231BMFX	1000 to 10500		3k Units Tape and Reel]
	LMP2231AMA	–40°C to 125°C		95 Units/Rail	
	LMP2231AMAE		LMP2231AMA	250 Units Tape and Reel]
8-Pin SOIC	LMP2231AMAX			2.5k Units Tape and Reel	M08A
8-PIN SOIC	LMP2231BMA			95 Units/Rail	INIU8A
	LMP2231BMAE		LMP2231BMA	250 Units Tape and Reel]
	LMP2231BMAX			2.5k Units Tape and Reel	1

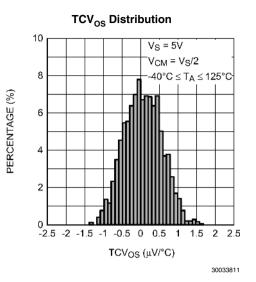
Typical Performance Characteristics Unless otherwise Specified: $T_A = 25^{\circ}C$, $V_S = 5V$, $V_{CM} = V_S/2$, where $V_S = V^+ - V^-$



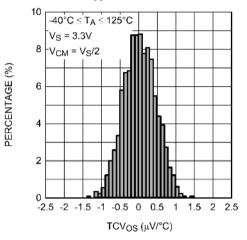


Offset Voltage Distribution



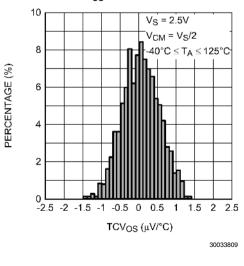


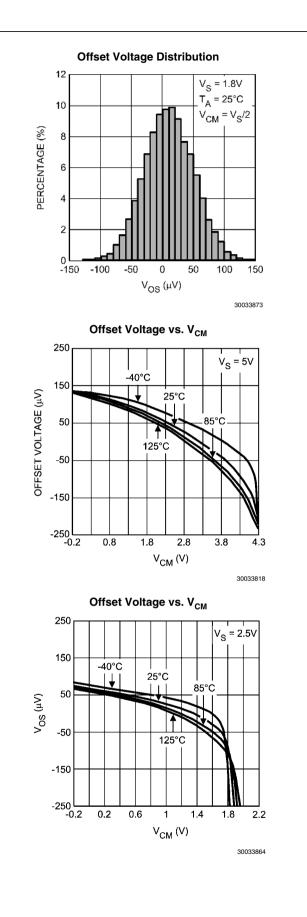
TCV_{OS} Distribution

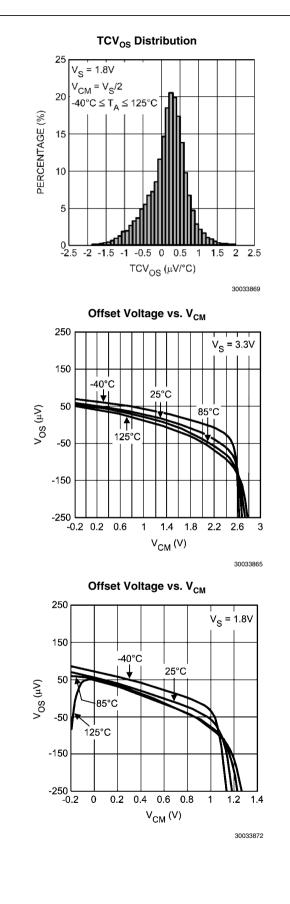


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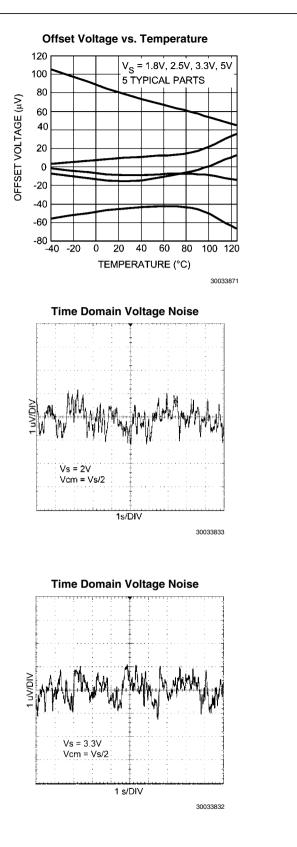
TCV_{OS} Distribution

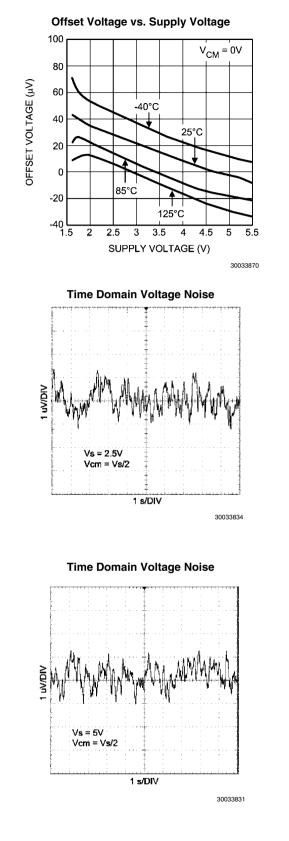


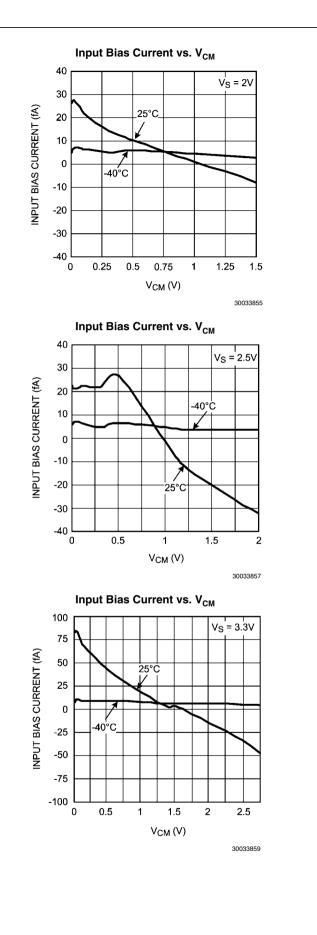


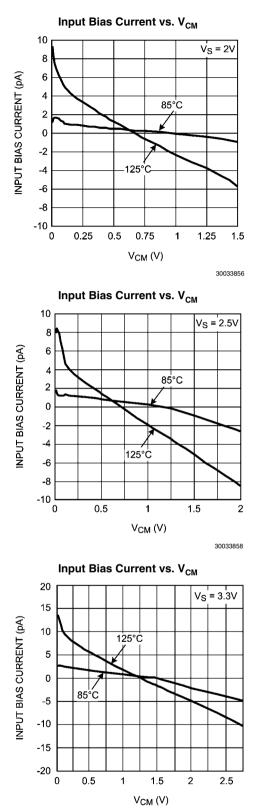






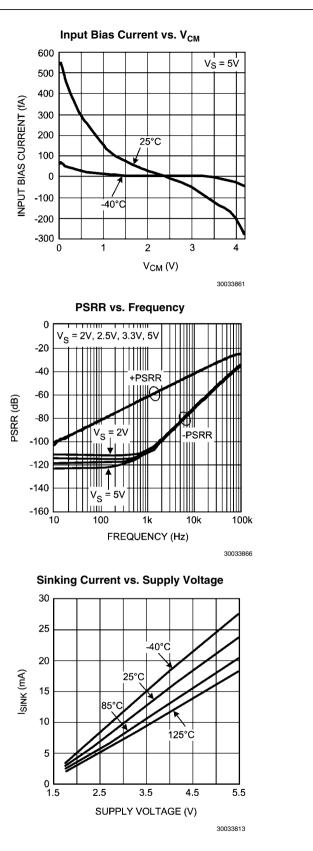


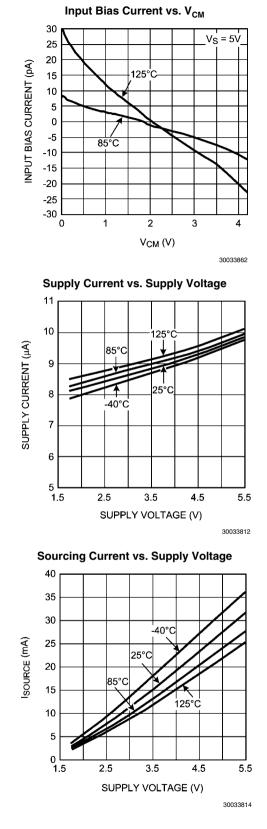


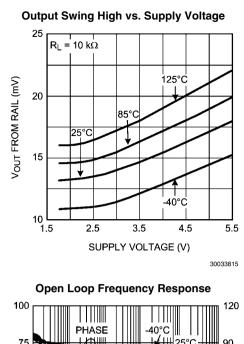


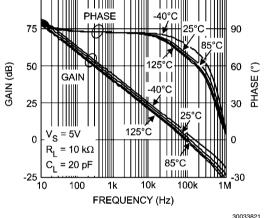
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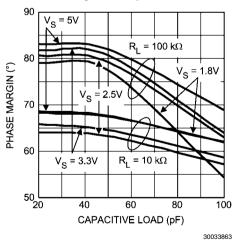


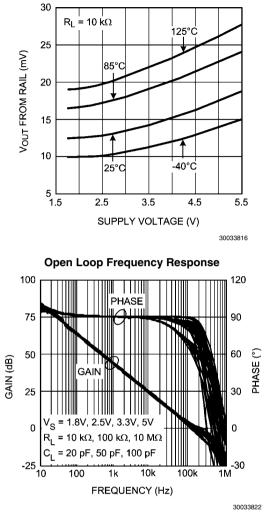




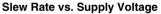


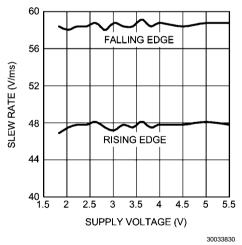
Phase Margin vs. Capacitive Load

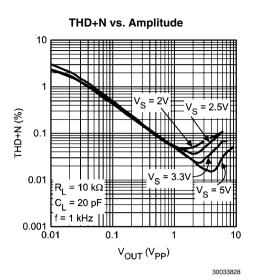


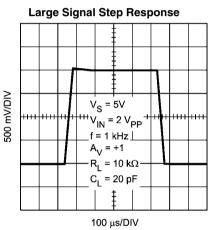


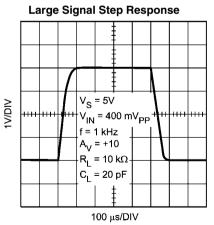
Output Swing Low vs. Supply Voltage

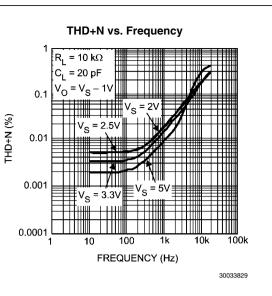




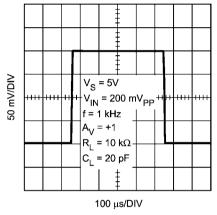


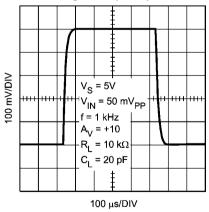




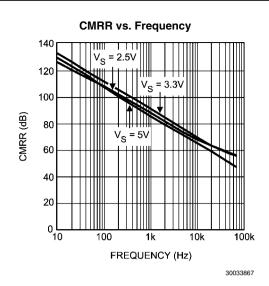


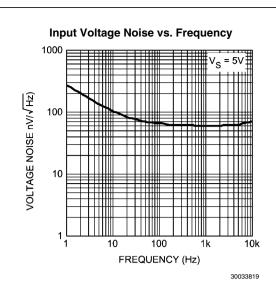






Small Signal Step Response





Application Information

The LMP2231 is a single CMOS precision amplifier that offer low offset voltage and low offset voltage drift, and high gain while only consuming 10 μ A of current per channel.

The LMP2231 is a micropower op amp, consuming only 10 μ A of current. Micropower op amps extend the run time of battery powered systems and reduce energy consumption in energy limited systems. The guaranteed supply voltage range of 1.8V to 5.0V along with the ultra-low supply current extend the battery run time in two ways. The extended guaranteed power supply voltage range of 1.8V to 5.0V enables the op amp to function when the battery voltage has depleted from its nominal value down to 1.8V. In addition, the lower power consumption increases the life of the battery.

The LMP2231 has an input referred offset voltage of only ±150 μ V maximum at room temperature. This offset is guaranteed to be less than ±230 μ V over temperature. This minimal offset voltage along with very low TCV_{OS} of only 0.3 μ V/°C typical allows more accurate signal detection and amplification in precision applications.

The low input bias current of only ± 20 fA gives the LMP2231 superiority for use in high impedance sensor applications. Bias Current of an amplifier flows through source resistance of the sensor and the voltage resulting from this current flow appears as a noise voltage on the input of the amplifier. The low input bias current enables the LMP2231 to interface with high impedance sensors while generating negligible voltage noise. Thus the LMP2231 provides better signal fidelity and a higher signal-to-noise ration when interfacing with high impedance sensors.

National Semiconductor is heavily committed to precision amplifiers and the market segment they serve. Technical support and extensive characterization data is available for sensitive applications or applications with a constrained error budget.

The operating supply voltage range of 1.8V to 5.5V over the extensive temperature range of -40° C to 125° C makes the LMP2231 an excellent choice for low voltage precision applications with extensive temperature requirements.

The LMP2231 is offered in the space saving 5-Pin SOT23 and 8-pin SOIC package. These small packages are ideal solutions for area constrained PC boards and portable electronics.

TOTAL NOISE CONTRIBUTION

The LMP2231 has a very low input bias current, very low input current noise, and low input voltage noise for micropower amplifier. As a result, this amplifier makes a great choice for circuits with high impedance sensor applications.

Figure 1 shows the typical input noise of the LMP2231 as a function of source resistance where:

 $\mathbf{e}_{\mathbf{n}}$ denotes the input referred voltage noise

 e_i is the voltage drop across source resistance due to input referred current noise or e_i = R_S * i_n

 \mathbf{e}_{t} shows the thermal noise of the source resistance

 \mathbf{e}_{ni} shows the total noise on the input.

Where:

$$e_{ni} = \sqrt{e_n^2 + e_i^2 + e_t^2}$$

The input current noise of the LMP2231 is so low that it will not become the dominant factor in the total noise unless source resistance exceeds 300 MΩ, which is an unrealistically high value. As is evident in Figure 1, at lower R_S values, total noise is dominated by the amplifier's input voltage noise. Once R_S is larger than a 100 kΩ, then the dominant noise factor becomes the thermal noise of R_S. As mentioned before, the current noise will not be the dominant noise factor for any practical application.

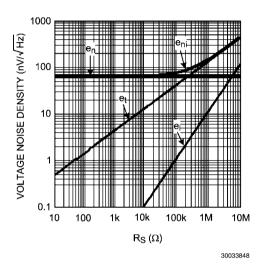


FIGURE 1. Total Input Noise

VOLTAGE NOISE REDUCTION

The LMP2231 has an input voltage noise of 60 nV/ \sqrt{Hz} . While this value is very low for micropower amplifiers, this input voltage noise can be further reduced by placing N amplifiers in parallel as shown in Figure 2. The total voltage noise on the output of this circuit is divided by the square root of the number of amplifiers used in this parallel combination. This is because each individual amplifier acts as an independent noise source, and the average noise of independent sources is the quadrature sum of the independent sources divided by the number of sources. For N identical amplifiers, this means:

REDUCED INPUT VOLTAGE NOISE =
$$\frac{1}{N} \sqrt{e_{n1}^2 + e_{n2}^2 + \dots + e_{nN}^2}$$

= $\frac{1}{N} \sqrt{Ne_n^2} = \frac{\sqrt{N}}{N} e_n$
= $\frac{1}{\sqrt{N}} e_n$

Figure 2 shows a schematic of this input voltage noise reduction circuit. Typical resistor values are: $R_G = 10\Omega$, $R_F = 1 k\Omega$, and $R_O = 1 k\Omega$.

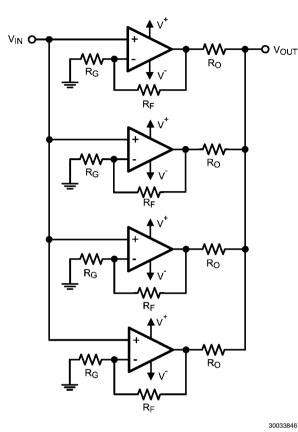


FIGURE 2. Noise Reduction Circuit

PRECISION INSTRUMENTATION AMPLIFIER

Measurement of very small signals with an amplifier requires close attention to the input impedance of the amplifier, gain of the overall signal on the inputs, and the gain on each input of the amplifier. This is because the difference of the input signal on the two inputs is of the interest and the common signal is considered noise. A classic circuit implementation is an instrumentation amplifier. Instrumentation amplifiers have a finite, accurate, and stable gain. They also have extremely high input impedances and very low output impedances. Finally they have an extremely high CMRR so that the amplifier can only respond to the differential signal. A typical instrumentation amplifier is shown in Figure 3.

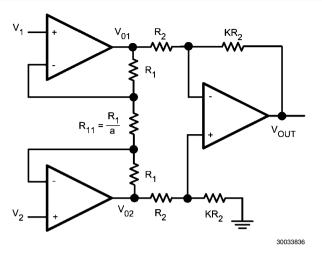


FIGURE 3. Instrumentation Amplifier

There are two stages in this amplifier. The last stage, output stage, is a differential amplifier. In an ideal case the two amplifiers of the first stage, input stage, would be set up as buffers to isolate the inputs. However they cannot be connected as followers because of mismatch of amplifiers. That is why there is a balancing resistor between the two. The product of the two stages of gain will give the gain of the instrumentation amplifier. Ideally, the CMRR should be infinite. However the output stage has a small non-zero common mode gain which results from resistor mismatch.

In the input stage of the circuit, current is the same across all resistors. This is due to the high input impedance and low input bias current of the LMP2231.

GIVEN:
$$I_{R_1} = I_{R_{11}}$$
 (1)

By Ohm's Law:

$$V_{01} - V_{02} = (2R_1 + R_{11}) I_{R_{11}}$$
$$= (2a + 1) R_{11} \bullet I_{R_{11}}$$
$$= (2a + 1) V_{R_{11}}$$
(2)

However:

$$V_{R_{11}} = V_1 - V_2$$
 (3)

So we have:

$$V_{O1} - V_{O2} = (2a+1)(V_1 - V_2)$$
 (4)

Now looking at the output of the instrumentation amplifier:

$$V_{O} = \frac{KR_{2}}{R_{2}} (V_{O2} - V_{O1})$$

= -K (V_{O1} - V_{O2}) (5)

Substituting from Equation 4:

V₀ =

-K (2a + 1) (
$$V_1 - V_2$$
) (6)

This shows the gain of the instrumentation amplifier to be:

Typical values for this circuit can be obtained by setting: a = 12 and K= 4. This results in an overall gain of -100.

SINGLE SUPPLY STRAIN GAGE BRIDGE AMPLIFIER

Strain gauges are popular electrical elements used to measure force or pressure. Strain gauges are subjected to an unknown force which is measured as a the deflection on a previously calibrated scale. Pressure is often measured using the same technique; however this pressure needs to be converted into force using an appropriate transducer. Strain gauges are often resistors which are sensitive to pressure or to flexing. Sense resistor values range from tens of ohms to several hundred kilo ohms. The resistance change which is a result of applied force across the strain gauge might be 1% of its total value. An accurate and reliable system is needed to measure this small resistance change. Bridge configurations offer a reliable method for this measurement.

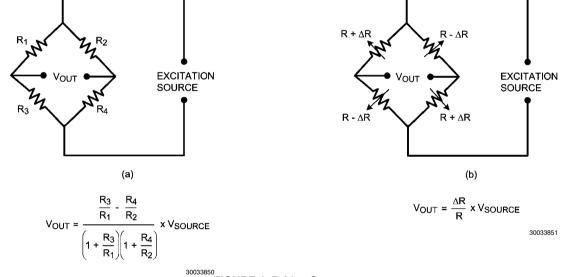
Bridge sensors are formed of four resistors, connected as a quadrilateral. A voltage source or a current source is used across one of the diagonals to excite the bridge while a voltage detector across the other diagonal measures the output voltage.

Bridges are mainly used as null circuits or to measure a differential voltages. Bridges will have no output voltage if the ratios of two adjacent resistor values are equal. This fact is used in null circuit measurements. These are particularly used in feedback systems which involve electrochemical elements or human interfaces. Null systems force an active resistor, such as a strain gauge, to balance the bridge by influencing the measured parameter.

Often in sensor applications at lease one of the resistors is a variable resistor, or a sensor. The deviation of this active element from its initial value is measured as an indication of change in the measured quantity. A change in output voltage represents the sensor value change. Since the sensor value change is often very small, the resulting output voltage is very small in magnitude as well. This requires an extensive and very precise amplification circuitry so that signal fidelity does not change after amplification.

Sensitivity of a bridge is the ratio of its maximum expected output change to the excitation voltage change.

Figure 4 (a) shows a typical bridge sensor and Figure 4(b) shows the bridge with four sensors. R in Figure 4(b) is the nominal value of the sense resistor and the deviations from R are proportional to the quantity being measured.





Instrumentation amplifiers are great for interfacing with bridge sensors. Bridge sensors often sense a very small differential signal in the presence of a larger common mode voltage. Instrumentation amplifiers reject this common mode signal.

Figure 5 shows a strain gauge bridge amplifier. In this application the LMP2231 is used to buffer the LM4140's precision output voltage. The LM4140A is a precision voltage reference. The other three LMP2231s are used to form an instrumentation amplifier. This instrumentation amplifier uses the LMP2231's high CMRR and low V_{OS} and TCV_{OS} to accurately amplify the small differential signal generated by the output of the bridge sensor. This amplified signal is then fed into the ADC121S021 which is a 12-bit analog to digital converter. This circuit works on a single supply voltage of 5V.

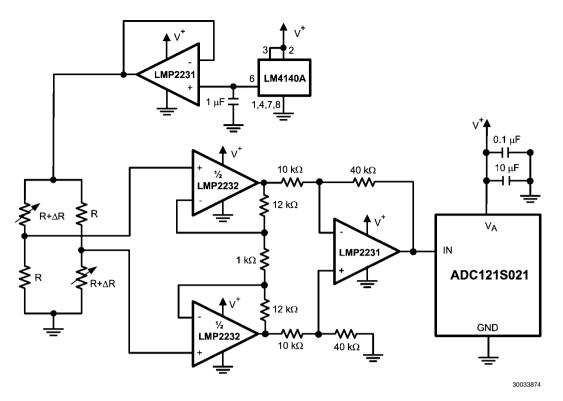


FIGURE 5. Strain Gauge Bridge Amplifier

PORTABLE GAS DETECTION SENSOR

Gas sensors are used in many different industrial and medical applications. They generate a current which is proportional to the percentage of a particular gas sensed in an air sample. This current goes through a load resistor and the resulting voltage drop is measured. Depending on the sensed gas and sensitivity of the sensor, the output current can be in the order of tens of microamperes to a few milliamperes. Gas sensor datasheets often specify a recommended load resistor value or they suggest a range of load resistors to choose from.

Oxygen sensors are used when air quality or oxygen delivered to a patient needs to be monitored. Fresh air contains 20.9% oxygen. Air samples containing less than 18% oxygen are considered dangerous. Oxygen sensors are also used in industrial applications where the environment must lack oxygen. An example is when food is vacuum packed. There are two main categories of oxygen sensors, those which sense oxygen when it is abundantly present (i.e. in air or near an oxygen tank) and those which detect traces of oxygen in ppm. Figure 6 shows a typical circuit used to amplify the output of an oxygen detector. The LMP2231 makes an excellent choice for this application as it only draws 10 µA of current and operates on supply voltages down to 1.8V. This application detects oxygen in air. The oxygen sensor outputs a known current through the load resistor. This value changes with the amount of oxygen present in the air sample. Oxygen sensors usually recommend a particular load resistor value or specify a range of acceptable values for the load resistor. Oxygen

sensors typically have a life of one to two years. The use of the micropower LMP2231 means minimal power usage by the op amp and it enhances the battery life. Depending on other components present in the circuit design, the battery could last for the entire life of the oxygen sensor. The precision specifications of the LMP2231, such as its very low offset voltage, low TCV_{OS}, low input bias current, low CMRR, and low PSRR are other factors which make the LMP2231 a great choice for this application.

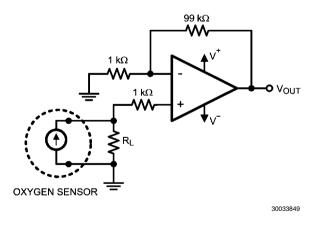
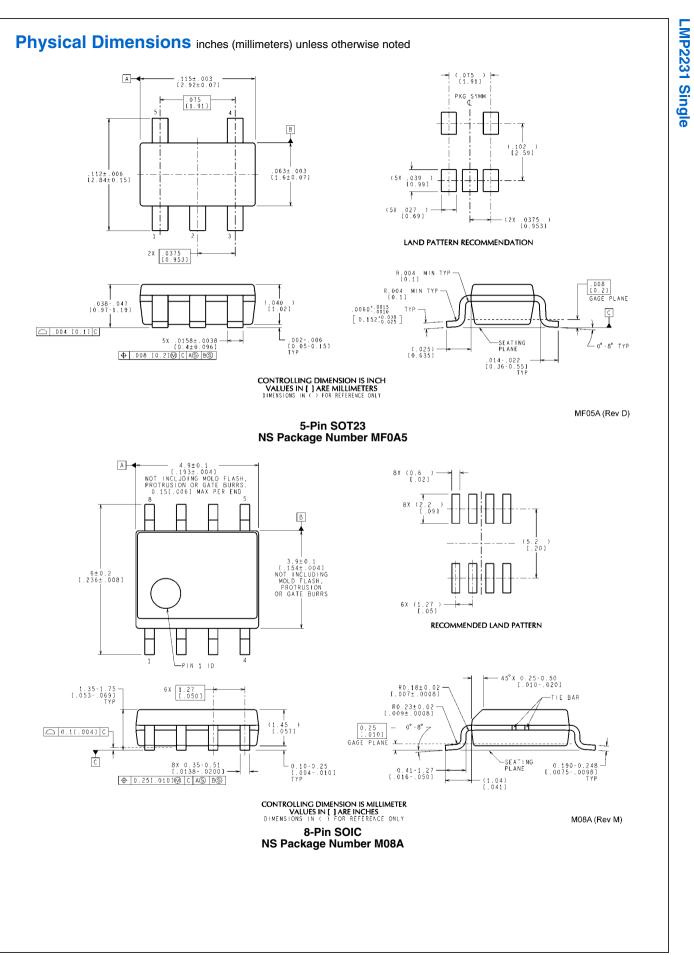


FIGURE 6. Precision Oxygen Sensor



Notes

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LDOs	www.national.com/ldo	Quality and Reliability	www.national.com/quality
LED Lighting	www.national.com/led	Feedback/Support	www.national.com/feedback
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