

SDIO101A

SD/SDIO/MMC/CE-ATA host controller

Rev. 1 — 13 June 2013

Product data sheet

1. General description

The SDIO101A is a SD/SDIO/MMC/CE-ATA host controller with a standard 16-bit asynchronous memory interface. The device conforms to the *SD Host Standard Specification Version 2.0* (see [Ref. 1](#)). The SDIO101A manages the physical layer of SD, SDIO, MMC and CE-ATA protocols and can be used together with SD Host Standard compatible driver software to add SD/SDIO/MMC/CE-ATA host functionality to a variety of microprocessor systems.

The SDIO101A supports both full-speed (< 25 MHz) and high-speed (< 52 MHz) data transmissions on the SD/SDIO/MMC/CE-ATA port. The SDIO101A offers separate pins for SD/SDIO/MMC/CE-ATA port supply voltage, host interface supply voltage and core supply voltage. The SD/SDIO/MMC/CE-ATA port can operate at a wide voltage range (1.8 V to 3.6 V) which allows the device to interface to a large variety of SD, SDIO, MMC or CE-ATA devices. The SDIO101A allows 1-bit and 4-bit SD transactions and 8-bit MMC/CE-ATA transactions. The 16-bit asynchronous memory interface can operate at a 2.5 V to 3.6 V voltage range.

A built-in, 2 kB data buffer allows for a low interrupt latency time and efficient communication with the host processor at high data rates. The SDIO101A provides a DMA request line that can be connected to an external DMA controller to off-load the host processor and increase overall system performance.

An on-board PLL allows a large range of SD/SDIO/MMC/CE-ATA clock speeds to be generated from a single externally available clock source. An additional fractional divider allows the SD clock speed to be fine-tuned with very fine granularity, which enables the user to achieve the maximum desired SD clock speed from the external clock source.

The SDIO101A offers 5 levels of power saving, including a 'Hibernate mode' where the on-board oscillator, PLL and data buffer memories are switched off, and a 'Coma mode' in which supply power to most of the device is internally switched off. This allows the device to be used in very power-critical applications.

2. Features and benefits

2.1 General

- Provides 1 SD/SDIO/MMC/CE-ATA slot, operating in 1-bit, 4-bit and 8-bit (MMC/CE-ATA) modes
- 2.5 V to 3.3 V host interface
- 1.8 V core supply voltage
- Separate SD supply voltage pin. SD/SDIO/MMC/CE-ATA slot is able to operate at a wide voltage range (1.8 V to 3.3 V).



- Compliant with *SDIO card specification version 2.00* (see [Ref. 2](#))
- Compliant with *SD Host Controller Standard Specification Version 2.0* (see [Ref. 1](#))
- Compliant with *SD Physical Layer Specification version 2.0* (see [Ref. 3](#))
- Compliant with *MMC Specification version 3.31 and 4.2* (see [Ref. 4](#))
- Supports CE-ATA Digital Protocol revision 1.1 (see [Ref. 5](#))
- Supports CE-ATA Digital Protocol commands (CMD60/CMD61)
- Dedicated SD Card Detection input pin (insertion/removal)
- Dedicated SD Card Write Protection input pin
- Full speed (< 25 MHz) and high-speed (< 52 MHz) SD data transmissions
- Supports interrupt and slave-DMA transfer operation
- Built-in 2 kB double data buffer (with 1 kB maximum block size) for efficient communication with host processor
- Supports SDIO features Multi-block, Suspend/Resume, Read Wait and Wake-up Control
- Up to 400 Mbit/s read and write data transfer rates at 50 MHz using MMC 8 data lines
- Up to 208 Mbit/s read and write data transfer rates at 52 MHz using SD 4 data lines
- On-board crystal oscillator and PLL
- 5 levels of power saving, including a 'Hibernate mode' where oscillator, PLL and memories are switched off, and a 'Coma mode' that internally switches off supply power to most of the chip
- Additional on-board fractional clock divider for fine-grained SD clock speed control
- Cyclic Redundancy Check (CRC) for command and data
- Programmable pull-up resistor on SD CMD and SD DATn lines
- Programmable drive strength for SDCLK output to optimize SD/SDIO/MMC/CE-ATA clock speed

2.2 Host processor interface

- Supports 16-bit asynchronous memory interface
- Separate host interface power supply pin, able to operate on 2.5 V to 3.3 V
- Programmable open collector or push-pull mode for $\overline{\text{INT}}$ interrupt pin output

3. Ordering information

Table 1. Ordering information

| Type number | Topside marking | Package | | Version |
|-------------|-----------------|---------|---|-----------|
| | | Name | Description | |
| SDIO101AIHR | D101A | HXQFN60 | plastic compatible thermal enhanced extremely thin quad flat package; no leads; 60 terminals; body 5 × 5 × 0.5 mm | SOT1133-2 |

3.1 Ordering options

Table 2. Ordering options

| Type number | Orderable part number | Package | Packing method | Minimum order quantity | Temperature |
|-------------|-----------------------|---------|---|------------------------|-------------------------------------|
| SDIO101AIHR | SDIO101AIHRZ | HXQFN60 | Reel 7" Q1/T1 *standard mark dry pack | 1500 | T _{amb} = -40 °C to +85 °C |
| SDIO101AIHR | SDIO101AIHRE | HXQFN60 | Standard marking * Tray dry pack, bakeable, single | 490 | T _{amb} = -40 °C to +85 °C |

4. Block diagram

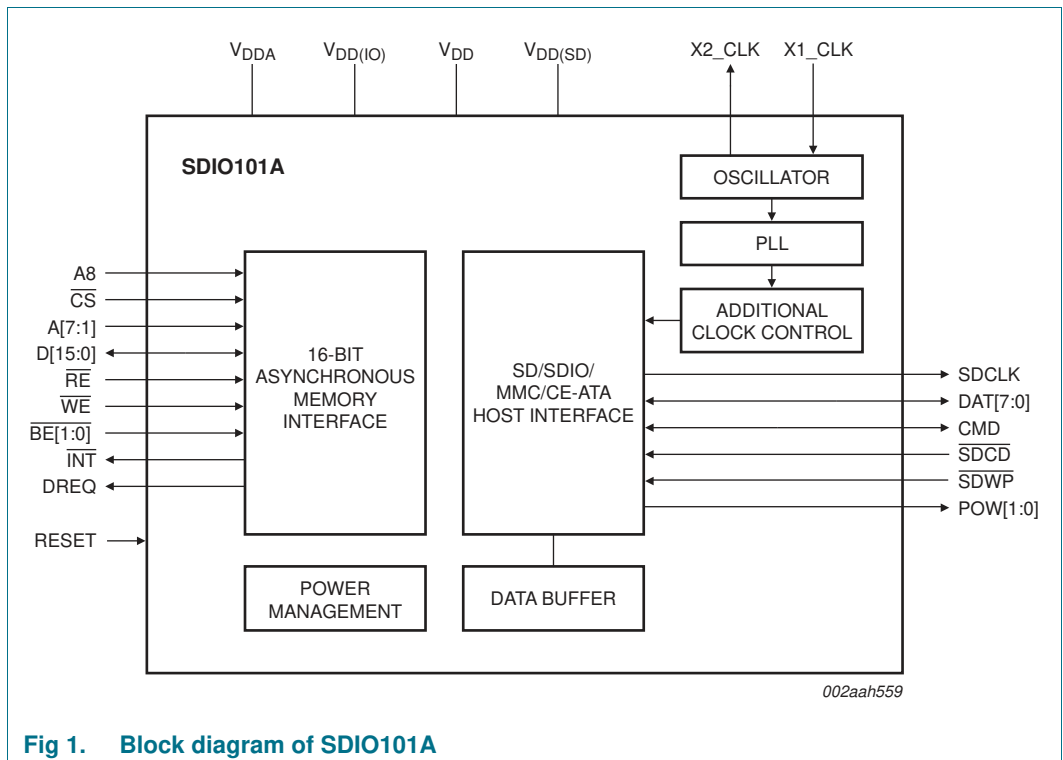
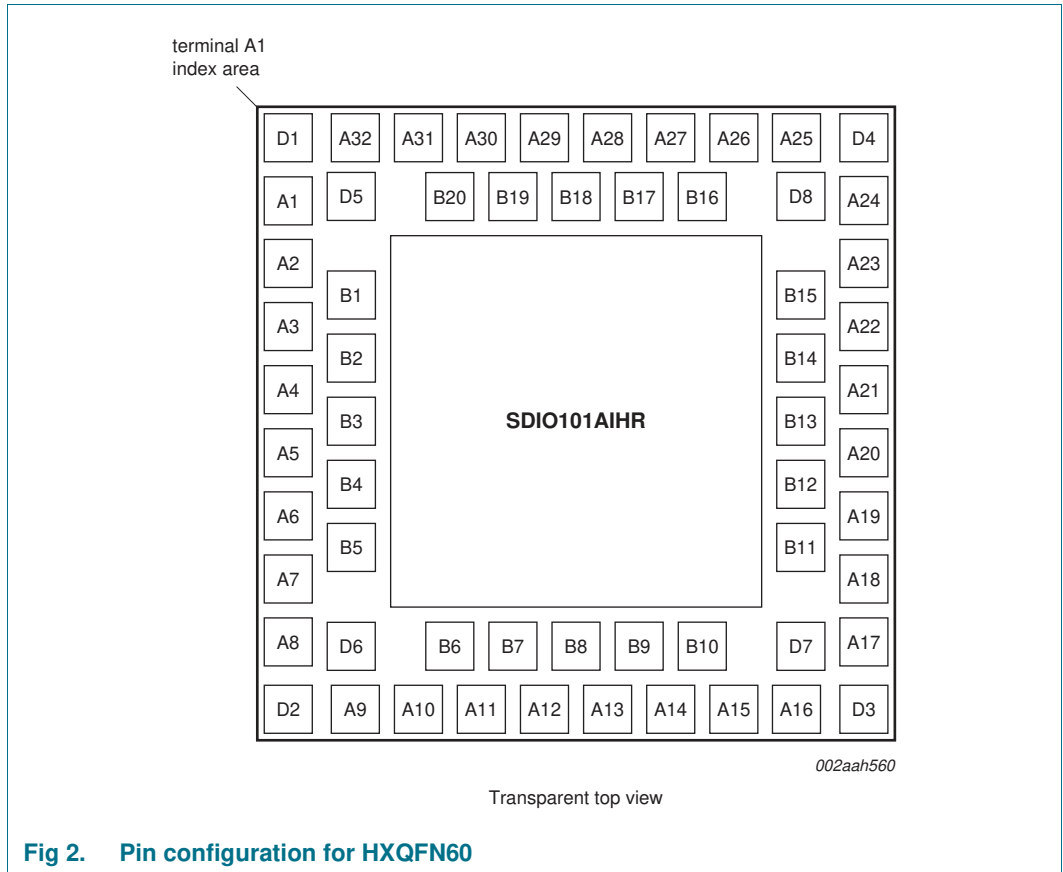


Fig 1. Block diagram of SDIO101A

5. Pinning information

5.1 Pinning



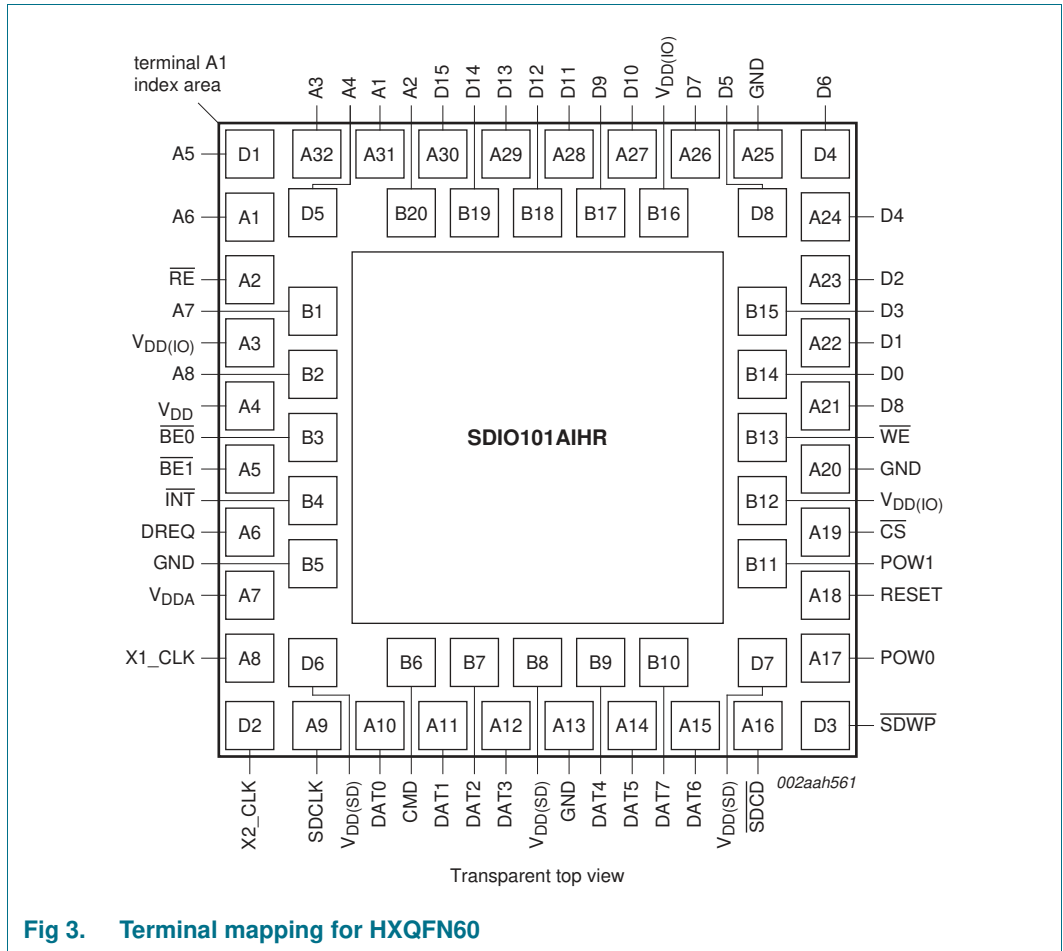


Fig 3. Terminal mapping for HXQFN60

5.2 Pin description

5.2.1 Pin description by function

Following are the signal descriptions on the SDIO101A interfaces. Pins are organized by function.

Table 3. Pin description by function

B = bidirectional; I = input; O = output; n.c. = not connected.

| Symbol | Pin | Type | Description |
|--|----------|------|--|
| SD/SDIO/MMC/CE-ATA interface signals | | | |
| SDCLK | A9 | O | SD clock output. This output clock is driven by the host controller during read and write transactions. |
| CMD | B6 | B | SD command line. This bidirectional signal is used to transfer commands and responses between the host and the card. |
| DAT0 | A10 | B | SD Data bit 0. |
| DAT1 | A11 | B | SD Data bit 1. |
| DAT2 | B7 | B | SD Data bit 2. |
| DAT3 | A12 | B | SD Data bit 3. |
| DAT4 | B9 | B | SD Data bit 4. |
| DAT5 | A14 | B | SD Data bit 5. |
| DAT6 | A15 | B | SD Data bit 6. |
| DAT7 | B10 | B | SD Data bit 7. |
| SDCD | A16 | I | SD card detect (active LOW). This pin can be used to detect insertion and removal of SD/SDIO/MMC cards. |
| SDWP | D3 | I | SD write protect (active LOW). This pin can be used to detect if the inserted SD/SDIO/MMC card is write protected. |
| System interface signals | | | |
| X1_CLK | A8 | I | Clock input. Must be connected to the system clock which is used to generate the host bus interface (see Section 6.4.3.1). |
| X2_CLK | D2 | O | Clock output. |
| RESET | A18 | I | Asynchronous reset (active HIGH). This active HIGH input pin unconditionally resets the entire device. |
| Card power supply control interface signals | | | |
| POW[1:0] | B11, A17 | O | SD power supply control bits. These bits can be used to control the voltage of an external power supply for the SD/SDIO/MMC/CE-ATA device. See Table 5 for details. |

Table 3. Pin description by function ...continued*B = bidirectional; I = input; O = output; n.c. = not connected.*

| Symbol | Pin | Type | Description |
|---------------------------------------|--|------|--|
| Host Interface control signals | | | |
| $\overline{\text{CS}}$ | A19 | I | Chip Select (active LOW). |
| A[7:1] | B1, A1, D1, D5, A32, B20, A31 | I | Address lines. Can be used to address the 256 bytes of the Standard Host register space. |
| A8 | B2 | I | Address 8. When accessing SDIO101A transmit or receive buffer under DMA control, this pin must be HIGH. This pin must be LOW when accessing other registers or when accessing transmit or receive buffer under interrupt control. |
| D[15:0] | A30, B19, A29, B18, A28, A27, B17, A21, A26, D4, D8, A24, B15, A23, A22, B14 | B | Data lines. Used to transfer data between host controller and the processor. |
| $\overline{\text{RE}}$ | A2 | I | Read Enable (active LOW). Initiates a read transaction when active. |
| $\overline{\text{WE}}$ | B13 | I | Write Enable (active LOW). Initiates a write transaction when active. |
| $\overline{\text{BE}}[1:0]$ | A5, B3 | I | Byte write enables (active LOW). When $\overline{\text{BE}}[0]$ is active, the least significant byte on the data bus can be written. When $\overline{\text{BE}}[1]$ is active, the most significant byte on the data bus can be written. |
| $\overline{\text{INT}}$ | B4 | O | Interrupt request (active LOW). Can be configured as push/pull or open-collector output. |
| DREQ | A6 | O | DMA request. |
| Power interface signals | | | |
| V_{DD} | A4 | - | Core power supply pin, 1.8 V. |
| V_{DDA} | A7 | - | Analog power supply, 1.8 V. |
| $V_{\text{DD(SD)}}$ | D6, B8, D7 | - | SD power supply pins, 1.8 V to 3.3 V. |
| $V_{\text{DD(IO)}}$ | B12, B16, A3 | - | Host interface power supply pins, 2.5 V to 3.3 V. |
| GND | B5, A13, A20, A25 ^[1] | - | Ground. |
| GND | center pad ^[1] | - | Ground. |

[1] HXQFN60 package die supply ground is connected to both GND pins and exposed center pad. GND pins must be connected to supply ground for proper device operation. For enhanced thermal, electrical, and board level performance, the exposed pad needs to be soldered to the board using a corresponding thermal pad on the board and for proper heat conduction through the board, thermal vias need to be incorporated in the PCB in the thermal pad region.

6. Functional description

The SDIO101A offers the SD Standard Host register set as defined in the *SD Host Standard Specification Version 2.0* (see [Ref. 1](#)), through which the Host Driver software can configure the host controller and initiate transactions to and from an SD/SDIO/MMC/CE-ATA target. On top of the Standard Host registers, 4 extra registers are available in the Host Controller register space, which can be used to control the additional features in the SDIO101A. These features are described in detail in [Section 6.4](#). [Section 6.2](#) gives an overview of the SDIO101A register set.

6.1 DMA mode

The SDIO101A supports slave DMA where the transferring of data between the host and the SDIO101A is under the control of the host's DMA controller. In this mode, the software can program DMA burst size (number of 16-bit words per DMA cycle) as well as the delay between back-to-back DMA requests from SDIO101A.

In DMA mode, Buffer Data Port 0 (0x20) and Buffer Data Port 1 (0x22) are mapped differently than in Interrupt mode — address line A8 must be at logic 1 when Buffer Data Ports are being accessed while the rest of the address lines are ignored by the SDIO101A. Once the DMA operation starts, all the accesses to the SDIO101A with A8 set to logic 1 will be considered as Buffer Data Ports access. To access other SDIO101A internal registers, address A8 must be set to logic 0.

The total number of DMA accesses to the Buffer Data Ports must be an even number. The first access from the host will be to Buffer Data Port 0, and the second access will be to Buffer Data Port 1. The SDIO101A will automatically alternate between Buffer Data Port 0 and Buffer Data Port 1 on each access by the host. This scheme allows the SDIO101A Buffer Data Ports to look like a continuous block of memory or FIFO to the DMA controller.

There are two registers that must be programmed for the SDIO101A to support DMA operation:

- Miscellaneous register (0xF8) bit 1 (enable slave DMA) must be set to logic 1.
- DMA burst size and DMA inter delay (back-to-back DREQs) must be programmed through DMA register (0xF4). DMA register bit [8:0] programs the DMA burst size (the number of 16-bit words to be transferred between the DMA controller and the SDIO101A), and DMA register bit [15:9] programs the delay time between two back-to-back DMA requests from SDIO101A (the inter delay value in bit [15:9] represents the number of SD clocks).

6.1.1 DMA read

When the receive buffer is empty, DREQ is at LOW state. Once the receive buffer has at least the number of 16-bit words equal to the programmed DMA burst size (DMA register [8:0]) DREQ goes HIGH. The DMA controller then can perform a block read of the receive buffer with the block size equal to the programmed DMA burst size in the DMA register.

The DREQ will go LOW once a block of data has been read from the SDIO101A's receive buffer, and DREQ will remain LOW for a period defined by DMA register bit [15:9]. The DREQ signal will go HIGH again if the receive buffer still holds at least the burst size of 16-bit word data.

6.1.2 DMA write

When the transmit buffer is empty, DREQ is at HIGH state. The DMA controller then can perform a block write to the receive buffer with the block size equal to the programmed DMA burst size programmed in DMA register [9:0].

The DREQ will go LOW once a block of data has been written to the SDIO101A's transmit buffer, and DREQ will remain LOW for a period defined by DMA register bit [15:9]. The DREQ signal will go HIGH again if the transmit buffer still has space to hold at least the burst size of 16-bit word data.

6.2 Standard Host register overview

Table 4. SD Host Controller register map

| Offset | Bits 15:8 | Bits 7:0 | Offset | Bits 15:8 | Bits 7:0 |
|---------------------|---|-------------------|---------------------|---|--------------|
| 0x02 | System Address (high) | | 0x00 | System Address (low) | |
| 0x06 | Block Count | | 0x04 | Block Size | |
| 0x0A | Argument1 | | 0x08 | Argument0 | |
| 0x0E | Command | | 0x0C | Transfer Mode | |
| 0x12 | Response1 | | 0x10 | Response0 | |
| 0x16 | Response3 | | 0x14 | Response2 | |
| 0x1A | Response5 | | 0x18 | Response4 | |
| 0x1E | Response7 | | 0x1C | Response6 | |
| 0x22 | Buffer Data Port1 | | 0x20 | Buffer Data Port 0 | |
| 0x26 | Present State | | 0x24 | Present State | |
| 0x2A | Wake-up Control | Block Gap Control | 0x28 | Power Control | Host Control |
| 0x2E | Software Reset | Time-out Control | 0x2C | Clock Control | |
| 0x32 | Error Interrupt Status | | 0x30 | Normal Interrupt Status | |
| 0x36 | Error Interrupt Status Enable | | 0x34 | Normal Interrupt Status Enable | |
| 0x3A | Error Interrupt Signal Enable | | 0x38 | Normal Interrupt Signal Enable | |
| 0x3E | reserved | | 0x3C | Auto CMD12 Error Status | |
| 0x42 | Capabilities | | 0x40 | Capabilities | |
| 0x46 | Capabilities (reserved) | | 0x44 | Capabilities (reserved) | |
| 0x4A | Maximum Current Capabilities | | 0x48 | Maximum Current Capabilities | |
| 0x4E | Maximum Current Capabilities (reserved) | | 0x4C | Maximum Current Capabilities (reserved) | |
| 0x52 | (reserved) | | 0x50 ^[1] | IO-cell Configuration | |
| - | - | | - | - | |
| 0xF6 ^[1] | Secondary Clock Control | | 0xF4 ^[1] | DMA register | |
| 0xFA ^[1] | PLL | | 0xF8 ^[1] | Miscellaneous | |
| 0xFE | Host Controller Version | | 0xFC | Slot Interrupt Status | |

[1] This register is not part of the Standard Host register set.

6.3 Standard Host register set description

The SDIO101A registers that are part of the Standard Host register set are described in detail in [Ref. 1](#). In this paragraph, we will only describe the specific implementation of the Standard register set in the SDIO101A that are different from [Ref. 1](#).

6.3.1 System Address register (offset 0x00)

Since master-DMA functionality is not implemented, all bits in this register will always read zero. Writes to this register will be ignored.

6.3.2 Block Size register (offset 0x04)

Data written to bits R[14:12] will be ignored. The maximum block size that can be programmed is 1 kB. Any block size higher than that will default to 1 kB.

6.3.3 Transfer Mode register (offset 0x0C)

Since master-DMA functionality is not implemented, bit R[00] will always read zero. Writes to this bit will be ignored.

6.3.4 Present State register (offset 0x24)

The SDIO101A supports multiple buffers, that is, the available data buffer space (2 kB) is larger than the Maximum Block Size (1 kB). The Buffer Write Enable bit R[10] indicates that there is room to write at least one more single block length (as specified in the Block Size register) in the data buffer even though previously-written blocks might still be present. Similarly, the Buffer Read Enable R[11] bit indicates that there is at least one single block length (as specified in the Block Size register) available in the data buffer.

6.3.5 Host Control register (offset 0x28)

A separate LED control pin SDLD is **not** supported in the SDIO101A. If desired, the user can use a GPIO pin on the Host Processor to implement this functionality. Bit R[00] in the Host Control register will always read zero, and writing to it will have no effect.

6.3.6 Power Control register (offset 0x29)

Bits R[03:00] control the POW[1:0] pins of the SDIO101A, which can be used to control an external power supply that powers the SD/SDIO/MMC/CE-ATA device. Two power modes are supported: 'normal' and 'low power'. It is up to the user to decide what voltage to associate with normal and low-power modes, but a typical implementation is 3.3 V for normal and 1.8 V for low-power mode. [Table 5](#) shows the relation between the Power Control register and the POW[1:0] pins.

Table 5. Relation between the Power Control register and the POW[1:0] pins

| Power Control register R[03:00] | POW[1:0] | Description |
|---------------------------------|----------|----------------------------|
| xxx0b | 00b | SD power off |
| 1011b | 01b | SD low power (1.8 V) on |
| 1101b | 10b | SD normal power (3.3 V) on |
| 1111b | 10b | SD normal power (3.3 V) on |

6.3.7 Capabilities register (offset 0x40)

The SDIO101A Capabilities register contents are shown in [Table 6](#).

Table 6. Contents of the Capabilities register (offset 0x40)

| Location | Attribute | Default | Description |
|----------|-----------|---------|--|
| 63:30 | reserved | 00h | reserved |
| 29 | reserved | 1b | reserved |
| 28 | reserved | 1b | reserved |
| 27 | reserved | 1b | reserved |
| 26 | R | 1b | low voltage (1.8 V) supported |
| 25 | R | 0b | 3.0 V not supported (defaults to normal voltage) |
| 24 | R | 1b | normal voltage (3.3 V) supported |
| 23 | R | 1b | suspend/resume supported |
| 22 | R | 0b | master DMA not supported |
| 21 | R | 1b | high-speed SD (> 25 MHz) supported |
| 20:18 | R | 001b | 8-bit supported |
| 17:16 | R | 10b | 2 kB maximum block length |
| 15:14 | reserved | 00h | reserved |
| 13:08 | R | 00h | get info through other method (Ref. 1) |
| 07 | R | 1b | time-out clock unit in MHz |
| 06 | reserved | 0b | reserved |
| 05:00 | R | 00h | get info through other method (Ref. 1) |

6.4 Additional register set description

The additional registers are not part of the *SD Host Standard Specification Version 2.0* (see [Ref. 1](#)). These registers do not have to be initialized, so Standard Host Driver software does not have to be aware of them.

6.4.1 IO Configuration register (offset 0x50)

The IO Configuration register offers three bits to set the drive strength of the IO cell used for driving the SDCLK pin. This way the user can adjust SDCLK rise/fall times according to their system performance requirements. Typically, drive strength should be set to LOW when the SD slot is operating on normal (2.7 V to 3.3 V) voltage, and to HIGH when the SD slot is operating on low voltage (1.8 V). Also, a bit is offered to disable the default pull-up resistors on the SD CMD and SD DATn lines, in case they are not required and the possible leakage current through these resistors is undesired.

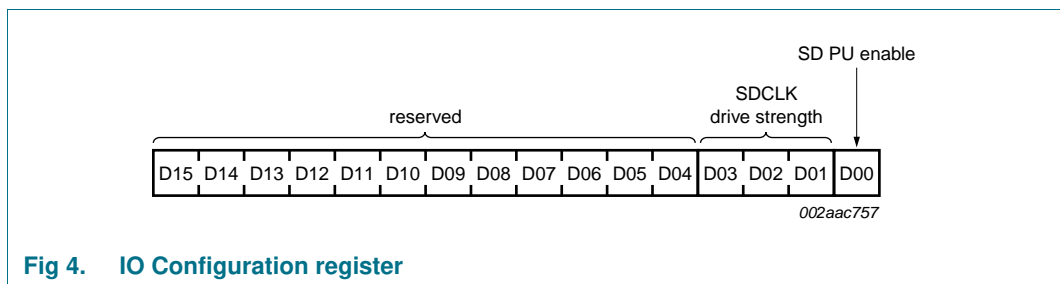


Fig 4. IO Configuration register

Table 7. Contents of the IO Configuration register (offset 0x50)

| Location | Attribute | Default | Description |
|----------|-----------|---------|--|
| 15:04 | reserved | 0h | reserved |
| 03:01 | R/W | 0h | SDCLK drive strength select. These bits can be used to program the drive strength of the SDCLK IO cell. Table 8 shows the possible values. |
| 00 | R/W | 0b | SD line pull-up. If set to b1, the internal pull-up resistors on the SD CMD and SD DATn lines are switched ON. |

Table 8. SDCLK drive strength programming

| IO Configuration register R[03:01] | SDCLK drive strength |
|------------------------------------|--------------------------------------|
| 000b | low (SD operating on 2.7 V to 3.6 V) |
| 0001b | reserved |
| 010b | reserved |
| 011b | reserved |
| 100b | high (SD operating on 1.8 V) |
| 101b | reserved |
| 110b | reserved |
| 111b | reserved |

6.4.2 DMA register (offset 0xF4)

The DMA register is located in the Common register area. This register controls the DREQ output. The DREQ LOW and HIGH times are programmed with DMA inter delay and DMA burst size.

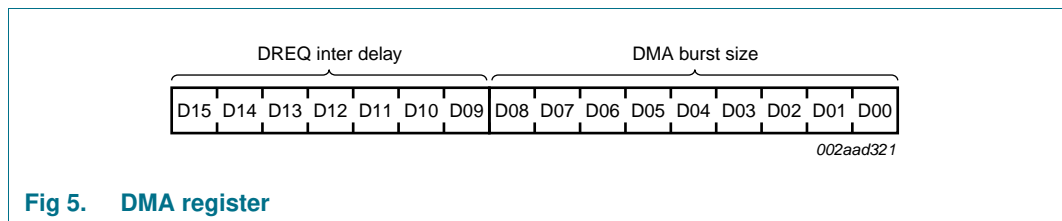


Fig 5. DMA register

Table 9. DREQ control programming

| Location | Attribute | Default | Description |
|----------|-----------|---------|---|
| 15:09 | R/W | 0h | DREQ delay period (DREQ LOW time) LOW time = value × SD clock cycle time |
| 08:01 | R/W | 0h | DMA burst size (DREQ HIGH time) |

Remark: Refer to [Section 6.1](#) for more detailed DMA description.

6.4.3 Secondary Clock Control register (offset 0xF6)

The Secondary Clock Control register is located in the Common register area. This register gives the user more control over the clock generation. An additional fractional divider is offered to program the SDCLK base frequency with higher granularity, allowing the design to use an existing (available) clock rather than an external crystal or oscillator. Figure 6 shows the architecture of the secondary clock control.

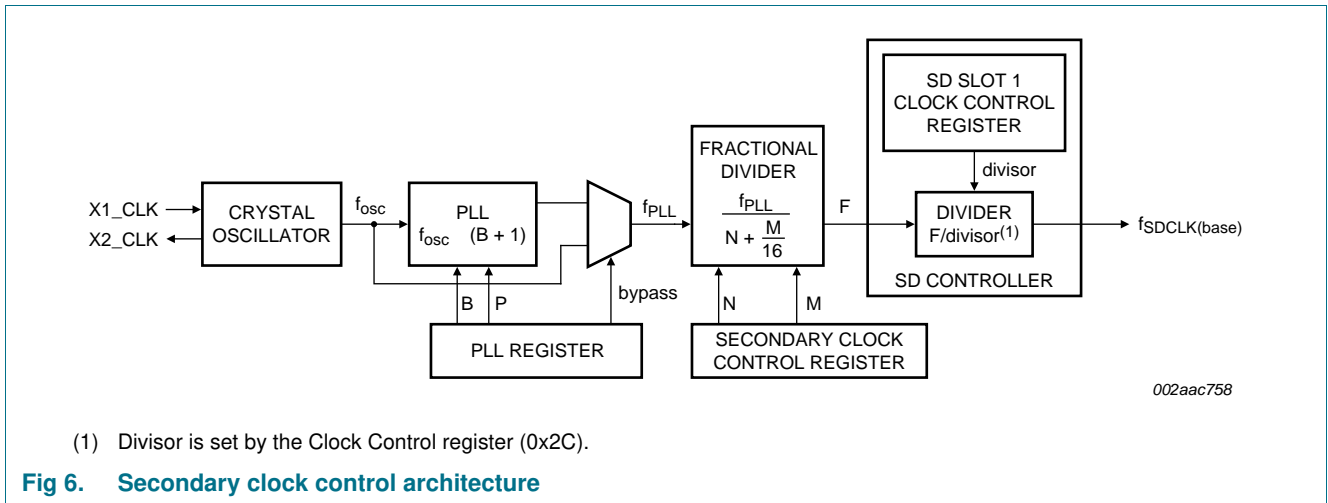


Fig 6. Secondary clock control architecture

The SDCLK base frequency can be calculated with Equation 1¹:

$$f_{SDCLK(base)} = \frac{f_{PLL}}{divisor \left(N + \frac{M}{16} \right)} \tag{1}$$

Where 'divisor' is the standard divisor as programmed in the Clock Control register; N is the integer divisor as programmed in the Secondary Clock Control register R[07:00]; M is the fractional divisor as programmed in the Secondary Clock Control register R[11:08]. Figure 7 and Table 10 below show the register bits of the Secondary Clock Control register.

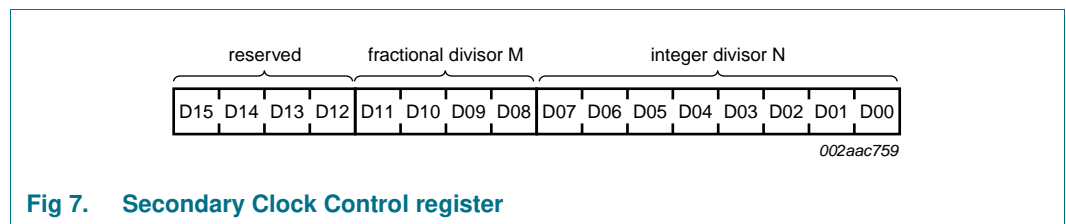


Fig 7. Secondary Clock Control register

Table 10. Contents of the Secondary Clock Control register (offset 0xF6)

| Location | Attribute | Default | Description |
|----------|-----------|---------|----------------------------|
| 15:12 | reserved | 00h | reserved |
| 11:08 | R/W | 00h | fractional divisor value M |
| 07:00 | R/W | 01h | integer divisor value N |

1. This is the average SD clock frequency. The peak SD clock frequency might be higher when the fractional divisor M is used.

6.4.3.1 SDIO101A X1_CLK input

It is recommended that the SDIO101A's input clock be connected to one of the systems available clock sources to eliminate the use of an external crystal. The best use case is to have the SDIO101A's X1_CLK input be connected to the processor's clock output (Figure 8) or processor's crystal output (Figure 9). In either case, the SDIO101A internal PLL can be used to boost up the X1_CLK input then divided down to the desired SDIO clock by using the internal divider in combination with the built-in fractional divider.

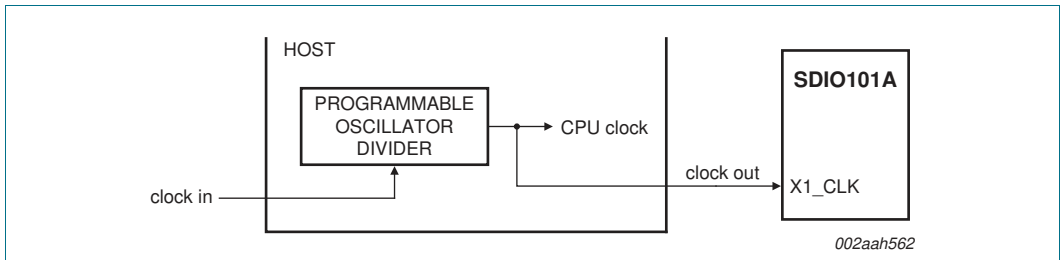


Fig 8. X1_CLK connected to processor's system clock

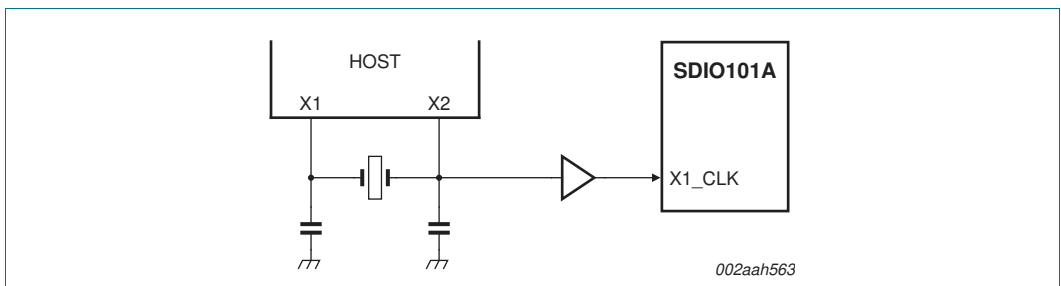


Fig 9. X1_CLK connected to processor crystal clock output

Figure 10 details a typical scenario where the host processor uses a 13 MHz crystal as its clock source, and the same clock is used by the SDIO101A to operate the SD clock as close to 50 MHz as possible.

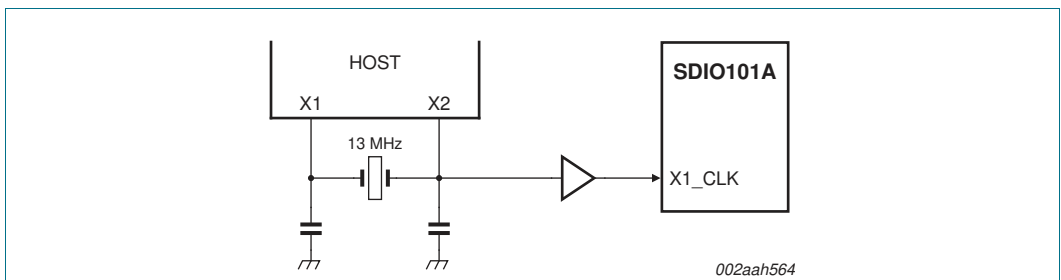


Fig 10. Host processor using 13 MHz crystal as clock source

With its input clock supplies by the processor crystal output, the SDIO101A internal PLL (0xFA) is used to boost the input frequency to 104 MHz, the standard Clock Control register (0x2C) and the fractional divider (0xF6) registers are then used to divide the 104 MHz to about 48.9 MHz to be used as SD clock.

PLL register (0xFA) settings:

- Bit 15 = 0b
- Bit 14 = 0b
- Bit [13:7] = 0000000b
- Bit [6:5] = 01b
- Bit [4:0] = 00111b; B = 7

Fractional divider (0xF6) settings:

- Bit [15:12] = 0000b; reserved bit
- Bit [11:8] = 0001b; M = 1
- Bit [7:0] = 00000001b; N = 1

Clock Control register (0x2C) settings:

- Bit [15:0] = 103h

$$f_{SDCLK(base)} = \frac{f_{PLL}}{divisor \left(N + \frac{M}{16} \right)}$$

$$= (13 \text{ MHz} \times 8) / (2 \times (1 + 1 / 16))$$

$$= 48.9 \text{ MHz}$$

6.4.4 Miscellaneous register (offset 0xF8)

The Miscellaneous register is located in the Common register area. This register can be programmed to put the device in the ‘Coma mode’ or ‘Hibernate mode’, extra-low power-down modes on top of the Standby mode programmable through bit R[00] in the Clock Control register. Also, a bit is offered to disable the DREQ DMA request line on the Host Interface. Lastly, a bit is offered to switch between open-drain and push-pull mode for the $\overline{\text{INT}}$ interrupt output pin. [Figure 11](#) and [Table 11](#) below show the register bits of the Miscellaneous register.

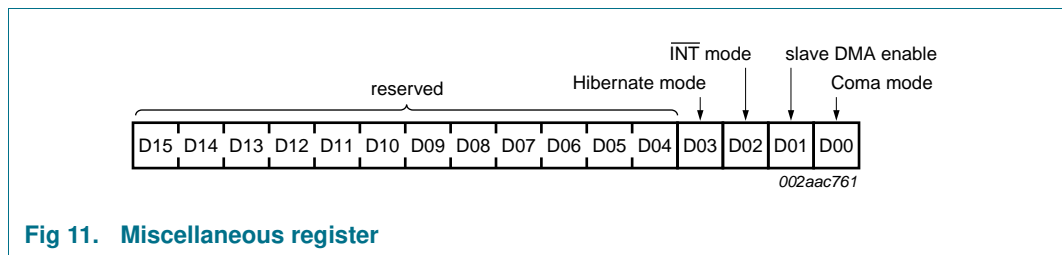


Fig 11. Miscellaneous register

Table 11. Contents of the Miscellaneous register (offset 0xF8)

| Location | Attribute | Default | Description |
|----------|-----------|---------|---|
| 15:04 | reserved | 00h | reserved |
| 03 | R/W | 0b | Hibernate mode select. When set to 1b, the oscillator, PLL and supply to the buffer memory will be switched OFF. Card detection is disabled. Clearing this bit will re-instate power to the buffer memory, the oscillator and PLL are enabled. |
| 02 | R/W | 0b | INT mode select. When set to 0b, the $\overline{\text{INT}}$ interrupt output pin will be open-drain mode. An external 10 k Ω pull-up resistor is required in this case. When set to 1b, the INT interrupt output pin will be in push-pull mode. |
| 01 | R/W | 1b | Slave DMA enable. If programmed to 1b, the DREQ signal will be functional. If programmed to 0b, the DREQ signal will be fixed to zero. |
| 00 | R/W | 0b | Coma mode. If programmed to 1b, power will internally be switched off to most of the device, resulting in a very low coma mode current. All state in the device will be lost, and no registers can be read or written, with the exception of the 'Software Reset for All' bit in the Software Reset register. Clearing this bit will re-instate power to the entire chip, and reset the SDIO101A. A hard-reset on the RESET pin will also bring the device back out of Coma mode. |

6.4.5 PLL register (offset 0xFA)

The PLL register is located in the Common register area. This register provides control over the Phase-Locked Loop, which is used in the SDIO101A to generate an SD base clock frequency from the crystal oscillator or external clock source. The default values of this register are such that the PLL multiplies the incoming frequency from the crystal oscillator by 5. This means that, if the PLL register is not programmed, the frequency generated by the crystal oscillator or external clock source should be 10.4 MHz in order to generate the 52 MHz maximum SDCLK speed. For the SD base clock frequency generated by the PLL from the Crystal oscillator frequency it holds

$$f_{PLL} = (B + 1) \times f_{CLK} \tag{2}$$

where B is the feedback divider value as programmed in R[04:00] of the PLL register. The user should determine the desired f_{PLL} , choose the required value B for the feedback divider based on the available clock source f_{OSC} , and then choose a value for post divider P (as programmed in R[06:05]) such that the following condition gets satisfied:

$$156 \text{ MHz} < 2 \times (P + 1) \times f_{PLL} < 320 \text{ MHz} \tag{3}$$

The post divider setting decided by the value of P does not affect the frequency value (in MHz) of the f_{PLL} . The only advantage of this post divider is in adjusting the duty cycle of the resulting f_{PLL} clock. The greater the value of P, the closer the duty cycle will be to 50 % (provided the condition mentioned in [Equation 3](#) is not violated, for a guaranteed behavior).

The PLL register also provides the possibility to bypass the PLL post divider, effectively setting a value of 1 for P. Also, the user can bypass the entire PLL. [Figure 12](#) and [Table 12](#) show the register bits of the PLL register.

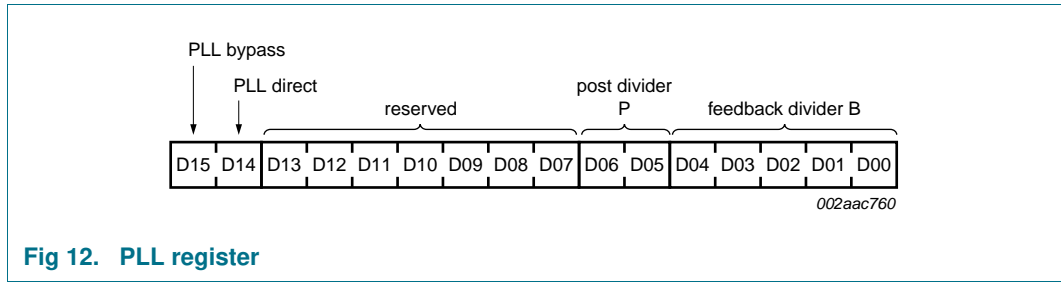


Table 12. Contents of the PLL register (offset 0xFA)

| Location | Attribute | Default | Description |
|----------|-----------|---------|--|
| 15 | R/W | 1b | PLL bypass. If this bit is 1b, the PLL is bypassed. The SDCLK base frequency is then equal to the frequency provided by the oscillator, either generated by a crystal or generated by an external clock. If this bit is 0b, the PLL is not bypassed. |
| 14 | R/W | 1b | PLL direct. If this bit is 1b, the post divider of the PLL is bypassed, effectively setting the post divider value P to 1b. In this mode, the duty cycle out of the PLL can be unequal to 50 %. If set to 0b, the post divider P is used, and its value is determined by R[06:05] of the PLL register. |
| 13:07 | reserved | 00h | reserved |
| 06:05 | R/W | 01h | PLL post divider P |
| 04:00 | R/W | 04h | PLL feedback divider B |

6.4.6 Host Controller Version register (offset 0xFE)

The SDIO101A Host Controller version is shown in [Table 13](#).

Table 13. Contents of the Host Controller Version register (offset 0xFE)

| Location | Attribute | Default | Description |
|----------|-----------|---------|-------------------------|
| 15:08 | R | 10h | SDIO101A version 1.0 |
| 07:00 | reserved | 00h | reserved ^[1] |

[1] These bits do not match Host Controller specification. Host driver should not use these bits.

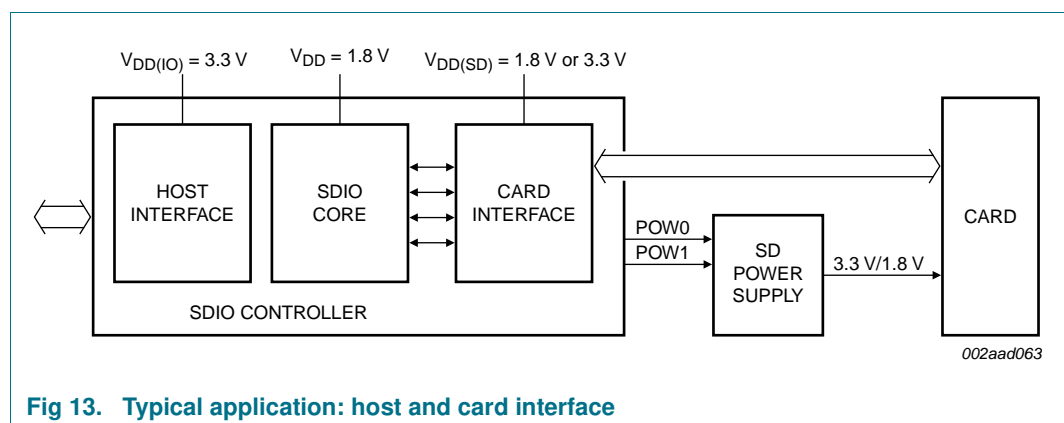
6.5 Power-saving modes

The SDIO101A provides 5 power-saving modes that can be used in different situations to minimize the power consumption of the device. [Table 14](#) below describes these modes and their associated register bits that can be programmed to enable them. Idle, Low Power and Standby modes can be used if card interrupts should still be serviced. The Hibernate mode will switch off the power to the SD device and the Coma mode switches off most of the Host Controller, therefore, card interrupts will not be generated. [Table 14](#) shows the 5 power-saving modes.

Table 14. SDIO101A Power-saving modes

| Mode | Associated register bits | Description |
|----------------|------------------------------|--|
| Idle mode | Clock Control register R[02] | SD Card clock stopped; oscillator and PLL are active. |
| Low-Power mode | Power Control register R[00] | SD Card power switched off. |
| Standby mode | Clock Control register R[00] | When the Clock Control register R[00] is set to b0, the SDIO101A internal clock is stopped, the PLL is in Power-down mode, the oscillator is active and all register states are maintained. The device will still respond to card interrupts. When waking up from Standby mode, after writing a b1 in the Clock Control register R[00], the data buffer FIFO pointers will reset to empty. |
| Coma mode | Miscellaneous register R[00] | When the Miscellaneous register R[00] is set to b1, the SDIO101A internal power is switched off. All device pins are 3-stated, and only a write to the 'Software Reset for All' bit in the Software Reset register or a hard reset on the RESET pin will wake up the device. All device states, including data buffer contents, are lost. Card insertion and removal detection through the SDCD pin is disabled. |
| Hibernate mode | Miscellaneous register R[03] | The oscillator, PLL and supply to the buffer memory will be switched off. All states are maintained, but data buffer contents are lost. Card insertion and removal detection through the SDCD pin is disabled. Upon wake-up, the data buffer FIFO pointers will reset to empty. |

7. Application design-in information



8. Basic architecture

The SDIO101A provides SD/SDIO/MMC/CE-ATA functionality to a microprocessor system as illustrated in [Figure 14](#). A standard SD/SDIO/MMC/CE-ATA driver running on the host processor will be able to access the standard host register set in the SDIO101A through the 16-bit memory interface, and initiate transactions to and from the SD card. An external SD power supply (controlled by the SDIO101A) can be used to supply the SD card.

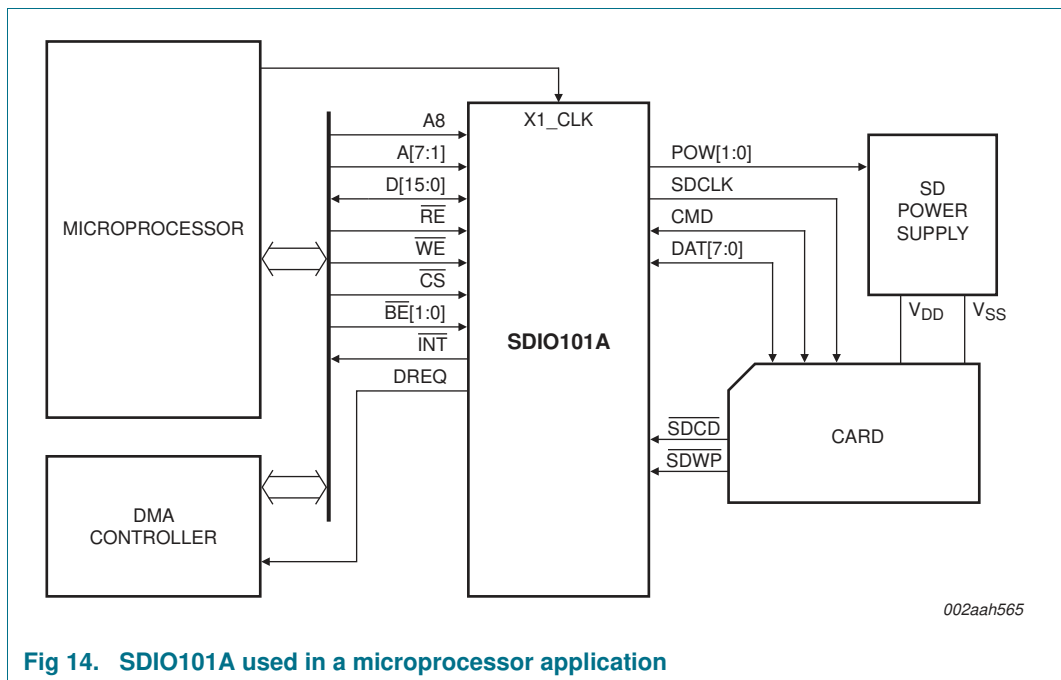


Fig 14. SDIO101A used in a microprocessor application

9. Limiting values

Table 15. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|---------------|---------------------------------|--|----------------|----------------|------|
| $V_{DD(I/O)}$ | input/output supply voltage | host interface; in 2.5 V to 3.3 V range | -0.3 | +4.6 | V |
| $V_{DD(SD)}$ | SD supply voltage | SD interface | | | |
| | | in 1.8 V range | -0.3 | +1.95 | V |
| | | in 3.3 V range | -0.3 | +3.6 | V |
| V_{DD} | supply voltage | core; 1.8 V range | -0.3 | +2.4 | V |
| V_I | input voltage | on any input pin | | | |
| | | 1.8 V interface | $V_{SS} - 0.3$ | $V_{DD} + 0.6$ | V |
| | | 3.3 V interface | -0.3 | +3.6 | V |
| T_{amb} | ambient temperature | operating | -40 | +85 | °C |
| T_{stg} | storage temperature | | -65 | +150 | °C |
| V_{ESD} | electrostatic discharge voltage | SD/MMC/SDIO interface; Human Body Model | -4 | +4 | kV |

10. Recommended operating conditions

Table 16. Operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|----------------|-----------------------------|---------------------------------|-----------------------|-----|------|------|
| V_{DD} | supply voltage | core | 1.65 | 1.8 | 1.95 | V |
| $V_{DD(I/O)}$ | input/output supply voltage | host interface | 2.25 | 3.3 | 3.6 | V |
| $V_{DD(SD)}$ | SD supply voltage | SD interface | 1.65 | 3.3 | 3.6 | V |
| $f_{clk(ext)}$ | external clock frequency | | [1] 1 | - | 52 | MHz |
| $I_{DD(AV)}$ | average supply current | $f = 13$ MHz; SDCLK = 25 MHz | - | 6 | - | mA |
| I_{DD} | supply current | Standby mode | - | 460 | - | μA |
| | | Hibernate mode | - | 69 | - | μA |
| | | Coma mode | - | 5 | - | μA |
| T_{oper} | operating temperature | | -40 | +25 | +85 | °C |

[1] If the PLL is not bypassed, the minimum input frequency is 10 MHz.

11. Static characteristics

Table 17. Static characteristics

| Symbol | Parameter | Conditions | $V_{DD(IO)} = 2.5\text{ V}$ | | $V_{DD(IO)} = 3.3\text{ V}$ | | Unit |
|--|----------------------------------|------------------------------|-----------------------------|----------|-----------------------------|----------|-------------------|
| | | | Min | Max | Min | Max | |
| $V_{IL(\text{clk})}$ | clock LOW-level input voltage | X1_CLK [1] | -0.3 | +0.6 | -0.3 | +0.6 | V |
| $V_{IH(\text{clk})}$ | clock HIGH-level input voltage | X1_CLK [1] | 2.4 | V_{DD} | 2.4 | V_{DD} | V |
| V_{IL} | LOW-level input voltage | | -0.3 | +0.65 | -0.3 | +0.8 | V |
| V_{IH} | HIGH-level input voltage | | 1.6 | V_{DD} | 2.1 | V_{DD} | V |
| V_{OL} | LOW-level output voltage | $I_{OL} = 2\text{ mA}$ | - | 0.4 | - | 0.4 | V |
| V_{OH} | HIGH-level output voltage | $I_{OH} = -800\ \mu\text{A}$ | 1.4 | - | 2.1 | - | V |
| I_{LIL} | LOW-level input leakage current | | - | 10 | - | 10 | μA |
| I_{LIH} | HIGH-level input leakage current | | - | 10 | - | 10 | μA |
| $I_{L(\text{clk})}$ | clock leakage current | X1_CLK | - | 30 | - | 30 | μA |
| C_i | input capacitance | | - | 5 | - | 5 | pF |
| Dynamic average supply current ($V_{DD(SD)} = 3.3\text{ V}$) | | | | | | | |
| $I_{DD(AV)}$ | average supply current | 25 MHz [2] | - | 7 | - | 7 | mA |
| | | 52 MHz [2] | - | 9 | - | 9 | mA |
| $I_{DD(IO)}$ | input/output supply current | 25 MHz [3] | - | 1.3 | - | 1.5 | mA |
| | | 52 MHz [3] | - | 1.3 | - | 1.5 | mA |
| $I_{DD(SD)}$ | SD supply current | 25 MHz | - | 1.5 | - | 1.5 | mA |
| | | 52 MHz | - | 2.3 | - | 2.3 | mA |
| Hibernate mode supply current ($V_{DD(SD)} = 3.3\text{ V}$) | | | | | | | |
| I_{DD} | supply current | | [2] | - | 130 | - | 130 μA |
| $I_{DD(IO)}$ | input/output supply current | 25 MHz | [3] | - | 20 | - | 20 μA |
| $I_{DD(SD)}$ | SD supply current | | | - | 1.5 | - | 1.5 μA |
| Standby mode supply current ($V_{DD(SD)} = 3.3\text{ V}$) | | | | | | | |
| I_{DD} | supply current | | [2] | - | 4 | - | 4 mA |
| $I_{DD(IO)}$ | input/output supply current | | [3] | - | 20 | - | 20 μA |
| $I_{DD(SD)}$ | SD supply current | | | - | 1.5 | - | 1.5 μA |
| Coma mode supply current ($V_{DD(SD)} = 3.3\text{ V}$) | | | | | | | |
| I_{DD} | supply current | | [2] | - | 0.6 | - | 0.6 μA |
| $I_{DD(IO)}$ | input/output supply current | | [3] | - | 20 | - | 20 μA |
| $I_{DD(SD)}$ | SD supply current | | | - | 0.5 | - | 0.5 μA |

[1] X1_CLK = 3.3 V only.

[2] I_{DD} is the supply on V_{DD} and V_{DDA} .

[3] $I_{DD(IO)}$ current might be higher or lower depending on the activity of the 16-bit data bus. The numbers specified in the data sheet are measured with no activity on the host controller bus. The data bus, address bus and control signals are pulled HIGH.

12. Dynamic characteristics

Table 18. Dynamic characteristics for 16-bit host bus interface

| Symbol | Parameter | Conditions | $V_{DD(IO)} = 2.5\text{ V}$ | | $V_{DD(IO)} = 3.3\text{ V}$ | | Unit |
|-------------------------|---|----------------------------|-----------------------------|--------|-----------------------------|--------|------|
| | | | Min | Max | Min | Max | |
| $t_{WL(X1_CLK)}$ | X1_CLK pulse width LOW | | 9 | - | 9 | - | ns |
| $t_{WH(X1_CLK)}$ | X1_CLK pulse width HIGH | | 9 | - | 9 | - | ns |
| f_{X1_CLK} | frequency on pin X1_CLK | | - | 52 | - | 52 | MHz |
| $t_{su(A)}$ | address set-up time | | 5 | - | 5 | - | ns |
| $t_{h(A)}$ | address hold time | | 10 | - | 5 | - | ns |
| $t_{h(WE-CS)}$ | hold time from \overline{WE} to \overline{CS} | | 0 | - | 0 | - | ns |
| $t_{d(CSL-WEL)}$ | delay time from \overline{CS} LOW to \overline{WE} LOW | | 0 | - | 0 | - | ns |
| $t_{w(WE)}$ | \overline{WE} pulse width | | 10 | - | 20 | - | ns |
| $t_{d(WE)}$ | \overline{WE} delay time | | 10 | - | 20 | - | ns |
| $t_{su(D-WEH)}$ | set-up time from data input to \overline{WE} HIGH | | 5 | - | 5 | - | ns |
| $t_{h(WEH-D)}$ | data input hold time after \overline{WE} HIGH | | 5 | - | 5 | - | ns |
| $t_{su(BEn)}$ | set-up time on pin \overline{BEn} | | 5 | - | 5 | - | ns |
| $t_{h(BEn)}$ | hold time on pin \overline{BEn} | | 5 | - | 5 | - | ns |
| $t_{h(RE-CS)}$ | hold time from \overline{RE} to \overline{CS} | | 0 | - | 0 | - | ns |
| $t_{d(CS-RE)}$ | delay time from \overline{CS} to \overline{RE} | | 0 | - | 0 | - | ns |
| $t_{w(RE)}$ | \overline{RE} pulse width | | 25 | - | 20 | - | ns |
| $t_{d(RE)}$ | \overline{RE} delay time | | 10 | - | 10 | - | ns |
| $t_{d(RE-Q)}$ | delay time from \overline{RE} to data output | 25 pF load | - | 20 | - | 25 | ns |
| $t_{dis(RE-QZ)}$ | disable time from \overline{RE} to high-impedance data output | 25 pF load | - | 20 | - | 15 | ns |
| $t_{w(RESET)}$ | pulse width on pin RESET | | 10 | - | 5 | - | ns |
| $t_{d(buf_full-INTL)}$ | delay time from buffer full to \overline{INT} LOW | receive buffer (receive) | - | 4XTAL1 | - | 4XTAL1 | ns |
| $t_{d(int_clr-INTH)}$ | delay time from interrupt clear to \overline{INT} HIGH | receive buffer (read) | - | 300 | - | 300 | ns |
| $t_{d(buf_emp-INTL)}$ | delay time from buffer empty to \overline{INT} LOW | transmit buffer (transmit) | - | 4XTAL2 | - | 4XTAL2 | ns |
| $t_{d(int_clr-INTH)}$ | delay time from interrupt clear to \overline{INT} HIGH | transmit buffer (write) | - | 80 | - | 80 | ns |
| $t_{su(A8)}$ | address 8 set-up time | | 5 | - | 5 | - | ns |
| $t_{su(A8-CS)}$ | set-up time from address 8 to \overline{CS} | | 5 | - | 5 | - | ns |
| $t_{d(SDCLK-DREQH)}$ | delay time from SDCLK to DREQ HIGH | | - | 20 | - | 15 | ns |
| $t_{d(CSH-DREQ)W}$ | write delay time from \overline{CS} HIGH to DREQ LOW | | - | 20 | - | 15 | ns |
| $t_{d(CSH-DREQ)R}$ | read delay time from \overline{CS} HIGH to DREQ LOW | | - | 20 | - | 15 | ns |

Table 19. Dynamic characteristics for MMC/SD/SDIO bus interface $V_{DD(SD)} = 2.7\text{ V to }3.3\text{ V}$.

| Symbol | Parameter | Conditions | 25 MHz | | 52 MHz | | Unit |
|-------------------------|-------------------|---------------------------------------|--------|-----|--------|-----|------|
| | | | Min | Max | Min | Max | |
| Clock | | | | | | | |
| t _{WL} | clock low time | 10 pF max. | 12 | - | 8 | - | ns |
| t _{WH} | clock high time | 10 pF max. | 12 | - | 8 | - | ns |
| t _{w(clk)} | clock pulse width | 10 pF max. | 40 | - | 18 | - | ns |
| t _{TLH} | clock rise time | 10 pF max. | - | 10 | - | 3 | ns |
| t _{THL} | clock fall time | 10 pF max. | - | 10 | - | 3 | ns |
| Input CMD, DATn | | | | | | | |
| t _{ISU} | input set-up time | 10 pF max. | 5 | - | 6 | - | ns |
| t _{IH} | input hold time | 10 pF max. | 5 | - | 2 | - | ns |
| Output CMD, DATn | | | | | | | |
| t _{ODLY} | output delay time | during data transfer mode; 40 pF max. | 0 | 14 | - | 14 | ns |
| t _{OH} | output hold time | | 2.5 | - | 2.5 | - | ns |

Table 20. Dynamic characteristics for MMC/SD/SDIO bus interface $V_{DD(SD)} = 1.70\text{ V to }1.95\text{ V}$.

| Symbol | Parameter | Conditions | 25 MHz | | 52 MHz | | Unit |
|-------------------------|-------------------|---------------------------------------|--------|-----|--------|-----|------|
| | | | Min | Max | Min | Max | |
| Clock | | | | | | | |
| t _{WL} | clock low time | 10 pF max. | 12 | - | 8 | - | ns |
| t _{WH} | clock high time | 10 pF max. | 12 | - | 8 | - | ns |
| t _{w(clk)} | clock pulse width | 10 pF max. | 40 | - | 18 | - | ns |
| t _{TLH} | clock rise time | 10 pF max. | - | 10 | - | 3 | ns |
| t _{THL} | clock fall time | 10 pF max. | - | 10 | - | 3 | ns |
| Input CMD, DATn | | | | | | | |
| t _{ISU} | input set-up time | 10 pF max. | 5 | - | 6 | - | ns |
| t _{IH} | input hold time | 10 pF max. | 5 | - | 2 | - | ns |
| Output CMD, DATn | | | | | | | |
| t _{ODLY} | output delay time | during data transfer mode; 40 pF max. | 0 | 14 | - | 14 | ns |
| t _{OH} | output hold time | | 2.5 | - | 2.5 | - | ns |

12.1 Timing diagrams

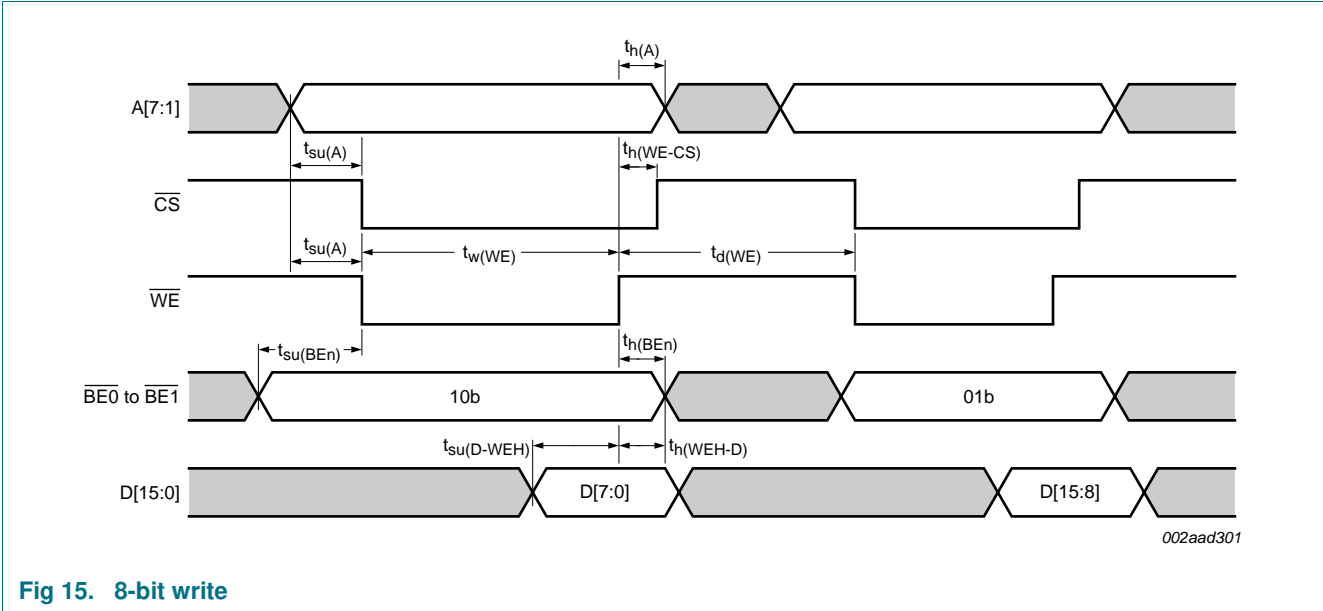


Fig 15. 8-bit write

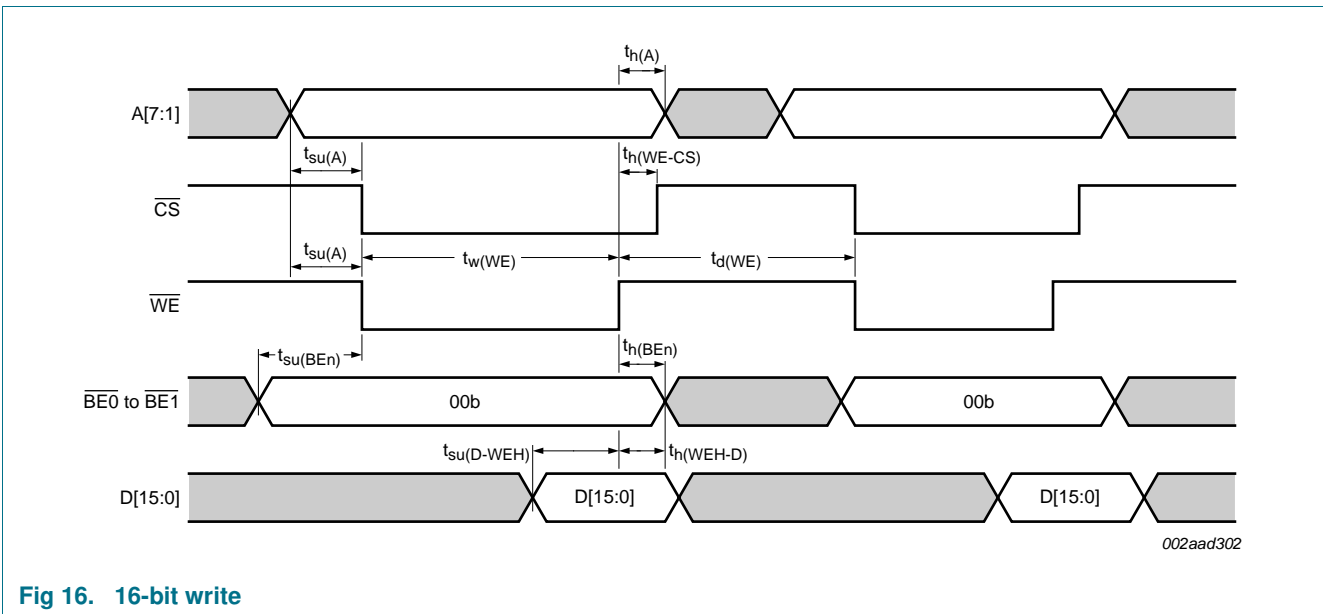


Fig 16. 16-bit write

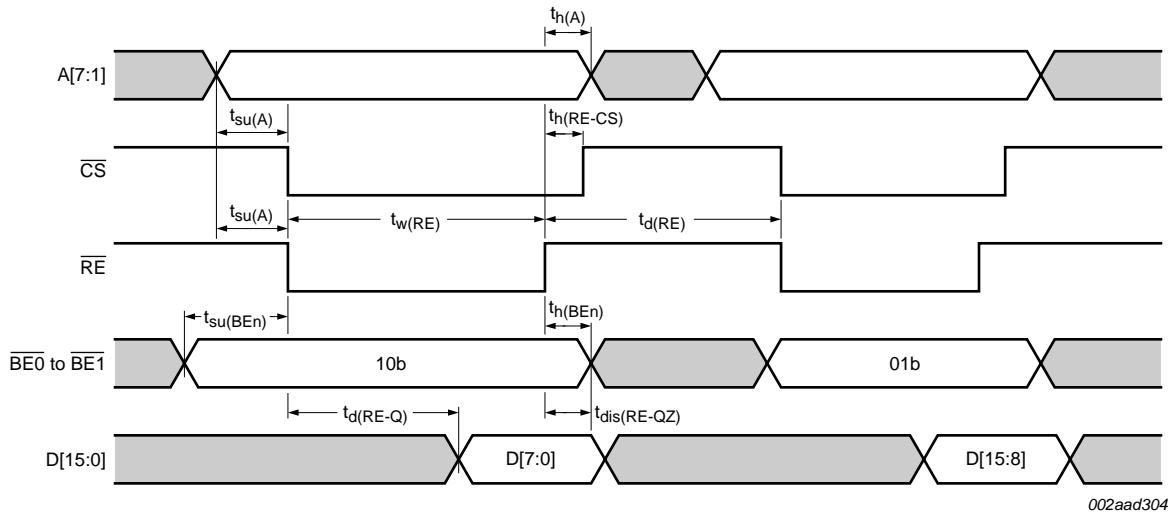


Fig 17. 8-bit read

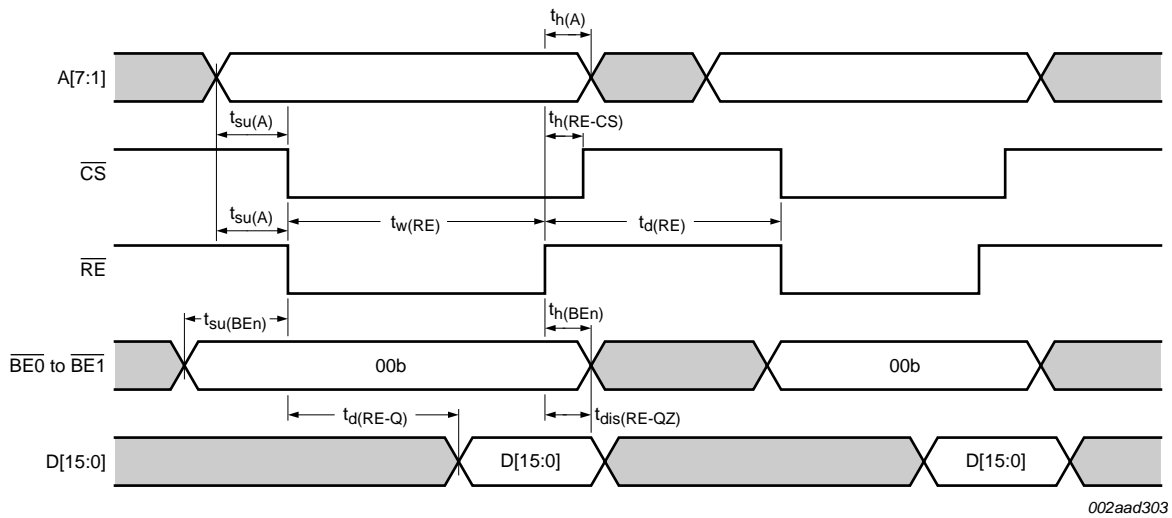


Fig 18. 16-bit read

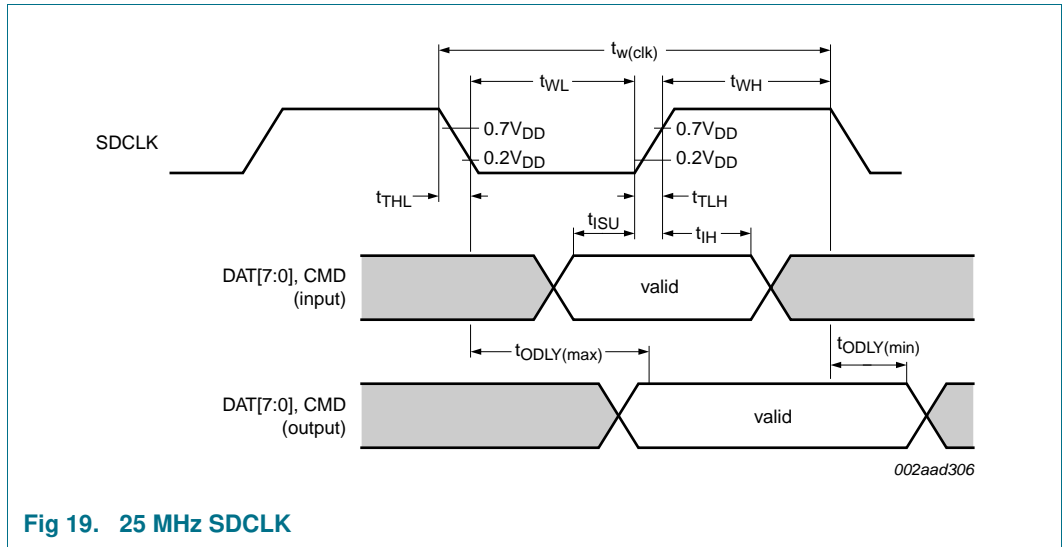


Fig 19. 25 MHz SDCLK

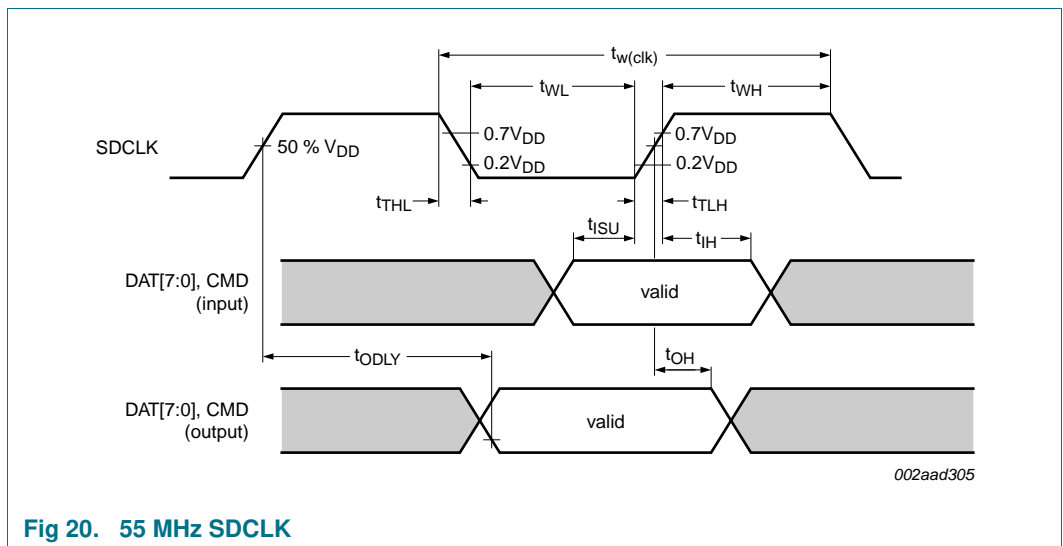


Fig 20. 55 MHz SDCLK

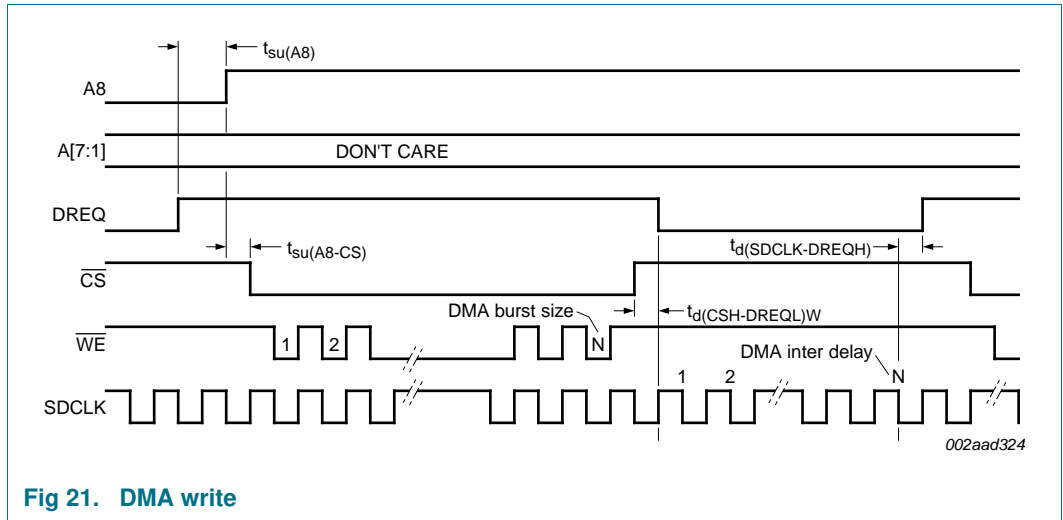


Fig 21. DMA write

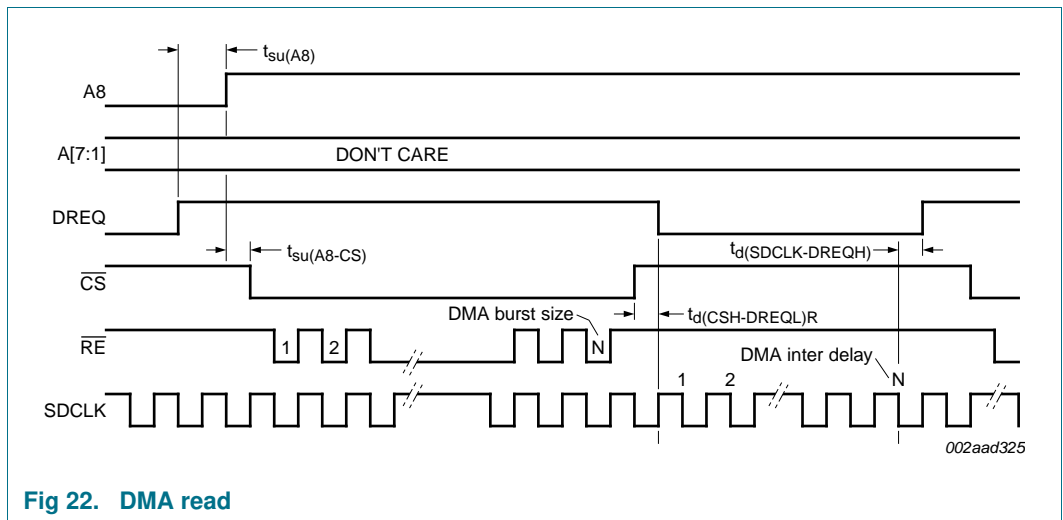


Fig 22. DMA read

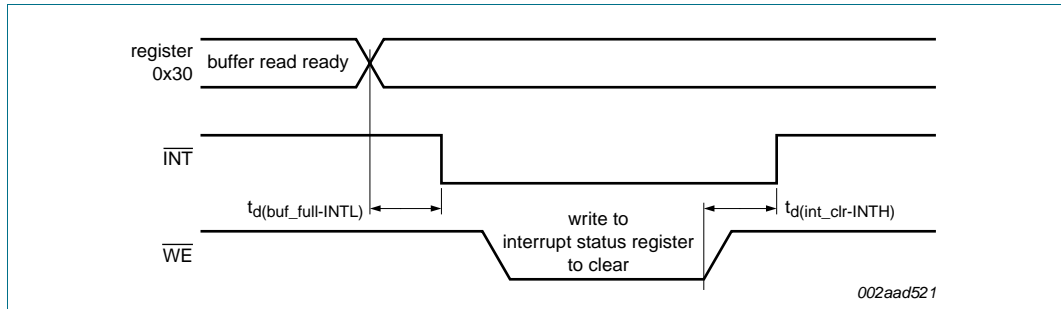


Fig 23. Buffer read ready interrupt

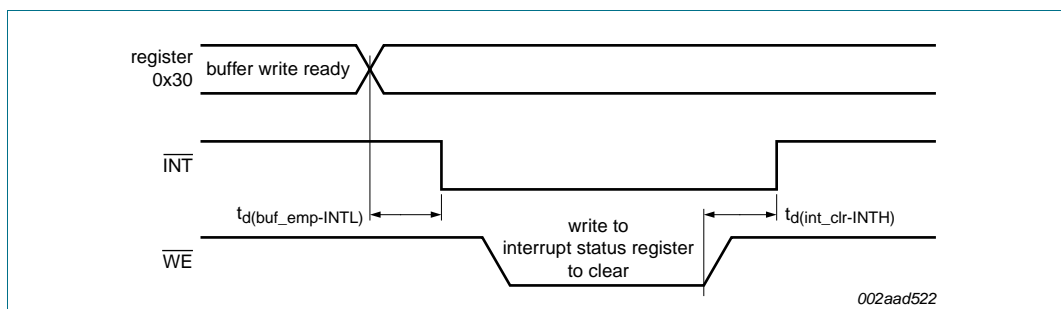
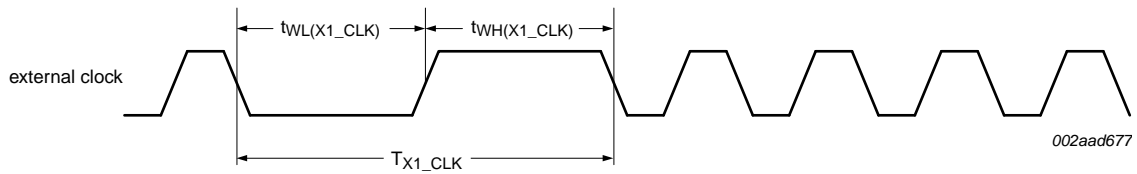


Fig 24. Buffer write ready interrupt



$$f_{X1_CLK} = \frac{1}{T_{X1_CLK}}$$

Fig 25. External clock timing

13. Package outline

HXQFN60: plastic compatible thermal enhanced extremely thin quad flat package; no leads; 60 terminals; body 5 x 5 x 0.5 mm

SOT1133-2

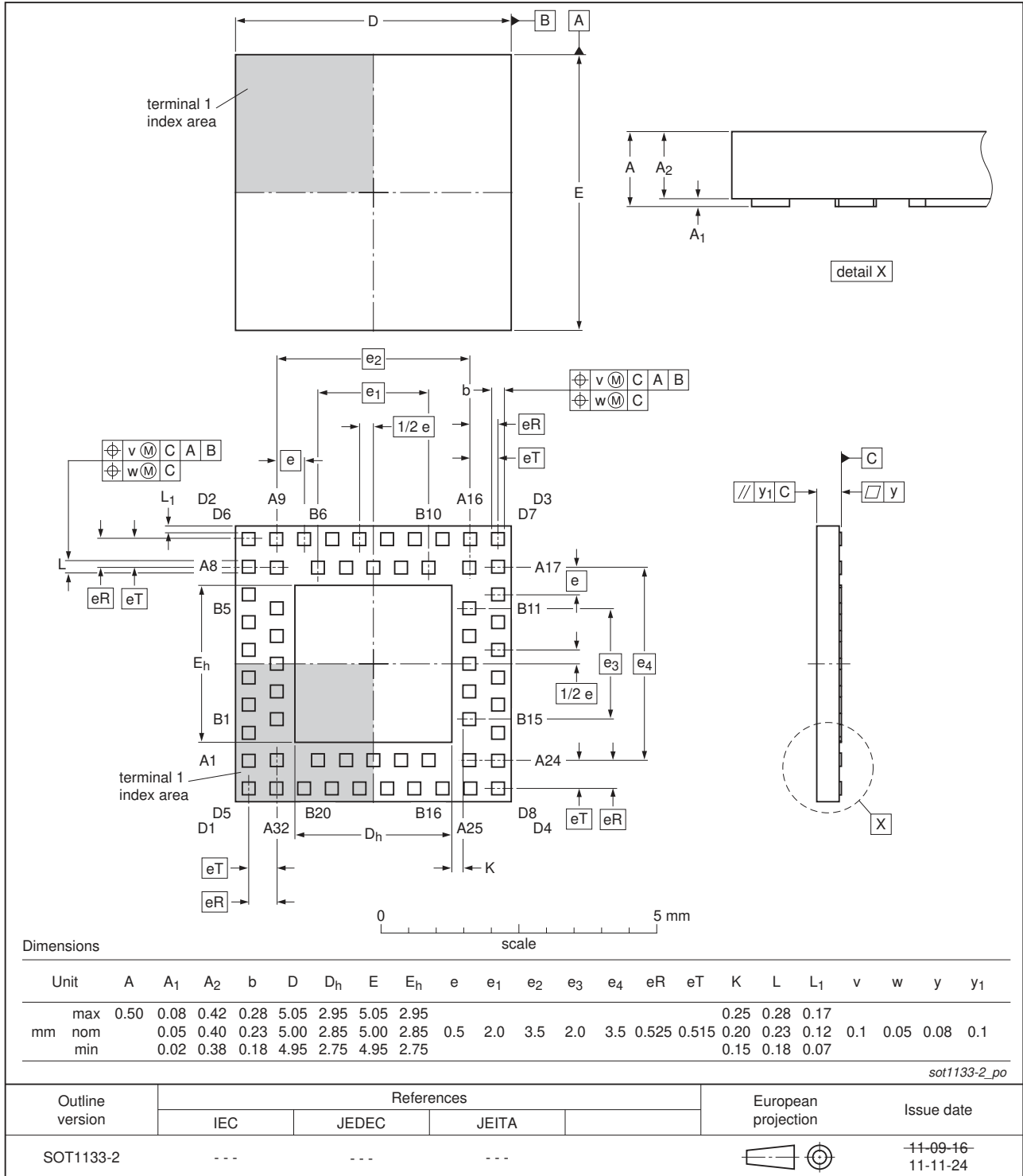


Fig 26. Package outline SOT1133-2 (HXQFN60)

14. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

14.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

14.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

14.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

14.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 27](#)) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 21](#) and [22](#)

Table 21. SnPb eutectic process (from J-STD-020D)

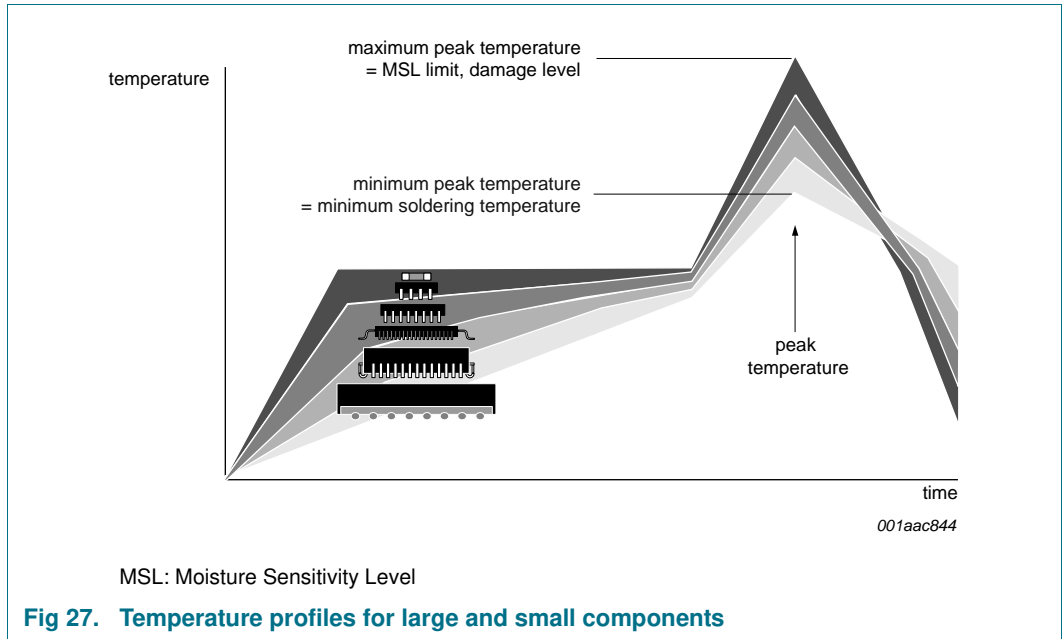
| Package thickness (mm) | Package reflow temperature (°C) | |
|------------------------|---------------------------------|-------|
| | Volume (mm ³) | |
| | < 350 | ≥ 350 |
| < 2.5 | 235 | 220 |
| ≥ 2.5 | 220 | 220 |

Table 22. Lead-free process (from J-STD-020D)

| Package thickness (mm) | Package reflow temperature (°C) | | |
|------------------------|---------------------------------|-------------|--------|
| | Volume (mm ³) | | |
| | < 350 | 350 to 2000 | > 2000 |
| < 1.6 | 260 | 260 | 260 |
| 1.6 to 2.5 | 260 | 250 | 245 |
| > 2.5 | 250 | 245 | 245 |

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 27](#).



For further information on temperature profiles, refer to Application Note AN10365 “Surface mount reflow soldering description”.

15. Appendix

15.1 Errata

This errata describes the functional behavior deviation of the SDIO101A from the data sheet Rev. 1.

15.1.1 Card detection in Hibernate mode or Coma mode

Card detection does not work when the device is in Coma mode or Hibernate mode. When put in these modes, the SDIO101A SD supply is powered down. When a card is inserted, the card detection circuit will not be able to detect the card because there is no power.

Workaround: If the card is to be put in Hibernate mode or Coma mode, a processor's GPIO pin with a pull-up resistor can be used to do card detect function. The pin is to be programmed as input, and set to interrupt on both edges. When a card is inserted, this GPIO pin will be pulled LOW by the card and an interrupt is generated. When a card is removed, this GPIO pin will be pulled HIGH by the pull-up resistor and an interrupt is generated.

15.1.2 SD side data rate limitation at 1.8 V

The current device does not work at 52 MHz when the $V_{DD(SD)}$ supply is at 1.8 V. When powered at 1.8 V, the SD side works up to about 30 MHz. (Please note that when $V_{DD(SD)}$ is 2.5 V to 3.3 V, there is no data rate limitation and the device works up to 52 MHz).

Workaround: There is no known workaround solution for this issue, if the card is to be used at 52 MHz with 1.8 V supply. To run the card at 52 MHz, $V_{DD(SD)}$ must be powered at 2.5 V minimum.

15.1.3 High current on V_{DD} pin after power-up

After power-up, V_{DD} pin draws close to 2 mA then the current slowly drops down to the idle current state at 68 μ A in about 40 seconds. This issue does not have any effect on the normal operation of the device, and the high current only occurs just after the device is powered up.

Workaround: We are investigating this issue to find out what might cause this problem. And, since the issue does not alter the behavior of the device and a root cause has not been identified, there is not a workaround for this issue at this time.

16. Abbreviations

Table 23. Abbreviations

| Acronym | Description |
|---------|---|
| CE-ATA | Consumer Electronics Advanced Technology Attachment |
| CPU | Central Processing Unit |
| DMA | Direct Memory Access |
| FIFO | First In, First Out |
| GPIO | General Purpose Input/Output |
| IO | Input/Output |
| kB | kiloByte |
| LED | Light Emitting Diode |
| MMC | Multi-Media Card |
| PCB | Printed-Circuit Board |
| PLL | Phase-Locked Loop |
| PU | Pull-Up |
| SD | Secure Digital |
| SDIO | Secure Digital Input/Output |

17. References

- [1] *SD Specifications Part A2, SD Host Controller Standard Specification, Version 2.00*, February 2007
- [2] *SD Specifications Part E1, SDIO Specification, Version 2.00*, February 8, 2007
- [3] *SD Specifications Part 1, Physical Layer Specification, Version 2.0*, May 9, 2006
- [4] *The Multimedia Card, System Specification Version 4.1*
- [5] *CE-ATA Digital Protocol, Version 1.1*

18. Revision history

Table 24. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|--------------|--------------|--------------------|---------------|------------|
| SDIO101A v.1 | 20130613 | Product data sheet | - | - |

19. Legal information

19.1 Data sheet status

| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

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