Features

- **Fast Read Access Time – 90 ns**
- **Word-wide or Byte-wide Configurable**
- **4-megabit Flash and Mask ROM Compatible**
- **Low-power CMOS Operation**
  - **– 100 µA Maximum Standby**
  - **– 50 mA Maximum Active at 5 MHz**
- **Wide Selection of JEDEC Standard Packages**
  - **– 40-lead 600 mil PDIP**
  - **– 44-lead SOIC (SOP)**
  - **– 48-lead TSOP (12 mm x 20 mm)**
- **5V ± 10% Power Supply**
- **High-reliability CMOS Technology**
  - **– 2,000V ESD Protection**
  - **– 200 mA Latch-up Immunity**
- **Rapid™ Programming Algorithm – 50 µs/Word (Typical)**
- **CMOS- and TTL-compatible Inputs and Outputs**
- **Integrated Product Identification Code**
- **Commercial and Industrial Temperature Ranges**

Description

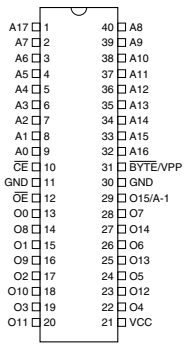
The AT27C400 is a low-power, high-performance, 4,194,304-bit, one-time programmable read-only memory (OTP EPROM) organized as either 256K by 16 or 512K by 8 bits. It requires a single 5V power supply in normal read mode operation. Any word can be accessed in less than 90 ns, eliminating the need for speed-reducing WAIT states. The by-16 organization makes this part ideal for high-performance 16- and 32-bit microprocessor systems. *(continued)*

Pin Configurations

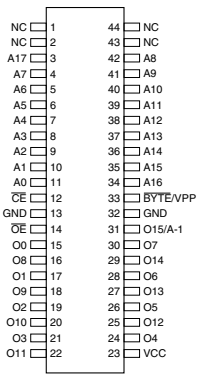
Pin Name	Function
A0 - A17	Addresses
O0 - O15	Outputs
O15/A-1	Output/Address
$\overline{BYTE}$/VPP	Byte Mode/ Program Supply
$\overline{CE}$	Chip Enable
$\overline{OE}$	Output Enable
NC	No Connect

Note: Both GND pins must be connected.

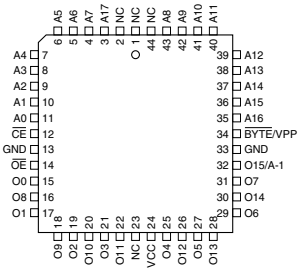
PDIP Top View



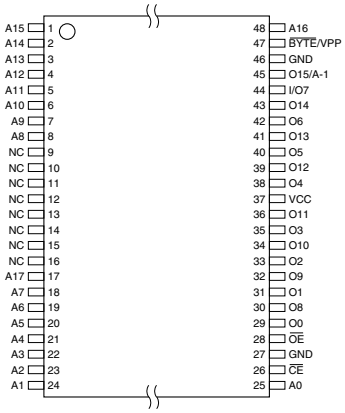
SOIC (SOP)



PLCC



TSOP
Type 1



4-megabit (256K x 16 or 512K x 8) OTP EPROM

AT27C400

Not Recommended for New Designs

Rev. 0844C–05/00

The AT27C400 can be organized as either word-wide or byte-wide. The organization is selected via the $\overline{BYTE}/V_{PP}$ pin. When $\overline{BYTE}/V_{PP}$ is asserted high (V_{IH}), the word-wide organization is selected and the O15/A-1 pin is used for O15 data output. When $\overline{BYTE}/V_{PP}$ is asserted low (V_{IL}), the byte-wide organization is selected and the O15/A-1 pin is used for the address pin A-1. When the AT27C400 is logically regarded as x16 (word-wide), but read in the byte-wide mode, then with A-1 = V_{IL}, the lower eight bits of the 16-bit word are selected and with A-1 = V_{IH}, the upper eight bits of the 16-bit word are selected.

In read mode, the AT27C400 typically consumes 15 mA. Standby mode supply current is typically less than 10 µA.

The AT27C400 is available in industry-standard, JEDEC-approved, one-time programmable (OTP) PDIP, SOIC (SOP) and TSOP packages. The device features two-line control ($\overline{CE}$, $\overline{OE}$) to eliminate bus contention in high-speed systems.

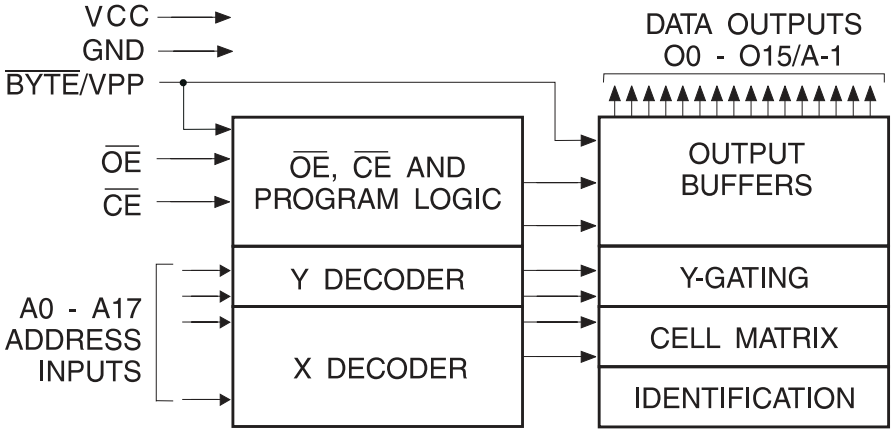
With high-density 256K word or 512K byte storage capability, the AT27C400 allows firmware to be stored reliably and to be accessed by the system without the delays of mass storage media.

Atmel's AT27C400 has additional features that ensure high quality and efficient production use. The Rapid™ Programming Algorithm reduces the time required to program the part and guarantees reliable programming. Programming time is typically only 50 µs/word. The Integrated Product Identification Code electronically identifies the device and manufacturer. This feature is used by industry-standard programming equipment to select the proper programming algorithms and voltages.

System Considerations

Switching between active and standby conditions via the Chip Enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device non-conformance. At a minimum, a 0.1 µF high-frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the V_{CC} and Ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a 4.7 µF bulk electrolytic capacitor should be utilized, again connected between the V_{CC} and Ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.

Block Diagram



Absolute Maximum Ratings*

Temperature under Bias	-55°C to +125°C
Storage Temperature	-65°C to +150°C
Voltage on Any Pin with Respect to Ground	-2.0V to +7.0V (1)
Voltage on A9 with Respect to Ground	-2.0V to +14.0V (1)
V_{PP} Supply Voltage with Respect to Ground	-2.0V to +14.0V (1)
Integrated UV Erase Dose	.7258 W •sec/cm^2

*NOTICE: Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note: 1. Minimum voltage is -0.6V DC, which undershoots to -2.0V for pulses of less than 20 ns. Maximum output pin voltage is V_{CC} + 0.75V DC, which may overshoot to +7.0V for pulses of less than 20 ns.

Operating Modes

Mode/Pin	$\overline{CE}$	$\overline{OE}$	Ai	$\overline{BYTE}/V_{PP}$	Outputs		
					O_0 - O_7	O_8 - O_{14}	O_{15}/A-1
Read Word-wide	V_{IL}	V_{IL}	X(1)	V_{IH}	D_{OUT}	D_{OUT}	D_{OUT}
Read Byte-wide Upper	V_{IL}	V_{IL}	X(1)	V_{IL}	D_{OUT}	High-Z	V_{IH}
Read Byte-wide Lower	V_{IL}	V_{IL}	X(1)	V_{IL}	D_{OUT}	High-Z	V_{IL}
Output Disable	X(1)	V_{IH}	X(1)	X		High-Z	
Standby	V_{IH}	X(1)	X(1)	X(5)		High-Z	
Rapid Program(2)	V_{IL}	V_{IH}	Ai	V_{PP}		D_{IN}	
PGM Verify	X	V_{IL}	Ai	V_{PP}		D_{OUT}	
PGM Inhibit	V_{IH}	V_{IH}	X(1)	V_{PP}		High-Z	
Product Identification(4)	V_{IL}	V_{IL}	A9 = V_H(3) A0 = V_{IH} or V_{IL} A1 - A17 = V_{IL}	V_{IH}		Identification Code	

Notes: 1. X can be V_{IL} or V_{IH}.
2. Refer to the programming characteristics tables in this datasheet.
3. V_H = 12.0 ± 0.5V.
4. Two identifier words may be selected. All inputs are held low (V_{IL}), except A9, which is set to V_H, and A0, which is toggled low (V_{IL}) to select the Manufacturer's Identification word and high (V_{IH}) to select the Device Code word.
5. Standby V_{CC} current (ISB) is specified with V_{PP} = V_{CC}. V_{CC} > V_{PP} will cause a slight increase in ISB.

DC and AC Operating Conditions for Read Operation

		AT27C400		
		-90	-12	-15
Operating Temperature (Case)	Com.	0°C - 70°C	0°C - 70°C	0°C - 70°C
	Ind.	-40°C - 85°C	-40°C - 85°C	-40°C - 85°C
V_{CC} Power Supply		5V ± 10%	5V ± 10%	5V ± 10%

DC and Operating Characteristics for Read Operation

Symbol	Parameter	Condition	Min	Max	Units
I_{LI}	Input Load Current	V_{IN} = 0V to V_{CC}		±1	µA
I_{LO}	Output Leakage Current	V_{OUT} = 0V to V_{CC}		±5	µA
I_{PP1}[2]	V_{PP}[1] Read/Standby Current	V_{PP} = V_{CC}		10	µA
I_{SB}	V_{CC}[1] Standby Current	I_{SB1} (CMOS), $\overline{CE}$ = V_{CC} ± 0.3V		100	µA
		I_{SB2} (TTL), $\overline{CE}$ = 2.0 to V_{CC} + 0.5V		1	mA
	V_{CC} Active Current	f = 5 MHz, I_{OUT} = 0 mA, $\overline{CE}$ = V_{IL}		40	mA
V_{IL}	Input Low Voltage		-0.6	0.8	V
V_{IH}	Input High Voltage		2.0	V_{CC} + 0.5	V
V_{OL}	Output Low Voltage	I_{OL} = 2.1 mA		0.4	V
V_{OH}	Output High Voltage	I_{OH} = -400 µA	2.4		V

Notes: 1. V_{CC} must be applied simultaneously or before V_{PP}, and removed simultaneously or after V_{PP}.

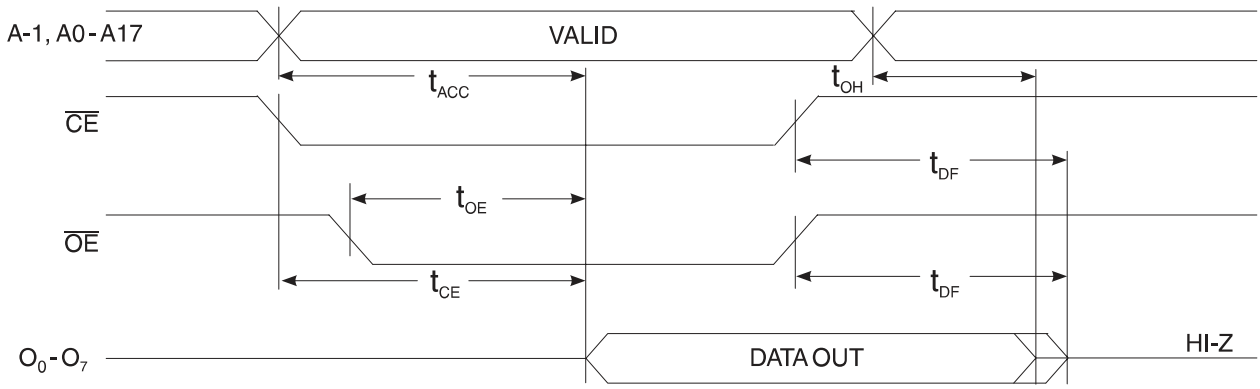
2. V_{PP} may be connected directly to V_{CC}, except during programming. The supply current would then be the sum of I_{CC} and I_{PP}.

AC Characteristics for Read Operation

			AT27C400						
			-90		-12		-15		
Symbol	Parameter	Condition	Min	Max	Min	Max	Min	Max	Units
t_{ACC}[2]	Address to Output Delay	$\overline{CE}$ = $\overline{OE}$ = V_{IL}		90		120		150	ns
t_{CE}[2]	$\overline{CE}$ to Output Delay	$\overline{OE}$ = V_{IL}		90		120		150	ns
t_{OE}[2][3]	$\overline{OE}$ to Output Delay	$\overline{CE}$ = V_{IL}		35		40		50	ns
t_{DF}[4][5]	$\overline{OE}$ or $\overline{CE}$ High to Output Float, whichever occurred first			20		30		35	ns
t_{OH}[4]	Output Hold from Address, $\overline{CE}$ or $\overline{OE}$, whichever occurred first		5		5		5		ns
t_{ST}	$\overline{BYTE}$ High to Output Valid			90		120		150	ns
t_{STD}	$\overline{BYTE}$ Low to Output Transition			40		50		60	ns

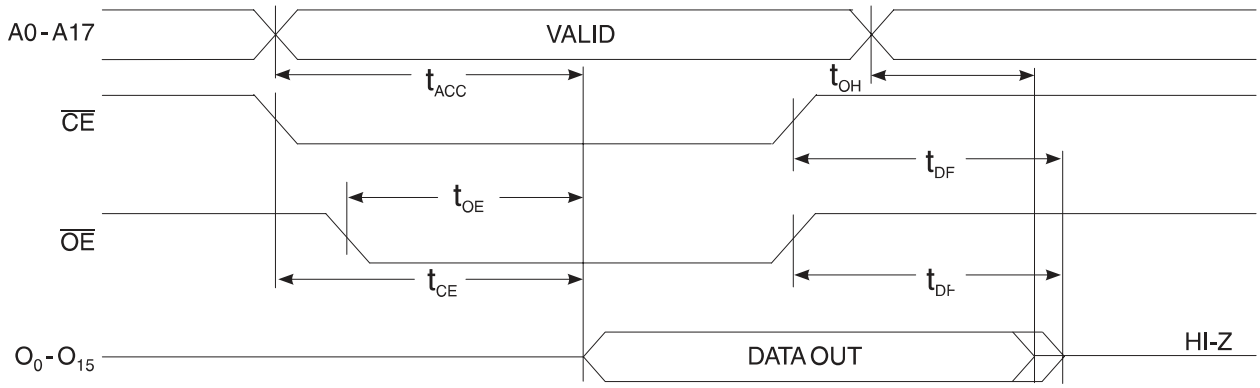
Note: 2, 3, 4, 5. See the AC Waveforms for Read Operation diagram.

Byte-wide Read Mode AC Waveforms



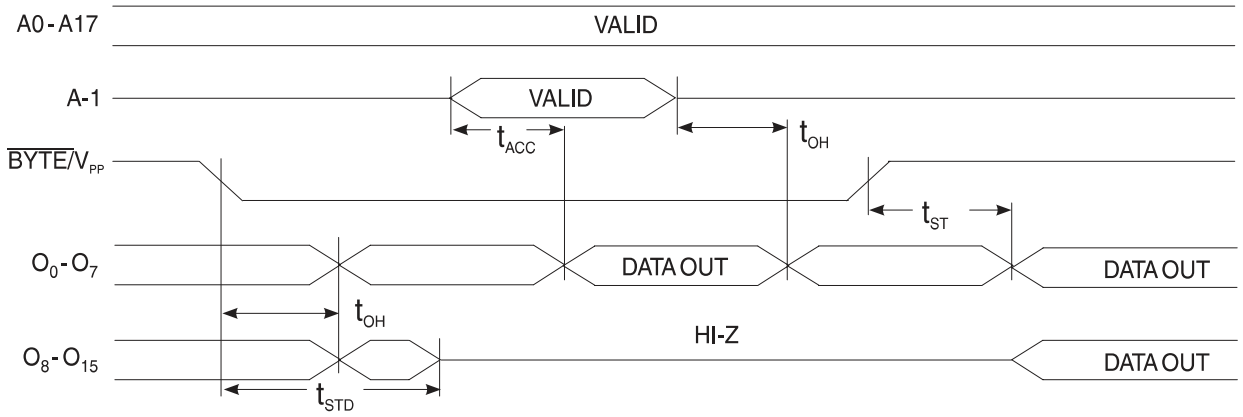
Note: $\overline{BYTE}/V_{PP} = V_{IL}$

Word-wide Read Mode AC Waveforms



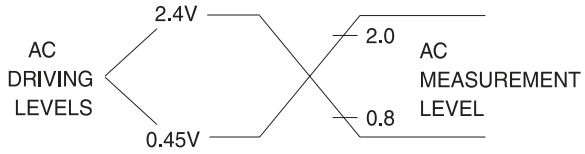
Note: $\overline{BYTE}/V_{PP} = V_{IH}$

$\overline{BYTE}$ Transition AC Waveforms



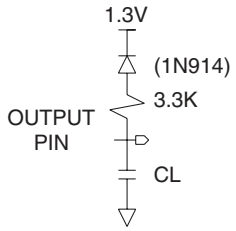
Notes:
1. Timing measurement references are 0.8V and 2.0V. Input AC drive levels are 0.45V and 2.4V, unless otherwise specified.
2. $\overline{OE}$ maybe delayed up to $t_{CE} - t_{OE}$ after the falling edge of $\overline{CE}$ without impact on t_{CE}.
3. $\overline{OE}$ maybe delayed up to $t_{ACC} - t_{OE}$ after the address is valid without impact on t_{ACC}.
4. This parameter is only sampled and is not 100% tested.
5. Output float is defined as the point when data is no longer driven.

Input Test Waveforms and Measurement Levels



t_R, t_F < 20 ns (10% to 90%)

Output Test Load



Note: C_L = 100 pF including jig capacitance.

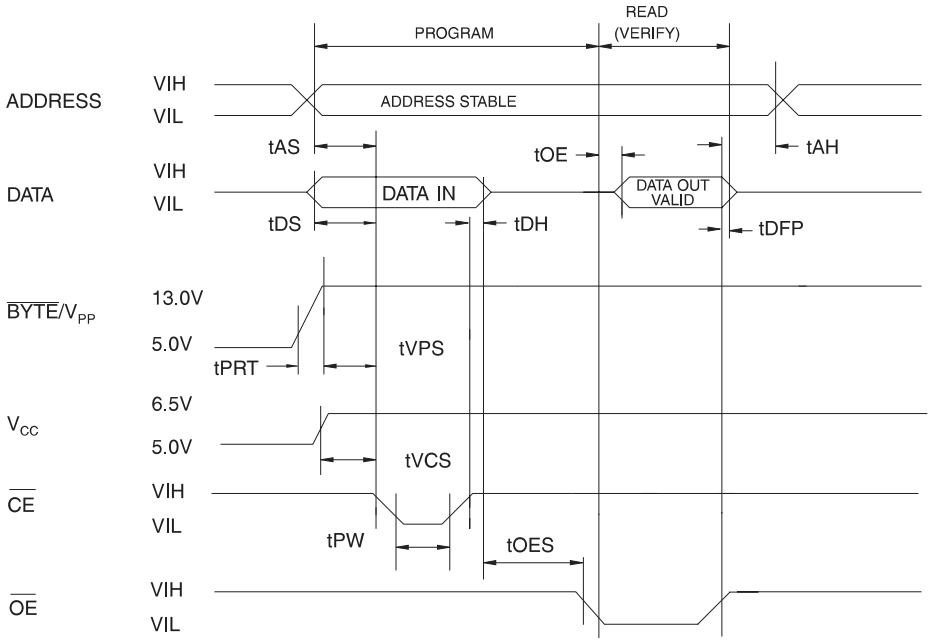
Pin Capacitance

f = 1 MHz, T = 25°C[1]

Symbol	Typ	Max	Units	Conditions
C_{IN}	4	10	pF	V_{IN} = 0V
C_{OUT}	8	12	pF	V_{OUT} = 0V

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not 100% tested.

Programming Waveforms[1]



Notes: 1. The Input Timing Reference is 0.8V for V_{IL} and 2.0V for V_{IH}.

2. t_{OE} and t_{DFP} are characteristics of the device but mist be accommodated by the programmer.

3. When programming the AT27C400, a 0.1 µF capacitor is required across V_{PP} and ground to suppress spurious voltage transients.

DC Programming Characteristics

TA = 25 ± 5°C, V_{CC} = 6.5 ± 0.25V, V_{PP} = 13.0 ± 0.25V

Symbol	Parameter	Test Conditions	Limits		Units
			Min	Max	
I_{LI}	Input Load Current	$V_{IN} = V_{IL}, V_{IH}$		±10	µA
V_{IL}	Input Low Level		-0.6	0.8	V
V_{IH}	Input High Level		2.0	V_{CC} + 0.5	V
V_{OL}	Output Low Voltage	I_{OL} = 2.1 mA		0.4	V
V_{OH}	Output High Voltage	I_{OH} = -400 µA	2.4		V
I_{CC2}	V_{CC} Supply Current (Program and Verify)			50	mA
I_{PP2}	V_{PP} Supply Current	$\overline{CE} = V_{IL}$		30	mA
V_{ID}	A9 Product Identification Voltage		11.5	12.5	V

AC Programming Characteristics

TA = 25 ± 5°C, V_{CC} = 6.5 ± 0.25V, V_{PP} = 13.0 ± 0.25V

Symbol	Parameter	Test Conditions[1]	Limits		Units
			Min	Max	
t_{AS}	Address Setup Time	Input Rise and Fall Times: (10% to 90%) 20 ns Input Pulse Levels: 0.45V to 2.4V Input Timing Reference Level: 0.8V to 2.0V Output Timing Reference Level: 0.8V to 2.0V	2		µs
t_{OES}	$\overline{OE}$ Setup Time		2		µs
t_{DS}	Data Setup Time		2		µs
t_{AH}	Address Hold Time		0		µs
t_{DH}	Data Hold Time		2		µs
t_{DFP}	$\overline{OE}$ High to Output Float Delay[2]		0	130	ns
t_{VPS}	V_{PP} Setup Time		2		µs
t_{VCS}	V_{CC} Setup Time		2		µs
t_{PW}	$\overline{CE}$ Program Pulse Width[3]		47.5	52.5	µs
t_{OE}	Data Valid from $\overline{OE}$			150	ns
t_{PRT}	$\overline{BYTE}/V_{PP}$ Pulse Rise Time During Programming		50		ns

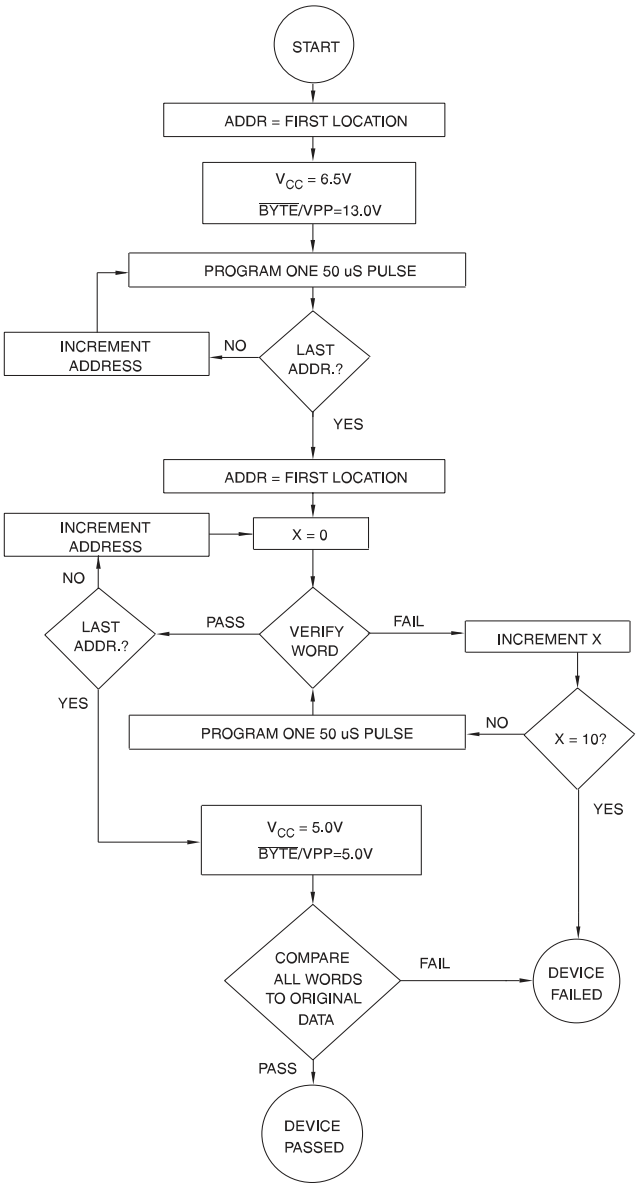
Notes:
1. V_{CC} must be applied simultaneously or before V_{PP} and removed simultaneously or after V_{PP}.
2. This parameter is only sampled and is not 100% tested. Output Float is defined as the point where data is no longer driven — see timing diagram.
3. Program Pulse width tolerance is 50 µsec ± 5%.

Atmel's 27C400 Integrated Product Identification Code

Codes	Pins									Hex Data
	A0	O15	O14	O13	O12	O11	O10	O9	O8	
		O7	O6	O5	O4	O3	O2	O1	O0	
Manufacturer	0	0	0	0	1	1	1	1	0	1E1E
Device Type	1	1	1	1	1	0	1	0	0	F4F4

Rapid Programming Algorithm

A 50 µs $\overline{CE}$ pulse width is used to program. The address is set to the first location. V_{CC} is raised to 6.5V and $\overline{BYTE}/V_{PP}$ is raised to 13.0V. Each address is first programmed with one 50 µs $\overline{CE}$ pulse without verification. Then a verification/reprogramming loop is executed for each address. In the event a word fails to pass verification, up to 10 successive 50 µs pulses are applied with a verification after each pulse. If the word fails to verify after 10 pulses have been applied, the part is considered failed. After the word verifies properly, the next address is selected until all have been checked. V_{PP} is then lowered to 5.0V and V_{CC} to 5.0V. All words are read again and compared with the original data to determine if the device passes or fails.



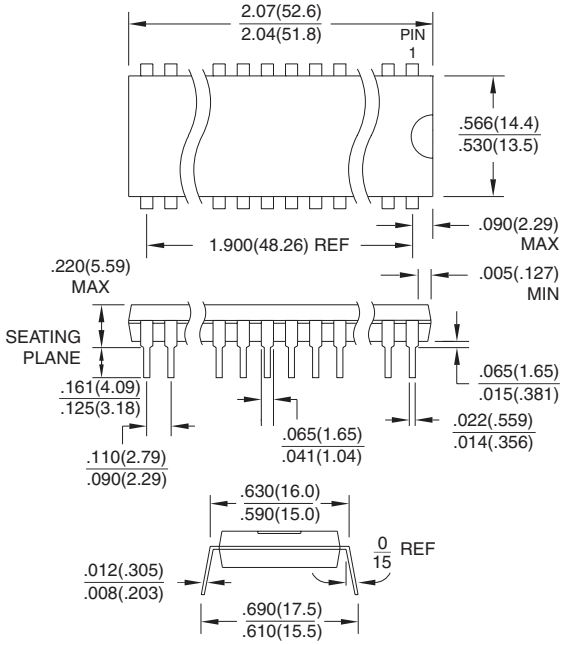
Ordering Information

t_{ACC} (ns)	I_{CC} (mA)		Ordering Code	Package	Operation Range
	Active	Standby			
90	40	0.1	AT27C400-90PC AT27C400-90RC AT27C400-90TC AT27C400-90JC	40P6 44R 48T 44J	Commercial (0°C to 70°C)
	40	0.1	AT27C400-90PI AT27C400-90RI AT27C400-90TI AT27C400-90JI	40P6 44R 48T 44J	Industrial (-40°C to 85°C)
120	40	0.1	AT27C400-12PC AT27C400-12RC AT27C400-12TC AT27C400-12JC	40P6 44R 48T 44J	Commercial (0°C to 70°C)
	40	0.1	AT27C400-12PI AT27C400-12RI AT27C400-12TI AT27C400-12JI	40P6 44R 48T 44J	Industrial (-40°C to 85°C)
150	40	0.1	AT27C400-15PC AT27C400-15RC AT27C400-15TC AT27C400-15JC	40P6 44R 48T 44J	Commercial (0°C to 70°C)
	40	0.1	AT27C400-15PI AT27C400-15RI AT27C400-15TI AT27C400-15JI	40P6 44R 48T 44J	Industrial (-40°C to 85°C)

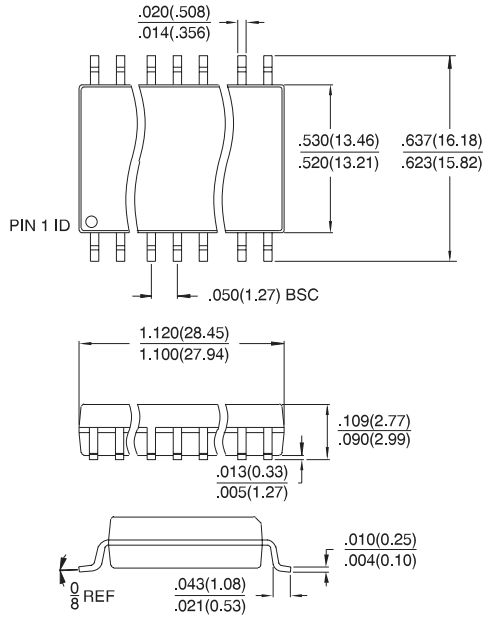
Package Type	
40P6	40-lead, 0.600" Wide, Plastic Dual Inline Package (PDIP)
44R	44-lead, 0.525" Wide, Plastic Gull Wing Small Outline Package (SOIC/SOP)
48T	48-lead, Plastic Thin Small Outline Package (TSOP) 12 x 20 mm
44J	44-lead, Plastic J-leaded Chip Carrier (PLCC)

Packaging Information

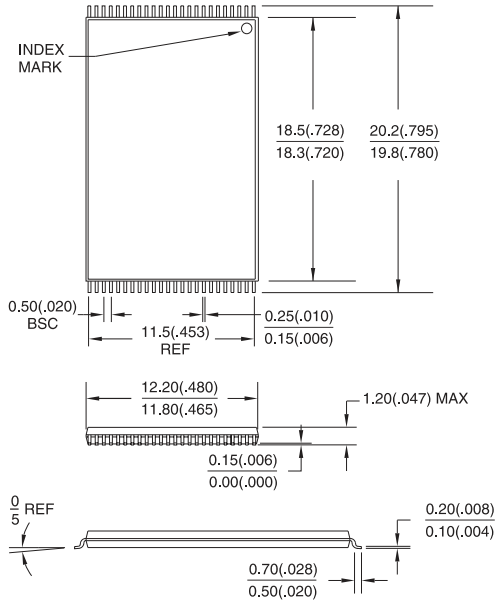
40P6, 40-lead, 0.600" Wide, Plastic Dual Inline Package (PDIP)
Dimensions in Inches and (Millimeters)
JEDEC STANDARD MS-011 AC



44R, 44-lead, 0.525" Wide, Plastic Gull Wing Small Outline (SOIC)
Dimensions in Inches and (Millimeters)

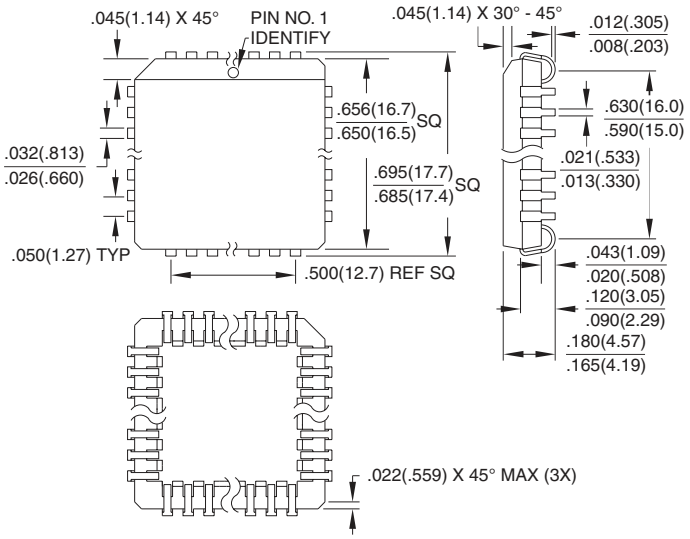


48T, 48-lead, Plastic Thin Small Outline Package (TSOP)
Dimensions in Millimeters and (Inches)*
JEDEC OUTLINE MO-142 DD



*Controlling dimension: millimeters

44J, 44-lead, Plastic J-leaded Chip Carrier (PLCC)
Dimensions in Inches and (Millimeters)
JEDEC STANDARD MS-018 AC



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0844C–05/00/xM